

# TinyML Sensor Ecosystem



# Traditional ML Sensors



# Embedded Sensor **Ecosystem**



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# Inertial Measurement Unit (**IMU**)

Accelerometer

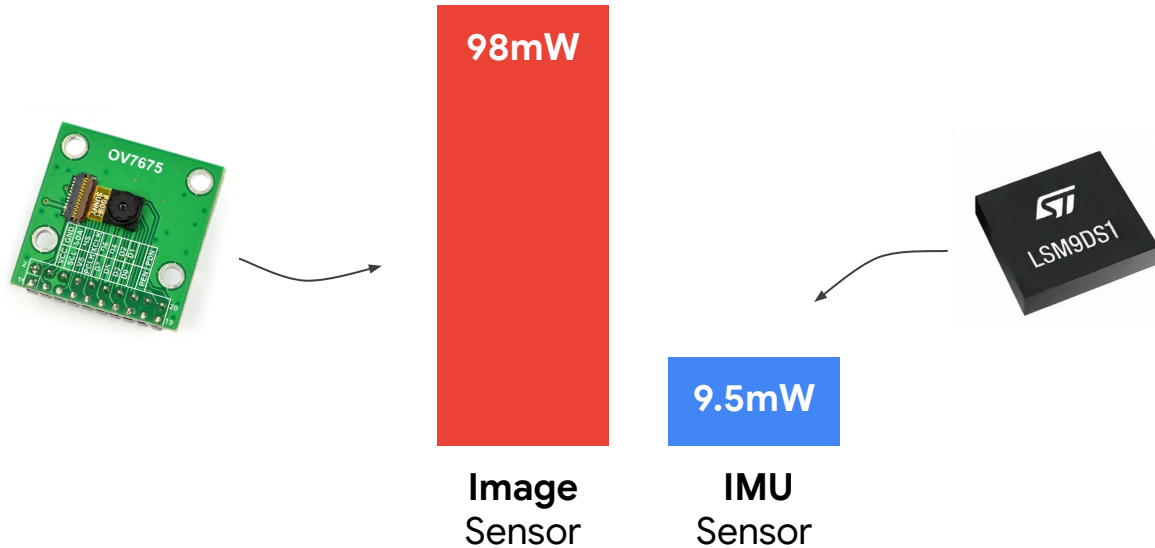


Gyroscope



Magnetometer

# Low Power Sensors



# Size, Weight, Price



# Applications of an IMU





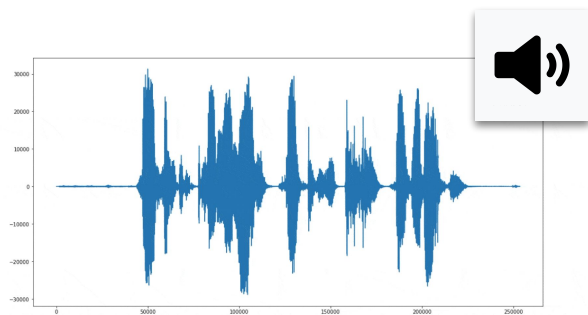
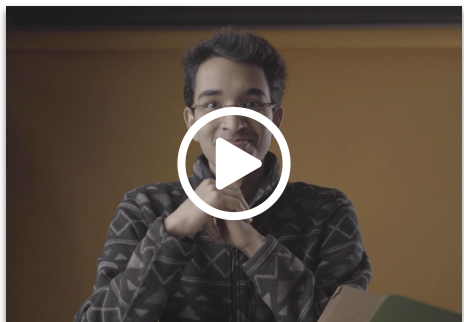
# Challenges

1. Interpretability

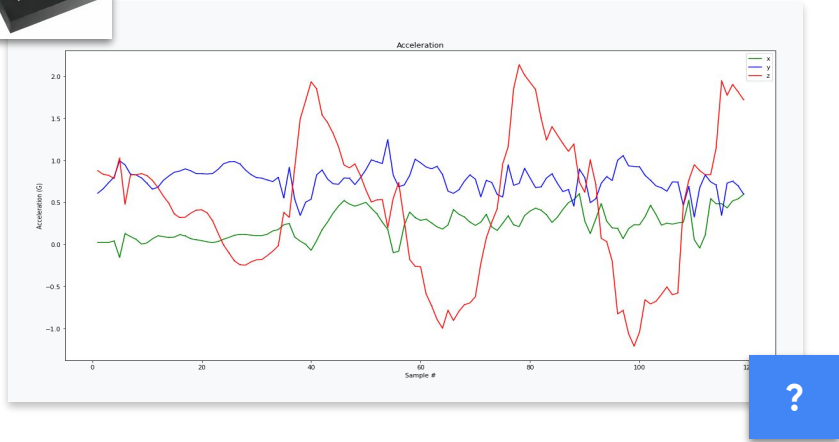
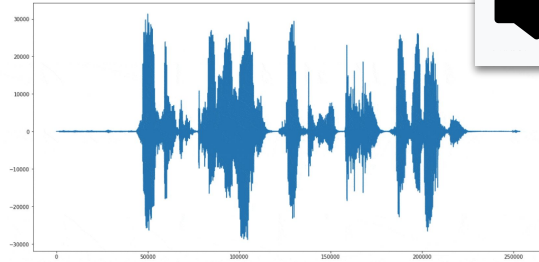
2. Sensor Drift

3. Deployment Sensitivity

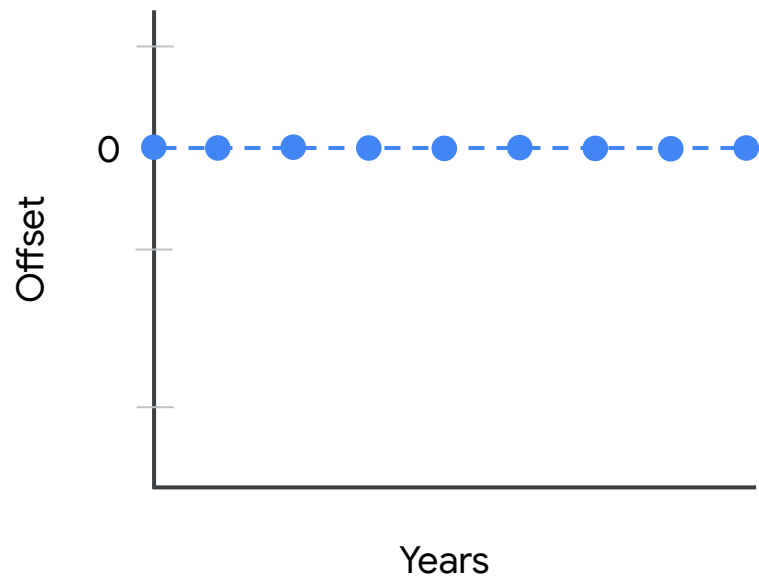
# Human interpretability



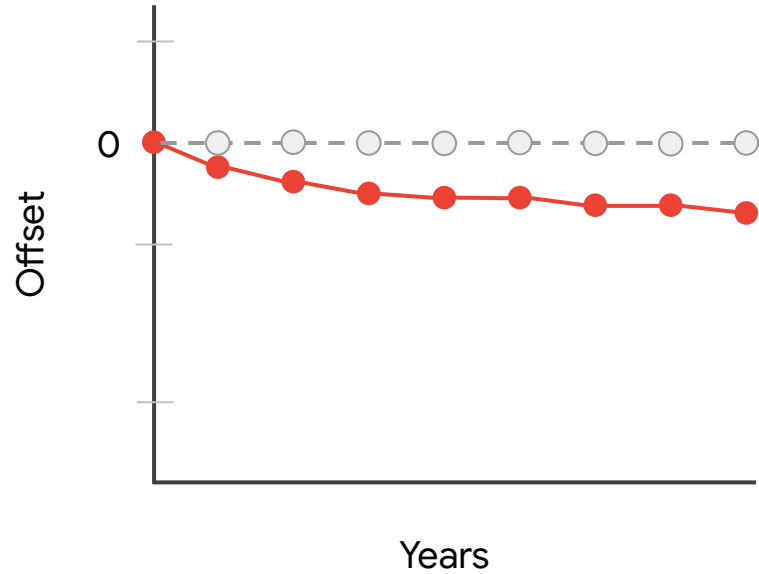
# Human interpretability



# Ideal Sensor

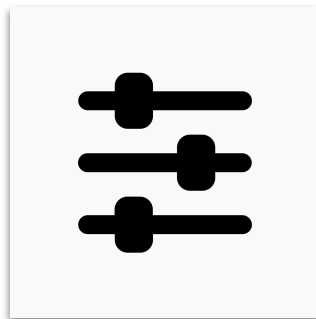


# Sensor Drift

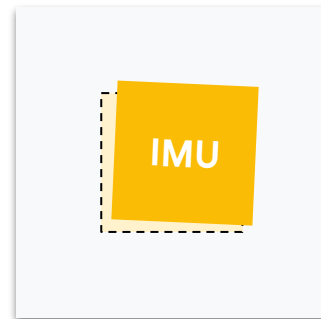


# Deployment Sensitivity

There are **minor differences** in deployment for sensors that can cause a **bias** in the data.



Parameter Tuning



Misalignment