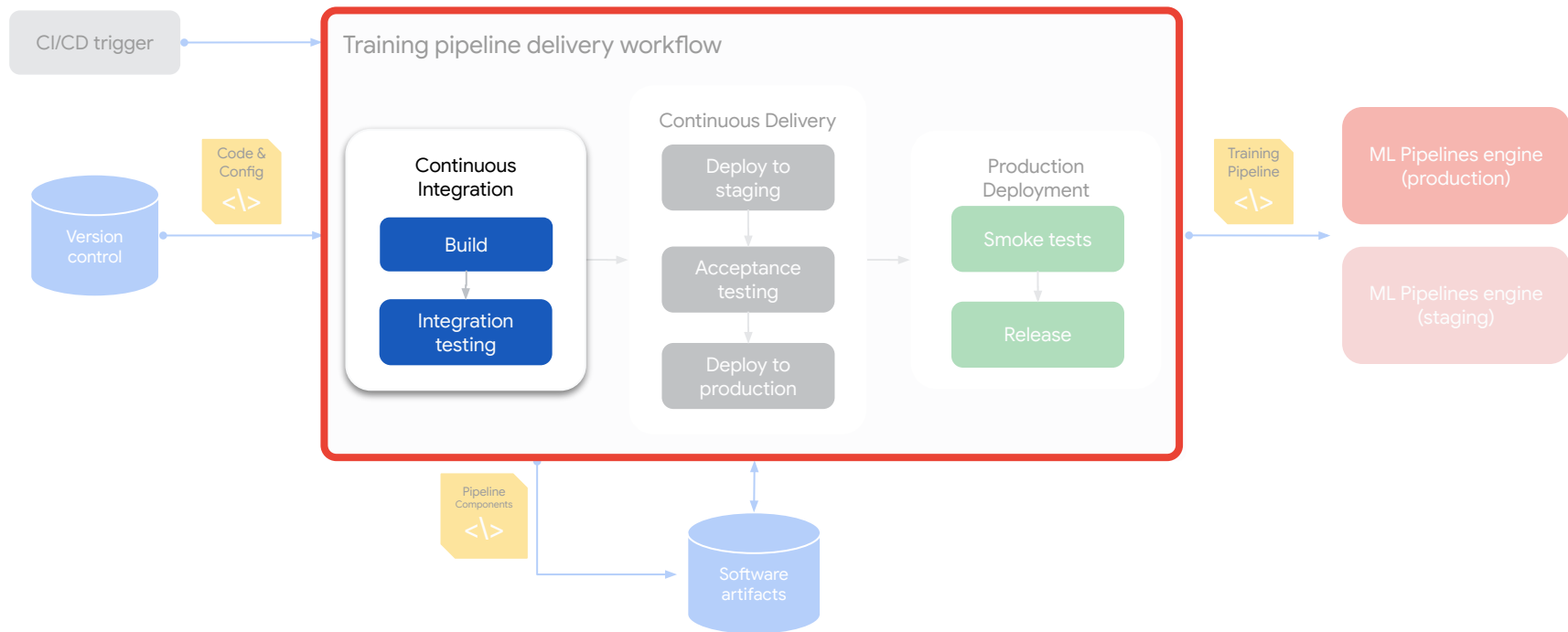


# Continuous Integration

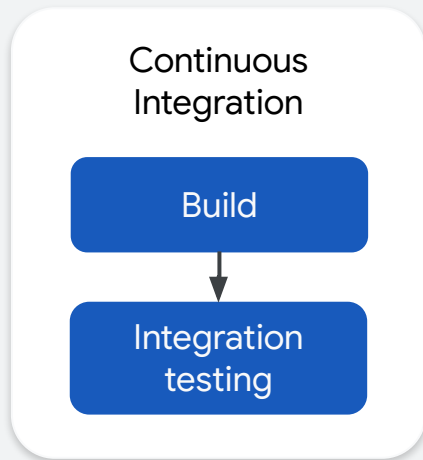


# MLOps: Training Operationalization



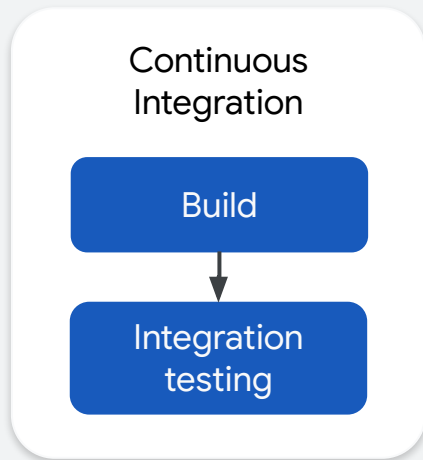
# TinyML CI Questions

- What does the **build environment** look like?
- What **types of assets** do I need to consider writing for testing?

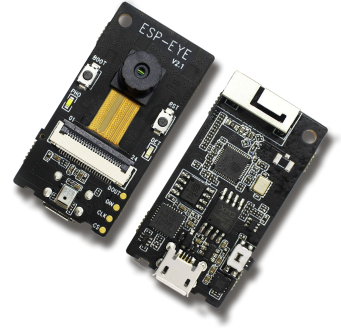
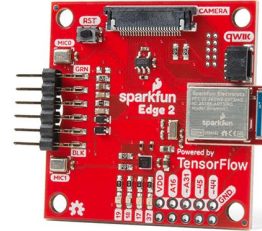
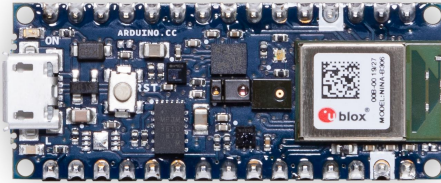


# TinyML CI Questions

- What does the build environment look like?
- What **types of assets** do I need to consider writing for testing?



# What Does the Build Environment Look Like?

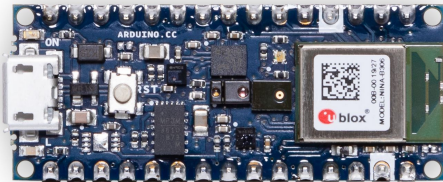


# What Does the Build Environment Look Like?



Board	MCU / ASIC	Clock	Memory	Sensors	Radio
Himax WE-I Plus EVB	HX6537-A 32-bit EM9D DSP	400 MHz	2MB flash 2MB RAM	Accelerometer, Mic, Camera	None
Arduino Nano 33 BLE Sense	32-bit nRF52840	64 MHz	1MB flash 256kB RAM	Mic, IMU, Temp, Humidity, Gesture, Pressure, Proximity, Brightness, Color	BLE
SparkFun Edge 2	32-bit ArtemisV1	48 MHz	1MB flash 384kB RAM	Accelerometer, Mic, Camera	BLE
Espressif EYE	32-bit ESP32-D0WD	240 MHz	4MB flash 520kB RAM	Mic, Camera	WiFi, BLE

# Arduino Example



on our **computer**

Code (C / C++)

Binary **firmware**

*upload  
via USB*

on the **Arduino**

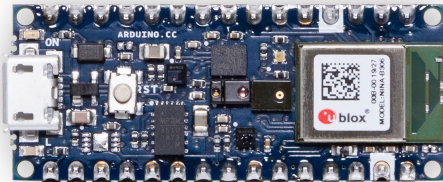
*for running tasks*

Binary **firmware**

*premade,  
load at startup*

Bootloader

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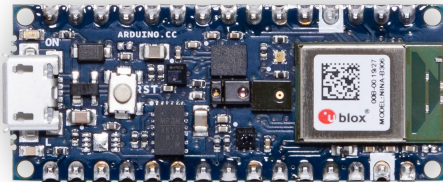
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# Arduino Example



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Bootloader

# Arduino Example

- Firmware is updated via a physical device connection
- **Possible to update (some) devices over the air (OTA)**



# Arduino Example

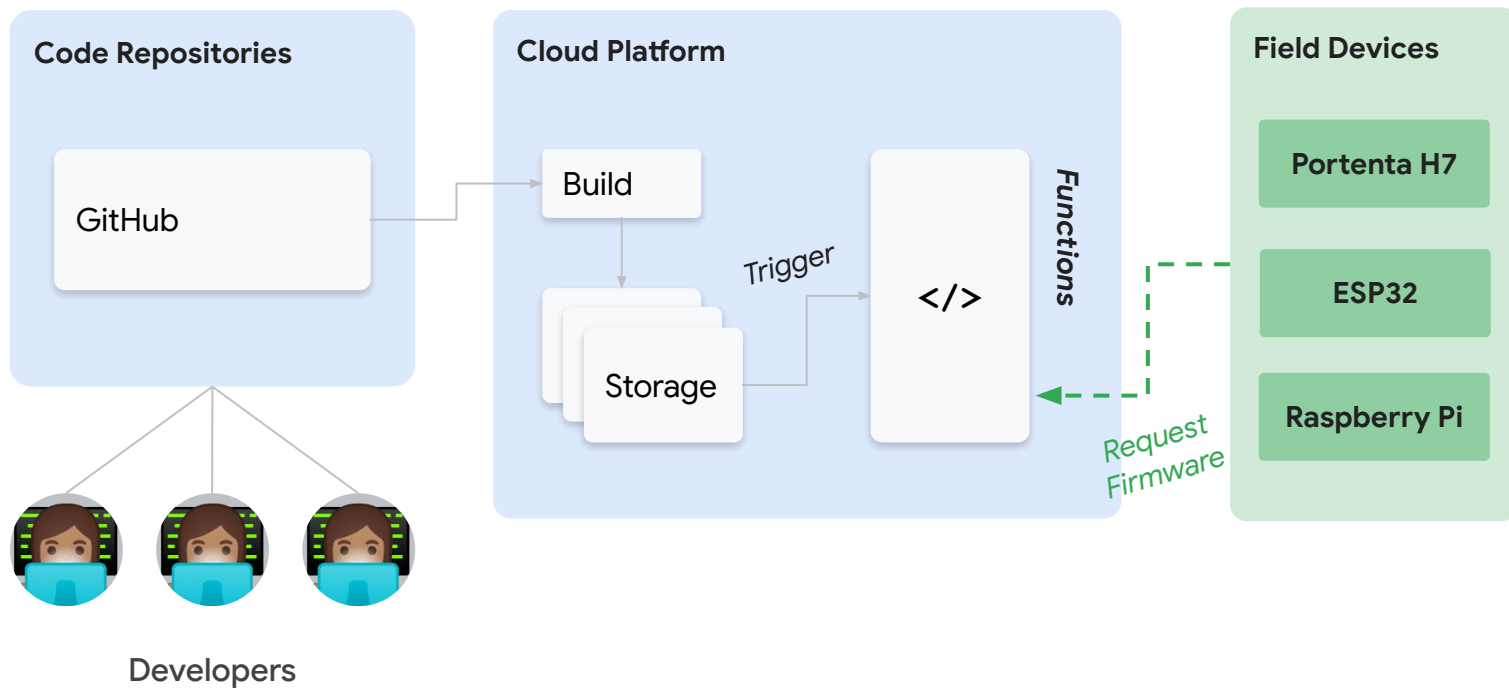
- Firmware is updated via a physical device connection
- **Possible to update (some) devices over the air (OTA)**
  - MKR WiFi 1010
  - Nano 33 IoT
  - Portenta H7

Arduino Cloud

OTA

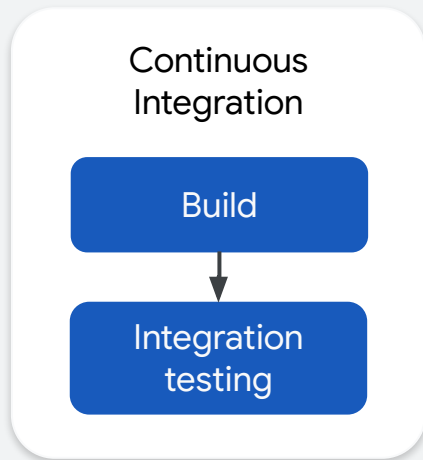


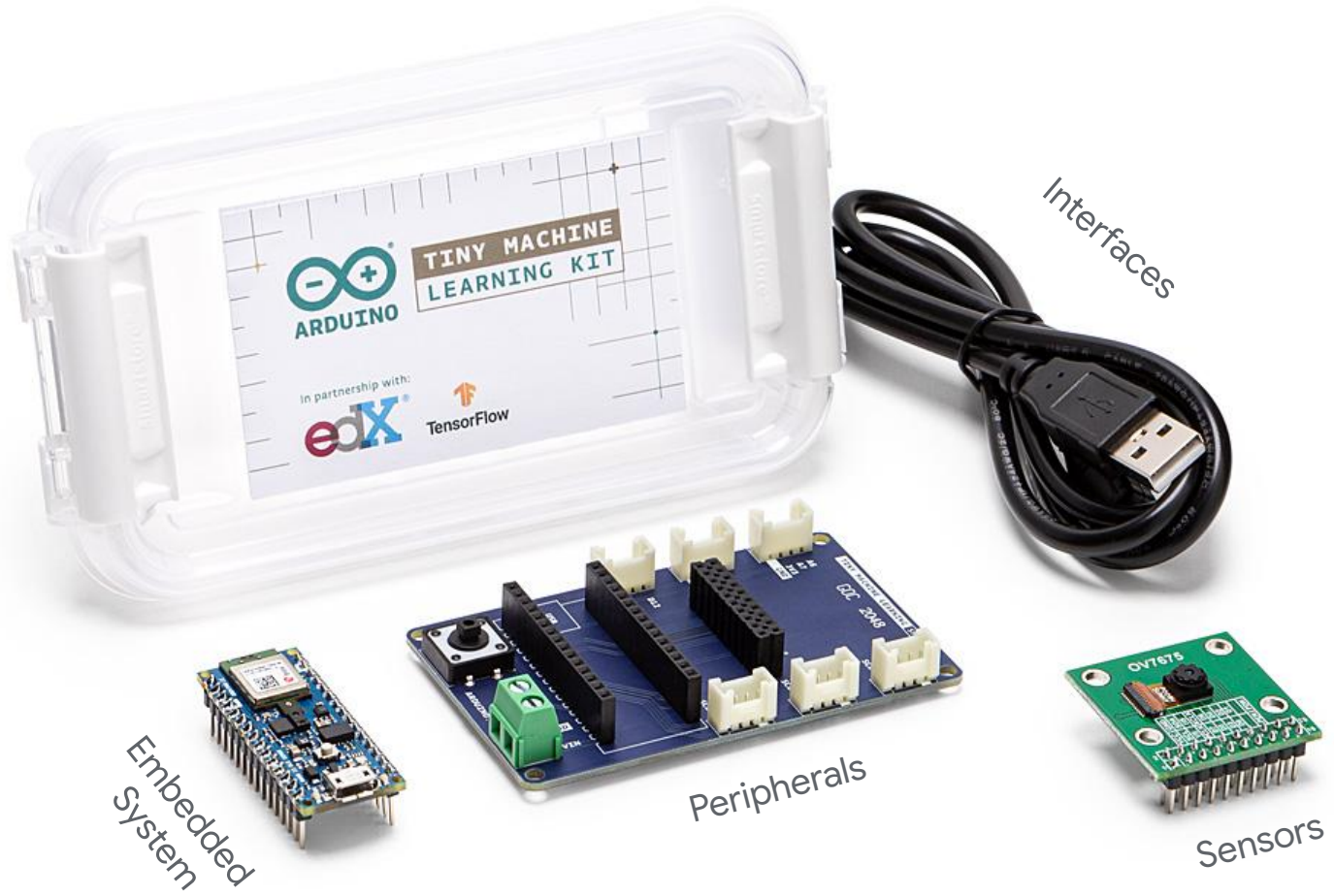
# Continuous Integration Architecture



# TinyML CI Questions

- What does the **build environment** look like?
- **What types of assets do I need to consider writing for testing?**





Embedded  
System

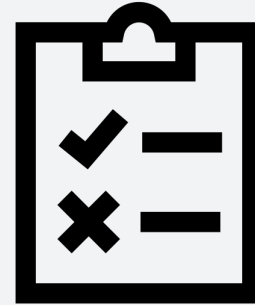
Peripherals

Sensors

Interfaces

# What to **test**?

1. Code
2. Model
3. Data
4. Sensors



# What to **test**?

1. **Code**
2. Model
3. Data
4. Sensors

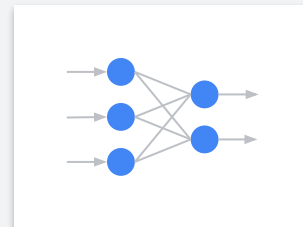


- **Unit Tests**
  - Definition
  - Types
  - Methods
  - Approaches
  - Levels



# What to **test**?

1. Code
- 2. Model**
3. Data
4. Sensors



## - **Model Concerns**

- Size
- Latency
- Accuracy
- Energy-efficiency
- Licensing

# What to **test**?

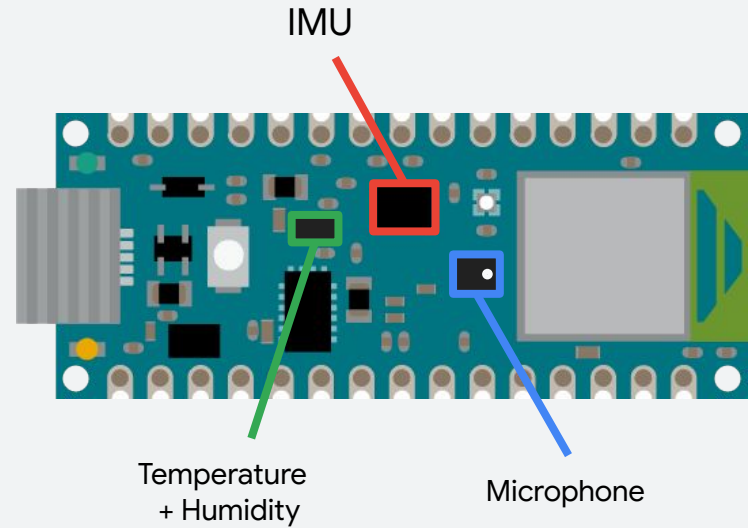
1. Code
2. Model
- 3. Data**
4. Sensors



- **Data Concerns**
  - Baseline dataset
  - Expand to different datasets
  - Synthetic datasets
  - Verify on production data

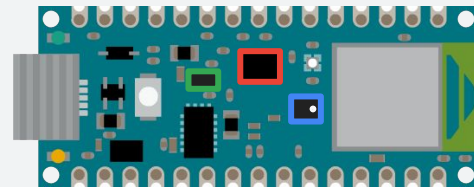
# What to **test**?

1. Code
2. Model
3. Data
4. **Sensors**



# What to **test**?

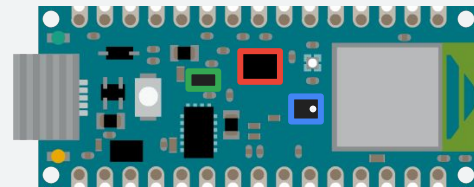
1. Code
2. Model
3. Data
- 4. Sensors**



- Do you test functionality on the **physical** devices?
  - Access to devices & sensors
  - Physical testing lab
  - Sensor variability

# What to **test**?

1. Code
2. Model
3. Data
- 4. Sensors**



- Do you test functionality on **emulation** devices?
  - Emulators cannot support all sensors
  - Cannot mimic sensor variations

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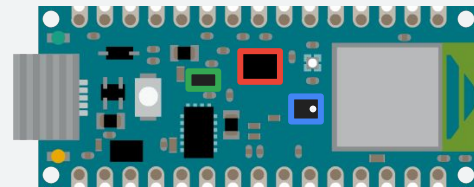
↑ SCROLL

By: antmicro

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# What to **test**?

1. Code
2. Model
3. Data
- 4. Sensors**



- Do you test functionality on **emulation** devices?
  - Emulators cannot support all sensors
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# Smartphones

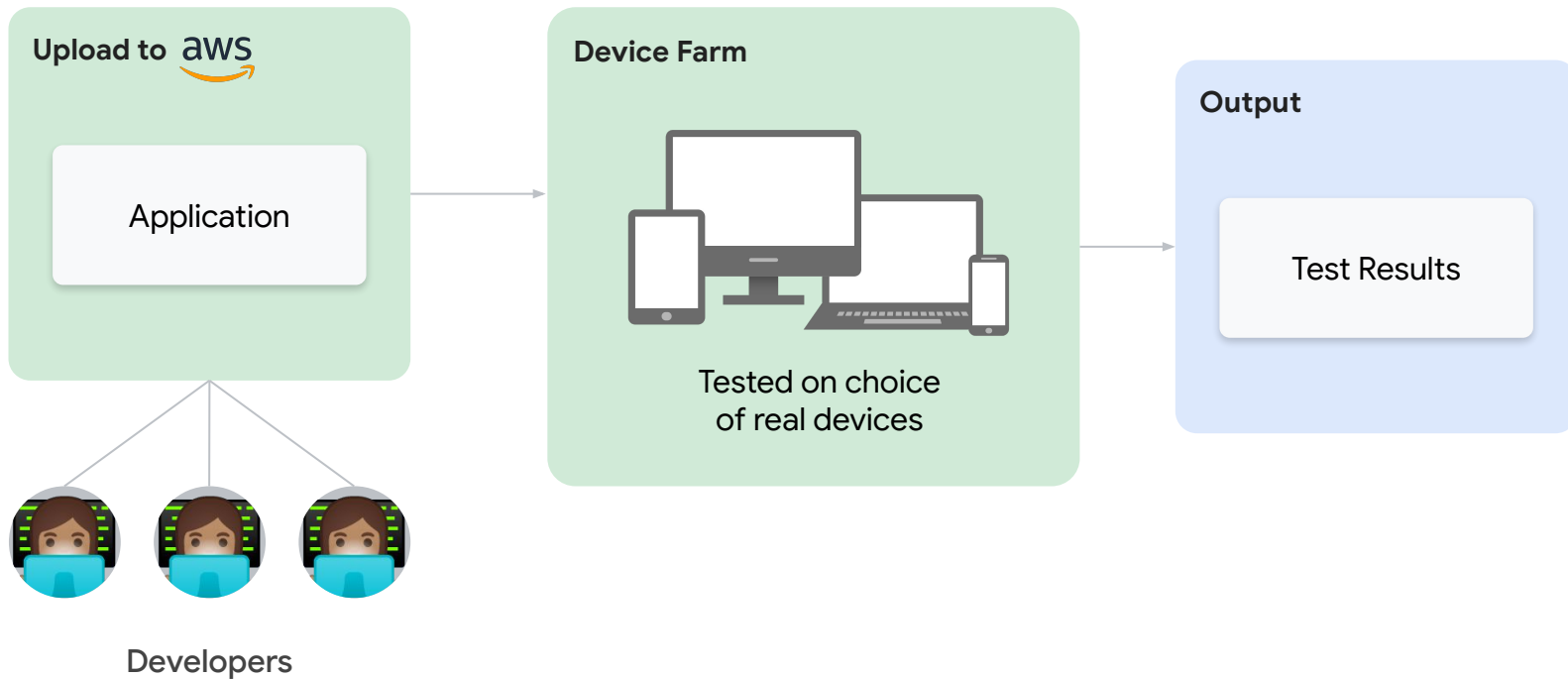








**Device Farm**



# MLOps: Training Operationalization

