Flock record

Flock(items, start, end, center):

- items: Set[Int]. Set of point identifiers.
- start: Int. Time instant when the flock starts.
- end: Int. Time instant when the flock finishes.
- center: Point. Geometric representation of the center of the flock.

Pseudo-code

Algorithm 1 Reporting current flocks

Require: Set of previous flocks \mathcal{F}' , Set of current maximal disks \mathcal{D} , a maximal distance a flock can travel between time intervals θ , minimum distance between points in a flock ε , minimum flock size μ and minimum flock duration δ .

```
1: \mathcal{R} \leftarrow apply DISTANCEJOIN operation between \mathcal{F}' and \mathcal{D} using \theta as distance constraint.
                                                                                                                                      ▶ Joining phase
 2: \mathcal{F}' \leftarrow \emptyset
 3: for each r:(disk, intersected\_flocks) in \mathcal{R} do
         new\_flocks \leftarrow \emptyset
 4:
         flock1 \leftarrow convert \ disk \ into \ a \ flock
                                                                                         > start and end become the current time instant.
 5:
         for each flock2 in intersected_flocks do
 6:
              i \leftarrow flock1.items \cap flock2.items
 7:
 8:
              s \leftarrow flock2.start
              e \leftarrow flock1.end
 9:
              c \leftarrow flock1.center
10:
              if i.size >= \mu then
11:
                   new\_flocks \leftarrow new\_flocks \cup Flock(i, s, e, c)
12:
              end if
13:
         end for
14:
         subsets \leftarrow \emptyset
15:
         for each f_1 in new\_flocks do
16:
              for each f_2 in new\_flocks do
17:
                  if f_1.items.size < f_2.items.size then
18:
                       if f_1.items is subset of f_2.items and f_1.start >= f_2.start then
19:
                            subsets \leftarrow subsets \cup f_1
20:
                       end if
21:
                   end if
22:
              end for
23:
         end for
24:
         \mathcal{F}' \leftarrow \mathcal{F}' \cup (new\_flocks - subsets)
25:
26: end for
27: \mathcal{F}_{\delta} \leftarrow \emptyset
                                                                                                                                  ▶ Reporting phase
28: for each flock in \mathcal{F}' do
         if flock.end - flock.start + 1 = \delta then
29:
              \mathcal{F}_{\delta} \leftarrow \mathcal{F}_{\delta} \cup flock
30:
         end if
31:
32: end for
33: \mathcal{F}_{\delta} \leftarrow \text{REMOVEPOSSIBLEREDUNDANTS}(\mathcal{F}_{\delta}, \epsilon)
34: Report flocks in \mathcal{F}_{\delta}
```

Algorithm 2 REMOVEPOSSIBLEREDUNDANTS function

```
Require: Set of flocks \mathcal{F} and a minimum distance \varepsilon.
 1: function REMOVEPOSSIBLEREDUNDANTS (\mathcal{F}, \varepsilon)
        \mathcal{R} \leftarrow apply Self-distanceJoin operation on \mathcal{F} using \varepsilon as distance constraint.
         subsets \leftarrow \emptyset
 3:
 4:
        for each r:(flock,intersected\_flocks) in \mathcal{R} do
             {\bf for\ each}\ \ flock 2\ {\rm in}\ intersected\_flock s\ \ {\bf do}
 5:
                 if flock.size < flock2.size then
 6:
                     if flock.items is subset of flock2.items then
 7:
                         subsets \leftarrow subsets \cup flock
 8:
                     end if
 9:
10:
                 end if
             end for
11:
        end for
12:
        return (\mathcal{F} - subsets)
14: end function
```