

BEAUTIFUL TITLE, ENGLISH

VÄLDIGT FIN TITEL

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Abstract

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1 Introduction

1.1 Motivation

1.2 Aim

1.3 Research Questions

This work explicitly answers the following questions:

- 1.
2. What methods can be used to detect anomalies in a dynamic real-time system?
3. How can the need for maintenance be detected from real-time processing of domain-specific data?
4. How can Predictive Maintenance be achieved by processing real-time domain-specific data?
5. How many days in advance can maintenance be predicted?
6. How can Predictive Maintenance be evaluated and compared to Corrective Maintenance?
7. How can faults be identified and isolated using Predictive Maintenance?
8. What data is required to realise fault identification and fault isolation in Predictive Maintenance?

1.4 Delimitations

The data available is from an existing IoT application mainly used to control units. The available sensors in the application can not be changed and additional sensors can not be added.



2 Theory



3 Data

This chapter describes the spatiotemporal dataset used in the thesis project. The data provider is briefly mentioned, followed by the structure of the data. This chapter also mentions issues encountered in the data set.

3.1 Background

The dataset was provided by Östgötatrafiken AB and contains GB of data. Östgötatrafiken AB is owned by Östergötland County and is responsible for the public transportation in the county. This thesis project only analysed the bus data available in the given data set. The dataset is a collection of documents, where one document represents a full day of data. A typical day has a document size of around GB.

300?

2.5?

Data Gathering

The process of gathering the data used in this thesis project can be generally described by the following simplified procedure:

1. Each Östgötatrafiken AB bus is running a system collecting data from sensors installed inside the bus.
2. The system collects the sensor data and transmits it to a central server or database.
3. A log containing all events for a full day is created and stored as a document in a collection.
4. The central server processes and analyses the data. The results from the data analysis is stored in the log.

Figure 3.1 illustrates the procedure. The collection of logs is the dataset used in this thesis project. The logs contain the GPS data from the buses and also events created by the "Internal Analysis" component in the system. The "Internal Analysis" component is simplified and is beyond the scope of this thesis project.

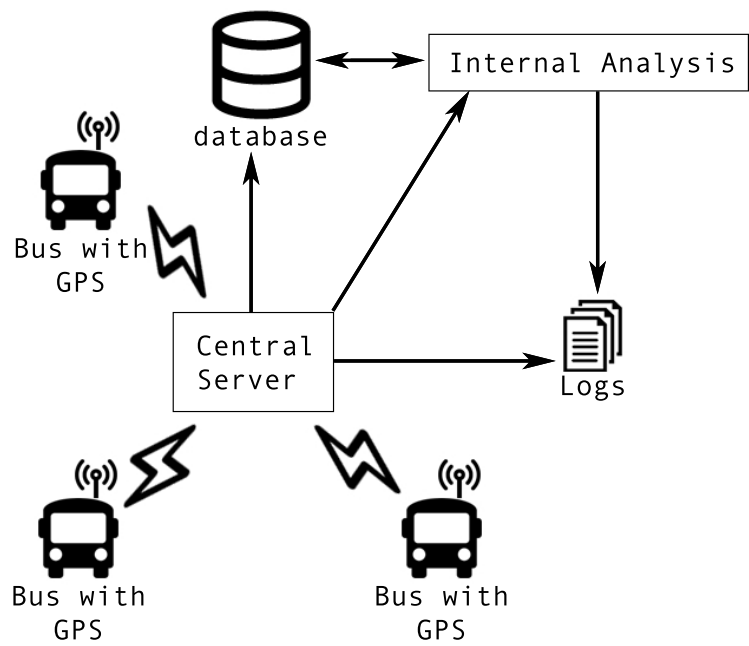


Figure 3.1: Simplified graph illustrating the data gathering process. Each bus is equipped with a GPS sensor and transmits its position to a central server/database. The dataset used in this thesis project is the log, which is a collection of documents. Each document contains the GPS data sent from all buses during a single day, together with data from the "Internal Analysis" component of the server.

3.2 Structure

A document in the dataset is made up of a large number of events representing a single day. A single day typically contains roughly 21 million events. Each event is represented by a single line of text. An event can be split into two groups: a header and a body. There are different types of events reported during the span of a single day. Each type has its own header and body structure.

Is it interesting to plot this exact number and its variance?

Event Example

		timestamp	event type	event id		
Header		2018-02-16T11:53:56.000000+01:00 2	ObservedPositionEvent	2623877798	Normal	
Body			vehicle id	GPS		
			0.1 Bus otraf.se 9031005990005485 5485	58.4233551025391,15.5914640426636		
				direction	speed	
				58.4233551025391,15.5914640426636 168.899993896484 0	5482445	

Figure 3.2: Example of a raw ObservedPositionEvent entry. The header and the body is separated by |||. Each parameter in the header and body is separated by a single |. Key parameters for the ObservedPositionEvent event type is highlighted.

Figure 3.2 illustrates an event with the event type ObservedPositionEvent. The header is defined as all the parameters before the ||| separator. All the parameters after

the separator is defined as the body of the event. In this example the header and body contain seven key parameters:

- *Timestamp*: A timestamp (2018-02-16T11:53:56.0000000+01:00), which is the timestamp from the system running on the bus.
- *Event Type*: The event type (ObservedPositionEvent).
- *Event ID*: The event id (2623877798). This is a number set by the system responsible for collecting the data from all buses. It is incremented for every event added to the log by either the database system or the "Internal Analysis" component in Figure 3.1.
- *Vehicle ID*: Unique ID for the bus transmitting its position.
- *GPS*: The GPS position of the bus in latitude and longitude.
- *Direction*: The direction of the bus.
- *Speed*: The current speed of the bus.

Event Types

The dataset contains 20 unique event types. Figure 3.3 visualises the distribution of event types for a random day in the dataset. The figure only gives an indication of what the true distribution could be, as it is computationally expensive to calculate the true distribution for the given dataset, due to its size. Knowledge about the true distribution is not required in order to reason about the event types. As the figure shows, the majority of events that occur are of the type ObservedPositionEvent, which is the event containing an updated GPS position for a vehicle.

Should we do a boxplot instead of the whole dataset? Will take a lot of time to create!

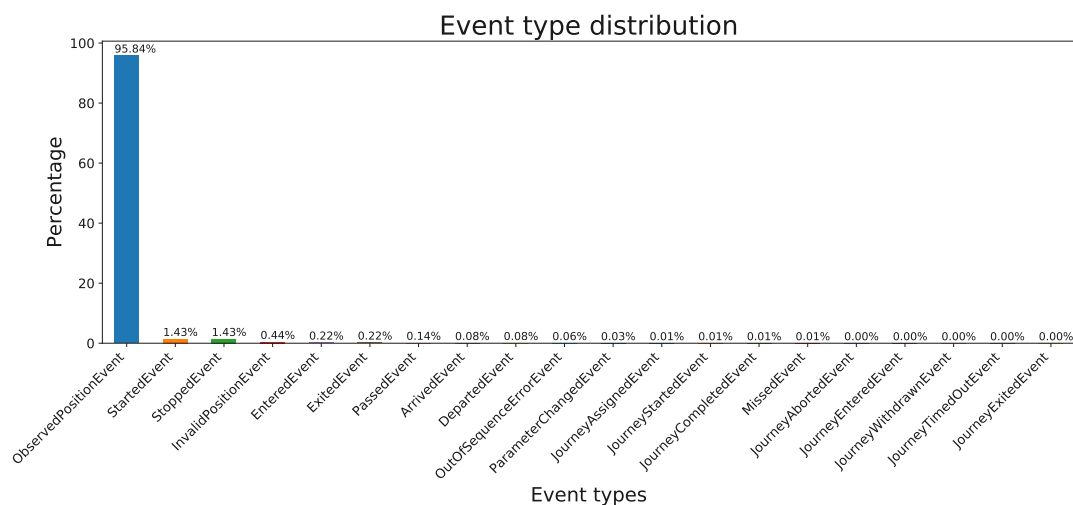


Figure 3.3: The distribution of event types for a random day in the dataset.

Of the 20 event types available in the dataset, this thesis project only used 11 of them. The events to use were chosen by analysing the log for a single day in great detail. Event types which occurred rarely and seemingly random were discarded, as no pattern could be determined for them. The InvalidPositionEvent type only contains the GPS position of the vehicle. The valid ObservedPositionEvent type also contains the Speed and Direction parameters. The GPS position of the InvalidPositionEvent events were always the same coordinates. In this thesis project the InvalidPositionEvent type was discarded, due to the missing parameters and static GPS position.

The 11 event types used in this thesis project were:

- *ObservedPositionEvent*:
- *StartedEvent*:
- *StoppedEvent*:
- *InvalidPositionEvent*:
- *ExitedEvent*:
- *EnteredEvent*:
- *PassedEvent*:
- *DepartedEvent*:
- *ArrivedEvent*:
- *ParameterChangedEvent*:
- *JourneyStartedEvent*:
- *JourneyAssignedEvent*:



4 Experiments



5 Discussion



6 Conclusion