

Computer Graphics Lab 1 & 2 Report

一、实验内容

1. 多边形填充扫描线算法与加权反走样的实现。
2. 二维线段裁剪 Cohen-Sutherland 算法的实现。
3. 二维线段裁剪 Liang-Barsky 算法的实现。

二、测试环境

OS: openSUSE 42.2 64Bit

CPU: Intel Core i7-6500U @ 2.50GHz

RAM: 8GB DDR4 2133MHz

Compiler Version: g++ (GCC) 6.3.0

三、实现过程

1. 多边形填充扫描线算法与加权反走样:

以下是图形属性设置:

```
10
11 const int maxX = 1080, maxY = 1920, maxP = 10;
12
```

maxX 和 maxY 决定图形的长和宽, maxP 是随机生成的点的个数。该程序随机生成 maxP 个点, 依次连接构成多边形 (不一定是简单多边形), 然后使用扫描线算法填充。

```
124
125     for (int j = 0; j < aliveEdge.size(); j++)
126         if (aliveEdge[j].yMax <= yCurr)
127             aliveEdge[j].alive = false;
128
129     for (int j = 0; j < aliveEdge.size(); j++)
130         aliveEdge[j].xCurr += 0.2 * aliveEdge[j].delta;
131
132     while (edgeCurr < maxP && edge[edgeCurr].yMin <= yCurr) {
133         Edge tempEdge = edge[edgeCurr];
134         tempEdge.xCurr += (yCurr - edge[edgeCurr].yMin) * tempEdge.delta;
135         aliveEdge.push_back(tempEdge);
136     }
137
```

使用 vector 实现活性边表, 同时使用 LazyTag 实现 O(1)删除。

以下是使用高斯分布函数计算得来的反走样加权矩阵:

```
46 const int val[5][5] = {
47     1, 2, 4, 2, 1,
48     2, 5, 6, 5, 2,
49     4, 6, 8, 6, 4,
50     2, 5, 6, 5, 2,
51     1, 2, 4, 2, 1,
52 }, SUM = 88;
```

该程序将一个像素细分成 5*5 的矩阵, 并对其进行填充, 而后根据其填充情况决定该像素的灰度值。

2. 二维裁剪的 Cohen-Sutherland 算法

```
12 const int LineW = 2;
13 const int xMax = 2500, xMin = 2000, yMax = 2700, yMin = 2200;
14 //const int xMax = maxX, xMin = 0, yMax = maxY, yMin = 0;
15
```

使用 LineW 规定线段宽度, (xMin, xMax)和(yMin, yMax)规定了裁剪框的属性。

```
49
50 void Cohen_Sutherland(Point& a, Point& b) {
51     int aOrder = 0, bOrder = 0;
52
53     if (a.x < xMin)
54         aOrder |= (1 << 0);
55     if (a.x > xMax)
56         aOrder |= (1 << 1);
57     if (a.y < yMin)
58         aOrder |= (1 << 2);
59     if (a.y > yMax)
60         aOrder |= (1 << 3);
61
62     if (b.x < xMin)
63         bOrder |= (1 << 0);
64     if (b.x > xMax)
65         bOrder |= (1 << 1);
66     if (b.y < yMin)
67         bOrder |= (1 << 2);
68     if (b.y > yMax)
69         bOrder |= (1 << 3);
70
```

根据线段端点 a, b 的位置信息将其编号。

```
70
71     if ((aOrder & bOrder) != 0) {
72         a = Point(-1, -1);
73         b = Point(-1, -1);
74         return;
75     }
76
77     if ((aOrder | bOrder) == 0)
78         return;
79
```

首先判断线段是否完全在裁剪框内外。

```

79
80     if (aOrder != 0) {
81         if ((aOrder & (1 << 0)) != 0) {
82             a.y = a.y + (b.y - a.y) / (b.x - a.x) * (xMin - a.x);
83             a.x = xMin;
84             Cohen_Sutherland(a, b);
85         }
86         else if ((aOrder & (1 << 1)) != 0) {
87             a.y = a.y + (b.y - a.y) / (b.x - a.x) * (xMax - a.x);
88             a.x = xMax;
89             Cohen_Sutherland(a, b);
90         }
91         else if ((aOrder & (1 << 2)) != 0) {
92             a.x = a.x + (b.x - a.x) / (b.y - a.y) * (yMin - a.y);
93             a.y = yMin;
94             Cohen_Sutherland(a, b);
95         }
96         else if ((aOrder & (1 << 3)) != 0) {
97             a.x = a.x + (b.x - a.x) / (b.y - a.y) * (yMax - a.y);
98             a.y = yMax;
99             Cohen_Sutherland(a, b);
100         }
101     }
102     else if (bOrder != 0) {
103         if ((bOrder & (1 << 0)) != 0) {
104             b.y = b.y + (a.y - b.y) / (a.x - b.x) * (xMin - b.x);
105             b.x = xMin;
106             Cohen_Sutherland(a, b);
107         }
108         else if ((bOrder & (1 << 1)) != 0) {
109             b.y = b.y + (a.y - b.y) / (a.x - b.x) * (xMax - b.x);
110             b.x = xMax;
111             Cohen_Sutherland(a, b);
112         }
113         else if ((bOrder & (1 << 2)) != 0) {
114             b.x = b.x + (a.x - b.x) / (a.y - b.y) * (yMin - b.y);
115             b.y = yMin;
116             Cohen_Sutherland(a, b);
117         }
118         else if ((bOrder & (1 << 3)) != 0) {
119             b.x = b.x + (a.x - b.x) / (a.y - b.y) * (yMax - b.y);
120             b.y = yMax;
121             Cohen_Sutherland(a, b);
122         }
123     }
124 }

```

判断线段哪一端点在裁剪框之外，将其裁剪后递归调用 CS 算法。

3. 二维裁剪的 Liang-Barsky 算法

```

127
128 void LiangYoudong_Barsky(Point& a, Point& b) {
129     if (a.x == b.x) {
130         if (a.y >= b.y)
131             swap(a, b);
132
133         if (a.x > xMax || b.x < xMin) {
134             a = Point(-1, -1);
135             b = Point(-1, -1);
136         }
137         else if (a.y > yMax || a.y < yMin) {
138             a = Point(-1, -1);
139             b = Point(-1, -1);
140         }
141         else {
142             a.y = max(a.y, (double) yMin);
143             b.y = min(b.y, (double) yMax);
144         }
145         return;
146     }
147
148     if (a.y == b.y) {
149         if (a.x >= b.x)
150             swap(a, b);
151
152         if (a.x > xMax || b.x < xMin) {
153             a = Point(-1, -1);
154             b = Point(-1, -1);
155         }
156         else if (a.y > yMax || a.y < yMin) {
157             a = Point(-1, -1);
158             b = Point(-1, -1);
159         }
160         else {
161             a.x = max(a.x, (double) xMin);
162             b.x = min(b.x, (double) xMax);
163         }
164         return;
165     }
166 }
167

```

首先处理水平和竖直的直线。

```

168
169     double t_xMin = (xMin - a.x) / (b.x - a.x),
170            t_xMax = (xMax - a.x) / (b.x - a.x),
171            t_yMin = (yMin - a.y) / (b.y - a.y),
172            t_yMax = (yMax - a.y) / (b.y - a.y);
173
174     if (t_yMin > t_yMax)
175         swap(t_yMin, t_yMax);
176     if (t_xMin > t_xMax)
177         swap(t_xMin, t_xMax);
178
179     double t_Begin = max(0.0, max(t_xMin, t_yMin)),
180            t_End = min(1.0, min(t_xMax, t_yMax));
181
182     if (t_Begin >= t_End) {
183         a = Point(-1, -1);
184         b = Point(-1, -1);
185     }
186     else {
187         Point aTemp = a, bTemp = b;
188
189         a.x = aTemp.x + t_Begin * (bTemp.x - aTemp.x);
190         a.y = aTemp.y + t_Begin * (bTemp.y - aTemp.y);
191
192         b.x = aTemp.x + t_End * (bTemp.x - aTemp.x);
193         b.y = aTemp.y + t_End * (bTemp.y - aTemp.y);
194     }
195

```

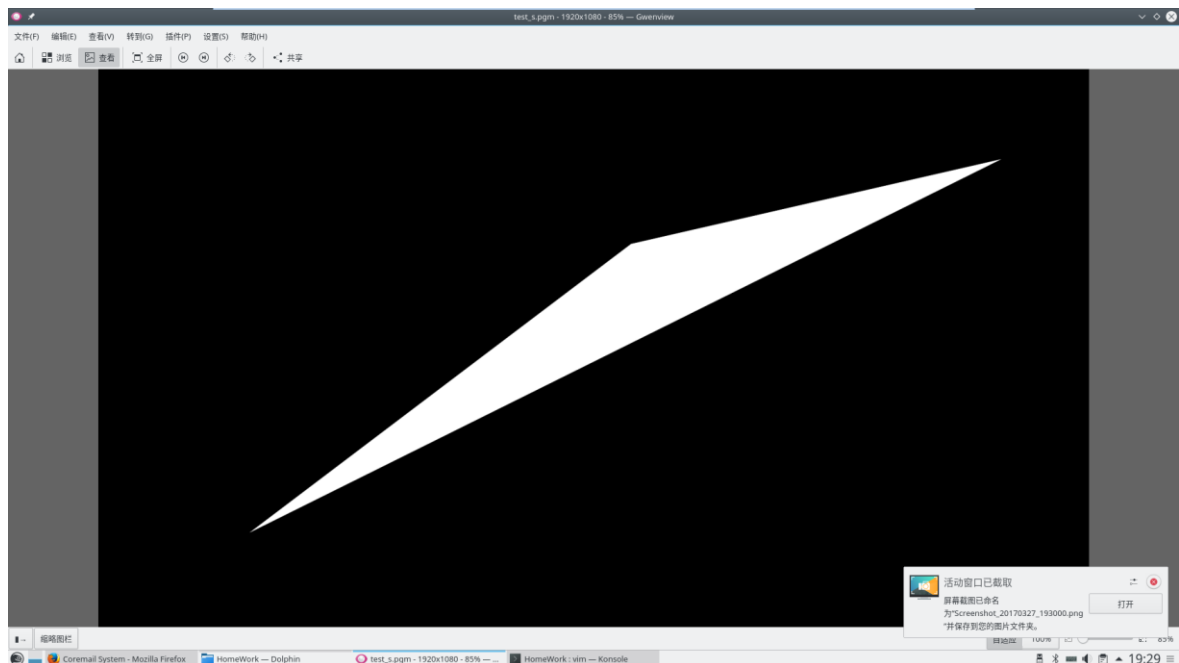
而后将其转化为参数表示，并求出在裁剪框内的参数范围。

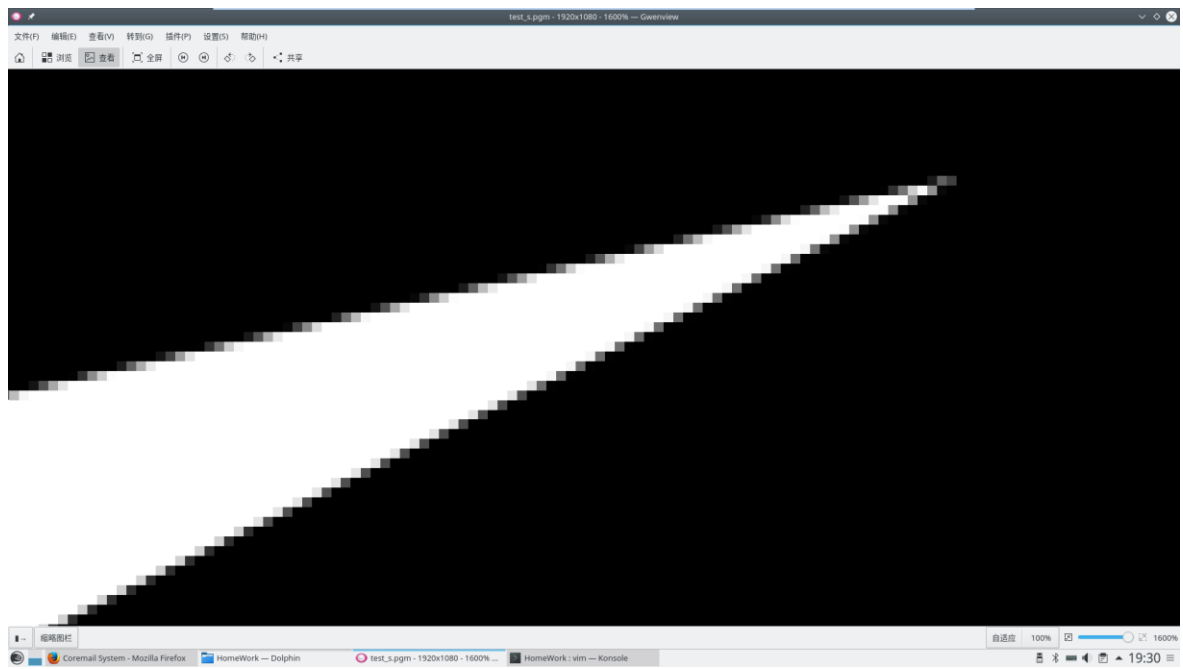
四、结果示例

注：输出以 PGM 灰度图片格式编码，所提交程序均会自动随机取点绘图。

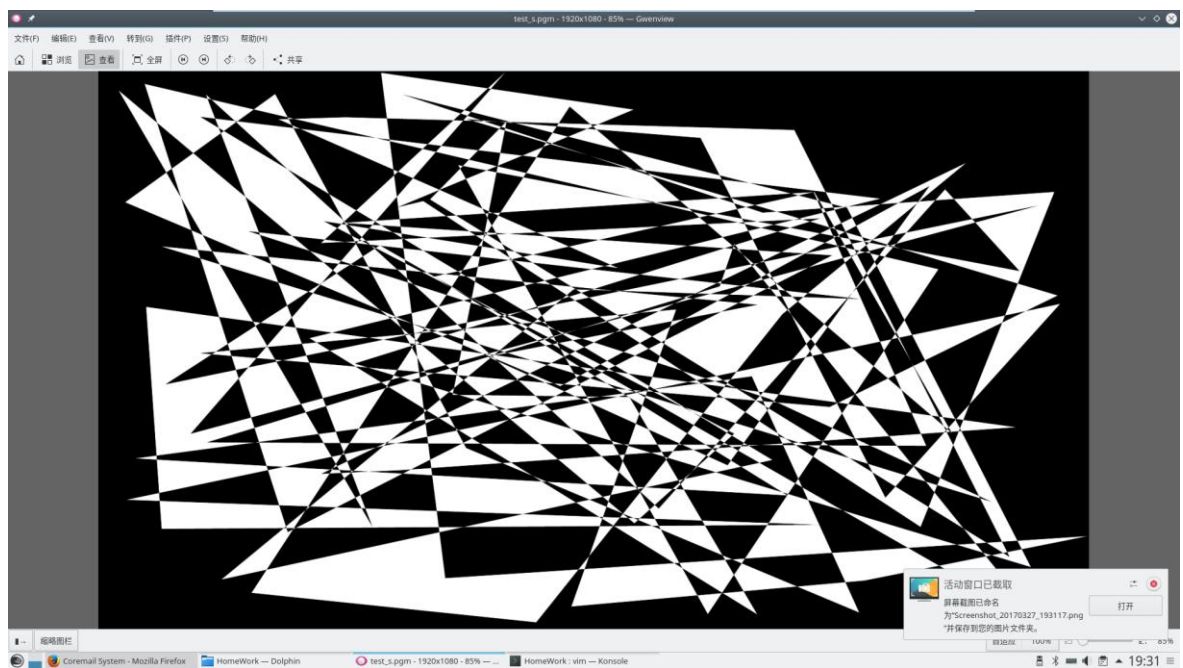
1. 多边形填充与反走样

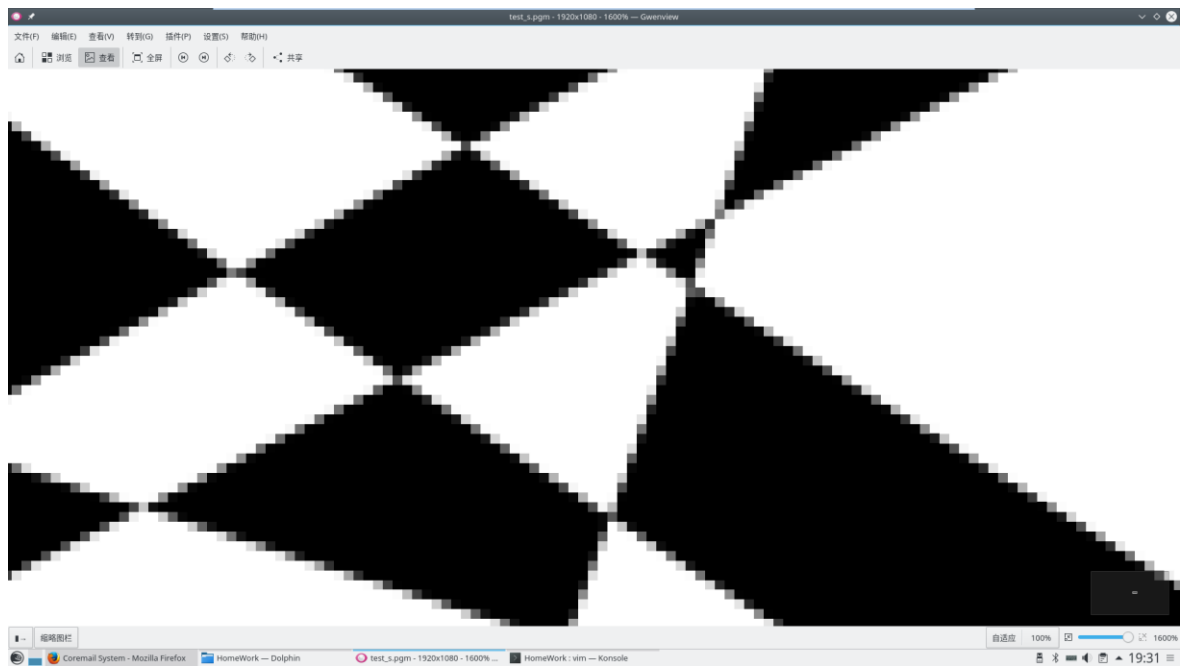
随机三角形：



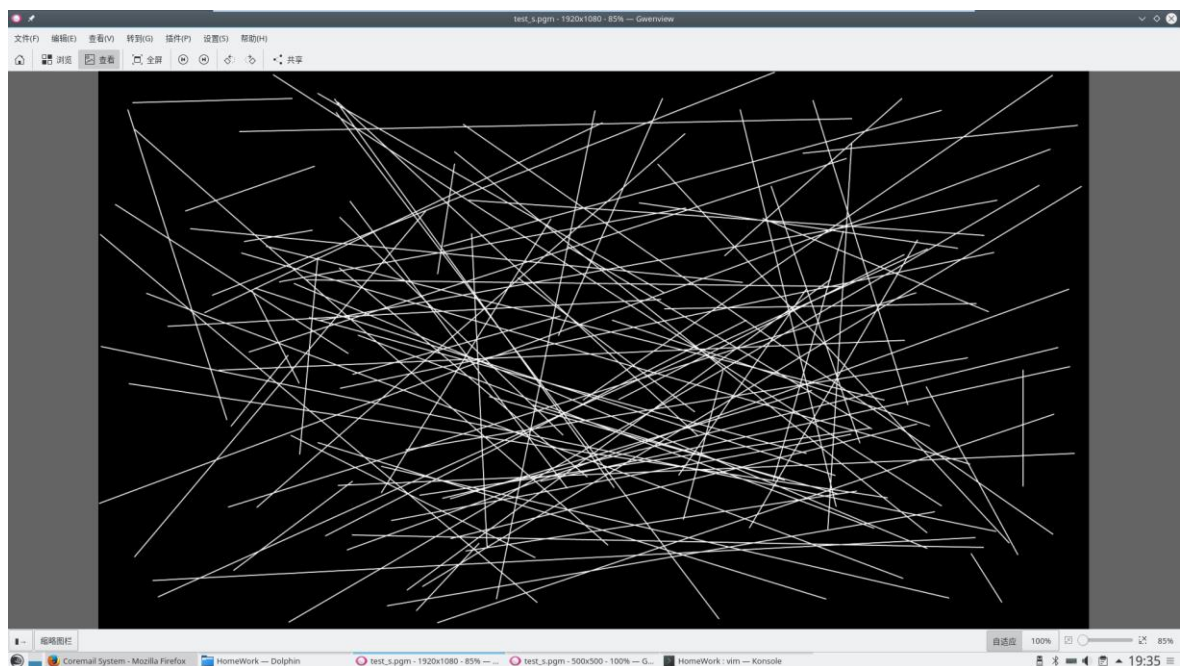


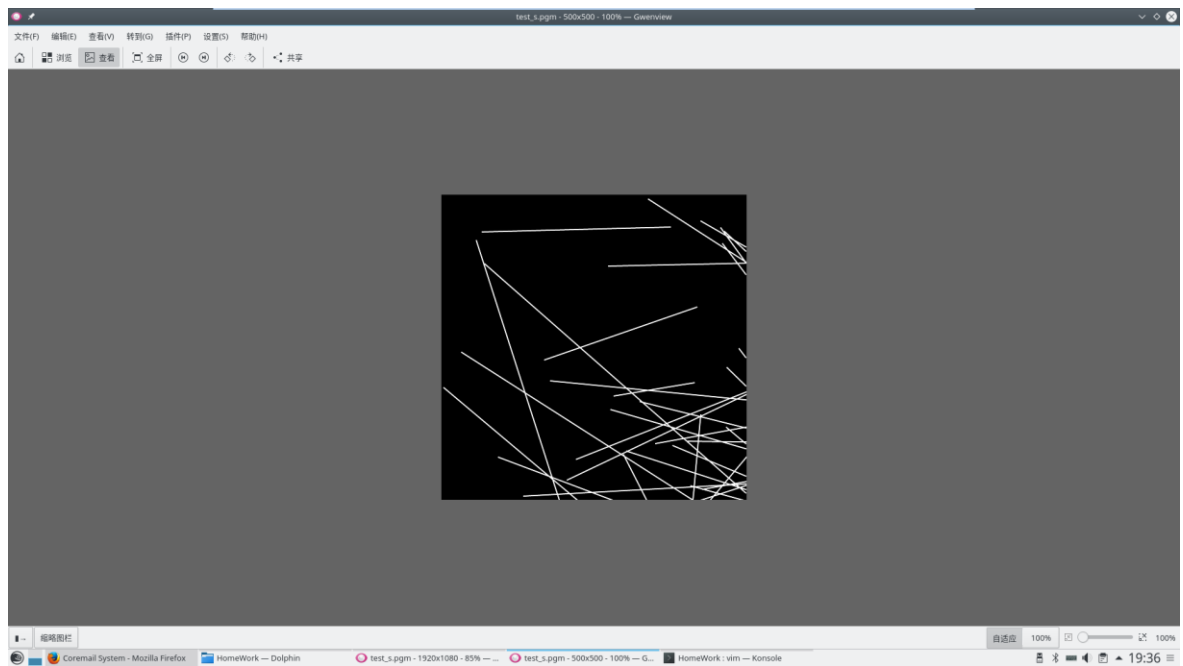
随机 100 边形：





2. 二维线段裁剪的 Cohen-Sutherland 算法





3. 二维线段裁剪的 Liang-Barsky 算法

