#### Distributed systems with MsgFlo

Flow-Based Programming over message queues

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Jon Nordby



@jononor

#### Basic MQTT communication

```
// Motor.cpp
mqtt.subscribe("motor/start", start_motor);
```

```
// Button.cpp
mqtt.publish("motor/start", button_pressed);
```

- + Works OK
- Connections hidden in code
  - Hardcoded functionality



## MsgFlo participant

#### // Motor.cpp

```
mqtt.subscribe("motor/start", start_motor);
mqtt.publish("msgflo/discover", motor_info);
```

#### // Button.cpp

```
mqtt.publish("msgflo/discover", button_info);
mqtt.publish("button/pressed", button_pressed);
```

- + Devices describe themselves
- + Reusable components! Something need to connect the topics

#### MsgFlo discovery message

```
"component": "fosdem2017/Button",
"role": "button",
"id": "button",
"label": "This is a button, it can be pressed",
"icon": null,
"outports": [{
 "id": "pressed",
 "type": "boolean"
 "queue": "button/pressed"
"inports": []
```

## Bind topics together

```
# motorcontrol.fbp
button(Button) PRESSED → START motor(Motor)
...
motor RUNNING → RED warninglight(Lamp)
```

- # bind the queues together \$ msgflo-setup motorcontrol.fbp
  - flowhub

# Foreign participants

# existingdevice.yml

```
# send MsgFlo discovery message
# on behalf of device
$ msgflo-register-foreign existingdevice.yml
```

# Live programming



## Full stack



