# - Parts used:

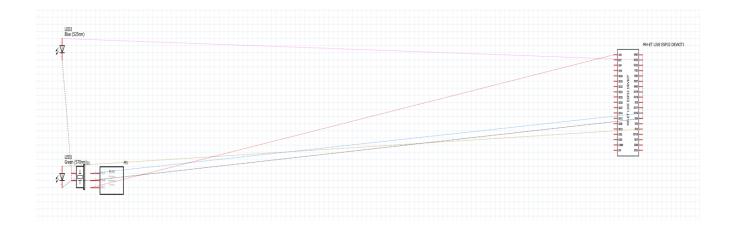
- (2x) Breadboard
- (1x) ESP32 Dev Module
- (1x) Buzzer
- (1x) FC-51
- (1x) Green LED
- (1x) Blue LED
- Jumper Wires

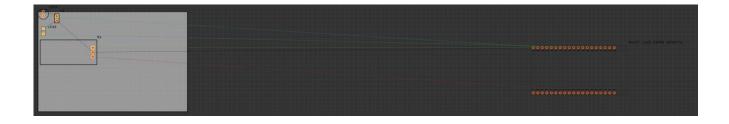
# - Software used :

- Arduino IDE
- Arduino Cloude Website

# **Project Description:**

The IoT Door Monitoring System is a sophisticated and versatile solution designed to provide advanced security and real-time door status notifications in various settings. Leveraging the power of Internet of Things (IoT) technology, this project offers comprehensive monitoring and remote-control capabilities, ensuring the safety and convenience of users.





# Algorithm and Program source code:

## A) Algorithm:

### 1. Import Necessary Libraries:

 Include the "thingProperties.h" library to define properties for the Arduino IoT Cloud.

#### 2. Define Pin Constants:

• Declare constants for the IR sensor input pin (IRPin), the buzzer output pin (buzzerPin), and an additional pin (I).

## 3. Setup Function:

- Initialize the serial communication at a baud rate of 9600 for debugging purposes.
- Configure the pin modes for the IR sensor, buzzer, and an additional pin.
- Initialize the Arduino IoT Cloud properties and establish a connection to the cloud service.
- Set the debug message level and print debug information.

#### 4. Loop Function:

- Continuously update the Arduino lot Cloud to handle property changes and cloud communication.
- Read the IR sensor (motion detector) input to detect motion.
- If no motion is detected (motionDetected is LOW), execute the following steps:
  - Turn on the buzzer to produce an audible alert.
  - Print "OK" to the serial monitor for debugging.
  - Set the text variable to "Door unlock."
  - Turn on an additional pin (I) to indicate door unlock status.
  - Delay for 1 second.
  - Turn off the buzzer and the additional pin (I).

### 5. onLedChange Function:

- This function is a callback that is automatically triggered when the state of the "led" property changes in the Arduino IoT Cloud.
- If the "led" property is set to true, it sets digital pin 2 to HIGH (turning on an LED).
- If the "led" property is set to false, it sets digital pin 2 to LOW (turning off the LED).

## B) Program Source Code:

```
GO TO IOT CLOUD

→ ESP32 Dev Module

                  Things_nov09a.ino
                                                  ReadMe.adoc
                                                                                  thingProperties.h
                                                                                                                 Secret
凸
                #include "thingProperties.h"
                int IRPin = 16;
圁
                int buzzerPin = 4;
const int 1 = 23;
            4
            6
                void setup()
            8 ▼ {
                  Serial.begin(9600);
pinMode(2, OUTPUT);
pinMode(1, OUTPUT);
            9
           10
           11
           12
                  pinMode(IRPin, INPUT);
           13
                  pinMode(buzzerPin,OUTPUT);
                   delay(1500);
Ø
           15
                  initProperties();
                   ArduinoCloud.begin(ArduinoIoTPreferredConnection);
           16
           17
                   setDebugMessageLevel(2);
②
                  ArduinoCloud.printDebugInfo();
           18
           19 }
           20
           21 void loop()
Ħ
           22 ▼ {
                  ArduinoCloud.update();
int motionDetected = digitalRead(IRPin);
if (motionDetected == LOW)
           23
           24
0
           25
           26 ▼
           27
                    digitalWrite(buzzerPin, HIGH);
                  Serial.print( " OK" );
text = " Door unlock ";
digitalWrite(1, HIGH);
           28
           29
           30
                     delay(1000);
digitalWrite(buzzerPin, LOW);
digitalWrite(1, LOW);
           31
           32
33
           34
           35
                }
           36
           37
                void onLedChange()
           38 ▼ {
           39
                   if(led==true)
           40 🕶
           41
                     digitalWrite(2,HIGH);
           42
           43
                   else
           44 +
           45
                     digitalWrite(2,LOW);
           46
           47
```

# Implementation:

