

# Analytical Geometry and Linear Algebra II, Lab 10

Symmetric matrices

Positive definite matrices and minima



- 1 A symmetric matrix S has n real eigenvalues  $\lambda_i$  and n orthonormal eigenvectors  $q_1, \dots, q_n$ .
- **2** Every real symmetric S can be diagonalized:  $S = Q\Lambda Q^{-1} = Q\Lambda Q^{T}$
- $\bf 3$  The number of positive eigenvalues of S equals the number of positive pivots.

# **Symmetric Matrices (2)**

Symmetric matrices S have orthogonal eigenvector matrices Q. Look at this again:

**Symmetry** 
$$S = X\Lambda X^{-1}$$
 becomes  $S = Q\Lambda Q^{T}$  with  $Q^{T}Q = I$ .

This says that every 2 by 2 symmetric matrix is (rotation)(stretch)(rotate back)

$$S = Q\Lambda Q^{\mathrm{T}} = \begin{bmatrix} \mathbf{q}_1 & \mathbf{q}_2 \end{bmatrix} \begin{bmatrix} \lambda_1 & \\ & \lambda_2 \end{bmatrix} \begin{bmatrix} \mathbf{q}_1^{\mathrm{T}} \\ \mathbf{q}_2^{\mathrm{T}} \end{bmatrix}. \tag{5}$$

Columns  $q_1$  and  $q_2$  multiply rows  $\lambda_1 q_1^T$  and  $\lambda_2 q_2^T$  to produce  $S = \lambda_1 q_1 q_1^T + \lambda_2 q_2 q_2^T$ .

Write A as S + N, symmetric matrix S plus skew-symmetric matrix N:

$$A = egin{bmatrix} 1 & 2 & 4 \\ 4 & 3 & 0 \\ 8 & 6 & 5 \end{bmatrix} = S + N \qquad \quad (S^{\mathrm{T}} = S \ \ \mathrm{and} \ \ N^{\mathrm{T}} = -N).$$

For any square matrix,  $S = \frac{1}{2}(A + A^{T})$  and N = \_\_\_\_ add up to A.

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#### **Answer**

$$A = \begin{bmatrix} 1 & 3 & 6 \\ 3 & 3 & 3 \\ 6 & 3 & 5 \end{bmatrix} + \begin{bmatrix} 0 & -1 & -2 \\ 1 & 0 & -3 \\ 2 & 3 & 0 \end{bmatrix} = \frac{1}{2}(A + A^{T}) + \frac{1}{2}(A - A^{T})$$
= symmetric + skew-symmetric.

Find an orthogonal matrix Q that diagonalizes  $S = \begin{bmatrix} -2 & 6 \\ 6 & 7 \end{bmatrix}$ . What is  $\Lambda$ ?

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#### **Answer**

$$\lambda=10 \text{ and } -5 \text{ in } \Lambda=\begin{bmatrix}10&0\\0&-5\end{bmatrix}, \ x=\begin{bmatrix}1\\2\end{bmatrix} \text{ and } \begin{bmatrix}2\\-1\end{bmatrix} \text{ have to be normalized to}$$
 unit vectors in  $Q=\frac{1}{\sqrt{5}}\begin{bmatrix}1&2\\2&-1\end{bmatrix}$ .

*True* (with reason) *or false* (with example).

- (a) A matrix with real eigenvalues and n real eigenvectors is symmetric.
- (b) A matrix with real eigenvalues and n orthonormal eigenvectors is symmetric.
- (c) The inverse of an invertible symmetric matrix is symmetric.
- (d) The eigenvector matrix Q of a symmetric matrix is symmetric.

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#### Answer

(a) False. 
$$A=\begin{bmatrix}1&2\\0&1\end{bmatrix}$$
 (b) True from  $A^{\mathrm{T}}=Q\Lambda Q^{\mathrm{T}}=A$  (c) True from  $S^{-1}=Q\Lambda^{-1}Q^{\mathrm{T}}$ 

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c) True from 
$$S^{-1} = Q\Lambda^{-1}Q^{\mathrm{T}}$$

#### **Positive Definite Matrices**

This section concentrates on *symmetric matrices that have positive eigenvalues*. If symmetry makes a matrix important, this extra property  $(all \ \lambda > 0)$  makes it truly special. When we say special, we don't mean rare. Symmetric matrices with positive eigenvalues are at the center of all kinds of applications. They are called *positive definite*.

Applications from ML

- Cholesky decomposition  $A = LDL^H$  (A special case of A = LU)
- Least squares computation reduction
- Support Vector Machine (SVM), kernel Positive-definite kernel
- Representer Theorem

Five tests

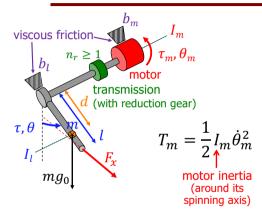
**Positive definite matrices** are the best. How to test S for  $\lambda_i > 0$ ?

- Test 1 Compute the **eigenvalues** of S: All eigenvalues positive
- Test 2 The **energy**  $x^{\mathrm{T}}Sx$  is positive for every vector  $x \neq 0$
- Test 3 The **pivots** in elimination on S are all positive
- Test 4 The upper left **determinants** of S are all positive
- Test 5  $S = A^T A$  for some matrix A with independent columns

## Dynamics of an actuated pendulum



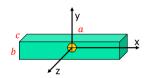
a first example



### Examples of body inertia matrices

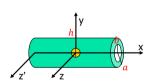


homogeneous bodies of mass  $m_i$ , with axes of symmetry



parallelepiped with sides

a (length/height), b and c (base)
$$I_{c} = \begin{pmatrix} I_{xx} & & \\ & I_{yy} & \\ & & I_{zz} \end{pmatrix} = \begin{pmatrix} \frac{1}{12}m(b^{2} + c^{2}) & & \\ & & \frac{1}{12}m(a^{2} + c^{2}) & \\ & & & \frac{1}{12}m(a^{2} + b^{2}) \end{pmatrix}$$

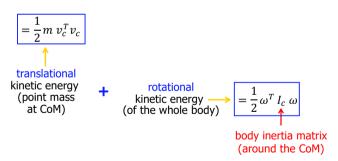


empty cylinder with length  $h_{\star}$ and external/internal radius a and b

$$I_{c} = \begin{pmatrix} \frac{1}{2}m(a^{2} + b^{2}) & & \\ & \frac{1}{12}m(3(a^{2} + b^{2}) + h^{2}) & \\ & & I_{zz} = I_{yy} \end{pmatrix}$$



#### Kinetic energy of a rigid body (cont)



Robotics 2

Example

Test S for positive definiteness:

$$S = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$

Solution: Test 1, 3, 4

The pivots of S are 2 and  $\frac{3}{2}$  and  $\frac{4}{3}$ , all positive. Its upper left determinants are 2 and 3 and 4, all positive. The eigenvalues of S are  $2-\sqrt{2}$  and 2 and  $2+\sqrt{2}$ , all positive. That completes tests 1, 2, and 3.

Solution: Test 5

 $A_2$  comes from  $S=LDL^{\rm T}$  (the symmetric version of S=LU). Elimination gives the pivots  $2,\frac{3}{2},\frac{4}{3}$  in D and the multipliers  $-\frac{1}{2},0,-\frac{2}{3}$  in L. **Just put**  $A_2=L\sqrt{D}$ .

Eigenvalues give the symmetric choice  $A_3 = Q\sqrt{\Lambda}Q^T$ . This is also successful with  $A_3^T A_3 = Q\Lambda Q^T = S$ . All tests show that the -1, 2, -1 matrix S is positive definite.

### **Positive Definite Matrices**

Solution: Test 2

$$\mathbf{x}^{\mathrm{T}} S \mathbf{x} = 2x_1^2 - 2x_1 x_2 + 2x_2^2 - 2x_2 x_3 + 2x_3^2$$
$$||A_2 \mathbf{x}||^2 = 2\left(x_1 - \frac{1}{2}x_2\right)^2 + \frac{3}{2}\left(x_2 - \frac{2}{3}x_3\right)^2 + \frac{4}{3}x_3^2$$

$$||A_3\boldsymbol{x}||^2 = \lambda_1(\boldsymbol{q}_1^{\mathrm{T}}\boldsymbol{x})^2 + \lambda_2(\boldsymbol{q}_2^{\mathrm{T}}\boldsymbol{x})^2 + \lambda_3(\boldsymbol{q}_3^{\mathrm{T}}\boldsymbol{x})^2$$

Using 
$$S = LDL^{\mathrm{T}}$$

Using 
$$S=Q\Lambda Q^{\mathrm{T}}$$



What is the function  $f = ax^2 + 2bxy + cy^2$  for each of these matrices? Complete the square to write each f as a sum of one or two squares  $f = d_1()^2 + d_2()^2$ .

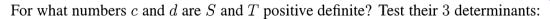
$$S_1 = \begin{bmatrix} 1 & 2 \\ 2 & 9 \end{bmatrix}$$
  $S_2 = \begin{bmatrix} 1 & 3 \\ 3 & 9 \end{bmatrix}$   $f = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$ 

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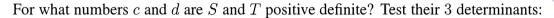
$$S_1 = \begin{bmatrix} 1 & 2 \\ 2 & 9 \end{bmatrix}$$
  $S_2 = \begin{bmatrix} 1 & 3 \\ 3 & 9 \end{bmatrix}$   $f = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$ 

Answer

$$f(x,y) = x^2 + 4xy + 9y^2 = (x+2y)^2 + 5y^2; \ x^2 + 6xy + 9y^2 = (x+3y)^2.$$



$$S = \begin{bmatrix} c & 1 & 1 \\ 1 & c & 1 \\ 1 & 1 & c \end{bmatrix} \quad \text{and} \quad T = \begin{bmatrix} 1 & 2 & 3 \\ 2 & d & 4 \\ 3 & 4 & 5 \end{bmatrix}.$$



$$S = \begin{bmatrix} c & 1 & 1 \\ 1 & c & 1 \\ 1 & 1 & c \end{bmatrix} \qquad \text{and} \qquad T = \begin{bmatrix} 1 & 2 & 3 \\ 2 & d & 4 \\ 3 & 4 & 5 \end{bmatrix}.$$

#### **Answer**

S is positive definite for c > 1; determinants  $c, c^2 - 1$ , and  $(c - 1)^2(c + 2) > 0$ .

T is *never* positive definite (determinants d-4 and -4d+12 are never both positive).

A positive definite matrix cannot have a zero (or even worse, a negative number) on its main diagonal. Show that this matrix fails to have  $x^T S x > 0$ :

$$\begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} 4 & 1 & 1 \\ 1 & 0 & 2 \\ 1 & 2 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$
 is not positive when  $(x_1, x_2, x_3) = ( , , )$ .

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 is not positive when  $(x_1, x_2, x_3) = ( , , )$ .

#### **Answer**

 $x^T S x$  is zero when  $(x_1, x_2, x_3) = (0, 1, 0)$  because of the zero on the diagonal. Actually  $x^T S x$  goes negative for x = (1, -10, 0) because the second pivot is negative.

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Without multiplying 
$$S = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 5 \end{bmatrix} \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$
, find

(a) the determinant of S

- (b) the eigenvalues of S
- (c) the eigenvectors of S
- (d) a reason why S is symmetric positive definite.

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- (c) the eigenvectors of S
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#### **Answer**

det 
$$S = (1)(10)(1) = 10$$
;  $\lambda = 2$  and 5;  $\boldsymbol{x}_1 = (\cos \theta, \sin \theta), \, \boldsymbol{x}_2 = (-\sin \theta, \cos \theta)$ ; the

 $\lambda$ 's are positive. So S is positive definite.

## **Positive Definite Matrices**

Important Application: Test for a Minimum

Does F(x,y) have a minimum if  $\partial F/\partial x=0$  and  $\partial F/\partial y=0$  at the point (x,y)=(0,0)?

For f(x), the test for a minimum comes from calculus: df/dx is zero and  $d^2f/dx^2 > 0$ . Two variables in F(x,y) produce a symmetric matrix S. It contains four second derivatives. Positive  $d^2f/dx^2$  changes to positive definite S:

Second derivatives 
$$S = \left[ \begin{array}{ccc} \partial^2 F/\partial x^2 & \partial^2 F/\partial x \partial y \\ \partial^2 F/\partial y \partial x & \partial^2 F/\partial y^2 \end{array} \right]$$



F(x,y) has a minimum if  $\partial F/\partial x = \partial F/\partial y = 0$  and S is positive definite.

Reason: S reveals the all-important terms  $ax^2 + 2bxy + cy^2$  near (x, y) = (0, 0). The second derivatives of F are 2a, 2b, 2b, 2c. For F(x, y, z) the matrix S will be 3 by 3.

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For  $F_1(x, y) = x^4/4 + x^2 + x^2y + y^2$  and  $F_2(x, y) = x^3 + xy - x$ , find the second-derivative matrices  $H_1$  and  $H_2$ :

$$H = \begin{pmatrix} \frac{\partial^2 F}{\partial x^2} & \frac{\partial^2 F}{\partial x \partial y} \\ \frac{\partial^2 F}{\partial y \partial x} & \frac{\partial^2 F}{\partial y^2} \end{pmatrix}.$$

 $H_1$  is positive-definite so  $F_1$  is concave up (= convex). Find the minimum point of  $F_1$  and the saddle point of  $F_2$  (look only where the first derivatives are zero).

#### **Answer: Subtask 1**

For  $F_1(x, y)$ , we first solve for the stationary point

$$\frac{\partial F_1}{\partial x} = x^3 + 2x + 2xy = 0 \ (1) \quad , \frac{\partial F_1}{\partial y} = x^2 + 2y = 0 \ (2)$$

From (2), we have  $y = -x^2/2$ . Plug this into (1), we have 2x = 0 and hence the only critical point is x = y = 0. At this point,

$$H_1 = \begin{pmatrix} \frac{\partial^2 F}{\partial x^2} & \frac{\partial^2 F}{\partial x \partial y} \\ \frac{\partial^2 F}{\partial y \partial x} & \frac{\partial^2 F}{\partial y^2} \end{pmatrix} = \begin{pmatrix} 3x^3 + 2 + 2y & 2x \\ 2x & 2 \end{pmatrix} = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}.$$

It is positive definite and hence (0,0) is a minimal point of  $F_1(x,y)$ .

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#### Answer: Subtask 2

For  $F_2(x,y)$ , we first solve for the stationary point

$$\frac{\partial F_2}{\partial x} = 3x^2 + y - 1 = 0, \frac{\partial F_2}{\partial y} = x = 0$$

This implies that y = 1. At this point (0, 1),

$$H_2 = \begin{pmatrix} \frac{\partial^2 F}{\partial x^2} & \frac{\partial^2 F}{\partial x \partial y} \\ \frac{\partial^2 F}{\partial y \partial x} & \frac{\partial^2 F}{\partial y^2} \end{pmatrix} = \begin{pmatrix} 6x & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$$

The eigenvalues of  $H_2$  at (0,1) is the solution to det  $(H_2 - \lambda I) = \lambda^2 - 1$ , which are  $\lambda_1 = 1$  and  $\lambda_2 = -1$ . They are with opposite signs and hence (0,1) is a saddle point of  $F_2(x,y)$ .

#### Reference material

- Lecture 28, Positive Definite Matrices and Minima
- 5. Positive Definite and Semidefinite Matrices
- "Introduction to Linear Algebra", pdf pages 349–374
   6.4 Symmetric, 6.5 Positive Definite matrices
- "Linear Algebra and Applications", pdf pages 355–376
   Positive Definite Matrices 6.1, 6.2

