HPSC Lab2

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1 Parallel Design

This assignment utilizes multiple cores to build out a grid. The objective is to get us thinking about how parallel pieces should connect to take advantage of the strengths present in parallel computing. As a result, this task functions more as a "change your way of thinking" assignment rather than a difficult coding assignment like those present in other classes. Nonetheless, parallelizing a grid like this turned out a lot harder than it initially seemed.

In this lab, we need to implement a finite difference solver for Laplace's equation on a grid that is decomposed among multiple processors using MPI for parallelism. The linear system is solved iteratively, and the code handles boundary conditions and communication between processors effectively.

- fd.cpp: This is the main program file that contains the main function. It initializes MPI, performs grid decomposition, forms a linear system, solves it using either Gauss-Seidel or Jacobi iteration, and plots the results. It also includes a class called LaplacianOnGrid.
- **fd.h**: This header file contains various include statements, macros, and typedefs used throughout the code. It's included in both **fd.cpp** and **gauss_seidel.h**.
- gauss_seidel.h: This header file defines a function **GS_or_Jacobi** that performs Gauss-Seidel or Jacobi iterations to solve a linear system. It's used in **fd.cpp** for solving the linear system.
- mpiinfo.h: This header file defines the mpiInfo class, which contains information about the MPI environment, such as the processor's rank, number of processors, grid decomposition, and functions for exchanging boundary information between processors.

In this lab we use a parallel approach for tackling the Laplace equation through a finite difference method using MPI (Message Passing Interface). It begins by dividing the problem domain into a grid, with each grid point representing a variable to be solved for. This 2D grid is then distributed across multiple MPI processes, creating a structured processor grid, where each process is assigned a unique identifier (myPE) and a position in the processor grid (iPE, jPE). Communication plays a pivotal role, as each processor needs to exchange boundary values with its neighboring processors to facilitate the solution of the Laplace equation. These neighbors are determined by the processor's position within the grid. The communication itself is handled through MPI point-to-point communication routines. The formulation of the linear system is central to the code's functionality.

The LaplacianOnGrid class defines the grid and its associated variables, ultimately constructing the matrix A and the right-hand side vector b that constitute the linear system Ax = b, representing the Laplace equation. The code accommodates various boundary conditions, including Dirichlet boundary conditions, depending on the specific problem requirements. For the iterative solution phase, the code implements two iterative methods, namely Gauss-Seidel and Jacobi. These methods continue to iterate until a convergence criterion is met. Each iteration involves not only updating the interior grid points but also communicating boundary values with neighboring processors and verifying convergence against a specified tolerance or a maximum iteration count. Parallel communication, managed by the ExchangeBoundaryInfo function, is vital for synchronizing boundary values between neighboring processors. This function sends values from one processor to another and receives values in return. The received boundary values are then employed to update boundary nodes and apply relevant boundary conditions for the subsequent iteration.

The main parallelization strategy centers on domain decomposition. By dividing the computational domain into smaller subdomains, each assigned to a different MPI process. Processors exclusively focus on their designated portions of the grid and interact solely with neighboring processors to solve the problem.

2 Self Evaluation

2.1 Luna

I really had a problem with the loading and compiling more than anything else. I have included the ex01 bat slurm file I had to modify, but it was throwing errors with required library dependencies until I made the change to update and use gcc instead of intel like originally written. On top of that, I made an error in changing around nPEx and nPEy that I could not even see until libstdc++ was fixed and various loading attempts occurred. I really spent a lot more time fighting my computer than actually coding the mpiInfo. I am glad Mehmood was able to get that part done so quickly and efficiently in that time.

2.2 Mehmood

At first, I had trouble running my program on a single processor. It took me a while to figure out that I needed to make changes to the slurm file by setting nPEx and nPEy to 1. I also had to modify the task nodes. After some trial and error, I finally managed to run it successfully.

I also had some issues when trying to plot graphs with Gnuplot. I made a simple mistake where every time I ran the command "load pc," it asked for a file name. It took me a while to realize that I should use the command "load 'pc" with single quotes around 'pc'.

Implementing boundary conditions and debugging the program was a bit challenging. Debugging took up a significant amount of time. I used multiple "cout" statements to check the program's outputs. When working on the boundary conditions, I learned that it was crucial to make sure that neighboring processors communicated accurately and on time. In the beginning, I got some strange plots due to communication errors between processors. I spent most of my time debugging for this lab. Due to the complex nature of the problem, we were solving, it took some time, but eventually, after watching the lecture multiple times, I was able to make it work.

3 Appendix A: Parallel Code

```
#include "fd.h"
3 void Exit()
4 {
    MPI_Barrier(MPI_COMM_WORLD);
    MPI_Finalize();
    exit(0);
8 }
9
10
11 // ==
  //
       \Pi
  11
      -11
           CLASS: mpiInfo
14
       \Pi
  11
15
16
  class mpiInfo
17
18 {
19
   public:
20
    int myPE;
21
    int numPE;
22
    int nRealx, nRealy;
23
    int nPEx, nPEy;
24
    int iPE , jPE;
25
    int iMin, iMax, jMin, jMax; // The global i-j numbers on this processor
26
27
    int nei_n, nei_s, nei_e, nei_w;
    int countx, county;
28
29
    double *phiL, *phiR;
30
    double *phiT, *phiB;
31
32
    double *phiSend_n, *phiSend_s;
33
    double *phiSend_e, *phiSend_w;
34
    double *phiRecv_n, *phiRecv_s, *phiRecv_e, *phiRecv_w;
35
36
    MPI_Status status;
37
38
    int
                 err;
39
                 tag;
40
    MPI_Request request;
41
    // -
42
    // |
43
    // |
             GridDecomposition: Set up PE numbering system in figure below and
44
45
    // |
                                 establish communication arrays.
    // |
47
    // |
                                 nPEx -- number of PEs in the x-direction
                                nPEy -- number of PEs in the y-direction
    //
48
                                 numPE = total number of PEs
    //
49
    //
50
                                  +----+ . . .
    //
51
52
    //
53
    //
```

```
// |
                                54
                                +----+ . . .
     //
     11
56
57
     //
     //
58
     //
59
                                1 1 1
     //
60
     //
                                | nPEx | nPEx+1|
61
     //
                                  1 1
62
                                +----+ . . .
     //
63
                                  1 1
64
     11
65
     //
                                                         | nPEx -1|
     //
                                      66
                                +----+ . . .
     //
67
     //
68
     //
69
     //
70
71
72
     void GridDecomposition(int _nPEx, int _nPEy, int nCellx , int nCelly)
73
74
75
      nRealx = nCellx + 1;
76
77
      nRealy = nCelly + 1;
78
      // Store and check incoming processor counts
79
80
      nPEx = _nPEx;
81
      nPEy = _nPEy;
82
83
      if (nPEx*nPEy != numPE)
84
        {
85
        if ( myPE == 0 ) cout << "Fatal Error: Number of PEs in x-y directions do
86
      not add up to numPE" << endl;</pre>
        MPI_Barrier(MPI_COMM_WORLD);
87
        MPI_Finalize();
88
89
        exit(0);
90
91
      // Get the i-j location of this processor, given its number. See figure above
92
93
       jPE = int(myPE/nPEx);
94
      iPE = myPE - jPE*nPEx;
95
96
      // Set neighbor values
97
98
      nei_n = nei_s = nei_e = nei_w = -1;
99
100
       if ( iPE > 0 )
101
102
      nei_w = myPE - 1;
103
104
        }
      if (jPE > 0)
106
```

```
nei_s = myPE-2;
107
108
       if ( iPE < nPEx-1 )
109
110
         {
      nei_e = myPE+1;
111
112
         }
       if (jPE < nPEy-1)
113
         {
114
      nei_n=myPE+2;
115
        }
116
117
118
119
       countx = nRealx + 2;
       county = nRealy + 2;
120
121
       phiL = new double [ county ];
122
       phiR = new double [ county ];
123
       phiT = new double [ countx ];
124
       phiB = new double [ countx ];
125
126
       phiSend_n = new double [ countx ];
127
       phiSend_s = new double [ countx ];
128
       phiSend_e = new double [ county ];
129
       phiSend_w = new double [ county ];
130
131
       phiRecv_n = new double [ countx ];
132
       phiRecv_s = new double [ countx ];
       phiRecv_e = new double [ county ];
133
       phiRecv_w = new double [ county ];
134
135
136
       tag = 0;
     }
137
138
     void ExchangeBoundaryInfo(VD &Solution, VD &b)
139
140
      sLOOP phiSend_n[s] = 0.;
141
      sLOOP phiSend_s[s] = 0.;
142
      tLOOP phiSend_e[t] = 0.;
143
144
      tLOOP phiSend_w[t] = 0.;
145
146
      // (1) Parallel communication on PE Boundaries: ** See fd.h for tLOOP and
147
       sLOOP macros **
      // -----
148
149
      // (1.1) Put them into communication arrays
150
151
      sLOOP phiSend_n[s] = Solution[pid(s, nRealy - 1)];
152
      sLOOP phiSend_s[s] = Solution[pid(s, 2)];
      tLOOP phiSend_e[t] = Solution[pid(nRealx - 1, t)];
154
      tLOOP phiSend_w[t] = Solution[pid(2, t)];
155
156
      // (1.2) Send them to neighboring PEs
157
      if ( nei_n >= 0 ) err = MPI_Isend(phiSend_n, nRealx + 2, MPI_DOUBLE, nei_n, 0,
158
       MPI_COMM_WORLD, &request);
      if ( nei_s >= 0 ) err = MPI_Isend(phiSend_s, nRealx + 2, MPI_DOUBLE, nei_s, 0,
159
```

```
MPI_COMM_WORLD, &request);
                         err = MPI_Isend(phiSend_e, nRealy + 2, MPI_DOUBLE, nei_e, 0,
      if ( nei_e >= 0 )
160
       MPI_COMM_WORLD, &request);
      if ( nei_w >= 0 ) err = MPI_Isend(phiSend_w, nRealy + 2, MPI_DOUBLE, nei_w, 0,
161
       MPI_COMM_WORLD, &request);
162
      // (1.3) Receive values from neighboring PEs' physical boundaries.
164
      if ( nei_n >= 0 ) { err = MPI_Irecv(phiRecv_n, nRealx + 2, MPI_DOUBLE, nei_n,
      0, MPI_COMM_WORLD, &request);
                                      MPI_Wait(&request,&status); }
      if ( nei_s >= 0 ) { err = MPI_Irecv(phiRecv_s, nRealx + 2, MPI_DOUBLE, nei_s,
       0, MPI_COMM_WORLD, &request);
                                      MPI_Wait(&request,&status); }
      if ( nei_e >= 0 ) { err = MPI_Irecv(phiRecv_e, nRealy + 2, MPI_DOUBLE, nei_e,
167
      0, MPI_COMM_WORLD, &request);
                                       MPI_Wait(&request,&status); }
      if ( nei_w >= 0 ) { err = MPI_Irecv(phiRecv_w, nRealy + 2, MPI_DOUBLE, nei_w,
168
      0, MPI_COMM_WORLD, &request);
                                       MPI_Wait(&request,&status); }
169
      // (1.4) If new information was received, store it in the candy-coating values
170
171
      if ( nei_n >= 0 ) sLOOP Solution[pid(s, nRealy + 1)] = phiRecv_n[s] ;
      if ( nei_s >= 0 ) sLOOP Solution[pid(s, 0)] = phiRecv_s[s] ;
173
      if ( nei_e >= 0 ) tLOOP Solution[pid(nRealx + 1, t)] = phiRecv_e[t] ;
      if ( nei_w >= 0 ) tLOOP Solution[pid(0, t)] = phiRecv_w[t] ;
177
      // (1.5) Apply exchanged information as BCs
      if ( nei_n >= 0 ) sLOOP b[pid(s, nRealy + 1)] = phiRecv_n[s] ;
179
      if ( nei_s \ge 0 ) sLOOP b[pid(s, 0)] = phiRecv_s[s] ;
180
      if ( nei_e >= 0 ) tLOOP b[pid(nRealx + 1, t)] = phiRecv_e[t] ;
181
      if ( nei_w \ge 0 ) tLOOP b[pid(0, t)] = phiRecv_w[t];
182
     };
183
184
185
     int pid(int i,int j) { return (i+1) + (j)*(nRealx+2); }
186
187
188
   };
```

Listing 1: mpiInfo.h

I also had to update my slurm file to get it to go. Unless I had it going with GCC and have it update, I would run into errors with libstdc++, and thus the whole thing would not load at all. Between this is and the error with my nPEx and nPEy, the files really fought back against me.

```
#!/bin/bash
2
  #
3
  #
4
5
    | This is a batch script for running a MPI parallel job on Summit
  #
    (o) To submit this job, enter: sbatch --export=CODE='/home/trmc7708/Lab2/
7
      fd_mpi/src' ex01.bat
    | (o) To check the status of this job, enter: squeue -u <username>
  #
9
10 # |
11
  # -
```

```
13 # -
14 # |
# | Part 1: Directives
16 # |
17 # -
18
19 #SBATCH --nodes=1
20 #SBATCH --ntasks=4
21 #SBATCH --time=00:01:00
22 #SBATCH --partition=atesting
#SBATCH --output=ex01-%j.out
25 # -
26 # |
27 # | Part 2: Loading software
30
31 module purge
32 module update gcc
33 module load gcc
34 module load impi
36 # -
37 # |
38 # | Part 3: User scripting
39 # |
40 # -
41
42 echo "=="
43 echo "||"
44 echo "|| Begin Execution of fd in slurm batch script."
45 echo "||"
46 echo "=="
47
   export OMPI_MCA_opal_common_ucx_opal_mem_hooks=1
48
49
   srun -n 4 ./fd -nPEx 2 -nPEy 2 -nCellx 5 -nCelly 5 > tty.out
50
51
52 echo "=="
53 echo "||"
54 echo "|| Execution of fd in slurm batch script complete."
55 echo "||"
56 echo "=="
```

Listing 2: The Slurm File

4 Appendix B: Output

4.1 Output of the Slurm

```
myPE: 1 x0 = 1
myPE: 1 x1 = 2
myPE: 1 y0 = 0
myPE: 1 y1 = 1
```

```
5 \text{ myPE}: 2 \text{ xO} = 0
6 \text{ myPE}: 2 \text{ x1} = 1
7 \text{ myPE}: 2 \text{ y0} = 1
8 \text{ myPE}: 2 \text{ y1} = 2
9 \text{ myPE}: 3 \text{ x0} = 1
10 myPE: 3 x1 = 2
  myPE: 3 y0 = 1
11
  myPE: 3 y1 = 2
12
13
   -----
14
16
   FINITE DIFFERENCE
   DEMO CODE
17
18
   Running on 4 processors
19
20
21
22
23
  Input Summary:
24
25
No. PE in x-direction: 2
               y-direction: 2
27
  No. Cells in x-direction: 5
29
             y-direction: 5
30
myPE: 0 x0 = 0
myPE: 0 x1 = 1
33 myPE: 0 y0 = 0
  myPE: 0 y1 = 1
35
  Form Linear System:
36
37
38
39
  Solve Linear System:
40
   -----
41
42
  Jacobi/GS converged in 57 iterations
43
44
  Plot Results:
45
```

Listing 3: tty.out

4.2 Outputs from Alpine

Before switching modules to update gcc and openmpi rather than intel

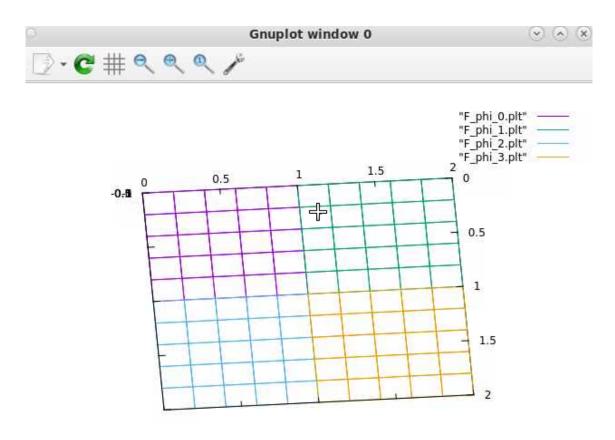
Listing 4: Output showing un-updated GCC warnings

After switching:

```
Lmod has detected the following error: These module(s) or extension(s) exist
  but cannot be loaded as requested: "impi"
     Try: "module spider impi" to see how to load the module(s).
4
5
6
  11
  || Begin Execution of fd in slurm batch script.
9
10
11
     ______
12
  WARNING: There was an error initializing an OpenFabrics device.
13
14
                c3cpu-a5-u34-3
15
    Local host:
    Local device: mlx5_0
18
  WARNING: There was an error initializing an OpenFabrics device.
19
20
    Local host:
                c3cpu-a5-u34-3
21
22
    Local device: mlx5_0
24
  WARNING: There was an error initializing an OpenFabrics device.
25
26
    Local host: c3cpu-a5-u34-3
27
   Local device: mlx5_0
28
  ______
  WARNING: There was an error initializing an OpenFabrics device.
31
32
    Local host:
33
                c3cpu-a5-u34-3
   Local device: mlx5_0
34
35
36
37
38 || Execution of fd in slurm batch script complete.
39
40
  ==
```

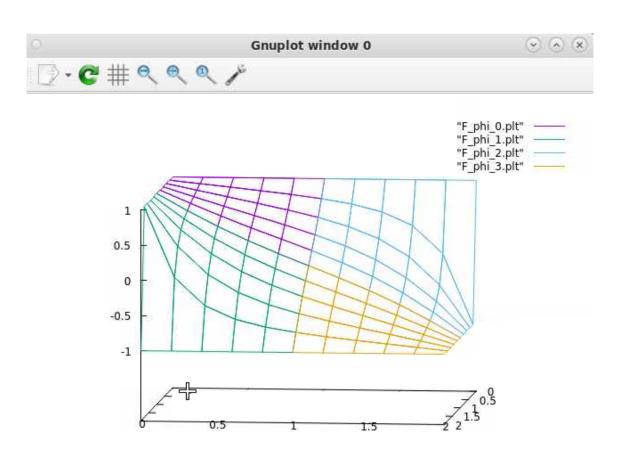
Listing 5: Output showing Warnings

4.3 Plot Images, showing interconnectivity



riew: 180.000, 4.00000 scale: 1.00000, 1.00000

Figure 1: Top Down Image



view: 81.0000, 96.0000 scale: 1.00000, 1.00000

Figure 2: Side Image

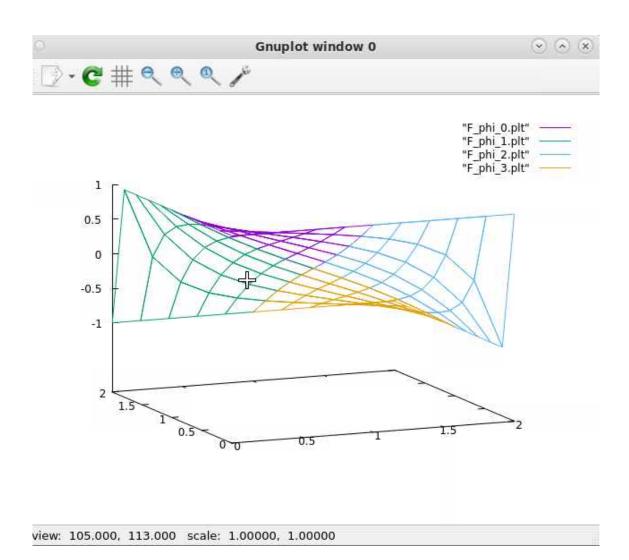
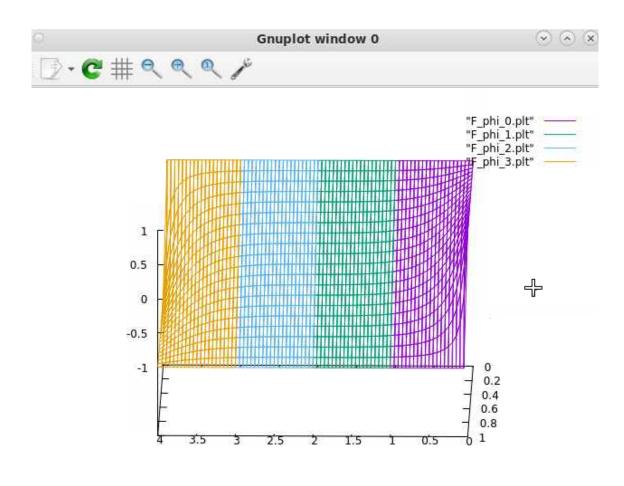


Figure 3: This one just looked cool



view: 71.0000, 181.000 scale: 1.00000, 1.00000

Figure 4: Challenge: nPEx 4 nPEy 1 with 20 cells each