```
_{m}odel()->
          Sequential
      Define model.model =
      Sequential()model.add(ZeroPadding2D(padding =
   \begin{array}{ll} & \end{array} & \begin{array}{ll} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \begin{array}{ll} & \end{array} & \end{array} & \begin{array}{ll} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \begin{array}{ll} & \end{array} & \end{array} & \begin{array}{ll} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \begin{array}{ll} & \end{array} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \end{array} & \end{array} & \begin{array}{ll} & \end{array} & \end{array} & \end{array} & \begin{array}{ll} & \end{array} & \begin{array}{ll} & \end{array} & \end{array} & \begin{array}{ll} & 
   "relu", padding =
"valid", kernel<sub>i</sub>nitializer =
"he<sub>u</sub>niform", input<sub>s</sub>hape =
(30, 30, 1), name =
(30, 30, 1)
   "convolution_layer"))model.add(MaxPooling2D(pool_size, name = "max_pooling_layer"))model.add(Flatten(name = "flatten_layer"))model.add(Dense(10, activation = "nattrace") = "flatten_layer")
     "softmax", name = \\"dense_{l}ayer")) Compile model. model. Compile (optimizer = \\
      Adam(), loss =
Adam(), loss =
"categorical_rossentropy", metrics =
["accuracy"])Returnmodel.returnmodel
conv_weights.h
dense_weights.h
definitions.h
conv_weights.h
definitions.h
in.dat
out.dat
gen_data.ipynb
totense_tream.int filter.hls::
     \bar{to_den}se_stream, intfilter, hls::
     stream < float >
      dense_to_softmax_stream)floatflat_value; floatdense_array[DENSE_SIZE] = 0;
                                                      _for_flat:
          for(inti =
      0; i <
      FLAT_SIZE/FILTERS; ++
     i) f \underline{lat}_v alue = flat_t o_d ense_s tream.read();
     d) intindex = filter * (FLAT_SIZE/FILTERS) + i; <math>dense_array[d] + = dense_w eights[index][d] * flat_value;
      \vec{j}) \overline{dense}_t o_s oftmax_s tream.write(dense_a rray[j]);
     L_{l}^{a}yer(floatpad_{i}mg0[PAD_{I}MG_{R}OWS][PAD_{I}^{A}MG_{C}OLS], floatpad_{i}mg1[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS], floatpad_{i}mg1[PAD_{I}MG_{C}OLS], float
     \tilde{conv_to_pool_s} treams[FILTERS]) convolution(pad_img0, 0, conv_to_pool_s treams[0]); convolution(pad_img1, 1, conv_to_
     flattening
      _{t}o_{f}lat_{s}tream, hls::
      stream < float >
        flat_to_dense_s tream) flat_for_rows: for (intr=0; r < POOL_IMG_ROWS; + r) flat_for_cols: for (intc=0; c < POOL_IMG_ROWS
   \begin{array}{l} \text{CNN} \\ in[IMG_ROWS][IMG_COLS], float prediction[DIGITS])/******Pre-processing data.******/\\ img0[PAD_IMG_ROWS][PAD_IMG_COLS] = \\ \vdots \\ \\ \end{array}
     0; normalization_and_padding(img_in, pad_img0);
   {}_{SYNTHESIS_{printf("Paddedimage.");print_{p}ad_{i}mg(pad_{i}mg);endifendif}\atop img1[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg2[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{C}OLS];floatpad_{i}mg3[PAD_{I}MG_{R}OWS][PAD_{I}MG_{R}OWS]]
          for(inti =
        PAD_IMG_ROWS; ++
     i) clone_f or_c ols:
          for(intj =
     [j] pad_i mg1[i][j] = pad_i mg0[i][j]; pad_i mg2[i][j] = pad_i mg0[i][j]; pad_i mg3[i][j] = pad_i mg3[i
     \begin{array}{ll} \sum_{section}(pad_{i}mg0,pad_{i}mg0[i][j];pad_{i}mg2[i][j]=pad_{i}mg0[i]\\ section(pad_{i}mg0,pad_{i}mg1,pad_{i}mg2,pad_{i}mg3,prediction);\\ \text{CNN} \end{array}
      _{R}esult_{1}.pngfigure()
      _{R}esult_{2}.pngfigure()
      _{R}esult_{3}.pngfigure()
```

 $_{p} redict_{1}00.png figure Accuracy \\ predict_{5}00.png figure Accuracy$