#### CHAPTER 3

Lists, Stacks, and Queues

§1 Abstract Data Type (ADT)

**【Definition】** Data Type = { Objects } ∪ { Operations }

[Example] int = 
$$\{0, \pm 1, \pm 2, \cdots, INT\_MAX, INT\_MIN\}$$
  
 $\cup \{+, -, \times, \div, \%, \cdots\}$ 

[Definition] An Abstract Data Type (ADT) is a data type that is organized in such a way that the specification on the objects and specification of the operations on the objects are separated from the representation of the objects and the implementation on the operations.

# §2 The List ADT

#### **❖** ADT:

**Objects:** (item<sub>0</sub>, item<sub>1</sub>, ..., item<sub>N-1</sub>)

### **Operations:**

- Finding the length, N, of a list.
- Printing all the items in a list.
- Making an empty list.
- Finding the k-th item from sist,  $0 \le k < N$ .
- Inserting a new item after the k-th item of a list,  $0 \le k < N$ .
- Deleting an item from a list.
- Finding next of the current item from a list.
- Finding previous of the current item from a list.

## 1. Simple Array implementation of Lists

 $\begin{array}{c|c} \mathbf{array}[\ i\ ] = \mathbf{item}_i & \underline{\mathbf{Address}} & \underline{\mathbf{Content}} \\ & \underline{\mathbf{.....}} & \underline{\mathbf{......}} \\ \mathbf{Sequential\ mapping} & \underline{\mathbf{array}+i} & \mathbf{item}_i \\ \mathbf{array}+i+1 & \mathbf{item}_{i+1} \\ \hline & \underline{\mathbf{.....}} \\ \end{array}$ 



**MaxSize** has to be

estimated.

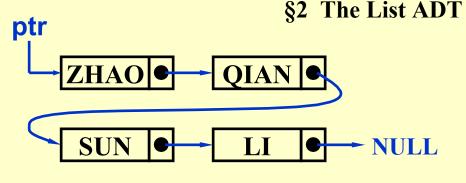
Find\_Kth takes O(1) time.

Insertion and Deletion not only take O(N) time, but also involve a lot of data movements which takes time.



#### 2. Linked Lists

Address	Data	Pointer
0010	SUN	1011
0011	QIAN	0010
0110	ZHAO	0011
1011	LI	NULL



izeof(struct list\_node));

of(struct list\_node));

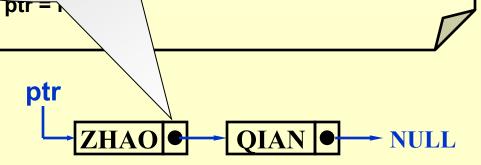
To link 'ZHAO' and 'QIAN':

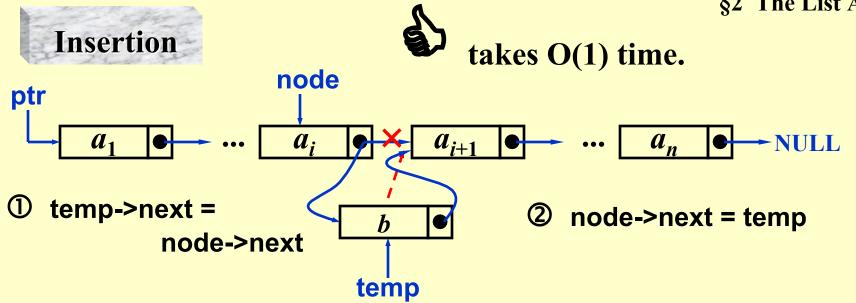
Head pointer ptr = 0110

**Initialization:** 

Locations of the nodes may change on different runs.

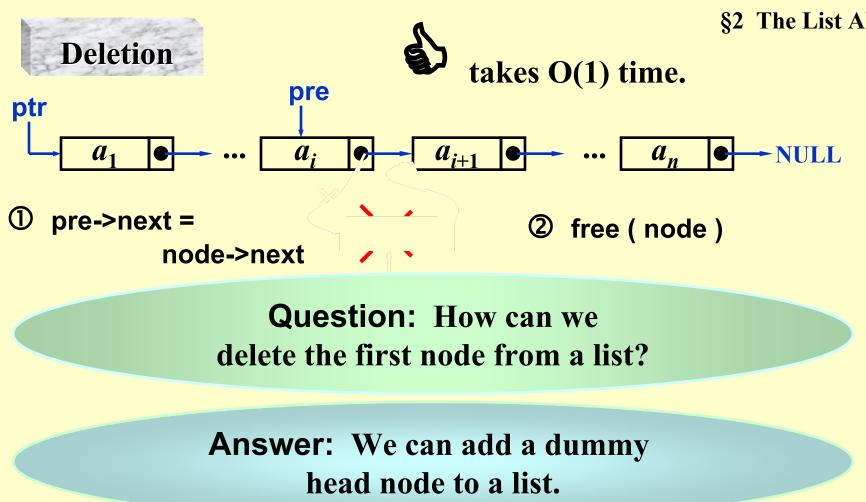
```
typedef struct list_node *ns
typedef struct list_node {
    char    data [ 4 ];
    list_ptr    next;
};
list_ptr    ptr;
```





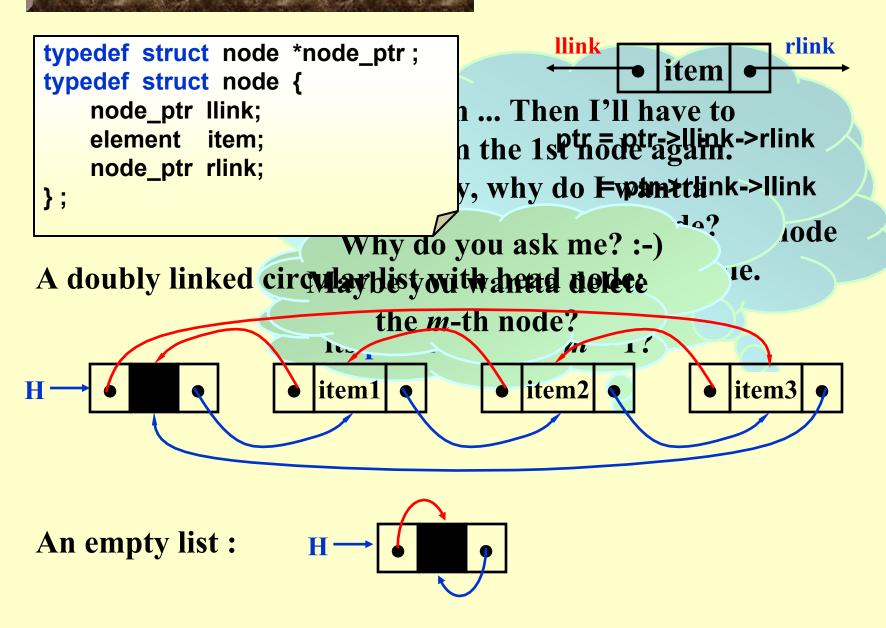
**Question:** What will happen if the order of the two steps is reversed?

**Question:** How can we insert a new first item?



Read programs in Figures 3.6-3.15 for detailed implementations of operations.

### **Doubly Linked Circular Lists**



# Two Applications

# **\* The Polynomial ADT**

**Objects**:  $P(x) = a_1 x^{e_1} + \dots + a_n x^{e_n}$ ; a set of ordered pairs of  $\langle e_i, a_i \rangle$  where  $a_i$  is the coefficient and  $e_i$  is the exponent.  $e_i$  are nonnegative integers.

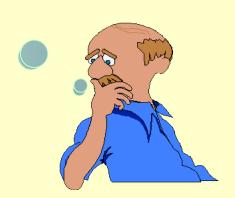
### **Operations:**

- Finding degree, max  $\{e_i\}$ , of a polynomial.
- Addition of two polynomials.
- Subtraction between two polynomials.
- Multiplication of two polynomials.
- Differentiation of a polynomial.

```
【Representation 1】
typedef struct {
    int CoeffArray [ MaxDegree + 1 ];
    int HighPower;
} *Polynomial;
```

```
Try to apply MultPolynomial (p.47) On P_1(x) = 10x^{1000} + 5x^{14} + 1 and P_2(x) = 3x^{1990} - 2x^{1492} + 11x + 5 -- now do you see my point?
```



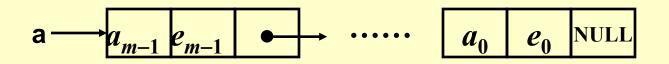


### [Representation 2]

```
Given: A(x) = a_{m-1}x^{e_{m-1}} + L + a_0x^{e_0}
where e_{m-1} > e_{m-2} > L > e_0 \ge 0 and a_i \ne 0 for i = 0, 1, L, m-1.
```

We represent each term as a node | Coefficient | Exponent | Next of

```
Declaration:
typedef struct poly_node *poly_ptr;
struct poly_node {
         Coefficient; /* assume coefficients are integers */
   int Exponent;
   poly_ptr Next;
typedef poly_ptr a; /* nodes sorted by exponent */
```

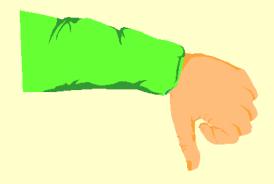


**Example** Suppose that we have 40,000 students and 2,500 courses. Print the students' name list for each course, and print the registered classes' list for each student.

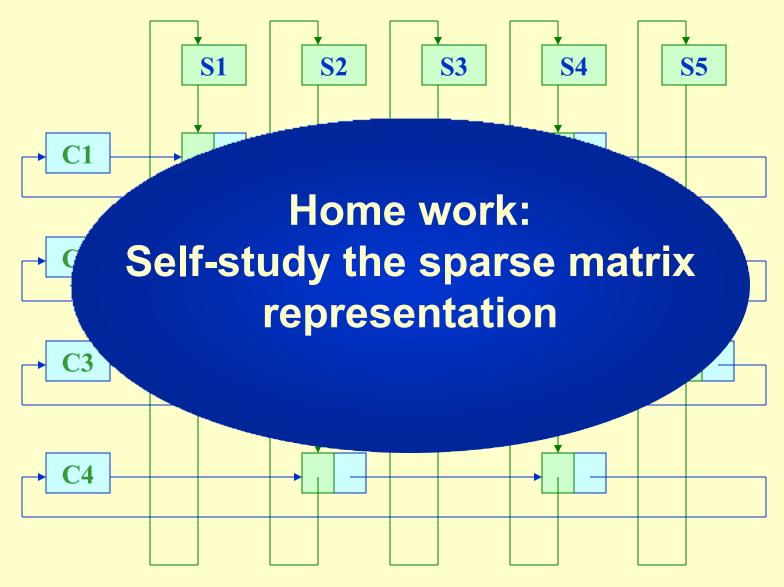
# [Representation 1]

## int Array[40000][2500];

$$Array[i][j] = \begin{cases} 1 & \text{if student } i \text{ is registered for course } j \\ 0 & \text{otherwise} \end{cases}$$



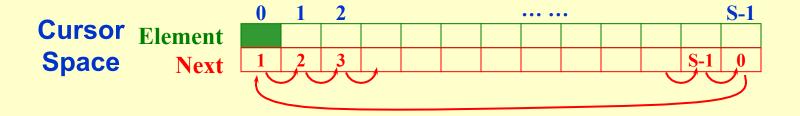
# [Representation 2]



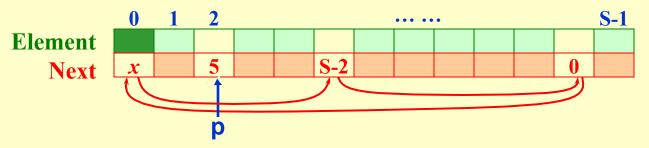
### 3. Cursor Implementation of Linked Lists (no pointer)

#### Features that a linked list must have:

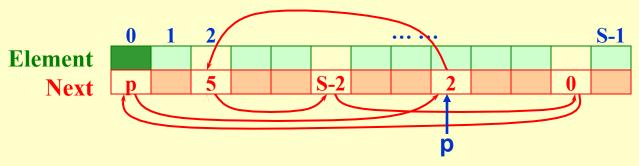
- a) The data are stored in a collection of structures. Each structure contains data and a pointer to the next structure.
- b) A new structure can be obtained from the system's global memory by a call to malloc and released by a call to free.



Note: The interface for the cursor implementation (given in Figure 3.27 on p. 52) is identical to the pointer implementation (given in Figure 3.6 on p. 40).



malloc: p = CursorSpace[ 0 ].Next ;
CursorSpace[ 0 ].Next = CursorSpace[ p ].Next ;



free(p): CursorSpace[ p ].Next = CursorSpace[ 0 ].Next ;
CursorSpace[ 0 ].Next = p ;

Read operation implementations given in Figures 3.31-3.35

Note: The cursor implementation is usually significantly faster because of the lack of memory management routines.