Homework Assignment 2

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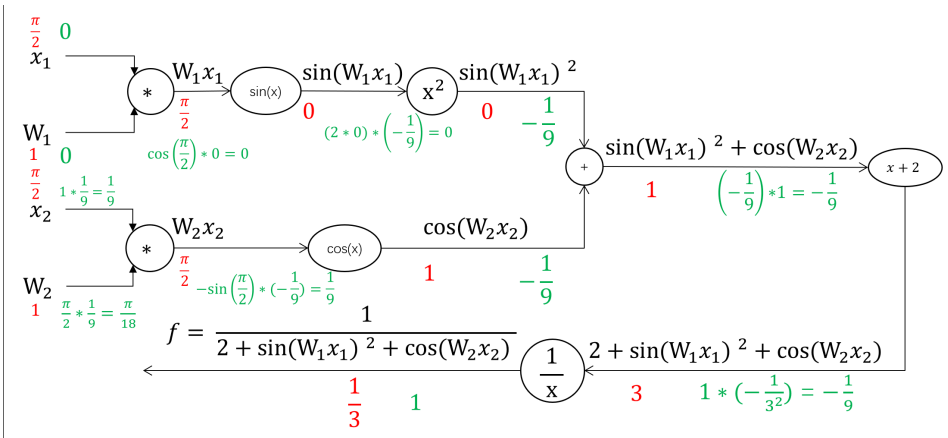
Problem 1 (Practice of scalar-based backpropagation)

(a)



$f(x) = \frac{1}{x}$ $\frac{df}{dx} = -\frac{1}{x^2}$

$f(x) = 2 + x$ $\frac{df}{dx} = 1$

$f(x,y) = x + y$ $\frac{df}{dx} = 1$ $\frac{df}{dy} = 1$

$f(x) = x^2$ $\frac{df}{dx} = 2x$

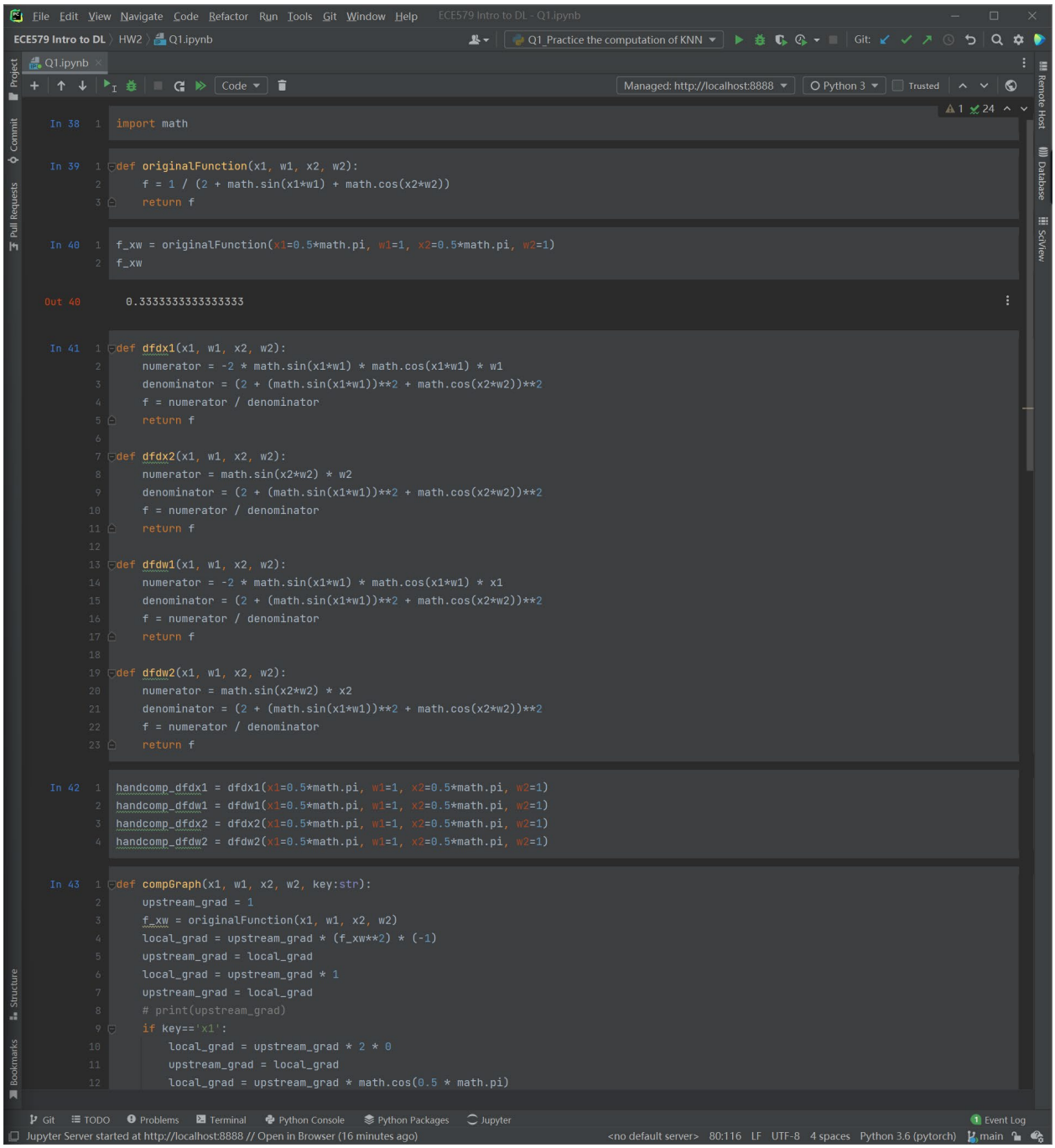
$f(x) = \sin(x)$ $\frac{df}{dx} = \cos(x)$

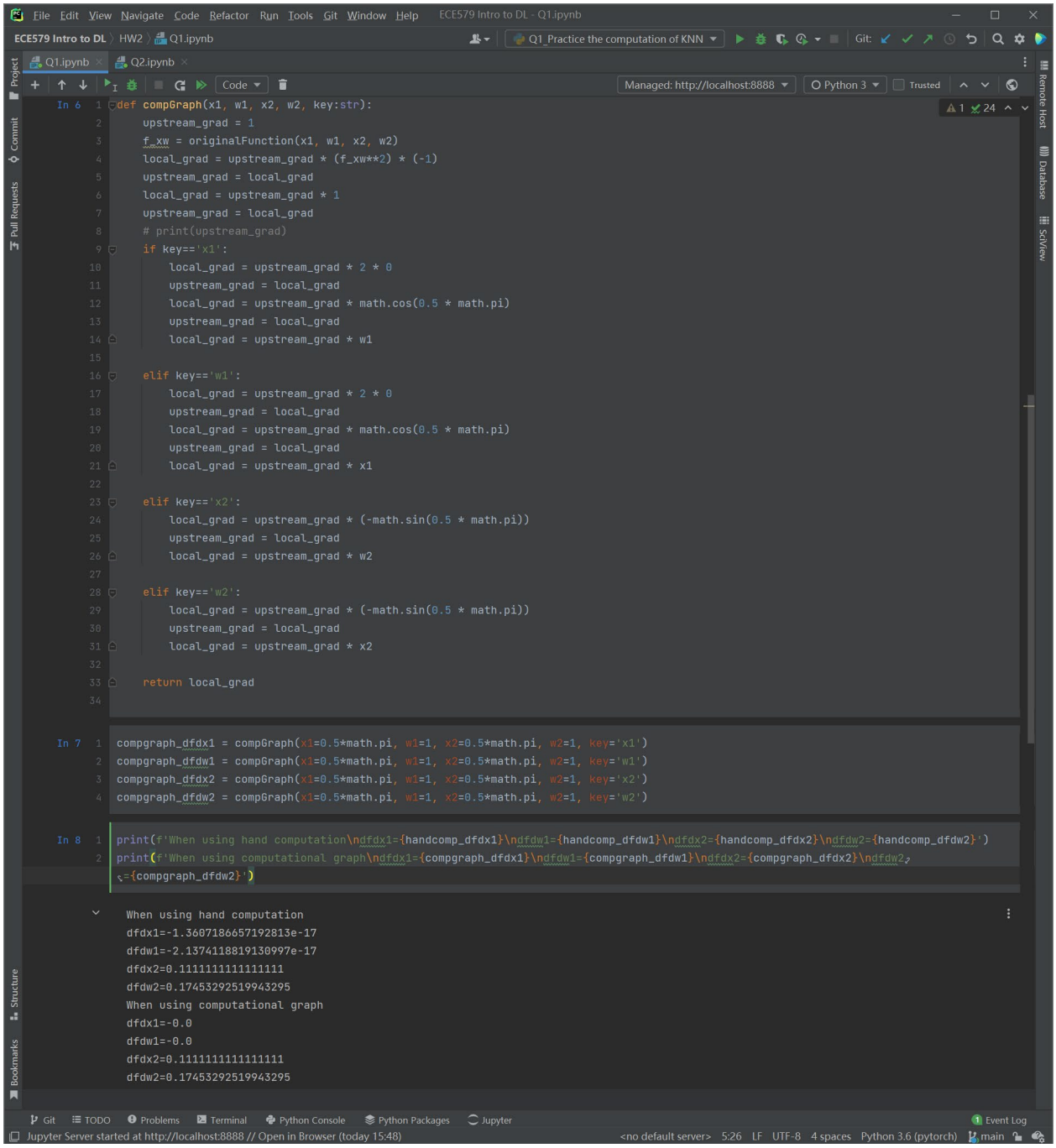
$f(x) = \cos(x)$ $\frac{df}{dx} = -\sin(x)$

$f(x) = W_1x_1$ $\frac{df}{dx} = W_1$

$f(x) = W_2x_2$ $\frac{df}{dx} = W_2$

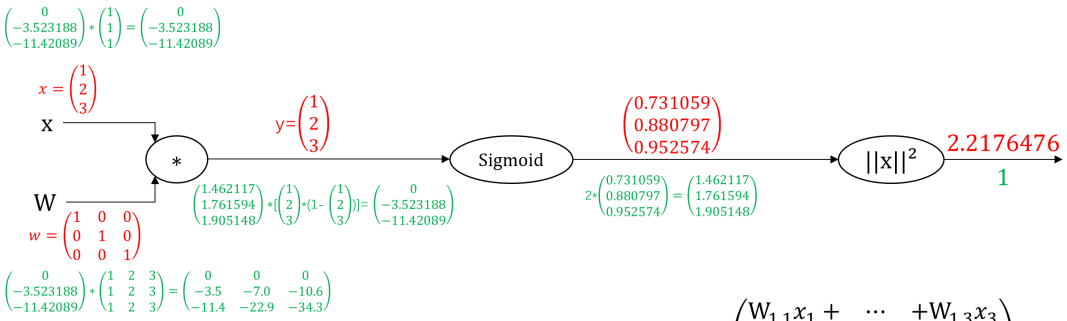
(b)


File Edit View Navigate Code Refactor Run Tools Git Window Help
ECE579 Intro to DL - Q1.ipynb
ECE579 Intro to DL 〉 HW2 〉 Q1.ipynb
Q1_Practice the computation of KNN
Git:
Q1.ipynb
Code
Managed: http://localhost:8888
Python 3
Trusted
In 38
import math
In 39
def originalFunction(x1, w1, x2, w2):
f = 1 / (2 + math.sin(x1*w1) + math.cos(x2*w2))
return f
In 40
f_xw = originalFunction(x1=0.5*math.pi, w1=1, x2=0.5*math.pi, w2=1)
f_xw
Out 40
0.3333333333333333
In 41
def dfdx1(x1, w1, x2, w2):
numerator = -2 * math.sin(x1*w1) * math.cos(x1*w1) * w1
denominator = (2 + (math.sin(x1*w1))**2 + math.cos(x2*w2))**2
f = numerator / denominator
return f
def dfdx2(x1, w1, x2, w2):
numerator = math.sin(x2*w2) * w2
denominator = (2 + (math.sin(x1*w1))**2 + math.cos(x2*w2))**2
f = numerator / denominator
return f
def dfdw1(x1, w1, x2, w2):
numerator = -2 * math.sin(x1*w1) * math.cos(x1*w1) * x1
denominator = (2 + (math.sin(x1*w1))**2 + math.cos(x2*w2))**2
f = numerator / denominator
return f
def dfdw2(x1, w1, x2, w2):
numerator = math.sin(x2*w2) * x2
denominator = (2 + (math.sin(x1*w1))**2 + math.cos(x2*w2))**2
f = numerator / denominator
return f
In 42
handcomp_dfdx1 = dfdx1(x1=0.5*math.pi, w1=1, x2=0.5*math.pi, w2=1)
handcomp_dfdw1 = dfdw1(x1=0.5*math.pi, w1=1, x2=0.5*math.pi, w2=1)
handcomp_dfdx2 = dfdx2(x1=0.5*math.pi, w1=1, x2=0.5*math.pi, w2=1)
handcomp_dfdw2 = dfdw2(x1=0.5*math.pi, w1=1, x2=0.5*math.pi, w2=1)
In 43
def compGraph(x1, w1, x2, w2, key:str):
upstream_grad = 1
f_xw = originalFunction(x1, w1, x2, w2)
local_grad = upstream_grad * (f_xw**2) * (-1)
upstream_grad = local_grad
local_grad = upstream_grad * 1
upstream_grad = local_grad
# print(upstream_grad)
if key=='x1':
local_grad = upstream_grad * 2 * 0
upstream_grad = local_grad
local_grad = upstream_grad * math.cos(0.5 * math.pi)
Git TODO Problems Terminal Python Console Python Packages Jupyter
Event Log
Jupyter Server started at http://localhost:8888 // Open in Browser (16 minutes ago)
<no default server> 80:116 LF UTF-8 4 spaces Python 3.6 (pytorch) main


File Edit View Navigate Code Refactor Run Tools Git Window Help
ECE579 Intro to DL - Q1.ipynb
ECE579 Intro to DL 〉 HW2 〉 Q1.ipynb
Q1_Practice the computation of KNN
Git:
Q1.ipynb
Q2.ipynb
Code
Managed: http://localhost:8888
Python 3
Trusted
In 6
def compGraph(x1, w1, x2, w2, key:str):
upstream_grad = 1
f_xw = originalFunction(x1, w1, x2, w2)
local_grad = upstream_grad * (f_xw**2) * (-1)
upstream_grad = local_grad
local_grad = upstream_grad * 1
upstream_grad = local_grad
# print(upstream_grad)
if key=='x1':
local_grad = upstream_grad * 2 * 0
upstream_grad = local_grad
local_grad = upstream_grad * math.cos(0.5 * math.pi)
upstream_grad = local_grad
local_grad = upstream_grad * w1
elif key=='w1':
local_grad = upstream_grad * 2 * 0
upstream_grad = local_grad
local_grad = upstream_grad * math.cos(0.5 * math.pi)
upstream_grad = local_grad
local_grad = upstream_grad * x1
elif key=='x2':
local_grad = upstream_grad * (-math.sin(0.5 * math.pi))
upstream_grad = local_grad
local_grad = upstream_grad * w2
elif key=='w2':
local_grad = upstream_grad * (-math.sin(0.5 * math.pi))
upstream_grad = local_grad
local_grad = upstream_grad * x2
return local_grad
In 7
compgraph_dfdx1 = compGraph(x1=0.5*math.pi, w1=1, x2=0.5*math.pi, w2=1, key='x1')
compgraph_dfdw1 = compGraph(x1=0.5*math.pi, w1=1, x2=0.5*math.pi, w2=1, key='w1')
compgraph_dfdx2 = compGraph(x1=0.5*math.pi, w1=1, x2=0.5*math.pi, w2=1, key='x2')
compgraph_dfdw2 = compGraph(x1=0.5*math.pi, w1=1, x2=0.5*math.pi, w2=1, key='w2')
In 8
print(f'When using hand computation\ndfdx1={handcomp_dfdx1}\ndfdw1={handcomp_dfdw1}\ndfdx2={handcomp_dfdx2}\ndfdw2={handcomp_dfdw2}')
print(f'When using computational graph\ndfdx1={compgraph_dfdx1}\ndfdw1={compgraph_dfdw1}\ndfdx2={compgraph_dfdx2}\ndfdw2={compgraph_dfdw2}')
When using hand computation
dfdx1=-1.3607186657192813e-17
dfdw1=-2.1374118819130997e-17
dfdx2=0.1111111111111111
dfdw2=0.17453292519943295
When using computational graph
dfdx1=-0.0
dfdw1=-0.0
dfdx2=0.1111111111111111
dfdw2=0.17453292519943295
Git TODO Problems Terminal Python Console Python Packages Jupyter
Event Log
Jupyter Server started at http://localhost:8888 // Open in Browser (today 15:48)
<no default server> 5:26 LF UTF-8 4 spaces Python 3.6 (pytorch) main

Problem 2 (Practice of vector-based backpropagation)

(a)



$$\frac{dL}{dx_{1,1}} = \frac{dy}{dx_{1,1}} * \frac{dL}{dy} = \begin{pmatrix}1\\0\\0\end{pmatrix} * \begin{pmatrix}0\\-3.523188\\-11.42089\end{pmatrix} = 0$$

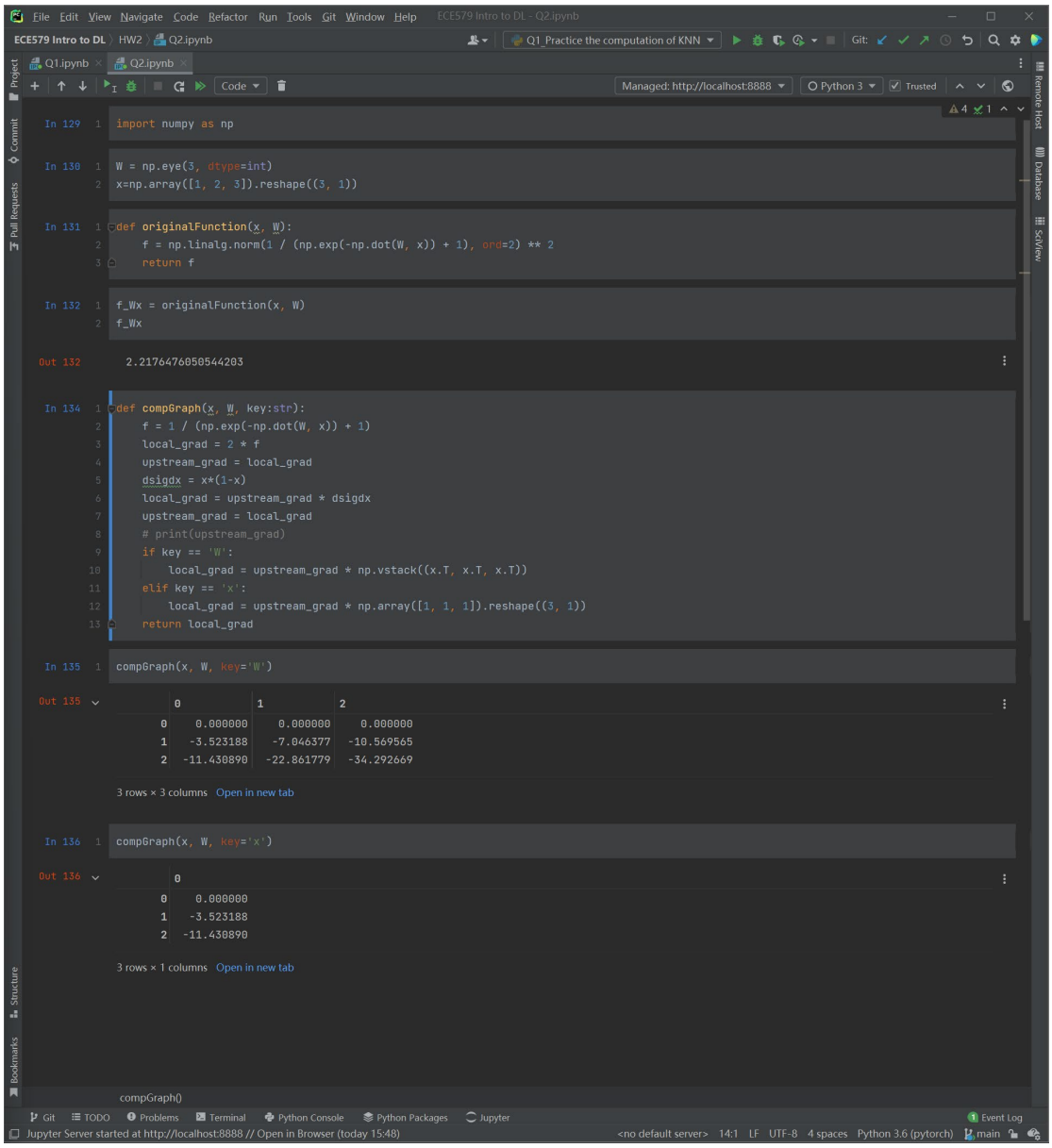
$$\frac{dL}{dx_{2,1}} = \frac{dy}{dx_{2,1}} * \frac{dL}{dy} = \begin{pmatrix}0\\1\\0\end{pmatrix} * \begin{pmatrix}0\\-3.523188\\-11.42089\end{pmatrix} = -3.523188$$

$$\frac{dL}{dx_{3,1}} = \frac{dy}{dx_{3,1}} * \frac{dL}{dy} = \begin{pmatrix}0\\0\\1\end{pmatrix} * \begin{pmatrix}0\\-3.523188\\-11.42089\end{pmatrix} = -11.42089$$

$$W \cdot \mathrm{x} = \begin{pmatrix} \mathrm{W}_{1,1}x_1 + & \cdots & +\mathrm{W}_{1,3}x_3 \\ \vdots & \vdots & \vdots \\ \mathrm{W}_{3,1}x_1 + & \cdots & +\mathrm{W}_{3,3}x_3 \end{pmatrix}$$

$\mathrm{f(x)= Sig(x)=h} \quad \frac{df}{dx} = h(1-h)$

$\mathrm{f(x)=||x||^2=x_{1,1}^2+ x_{2,1}^2+ x_{3,1}^2} \quad \frac{df}{dx_{i,1}} = 2x_{i,1}$



The answer is as same as I calculate by my hand.