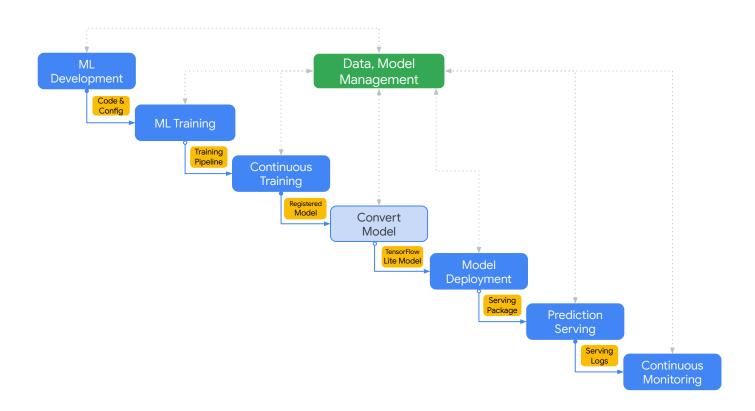
ML Frameworks and The Lay Of The Land

The MLOps Process for **TinyML**



The MLOps Personas



ML Engineer



ML Researcher



Data Scientist



Data Engineer



Software Engineer



DevOps



Business Analyst

ML Frameworks















TensorFlow

Google's **TensorFlow**Open source ML framework
Released in 2015



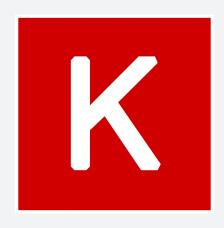
PyTorch

Developed by **Facebook** Al Research Open source ML framework *Released in 2017*

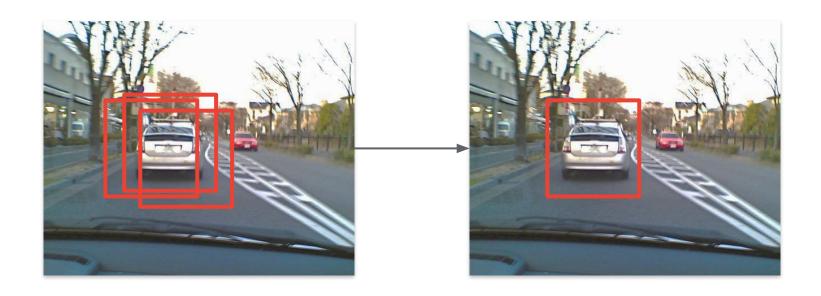


Keras

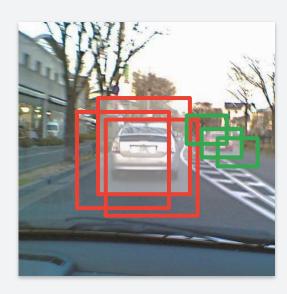
Primarily supported by **Google**Open source DL framework
Released in 2015



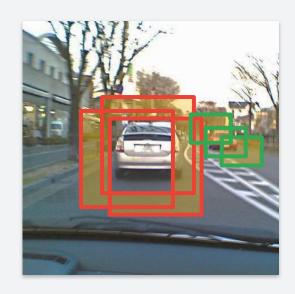
ML Framework	K		C
Ease of use	User-friendly	Incomprehensive API	Integrated with Python
API Level	High-level API	Both High/Low-Level	Low-level API
Architecture	Simple, readable, concise	Not easy to use	Complex
Speed	Slow	Fast	Fast
Debugging	No need to debug	Difficult	Helpful capabilities
Creator	(Not sole library)	Google	Facebook



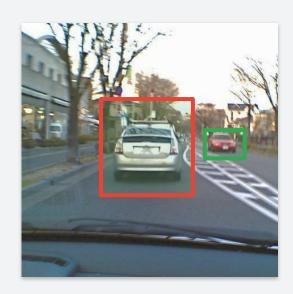
1. Select boxes with highest objectiveness score

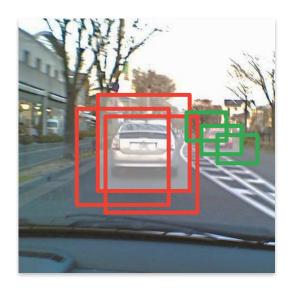


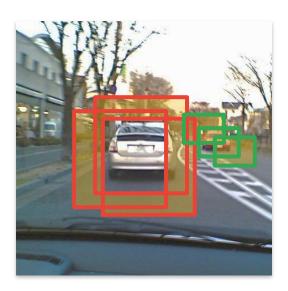
- Select boxes with highest objectiveness score
- Compare overlap and remove boxes with >50% overlap

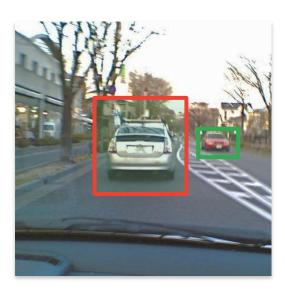


- Select boxes with highest objectiveness score
- Compare overlap and remove boxes with >50% overlap
- Move to next highest objectiveness score and return to Step 2.

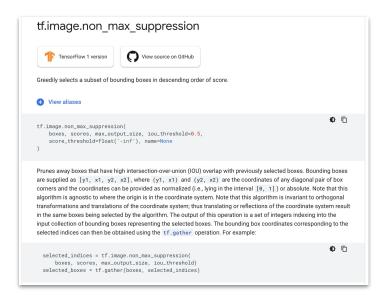














 $\mbox{torchvision.ops.nms} (\mbox{boxes: torch.Tensor, scores: torch.Tensor, iou_threshold: float}) \rightarrow \mbox{torch.Tensor [SOURCE]}$

Performs non-maximum suppression (NMS) on the boxes according to their intersection-over-union (IoU).

NMS iteratively removes lower scoring boxes which have an IoU greater than iou_threshold with another (higher scoring) box.

If multiple boxes have the exact same score and satisfy the IoU criterion with respect to a reference box, the selected box is not guaranteed to be the same between CPU and GPU. This is similar to the behavior of argsort in PyTorch when repeated values are present.

Parameters

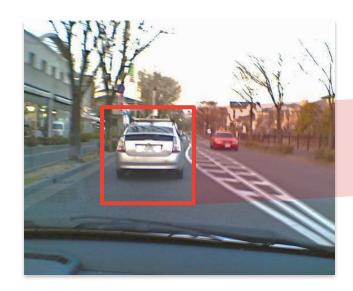
- boxes (Tensor[N,4])) boxes to perform NMS on. They are expected to be in (x1, y1, x2, y2) format with 0 <= x1 < x2 and 0 <= y1 < y2.
- scores (Tensor[N]) scores for each one of the boxes
- iou_threshold (float) discards all overlapping boxes with IoU > iou_threshold

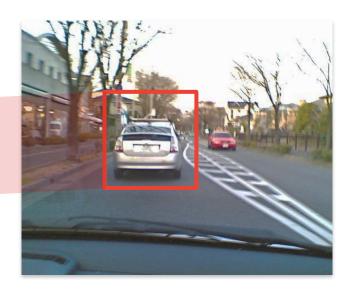
Returns

int64 tensor with the indices of the elements that have been kept by NMS, sorted in decreasing order of scores

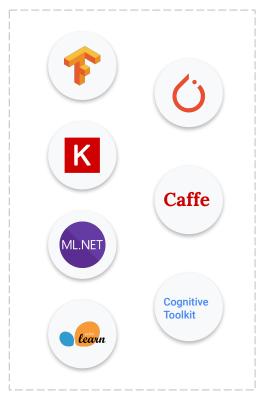
Return type

Tensor





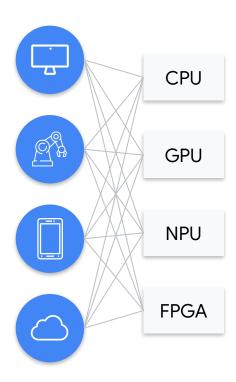
Training Framework



Training Framework



Deployment Target

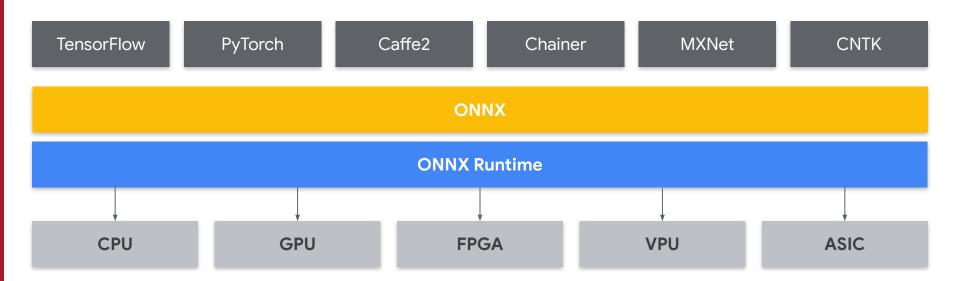


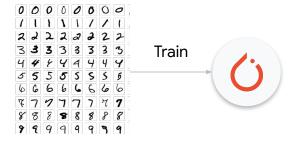
Training Framework

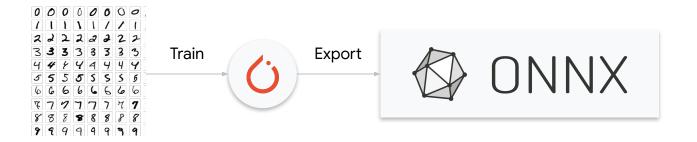


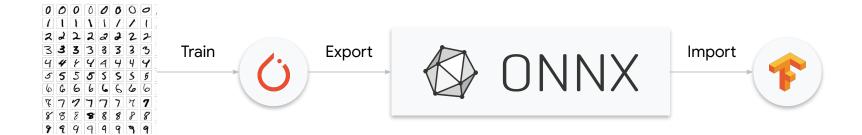
Deployment Target











Export and Model Portability Issues

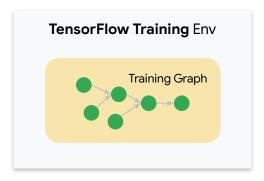
 Ops may (not) be supported evenly across all systems

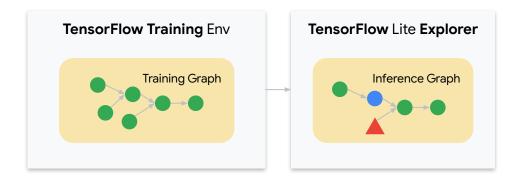


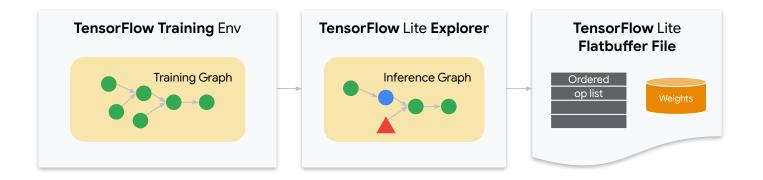
Export and Model Portability Issues

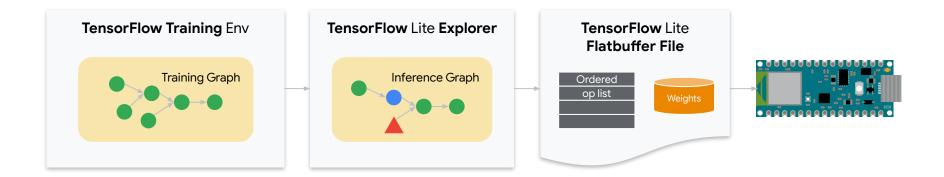
- Ops may (not) be supported evenly across all systems
- Frameworks implement their own library functions (e.g., NMS for detection)

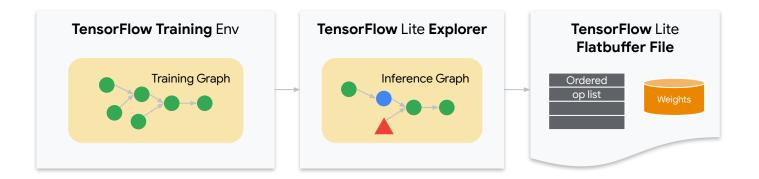












- More robust toolchain for debugging and optimization
- Get to reuse the existing optimization infrastructure