Data Mining / Intelligent Data Analysis: Metrics

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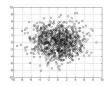
Overview

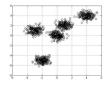
- Motivation
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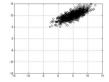


Discovering Structure in Data

Figure: Examples of structured data: spherically distributed single cluster (left), multiple-source data (centre), shifted correlated data (right)







- For example, each data point might be a vector of measurements from an array of sensors in a structure or a train. The clusters in the centre figure might correspond to different states of the structure/train
- Clustering discovers structure in multi-source data (center)



What is a metric?

- Let X be a set of vectors. $X \times X$ denotes the set of pairs $X \times X = \{(x, y) : x, y \in X\}$
- A **metric** is a function $d: X \times X \to \mathbb{R}^+$ such that

$$d(x,y) \geq 0, \forall x, y \in X \tag{1}$$

$$d(x, y) = 0$$
, if and only if $x = y$ (2)

$$d(x,y) = d(y,x), \forall x, y \in X$$
 (3)

$$d(x,y) \leq d(x,z) + d(z,y), \forall x,y,z \in X$$
 (4)

Property (3) indicates that a metric must be bf symmetric. Property (4) is the **triangle inequality**.

- ullet R⁺ is the set of **positive** real numbers
- A metric is sometimes called a **distance function**



The Euclidean metric

• Suppose $X = \mathbb{R}^N$ is N-dimensional space and $x, y \in X$, where

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix} \tag{5}$$

The **Euclidean metric** is given by

$$d_2(x,y) = \sqrt{\sum_{n=1}^{N} (x_n - y_n)^2}$$
 (6)

This is the normal notion of distance in Euclidean space



The **squared** Euclidean metric

- Sometimes the square root is ommitted.
- The results is the squared Euclidean metric

$$d_2^{sq}(x,y) = \sum_{n=1}^{N} (x_n - y_n)^2$$
 (7)

 This is useful, for example, if all that is needed is to find the closest point to a reference point

The L^p metrics

- The Euclidean metric is one of a family of metrics called the L_p metrics, denoted by d_p
- In general, for any positive integer p

$$d_p(x,y) = (\sum_{n=1}^{N} (x_n - y_n)^p)^{\frac{1}{p}}$$
 (8)

The cases p=1 and $p=\infty$ are most common

$$d_1(x,y) = \sum_{n=1}^{N} |x_n - y_n|$$
 (9)

$$d_{\infty}(x,y) = \max_{n=1,\dots,N} |x_n - y_n| \tag{10}$$

 d_1 is referred to as the **City Block** metric

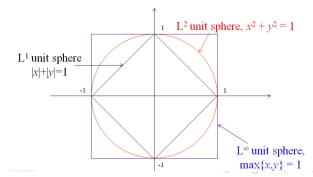


Unit spheres for d_1 , d_2 and d_{∞}

• The **unit sphere** for a metric *d* is the set

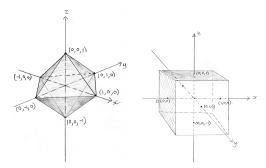
$$U_d = \{x : d(x,0) = 1\}$$
 (11)

Figure: Unit spheres for d_1 , d_2 and d_{∞}



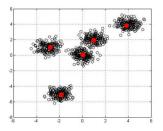
Unite spheres (3D)

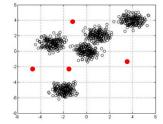
Figure: Unit spheres in 3-dimensions for the City-Block L^1 metric (left) and L^∞ metric (right)



Representing clusters as centroids

Figure: Good (L) and poor (R) representation of clusters with centroids





- Centroids are data points located to represent a set of clusters
- Requires correct number of centroids in correct locations
- In general, the number and location of the clusters is unknown



Distortion

- Distortion is a measure of how well a set of centroids $C = \{c_1, ..., c_K\}$ fits a set of data $X = \{x_1, ..., x_N\}$
- Let d be a metric
- Let $c_{i(n)}$ be the closest centroid to x_n (n = 1, ..., N)

$$d(x_n, c_{i(n)}) = \min_{k=1,\dots,K} d(x_n, c_k)$$
 (12)

• The *Distortion* for the centroids *C* relative to the data set *X* is

$$Dist(C, X) = \frac{1}{N} \sum_{n=1}^{N} d(x_n, c_{i(n)})$$
 (13)

Distortion

- Dist(C, X) is the average distance between x_n and its closest centroid
- The best centroid set is the set \bar{C} where

$$Dist(\bar{C}, X) = min_C Dist(C.X)$$
 (14)

- How do we find \bar{C} the best set of centroids?
- In general we can't, but we can use a clustering algorithm to find a set of centroids that is locally optimal
- We'll see how to do this in the next lecture K-means clustering



Summary

- Motivation cluster analysis
- Properties of a metric
- The L^p family of metrics
- Centroids and distortion