



# Dewarping 360 Image by OpenCV C++

Mechatronics Engineering Technology

Department of Mechanical Engineering Technology

College of Industrial Technology

King Mongkut's University of Technology North Bangkok (2022)

# Member

Mr. Khanatuch

Mr. Teerachot



# Agenda

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Summary

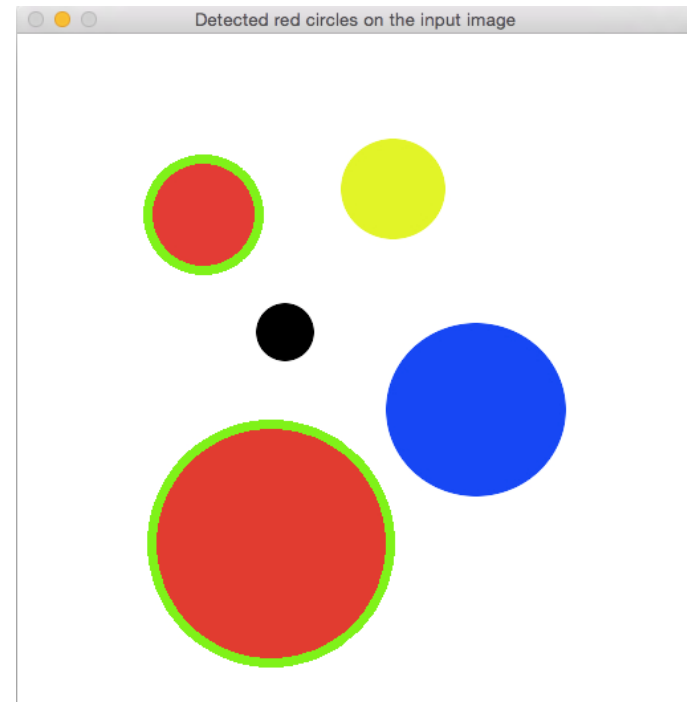


# Overview

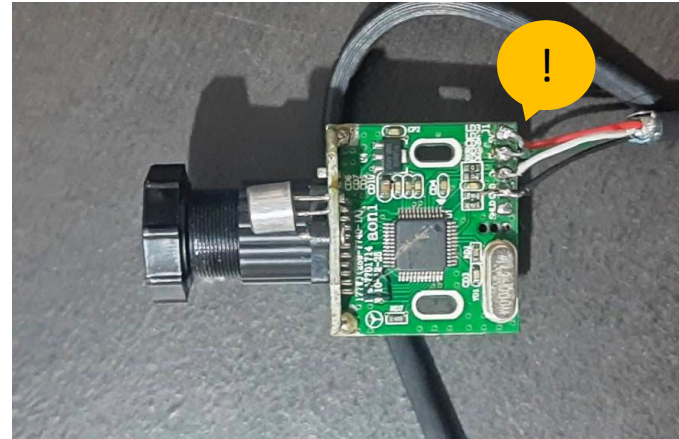
## Dewarping 360 Image



## Ball Tracking



# Hardware

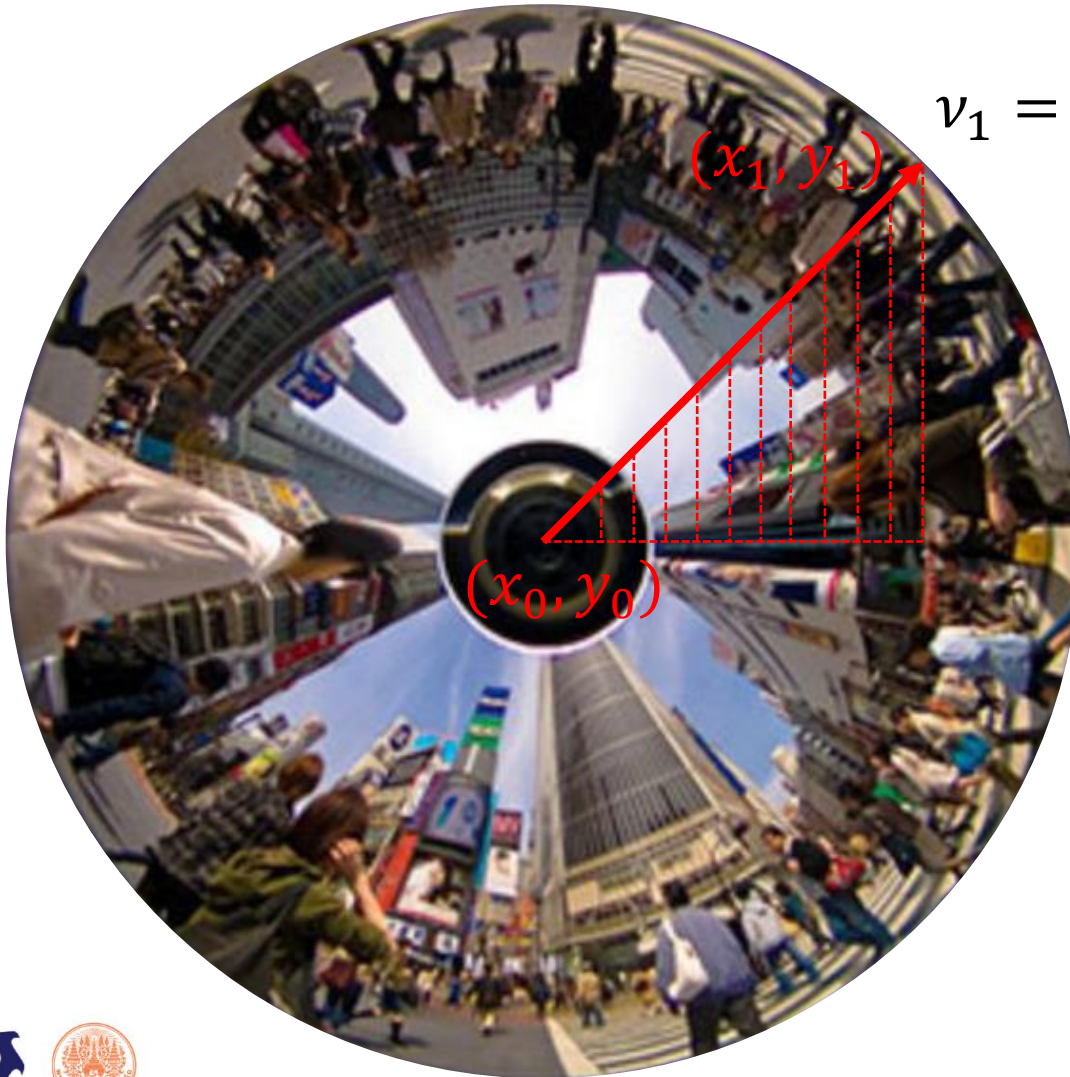


# Platform





# Principal



$$v_1 = (x_1 - x_0)i + (y_1 - y_0)j$$

$$x_1 = r \cdot \cos\theta$$

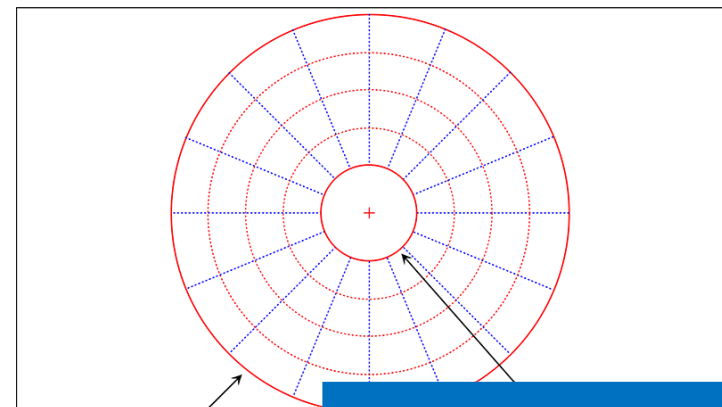
$$y_1 = r \cdot \sin\theta$$

$$0 < \theta < 360$$

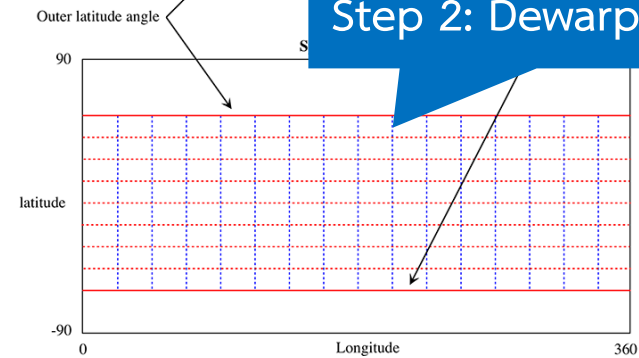
$$0 < r < r_{max}$$

# Method

Step 1: Get Image



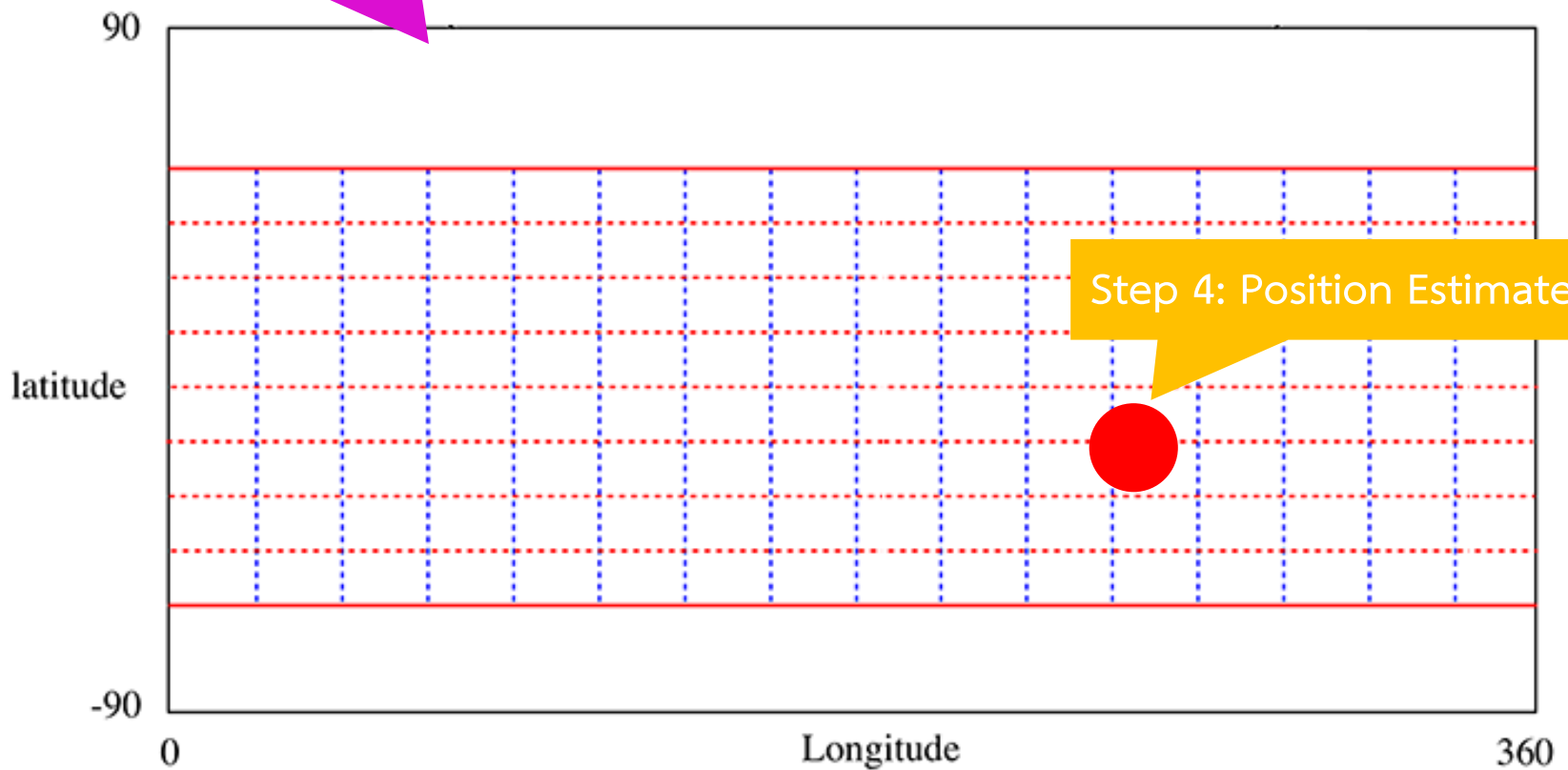
Step 2: Dewarping Image





# Method

Step 3: Ball Detection



Step 4: Position Estimate



# Environment



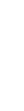
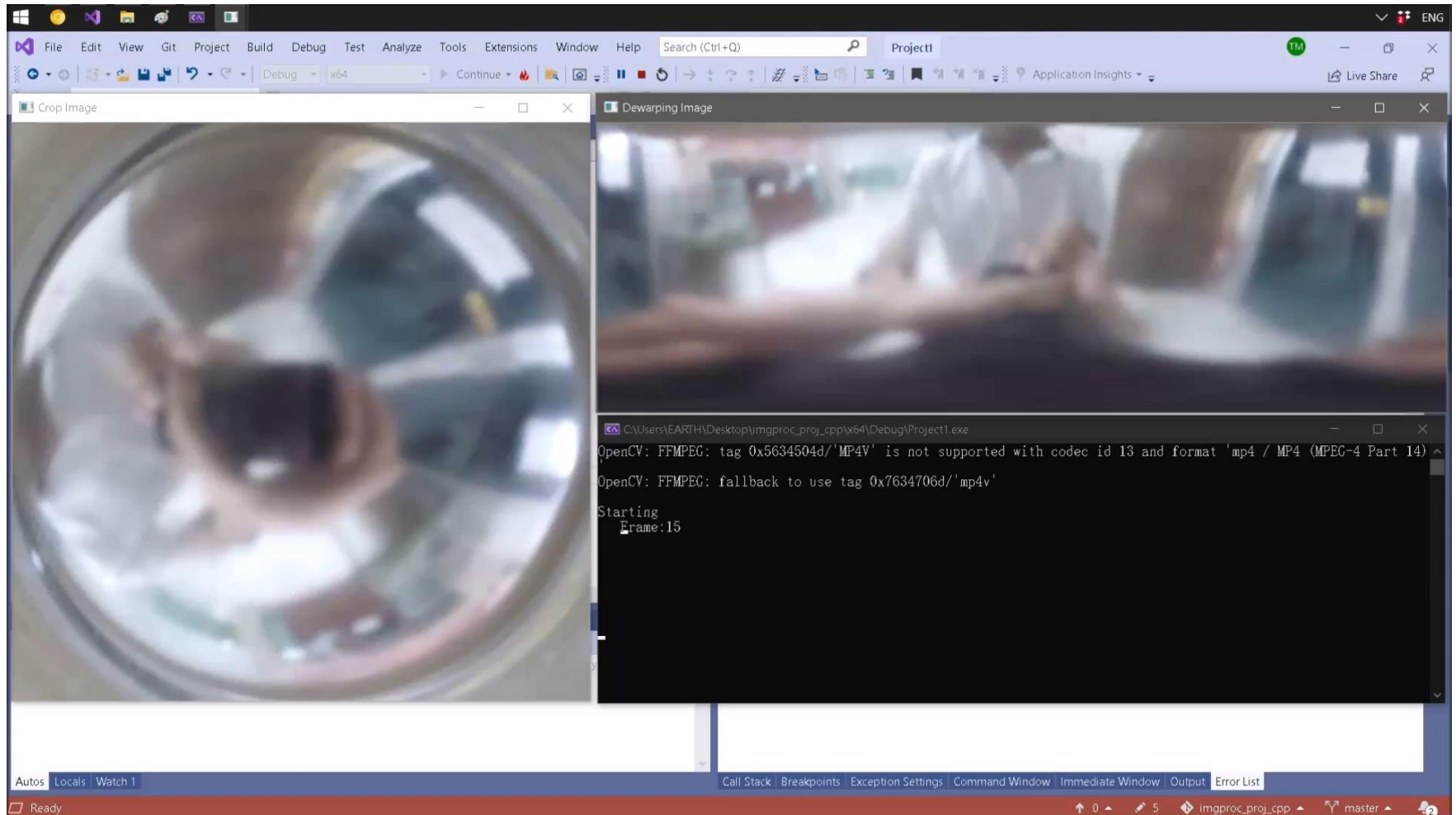
# Experiment : Dewarping Image



```
/* dewarping proccess */  
for (float t = 0; t < dw_img.cols; t += 1)  
{  
    for (float r = 0; r < dw_img.rows; r += 1)  
    {  
        int x = r * res_r * cos(t * (double)res_c * deg_rad) + rad;  
        int y = rad - r * (double)res_r * sin(t * (double)res_c * deg_rad);  
        int col = dw_img.cols - 1 - t;  
        int row = dw_img.rows - 1 - r;  
        dw_img.at<Vec3b>(row, col) = crop_img.at<Vec3b>(y, x);  
    }  
}
```



# Experiment : Dewarping Video





# Experiment : Ball Tracking

The screenshot displays the Visual Studio Code IDE with a C++ project named 'Project1'. The code in `main.cpp` implements a ball tracking algorithm using OpenCV. It includes functions for image cropping, dewarping, and circle detection using the Hough transform. The program outputs the ball's coordinates to the console.

```
int col = dw_img.col;
int row = dw_img.row;
dw_img.at<Vec3b>(row, col) = Vec3b(0, 0, 0);
}

#define circleDetect
#ifdef circleDetect
/* split red color channel */
split(dw_img, diff_img);
gray_img = diff_img[2];

/* circle detect */
HoughCircles(gray_img, circles, HOUGH_METHOD_GRAB, 1, 100, 1, 1, 1, 1);
for (size_t i = 0; i < circles.size(); i++)
{
    Vec3i c = circles[i];
    Point center = Point(c[0], c[1]);
    int rad = c[2];

    if (c[1] > 75 && c[1] < 225)
    {
        circle(dw_img, center, rad, Scalar(0, 0, 0), 1);
        numBall++;
    }
}
```

The 'Dewarping Image' window shows a red dot at the ball's position. The Output window displays the following text:

```
OpenCV: FFMPEG: tag 0x5634504d/'MP4V' is not supported with codec id 13 and format 'mp4 / MP4 (MPEG-4 Part 14)'
OpenCV: FFMPEG: fallback to use tag 0x7634706d/'mp4v'

Ball coordinates
[156, 104]
```



# Result : Framerate

(Source: 960x540 pixel)

```
Microsoft Visual Studio Debug Console

OpenCV: FFMPEG: tag 0x5634504d/'MP4V' is not supported with codec
id 13 and format 'mp4 / MP4 (MPEG-4 Part 14)'
OpenCV: FFMPEG: fallback to use tag 0x7634706d/'mp4v'

Previous framerate
29
Minimum Framerate: 6
Maximum Framerate: 31
Average Framerate: 25

Finished

C:\Users\EARTH\Desktop\imgproc_proj_cpp\x64\Debug\Project1.exe (p
rocess 18672) exited with code 0.
To automatically close the console when debugging stops, enable T
ools->Options->Debugging->Automatically close the console when de
bugging stops.
Press any key to close this window . . .
```





# Result : Tracking

(Source: 1min7sec)



Ball discovered

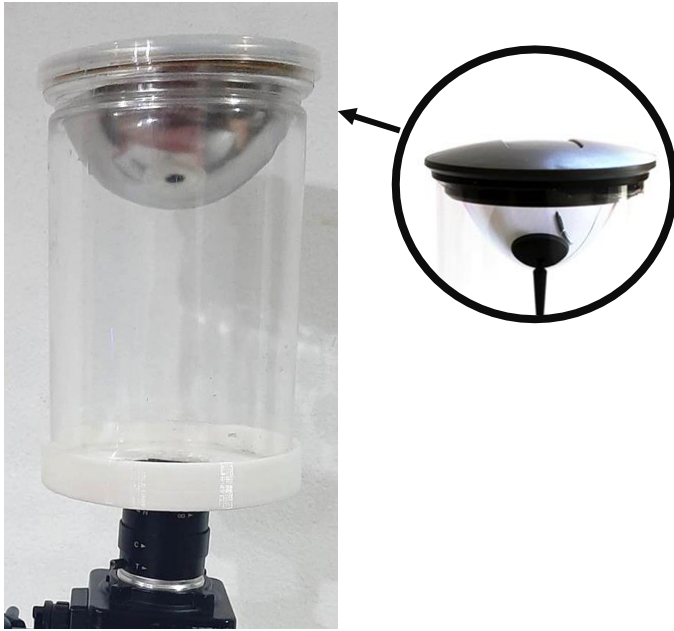
= 656/1629 Frames

%Discovered

$$= \frac{656}{1629} \times 100 = 40.27\%$$

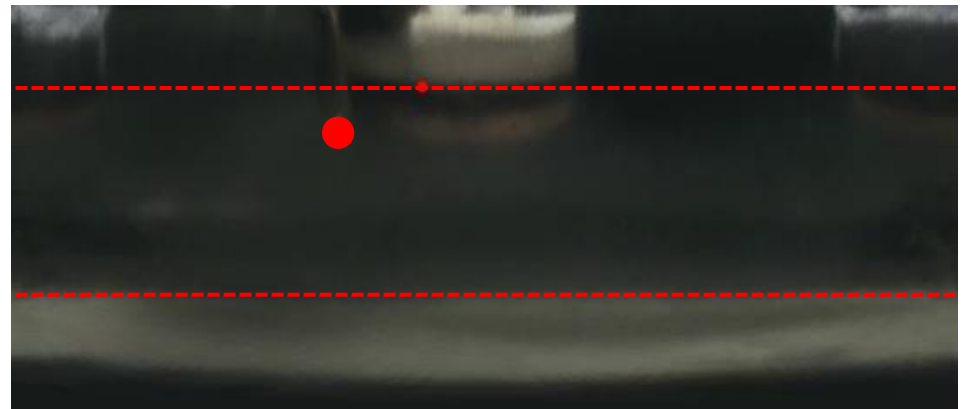


# Summary



## Factor of dewarping process

- Image quality
- Framerate
- Reflection mirror



## Factor of ball tracking

- Image quality
- Dynamic light
- Camera distortion



# Appendix

## Source Code

Available : [https://github.com/M-TRCH/Dewarping\\_360\\_Image](https://github.com/M-TRCH/Dewarping_360_Image)

## Dewarping 360 Image Principal

Available : <http://paulbourke.net/panorama/LucyCamera/>

## Contours Hierarchy

Available : [https://docs.opencv.org/3.4.1/d9/d8b/tutorial\\_py\\_contours\\_hierarchy.html](https://docs.opencv.org/3.4.1/d9/d8b/tutorial_py_contours_hierarchy.html)

## Contour Detection

Available : <https://learnopencv.com/contour-detection-using-opencv-python-c/>

## Shape Detection

Available : <https://opencvproject.wordpress.com/projects-files/detection-shape/>

## Hough Circle Transform

Available : [https://docs.opencv.org/3.4/d4/d70/tutorial\\_hough\\_circle.html](https://docs.opencv.org/3.4/d4/d70/tutorial_hough_circle.html)

