

R.O.: system, consists of :

A - particle, rectilinear motion

D - body, rot. motion

B - disk, planar motion

Method: General equation of dynamics. It is most suitable method for finding accelerations and making diff. equations of motion.

Algorithm:

- 1) To draw a picture with all active forces and reactions.
- 2) Define moments and forces of inertia
- 3) To declare a possible movement of one points of the system and derive others using it.
- 4) Write equation and solve the task.

$$\sum (F + \varphi) \cdot \delta v = 0$$

Solution:

$$\sum A = m_1 g \delta s_1 - \varphi_1 \delta s_1 - M \delta \varphi - \varphi_2 \delta s_1 = 0$$

$$\varphi_1 = m a_1$$

$$\varepsilon = \frac{a_1}{R-v}$$

$$a_c = \varepsilon \cdot r = \frac{a_1 v}{R-v}$$

$$\delta \varphi = \frac{\delta s_1}{R-v}$$

$$\varphi_2 = m_2 a_c = m_2 \frac{a_1 v}{R-v}$$

substitute

$$m_1 g \delta s_1 - m_1 \boxed{a_1} \delta s_1 - m_2 \frac{\boxed{a_1}^2}{R-v} \cdot \frac{\delta s_1}{R-v} - \frac{m_2 \boxed{a_1} v^2}{(R-v)^2} \delta s_1 = 0$$

$$\Rightarrow \boxed{a_1} = \dots$$

