### **ICNPG 2023**

### Python y Julia



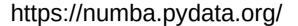




### GPUs y python

- Numba
- Cupy
- RAPIDS
- PyCUDA
- Etc...

- Interpreted languages:
  - · Python, Ruby, or JavaScript, etc.
  - Execute code directly from the source code without the need for a compilation step.
  - often have a simpler syntax and are easier to learn, read, and write.
  - better support for dynamic typing and dynamic memory management.
  - slower than compiled languages because they must interpret the code at runtime.
- · Compiled languages:
  - C, C++, Fortran, Julia, etc.
  - require a compilation step to translate the source code into machine code.
  - tend to have a more complex syntax and require more experience to learn, read, and write.
  - They often have better support for static typing and memory management.





# Accelerate Python Functions

Numba translates Python functions to optimized machine code at runtime using the industry-standard LLVM compiler library. Numba-compiled numerical algorithms in Python can approach the speeds of C or FORTRAN.

You don't need to replace the Python interpreter, run a separate compilation step, or even have a C/C++ compiler installed. Just apply one of the Numba decorators to your Python function, and Numba does the rest.

```
from numba import njit
import random

@njit
def monte_carlo_pi(nsamples):
    acc = 0
    for i in range(nsamples):
        x = random.random()
        y = random.random()
        if (x ** 2 + y ** 2) < 1.0:
        acc += 1
    return 4.0 * acc / nsamples</pre>
```



### https://numba.pydata.org/

### **Portable Compilation**

Ship high performance Python applications without the headache of binary compilation and packaging. Your source code remains pure Python while Numba handles the compilation at runtime. We test Numba continuously in more than 200 different platform configurations.

Numba supports Intel and AMD x86, POWER8/9, and ARM CPUs (including Apple M1), NVIDIA GPUs, Python 3.7-3.10, as well as Windows/macOS/Linux. Precompiled Numba binaries for most systems are available as conda packages and pip-installable wheels.

### **GPU** Acceleration



https://numba.readthedocs.io/en/stable/cuda/index.html

With support for NVIDIA CUDA, Numba lets you write parallel GPU algorithms entirely from Python.



### https://numba.pydata.org/

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### **GPU** Acceleration



With support for NVIDIA CUDA, Numba lets you write parallel GPU algorithms entirely from Python.

```
1 import numpy as np
2 from numba import cuda
```

```
1  @cuda.jit
2  def f(a, b, c):
3     # like threadIdx.x + (blockIdx.x * blockDim.x)
4     tid = cuda.grid(1)
5     size = len(c)
6
7     if tid < size:
        c[tid] = a[tid] + b[tid]</pre>
```

```
1  N = 100000
2  a = cuda.to_device(np.random.random(N))
3  b = cuda.to_device(np.random.random(N))
4  c = cuda.device_array_like(a)
```

#### FOR CUDA USERS

- ☐ Numba for CUDA GPUs
  - **⊞** Overview

  - Writing Device Functions
  - - **CUDA Fast Math**
- **⊞ Cooperative Groups**
- ⊞ Random Number Generation
- ⊕ Device management
- **⊞** The Device List
  - Device UUIDs
- **⊞ Examples**
- ⊕ Debugging CUDA Python with the the CUDA Simulator
- ⊕ GPU Reduction
- CUDA Ufuncs and Generalized
   Ufuncs
- **⊞ Sharing CUDA Memory**
- ⊕ CUDA Array Interface (Version 3)
- ⊞ External Memory Management (EMM) Plugin interface
- **⊞ CUDA Bindings**
- Calling foreign functions from Python kernels
- ⊕ On-disk Kernel Caching
- ⊕ CUDA Minor Version Compatiblity



NumPy/SciPy-compatible Array Library for GPU-accelerated Computing with Python

https://cupy.dev/

#### **HIGHLY COMPATIBLE WITH NUMPY & SCIPY**

```
>>> x = cp.arange(6, dtype='f').reshape(2, 3)
>>> y = cp.arange(3, dtype='f')
>>> kernel = cp.ElementwiseKernel(
        'float32 x, float32 y', 'float32 z',
. . .
     if (x - 2 > y) {
      z = x * y;
     } else {
      z = x + y;
      ''', 'my kernel')
>>> kernel(x, y)
array([[ 0., 2., 4.],
      [ 0., 4., 10.]], dtype=float32)
```

```
The N-dimensional array (ndarray)
Universal functions ( cupy, ufunc )
Routines (NumPv)
Routines (SciPy)
CuPy-specific functions
Low-level CUDA support
Custom kernels
Distributed
Environment variables
Comparison Table
Python Array API Support
```

## RAPIDS **GPU Accelerated Data Science**

### **PRFASTER PANDAS** WITH CUDF

cuDF is a near drop in replacement to pandas for most use cases and has greatly improved performance.

### **夢 FASTER SCIKIT-LEARN** WITH CUML

cuML brings huge speedups to ML modeling with an API that matches scikit-learn.

### ♥ FASTER NETWORKX WITH CUGRAPH

cuGraph makes migration from networkX easy, accelerates graph analytics, and allows scaling far beyond

existing tools.

- Dataframe processing with cuDF (similar API to pandas).
- ▶ Machine learning with cuML (similar API to scikit-learn)
- ▶ Graph processing with cuGraph (similar API to networkX)
- ▶ Spatial analytics with cuSpatial (similar API to geoPandas)
- ▶ Image processing with cuCIM (similar API to scikit-image)
- ▶ Signal processing cuSignal (similar API to scipy.signal)
- Seamless cross-filtered dashboards with cuxfilter
- ▶ Low level compute primitives with RAFT
- ▶ Apache Spark acceleration with Spark RAPIDS

```
url = "https://qithub.com/plotly/datasets/raw/master/tips.csy"
content = requests.get(url).content.decode('utf-8')
tips_df = cudf.read_csv(StringIO(content))
tips_df['tip_percentage'] = tips_df['tip'] / tips_df['total_bill'] * 100
print(tips_df.groupby('size').tip_percentage.mean())
```

### Ejercicio

```
#@title numpy
import numpy as np
import time
n = 100000000
# create x and y vectors
x = np.arange(1, n+1, dtype=np.float32)
y = np.arange(n, 0, -1, dtype=np.float32)
start time = time.time()
# create z vector
z = x + y
# normalize z by its Euclidean norm
norm = np.linalq.norm(z)
\#z norm = z / norm
# sum the elements of the final result
result = np.sum(z)/norm
# print the result and the time taken
print("Result:", result)
print("Time taken:", (time.time() - start time) * 1000000, "us")
tnumpy = (time.time() - start time) * 1000000
#print(x,y,z,z norm)
```

$$S = rac{\sum_{i=0}^{n}(x_i + y_i)}{\sqrt{\sum_{i=0}^{n}(x_i + y_i)^2}}$$

### Ejercicio: hacerlo en CUPY y NUMBA

### Tasa de contagio

$$\frac{dS}{dt} = -\beta SI,$$

$$\frac{dI}{dt} = \beta SI - \gamma I,$$

$$\frac{dR}{dt} = \gamma I.$$

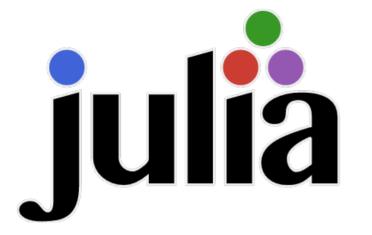
Método de Euler

$$S(t + \Delta t) = S(t) + \Delta t [-\beta I(t)S(t)]$$

$$I(t + \Delta t) = I(t) + \Delta t [\beta I(t) S(t) - \gamma I(t)]$$

$$R(t + \Delta t) = R(t) + \Delta t [\gamma I(t)]$$

Suceptible, Infectado, Recuperado



Julia is a good choice for numerical computing and scientific computing tasks that require **high performance and parallelism**, while Python is a good choice for general-purpose programming, web development, and data analysis tasks that require a large ecosystem of libraries and tools.

#### Julia in a Nutshell

#### Fast

Julia was designed from the beginning for high performance. Julia programs compile to efficient native code for multiple platforms via LLVM.

### Composable

Julia uses multiple dispatch as a paradigm, making it easy to express many object-oriented and functional programming patterns. The talk on the Unreasonable Effectiveness of Multiple Dispatch explains why it works so well.

#### Dynamic

Julia is dynamically typed, feels like a scripting language, and has good support for interactive use.

#### General

Julia provides asynchronous I/O, metaprogramming, debugging, logging, profiling, a package manager, and more. One can build entire Applications and Microservices in Julia.

### Reproducible

Reproducible environments make it possible to recreate the same Julia environment every time, across platforms, with pre-built binaries.

#### Open source

Julia is an open source project with over 1,000 contributors. It is made available under the MIT license. The source code is available on GitHub.





### **CUDA** programming in Julia

The CUDA.jl package is the main entrypoint for programming NVIDIA GPUs in Julia. The package makes it possible to do so at various abstraction levels, from easy-to-use arrays down to hand-written kernels using low-level CUDA APIs.

### interactivo

```
Julia
julia> import Pkg; Pkg.add("CUDA")
julia> using CUDA
julia> CUDA.versioninfo()
```

```
module load julia-....

Julia myprog.jl

nvprof myprog.jl

qsub jobGPU
```

## Mapeo logístico

$$x_{n+1} = rx_n(1-x_n), \quad 0 \le r \le 4$$

In a fascinating and influential review article, Robert May (1976) emphasized that even simple nonlinear maps could have very complicated dynamics. The article ends memorably with "an evangelical plea for the introduction of these difference equations into elementary mathematics courses, so that students' intuition may be enriched by seeing the wild things that simple nonlinear equations can do."

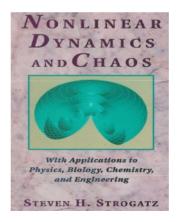
Robert May, Baron May of Oxford



Científico

Nacimiento: 8 de enero de 1936, Sídney, Australia Fallecimiento: 28 de abril de 2020, Oxford, Reino

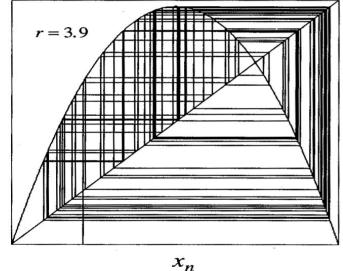
Unido



Converge a un punto fijo... ¿qué otra cosa puede pasar en general?

## Mapeo logístico

$$x_{n+1} = rx_n(1-x_n), \ 0 \le r \le 4$$

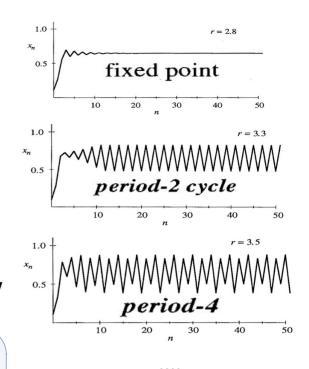


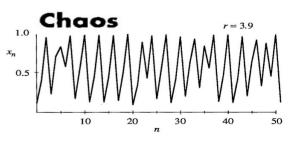
 $x_{n+1}$ 

 $r_3 = 3.54409...$  8  $r_4 = 3.5644...$  16  $r_5 = 3.568759...$  32  $\vdots$   $\vdots$   $r_{\infty} = 3.569946..$   $\infty$ 

 $r_2 = 3.449...$ 

(period 2 is born)





### Chaos and Periodic Windows

Manos a la obra

Liapunov Exponent 
$$\lambda \approx \frac{1}{n} \ln \left| \prod_{i=0}^{n-1} f'(x_i) \right|$$



ICNPG julia logistic.ipynb