

File: C:\Users\M4rc05\Documents\Vex\Starstruck\2223-G\3-29-2017\PID test.c

```
#pragma config(Sensor, dgtl1,  RightEncoder,  sensorQuadEncoder)
#pragma config(Sensor, dgtl3,  LeftEncoder,  sensorQuadEncoder)
#pragma config(Motor,  port1,          LeftMotor,      tmotorVex393 HBridge, openLoop, encoderPort, dgtl3)
#pragma config(Motor,  port10,         RightMotor,     tmotorVex393_HBridge, openLoop, reversed, encoderPort, dgtl1)
/*!!Code automatically generated by 'ROBOTC' configuration wizard    !!*/

task main(){
    while(1==1){
        motor[port1] = 127;
        motor[port10] = 127;
    }
}
```

