



# Analytical Geometry and Linear Algebra I, Lab 4

Inverse Matrix  
Change of basis

1. Смену базиса давать через вывод формулы: вектор - фреймлесс, а координаты вектора - нет. Поэтому можно вот выразить ручку по разному. Все на основе линейных комбинаций.

Есть 2 твои формулы - бро  $E' = EA$  и  $Ex = E'x'$ . Разновидность бро  $Ex = Eb + E'x'$ , где  $E = [e_1 \ e_2 \ e_3]$ ,  $E = [e'_1 \ e'_2 \ e'_3]$

2. Забить на слайды и объяснять на маркерах, ручках и доске про смену базиса

## Questions from the class



*No questions for today*

# Inverse Matrix

*Why do we need it?*



Say we want to find matrix  $X$ , and we know matrix  $A$  and  $B$ :

$$XA = B$$

It would be nice to divide both sides by  $A$  (to get  $X=B/A$ ), but remember **we can't divide**.

But what if we multiply both sides by  $A^{-1}$  ?

$$XAA^{-1} = BA^{-1}$$

And we know that  $AA^{-1} = I$ , so:

$$XI = BA^{-1}$$

We can remove  $I$  (for the same reason we can remove "1" from  $1x = ab$  for numbers):

$$X = BA^{-1}$$

And we have our answer (assuming we can calculate  $A^{-1}$ )

# Inverse Matrix

## *Properties*

1.  $\det(A^{-1}) = \frac{1}{\det(A)}$
2.  $(AB)^{-1} = A^{-1}B^{-1}$
3.  $(A^{-1})^T = (A^T)^{-1}$
4.  $(kA)^{-1} = \frac{A^{-1}}{k}$
5.  $(A^{-1})^{-1} = A$

# Inverse Matrix

*How to find*

There are 2 ways:

1. Classical approach
2. Gauss-Jordan



# Inverse Matrix: Classical Approach

## Theory

$$A_{2 \times 2}^{-1} = \frac{C^T}{\det(A)}, \text{ where } C \text{ is a matrix of cofactors.}$$

$$C_{2 \times 2} = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix}, \text{ where } C_{ij} = (-1)^{i+j} M_{ij} \text{ — (we met it on previous lab (lab 3))}$$

# Inverse Matrix: Classical Approach

## Case Study

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}. \text{ Let's find } A^{-1}.$$

1. Find a determinant (shouldn't be equal to 0, otherwise  $\rightarrow$  stop calculations).

$$\det(A) = 1 \cdot 4 - 2 \cdot 3 = -2$$

2. Find Cofactor matrix

$$C_{11} = (-1)^{1+1}M_{11} = (-1)^2|4| = 4$$

$$C_{12} = (-1)^{1+2}M_{12} = (-1)^3|3| = -3$$

$$C_{21} = (-1)^{2+1}M_{21} = (-1)^3|2| = -2$$

$$C_{22} = (-1)^{2+2}M_{22} = (-1)^4|1| = 1$$

$$C = \begin{bmatrix} 4 & -3 \\ -2 & 1 \end{bmatrix}$$

3. Transpose cofactor matrix

$$C^T = \begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix}$$

4. Substitute it to the main formula

$$A^{-1} = \frac{\begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix}}{-2} = \begin{bmatrix} -2 & 1 \\ 1.5 & -0.5 \end{bmatrix}$$



# Inverse Matrix: Gauss-Jordan

*Core Idea & Case study ( $2 \times 2$ )*

The



## └ Inverse Matrix: Gauss-Jordan

Не забудь, нужно подумать как оформить эту штуку честь по чести. А то вроде ее и понимают, но времени не много. Как это оформить нормально.

## Reference material



- Inverse Matrix (OnlineMschool)
- Gauss-Jordan (Wiki)
- Matrix Rank (OnlineMschool)

# Deserve "A" grade!

– Oleg Bulichev

✉ o.bulichev@innopolis.ru

📍 @Lupasic

🏢 Room 105 (Underground robotics lab)