



LuaCV

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Chapter 1

About LuaCV

LuaCV is OpenCV library wrapper for Lua language. Main goal is to access fast image processing library to light-weight, non-type language. Thanks to CMake project is a much easier to compile it under many OS platforms which are supported by OpenCV. LuaCV is being developed at BRNO UNIVERSITY OF TECHNOLOGY in Czech Republic and it aims to partially replace Matlab in our Image Processing Courses. In current stage of development of LuaCV are implemented C API function and objects from imgproc/core/highgui/calibration modules.

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Chapter 2

Changelog

There is list of changes between LuaCV versions in this chapter.

2.1 Changes in 0.2.1

- New modular system
- Some samples completion
- Beginings of OpenCV C++ API
- No further backward compatibility for Lua 5.1

2.2 Changes in 0.2.0

- Almost all OpenCV C API implemented.
- Many new samples to test new functions.
- Allocation bugs fixed.
- OpenCV 2.3 compatibility.
- Lua 5.2 compatibility.
- NSIS MS Windows installer.
- Partial documentation.

2.3 Changes in 0.1.4

- New allocation system for all objects (using boxed pointer). Big objects like matrix and images aren't copied now. You can releas every object by `obj=nil collectgarbage('collect')` Releasing of objects is done by `__gc` callback with `(cvFree/cvRelease* func)`.
- Minor changes in LuaCV API to maximize optimalization by compiler (template functions, using aligned OpenCV alloc/free).
- Some new types for image processing module (`CvSubdiv2D*`).

- Implemented functions for CvGraph handling in core module.
- Implemented various containers for imgproc module.
- Whole highgui C API is implemented (or almost all functions from C api).
- Most of functions from imgproc C API module are implemented, but need proper testing.
- New samples in sample directory to test new implemented functions from imgproc module (almost all c api samples).
- OpenCV callback functions for trackbars and mouse events are now fully implemented. See functions `CreateTrackbar` and `SetMouseCallback` from highgui module or samples for basic usage.

2.4 Changes in 0.1.3

- Whole wrapper was rewritten to new OpenCV 2.2. It has to be done because of new modular system in OpenCV. And that's why new LuaCV won't be back compatible with OpenCV < 2.2.

Chapter 3

Function reference manual

This section contains actual references for LuaCV functions sorted by name and modules . There is actually implemented only C API OpenCV functions in LuaCV, but C API is still major part of OpenCV functions.

3.1 Module core

3.1.1 AXPY

- **AXPY**([CvArr](#) src1, [num](#) real_scalar, [CvArr](#) src2, [CvArr](#) dst)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src1	A wrapped OpenCV object of type CvArr
real_scalar	A floating point number
src2	A wrapped OpenCV object of type CvArr
dst	A wrapped OpenCV object of type CvArr

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.2 Abs

- **Abs**([CvArr](#) src1, [CvArr](#) dst)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
dst	A wrapped OpenCV object of type CvArr

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.3 AbsDiff

- **AbsDiff**([CvArr](#) src1, [CvArr](#) src2, [CvArr](#) dst)

Calculates absolute difference between two arrays.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	The first source array
src2	The second source array
dst	The destination array

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.4 AbsDiffS

- **AbsDiffS**([CvArr](#) src1, [CvArr](#) dst, [CvScalar](#) value)

Calculates absolute difference between an array and a scalar.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
dst	The destination array
value	The scalar

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.5 Add

- **Add**([CvArr](#) src1, [CvArr](#) src2, [CvArr](#) dst, [CvArr](#) mask=nil)

Computes the per-element sum of two arrays.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	The first source array
src2	The second source array
dst	The destination array
mask	Operation mask, 8-bit single channel array; specifies elements of the destination array to be changed

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.6 AddS

- **AddS**(CvArr src1, CvScalar value, CvArr dst, CvArr mask=nil)

Computes the sum of an array and a scalar.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
value	Added scalar
dst	The destination array
mask	Operation mask, 8-bit single channel array; specifies elements of the destination array to be changed

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.7 AddWeighted

- **AddWeighted**(CvArr src1, num alpha, CvArr src2, num beta, num gamma, CvArr dst)

Computes the weighted sum of two arrays.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	The first source array
alpha	Weight for the first array elements
src2	The second source array
beta	Weight for the second array elements
gamma	Scalar, added to each sum
dst	The destination array

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.8 And

- **And**([CvArr](#) src1, [CvArr](#) src2, [CvArr](#) dst, [CvArr](#) mask=nil)

Calculates per-element bit-wise conjunction of two arrays.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src1	The first source array
src2	The second source array
dst	The destination array
mask	Operation mask, 8-bit single channel array; specifies elements of the destination array to be changed

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.9 AndS

- **AndS**([CvArr](#) src1, [CvScalar](#) value, [CvArr](#) dst, [CvArr](#) mask=nil)

Calculates per-element bit-wise conjunction of an array and a scalar.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src1	A wrapped OpenCV object of type <code>CvArr</code>
value	Scalar to use in the operation
dst	The destination array
mask	Operation mask, 8-bit single channel array; specifies elements of the destination array to be changed

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.10 AvgSdv

- **AvgSdv**(`CvArr` arr, `CvScalar` mean, `CvScalar` std_dev, `CvArr` mask=nil)

Calculates average (mean) of array elements.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

arr	The array
mean	Mean value, a <code>CvScalar</code>
std_dev	A wrapped OpenCV object of type <code>CvScalar</code>
mask	The optional operation mask

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.11 BackProjectPCA

- **BackProjectPCA**(`CvArr` proj, `CvArr` mean, `CvArr` eigenvals, `CvArr` result)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

proj	A wrapped OpenCV object of type CvArr
mean	A wrapped OpenCV object of type CvArr
eigenvals	A wrapped OpenCV object of type CvArr
result	A wrapped OpenCV object of type CvArr

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.12 CalcCovarMatrix

- **CalcCovarMatrix**([CvArr](#)[] vects, [int](#) count, [CvArr](#) cov_mat, [CvArr](#) avq, [int](#) flags)

Calculates covariance matrix of a set of vectors.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

vects	The input vectors, all of which must have the same type and the same size. The vectors do not have to be 1D, they can be 2D (e.g., images) and so forth
count	The number of input vectors
cov_mat	A wrapped OpenCV object of type CvArr
avq	A wrapped OpenCV object of type CvArr
flags	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.13 CalcPCA

- **CalcPCA**([CvArr](#) data, [CvArr](#) mean, [CvArr](#) eigenvals, [CvArr](#) eigenvects, [int](#) flags)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

data	A wrapped OpenCV object of type CvArr
mean	A wrapped OpenCV object of type CvArr
eigenvals	A wrapped OpenCV object of type CvArr
eigenvects	A wrapped OpenCV object of type CvArr
flags	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.14 CartToPolar

- **CartToPolar**([CvArr](#) x, [CvArr](#) y, [CvArr](#) magnitude, [CvArr](#) angle=nil, [int](#) angle_in_degrees=0)

Calculates the magnitude and/or angle of 2d vectors.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

x	The array of x-coordinates
y	The array of y-coordinates
magnitude	The destination array of magnitudes, may be set to NULL if it is not needed
angle	The destination array of angles, may be set to NULL if it is not needed. The angles are measured in radians (0 to 2π) or in degrees (0 to 360 degrees).
angle_in_degrees	An integer type number with default value 0

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.15 Cbrt

- **num Cbrt**(num value)

Calculates the cubic root

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

value	The input floating-point value
--------------	--------------------------------

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.16 Ceil

- **int Ceil**(num value)

Converts a floating-point number to the nearest integer value that is not smaller than the argument.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

value	The input floating-point value
--------------	--------------------------------

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.17 ChangeSeqBlock

- **ChangeSeqBlock**([userdata](#) reader, [int](#) direction)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

reader	An unspecified C pointer to memory
direction	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.18 CheckArr

- **int CheckArr**([CvArr](#) arr, [int](#) flags=0, [num](#) min_val=0, [num](#) max_val=0)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

arr	A wrapped OpenCV object of type CvArr
flags	An integer type number with default value 0
min_val	A floating point number with default value 0
max_val	A floating point number with default value 0

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.19 Circle

- **Circle**([CvArr](#) img, [CvPoint](#) center, [int](#) radius, [CvScalar](#) color, [int](#) thickness=1, [int](#) line_type=8, [int](#) shift=0)

Draws a circle.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

img	Image where the circle is drawn
center	Center of the circle
radius	Radius of the circle
color	Circle color
thickness	Thickness of the circle outline if positive, otherwise this indicates that a filled circle is to be drawn
line_type	An integer type number with default value 8
shift	Number of fractional bits in the center coordinates and radius value

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.20 ClearGraph

- **ClearGraph**([CvGraph](#) graph)

Clears a graph.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

graph	Graph
--------------	-------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.21 ClearMemStorage

- **ClearMemStorage**([CvMemStorage](#) storage)

Clears memory storage.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

storage	Memory storage
----------------	----------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.22 ClearND

- **ClearND**([CvArr](#) arr, [int](#)[] idx)

Clears a specific array element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

arr	Input array
idx	Array of the element indices

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.23 ClearSeq

- **ClearSeq**([CvSeq](#) seq)
Clears a sequence.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
------------	----------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.24 ClearSet

- **ClearSet**([CvSet](#) set_header)
Clears a set.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

set_header	A wrapped OpenCV object of type CvSet
-------------------	---------------------------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.25 ClipLine

- **int** **ClipLine**(**CvSize** img_size, **CvPoint** pt1, **CvPoint** pt2)

Clips the line against the image rectangle.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

img_size	A wrapped OpenCV object of type CvSize
pt1	First ending point of the line segment. It is modified by the function.
pt2	Second ending point of the line segment. It is modified by the function.

Returns

int - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.26 Cmp

- **Cmp**(**CvArr** src1, **CvArr** src2, **CvArr** dst, **int** cmp_op)

Performs per-element comparison of two arrays.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	The first source array
src2	The second source array. Both source arrays must have a single channel.
dst	The destination array, must have 8u or 8s type
cmp_op	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.27 CmpS

- **CmpS**([CvArr](#) src1, [num](#) value, [CvArr](#) dst, [int](#) cmp_op)

Performs per-element comparison of an array and a scalar.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src1	A wrapped OpenCV object of type CvArr
value	The scalar value to compare each array element with
dst	The destination array, must have 8u or 8s type
cmp_op	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.28 CompleteSymm

- **CompleteSymm**([CvMat](#) matrix, [int](#) LtoR=0)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

matrix	A wrapped OpenCV object of type CvMat
LtoR	An integer type number with default value 0

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.29 Convert

- **Convert**([CvArr](#) src, [CvArr](#) dst)
Converts one array to another.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source array
dst	Destination array

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.30 ConvertScale

- **ConvertScale**([CvArr](#) src, [CvArr](#) dst, [num](#) scale=1, [num](#) shift=0)
Converts one array to another with optional linear transformation.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source array
dst	Destination array
scale	Scale factor
shift	Value added to the scaled source array elements

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.31 ConvertScaleAbs

- **ConvertScaleAbs**([CvArr](#) src, [CvArr](#) dst, [num](#) scale=1, [num](#) shift=0)

Converts input array elements to another 8-bit unsigned integer with optional linear transformation.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src	Source array
dst	Destination array (should have 8u depth)
scale	ScaleAbs factor
shift	Value added to the scaled source array elements

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.32 Copy

- **Copy**([CvArr](#) src, [CvArr](#) dst, [CvArr](#) mask=nil)

Copies one array to another.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src	The source array
dst	The destination array
mask	Operation mask, 8-bit single channel array; specifies elements of the destination array to be changed

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.33 CountNonZero

- **int CountNonZero**(**CvArr** arr)

Counts non-zero array elements.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

arr	The array must be a single-channel array or a multi-channel image with COI set
------------	--

Returns

int - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.34 CreateData

- **CreateData**(**CvArr** arr)

Allocates array data

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

arr	Array header
------------	--------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.35 CreateGraph

- **CreateGraph**([int](#) graph_flags, [int](#) header_size, [int](#) vtx_size, [int](#) edge_size, [CvMemStorage](#) storage)

Creates an empty graph.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

graph_flags	An integer type number
header_size	Graph header size; may not be less than <code>sizeof (CvGraph)</code>
vtx_size	Graph vertex size; the custom vertex structure must start with Cv-GraphVtx (use <code>CV_GRAPH_VERTEX_FIELDS ()</code>)
edge_size	Graph edge size; the custom edge structure must start with Cv-GraphEdge (use <code>CV_GRAPH_EDGE_FIELDS ()</code>)
storage	The graph container

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.36 CreateSeqBlock

- **CreateSeqBlock**([CvSeqWriter](#) writer)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

writer	A wrapped OpenCV object of type CvSeqWriter
---------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.37 CrossProduct

- **CrossProduct**([CvArr](#) src1, [CvArr](#) src2, [CvArr](#) dst)

Calculates the cross product of two 3D vectors.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	The first source vector
src2	The second source vector
dst	The destination vector

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.38 CvtSeqToArray

- [userdata](#) **CvtSeqToArray**([CvSeq](#) seq, [userdata](#)[] elements, [CvSlice](#) slice=CV_WHOLE_SEQ, [string](#) convert_to="")

Copies a sequence to one continuous block of memory.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
elements	Pointer to the destination array that must be large enough. It should be a pointer to data, not a matrix header.
slice	The sequence portion to copy to the array
convert_to	An array of characters with default value <i>with default value</i> <code>CV_WHOLE_SEQ</code>

Returns

[userdata](#) - An unspecified C pointer to memory

The documentation was generated from :

- lua_core.cpp

3.1.39 DCT

- **DCT**([CvArr](#) src, [CvArr](#) dst, [int](#) flags)

Performs a forward or inverse Discrete Cosine transform of a 1D or 2D floating-point array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src	Source array, real 1D or 2D array
dst	Destination array of the same size and same type as the source
flags	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.40 DFT

- **DFT**([CvArr](#) src, [CvArr](#) dst, [int](#) flags, [int](#) nonzero_rows=0)

Performs a forward or inverse Discrete Fourier transform of a 1D or 2D floating-point array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

src	Source array, real or complex
dst	Destination array of the same size and same type as the source
flags	An integer type number
nonzero_rows	An integer type number with default value 0

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.41 DecRefData

- **DecRefData**(CvArr arr)

Decrements an array data reference counter.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

arr	Pointer to an array header
------------	----------------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.42 Det

- **num Det**(CvArr mat)

Returns the determinant of a matrix.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

mat	The source matrix
------------	-------------------

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.43 Div

- **Div**([CvArr](#) src1, [CvArr](#) src2, [CvArr](#) dst, [num](#) scale=1)

Performs per-element division of two arrays.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

src1	The first source array. If the pointer is NULL, the array is assumed to be all 1's.
src2	The second source array
dst	The destination array
scale	Optional scale factor

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.44 DotProduct

- **num DotProduct**([CvArr](#) src1, [CvArr](#) src2)

Calculates the dot product of two arrays in Euclidian metrics.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

src1	The first source array
src2	The second source array

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.45 DrawContours

- **DrawContours**(**CvArr** img, **CvSeq** contour, **CvScalar** external_color, **CvScalar** hole_color, **int** max_level, **int** thickness=1, **int** line_type=8, **CvPoint** offset=Point(0,0))

Draws contour outlines or interiors in an image.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

img	Image where the contours are to be drawn. As with any other drawing function, the contours are clipped with the ROI.
contour	Pointer to the first contour
external_color	Color of the external contours
hole_color	Color of internal contours (holes)
max_level	An integer type number
thickness	An integer type number with default value <i>1</i>
line_type	An integer type number with default value <i>8</i>
offset	A wrapped OpenCV object of type CvPoint with default value <i>Point(0</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.46 EigenVV

- **EigenVV**(*CvArr* mat, *CvArr* evecs, *CvArr* evals, *num* eps=0, *int* lowindex=-1, *int* highindex=-1)

Computes eigenvalues and eigenvectors of a symmetric matrix.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

mat	The input symmetric square matrix, modified during the processing
evecs	The output matrix of eigenvectors, stored as subsequent rows
evals	The output vector of eigenvalues, stored in the descending order (order of eigenvalues and eigenvectors is synchronized, of course)
eps	A floating point number with default value 0
lowindex	An integer type number with default value <i>with default value 0</i>
highindex	An integer type number with default value <i>with default value with default value 0</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.47 Ellipse

- **Ellipse**(*CvArr* img, *CvPoint* center, *CvSize* axes, *num* angle, *num* start_angle, *num* end_angle, *CvScalar* color, *int* thickness=1, *int* line_type=8, *int* shift=0)

Draws a simple or thick elliptic arc or an fills ellipse sector.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

img	The image
center	Center of the ellipse
axes	Length of the ellipse axes

angle	Rotation angle
start_angle	Starting angle of the elliptic arc
end_angle	Ending angle of the elliptic arc.
color	Ellipse color
thickness	Thickness of the ellipse arc outline if positive, otherwise this indicates that a filled ellipse sector is to be drawn
line_type	An integer type number with default value 8
shift	Number of fractional bits in the center coordinates and axes' values

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.48 Ellipse2Poly

- **int Ellipse2Poly**(**CvPoint** center, **CvSize** axes, **int** angle, **int** argc_end, **CvPoint** pts, **int** delta)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

center	A wrapped OpenCV object of type CvPoint
axes	A wrapped OpenCV object of type CvSize
angle	An integer type number
argc_end	An integer type number
pts	A wrapped OpenCV object of type CvPoint
delta	An integer type number

Returns

int - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.49 EllipseBox

- **EllipseBox**([CvArr](#) img, [CvBox2D](#) box, [CvScalar](#) color, [int](#) thickness=1, [int](#) line_type=8, [int](#) shift=0)

Draws a simple or thick elliptic arc or fills an ellipse sector.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

img	Image
box	The enclosing box of the ellipse drawn
color	A wrapped OpenCV object of type <code>CvScalar</code>
thickness	Thickness of the ellipse boundary
line_type	An integer type number with default value <code>8</code>
shift	Number of fractional bits in the box vertex coordinates

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.50 Exp

- **Exp**([CvArr](#) src1, [CvArr](#) dst)

Calculates the exponent of every array element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src1	A wrapped OpenCV object of type <code>CvArr</code>
dst	The destination array, it should have <code>double</code> type or the same type as the source

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.51 FastArctan

- **num** **FastArctan**(**num** y, **num** x)

Calculates the angle of a 2D vector.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

y	y-coordinate of 2D vector
x	x-coordinate of 2D vector

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.52 FillConvexPoly

- **FillConvexPoly**(**CvArr** img, **CvPoint** pts, **int** npts, **CvScalar** color, **int** line_type=8, **int** shift=0)

Fills a convex polygon.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

img	Image
pts	Array of pointers to a single polygon
npts	Polygon vertex counter
color	Polygon color
line_type	An integer type number with default value 8
shift	Number of fractional bits in the vertex coordinates

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.53 FillPoly

- **FillPoly**([CvArr](#) img, [CvPoint\[\]](#) pts, [int\[\]](#) npts, [int](#) contours, [CvScalar](#) color, [int](#) line_type=8, [int](#) shift=0)

Fills a polygon's interior.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

img	Image
pts	Array of pointers to polygons
npts	Array of polygon vertex counters
contours	Number of contours that bind the filled region
color	Polygon color
line_type	An integer type number with default value 8
shift	Number of fractional bits in the vertex coordinates

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.54 Flip

- **Flip**([CvArr](#) src, [CvArr](#) dst=nil, [int](#) flip_mode=0)

Flip a 2D array around vertical, horizontal or both axes.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src	Source array
dst	A wrapped OpenCV object of type <code>CvArr</code> with default value <i>nil</i>
flip_mode	An integer type number with default value <i>0</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.55 Floor

- **int Floor**(*num* value)

Converts a floating-point number to the nearest integer value that is not larger than the argument.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

value	The input floating-point value
--------------	--------------------------------

Returns

int - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.56 FlushSeqWriter

- **FlushSeqWriter**(*CvSeqWriter* writer)

Updates sequence headers from the writer.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

writer	Writer state
---------------	--------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.57 GEMM

- **GEMM**([CvArr](#) src1, [CvArr](#) src2, [num](#) alpha, [CvArr](#) src3, [num](#) beta, [CvArr](#) dst, [int](#) tABC=0)

Performs generalized matrix multiplication.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	The first source array
src2	The second source array
alpha	A floating point number
src3	The third source array (shift). Can be NULL, if there is no shift.
beta	A floating point number
dst	The destination array
tABC	An integer type number with default value 0

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.58 GetDims

- **int** **GetDims**([CvArr](#) arr, [int\[\]](#) sizes=nil)

Returns list of array dimensions

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

arr	Input array
sizes	An integer type number which is an array with default value <i>nil</i>

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.59 GetDimsSize

- [int](#) **GetDimsSize**([CvArr](#) arr,[int](#) index)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

arr	A wrapped OpenCV object of type CvArr
index	An integer type number

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.60 GetElemType

- [int](#) **GetElemType**([CvArr](#) arr)

Returns type of array elements.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

arr	Input array
------------	-------------

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.61 GetImageCOI

- [int](#) **GetImageCOI**([IplImage](#) image)

Returns the index of the channel of interest.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	A pointer to the image header
--------------	-------------------------------

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.62 GetOptimalDFTSize

- [int](#) **GetOptimalDFTSize**([int](#) size0)

Returns optimal DFT size for a given vector size.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

size0	Vector size
--------------	-------------

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.63 GetReal1D

- [num](#) **GetReal1D**([CvArr](#) arr, [int](#) idx0)

Return a specific element of single-channel 1D array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

arr	Input array. Must have a single channel.
idx0	The first zero-based component of the element index

Returns

[num](#) - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.64 GetReal2D

- [num](#) **GetReal2D**([CvArr](#) arr, [int](#) idx0, [int](#) idx1)

Return a specific element of single-channel 2D array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

arr	Input array. Must have a single channel.
idx0	The first zero-based component of the element index
idx1	The second zero-based component of the element index

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.65 GetReal3D

- **num** **GetReal3D**(**CvArr** arr, **int** idx0, **int** idx1, **int** idx2)

Return a specific element of single-channel array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

arr	Input array. Must have a single channel.
idx0	The first zero-based component of the element index
idx1	The second zero-based component of the element index
idx2	The third zero-based component of the element index

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.66 GetRealND

- **num** **GetRealND**(**CvArr** arr, **int**[] idx)

Return a specific element of single-channel array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

arr	Input array
idx	Array of the element indices

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.67 GetSeqElem

- **userdata** **GetSeqElem**(**CvSeq** seq, **int** index, **string** convert_to="")

Returns a pointer to a sequence element according to its index.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
index	Index of element
convert_to	An array of characters with default value

Returns

userdata - An unspecified C pointer to memory

The documentation was generated from :

- lua_core.cpp

3.1.68 GetSeqReaderPos

- **int** **GetSeqReaderPos**(**CvSeqReader** reader)

Returns the current reader position.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

reader	Reader state
---------------	--------------

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.69 GetTextSize

- [int](#) **GetTextSize**([string](#) text, [CvFont](#) font, [CvSize](#) text_size)

Retrieves the width and height of a text string.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

text	An array of characters
font	Pointer to the font structure
text_size	A wrapped OpenCV object of type CvSize

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.70 GetTickCount

- [num](#) **GetTickCount**()

Returns the number of ticks.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

<i>none</i>	function doesn't have input arguments.
-------------	--

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.71 GetTickFrequency

- **num GetTickFrequency()**

Returns the number of ticks per microsecond.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

<i>none</i>	function doesn't have input arguments.
-------------	--

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.72 GraphAddEdge

- **int GraphAddEdge(CvGraph graph, int start_idx, int end_idx, CvGraphEdge edge=nil, CvGraphEdge inserted_edge=nil)**

Adds an edge to a graph.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

graph	Graph
start_idx	Index of the starting vertex of the edge
end_idx	Index of the ending vertex of the edge. For an unoriented graph, the order of the vertex parameters does not matter.
edge	Optional input parameter, initialization data for the edge
in-serted_edge	Optional output parameter to contain the address of the inserted edge

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.73 GraphAddEdgeByPtr

- [int](#) **GraphAddEdgeByPtr**([CvGraph](#) graph, [CvGraphVtx](#) start_vtx, [CvGraphVtx](#) end_vtx, [CvGraphEdge](#) edge=nil, [CvGraphEdge](#) inserted_edge=nil)

Adds an edge to a graph by using its pointer.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

graph	Graph
start_vtx	Pointer to the starting vertex of the edge
end_vtx	Pointer to the ending vertex of the edge. For an unoriented graph, the order of the vertex parameters does not matter.
edge	Optional input parameter, initialization data for the edge
in-serted_edge	Optional output parameter to contain the address of the inserted edge within the edge set

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.74 GraphAddVtx

- **int** **GraphAddVtx**([CvGraph](#) graph, [CvGraphVtx](#) vtx=nil, [CvGraphVtx](#) inserted_vtx=nil)

Adds a vertex to a graph.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

graph	Graph
vtx	Optional input argument used to initialize the added vertex (only user-defined fields beyond <code>sizeof(CvGraphVtx)</code> are copied)
inserted_vtx	A wrapped OpenCV object of type <code>CvGraphVtx</code> with default value <i>nil</i>

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.75 GraphEdgIdx

- **int** **GraphEdgIdx**([CvGraph](#) graph, [CvGraphEdge](#) edge)

Returns the index of a graph edge.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

graph	Graph
edge	Pointer to the graph edge

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.76 GraphGetEdgeCount

- [int GraphGetEdgeCount\(CvGraph graph\)](#)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

graph	A wrapped OpenCV object of type CvGraph
--------------	---

Returns

- [int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.77 GraphGetVtxCount

- [int GraphGetVtxCount\(CvGraph graph\)](#)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

graph	A wrapped OpenCV object of type CvGraph
--------------	---

Returns

- [int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.78 GraphRemoveEdge

- **GraphRemoveEdge**([CvGraph](#) graph, [int](#) start_idx, [int](#) end_idx)

Removes an edge from a graph.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

graph	Graph
start_idx	Index of the starting vertex of the edge
end_idx	Index of the ending vertex of the edge. For an unoriented graph, the order of the vertex parameters does not matter.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.79 GraphRemoveEdgeByPtr

- **GraphRemoveEdgeByPtr**([CvGraph](#) graph, [CvGraphVtx](#) start_vtx, [CvGraphVtx](#) end_vtx)

Removes an edge from a graph by using its pointer.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

graph	Graph
start_vtx	Pointer to the starting vertex of the edge
end_vtx	Pointer to the ending vertex of the edge. For an unoriented graph, the order of the vertex parameters does not matter.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.80 GraphRemoveVtx

- **GraphRemoveVtx**([CvGraph](#) graph, [int](#) index)

Removes a vertex from a graph.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

graph	Graph
index	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.81 GraphRemoveVtxByPtr

- **GraphRemoveVtxByPtr**([CvGraph](#) graph, [CvGraphVtx](#) vtx)

Removes a vertex from a graph by using its pointer.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

graph	Graph
vtx	Pointer to the removed vertex

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.82 GraphVtxDegree

- **int** **GraphVtxDegree**([CvGraph](#) graph, **int** vtx_idx)
Counts the number of edges indicent to the vertex.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

graph	Graph
vtx_idx	An integer type number

Returns

int - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.83 GraphVtxDegreeByPtr

- **int** **GraphVtxDegreeByPtr**([CvGraph](#) graph, [CvGraphVtx](#) vtx)
Finds an edge in a graph.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

graph	Graph
vtx	Pointer to the graph vertex

Returns

int - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.84 GraphVtxIdx

- `int GraphVtxIdx(CvGraph graph, CvGraphVtx vtx)`

Returns the index of a graph vertex.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

graph	Graph
vtx	Pointer to the graph vertex

Returns

- `int` - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.85 InRange

- `InRange(CvArr src1, CvArr lower, CvArr upper, CvArr dst)`

Checks that array elements lie between the elements of two other arrays.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
lower	The inclusive lower boundary array
upper	The exclusive upper boundary array
dst	The destination array, must have 8u or 8s type

Returns

- `none` - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.86 InRangeS

- **InRangeS**([CvArr](#) src1, [CvScalar](#) lower, [CvScalar](#) upper, [CvArr](#) dst)

Checks that array elements lie between two scalars.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
lower	The inclusive lower boundary
upper	The exclusive upper boundary
dst	The destination array, must have 8u or 8s type

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.87 IncRefData

- **IncRefData**([CvArr](#) arr)

Increments array data reference counter.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

arr	Array header
------------	--------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.88 InitFont

- **InitFont**([CvFont](#) font, [int](#) font_face, [num](#) hscale, [num](#) vscale, [num](#) shear=0, [int](#) thickness=1, [int](#) line_type=8)

Initializes font structure.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

font	Pointer to the font structure initialized by the function
font_face	An integer type number
hscale	Horizontal scale. If equal to 1.0f, the characters have the original width depending on the font type. If equal to 0.5f, the characters are of half the original width.
vscale	Vertical scale. If equal to 1.0f, the characters have the original height depending on the font type. If equal to 0.5f, the characters are of half the original height.
shear	A floating point number with default value 0
thickness	Thickness of the text strokes
line_type	An integer type number with default value 8

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.89 InitLineIterator

- **int InitLineIterator**([CvArr](#) image, [CvPoint](#) pt1, [CvPoint](#) pt2, [CvLineIterator](#) line_iterator, [int](#) connectivity=8, [int](#) left_to_right=0)

Initializes the line iterator.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

image	Image to sample the line from
pt1	First ending point of the line segment
pt2	Second ending point of the line segment

line_iterator	Iterator over the pixels of the line
connectivity	The scanned line connectivity, 4 or 8.
left_to_right	An integer type number with default value 0

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.90 InitNArrayIterator

- [int InitNArrayIterator](#)([int](#) count, [CvArr](#) arrs[], [CvArr](#) mask, [CvMatND](#) stubs, [CvNArrayIterator](#) array_iterator, [int](#) flags=0)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

count	An integer type number
arrs	A wrapped OpenCV object of type CvArr
mask	A wrapped OpenCV object of type CvArr
stubs	A wrapped OpenCV object of type CvMatND
array_iterator	A wrapped OpenCV object of type CvNArrayIterator
flags	An integer type number with default value 0

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.91 InitTreeNodeIterator

- **InitTreeNodeIterator**([CvTreeNodeIterator](#) tree_iterator, [userdata](#) first, [int](#) max_level)

Initializes the tree node iterator.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

tree_iterator	Tree iterator initialized by the function
first	The initial node to start traversing from
max_level	The maximal level of the tree (<i>first</i> node assumed to be at the first level) to traverse up to. For example, 1 means that only nodes at the same level as <i>first</i> should be visited, 2 means that the nodes on the same level as <i>first</i> and their direct children should be visited, and so forth.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.92 InsertNodeIntoTree

- **InsertNodeIntoTree**([userdata](#) node, [userdata](#) parent, [userdata](#) frame)

Adds a new node to a tree.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

node	The inserted node
parent	The parent node that is already in the tree
frame	The top level node. If <i>parent</i> and <i>frame</i> are the same, the <i>v_prev</i> field of <i>node</i> is set to NULL rather than <i>parent</i> .

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.93 InvSqrt

- **num** **InvSqrt**(**num** value)

Calculates the inverse square root.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

value	The input floating-point value
--------------	--------------------------------

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.94 Invert

- **num** **Invert**(**CvArr** src, **CvArr** dst, **int** method=CV_LU)

Finds the inverse or pseudo-inverse of a matrix.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	The source matrix
dst	The destination matrix
method	An integer type number with default value <i>CV_LU</i>

Returns

`num` - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.95 `IpDepth`

- `int IpDepth(int type)`

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

type	An integer type number
-------------	------------------------

Returns

`int` - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.96 `IsInf`

- `int IsInf(num value)`

Determines if the argument is Infinity.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

value	The input floating-point value
--------------	--------------------------------

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.97 IsNaN

- [int](#) **IsNaN**([num](#) value)

Determines if the argument is Not A Number.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

value	The input floating-point value
--------------	--------------------------------

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.98 KMeans2

- [int](#),[num](#) **KMeans2**([CvArr](#) samples, [int](#) cluster_count, [CvArr](#) labels, [CvTermCriteria](#) termcrit, [int](#) attmepts=1, [CvRNG](#) rng=0, [int](#) flags=0, [CvArr](#) _centers=0, [num](#) compactness=0)

Splits set of vectors by a given number of clusters.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

samples	Floating-point matrix of input samples, one row per sample
cluster_count	An integer type number

labels	Output integer vector storing cluster indices for every sample
termcrit	Specifies maximum number of iterations and/or accuracy (distance the centers can move by between subsequent iterations)
attempts	An integer type number with default value <i>1</i>
rng	Optional external random number generator; can be used to fully control the function behaviour
flags	An integer type number with default value <i>0</i>
_centers	A wrapped OpenCV object of type <code>CvArr</code> with default value <i>0</i>
compactness	A floating point number with default value <i>0</i>

Returns

- `int` - An integer type number defined by architecture
- `num` - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.99 LUT

- **LUT**(`CvArr` src, `CvArr` dst, `CvArr` lut)
Performs a look-up table transform of an array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source array of 8-bit elements
dst	Destination array; will have the same size and the same number of channels as <code>src</code> , and the same depth as <code>lut</code>
lut	Look-up table of 256 elements. In the case of multi-channel source array, the table should either have a single channel (in this case the same table is used for all channels) or the same number of channels as in the source array

Returns

- none** - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.100 Line

- **Line**(*CvArr* img, *CvPoint* pt1, *CvPoint* pt2, *CvScalar* color, *int* thickness=1, *int* line_type=8, *int* shift=0)

Draws a line segment connecting two points.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

img	The image
pt1	First point of the line segment
pt2	Second point of the line segment
color	Line color
thickness	Line thickness
line_type	An integer type number with default value 8
shift	Number of fractional bits in the point coordinates

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.101 Load

- **userdata,string Load**(*string* filename, *string* convert_to="", *CvMemStorage* storage=nil, *string* name="")

Loads an object from a file.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

filename	File name
convert_to	An array of characters with default value
storage	Memory storage for dynamic structures, such as CvSeq or CvGraph . It is not used for matrices or images.
name	Optional object name. If it is NULL, the first top-level object in the storage will be loaded.

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Returns

- [userdata](#) - An unspecified C pointer to memory
- [string](#) - An array of characters

The documentation was generated from :

- lua_core.cpp

3.1.102 Log

- Log**([CvArr](#) src1, [CvArr](#) dst)

Calculates the natural logarithm of every array element's absolute value.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src1	A wrapped OpenCV object of type CvArr
dst	The destination array, it should have double type or the same type as the source

Returns

- none** - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.103 Mahalanobis

- num Mahalanobis**([CvArr](#) vec1, [CvArr](#) vec2, [CvArr](#) mat)

Calculates the Mahalanobis distance between two vectors.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

vec1	The first 1D source vector
vec2	The second 1D source vector
mat	A wrapped OpenCV object of type CvArr

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.104 MatMul

- **MatMul**(**CvArr** src1, **CvArr** src2, **CvArr** dst)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
src2	A wrapped OpenCV object of type CvArr
dst	A wrapped OpenCV object of type CvArr

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.105 MatMulAdd

- **MatMulAdd**(**CvArr** src1, **CvArr** src2, **CvArr** src3, **CvArr** dst)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
src2	A wrapped OpenCV object of type CvArr
src3	A wrapped OpenCV object of type CvArr
dst	A wrapped OpenCV object of type CvArr

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.106 Max

- **Max**([CvArr](#) src1, [CvArr](#) src2, [CvArr](#) dst)
Finds per-element maximum of two arrays.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	The first source array
src2	The second source array
dst	The destination array

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.107 MaxS

- **MaxS**([CvArr](#) src1, [num](#) value, [CvArr](#) dst)
Finds per-element maximum of array and scalar.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
value	The scalar value
dst	The destination array

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.108 Merge

- **Merge**([CvArr](#) src0, [CvArr](#) src1=nil, [CvArr](#) src2=nil, [CvArr](#) src3=nil, [CvArr](#) dst)

Composes a multi-channel array from several single-channel arrays or inserts a single channel into the array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src0	Input channel 0
src1	Input channel 1
src2	Input channel 2
src3	Input channel 3
dst	Destination array

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.109 Min

- **Min**([CvArr](#) src1, [CvArr](#) src2, [CvArr](#) dst)

Finds per-element minimum of two arrays.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src1	The first source array
src2	The second source array
dst	The destination array

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Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.110 MinMaxLoc

- **num,num MinMaxLoc**(**CvArr** arr, **CvPoint** min_loc=nil, **CvPoint** max_loc=nil, **CvArr** mask=nil)

Finds global minimum and maximum in array or subarray.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

arr	The source array, single-channel or multi-channel with COI set
min_loc	A wrapped OpenCV object of type CvPoint with default value <i>nil</i>
max_loc	A wrapped OpenCV object of type CvPoint with default value <i>nil</i>
mask	The optional mask used to select a subarray

Returns

num - A floating point number defined by lua.h header, in default it is type double

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.111 MinS

- **MinS**(**CvArr** src1, **num** value, **CvArr** dst)

Finds per-element minimum of an array and a scalar.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src1	A wrapped OpenCV object of type CvArr
value	The scalar value
dst	The destination array

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.112 MixChannels

- **MixChannels**([CvArr](#) src, [int](#) src_count, [CvArr](#) dst, [int](#) dst_count, [int](#)[] from_to, [int](#) pair_count)

Copies several channels from input arrays to certain channels of output arrays

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Input arrays
src_count	An integer type number
dst	Destination arrays
dst_count	An integer type number
from_to	An integer type number which is an array
pair_count	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.113 Mul

- **Mul**([CvArr](#) src1, [CvArr](#) src2, [CvArr](#) dst, [num](#) scale=1)

Calculates the per-element product of two arrays.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	The first source array
src2	The second source array
dst	The destination array
scale	Optional scale factor

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.114 MulSpectrums

- **MulSpectrums**([CvArr](#) src1, [CvArr](#) src2, [CvArr](#) dst, [int](#) flags)

Performs per-element multiplication of two Fourier spectrums.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

src1	The first source array
src2	The second source array
dst	The destination array of the same type and the same size as the source arrays
flags	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.115 MulTransposed

- **MulTransposed**([CvArr](#) src1, [CvArr](#) dst, [int](#) order, [CvArr](#) delta=nil, [num](#) scale=1)

Calculates the product of an array and a transposed array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

src1	A wrapped OpenCV object of type <code>CvArr</code>
dst	The destination matrix. Must be <code>CV_32F</code> or <code>CV_64F</code> .
order	Order of multipliers
delta	An optional array, subtracted from <code>src</code> before multiplication
scale	An optional scaling

Returns

none - function doesn't return anything.

The documentation was generated from :

- `lua_core.cpp`

3.1.116 NextGraphItem

- **`int NextGraphItem(CvGraphScanner scanner)`**

Executes one or more steps of the graph traversal procedure.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

scanner	Graph traversal state. It is updated by this function.
----------------	--

Returns

`int` - An integer type number defined by architecture

The documentation was generated from :

- `lua_core.cpp`

3.1.117 NextNArraySlice

- **`int NextNArraySlice(CvNArrayIterator array_iterator)`**

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

array_iterator	A wrapped OpenCV object of type CvNArrayIterator
-----------------------	--

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.118 NextTreeNode

- [userdata](#) **NextTreeNode**([CvTreeNodeIterator](#) tree_iterator)

Returns the currently observed node and moves the iterator toward the next node.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

tree_iterator	Tree iterator initialized by the function
----------------------	---

Returns

[userdata](#) - An unspecified C pointer to memory

The documentation was generated from :

- lua_core.cpp

3.1.119 Norm

- [num](#) **Norm**([CvArr](#) arr1, [CvArr](#) arr2=nil, [int](#) norm_type=CV_L2, [CvArr](#) mask=nil)

Calculates absolute array norm, absolute difference norm, or relative difference norm.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

arr1	The first source image
arr2	The second source image. If it is NULL, the absolute norm of <code>arr1</code> is calculated, otherwise the absolute or relative norm of <code>arr1-arr2</code> is calculated.
norm_type	An integer type number with default value <code>CV_L2</code>
mask	The optional operation mask

Returns

`num` - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.120 Normalize

- **Normalize**(`CvArr` src, `CvArr` dst, `num` a=1, `num` b=0, `int` norm_type=CV_L2, `CvArr` mask=nil)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

src	A wrapped OpenCV object of type <code>CvArr</code>
dst	A wrapped OpenCV object of type <code>CvArr</code>
a	A floating point number with default value <code>1</code>
b	A floating point number with default value <code>0</code>
norm_type	An integer type number with default value <code>CV_L2</code>
mask	A wrapped OpenCV object of type <code>CvArr</code> with default value <code>nil</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.121 Not

- **Not**([CvArr](#) src1, [CvArr](#) dst)

Performs per-element bit-wise inversion of array elements.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
dst	The destination array

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.122 Or

- **Or**([CvArr](#) src1, [CvArr](#) src2, [CvArr](#) dst, [CvArr](#) mask=nil)

Calculates per-element bit-wise disjunction of two arrays.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	The first source array
src2	The second source array
dst	The destination array
mask	Operation mask, 8-bit single channel array; specifies elements of the destination array to be changed

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.123 OrS

- **OrS**(CvArr src1, CvScalar value, CvArr dst, CvArr mask=nil)

Calculates a per-element bit-wise disjunction of an array and a scalar.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
value	Scalar to use in the operation
dst	The destination array
mask	Operation mask, 8-bit single channel array; specifies elements of the destination array to be changed

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.124 PerspectiveTransform

- **PerspectiveTransform**(CvArr src1, CvArr dst, CvMat mat)

Performs perspective matrix transformation of a vector array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
dst	The destination three-channel floating-point array
mat	3×3 or 4×4 transformation matrix

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.125 PolarToCart

- **PolarToCart**([CvArr](#) magnitude, [CvArr](#) angle, [CvArr](#) x, [CvArr](#) y, [int](#) angle_in_degrees=0)

Calculates Cartesian coordinates of 2d vectors represented in polar form.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

magnitude	The array of magnitudes. If it is NULL, the magnitudes are assumed to be all 1's.
angle	The array of angles, whether in radians or degrees
x	The destination array of x-coordinates, may be set to NULL if it is not needed
y	The destination array of y-coordinates, may be set to NULL if it is not needed
angle_in_degrees	An integer type number with default value 0

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.126 PolyLine

- **PolyLine**([CvArr](#) img, [CvPoint](#)[] pts, [int](#)[] npts, [int](#) contours, [int](#) is_closed, [CvScalar](#) color, [int](#) thickness=1, [int](#) line_type=8, [int](#) shift=0)

Draws simple or thick polygons.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

img	Image
pts	Array of pointers to polygons
npts	Array of polygon vertex counters
contours	Number of contours that bind the filled region
is_closed	An integer type number
color	Polyline color
thickness	Thickness of the polyline edges
line_type	An integer type number with default value 8
shift	Number of fractional bits in the vertex coordinates

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.127 Pow

- **Pow**(CvArr src1, CvArr dst, num power)

Raises every array element to a power.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
dst	The destination array, should be the same type as the source
power	The exponent of power

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.128 PrevTreeNode

- **userdata PrevTreeNode**(CvTreeNodeIterator tree_iterator)

Returns the currently observed node and moves the iterator toward the previous node.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

tree_iterator	Tree iterator initialized by the function
----------------------	---

Returns

[userdata](#) - An unspecified C pointer to memory

The documentation was generated from :

- lua_core.cpp

3.1.129 ProjectPCA

- **ProjectPCA**([CvArr](#) data, [CvArr](#) mean, [CvArr](#) eigenvals, [CvArr](#) result)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

data	A wrapped OpenCV object of type CvArr
mean	A wrapped OpenCV object of type CvArr
eigenvals	A wrapped OpenCV object of type CvArr
result	A wrapped OpenCV object of type CvArr

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.130 Ptr1D

- [userdata](#), [int](#) **Ptr1D**([CvArr](#) arr, [int](#) idx0, [int](#) gettype=0)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

arr	A wrapped OpenCV object of type CvArr
idx0	An integer type number
gettype	An integer type number with default value 0

Returns

[userdata](#) - An unspecified C pointer to memory
[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.131 Ptr2D

- [userdata](#), [int](#) **Ptr2D**([CvArr](#) arr, [int](#) idx0, [int](#) idx1, [int](#) gettype=0)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

arr	A wrapped OpenCV object of type CvArr
idx0	An integer type number
idx1	An integer type number
gettype	An integer type number with default value 0

Returns

[userdata](#) - An unspecified C pointer to memory
[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.132 Ptr3D

- `userdata, int Ptr3D(CvArr arr, int idx0, int idx1, int idx2, int gettype=0)`

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

arr	A wrapped OpenCV object of type CvArr
idx0	An integer type number
idx1	An integer type number
idx2	An integer type number
gettype	An integer type number with default value 0

Returns

- `userdata` - An unspecified C pointer to memory
- `int` - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.133 PtrND

- `userdata, int, int PtrND(CvArr arr, int[] idx, int gettype=0, int create_node=1, int gethashval=0)`

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

arr	A wrapped OpenCV object of type CvArr
idx	An integer type number which is an array
gettype	An integer type number with default value 0
create_node	An integer type number with default value 1
gethashval	An integer type number with default value 0

Returns

- [userdata](#) - An unspecified C pointer to memory
- [int](#) - An integer type number defined by architecture
- [int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.134 PutText

- **PutText**([CvArr](#) img, [string](#) text, [CvPoint](#) org, [CvFont](#) font, [CvScalar](#) color)

Draws a text string.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

img	Input image
text	String to print
org	Coordinates of the bottom-left corner of the first letter
font	Pointer to the font structure
color	Text color

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.135 RandArr

- **RandArr**([CvRNG](#) rng, [CvArr](#) arr, [int](#) dist_type, [CvScalar](#) param1, [CvScalar](#) param2)

Fills an array with random numbers and updates the RNG state.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

rng	RNG state initialized by RNG
arr	The destination array
dist_type	An integer type number
param1	The first parameter of the distribution. In the case of a uniform distribution it is the inclusive lower boundary of the random numbers range. In the case of a normal distribution it is the mean value of the random numbers.
param2	The second parameter of the distribution. In the case of a uniform distribution it is the exclusive upper boundary of the random numbers range. In the case of a normal distribution it is the standard deviation of the random numbers.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.136 RandInt

- `int RandInt(CvRNG rng)`

Returns a 32-bit unsigned integer and updates RNG.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

rng	RNG state initialized by <code>RandInit</code> and, optionally, customized by <code>RandSetRange</code> (though, the latter function does not affect the discussed function outcome)
------------	--

Returns

`int` - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.137 RandReal

- **num** **RandReal**(CvRNG rng)

Returns a floating-point random number and updates RNG.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

rng	RNG state initialized by RNG
------------	-------------------------------------

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.138 RandShuffle

- **RandShuffle**(CvArr mat, CvRNG rng, **num** iter_factor=1)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

mat	A wrapped OpenCV object of type CvArr
rng	A wrapped OpenCV object of type CvRNG
iter_factor	A floating point number with default value <i>1</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.139 Rectangle

- **Rectangle**([CvArr](#) img, [CvPoint](#) pt1, [CvPoint](#) pt2, [CvScalar](#) color, [int](#) thickness=1, [int](#) line_type=8, [int](#) shift=0)

Draws a simple, thick, or filled rectangle.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

img	Image
pt1	One of the rectangle's vertices
pt2	Opposite rectangle vertex
color	Line color (RGB) or brightness (grayscale image)
thickness	Thickness of lines that make up the rectangle. Negative values, e.g., CV_FILLED, cause the function to draw a filled rectangle.
line_type	An integer type number with default value 8
shift	Number of fractional bits in the point coordinates

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.140 Reduce

- **Reduce**([CvArr](#) src, [CvArr](#) dst, [int](#) dim=-1, [int](#) op=CV_REDUCE_SUM)

Reduces a matrix to a vector.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

src	The input matrix.
dst	The output single-row/single-column vector that accumulates somehow all the matrix rows/columns.
dim	The dimension index along which the matrix is reduced. 0 means that the matrix is reduced to a single row, 1 means that the matrix is reduced to a single column and -1 means that the dimension is chosen automatically by analysing the dst size.
op	An integer type number with default value <i>CV_REDUCE_SUM</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.141 ReleaseGraphScanner

- **ReleaseGraphScanner**([CvGraphScanner](#) scanner)

Completes the graph traversal procedure.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

scanner	Double pointer to graph traverser
----------------	-----------------------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.142 ReleaseImage

- **ReleaseImage**([IplImage](#) image)

Deallocates the image header and the image data.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	Double pointer to the image header
--------------	------------------------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.143 ReleaseImageHeader

- **ReleaseImageHeader**([IplImage](#) image)

Deallocates an image header.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

image	Double pointer to the image header
--------------	------------------------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.144 ReleaseMat

- **ReleaseMat**([CvMat](#) mat)

Deallocates a matrix.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

mat	Double pointer to the matrix
------------	------------------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.145 ReleaseMatND

- **ReleaseMatND**([CvMatND](#) mat)

Deallocates a multi-dimensional array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

mat	Double pointer to the array
------------	-----------------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.146 ReleaseMemStorage

- **ReleaseMemStorage**([CvMemStorage](#) storage)

Releases memory storage.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

storage	Pointer to the released storage
----------------	---------------------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.147 ReleaseSparseMat

- **ReleaseSparseMat**([CvSparseMat](#) mat)

Deallocates sparse array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

mat	Double pointer to the array
------------	-----------------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.148 RemoveNodeFromTree

- **RemoveNodeFromTree**([userdata](#) node, [userdata](#) frame)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

node	An unspecified C pointer to memory
frame	An unspecified C pointer to memory

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.149 Repeat

- **Repeat**([CvArr](#) src, [CvArr](#) dst)

Fill the destination array with repeated copies of the source array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source array, image or matrix
dst	Destination array, image or matrix

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.150 ResetImageROI

- **ResetImageROI**([IplImage](#) image)

Resets the image ROI to include the entire image and releases the ROI structure.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	A pointer to the image header
--------------	-------------------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.151 RestoreMemStoragePos

- **RestoreMemStoragePos**([CvMemStorage](#) storage, [CvMemStorage](#) pos)

Restores memory storage position.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

storage	Memory storage
pos	New storage top position

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.152 Round

- **int Round**([num](#) value)

Converts a floating-point number to the nearest integer value.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

value	The input floating-point value
--------------	--------------------------------

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.153 SVBkSb

- **SVBkSb**([CvArr](#) W, [CvArr](#) U, [CvArr](#) V, [CvArr](#) B, [CvArr](#) X, [int](#) flags)

Performs singular value back substitution.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

W	Matrix or vector of singular values
U	Left orthogonal matrix (tranposed, perhaps)
V	Right orthogonal matrix (tranposed, perhaps)
B	The matrix to multiply the pseudo-inverse of the original matrix <i>A</i> by. This is an optional parameter. If it is omitted then it is assumed to be an identity matrix of an appropriate size (so that <i>X</i> will be the reconstructed pseudo-inverse of <i>A</i>).
X	The destination matrix: result of back substitution
flags	Operation flags, should match exactly to the <code>flags</code> passed to SVD

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.154 SVD

- **SVD**([CvArr](#) A, [CvArr](#) W, [CvArr](#) U=nil, [CvArr](#) V=nil, [int](#) flags=0)

Performs singular value decomposition of a real floating-point matrix.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

A	Source $M \times N$ matrix
W	Resulting singular value diagonal matrix ($M \times N$ or $\min(M,N) \times \min(M,N)$) or $\min(M,N) \times 1$ vector of the singular values
U	Optional left orthogonal matrix, $M \times \min(M,N)$ (when <code>CV_SVD_U_T</code> is not set), or $\min(M,N) \times M$ (when <code>CV_SVD_U_T</code> is set), or $M \times M$ (regardless of <code>CV_SVD_U_T</code> flag).
V	Optional right orthogonal matrix, $N \times \min(M,N)$ (when <code>CV_SVD_V_T</code> is not set), or $\min(M,N) \times N$ (when <code>CV_SVD_V_T</code> is set), or $N \times N$ (regardless of <code>CV_SVD_V_T</code> flag).
flags	An integer type number with default value 0

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.155 SaveMemStorage

- **SaveMemStorage**([CvMemStorage](#) storage, [CvMemStorage](#) pos)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

storage	A wrapped OpenCV object of type <code>CvMemStorage</code>
pos	A wrapped OpenCV object of type <code>CvMemStorage</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.156 ScaleAdd

- **ScaleAdd**([CvArr](#) src1, [CvScalar](#) scale, [CvArr](#) src2, [CvArr](#) dst)

Calculates the sum of a scaled array and another array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

src1	The first source array
scale	Scale factor for the first array
src2	The second source array
dst	The destination array

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.157 SeqElemIdx

- **int SeqElemIdx**([CvSeq](#) seq, [userdata](#) element, [CvSeqBlock](#) block=nil)

Returns the index of a specific sequence element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

seq	Sequence
element	Pointer to the element within the sequence
block	Optional argument. If the pointer is not NULL, the address of the sequence block that contains the element is stored in this location.

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.158 SeqInsert

- **userdata** **SeqInsert**(**CvSeq** seq, **int** before_index, **userdata** element=nil)

Inserts an element in the middle of a sequence.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
before_index	An integer type number
element	An unspecified C pointer to memory with default value <i>nil</i>

Returns

userdata - An unspecified C pointer to memory

The documentation was generated from :

- lua_core.cpp

3.1.159 SeqInsertSlice

- **SeqInsertSlice**(**CvSeq** seq, **int** before_index, **CvArr** from_arr)

Inserts an array in the middle of a sequence.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
before_index	An integer type number
from_arr	A wrapped OpenCV object of type CvArr

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.160 SeqInvert

- **SeqInvert**([CvSeq](#) seq)

Reverses the order of sequence elements.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
------------	----------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.161 SeqPop

- **SeqPop**([CvSeq](#) seq, [userdata](#) element=nil)

Removes an element from the end of a sequence.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
element	Optional parameter . If the pointer is not zero, the function copies the removed element to this location.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.162 SeqPopFront

- **SeqPopFront**([CvSeq](#) seq, [userdata](#) element=nil)

Removes an element from the beginning of a sequence.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

seq	Sequence
element	Optional parameter. If the pointer is not zero, the function copies the removed element to this location.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.163 SeqPopMulti

- **SeqPopMulti**([CvSeq](#) seq, [userdata](#)[] elements, [int](#) count, [int](#) in_front=0, [string](#) convert_to="")

Removes several elements from either end of a sequence.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

seq	Sequence
elements	Removed elements
count	Number of elements to pop
in_front	An integer type number with default value 0
convert_to	An array of characters with default value <i>with default value 0</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.164 SeqPush

- [userdata](#) **SeqPush**([CvSeq](#) seq, [userdata](#) element=nil)

Adds an element to the end of a sequence.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
element	Added element

Returns

[userdata](#) - An unspecified C pointer to memory

The documentation was generated from :

- lua_core.cpp

3.1.165 SeqPushFront

- [userdata](#) **SeqPushFront**([CvSeq](#) seq, [userdata](#) element=nil)

Adds an element to the beginning of a sequence.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
element	Added element

Returns

[userdata](#) - An unspecified C pointer to memory

The documentation was generated from :

- lua_core.cpp

3.1.166 SeqPushMulti

- **SeqPushMulti**([CvSeq](#) seq, [userdata](#)[] elements, [int](#) count, [int](#) in_front=0)

Pushes several elements to either end of a sequence.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
elements	Added elements
count	Number of elements to push
in_front	An integer type number with default value 0

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.167 SeqRemove

- **SeqRemove**([CvSeq](#) seq, [int](#) index)

Removes an element from the middle of a sequence.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
index	Index of removed element

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.168 SeqRemoveSlice

- **SeqRemoveSlice**([CvSeq](#) seq, [CvSlice](#) slice)

Removes a sequence slice.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
slice	The part of the sequence to remove

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.169 Set

- **Set**([CvArr](#) src, [CvScalar](#) value, [CvArr](#) mask=nil)

Sets every element of an array to a given value.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	A wrapped OpenCV object of type CvArr
value	The assigned value
mask	Operation mask, 8-bit single channel array; specifies elements of the destination array to be changed

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.170 Set1D

- **Set1D**([CvArr](#) arr, [int](#) idx0, [CvScalar](#) value)

Set a specific array element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

arr	Input array
idx0	An integer type number
value	The value to assign to the element

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.171 Set2D

- **Set2D**([CvArr](#) arr,[int](#) idx0, [int](#) idx1, [CvScalar](#) value)

Set a specific array element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

arr	Input array
idx0	Zero-based element row index
idx1	Zero-based element column index
value	The value to assign to the element

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.172 Set3D

- **Set3D**([CvArr](#) arr, [int](#) idx0, [int](#) idx1, [int](#) idx2, [CvScalar](#) value)

Set a specific array element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

arr	Input array
idx0	Zero-based element index
idx1	Zero-based element index
idx2	Zero-based element index
value	The value to assign to the element

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.173 SetAdd

- [int](#), [userdata](#) **SetAdd**([CvSet](#) set_header, [CvSetElem](#) elem=nil, [int](#) get-newelem_ptr=0)

Occupies a node in the set.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

set_header	A wrapped OpenCV object of type CvSet
elem	Optional input argument, an inserted element. If not NULL, the function copies the data to the allocated node (the MSB of the first integer field is cleared after copying).
get-newelem_ptr	An integer type number with default value 0

Returns

- [int](#) - An integer type number defined by architecture
- [userdata](#) - An unspecified C pointer to memory

The documentation was generated from :

- lua_core.cpp

3.1.174 SetData

- SetData**([CvArr](#) arr, [num](#)[] data, [int](#) step, table type)

Assigns user data to the array header.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

arr	Array header
data	User data
step	Full row length in bytes
type	A lua table

Returns

- none** - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.175 SetIdentity

- SetIdentity**([CvArr](#) mat, [CvScalar](#) value=[RealScalar](#)(1))

Initializes a scaled identity matrix.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

mat	The matrix to initialize (not necessarily square)
value	The value to assign to the diagonal elements

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.176 SetImageCOI

- **SetImageCOI**([IplImage](#) image, [int](#) coi)

Sets the channel of interest in an IplImage.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	A pointer to the image header
coi	The channel of interest. 0 - all channels are selected, 1 - first channel is selected, etc. Note that the channel indices become 1-based.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.177 SetImageROI

- **SetImageROI**([IplImage](#) image, [CvRect](#) rect)

Sets an image Region Of Interest (ROI) for a given rectangle.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	A pointer to the image header
rect	The ROI rectangle

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.178 SetND

- **SetND**(CvArr arr, int[] idx, CvScalar value)

Set a specific array element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

arr	Input array
idx	An integer type number which is an array
value	The value to assign to the element

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.179 SetReal1D

- **SetReal1D**(CvArr arr, int idx0, num value)

Set a specific array element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

arr	Input array
idx0	An integer type number
value	The value to assign to the element

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.180 SetReal2D

- **SetReal2D**(**CvArr** arr, **int** idx0, **int** idx1, **num** value)

Set a specific array element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

arr	Input array
idx0	Zero-based element row index
idx1	Zero-based element column index
value	The value to assign to the element

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.181 SetReal3D

- **SetReal3D**(**CvArr** arr, **int** idx0, **int** idx1, **int** idx2, **num** value)

Set a specific array element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

arr	Input array
idx0	Zero-based element index
idx1	Zero-based element index
idx2	Zero-based element index
value	The value to assign to the element

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.182 SetRealND

- **SetRealND**([CvArr](#) arr, [int](#)[] idx, [num](#) value)

Set a specific array element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

arr	Input array
idx	An integer type number which is an array
value	The value to assign to the element

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.183 SetRemove

- **SetRemove**([CvSet](#) set_header, [int](#) index)

Removes an element from a set.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

set_header	A wrapped OpenCV object of type CvSet
index	Index of the removed element

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.184 SetRemoveByPtr

- **SetRemoveByPtr**([CvSet](#) set_header, [userdata](#) elem)

Removes a set element based on its pointer.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

set_header	A wrapped OpenCV object of type CvSet
elem	Removed element

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.185 SetSeqBlockSize

- **SetSeqBlockSize**([CvSeq](#) seq, [int](#) delta_elems)

Sets up sequence block size.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
delta_elems	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.186 SetSeqReaderPos

- **SetSeqReaderPos**([CvSeqReader](#) reader, [int](#) index, [int](#) is_relative=0)

Moves the reader to the specified position.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

reader	Reader state
index	The destination position. If the positioning mode is used (see the next parameter), the actual position will be <code>index mod reader->seq->total</code> .
is_relative	If it is not zero, then <code>index</code> is a relative to the current position

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.187 SetZero

- **SetZero**([CvArr](#) arr)

Clears the array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

arr	Array to be cleared
------------	---------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.188 SliceLength

- **int SliceLength**(CvSlice slice, CvSeq seq)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

slice	A wrapped OpenCV object of type CvSlice
seq	A wrapped OpenCV object of type CvSeq

Returns

int - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.189 Solve

- **int Solve**(CvArr src1, CvArr src2, CvArr dst, int method=CV_LU)

Solves a linear system or least-squares problem.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
src2	A wrapped OpenCV object of type CvArr
dst	A wrapped OpenCV object of type CvArr
method	An integer type number with default value <i>CV_LU</i>

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.190 SolveCubic

- [int](#) **SolveCubic**([CvMat](#) coeffs, [CvMat](#) roots)

Finds the real roots of a cubic equation.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

coeffs	The equation coefficients, an array of 3 or 4 elements
roots	The output array of real roots which should have 3 elements

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.191 SolvePoly

- **SolvePoly**([CvMat](#) coeffs , [CvMat](#) roots2, [int](#) maxiter=20, [int](#) fig=100)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

coeffs	A wrapped OpenCV object of type CvMat
roots2	A wrapped OpenCV object of type CvMat
maxiter	An integer type number with default value 20
fig	An integer type number with default value 100

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.192 Sort

- **Sort**([CvArr](#) src, [CvArr](#) dst=nil, [CvArr](#) idxmat=nil, [int](#) flags=0)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	A wrapped OpenCV object of type CvArr
dst	A wrapped OpenCV object of type CvArr with default value <i>nil</i>
idxmat	A wrapped OpenCV object of type CvArr with default value <i>nil</i>
flags	An integer type number with default value <i>0</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.193 Split

- **Split**([CvArr](#) src, [CvArr](#) dst0, [CvArr](#) dst1, [CvArr](#) dst2, [CvArr](#) dst3)

Divides multi-channel array into several single-channel arrays or extracts a single channel from the array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source array
dst0	Destination channel 0
dst1	Destination channel 1
dst2	Destination channel 2
dst3	Destination channel 3

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.194 Sqrt

- **num** **Sqrt**(**num** value)

Calculates the square root.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

value	The input floating-point value
--------------	--------------------------------

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.195 StartAppendToSeq

- **StartAppendToSeq**(**CvSeq** seq, **CvSeqWriter** writer)

Initializes the process of writing data to a sequence.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Pointer to the sequence
writer	Writer state; initialized by the function

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.196 StartReadSeq

- **StartReadSeq**([CvSeq](#) seq, [CvSeqReader](#) reader, [int](#) reverse=0)

Initializes the process of sequential reading from a sequence.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

seq	Sequence
reader	Reader state; initialized by the function
reverse	Determines the direction of the sequence traversal. If <code>reverse</code> is 0, the reader is positioned at the first sequence element; otherwise it is positioned at the last element.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.197 StartWriteSeq

- **StartWriteSeq**([int](#) seq_flags, [int](#) header_size, [int](#) elem_size, [CvMemStorage](#) storage, [CvSeqWriter](#) writer)

Creates a new sequence and initializes a writer for it.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

seq_flags	Flags of the created sequence. If the sequence is not passed to any function working with a specific type of sequences, the sequence value may be equal to 0; otherwise the appropriate type must be selected from the list of predefined sequence types.
header_size	Size of the sequence header. The parameter value may not be less than <code>sizeof(CvSeq)</code> . If a certain type or extension is specified, it must fit within the base type header.
elem_size	Size of the sequence elements in bytes; must be consistent with the sequence type. For example, if a sequence of points is created (element type <code>CV_SEQ_ELTYPE_POINT</code>), then the parameter <code>elem_size</code> must be equal to <code>sizeof(CvPoint)</code> .
storage	Sequence location
writer	Writer state; initialized by the function

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.198 Sub

- **Sub**([CvArr](#) src1, [CvArr](#) src2, [CvArr](#) dst, [CvArr](#) mask=nil)

Computes the per-element difference between two arrays.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src1	The first source array
src2	The second source array
dst	The destination array
mask	Operation mask, 8-bit single channel array; specifies elements of the destination array to be changed

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.199 SubRS

- **SubRS**([CvArr](#) src1, [CvScalar](#) value, [CvArr](#) dst, [CvArr](#) mask=nil)

Computes the difference between a scalar and an array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
value	Scalar to subtract from
dst	The destination array
mask	Operation mask, 8-bit single channel array; specifies elements of the destination array to be changed

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.200 SubS

- **SubS**([CvArr](#) src1, [CvScalar](#) value, [CvArr](#) dst, [CvArr](#) mask=nil)

Computes the difference between an array and a scalar.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
value	Subtracted scalar
dst	The destination array
mask	Operation mask, 8-bit single channel array; specifies elements of the destination array to be changed

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.201 Transform

- **Transform**(CvArr src1, CvArr dst, CvMat transmat, CvMat shiftvec=nil)

Performs matrix transformation of every array element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
dst	The destination array
transmat	Transformation matrix
shiftvec	Optional shift vector

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.202 Transpose

- **Transpose**(CvArr src1, CvArr dst)

Transposes a matrix.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

src1	A wrapped OpenCV object of type <code>CvArr</code>
dst	The destination matrix

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.203 Xor

- **Xor**(`CvArr` src1, `CvArr` src2, `CvArr` dst, `CvArr` mask=nil)

Performs per-element bit-wise "exclusive or" operation on two arrays.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

src1	The first source array
src2	The second source array
dst	The destination array
mask	Operation mask, 8-bit single channel array; specifies elements of the destination array to be changed

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.204 XorS

- **XorS**(`CvArr` src1, `CvScalar` value, `CvArr` dst, `CvArr` mask=nil)

Performs per-element bit-wise "exclusive or" operation on an array and a scalar.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src1	A wrapped OpenCV object of type CvArr
value	Scalar to use in the operation
dst	The destination array
mask	Operation mask, 8-bit single channel array; specifies elements of the destination array to be changed

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.205 getrawdata

- [userdata](#), [int](#) **getrawdata**([CvArr](#) arr, table type)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

arr	A wrapped OpenCV object of type CvArr
type	A lua table

Returns

[userdata](#) - An unspecified C pointer to memory
[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_core.cpp

3.1.206 iGet

- `num[] iGet(IplImage image, table type, int row, int col)`

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	A wrapped OpenCV object of type IplImage
type	A lua table
row	An integer type number
col	An integer type number

Returns

`num` - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.207 iSet

- `iSet(IplImage image, table type, int row, int col, num[] value)`

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	A wrapped OpenCV object of type IplImage
type	A lua table
row	An integer type number
col	An integer type number
value	A floating point number which is an array

Returns

`none` - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.1.208 mGet

- `num[] mGet(CvMat mat, table type, int row, int col)`

Returns the particular element of single-channel floating-point matrix.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

mat	Input matrix
type	A lua table
row	The zero-based index of row
col	The zero-based index of column

Returns

`num` - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_core.cpp

3.1.209 mSet

- `mSet(CvMat mat, table type, int row, int col, num[] value)`

Returns a specific element of a single-channel floating-point matrix.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

mat	The matrix
type	A lua table
row	The zero-based index of row
col	The zero-based index of column
value	The new value of the matrix element

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_core.cpp

3.2 Module calib3d

3.2.1 CalcMatMulDeriv

- **CalcMatMulDeriv**([CvMat](#) A, [CvMat](#) B, [CvMat](#) dAbda, [CvMat](#) daBdb)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

A	A wrapped OpenCV object of type CvMat
B	A wrapped OpenCV object of type CvMat
dAbda	A wrapped OpenCV object of type CvMat
daBdb	A wrapped OpenCV object of type CvMat

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.2 CalibrateCamera2

- **num** **CalibrateCamera2**([CvMat](#) object_points, [CvMat](#) image_points, [CvMat](#) point_counts, [CvSize](#) image_size, [CvMat](#) camera_matrix, [CvMat](#) distortion_matrix, [CvMat](#) rotation_vectors=nil, [CvMat](#) translation_vectors=nil, [int](#) flags=0)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

object_points	A wrapped OpenCV object of type <code>CvMat</code>
image_points	A wrapped OpenCV object of type <code>CvMat</code>
point_counts	A wrapped OpenCV object of type <code>CvMat</code>
image_size	A wrapped OpenCV object of type <code>CvSize</code>
camera_matrix	A wrapped OpenCV object of type <code>CvMat</code>
distortion_matrix	A wrapped OpenCV object of type <code>CvMat</code>
rotation_vectors	A wrapped OpenCV object of type <code>CvMat</code> with default value <i>nil</i>
translation_vectors	A wrapped OpenCV object of type <code>CvMat</code> with default value <i>nil</i>
flags	An integer type number with default value <i>0</i>

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_calib3d.cpp

3.2.3 CalibrationMatrixValues

- **num,num,num,num CalibrationMatrixValues**(`CvMat` camera_matrix, `CvSize` image_size, **num** aperture_width=0, **num** aperture_height=0, `CvPoint2D64f` principal_point=*nil*)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

camera_matrix	A wrapped OpenCV object of type <code>CvMat</code>
image_size	A wrapped OpenCV object of type <code>CvSize</code>
aperture_width	A floating point number with default value <i>0</i>
aperture_height	A floating point number with default value <i>0</i>
principal_point	A wrapped OpenCV object of type <code>CvPoint2D64f</code> with default value <i>nil</i>

Returns

- `num` - A floating point number defined by lua.h header, in default it is type double
- `num` - A floating point number defined by lua.h header, in default it is type double
- `num` - A floating point number defined by lua.h header, in default it is type double
- `num` - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_calib3d.cpp

3.2.4 CheckChessboard

- **CheckChessboard**(`IplImage` src, `CvSize` size)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src	A wrapped OpenCV object of type <code>IplImage</code>
size	A wrapped OpenCV object of type <code>CvSize</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.5 ComposeRT

- **ComposeRT**(`CvMat` _rvec1, `CvMat` _tvec1, `CvMat` _rvec2, `CvMat` _tvec2, `CvMat` _rvec3, `CvMat` _tvec3, `CvMat` dr3dr1=nil, `CvMat` dr3dt1=nil, `CvMat` dr3dr2=nil, `CvMat` dr3dt2=nil, `CvMat` dt3dr1=nil, `CvMat` dt3dt1=nil, `CvMat` dt3dr2=nil, `CvMat` dt3dt2=nil)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

_rvec1	A wrapped OpenCV object of type <code>CvMat</code>
_tvec1	A wrapped OpenCV object of type <code>CvMat</code>
_rvec2	A wrapped OpenCV object of type <code>CvMat</code>
_tvec2	A wrapped OpenCV object of type <code>CvMat</code>
_rvec3	A wrapped OpenCV object of type <code>CvMat</code>
_tvec3	A wrapped OpenCV object of type <code>CvMat</code>
dr3dr1	A wrapped OpenCV object of type <code>CvMat</code> with default value <i>nil</i>
dr3dt1	A wrapped OpenCV object of type <code>CvMat</code> with default value <i>nil</i>
dr3dr2	A wrapped OpenCV object of type <code>CvMat</code> with default value <i>nil</i>
dr3dt2	A wrapped OpenCV object of type <code>CvMat</code> with default value <i>nil</i>
dt3dr1	A wrapped OpenCV object of type <code>CvMat</code> with default value <i>nil</i>
dt3dt1	A wrapped OpenCV object of type <code>CvMat</code> with default value <i>nil</i>
dt3dr2	A wrapped OpenCV object of type <code>CvMat</code> with default value <i>nil</i>
dt3dt2	A wrapped OpenCV object of type <code>CvMat</code> with default value <i>ni</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.6 ComputeCorrespondEpilines

- **ComputeCorrespondEpilines**(`CvMat` points, `int` which_image, `CvMat` fundamental_matrix, `CvMat` correspondent_lines)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

points	A wrapped OpenCV object of type <code>CvMat</code>
which_image	An integer type number
fundamental_matrix	A wrapped OpenCV object of type <code>CvMat</code>
correspondent_lines	A wrapped OpenCV object of type <code>CvMat</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.7 ConvertPointsHomogeneous

- **ConvertPointsHomogeneous**([CvMat](#) src, [CvMat](#) dst)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	A wrapped OpenCV object of type CvMat
dst	A wrapped OpenCV object of type CvMat

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.8 CorrectMatches

- **CorrectMatches**([CvMat](#) F, [CvMat](#) points1, [CvMat](#) points2, [CvMat](#) new_points1, [CvMat](#) new_points2)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

F	A wrapped OpenCV object of type CvMat
points1	A wrapped OpenCV object of type CvMat
points2	A wrapped OpenCV object of type CvMat

new_points1	A wrapped OpenCV object of type CvMat
new_points2	A wrapped OpenCV object of type CvMat

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.9 DecomposeProjectionMatrix

- **DecomposeProjectionMatrix**([CvMat](#) projMatr, [CvMat](#) calibMatr, [CvMat](#) rotMatr, [CvMat](#) posVect, [CvMat](#) rotMatrX=nil, [CvMat](#) rotMatrY=nil, [CvMat](#) rotMatrZ=nil, [CvPoint3D64f](#) eurlerAngles=nil)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

projMatr	A wrapped OpenCV object of type CvMat
calibMatr	A wrapped OpenCV object of type CvMat
rotMatr	A wrapped OpenCV object of type CvMat
posVect	A wrapped OpenCV object of type CvMat
rotMatrX	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
rotMatrY	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
rotMatrZ	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
eurlerAngles	A wrapped OpenCV object of type CvPoint3D64f with default value <i>nil</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.10 DrawChessboardCorners

- **DrawChessboardCorners**([CvArr](#) image, [CvSize](#) pattern_size, [CvPoint2D32f](#)[] corners, [int](#) count, [int](#) pattern_was_found)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	A wrapped OpenCV object of type CvArr
pattern_size	A wrapped OpenCV object of type CvSize
corners	A wrapped OpenCV object of type CvPoint2D32f which is an array
count	An integer type number
pattern_was_found	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.11 FindChessboardCorners

- **int FindChessboardCorners**([CvArr](#) image, [CvSize](#) pattern_size, [CvPoint2D32f](#)[] corners, [int](#) flags=([CV_CALIB_CB_ADAPTIVE_THRESH](#)+[CV_CALIB_CB_NORMALIZE_IMAGE](#)))

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	A wrapped OpenCV object of type CvArr
pattern_size	A wrapped OpenCV object of type CvSize
corners	A wrapped OpenCV object of type CvPoint2D32f which is an array
flags	An integer type number with default value (CV_CALIB_CB_ADAPTIVE_THRESH

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_calib3d.cpp

3.2.12 FindExtrinsicCameraParams2

- **FindExtrinsicCameraParams2**([CvMat](#) object_points, [CvMat](#) image_points, [CvMat](#) camera_matrix, [CvMat](#) distortoin_coeffs, [CvMat](#) rotation_vector, [CvMat](#) translation_vector, [int](#) use_extrinsic_guess=0)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

object_points	A wrapped OpenCV object of type CvMat
image_points	A wrapped OpenCV object of type CvMat
camera_matrix	A wrapped OpenCV object of type CvMat
distortoin_coeffs	A wrapped OpenCV object of type CvMat
rotation_vector	A wrapped OpenCV object of type CvMat
translation_vector	A wrapped OpenCV object of type CvMat
use_extrinsic_guess	An integer type number with default value 0

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.13 FindFundamentalMat

- **num FindFundamentalMat**([CvMat](#) points1, [CvMat](#) points2, [CvMat](#) fundamental_matrix, [int](#) method=CV_FM_RANSAC, [num](#) param1=3, [num](#) param2=0.99, [CvMat](#) status=nil)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

points1	A wrapped OpenCV object of type CvMat
points2	A wrapped OpenCV object of type CvMat
fundamental_matrix	A wrapped OpenCV object of type CvMat
method	An integer type number with default value <i>CV_FM_RANSAC</i>
param1	A floating point number with default value <i>3</i>
param2	A floating point number with default value <i>0</i>
status	A wrapped OpenCV object of type CvMat with default value <i>nil</i>

Returns

[num](#) - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_calib3d.cpp

3.2.14 FindHomography

- **num FindHomography**([CvMat](#) src_points, [CvMat](#) dst_points, [CvMat](#) homography, [int](#) method=0, [num](#) ransacReprojThreshold=3, [CvMat](#) mask=nil)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

src_points	A wrapped OpenCV object of type CvMat
dst_points	A wrapped OpenCV object of type CvMat
homography	A wrapped OpenCV object of type CvMat
method	An integer type number with default value <i>0</i>

ransacReprojThreshold	A floating point number with default value 3
mask	A wrapped OpenCV object of type CvMat with default value <i>nil</i>

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_calib3d.cpp

3.2.15 FindStereoCorrespondenceBM

- **FindStereoCorrespondenceBM**(**CvArr** left, **CvArr** right, **CvArr** disparity, CvStereoBMStatestate)

Computes the disparity map using block matching algorithm.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

left	The left single-channel, 8-bit image.
right	The right image of the same size and the same type.
disparity	The output single-channel 16-bit signed, or 32-bit floating-point disparity map of the same size as input images. In the first case the computed disparities are represented as fixed-point numbers with 4 fractional bits (i.e. the computed disparity values are multiplied by 16 and rounded to integers).

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.16 FindStereoCorrespondenceGC

- **FindStereoCorrespondenceGC**(**CvMat** left, **CvMat** right, **CvMat** disparityLeft, **CvMat** disparityRight, CvStereoBMStatestate, **int** useDiparityGuess=0)

Computes the disparity map using graph cut-based algorithm.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

left	The left single-channel, 8-bit image.
right	The right image of the same size and the same type.
disparityLeft	A wrapped OpenCV object of type <code>CvMat</code>
disparityRight	A wrapped OpenCV object of type <code>CvMat</code>
useDisparityGuess	An integer type number with default value <code>0</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.17 GetOptimalNewCameraMatrix

- **GetOptimalNewCameraMatrix**(`CvMat` camera_matrix, `CvMat` dist_coeffs, `CvSize` image_size, `num` alpha, `CvMat` new_camera_matrix, `CvSize` new_image_size=`cv.Size(0,0)`, `CvRect` valid_pixel_roi=`nil`)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

camera_matrix	A wrapped OpenCV object of type <code>CvMat</code>
dist_coeffs	A wrapped OpenCV object of type <code>CvMat</code>
image_size	A wrapped OpenCV object of type <code>CvSize</code>
alpha	A floating point number
new_camera_matrix	A wrapped OpenCV object of type <code>CvMat</code>
new_image_size	A wrapped OpenCV object of type <code>CvSize</code> with default value <code>cv</code>
valid_pixel_roi	A wrapped OpenCV object of type <code>CvRect</code> with default value <code>nil</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.18 InitIntrinsicParams2D

- **InitIntrinsicParams2D**([CvMat](#) object_points, [CvMat](#) image_points, [CvMat](#) npoints, [CvSize](#) image_size, [CvMat](#) camera_matrix, [num](#) aspect_ratio=0)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

object_points	A wrapped OpenCV object of type CvMat
image_points	A wrapped OpenCV object of type CvMat
npoints	A wrapped OpenCV object of type CvMat
image_size	A wrapped OpenCV object of type CvSize
camera_matrix	A wrapped OpenCV object of type CvMat
aspect_ratio	A floating point number with default value <i>0</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.19 POSIT

- **POSIT**([CvPOSITObject](#) posit_obj, [CvPoint2D32f\[\]](#) image_points, [num](#) focal_lenght, [CvTermCriteria](#) criteria,)

Implements the POSIT algorithm.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

posit_obj	A wrapped OpenCV object of type CvPOSITObject
image_points	A wrapped OpenCV object of type CvPoint2D32f which is an array
focal_lenght	A floating point number
criteria	Termination criteria of the iterative POSIT algorithm

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.20 ProjectPoints2

- **ProjectPoints2**([CvMat](#) object_points, [CvMat](#) rotation_vector, [CvMat](#) translation_vector, [CvMat](#) camera_matrix, [CvMat](#) distortoin_coeffs, [CvMat](#) image_points, [CvMat](#) dpdrot=nil, [CvMat](#) dpdt=nil, [CvMat](#) dpdf=nil, [CvMat](#) dpdc=nil, [CvMat](#) dpddist=nil, [num](#) aspect_ratio=0)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

object_points	A wrapped OpenCV object of type CvMat
rotation_vector	A wrapped OpenCV object of type CvMat
translation_vector	A wrapped OpenCV object of type CvMat
camera_matrix	A wrapped OpenCV object of type CvMat
distortoin_coeffs	A wrapped OpenCV object of type CvMat
image_points	A wrapped OpenCV object of type CvMat

dpdrot	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
dpdt	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
dpdf	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
dpdc	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
dpddist	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
as- pect_ratio	A floating point number with default value <i>0</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.21 RANSACUpdateNumIters

- **num** **RANSACUpdateNumIters**(**num** p, **num** err_prob, **int** model_points, **int** max_iter)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

p	A floating point number
err_prob	A floating point number
model_points	An integer type number
max_iter	An integer type number

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_calib3d.cpp

3.2.22 RQDecomp3x3

- **RQDecomp3x3**([CvMat](#) matrixM, [CvMat](#) matrixR, [CvMat](#) matrixQ, [CvMat](#) matrixQx=nil, [CvMat](#) matrixQy=nil, [CvMat](#) matrixQz=nil, [CvPoint3D64f](#) eurlerAngles=nil)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

matrixM	A wrapped OpenCV object of type CvMat
matrixR	A wrapped OpenCV object of type CvMat
matrixQ	A wrapped OpenCV object of type CvMat
matrixQx	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
matrixQy	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
matrixQz	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
eurlerAngles	A wrapped OpenCV object of type CvPoint3D64f with default value <i>nil</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.23 ReleasePOSITObject

- **ReleasePOSITObject**([CvPOSITObject](#) posit_obj)

Deallocates a 3D object structure.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

posit_obj	A wrapped OpenCV object of type CvPOSITObject
------------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.24 ReleaseStereoBMState

- **ReleaseStereoBMState**([CvStereoBMState](#) state)

Releases block matching stereo correspondence structure.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

state	Double pointer to the released structure.
--------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.25 ReleaseStereoGCState

- **ReleaseStereoGCState**([CvStereoGCState](#) state)

Releases the state structure of the graph cut-based stereo correspondence algorithm.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

state	Double pointer to the released structure.
--------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.26 ReprojectImageTo3D

- **ReprojectImageTo3D**([CvArr](#) disparityImage, [CvArr](#) _3dImage, [CvMat](#) Q, [int](#) handleMissingValues=0)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

disparityImage	A wrapped OpenCV object of type CvArr
_3dImage	A wrapped OpenCV object of type CvArr
Q	A wrapped OpenCV object of type CvMat
handleMissingValues	An integer type number with default value 0

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.27 Rodrigues2

- **num Rodrigues2**([CvMat](#) src, [CvMat](#) dst, [CvMat](#) jacobian=nil)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	A wrapped OpenCV object of type CvMat
dst	A wrapped OpenCV object of type CvMat
jacobian	A wrapped OpenCV object of type CvMat with default value <i>nil</i>

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_calib3d.cpp

3.2.28 StereoCalibrate

- **num StereoCalibrate**([CvMat](#) object_points, [CvMat](#) image_points, [CvMat](#) camera_matrix1, [CvMat](#) dist_coeffs1, [CvMat](#) camera_matrix2, [CvMat](#) dist_coeffs2, [CvSize](#) size, [CvMat](#) R, [CvMat](#) T, [CvMat](#) E=nil, [CvMat](#) P2, [CvMat](#) F=nil, [CvTermCriteria](#) term_crit=cv.TermCriteria(CV_TERMCRIT_ITER+CV_TERMCRIT_EPS,30,0,000006), [int](#) flags=CV_CALIB_FIX_INTRINSIC)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

object_points	A wrapped OpenCV object of type CvMat
image_points	A wrapped OpenCV object of type CvMat
camera_matrix1	A wrapped OpenCV object of type CvMat
dist_coeffs1	A wrapped OpenCV object of type CvMat
camera_matrix2	A wrapped OpenCV object of type CvMat
dist_coeffs2	A wrapped OpenCV object of type CvMat
size	A wrapped OpenCV object of type CvSize
R	A wrapped OpenCV object of type CvMat
T	A wrapped OpenCV object of type CvMat
E	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
P2	A wrapped OpenCV object of type CvMat
F	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
term_crit	A wrapped OpenCV object of type CvTermCriteria with default value <i>cv</i>
flags	An integer type number with default value <i>CV_CALIB_FIX_INTRINSIC</i>

Returns

- num** - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_calib3d.cpp

3.2.29 StereoRectify

- **StereoRectify**([CvMat](#) camera_matrix1, [CvMat](#) camera_matrix2, [CvMat](#) dist_coeffs1, [CvMat](#) dist_coeffs2, [CvSize](#) image_size, [CvMat](#) R, [CvMat](#) T, [CvMat](#) R1, [CvMat](#) R2, [CvMat](#) P1, [CvMat](#) P2, [CvMat](#) Q=nil, [int](#) flags=CV_CALIB_ZERO_DISPARITY, [num](#) alpha=-1, [CvSize](#) new_image_size=cv.Size(0,0), [CvRect](#) valid_pix_roi1=nil, [CvRect](#) valid_pix_roi2=nil)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

camera_matrix1	A wrapped OpenCV object of type CvMat
camera_matrix2	A wrapped OpenCV object of type CvMat
dist_coeffs1	A wrapped OpenCV object of type CvMat
dist_coeffs2	A wrapped OpenCV object of type CvMat
image_size	A wrapped OpenCV object of type CvSize
R	A wrapped OpenCV object of type CvMat
T	A wrapped OpenCV object of type CvMat
R1	A wrapped OpenCV object of type CvMat
R2	A wrapped OpenCV object of type CvMat
P1	A wrapped OpenCV object of type CvMat
P2	A wrapped OpenCV object of type CvMat
Q	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
flags	An integer type number with default value <i>CV_CALIB_ZERO_DISPARITY</i>
alpha	A floating point number with default value <i>with default value CV_CALIB_ZERO_DISPARITY</i>
new_image_size	A wrapped OpenCV object of type CvSize with default value <i>cv</i>
valid_pix_roi1	A wrapped OpenCV object of type CvRect with default value <i>nil</i>
valid_pix_roi2	A wrapped OpenCV object of type CvRect with default value <i>nil</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.30 StereoRectifyUncalibrated

- **num StereoRectifyUncalibrated**([CvMat](#) points1, [CvMat](#) points2, [CvMat](#) F, [CvSize](#) img_size, [CvMat](#) H1, [CvMat](#) T, [CvMat](#) H2, [num](#) threshold=5)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

points1	A wrapped OpenCV object of type CvMat
points2	A wrapped OpenCV object of type CvMat
F	A wrapped OpenCV object of type CvMat
img_size	A wrapped OpenCV object of type CvSize
H1	A wrapped OpenCV object of type CvMat
T	A wrapped OpenCV object of type CvMat
H2	A wrapped OpenCV object of type CvMat
threshold	A floating point number with default value 5

Returns

[num](#) - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_calib3d.cpp

3.2.31 TriangulatePoints

- **TriangulatePoints**([CvMat](#) projMatr1, [CvMat](#) projMatr2, [CvMat](#) projPoints1, [CvMat](#) projPoints2, [CvMat](#) points4D)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

projMatr1	A wrapped OpenCV object of type CvMat
projMatr2	A wrapped OpenCV object of type CvMat
projPoints1	A wrapped OpenCV object of type CvMat
projPoints2	A wrapped OpenCV object of type CvMat
points4D	A wrapped OpenCV object of type CvMat

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.2.32 ValidateDisparity

- **ValidateDisparity**([CvArr](#) disparity, [CvArr](#) cost, [int](#) minDisparity, [int](#) numberOfDisparities, [int](#) disp12MaxDiff=1)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

disparity	A wrapped OpenCV object of type CvArr
cost	A wrapped OpenCV object of type CvArr
minDisparity	An integer type number
numberOfDisparities	An integer type number
disp12MaxDiff	An integer type number with default value <i>1</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_calib3d.cpp

3.3 Module highgui

3.3.1 AddText

- **AddText**([CvArrimg](#), [string](#) text, [CvPoint](#) org, [CvFont](#) arg2)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

text	An array of characters
org	A wrapped OpenCV object of type CvPoint
arg2	A wrapped OpenCV object of type CvFont

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.2 ConvertImage

- **ConvertImage**(CvArr src, CvArr dst, int flags=0

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source image.
dst	Destination image. Must be single-channel or 3-channel 8-bit image.
flags	An integer type number with default value

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.3 CreateTrackbar

- **int CreateTrackbar**(string tbarname, string wname, int count, func on_change(int pos))

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

tbarname	An array of characters
wname	An array of characters
count	Maximal position of the slider. Minimal position is always 0.
on_change(int	A lua function

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_highgui.cpp

3.3.4 DestroyAllWindows

- **DestroyAllWindows()**

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

<i>none</i>	function doesn't have input arguments.
-------------	--

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.5 DestroyWindow

- **DestroyWindow([string](#) name)**

Destroys a window.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

name	Name of the window to be destroyed.
-------------	-------------------------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.6 DisplayOverlay

- **DisplayOverlay**([string](#) name, [string](#) text, [int](#) delaysms)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

name	An array of characters
text	An array of characters
delaysms	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.7 DisplayStatusBar

- **DisplayStatusBar**([string](#) name, [string](#) text, [int](#) delaysms)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

name	An array of characters
text	An array of characters
delays	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.8 FOURCC

- `num` **CV_FOURCC**(`string`[4] codec)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

Returns

`num` - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_highgui.cpp

3.3.9 GetCaptureDomain

- `int` **GetCaptureDomain**(`CvCapture` capture)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

capture	A wrapped OpenCV object of type CvCapture
----------------	---

Returns

int - An integer type number defined by architecture

The documentation was generated from :

- lua_highgui.cpp

3.3.10 GetCaptureProperty

- **num** **GetCaptureProperty**(**CvCapture** capture, **int** property_id)
Gets video capturing properties.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

capture	video capturing structure.
property_id	Property identifier. Can be one of the following:

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_highgui.cpp

3.3.11 GetTrackbarPos

- **int** **GetTrackbarPos**(**string** trackbar_name, **string** window_name)
Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

track-bar_name	An array of characters
window_name	An array of characters

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_highgui.cpp

3.3.12 GetWindowHandle

- [userdata](#) **GetWindowHandle**([string](#) name)

Gets the window's handle by its name.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

name	An array of characters
-------------	------------------------

Returns

[userdata](#) - An unspecified C pointer to memory

The documentation was generated from :

- lua_highgui.cpp

3.3.13 GetWindowName

- [string](#) **GetWindowName**([userdata](#) handle)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

handle	An unspecified C pointer to memory
---------------	------------------------------------

Returns

[string](#) - An array of characters

The documentation was generated from :

- lua_highgui.cpp

3.3.14 GetWindowProperty

- [num](#) **GetWindowProperty**([string](#) name, [int](#) prop_id)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

name	An array of characters
prop_id	An integer type number

Returns

[num](#) - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_highgui.cpp

3.3.15 GrabFram

- [int](#) **GrabFram**([CvCapture](#) capture)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

capture	A wrapped OpenCV object of type CvCapture
----------------	---

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_highgui.cpp

3.3.16 InitSystem

- **int InitSystem**([int](#) argc, [string](#)[] argv)

Initializes HighGUI.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

argc	Number of command line arguments
argv	Array of command line arguments

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_highgui.cpp

3.3.17 LoadWindowParameters

- **LoadWindowParameters**([string](#) name)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

name	An array of characters
-------------	------------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.18 MoveWindow

- **MoveWindow**([string](#) name, [int](#) x, [int](#) y)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

name	Name of the window to be moved.
x	New x coordinate of the top-left corner
y	New y coordinate of the top-left corner

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.19 NamedWindow

- **int NamedWindow**([string](#) name, [int](#) flags=CV_WINDOW_AUTOSIZE)

Creates a window.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

name	Name of the window in the window caption that may be used as a window identifier.
flags	Flags of the window. Currently the only supported flag is CV_WINDOW_AUTOSIZE. If this is set, window size is automatically adjusted to fit the displayed image (see ShowImage), and the user can not change the window size manually.

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_highgui.cpp

3.3.20 ReleaseCapture

- **ReleaseCapture**([CvCapture](#) capture)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

capture	Pointer to video the capturing structure.
----------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.21 ReleaseVideoWriter

- **ReleaseVideoWriter**([CvVideoWriter](#) writer)

Releases the AVI writer.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

writer	Pointer to the video file writer structure.
---------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.22 ResizeWindow

- **ResizeWindow**([string](#) name, [int](#) width, [int](#) height)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

name	Name of the window to be resized.
width	New width
height	New height

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.23 SaveImage

- **int SaveImage**([string](#) filename, [CvArr](#) image, [int](#)[] params)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

filename	Name of the file.
image	Image to be saved.
params	An integer type number which is an array

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_highgui.cpp

3.3.24 SaveWindowParameters

- **SaveWindowParameters**([string](#) name)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

name	An array of characters
-------------	------------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.25 SetCaptureProperty

- **int SetCaptureProperty**([CvCapture](#) capture, [int](#) property_id, [num](#) value)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

capture	video capturing structure.
property_id	property identifier. Can be one of the following:
value	value of the property.

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_highgui.cpp

3.3.26 SetMouseCallback

- **SetMouseCallback**([string](#) wname, func on_mouse([int](#) event,[int](#) x,[int](#) y, [int](#) flags)

Assigns callback for mouse events.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

wname	An array of characters
on_mouse(int	A lua function
x	An integer type number
y	An integer type number
flags	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.27 SetTrackbarPos

- **SetTrackbarPos**([string](#) trackbar_name, [string](#) window_name, [int](#) pos)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

track-bar_name	An array of characters
window_name	An array of characters
pos	New position.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.28 SetWindowProperty

- **SetWindowProperty**([string](#) name, [int](#) prop_id, [num](#) prop_value)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

name	An array of characters
prop_id	An integer type number
prop_value	A floating point number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.29 ShowImage

- **ShowImage**([string](#) name, [CvArr](#) image)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

name	Name of the window.
image	Image to be shown.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_highgui.cpp

3.3.30 StartWindowThread

- [int StartWindowThread\(\)](#)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

<i>none</i>	function doesn't have input arguments.
-------------	--

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_highgui.cpp

3.3.31 WaitKey

- [int WaitKey\(int delay=0\)](#)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

delay	Delay in milliseconds.
--------------	------------------------

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_highgui.cpp

3.3.32 WriteFrame

- [int](#) **WriteFrame**([CvVideoWriter](#) writer, [IplImage](#) image)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

writer	Video writer structure
image	The written frame

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_highgui.cpp

3.4 Module imgproc

3.4.1 Acc

- **Acc**([CvArr](#) image, [CvArr](#) sum, [CvArr](#) mask=nil)

Adds a frame to an accumulator.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	Input image, 1- or 3-channel, 8-bit or 32-bit floating point. (each channel of multi-channel image is processed independently)
sum	Accumulator with the same number of channels as input image, 32-bit or 64-bit floating-point
mask	Optional operation mask

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.2 AdaptiveThreshold

- **AdaptiveThreshold**(**CvArr** src, **CvArr** dst, **num** max_values, **int** adaptive_method=CV_ADAPTIVE_THRESH_MEAN_C, **int** threshold_type=CV_THRESH_BINARY, **int** block_size=3, **num** param1=5)

Applies an adaptive threshold to an array.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src	Source image
dst	Destination image
max_values	A floating point number
adaptive_method	Adaptive thresholding algorithm to use: CV_ADAPTIVE_THRESH_MEAN_C or CV_ADAPTIVE_THRESH_GAUSSIAN_C (see the discussion)
threshold_type	An integer type number with default value <i>CV_THRESH_BINARY</i>
block_size	An integer type number with default value 3
param1	The method-dependent parameter. For the methods CV_ADAPTIVE_THRESH_MEAN_C and CV_ADAPTIVE_THRESH_GAUSSIAN_C it is a constant subtracted from the mean or weighted mean (see the discussion), though it may be negative

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.3 ArcLength

- **num** **ArcLength**(**CvArr** contour, **CvSlice** slice=CV_WHOLE_SEQ, **int** is_closed=-1)

Calculates the contour perimeter or the curve length.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

contour	A wrapped OpenCV object of type CvArr
slice	Starting and ending points of the curve, by default, the whole curve length is calculated
is_closed	An integer type number with default value <i>with default value CV_WHOLE_SEQ</i>

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_imgproc.cpp

3.4.4 BoxPoints

- **BoxPoints**(**CvBox2D** box, **CvPoint2D32f**[] pt)

Finds the box vertices.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

box	Box
pt	A wrapped OpenCV object of type CvPoint2D32f which is an array

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Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.5 CalcArrBackProject

- **CalcArrBackProject**([IpLlImage](#) image, [CvArr](#) dst, [CvHistogram](#) hist)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

image	A wrapped OpenCV object of type IpLlImage
dst	A wrapped OpenCV object of type CvArr
hist	A wrapped OpenCV object of type CvHistogram

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.6 CalcArrBackProjectPatch

- **CalcArrBackProjectPatch**([IpLlImage](#) image, [CvArr](#) dst, [CvSize](#) range, [CvHistogram](#) hist, [int](#) method, [num](#) factor)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

image	A wrapped OpenCV object of type IpLlImage
dst	A wrapped OpenCV object of type CvArr

range	A wrapped OpenCV object of type CvSize
hist	A wrapped OpenCV object of type CvHistogram
method	An integer type number
factor	A floating point number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.7 CalcArrHist

- **CalcArrHist**(CvArr arr, CvHistogram hist, int accumulate=0, CvArr mask=NULL)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

arr	A wrapped OpenCV object of type CvArr
hist	A wrapped OpenCV object of type CvHistogram
accumulate	An integer type number with default value 0
mask	A wrapped OpenCV object of type CvArr with default value NULL

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.8 CalcBayesianProb

- **CalcBayesianProb**(CvHistogram src, int number, CvHistogram dst)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	A wrapped OpenCV object of type CvHistogram
number	An integer type number
dst	A wrapped OpenCV object of type CvHistogram

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.9 CalcHist

- **CalcHist**([CvArr](#) image, [CvHistogram](#) hist, [int](#) accumulate=0, [CvArr](#) mask=NULL)

Calculates the histogram of image(s).

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	Source images (though you may pass CvMat** as well)
hist	Pointer to the histogram
accumulate	Accumulation flag. If it is set, the histogram is not cleared in the beginning. This feature allows user to compute a single histogram from several images, or to update the histogram online
mask	The operation mask, determines what pixels of the source images are counted

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.10 CalcProbDensity

- **CalcProbDensity**([CvHistogram](#) hist1, [CvHistogram](#) hist2, [CvHistogram](#) dst_hist, [num](#) scale=255)

Divides one histogram by another.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

hist1	first histogram (the divisor)
hist2	second histogram
dst_hist	destination histogram
scale	scale factor for the destination histogram

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.11 CalcSubdivVoronoi2D

- **CalcSubdivVoronoi2D**([CvSubdiv2D](#) subdiv)

Calculates the coordinates of Voronoi diagram cells.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

subdiv	Delaunay subdivision, in which all the points are already added
---------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.12 Canny

- **Canny**([CvArr](#) image, [CvArr](#) edges, [num](#) threshold1, [num](#) threshold2, [int](#) aperture_size=3)

Finds edges in an image using Canny algorithm.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	Single-channel 8-bit input image
edges	The output edge map. It will have the same size and the same type as <code>image</code>
threshold1	The first threshold for the hysteresis procedure
threshold2	The second threshold for the hysteresis procedure
aperture_size	An integer type number with default value 3

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.13 CheckContourConvexity

- **int** **CheckContourConvexity**([CvArr](#) contour)

Tests contour convexity.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

contour	Tested contour (sequence or array of points)
----------------	--

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_imgproc.cpp

3.4.14 ClearHist

- **ClearHist**([CvHistogram](#) hist)

Clears the histogram.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

hist	Histogram
-------------	-----------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.15 ClearSubdivVoronoi2D

- **ClearSubdivVoronoi2D**([CvSubdiv2D](#) subdiv)

Removes all virtual points.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

subdiv	Delaunay subdivision
---------------	----------------------

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.16 CompareHist

- **num** **CompareHist**([CvHistogram](#) hist1, [CvHistogram](#) hist2, [int](#) method)

Compares two dense histograms.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

hist1	The first dense histogram
hist2	The second dense histogram
method	An integer type number

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_imgproc.cpp

3.4.17 ContourArea

- **num** **ContourArea**([CvArr](#) contour, [CvSlice](#) slice=CV_WHOLE_SEQ, [int](#) oriented=0)

Calculates the area of a whole contour or a contour section.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

contour	Contour (sequence or array of vertices)
slice	Starting and ending points of the contour section of interest, by default, the area of the whole contour is calculated
oriented	An integer type number with default value 0

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_imgproc.cpp

3.4.18 ContourPerimetre

- **num ContourPerimetre**(CvArr contour)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

contour	A wrapped OpenCV object of type CvArr
----------------	---------------------------------------

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_imgproc.cpp

3.4.19 ConvertMaps

- **ConvertMaps**(CvArr mapx, CvArr mapy, CvArr mapxy, CvArr mapalpha)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

mapx	A wrapped OpenCV object of type CvArr
mapy	A wrapped OpenCV object of type CvArr
mapxy	A wrapped OpenCV object of type CvArr
mapalpha	A wrapped OpenCV object of type CvArr

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.20 CopyHist

- **CopyHist**([CvHistogram](#) src, [CvHistogram](#) dst)

Copies a histogram.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source histogram
dst	Pointer to destination histogram

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.21 CopyMakeBorder

- **CopyMakeBorder**([CvArr](#) src, [CvArr](#) dst, [CvPoint](#) offset, [int](#) bordertype, [CvScalar](#) value=[ScalarAll\(0\)](#))

Copies an image and makes a border around it.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	The source image
dst	The destination image
offset	Coordinates of the top-left corner (or bottom-left in the case of images with bottom-left origin) of the destination image rectangle where the source image (or its ROI) is copied. Size of the rectangle matches the source image size/ROI size
bordertype	An integer type number
value	Value of the border pixels if bordertype is <code>IPL_BORDER_CONSTANT</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.22 CorenerEigenValsAndVecs

- **CorenerEigenValsAndVecs**([CvArr](#) image, [CvArr](#) eigenvv, [int](#) block_size, [int](#) aperture_size=3)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	A wrapped OpenCV object of type CvArr
eigenvv	A wrapped OpenCV object of type CvArr
block_size	An integer type number
aperture_size	An integer type number with default value 3

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.23 CorenerHarris

- **CorenerHarris**([CvArr](#) image, [CvArr](#) harris_responce, [int](#) block_size, [int](#) aperture_size=3, [num](#) k=0.04)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	A wrapped OpenCV object of type <code>CvArr</code>
harris_response	A wrapped OpenCV object of type <code>CvArr</code>
block_size	An integer type number
aperture_size	An integer type number with default value <code>3</code>
k	A floating point number with default value <code>0</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.24 CreatePyramid

- `userdata CreatePyramid(CvArr img, int extra_layers, num rate, CvSize[] layer_sizes=nil, CvArr bufarr=nil, int calc=0, int filter=CV_GAUSSIAN_5x5)`

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

img	A wrapped OpenCV object of type <code>CvArr</code>
extra_layers	An integer type number
rate	A floating point number
layer_sizes	A wrapped OpenCV object of type <code>CvSize</code> which is an array with default value <i>nil</i>
bufarr	A wrapped OpenCV object of type <code>CvArr</code> with default value <i>nil</i>
calc	An integer type number with default value <code>0</code>
filter	An integer type number with default value <code>CV_GAUSSIAN_5x5</code>

Returns

`userdata` - An unspecified C pointer to memory

The documentation was generated from :

- lua_imgproc.cpp

3.4.25 CreateSubdivDelaunay2D

- **CreateSubdivDelaunay2D**([CvRect](#) rect, [CvMemStorage](#) storage)

Creates an empty Delaunay triangulation.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

rect	Rectangle that includes all of the 2d points that are to be added to the subdivision
storage	Container for subdivision

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.26 CvtColor

- **CvtColor**([CvArr](#) src, [CvArr](#) dst, [int](#) code)

Converts an image from one color space to another.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	The source 8-bit (8u), 16-bit (16u) or single-precision floating-point (32f) image
dst	The destination image of the same data type as the source. The number of channels may be different
code	Color conversion operation that can be specified using <code>CV_SRC_COLOR_SPACE</code> 2 <code>dst_color_space</code> constants (see below)

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.27 Dilate

- **Dilate**([CvArr](#) src, [CvArr](#) dst, [IplConvKernel](#) element=nil, [int](#) iterations=1)

Dilates an image by using a specific structuring element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src	Source image
dst	Destination image
element	A wrapped OpenCV object of type IplConvKernel with default value <i>nil</i>
iterations	Number of times dilation is applied

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.28 DistTransfomr

- **DistTransfomr**([CvArr](#) src, [CvArr](#) dst, [int](#) distance_type=CV_DIST_L2, [int](#) mask_size=3, [num\[\]](#) mask=nil, [CvArr](#) labels=0)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

src	A wrapped OpenCV object of type <code>CvArr</code>
dst	A wrapped OpenCV object of type <code>CvArr</code>
distance_type	An integer type number with default value <code>CV_DIST_L2</code>
mask_size	An integer type number with default value <code>3</code>
mask	A floating point number which is an array with default value <code>nil</code>
labels	A wrapped OpenCV object of type <code>CvArr</code> with default value <code>0</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.29 EqualizeHist

- **EqualizeHist**(`CvArr` src, `CvArr` dst)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	A wrapped OpenCV object of type <code>CvArr</code>
dst	A wrapped OpenCV object of type <code>CvArr</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.30 Erode

- **Erode**(`CvArr` src, `CvArr` dst, `IplConvKernel` element=`nil`, `int` iterations=`1`)

Erodes an image by using a specific structuring element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

src	Source image
dst	Destination image
element	A wrapped OpenCV object of type <code>IplConvKernel</code> with default value <i>nil</i>
iterations	Number of times erosion is applied

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.31 Filter2D

- **Filter2D**([CvArr](#) src, [CvArr](#) dst, [CvMat](#) kernel, [CvPoint](#) anchor=Point(-1,-1))
Convolves an image with the kernel.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

src	The source image
dst	The destination image
kernel	Convolution kernel, a single-channel floating point matrix. If you want to apply different kernels to different channels, split the image into separate color planes using Split and process them individually
anchor	The anchor of the kernel that indicates the relative position of a filtered point within the kernel. The anchor should lie within the kernel. The special default value (-1,-1) means that it is at the kernel center

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.32 FindContours

- `int, CvSeq FindContours(CvArr image, CvMemStorage storage, int header_size=CvContour[Size], int mode=CV_RETR_LISTS, int method=CV_CHAIN_APPROX_SIMPLE, CvPoint offset=Point(0,0))`

Finds the contours in a binary image.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

image	The source, an 8-bit single channel image. Non-zero pixels are treated as 1's, zero pixels remain 0's - the image is treated as <code>binary</code> . To get such a binary image from grayscale, one may use Threshold , AdaptiveThreshold or Canny . The function modifies the source image's content
storage	Container of the retrieved contours
header_size	An integer type number with default value <code>CvContour</code>
mode	An integer type number with default value <code>CV_RETR_LISTS</code>
method	An integer type number with default value <code>CV_CHAIN_APPROX_SIMPLE</code>
offset	Offset, by which every contour point is shifted. This is useful if the contours are extracted from the image ROI and then they should be analyzed in the whole image context

Returns

- `int` - An integer type number defined by architecture
- `CvSeq` - A wrapped OpenCV object of type `CvSeq`

The documentation was generated from :

- `lua_imgproc.cpp`

3.4.33 FindCornerSubPix

- `FindCornerSubPix(CvArr image, CvPoint2D32f[] corners, CvSize win, CvSize zero_none, CvTermCriteria criteria)`

Refines the corner locations.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

image	Input image
corners	Initial coordinates of the input corners as a list of (x, y) pairs
win	Half of the side length of the search window. For example, if <code>win=(5,5)</code> , then a $5*2+1 \times 5*2+1 = 11 \times 11$ search window would be used
zero_none	A wrapped OpenCV object of type <code>CvSize</code>
criteria	Criteria for termination of the iterative process of corner refinement. That is, the process of corner position refinement stops either after a certain number of iterations or when a required accuracy is achieved. The <code>criteria</code> may specify either of or both the maximum number of iteration and the required accuracy

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.34 FindFeatures

- **FindFeatures**([CvFeatureTree](#) tr, [CvMat](#) query_points, [CvMat](#) indices, [CvMat](#) dist, [int](#) k, [int](#) emax=20)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

tr	A wrapped OpenCV object of type <code>CvFeatureTree</code>
query_points	A wrapped OpenCV object of type <code>CvMat</code>
indices	A wrapped OpenCV object of type <code>CvMat</code>
dist	A wrapped OpenCV object of type <code>CvMat</code>
k	An integer type number
emax	An integer type number with default value <i>20</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.35 FindFeaturesBoxed

- **int FindFeaturesBoxed**([CvFeatureTree](#) tr, [CvMat](#) bounds_im, [CvMat](#) bounds_max, [CvMat](#) out_indices)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

tr	A wrapped OpenCV object of type CvFeatureTree
bounds_im	A wrapped OpenCV object of type CvMat
bounds_max	A wrapped OpenCV object of type CvMat
out_indices	A wrapped OpenCV object of type CvMat

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_imgproc.cpp

3.4.36 FitLine

- **FitLine**([CvArr](#) points, [int](#) dist_type, [num](#) param, [num](#) reps, [num](#) aeps, [num](#)[])
line)

Fits a line to a 2D or 3D point set.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

points	Sequence or array of 2D or 3D points with 32-bit integer or floating-point coordinates
dist_type	The distance used for fitting (see the discussion)
param	Numerical parameter (C) for some types of distances, if 0 then some optimal value is chosen

reps	Sufficient accuracy for the radius (distance between the coordinate origin and the line). 0.01 is a good default value.
aeps	Sufficient accuracy for the angle. 0.01 is a good default value.
line	A floating point number which is an array

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.37 FloodFill

- **FloodFill**([CvArr](#) image, [CvPoint](#) seed_point, [CvScalar](#) new_val, [CvScalar](#) lo_diff=ScalarAll(0), [CvScalar](#) up_diff=ScalarAll(0), [CvConnectedComp](#) comp=nil, [int](#) flags=4, [CvArr](#) mask=nil)

Fills a connected component with the given color.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

image	Input 1- or 3-channel, 8-bit or floating-point image. It is modified by the function unless the <code>CV_FLOODFILL_MASK_ONLY</code> flag is set (see below)
seed_point	The starting point
new_val	New value of the repainted domain pixels
lo_diff	Maximal lower brightness/color difference between the currently observed pixel and one of its neighbors belonging to the component, or a seed pixel being added to the component. In the case of 8-bit color images it is a packed value
up_diff	Maximal upper brightness/color difference between the currently observed pixel and one of its neighbors belonging to the component, or a seed pixel being added to the component. In the case of 8-bit color images it is a packed value
comp	Returned connected component for the repainted domain. Note that the function does not fill <code>comp->contour</code> field. The boundary of the filled component can be retrieved from the output mask image using FindContours
flags	An integer type number with default value 4

mask	Operation mask, should be a single-channel 8-bit image, 2 pixels wider and 2 pixels taller than <code>image</code> . If not NULL, the function uses and updates the mask, so the user takes responsibility of initializing the <code>mask</code> content. Floodfilling can't go across non-zero pixels in the mask, for example, an edge detector output can be used as a mask to stop filling at edges. It is possible to use the same mask in multiple calls to the function to make sure the filled area do not overlap. Note: because the mask is larger than the filled image, a pixel in <code>mask</code> that corresponds to (x,y) pixel in <code>image</code> will have coordinates $(x+1,y+1)$
-------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.38 GetCentralMoment

- **num** `GetCentralMoment`(`CvMoments` moments, `int` x_order, `int` y_order)

Retrieves the central moment from the moment state structure.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

moments	Pointer to the moment state structure
x_order	x order of the retrieved moment, <code>x_order</code> ≥ 0
y_order	y order of the retrieved moment, <code>y_order</code> ≥ 0 and <code>x_order</code> + <code>y_order</code> ≤ 3

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_imgproc.cpp

3.4.39 GetHuMoments

- **GetHuMoments**(`CvMoments` moments, `CvHuMoments` hu_moments)

Calculates the seven Hu invariants.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

moments	The input moments, computed with Moments
hu_moments	A wrapped OpenCV object of type CvHuMoments

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.40 GetMinMaxHistValue

- float, float, **int int** **GetMinMaxHistValue**([CvHistogram](#) hist)

Finds the minimum and maximum histogram bins.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

hist	Histogram
-------------	-----------

Returns

- [float](#) - A floating point number which must be float
- [float](#) - A floating point number which must be float
- [int](#) - An integer type number defined by architecture
- [int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_imgproc.cpp

3.4.41 GetNormalizedCentralMoment

- **num** **GetNormalizedCentralMoment**([CvMoments](#) moments, [int](#) x_order, [int](#) y_order)

Retrieves the normalized central moment from the moment state structure.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

moments	Pointer to the moment state structure
x_order	x order of the retrieved moment, $x_order \geq 0$
y_order	y order of the retrieved moment, $y_order \geq 0$ and $x_order + y_order \leq 3$

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_imgproc.cpp

3.4.42 GetQuadrangleSubPix

- **GetQuadrangleSubPix**([CvArr](#) src, [CvArr](#) dst, [CvMat](#) map_matrix)

Retrieves the pixel quadrangle from an image with sub-pixel accuracy.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source image
dst	Extracted quadrangle
map_matrix	A wrapped OpenCV object of type CvMat

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.43 GetRectSubPix

- **GetRectSubPix**([CvArr](#) src, [CvArr](#) dst, [CvPoint2D32f](#) center)

Retrieves the pixel rectangle from an image with sub-pixel accuracy.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source image
dst	Extracted rectangle
center	Floating point coordinates of the extracted rectangle center within the source image. The center must be inside the image

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.44 GetSpatialMoment

- **num** **GetSpatialMoment**([CvMoments](#) moments, [int](#) x_order, [int](#) y_order)

Retrieves the spatial moment from the moment state structure.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

moments	The moment state, calculated by Moments
x_order	x order of the retrieved moment, <code>x_order >= 0</code>
y_order	y order of the retrieved moment, <code>y_order >= 0</code> and <code>x_order + y_order <= 3</code>

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_imgproc.cpp

3.4.45 GoodFeaturesToTrack

- **int GoodFeaturesToTrack**([CvArr](#) image, [CvArr](#) eigen_image, [CvArr](#) temp_image, [CvPoint2D32f](#)[] corners, [int](#) count, [num](#) quality_level, [num](#) min_distance, [CvMat](#) mask=nil, [int](#) block_size=3, [int](#) use_harris=0, [num](#) k=0.04)

Determines strong corners on an image.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	The source 8-bit or floating-point 32-bit, single-channel image
eigen_image	A wrapped OpenCV object of type CvArr
temp_image	A wrapped OpenCV object of type CvArr
corners	Output parameter; detected corners
count	An integer type number
quality_level	A floating point number
min_distance	A floating point number
mask	Region of interest. The function selects points either in the specified region or in the whole image if the mask is NULL
block_size	An integer type number with default value 3
use_harris	An integer type number with default value 0
k	Free parameter of Harris detector; used only if (<code>useHarris!=0</code>)

Returns

- [int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_imgproc.cpp

3.4.46 HoughLines2

- **HoughLines2**([CvArr](#) image, [userdata](#) line_storage, [int](#) method, [num](#) rho, [num](#) theta, [int](#) threshold, [num](#) param1=0, param2=0)

Finds lines in a binary image using a Hough transform.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	The 8-bit, single-channel, binary source image. In the case of a probabilistic method, the image is modified by the function
line_storage	An unspecified C pointer to memory
method	An integer type number
rho	Distance resolution in pixel-related units
theta	Angle resolution measured in radians
threshold	Threshold parameter. A line is returned by the function if the corresponding accumulator value is greater than <code>threshold</code>
param1	A floating point number with default value <code>0</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.47 InitSubdivDelaunay2D

- **InitSubdivDelaunay2D**([CvSubdiv2D](#) subdiv, [CvRect](#) rect)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

subdiv	A wrapped OpenCV object of type <code>CvSubdiv2D</code>
rect	A wrapped OpenCV object of type <code>CvRect</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.48 InitUndistortMap

- **InitUndistortMap**([CvMat](#) camera_matrix, [CvMat](#) distortion_coeffs, [CvArr](#) mapx, [CvArr](#) mapy)

Computes an undistortion map.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

camera_matrix	A wrapped OpenCV object of type CvMat
distortion_coeffs	A wrapped OpenCV object of type CvMat
mapx	A wrapped OpenCV object of type CvArr
mapy	A wrapped OpenCV object of type CvArr

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.49 InitUndistortRectifyMap

- **InitUndistortRectifyMap**([CvMat](#) camera_matrix, [CvMat](#) distortion_coeffs, [CvMat](#) R, [CvMat](#) new_camera_matrix, [CvArr](#) mapx, [CvArr](#) mapy)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

camera_matrix	A wrapped OpenCV object of type CvMat
distortion_coeffs	A wrapped OpenCV object of type CvMat
R	A wrapped OpenCV object of type CvMat

new_camera_matrix	A wrapped OpenCV object of type CvMat
mapx	A wrapped OpenCV object of type CvArr
mapy	A wrapped OpenCV object of type CvArr

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.50 Inpaint

- **Inpaint**([CvArr](#) src, [CvArr](#) inpaint_mask, [CvArr](#) dst, [num](#) inpaintRange, [int](#) flags)

Inpaints the selected region in the image.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

src	The input 8-bit 1-channel or 3-channel image.
inpaint_mask	A wrapped OpenCV object of type CvArr
dst	The output image of the same format and the same size as input.
inpaintRange	A floating point number
flags	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.51 Integral

- **Integral**([CvArr](#) image, [CvArr](#) sum, [CvArr](#) sqsum=nil, [CvArr](#) tilted_sum=nil)

Calculates the integral of an image.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

image	The source image, $W \times H$, 8-bit or floating-point (32f or 64f)
sum	The integral image, $(W + 1) \times (H + 1)$, 32-bit integer or double precision floating-point (64f)
sqsum	The integral image for squared pixel values, $(W + 1) \times (H + 1)$, double precision floating-point (64f)
tilted_sum	A wrapped OpenCV object of type CvArr with default value <i>nil</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.52 LSHAdd

- **LSHAdd**([CvLSH](#) lsh, [CvMat](#) data, [CvMat](#) indices=nil)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

lsh	A wrapped OpenCV object of type CvLSH
data	A wrapped OpenCV object of type CvMat
indices	A wrapped OpenCV object of type CvMat with default value <i>nil</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.53 LSHRemove

- **LSHRemove**([CvLSH](#) lsh, [CvMat](#) indices)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

lsh	A wrapped OpenCV object of type CvLSH
indices	A wrapped OpenCV object of type CvMat

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.54 Laplace

- **Laplace**([CvArr](#) src, [CvArr](#) dst, [int](#) aperture_size=3)

Calculates the Laplacian of an image.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source image
dst	Destination image
aperture_size	An integer type number with default value 3

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.55 LinearPolar

- **LinearPolar**([CvArr](#) src, [CvArr](#) dst, [CvPoint2D32f](#) center, [num](#) maxRadius, [int](#) flags=CV_INTER_LINEAR+CV_WARP_FILL_OUTLIERS)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	A wrapped OpenCV object of type <code>CvArr</code>
dst	A wrapped OpenCV object of type <code>CvArr</code>
center	A wrapped OpenCV object of type <code>CvPoint2D32f</code>
maxRadius	A floating point number
flags	An integer type number with default value <code>CV_INTER_LINEAR</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.56 LogPolar

- **LogPolar**([CvArr](#) src, [CvArr](#) dst, [CvPoint2D32f](#) center, [num](#) M, [int](#) flags=CV_INTER_LINEAR+CV_WARP_FILL_OUTLIERS)

Remaps an image to log-polar space.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source image
dst	Destination image
center	The transformation center; where the output precision is maximal
M	Magnitude scale parameter. See below
flags	An integer type number with default value <code>CV_INTER_LINEAR</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.57 MatchShapes

- **num MatchShapes**(*userdata* object1, *userdata* object2, *int* method, *num* parameter=0)

Compares two shapes.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

object1	First contour or grayscale image
object2	Second contour or grayscale image
method	An integer type number
parameter	Method-specific parameter (is not used now)

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_imgproc.cpp

3.4.58 MatchTemplate

- **MatchTemplate**(*CvArr* image, *CvArr* templ, *CvArr* result, *int* method)

Compares a template against overlapped image regions.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

image	Image where the search is running; should be 8-bit or 32-bit floating-point
templ	Searched template; must be not greater than the source image and the same data type as the image
result	A wrapped OpenCV object of type CvArr
method	Specifies the way the template must be compared with the image regions (see below)

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.59 MinEnclosingCircle

- `int,num MinEnclosingCircle(CvArr points, CvPoint2D32f center)`

Finds the circumscribed circle of minimal area for a given 2D point set.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

points	Sequence or array of 2D points
center	Output parameter; the center of the enclosing circle

Returns

- `int` - An integer type number defined by architecture
- `num` - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_imgproc.cpp

3.4.60 Moments

- `Moments(CvArr arr, CvMoments moments, int binary=0)`

Calculates all of the moments up to the third order of a polygon or rasterized shape.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

arr	Image (1-channel or 3-channel with COI set) or polygon (CvSeq of points or a vector of points)
moments	Pointer to returned moment's state structure
binary	(For images only) If the flag is non-zero, all of the zero pixel values are treated as zeroes, and all of the others are treated as 1's

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.61 MorphologyEx

- **MorphologyEx**([CvMat](#) src, [CvMat](#) dst, [CvArr](#) temp, [IplConvKernel](#) element, [int](#) operation, [int](#) iterations=1)

Performs advanced morphological transformations.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

src	Source image
dst	Destination image
temp	Temporary image, required in some cases
element	Structuring element
operation	An integer type number
iterations	Number of times erosion and dilation are applied

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.62 MultiplyAcc

- **MultiplyAcc**([CvArr](#) image1, [CvArr](#) image2, [CvArr](#) acc, [CvArr](#) mask=nil)

Adds the product of two input images to the accumulator.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image1	First input image, 1- or 3-channel, 8-bit or 32-bit floating point (each channel of multi-channel image is processed independently)
image2	Second input image, the same format as the first one
acc	Accumulator with the same number of channels as input images, 32-bit or 64-bit floating-point
mask	Optional operation mask

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.63 NormalizeHist

- **NormalizeHist**([CvHistogram](#) hist, [num](#) factor)

Normalizes the histogram.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

hist	Histogram
factor	Normalization factor

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.64 PointPolygonTest

- **num** **PointPolygonTest**(**CvArr** contour, **CvPoint2D32f** pt, **int** measure_dist)
Point in contour test.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

contour	Input contour
pt	The point tested against the contour
measure_dist	If it is non-zero, the function estimates the distance from the point to the nearest contour edge

Returns

- num** - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_imgproc.cpp

3.4.65 PreCornerDetect

- **PreCornerDetect**(**CvArr** image, **CvArr** corners, **int** aperature_size=3)
Calculates the feature map for corner detection.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	Input image
corners	Image to store the corner candidates
aperature_size	An integer type number with default value 3

Returns

- none** - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.66 PyrDown

- **PyrDown**([CvArr](#) src, [CvArr](#) dst, [int](#) filter=CV_GAUSSIAN_5x5)

Downsamples an image.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	The source image
dst	The destination image, should have a half as large width and height than the source
filter	Type of the filter used for convolution; only CV_GAUSSIAN_5x5 is currently supported

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.67 PyrMeanShiftFiltering

- **PyrMeanShiftFiltering**([CvArr](#) src, [CvArr](#) dst, [num](#) sp, [num](#) sr, [int](#) max_level=1, [CvTermCriteria](#) termcrit=TermCriteria(CV_TERMCRIT_ITER+CV_TERMCRIT_EPS,5,1))

Does meanshift image segmentation

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	The source 8-bit, 3-channel image.
dst	The destination image of the same format and the same size as the source.
sp	The spatial window radius.

sr	The color window radius.
max_level	Maximum level of the pyramid for the segmentation.
termcrit	Termination criteria: when to stop meanshift iterations.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.68 PyrSegmentation

- **PyrSegmentation**([IplImage](#) src, [IplImage](#) dst, [CvMemStorage](#) storage, [CvSeq](#) comp, [int](#) level, [num](#) threshold1, [num](#) threshold2)

Implements image segmentation by pyramids.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

src	The source image
dst	The destination image
storage	Storage; stores the resulting sequence of connected components
comp	Pointer to the output sequence of the segmented components
level	Maximum level of the pyramid for the segmentation
threshold1	Error threshold for establishing the links
threshold2	Error threshold for the segments clustering

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.69 PyrUp

- **PyrUp**([CvArr](#) src, [CvArr](#) dst, [int](#) filter=CV_GAUSSIAN_5x5)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

src	A wrapped OpenCV object of type CvArr
dst	A wrapped OpenCV object of type CvArr
filter	An integer type number with default value <i>CV_GAUSSIAN_5x5</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.70 ReleaseFeatureTree

- **ReleaseFeatureTree**([CvFeatureTree](#) tr)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

tr	A wrapped OpenCV object of type CvFeatureTree
-----------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.71 ReleaseHist

- **ReleaseHist**([CvHistogram](#) hist)

Releases the histogram.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

hist	Double pointer to the released histogram
-------------	--

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.72 ReleaseLSH

- **ReleaseLSH**([CvLSH](#) lsh)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

lsh	A wrapped OpenCV object of type CvLSH
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Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.73 ReleasePyramid

- **ReleasePyramid**([CvMat](#) pyramid, [int](#) extra_layers)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

pyramid	A wrapped OpenCV object of type CvMat
extra_layers	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.74 ReleaseStructuringElement

- **ReleaseStructuringElement**([IplConvKernel](#) kernel)

Deletes a structuring element.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

kernel	A wrapped OpenCV object of type IplConvKernel
---------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.75 Remap

- **Remap**([CvArr](#) src, [CvArr](#) dst, [CvArr](#) mapx, [CvArr](#) mapy, [int](#) flags=CV_INTER_LINEAR+CV_WARP_FILL_OUT
[CvScalar](#) fillval=ScalarAll(0))

Applies a generic geometrical transformation to the image.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source image
dst	Destination image
mapx	The map of x-coordinates (CV_32FC1 image)
mapy	The map of y-coordinates (CV_32FC1 image)
flags	An integer type number with default value <i>CV_INTER_LINEAR</i>
fillval	A value used to fill outliers

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.76 Resize

- **Resize**(*CvArr* src, *CvArr* dst, *int* interpolation=*CV_INTER_LINEAR*)

Resizes an image.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source image
dst	Destination image
interpolation	An integer type number with default value <i>CV_INTER_LINEAR</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.77 RunningAvg

- **RunningAvg**([CvArr](#) image, [CvArr](#) acc, [num](#) alpha, [CvArr](#) mask=nil)

Updates the running average.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	Input image, 1- or 3-channel, 8-bit or 32-bit floating point (each channel of multi-channel image is processed independently)
acc	Accumulator with the same number of channels as input image, 32-bit or 64-bit floating-point
alpha	Weight of input image
mask	Optional operation mask

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.78 SampleLine

- [int,userdata](#) **SampleLine**([CvMat](#) image, [CvPoint](#) pt1, [CvPoint](#) pt2, [int](#) connectivity=8)

Reads the raster line to the buffer.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	Image to sample the line from
pt1	Starting line point
pt2	Ending line point
connectivity	The line connectivity, 4 or 8

Returns

- `int` - An integer type number defined by architecture
- `userdata` - An unspecified C pointer to memory

The documentation was generated from :

- lua_imgproc.cpp

3.4.79 Smooth

- **Smooth**(`CvArr` src, `CvArr` dst, `int` smoothtype=CV_GAUSSIAN, `int` size1=3, `int` size2=0, `num` sigma1=0, `num` sigma2=0)

Smooths the image in one of several ways.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	The source image
dst	The destination image
smoothtype	An integer type number with default value <i>CV_GAUSSIAN</i>
size1	An integer type number with default value <i>3</i>
size2	An integer type number with default value <i>0</i>
sigma1	A floating point number with default value <i>0</i>
sigma2	A floating point number with default value <i>0</i>

Returns

- none** - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.80 Sobel

- **Sobel**(`CvArr` src, `CvArr` dst, `int` xorder, `int` yorder, `int` aperture_size=3)

Calculates the first, second, third or mixed image derivatives using an extended Sobel operator

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	The source image
dst	The destination image; will have the same size and the same number of channels as <code>src</code>
xorder	Order of the derivative x
yorder	Order of the derivative y
aperture_size	An integer type number with default value 3

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.81 SquareAcc

- **SquareAcc**([CvArr](#) image, [CvArr](#) sqsum, [CvArr](#) mask=nil)

Adds the square of the source image to the accumulator.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	Input image, 1- or 3-channel, 8-bit or 32-bit floating point (each channel of multi-channel image is processed independently)
sqsum	Accumulator with the same number of channels as input image, 32-bit or 64-bit floating-point
mask	Optional operation mask

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.82 StartReadChainPoints

- **StartReadChainPoints**([CvChain](#) chain, [CvChainPtReader](#) reader)

Initializes the chain reader.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

chain	A wrapped OpenCV object of type CvChain
reader	A wrapped OpenCV object of type CvChainPtReader

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.83 Subdiv2DLocate

- [int](#), [CvSubdiv2DEdge](#), [CvSubdiv2DPoint](#) **Subdiv2DLocate**([CvSubdiv2D](#) subdiv, [CvPoint2D32f](#) pt)

Returns the location of a point within a Delaunay triangulation.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

subdiv	Delaunay or another subdivision
pt	The point to locate

Returns

- [int](#) - An integer type number defined by architecture
- [CvSubdiv2DEdge](#) - A wrapped OpenCV object of type CvSubdiv2DEdge
- [CvSubdiv2DPoint](#) - A wrapped OpenCV object of type CvSubdiv2DPoint

The documentation was generated from :

- lua_imgproc.cpp

3.4.84 SubstituteContour

- **SubstituteContour**([CvContourScanner](#) scanner, [CvSeq](#) new_contour)

Replaces a retrieved contour.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

scanner	Contour scanner initialized by StartFindContours
new_contour	Substituting contour

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.85 ThreshHist

- **ThreshHist**([CvHistogram](#) hist, [num](#) factor)

Thresholds the histogram.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

hist	Pointer to the histogram
factor	A floating point number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.86 Threshold

- **num** **Threshold**(**CvArr** src, **CvArr** dst, **num** threshold, **num** max_value, **int** thresh-old_type)

Applies a fixed-level threshold to array elements.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source array (single-channel, 8-bit or 32-bit floating point)
dst	Destination array; must be either the same type as <code>src</code> or 8-bit
threshold	Threshold value
max_value	A floating point number
thresh-old_type	An integer type number

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_imgproc.cpp

3.4.87 TriangleArea

- **num** **TriangleArea**(**CvPoint2D32f** a, **CvPoint2D32f** b, **CvPoint2D32f** c)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

a	A wrapped OpenCV object of type <code>CvPoint2D32f</code>
b	A wrapped OpenCV object of type <code>CvPoint2D32f</code>
c	A wrapped OpenCV object of type <code>CvPoint2D32f</code>

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_imgproc.cpp

3.4.88 Undistort2

- **Undistort2**([CvArr](#) src, [CvArr](#) dst, [CvMat](#) camera_matrix, [CvMat](#) distortion_coeffs, [CvMat](#) new_camera_matrix=nil)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	A wrapped OpenCV object of type CvArr
dst	A wrapped OpenCV object of type CvArr
camera_matrix	A wrapped OpenCV object of type CvMat
distortion_coeffs	A wrapped OpenCV object of type CvMat
new_camera_matrix	A wrapped OpenCV object of type CvMat with default value <i>nil</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.89 UndistortPoints

- **UndistortPoints**([CvMat](#) src, [CvMat](#) dst, [CvMat](#) camera_matrix, [CvMat](#) distortion_coeffs, [CvMat](#) R=nil, [CvMat](#) P=nil)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	A wrapped OpenCV object of type CvMat
dst	A wrapped OpenCV object of type CvMat
camera_matrix	A wrapped OpenCV object of type CvMat
distortion_coeffs	A wrapped OpenCV object of type CvMat
R	A wrapped OpenCV object of type CvMat with default value <i>nil</i>
P	A wrapped OpenCV object of type CvMat with default value <i>nil</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.90 WarpAffine

- **WarpAffine**([CvArr](#) src, [CvArr](#) dst, [CvMat](#) map_matrix, [int](#) flags=(CV_INTER_LINEAR+CV_WARP_FILL_OUTLIERS), [CvScalar](#) fillval=ScalarAll(0))

Applies an affine transformation to an image.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source image
dst	Destination image
map_matrix	A wrapped OpenCV object of type CvMat
flags	An integer type number with default value (<i>CV_INTER_LINEAR</i>)
fillval	A value used to fill outliers

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.91 WarpPerspective

- **WarpPerspective**([CvArr](#) src, [CvArr](#) dst, [CvMat](#) map_matrix, [int](#) flags=CV_INTER_LINEAR+CV_WARP_FILL, [CvScalar](#) fillval=ScalarAll(0))

Applies a perspective transformation to an image.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

src	Source image
dst	Destination image
map_matrix	A wrapped OpenCV object of type CvMat
flags	An integer type number with default value <i>CV_INTER_LINEAR</i>
fillval	A value used to fill outliers

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.92 Watershed

- **Watershed**([CvArr](#) image, [CvArr](#) markers)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	A wrapped OpenCV object of type CvArr
markers	A wrapped OpenCV object of type CvArr

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.93 cvLSHQuery

- **cvLSHQuery**([CvLSH](#) lsh, [CvMat](#) query_points, [CvMat](#) indices, [CvMat](#) dist, [int](#) k, [int](#) emax)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

lsh	A wrapped OpenCV object of type CvLSH
query_points	A wrapped OpenCV object of type CvMat
indices	A wrapped OpenCV object of type CvMat
dist	A wrapped OpenCV object of type CvMat
k	An integer type number
emax	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_imgproc.cpp

3.4.94 cvLSHSize

- **int cvLSHSize**([CvLSH](#) lsh)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

lsh	A wrapped OpenCV object of type CvLSH
------------	---------------------------------------

Returns

[int](#) - An integer type number defined by architecture

The documentation was generated from :

- lua_imgproc.cpp

3.5 Module features2d

3.5.1 SURFParams

- **SURFParams**([CvArr](#) img, [CvArr](#) mask, [CvSeq](#) keypoints, [CvSeq](#) descriptors, [CvMemStorage](#) storage, [CvSURFParams](#) params, [int](#) useProvidedKeyPts=0)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

img	A wrapped OpenCV object of type CvArr
mask	A wrapped OpenCV object of type CvArr
keypoints	A wrapped OpenCV object of type CvSeq
descriptors	A wrapped OpenCV object of type CvSeq
storage	A wrapped OpenCV object of type CvMemStorage
params	A wrapped OpenCV object of type CvSURFParams
useProvidedKeyPts	An integer type number with default value 0

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_features2d.cpp

3.6 Module video

3.6.1 BGCodeBookClearStale

- **BGCodeBookClearStale**([CvBGCodeBookModel](#) model, [int](#) staleThresh, [CvRect](#) roi=cv.Rect(0,0,0,0), [CvArr](#) mask=nil)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

model	A wrapped OpenCV object of type CvBGCodeBookModel
staleThresh	An integer type number
roi	A wrapped OpenCV object of type CvRect with default value <i>cv</i>
mask	A wrapped OpenCV object of type CvArr with default value <i>nil</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_video.cpp

3.6.2 BGCodeBookDiff

- **num** **BGCodeBookDiff**([CvBGCodeBookModel](#) model, [CvArr](#) image, [CvArr](#) fg-mask, [CvRect](#) roi=cv.Rect(0,0,0,0))

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

model	A wrapped OpenCV object of type CvBGCodeBookModel
image	A wrapped OpenCV object of type CvArr
fgmask	A wrapped OpenCV object of type CvArr
roi	A wrapped OpenCV object of type CvRect with default value <i>cv</i>

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_video.cpp

3.6.3 BGCodeBookUpdate

- **BGCodeBookUpdate**([CvBGCodeBookModel](#) model, [CvArr](#) image, [CvRect](#) roi=cv.Rect(0,0,0,0), [CvArr](#) mask=nil)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

model	A wrapped OpenCV object of type CvBGCodeBookModel
image	A wrapped OpenCV object of type CvArr
roi	A wrapped OpenCV object of type CvRect with default value cv
mask	A wrapped OpenCV object of type CvArr with default value <i>nil</i>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_video.cpp

3.6.4 CalcAffineFlowPyrLK

- **string CalcAffineFlowPyrLK**([CvArr](#) prev, [CvArr](#) curr, [CvArr](#) prev_pyr, [CvArr](#) curr_pyr, [CvPoint2D32f](#)[] prev_features, [CvPoint2D32f](#)[] curr_features, [num](#)[] matrices, [int](#) count, [CvSize](#) win_size, [int](#) level, [CvTermCriteria](#) criteria, [int](#) flags)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

prev	A wrapped OpenCV object of type CvArr
curr	A wrapped OpenCV object of type CvArr
prev_pyr	A wrapped OpenCV object of type CvArr
curr_pyr	A wrapped OpenCV object of type CvArr
prev_features	A wrapped OpenCV object of type CvPoint2D32f which is an array
curr_features	A wrapped OpenCV object of type CvPoint2D32f which is an array
matrices	A floating point number which is an array

count	An integer type number
win_size	A wrapped OpenCV object of type CvSize
level	An integer type number
criteria	A wrapped OpenCV object of type CvTermCriteria
flags	An integer type number

Returns

[string](#) - An array of characters

The documentation was generated from :

- lua_video.cpp

3.6.5 CalcGlobalOrientation

- [num](#) **CalcGlobalOrientation**([CvArr](#) orientation, [CvArr](#) mask, [CvArr](#) mhi, [num](#) timestamp, [num](#) duration)

Calculates the global motion orientation of some selected region.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

orientation	Motion gradient orientation image; calculated by the function CalcMotionGradient
mask	Mask image. It may be a conjunction of a valid gradient mask, obtained with CalcMotionGradient and the mask of the region, whose direction needs to be calculated
mhi	Motion history image
timestamp	Current time in milliseconds or other units, it is better to store time passed to UpdateMotionHistory before and reuse it here, because running UpdateMotionHistory and CalcMotionGradient on large images may take some time
duration	Maximal duration of motion track in milliseconds, the same as UpdateMotionHistory

Returns

[num](#) - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_video.cpp

3.6.6 CalcMotionGradient

- **CalcMotionGradient**([CvArr](#) mhi, [CvArr](#) mask, [CvArr](#) orientation, [num](#) delta1, [num](#) delta2, [int](#) aperature_size=3)

Calculates the gradient orientation of a motion history image.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

mhi	Motion history image
mask	Mask image; marks pixels where the motion gradient data is correct; output parameter
orientation	Motion gradient orientation image; contains angles from 0 to 360 degrees
delta1	See below
delta2	See below
aperature_size	An integer type number with default value 3

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_video.cpp

3.6.7 CalcOpticalFlowBM

- **CalcOpticalFlowBM**([CvArr](#) prev, [CvArr](#) cur, [CvSize](#) block_size, [CvSize](#) shift_size, [CvSize](#) max_range, [int](#) use_previous, [CvArr](#) velx, [CvArr](#) vely)

Calculates the optical flow for two images by using the block matching method.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

prev	First image, 8-bit, single-channel
cur	A wrapped OpenCV object of type <code>CvArr</code>
block_size	A wrapped OpenCV object of type <code>CvSize</code>
shift_size	A wrapped OpenCV object of type <code>CvSize</code>
max_range	Size of the scanned neighborhood in pixels around the block
use_previous	An integer type number
velx	A wrapped OpenCV object of type <code>CvArr</code>
vely	Vertical component of the optical flow of the same size <code>velx</code> , 32-bit floating-point, single-channel

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_video.cpp

3.6.8 CalcOpticalFlowFarneback

- **CalcOpticalFlowFarneback**(`CvArr` prev, `CvArr` next, `CvArr` flow, `num` pyr_scale, `int` levels, `int` winsize, `int` iterations, `int` poly_n, `num` poly_sigma, `int` flags)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

prev	A wrapped OpenCV object of type <code>CvArr</code>
next	A wrapped OpenCV object of type <code>CvArr</code>
flow	A wrapped OpenCV object of type <code>CvArr</code>
pyr_scale	A floating point number
levels	An integer type number
winsize	An integer type number
iterations	An integer type number
poly_n	An integer type number
poly_sigma	A floating point number
flags	An integer type number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_video.cpp

3.6.9 CalcOpticalFlowHS

- **CalcOpticalFlowHS**([CvArr](#) prev, [CvArr](#) cur, [int](#) use_previous, [CvArr](#) velx, [CvArr](#) vely, [num](#) lambda, [CvTermCriteria](#) criteria)

Calculates the optical flow for two images.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

prev	First image, 8-bit, single-channel
cur	A wrapped OpenCV object of type CvArr
use_previous	An integer type number
velx	Horizontal component of the optical flow of the same size as input images, 32-bit floating-point, single-channel
vely	Vertical component of the optical flow of the same size as input images, 32-bit floating-point, single-channel
lambda	Lagrangian multiplier
criteria	Criteria of termination of velocity computing

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_video.cpp

3.6.10 CalcOpticalFlowLK

- **CalcOpticalFlowLK**([CvArr](#) prev, [CvArr](#) cur, [CvSize](#) win_size, [CvArr](#) velx, [CvArr](#) vely)

Calculates the optical flow for two images.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

prev	First image, 8-bit, single-channel
cur	A wrapped OpenCV object of type <code>CvArr</code>
win_size	A wrapped OpenCV object of type <code>CvSize</code>
velx	Horizontal component of the optical flow of the same size as input images, 32-bit floating-point, single-channel
vely	Vertical component of the optical flow of the same size as input images, 32-bit floating-point, single-channel

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_video.cpp

3.6.11 CalcOpticalFlowPyrLK

- **string** `CalcOpticalFlowPyrLK`(`CvArr` prev, `CvArr` curr, `CvArr` prev_pyr, `CvArr` curr_pyr, `CvPoint2D32f`[] prev_features, `CvPoint2D32f`[] curr_features, `int` count, `CvSize` win_size, `int` level, `CvTermCriteria` criteria, `int` flags)

Calculates the optical flow for a sparse feature set using the iterative Lucas-Kanade method with pyramids.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

prev	First frame, at time t
curr	Second frame, at time $t + dt$
prev_pyr	A wrapped OpenCV object of type <code>CvArr</code>
curr_pyr	A wrapped OpenCV object of type <code>CvArr</code>
prev_features	A wrapped OpenCV object of type <code>CvPoint2D32f</code> which is an array
curr_features	A wrapped OpenCV object of type <code>CvPoint2D32f</code> which is an array
count	Number of feature points
win_size	A wrapped OpenCV object of type <code>CvSize</code>
level	Maximal pyramid level number. If 0, pyramids are not used (single level), if 1, two levels are used, etc

criteria	Specifies when the iteration process of finding the flow for each point on each pyramid level should be stopped
flags	An integer type number

Returns

[string](#) - An array of characters

The documentation was generated from :

- lua_video.cpp

3.6.12 CamShift

- [num](#) **CamShift**([CvArr](#) prob_image, [CvRect](#) window, [CvTermCriteria](#) criteria, [CvConnectedComp](#) comp, [CvBox2D](#) box=nil)

Finds the object center, size, and orientation

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

prob_image	A wrapped OpenCV object of type CvArr
window	Initial search window
criteria	Stop criteria for the underlying meanShift
comp	A wrapped OpenCV object of type CvConnectedComp
box	A wrapped OpenCV object of type CvBox2D with default value <i>nil</i>

Returns

[num](#) - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_video.cpp

3.6.13 ChangeDetection

- [num](#) **ChangeDetection**([IpImage](#) prev_frame, [IpImage](#) curr_frame, [IpImage](#) change_mask)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

prev_frame	A wrapped OpenCV object of type <code>IplImage</code>
curr_frame	A wrapped OpenCV object of type <code>IplImage</code>
change_mask	A wrapped OpenCV object of type <code>IplImage</code>

Returns

`num` - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_video.cpp

3.6.14 EstimateRigidTransform

- `int EstimateRigidTransform(CvArr A, CvArr B, CvMat M, int full_affine)`

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

A	A wrapped OpenCV object of type <code>CvArr</code>
B	A wrapped OpenCV object of type <code>CvArr</code>
M	A wrapped OpenCV object of type <code>CvMat</code>
full_affine	An integer type number

Returns

`int` - An integer type number defined by architecture

The documentation was generated from :

- lua_video.cpp

3.6.15 MeanShift

- **num** **MeanShift**([CvArr](#) prob_image, [CvRect](#) window, [CvTermCriteria](#) criteria, [CvConnectedComp](#) comp)

Finds the object center on back projection.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

prob_image	Back projection of the object histogram (see CalcBackProject)
window	Initial search window
criteria	Criteria applied to determine when the window search should be finished
comp	Resultant structure that contains the converged search window coordinates (<code>comp->rect</code> field) and the sum of all of the pixels inside the window (<code>comp->area</code> field)

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_video.cpp

3.6.16 RefineForegroundMaskBySegm

- **RefineForegroundMaskBySegm**([CvSeq](#) segments, [CvBGStatModel](#) bg_model)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

segments	A wrapped OpenCV object of type CvSeq
bg_model	A wrapped OpenCV object of type CvBGStatModel

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_video.cpp

3.6.17 ReleaseBGCodeBookModel

- **ReleaseBGCodeBookModel**([CvBGCodeBookModel](#) model)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

model	A wrapped OpenCV object of type CvBGCodeBookModel
--------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_video.cpp

3.6.18 ReleaseBGStatModel

- **ReleaseBGStatModel**([CvBGStatModel](#) model)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

model	A wrapped OpenCV object of type CvBGStatModel
--------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_video.cpp

3.6.19 ReleaseKalman

- **ReleaseKalman**([CvKalman](#) kalman)
Deallocates the Kalman filter structure.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

kalman	double pointer to the Kalman filter structure
---------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_video.cpp

3.6.20 UpdateBGStatModel

- **num UpdateBGStatModel**([IplImage](#) current_frame, [CvBGStatModel](#) bg_model, [num](#) learningRate=-1)
Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

current_frame	A wrapped OpenCV object of type IplImage
bg_model	A wrapped OpenCV object of type CvBGStatModel
learningRate	A floating point number with default value

Returns

[num](#) - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_video.cpp

3.6.21 UpdateMotionHistory

- **UpdateMotionHistory**([CvArr](#) silhouette, [CvArr](#) mhi, [num](#) timestamp, [num](#) duration)

Updates the motion history image by a moving silhouette.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

silhouette	Silhouette mask that has non-zero pixels where the motion occurs
mhi	Motion history image, that is updated by the function (single-channel, 32-bit floating-point)
timestamp	Current time in milliseconds or other units
duration	Maximal duration of the motion track in the same units as <code>timestamp</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_video.cpp

3.7 Module legacy

3.7.1 3dTracker2dTrackedObject

- **3dTracker2dTrackedObject**([int](#) id, [CvPoint2D32f](#) p)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

id	An integer type number
p	A wrapped OpenCV object of type <code>CvPoint2D32f</code>

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.2 3dTracker3dTrackedObject

- **3dTracker3dTrackedObject**(int id, [CvPoint3D32f](#) p)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

id	An integer type number
p	A wrapped OpenCV object of type CvPoint3D32f

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.3 CalcDecompCoeff

- **num CalcDecompCoeff**([IplImage](#) obj, [IplImage](#) eigObj, [IplImage](#) avg)

Calculates the decomposition coefficient of an input object.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

obj	Input object.
eigObj	Eigen object.
avg	Averaged object.

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_legacy.cpp

3.7.4 CalcPGH

- **CalcPGH**([CvSeq](#) contour, [CvHistogram](#) hist)

Calculates a pair-wise geometrical histogram for a contour.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

contour	Input contour. Currently, only integer point coordinates are allowed
hist	Calculated histogram; must be two-dimensional

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.5 CreateGLCMDescriptors

- **CreateGLCMDescriptors**([CvGLCM](#) destGLCM, [int](#) descriptorOptimizationType=[CV_GLCMDESC_OPTIMIZATION_ALLOWDOUBLENES](#)T)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

destGLCM	A wrapped OpenCV object of type CvGLCM
descriptorOptimizationType	An integer type number with default value CV_GLCMDESC_OPTIMIZATION_ALLOWDOUBLENES T

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.6 CreateHandMask

- **CreateHandMask**([CvSeq](#) hand_points, [IplImage](#) img_mask, [CvRect](#) roi)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

hand_points	A wrapped OpenCV object of type CvSeq
img_mask	A wrapped OpenCV object of type IplImage
roi	A wrapped OpenCV object of type CvRect

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.7 DeInterlace

- **DeInterlace**([CvArr](#) frame, [CvArr](#) fieldEven, [CvArr](#) fieldOdd)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

frame	A wrapped OpenCV object of type CvArr
fieldEven	A wrapped OpenCV object of type CvArr
fieldOdd	A wrapped OpenCV object of type CvArr

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.8 EViterbi

- **num EViterbi**([CvImgObsInfo](#) obs_info, [CvEHMM](#) hmm)

Executes the Viterbi algorithm for the embedded HMM.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

obs_info	A wrapped OpenCV object of type CvImgObsInfo
hmm	HMM structure.

Returns

[num](#) - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_legacy.cpp

3.7.9 EstimateHMMStateParams

- **EstimateHMMStateParams**([CvImgObsInfo](#)[] obs_info_array, [int](#) num_img, [CvEHMM](#) hmm)

Estimates all of the parameters of every HMM state.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

obs_info_array	A wrapped OpenCV object of type CvImgObsInfo which is an array
num_img	An integer type number
hmm	HMM.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.10 EstimateObsProb

- **EstimateObsProb**([CvImgObsInfo](#) obs_info, [CvEHMM](#) hmm)

Computes the probability of every observation of several images.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

obs_info	A wrapped OpenCV object of type CvImgObsInfo
hmm	HMM structure.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.11 EstimateTransProb

- **EstimateTransProb**([CvImgObsInfo](#)[] obs_info_array, [int](#) num_img, [CvEHMM](#) hmm)

Computes transition probability matrices for the embedded HMM.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

obs_info_array	A wrapped OpenCV object of type CvImgObsInfo which is an array
num_img	An integer type number
hmm	HMM.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.12 GetGLCMDescriptor

- **num** **GetGLCMDescriptor**(**CvGLCM** glcm, **int** step, **int** descriptor)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

glcm	A wrapped OpenCV object of type CvGLCM
step	An integer type number
descriptor	An integer type number

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_legacy.cpp

3.7.13 GetGLCMDescriptorStatistics

- **num,num** **GetGLCMDescriptorStatistics**(**CvGLCM** glcm, **int** descriptor)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

glcm	A wrapped OpenCV object of type CvGLCM
descriptor	An integer type number

Returns

- [num](#) - A floating point number defined by lua.h header, in default it is type double
- [num](#) - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_legacy.cpp

3.7.14 InitMixSegm

- **InitMixSegm**([CvImgObsInfo](#)[] obs_info_array, [int](#) num_img, [CvEHMM](#) hmm)
Segments all observations within every internal state of HMM using state mixture components.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

obs_info_array	A wrapped OpenCV object of type CvImgObsInfo which is an array
num_img	An integer type number
hmm	HMM.

Returns

- none** - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.15 MatchContourTrees

- **num** **MatchContourTrees**([CvContourTree](#) tree1, [CvContourTree](#) tree2, [int](#) method, [num](#) threshold)
Compares two contours using their tree representations.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

tree1	First contour tree
tree2	Second contour tree
method	Similarity measure, only <code>CV_CONTOUR_TREES_MATCH_I1</code> is supported
threshold	Similarity threshold

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_legacy.cpp

3.7.16 MixSegmL2

- **MixSegmL2**([CvImgObsInfo](#)[] obs_info_array, [int](#) num_img, [CvEHMM](#) hmm)
Segments the observations from all of the training images using the mixture components of the newly assigned states.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

obs_info_array	A wrapped OpenCV object of type <code>CvImgObsInfo</code> which is an array
num_img	An integer type number
hmm	HMM.

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.17 Release2DHMM

- **Release2DHMM**([CvEHMM](#) hmm)
Releases a 2D, embedded HMM.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

hmm	Address of the pointer to the HMM to be released.
------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.18 ReleaseFaceTracker

- **ReleaseFaceTracker**([CvFaceTracker](#) ppFaceTracker)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

ppFaceTracker	A wrapped OpenCV object of type CvFaceTracker
----------------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.19 ReleaseGLCM

- **ReleaseGLCM**([CvGLCM](#) glcm)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
[\(view full description\)](#)

Parameters

glcm	A wrapped OpenCV object of type CvGLCM
-------------	--

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.20 ReleaseObsInfo

- **ReleaseObsInfo**([CvImgObsInfo](#) obs_info)

Releases the observation vector structures.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

obs_info	A wrapped OpenCV object of type CvImgObsInfo
-----------------	--

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.7.21 SnakelImage

- **num,num,num SnakelImage**([IpImage](#) image, [CvPoint\[\]](#) points, [int](#) lenght, [num](#) alpha, [num](#) beta, [num](#) gamma, [int](#) coeff_usage, [CvSize](#) win, [CvTermCriteria](#) criteria, [int](#) calc_gradient=1)

Changes the contour position to minimize its energy.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

image	The source image or external energy field
points	Contour points (snake)
length	An integer type number
alpha	A floating point number
beta	Weight[s] of curvature energy, similar to <code>alpha</code>
gamma	Weight[s] of image energy, similar to <code>alpha</code>
co-eff_usage	An integer type number
win	Size of neighborhood of every point used to search the minimum, both <code>win.width</code> and <code>win.height</code> must be odd
criteria	Termination criteria
calc_gradient	Gradient flag; if not 0, the function calculates the gradient magnitude for every image pixel and considers it as the energy field, otherwise the input image itself is considered

Returns

- `num` - A floating point number defined by `lua.h` header, in default it is type double
- `num` - A floating point number defined by `lua.h` header, in default it is type double
- `num` - A floating point number defined by `lua.h` header, in default it is type double

The documentation was generated from :

- `lua_legacy.cpp`

3.7.22 TrackFace

- `int, num` **TrackFace**(`CvFaceTracker` pFaceTracking, `IplImage` imgGray, `CvRect[]` pRects, `int` nRects, `CvPoint` ptRotate)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

pFace-Tracking	A wrapped OpenCV object of type <code>CvFaceTracker</code>
imgGray	A wrapped OpenCV object of type <code>IplImage</code>
pRects	A wrapped OpenCV object of type <code>CvRect</code> which is an array
nRects	An integer type number
ptRotate	A wrapped OpenCV object of type <code>CvPoint</code>

Returns

- [int](#) - An integer type number defined by architecture
- [num](#) - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_legacy.cpp

3.7.23 UniformImgSegm

- **UniformImgSegm**([CvImgObsInfo](#) obs_info, [CvEHMM](#) ehmm)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

obs_info	A wrapped OpenCV object of type CvImgObsInfo
ehmm	A wrapped OpenCV object of type CvEHMM

Returns

- none** - function doesn't return anything.

The documentation was generated from :

- lua_legacy.cpp

3.8 Module objdetect

3.8.1 ReleaseHaarClassifierCascade

- **ReleaseHaarClassifierCascade**([CvHaarClassifierCascade](#) cascade)

Releases the haar classifier cascade.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

([view full description](#))

Parameters

cascade	Double pointer to the released cascade. The pointer is cleared by the function
----------------	--

Generated by Lua and Doxygen latex template

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_objdetect.cpp

3.8.2 ReleaseLatentSvmDetector

- **ReleaseLatentSvmDetector**([CvLatentSvmDetector](#) detector)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

detector	A wrapped OpenCV object of type CvLatentSvmDetector
-----------------	---

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_objdetect.cpp

3.8.3 RunHaarClassifierCascade

- **num** **RunHaarClassifierCascade**([CvHaarClassifierCascade](#) cascade, [CvPoint](#) pt, [int](#) start_stage=0)

Runs a cascade of boosted classifiers at the given image location.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.
([view full description](#))

Parameters

cascade	Haar classifier cascade
pt	The upper left point of window in which the features will be computed. Size of the window is equal to size of training images.
start_stage	Initial zero-based index of the cascade stage to start from. The function assumes that all the previous stages are passed. This feature is used internally by HaarDetectObjects for better processor cache utilization.

Returns

num - A floating point number defined by lua.h header, in default it is type double

The documentation was generated from :

- lua_objdetect.cpp

3.8.4 SetImagesHaarClassifierCascade

- **SetImagesHaarClassifierCascade**([CvHaarClassifierCascade](#) cascade, [CvArr](#) sum, [CvArr](#) sqsum, [CvArr](#) tilted_sum, [num](#) scale)

Non details detected.

Detailed Description

Full function's description can be found at the OpenCV official wiki, see link below.

[\(view full description\)](#)

Parameters

cascade	A wrapped OpenCV object of type CvHaarClassifierCascade
sum	A wrapped OpenCV object of type CvArr
sqsum	A wrapped OpenCV object of type CvArr
tilted_sum	A wrapped OpenCV object of type CvArr
scale	A floating point number

Returns

none - function doesn't return anything.

The documentation was generated from :

- lua_objdetect.cpp

Chapter 4

Object reference manual

There are implemented plenty of OpenCV structures in LuaCV, even dynamical structures are partially implemented (CvSeq, CvGraph, ...). Due to Lua callback functions (`__newindex`, `__index`) is possible to set and get variables from some of OpenCV C structure attributes from Lua. It's not efficient but it's possible e.g. each OpenCV pointer has his own metatable with callbacks.

4.1 Basic Lua and LuaCV types

These are base Lua and LuaCV types, Lua is in default set to have number type as double, but due to many OpenCV functions, there is need for integer type

Types

- **number** - Base Lua number given by lua.conf setting
- **float** - C++ float number
- **string** - Base Lua string
- **userdata** - Raw C++ pointer without metatable
- **int** - C++ integer number

4.2 Cv3dTracker2dTrackedObject

No description detected

Attributes

- **number** - id
- **CvPoint2D32f** - p

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/Cv3dTracker2dTrackedObject.cpp

4.3 Cv3dTrackerTrackedObject

No description detected

Attributes

- [number](#) - id
- [CvPoint3D32f](#) - p

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/Cv3dTrackerTrackedObject.cpp

4.4 CvArr

Arbitrary array

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvArr.cpp

4.5 CvBGCodeBookElem

No description detected

Attributes

- [UserData](#) - next
- [number](#) - stale
- [number](#) - tLastUpdate

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvBGCodeBookElem.cpp

4.6 CvBGCodeBookModel

No description detected

Attributes

- [UserData](#) - freeList
- [CvSize](#) - size
- [CvMemStorage](#) - storage
- [number](#) - t

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvBGCodeBookModel.cpp

4.7 CvBGPixelCCStatTable

No description detected

Attributes

- [number](#) - Pv
- [number](#) - Pvb

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvBGPixelCCStatTable.cpp

4.8 CvBGPixelCStatTable

No description detected

Attributes

- [number](#) - Pv
- [number](#) - Pvb

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvBGPixelCStatTable.cpp

4.9 CvBGPixelStat

No description detected

Attributes

- [CvBGPixelCStatTable](#) - ctable
- [CvBGPixelCCStatTable](#) - cctable
- [number](#) - is_trained_st_model
- [number](#) - is_trained_dyn_model
- [number](#) - Pbcc
- [number](#) - Pbc

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvBGPixelStat.cpp

4.10 CvBGStatModel

No description detected

Attributes

- [UserData](#) - background
- [UserData](#) - foreground
- [CvSeq](#) - foreground_regions
- [number](#) - layer_count
- [CvMemStorage](#) - storage
- [number](#) - type

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvBGStatModel.cpp

4.11 CvBox2D

No description detected

Attributes

- [number](#) - angle
- [CvPoint2D32f](#) - center
- [CvSize2D32f](#) - size

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvBox2D.cpp

4.12 CvCapture

Video capturing structure.

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvCapture.cpp

4.13 CvChain

No description detected

Attributes

- [UserData](#) - block_max
- [number](#) - delta_elems
- [number](#) - elem_size
- [CvSeqBlock](#) - first
- [number](#) - flags
- [CvSeqBlock](#) - free_blocks
- [number](#) - header_size
- [CvSeq](#) - h_prev
- [CvSeq](#) - h_next
- [CvPoint](#) - origin
- [UserData](#) - ptr
- [CvMemStorage](#) - storage
- [number](#) - total
- [CvSeq](#) - v_prev
- [CvSeq](#) - v_next

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvChain.cpp

4.14 CvChainPtReader

No description detected

Attributes

- [CvSeqBlock](#) - block
- [UserData](#) - block_min
- [UserData](#) - block_max
- [number](#) - code
- [number](#) - delta_index
- [number](#) - header_size
- [UserData](#) - ptr
- [CvPoint](#) - pt
- [UserData](#) - prev_elem
- [CvSeq](#) - seq

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvChainPtReader.cpp

4.15 CvConnectedComp

No description detected

Attributes

- [number](#) - area
- [CvSeq](#) - contour
- [CvRect](#) - rect
- [CvScalar](#) - value

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvConnectedComp.cpp

4.16 CvContour

No description detected

Attributes

- [UserData](#) - block_max
- [number](#) - color
- [number](#) - delta_elems
- [number](#) - elem_size
- [CvSeqBlock](#) - first
- [number](#) - flags
- [CvSeqBlock](#) - free_blocks
- [number](#) - header_size
- [CvSeq](#) - h_prev
- [CvSeq](#) - h_next
- [UserData](#) - ptr
- [CvRect](#) - rect
- [CvMemStorage](#) - storage
- [number](#) - total
- [CvSeq](#) - v_prev
- [CvSeq](#) - v_next

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvContour.cpp

4.17 CvContourScanner

No description detected

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvContourScanner.cpp

4.18 CvContourTree

No description detected

Attributes

- [UserData](#) - block_max
- [number](#) - delta_elems
- [number](#) - elem_size
- [CvSeqBlock](#) - first
- [number](#) - flags
- [CvSeqBlock](#) - free_blocks
- [number](#) - header_size
- [CvSeq](#) - h_prev
- [CvSeq](#) - h_next
- [UserData](#) - ptr
- [CvPoint](#) - p1
- [CvPoint](#) - p2
- [CvMemStorage](#) - storage
- [number](#) - total
- [CvSeq](#) - v_prev
- [CvSeq](#) - v_next

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvContourTree.cpp

4.19 CvEHMM

No description detected

Attributes

- [number](#) - level
- [number](#) - num_states

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvEHMM.cpp

4.20 CvFaceTracker

No description detected

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvFaceTracker.cpp

4.21 CvFeatureTree

No description detected

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvFeatureTree.cpp

4.22 CvFGDStatModel

No description detected

Attributes

- [UserData](#) - Ftd
- [UserData](#) - Fbd
- [UserData](#) - background
- [UserData](#) - foreground
- [CvSeq](#) - foreground_regions

- [number](#) - layer_count
- [CvBGPixelStat](#) - pixel_stat
- [UserData](#) - prev_frame
- [CvFGDStatModelParams](#) - params
- [CvMemStorage](#) - storage
- [number](#) - type

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvFGDStatModel.cpp

4.23 CvFGDStatModelParams

No description detected

Attributes

- [number](#) - alpha1
- [number](#) - alpha2
- [number](#) - alpha3
- [number](#) - delta
- [number](#) - is_obj_without_holes
- [number](#) - Lc
- [number](#) - Lcc
- [number](#) - N1c
- [number](#) - N2c
- [number](#) - N1cc
- [number](#) - N2cc
- [number](#) - minArea
- [number](#) - perform_morphing
- [number](#) - T

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvFGDStatModelParams.cpp

4.24 CvFont

No description detected

Attributes

- [UserData](#) - ascii
- [UserData](#) - cyrillic
- [number](#) - dx
- [number](#) - font_face
- [UserData](#) - greek
- [number](#) - hscale
- [number](#) - line_type
- [number](#) - shear
- [number](#) - thickness
- [number](#) - vscale

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvFont.cpp

4.25 CvGaussBGModel

No description detected

Attributes

- [UserData](#) - background
- [number](#) - countFrames
- [UserData](#) - foreground
- [CvSeq](#) - foreground_regions
- [CvGaussBGPoint](#) - g_point
- [number](#) - layer_count
- [CvGaussBGStatModelParams](#) - params
- [CvMemStorage](#) - storage
- [number](#) - type

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvGaussBGModel.cpp

4.26 CvGaussBGPoint

No description detected

Attributes

- [CvGaussBGValues](#) - g_values

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvGaussBGPoint.cpp

4.27 CvGaussBGStatModelParams

No description detected

Attributes

- [number](#) - bg_threshold
- [number](#) - minArea
- [number](#) - n_gauss
- [number](#) - std_threshold
- [number](#) - variance_init
- [number](#) - weight_init
- [number](#) - win_size

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvGaussBGStatModelParams.cpp

4.28 CvGaussBGValues

No description detected

Attributes

- [number](#) - match_sum
- [number](#) - weight

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvGaussBGValues.cpp

4.29 CvGLCM

No description detected

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvGLCM.cpp

4.30 CvGraph

Oriented or unoriented weighted graph.

Attributes

- [number](#) - active_count
- [UserData](#) - block_max
- [number](#) - delta_elems
- [CvSet](#) - edges
- [number](#) - elem_size
- [CvSeqBlock](#) - first
- [number](#) - flags
- [CvSeqBlock](#) - free_blocks
- [CvSetElem](#) - free_elems

- [number](#) - header_size
- [CvSeq](#) - h_prev
- [CvSeq](#) - h_next
- [UserData](#) - ptr
- [CvMemStorage](#) - storage
- [number](#) - total
- [CvSeq](#) - v_prev
- [CvSeq](#) - v_next

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvGraph.cpp

4.31 CvGraphEdge

No description detected

Attributes

- [number](#) - flags
- [number](#) - weight

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvGraphEdge.cpp

4.32 CvGraphScanner

Graph traversal state.

Attributes

- [CvGraphEdge](#) - edge
- [CvGraphVtx](#) - dst
- [CvGraph](#) - graph
- [number](#) - index

- [number](#) - mask
- [CvSeq](#) - stack
- [CvGraphVtx](#) - vtx

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvGraphScanner.cpp

4.33 CvGraphVtx

No description detected

Attributes

- [number](#) - flags
- [CvGraphEdge](#) - first

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvGraphVtx.cpp

4.34 CvGraphVtx2D

No description detected

Attributes

- [number](#) - flags
- [CvGraphEdge](#) - first
- [CvPoint2D32f](#) - ptr

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvGraphVtx2D.cpp

4.35 CvHaarClassifier

No description detected

Attributes

- [number](#) - count
- [CvHaarFeature](#) - haar_feature

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvHaarClassifier.cpp

4.36 CvHaarClassifierCascade

No description detected

Attributes

- [number](#) - count
- [number](#) - flags
- [CvSize](#) - orig_window_size
- [CvSize](#) - real_window_size
- [number](#) - scale
- [CvHaarStageClassifier](#) - stage_classifier

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvHaarClassifierCascade.cpp

4.37 CvHaarFeature

No description detected

Attributes

- [number](#) - tilted

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvHaarFeature.cpp

4.38 CvHaarStageClassifier

No description detected

Attributes

- [number](#) - count
- [number](#) - child
- [CvHaarClassifier](#) - classifier
- [number](#) - next
- [number](#) - parent
- [number](#) - threshold

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvHaarStageClassifier.cpp

4.39 CvHistogram

Multi-dimensional histogram.

Attributes

- [UserData](#) - bins
- [CvMatND](#) - mat
- [number](#) - type

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvHistogram.cpp

4.40 CvHuMoments

No description detected

Attributes

- [number](#) - hu1
- [number](#) - hu2
- [number](#) - hu3
- [number](#) - hu4
- [number](#) - hu5
- [number](#) - hu6
- [number](#) - hu7

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvHuMoments.cpp

4.41 CvImgObsInfo

No description detected

Attributes

- [number](#) - obs_x
- [number](#) - obs_y
- [number](#) - obs_size

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvImgObsInfo.cpp

4.42 CvKalman

Kalman filter state.

Attributes

- [number](#) - CP
- [number](#) - DP
- [number](#) - MP
- [UserData](#) - control_matrix
- [UserData](#) - error_cov_pre
- [UserData](#) - error_cov_post
- [UserData](#) - gain
- [UserData](#) - measurement_noise_cov
- [UserData](#) - measurement_matrix
- [UserData](#) - process_noise_cov
- [UserData](#) - state_pre
- [UserData](#) - state_post
- [UserData](#) - transition_matrix
- [UserData](#) - temp1
- [UserData](#) - temp2
- [UserData](#) - temp3
- [UserData](#) - temp4
- [UserData](#) - temp5

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvKalman.cpp

4.43 CvLatentSvmDetector

No description detected

Attributes

- [number](#) - num_filters
- [number](#) - num_components
- [number](#) - score_threshold

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- `objects/CvLatentSvmDetector.cpp`

4.44 CvLineIterator

No description detected

Attributes

- `number` - `err`
- `number` - `minus_delta`
- `number` - `minus_step`
- `number` - `plus_delta`
- `number` - `plus_step`
- `UserData` - `ptr`

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- `objects/CvLineIterator.cpp`

4.45 CvLSH

No description detected

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- `objects/CvLSH.cpp`

4.46 CvLSHOperations

No description detected

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvLSHOperations.cpp

4.47 CvLSVMFilterObject

No description detected

Attributes

- [number](#) - numFeatures
- [number](#) - sizeX
- [number](#) - sizeY
- [CvLSVMFilterPosition](#) - V

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvLSVMFilterObject.cpp

4.48 CvLSVMFilterPosition

No description detected

Attributes

- [number](#) - l
- [number](#) - x

- [number](#) - y

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvLSVMFilterPosition.cpp

4.49 CvMat

A multi-channel matrix.

Attributes

- [number](#) - cols
- [number](#) - height
- [number](#) - rows
- [number](#) - step
- [number](#) - type
- [number](#) - width

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvMat.cpp

4.50 CvMatND

Multi-dimensional dense multi-channel array.

Attributes

- [number](#) - dims
- [number](#) - hdr_refcount
- [number](#) - type

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- `objects/CvMatND.cpp`

4.51 CvMemBlock

Memory storage block.

Attributes

- [CvMemBlock](#) - next
- [CvMemBlock](#) - prev

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- `objects/CvMemBlock.cpp`

4.52 CvMemStorage

Growing memory storage.

Attributes

- [CvMemBlock](#) - bottom
- [number](#) - block_size
- [number](#) - free_space
- [CvMemStorage](#) - parent
- [number](#) - signature
- [CvMemBlock](#) - top

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- `objects/CvMemStorage.cpp`

4.53 CvMemStoragePos

Memory storage position.

Attributes

- [number](#) - free_space
- [CvMemBlock](#) - top

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvMemStoragePos.cpp

4.54 CvMoments

No description detected

Attributes

- [number](#) - inv_sqrt_m00
- [number](#) - m00
- [number](#) - m10
- [number](#) - m01
- [number](#) - m20
- [number](#) - m11
- [number](#) - m02
- [number](#) - m30
- [number](#) - m21
- [number](#) - m12
- [number](#) - m03
- [number](#) - mu20
- [number](#) - mu11
- [number](#) - mu02
- [number](#) - mu30
- [number](#) - mu21
- [number](#) - mu12
- [number](#) - mu03

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvMoments.cpp

4.55 CvMSERParams

No description detected

Attributes

- [number](#) - delta
- [number](#) - maxArea
- [number](#) - minArea
- [number](#) - maxVariation
- [number](#) - minDiversity
- [number](#) - maxEvolution
- [number](#) - areaThreshold
- [number](#) - minMargin
- [number](#) - edgeBlurSize

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvMSERParams.cpp

4.56 CvNArrayIterator

No description detected

Attributes

- [number](#) - count
- [number](#) - dims
- [CvSize](#) - size

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvNArrayIterator.cpp

4.57 CvObjectDetection

No description detected

Attributes

- [CvRect](#) - rect
- [number](#) - score

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvObjectDetection.cpp

4.58 CvPoint

2D point with integer coordinates (usually zero-based).

Attributes

- [number](#) - x
- [number](#) - y

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvPoint.cpp

4.59 CvPoint2D32f

2D point with floating-point coordinates

Attributes

- [number](#) - x
- [number](#) - y

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvPoint2D32f.cpp

4.60 CvPoint2D64f

2D point with double precision floating-point coordinates

Attributes

- `number` - x
- `number` - y

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- `objects/CvPoint2D64f.cpp`

4.61 CvPoint3D32f

3D point with floating-point coordinates

Attributes

- `number` - x
- `number` - y
- `number` - z

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- `objects/CvPoint3D32f.cpp`

4.62 CvPoint3D64f

3D point with double precision floating-point coordinates

Attributes

- `number` - x
- `number` - y

- [number](#) - z

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvPoint3D64f.cpp

4.63 CvPOSITObject

No description detected

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvPOSITObject.cpp

4.64 CvQuadEdge2D

Quad-edge of planar subdivision.

Attributes

- [number](#) - flags

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvQuadEdge2D.cpp

4.65 CvRect

Offset (usually the top-left corner) and size of a rectangle.

Attributes

- [number](#) - height
- [number](#) - width
- [number](#) - x
- [number](#) - y

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvRect.cpp

4.66 CvRNG

No description detected

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvRNG.cpp

4.67 CvScalar

A container for 1-,2-,3- or 4-tuples of doubles.

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvScalar.cpp

4.68 CvSeq

Growable sequence of elements.

Attributes

- [UserData](#) - block_max
- [number](#) - delta_elems
- [number](#) - elem_size
- [CvSeqBlock](#) - first
- [number](#) - flags
- [CvSeqBlock](#) - free_blocks
- [number](#) - header_size
- [CvSeq](#) - h_prev
- [CvSeq](#) - h_next
- [UserData](#) - ptr
- [CvMemStorage](#) - storage
- [number](#) - total
- [CvSeq](#) - v_prev
- [CvSeq](#) - v_next

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvSeq.cpp

4.69 CvSeqBlock

Continuous sequence block.

Attributes

- [number](#) - count
- [UserData](#) - data
- [CvSeqBlock](#) - next
- [CvSeqBlock](#) - prev
- [number](#) - start_index

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvSeqBlock.cpp

4.70 CvSeqReader

No description detected

Attributes

- [CvSeqBlock](#) - block
- [UserData](#) - block_min
- [UserData](#) - block_max
- [number](#) - delta_index
- [number](#) - header_size
- [UserData](#) - ptr
- [UserData](#) - prev_elem
- [CvSeq](#) - seq

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvSeqReader.cpp

4.71 CvSeqWriter

No description detected

Attributes

- [CvSeqBlock](#) - block
- [UserData](#) - block_min
- [UserData](#) - block_max
- [number](#) - header_size
- [UserData](#) - ptr
- [CvSeq](#) - seq

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvSeqWriter.cpp

4.72 CvSet

Collection of nodes.

Attributes

- [number](#) - active_count
- [UserData](#) - block_max
- [number](#) - delta_elems
- [number](#) - elem_size
- [number](#) - flags
- [CvSeqBlock](#) - free_blocks
- [CvSetElem](#) - free_elems
- [CvSeqBlock](#) - first
- [number](#) - header_size
- [CvSeq](#) - h_prev
- [CvSeq](#) - h_next
- [UserData](#) - ptr
- [CvMemStorage](#) - storage
- [number](#) - total
- [CvSeq](#) - v_prev
- [CvSeq](#) - v_next

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvSet.cpp

4.73 CvSetElem

No description detected

Attributes

- [number](#) - flags
- [CvSetElem](#) - next_free

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvSetElem.cpp

4.74 CvSize

Pixel-accurate size of a rectangle.

Attributes

- [number](#) - height
- [number](#) - width

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvSize.cpp

4.75 CvSize2D32f

Sub-pixel accurate size of a rectangle.

Attributes

- [number](#) - height
- [number](#) - width

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvSize2D32f.cpp

4.76 CvSlice

A sequence slice.

Attributes

- [number](#) - end_index
- [number](#) - start_index

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvSlice.cpp

4.77 CvSparseMat

Multi-dimensional sparse multi-channel array.

Attributes

- [number](#) - dims
- [number](#) - hdr_refcount
- [CvSet](#) - heap
- [number](#) - hashsize
- [number](#) - idxoffset
- [number](#) - type
- [number](#) - valoffset

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvSparseMat.cpp

4.78 CvSparseMatIterator

No description detected

Attributes

- [number](#) - curidx
- [CvSparseMat](#) - mat
- [CvSparseNode](#) - node

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvSparseMatIterator.cpp

4.79 CvSparseNode

No description detected

Attributes

- [number](#) - hashval
- [CvSparseNode](#) - next

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvSparseNode.cpp

4.80 CvStarDetectorParams

No description detected

Attributes

- [number](#) - maxSize
- [number](#) - responseThreshold
- [number](#) - lineThresholdProjected
- [number](#) - lineThresholdBinarized
- [number](#) - suppressNonmaxSize

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvStarDetectorParams.cpp

4.81 CvStarKeypoint

No description detected

Attributes

- [CvPoint](#) - pt
- [number](#) - response
- [number](#) - size

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvStarKeypoint.cpp

4.82 CvStereoBMState

The structure for block matching stereo correspondence algorithm.

Attributes

- [number](#) - SADWindowSize
- [UserData](#) - cost
- [UserData](#) - disp
- [number](#) - disp12MaxDiff
- [number](#) - minDisparity
- [number](#) - numberOfDisparities
- [number](#) - preFilterType
- [number](#) - preFilterSize
- [number](#) - preFilterCap
- [UserData](#) - preFilteredImg0
- [UserData](#) - preFilteredImg1
- [CvRect](#) - roi1
- [CvRect](#) - roi2
- [number](#) - speckleWindowSize
- [number](#) - speckleRange
- [UserData](#) - slidingSumBuf
- [number](#) - textureThreshold
- [number](#) - trySmallerWindows
- [number](#) - uniquenessRatio

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvStereoBMState.cpp

4.83 CvStereoGCState

The structure for graph cuts-based stereo correspondence algorithm

Attributes

- `number` - `lthreshold`
- `number` - `K`
- `UserData` - `dispLeft`
- `UserData` - `dispRight`
- `UserData` - `edgeBuf`
- `number` - `interactionRadius`
- `number` - `lambda`
- `number` - `lambda1`
- `number` - `lambda2`
- `UserData` - `left`
- `number` - `minDisparity`
- `number` - `maxIters`
- `number` - `numberOfDisparities`
- `number` - `occlusionCost`
- `UserData` - `ptrLeft`
- `UserData` - `ptrRight`
- `UserData` - `right`
- `UserData` - `vtxBuf`

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- `objects/CvStereoGCState.cpp`

4.84 CvSubdiv2D

Planar subdivision.

Attributes

- `number` - `active_count`
- `UserData` - `block_max`
- `CvPoint2D32f` - `bottomright`
- `number` - `delta_elems`
- `CvSeq` - `edges`

- [number](#) - elem_size
- [CvSeqBlock](#) - first
- [number](#) - flags
- [CvSeqBlock](#) - free_blocks
- [CvSetElem](#) - free_elems
- [number](#) - header_size
- [CvSeq](#) - h_prev
- [CvSeq](#) - h_next
- [number](#) - is_geometry_valid
- [UserData](#) - ptr
- [number](#) - quad_edges
- [CvMemStorage](#) - storage
- [UserData](#) - recent_edge
- [number](#) - total
- [CvPoint2D32f](#) - topleft
- [CvSeq](#) - v_prev
- [CvSeq](#) - v_next

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvSubdiv2D.cpp

4.85 CvSubdiv2DEdge

No description detected

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvSubdiv2DEdge.cpp

4.86 CvSubdiv2DPoint

Point of original or dual subdivision.

Attributes

- [number](#) - flags
- [UserData](#) - first
- [number](#) - id
- [CvPoint2D32f](#) - pt

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvSubdiv2DPoint.cpp

4.87 CvSURFParams

No description detected

Attributes

- [number](#) - extended
- [number](#) - hessianThreshold
- [number](#) - nOctaves
- [number](#) - nOctaveLayers
- [number](#) - upright

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/CvSURFParams.cpp

4.88 CvSURFPoint

A SURF keypoint, represented as a tuple `((x, y), laplacian, size, dir, hessian)`.

Attributes

- [number](#) - dir
- [number](#) - hessian

- [number](#) - laplacian
- [CvPoint2D32f](#) - pt
- [number](#) - size

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvSURFPoint.cpp

4.89 CvTermCriteria

Termination criteria for iterative algorithms.

Attributes

- [number](#) - epsilon
- [number](#) - max_iter
- [number](#) - type

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvTermCriteria.cpp

4.90 CvTreeNodeIterator

Opens existing or creates new file storage.

Attributes

- [number](#) - level
- [UserData](#) - node
- [number](#) - max_level

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvTreeNodeIterator.cpp

4.91 CvVideoWriter

No description detected

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/CvVideoWriter.cpp

4.92 IplConvKernel

An IplConvKernel is a rectangular convolution kernel, created by function **CreateStructuringElementEx**.

Attributes

- [number](#) - anchorX
- [number](#) - anchorY
- [number](#) - nCols
- [number](#) - nRows
- [number](#) - nShiftR

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/IplConvKernel.cpp

4.93 IplConvKernelFP

No description detected

Attributes

- [number](#) - anchorX
- [number](#) - anchorY
- [number](#) - nCols
- [number](#) - nRows

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/lplConvKernelFP.cpp

4.94 IpImage

IPL image header

Attributes

- [number](#) - ID
- [number](#) - align
- [number](#) - depth
- [number](#) - dataOrder
- [number](#) - height
- [number](#) - imageSize
- [number](#) - nSize
- [number](#) - nChannels
- [number](#) - origin
- [number](#) - widthStep
- [number](#) - width

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.
([view full description](#))

The documentation for this object was generated from :

- objects/lplImage.cpp

4.95 IpROI

No description detected

Attributes

- [number](#) - coi
- [number](#) - height
- [number](#) - width
- [number](#) - xOffset
- [number](#) - yOffset

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/IpROI.cpp

4.96 IpTileInfo

No description detected

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/IpTileInfo.cpp

4.97 Mat

No description detected

Attributes

- No attributes detected.

Detailed Description

Full object's description can be found at the OpenCV official wiki, see the link below.

[\(view full description\)](#)

The documentation for this object was generated from :

- objects/Mat.cpp

Chapter 5

Constant reference manual

This chapter includes all of registered macros from OpenCV to LuaCV. Only simple macros e.g constants are supported because, there are plenty of macro functions in OpenCV C API code.

5.1 Constants from core module

List of constants from core module

Constants

CV_AA	16
CV_AUTOSTEP	0 x7ffffff
CV_AUTO_STEP	0 x7ffffff
CV_BACK	0
CV_C	1
CV_CHOLESKY	3
CV_CMP_EQ	0
CV_CMP_GE	2
CV_CMP_GT	1
CV_CMP_LE	4
CV_CMP_LT	3
CV_CMP_NE	5
CV_CN_MAX	512
CV_CN_SHIFT	3
CV_COVAR_COLS	16
CV_COVAR_NORMAL	1
CV_COVAR_ROWS	8
CV_COVAR_SCALE	4
CV_COVAR_SCRAMBLED	0
CV_COVAR_USE_AVG	2
CV_DEPTH_MAX	(1 << CV_CN_SHIFT)
CV_DIFF	16

CV_DIFF_C	(CV_DIFF CV_C)
CV_DIFF_L1	(CV_DIFF CV_L1)
CV_DIFF_L2	(CV_DIFF CV_L2)
CV_DXT_FORWARD	0
CV_DXT_INVERSE	1
CV_DXT_INVERSE_SCALE	CV_DXT_INV_SCALE
CV_DXT_MUL_CONJ	8 /* conjugate the second argument of cvMulSpectrums */
CV_DXT_ROWS	4 /* transform each row individually */
CV_DXT_SCALE	2 /* divide result by size of array */
CV_ErrModeLeaf	0 /* Print error and exit program */
CV_ErrModeParent	1 /* Print error and continue */
CV_ErrModeSilent	2 /* Don't print and continue */
CV_FILLED	-1
CV_FONT_HERSHEY_COMPLEX	3
CV_FONT_HERSHEY_COMPLEX_SMALL	5
CV_FONT_HERSHEY_DUPLEX	2
CV_FONT_HERSHEY_PLAIN	1
CV_FONT_HERSHEY_SCRIPT_COMPLEX	7
CV_FONT_HERSHEY_SCRIPT_SIMPLEX	6
CV_FONT_HERSHEY_SIMPLEX	0
CV_FONT_HERSHEY_TRIPLEX	4
CV_FONT_ITALIC	16
CV_FONT_VECTOR0	CV_FONT_HERSHEY_SIMPLEX
CV_FRONT	1
CV_GEMM_A_T	1
CV_GEMM_B_T	2
CV_GEMM_C_T	4
CV_GRAPH	CV_SEQ_KIND_GRAPH
CV_GRAPH_FLAG_ORIENTED	(1 << CV_SEQ_FLAG_SHIFT)
CV_HIST_ARRAY	0
CV_HIST_MAGIC_VAL	0x42450000
CV_HIST_RANGES_FLAG	(1 << 11)
CV_HIST_SPARSE	1
CV_HIST_TREE	CV_HIST_SPARSE
CV_HIST_UNIFORM	1
CV_HIST_UNIFORM_FLAG	(1 << 10)
CV_KMEANS_USE_INITIAL_LABELS	1
CV_L1	2
CV_L2	4
CV_LOG2	0.69314718055994530941723212145818
CV_LU	0
CV_MAGIC_MASK	0xFFFF0000
CV_MAT_CN_MASK	((CV_CN_MAX - 1) << CV_CN_SHIFT)
CV_MAT_CONT_FLAG	(1 << CV_MAT_CONT_FLAG_SHIFT)
CV_MAT_CONT_FLAG_SHIFT	14
CV_MAT_DEPTH_MASK	(CV_DEPTH_MAX - 1)

CV_MAT_MAGIC_VAL	0x42420000
CV_MAT_TYPE_MASK	(CV_DEPTH_MAX+CV_CN_MAX - 1)
CV_MAX_ARR	10
CV_MAX_DIM	32
CV_MAX_DIM_HEAP	(1 << 16)
CV_MINMAX	32
CV_NORMAL	16
CV_NORM_MASK	7
CV_NO_CN_CHECK	2
CV_NO_DEPTH_CHECK	1
CV_NO_SIZE_CHECK	4
CV_ORIENTED_GRAPH	(CV_SEQ_KIND_GRAPH CV_GRAPH_FLAG_ORIENTED)
CV_PCA_DATA_AS_COL	1
CV_PCA_DATA_AS_ROW	0
CV_PCA_USE_AVG	2
CV_PI	3.1415926535897932384626433832795
CV_QR	4
CV_RAND_NORMAL	1
CV_RAND_UNI	0
CV_REDUCE_AVG	1
CV_REDUCE_MAX	2
CV_REDUCE_MIN	3
CV_REDUCE_SUM	0
CV_RELATIVE	8
CV_RELATIVE_C	(CV_RELATIVE CV_C)
CV_RELATIVE_L1	(CV_RELATIVE CV_L1)
CV_RELATIVE_L2	(CV_RELATIVE CV_L2)
CV_SEQ_CHAIN	(CV_SEQ_KIND_CURVE CV_SEQ_ELTYPE_CODE)
CV_SEQ_CHAIN_CONTOUR	(CV_SEQ_FLAG_CLOSED CV_SEQ_CHAIN)
CV_SEQ_CONNECTED_COMP	(CV_SEQ_KIND_GENERIC CV_SEQ_ELTYPE_CONNECTED_COMP)
CV_SEQ_CONTOUR	CV_SEQ_POLYGON
CV_SEQ_ELTYPE_BITS	12
CV_SEQ_ELTYPE_CODE	CV_8UC1 /* freeman code: 0..7 */
CV_SEQ_ELTYPE_CONNECTED_COMP	0 /* connected component */
CV_SEQ_ELTYPE_GENERIC	0
CV_SEQ_ELTYPE_GRAPH_EDGE	0 /* &next_o, &next_d, &vtx_o, &vtx_d */
CV_SEQ_ELTYPE_GRAPH_VERTEX	0 /* first_edge, &(x,y) */
CV_SEQ_ELTYPE_INDEX	CV_32SC1 /*#(x,y) */
CV_SEQ_ELTYPE_MASK	((1 << CV_SEQ_ELTYPE_BITS) - 1)
CV_SEQ_ELTYPE_POINT	CV_32SC2 /*(x,y) */
CV_SEQ_ELTYPE_POINT3D	CV_32FC3 /*(x,y,z) */
CV_SEQ_ELTYPE_PPOINT	CV_SEQ_ELTYPE_PTR /*&(x,y)*/
CV_SEQ_ELTYPE_PTR	CV_USRTYPE1
CV_SEQ_ELTYPE_TRIAN_ATR	0 /* vertex of the binary tree */

CV_SEQ_FLAG_CLOSED	(1 << CV_SEQ_FLAG_SHIFT)
CV_SEQ_FLAG_CONVEX	(0 << CV_SEQ_FLAG_SHIFT)
CV_SEQ_FLAG_HOLE	(2 << CV_SEQ_FLAG_SHIFT)
CV_SEQ_FLAG_SHIFT	(CV_SEQ_KIND_BITS + CV_SEQ_ELTYPE_BITS)
CV_SEQ_FLAG_SIMPLE	(0 << CV_SEQ_FLAG_SHIFT)
CV_SEQ_INDEX	(CV_SEQ_KIND_GENERIC CV_SEQ_ELTYPE_INDEX)
CV_SEQ_KIND_BIN_TREE	(2 << CV_SEQ_ELTYPE_BITS)
CV_SEQ_KIND_BITS	2
CV_SEQ_KIND_CURVE	(1 << CV_SEQ_ELTYPE_BITS)
CV_SEQ_KIND_GENERIC	(0 << CV_SEQ_ELTYPE_BITS)
CV_SEQ_KIND_GRAPH	(1 << CV_SEQ_ELTYPE_BITS)
CV_SEQ_KIND_MASK	((1 << CV_SEQ_KIND_BITS) - 1) << CV_SEQ_ELTYPE_BITS)
CV_SEQ_KIND_SUBDIV2D	(2 << CV_SEQ_ELTYPE_BITS)
CV_SEQ_MAGIC_VAL	0x42990000
CV_SEQ_POINT3D_SET	(CV_SEQ_KIND_GENERIC CV_SEQ_ELTYPE_POINT3D)
CV_SEQ_POINT_SET	(CV_SEQ_KIND_GENERIC CV_SEQ_ELTYPE_POINT)
CV_SEQ_POLYGON	(CV_SEQ_FLAG_CLOSED CV_SEQ_POLYLINE)
CV_SEQ_POLYGON_TREE	(CV_SEQ_KIND_BIN_TREE CV_SEQ_ELTYPE_TRIAN_ATR)
CV_SEQ_POLYLINE	(CV_SEQ_KIND_CURVE CV_SEQ_ELTYPE_POINT)
CV_SEQ_SIMPLE_POLYGON	(CV_SEQ_FLAG_SIMPLE CV_SEQ_POLYGON)
CV_SET_ELEM_FREE_FLAG	(1 << (sizeof(int)*8-1))
CV_SET_ELEM_IDX_MASK	((1 << 26) - 1)
CV_SET_MAGIC_VAL	0x42980000
CV_SORT_ASCENDING	0
CV_SORT_DESCENDING	16
CV_SORT_EVERY_COLUMN	1
CV_SORT_EVERY_ROW	0
CV_SPARSE_MAT_MAGIC_VAL	0x42440000
CV_STORAGE_MAGIC_VAL	0x42890000
CV_SVD	1
CV_SVD_MODIFY_A	1
CV_SVD_SYM	2
CV_SVD_U_T	2
CV_SVD_V_T	4
CV_TERMCRT_EPS	2
CV_TERMCRT_ITER	1
CV_TERMCRT_NUMBER	CV_TERMCRT_ITER
CV_USRTYPE1	7

CV_WHOLE_SEQ_END_INDEX	0 x3ffffff
IPL_ALIGN_16BYTES	16
IPL_ALIGN_32BYTES	32
IPL_ALIGN_4BYTES	4
IPL_ALIGN_8BYTES	8
IPL_ALIGN_DWORD	IPL_ALIGN_4BYTES
IPL_ALIGN_QWORD	IPL_ALIGN_8BYTES
IPL_BORDER_CONSTANT	0
IPL_BORDER_REFLECT	2
IPL_BORDER_REFLECT_101	4
IPL_BORDER_REPLICATE	1
IPL_BORDER_WRAP	3
IPL_DATA_ORDER_PIXEL	0
IPL_DATA_ORDER_PLANE	1
IPL_DEPTH_SIGN	0x80000000
IPL_IMAGE_DATA	2
IPL_IMAGE_HEADER	1
IPL_IMAGE_MAGIC_VAL	((int)sizeof(IplImage))
IPL_IMAGE_ROI	4
IPL_ORIGIN_BL	1
IPL_ORIGIN_TL	0

The documentation for this object was generated from :

- lua_core.cpp

5.2 Constants from calib3d module

List of constants from calib3d module

Constants

CV_CALIB_CB_ADAPTIVE_THRESH	1
CV_CALIB_CB_FILTER_QUADS	4
CV_CALIB_CB_NORMALIZE_IMAGE	2
CV_CALIB_FIX_ASPECT_RATIO	2
CV_CALIB_FIX_FOCAL_LENGTH	16
CV_CALIB_FIX_INTRINSIC	256
CV_CALIB_FIX_K1	32
CV_CALIB_FIX_K2	64
CV_CALIB_FIX_K3	128
CV_CALIB_FIX_PRINCIPAL_POINT	4
CV_CALIB_SAME_FOCAL_LENGTH	512
CV_CALIB_USE_INTRINSIC_GUESS	1
CV_CALIB_ZERO_DISPARITY	1024
CV_CALIB_ZERO_TANGENT_DIST	8

CV_FM_7POINT	1
CV_FM_8POINT	2
CV_FM_LMEDS	CV_LMEDS
CV_FM_LMEDS_ONLY	CV_LMEDS
CV_FM_RANSAC	CV_RANSAC
CV_FM_RANSAC_ONLY	CV_RANSAC
CV_LMEDS	4
CV_RANSAC	8
CV_STEREO_BM_BASIC	0
CV_STEREO_BM_FISH_EYE	1
CV_STEREO_BM_NARROW	2
CV_STEREO_BM_NORMALIZED_RESPONSE	0
CV_STEREO_GC_OCCLUDED	SHRT_MAX

The documentation for this object was generated from :

- lua_calib3d.cpp

5.3 Constants from highgui module

List of constants from highgui module

Constants

CV_CAP_ANY	0
CV_CAP_CMU1394	300
CV_CAP_DC1394	300
CV_CAP_DSHOW	700
CV_CAP_FIREWARE	300
CV_CAP_FIREWIRE	300
CV_CAP_IEEE1394	300
CV_CAP_MIL	100
CV_CAP_PROP_BRIGHTNESS	10
CV_CAP_PROP_CONTRAST	11
CV_CAP_PROP_CONVERT_RGB	16
CV_CAP_PROP_EXPOSURE	15
CV_CAP_PROP_FORMAT	8
CV_CAP_PROP_FOURCC	6
CV_CAP_PROP_FPS	5
CV_CAP_PROP_FRAME_COUNT	7
CV_CAP_PROP_FRAME_HEIGHT	4
CV_CAP_PROP_FRAME_WIDTH	3
CV_CAP_PROP_GAIN	14
CV_CAP_PROP_HUE	13
CV_CAP_PROP_MODE	9
CV_CAP_PROP_POS_AVI_RATIO	2

CV_CAP_PROP_POS_FRAMES	1
CV_CAP_PROP_POS_MSEC	0
CV_CAP_PROP_RECTIFICATION	18
CV_CAP_PROP_SATURATION	12
CV_CAP_PROP_WHITE_BALANCE	17
CV_CAP_QT	500
CV_CAP_STEREO	400
CV_CAP_TYZX	400
CV_CAP_UNICAP	600
CV_CAP_V4L	200
CV_CAP_V4L2	200
CV_CAP_VFW	200
CV_CVTIMG_FLIP	1
CV_CVTIMG_SWAP_RB	2
CV_EVENT_FLAG_ALTKEY	32
CV_EVENT_FLAG_CTRLKEY	8
CV_EVENT_FLAG_LBUTTON	1
CV_EVENT_FLAG_MBUTTON	4
CV_EVENT_FLAG_RBUTTON	2
CV_EVENT_FLAG_SHIFTKEY	16
CV_EVENT_LBUTTONDOWNCLK	7
CV_EVENT_LBUTTONDOWN	1
CV_EVENT_LBUTTONUP	4
CV_EVENT_MBUTTONDOWNCLK	9
CV_EVENT_MBUTTONDOWN	3
CV_EVENT_MBUTTONUP	6
CV_EVENT_MOUSEMOVE	0
CV_EVENT_RBUTTONDOWNCLK	8
CV_EVENT_RBUTTONDOWN	2
CV_EVENT_RBUTTONUP	5
CV_FOURCC_DEFAULT	CV_FOURCC('I', 'Y', 'U', 'V') /* Use default codec for specified filename (Linux only) */
CV_FOURCC_PROMPT	—1 /* Open Codec Selection Dialog (Windows only) */
CV_IMWRITE_JPEG_QUALITY	1
CV_IMWRITE_PNG_COMPRESSION	16
CV_IMWRITE_PXM_BINARY	32
CV_LOAD_IMAGE_ANYCOLOR	4
CV_LOAD_IMAGE_ANYDEPTH	2
CV_LOAD_IMAGE_COLOR	1
CV_LOAD_IMAGE_GRAYSCALE	0
CV_LOAD_IMAGE_UNCHANGED	—1
CV_TYZX_COLOR	402
CV_TYZX_LEFT	400
CV_TYZX_RIGHT	401
CV_TYZX_Z	403

CV_WINDOW_AUTOSIZE	
HG_AUTOSIZE	CV_WINDOW_AUTOSIZE

The documentation for this object was generated from :

- lua_highgui.cpp

5.4 Constants from imgproc module

List of constants from imgproc module

Constants

CV_ADAPTIVE_THRESH_GAUSSIAN_C	1
CV_ADAPTIVE_THRESH_MEAN_C	0
CV_BGR2BGR555	22
CV_BGR2BGR565	12
CV_BGR2BGRA	0
CV_BGR2GRAY	6
CV_BGR2HLS	52
CV_BGR2HSV	40
CV_BGR2Lab	44
CV_BGR2Luv	50
CV_BGR2RGB	4
CV_BGR2RGBA	2
CV_BGR2XYZ	32
CV_BGR2YCrCb	36
CV_BGR5552BGR	24
CV_BGR5552BGRA	28
CV_BGR5552GRAY	31
CV_BGR5552RGB	25
CV_BGR5552RGBA	29
CV_BGR5652BGR	14
CV_BGR5652BGRA	18
CV_BGR5652GRAY	21
CV_BGR5652RGB	15
CV_BGR5652RGBA	19
CV_BGRA2BGR	1
CV_BGRA2BGR555	26
CV_BGRA2BGR565	16
CV_BGRA2GRAY	10
CV_BGRA2RGB	CV_RGBA2BGR
CV_BGRA2RGBA	5
CV_BILATERAL	4
CV_BLUR	1
CV_BLUR_NO_SCALE	0

CV_BayerBG2BGR	46
CV_BayerBG2RGB	CV_BayerRG2BGR
CV_BayerGB2BGR	47
CV_BayerGB2RGB	CV_BayerGR2BGR
CV_BayerGR2BGR	49
CV_BayerGR2RGB	CV_BayerGB2BGR
CV_BayerRG2BGR	48
CV_BayerRG2RGB	CV_BayerBG2BGR
CV_CANNY_L2_GRADIENT	(1 << 31)
CV_CHAIN_APPROX_NONE	1
CV_CHAIN_APPROX_SIMPLE	2
CV_CLOCKWISE	1
CV_COLORCVT_MAX	100
CV_COMP_BHATTACHARYYA	3
CV_COMP_CHISQR	1
CV_COMP_CORREL	0
CV_COMP_INTERSECT	2
CV_CONTOURS_MATCH_I1	1
CV_CONTOURS_MATCH_I2	2
CV_CONTOURS_MATCH_I3	3
CV_COUNTER_CLOCKWISE	2
CV_DIST_L1	1
CV_DIST_L2	2
CV_DIST_MASK_3	3
CV_DIST_MASK_5	5
CV_DIST_MASK_PRECISE	0
CV_FLOODFILL_FIXED_RANGE	(1 << 16)
CV_FLOODFILL_MASK_ONLY	(1 << 17)
CV_GAUSSIAN	2
CV_GRAY2BGR	8
CV_GRAY2BGR555	30
CV_GRAY2BGR565	20
CV_GRAY2BGRA	9
CV_GRAY2RGB	CV_GRAY2BGR
CV_GRAY2RGBA	CV_GRAY2BGRA
CV_HLS2BGR	60
CV_HLS2RGB	61
CV_HOUGH_GRADIENT	3
CV_HOUGH_MULTI_SCALE	2
CV_HOUGH_PROBABILISTIC	1
CV_HOUGH_STANDARD	0
CV_HSV2BGR	54
CV_HSV2RGB	55
CV_INPAINT_NS	0
CV_INPAINT_TELEA	1
CV_INTER_AREA	3
CV_INTER_CUBIC	2

CV_INTER_LINEAR	1
CV_INTER_NN	0
CV_Lab2BGR	56
CV_Lab2RGB	57
CV_Luv2BGR	58
CV_Luv2RGB	59
CV_MAX_SOBEL_KSIZE	7
CV_MEDIAN	3
CV_MOP_BLACKHAT	6
CV_MOP_CLOSE	3
CV_MOP_GRADIENT	4
CV_MOP_OPEN	2
CV_MOP_TOPHAT	5
CV_NEXT_AROUND_LEFT	0x13
CV_POLY_APPROX_DP	0
CV_RETR_CCOMP	2
CV_RETR_LIST	1
CV_RETR_TREE	3
CV_RGB2BGR	CV_BGR2RGB
CV_RGB2BGR555	23
CV_RGB2BGR565	13
CV_RGB2BGRA	CV_BGR2RGBA
CV_RGB2GRAY	7
CV_RGB2HLS	53
CV_RGB2HSV	41
CV_RGB2Lab	45
CV_RGB2Luv	51
CV_RGB2RGBA	CV_BGR2BGRA
CV_RGB2XYZ	33
CV_RGB2YCrCb	37
CV_RGBA2BGR	3
CV_RGBA2BGR555	27
CV_RGBA2BGR565	17
CV_RGBA2BGRA	CV_BGRA2RGBA
CV_RGBA2GRAY	11
CV_RGBA2RGB	CV_BGRA2BGR
CV_SCHARR	-1
CV_SHAPE_CROSS	1
CV_SHAPE_CUSTOM	100
CV_SHAPE_ELLIPSE	2
CV_SHAPE_RECT	0
CV_THRESH_BINARY	0
CV_THRESH_BINARY_INV	1
CV_THRESH_MASK	7
CV_THRESH_OTSU	8 /* use Otsu algorithm to choose the optimal threshold value;
CV_THRESH_TOZERO	3

CV_THRESH_TOZERO_INV	4
CV_THRESH_TRUNC	2
CV_TM_CCOEFF	4
CV_TM_CCOEFF_NORMED	5
CV_TM_CCORR	2
CV_TM_CCORR_NORMED	3
CV_TM_SQDIFF	0
CV_TM_SQDIFF_NORMED	1
CV_WARP_FILL_OUTLIERS	8
CV_WARP_INVERSE_MAP	16
CV_XYZ2BGR	34
CV_XYZ2RGB	35
CV_YCrCb2BGR	38
CV_YCrCb2RGB	39

The documentation for this object was generated from :

- lua_imgproc.cpp

5.5 Constants from features2d module

List of constants from features2d module

Constants

The documentation for this object was generated from :

- lua_features2d.cpp

5.6 Constants from video module

List of constants from video module

Constants

CV_BGFG_FGD_ALPHA_1	0.1f
CV_BGFG_FGD_ALPHA_2	0.005f
CV_BGFG_FGD_ALPHA_3	0.1f
CV_BGFG_FGD_BG_UPDATE_TRESH	0.5f
CV_BGFG_FGD_DELTA	2
CV_BGFG_FGD_LC	128
CV_BGFG_FGD_LCC	64
CV_BGFG_FGD_MINAREA	15.f
CV_BGFG_FGD_N1C	15

CV_BGFG_FGD_N1CC	25
CV_BGFG_FGD_N2C	25
CV_BGFG_FGD_N2CC	40
CV_BGFG_FGD_T	0.9f
CV_BGFG_MOG_BACKGROUND_THRESHOLD	0.7 /* threshold sum of weights for background test */
CV_BGFG_MOG_MAX_NGAUSSIANS	500
CV_BGFG_MOG_MINAREA	15.f
CV_BGFG_MOG_NCOLORS	3
CV_BGFG_MOG_NGAUSSIANS	5 /* = K = number of Gaussians in mixture */
CV_BGFG_MOG_SIGMA_INIT	30
CV_BGFG_MOG_STD_THRESHOLD	2.5 /* lambda=2.5 is 99% */
CV_BGFG_MOG_WEIGHT_INIT	0.05
CV_BGFG_MOG_WINDOW_SIZE	200 /* Learning rate; alpha = 1/CV_GBG_WINDOW_SIZE */
CV_LKFLOW_GET_MIN_EIGENVALS	8
CV_LKFLOW_INITIAL_GUESSES	4
CV_LKFLOW_PYR_A_READY	1
CV_LKFLOW_PYR_B_READY	2

The documentation for this object was generated from :

- lua_video.cpp

5.7 Constants from legacy module

List of constants from legacy module

Constants

CV_ARRAY	2
CV_CAMERA_TO_WARP	1
CV_CONTOUR_TREES_MATCH_I1	1 };
CV_DISPARITY_BIRCHFIELD	0
CV_DOMINANT_IPAN	1
CV_GLCMDESC_CLUSTERSHADE	5
CV_GLCMDESC_CLUSTERTENDENCY	4
CV_GLCMDESC_CONTRAST	3
CV_GLCMDESC_CORRELATION	6
CV_GLCMDESC_CORRELATIONINFO1	7
CV_GLCMDESC_CORRELATIONINFO2	8
CV_GLCMDESC_ENERGY	1
CV_GLCMDESC_ENTROPY	0
CV_GLCMDESC_HOMOGENITY	2
CV_GLCMDESC_MAXIMUMPROBABILITY	9

CV_GLCMDESC_OPTIMIZATION_ALLOWDOUBLENEST	10
CV_GLCMDESC_OPTIMIZATION_ALLOWTRIPLENEST	11
CV_GLCMDESC_OPTIMIZATION_HISTOGRAM	4
CV_GLCM_ALL	0
CV_GLCM_DESC	2
CV_GLCM_GLCM	1
CV_GLCM_OPTIMIZATION_HISTOGRAM	0
CV_GLCM_OPTIMIZATION_LUT	-1
CV_GLCM_OPTIMIZATION_NONE	-2
CV_IDP_BIRCHFIELD_PARAM1	25
CV_IDP_BIRCHFIELD_PARAM2	5
CV_IDP_BIRCHFIELD_PARAM3	12
CV_IDP_BIRCHFIELD_PARAM4	15
CV_IDP_BIRCHFIELD_PARAM5	25
CV_NUM_FACE_ELEMENTS	3
CV_UNDEF_SC_PARAM	12345 <i>//default value of parameters</i>
CV_VALUE	1
CV_WARP_TO_CAMERA	2

The documentation for this object was generated from :

- lua_legacy.cpp

5.8 Constants from objdetect module

List of constants from objdetect module

Constants

CV_HAAR_DO_CANNY_PRUNING	1
CV_HAAR_DO_ROUGH_SEARCH	8
CV_HAAR_FIND_BIGGEST_OBJECT	4
CV_HAAR_SCALE_IMAGE	2

The documentation for this object was generated from :

- lua_objdetect.cpp