

# Analytical Geometry and Linear Algebra II, Lab 2

Gaussian elimination recap
A=LU, A=LDV, PA=LU factorization



Algorithm

$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix}$$

Algorithm

$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

Training task

$$\begin{cases} 2x_1 + 3x_2 - x3 = 9 \\ x_1 - 2x_2 + x_3 = 3 \\ x_1 + 2x_3 = 2 \end{cases}$$

Training task

$$\begin{cases} 2x_1 + 3x_2 - x3 = 9 \\ x_1 - 2x_2 + x_3 = 3 \\ x_1 + 2x_3 = 2 \end{cases} \text{ Ans: } \begin{cases} x_1 = 4 \\ x_2 = 0 \\ x_3 = -1 \end{cases}$$

Example of A=LU

$$\begin{bmatrix}
2 & 1 & 1 \\
4 & -6 & 0 \\
-2 & 7 & 2
\end{bmatrix}$$

Example of A=LU

$$\begin{bmatrix}
2 & 1 & 1 \\
4 & -6 & 0 \\
-2 & 7 & 2
\end{bmatrix}
\rightarrow
\begin{bmatrix}
1 & 0 & 0 \\
2 & 1 & 0 \\
-1 & -1 & 1
\end{bmatrix}
\begin{bmatrix}
2 & 1 & 1 \\
0 & -8 & -2 \\
0 & 0 & 1
\end{bmatrix}$$

Example of A=LDV

$$\begin{bmatrix}
2 & 1 & 1 \\
4 & -6 & 0 \\
-2 & 7 & 2
\end{bmatrix}
\rightarrow
\begin{bmatrix}
1 & 0 & 0 \\
2 & 1 & 0 \\
-1 & -1 & 1
\end{bmatrix}
\begin{bmatrix}
2 & 0 & 0 \\
0 & -8 & 0 \\
0 & 0 & 5
\end{bmatrix}
\begin{bmatrix}
1 & 1/2 & 1/2 \\
0 & 1 & 1/4 \\
0 & 0 & 1
\end{bmatrix}$$

Oleg Bulichev AGLA2 3

Formal Idea

$$A = LU = \begin{pmatrix} lower triangular L \\ 1's on the diagonal \end{pmatrix} \begin{pmatrix} upper triangluar U \\ pivots on the diagonal \end{pmatrix}$$

**Requirements**: No row exchanges as Gaussian elimination reduces square A to U

$$A = LDU = \begin{pmatrix} lower triangular L \\ 1's on the diagonal \end{pmatrix} \begin{pmatrix} pivot matrix \\ D is diagonal \end{pmatrix} \begin{pmatrix} upper triangluar U \\ 1's on the diagonal \end{pmatrix}$$

**Requirements**: No row exchanges. The pivots in *D* are divided out to leave 1's on the diagonal of *U*. If *A* is symmetric, then *U* is  $L^T$  and  $A = LDL^T$ .

Application: Theory

$$Ax = b \rightarrow$$

Application: Theory

$$Ax = b \to \underbrace{LU}_A x = b$$

Application: Theory

$$Ax = b \to \underbrace{LU}_{A} x = b \to L \underbrace{c}_{Ux} = b$$

Application: Theory

$$Ax = b \rightarrow \underbrace{LU}_{A} x = b \rightarrow L \underbrace{c}_{Ux} = b \rightarrow Ux = c \rightarrow Ans: x$$

There are two steps:

- 1. Factor (from A find its factors L and U)
- 2. **Solve** (from *L* and *U* and *b* find the solution *x*)

A=LU factorization
Application Theory  $Ax = b \rightarrow \underbrace{UU}_{A} x = b \rightarrow \underbrace{U}_{G} x = b \rightarrow Ux = c \rightarrow Ans; x$ There are two steps:

1. Factor (from A find its factors, I and I/I)

2. Solve (from L and U and b find the solution x)

The best use for A=LU is when you need to solve an equation where the right-hand side depends on the previous answer

#### Description

Try to solve such systems using:

- Gauss-Jordan elimination
- IU factorization

Compare time consumption

$$AX = B$$
, where  $A = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 3 & 3 \\ -3 & 10 & 2 \end{bmatrix}$ ,  $B = \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix}$ 

$$B_{j+1} = B_j + X_j$$
, for  $j = 1, 2$ , where  $B_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ 

# Application: Case Study

#### Description

#### Try to solve such systems using:

- Gauss-Jordan elimination
- IU factorization

#### Compare time consumption

$$AX = B$$
, where  $A = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 3 & 3 \\ -3 & 10 & 2 \end{bmatrix}$ ,  $B = \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix}$ 

$$B_{j+1} = B_j + X_j$$
, for  $j = 1, 2$ , where  $B_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ 

$$A = \underbrace{\begin{bmatrix} \frac{-1}{3} & \frac{16}{29} & 1\\ \frac{-2}{3} & 0 & 0\\ 1 & 0 & 0 \end{bmatrix}}_{\begin{bmatrix} 0 & \frac{29}{3} & \frac{13}{3}\\ 0 & 0 & \frac{-21}{2} \end{bmatrix}}_{[0 & \frac{13}{3} & \frac{13}{3}]} = \underbrace{\begin{bmatrix} 1 & 0 & 0\\ 2 & 1 & 0\\ -3 & -16 & 1 \end{bmatrix}}_{[0 & 0 & 21]} \underbrace{\begin{bmatrix} 1 & 2 & 1\\ 0 & -1 & 1\\ 0 & 0 & 21 \end{bmatrix}}_{[0 & 0 & 21]}, B_2 = \begin{bmatrix} \frac{5}{7}\\ \frac{3}{7}\\ \frac{-4}{7} \end{bmatrix}, B_3 = \begin{bmatrix} \frac{73}{49}\\ \frac{109}{147}\\ \frac{-185}{147} \end{bmatrix}$$

Which number c leads to zero in the second pivot position? A row exchange is needed and A = LU will not be possible. Which c produces zero in the third pivot position? Then a row exchange can't help and elimination fails:

$$A = \begin{bmatrix} 1 & c & 0 \\ 2 & 4 & 1 \\ 3 & 5 & 1 \end{bmatrix}.$$

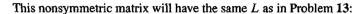
Which number c leads to zero in the second pivot position? A row exchange is needed and A = LU will not be possible. Which c produces zero in the third pivot position? Then a row exchange can't help and elimination fails:

$$A = \begin{bmatrix} 1 & c & 0 \\ 2 & 4 & 1 \\ 3 & 5 & 1 \end{bmatrix}.$$

#### **Answer**

c=2 leads to zero in the second pivot position: exchange rows and not singular.

c=1 leads to zero in the third pivot position. In this case the matrix is *singular*.



Find L and U for

$$A = \begin{bmatrix} a & r & r & r \\ a & b & s & s \\ a & b & c & t \\ a & b & c & d \end{bmatrix}.$$

Find the four conditions on a, b, c, d, r, s, t to get A = LU with four pivots.

This nonsymmetric matrix will have the same L as in Problem 13:

Find 
$$L$$
 and  $U$  for

$$A = \begin{bmatrix} a & r & r & r \\ a & b & s & s \\ a & b & c & t \\ a & b & c & d \end{bmatrix}.$$

Find the four conditions on a, b, c, d, r, s, t to get A = LU with four pivots.

#### **Answer**

If A and B have nonzeros in the positions marked by x, which zeros (marked by 0) stay zero in their factors L and U?

$$A = \begin{bmatrix} x & x & x & x \\ x & x & x & 0 \\ 0 & x & x & x \\ 0 & 0 & x & x \end{bmatrix} \qquad B = \begin{bmatrix} x & x & x & 0 \\ x & x & 0 & x \\ x & 0 & x & x \\ 0 & x & x & x \end{bmatrix}.$$

$$B = \begin{bmatrix} x & x & x & 0 \\ x & x & 0 & x \\ x & 0 & x & x \\ 0 & x & x & x \end{bmatrix}$$

If A and B have nonzeros in the positions marked by x, which zeros (marked by 0) stay zero in their factors L and U?

$$A = \begin{bmatrix} x & x & x & x \\ x & x & x & 0 \\ 0 & x & x & x \\ 0 & 0 & x & x \end{bmatrix} \qquad B = \begin{bmatrix} x & x & x & 0 \\ x & x & 0 & x \\ x & 0 & x & x \\ 0 & x & x & x \end{bmatrix}.$$

#### **Answer**

For the first matrix A, L keeps the 3 lower zeros at the start of rows. But U may not have the upper zero where  $A_{24} = 0$ . For the second matrix B, L keeps the bottom left zero at the start of row 4. U keeps the upper right zero at the start of column 4. One zero in A and two zeros in B are filled in.

## Reference material

- Lecture 4 MIT course
- "Linear Algebra and Applications", pdf pages 46–86
- "Introduction to Linear Algebra", pdf pages 349–374
  2.2 The Idea of Elimination, 2.6 Elimination = Factorization:

A = LU

• This lab video, 2022 year

