



Pseudoinverse

- $J^\#$ always **exists**, and is the **unique** matrix satisfying

$$\begin{aligned} J J^\# J &= J & J^\# J J^\# &= J^\# \\ (J J^\#)^T &= J J^\# & (J^\# J)^T &= J^\# J \end{aligned}$$

- if J is **full (row) rank**, $J^\# = J^T (J J^T)^{-1}$; else, it is computed numerically using the SVD (Singular Value Decomposition) of J (**pinv** of Matlab)



Computation of pseudoinverses

- **show** that the pseudoinverse of J is equal to

$$J = U\Sigma V^T \quad \Rightarrow \quad J^\# = V\Sigma^\# U^T \quad \Sigma^\# = \begin{pmatrix} \frac{1}{\sigma_1} & & & \\ & \ddots & & \\ & & \frac{1}{\sigma_\rho} & \\ & & & 0_{(M-\rho) \times (M-\rho)} \\ \hline & & & & 0_{(N-M) \times M} \end{pmatrix}$$

for any rank ρ of J