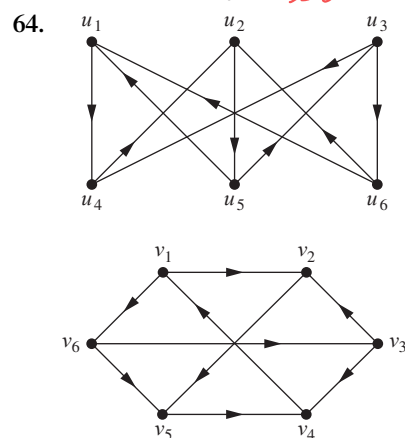
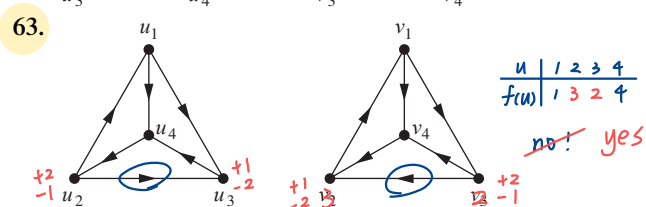
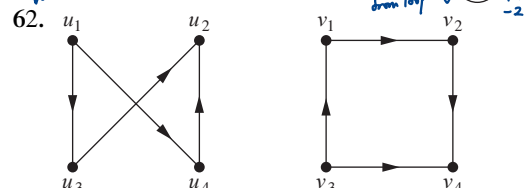
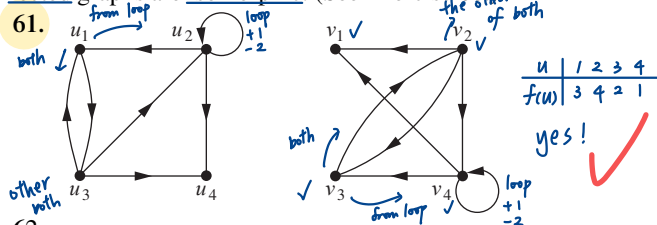


In Exercises 61–64 determine whether the given pair of directed graphs are isomorphic. (See Exercise 60)



65. Show that if G and H are isomorphic directed graphs, then the converses of G and H (defined in the preamble of Exercise 67 of Section 10.2) are also isomorphic.

66. Show that the property that a graph is bipartite is an isomorphic invariant.

67. Find a pair of nonisomorphic graphs with the same degree sequence (defined in the preamble to Exercise 36 in Section 10.2) such that one graph is bipartite, but the other graph is not bipartite.

*68. How many nonisomorphic directed simple graphs are there with n vertices, when n is

- a) 2? b) 3? c) 4?

*69. What is the product of the incidence matrix and its transpose for an undirected graph?

*70. How much storage is needed to represent a simple graph with n vertices and m edges using

- a) adjacency lists?
b) an adjacency matrix?
c) an incidence matrix?

A devil's pair for a purported isomorphism test is a pair of nonisomorphic graphs that the test fails to show that they are not isomorphic.

71. Find a devil's pair for the test that checks the degree sequence (defined in the preamble to Exercise 36 in Section 10.2) in two graphs to make sure they agree.

72. Suppose that the function f from V_1 to V_2 is an isomorphism of the graphs $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$. Show that it is possible to verify this fact in time polynomial in terms of the number of vertices of the graph, in terms of the number of comparisons needed.

10.4 Connectivity

Introduction

Many problems can be modeled with paths formed by traveling along the edges of graphs. For instance, the problem of determining whether a message can be sent between two computers using intermediate links can be studied with a graph model. Problems of efficiently planning routes for mail delivery, garbage pickup, diagnostics in computer networks, and so on can be solved using models that involve paths in graphs.

Paths

Informally, a path is a sequence of edges that begins at a vertex of a graph and travels from vertex to vertex along edges of the graph. As the path travels along its edges, it visits the vertices along this path, that is, the endpoints of these edges.

$12/15$ 14:47
1 read
17:24

A formal definition of paths and related terminology is given in Definition 1.

DEFINITION 1

Let n be a nonnegative integer and G an undirected graph. A *path* of length n from u to v in G is a sequence of n edges e_1, \dots, e_n of G for which there exists a sequence $x_0 = u, x_1, \dots, x_{n-1}, x_n = v$ of vertices such that e_i has, for $i = 1, \dots, n$, the endpoints x_{i-1} and x_i . When the graph is simple, we denote this path by its vertex sequence x_0, x_1, \dots, x_n (because listing these vertices uniquely determines the path). The path is a *circuit* if it begins and ends at the same vertex, that is, if $u = v$, and has length greater than zero. The path or circuit is said to pass through the vertices x_1, x_2, \dots, x_{n-1} or traverse the edges e_1, e_2, \dots, e_n . A path or circuit is *simple* if it does not contain the same edge more than once.

When it is not necessary to distinguish between multiple edges, we will denote a path e_1, e_2, \dots, e_n , where e_i is associated with $\{x_{i-1}, x_i\}$ for $i = 1, 2, \dots, n$ by its vertex sequence x_0, x_1, \dots, x_n . This notation identifies a path only as far as which vertices it passes through. Consequently, it does not specify a unique path when there is more than one path that passes through this sequence of vertices, which will happen if and only if there are multiple edges between some successive vertices in the list. Note that a path of length zero consists of a single vertex.

Remark: There is considerable variation of terminology concerning the concepts defined in Definition 1. For instance, in some books, the term **walk** is used instead of *path*, where a walk is defined to be an alternating sequence of vertices and edges of a graph, $v_0, e_1, v_1, e_2, \dots, v_{n-1}, e_n, v_n$, where v_{i-1} and v_i are the endpoints of e_i for $i = 1, 2, \dots, n$. When this terminology is used, **closed walk** is used instead of *circuit* to indicate a walk that begins and ends at the same vertex, and **trail** is used to denote a walk that has no repeated edge (replacing the term *simple path*). When this terminology is used, the terminology **path** is often used for a trail with no repeated vertices, conflicting with the terminology in Definition 1. Because of this variation in terminology, you will need to make sure which set of definitions are used in a particular book or article when you read about traversing edges of a graph. The text [GrYe06] is a good reference for the alternative terminology described in this remark.

EXAMPLE 1 In the simple graph shown in Figure 1, a, d, c, f, e is a simple path of length 4, because $\{a, d\}$, $\{d, c\}$, $\{c, f\}$, and $\{f, e\}$ are all edges. However, d, e, c, a is not a path, because $\{e, c\}$ is not an edge. Note that b, c, f, e, b is a circuit of length 4 because $\{b, c\}$, $\{c, f\}$, $\{f, e\}$, and $\{e, b\}$ are edges, and this path begins and ends at b . The path a, b, e, d, a, b , which is of length 5, is not simple because it contains the edge $\{a, b\}$ twice. ◀

Paths and circuits in directed graphs were introduced in Chapter 9. We now provide more general definitions.

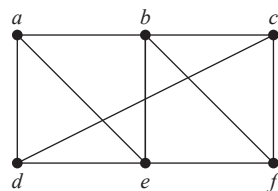


FIGURE 1 A Simple Graph.

DEFINITION 2

Let n be a nonnegative integer and G a directed graph. A *path* of length n from u to v in G is a sequence of edges e_1, e_2, \dots, e_n of G such that e_1 is associated with (x_0, x_1) , e_2 is associated with (x_1, x_2) , and so on, with e_n associated with (x_{n-1}, x_n) , where $x_0 = u$ and $x_n = v$. When there are no multiple edges in the directed graph, this path is denoted by its vertex sequence $x_0, x_1, x_2, \dots, x_n$. A path of length greater than zero that begins and ends at the same vertex is called a *circuit* or *cycle*. A path or circuit is called *simple* if it does not contain the same edge more than once.

Remark: Terminology other than that given in Definition 2 is often used for the concepts defined there. In particular, the alternative terminology that uses *walk*, *closed walk*, *trail*, and *path* (described in the remarks following Definition 1) may be used for directed graphs. See [GrYe05] for details.

Note that the terminal vertex of an edge in a path is the initial vertex of the next edge in the path. When it is not necessary to distinguish between multiple edges, we will denote a path e_1, e_2, \dots, e_n , where e_i is associated with (x_{i-1}, x_i) for $i = 1, 2, \dots, n$, by its vertex sequence x_0, x_1, \dots, x_n . The notation identifies a path only as far as which the vertices it passes through. There may be more than one path that passes through this sequence of vertices, which will happen if and only if there are multiple edges between two successive vertices in the list.

Paths represent useful information in many graph models, as Examples 2–4 demonstrate.

EXAMPLE 2

Paths in Acquaintanceship Graphs In an acquaintanceship graph there is a path between two people if there is a chain of people linking these people, where two people adjacent in the chain know one another. For example, in Figure 6 in Section 10.1, there is a chain of six people linking Kamini and Ching. Many social scientists have conjectured that almost every pair of people in the world are linked by a small chain of people, perhaps containing just five or fewer people. This would mean that almost every pair of vertices in the acquaintanceship graph containing all people in the world is linked by a path of length not exceeding four. The play *Six Degrees of Separation* by John Guare is based on this notion. ◀

EXAMPLE 3

Paths in Collaboration Graphs In a collaboration graph, two people a and b are connected by a path when there is a sequence of people starting with a and ending with b such that the endpoints of each edge in the path are people who have collaborated. We will consider two particular collaboration graphs here. First, in the academic collaboration graph of people who have written papers in mathematics, the **Erdős number** of a person m (defined in terms of relations in Supplementary Exercise 14 in Chapter 9) is the length of the shortest path between m and the extremely prolific mathematician Paul Erdős (who died in 1996). That is, the Erdős number of a mathematician is the length of the shortest chain of mathematicians that begins with Paul Erdős and ends with this mathematician, where each adjacent pair of mathematicians have written a joint paper. The number of mathematicians with each Erdős number as of early 2006, according to the Erdős Number Project, is shown in Table 1.

In the Hollywood graph (see Example 3 in Section 10.1) two actors a and b are linked when there is a chain of actors linking a and b , where every two actors adjacent in the chain have acted in the same movie. In the Hollywood graph, the **Bacon number** of an actor c is defined to be the length of the shortest path connecting c and the well-known actor Kevin Bacon. As new movies are made, including new ones with Kevin Bacon, the Bacon number of actors can change. In Table 2 we show the number of actors with each Bacon number as of early 2011 using data from the Oracle of Bacon website. The origins of the Bacon number of an actor dates back to the early 1990s, when Kevin Bacon remarked that he had worked with everyone in Hollywood or someone who worked with them. This lead some people to invent a party



Replace Kevin Bacon by your own favorite actor to invent a new party game

still not sure how does it work? How does the # come up ??

Links

TABLE 1 The Number of Mathematicians with a Given Erdős Number (as of early 2006).

<i>Erdős Number</i>	<i>Number of People</i>
0	1
1	504
2	6,593
3	33,605
4	83,642
5	87,760
6	40,014
7	11,591
8	3,146
9	819
10	244
11	68
12	23
13	5

??

TABLE 2 The Number of Actors with a Given Bacon Number (as of early 2011).

<i>Bacon Number</i>	<i>Number of People</i>
0	1
1	2,367
2	242,407
3	785,389
4	200,602
5	14,048
6	1,277
7	114
8	16

game where participants were challenged to find a sequence of movies leading from each actor named to Kevin Bacon. We can find a number similar to a Bacon number using any actor as the center of the acting universe. ◀

Connectedness in Undirected Graphs

When does a computer network have the property that every pair of computers can share information, if messages can be sent through one or more intermediate computers? When a graph is used to represent this computer network, where vertices represent the computers and edges represent the communication links, this question becomes: When is there always a path between two vertices in the graph?

DEFINITION 3

An undirected graph is called *connected* if there is a path between every pair of distinct vertices of the graph. An undirected graph that is not *connected* is called *disconnected*. We say that we *disconnect* a graph when we remove vertices or edges, or both, to produce a disconnected subgraph.

Thus, any two computers in the network can communicate if and only if the graph of this network is connected.

EXAMPLE 4

The graph G_1 in Figure 2 is connected, because for every pair of distinct vertices there is a path between them (the reader should verify this). However, the graph G_2 in Figure 2 is not connected. For instance, there is no path in G_2 between vertices a and d . ◀

We will need the following theorem in Chapter 11.

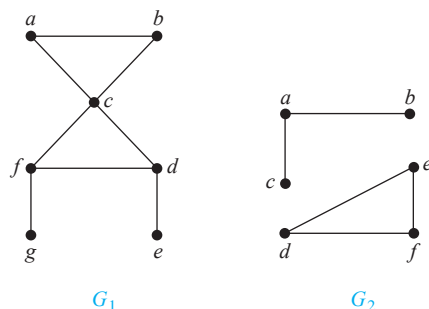


FIGURE 2 The Graphs G_1 and G_2 .

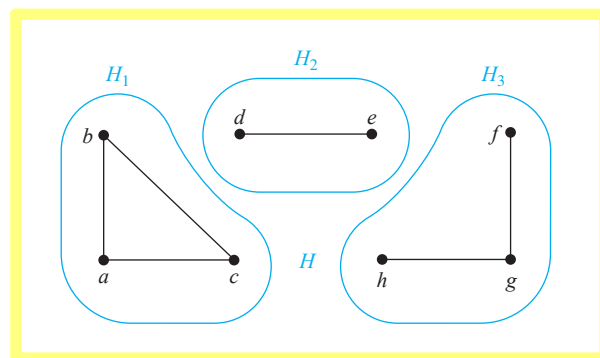


FIGURE 3 The Graph H and Its Connected Components H_1 , H_2 , and H_3 .

THEOREM 1

There is a simple path between every pair of distinct vertices of a connected undirected graph.

Proof: Let u and v be two distinct vertices of the connected undirected graph $G = (V, E)$. Because G is connected, there is at least one path between u and v . Let x_0, x_1, \dots, x_n , where $x_0 = u$ and $x_n = v$, be the vertex sequence of a path of least length. This path of least length is simple. To see this, suppose it is not simple. Then $x_i = x_j$ for some i and j with $0 \leq i < j$. This means that there is a path from u to v of shorter length with vertex sequence $x_0, x_1, \dots, x_{i-1}, x_j, \dots, x_n$ obtained by deleting the edges corresponding to the vertex sequence x_i, \dots, x_{j-1} . \triangleleft

CONNECTED COMPONENTS A **connected component** of a graph G is a **connected subgraph of G that is not a proper subgraph of another connected subgraph of G** . That is, a connected component of a graph G is a maximal connected subgraph of G . A graph G that is not connected has two or more connected components that are disjoint and have G as their union. } ???



EXAMPLE 5 What are the connected components of the graph H shown in Figure 3?

Solution: The graph H is the union of three disjoint connected subgraphs H_1 , H_2 , and H_3 , shown in Figure 3. These three subgraphs are the connected components of H . \triangleleft

EXAMPLE 6 Connected Components of Call Graphs Two vertices x and y are in the same component of a telephone call graph (see Example 4 in Section 10.1) when there is a sequence of telephone calls beginning at x and ending at y . When a call graph for telephone calls made during a particular day in the AT&T network was analyzed, this graph was found to have 53,767,087 vertices, more than 170 million edges, and more than 3.7 million connected components. Most of these components were small; approximately three-fourths consisted of two vertices representing pairs of telephone numbers that called only each other. This graph has one huge connected component with 44,989,297 vertices comprising more than 80% of the total. Furthermore, every vertex in this component can be linked to any other vertex by a chain of no more than 20 calls. \triangleleft



How Connected is a Graph?

Suppose that a graph represents a computer network. Knowing that this graph is connected tells us that any two computers on the network can communicate. However, we would also like to understand how reliable this network is. For instance, will it still be possible for all computers to communicate after a router or a communications link fails? To answer this and similar questions, we now develop some new concepts.

Sometimes the removal from a graph of a vertex and all incident edges produces a subgraph with more connected components. Such vertices are called **cut vertices** (or **articulation points**). The removal of a cut vertex from a connected graph produces a subgraph that is not connected. Analogously, an edge whose removal produces a graph with more connected components than in the original graph is called a **cut edge** or **bridge**. Note that in a graph representing a computer network, a cut vertex and a cut edge represent an essential router and an essential link that cannot fail for all computers to be able to communicate.

EXAMPLE 7

Find the cut vertices and cut edges in the graph G_1 shown in Figure 4.

Solution: The cut vertices of G_1 are b , c , and e . The removal of one of these vertices (and its adjacent edges) disconnects the graph. The cut edges are $\{a, b\}$ and $\{c, e\}$. Removing either one of these edges disconnects G_1 .

VERTEX CONNECTIVITY Not all graphs have cut vertices. For example, the complete graph K_n , where $n \geq 3$, has no cut vertices. When you remove a vertex from K_n and all edges incident to it, the resulting subgraph is the complete graph K_{n-1} , a connected graph. **Connected graphs without cut vertices** are called **nonseparable graphs**, and can be thought of as more connected than those with a cut vertex. We can extend this notion by defining a more granulated measure of graph connectivity based on the minimum number of vertices that can be removed to disconnect a graph.

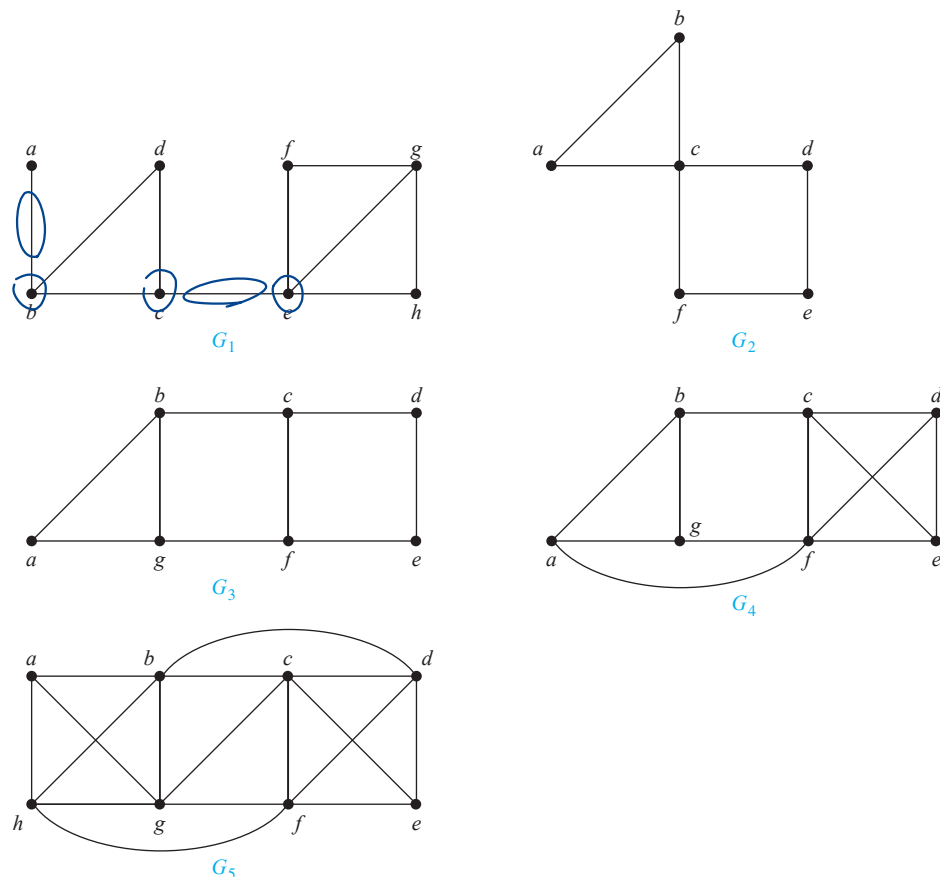


FIGURE 4 Some Connected Graphs

the definition above and the answers below doesn't match. The ex. is easily understandable, but the ↑ is like a whole different thing.

A subset V' of the vertex set V of $G = (V, E)$ is a **vertex cut**, or **separating set**, if $G - V'$ is **disconnected**. For instance, in the graph in Figure 1, the set $\{b, c, e\}$ is a vertex cut with three vertices, as the reader should verify. We leave it to the reader (Exercise 51) to show that **every connected graph, except a complete graph, has a vertex cut**. We define the **vertex connectivity** of a noncomplete graph G , denoted by $\kappa(G)$, as **the minimum number of vertices in a vertex cut**.

κ is the lowercase Greek letter kappa.

When G is a complete graph, it has no vertex cuts, because removing any subset of its vertices and all incident edges still leaves a complete graph. Consequently, we cannot define $\kappa(G)$ as the minimum number of vertices in a vertex cut when G is complete. Instead, we set $\kappa(K_n) = n - 1$, **the number of vertices needed to be removed to produce a graph with a single vertex**.


Consequently, for every graph G , $\kappa(G)$ is minimum number of vertices that can be removed from G to either disconnect G or produce a graph with a single vertex. We have $0 \leq \kappa(G) \leq n - 1$ if G has n vertices, $\kappa(G) = 0$ if and only if G is disconnected or $G = K_1$, and $\kappa(G) = n - 1$ if and only if G is complete [see Exercise 52(a)].

The larger $\kappa(G)$ is, the more connected we consider G to be. Disconnected graphs and K_1 have $\kappa(G) = 0$, connected graphs with cut vertices and K_2 have $\kappa(G) = 1$, graphs without cut vertices that can be disconnected by removing two vertices and K_3 have $\kappa(G) = 2$, and so on. We say that a graph is **k -connected** (or **k -vertex-connected**), if $\kappa(G) \geq k$. A graph G is 1-connected if it is connected and not a graph containing a single vertex; a graph is 2-connected, or **biconnected**, if it is nonseparable and has at least three vertices. Note that if G is a k -connected graph, then G is a j -connected graph for all j with $0 \leq j \leq k$.

EXAMPLE 8

Find the vertex connectivity for each of the graphs in Figure 4.

Solution: Each of the five graphs in Figure 4 is connected and has more than vertex, so each of these graphs has positive vertex connectivity. Because G_1 is a connected graph with a cut vertex, as shown in Example 7, we know that $\kappa(G_1) = 1$. Similarly, $\kappa(G_2) = 1$, because c is a cut vertex of G_2 .

The reader should verify that G_3 has **no cut vertices**, but that $\{b, g\}$ is a **vertex cut**. Hence, $\kappa(G_3) = 2$. Similarly, because G_4 has a **vertex cut** of size two, $\{c, f\}$, but **no cut vertices**. It follows that $\kappa(G_4) = 2$. The reader can verify that G_5 has **no vertex cut** of size two, but $\{b, c, f\}$ is a **vertex cut** of G_5 . Hence, $\kappa(G_5) = 3$. 


EDGE CONNECTIVITY We can also measure the connectivity of a connected graph $G = (V, E)$ in terms of the minimum number of edges that we can remove to disconnect it. If a graph has a cut edge, then we need only remove it to disconnect G . If G does not have a cut edge, we look for the smallest set of edges that can be removed to disconnect it. A set of edges E' is called an **edge cut** of G if the **subgraph $G - E'$ is disconnected**. The **edge connectivity** of a graph G , denoted by $\lambda(G)$, is **the minimum number of edges in an edge cut** of G . This defines $\lambda(G)$ for all connected graphs with more than one vertex because it is always possible to disconnect such a graph by removing all edges incident to one of its vertices. Note that $\lambda(G) = 0$ if G is not connected. We also specify that $\lambda(G) = 0$ if G is a graph consisting of a single vertex. It follows that if G is a graph with n vertices, then $0 \leq \lambda(G) \leq n - 1$. We leave it to the reader [Exercise 52(b)] to show that $\lambda(G) = n - 1$ where G is a graph with n vertices if and only if $G = K_n$, which is equivalent to the statement that $\lambda(G) \leq n - 2$ when G is not a complete graph.

λ is the lowercase Greek letter lambda.

EXAMPLE 9 Find the edge connectivity of each of the graphs in Figure 4.

Solution: Each of the five graphs in Figure 4 is connected and has more than one vertex, so we know that all of them have positive edge connectivity. As we saw in Example 7, G_1 has a cut edge, so $\lambda(G_1) = 1$.

The graph G_2 has no cut edges, as the reader should verify, but the removal of the two edges $\{a, b\}$ and $\{a, c\}$ disconnects it. Hence, $\lambda(G_2) = 2$. Similarly, $\lambda(G_3) = 2$, because G_3 has no cut edges, but the removal of the two edges $\{b, c\}$ and $\{f, g\}$ disconnects it.

The reader should verify that the removal of no two edges disconnects G_4 , but the removal of the three edges $\{b, c\}$, $\{a, f\}$, and $\{f, g\}$ disconnects it. Hence, $\lambda(G_4) = 3$. Finally, the reader should verify that $\lambda(G_5) = 3$, because the removal of any two of its edges does not disconnect it, but the removal of $\{a, b\}$, $\{a, g\}$, and $\{a, h\}$ does. 

AN INEQUALITY FOR VERTEX CONNECTIVITY AND EDGE CONNECTIVITY

When $G = (V, E)$ is a noncomplete connected graph with at least three vertices, the minimum degree of a vertex of G is an upper bound for both the vertex connectivity of G and the edge connectivity of G . That is, $\kappa(G) \leq \min_{v \in V} \deg(v)$ and $\lambda(G) \leq \min_{v \in V} \deg(v)$. To see this, observe that deleting all the neighbors of a fixed vertex of minimum degree disconnects G , and deleting all the edges that have a fixed vertex of minimum degree as an endpoint disconnects G .

In Exercise 55, we ask the reader to show that $\kappa(G) \leq \lambda(G)$ when G is a connected noncomplete graph. Note also that $\kappa(K_n) = \lambda(K_n) = \min_{v \in V} \deg(v) = n - 1$ when n is a positive integer and that $\kappa(G) = \lambda(G) = 0$ when G is a disconnected graph. Putting these facts together, establishes that for all graphs G ,

$$\kappa(G) \leq \lambda(G) \leq \min_{v \in V} \deg(v).$$

APPLICATIONS OF VERTEX AND EDGE CONNECTIVITY Graph connectivity plays an important role in many problems involving the reliability of networks. For instance, as we mentioned in our introduction of cut vertices and cut edges, we can model a data network using vertices to represent routers and edges to represent links between them. The vertex connectivity of the resulting graph equals the minimum number of routers that disconnect the network when they are out of service. If fewer routers are down, data transmission between every pair of routers is still possible. The edge connectivity represents the minimum number of fiber optic links that can be down to disconnect the network. If fewer links are down, it will still be possible for data to be transmitted between every pair of routers.

We can model a highway network, using vertices to represent highway intersections and edges to represent sections of roads running between intersections. The vertex connectivity of the resulting graph represents the minimum number of intersections that can be closed at a particular time that makes it impossible to travel between every two intersections. If fewer intersections are closed, travel between every pair of intersections is still possible. The edge connectivity represents the minimum number of roads that can be closed to disconnect the highway network. If fewer highways are closed, it will still be possible to travel between any two intersections. Clearly, it would be useful for the highway department to take this information into account when planning road repairs.

Connectedness in Directed Graphs

There are two notions of connectedness in directed graphs, depending on whether the directions of the edges are considered.

DEFINITION 4

A directed graph is strongly connected if there is a path from a to b and from b to a whenever a and b are vertices in the graph.

For a directed graph to be strongly connected there must be a sequence of directed edges from any vertex in the graph to any other vertex. A directed graph can fail to be strongly connected but still be in “one piece.” Definition 5 makes this notion precise.

DEFINITION 5

A directed graph is *weakly connected* if there is a path between every two vertices in the underlying undirected graph.

That is, a directed graph is weakly connected if and only if there is always a path between two vertices when the directions of the edges are disregarded. Clearly, any strongly connected directed graph is also weakly connected.

EXAMPLE 10 Are the directed graphs G and H shown in Figure 5 strongly connected? Are they weakly connected?

Solution: G is strongly connected because there is a path between any two vertices in this directed graph (the reader should verify this). Hence, G is also weakly connected. The graph H is not strongly connected. There is no directed path from a to b in this graph. However, H is weakly connected, because there is a path between any two vertices in the underlying undirected graph of H (the reader should verify this). ◀

STRONG COMPONENTS OF A DIRECTED GRAPH The subgraphs of a directed graph G that are strongly connected but not contained in larger strongly connected subgraphs, that is, the maximal strongly connected subgraphs, are called the **strongly connected components** or **strong components** of G . Note that if a and b are two vertices in a directed graph, their strong components are either the same or disjoint. (We leave the proof of this last fact as Exercise 17.)

EXAMPLE 11 The graph H in Figure 5 has three strongly connected components, consisting of the vertex a ; the vertex e ; and the subgraph consisting of the vertices b, c , and d and edges (b, c) , (c, d) , and (d, b) . ◀

EXAMPLE 12 **The Strongly Connected Components of the Web Graph** The Web graph introduced in Example 5 of Section 10.1 represents Web pages with vertices and links with directed edges. A snapshot of the Web in 1999 produced a Web graph with over 200 million vertices and over 1.5 billion edges (numbers that have now grown considerably). (See [Br00] for details.)



In 2010 the Web graph was estimated to have at least 55 billion vertices and one trillion edges. This implies that more than 40 TB of computer memory would have been needed to represent its adjacency matrix.

The underlying undirected graph of this Web graph is not connected, but it has a connected component that includes approximately 90% of the vertices in the graph. The subgraph of the original directed graph corresponding to this connected component of the underlying undirected graph (that is, with the same vertices and all directed edges connecting vertices in this graph) has one very large strongly connected component and many small ones. The former is called the **giant strongly connected component (GSCC)** of the directed graph. A Web page in this component can be reached following links starting at any other page in this component. The GSCC in the Web graph produced by this study was found to have over 53 million vertices. The remaining vertices in the large connected component of the undirected graph represent three different types of Web pages: pages that can be reached from a page in the GSCC, but do not link back to these pages following a series of links; pages that link back to pages in the

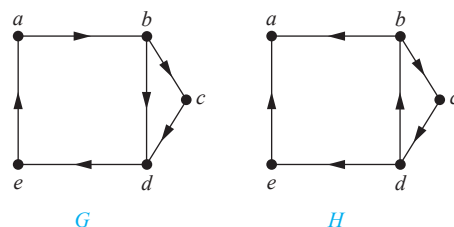


FIGURE 5 The Directed Graphs G and H .

GSCC following a series of links, but cannot be reached by following links on pages in the GSCC; and pages that cannot reach pages in the GSCC and cannot be reached from pages in the GSCC following a series of links. In this study, each of these three other sets was found to have approximately 44 million vertices. (It is rather surprising that these three sets are close to the same size.)

Paths and Isomorphism

There are several ways that paths and circuits can help determine whether two graphs are isomorphic. For example, the existence of a simple circuit of a particular length is a useful invariant that can be used to show that two graphs are not isomorphic. In addition, paths can be used to construct mappings that may be isomorphisms.

As we mentioned, a useful isomorphic invariant for simple graphs is the existence of a simple circuit of length k , where k is a positive integer greater than 2. (The proof that this is an invariant is left as Exercise 60.) Example 13 illustrates how this invariant can be used to show that two graphs are not isomorphic.

EXAMPLE 13

Determine whether the graphs G and H shown in Figure 6 are isomorphic.

Solution: Both G and H have six vertices and eight edges. Each has four vertices of degree three, and two vertices of degree two. So, the three invariants—number of vertices, number of edges, and degrees of vertices—all agree for the two graphs. However, H has a simple circuit of length three, namely, v_1, v_2, v_6, v_1 , whereas G has no simple circuit of length three, as can be determined by inspection (all simple circuits in G have length at least four). Because the existence of a simple circuit of length three is an isomorphic invariant, G and H are not isomorphic.

We have shown how the existence of a type of path, namely, a simple circuit of a particular length, can be used to show that two graphs are not isomorphic. We can also use paths to find mappings that are potential isomorphisms.

EXAMPLE 14

Determine whether the graphs G and H shown in Figure 7 are isomorphic.

Solution: Both G and H have five vertices and six edges, both have two vertices of degree three and three vertices of degree two, and both have a simple circuit of length three, a simple circuit of length four, and a simple circuit of length five. Because all these isomorphic invariants agree, G and H may be isomorphic.

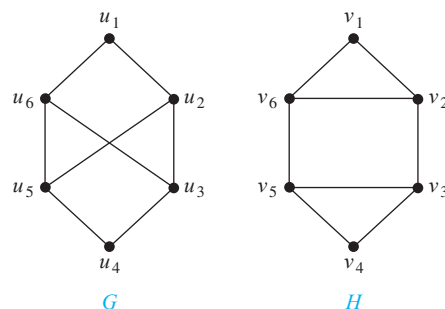


FIGURE 6 The Graphs G and H .

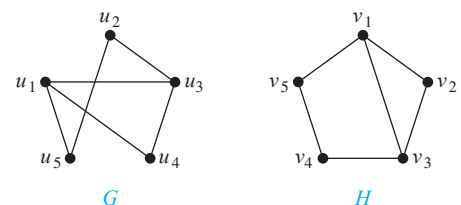


FIGURE 7 The Graphs G and H .

To find a possible isomorphism, we can follow paths that go through all vertices so that the corresponding vertices in the two graphs have the same degree. For example, the paths u_1, u_4, u_3, u_2, u_5 in G and v_3, v_2, v_1, v_5, v_4 in H both go through every vertex in the graph; start at a vertex of degree three; go through vertices of degrees two, three, and two, respectively; and end at a vertex of degree two. By following these paths through the graphs, we define the mapping f with $f(u_1) = v_3$, $f(u_4) = v_2$, $f(u_3) = v_1$, $f(u_2) = v_5$, and $f(u_5) = v_4$. The reader can show that f is an isomorphism, so G and H are isomorphic, either by showing that f preserves edges or by showing that with the appropriate orderings of vertices the adjacency matrices of G and H are the same. ◀

Counting Paths Between Vertices

The number of paths between two vertices in a graph can be determined using its adjacency matrix.

THEOREM 2

Let G be a graph with adjacency matrix A with respect to the ordering v_1, v_2, \dots, v_n of the vertices of the graph (with directed or undirected edges, with multiple edges and loops allowed). The number of different paths of length r from v_i to v_j , where r is a positive integer, equals the (i, j) th entry of A^r .

Proof: The theorem will be proved using mathematical induction. Let G be a graph with adjacency matrix A (assuming an ordering v_1, v_2, \dots, v_n of the vertices of G). The number of paths from v_i to v_j of length 1 is the (i, j) th entry of A , because this entry is the number of edges from v_i to v_j .

Assume that the (i, j) th entry of A^r is the number of different paths of length r from v_i to v_j . This is the inductive hypothesis. Because $A^{r+1} = A^r A$, the (i, j) th entry of A^{r+1} equals

$$b_{i1}a_{1j} + b_{i2}a_{2j} + \cdots + b_{in}a_{nj},$$

where b_{ik} is the (i, k) th entry of A^r . By the inductive hypothesis, b_{ik} is the number of paths of length r from v_i to v_k .

A path of length $r + 1$ from v_i to v_j is made up of a path of length r from v_i to some intermediate vertex v_k , and an edge from v_k to v_j . By the product rule for counting, the number of such paths is the product of the number of paths of length r from v_i to v_k , namely, b_{ik} , and the number of edges from v_k to v_j , namely, a_{kj} . When these products are added for all possible intermediate vertices v_k , the desired result follows by the sum rule for counting. ◀

EXAMPLE 15 How many paths of length four are there from a to d in the simple graph G in Figure 8?

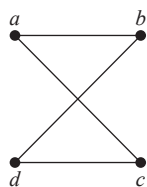


FIGURE 8 The Graph G .

Solution: The adjacency matrix of G (ordering the vertices as a, b, c, d) is

$$A = \begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix}.$$

Hence, the number of paths of length four from a to d is the $(1, 4)$ th entry of A^4 . Because

$$A^4 = \begin{bmatrix} 8 & 0 & 0 & 8 \\ 0 & 8 & 8 & 0 \\ 0 & 8 & 8 & 0 \\ 8 & 0 & 0 & 8 \end{bmatrix},$$



there are exactly eight paths of length four from a to d . By inspection of the graph, we see that a, b, a, b, d ; a, b, a, c, d ; a, b, d, b, d ; a, b, d, c, d ; a, c, a, b, d ; a, c, a, c, d ; a, c, d, b, d ; and a, c, d, c, d are the eight paths of length four from a to d .

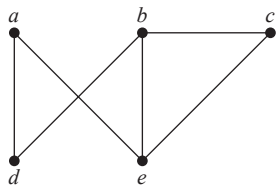
Theorem 2 can be used to find the length of the shortest path between two vertices of a graph (see Exercise 56), and it can also be used to determine whether a graph is connected (see Exercises 61 and 62).

Exercises

1. Does each of these lists of vertices form a path in the following graph? Which paths are simple? Which are circuits? What are the lengths of those that are paths? ④

- a) a, e, b, c, b
c) e, b, a, d, b, e

- b) a, e, a, d, b, c, a
d) c, b, d, a, e, c

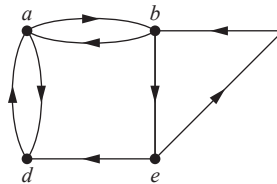


- ① (a) yes ✓ (b) no ✓
(c) no ✓ (d) yes ✓
② (d) ✓
③ (d) ✓
④ (a) 4 ✓ (d) 5 ✓

2. Does each of these lists of vertices form a path in the following graph? Which paths are simple? Which are circuits? What are the lengths of those that are paths?

- a) a, b, e, c, b
c) a, d, b, e, a

- b) a, d, a, d, a
d) a, b, e, c, b, d, a



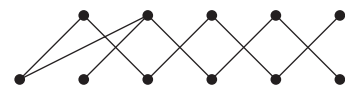
In Exercises 3–5 determine whether the given graph is connected.

3.

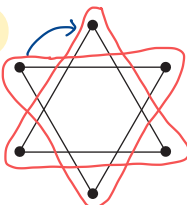


no ✓

4.



5.



no ✓

6. How many connected components does each of the graphs in Exercises 3–5 have? For each graph find each of its connected components.

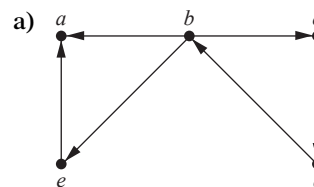
7. What do the connected components of acquaintanceship graphs represent?

8. What do the connected components of a collaboration graph represent?

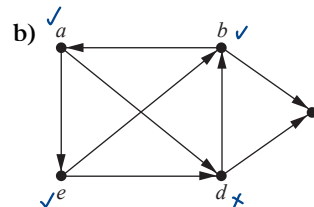
9. Explain why in the collaboration graph of mathematicians (see Example 3 in Section 10.1) a vertex representing a mathematician is in the same connected component as the vertex representing Paul Erdős if and only if that mathematician has a finite Erdős number.

10. In the Hollywood graph (see Example 3 in Section 10.1), when is the vertex representing an actor in the same connected component as the vertex representing Kevin Bacon?

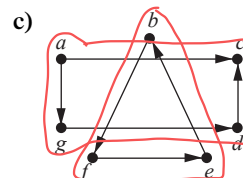
11. Determine whether each of these graphs is strongly connected and if not, whether it is weakly connected. ②



- ① no ✓
② yes ✓

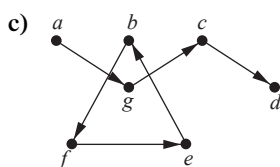
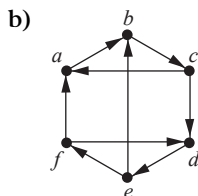
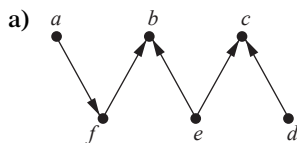


- ① no ✓
② yes ✓



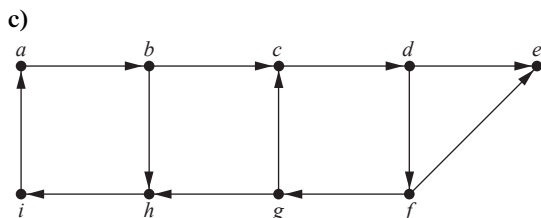
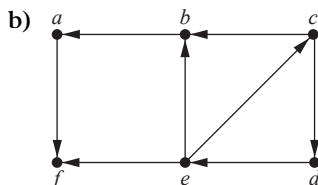
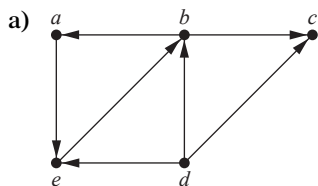
- ① no ✓
② no ✓

12. Determine whether each of these graphs is strongly connected and if not, whether it is weakly connected.

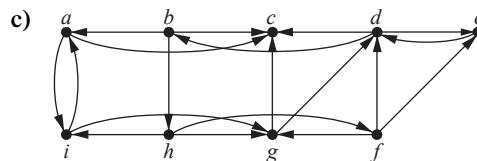
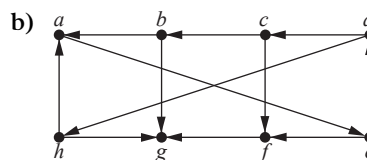
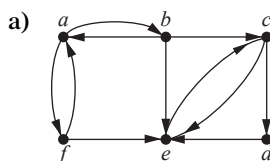


13. What do the strongly connected components of a telephone call graph represent?

14. Find the strongly connected components of each of these graphs.



15. Find the strongly connected components of each of these graphs.



Suppose that $G = (V, E)$ is a directed graph. A vertex $w \in V$ is **reachable** from a vertex $v \in V$ if there is a directed path from v to w . The vertices v and w are **mutually reachable** if there are both a directed path from v to w and a directed path from w to v in G .

16. Show that if $G = (V, E)$ is a directed graph and u, v , and w are vertices in V for which u and v are mutually reachable and v and w are mutually reachable, then u and w are mutually reachable.

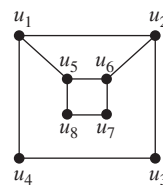
17. Show that if $G = (V, E)$ is a directed graph, then the strong components of two vertices u and v of V are either the same or disjoint. [Hint: Use Exercise 16.]

18. Show that all vertices visited in a directed path connecting two vertices in the same strongly connected component of a directed graph are also in this strongly connected component.

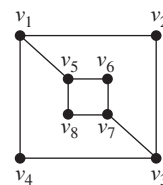
19. Find the number of paths of length n between two different vertices in K_4 if n is

a) 2. b) 3. c) 4. d) 5.

20. Use paths either to show that these graphs are not isomorphic or to find an isomorphism between these graphs.

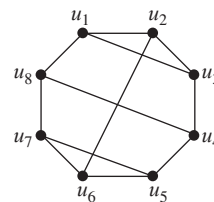


G

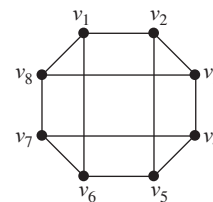


H

21. Use paths either to show that these graphs are not isomorphic or to find an isomorphism between them.

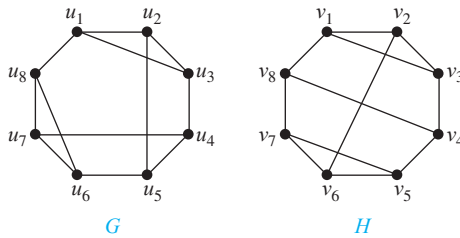


G

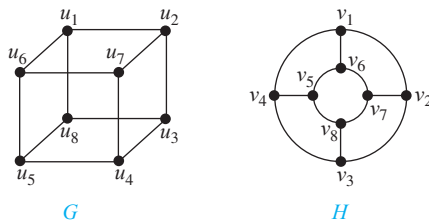


H

22. Use paths either to show that these graphs are not isomorphic or to find an isomorphism between them.



23. Use paths either to show that these graphs are not isomorphic or to find an isomorphism between them.



24. Find the number of paths of length n between any two adjacent vertices in $K_{3,3}$ for the values of n in Exercise 19.

25. Find the number of paths of length n between any two nonadjacent vertices in $K_{3,3}$ for the values of n in Exercise 19.

26. Find the number of paths between c and d in the graph in Figure 1 of length *a bit too hard to come up*

- a) 2. 0 b) 3. 3 c) 4. 4 d) 5. 7 e) 6. f) 7.

27. Find the number of paths from a to e in the directed graph in Exercise 2 of length

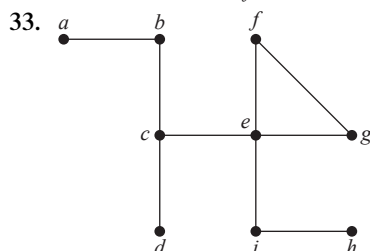
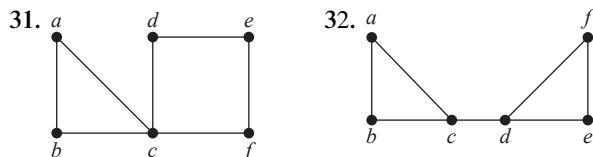
- a) 2. 1 b) 3. 0 c) 4. 1 d) 5. 1 e) 6. 5 f) 7. 3

- *28. Show that every connected graph with n vertices has at least $n - 1$ edges.

29. Let $G = (V, E)$ be a simple graph. Let R be the relation on V consisting of pairs of vertices (u, v) such that there is a path from u to v or such that $u = v$. Show that R is an equivalence relation.

- *30. Show that in every simple graph there is a path from every vertex of odd degree to some other vertex of odd degree.

In Exercises 31–33 find all the cut vertices of the given graph.



34. Find all the cut edges in the graphs in Exercises 31–33.

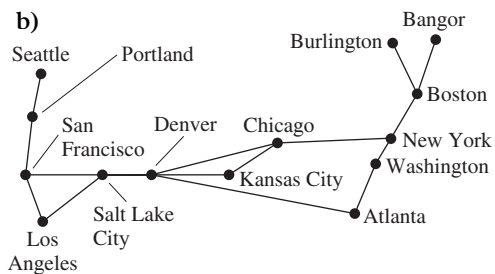
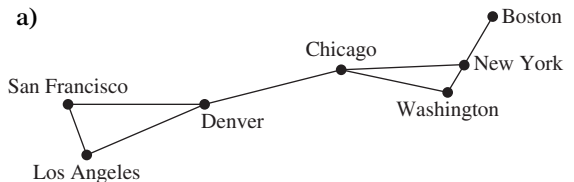
- *35. Suppose that v is an endpoint of a cut edge. Prove that v is a cut vertex if and only if this vertex is not pendant.

- *36. Show that a vertex c in the connected simple graph G is a cut vertex if and only if there are vertices u and v , both different from c , such that every path between u and v passes through c .

- *37. Show that a simple graph with at least two vertices has at least two vertices that are not cut vertices.

- *38. Show that an edge in a simple graph is a cut edge if and only if this edge is not part of any simple circuit in the graph.

39. A communications link in a network should be provided with a backup link if its failure makes it impossible for some message to be sent. For each of the communications networks shown here in (a) and (b), determine those links that should be backed up.



A **vertex basis** in a directed graph G is a minimal set B of vertices of G such that for each vertex v of G not in B there is a path to v from some vertex B .

40. Find a vertex basis for each of the directed graphs in Exercises 7–9 of Section 10.2.

41. What is the significance of a vertex basis in an influence graph (described in Example 2 of Section 10.1)? Find a vertex basis in the influence graph in that example.

42. Show that if a connected simple graph G is the union of the graphs G_1 and G_2 , then G_1 and G_2 have at least one common vertex.

- *43. Show that if a simple graph G has k connected components and these components have n_1, n_2, \dots, n_k vertices, respectively, then the number of edges of G does not exceed

$$\sum_{i=1}^k C(n_i, 2).$$