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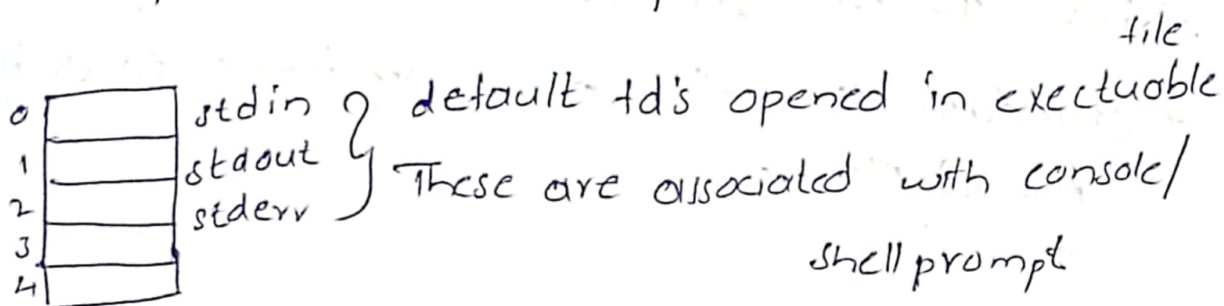
FILE MANAGEMENT SUBSYSTEMS

comp → POC →
process id

File I/O operations

File descriptor table

fd table → keeps the track of opened file information



Each index in the fd table have file descriptor associated with opened file information.

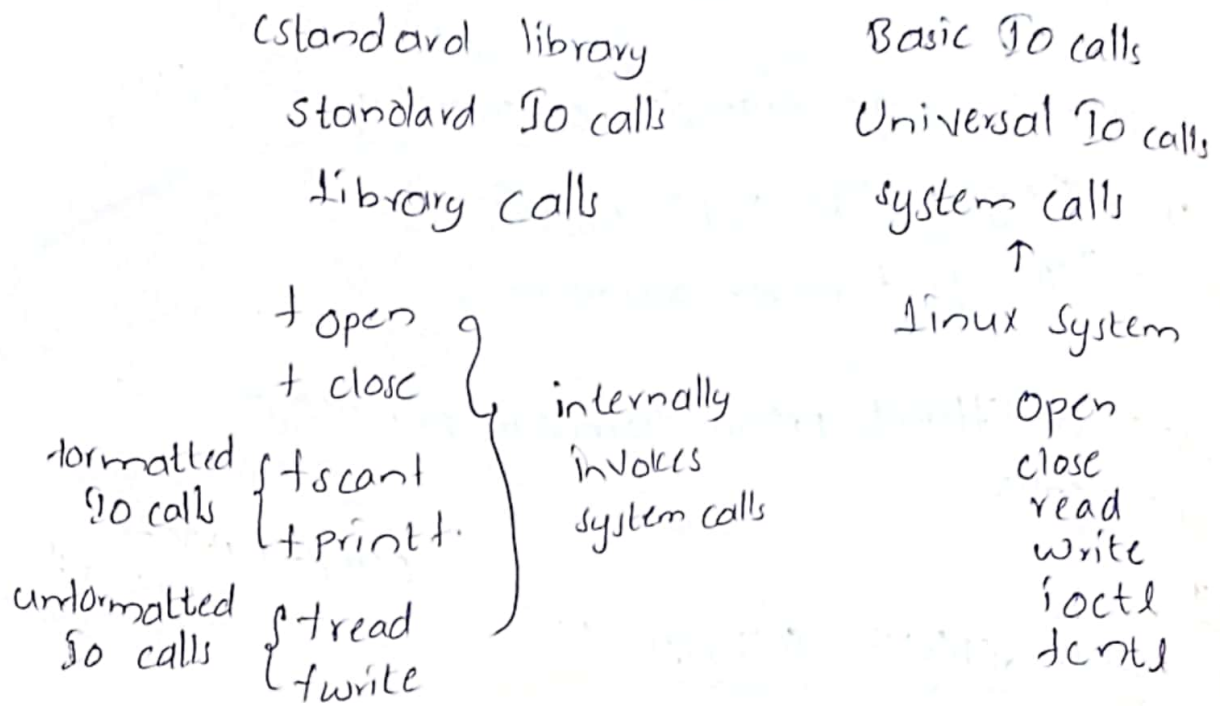
Q. Who opens the default fd's?

Terminal opens the default fd's

* Linux shell / terminal is the parent process of the a.out

* When a.out is created as child process then the contents of fd table are copied from terminal.

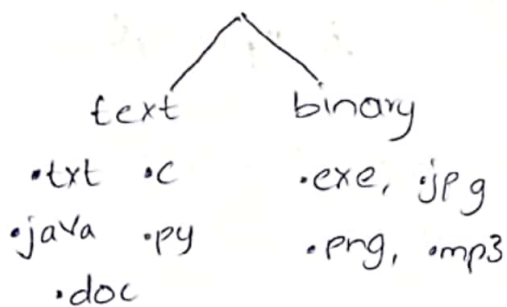
File IO operations can be done by two different type of calls.



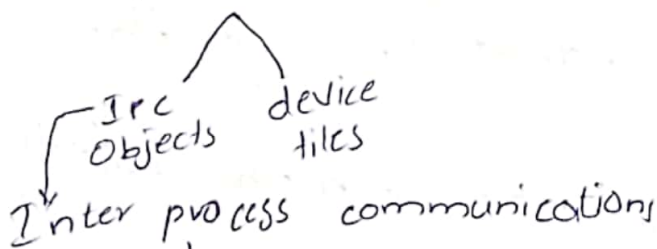
* Standard IO calls, will available in almost all the plat forms like windows, Linux, Mac, Android etc.

* Basic IO calls will specific to Linux system.

* standard IO calls are applicable to only normal files



* Basic IO calls are applicable to normal files and special files



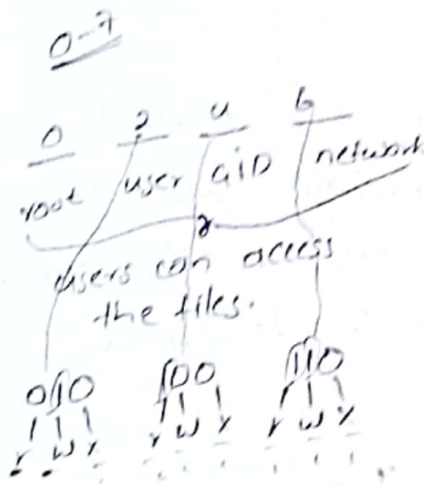
For establishing comm b/w 2 process

* Disadvantages is it is only applicable to Linux

BASIC IO CALLS

open → open(filename, mode, permissions);

It is applicable to file when we create a file.



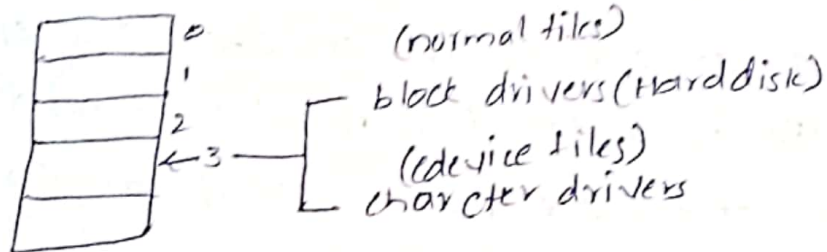
Read - O_RDONLY
Write - O_WRONLY
R/W - O_RDWR
append - O_APPEND
truncate - O_TRUNC

create - O_CREAT
if file doesn't exist

open("filename.txt", O_RDONLY);

vfs → sys-open

open creates an entry in fd table in the next freely available index



open returns index to the fd table entry on success

open returns '-1' on failure.

fd = open("filename.txt", O_RDONLY/O_CREAT, 0700);

root	}	rwx
user		100 - 4 → read
Group		110 - 6 → read & write
network		111 - 7 → read, write, execute

sudo is used for applying the root permissions.

root user have default permissions to access all the permissions.

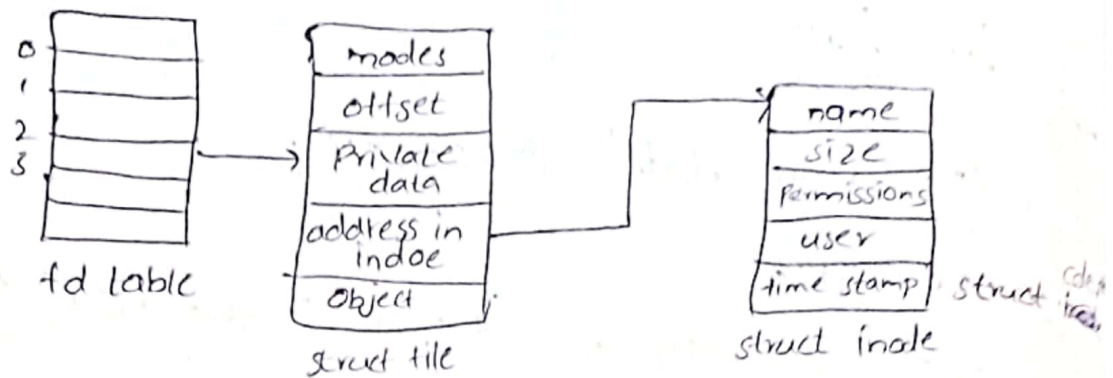
User group network → The permissions are indicated by octal

User	group	network
rwX	rwX	rwX
111	000	000
7	0	0

0700
user file

The subsequent read & write system calls will be using `fd` to read & write

- * Through this `fd` table only file object is created
- * file object is also type of a structure `struct file`
- * Members of the file objects are modes, offset/position, private data, address of inode object



- * Inode contains information about the file.
- * File object contains information about the open file.
- * When a file is created it is stored in Hard disk. The structure of file are name, size, permission, user, time stamps.
- * Inode object is created with the creation of file. It is the part of file stored in hard disk.
- * When the file is opened file object is created in kernel space of RAM. Inode object is copied from hard disk to kernel space of RAM.
- * `fd` table entry points to file object and it points to inode object.

int write (int fd, void *buf, int len);

↑ ↑ ↑

index to table entry (returned by open) Data which needs to be written to file number of bytes to be written

On success write returns number of bytes written to file.

Write is able to write only 50 bytes that's why it return no. of bytes written to file.

On failure it returns '-1'

int read (int fd, void *buf, int len)

↑ ↑ ↑

index to table entry buffer where read data from file shall be stored max. no. of bytes to be read.

On success read returns no. of bytes read.

On failure it returns '-1'

“unistd.h”

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Reading the file

Reasons of failing

- * file doesn't exist
- * file doesn't have relevant operational permissions.
- * File doesn't have relevant group, user, network permissions.

```
#include <stdio.h>
#include <unistd.h>
```

```
void main()
```

```
{
    int fd, int ret;
```

```
    char buf[64];
```

```
    fd = open("file.txt", O_RDONLY);
```

```
    if (fd < 0)
```

```
    {
        printf("Failed to open the file\n");
        return;
```

```
    }
```

```
    ret = read(fd, buf, 64);
```

```
    if (ret < 0)
```

```
    {
        printf("Failed to read the file\n");
        close(fd);
        return;
```

```
    }
```

```
    buf[ret] = NULL;
    printf("%s", buf);
    close(fd);
```

```
}
```

* if read returns
it means we have
reached end of
the file.

→ If we don't place this condition
then buf returns all the remaining
characters present there. If we
place NULL then it prints the
strings present in the file.

Writing to the file

```
#include <stdio.h>
#include <unistd.h>
void main()
```

```
{
    int fd, ret;
    char but[] = "hello";
    fd = open("file.txt", O_WRONLY);
    if (fd < 0)
    {
        printf("Failed to open the file\n");
        return;
    }
    ret = write(fd, but, strlen(but));
    if (ret < 0)
    {
        printf("Fail to write in to the file\n");
        close(fd);
        return;
    }
    close(fd);
}
```

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printf invokes write
scanf invokes read

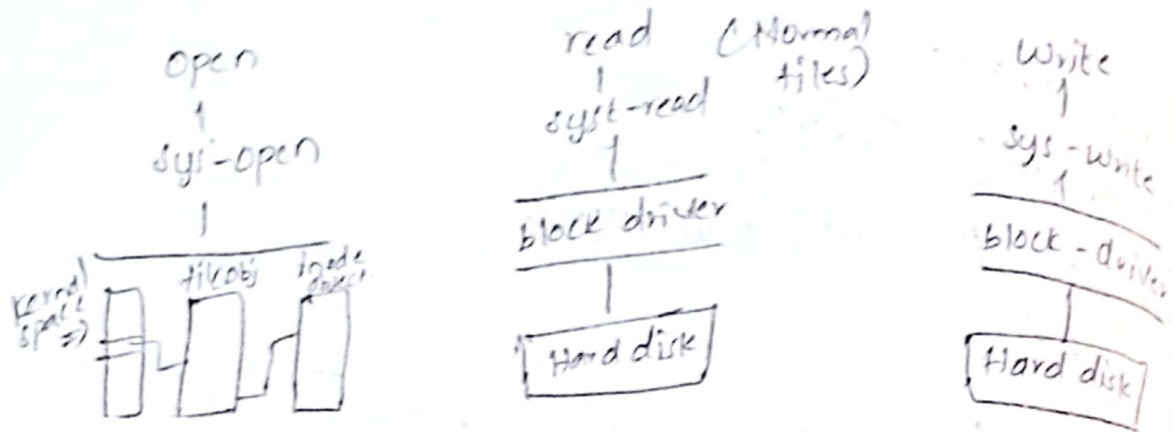
sys - write
sys - read



scanf → scanf
printf → printf
scanf
printf

* printf invokes write system call on fd1 similarly
scanf invokes read system call on fd0

- * Read system call is a blocking call, scan't block because of read() (ipc obj, device, special file)
- * Read blocks only when operating on special files. it never blocks on normal files.



- * In device files read goes to character driver.
- * User space can fetch the contents of file object and inode object.
- * To fetch inode object we use `fstat()` call.
- * To fetch file object we use `fctl()` call.

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`struct stat buf;`

`fstat(fd, struct stat*);` | `stat("filename.txt", struct stat*);`
`fstat(fd, &buf);` | `stat("filename.txt", &buf);`

It fetches the contents of inode object and fills the `struct stat buf`.

To change the permissions of file we use command line/system call.

command line interface is directly executed from kernel shell.

$\left. \begin{array}{l} \text{chmod()} \\ \text{tchmod()} \end{array} \right\} \begin{array}{l} \text{for} \\ \text{system calls} \end{array}$

chmod() is for command line interface

in comm and line interface $\left\{ \begin{array}{l} \text{chmod +0660 filename.txt} \rightarrow \text{to change the permissions} \\ \text{chmod +x filename} \rightarrow \text{to apply the individual permissions} \end{array} \right.$

$\text{chmod("filename", 0660);}$
 tchmod(fd, 0660);

Context Switching

* Switching of CPU from one process to another process is called as context switching

Q. What is reason of context switching?

In Round-Robin scheduling

1. when the process is completed
2. CPU time has expired.

In preemptive priority based scheduling

1. When the process is completed then CPU is given to next high priority task execute
2. Any Higher priority task come to execution.

solu

ARM Processors:

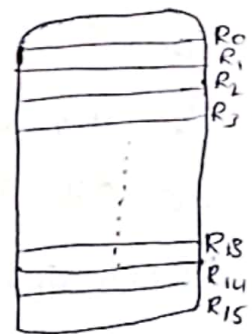
$R_0 - R_7$ General Purpose registers

$R_8 - R_{15}$ special purpose registers

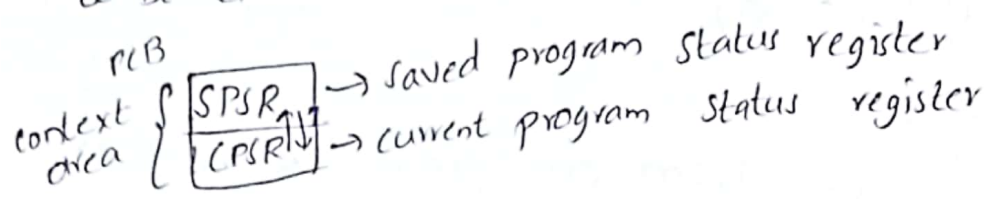
R_{13} - stack pointer (SP)

R_{14} - Link registers (LR)

R_{15} - Program Counter (PC)



- * Stack pointer points to the top of the stack.
- * Link register points to the location of the next instruction.
It keeps the address of the instruction which is next to the function call.
- * Program counter points to the address of next instruction.
- * CPU uses program counter to get the next instruction to be executed.



If P_1 process is going to switch to P_2 process then the P_1 related registers should be stored in SPSR and it is switched from P_1 to P_2 then the contents of SPSR into CPSR and reload it in to the user space.

- * Just before switching from one process to another process the current status register will be stored in saved program status register.
- * Just before executing the next program SPSR information will be fetched to EPSR to reload R_0 - R_{15} related to next process.
- * The information stored in registers R_0 - R_{15} is called as context info.
- * Push 16 POP one assembly level instruction to fetch & store the data from stack pointer.
- * branch & link assembly instruction to stored next instruction address before jump into functions address space in link register.