# XIATAO SUN

#### **EDUCATION**

University of Pennsylvania

Aug. 2021 - May 2023

M.S. in Robotics GPA: 3.90/4.0

Rensselaer Polytechnic Institute

Aug. 2017 - May 2021

B.S. in Mechanical Engineering

GPA 3.93/4.0

Honor: Summa Cum Laude, Dean's Honor List, Member of Tau Beta Pi

#### RESEARCH & INTERNSHIP EXPERIENCE

### mLAB(Real-Time and Embedded Systems Lab)

Research Assistant

Nov. 2021 - Present Philadelphia, PA

- · Built autonomous driving simulation in VR and MR using Unreal Engine4 and Python based on CARLA and OpenXR framework
- · Developed real-time data transmission between server and client for steering wheel position calibration using Python Flask as the REST API and Unreal VaRest plugin for accessing the API
- · Achieved high-fidelity graphics with optimized collision detection using a detailed mesh rendering for VR perspective and mesh with reduced polygons as a collider
- · Currently developing a Unity autonomous driving simulator from scratch for Mixed Reality application

# Qingdao Tian Yi Data Tech Co., Ltd.

Co-Founder, CTO

 ${\rm May}~2021$  - Present

 $Qingdao,\ China$ 

- · Led the technological development of a healthcare platform
- · Designed and planned the overall software architecture and the roadmap
- · Developed the entire demo of the platform using Python, MySQL, HTML, Bootstrap, JavaScript, jQuery, and other relevant back-end and front-end technologies from scratch
- · Deployed the application on AWS using CentOS for operating system, uWSGI for multithreading and web server gateway interface, and GoDaddy for DNS hosting
- · Managed the development team and assessed employees performance

#### CeMSIM (Center for Modeling, Simulation, & Imaging in Medicine)

 $Under graduate\ Student\ Researcher$ 

Jun. 2020 - Dec. 2020 Troy, NY

- · Developed the entire simulation environment, fixed errors in models, and tuned the graphics via High-Definition Rendering
- Pipeline

  Based on XR Plug-in Framework, developed most player interaction mechanics and a variety of locomotion system inte-
- grated together, including continuous movement, snap turn, and teleportation
- · Developed AI agents in Unity Machine Learning platform based on PPO (proximal policy optimization) for a push block task

#### School of Engineering at Rensselaer Polytechnic Institute

AR/VR Developer

Jan. 2020 - May 2020

Troy, NY

- · Built a VR environment of MILL (Manufacturing Innovation Learning Laboratory) and synchronized it with the actual MILL lab, using Unreal Engine 4, Blueprint and Maya
- · Developed a continuous locomotion with dynamic collision detection, automatic height adjustment, and auto-alignment between player model and outside collider

#### Department of MANE at Rensselaer Polytechnic Institute

May 2019 - May 2020

Course Development Assistant

Troy, NY

- · Built a virtual environment as graphical user interface for students in Propulsion Systems course, using Unity3D, Blender and C#
- · Employed MATLAB to get curve fit of thermal dynamics system to fit into C# code in Unity program
- · Developed the entire simulation program from scratch, responsible for designing and constructing environment, postprocessing, and visual effects, as well as programming for interaction mechanics based on SteamVR Plugin in Unity
- · Helped on finding the curve fit for the underlying thermodynamic model that governed the simulation by using MATLAB

# Department of Chemical Engineering at Rensselaer Polytechnic Institute VR Developer

May 2019 - May 2020 *Troy*, NY

- · Developed a virtual reality lab for students' practice in process control and thermodynamics, using Unity3D and C# for game logic and Blender for 3D modeling
- · Transformed the original flat screen simulation into virtual reality, developed VR interaction mechanics and teleportation locomotion system in this project based on SteamVR Plugin in Unity
- · Worked on graphics enhancement and 3D modeling for a variety of objects, such as heat exchanger and water tank

# Liandessen Electrical Institution and Technology Co., Ltd.

Sep. 2019 - Dec. 2019

Mechanical Engineer Intern

Qingdao, China

- · Selected and arranged modes in an appropriate way, analyzed structure of parts to identify whether they had undercut or not, and examined the types of sidestep
- · Determined the cooling method and pipe arrangement, and clarified the quantity and position of inserts
- · Utilized CAD to draw and verify part diagram

# Rensselaer Artificial Intelligence and Reasoning Lab

Sep. 2018 - Dec. 2018

 $Undergraduate\ Student\ Researcher$ 

Troy, NY

· Researched on the logical differences between eastern and western culture, assisted in building prototyping NLP translating programs, such as word parser, with the help of logical translation by using Python

#### Goertek Electronics

Jun. 2018 – Jul. 2018

Embedded System Developer Intern

Qingdao, China

· Tested and debugged the prototype of OPPO O-Free, a truly wireless earbud, using SDK from Snapdragon and GAIA

#### KNOWLEDGE & TECHINCAL SKILLS

Knowledge

Control, Path Planning, Filter, XR Development, Machine Learning,
Data Analytics, Web Development, Embedded System Development

Programming Languages C, C++, C#, Python, MATLAB, SQL, HTML, JavaScript

Web Development Tools Flask, SQLAlchemy, Vue.js, jQuery CAD Software NX Unigraphics, SpaceClaim

**3D Modeling Software** Blender, Maya, ZBrush, Marvelous Designer, Substance Painter

Game Engines Unity, Unreal Engine 4

Data Analytics Tools

Jupyter Notebook, Pandas, Matplotlib, Seaborn, PySpark

Machine Learning Frameworks

PyTorch, MXNet, Unity ML-Agents, Tensorflow, Spark ML

Language Mandarin, English

Other Technical Skills Docker, LaTeX, LabVIEW, Lathe, Vertical Drill, Welding, FL Studio, Piano

#### **COURSEWORKS**

MEAM520 Introduction to Robotics
MEAM620 Advanced Robotics
ESE650 Learning in Robotics
CIS545 Big Data Analytics

**EAS545** Engineering Entrepreneurship I