#### AdaBoost

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#### Content

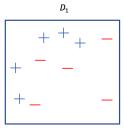
- Boosting
- 2 AdaBoost

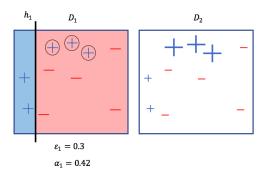
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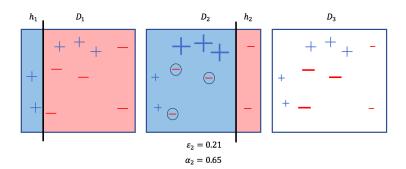
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- To begin, we define an algorithm for finding the rules of thumb, which we call a weak learner.

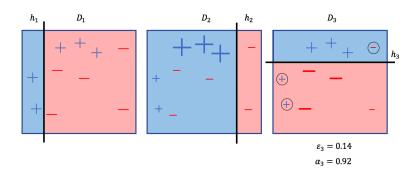
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- The boosting algorithm repeatedly calls this weak learner, each time feeding it a different distribution over the training data (in Adaboost).

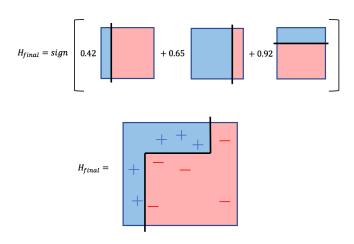
- Boosting refers to a general and provably effective method of producing a very accurate classifier by combining rough and moderately inaccurate rules of thumb.
- To begin, we define an algorithm for finding the rules of thumb, which we call a weak learner.
- The boosting algorithm repeatedly calls this weak learner, each time feeding it a different distribution over the training data (in Adaboost).
- Each call generates a weak classifier and we must combine all
  of these into a single classifier that, hopefully, is much more
  accurate than any one of the rules.











• As usual we are given a data set:

$$\mathcal{D} = \{(\mathbf{x}_i, y_i) : \mathbf{x}_i \in \mathbb{R}^d, y_i \in \{-1, +1\}, i = 1, 2, \dots, m\}.$$

- Where  $x_i$  could represent the features vector of an image patch, and  $y_i$  is whether or not the image is a face.
- First, we need to define a distribution D over the dataset  $\mathcal{D}$  such that  $\sum_i D(i) = 1$ .

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- So, we want only a classifier that does not have exactly 50% error (since these classifiers would add no information).
- The error rate of a weak classifier  $h_t(x)$  is calculated empirically over the training data:

$$\epsilon(h_t) = \frac{1}{m} \sum_{i=1}^m \delta(h_t(x_i) \neq y_i) < \frac{1}{2}.$$

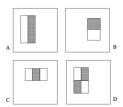
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 One possible weak classifier could be a haar-like feature of this kind:



The feature value es the difference of the pixels sums of the white regions and black regions.

 Define the integral image as the image whose pixel value at a particular pixel x, y is the sum of the pixel values to the left and above x, y in the original image:

$$ii(x,y) = \sum_{x' \le x, y' \le y} i(x', y')$$

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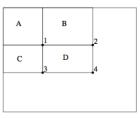
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• Use the following pair of recurrences to compute the integral image in just one pass.

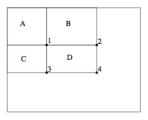
$$s(x,y) = s(x,y-1) + i(x,y)$$

$$ii(x, y) = ii(x - 1, y) + s(x, y)$$

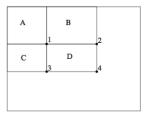
where we define s(x, -1) = 0 and ii(-1, y) = 0.



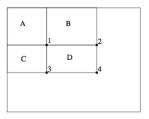
 The sum of a particular rectangle can be computed in just 4 references using the integral image.



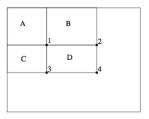
• The value at point 1 is the sum of the pixels in rectangle A.



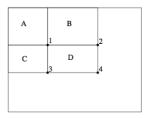
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- Point 2 is A+B.
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- So, the sum within D alone is 4-2-3+1.

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- The weak learner searches for the optimal threshold classification function, such that the minimum number of examples are misclassified.
- The weak classifier  $h_t(\mathbf{x})$  hence consists of the feature  $f_t(\mathbf{x})$ , a threshold  $\theta_t$ , and a parity  $p_t = \{-1, +1\}$  indicating the direction of the inequality sign:

$$h_t(\mathbf{x}) = egin{cases} +1 & ext{if } p_t f_t(\mathbf{x}) < p_t heta_t \ -1 & ext{otherwise}. \end{cases}$$

• Let's assume we have selected T weak classifiers and a scalar constant  $\alpha_t$  associated with each:

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• Define the strong classifier as the sign of this inner product:

$$H(\mathbf{x}) = \operatorname{sign}\left[F(\mathbf{x})\right] = \operatorname{sign}\left[\sum_{t=1}^{T} \alpha_t h_t(\mathbf{x})\right].$$

Given  $\mathcal{D} = (x_i, y_i), \dots, (x_m, y_m)$  as before.

Initialize the distribution  $D_1$  to be uniform:  $D_1(i) = \frac{1}{m}$ .

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Compute the weighted error for each weak classifier.

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Select the weak classifier with minimum error.

$$h_t = \arg\min_h \epsilon_t(h)$$

2. Set weight  $\alpha_t$  based on the error:

$$\alpha_t = \frac{1}{2} \ln \left( \frac{1 - \epsilon_t(h_t)}{\epsilon_t(h_t)} \right)$$

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3. Update the distribution based on the performance so far:

$$D_{t+1}(i) = \frac{1}{Z_t} D_t(i) \exp[-\alpha_t y_i h_t(x_i)]$$

where  $Z_t$  is a normalization factor to keep  $D_{t+1}$  a distribution.

Note the careful evaluation of the term inside of the exp based on the possible  $\{-1, +1\}$  values of the label.

 The selected weight for each new weak classifier is always positive.

$$\epsilon_t(h_t) < 1 \Rightarrow \alpha_t = \frac{1}{2} \ln \frac{1 - \epsilon_t(h_t)}{\epsilon_t(h_t)} > 0$$

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 The smaller the classification error, the bigger the weight and the more this particular weak classifier will impact the final strong classifier.

$$\epsilon(h_A) < \epsilon(h_B) \Rightarrow \alpha_A > \alpha_B$$

• The weights of the data points are multiplied by  $\exp[-\alpha_t y_i h_t(\mathbf{x}_i)]$ .

$$\exp[-\alpha_t y_i h_t(\mathbf{x}_i)] = \begin{cases} \exp[-\alpha_t] < 1 & \text{if } h_t(\mathbf{x}_i) = y_i \\ \exp[\alpha_t] > 1 & \text{if } h_t(\mathbf{x}_i) \neq y_i \end{cases}$$

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- The weights of correctly classified points are reduced and the weights of incorrectly classified points are increased.
- Hence, the incorrectly classified points will receive more attention in the next run.

 At each iteration, the weights on the data points are normalized by

$$Z_t = \sum_{\mathbf{x}_i} D_t(\mathbf{x}_i) \exp[-\alpha_t y_i h_t(\mathbf{x}_i)]$$
$$= \sum_{\mathbf{x}_i \in \mathcal{A}} D_t(\mathbf{x}_i) \exp[-\alpha_t] + \sum_{\mathbf{x}_i \in \overline{\mathcal{A}}} D_t(\mathbf{x}_i) \exp[\alpha_t]$$

where A is the set of correctly classified points:

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where A is the set of correctly classified points:

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• We can write these normalization factors as functions of  $\alpha_t$  and  $h_t$ , then:

$$Z_t = Z_t(\alpha_t, h_t)$$

• We want to find  $h_t$  and  $\alpha_t$  that minimize  $Z(h_t, \alpha_t)$ :

$$(h_t, \alpha_t)^* = \arg\min Z(\alpha_t, h_t)$$

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where A is the set of correctly classified points:

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• Take the derivative w.r.t.  $\alpha_t$  and set it to zero:

$$\frac{dZ(h_t, \alpha_t)}{d\alpha_t} = \sum_{\mathbf{x}_i \in \mathcal{A}} -D_t(\mathbf{x}_i) \exp[-\alpha_t] + \sum_{\mathbf{x}_i \in \overline{\mathcal{A}}} D_t(\mathbf{x}_i) \exp[\alpha_t] = 0$$

So we have

$$\sum_{\mathbf{x}_i \in \mathcal{A}} -D_t(\mathbf{x}_i) \exp[-\alpha_t] + \sum_{\mathbf{x}_i \in \overline{\mathcal{A}}} D_t(\mathbf{x}_i) \exp[\alpha_t] = 0$$

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So we have

$$\begin{split} \sum_{\mathbf{x}_i \in \mathcal{A}} -D_t(\mathbf{x}_i) \exp[-\alpha_t] + \sum_{\mathbf{x}_i \in \overline{\mathcal{A}}} D_t(\mathbf{x}_i) \exp[\alpha_t] &= 0 \\ \sum_{\mathbf{x}_i \in \mathcal{A}} D_t(\mathbf{x}_i) &= \sum_{\mathbf{x}_i \in \overline{\mathcal{A}}} D_t(\mathbf{x}_i) \frac{\exp[\alpha_t]}{\exp[-\alpha_t]} \\ \sum_{\mathbf{x}_i \in \mathcal{A}} D_t(\mathbf{x}_i) &= \sum_{\mathbf{x}_i \in \overline{\mathcal{A}}} D_t(\mathbf{x}_i) \exp[2\alpha_t] \end{split}$$

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And, by definition, we can write the error as

$$\epsilon_t(h) = \sum_{i=1}^m D_t(\mathbf{x}_i) \, \delta(h(\mathbf{x}_i) \neq y_i) = \sum_{\mathbf{x}_i \in \overline{\mathcal{A}}} D_t(\mathbf{x}_i), \, \forall h$$

Therefore, by substituting

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we get

$$1 - \epsilon_t(h) = \epsilon_t(h) \exp[2\alpha_t]$$

$$\exp[2\alpha_t] = \frac{1 - \epsilon_t(h)}{\epsilon_t(h)}$$

$$\alpha_t = \frac{1}{2} \ln \left(\frac{1 - \epsilon_t(h)}{\epsilon_t(h)}\right)$$

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in

$$Z(h_t, \alpha_t) = \sum_{\mathbf{x}_i \in \mathcal{A}} D_t(\mathbf{x}_i) \exp[-\alpha_t] + \sum_{\mathbf{x}_i \in \overline{\mathcal{A}}} D_t(\mathbf{x}_i) \exp[\alpha_t]$$

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$$Z(h_t, \alpha_t) = \left( 1 - \epsilon_t(h_t) \right) \sqrt{\frac{\epsilon_t(h_t)}{1 - \epsilon_t(h_t)}} + \epsilon_t(h_t) \sqrt{\frac{1 - \epsilon_t(h_t)}{\epsilon_t(h_t)}}$$

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$$= 2\sqrt{\epsilon_t(h_t)\left(1 - \epsilon_t(h_t)\right)}$$

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Changing variable  $\gamma_t = \frac{1}{2} - \epsilon_t(h_t)$ ,  $\gamma_t \in (0, \frac{1}{2}]$ 

$$= \sqrt{1 - 4\gamma_t^2} \leq \exp[-2\gamma_t^2]$$

• Therefore, after *t* steps, the error rate of the strong classifier is bounded on top by

$$\operatorname{Err}(H) = Z \leq \exp\left[-2\sum_{t=1}^{T} \gamma_t^2\right]$$

• Therefore, after *t* steps, the error rate of the strong classifier is bounded on top by

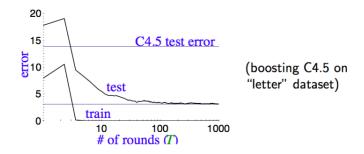
$$\operatorname{Err}(H) = Z \leq \exp \left[ -2 \sum_{t=1}^{T} \gamma_t^2 \right]$$

Hence, each step decreases the upper bound exponentially.

 Therefore, after t steps, the error rate of the strong classifier is bounded on top by

$$\operatorname{Err}(H) = Z \leq \exp \left[ -2 \sum_{t=1}^{T} \gamma_t^2 \right]$$

- Hence, each step decreases the upper bound exponentially.
- And, a weak classifier with small error rate will lead to faster descent.



Plot taken from Schapire's and Corso's slides

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Thank you!

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