

Lab 11 - Apply Penalty Methods to Evolutionary Algorithms to Solve Constrained Optimization Problems

CSE, SUSTech

Outline of This Lab

- Teaching Assistant
- What is Constrained Optimization Problem?
- What are Penalty Methods in Evolutionary Algorithms?
- Test Problems
- Experimental Setup
- Illustrate the Results!

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What is Constrained Optimization Problem?

The general problem we considered here can be described as:

$$\begin{array}{l} \min_x \{f(x)\} \\ \text{subject to} \end{array}$$

$$g_i(x) \leq 0, i = 1, 2, \dots, m$$

$$h_j(x) = 0, j = 1, 2, \dots, p$$

where

- x is the n -dimensional vector, $x = (x_1, x_2, \dots, x_n)$;
- $f(x)$ is the objective function;
- $g_i(x)$ is the inequality constraint;
- $h_j(x)$ is the equality constraint.

Denote the whole search space as S and the feasible space as F , $F \subset S$. It is important to note that the global in F might not be the same as that in S .

What are Penalty Methods in Evolutionary Algorithms?

-Introduction

NewObjectiveFunction = OriginalObjectiveFunction +
PenaltyCoefficient * DegreeOfConstraintViolation

The general form of the exterior penalty function method:

$$\psi(\mathbf{x}) = f(\mathbf{x}) + \left(\sum_{i=1}^m r_i G_i(\mathbf{x}) + \sum_{j=1}^p c_j H_j(\mathbf{x}) \right),$$

where

- ✓ $\psi(x)$ is the new objective function to be minimised,
- ✓ $f(x)$ is the original objective function,
- ✓ r_i and c_j are penalty factors (coefficients),
- ✓ $G_i(x) = (\max(0, g_i(x)))^\beta$ and $H_j(x) = \max(0, |h_j(x)|^\gamma)$.
- ✓ β and γ are usually chosen as 1 or 2.

What are Penalty Methods in Evolutionary Algorithms?

-Static Penalty Functions

$$\psi(\mathbf{x}) = f(\mathbf{x}) + \sum_{i=1}^m r_i (G_i(\mathbf{x}))^2$$

where r_i 's are pre-defined and fixed .

- ✓ Equality constraints can be converted into inequality ones:

$$h_j(x) \Rightarrow |h_j(x)| - \varepsilon \leq 0$$

where $\varepsilon > 0$ is a small number.

- ✓ Simple and easy to implement.
- ✓ Requires rich domain knowledge to set r_i 's.
- ✓ r_i 's can be divided into a number of different levels. When to use which is determined by a set of heuristic rules.

Test Problems I

The first optimization problem G1 consists of minimizing:

$$f(\mathbf{x}) = 5x_1 + 5x_2 + 5x_3 + 5x_4 - 5 \sum_{i=1}^4 x_i^2 - \sum_{i=5}^{13} x_i$$

subject to

$$\begin{aligned} 2x_1 + 2x_2 + x_{10} + x_{11} &\leq 10 \\ 2x_1 + 2x_3 + x_{10} + x_{12} &\leq 10 \\ 2x_2 + 2x_3 + x_{11} + x_{12} &\leq 10 \\ -8x_1 + x_{10} &\leq 0 \\ -8x_2 + x_{11} &\leq 0 \\ -8x_3 + x_{12} &\leq 0 \\ -2x_4 - x_5 + x_{10} &\leq 0 \\ -2x_6 - x_7 + x_{11} &\leq 0 \\ -2x_8 - x_9 + x_{12} &\leq 0 \end{aligned}$$

where

$$\begin{aligned} 0 \leq x_i &\leq 1, & i = 1, \dots, 9; \\ 0 \leq x_i &\leq 100, & i = 10, 11, 12; \\ 0 \leq x_i &\leq 1, & i = 13 \end{aligned}$$

Test Problems II

The second optimization problem minimizing:

$$\begin{aligned} f(\mathbf{x}) = & x_1^2 + x_2^2 + x_1x_2 - 14x_1 - 16x_2 + (x_3 - 10)^2 \\ & + 4(x_4 - 5)^2 + (x_5 - 3)^2 + 2(x_6 - 1)^2 + 5x_7^2 \\ & + 7(x_8 - 11)^2 + 2(x_9 - 10)^2 + (x_{10} - 7)^2 + 45 \end{aligned}$$

subject to

$$\begin{aligned} 105 - 4x_1 - 5x_2 + 3x_7 - 9x_9 &\geq 0 \\ -3(x_1 - 2)^2 - 4(x_2 - 3)^2 - 2x_3^2 + 7x_4 + 120 &\geq 0 \\ -10x_1 + 8x_2 + 17x_7 - 2x_8 &\geq 0 \\ -x_1^2 - 2x(x_2 - 2)^2 + 2x_1x_2 - 14x_5 + 6x_6 &\geq 0 \\ 8x_1 - 2x_2 - 5x_9 + 2x_{10} + 12 &\geq 0 \\ -5x_1^2 - 8x_2 - (x_3 - 6)^2 + 2x_4 + 40 &\geq 0 \\ 3x_1 - 6x_2 - 12(x_9 - 8)^2 + 7x_{10} &\geq 0 \\ -0.5(x_1 - 8)^2 - 2(x_2 - 4) - 3x_5^2 + x_6 + 30 &\geq 0 \end{aligned}$$

where

$$-10 \leq x_i \leq 10, \quad i = 1, \dots, 10$$

Experimental Setup

Implement an evolutionary algorithm with penalty functions to solve the above constrained optimization problems with 30 runs for each.

- ✓ population size: 50
- ✓ maximum generation number: 200

Illustrate The Results!

- Provide the obtained average best, mean, and standard deviation values of the two constrained optimization problems;
- Plot 2 figures to display the average fitness values over generations for the two constrained optimization problems, respectively .
 - ✓ x-axis: generation number
 - ✓ y-axis: average best fitness value

Note:

- ✓ The global minimum of the Problem 1 is known to be

$x^* = (1,1,1,1,1,1,1,1,1,3,3,3,1)$ with $f(x^*) = -15$.

- ✓ The global minimum of the Problem 2 is known to be

$x^* = (2.171996, 2.363683, 8.773926, 5.095984, 0.9906548, 1.430574, 1.321644, 9.828726, 8.280092, 8.375927)$

with $f(x^*) = 24.3062091$.