File: C:\Users\M4rc05\Documents\Vex\Starstruck\2223-G\3-28-2007\EncoderValues.c #pragma config(Sensor, dgtl1, LeftQuadEncoder1, sensorQuadEncoder) #pragma config(Sensor, dgtl3, RightQuadEncoder1, sensorQuadEncoder) //*!!Code automatically generated by 'ROBOTC' configuration wizard !!*// task main() { while(1==1) { writeDebugStreamLine("Left Encoder: %i. \t Right Encoder: %i.", SensorValue[LeftQuadEncoder1], SensorValue[RightQuadEncoder1]); wait1Msec(100); } }