Speed sensor statemachine

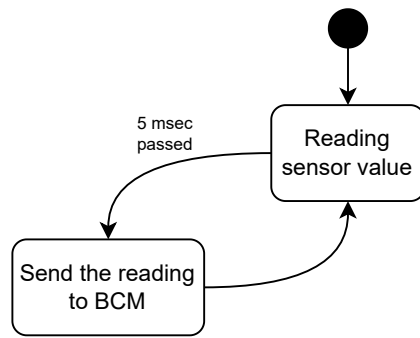**Reading sensor value**

Send the reading to BCM

5 msec passed

Note: this state machine will be used if the Basic Communication module is just going to call this update function