

# A Fast Low-Level Error Detection Technique

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# Problem & Solutions Overview

- **Problem:** Transient hardware faults (soft errors) due to shrinking transistor sizes and operating voltages.
- **Impact:** Soft errors can cause Silent Data Corruptions (SDCs), compromising system dependability.
- **Solutions:**
  - ① Traditional: Hardware-based methods such as:
    - voltage guard bands
    - redundancy

have high overhead in performance and energy consumption.
  - ② Software-Based: Error Detection by Duplicating Instructions (EDDI)

has been proposed as a flexible, resource-efficient alternative.

# EDDI Methods

- **EDDI:** Duplicates instructions at compile time and checks for mismatches at runtime.

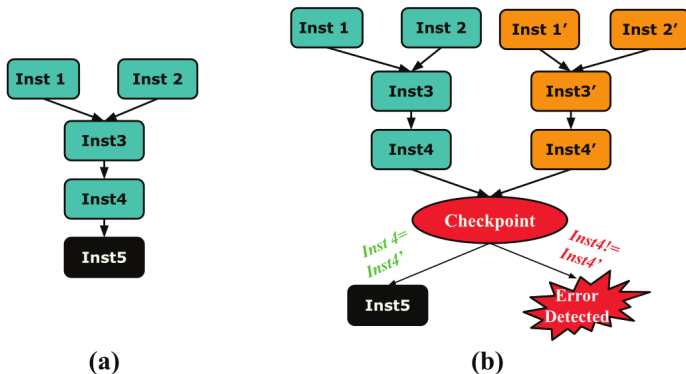


Figure: High-level idea of EDDI

# EDDI Methods (Cont.)

- **Existing EDDI Methods:**

- ① Mostly at IR level

reduced fault coverage when tested at the assembly level.

- **Problem with IR-Level EDDI:**

- Fault coverage gaps at IR level.
  - Reduced effectiveness when evaluated at assembly level.
  - Underestimated error detection at lower levels.
  - Need for assembly-level implementation for better fault protection.

# IR Code Example Using EDDI

```
1 // High-level C code
2 int add(int a, int b) {
3     return a + b;
4 }
```

```
1 define i32 @add(i32 %a, i32 %b) {
2 entry:
3     %a.addr = alloca i32, align 4
4     %b.addr = alloca i32, align 4
5     store i32 %a, i32* %a.addr, align 4
6     store i32 %b, i32* %b.addr, align 4
7 ;Duplicate instruction
8     %0 = load i32, i32* %a.addr, align 4
9     %1 = load i32, i32* %a.addr, align 4
10 ;Duplicate instruction
11     %2 = load i32, i32* %b.addr, align 4
```

Figure: (a)

```
1 // High-level C code
2 int add(int a, int b) {
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4 }
```

```
1 define i32 @add(i32 %a, i32 %b) {
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7 ;Duplicate instruction
8     %0 = load i32, i32* %a.addr, align 4
9     %1 = load i32, i32* %a.addr, align 4
10 ;Duplicate instruction
11     %2 = load i32, i32* %b.addr, align 4
```

Figure: (b)

# Main Contribution

## ① Proposed Solution:

- FERRUM: Optimized assembly-level EDDI.
- Enhancements: Utilizes SIMD and compiler optimizations.
- Improves: Fault coverage and performance.

## ② Key Findings & Results:

- 28% gap in fault coverage (IR-level vs. assembly-level).
- 100% fault coverage with FERRUM at assembly level.
- Higher overhead in assembly-level EDDI; optimizations reduce it.
- 52% reduction in runtime overhead with FERRUM, no loss in fault coverage.

# Background

- ① **Fault Model:** Single bit-flip faults; memory protected by ECC.
- ② **Fault Simulation:** Assembly-level fault injection; beam testing infeasible.
- ③ **EDDI:** Instruction duplication, runtime comparison.
- ④ **Compilation:**
  - IR-level: Common, uses LLVM tools.
  - Assembly-level: Rare, closer to hardware.
- ⑤ **Platform:** x86 ISA.



# Figure

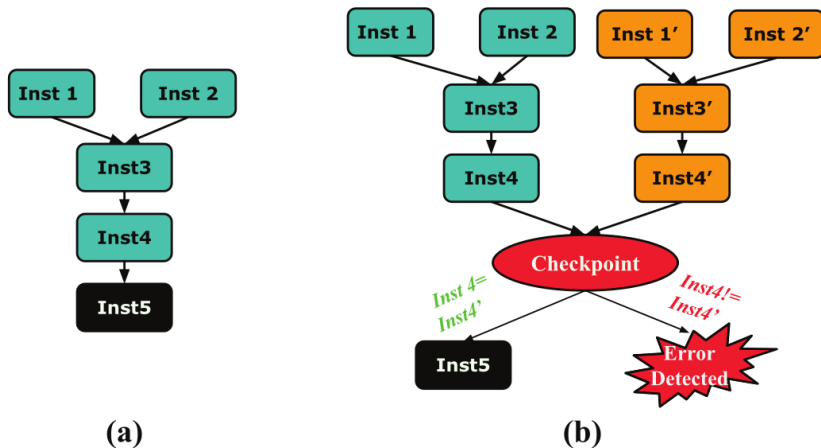


Figure: Creodocs logo.

# Definitions & Examples

## Definition

A **prime number** is a number that has exactly two divisors.

## Example

- 2 is prime (two divisors: 1 and 2).
- 3 is prime (two divisors: 1 and 3).
- 4 is not prime (**three** divisors: 1, 2, and 4).

You can also use the theorem, lemma, proof and corollary environments.

# Theorem, Corollary & Proof

Theorem (Mass–energy equivalence)

$$E = mc^2$$

Corollary

$$x + y = y + x$$

Proof.

$$\omega + \phi = \epsilon$$



# Equation

$$\cos^3 \theta = \frac{1}{4} \cos \theta + \frac{3}{4} \cos 3\theta \quad (1)$$

## Example (Theorem Slide Code)

```
^^I^^I^^I\begin{frame}  
^^I^^I^^I^^I\frametitle{Theorem}  
^^I^^I^^I^^I\begin{theorem}[Mass--energy equivalence]  
^^I^^I^^I^^I^^I$E = mc^2$  
^^I^^I^^I^^I\end{theorem}  
^^I^^I\end{frame}
```

Slide without title.

# Citing References

An example of the `\cite` command to cite within the presentation:

This statement requires citation [Smith, 2022, Kennedy, 2023].

# References



John Smith (2022)

Publication title

*Journal Name* 12(3), 45 – 678.



Annabelle Kennedy (2023)

Publication title

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# Acknowledgements

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# The End

## Questions? Comments?