Bharathwaj M

Skills

- Frontend Program: HTML|CSS|JavaScript
- Programming Languages:C|C++|Python|Java
- Databases:MySQL
- Robotics: ROS, Arduino IDE, PLC, RoboDK, Motoman Robo Simulation, PLC, Automation Studio
- 3D Model: Fusion 360, Solidworks

Experience

Thedush Robotics

06/2024-08/2024

• Auto-docking System for TurtleBot3: Implemented using ROS 2 Humble, integrating pattern recognition and TF frame transformations for precise docking. Post Link

- Multi-sensor Auto-docking Simulations: Combined 2D LiDAR, 3D LiDAR, and a depth camera on a single TurtleBot3, simulating in the factory environment in Gazebo and RViz2.
- **Simulation and Real-world Applications:** Conducted tasks entirely in **ROS 2 Humble**, strengthening both theoretical knowledge and practical expertise. **Post Link**

CODTECH IT SOLUTIONS

04/2024-04/2024

Webdeveloper/Promotionspecialist

Hyderabad ,Telangana,Remotework

Coimabatore, TamilNadu

Developed Rocky Weather, a weather application website using HTML, CSS, JavaScript, and APIs for accurate weather information, while also working as a LinkedIn Promotion Specialist to enhance brand visibility, boost engagement, and drive targeted traffic through strategic content and networking campaigns. Link

<u>CodeClause</u>

02/2024-03/2024

FrontendEngineer-Internship

Pune, Maharashtra, Remotework

- Developed a **weather application** leveraging **HTML**, **CSS**, **and JavaScript**, integrated with a third-party **weather API** to display real-time data in an intuitive interface.
- Built a user-friendly **e-cart application** using **React.js**, featuring dynamic product listings, cart management, and state handling for seamless e-commerce experiences. <u>Link</u>

Projects

Smart Stocking and Restocking System - AGVs, Robotic Arms, Sensors, Cameras Ongoing

09/2024 - Ongoing

- Developing an automated system for **stocking and restocking using AGVs** for transport, robotic arms for precise stocking, and sensors for real-time inventory tracking.
- Utilizing cameras for product identification and system monitoring, with continuous refinement through testing and feedback.

<u>Underwater Mini Robot - Arduino, PVC, RF Module, Motor Shield, Propeller</u>

07/2023-05/2024

- Designed and built an underwater mini-robot using PVC pipes, Arduino (UNO & Nano), Motor Shield Adafruit, and propellers, programmed via Arduino IDE.
- Integrated a 433 MHz RF module for remote control, enabling efficient underwater navigation and operations.
- Successfully demonstrated the robot's functionality, showcasing precise movement and reliability in a controlled underwater environment.

 Video Clip

<u>CoVid-19--Helper-</u>

06/2022-05/2023

Developed a COVID-19 assistance platform with real-time tracking and vaccination updates using HTML, CSS,

JavaScript, and API integration for dynamic data visualization. Code

Education

Bachelor of Engineering in Robotics and Automation

Expected Graduation - 2026

Sri Ramakrishna Engineering College | Coimbatore, TamilNadu | GPA - 7.86| CGPA - 7.68(upto IV sem)

- Concentration: Robotics, ROS and Simulations.
- Relevant Courseworks: Localization and navigation using ROS, Trajectory planning for a Manipulator and AGV, Implementing
- *A Algorithm for finding the optimal path for a AGV, Robotic process automation, Machine learning for Robotics, Object-Oriented Programming(OOPs).