

Nature Inspired Search and Optimisation

Advanced Aspects of Nature Inspired Search and Optimisation

Lecture 3: Optimization Problems and Local Search Algorithms

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What we learned and what we will learned

- What we learned last week:
 - Randomised algorithms
 - The important of randomness in algorithms
- We will learn this week:
 - What is optimisation
 - How to solve optimisation problems using:
 - Randomised algorithms
 - Local search
 - Stochastic local search algorithms.
- Note: Nature Inspired Optimisation and Search algorithms \in Randomised algorithms, esp. Stochastic Local Search algorithm \in Heuristic algorithms \in Search and enumeration algorithms

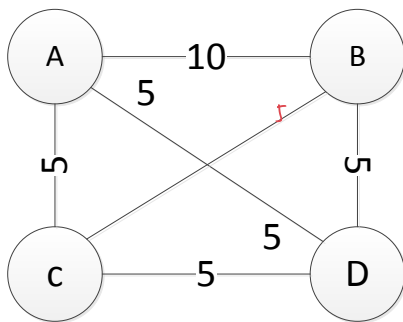
Outline of Topics

- 1 Travelling salesman problem
- 2 Solving optimisation problems
 - Solving TSP problems using heuristic algorithms
 - Randomised algorithms
 - Local search search
- 3 Conclusion

Travelling salesman problem (TSP)

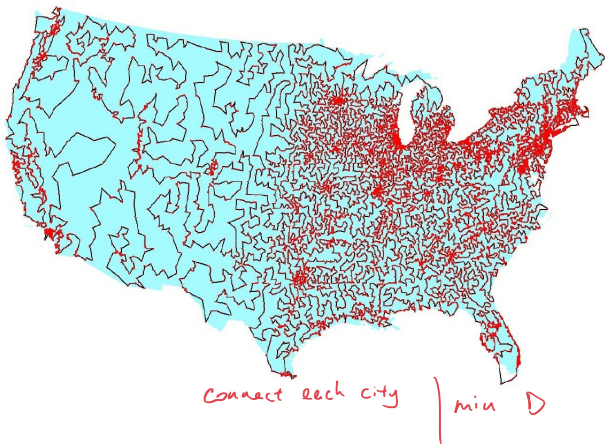
Travelling salesman problem (TSP):

- Given: a list of cities and the distances between each pair of them,
- Sought: the shortest route that visits each city exactly once and returns to the origin city



True TSP example

Optimal solution for “usa13509” from [TSPLIB](#). Cities with population at least 500 in the continental US (in 1995). In total 13509 cities.



Kaggle Traveling Santa 2018

Kaggle Traveling Santa 2018.

Travelling salesman problem (TSP)

- Mentioned in a travelling salesman handbook in 1832
- Formally defined by the Irish mathematician William. R. Hamilton
- One of the most prominent and widely studied combinatorial **optimisation problems** in computer science and operations research
- Many optimisation problems, e.g., Printed Circuit Boards (PSB) design can be formulated as TSP or its variations
- Conceptually simple but **computationally difficult**: best benchmark for development and evaluation of combinatorial **optimisation algorithms**

What is optimisation

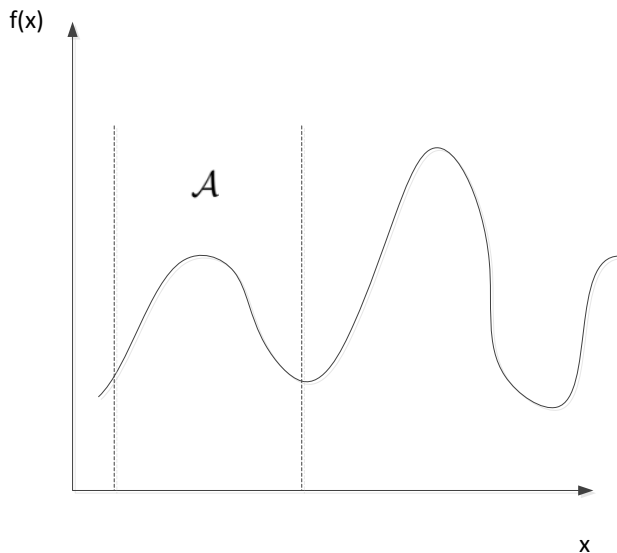
- Optimization: to find the best or optimal solution to a problem
- Examples are everywhere:
 - Portfolio optimisation: you have an investment portfolio, e.g., cash and shares, you know the potential return and financial risk of each asset.
multi-objective (with arrows pointing to 'return' and 'risk')
 How to build the perfect investment portfolio to maximise the return while keep risk in control?
 - Engineering optimisation: you are required to design a product with some materials. How to design a product with minimal materials while keeping the quality?

Max (above 'return') and *Min* (above 'risk')


Definition of optimisation

- Definition:
 - Given: a **function** $f(x) : \mathcal{A} \rightarrow \mathbb{R}$ from some **set** \mathcal{A} to the real numbers
 - Sought: an element x^* in \mathcal{A} such that $f(x^*) \leq f(x)$ ("minimisation") or $f(x^*) \geq f(x)$ ("maximisation") for all x in \mathcal{A} .
- Function $f(x)$ is called **objective function**, or cost function (minimisation), fitness function (maximisation and in Evolutionary Computation)
- \mathcal{A} is called **feasible set**, which is some subset of the Euclidean space specified by a set of constraints
- The domain \mathcal{A} of $f(x)$ is called the **search space**, while the elements of \mathcal{A} , e.g., $x \in \mathcal{A}$ are called **candidate solutions** or feasible solutions.

Definition of optimisation



Categories of optimisation problems

- Depends on the nature of objective function:
 - Linear vs non-linear
 - Linear function:
 - **Additivity**: $f(x + y) = f(x) + f(y)$ *linear programming*
 - **Homogeneity**: $f(\alpha x) = \alpha f(x)$ for all α
 - If it is non-linear:
 - Convex vs non-convex 
 - Question: which is more difficult?
 - Multi-objective vs single objective
 - Constrained vs non-constrained
- Depends on the nature of solutions:
 - Continuous vs Discrete (also known as a combinatorial optimization)

Question

- **Question 1:** What kind of optimisation problem is TSP? *non-linear*
- **Question 2:** What algorithm you can use to solve TSP?

Optimisation algorithms

- Mathematical programming algorithms, e.g., linear programming
- Search and enumeration algorithms
 - Brute force algorithms, enumerating all possible candidate solutions and check
 - Improved brute force algorithms, e.g., branch and bound algorithms
 - Heuristic algorithms *within a reasonable time frame*
 - Randomised algorithms
 - Local search, e.g., hill climbing and greedy search

Solving TSP

Answer to Question 2: Solve TSP using:

- Mathematical programming algorithms, e.g., [linear programming](#)
- Brute force or improved brute force algorithm, e.g., [branch and bound](#)
- **Heuristic algorithms**

Why heuristic algorithms for TSP?

- TSP is difficult for other algorithms
 - Brute force algorithms: complexity is $O(n!)$, the factorial of the number of cities.
 - Improved brute force algorithms, e.g., [branch and cut algorithms](#): $O(1.9999^n)$ [1] $n! \rightarrow 2^n$
 - Still time consuming, e.g., for usa13509, the running time required is 2^{13509}
 - In fact, usa13509 was solved in 1998 by Rice University using two clusters of 44 CPUs, took approximately three months from start to finish ([see News](#))
 - The largest instance of TSP problem is an instance in TSPLIB of 85,900 cities, taking over 136 CPU-years [2]!
 - Linear programming: essentially an integer linear programming problem, itself is a NP-hard problem (See [Why LP cannot solve large instances of NP-complete problems in polynomial time](#))

[1] Woeginger, G.J. (2003), "Exact Algorithms for NP-Hard Problems: A Survey", Combinatorial Optimization: Eureka, You Shrink! Lecture notes in computer science, vol. 2570, Springer, pp. 185-207. [2] Applegate, D. L.; Bixby, R. M.; Chvatal, V.; Cook, W. J. (2006), The Traveling Salesman Problem, ISBN 0-691-12993-2.

Randomised algorithms

- Two categories of randomised algorithms:
 - Using random numbers to **find a solution** to a problem (today)
 - Using random numbers to **improve a solution** to a problem (next lecture)
- For the first category, two representative simple algorithms:
 - Las Vegas algorithm
 - Monte Carlo algorithm ✓ *no optimised target*
- **Question 1:** Which one should we choose?
- **Question 2:** How to generate random solutions to TSP?

Array *random permutation*

fully-connected graph

{
ABCD
BACD
⋮
}

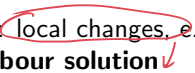
Randomised search algorithms

- We will demonstrate how randomised algorithm solve a small TSP problem: 48 capitals of the US (called ATT48), of which the known optimal solution by some brute force algorithms search is 10628
- Let's run the code
- Observation: Randomised search algorithms such as Monte Carlo return bad results
- **Question:** Why randomised search algorithms cannot solve TSP?

Randomised search algorithms

- Question: Why randomised search algorithms cannot solve TSP?
- Answer: This is because the number of good solutions of TSP is just a **very tiny portion** of a vast number of all feasible solutions – to find a needle in a haystack *vast search space*
- Reminder: Heuristic algorithms
 - Randomised algorithms *X*
 - Local search, e.g., hill climbing and greedy search

Local search algorithms

- **Local search:** a heuristic algorithm for solving hard optimization problems
 - **Idea:** start with an initial guess at a solution and **incrementally improve it** until it is one
 - **Incremental improvement:** local changes, e.g., the algorithm iteratively moves to a **neighbour solution** 
 - Search → **Neighbour solution:** Depends on the definition of a neighbourhood relation on the search space, but generally based on similarity (distance) measure
 - Question: Why use neighbour solutions? What are the drawbacks?

Generic local search algorithm

Generic local search algorithm

```
①  $x_0 :=$  generate initial solution  
   terminationflag := false  
    $x := x_0$   
② while (terminationflag != true)  
       Modify the current solution to a neighbour one  $v \in \mathcal{A}$   
       If  $f(v) < f(x)$  then  $x := v$   
       If a termination criterion is met: terminationflag := true  
Output  $x$ 
```

Note: termination criterion could be maximum iteration is reached or no improvement for a certain iterations.

Hill climbing algorithm

- One of the simplest local search algorithms
- Hill climbing is an algorithm that more like “climbing Everest in thick fog with amnesia”
- An iterative algorithm:
 - Starts with an arbitrary solution to a problem,
 - Iteratively searches a better solution from the current solution's **immediate neighbour solutions**
 - Immediate neighbour solutions: most similar solutions to the current solution.
- Two types of hill climbing:
 - 1) • **Simple hill climbing**: chooses the **first** better solution
 - 2) • **Steepest ascent/descent hill climbing**: compares all neighbour solutions and chooses **the best** solution – greedy search

Simple hill climbing algorithm

Simple hill climbing algorithm

$x_0 :=$ generate initial solution

terminationflag $:=$ false

$x := x_0$

while (terminationflag \neq true)

 Modify the current solution to a **immediate** neighbour one $v \in \mathcal{A}$

 If $f(v) < f(x)$ then $x := v$

 If a termination criterion is met: terminationflag $:=$ true

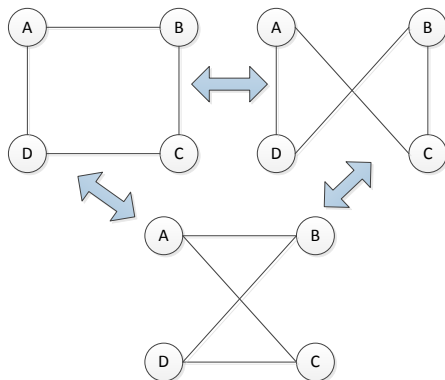
Output x

Hill climbing for TSP problem

- **Question:** How to construct the **immediate neighbour solutions** of the current solution for TSP?

Let's take a look at some simple examples

- 2-3 cities: only one solutions
- 4 cities: 3 solutions
- **Question:** How those tours of the 4 cities TSP differ?



Conclusion

- Optimisation problems can be very difficult
- Heuristic algorithms, esp. local search are useful for difficult optimisation problems
- Optimisation is all about exploration and exploitation
- Randomness can facilitate exploration, but not exploitation (local search)