

Los puntos fijos no son simplemente x_j^u sino que también $-x_j^u$

no solamente están estos equilibrios, sino que también hay mínimos que son estados mezcla

Definimos una métrica sobre configuraciones de actividad neuronal

Supongamos que tenemos dos configuraciones x_j, y_j

OVERLAP

$$m = \frac{1}{N} \sum_{j=1}^N x_j y_j$$

1 cuando las conf. son iguales
-1 cuando $x_j = -y_j$

Si las configuraciones son estadísticamente ind., m tendrá una distribución gaussiana con $\mu = 0$ y $\sigma = \frac{1}{\sqrt{N}}$

ejemplos

estados x_j^1, x_j^2, x_j^3

↓ construye un estado mezcla $x_j^n = \text{sg}(x_j^1 + x_j^2 + x_j^3)$

$$\begin{aligned} m^{1,n} &= \frac{1}{N} \sum_{j=1}^N x_j^1 \text{sg}(x_j^1 + x_j^2 + x_j^3) \\ &= \frac{1}{N} \sum_{j=1}^N \text{sg}(x_j^1 (x_j^1 + x_j^2 + x_j^3)) \\ &= \frac{1}{N} \sum_{j=1}^N \text{sg}\left(1 + \underbrace{x_j^1 x_j^2}_{\pm 1} + \underbrace{x_j^1 x_j^3}_{\pm 1}\right) \end{aligned}$$

$$= \frac{1}{N} \left(\frac{3}{4} - \frac{1}{4} \right) \cdot N$$

$$= \frac{1}{2}$$

1 + 1 + 1 = 3	$\left\{ \begin{array}{l} \text{c/u} \\ \text{con} \\ \text{prob} \\ 1/4 \end{array} \right.$
1 - 1 + 1 = 1	
1 + 1 - 1 = 1	
1 - 1 - 1 = -1	

$$S_j(0) = \text{sg}(x_j^1 + x_j^2 + x_j^3)$$

$$S_i(1) = \text{sg}\left(\sum_{j=1}^N w_{ij} S_j(0)\right)$$

$$= \text{sg}\left(\sum_{j=1}^N \left(\frac{1}{N} \sum_{u=1}^P x_i^u x_j^u\right) \text{sg}(x_j^1 + x_j^2 + x_j^3)\right)$$

$$= \text{sg}\left(\sum_{u=1,2,3} \sum_j \frac{x_i^u x_j^u}{N} \text{sg}(x_j^1 + x_j^2 + x_j^3) + \sum_{u>3} \sum_j \frac{x_i^u x_j^u}{N} \text{sg}(x_j^1 + x_j^2 + x_j^3)\right)$$

$$= \text{sg}\left(\sum_{u=1,2,3} x_i^u \underbrace{m^{un}}_{1/2} + \sum_{u>3} x_i^u \underbrace{m^{un}}_{\mathcal{N}(0, \sigma=1/\sqrt{N})}\right)$$

$$\Rightarrow S_i(1) = \text{sg}\left(\frac{x_i^1 + x_i^2 + x_i^3}{2} + 2R\right)$$

$$R = \mathcal{N}(0, \sigma = \sqrt{\frac{P-3}{N}})$$

Los estados mezcla son más interesantes

DINÁMICA ESTOCÁSTICA

$$h_i(\tau) = \sum_{j=1}^N w_{ij} s_j(\tau)$$

$s_i(\tau+1)$ depende probabilísticamente de $h_i(\tau)$

$$P(s_i(\tau+1)=1) = \frac{e^{\beta h_i(\tau)}}{e^{\beta h_i(\tau)} + e^{-\beta h_i(\tau)}}$$

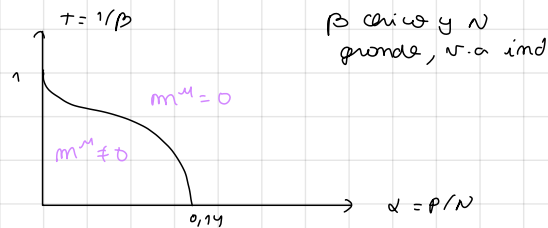
$$P(s_i(\tau+1)=-1) = \frac{e^{-\beta h_i(\tau)}}{e^{\beta h_i(\tau)} + e^{-\beta h_i(\tau)}}$$

$\beta \rightarrow 0$ límite estocástico ($P(s_i=1) = P(s_i=-1) = 1/2$)
 $\beta \rightarrow \infty$: $\begin{cases} s_i(\tau+1)=1 & h_i(\tau) > 0 \\ s_i(\tau+1)=-1 & h_i(\tau) < 0 \end{cases}$
 límite determinístico.

envelop entre el mínimo y la conf. del sist a tiempo τ

$$m^M = \frac{1}{N} \sum_{j=1}^N \underbrace{\langle s_i(\tau) \rangle}_{\text{valor medio sobre la dinámica}} x_j^M$$

Vamos a obtener:



Aproximación de campo medio

Aproximación en modelos con n.a estocástica. Hay una serie de problemas donde esta es exacta.

Consideremos la simplificación donde $w_{ij} = w \quad \forall i, j$

$$\begin{aligned} \text{En ese caso: } h_i(\tau) &= \frac{1}{N} \sum_{j=1}^N w s_j(\tau) \\ &= \frac{w}{N} \sum_{j=1}^N s_j(\tau) \end{aligned}$$

cada neurona ve un mismo campo
 $h_i(\tau) \mapsto h(\tau)$

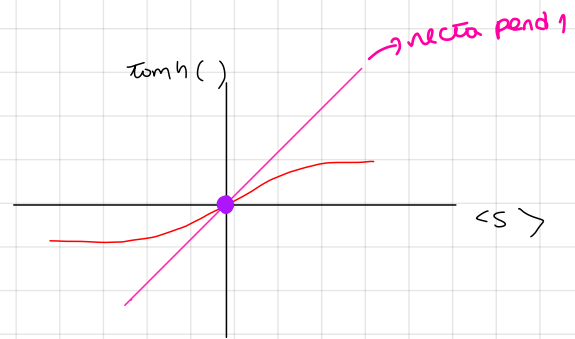
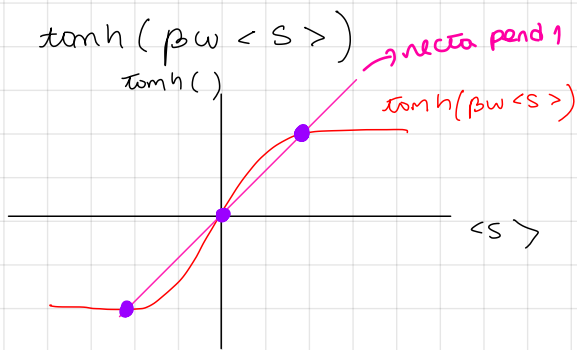
$$P(s(\tau+1)=1) = \frac{e^{\beta h}}{e^{\beta h} + e^{-\beta h}} = 1 - P(s(\tau+1)=-1)$$

$$\begin{aligned} \langle s(\tau+1) \rangle &= 1 \cdot P(s(\tau+1)=1) - 1 \cdot P(s(\tau+1)=-1) \\ &= \tanh(\beta h(\tau)) \end{aligned}$$

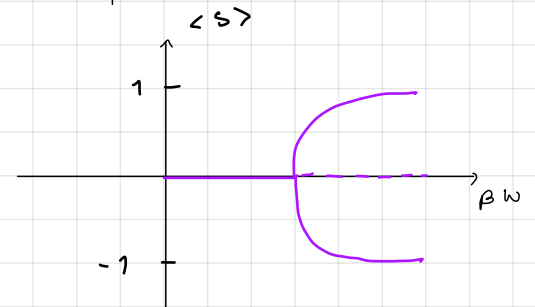
$$\text{aproximación } h(\tau) \mapsto \langle h(\tau) \rangle = w \langle s(\tau) \rangle$$

$$\text{en el eq } \langle s_i(\tau) \rangle = \langle s_i(\tau+1) \rangle$$

$$\Rightarrow \langle s(\tau) \rangle = \tanh(\beta w \langle s(\tau) \rangle) \rightarrow \text{se encuentran con el gráfico (alejo)}$$



intersecciones en función de βw



Modelo de Hopfield

$$\langle S_i(t+1) \rangle = \tanh(\beta h_i(t))$$

(compuesto medio)

$$h_i(t) = \sum_{j=1}^N w_{ij} S_j(t)$$

$$\langle S_i(t+1) \rangle = \tanh(\beta \langle h_i(t) \rangle)$$

$$\langle h_i(t) \rangle = \sum_{j=1}^N w_{ij} \langle S_j(t) \rangle$$

$w_{ij} = \frac{1}{N} \sum_{\mu=1}^N x_i^{\mu} x_j^{\mu}$

Supongamos que estamos en el equilibrio

$$\langle S_i \rangle = \tanh\left(\frac{\beta}{N} \sum_{j=1}^N x_i^{\mu} x_j^{\mu} \langle S_j \rangle\right)$$

dependencia de los x_i^{μ}

$$\Rightarrow \sum_i \frac{x_i^{\mu}}{N} \langle S_i \rangle = \sum_i x_i^{\mu} \tanh\left(\frac{\beta}{N} \sum_{j=1}^N x_i^{\mu} x_j^{\mu} \langle S_j \rangle\right)$$

$$(\pm 1) \tanh(x) = \tanh(\pm x)$$

$$\Rightarrow m^{\mu} = \frac{1}{N} \sum_{i=1}^N \tanh\left(\frac{\beta}{N} \sum_{j=1}^N x_i^{\mu} x_j^{\mu} m^{\mu} \langle S_j \rangle\right)$$

Supongamos que el estado inicial es cercano a uno de los estados

$$\text{ANZATZ} \quad m^1 \sim O(1) \quad m^{\mu} = O\left(\frac{1}{\sqrt{N}}\right) \quad \mu > 1$$

$$m^{\mu} = \frac{1}{N} \sum_i x_i^{\mu} \tanh\left(\frac{\beta}{N} \left(x_i^1 m^1 + \sum_{\mu > 1} x_i^{\mu} m^{\mu}\right)\right)$$

$$= \frac{1}{N} \sum_i x_i^{\mu} \tanh\left(\beta \left[\underbrace{x_i^1 m^1}_{O(1)} + \underbrace{x_i^{\mu} m^{\mu}}_{O\left(\frac{1}{\sqrt{N}}\right)} + \underbrace{\sum_{\mu \neq \mu} x_i^{\mu} m^{\mu}}_{O\left(\frac{1}{\sqrt{N}}\right)}\right]\right)$$

pequeño grande

expresión en términos de términos grandes

$$m^{\nu} = \frac{1}{N} \sum_{i=1}^N x_i^{\nu} \left[\tanh \left(\beta \left[x_i^1 m^1 + \sum_{u \neq 1, \nu} x_i^u m^u \right] \right) \right] + \left[1 - \tanh \left(\beta \left(x_i^1 m^1 + \sum_{u \neq 1, \nu} x_i^u m^u \right) \right) x_i^{\nu} m^{\nu} \right]$$

$$\stackrel{(*)}{=} \frac{1}{N} \sum_{i=1}^N x_i^{\nu} x_i^1 \tanh \left(\beta \left[m^1 + \sum_{u \neq 1, \nu} \underbrace{x_i^1 x_i^u}_{\pm m^u} m^u \right] \right) + \frac{1}{N} \sum_{i=1}^N \left[1 - \tanh^2 \left(\beta \left[m^1 + \sum_{u \neq 1, \nu} \underbrace{x_i^1 x_i^u}_{\pm m^u} m^u \right] \right) \right] m^{\nu} \beta$$

distribución normal con
 $\mu = 0$ (TCL)
 $\sigma = \alpha R$

$$\text{con } R = \frac{1}{\alpha} \sum_{u \neq 1, \nu} m^u{}^2$$

Para N grande $\xrightarrow{\text{aproximamos}}$

$$\int_{-\infty}^{\infty} \frac{dz}{\sqrt{2\pi}} e^{-z^2/2} \left[1 - \tanh^2 \left[\beta (m^1 + \sqrt{\alpha R} z) \right] \right] m^{\nu} \beta$$

media es μ
varianza 1

$$q = \int_{-\infty}^{\infty} \frac{dz}{\sqrt{2\pi}} \tanh^2 \left[\beta (m^1 + \sqrt{\alpha R} z) \right] e^{-z^2/2}$$

$$f(x_i) : x_i \sim P(x)$$

$$\frac{1}{N} \sum f(x_i) = \int dx P(x) f(x)$$

reemplazamos
el prom por

$$\Rightarrow m^{\nu} = m^{\nu} \beta - m^{\nu} \beta q = m^{\nu} \beta (1 - q)$$

$$\Leftrightarrow m^{\nu} \left[1 - \beta (1 - q) \right] \underset{\text{de (*)}}{=} \frac{1}{N} \sum x_i^{\nu} x_i^1 \tanh \left(\beta \left[m^1 + \sum_{u \neq 1, \nu} x_i^u m^u \right] \right)$$

$$\Rightarrow m^{\nu} = \frac{\frac{1}{N} \sum x_i^{\nu} x_i^1 \tanh \left(\beta \left[m^1 + \sum_{u \neq 1, \nu} x_i^u m^u \right] \right)}{1 - \beta (1 - q)}$$

$$\boxed{R = \frac{q}{[1 - \beta (1 - q)]^2}}$$

$$m^1 = \frac{1}{N} \sum \tanh \left(\beta \left[m^1 + \sum_{u \neq 1} x_i^u x_i^1 m^u \right] \right)$$

$$m^1 = \int_{-\infty}^{\infty} \frac{dz}{\sqrt{2\pi}} e^{-z^2/2} \tanh \left[\beta (m^1 + \sqrt{\alpha R} z) \right]$$

$$q = \int_{-\infty}^{\infty} \frac{dz}{\sqrt{2\pi}} e^{-z^2/2} \tanh^2 \left[\beta (m^1 + \sqrt{\alpha R} z) \right]$$

