

示例3——语音导航

机器人端（SSH登录）：

1、启动底盘

```
roslaunch gohi_hw gohi_hw.launch
```

2、启动激光雷达

```
roslaunch rplidar_ros rplidar.launch
```

3、启动定位

```
roslaunch gohi_2dnav move_base_amcl_5cm.launch
```

PC端：

4、开启rviz、装载参数模型

```
roslaunch rviz rviz
```

5、修改位置点

```
gedit /home/ros/gothi_ws/src/gothi_gowhere/scripts/voice_to_site.py
```

6启动语音导航

```
roslaunch gothi_gowhere voice_to_specific_point.launch
```

7、启动语音识别

```
roslaunch simple_voice simple_voice_default.launch
```