

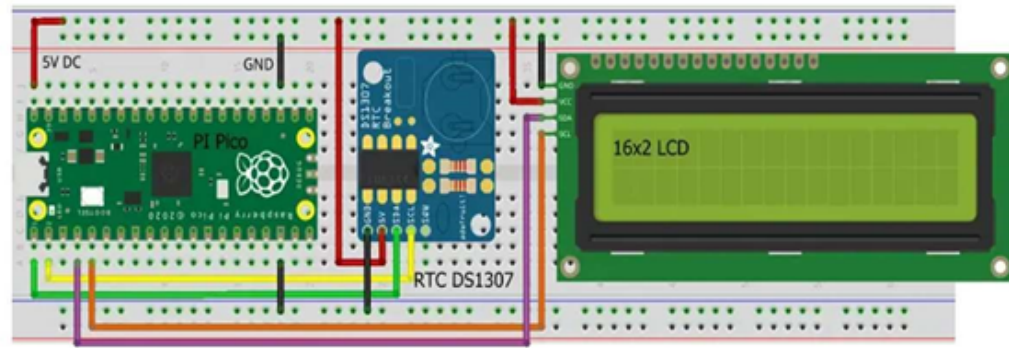
Project Name: Digital clock Using Raspberry Pi Pico

Group No: 6

Roll No: 13,19,21,25

Software:

fritzing:



Code:

```
#ds1302.py
from machine import Pin

DS1302_REG_SECOND = (0x80)
DS1302_REG_MINUTE = (0x82)
DS1302_REG_HOUR = (0x84)
DS1302_REG_DAY = (0x86)
DS1302_REG_MONTH = (0x88)
DS1302_REG_WEEKDAY = (0x8A)
DS1302_REG_YEAR = (0x8C)
DS1302_REG_WP = (0x8E)
DS1302_REG_CTRL = (0x90)
DS1302_REG_RAM = (0xC0)

class DS1302:
    def __init__(self, clk, dio, cs):
        self.clk = clk
        self.dio = dio
        self.cs = cs
        self.clk.init(Pin.OUT)
        self.cs.init(Pin.OUT)

    def _dec2hex(self, dat):
        return (dat//10) * 16 + (dat % 10)

    def _hex2dec(self, dat):
        return (dat//16) * 10 + (dat % 16)

    def _write_byte(self, dat):
        self.dio.init(Pin.OUT)
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for i in range(8):
    self.dio.value((dat >> i) & 1)
    self.clk.value(1)
    self.clk.value(0)

def _read_byte(self):
    d = 0
    self.dio.init(Pin.IN)
    for i in range(8):
        d = d | (self.dio.value() << i)
        self.clk.value(1)
        self.clk.value(0)
    return d

def _get_reg(self, reg):
    self.cs.value(1)
    self._write_byte(reg)
    t = self._read_byte()
    self.cs.value(0)
    return t

def _set_reg(self, reg, dat):
    self.cs.value(1)
    self._write_byte(reg)
    self._write_byte(dat)
    self.cs.value(0)

def _wr(self, reg, dat):
    self._set_reg(DS1302_REG_WP, 0)
    self._set_reg(reg, dat)
    self._set_reg(DS1302_REG_WP, 0x80)

def start(self):
    t = self._get_reg(DS1302_REG_SECOND + 1)
    self._wr(DS1302_REG_SECOND, t & 0x7f)

def stop(self):
    t = self._get_reg(DS1302_REG_SECOND + 1)
    self._wr(DS1302_REG_SECOND, t | 0x80)

def second(self, second=None):
    if second == None:
        return self._hex2dec(self._get_reg(DS1302_REG_SECOND+1)) % 60
    else:
        self._wr(DS1302_REG_SECOND, self._dec2hex(second % 60))

def minute(self, minute=None):
    if minute == None:
        return self._hex2dec(self._get_reg(DS1302_REG_MINUTE+1))
    else:
        self._wr(DS1302_REG_MINUTE, self._dec2hex(minute % 60))

def hour(self, hour=None):

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    if hour == None:
        return self._hex2dec(self._get_reg(DS1302_REG_HOUR+1))
    else:
        self._wr(DS1302_REG_HOUR, self._dec2hex(hour % 24))

def weekday(self, weekday=None):
    if weekday == None:
        return self._hex2dec(self._get_reg(DS1302_REG_WEEKDAY+1))
    else:
        self._wr(DS1302_REG_WEEKDAY, self._dec2hex(weekday % 8))

def day(self, day=None):
    if day == None:
        return self._hex2dec(self._get_reg(DS1302_REG_DAY+1))
    else:
        self._wr(DS1302_REG_DAY, self._dec2hex(day % 32))

def month(self, month=None):
    if month == None:
        return self._hex2dec(self._get_reg(DS1302_REG_MONTH+1))
    else:
        self._wr(DS1302_REG_MONTH, self._dec2hex(month % 13))

def year(self, year=None):
    if year == None:
        return self._hex2dec(self._get_reg(DS1302_REG_YEAR+1)) + 2000
    else:
        self._wr(DS1302_REG_YEAR, self._dec2hex(year % 100))

def date_time(self, dat=None):
    if dat == None:
        return [self.year(), self.month(), self.day(), self.weekday(), self.hour(), self.minute(),
self.second()]
    else:
        self.year(dat[0])
        self.month(dat[1])
        self.day(dat[2])
        self.weekday(dat[3])
        self.hour(dat[4])
        self.minute(dat[5])
        self.second(dat[6])

def ram(self, reg, dat=None):
    if dat == None:
        return self._get_reg(DS1302_REG_RAM + 1 + (reg % 31)*2)
    else:
        self._wr(DS1302_REG_RAM + (reg % 31)*2, dat)

#lcd.py
import time

class LcdApi:

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# Implements the API for talking with HD44780 compatible character LCDs.
# This class only knows what commands to send to the LCD, and not how to get
# them to the LCD.
#
# It is expected that a derived class will implement the hal_xxx functions.
#
# The following constant names were lifted from the avrlib lcd.h header file,
# with bit numbers changed to bit masks.

# HD44780 LCD controller command set
LCD_CLR      = 0x01 # DB0: clear display
LCD_HOME     = 0x02 # DB1: return to home position

LCD_ENTRY_MODE = 0x04 # DB2: set entry mode
LCD_ENTRY_INC  = 0x02 # DB1: increment
LCD_ENTRY_SHIFT = 0x01 # DB0: shift

LCD_ON_CTRL    = 0x08 # DB3: turn lcd/cursor on
LCD_ON_DISPLAY = 0x04 # DB2: turn display on
LCD_ON_CURSOR  = 0x02 # DB1: turn cursor on
LCD_ON_BLINK   = 0x01 # DB0: blinking cursor

LCD_MOVE      = 0x10 # DB4: move cursor/display
LCD_MOVE_DISP = 0x08 # DB3: move display (0-> move cursor)
LCD_MOVE_RIGHT = 0x04 # DB2: move right (0-> left)

LCD_FUNCTION   = 0x20 # DB5: function set
LCD_FUNCTION_8BIT = 0x10 # DB4: set 8BIT mode (0->4BIT mode)
LCD_FUNCTION_2LINES = 0x08 # DB3: two lines (0->one line)
LCD_FUNCTION_10DOTS = 0x04 # DB2: 5x10 font (0->5x7 font)
LCD_FUNCTION_RESET = 0x30 # See "Initializing by Instruction" section

LCD_CGRAM      = 0x40 # DB6: set CG RAM address
LCD_DDRAM      = 0x80 # DB7: set DD RAM address

LCD_RS_CMD     = 0
LCD_RS_DATA    = 1

LCD_RW_WRITE   = 0
LCD_RW_READ    = 1

def __init__(self, num_lines, num_columns):
    self.num_lines = num_lines
    if self.num_lines > 4:
        self.num_lines = 4
    self.num_columns = num_columns
    if self.num_columns > 40:
        self.num_columns = 40
    self.cursor_x = 0
    self.cursor_y = 0
    self.implied_newline = False
    self.backlight = True
    self.display_off()

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self.backlight_on()
self.clear()
self.hal_write_command(self.LCD_ENTRY_MODE | self.LCD_ENTRY_INC)
self.hide_cursor()
self.display_on()

def clear(self):
    # Clears the LCD display and moves the cursor to the top left corner
    self.hal_write_command(self.LCD_CLR)
    self.hal_write_command(self.LCD_HOME)
    self.cursor_x = 0
    self.cursor_y = 0

def show_cursor(self):
    # Causes the cursor to be made visible
    self.hal_write_command(self.LCD_ON_CTRL | self.LCD_ON_DISPLAY |
                           self.LCD_ON_CURSOR)

def hide_cursor(self):
    # Causes the cursor to be hidden
    self.hal_write_command(self.LCD_ON_CTRL | self.LCD_ON_DISPLAY)

def blink_cursor_on(self):
    # Turns on the cursor, and makes it blink
    self.hal_write_command(self.LCD_ON_CTRL | self.LCD_ON_DISPLAY |
                           self.LCD_ON_CURSOR | self.LCD_ON_BLINK)

def blink_cursor_off(self):
    # Turns on the cursor, and makes it no blink (i.e. be solid)
    self.hal_write_command(self.LCD_ON_CTRL | self.LCD_ON_DISPLAY |
                           self.LCD_ON_CURSOR)

def display_on(self):
    # Turns on (i.e. unblanks) the LCD
    self.hal_write_command(self.LCD_ON_CTRL | self.LCD_ON_DISPLAY)

def display_off(self):
    # Turns off (i.e. blanks) the LCD
    self.hal_write_command(self.LCD_ON_CTRL)

def backlight_on(self):
    # Turns the backlight on.

    # This isn't really an LCD command, but some modules have backlight
    # controls, so this allows the hal to pass through the command.
    self.backlight = True
    self.hal_backlight_on()

def backlight_off(self):
    # Turns the backlight off.

    # This isn't really an LCD command, but some modules have backlight
    # controls, so this allows the hal to pass through the command.

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self.backlight = False
self.hal_backlight_off()

def move_to(self, cursor_x, cursor_y):
    # Moves the cursor position to the indicated position. The cursor
    # position is zero based (i.e. cursor_x == 0 indicates first column).
    self.cursor_x = cursor_x
    self.cursor_y = cursor_y
    addr = cursor_x & 0x3f
    if cursor_y & 1:
        addr += 0x40 # Lines 1 & 3 add 0x40
    if cursor_y & 2: # Lines 2 & 3 add number of columns
        addr += self.num_columns
    self.hal_write_command(self.LCD_DDRAM | addr)

def putchar(self, char):
    # Writes the indicated character to the LCD at the current cursor
    # position, and advances the cursor by one position.
    if char == '\n':
        if self.implied_newline:
            # self.implied_newline means we advanced due to a wraparound,
            # so if we get a newline right after that we ignore it.
            pass
        else:
            self.cursor_x = self.num_columns
    else:
        self.hal_write_data(ord(char))
        self.cursor_x += 1
    if self.cursor_x >= self.num_columns:
        self.cursor_x = 0
        self.cursor_y += 1
        self.implied_newline = (char != '\n')
    if self.cursor_y >= self.num_lines:
        self.cursor_y = 0
    self.move_to(self.cursor_x, self.cursor_y)

def putstr(self, string):
    # Write the indicated string to the LCD at the current cursor
    # position and advances the cursor position appropriately.
    for char in string:
        self.putchar(char)

def custom_char(self, location, charmap):
    # Write a character to one of the 8 CGRAM locations, available
    # as chr(0) through chr(7).
    location &= 0x7
    self.hal_write_command(self.LCD_CGRAM | (location << 3))
    self.hal_sleep_us(40)
    for i in range(8):
        self.hal_write_data(charmap[i])
        self.hal_sleep_us(40)
    self.move_to(self.cursor_x, self.cursor_y)

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def hal_backlight_on(self):
    # Allows the hal layer to turn the backlight on.
    # If desired, a derived HAL class will implement this function.
    pass

def hal_backlight_off(self):
    # Allows the hal layer to turn the backlight off.
    # If desired, a derived HAL class will implement this function.
    pass

def hal_write_command(self, cmd):
    # Write a command to the LCD.
    # It is expected that a derived HAL class will implement this function.
    raise NotImplementedError

def hal_write_data(self, data):
    # Write data to the LCD.
    # It is expected that a derived HAL class will implement this function.
    raise NotImplementedError

def hal_sleep_us(self, usecs):
    # Sleep for some time (given in microseconds)
    time.sleep_us(usecs)

#lcd_api.py
import utime
import gc

from lcd_api import LcdApi
from machine import I2C

# PCF8574 pin definitions
MASK_RS = 0x01    # P0
MASK_RW = 0x02    # P1
MASK_E  = 0x04    # P2

SHIFT_BACKLIGHT = 3 # P3
SHIFT_DATA      = 4 # P4-P7

class I2cLcd(LcdApi):

    #Implements a HD44780 character LCD connected via PCF8574 on I2C

    def __init__(self, i2c, i2c_addr, num_lines, num_columns):
        self.i2c = i2c
        self.i2c_addr = i2c_addr
        self.i2c.writeto(self.i2c_addr, bytes([0]))
        utime.sleep_ms(20) # Allow LCD time to powerup
        # Send reset 3 times
        self.hal_write_init_nibble(self.LCD_FUNCTION_RESET)
        utime.sleep_ms(5) # Need to delay at least 4.1 msec
        self.hal_write_init_nibble(self.LCD_FUNCTION_RESET)
        utime.sleep_ms(1)
        self.hal_write_init_nibble(self.LCD_FUNCTION_RESET)

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    utime.sleep_ms(1)
    # Put LCD into 4-bit mode
    self.hal_write_init_nibble(self.LCD_FUNCTION)
    utime.sleep_ms(1)
    LcdApi.__init__(self, num_lines, num_columns)
    cmd = self.LCD_FUNCTION
    if num_lines > 1:
        cmd |= self.LCD_FUNCTION_2LINES
    self.hal_write_command(cmd)
    gc.collect()

def hal_write_init_nibble(self, nibble):
    # Writes an initialization nibble to the LCD.
    # This particular function is only used during initialization.
    byte = ((nibble >> 4) & 0x0f) << SHIFT_DATA
    self.i2c.writeto(self.i2c_addr, bytes([byte | MASK_E]))
    self.i2c.writeto(self.i2c_addr, bytes([byte]))
    gc.collect()

def hal_backlight_on(self):
    # Allows the hal layer to turn the backlight on
    self.i2c.writeto(self.i2c_addr, bytes([1 << SHIFT_BACKLIGHT]))
    gc.collect()

def hal_backlight_off(self):
    #Allows the hal layer to turn the backlight off
    self.i2c.writeto(self.i2c_addr, bytes([0]))
    gc.collect()

def hal_write_command(self, cmd):
    # Write a command to the LCD. Data is latched on the falling edge of E.
    byte = ((self.backlight << SHIFT_BACKLIGHT) |
            (((cmd >> 4) & 0x0f) << SHIFT_DATA))
    self.i2c.writeto(self.i2c_addr, bytes([byte | MASK_E]))
    self.i2c.writeto(self.i2c_addr, bytes([byte]))
    byte = ((self.backlight << SHIFT_BACKLIGHT) |
            ((cmd & 0x0f) << SHIFT_DATA))
    self.i2c.writeto(self.i2c_addr, bytes([byte | MASK_E]))
    self.i2c.writeto(self.i2c_addr, bytes([byte]))
    if cmd <= 3:
        # The home and clear commands require a worst case delay of 4.1 msec
        utime.sleep_ms(5)
    gc.collect()

def hal_write_data(self, data):
    # Write data to the LCD. Data is latched on the falling edge of E.
    byte = (MASK_RS |
            (self.backlight << SHIFT_BACKLIGHT) |
            (((data >> 4) & 0x0f) << SHIFT_DATA))
    self.i2c.writeto(self.i2c_addr, bytes([byte | MASK_E]))
    self.i2c.writeto(self.i2c_addr, bytes([byte]))
    byte = (MASK_RS |
            (self.backlight << SHIFT_BACKLIGHT) |

```



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        ((data & 0x0f) << SHIFT_DATA))
        self.i2c.writeto(self.i2c_addr, bytes([byte | MASK_E]))
        self.i2c.writeto(self.i2c_addr, bytes([byte]))
        gc.collect()
#main.py

"""

DS1302 real-time clock module

Special thanks to yunline for the DS1302 Library:
https://github.com/omarbenhamid/micropython-ds1302-rtc
and T-622 for the I2C LCD library: https://github.com/T-622/RPI-PICO-I2C-LCD

Remember to check out more tutorials on NerdCave - https://www.youtube.com/c/NerdCaveYT

Project Pinout
VCC - VSYS (PIN39)
GND - GND (Any ground on Pico)
CLK - GP18 (PIN24)
DAT - GP17 (PIN22)
RST - GP16 (PIN21)

"""

from machine import I2C, Pin
from ds1302 import DS1302
from pico_i2c_lcd import I2cLcd

I2C_ADDR = 63
I2C_NUM_ROWS = 2
I2C_NUM_COLS = 16

i2c = I2C(0, sda=machine.Pin(0), scl=machine.Pin(1), freq=400000)
lcd = I2cLcd(i2c, I2C_ADDR, I2C_NUM_ROWS, I2C_NUM_COLS)

ds = DS1302(Pin(18), Pin(17), Pin(16))

ds.date_time() # returns the current datetime.

#ds.date_time([2023, 3, 2, 0, 8, 17, 50, 0]) # set datetime.

#ds.hour() # returns hour.
#print(ds.date_time())

while True:
    (Y,M,D,day,hr,m,s)=ds.date_time()
    if s < 10:
        s = "0" + str(s)
    if m < 10:
        m = "0" + str(m)

```

	<pre> if hr < 10: hr = "0" + str(hr) if D < 10: D = "0" + str(D) if M < 10: M = "0" + str(M) lcd.move_to(0,0) lcd.putstr("Time:") lcd.move_to(6,0) lcd.putstr(str(hr) + ":" + str(m) + ":" + str(s)) lcd.move_to(0,1) lcd.putstr("Date:") lcd.move_to(6,1) lcd.putstr(str(D) + "/" + str(M) + "/" + str(Y)) </pre>
Reference	1. https://www.instructables.com/Raspberry-Pi-Pico-Alarm-Clock/