### **Computer Graphics**

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#### Outline

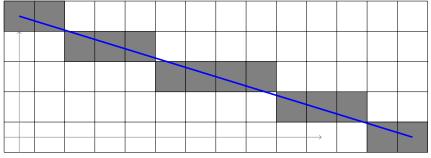
- Drawing Algorithms
  - Line Drawing Algorithms: §6

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- Drawing Algorithms
  - Line Drawing Algorithms: §6

# Which pixels?

Which pixels do we "light up" when drawing the line **segment** (0,4) to (13,0)? (Note pixel "surrounds" the (x,y) value.)



A line-drawing demo

- The equation of a line is y = mx + c, where  $m = \frac{\Delta y}{\Delta x}$  is its slope and c is its y-intercept (when x = 0)
- The line containing  $p=(x_p,y_p)$  and  $q=(x_q,y_q)$  has slope  $m=\frac{y_q-y_p}{x_q-x_p}$
- For the same line we can figure out c since every (x, y) on must satisfy

$$\frac{(y - y_p)}{(x - x_p)} = m$$
$$(y - y_p) = m(x - x_p)$$
$$y = mx + (y_p - mx_p)$$

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Another way to look on this is

$$c = y - mx|_{(x_q, y_q)} = y_q - mx_q$$

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- If slope is  $m = \frac{\Delta y}{\Delta x}$  and we're "standing" on line then advancing  $\Delta x$  units in x-direction and  $\Delta y$  units in y-direction brings us back on to line
- If we advance pixel in x-direction then we must advance
   pixels in y-direction to compensate
- To draw a line segment between two points we start at one end point and move towards the other as follows:
  - If line has \_\_\_\_\_\_ then we "sample" at (step along) successive values of \_\_\_\_ and

$$y_{k+1} = y_k + m$$

• If the line has  $\underbrace{\hspace{1cm}}$  then  $\frac{1}{m}$  is small and so we sample successively on  $\underbrace{\hspace{1cm}}$  using

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- This is much faster than solving y = mx + c repeatedly

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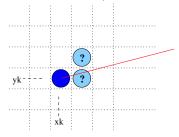
```
void lineDDA (int x0, int y0, int xEnd, int yEnd)
  int dx = xEnd - x0, dy = yEnd - y0, steps, k;
  float xIncrement, yIncrement, x = x0, y = y0;
  if (fabs(dx) > fabs(dy)) steps = fabs (dx);
  else steps = fabs (dy);
  xIncrement = float (dx) / float (steps);
  vIncrement = float (dy) / float (steps);
  setPixel (round (x), round (y)); // round(x) = in
  for (k = 0; k < steps; k++) {
   x += xIncrement;
   y += yIncrement;
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# Bresenham's Line-Drawing Algorithm

- DDA requires floating point arithmetic
- Bresenham's algorithm requires only (much faster) integer calculations
- The general idea also works for circles and other curves
- Idea: as with prev. alg., from current pixel  $(x_k, y_k)$ , we need to decide where to go to next
- Assuming (w.l.o.g.) that |m| < 1, and so we will **sample** at successive values of x again but increasing x
- That is with  $x_{k+1} = x_k + 1$ ; find the best choice for  $y_{k+1}$



- Given x co-ordinate of  $x_k + 1$ , what is **best** y value,  $y_{k+1} = y_k$  or  $y_{k+1} = y_k + 1$  (for the previous line)?
- The **exact** value is  $y = m(x_k + 1) + c$
- So we should choose the value closest to this as best
- The two differences or errors are:

$$d_l = y - y_k$$
  
=  $m(x_k + 1) + c - y_k$ , and  
 $d_u = y_k + 1 - y$   
=  $y_k + 1 - m(x_k + 1) - c$ 

•  $d_l > d_u \rightarrow d_l - d_u > 0$  so sign tells us which is larger; then combining these

$$d_l - d_u = 2m(x_k + 1) - 2y_k + 2c - 1$$

- In  $d_l d_u = 2m(x_k + 1) 2y_k + 2c 1$  we still have  $m = \frac{\Delta y}{\Delta x}$  which is a **real** no.; try fix this
- If we assume that  $\Delta x > 0$  (always scan from left to right in x) then multiply through by  $\Delta x$ . Let  $\bigcirc$  be the  $\bigcirc$  predicate:

$$p_k = \Delta x (d_l - d_u)$$
  
=  $2\Delta y x_k - 2\Delta x y_k + C$ 

has the same sign as before, where  $C = 2\Delta y + 2c\Delta x - \Delta x$  is a **constant** throughout

- So  $p_k > 0 \Rightarrow d_l > d_u$  and the upper y,  $y_{k+1}$ , is closest
- Having decided on  $y_k$ , compute  $p_k$  to find the better  $y_{k+1}$
- Likewise, computing  $p_{k+1} = 2\Delta y x_{k+1} 2\Delta x y_{k+1} + C$  tells us what  $y_{k+2}$  to choose at  $x = x_{k+2}$

- Can we squeeze any more juice from this?
- Subtracting successive values of p:

$$p_{k+1} - p_k = 2\Delta y x_{k+1} - 2\Delta x y_{k+1} + C - (2\Delta y x_k - 2\Delta x y_k + C)$$

$$= 2\Delta y (x_{k+1} - x_k) - 2\Delta x (y_{k+1} - y_k)$$

$$= 2\Delta y - 2\Delta x (y_{k+1} - y_k)$$

and

$$p_{k+1} = p_k + 2\Delta y - 2\Delta x(y_{k+1} - y_k)$$

• The initial condition is (see  $p_k$  on prev. slide)

$$p_0 = 2\Delta y x_0 - 2\Delta x y_0 + 2\Delta y + 2c\Delta x - \Delta x$$
$$= 2\Delta y - \Delta x$$

since 
$$y_0 = \frac{\Delta y}{\Delta x} x_0 + c$$

- $p_{k+1} = p_k + 2\Delta y 2\Delta x(y_{k+1} y_k)$
- $p_0 = 2\Delta y \Delta x$
- $p_k < 0 \Rightarrow$  stay with same y-value:  $y_{k+1} = y_k$
- Note that  $2\Delta y$  and  $2\Delta x$  are **constants**
- Procedure:
  - Compute  $p_0$  and use this to tell whether  $y_1$  stays with same value as  $y_0$  or to use  $y_0 + 1$  at  $x_1 = x_0 + 1$
  - We use this *y*-information in computing *p*<sub>1</sub>:

$$p_1 = p_0 + 2\Delta y - 2\Delta x(y_1 - y_0)$$

- Repeatedly use y-information from  $p_k$  to calc  $p_{k+1}$
- Note: each predicate  $p_k$  says what to at **next** sample,  $x_{k+1}$

- The previous treatment was for "gently increasing lines" lines of the form 0 ≤ m ≤ 1
- What about "gently decreasing lines"?
- A similar derivation to the previous one can be done for when y decreases as x increases:
  - For consistency with previous case we base predicate p<sub>k</sub> on "predicate less than 0 means we stay with current y"
  - To do this we must set

$$p_k = \Delta x (d_u - d_l)$$

- The exact same formulae as before are yielded with the exception that  $(y_{k+1} y_k) = -1 \text{ or } 0$  opposite to previous
- To fix for this always in either case use absolute value of  $\Delta y$
- As with DDA if 1 < |m| (slope is steep either positive or negative) we sample with increasing y to improve coverage