ICNPG 2023

Thrust





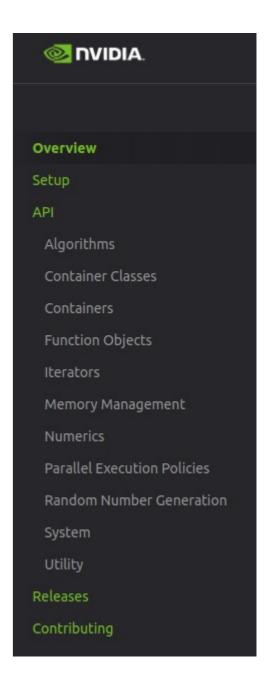


¿ Que es Thrust?

Thrust: The C++ Parallel Algorithms Library



https://nvidia.github.io/thrust/



Portabilidad: device backends

Mismo programa, distintos ejecutables

Serial en CPU: solo copiar los headers de thrust y usar el compilador de siempre

```
g++ -fopenmp -lgomp device_backends.cpp -DTHRUST_DEVICE_SYSTEM=THRUST_DEVICE_SYSTEM_CPP -o cpp.out -I...
```

Paralelo en CPU: solo copiar los headers de thrust y usar el compilador de siempre

```
g++ -fopenmp -lgomp device_backends.cpp -DTHRUST_DEVICE_SYSTEM=THRUST_DEVICE_SYSTEM_OMP -o omp.out -I...
```

Paralelo en GPU: usar nvcc y gpu de nvidia...

```
nvcc device_backends.cu -DTHRUST_DEVICE_SYSTEM=THRUST_DEVICE_SYSTEM_CUDA -o cuda.out
```

Experimentar con device_backends.cu

/share/apps/icnpg/clases/Clases_Thrust/clase_B/device_backends

```
thrust::device_vector<float> dx=hx;
cronosin.tic();
float init=dx[0];
float suma = thrust::reduce(dx.begin(),dx.end(),init,thrust::minimum<float>());
```

Execution policies: drop in replacement

```
#include <thrust/system/omp/execution_policy.h>
#include <thrust/sort.h>
#include <cstdlib>
#include <algorithm>
#include <iostream>
#include <vector>
int main(void)
  // serially generate 1M random numbers
  std::vector<int> vec(1 << 20);
  std::generate(vec.begin(), vec.end(), rand);
  // sort data in parallel with OpenMP by specifying its execution policy
  thrust::sort(thrust::omp::par, vec.begin(), vec.end());
  // report the largest number
  std::cout << "Largest number is " << vec.back() << std::endl;
```

System-specific vector

```
#include <thrust/system/omp/vector.h>
#include <thrust/sort.h>
#include <cstdlib>
#include <algorithm>
#include <iostream>
int main(void)
  // serially generate 1M random numbers
  thrust::omp::vector<int> vec(1 << 20);
  std::generate(vec.begin(), vec.end(), rand);
  // sort data in parallel with OpenMP
  thrust::sort(vec.begin(), vec.end());
  // no need to transfer data back to host
  // report the largest number
  std::cout << "Largest number is " << vec.back() << std::endl;
  return 0;
```

Programación híbrida: system-specific vector

/share/apps/icnpg/clases/Clases_Thrust/clase_B/omp_vs_cuda/ompvscuda.cu

Un solo Programa

Paralelizacion para GPU

Paralelizacion para CPU multicore

Simultáneamente...

C++ Standard Library

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11-14 minutes

In the <u>C++</u> programming language, the **C++ Standard Library** is a collection of <u>classes</u> and <u>functions</u>, which are written in the <u>core</u> <u>language</u> and part of the C++ <u>ISO</u> Standard itself.[1]

Un subconjunto de la std

Un laboratorio...

Boost (C++ libraries)

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5-6 minutes

Boost



Boost is a set of <u>libraries</u> for the <u>C++</u> programming language that provides support for tasks and structures such as <u>linear algebra</u>, <u>pseudorandom number generation</u>, multithreading, <u>image</u> <u>processing</u>, <u>regular expressions</u>, and <u>unit testing</u>. It contains 164 individual libraries (as of version 1.76).[3]

Standard Template Library

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17-22 minutes

For other uses, see STL.

The **Standard Template Library** (**STL**) is a <u>software library</u> for the <u>C++</u> programming language that influenced many parts of the <u>C++</u> <u>Standard Library</u>. It provides four components called <u>algorithms</u>, containers, functions, and iterators.[1]

Standard Template Library más abstracción sin menos eficiencia

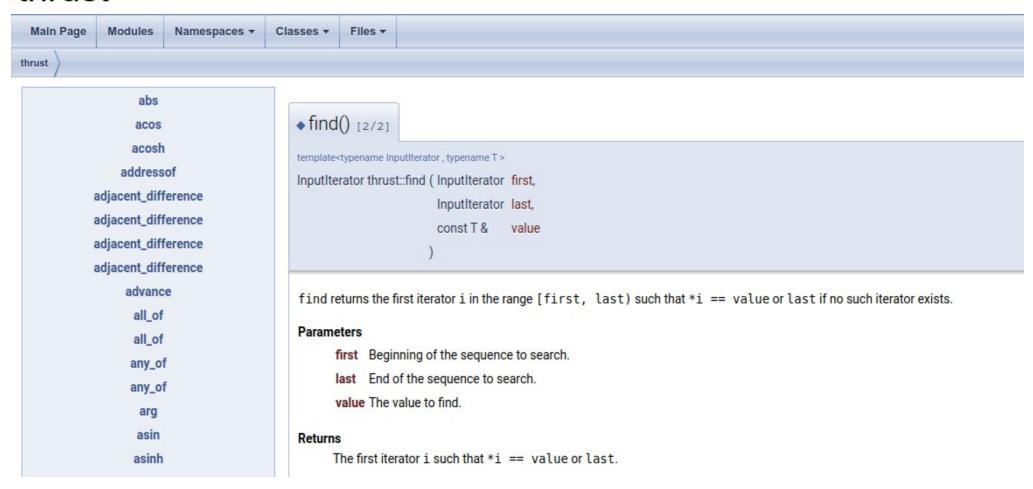
From Wikipedia, the free encyclopedia

- The Standard Template Library (STL) **is a software library for the C++** programming language that influenced many parts of the C++ Standard Library. It provides four components called *algorithms, containers, functional, and iterators*.
- The STL provides a set of common classes for C++, such as containers and associative arrays, that can be used with *any built-in type and with any user-defined type* that supports some elementary operations (such as copying and assignment).
- STL *algorithms are independent of containers*, which significantly reduces the complexity of the library.
- The STL achieves its results through the use of templates. This approach provides compiletime polymorphism that is often more efficient than traditional run-time polymorphism.
 Modern C++ compilers are tuned to minimize abstraction penalty arising from heavy use of the STL.
- The STL was created as the first library of generic algorithms and data structures for C++, with four ideas in mind: generic programming, abstractness without loss of efficiency, the Von Neumann computation model, and value semantics...

Thrust API (inspirada en STL)

http://thrust.github.io/doc/modules.html

thrust



Thrust API "Snippets"

http://thrust.github.io/doc/modules.html

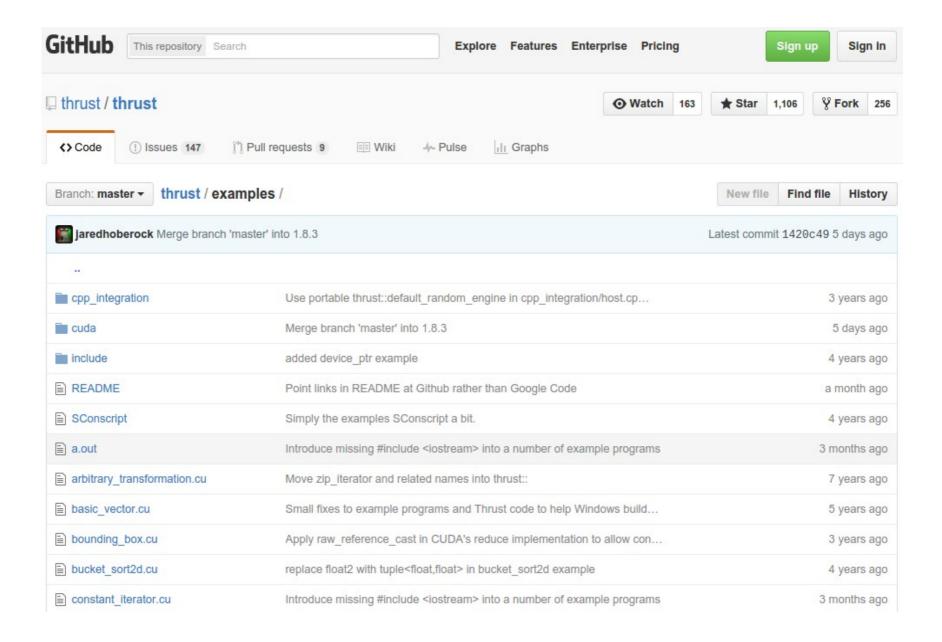
```
#include <thrust/find.h>
#include <thrust/device_vector.h>
...
thrust::device_vector<int> input(4);
input[0] = 0;
input[1] = 5;
input[2] = 3;
input[3] = 7;
thrust::device_vector<int>::iterator iter;
iter = thrust::find(input.begin(), input.end(), 3); // returns input.first() + 2
iter = thrust::find(input.begin(), input.end(), 5); // returns input.first() + 1
iter = thrust::find(input.begin(), input.end(), 9); // returns input.end()
```

See also

find_if

mismatch

https://github.com/thrust/thrust/tree/master/examples



Componentes de Thrust

• Containers:

- Para manejar el contenido en memoria del host y del device.
- Simplifican las copias D → H, H → D.
- Mucho mas que un array, son colecciones *genéricas* de objetos.

• Iteradores:

- Actúan como punteros...
- Pero mantienen info del espacio de memoria.

• Algoritmos:

- Se aplican a rangos de containers, delimitados por iteradores.
- Son *genéricos*, flexibles, y portables.

Operadores predefinidos

General types and operators

```
#include <thrust/reduce.h>
// declare storage
device vector<int> i_vec = ...
device vector<float> f vec = ...
// sum of integers (equivalent calls)
reduce(i_vec.begin(), i_vec.end());
reduce(i vec.begin(), i vec.end(), 0, plus<int>());
// sum of floats (equivalent calls)
reduce(f_vec.begin(), f_vec.end());
reduce(f_vec.begin(), f_vec.end(), 0.0f, plus<float>());
// maximum of integers
reduce(i_vec.begin(), i_vec.end(), 0, maximum<int>());
```

Operadores propios

General types and operators

```
struct negate float2
 {
               device
      host
    float2 operator()(float2 a)
        return make float2(-a.x, -a.y);
 };
 // declare storage
 device vector<float2> input = ...
 device vector<float2> output = ...
 // create functor
 negate_float2 func;
 // negate vectors
 transform(input.begin(), input.end(), output.begin(), func);
© 2008 NVIDIA Corporation
```

Comparadores propios

General types and operators

```
compare x component of two float2 structures
 struct compare float2
      host device
    bool operator()(float2 a, float2 b)
        return a.x < b.x;
 // declare storage
device vector<float2> vec = ...
 // create comparison functor
compare float2 comp;
 // sort elements by x component
sort(vec.begin(), vec.end(), comp);
© 2008 NVIDIA Corporation
```

```
Ejemplo:
struct Persona{
      ...datos de una persona;
};
Persona p;
p.inicializacion();
device vector Gente(40000000);
sort(Gente.begin(),Gente.end(),
comparador de edad);
Gente[0] → datos de
la persona mas joven;
Gente[40000000-1] → datos del
Mas viejo:
```

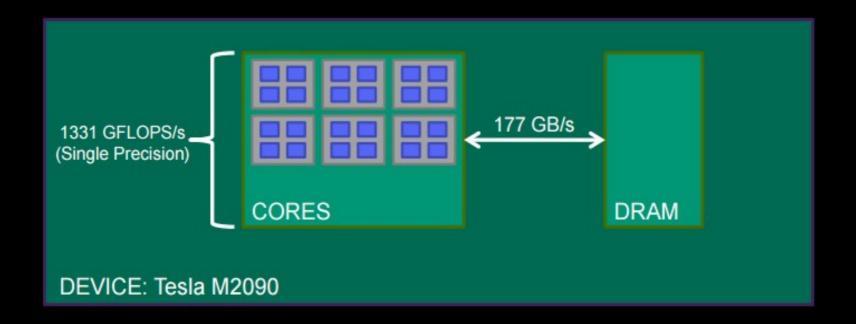
Predicados propios

Operators with State

```
compare x component of two float2 structures
struct is greater than
   int threshold;
   is greater than(int t) { threshold = t; }
     host device
   bool operator()(int x) { return x > threshold; }
};
device vector<int> vec = ...
// create predicate functor (returns true for x > 10)
is greater than pred(10);
// count number of values > 10
int result = count if(vec.begin(), vec.end(), pred);
```

```
Ejemplo:
struct Persona{
      ...datos de una persona;
Persona p:
p.inicializacion();
device vector Gente(40000000);
Int M =
count if(Gente.begin(),Gente.end(),
vive en bariloche);
M ==
numero de personas que viven en Bche
```

Simplified View of a GPU



Best Practices

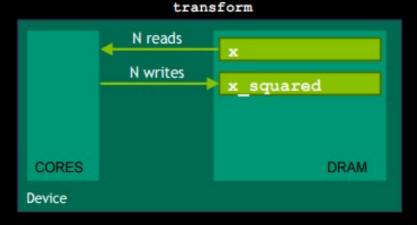
- In general
 - Many applications are limited by memory bandwidth
- Best Practices
 - Fusion
 - Combined related operations together
 - Structure of Arrays
 - Ensure memory coalescing
 - Implicit sequences
 - Eliminate memory accesses and storage

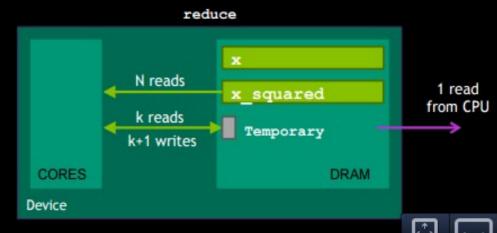
Fusion: Sum of squares $\sum x_i^2$

```
struct square { __device__ _host__ float operator() (float xi) { return xi*xi; } };
float sum_of_squares(const thrust::device_vector<float> &x)
{
    size_t N = x.size();
    thrust::device_vector<float> x_squared(N); // Temporary storage: N elements.

    // Compute x^2: N reads + N writes.
    thrust::transform(x.begin(), x.end(), x_squared.begin(), square());

    // Compute the sum of x^2s: N + k reads + k+1 writes (k is a small constant).
    return thrust::reduce(x_squared.begin(), x_squared.end());
}
```





Fusion

Device

Combined related operations together

```
float fused sum of squares(const thrust::device vector<float> &x)
  // Compute the x^2s and their sum: N + k reads + k+1 writes (k is a small constant).
  return thrust::reduce(
    thrust::make transform iterator(x.begin(), square()),
    thrust::make transform iterator(x.end(),
                                                square()));
              transform reduce
                                                      We save:

    N temporary storage (x_squared)

               N reads

    N writes (to x_squared)

    N reads (from x squared)

               k reads
                          Temporary
              k+1 writes
                                              1 read
                                             from CPU
                                   DRAM
    CORES
```

thrust

Main Page	Modules	Namespaces	Classes	Files		
Fancy Iterators						
Iterators						

Classes

```
thrust::constant_iterator< Value, Incrementable, System >
       thrust::counting iterator< Incrementable, System, Traversal, Difference >
class
       thrust::discard_iterator< System >
class
       thrust::iterator_adaptor< Derived, Base, Value, System, Traversal, Reference, Difference >
class
       thrust::iterator_facade< Derived, Value, System, Traversal, Reference, Difference >
class
       thrust::iterator core access
       thrust::permutation iterator< ElementIterator, IndexIterator >
       thrust::reverse iterator< BidirectionalIterator >
class
       thrust::transform_iterator< AdaptableUnaryFunction, Iterator, Reference, Value >
      thrust::zip iterator< IteratorTuple >
class
```

- constant_iterator
- counting_iterator
- transform iterator
- permutation_iterator
- zip_iterator

transform_iterator

- Representa un puntero a un rango de valores después de una transformación por una función.
- Util para crear un rango lleno con el resultado de aplicar una operacion sobre otro rango sin guardarlo explícitamente en memoria ni ejecutando la transformación...
- Facilita la "fusión de kernels", pateando la ejecución de la transformación hasta que el valor transformado es necesitado, minimizando asi memoria y ancho de banda.

```
int main(void)
  thrust::device vector<float> v(4);
  v[0] = 1.0f; v[1] = 4.0f; v[2] = 9.0f; v[3] = 16.0f;
  typedef thrust::device vector<float>::iterator FloatIterator;
  thrust::transform iterator<square root, FloatIterator> iter(v.begin(), square root());
  *iter: // returns 1.0f
  iter[0]; // returns 1.0f;
  iter[1]; // returns 2.0f;
  iter[2]; // returns 3.0f;
  iter[3]; // returns 4.0f;
  // iter[4] is an out-of-bounds error
```

Implicit Sequences

- Often we need ranges following a sequential pattern
 - Constant ranges

```
[1, 1, 1, 1, ...]
```

Incrementing ranges

```
[0, 1, 2, 3, ...]
```

Implicit ranges require no storage

```
- thrust::constant_iterator
```

- thrust::counting iterator

```
x = \{0,1,2,...\} \rightarrow f(x) = \{f(0),f(1),...\}
```

```
int main(int arch, char **argv)
  srand(13); int N=10000000;
  thrust::device vector<float> x(N); // abscisa
   thrust::device vector<float> y(N); // coordenada
   thrust::sequence(x.begin(),x.end()); // x=\{0,1,2,3,...N-1\}
   float a=1.0; mifuncion op(a);
  thrust::transform(x.begin(),x.end(), y.begin(),op);
   std::cout << y[2] << " vs " << sin(a*2.0) << std::endl;
```

counting_iterator

- Representa un puntero a un rando de valores constantes.
- Util para crear una secuencia constante sin usar memoria.
- Si uso economiza memoria y ancho de banda.

```
int main(int arch, char **argv)
    int N=10000000;
    thrust::device vector<float> y(N); // coordenada
    float a=1.0; mifuncion op(a);
    thrust::transform(thrust::make counting iterator(0),
                      thrust::make counting iterator(N),
                      y.begin(),op);
```

counting_iterator

- Representa un puntero a un rando de valores constantes.
- Util para crear una secuencia constante sin usar memoria.
- Si uso economiza memoria y ancho de banda.

```
int main(int arch, char **argv)
{
    int N=10000000;
    thrust::device_vector<float> y(N); // coordenada
    float a=1.0; mifuncion op(a);

    thrust::counting_iterator<int> first(0);
    thrust::counting_iterator<int> last(N);
    thrust::transform(first,last,y.begin(),op);
}
```

constant_iterator

- Representa un puntero a un rango de valores constantes.
- Útil para crear una secuencia constante sin usar memoria.
- Su uso economiza memoria y ancho de banda.

```
include <thrust/iterator/constant_iterator.h>
...
// create iterators
thrust::constant_iterator<int> first(10);
thrust::constant_iterator<int> last = first + 3;
first[0] // returns 10
first[1] // returns 10
first[100] // returns 10
// sum of [first, last)
thrust::reduce(first, last); // returns 30 (i.e. 3 * 10)
```

constant_iterator

- Representa un puntero a un rango de valores constantes.
- Útil para crear una secuencia constante sin usar memoria.
- Su uso economiza memoria y ancho de banda.

```
int main(void)
    thrust::device vector<int> data(4);
    data[0] = 3; data[1] = 7;
    data[2] = 2; data[3] = 5;
    // add 10 to all values in data
    thrust::transform(data.begin(), data.end(),thrust::constant iterator<int>(10),
                      data.begin(), thrust::plus<int>());
    // data is now [13, 17, 12, 15]
    // print result
    thrust::copy(data.begin(), data.end(),
             std::ostream iterator<int>(std::cout, "\n"));
    return 0;
```

Permutaciones

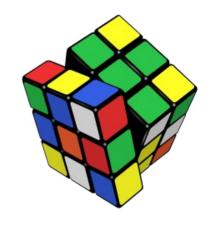
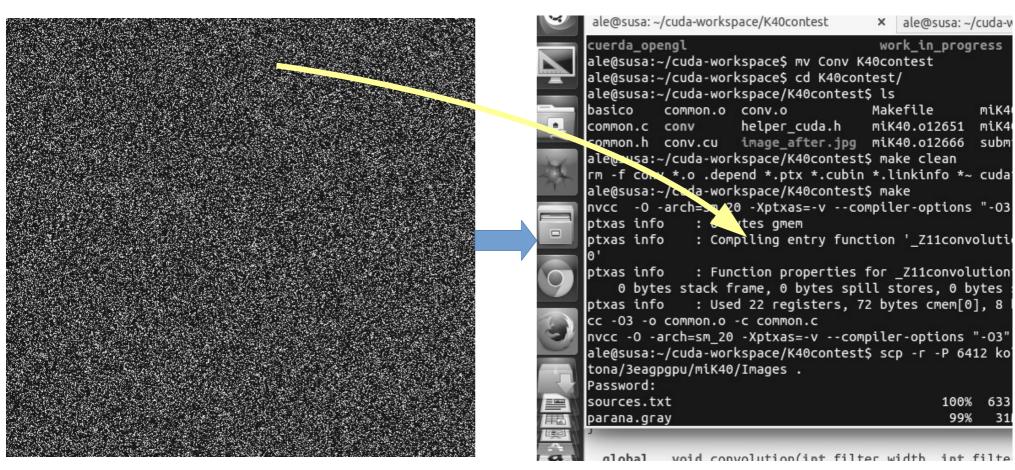


Imagen "encriptada"

Imagen "desencriptada"



Los pixels están mezclados usando un mapeo dado...

permutation_iterator

- Representa un puntero a una vision reordenada de un rango.
- Util para fusionar las operaciones de "scatter" y "gather" con otros algoritmos.

```
int main(void)
   // gather locations
   thrust::device vector<int> map(4);
   map[0] = 3; map[1] = 1; map[2] = 0; map[3] = 5;
   // array to gather from
   thrust::device vector<int> source(6);
   source[0] = 10;
   source[1] = 20;
   source[2] = 30;
                                             sum = source[map[0]] +
   source[3] = 40;
                                                   source[map[1]]+ ...
   source[4] = 50;
   source[5] = 60;
   // fuse gather with reduction:
   // sum = source[map[0]] + source[map[1]] + ...
   int sum = thrust::reduce(thrust::make permutation iterator(source.begin(), map.begin()),
                            thrust::make permutation iterator(source.begin(), map.end()));
    return 0;
```

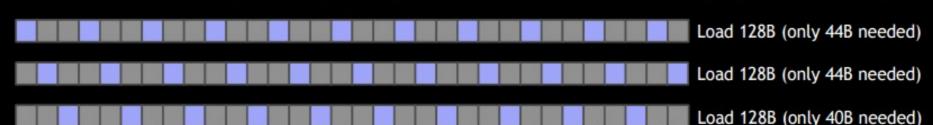
Structure of Arrays

```
struct Float3 { float x, y, z; };
```

Array of 32 Float3: Float3[32] (32 Float3 = 32x12B = 384B)



■ Load the 32 x: 3 x 128B. Same for y and z \Rightarrow 3x3x128B = 1.125KB (only 384B needed)¹



¹GPUs based on Fermi and Kepler architectures have L1-cache to help here.

Structure of Arrays

Group xs, ys and zs

```
struct StructOfFloats
{
   thrust::device_vector<float> x;
   thrust::device_vector<float> y;
   thrust::device_vector<float> z;
};
```

■ Load \mathbf{x} : 1 x 128B. Same for \mathbf{y} and $\mathbf{z} \Rightarrow 3x128B = 384B$ (all needed)

Structure of Arrays

Example: Scale a sequence of Float3

```
struct scale
  typedef thrust::tuple<float, float, float> Float3;
 float s;
  scale(float s) : s(s) {}
   host device Float3 operator() (Float3 t)
   float x = thrust::get<0>( t );
   float y = thrust::get<1>( t );
   float z = thrust::get<2>( t );
   return thrust::make tuple( s*x, s*y, s*z );
};
thrust::transform(
  thrust::make zip iterator(thrust::make tuple(x.begin(), y.begin(), z.begin())),
  thrust::make zip iterator(thrust::make tuple(x.end(), y.end(), z.end())),
  thrust::make zip iterator(thrust::make tuple(x.begin(), y.begin(), z.begin())),
  scale( 2.0f ));
```

Hands On

/share/apps/icnpg/clases/Clases_Thrust/clase_B/SoAvsAoS

Array de estructuras (AoS)

```
thrust::device_vector<MyStruct> structures(N);
thrust::sort(structures.begin(), structures.end());
```

Necesito comparador custom

```
struct MyStruct
{
  int key;
  float value;

  __host____device__
  bool operator<(const MyStruct other) const
  {
    return key < other.key;
  }
};</pre>
```

VS

Estructuras de arrays (SoA)

```
thrust::device_vector<int> keys(N);
thrust::device_vector<float> values(N);
thrust::sort_by_key(keys.begin(), keys.end(), values.begin());
```

Comparador default de int

Ejemplo de Kernel fusion

$$\langle x
angle = \sum_i x_i/N$$

$$\langle (x-\langle x \rangle)^2 \rangle = \sum_i (x_i - \langle x \rangle)^2 / N$$

```
thrust::transform_reduce
(
    d_vec.begin(), d_vec.end(),
    [=] __device__ (double x)
    {
        return thrust::make_tuple(x,x*x);
    },
    thrust::make_tuple(0.,0.),
    [=] __device__ (auto b, auto a){
        return
        thrust::make_tuple(
            thrust::get<0>(a)+thrust::get<0>(b),
            thrust::get<1>(a)+thrust::get<1>(b)
        );
    }
);
```

- Calculo la media y la varianza lanzando dos kernel reduce
- ¿Las puedo calcular en uno solo kernel reduce?
- Entra d_vec, sale la media y la varianza
- La tupla me permite agrupar variables distintas
- Defino transformacion sobre la tupla (identidad o elevar al cuadrado)
- Defino operacion de reduccion sobre la tupla (suma de sus respectivos elementos)

Ejercicio

$$S = rac{\sum_{i=0}^{n}(x_i + y_i)}{\sqrt{\sum_{i=0}^{n}(x_i + y_i)^2}}$$

Aplicación: Modelo de Epidemias

Tasa de contagio

$$\frac{dS}{dt} = -\beta SI,$$

$$\frac{dI}{dt} = \beta SI - \gamma I,$$

$$\frac{dR}{dt} = \gamma I.$$

Método de Euler

$$S(t + \Delta t) = S(t) + \Delta t[-\beta I(t)S(t)]$$

$$I(t + \Delta t) = I(t) + \Delta t [\beta I(t)S(t) - \gamma I(t)]$$

$$R(t + \Delta t) = R(t) + \Delta t[\gamma I(t)]$$

Suceptible, Infectado, Recuperado