# Update

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## Outline

Algorithms

Performance evaluation

# Algorithms

- ► Split the problem in two stages:
  - 1. Find maximal disks at each timestamp (MaximalFinder) and
  - 2. Join maximal disks between adjancent timestamps (FlockFinder)
- ► Pseudocode for both algorithms available online: MaximalFinder<sup>1</sup> and FlockFinder<sup>2</sup>.



<sup>1</sup>https://tinyurl.com/y741ld5k

<sup>&</sup>lt;sup>2</sup>https://tinyurl.com/yac26guf

# Maximal finder overall steps

- 1. Indexing points...
- 2. Getting pairs...
- 3. Computing centers...
- 4. Indexing centers...
- 5. Getting disks...
- 6. Filtering disks  $< \mu$ ...
- 7. Prunning duplicate candidates...
- 8. Indexing candidates...
- 9. Getting expansions...
- 10. Finding maximal disks.

### Flock finder

- 1. Set of disks for  $t_i$ ...
- 2. Set of disks for  $t_{i+\delta}$ ...
- 3. Joining timestams...
- 4. Checking internal timestamps.

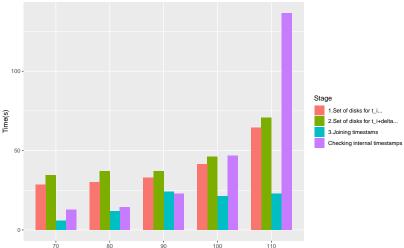
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# Performance

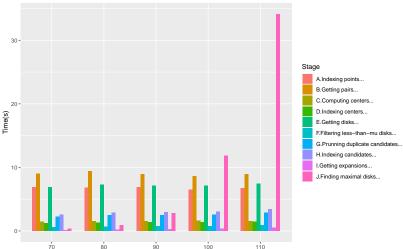




ε(mts)

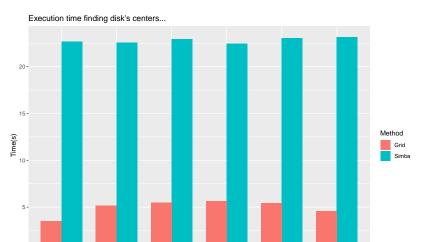
# Performance





ε(mts)

# Performance



70

80

0 -

ε(mts)

100

110

90

120

### Bottlenecks

#### 1. In flock finder:

▶ Checking internal timestamps: When merge last approach prunes enough points it works as expected but large amount of intermediate points have huge impact.

#### 2. In maximal finder:

Finding maximal disks: Even the new implementation is more stable, the most costly operation is removing duplicates and redundant disks.

#### 3. Overall:

- ▶ Online approach requires indexing at each timestamp.
- Simba indexing is slow.

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- 1. Explore alternatives in Simba<sup>3</sup>
  - ► There are QuadTree and KDTree partitioners but they are not fully-integrated as indeces. (QuadTree only support 2D.)
  - For partitioning, RTree is already faster than QuadTree and KDTree in 2D and 3D datasets.
- 2. Grid indexing
  - ► Include the Grid partitioner in Simba and work on its index integration.
  - ► Implement distance join by my own.