

# Analytical Geometry and Linear Algebra II, Lab 2

Gaussian elimination recap
A=LU, A=LDV, PA=LU factorization



Algorithm

$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix}$$

Algorithm

$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

Training task

$$\begin{cases} 2x_1 + 3x_2 - x_3 = 9 \\ x_1 - 2x_2 + x_3 = 3 \\ x_1 + 2x_3 = 2 \end{cases}$$

Training task

$$\begin{cases} 2x_1 + 3x_2 - x_3 = 9 \\ x_1 - 2x_2 + x_3 = 3 \\ x_1 + 2x_3 = 2 \end{cases} \text{ Ans: } \begin{cases} x_1 = 4 \\ x_2 = 0 \\ x_3 = -1 \end{cases}$$

Example of A=LU

$$\begin{bmatrix}
2 & 1 & 1 \\
4 & -6 & 0 \\
-2 & 7 & 2
\end{bmatrix}$$

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$$\begin{bmatrix}
2 & 1 & 1 \\
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\end{bmatrix}
\rightarrow
\begin{bmatrix}
1 & 0 & 0 \\
2 & 1 & 0 \\
-1 & -1 & 1
\end{bmatrix}
\begin{bmatrix}
2 & 1 & 1 \\
0 & -8 & -2 \\
0 & 0 & 1
\end{bmatrix}$$

Example of A=LDV

$$\begin{bmatrix}
2 & 1 & 1 \\
4 & -6 & 0 \\
-2 & 7 & 2
\end{bmatrix}
\rightarrow
\begin{bmatrix}
1 & 0 & 0 \\
2 & 1 & 0 \\
-1 & -1 & 1
\end{bmatrix}
\begin{bmatrix}
2 & 0 & 0 \\
0 & -8 & 0 \\
0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
1 & 1/2 & 1/2 \\
0 & 1 & 1/4 \\
0 & 0 & 1
\end{bmatrix}$$

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How to convert LU to LDV

Split *U* into 
$$\begin{bmatrix} d_1 & & & & \\ & d_2 & & & \\ & & \ddots & & \\ & & & d_n \end{bmatrix} \begin{bmatrix} 1 & u_{12}/d_1 & u_{13}/d_1 & \cdot \\ & 1 & u_{23}/d_2 & \cdot \\ & & \ddots & \vdots \\ & & & 1 \end{bmatrix}$$

Formal Idea

$$A = LU = \begin{pmatrix} lower triangular L \\ 1's on the diagonal \end{pmatrix} \begin{pmatrix} upper triangluar U \\ pivots on the diagonal \end{pmatrix}$$

**Requirements**: No row exchanges as Gaussian elimination reduces square A to U

$$A = LDU = \begin{pmatrix} lower triangular L \\ 1's on the diagonal \end{pmatrix} \begin{pmatrix} pivot matrix \\ D is diagonal \end{pmatrix} \begin{pmatrix} upper triangluar U \\ 1's on the diagonal \end{pmatrix}$$

**Requirements**: No row exchanges. The pivots in *D* are divided out to leave 1's on the diagonal of *U*. If *A* is symmetric, then *U* is  $L^T$  and  $A = LDL^T$ .

Application: Theory

$$Ax = b \rightarrow$$

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$$Ax = b \to \underbrace{LU}_A x = b$$

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$$Ax = b \to \underbrace{LU}_{A} x = b \to L \underbrace{c}_{Ux} = b$$

Application: Theory

$$Ax = b \rightarrow \underbrace{LU}_{A} x = b \rightarrow L \underbrace{c}_{Ux} = b \rightarrow Ux = c \rightarrow Ans: x$$

There are two steps:

- 1. Factor (from A find its factors L and U)
- 2. **Solve** (from *L* and *U* and *b* find the solution *x*)

#### Description

Try to solve such systems using:

- Gauss-Jordan elimination
- IU factorization

Compare time consumption

$$AX = B$$
, where  $A = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 3 & 3 \\ -3 & 10 & 2 \end{bmatrix}$ ,  $B = \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix}$ 

$$B_{j+1} = B_j + X_j$$
, for  $j = 1, 2$ , where  $B_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ 

Application: Case Study

#### Description

Try to solve such systems using:

- Gauss-Jordan elimination
- LU factorization

#### Compare time consumption

$$AX = B$$
, where  $A = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 3 & 3 \\ -3 & 10 & 2 \end{bmatrix}$ ,  $B = \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix}$ 

$$B_{j+1} = B_j + X_j$$
, for  $j = 1, 2$ , where  $B_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ 

$$A = \underbrace{\begin{bmatrix} \frac{-1}{3} & \frac{16}{29} & 1\\ \frac{-2}{3} & 0 & 0\\ 1 & 0 & 0 \end{bmatrix}}_{\begin{bmatrix} -3 & 10 & 2\\ 0 & \frac{29}{3} & \frac{13}{3}\\ 0 & 0 & \frac{-21}{2} \end{bmatrix}}_{= \begin{bmatrix} 1 & 0 & 0\\ 2 & 1 & 0\\ -3 & -16 & 1 \end{bmatrix}}_{= \begin{bmatrix} 1 & 2 & 1\\ 0 & -1 & 1\\ 0 & 0 & 21 \end{bmatrix}}, B_2 = \begin{bmatrix} \frac{5}{7}\\ \frac{3}{7}\\ \frac{-4}{7} \end{bmatrix}, B_3 = \begin{bmatrix} \frac{73}{49}\\ \frac{109}{147}\\ \frac{-185}{147} \end{bmatrix}$$

Which number c leads to zero in the second pivot position? A row exchange is needed and A = LU will not be possible. Which c produces zero in the third pivot position? Then a row exchange can't help and elimination fails:

$$A = \begin{bmatrix} 1 & c & 0 \\ 2 & 4 & 1 \\ 3 & 5 & 1 \end{bmatrix}.$$

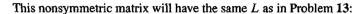
Which number c leads to zero in the second pivot position? A row exchange is needed and A = LU will not be possible. Which c produces zero in the third pivot position? Then a row exchange can't help and elimination fails:

$$A = \begin{bmatrix} 1 & c & 0 \\ 2 & 4 & 1 \\ 3 & 5 & 1 \end{bmatrix}.$$

#### **Answer**

c=2 leads to zero in the second pivot position: exchange rows and not singular.

c=1 leads to zero in the third pivot position. In this case the matrix is *singular*.



Find L and U for

$$A = \begin{bmatrix} a & r & r & r \\ a & b & s & s \\ a & b & c & t \\ a & b & c & d \end{bmatrix}.$$

Find the four conditions on a, b, c, d, r, s, t to get A = LU with four pivots.

This nonsymmetric matrix will have the same L as in Problem 13:

Find 
$$L$$
 and  $U$  for

$$A = \begin{bmatrix} a & r & r & r \\ a & b & s & s \\ a & b & c & t \\ a & b & c & d \end{bmatrix}.$$

Find the four conditions on a, b, c, d, r, s, t to get A = LU with four pivots.

#### **Answer**

If A and B have nonzeros in the positions marked by x, which zeros (marked by 0) stay zero in their factors L and U?

$$A = \begin{bmatrix} x & x & x & x \\ x & x & x & 0 \\ 0 & x & x & x \\ 0 & 0 & x & x \end{bmatrix} \qquad B = \begin{bmatrix} x & x & x & 0 \\ x & x & 0 & x \\ x & 0 & x & x \\ 0 & x & x & x \end{bmatrix}.$$

$$B = \begin{bmatrix} x & x & x & 0 \\ x & x & 0 & x \\ x & 0 & x & x \\ 0 & x & x & x \end{bmatrix}.$$

If A and B have nonzeros in the positions marked by x, which zeros (marked by 0) stay zero in their factors L and U?

$$A = \begin{bmatrix} x & x & x & x \\ x & x & x & 0 \\ 0 & x & x & x \\ 0 & 0 & x & x \end{bmatrix} \qquad B = \begin{bmatrix} x & x & x & 0 \\ x & x & 0 & x \\ x & 0 & x & x \\ 0 & x & x & x \end{bmatrix}.$$

#### **Answer**

For the first matrix A, L keeps the 3 lower zeros at the start of rows. But U may not have the upper zero where  $A_{24} = 0$ . For the second matrix B, L keeps the bottom left zero at the start of row 4. U keeps the upper right zero at the start of column 4. One zero in A and two zeros in B are filled in.

### Reference material

- Lecture 4 MIT course
- "Linear Algebra and Applications", pdf pages 46–86
- "Introduction to Linear Algebra", pdf pages 42–134 2.2 - The Idea of Elimination. 2.6 - Elimination = Factorization: A = LU

• This lab video, 2022 year

# Preparation material for the next class

1. Lecture 6, Gilbert Strang

**Goal** is to understand the basics of spaces and how Null Space appeared.

2. Khan Academy: Null space

It contains a good case study how to calculate Null space.

3. Matrix Algebra for Engineers: Null Space Another nice example how to find N(A).

4. "Linear Algebra and Applications", pdf pages 96–106
What does partial and full solutions means

5. The Big Picture of Linear Algebra

Extra for now If you want to get the global view of four subspaces

