

Analytical Geometry and Linear Algebra I, Lab 10

Conic sections (2nd order curve equation): Hyperbola
From general to canonical form
Tangent line to a curve

Questions for today

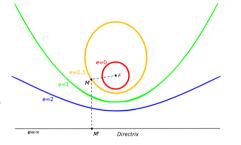
- How can I work with general form of 2nd order curve equation?
- How it relates with cone?
- What forms of equation do we have?

Some definitions, which can be helpful

Eccentricity, Directrix

Eccentricity is a measure of how much a conic section deviates from being circular.

It is a constant ration between distance from focal to point on the curve and from the point on the curve to **directrix**.



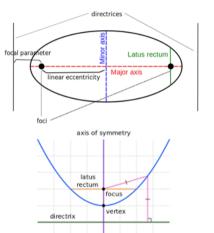


Linear eccentricity, Latus Rectrum, Focal parameter

The **linear eccentricity** is the distance between the center and the focus (or one of the two foci).

The **latus rectum** is the chord parallel to the directrix and passing through the focus (or one of the two foci).

The **focal parameter** is the distance from the focus (or one of the two foci) to the directrix.



Parabola

Forms:

- Canonical $(x x_{\text{shift}})^2 = 2p(y y_{\text{shift}})$
- General $Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$, where either A = 0 or C = 0, not both, if B = 0

• Parametric
$$\begin{cases} x = \sqrt{2}pt \\ y = pt^2 \end{cases}$$



Parabola $y = x^2$, $p = \frac{1}{2}$

Properties:

- Vertex $\begin{pmatrix} O \\ O \end{pmatrix} + \begin{pmatrix} x_{\text{shift}} \\ y_{\text{shift}} \end{pmatrix}$
- Center Not defined
- Eccentricity e = 1
- Linear Eccentricity Not defined

• Foci
$$F = \begin{pmatrix} 0 \\ \frac{p}{2} \end{pmatrix} + \begin{pmatrix} x_{\text{shift}} \\ y_{\text{shift}} \end{pmatrix}$$

- Latus Rectum (length of chord)
 |2p|
- Focal parameter p
- Discriminant $\mathfrak{D} = B^2 4AC = 0$
- Directrix eq. $y = -\frac{p}{2} + y_{\text{shift}}$

• Tangent eq. $x(x_{tan} - x_{shift}) = p(y - y_{tan}) + x_{tan}(x_{tan} - x_{shift})$

•
$$r = |\overline{FM}| = \sqrt{(x - \frac{p}{2})^2 + y^2}$$

 \(\Delta MFD \) is isosceles, where MD tangent to M

Ellipse

Forms:

• Canonical
$$\frac{(x-x_{\text{shift}})^2}{a^2} + \frac{(y-y_{\text{shift}})^2}{b^2} = 1$$

• General
$$Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$$
, where $AC > 0$, if $B = 0$

• Parametric
$$\begin{cases} x = a \cos(\alpha) \\ y = b \sin(\alpha) \end{cases}$$

Properties:

• Vert
$$\begin{pmatrix} \pm a \\ 0 \end{pmatrix} \& \begin{pmatrix} 0 \\ \pm b \end{pmatrix} + \begin{pmatrix} x_{\text{shift}} \\ y_{\text{shift}} \end{pmatrix}$$

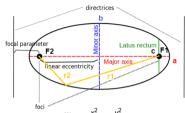
- **Center (**0; 0**)** + (x_{shift} ; y_{shift})
- Eccentricity $0 \le e < 1$, $e = \sqrt{1 - \frac{b^2}{a^2}}$
- Linear Eccentricity $c = \sqrt{a^2 b^2}$

• Foci

$$F = \begin{pmatrix} \pm (c = e \ a) \\ 0 \end{pmatrix} + \begin{pmatrix} x_{\text{shift}} \\ y_{\text{shift}} \end{pmatrix}$$

• Latus Rectum (length of chord)
$$\frac{2b^2}{a}$$

- Focal parameter $\frac{b^2}{\sqrt{a^2-b^2}}$
- Discriminant $\mathfrak{D} = B^2 4AC < 0$



Ellipse
$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

- Directrix eq. $x = \pm \frac{a}{e} + x_{\text{shift}}$
- Tangent eq. (w/o shift) $\frac{x_{tangent}x}{a^2} + \frac{y_{tangent}y}{b^2} =$
- $r_1 + r_2 = 2a$
- $r_{1,2} = |\overline{F_{1,2}M}| = \sqrt{(x \pm c)^2 + y^2}$
- $\frac{r_1}{d_1} = e$

Hyperbola

Forms:

• Canonical
$$\frac{(x-x_{\text{shift}})^2}{a^2} - \frac{(y-y_{\text{shift}})^2}{b^2} = 1$$

• **General**
$$Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$$
, where $AC < 0$

• Parametric
$$\begin{cases} x = \frac{a}{\cos(\alpha)} \\ y = b \tan(\alpha) \end{cases}$$

Properties:

• Vertex
$$\begin{pmatrix} \pm a \\ 0 \end{pmatrix} + \begin{pmatrix} x_{\text{shift}} \\ y_{\text{shift}} \end{pmatrix}$$

• Center (0; 0) +
$$(x_{\text{shift}}; y_{\text{shift}})$$

• Eccentricity
$$e > 1$$
, $e = \sqrt{1 + \frac{b^2}{a^2}}$

• Linear Eccentricity
$$c = \sqrt{a^2 + b^2}$$

Foci

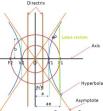
$$F = \begin{pmatrix} \pm c = \pm (e \ a) \\ 0 \end{pmatrix} + \begin{pmatrix} x_{\text{shift}} \\ y_{\text{shift}} \end{pmatrix}$$

• Latus Rectum
$$\frac{2b^2}{a}$$

• Focal parameter
$$\frac{b^2}{\sqrt{a^2+b^2}}$$

• Discriminant
$$\mathfrak{D} = B^2 - 4AC > 0$$

• Directrix eq.
$$x = \pm \frac{a}{e} + x_{\text{shift}}$$



$$Hyperbola \frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$$

• Asymptots eq.

$$y = \pm \frac{b}{a}(x + x_{\text{shift}}) + y_{\text{shift}}$$

Tangent eq. (w/o shift)
$$\frac{x_{tangent}x}{a^2} - \frac{y_{tangent}y}{b^2} = 1$$

•
$$r = |\overline{F_{closest}M}| = |x e - a|$$

$$\frac{r_1}{d_1} = e$$

Task 1



Find the centre and eccentricity of the hyperbola $9x^2 - 4y^2 + 18x + 16y - 43 = 0$

Answer

$$9 (x^{2} + 2x) - 4 (y^{2} - 4y) - 43 = 0$$

$$9 (x + 1)^{2} - 9 - 4(y - 2)^{2} + 19 - 43 = 0$$

$$9 (x + 1)^{2} - 4 (y - 2)^{2} = 36$$

Hence, centre is (-1, 2), $a^2 = 4$ and $b^2 = 9$.

$$\frac{(x+1)^2}{4} - \frac{(y-2)^2}{9} = 1$$

$$b^2 = a^2 (e^2 - 1) \text{ gives } e = \frac{\sqrt{13}}{2}.$$

$$Ax^{2} + Cy^{2} + 2Dx + 2Ey + F = 0$$
 — General form.

Special case: when B = 0

Example of transformation from general to canonical form:

$$16x^{2} + 25y^{2} - 32x + 50y - 359 = 0 \Rightarrow$$

$$(16x^{2} - 32x) + (25y^{2} + 50y) - 359 = 0 \Rightarrow$$

$$16(x^{2} - 2x) + 25(y^{2} + 2y) = 359 \Rightarrow$$

$$16(x^{2} - 2x + 1) + 25(y^{2} + 2y + 1) = 350 + 16 + 25 \Rightarrow$$

$$16(x - 1)^{2} + 25(y + 1)^{2} = 400 \Rightarrow$$

$$\frac{(x - 1)^{2}}{25} + \frac{(y + 1)^{2}}{16} = 1$$

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From general to canonical form

General case: classical method

Algorithm

1. Find angle of rotation, using $(A - C) \sin(2\alpha) + B \cos(2\alpha) = 0$. If bad angle, try to do the following:

$$\cot(2\alpha) = \frac{\mathsf{A} - \mathsf{C}}{\mathsf{B}}; \cos(2\alpha) = \cos(\operatorname{arccot}(2\alpha)) = \frac{\mathsf{A} - \mathsf{C}}{\sqrt{(\mathsf{A} - \mathsf{C})^2 + \mathsf{B}^2}} \rightarrow \begin{cases} \cos(\alpha) = \frac{\sqrt{2}}{2} \sqrt{1 + \cos(2\alpha)} \\ \sin(\alpha) = \frac{\sqrt{2}}{2} \sqrt{1 - \cos(2\alpha)} \end{cases}$$

- 2. Using roration matrix, write down a transformation from $\begin{bmatrix} x \\ y \end{bmatrix} \rightarrow \begin{bmatrix} x' \\ y' \end{bmatrix}$; $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x' \cos(\alpha) y' \sin(\alpha) \\ x' \sin(\alpha) + y' \cos(\alpha) \end{bmatrix}$
- 3. Substitute it to original equation and simplify to a canonical equation with shifting (for instance, $\frac{(x' + x_{shift})^2}{2} + \frac{(y' + y_{shift})^2}{8} = 1$)
- 4. Change the variables again $\begin{bmatrix} x' \\ y' \end{bmatrix} \rightarrow \begin{bmatrix} x'' \\ y'' \end{bmatrix}$; $\begin{bmatrix} x'' \\ y'' \end{bmatrix} = \begin{bmatrix} x' + x_{shift} \\ y' + y_{shift} \end{bmatrix}$). It gives you a canonical form.
- 5. Write a system which shows $\begin{bmatrix} x'' \\ y'' \end{bmatrix} = \begin{bmatrix} f(x, y) \\ g(x, y) \end{bmatrix}$. You need to agregate (2) and (4) to (5)

From general to canonical form

Classical method: case study (1)

2 y = -2 (1) a, b, c, e, directrix eq., asymptots ?

1) Classical method

$$A = 0, B = 1, C = 0$$

$$(A - c) \sin 2x + B \cos 2x = 0 \Rightarrow \cos 2x = 0 \Rightarrow 2x = 90$$

$$\begin{cases}
\alpha = \frac{1}{\sqrt{2}} x^{1} - \frac{1}{\sqrt{2}} y^{1} = \frac{1}{\sqrt{2}} (x^{1} - y^{1}) \\
y = \frac{1}{\sqrt{2}} x^{2} + \frac{1}{\sqrt{2}} y^{3} = \frac{1}{\sqrt{2}} (x^{2} + y^{3})
\end{cases}$$

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$$xy = -2 \qquad (1) \quad \text{a. b. c. e. directrix eq., asymptots -?}$$

$$A = 0, \quad S = 1, \quad C = 0$$

$$(A = C) \text{ Ain } 2 + 4 \text{ As } \cos 2 x = 0 \Rightarrow \cos 2 x = 0 \Rightarrow 2 x = 90^{\circ}$$

$$\begin{cases} x = \frac{1}{\sqrt{2}}x^{1} - \frac{1}{\sqrt{2}}y^{1} = \frac{1}{\sqrt{2}}(x^{1} - y^{1}) \\ y = \frac{1}{\sqrt{2}}x^{1} + \frac{1}{\sqrt{2}}y^{1} = \frac{1}{\sqrt{2}}(x^{1} + y^{1}) \end{cases}$$

$$\begin{cases} x = \frac{1}{\sqrt{2}}x^{1} - \frac{1}{\sqrt{2}}y^{1} = \frac{1}{\sqrt{2}}(x^{1} - y^{1}) \\ y = \frac{1}{\sqrt{2}}x^{1} + \frac{1}{\sqrt{2}}y^{1} = \frac{1}{\sqrt{2}}(x^{1} + y^{1}) \end{cases}$$

$$\begin{cases} x = \frac{2^{1} - y^{1}}{\sqrt{2}} \\ y = \frac{1}{\sqrt{2}}x^{1} + \frac{1}{\sqrt{2}}y^{1} = \frac{1}{\sqrt{2}}(x^{1} + y^{1}) \end{cases}$$

$$\begin{cases} x = \frac{2^{1} - y^{1}}{\sqrt{2}} \\ y = \frac{2^{1} - y^{1}}{\sqrt{2}} \end{cases}$$

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$$\begin{cases} x = \frac{2^{1} - y^{$$

General case: Other way

Problem

In some cases it's quite tough to convert from general form to canonical using classical method from the class (bad numbers).

Solution

$$f = Ax^2 + Bxy + Cy^2 + Dx + Ey + F = 0$$

converts into canonical form in new variables x'' , y'' by

the equation:
$$\frac{(x'')^2}{-S/(\lambda_1^2\lambda_2)} + \frac{(y'')^2}{-S/(\lambda_1\lambda_2^2)} = 1, \text{ where}$$

- S is determinant of $\begin{pmatrix} A & B/2 & D/2 \\ B/2 & C & E/2 \\ D/2 & E/2 & F \end{pmatrix}$ matrix
- $\lambda_{1,2}$ are the eigenvalues of $\begin{pmatrix} A & B/2 \\ B/2 & C \end{pmatrix}$ matrix.

It can be found using this equation:

$$\lambda^2 - (A + C)\lambda + (AC - (B/2)^2) = 0$$

Using *canonical form*, we can find *a*, *b*, *c*, *e* for the curve, but not *coordinate dependent properties* (*like vertex*, *directrix eq.*). For this purpose, we need to find **angle** and **shift**.

Angle:
$$(A - C)\sin(2\alpha) + B\cos(2\alpha) = 0$$
; $\rightarrow \alpha = ...$

Shift (center of the curve)

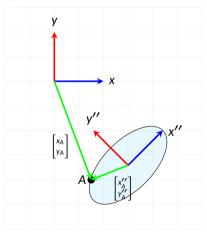
$$\begin{cases} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \\ \rightarrow 2 \text{ equations of line} \\ \rightarrow \text{ solve system } (x_c; y_c) \end{cases}$$

Using this transformation, we can find original coordinates, knowing the new one

$$\begin{bmatrix} x_A \\ y_A \\ 1 \end{bmatrix} = \begin{bmatrix} \cos(\alpha) & -\sin(\alpha) & x_c \\ \sin(\alpha) & \cos(\alpha) & y_c \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_A'' \\ y_A'' \\ 1 \end{bmatrix}$$

From general to canonical form

General case: Other way (2)





Other method: case study

$$24f = -2 \quad (1)$$
 a, b, c, e, directrix eq., asymptots -?
2) Other method
$$27f + 24f + 24f$$

Asymptotes eq. in new basis
$$x \ge \frac{1}{2} \frac{1}{\sqrt{r}}$$

Any $x \ge \frac{1}{2} \frac{1}{\sqrt{r}}$

For finding coordinate dependent data (equations like (4), (5)), we need to find angle of rotation and a shift.

For finding coordinate dependent data (equations like (4), (5)), we need to find angle of rotation and a shift.

Angle

Angle

$$Angle$$

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For finding coordinate dependent data (equations like (4), (5)), we need to find angle

Angle

$$A = \frac{1}{A - C}$$
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Partial derivative

Partial derivative

 $A = \frac{1}{A - C}$
 $A = \frac{1}{A - C}$

If younced to find just coordinates (like foci), put it here

If you need to find just coordinates (like fool), put it here'

If you need to find an equation
$$\Rightarrow \mathcal{H} \left[\begin{array}{c} x \\ y \\ y \end{array} \right] = \left[\begin{array}{c} x \\ y \\ y \end{array} \right]$$

Put it

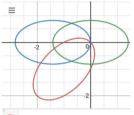
Transform
$$x^2 - xy + y^2 + x + y = 0$$
 into canonical form

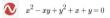
Task 2

Answer

```
x^{2}-xy+y^{2}+x+y=0
A = 1 \quad A(5 = -1) \quad C = -1
(C - 4) \sin 2x + 2 \cos \cos 2x = 0
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$$\frac{(x+\sqrt{2})^2}{2} + \frac{y^2}{\frac{2}{3}} = 1$$

$$\frac{x^2}{2} + \frac{y^2}{\frac{2}{3}} =$$

Prove that a curve given by $7x^2 + 48xy - 7y^2 - 62x - 34y + 98 = 0$ is a hyperbola. Find the eccentricity of this hyperbola, coordinates of its center and foci. Find the equations of axes, asymptotes and directrices of this hyperbola.

Answer

```
Eccentricity is \sqrt{2};

center - (1; 1);

foci -F_1(-\frac{1}{5}; \frac{13}{5}), F_2(\frac{11}{5}; \frac{-3}{5});

real axis is 4x + 3y - 7 = 0;

imaginary axis -3x - 4y + 1 = 0;

directrices are 3x - 4y - 4 = 0 and 3x - 4y + 6 = 0;

asymptotes -x + 7y = 9, 7x - y = 6.
```

Find the equation to the hyperbola that passes through (2; 3) and has for its asymptotes the lines 4x + 3y - 7 = 0 and x - 2y = 1

Task 4

Answer

The combined equation of the asymptotes is (4x + 3y - 7)(x - 2y - 1) = 0.

Hence, the equation of the hyperbola is (4x + 3y - 7)(x - 2y - 1) + k = 0.

This pass through (2,3).

$$(8+9-7)(2-6-1)+k=0$$

 $\therefore k=50$

Hence, the equation of the hyperbola is

$$(4x+3y-7)(x-2y-1)+50=0$$
(i.e.)
$$4x^2-5xy-6y^2-11x+11y+57=0$$



Find the equations of lines tangent to curve $6xy + 8y^2 - 12x - 26y + 11 = 0$ that are

- (a) parallel to line 6x + 17y 4 = 0;
- (b) perpendicular to line 41x 24y + 3 = 0;
- (c) parallel to line y = 2.

Task 5

Answer (a)

$$6xy + 8y^{2} - 12x - 26y + 171 = 0 (1)$$
Parallel to the line $6x + 17y - 9 = 0 / 2$
It means, that $kx + 6 = y$

$$5 \text{ should be the same in tangent (1) and (2)}$$

$$k \text{ in (2)} \quad k = -\frac{6}{17}$$
Parallel lines have the same "k" (slope), but different "b" - intercept
$$\frac{d(1)}{dx} = 6xy^{1} + 16yy^{2} - 12 - 26y^{1} + 6y$$

$$y'' = \frac{12 - 6y}{6x + 16y - 26} = k$$

$$\frac{12 - 6y}{6x + 16y - 26} = -\frac{6}{17} = y = 6x + 8/3$$

mm

Answer

- (a) 6x + 17y 10 = 0 and 6x + 17y 46 = 0
- (b) 24x + 41y 22 = 0 and 24x + 41y 94 = 0
- (c) no solution

Determine types of curves given by the following equations. For each of the curves, find its canonical coordinate system (i.e. indicate the coordinates of origin and new basis vectors in the initial coordinate system) and its canonical equation.

(a)
$$9x^2 - 16y^2 - 6x + 8y - 144 = 0$$
;

(b)
$$9x^2 + 4y^2 + 6x - 4y - 2 = 0$$
;

(c)
$$12x^2 - 12x - 32y - 29 = 0$$
;

(d)
$$xy + 2x + y = 0$$
;

(e)
$$5x^2 + 12xy + 10y^2 - 6x + 4y - 1 = 0$$
;

(f)
$$8x^2 + 34xy + 8y^2 + 18x - 18y - 17 = 0$$
;

(g)
$$25x^2 - 30xy + 9y^2 + 68x + 19 = 0$$
;

(h)
$$x^2 + 2xy + y^2 - 5x - 5y + 4 = 0$$
.



Answer (may contain typos, recommend to check by geogebra)

- (a) hyperbola $\frac{X^2}{16} \frac{Y^2}{9} = 1$, $O'(\frac{1}{3}; \frac{1}{4})$
- (b) ellipse $X^2 + \frac{Y^2}{4/9} = 1$, $O'(-\frac{1}{3}; \frac{1}{2})$
- (c) parabola $X^2 = \frac{8}{3}Y$, $O'(\frac{1}{2}; -1)$
- (d) hyperbola $\frac{X^2}{4} \frac{Y^2}{4} = 1$, O'(-1; -2)
- (e) ellipse $\frac{X^2}{1}4 + Y^2 = 1$, O'(3; -2)
- (f) hyperbola $\frac{X^2}{1/9} \frac{Y^2}{1/25} = 1$, O'(1; -1)
- (g) parabola $Y^2 = \frac{6}{\sqrt{34}}, O'(-\frac{11}{17}; \frac{10}{17})$
- (h) two parallel lines given by the equations x + y = 4 and x + y = 1 in initial coordinates.

Reference material

- Conic sections (slides, rus)
- How to find centre of conic (video, eng)
- Find the equation of major and minor axis of the given conic
- How to go from general to canonical form (mathprofi, rus)

