

# On the second bounded cohomology of groups acting on a product of two Gromov-hyperbolic spaces

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## Abstract

We want to classify the second bounded cohomology of groups acting on a product of two Gromov-Hyperbolic spaces.

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## 1 Introduction

In [1], K.Fujiwara proved that, if a group  $G$  acts on a Gromov-hyperbolic space  $X$  isometrically and properly, with limit set  $|L(G)| \geq 3$ , then  $H_b^2(G; \mathbb{R})$  has infinite dimension. We found that his proof is also valid in a more general setting (Theorem 3.1).

For a group  $G$ , denote

$$C_b^n(G, \mathbb{R}) := \left\{ \varphi: G^n \rightarrow \mathbb{R} : \sup_{g_1, \dots, g_n \in G} |\varphi(g_1, \dots, g_n)| < \infty \right\}$$

where  $\varphi$  is just a map instead of a homomorphism. Define the boundary operator  $\delta: C_b^n(G, \mathbb{R}) \rightarrow C_b^{n+1}(G, \mathbb{R})$  as follow: For any  $\varphi \in C_b^n(G, \mathbb{R})$ , let

$$\delta\varphi(g_0, \dots, g_n) := \varphi(g_1, \dots, g_n) + \sum_{i=1}^n (-1)^i \varphi(g_0, \dots, g_{i-1}g_i, \dots, g_n) + (-1)^{n+1} \varphi(g_0, \dots, g_{n-1}).$$

It's easy to check that  $\delta\varphi \in C_b^{n+1}(G, \mathbb{R})$  and  $\delta^2 = 0$ . So  $(C_b^*(G, \mathbb{R}), \delta)$  is a cochain complex.

**Definition 1.1.** The *bounded cohomology* of  $G$  is defined by

$$H_b^*(G, \mathbb{R}) := \frac{\ker \delta^*}{\text{im } \delta^{*-1}}.$$

It is well known that  $H_b^1(G; \mathbb{R})$  is trivial for any group, and that  $H_b^n(G; \mathbb{R})$  is trivial for all  $n \geq 1$  if  $G$  is amenable. See [2] as general reference.

Motivated by this example:

**Example 1.2.** Let's consider the Baumslag-Solitar Group  $BS(1, 2) = \langle a, t : tat^{-1} = a^2 \rangle$ .

1. There is a non-proper action of  $BS(1, 2)$  on  $\mathbb{H}^2$ : notice that  $\text{Isom}(\mathbb{H}^2) = \text{PSL}(2, \mathbb{R})$ , let  $a \mapsto \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$  and  $t \mapsto \begin{pmatrix} \sqrt{2} & 0 \\ 0 & \frac{1}{\sqrt{2}} \end{pmatrix}$ .

2. There is a non-proper action of  $BS(1, 2)$  on  $T$ , where  $T$  is the corresponding Bass-Serre tree of degree 3:  $BS(1, 2)$  can be written as a HNN-extension:

$$BS(1, 2) = \langle a, t : tat^{-1} = a^2 \rangle = \langle a \rangle_{a \sim a^2}.$$

But the induced action  $BS(1, 2) \curvearrowright \mathbb{H}^2 \times T$  is proper.

we asked this question:

**Question 1.3.** If  $G$  can act on two hyperbolic spaces  $X, Y$  isometrically and coboundedly (and non-properly), which induce a proper action of  $G$  on  $X \times Y$  with  $\ell^1$ -norm, what can we say about  $H_b^2(G; \mathbb{R})$ ?

## 2 Preliminaries

In this section, we collect some definitions and facts on hyperbolic spaces and groups acting on them. See [3] as general reference.

If any two points in  $X$  are joined by a geodesic, then we say  $X$  is *geodesic*. For  $\delta \geq 0$ , if any side of a triangle is contained in the  $\delta$ -neighborhood of the union of the other two sides, then the triangle is called  $\delta$ -thin. If every geodesic triangle in  $X$  is  $\delta$ -thin, we say that  $X$  is  $\delta$ -hyperbolic. A *Gromov-hyperbolic space* is a space which is  $\delta$ -hyperbolic for some  $\delta \geq 0$ .

**Definition 2.1.** Let  $\alpha$  be a path in a geodesic space  $X$ . If we have, for some  $K$  and  $\varepsilon$ ,

$$\frac{|t - s|}{K} - \varepsilon \leq d(\alpha(t), \alpha(s))$$

for all  $t$  and  $s$ , then  $\alpha$  is called a  $(K, \varepsilon)$ -quasi-geodesic.

Now we recall the definition of the boundary of a hyperbolic space. Let  $X$  be a Gromov-hyperbolic space. Take a base point  $x_0 \in X$ . Given  $x, y \in X$ , we define the *Gromov product*

$$(x \cdot y) := \frac{1}{2} (d(x_0, x) + d(x_0, y) - d(x, y)).$$

A sequence  $(x_i)_i$  of points in  $X$  is called *convergent at infinity* if

$$\lim_{i, j \rightarrow \infty} (x_i \cdot x_j) = \infty.$$

We define a relation denoted by “ $\sim$ ” on the set of sequences which are convergent at infinity by

$$(x_i) \sim (y_j) \Leftrightarrow \lim_{i, j \rightarrow \infty} (x_i \cdot y_j) = \infty.$$

This relation is an equivalence relation if  $X$  is Gromov-hyperbolic. The *boundary*  $\partial X$  is the set of the equivalence classes of sequences in  $X$  which are convergent at infinity. If  $(x_i)_i$  is in a class  $a \in \partial X$ , we write  $\lim_i x_i = a$ . Let  $\alpha$  be a quasi-geodesic. Then the sequence  $(\alpha(i))_i$  and  $(\alpha(-i))_i$  are convergent at infinity. We write

$$\alpha(\pm\infty) := \lim_{i \rightarrow \pm\infty} \alpha(i).$$

Suppose a group  $G$  acts on  $X$  isometrically. Then  $G$  acts on  $\partial X$  by  $g \cdot (x_i) = (g \cdot x_i)$ . The *limit set*  $L(G) \subset \partial X$  of the action is defined by

$$L(G) = \{[(x_i)_i] \in \partial X : x_i = g_i \cdot x_0, g_i \in G, 1 \leq i < \infty\}.$$

It is well-known that the number of the points in  $L(G)$  is 0, 1, 2 or  $\infty$ .

**Definition 2.2.** Suppose  $G$  acts on  $X$  and  $x_0 \in X$ . Let  $g \in G$ . If  $\{g^i \cdot x_0\}_{i \in \mathbb{Z}}$  is quasi-isometric to  $\mathbb{Z}$  with its standard word metric, then  $g$  is called a *hyperbolic isometry (element)*.

**Definition 2.3.** Suppose  $g \in G$  is a hyperbolic isometry of a Gromov-hyperbolic space  $X$ . Let  $x_0 \in X$ . We define  $g^{\pm\infty} \in \partial X$  by

$$g^{\pm\infty} := \lim_{i \rightarrow \pm\infty} g^i \cdot x_0.$$

Note that the result does not depend on the choice of  $x_0$ .

### 3 Discussion

We can consider the classification of unbounded isometric actions on Gromov Hyperbolic spaces [3]:

1. horocyclic (parabolic): if there is no hyperbolic elements;
2. lineal: if all hyperbolic elements have the same fixed points;
3. focal (quasi-parabolic): if all hyperbolic elements have exactly one common fixed point;
4. of general type: if there are two independent hyperbolic elements,

where independent hyperbolic elements  $g_1, g_2$  means that  $g_1^{+\infty} \neq g_2^{\pm\infty}$  and  $g_1^{-\infty} \neq g_2^{\pm\infty}$ .

It's well-known that any group has a horocyclic action on a Gromov-hyperbolic space. So the first case is trivial. That's why we suppose that  $G \curvearrowright X, Y$  are cobounded.

We found that, in [1], the conditions “ $|L(G)| \geq 3$ ” and “proper action” are only used to prove that there are two independent hyperbolic elements  $g_1, g_2 \in G$ . So in our setting, we have

**Theorem 3.1.** Suppose  $G$  acts on two hyperbolic spaces  $X, Y$  isometrically and coboundedly, which induce a proper action of  $G$  on  $X \times Y$  with  $\ell^1$ -norm. If one of the action  $G \curvearrowright X, Y$  is of general type, then  $H_b^2(G; \mathbb{R})$  has infinite dimension.

For Question 1.3, there are three cases left:

1. two actions  $G \curvearrowright X, Y$  are both lineal;
2. one of the action  $G \curvearrowright X, Y$  is lineal and the other is focal;
3. two actions  $G \curvearrowright X, Y$  are both focal.

**Theorem 3.2.** If the two actions  $G \curvearrowright X, Y$  are both lineal, then  $G$  is virtually abelian. Therefore, the second bounded cohomology of  $G$  vanishes.

*Proof.* Consider a subgroup with index 2, we can assume that the two lineal actions are orientable. Then all the commutators of  $G$  act on  $X$  and  $Y$  uniformly boundedly hence on  $X \times Y$ . And because the action on  $X \times Y$  is proper,  $G$  must have only finite commutators. Therefore,  $G$  is virtually abelian. In fact,  $G$  must be isometric to trivial group,  $\mathbb{Z}$  or  $\mathbb{Z}^2$ .  $\square$

The goal is to classify the groups satisfying Case (2) and Case (3).

**Example 3.3.** In Example 1.2, the two actions are both focal. And because  $BS(1, 2) = \mathbb{Z} \begin{bmatrix} 1 \\ 2 \end{bmatrix} \rtimes \mathbb{Z}$  is solvable hence amenable,  $H_b^2(BS(1, 2), \mathbb{R}) = 0$ . This gives an example of Case (3).

### References

- [1] Koji Fujiwara. The second bounded cohomology of a group acting on a Gromov-hyperbolic space. *Proc. London Math. Soc. (3)*, 76(1):70–94, 1998.
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- [3] M. Gromov. Hyperbolic groups. In *Essays in group theory*, volume 8 of *Math. Sci. Res. Inst. Publ.*, pages 75–263. Springer, New York, 1987.