

Preview of TinyML Applications



Acoustic Sensors

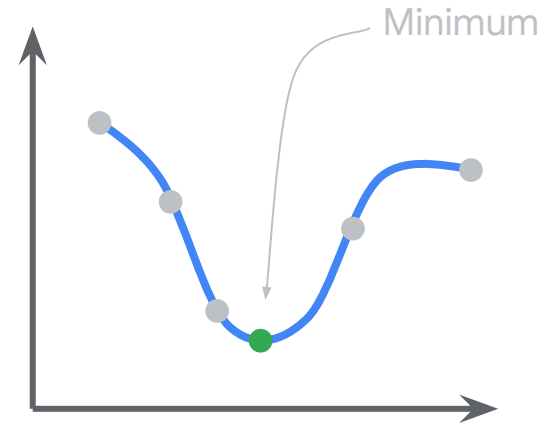
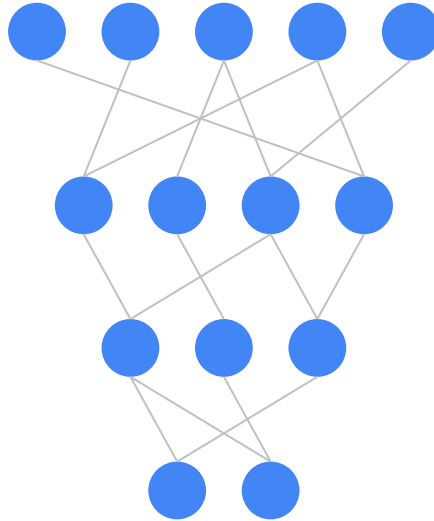
Ultrasonic, Microphones,
Geophones, Vibrometers

Image Sensors

Thermal, Image

Motion Sensors

Gyroscope, Radar,
Accelerometer



TinyML Application Areas



Home



Office

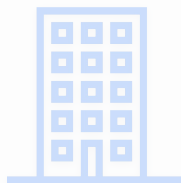


Industry

TinyML Application Areas



Home



Office



Industry

Keyword Spotting





Step 1
Audio input
from microphone
(sensor)



input
complete



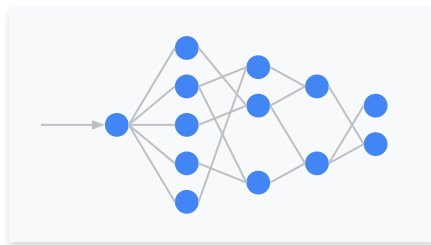


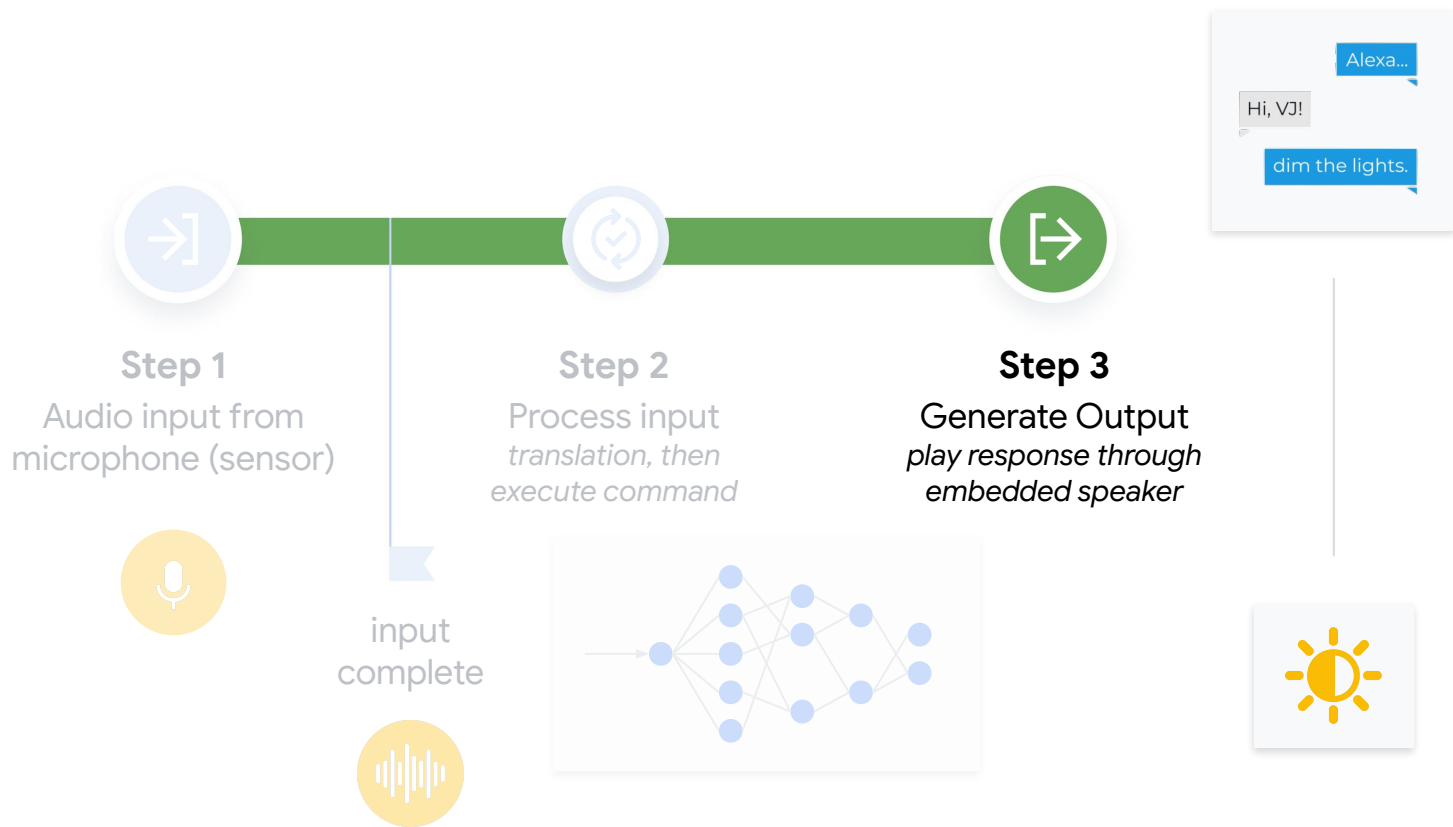
Step 2

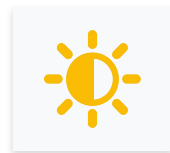
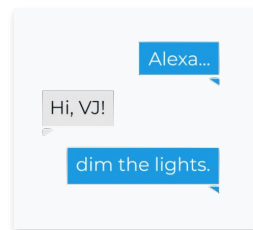
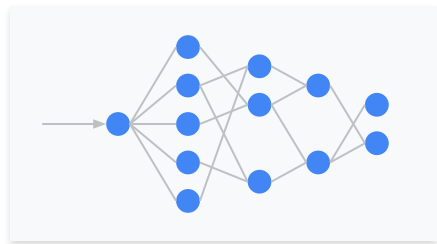
Process input
translation, then
execute command



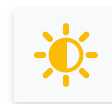
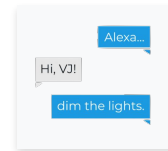
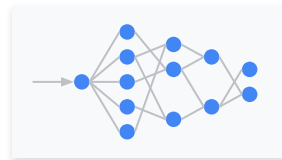
input
complete







Questions



- How do we **capture** the data to feed into the neural network?
- How do you **design** the neural network to take in the speech signal?
- What **dataset** does the neural network need to be trained?
- How do we **pre-process** the data for neural network inference?
- How do you **post-process** the neural network output?
- How do you make sure there is no **bias** in the dataset?
- How do you **deploy** this on the microcontroller?

TinyML Application Areas



Home

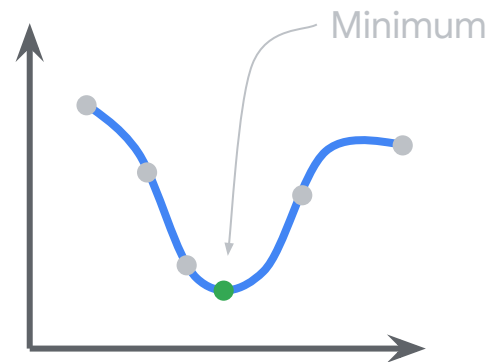
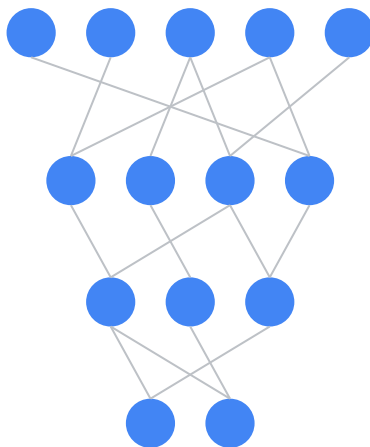


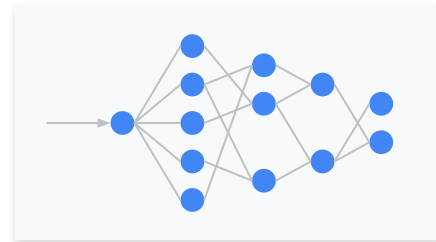
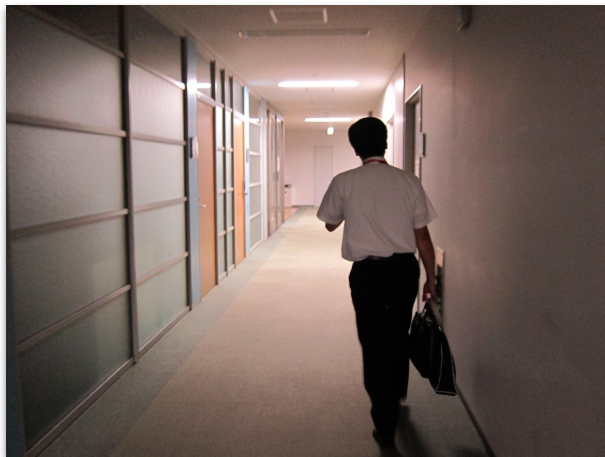
Office

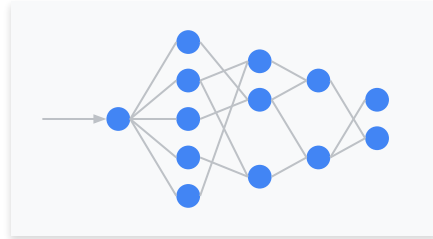
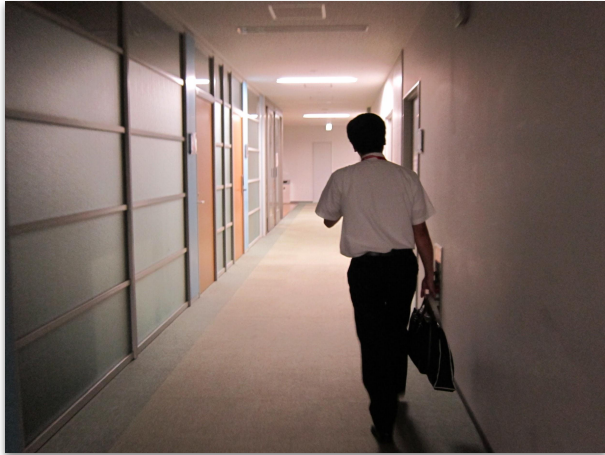


Industry

Image Sensors
Thermal, Image

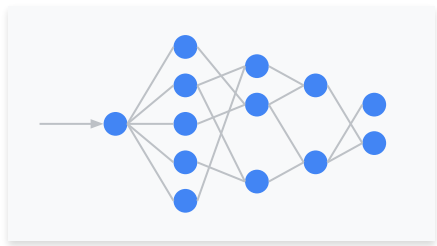






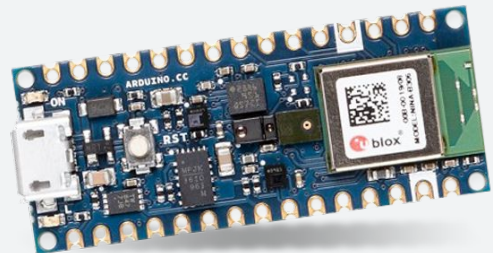
ML Model Evolution

- **MobileNet (2015)**
 - **MobileNetv1**
 - 70.6% accuracy
 - 16.9MB in size

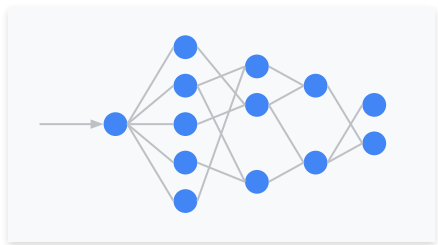


Problem

Our board (in your kit for Course 3) only has **256KB** of RAM (memory) yet **MobileNetv1** needs **16.9MB**!



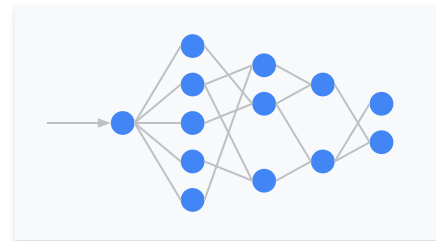
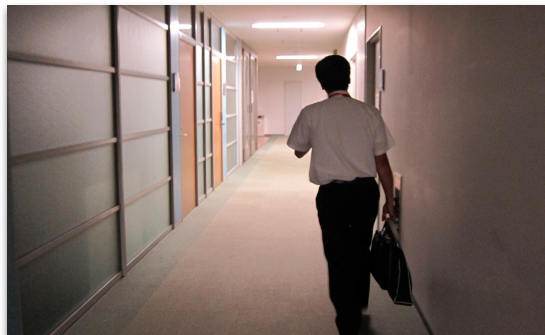
How do we engineer a **TinyML** vision network?



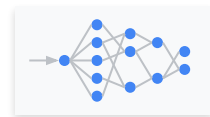
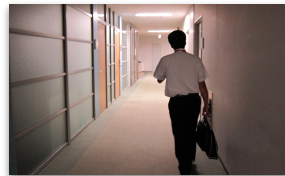
Think:

- Compute **operations**
- Operator **numerics**
- **Compression**
methods (e.g.,
pruning, quantization)

What is the **end-to-end** workflow?



Questions

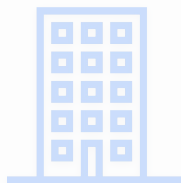


- How do we **capture** the data to feed into the neural network?
- How do you **design** the neural network to take in the image?
- What **dataset** does the neural network need to be trained?
- How do we **pre-process** the data for neural network inference?
- How do you **post-process** the neural network output?
- How do you make sure there is no **bias** in the dataset?
- How do you **deploy** this on the microcontroller?
- *How do we ensure that the neural network is **resilient**?*
- *How do we get the neural network to **train faster**?*

TinyML Application Areas



Home

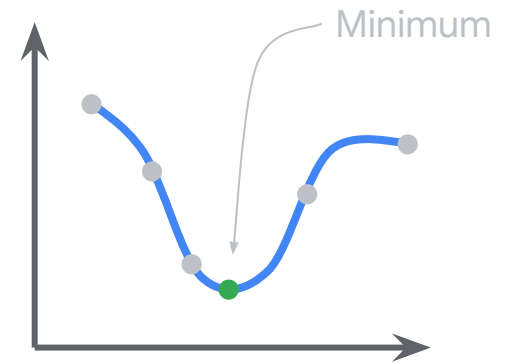
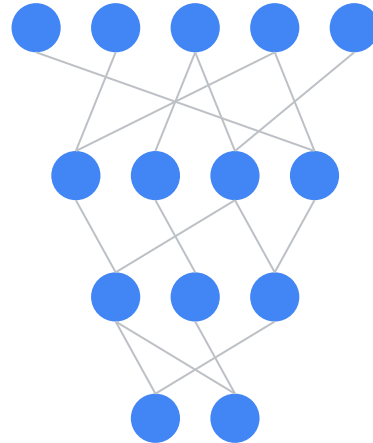


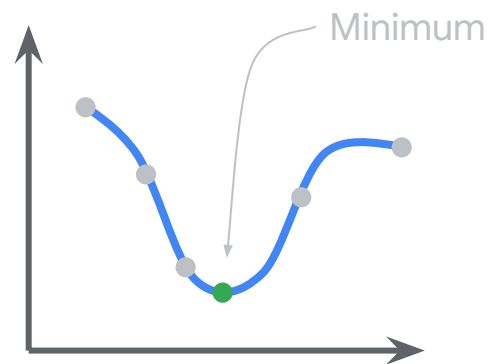
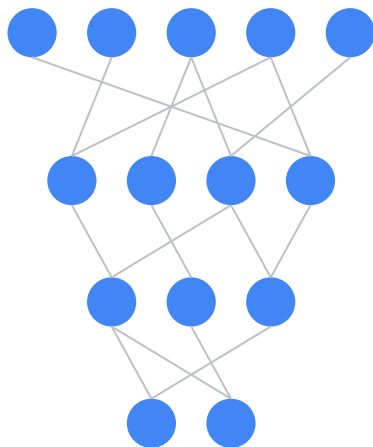
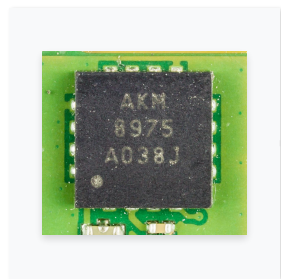
Office

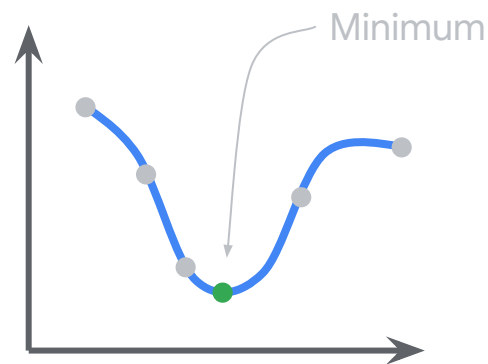
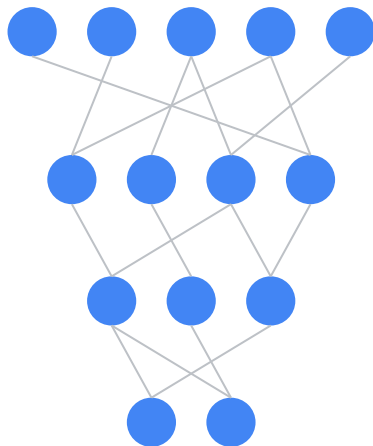


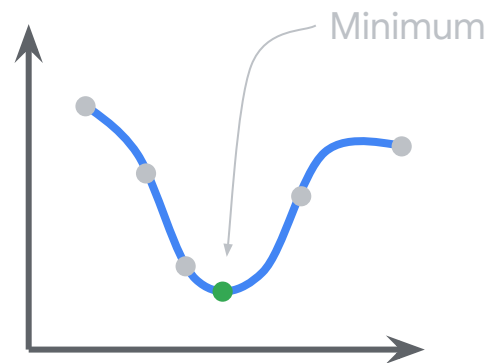
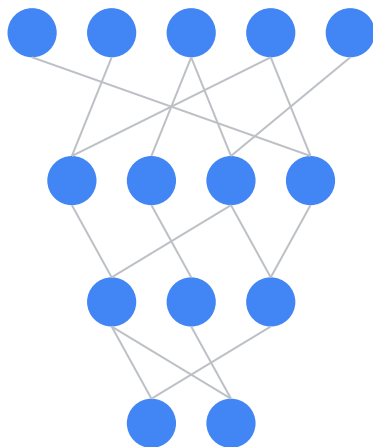
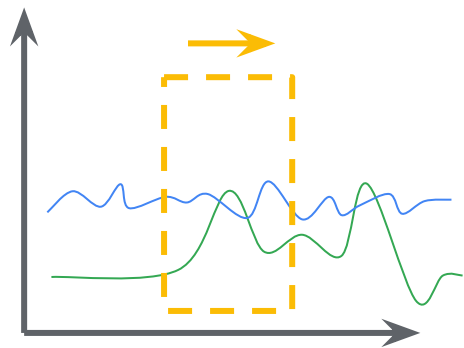
Industry

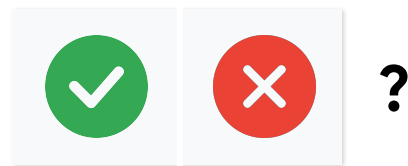
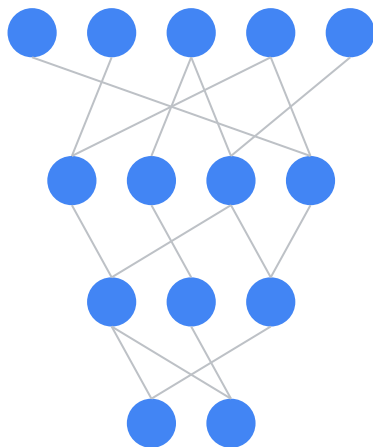
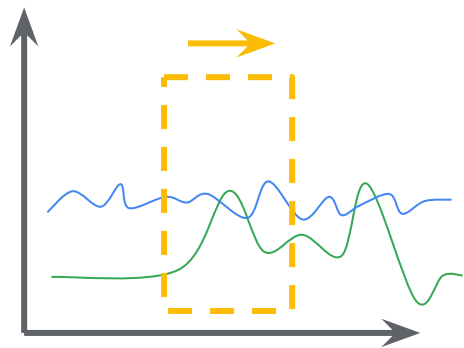
Motion Sensors
Gyroscope, Radar,
Accelerometer

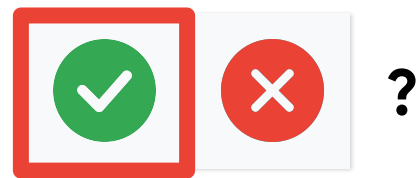
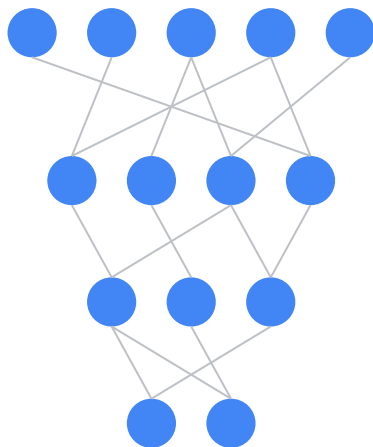
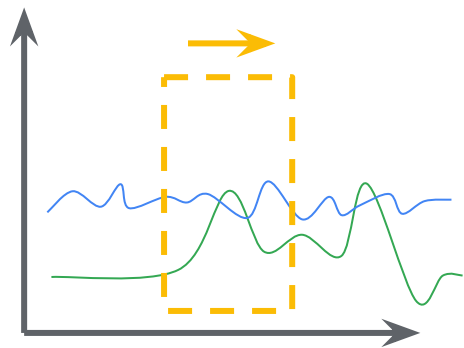


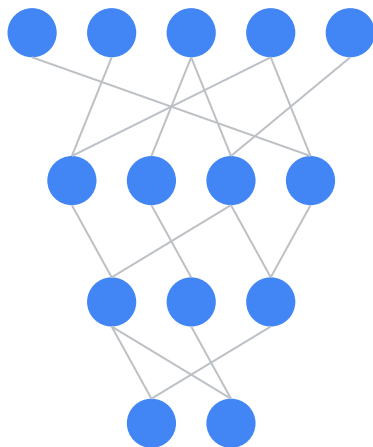
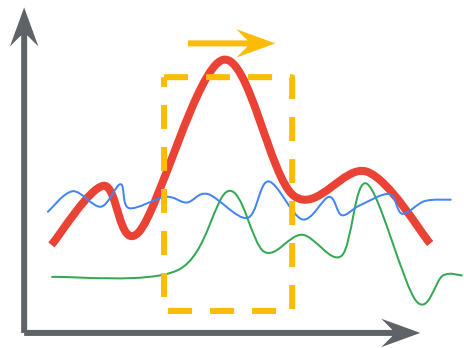


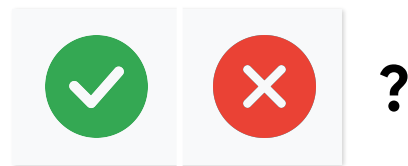
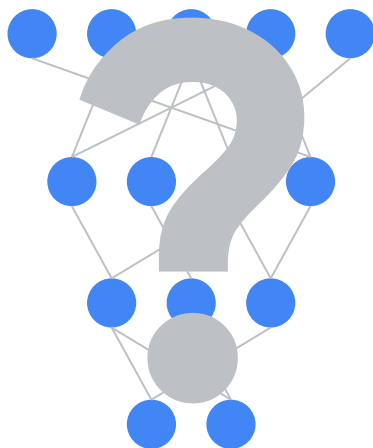
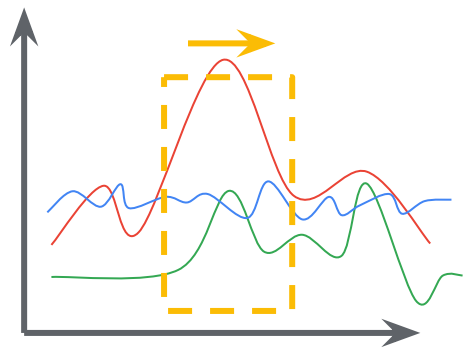




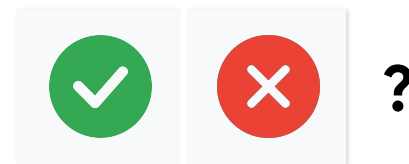
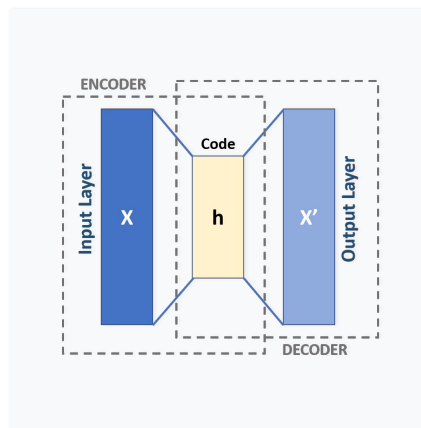
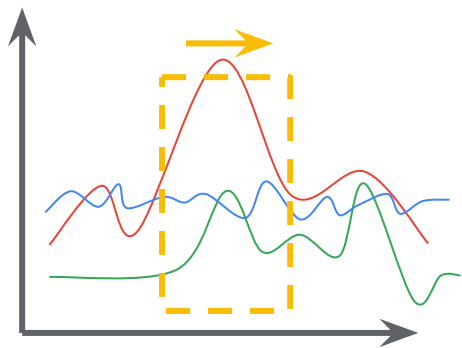




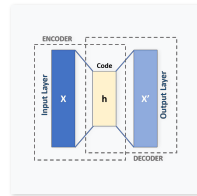
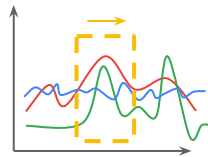




Autoencoder



Questions



- How do we **capture** the **time-series** data to feed into the neural network?
- How do we **pre-process** the data for neural network inference?
- How do you **design** the **autoencoder** neural network?
- What **dataset** does the neural network need to be trained?
- How do you **post-process** the neural network output?
- How do you make sure there is no **bias** in the dataset?
- How do you **deploy** this on the microcontroller?