Lab 6

Gram - Schmidt

```
zero = [0;0;0];
```

Define our basis

```
a = [2;1;0]
a = 3 \times 1
2
1
0
b = [0;0;4]
b = 3 \times 1
```

4 c = [2.5;3;0]

0

```
c = 3×1
2.5000
3.0000
```

Current basis

ans = 8

Let's check, is it orthogonal?

```
dot(a,b)
ans = 0

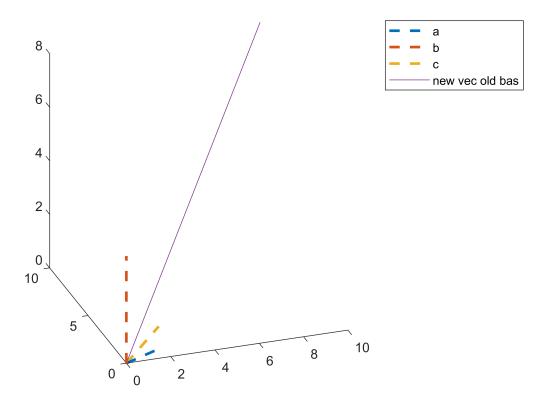
dot(b,c)
ans = 0

dot(a,c)
```

As it can be seen, it is not (it should be equal to 0)

For checking the concepts, let's consider some vector, which will be a linear combination of our basis.

```
new_vec_el = [1;2;3];
new vec_old_bas = new_vec_el(1)*a + new_vec_el(2)*b + new_vec_el(3)*c
new_vec_old_bas = 3×1
   9.5000
  10.0000
   8.0000
new_vec_old_bas_norm = new_vec_el(1)*a./norm(a) + new_vec_el(2)*b./norm(b) + new_vec_el(3)*c./r
new_vec_old_bas_norm = 3 \times 1
   2.8150
   2.7519
   2.0000
figure
plot3([zero(1) a(1)], [zero(2) a(2)], [zero(3) a(3)], '--', "LineWidth", 2)
plot3([zero(1) b(1)], [zero(2) b(2)],[zero(3) b(3)],'--',"LineWidth",2)
plot3([zero(1) c(1)], [zero(2) c(2)],[zero(3) c(3)],'--',"LineWidth",2)
hold on
plot3([zero(1) new_vec_old_bas(1)], [zero(2) new_vec_old_bas(2)],[zero(3) new_vec_old_bas(3)])
legend('a','b','c','new vec old bas')
view([-19.1 25.2])
```



There is a Gram-Schmidt algorithm, there is a link, which is understandable.

We define the projection operator by

$$\operatorname{proj}_{\mathbf{u}}\left(\mathbf{v}\right) = \frac{\langle \mathbf{u}, \mathbf{v} \rangle}{\langle \mathbf{u}, \mathbf{u} \rangle} \mathbf{u},$$

The Gram-Schmidt process then works as follows:

$$\begin{aligned} \mathbf{u}_1 &= \mathbf{v}_1, & \mathbf{e}_1 &= \frac{\mathbf{u}_1}{\|\mathbf{u}_1\|} \\ \mathbf{u}_2 &= \mathbf{v}_2 - \operatorname{proj}_{\mathbf{u}_1} \left(\mathbf{v}_2 \right), & \mathbf{e}_2 &= \frac{\mathbf{u}_2}{\|\mathbf{u}_2\|} \\ \mathbf{u}_3 &= \mathbf{v}_3 - \operatorname{proj}_{\mathbf{u}_1} \left(\mathbf{v}_3 \right) - \operatorname{proj}_{\mathbf{u}_2} \left(\mathbf{v}_3 \right), & \mathbf{e}_3 &= \frac{\mathbf{u}_3}{\|\mathbf{u}_3\|} \\ \mathbf{u}_4 &= \mathbf{v}_4 - \operatorname{proj}_{\mathbf{u}_1} \left(\mathbf{v}_4 \right) - \operatorname{proj}_{\mathbf{u}_2} \left(\mathbf{v}_4 \right) - \operatorname{proj}_{\mathbf{u}_3} \left(\mathbf{v}_4 \right), & \mathbf{e}_4 &= \frac{\mathbf{u}_4}{\|\mathbf{u}_4\|} \\ &\vdots & \vdots & \vdots & \\ \mathbf{u}_k &= \mathbf{v}_k - \sum_{j=1}^{k-1} \operatorname{proj}_{\mathbf{u}_j} \left(\mathbf{v}_k \right), & \mathbf{e}_k &= \frac{\mathbf{u}_k}{\|\mathbf{u}_k\|}. \end{aligned}$$

$$B = 3 \times 1$$
0
0
4

$$C = c - (A'*c)./(A'*A)*A - (B'*c)./(B'*B)*B$$

There is a new basis

$$New_BASIS = rats([A B C])$$

And it is orthogonal, because all of our dot products are equal to 0

```
dot(A,B)
ans = 0

round(dot(B,C))
ans = 0

round(dot(A,C))
ans = 0
```

Let's put our old vector scalar values in new basis

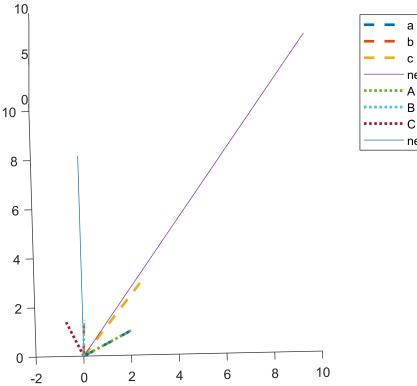
view([-1.45 69.72])

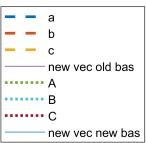
```
new_vec_new_bas = new_vec_el(1)*A + new_vec_el(2)*B + new_vec_el(3)*C

new_vec_new_bas = 3x1
    -0.1000
    5.2000
    8.0000

figure
plot3([zero(1) a(1)], [zero(2) a(2)],[zero(3) a(3)],'--',"LineWidth",2)
hold on
plot3([zero(1) b(1)], [zero(2) b(2)], [zero(3) b(3)], --', "LineWidth", 2)
```

```
figure
plot3([zero(1) a(1)], [zero(2) a(2)],[zero(3) a(3)],'--',"LineWidth",2)
hold on
plot3([zero(1) b(1)], [zero(2) b(2)],[zero(3) b(3)],'--',"LineWidth",2)
hold on
plot3([zero(1) c(1)], [zero(2) c(2)],[zero(3) c(3)],'--',"LineWidth",2)
hold on
plot3([zero(1) new_vec_old_bas(1)], [zero(2) new_vec_old_bas(2)],[zero(3) new_vec_old_bas(3)])
hold on
plot3([zero(1) A(1)], [zero(2) A(2)],[zero(3) A(3)],':',"LineWidth",2)
hold on
plot3([zero(1) B(1)], [zero(2) B(2)],[zero(3) B(3)],':',"LineWidth",2)
hold on
plot3([zero(1) C(1)], [zero(2) C(2)],[zero(3) C(3)],':',"LineWidth",2)
hold on
plot3([zero(1) new_vec_new_bas(1)], [zero(2) new_vec_new_bas(2)],[zero(3) new_vec_new_bas(3)])
legend('a','b','c','new vec old bas','A','B','C','new vec new bas')
```





As it can be seen, there are not in the same position.

```
New_BASIS_NORM = ([A./norm(A) B./norm(B) C./norm(C)]);
```

Gram - Schmidt is complete, there is our OrthoNormal basis

Even with norm values, our vector is not equal from the old basis. That means, that using this tech we can only assume that we have the same space with some linear mapping between them.

```
new_vec_new_bas_norm = new_vec_el(1)*A./norm(A) + new_vec_el(2)*B./norm(B) + new_vec_el(3)*C./r
new_vec_new_bas_norm = 3x1
    -0.4472
    3.1305
    2.0000
```

Solving simple linear equation, we can find the same vector in new basis

```
new_vec_el_in_new_bas = linsolve(New_BASIS_NORM,new_vec_old_bas)
```

```
8.0000
4.6957

new_vec_new_bas_norm_correct_el = new_vec_el_in_new_bas(1)*A./norm(A) + new_vec_el_in_new_bas(2)
new_vec_new_bas_norm_correct_el = 3×1
9.5000
10.0000
8.0000
```

new_vec_old_bas

new_vec_el_in_new_bas = 3x1

12.9692

new_vec_old_bas = 3×1 9.5000 10.0000 8.0000