VECTORS:

 $e = [e_0, e_1, e_2]$: Vector which represents the eye (where the camera is located).

 $t = [t_0, t_1, t_2]$: Vector which defines the direction in which the eye is looking and the length between the eye and the projection plane.

 $p = [p_0, p_1, p_2]$: Vector which represents the position of a point in space.

THE PROJECTION PLANE:

It is a plane which is located at the position e + t and its normal vector is t. Its general form can be written as:

$$t_0(x - (e_0 + t_0)) + t_1(y - (e_1 + t_1)) + t_2(z - (e_2 + t_2)) = 0$$

THE EYE-POINT LINE:

In real life light travels linearly as it gets reflected on surfaces. In this case, the light reflected from the point towards the eye can be represented with a line, and it will get projected into the projection plane. It's vectorial form can be written as:

$$e + a(p - e)$$

Where a is a random scalar.

Projecting a point into the projection plane means finding which a coefficient makes the resulting vector land on the plane. To do this, we have to solve a system of equations using the parametric form of this line:

$$x + 0y + 0z - (p0 - e0)a = e0$$

 $0x + y + 0z - (p1 - e1)a = e1$
 $0x + 0y + z - (p2 - e2)a = e2$

EXAMPLE:

$$e = [2, 2, 2]$$

 $t = [-0.42, -0.57, 0.71]$
 $p = [5, -3, 7]$

```
\mathsf{eq} \ = \ [\mathsf{t}(1),\ \mathsf{t}(2),\ \mathsf{t}(3),\ 0,\ ((\mathsf{e}(1)+\mathsf{t}(1))*\mathsf{t}(1)\ +\ (\mathsf{e}(2)+\mathsf{t}(2))*\mathsf{t}(2)\ +\ (\mathsf{e}(3)+\mathsf{t}(3))*\mathsf{t}(3));\ 1,\ 0,\ 0,
(-(p(1) - e(1))), e(1); 0, 1, 0, (-(p(2) - e(2))), e(2); 0, 0, 1, (-(p(3) - e(3))), e(3)]
eq =
  -0.4200
            -0.5700
                           0.7100
                                              0
                                                    0.4454
   1.0000
                                     -3.0000
                                                   2.0000
                                 0 5.0000
                                                  2.0000
          Θ
               1.0000
          0
                           1.0000 -5.0000
                                                    2.0000
octave:7> res = rref(eq)
res =
    1.0000
                                                    2.5868
          0
               1.0000
                                  0
                                              0
                                                    1.0220
                           1.0000
                                                    2.9780
          0
                                                    0.1956
                      0
                                  0
                                        1.0000
```

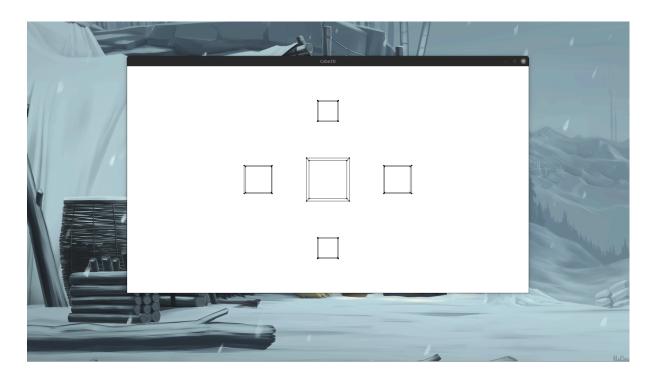
The solution is the vector p' = [2.5868, 1.0220, 2.9780] in which a = 0.1956.

SHOWING IT ON SCREEN:

To show the view plane on screen in a way that the direction you point at is the center of the screen, it is needed to displace the screen view. For example:

- If we are projecting a scene into a screen defined with coordinates x and y, then we have to move the screen view relative to where the vector [0, 0, 1] lands on the view plane (let's call this projection v) and where the camera is currently looking at.
- In other words, we'd have to find the vector v (e + t) and move the screen view according to its x and y components.

RESULTS:



CONCLUSION:

This method is kinda tricky and it might be computationally inefficient since you have to solve a system of 4 equations for every point in the scene. It's easier to just move the scene and let the view stay in place.