```
In [15]:
```

```
1
    class Node:
 2
        def __init__ (self, state, parent, actions, totalcost):
 3
            self.state=state
 4
            self.parent=parent
 5
            self.actions=actions
 6
            self.totalcost=totalcost
 7
    graph={'A':Node('A',None,['B','E','C'],None),
 8
 9
           'B':Node('B',None,['D','E','A'],None),
           'C': Node('C', None, ['A', 'F', 'G'], None),
10
           'D':Node('D',None,['B','E'],None),
11
           'E':Node('E',None,['A','B','D'],None),
12
           'F':Node('F',None,['C'],None),
13
           'G':Node('G',None,['C'],None),
14
          }
15
16
    def DFS():
17
18
        initialState='A'
19
        goalState='D'
20
21
22
        graph={'A':Node('A',None,['B','E','C'],None),
           'B':Node('B',None,['D','E','A'],None),
'C':Node('C',None,['A','F','G'],None),
23
24
25
           'D':Node('D',None,['B','E'],None),
           'E':Node('E',None,['A','B','D'],None),
26
           'F':Node('F',None,['C'],None),
27
28
           'G':Node('G',None,['C'],None),
29
          }
30
31
        frontier=[initialState]
32
        explored=[]
33
34
        while len(frontier)!=0:
35
            currentnode=frontier.pop(len(frontier)-1)
36
            print(currentnode)
37
            explored.append(currentnode)
38
            currentchildren=[]
            for child in graph(currentnode).actions:
39
40
                 if child not in frontier and child not in explored:
41
                     graph[child].parent=cuurentnode
42
                     if graph[child].state==goalstate:
43
                         print(explored)
44
                         return actionsequence(graph,initialstate,goalstate)
45
                     currentchildren=currentchildren+1
                     frontier.append(child)
46
47
            if currentchildren==0:
48
                 del explored[len(explored)-1]
49
50
    solution=DFS()
51
   print(solution)
52
53
   def actionsequence(graph,initialstate,goalstate):
54
        solution=[goalstate]
55
        currentparent=graph[goalstate].parent
56
        while currentparent!=None:
57
            solution.append(currentparent)
58
            currentparent=graph(currentparent).parent
59
        solution.reverse()
```

Α

```
Traceback (most recent call last)
TypeError
~\AppData\Local\Temp/ipykernel_1136/3056991769.py in <module>
     48
                    del explored[len(explored)-1]
     49
---> 50 solution=DFS()
     51 print(solution)
     52
~\AppData\Local\Temp/ipykernel_1136/3056991769.py in DFS()
     37
                explored.append(currentnode)
     38
                currentchildren=[]
---> 39
                for child in graph(currentnode).actions:
                    if child not in frontier and child not in explored:
     40
     41
                        graph[child].parent=cuurentnode
TypeError: 'dict' object is not callable
In [ ]:
 1
    #solution:
 2
 3 | Final path:['D', 'B', 'A', 'C']
   Explored:D, E, A
```

```
In [58]:
```

```
# Lab task 2 Practice:
 2
 3
   class Trie:
        def __init__(self):
 4
 5
            self.character = {}
 6
            self.isLeaf = False
 7
 8
 9
   def insert(root, s):
10
        curr = root
11
12
        for ch in s:
13
            curr = curr.character.setdefault(ch, Trie())
14
        curr.isLeaf = True
15
16
17
18
   row = [-1, -1, -1, 0, 1, 0, 1, 1]
   col = [-1, 1, 0, -1, -1, 1, 0, 1]
19
20
21
22
   def isSafe(x, y, processed, board, ch):
23
24
        return (0 <= x < len(processed)) and (0 <= y < len(processed[0])) and \setminus
25
                not processed[x][y] and (board[x][y] == ch)
26
27
   def searchBoggle(root, board, i, j, processed, path, result):
28
29
        if root.isLeaf:
30
31
            result.add(path)
32
33
34
        processed[i][j] = True
35
36
37
38
        for key, value in root.character.items():
39
            for k in range(len(row)):
40
                if isSafe(i + row[k], j + col[k], processed, board, key):
                     searchBoggle(value, board, i + row[k], j + col[k],
41
42
                                  processed, path + key, result)
43
44
45
        processed[i][j] = False
46
47
48
49
   def searchInBoggle(board, words):
50
51
        result = set()
52
        if not board or not len(board):
53
            return
        root = Trie()
54
55
        for word in words:
56
            insert(root, word)
57
        (M, N) = (len(board), len(board[0]))
58
59
```

```
processed = [[False for x in range(N)] for y in range(M)]
60
61
        for i in range(M):
             for j in range(N):
62
                 ch = board[i][j]
63
                 if ch in root.character:
64
                     searchBoggle(root.character[ch], board, i, j, processed, ch, result)
65
66
67
68
         return result
69
70
71
    if __name__ == '__main__':
72
        board = [
             ['M','S','E','F'],
['R','A','T','D'],
73
74
             ['L','O','N','E'],
75
             ['K','A','F','B']
76
         ]
77
78
79
        words = ['START', 'NOTE', 'SAND', 'STONED']
        searchInBoggle(board, words)
80
81
        validWords = searchInBoggle(board, words)
82
        print(validWords)
83
84
{'NOTE', 'STONED', 'SAND'}
In [ ]:
 1
In [ ]:
```

1