

# Chapter 0: Banach Spaces

## Introduction

This section is quite incomplete, and all over the place. I have been meaning to put all the notation/terminology I am going to use in this section. Please skip to the Chapter 1 for now.

## Banach Spaces

A *Banach space* is a normed vector space that is Cauchy-complete under the usual metric induced by its norm.

If  $E$  and  $F$  are Banach spaces over  $\mathbb{R}$ . We will denote the norms on  $E$ , and  $F$  by single lines, so

$$|x| = \|x\|_E \quad \text{and} \quad |y| = \|y\|_F \quad \forall x \in E, y \in F$$

$\mathcal{L}(E, F)$  will denote the space of linear maps between  $E$  and  $F$ . In the category of Banach spaces, the space of morphisms are called *toplinear morphisms* - or *CLMs* (*continuous linear maps*); which we will denote by  $L(E, F)$  for toplinear morphisms between  $E$  and  $F$ .

We use  $\|\cdot\|_{L(E, F)}$  or  $\|\cdot\|$  to denote the operator norm, depending on how much emphasis we wish to place on  $L(E, F)$ . Recall,

$$\begin{aligned} \|\varphi\|_{L(E, F)} &= \inf \left\{ A \geq 0, |\varphi(x)| \leq A|x| \forall x \in E \right\} \\ &= \sup \left\{ |\varphi(x)|, x \in E, |x| = 1 \right\} \end{aligned}$$

By the open mapping theorem: any continuous surjective linear map is an open map. Hence invertible elements in  $L(E, F)$  are naturally called *toplinear isomorphisms*. If  $\varphi \in L(E, F)$  such that  $\varphi$  preserves the norm between the Banach Spaces, that is for every  $x \in E$ ,  $|x| = |\varphi(x)|$  then we call  $\varphi$  an *isometry*, or a *Banach space isomorphism*. If  $E_1$  and  $E_2$  are Banach spaces, we will use the usual *product norm*  $(x_1, x_2) \mapsto \max(|x_1|, |x_2|)$ .

- We say a map  $F$  is *between* the spaces  $X$  and  $Y$  if  $F : X \rightarrow Y$ .
- $\mathcal{L}(V^k, W)$  denotes the space of  $k$ -linear maps from  $V$  to  $W$  that are not necessarily continuous.

### Proposition 2.1: Hahn Banach Theorem (Geometric Form)

Let  $E$  be a Banach space,  $A$  and  $B$  are closed disjoint subsets of  $E$ . Assuming one of the two is compact, then there exists a  $\text{clf } \lambda$  which *strictly separates*  $A$  and  $B$ .

$$A \subseteq [\lambda \leq \alpha - \varepsilon] \quad \text{and} \quad B \subseteq [\lambda \geq \alpha + \varepsilon] \tag{1}$$

for  $\alpha \in \mathbb{R}$  and  $\varepsilon > 0$ .

### Definition 2.1: Product of Banach Spaces

Let  $E_1, \dots, E_k$  be Banach spaces over  $\mathbb{R}$ . The Cartesian product of  $(E_1, \dots, E_k)$  is denoted by  $\prod_i^k E_i$ .

It is again a Banach space with the norm

$$(x_1, \dots, x_k) \mapsto |(x_1, \dots, x_k)| = \sup_{1 \leq i \leq k} |x_i| \quad (2)$$

## Vector Spaces

Let  $V$  be any vector space over  $\mathbb{R}$  or  $\mathbb{C}$ , and  $\{v_\alpha\} \subseteq V$ , the symbol  $\sum^\wedge v_\alpha$  refers to a partially specified object which is any **finite** linear combination of the elements of  $\{v_\alpha\}$ . If the cardinality of  $\{v_\alpha\}$  is finite,

$$\sum^\wedge v_\alpha = \sum^\wedge v_{\underline{k}} \text{ for some } k \geq 1. \quad (3)$$

where eq. (3) should be interpreted as eq. (4)

$$\sum^\wedge v_{\underline{k}} = \sum_{i=\underline{k}} c^i v_i \quad (4)$$

for some  $c^i \in \mathbb{R}$  or  $\mathbb{C}$  where  $i = \underline{k}$ .

Composition of maps: If  $f : E \rightarrow F$  and  $g : F \rightarrow G$  are maps between Banach spaces, we write  $gf$  to mean  $g \circ f$ .

## Enumeration of lists

We use the following notation to simplify computations concerning multilinear maps. Let  $E$  and  $F$  be sets, elements  $v_1, \dots, v_k \in E$ , and a map  $f : E \rightarrow F$ .

- Listing individual elements:  $v_{\underline{k}}$  means  $v_1, \dots, v_k$  as separate elements.
- Creating a  $k$ -list:  $(v_{\underline{k}}) = (v_1, \dots, v_k) \in \prod E_{j \leq k}$  if  $v_i \in E_i$  for  $i = \underline{k}$ .
- Double indices:  $(v_{\underline{n_k}}) = (v_{\underline{n_k}}) = (v_{n_1}, \dots, v_{n_k})$ , and

$$(v_{\underline{n_k}}) \neq (v_{n_{(1, \dots, k)}})$$

- Closest bracket convention:

$$(v_{(n_k)}) = (v_{(n_1, \dots, n_k)}) \quad \text{and} \quad (v_{n_{(k)}}) = (v_{n_{(1, \dots, k)}})$$

- Underlining 0 means it is iterated 0 times:

$$(v_{\underline{0}}, a, b, c) = (a, b, c)$$

- Skipping an index:

$$(v_{\underline{i-1}}, v_{i+\underline{k-i}}) = (v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_k)$$

for  $i = \underline{k}$ .

- Applying  $f$  to a particular index:

$$(v_{\underline{i-1}}, f(v_i), v_{i+\underline{k-i}}) = (v_1, \dots, v_{i-1}, f(v_i), v_{i+1}, \dots, v_k)$$

Of course, if  $i = 1$ , then the above expression reads  $(f(v_1), v_2, \dots, v_k)$  by the  $\underline{0}$  interpretation.

- In any list using this 'underline' notation, we can find the size of a list by summing over all the underlined terms, and the number of terms with no underline.
- If  $\wedge : E \times E \rightarrow F$  is any associative binary operation,

$$\bigcirc (v_{\underline{k}}) = v_1 \wedge \dots \wedge v_k$$

#### Remark 4.1: Preview of exterior calculus

We can write the formula for the determinant of a  $\mathbb{R}^{k \times k}$  matrix in this notation. Suppose  $a_i \in \mathbb{R}$ , and  $b_i \in \mathbb{R}^{k-1}$  for  $i = \underline{k}$ .

$$M = \begin{bmatrix} a_1 & \dots & a_k \\ | & & | \\ b_1 & \dots & b_k \\ | & & | \end{bmatrix}$$

The determinant of  $M$  is a linear combination of determinants of  $k - 1$ -sized matrices, given in terms of the columns of  $b$

$$\det(M) = \sum_{i=\underline{k}} (-1)^{i-1} a_i \det(b_{\underline{i-1}}, b_{i+\underline{k-i}})$$

# Chapter 1: Multilinear maps

## Bilinear maps

### Definition 1.1: Bilinear map

A map  $\varphi : E_1 \times E_2 \rightarrow F$ , where  $F$  is also a Banach space, is said to be *bilinear* if

$$\varphi(x, \cdot) : E_2 \rightarrow F \quad \text{and} \quad \varphi(\cdot, y) : E_1 \rightarrow F$$

are linear for every  $x \in E_1$  and  $y \in E_2$ .

### Proposition 1.1: Continuity criterion of a bilinear map

Let  $E_1, E_2, F$  be Banach spaces, a bilinear map  $m : E_1 \times E_2 \rightarrow F$  is continuous if and only if there exists a  $C \geq 0$ , where

$$|m(x, y)| \leq C|x||y| \tag{5}$$

*Proof.* Suppose such a  $C$  exists, fix a convergent sequence  $(x_n, y_n) \rightarrow (x, y)$  in  $E_1 \times E_2 = E$ . Because the projection maps are continuous, this means  $x_n \rightarrow x$  and  $y_n \rightarrow y$ . Using inspiration from the proof where  $x_n y_n \rightarrow xy$ , where

$$x_n(y_n - y) + (x_n - x)y = x_n y_n - xy \quad x, y, x_n, y_n \in \mathbb{R}$$

Using the inspiration, and replacing multiplication in  $\mathbb{R}$  with the bilinear map  $m$ , we have:

$$\begin{aligned} m(x_n, y_n - y) + m(x_n - x, y) &= m(x_n, y_n) - m(x, y) \\ |m(x_n, y_n) - m(x, y)| &\leq C[|x_n| \cdot |y_n - y| + |x_n - x| \cdot |y|] \rightarrow 0 \end{aligned}$$

Conversely, if  $m$  is continuous, then it is continuous at the origin  $(0, 0) = 0$ . There exists a  $\delta$  where  $|(x, y)| \leq \delta$  implies  $|m(x, y)| \leq 1$ . Now, if  $x, y \neq 0$  are elements in  $E$ , we normalize so that  $(x, y)$  has length  $\delta$

$$|(x|x|^{-1}\delta, y|y|^{-1}\delta)| = \delta|(x|x|^{-1}, y|y|^{-1})| = \delta$$

So that  $|m(x|x|^{-1}\delta, y|y|^{-1}\delta)| \leq 1$ , using bilinearity of  $m$ :

$$|m(x, y)| \leq \delta^{-2}|x| \cdot |y|$$

Setting  $\delta^{-2} = C$  finishes the proof (notice if either  $x$  or  $y$  is 0, then  $m$  is trivially 0 and the inequality holds). ■

### Proposition 1.2: $L(E_1, E_2; F)$ is isomorphic to $L(E_1, L(E_2, F))$

For each bilinear map  $\omega \in L(E_1, E_2; F)$ , there exists a unique map  $\varphi_\omega \in L(E_1, L(E_2, F))$  such that  $|\omega| = |\varphi_\omega|$ ; such that for every  $(x, y) \in E_1 \times E_2$ ,  $\omega(x, y) = \varphi_\omega(x)(y)$ .

*Proof.* Let  $\varphi_\omega : E_1 \rightarrow L(E_2, F)$  be the unique map such that  $\varphi_\omega(x)(y) = \omega(x, y)$ . Proposition 1.1 shows that  $\varphi_\omega(x)$  is a continuous linear map into  $F$  at each  $x$ , and  $|\varphi_\omega(x)| \leq |\omega||x|$ . This holds for an arbitrary  $x$ , and  $\varphi_\omega(\cdot)$  is clearly linear, hence  $|\varphi_\omega| \leq |\omega|$ . Reversing the roles of  $\omega$  and  $\varphi$  shows proves the other

estimate.

The rule as outlined above is linear in  $\omega$ ; and it is not hard to see  $\varphi : L(E_1, E_2; F) \rightarrow L(E_1, L(E_2, F))$  is an injection. By the open mapping theorem, the proposition is proven if  $\varphi$  is a surjection. Fix  $\theta \in L(E_1, L(E_2, F))$ , define a map  $\omega : E_1 \times E_2 \rightarrow F$  such that  $\omega(x, \cdot) = \theta(x)(\cdot)$ . So that  $\omega$  is linear in its second argument. To show  $\omega$  is linear in its first: fix a linear combination  $A = \sum^\wedge x$  in  $E_1$ , and  $y \in E_2$ .

$$\omega(A, y) = \theta(\sum^\wedge x)(y) = \sum^\wedge \theta(x)(y) = \sum^\wedge \omega(x, y)$$

Continuity follows from Equation (5), and  $\varphi_\omega = \theta$  as needed. ■

## $k$ -linear maps

### Definition 2.1: $k$ -linear maps

Let  $E_{\underline{k}}, F$  be Banach spaces. A map  $\varphi : \prod E_{\underline{k}}$  is  $k$ -linear if for every  $i = \underline{k}$ ,  $v_i \in E_i$ ,

$$\varphi(\cdot \frac{i-1}{i}, v_i, \cdot \frac{k-i}{k-i}) : \bigoplus (E_{i-1}, E_{i+k-i}) \rightarrow F \text{ is } (k-1)\text{-linear}$$

A  $k$ -linear *symmetric* map between Banach spaces  $E, F$  is a map  $A \in \mathcal{L}(E^k, F)$  such that for every  $k$ -permutation  $\theta \in S_{\underline{k}}$ ,

$$A(v_{\underline{k}}) = A(v_{\theta(\underline{k})})$$

The following theorem should give confidence to the notation we have adopted to use.

### Proposition 2.1: Continuity criterion of $k$ -linear maps

Let  $E_{\underline{k}}$  and  $F$  be Banach spaces, a  $k$ -linear map  $\varphi : \prod E_{\underline{k}} \rightarrow F$  is continuous iff there exists a  $C > 0$ , such that for every  $x_i \in E_i$ ,  $i = \underline{k}$

$$|\varphi(x_{\underline{k}})| \leq C \prod |x_{\underline{k}}|$$

*Proof.* Suppose  $\varphi$  is continuous, then it is continuous at the origin. Picking  $\varepsilon = 1$  induces a  $\delta > 0$  such that for  $|(x_{\underline{k}})| \leq \delta$ ,  $|\varphi(x_{\underline{k}})| \leq 1$ . The usual trick of normalizing an arbitrary vector  $(x_{\underline{k}}) \in \prod E_{\underline{k}}$  does the job:

$$\left| \varphi(x_{\underline{k}} \cdot |x_{\underline{k}}|^{-1} \cdot \delta) \right| \leq 1 \implies |\varphi(x_{\underline{k}})| \leq \delta^{-k} \prod |x_{\underline{k}}|$$

Conversely, fix a sequence (indexed by  $n$ , in  $k$  elements in the product space  $\prod E_{\underline{k}}$ ), so

$$(x_{\underline{n}}^k) \rightarrow (x_{\underline{k}}^k) \text{ as } n \rightarrow +\infty \tag{6}$$

To proceed any further, we need to prove an important equation that decomposes a difference in  $\varphi$ .

$$\varphi(b^{\underline{k}}) - \varphi(a^{\underline{k}}) = \sum_{i=\underline{k}} \varphi(b^{\underline{i}-1}, \Delta_i, a^{\underline{i}+k-i}) \tag{7}$$

where  $(b^{\underline{k}})$  and  $(a^{\underline{k}})$  are elements in  $\prod E_{\underline{k}}$ , and  $\Delta_i = b^i - a^i$  for  $i = \underline{k}$ . The proof is in the following note, which is in more detail than usual - to help the reader ease into the new notation.

**Note 2.1**

We proceed by induction, and eq. (7) follows by setting  $m = k$  in

$$\varphi(a^{\underline{k}}) = \varphi(b^{\underline{m}}, a^{m+k-\underline{m}}) - \sum_{i=\underline{m}} \varphi(b^{i-1}, \Delta_i, a^{i+k-i}) \quad (8)$$

Base case: set  $m = 1$ , by definition of  $k$ -linearity (def. 2.1) of  $\varphi$ . Since  $a^1 = b^1 - \Delta_1$ ,

$$\varphi(a^{\underline{k}}) = \varphi(b^1 - \Delta_1, a^{1+k-1}) = \varphi(b^1, a^{1+k-1}) - \varphi(\Delta_1, a^{1+k-1})$$

Induction hypothesis: suppose eq. (8) holds for a fixed  $m$ . Since  $a^{m+1} = b^{m+1} - \Delta_{m+1}$ ,

$$\begin{aligned} \varphi(a^{\underline{k}}) &= \varphi(b^{\underline{m}}, a^{m+k-\underline{m}}) - \sum_{i=\underline{m}} \varphi(b^{i-1}, \Delta_i, a^{i+k-i}) \\ &= \varphi(b^{\underline{m}}, a^{m+1}, a^{(m+1)+k-(m+1)}) - \sum_{i=\underline{m}} \varphi(b^{i-1}, \Delta_i, a^{i+k-i}) \\ &= \varphi(b^{m+1}, a^{(m+1)+k-(m+1)}) - \varphi(b^{m+1}, \Delta_{m+1}, a^{(m+1)+k-(m+1)}) - \sum_{i=\underline{m}} \varphi(b^{i-1}, \Delta_i, a^{i+k-i}) \end{aligned}$$

and this proves eq. (7)

We substitute  $a^i = x^i$ , and  $b^i = x_n^i$  for  $i = \underline{k}$ , and eq. (7) becomes eq. (9)

$$\varphi(x_n^{\underline{k}}) - \varphi(x^{\underline{k}}) = \sum_{i=\underline{k}} \varphi(x_n^{i-1}, x_n^i - x^i, x^{i+k-i}) \quad (9)$$

Then the triangle inequality reads

$$\begin{aligned} \left| \varphi(x_n^{\underline{k}}) - \varphi(x^{\underline{k}}) \right| &\leq \sum_{i=\underline{k}} \left| \varphi(x_n^{i-1}, x_n^i - x^i, x^{i+k-i}) \right| \\ &\leq \sum_{i=\underline{k}} |\varphi| \cdot \bigoplus \left( x_n^{i-1}, \Delta_i, x^{i+k-i} \right) \\ &\leq \sum_{i=\underline{k}} |\varphi| \cdot |x_n^i - x^i| \bigoplus \left( x_n^{i-1}, x^{i+k-i} \right) \\ &\lesssim_n |\varphi| \sup_{i=\underline{k}} |x_n^i - x^i| \rightarrow 0 \end{aligned}$$

where we identify the product  $\bigoplus(v^{\underline{k}})$  with the product of their norms  $\bigoplus(|v^{\underline{k}}|)$ . ■

**Remark 2.1: Currying isomorphism**

The  $k$ -linear variant of prop. 1.2 holds. We will use but not prove this fact.

**Remark 2.2:  $k$ -linear maps from the same space**

We denote the space of  $k$ -linear maps from  $E$  into  $F$  by  $L(E_{\underline{k}}; F) = L(E^{\underline{k}}, F) = L^k(E, F)$ . *Tensors* on



$E$  are  $k$ -linear maps from the product space of  $E$  into  $\mathbb{R}$ , by replacing  $F$  with  $\mathbb{R}$ .

## Chapter 2: Differentiation

## The derivative

### Definition 1.1: Open sets and neighbourhoods

If  $U$  is an open subset of a topological space  $X$ , we denote this by  $U \subseteq X$ . If  $U$  is a *neighbourhood* of a point  $p \in X$ , we write  $p \in U$ .

We do not require neighbourhoods to be open sets; rather, we say  $U$  is a neighbourhood of  $p$  when the interior of  $U$  contains  $p$ .

### Definition 1.2: Little $o$

A real-valued function in a real variable defined for all  $t$  sufficiently small is said to be  $o(t)$  if  $\lim_{t \rightarrow 0} o(t)/t = 0$ . A map  $\psi : U \rightarrow F$  where  $U \subseteq E$  contains 0 in  $E$ , is said to be  $o(h)$  if  $|\psi(h)|/|h| \rightarrow 0$  as  $h \rightarrow 0$  in  $E$ .

### Definition 1.3: Differentiability

Let  $f : E \rightarrow F$  be a map, replacing  $E$  and  $F$  by their open subsets if necessary. We say  $f$  is *differentiable* at  $x \in E$  when there exists a **continuous linear map on  $E$** :  $\lambda \in L(E, F)$  such that

$$f(x + h) = f(x) + \lambda h + o(h) \quad \text{for sufficiently small } h \quad (10)$$

The role  $o(h)$  plays here is a map from  $U \rightarrow F$ , where  $U$  is some neighbourhood of 0.

### Proposition 1.1: Basic properties of the derivative

If  $f$  is differentiable at  $x$ , then the  $\lambda$  in eq. (10) is unique. We write  $f'(x) = Df(x) = \lambda$  as in ?? . Furthermore, if  $f'(x)$  and  $g'(x)$  exist, then  $(f + g)'(x) = f'(x) + g'(x)$  as linear maps, similar for scalar multiplication.

*Proof.* Suppose  $\lambda_i \in L(E, F)$  are both derivatives of  $f$  at  $x$ . Then,

$$\begin{cases} f(x + h) = f(x) + \lambda_1(h) + o(h) \\ f(x + h) = f(x) + \lambda_2(h) + o(h) \end{cases}$$

And  $(\lambda_1 - \lambda_2)(h) = o(h) = \varphi(h) \cdot |h|$ , where  $\varphi(h) \rightarrow 0$  as  $h \rightarrow 0$ . Using the operator norm, we see that

$$\|\lambda_1 - \lambda_2\|_{L(E, F)} \leq |\varphi(h)| \rightarrow 0$$

This proves uniqueness. Suppose  $f$  and  $g$  are differentiable at  $x$ , denote  $\lambda_f = f'(x)$  (resp.  $g'(x)$ ). The definition of def. 1.3 reads

$$\begin{aligned} f(x + h) + g(x + h) &= (f(x) + g(x)) + (\lambda_f(h) + \lambda_g(h)) + o(h) + o(h) \\ (f + g)(x + h) &= (f + g)(x) + (\lambda_f + \lambda_g)(h) + o(h) \end{aligned} \quad (11)$$

since eq. (11) satisfies eq. (10), the proof is complete. ■

**Proposition 1.2: Chain rule**

Let  $E, F, G$  be Banach spaces. If  $f \in C^1(E, F)$ ,  $g \in C^1(F, G)$ , for every  $x \in E$ ,

$$(g \circ f)'(x) = g'(f(x)) \circ f'(x) \quad (12)$$

*Proof.* Since  $f$  is differentiable at  $x$ ,  $f(x + h) = f(x) + f'(x)(h) + o_1(h)$ , (resp. for  $g$ ,  $o_2(h)$ ). Set  $k(h) = f(x + h) - f(x)$ , and

$$\begin{aligned} g(f(x + h)) &= g(f(x)) + g'(f(x))(k(h)) + o_2(k(h)) \\ &= g(f(x)) + g'(f(x))(f'(x)(h) + o_1(h)) + o_2(k(h)) \\ (g \circ f)(x + h) &= (g \circ f)(x) + g'(f(x)) \circ f'(x)(h) + g'(f(x))(o_1(h)) + o_2(k(h)) \\ (g \circ f)(x + h) &= (g \circ f)(x) + g'(f(x)) \circ f'(x)(h) + o(h) \end{aligned}$$

because  $|A(o_1(h))| \leq |A||o_1(h)|$  for all  $A \in L(E, F)$ ; and  $o(k(h)) = o(h)$  for every continuous  $k : E \rightarrow F$  such that  $k(h) \rightarrow 0$  as  $h \rightarrow 0$ . ■

**Proposition 1.3: Derivatives of CLMs**

If  $\lambda \in L(E, F)$ , then  $\lambda \in C^1(E, F)$  and  $D\lambda(x) = \lambda$  for every  $x \in E$ . Furthermore, if  $f \in C^1(E, F)$ , and  $\nu \in L(F, G)$ , then the composition  $\nu \circ f$  is in  $C^1(E, G)$ , and  $(\nu \circ f)'(x) = \nu \circ f'(x)$  for every  $x \in E$ .

*Proof.* See  $\lambda(x + h) = \lambda(x) + \lambda(h) + 0$  at every  $x \in E$ . Using the chain rule (prop. 1.2) proves the second claim. ■

**Proposition 1.4: Product rule in  $k$  variables**

Let  $m : \prod F_{\underline{k}} \rightarrow G$  be a  $k$ -linear map between Banach spaces  $F_{\underline{k}}$  and  $G$ . Suppose  $f_i \in C^1(E, F_i)$  with  $i = \underline{k}$ , writing

$$m(f_{\underline{k}})(x) = m(f_{\underline{k}}(x)) \quad (13)$$

then  $m(f_{\underline{k}})$  is in  $C^1(E, G)$  and for every  $y \in E$ ,

$$Dm(f_{\underline{k}})(x)(y) = \sum_{i=\underline{k}} m(f_{\underline{i}-1}(x), Df_i(x)(y), f_{i+\underline{k}-i}(x)) \quad (14)$$

*Proof.* Let  $x$  be fixed. Equation (14) is proven if we show eq. (15)

$$m(f_{\underline{k}})(x + h) = m(f_{\underline{k}})(x) + \left( \sum_{i=\underline{k}} m(f_{\underline{i}-1}(x), Df_i(x)(h), f_{i+\underline{k}-i}(x)) \right) + o(h) \quad (15)$$

and for sufficiently small  $h$  we have

$$f_i(x + h) - f_i(x) = Df_i(x)(h) + o(h^i) \quad (16)$$

We will use the difference formula in eq. (8), with the following substitutions

$$f_i(x + h) = b^i \quad f_i(x) = a^i \quad (17)$$

$$Df_i(x)(h) = c^i \quad o(h^i) = \varepsilon^i \quad (18)$$

$$f_i(x + h) - f_i(x) = c^i + \varepsilon^i \quad \Delta^i = o(h^i) + c^i \quad (19)$$

With these substitutions, the equation we want to prove (eq. (14)) becomes eq. (20)

$$m(b^{\underline{k}}) - m(a^{\underline{k}}) = \left( \sum_{i=\underline{k}} m(a^{i-1}, c^i, a^{i+k-i}) \right) + o(h) \quad (20)$$

Starting from eq. (8),

$$m(b^{\underline{k}}) - m(a^{\underline{k}}) = \sum_{i=\underline{k}} m(b^{i-1}, \Delta^i, a^{i+k-i})$$

We can expand each term, if  $i = \underline{k}$ ,

$$m(b^{i-1}, \Delta^i, a^{i+k-i}) = m(b^{i-1}, c^i, a^{i+k-i}) + m(b^{i-1}, o(h^i), a^{i+k-i}) \quad (21)$$

Let us study the first term in eq. (21), and with  $i$  held fixed, define

$$m_i(z^{i-1}) = m(z^{i-1}, c_i, a^{i+k-i}) \quad (22)$$

Expanding the first term within eq. (21), and because  $m_i$  as defined in eq. (22) is  $i-1$ -linear (because it is a  $k$ -linear map with  $k - (i-1)$  variables held constant); we use eq. (8) again.

$$m_i(b^{i-1}) = \left( \sum_{j=\underline{k}} m_i(b^j, \Delta^j, a^{j+(i-1)-j}) \right) + m_i(a^{i-1}) \quad (23)$$

Unboxing the last term in eq. (23) using the definition of  $m_i$  reads

$$m(b^{i-1}, \Delta^i, a^{i+k-i}) = m(a^{i-1}, c^i, a^{i+k-i}) + \sum_{j=i-1} m_i(b^j, \Delta^j, a^{j+(i-1)-j}) \quad (24)$$

We wish to remove all of the  $b^i$ s. Since  $\Delta^i = c^i + \varepsilon^i$  (eq. (19)), we have

$$\begin{aligned} m(b^{\underline{k}}) - m(a^{\underline{k}}) &= \sum_{i=\underline{k}} m(b^{i-1}, c^i, a^{i+k-i}) + m(b^{i-1}, \varepsilon^i, a^{i+k-i}) \\ &= \left( \sum_{i=\underline{k}} m_i(b^{i-1}) \right) + \sum_{i=\underline{k}} m(b^{i-1}, \varepsilon^i, a^{i+k-i}) \\ &= \left( \sum_{i=\underline{k}} m_i(a^{i-1}) + \sum_{j=i-1} m_i(b^{j-1}, \Delta^j, a^{j+(i-1)-j}) \right) + \sum_{i=\underline{k}} m(b^{i-1}, \varepsilon^i, a^{i+k-i}) \\ &= \left( \sum_{i=\underline{k}} m_i(a^{i-1}) \right) + \sum_{\substack{i=\underline{k} \\ j=i-1}} m_i(b^{j-1}, \Delta^j, a^{j+(i-1)-j}) + \sum_{i=\underline{k}} m(b^{i-1}, \varepsilon^i, a^{i+k-i}) \end{aligned} \quad (25)$$

The last term within eq. (25) is  $o(h)$ , since it is a linear combination of  $o(h^i)$ s.

$$\left| \sum_{i=\underline{k}} m(b^{i-1}, \varepsilon^i, a^{i+k-i}) \right| \lesssim_{m,a,b} |o(h)| \quad (26)$$

Each summand in the second last term in eq. (25) is  $o(h)$  as well, as

$$\begin{aligned}
 |m_i(b^{j-1}, \Delta^j, a^{j+(i-1)-j})| &\leq |m_i| \left( \prod (b^{j-1}, \Delta^j, a^{j+(i-1)-j}) \right) \\
 &\leq |m| \cdot \left( \prod (c^i, a^{i+k-i}) \right) \left( \prod (b^{j-1}, \Delta^j, a^{j+(i-1)-j}) \right) \\
 &\lesssim_{m,a,b} \sup_{\substack{i=k \\ j=i-1}} |c^i| \cdot |\Delta^j| \\
 &\lesssim_{m,a,b} \sup_{\substack{i=k \\ j=i-1}} |Df_i(x)(h)| \cdot |f_j(x+h) - f_j(x)| \\
 &\lesssim_{m,a,b} |Df_i(x)||h| \sup_{\substack{i=k \\ j=i-1}} |\Delta^j| \\
 &\lesssim_{m,a,b} |o(h)|
 \end{aligned} \tag{27}$$

for the second last estimate we used  $\Delta^j \rightarrow 0$ . Therefore the second term in eq. (25) is  $o(h)$ , and eq. (15) is proven. Therefore  $m(f_k)$  is differentiable at  $x$ . Continuity of  $Dm(f_k)$  follows from the fact that

$$Dm(f_k)(x) = \sum_{i=k} m(f_{i-1}(x), Df_i(x)(\cdot), f_{i+k-i}(x)) \tag{28}$$

and each of the summands eq. (28) can be broken down as the product of the compositions shown in eqs. (29) and (30)

$$x \mapsto (f_{i-1}(x), f_{i+k-i}(x)) \mapsto m(f_{i-1}(x), \cdot, f_{i+k-i}(x)) \tag{29}$$

$$x \mapsto Df_i(x)(\cdot) \tag{30}$$

which are continuous from  $E$  to  $L(E, F)$ . ■

## Chapter 3: Integration

## Introduction

This chapter will be on the integration of *regulated* mappings, the space of which are precisely the uniform closure of rectangle functions. from a compact interval. We will go through some of the elementary results, and prove the Fundamental Theorem.

## Integration of step mappings

### Definition 2.1: Partition on $[a, b]$

Let  $I = [a, b]$  be a compact interval. An  $N$ -partition  $P$  on  $I$  is a list of  $N + 1$  elements in  $[a, b]$ , which are assumed to be well ordered as in  $p_0 \leq p_1 \leq \dots \leq p_N$ .

$$P = (a = p_0, p_1, \dots, p_N = b) \quad \text{or} \quad P = (p_0, \underline{p_N}) \quad (31)$$

The space of partitions on  $I$  will be denoted by  $I_p$ .

As per usual, we have *common refinements of partitions*, given two partitions  $P$  and  $Q$  on the same compact interval  $I = [a, b]$ , where  $P$  is defined as in eq. (31), and  $Q = (q_0, \underline{q_N})$  similarly. The common refinement of  $P$  and  $Q$  is another partition  $R$  on  $I$  which contains all of the elements in  $P \cup Q$ .

- Given a partition  $P$  of size  $N$  represented as  $P = (p_0, \underline{p_N})$ , the cells of  $P$  are indexed using their rightmost points.
- The interval  $(p_{i-1}, p_i)$  is denoted as  $\text{cell}(p_i)$ , and
- the *length* of the  $i$ th cell:  $|\text{cell } p_i| = |p_i - p_{i-1}|$ .
- If we want to sequence the cells of  $P$  based on their right endpoints, it is expressed as  $\text{cell}(P) = (\text{cell}(\underline{p_N}))$ .
- Note that these cells do not form a disjoint union of  $I$ .

### Remark 2.1: Assume all intervals are compact

For the rest of this chapter, we assume all intervals are compact and of the form  $I = [a, b]$ . If  $P, Q, R$  are partitions, their elements will be represented by  $p_i$ , (resp.  $r_i, q_i$ ).

### Definition 2.2: Step mapping

A step mapping on  $I = [a, b]$  is a vector space of maps from  $I$  to a Banach space  $E$  over  $\mathbb{R}$ . It is equipped with the supremum norm, and its elements are denoted by  $\Sigma$ ,

$$\Sigma = \left\{ f : [a, b] \rightarrow E, \text{ there exists a } N\text{-partition } P \in I_p, \{v_{\underline{N}}\} \subseteq E \text{ such that } f|_{(p_{i-1}, p_i)} = v_i \forall i = \underline{N} \right\} \quad (32)$$

If  $f \in \Sigma$ , we denote its norm by  $\|f\|_u = \sup_{x \in I} |f(x)|$ .



**Definition 2.3: Integration on  $\Sigma$**

If  $f \in \Sigma$  and is of the form inside the set-builder notation in eq. (32), we define the integral of  $f$  by

$$\int_a^b f = \sum_{i=\underline{N}} (p_i - p_{i-1})v_i \quad (33)$$

**Remark 2.2: Distinguishing between intervals  $I, J$**

If  $I$  and  $J$  are compact intervals, we distinguish the step mappings from  $I$  and  $J$  by  $\Sigma_I$  and  $\Sigma_J$ .

We now state some definition and properties of eq. (33) which we will not prove.

**Proposition 2.1: Properties of the integral on  $\Sigma$**

Let  $I$  and  $J$  be intervals,  $f, f_{\underline{k}} \in \Sigma_I$ , and  $g \in \Sigma_J$ .

- The integral is linear, that is

$$\int \sum^{\wedge} f_{\underline{k}} = \sum^{\wedge} \int f_{\underline{k}} \quad (34)$$

- The integral over  $[b, a]$  is *defined* to be the negative of eq. (33):

$$\int_a^b f = - \int_b^a f \quad (35)$$

- The integral is domain-additive, if  $b = c$ , then

$$\int_a^b f + \int_c^d g = \int_a^d (f + g) \quad (36)$$

where we identify  $(f + g)$  to be the step mapping in  $\Sigma_{[a,d]}$  whose restriction  $I$  (resp.  $J$ ) agree with  $f$  (resp.  $g$ ).

## Product of step mappings

Let  $E_{\underline{k}}$  be Banach spaces, and  $I = [a, b]$  a fixed compact interval. Let  $E$  refer to the product space  $\prod E_{\underline{k}}$ , which is equipped with the supremum norm as outlined in def. 2.1

$$\Sigma_i = \left\{ f_i : I \rightarrow E_i, f_i \text{ is a step mapping.} \right\}$$

There are two ways of defining the space of step-mappings from  $I$  into  $E$  eqs. (37) and (38). Using a combinatorial argument with common refinements, it is not hard to see the two are subsets of each other.

$$\Sigma_E^1 = \left\{ f : I \rightarrow E, \text{proj}_i f \in \Sigma_i \forall i = \underline{k} \right\} \quad (37)$$

$$\Sigma_E^2 = \left\{ f : I \rightarrow E, f \text{ is a step mapping.} \right\} \quad (38)$$

And since the product space  $E$  is toplinearly isomorphic to its external direct sum,  $E_1 \times \cdots \times E_k$ , the integral over  $\Sigma_E = \Sigma_E^1 = \Sigma_E^2$  is defined to be

$$\int_a^b f = \left( \int_a^b \text{proj}_{\underline{k}} f \right) = \left( \int_a^b \text{proj}_1 f, \dots, \int_a^b \text{proj}_k f \right) \quad (39)$$

## Regulated mappings

### Definition 4.1: Regulated mappings

Let  $I$  be a compact interval. A mapping from  $I$  into  $E$  is *regulated* if it is the uniform limit of step mappings. We denote the space of regulated mappings by  $\overline{\Sigma}_I$  or  $\overline{\Sigma}$ .

### Proposition 4.1: Continuity implies a regulated mapping

Every continuous function  $f : I \rightarrow E$  is the uniform limit of step mappings in  $\Sigma_I = \Sigma$ .

*Proof.* Let  $f \in C(I, E)$ , the continuity of  $f$  is uniform; given  $\varepsilon > 0$  there exists  $\delta > 0$  where  $|y - x| < \delta$  implies  $|f(y) - f(x)| < \varepsilon$ .  $\delta$  induces a smallest integer  $n \geq 1$  such that  $p_n = a + n\delta > b$ . Define  $p_0 = a$  and  $p_i = a + i\delta$ , relabelling  $p_n = b$ , we see that  $P = (p_0, p_n)$  is a partition.

We construct a step mapping by sampling values of  $f$ . Set  $g|_{\text{cell}(p_i)} = f(p_i)$ ,  $g(a) = f(a)$ ,  $g(p_i) = f(p_i)$ . Defining the endpoints is necessary, and  $g$  still remains a member of  $\Sigma_I$  by eq. (32). Each  $x \in I \setminus P$  belongs in some  $\text{cell}(p_i)$ , of which  $|p_i - x| < \delta$ , and  $g(x) = f(p_i)$  implies  $|g(x) - f(x)| < \delta$ . If  $x$  is in  $P$ , then  $g(x) = f(x)$ , and  $\|f - g\|_u \leq +\varepsilon$ . ■

### Proposition 4.2: Integration of regulated mappings

Let  $f : I \rightarrow E$  be continuous, if  $\{f_n\} \subseteq \Sigma$  converges uniformly to  $f$ , then  $\{\int_a^b f_n\}$  is Cauchy in  $E$ , whose limit we *define* to be  $\int_a^b f$  — the integral of  $f$ . Furthermore,

1. For any regulated mapping  $f : I \rightarrow E$ ,

$$\left| \int_a^b f \right| \leq \int_a^b |f| \leq (b - a) \|f\|_u \quad (40)$$

2. The integral on  $\overline{\Sigma}$  (resp.  $\overline{\Sigma}_I, \overline{\Sigma}_J$ ) satisfies all of the properties in prop. 2.1.

*Proof.* Let  $f$  be a step mapping on  $E$ , we wish to show eq. (40) holds. If  $f$  is induced by some  $n$ -partition  $P$ ,

$$\int_a^b f = \sum_{i=\underline{n}} |\text{cell}(p_i)| f(p_i) \leq \sum_{i=\underline{n}} |\text{cell}(p_i)| \|f(p_i)\| = \int_a^b |f| \quad (41)$$

The integral in eq. (41) should be interpreted as a Riemann integral on  $\mathbb{R}$ , and eq. (42) is immediate:

$$\int_a^b |f| \leq |b - a| \|f\|_u \quad (42)$$

Next, let  $\{f_n\}_{n \geq 1}$  be a sequence of step mappings in  $I$  which converges uniformly to  $f \in \overline{\Sigma}$ . Equation (42) tells us the sequence of integrals is uniformly Cauchy, as

$$\left| \int_a^b f_m - \int_a^b f_n \right| \leq |b - a| \|f_m - f_n\|_u \quad (43)$$

Hence  $\int_a^b f$  is well defined, eq. (40) and the properties listed in prop. 2.1 follow upon taking limits. ■

#### Proposition 4.3: Integration and clms

Let  $E$  and  $F$  be Banach spaces, and  $\lambda \in L(E, F)$ . For a fixed interval  $I$ , denote the space of step mappings from  $I$  to  $E$  (resp.  $F$ ) by  $\Sigma_E$  (resp.  $\Sigma_F$ ), and regulated mappings similarly. If  $\{f_n\} \subseteq \Sigma_E$  converges uniformly to  $f \in \overline{\Sigma_E}$ , then  $\{\lambda f_n\} \rightarrow \lambda f$  uniformly in  $\overline{\Sigma_F}$ . Moreover,

$$\lambda \left( \int_a^b f \right) = \int_a^b \lambda f \quad (44)$$

*Proof.* The map  $\lambda$  is Lipschitz between  $E$  and  $F$ , and it descends into a map between the vector spaces  $\Sigma_E$  and  $\Sigma_F$  by composition. If  $f$  is a step mapping, and  $f|_{\text{cell}(p_i)} = v_i$  for  $i = \underline{k}$ ; the composition of  $f$  with  $\lambda$  is again a step mapping  $\lambda f|_{\text{cell}(p_i)} = \lambda v_i$ .

It is not hard to see  $\|\lambda f\|_u \leq |\lambda| \|f\|_u$ , and

- $\lambda$  is Lipschitz between  $E$  and  $F$ ,
- $\lambda$ , when viewed as a map between  $\Sigma_E$  and  $\Sigma_F$ , is Lipschitz.

Computing the integral of  $\lambda f \in \Sigma_F$ ,

$$\int_a^b \lambda f = \sum_{i=\underline{k}} |\text{cell}(p_i)| \lambda v_i = \lambda \left( \sum_{i=\underline{k}} |\text{cell}(p_i)| v_i \right) = \lambda \int_a^b f$$

proves eq. (44) for step mappings, and the general case follows from continuity. ■

### Fundamental Theorem of Calculus

#### Proposition 5.1

Let  $I$  be a compact interval, and  $f : I \rightarrow E$  be regulated. Defining  $\varphi : I \rightarrow E$  as the *integral of  $f$  with basepoint  $a$*

$$\varphi(t) = \int_a^t f \quad (45)$$

Then  $\varphi$  is differentiable where  $f$  is continuous, and if  $t_0 \in I$  is such a point:

$$(D\varphi)(t_0) = f(t_0) \quad (46)$$

**Remark 5.1: Identifications**

The left hand side in eq. (46) should be thought of as a clm in  $L(\mathbb{R}, E)$ . We identify the point  $f(t_0)$  as the map  $t \mapsto t \cdot f(t_0)$ .

*Proof.* Suppose  $f$  is continuous at  $t_0$ . For all  $h$  sufficiently small, set  $\varepsilon(h) = \sup_{|t-t_0| \leq h, t \in I} |f(t) - f(t_0)|$  as the modulus of continuity; where  $\varepsilon(h) \rightarrow 0$  as  $h \rightarrow 0$ . Applying the well-known technique of estimating the integrand  $f(t) = [f(t) - f(t_0)] + f(t_0)$ , we have

$$\begin{aligned} \varphi(t_0 + h) - \varphi(t_0) &= \int_{t_0}^{t_0+h} f(t) dt \\ &= f(t_0) \cdot h + \int_{t_0}^{t_0+h} [f(t) - f(t_0)] dt \end{aligned} \quad (47)$$

The last term within eq. (47) is  $o(h)$ , and the proof is complete.  $\blacksquare$

**Mean value theorems**

If  $\lambda \in L(E, F)$ , and  $x \in E$ , we write  $\lambda \dot{x} = x \dot{\lambda}$ . If  $t \in \mathbb{R}$ , and we want to think of  $x$  as the map  $t \mapsto tx$ , we will write  $t \cdot x = x \cdot t = tx$  to emphasize the role that  $x$  plays. The duality pairing between  $L(E, F) \times E \rightarrow F$  is bilinear and continuous. For any regulated mapping  $\alpha : I \rightarrow L(E, F)$ ,

$$\int_a^b \alpha(t) \cdot x dt = \left( \int_a^b \alpha(t) dt \right) \cdot x \quad (48)$$

Furthermore, if  $f \in C^1(I, E)$ , we use the notation  $f'(t)$  to refer to  $Df(t)$ ; and we identify  $f'(t)$  with an element in  $E$ ; while  $Df(t)$  should be thought of as a mapping in  $L(\mathbb{R}, E)$ .

**Lemma 6.1: Constant curves**

If  $\alpha \in C^1(I, E)$ ,  $\alpha' = 0$ , iff  $\alpha$  is constant.

*Proof.* Suppose  $\alpha'$  vanishes, and assume for contradiction there exists points  $t_0 < t_1$  in  $I$  such that  $\alpha(t_0) \neq \alpha(t_1)$ . Hahn Banach gives us a clf  $\lambda \in L(E, \mathbb{R})$  that strictly separates the two points. See prop. 2.1 for a refresher. The ordinary derivative of  $\lambda \circ f$  is 0 everywhere which implies  $\lambda \circ f$  is constant. The converse is trivial.  $\blacksquare$

**Lemma 6.2: FTC 2**

Let  $f \in C^1(I, E)$ , then

$$f(b) - f(a) = \int_a^b f'(t) dt \quad (49)$$

where the integrand in eq. (49) is — rigorously speaking — a map  $\mathbb{R} \rightarrow L(\mathbb{R}, E)$ , but we treat  $f'(t) \in E$ .

*Proof.* Throughout this proof, we will treat  $f' : \mathbb{R} \rightarrow E$ . Because  $f'$  is continuous everywhere, it is regulated. Define  $\varphi(t) = \int_a^t f'(t) dt$ , by eq. (46):

$$\varphi'(t) - f'(t) \equiv 0$$

By lem. 6.1, it suffices to show  $(\varphi - f)(t) = f(a)$  at any point  $t \in [a, b]$ . Take  $t = a$ , and  $(\varphi(a) - f(a)) = 0$ , so that

$$\varphi(t) = f(t) + f(a)$$

and eq. (49) follows. ■

**Remark 6.1: Usefulness of FTC 2**

lem. 6.2 is most useful when  $[a, b] = [0, 1]$ , and the  $f$  is a curve interpolating between a  $C^1$  function evaluated two different points, as in prop. 6.1.

**Proposition 6.1: MVT 1**

Let  $U \subseteq E$  and  $x \in U$ ,  $y \in E$ . If the line segment  $L = \{x + ty, 0 \leq t \leq 1\}$  is also contained in  $U$  (draw a picture), then eq. (50) holds.

$$f(x + y) = f(x) + \int_0^1 Df(x + ty)y dt = \left( \int_0^1 Df(x + ty) dt \right) \cdot y \quad (50)$$

*Proof.* The curve  $g(t) = f(x + ty)$  is composed of  $f \circ l(t)$ , for  $l(t) = x + ty$ . It has derivative

$$g'(t) = Df(x + ty) \circ l'(t) = Df(x + ty) \circ (y \in L(\mathbb{R}, E))$$

By lem. 6.2,  $g(1) - g(0) = \int_0^1 Df(x + ty) \cdot y dt$ . Given  $g(1) - g(0) = f(x + y) - f(x)$ , the proof is complete. ■

## Chapter 4: Higher order derivatives

## Introduction

We start with the definition of  $C^p(E, F)$ . Let  $E$  and  $F$  be Banach Spaces, if  $p \geq 1$  is an integer, we define the class  $C^p$  to be the set of maps which are  $p$  times differentiable, and  $D^p f \in C(E, X)$ , where

$$X = L(E, L(E, L(E, \dots F))) \text{ } p \text{ times } \xLeftrightarrow{\mathcal{L}} L(E^p, F)$$

Sometimes we replace  $E$  with an open subset  $U \subseteq E$  if necessary, and we write  $f \in C(U, F)$  if  $D^p \in C(U, X)$ . Note, even if  $f \in C^1(U, F)$ ,  $Df$  is still a map from  $U$  into  $L(E, F)$ .

We will prove two major results in this section.

- The structure of the derivative  $D^p f$ , in particular, if  $f \in C^p(E, F)$ , then  $D^p f(x)$  is a *symmetric multilinear map* in  $p$  arguments.
- Taylor's Theorem

## The second derivative

### Proposition 2.1: Product rule in 2 variables

Let  $E_1$ ,  $E_2$  and  $F$  be Banach spaces, if  $\omega : E_1 \times E_2 \rightarrow F$  is bilinear and continuous, then  $\omega$  is differentiable, and for every  $(x_1, x_2) \in E_1 \times E_2$ ,  $(v_1, v_2) \in E_1 \times E_2$ ,

$$D\omega(x_1, x_2)(v_1, v_2) = \omega(x_1, v_2) + \omega(v_1, x_2)$$

Furthermore,  $D^2\omega(x, y) = D\omega \in L(E^2, F)$ , and  $D^3\omega = 0$ .

*Proof.* By the definition of  $\omega$ , using the familiar interpolation method

$$\omega(x_1 + h_2, x_2 + h_2) = \omega(x_1, x_2) + \omega(x_1, h_2) + \omega(h_1, x_2) + \omega(h_1, h_2)$$

by continuity of  $\omega$ , the last term (which we wish to make  $o(h)$ ):

$$|\omega(h_1, h_2)| \leq \|\omega\| \cdot |(h_1, h_2)|^2$$

so that  $\omega(h_1, h_2) = o(h)$ , and  $D\omega(x_1, x_2)$  exists and is continuous, and is given by the *linear map*  $\omega(x_1, \cdot) + \omega(\cdot, x_2)$ . The rest of the proof follows, if it is not immediately obvious then read the following note.

### Note 2.1

Write  $E = E_1 \times E_2$  for convenience. The linear map  $A = D\omega(x_1, x_2)$  takes arguments  $E$  into  $F$ , consider the projections  $\pi_1$  and  $\pi_2$ , and  $v \in E_1 \times E_2$ , then

$$A(v) = \omega(x_1, \pi_1 v) + \omega(\pi_2 v, x_2)$$

We can view  $A(x) = D\omega(x_1, x_2) \in L(E, F)$ . It is clear that  $A$  is linear in  $x$ , if we fix  $v \in E$ ,

$$A(x + y, v) = \omega(\pi_1(x + y), \pi_2 v) + \omega(\pi_1 v, \pi_2(x + y)) = A(x, v) + A(y, v)$$

and similarly for scalar multiplication. Hence  $DA(x) = A \in L(E, L(E, F))$  and  $D^2 A(x) = D^3 \omega = 0$ .

Our next result is the following, which states that if  $f : U \rightarrow F$  where  $U \subseteq E$ , and  $Df, DDf = D^2f$  exists and are continuous maps from  $U$  into  $L(E, F)$  and  $L(E, L(E, F))$  respectively, then  $D^2f(x)$  is a *symmetric bilinear map*. The proof is non-trivial, and relies on computing the 'Lie Bracket':

$$D^2f(x)(v, w) - D^2f(x)(w, v)$$

Which we will prove is equal to 0 for every  $x \in U$ , and  $v, w \in E$ .

**Proposition 2.2: Second derivative is symmetric**

Let  $f \in C^2(U, F)$ , where  $U \subseteq E$  with the possibility that  $U = E$ . For every point  $x \in U$ , the *second derivative*  $D^2f(x)$  is bilinear and symmetric.

*Proof.* Fix  $x \in U \ni B(r) + x \subseteq U$ . We restrict our attention to vectors  $v, w \in E$  where  $|v|, |w| < r2^{-1}$  for now, so that the

$$\{x, x + w, x + v, x + v + w\} \subseteq U$$

We will denote the following quantity by  $\Delta$

$$\Delta = f(x + w + v) - f(x + w) - f(x + v) + f(x)$$

By rearranging terms, we see that  $\Delta$  can be approximated in two ways:

- Postponing the discussion about the the domain of  $y$ , set  $g(y) = f(y + v) - f(y)$  is  $C^2$ , and

$$\Delta = g(x + w) - g(x) \tag{51}$$

- Again, for  $y$  sufficiently close to  $x$ , define  $h(y) = f(y + w) - f(y)$ , and

$$\Delta = h(x + v) - h(x) \tag{52}$$

- To find the domain for  $y$ , an easy argument using the Triangle inequality gives us  $g, h \in C^2(B(r2^{-1}) + x, F)$ ,
- Leaving the computations of  $h$  as an exercise, we compute  $Dg$ , recall the shift map  $y \mapsto y + v$  commutes with  $D$ , and

$$Dg(y) = D(\tau_{-w}f)(y) - Df(y) = Df(y + w) - Df(y) \tag{53}$$

Using MVT twice, once on Equation (51) (the line segment  $x + tw$ ,  $0 \leq t \leq 1$  is contained in the domain of  $g$ ), and another time on Equation (53) (with  $y = x + tw$  in the integrand). We obtain:

$$\begin{aligned} \Delta &= g(x + w) - g(x) \\ &= \int_0^1 Dg(x + tw) \cdot w dt \\ &= \int_0^1 \int_0^1 D^2f(x + tw + sv) \cdot v ds dt \cdot w \\ &= \int_0^1 \int_0^1 D^2f(x + tw + sv) ds dt \cdot v \cdot w \end{aligned}$$



We can rewrite the application of  $v$  then  $w$  by  $\cdot(v, w)$ , and using the approximation  $D^2 f(x + tw + sv) \cdot (v, w) = D^2 f(x) \cdot (v, w) + \delta_1(tw, sv)$ . Integrating over  $s, t$  gives

$$\Delta = D^2 f(x) \cdot (v, w) + \int_0^1 \int_0^1 \delta_1(tw, sv) ds dt$$

### Note 2.2

The error term  $\delta_1$  in the integrand is given by

$$\delta_1(tw, sv) = D^2 f(x + tw + sv)(v, w) - D^2 f(x)(v, w)$$

for  $v, w$  sufficiently small and  $0 \leq s, t \leq 1$ .

A similar argument for  $h$  shows that  $\Delta = D^2 f(x) \cdot (w, v) + \int_0^1 \int_0^1 \delta_2(tw, sv) ds dt$ . Combining the two together, the following holds for all  $v, w$  sufficiently small:

$$D^2 f(x) \cdot (v, w) - D^2 f(x) \cdot (w, v) = \int_0^1 \int_0^1 \delta_1(tw, sv) ds dt - \int_0^1 \int_0^1 \delta_2(tw, sv) ds dt \quad (54)$$

To show the right hand side is 0, we will need the following note.

### Note 2.3

We wish to show the RHS of Equation (54) is 0. We begin by controlling the RHS and show that it is super-bilinear; meaning it shrinks after than the product  $|v||w|$ . Then, we will prove a lemma which will show the only bilinear map that satisfies this property is the 0 map.

- For  $j = 1, 2$ , relabel  $\delta = \delta_j$  for convenience. We can use the  $L^1$  inequality, to obtain the estimate

$$\left| \int_0^1 \int_0^1 \delta(tw, sv) ds dt \right| \leq \int_0^1 \int_0^1 |\delta(tw, sv)| ds dt \quad (55)$$

- $\delta(tw, sv)$  is controlled by  $|D^2 f(x + tw + sv) - D^2 f(x)| |v| |w|$ . Take  $y = tw + sv$ , then  $|y| \leq |tw| + |sv|$ . Hence,

$$|\delta_j| \leq |D^2 f(x + tw + sv) - D^2 f(x)| |v| |w| \quad (56)$$

- Let  $A$  denote the span of  $w, v$  for scalars  $s, t \in [0, 1]$ . In symbols,

$$A = \left\{ tw + sv, s, t \in [0, 1] \right\}$$

$A$  is clearly compact, and the continuity of  $D^2 f$  means

$$R(v, w, \delta) = \sup_{y \in A} |D^2 f(x + y) - D^2 f(x)| \quad \text{is finite,} \quad \text{and} \quad \lim_{(v, w) \rightarrow 0} R(v, w, \delta) = 0 \quad (57)$$

See remark 2.1 for a generalization of this argument.

- Relabel  $R(v, w)$  to be the maximum across  $R(v, w, \delta_1)$  and  $R(v, w, \delta_2)$ .

- Combining Equations (55) to (57), we obtain the following bound on Equation (54)

$$\begin{aligned}
 \left| D^2 f(x) \cdot (v, w) - D^2 f(x) \cdot (w, v) \right| &\leq \left| \iint \delta_1(tw, sv) ds dt - \iint \delta_2(tw, sv) ds dt \right| \\
 &\leq \iint |\delta_1| ds dt + \iint |\delta_2| ds dt \\
 &\leq |v||w|R(v, w)
 \end{aligned} \tag{58}$$

The following Lemma gives a useful criterion to check when a multilinear map is identically 0.

### Lemma 2.1

Let  $E$  be a Banach space, and  $k \geq 1$  be an integer. If  $\lambda \in L(E^k, F)$  and there exists another map  $\theta : E^k \rightarrow F$  (defined perhaps on an open neighbourhood of the origin), such that

$$|\lambda(u_{\underline{k}})| \leq |\theta(u_{\underline{k}})| \cdot \prod |u_{\underline{k}}|$$

for all  $(u_{\underline{k}})$  sufficiently small. And  $\lim_{(u_{\underline{k}}) \rightarrow 0} \theta(u_{\underline{k}}) = 0$ , then,  $\lambda = 0$ .

*Proof.* Fix arbitrary  $(u_{\underline{k}}) \in E^k$ , for  $s > 0$  sufficiently small, the left hand side of the equation reads

$$|s|^k |\lambda(u_{\underline{k}})| \leq |\theta(su_{\underline{k}})| \cdot |s|^k \prod |u_{\underline{k}}|$$

The rest of the argument is Archimedean: divide by  $|s|^k$  and send  $s \rightarrow 0$  (while paying attention to the term with  $\theta$ ): perhaps after relabelling  $v_s = su_{\underline{k}}$  for sufficiently small  $s$ , then  $|\theta(v_s)| \rightarrow 0$  as  $s \rightarrow 0$ . ■

### Remark 2.1: Compact linear combinations

Generalization of the "compact linear combination" argument used above. Let  $(t_{\underline{k}}) \subseteq \mathbb{C}^k$  or  $\mathbb{R}^k$ , and vectors  $v_{\underline{k}} \in E$ . Suppose further  $(t_{\underline{k}}) \subseteq A$  is compact in  $\mathbb{C}^k$  or  $\mathbb{R}^k$ . It is clear that if  $y = t_i v^i \in E$ , where the summation convention is in effect. Then,

$$|y| \lesssim_A |(v^{\underline{k}})|_{E^k}$$

Now, fix a continuous function  $f \in C(E, F)$ , we can approximate the maximum error over all such  $y$

$$\sup_{y \in B} |f(x + y) - f(x)| < \varepsilon \quad \forall |y| \lesssim_A |(v^{\underline{k}})| < \delta$$

where

$$B = \left\{ \sum t_i v^i, (t_{\underline{k}}) \subseteq A, (v^{\underline{k}}) \in E^k \right\}$$

## The $p$ -th derivatives

If  $f$  is  $p$  times differentiable, and  $f, Df, D^2f, \dots, D^p f$  are all continuous, then we say  $f \in C^p(E, F)$  (replacing  $E$  with an open subset of  $E$  if necessary).

### Proposition 3.1

If  $f \in C^p(E, F)$ , then  $D^p f(x)$  is symmetric for every  $x \in E$ . (Replace  $E$  with an open set if necessary).

*Proof.* The main proof proceeds as follows. We will use induction on  $p$ , with  $p = 2$  serving as the base case. Our induction hypothesis is that for every  $f \in C^{p-1}(E, F)$ , for every permutation  $\beta \in S_{p-1}$ , at every point  $x \in E$ , for every possible choice of  $p-1$  vectors  $(v_2, \dots, v_p) = (v_{1+\underline{p-1}})$ ,

$$D^{p-1}f(x)(v_{1+\underline{p-1}}) = D^{p-1}f(x)(v_{1+\beta(\underline{p-1})})$$

To prove the assertion for  $p$ , it suffices to show  $D^p f(x)(v_p)$  is invariant under transpositions of indices; since the transpositions generate  $S_p$ . Furthermore, the transpositions in  $S_p$  are generated by

- the transposition  $(1, 2, \dots) \mapsto (2, 1, \dots)$  where the omitted indices are held fixed, and
- the transpositions which leave the first index fixed:

$$(1, 1 + \underline{p-1}) \mapsto (1, 1 + \beta(\underline{p-1}))$$

where  $\beta \in S_{p-1}$

so it suffices to prove invariance under those two types of transpositions. Let  $g = D^{p-2}f$ , so  $g \in C^2(E, L(E^{p-2}, F))$ . Because the application of vectors (currying) on a multilinear map  $A \in L(E^p, F)$  is associative, illustrated as follows:

$$(A \cdot v_1) \cdot v_2 = A \cdot (v_1, v_2) = A(v_1, v_2, \cdot) \in L(E^{p-2}, F)$$

Then, let  $\lambda : L(E^{p-2}, F) \rightarrow F$  be the evaluation map at  $(v_3, \dots, v_p) = (v_{2+\underline{p-2}})$ . Using the base case on  $D^{p-2}f = g \in C^2(E, L(E^{p-2}, F))$ ,

$$(D^2g)(x)(v_1, v_2) = (D^2g)(x)(v_2, v_1) \implies \lambda((D^2g)(x)(v_1, v_2)) = \lambda((D^2g)(x)(v_2, v_1))$$

But  $\lambda$  is the map that *applies* the rest of the vectors, and

$$(D^2g)(x)(v_1, v_2) \cdot (v_{2+\underline{p-2}}) = (D^2g)(x)(v_2, v_1) \cdot (v_{2+\underline{p-2}}) \quad (59)$$

Since  $D$  commutes with continuous linear maps (and  $\lambda$  is continuous because  $(v_{2+\underline{p-2}})$  is fixed),

$$\lambda(D^2(D^{p-2}f)) = D(\lambda(D(D^{p-2}f))) = D(D\lambda \circ D^{p-2}f) = D^2(\lambda \circ D^{p-2}f) \quad (60)$$

Substituting Equation (59) for the rightmost hand side of Equation (60) gives the result.

### Note 3.1

There are no magic 'identifications' being made here. To be perfectly clear, for each  $x \in E$ ,  $g(x)$  is an element in  $L(E^{p-2}, F)$ , and  $(D^2g)(x) \in L(E^2, L(E^{p-2}, F))$ . Evaluating  $g$  at a point  $x$  gives a bilinear map that takes values in the Banach space  $L(E^{p-2}, F)$ .

For the second case, beginning from the induction hypothesis. If  $\theta$  is a  $p$ -permutation that leaves the first coordinate unchanged, then there exists a unique  $p-1$ -permutation  $\beta \in S_{p-1}$  such that

$$\begin{aligned} (\theta(\underline{p})) &= (1, \theta(1 + \underline{p-1})) \\ &= (1, 1 + \beta(\underline{p-1})) \end{aligned} \tag{61}$$

Using a similar argument as the first case, set  $g = D^{p-1}f$  and  $\lambda, \lambda' \in L(E^{p-1}, F)$  to be the evaluation maps of  $(v_1, v_{1+\underline{p-1}}) = (v_{\underline{p}})$  and  $(v_1, v_{1+\beta(\underline{p-1})})$  respectively. Rehearsing the same proof as before:

$$\begin{aligned} (D^p f)(x)(v_{\underline{p}}) &= D(\lambda D^{p-1} f)(x)(v_1) && \text{Equation (60)} \\ &= D(\lambda' D^{p-1} f)(x)(v_1) && \text{ind. hyp.} \\ &= (D^p f)(x)(v_{\theta(\underline{p})}) && \text{Equation (60)} \end{aligned}$$

This proves the induction step, and the proof is complete. ■

Before stating and proving Taylor's Theorem, an important remark on the 'postcomposition' of linear maps. Summarized in the following note.

### Note 3.2

Let  $f \in C^p(E, F)$ , and  $\lambda \in L^p(F, G)$ .  $\lambda$  induces a map between  $L(E^p, F)$  and  $L(E^p, G)$  by postcomposing any multi-linear map  $A \in L(E^p, F)$  by  $\lambda$ . Denoting this map by  $\lambda_*$ ,

$$\lambda_* : L(E^p, F) \rightarrow L(E^p, G)$$

It is clear  $\lambda_*$  is linear and continuous. And its action on  $A$ , evaluated at  $(v_{\underline{p}}) \in E^p$  is given by

$$\lambda_*(A) \in L(E^p, G) \quad (\lambda_*(A))(v_{\underline{p}}) = \lambda(A(v_{\underline{p}})) = (\lambda \circ A)(v_{\underline{p}})$$

Now, recall that for  $p = 1$

$$[D(\lambda \circ f)](x) = \lambda[(Df)(x)]$$

To simplify the notation, we want to 'move' the evaluation  $x$  outside of the brackets, and somehow write  $x \mapsto \lambda[(Df)(x)]$  as one map between  $E$  and  $L(E, G)$ . We further *identify*  $\lambda$  as this map, so that

$$[D(\lambda \circ f)](x) = \lambda = (\lambda \circ Df)(x)$$

Dropping the  $x$  from the expression, for  $p \geq 2$  *assuming a similar formula holds*, then we write  $[D^p(\lambda \circ f)] = \lambda_* \circ D^p f$ . We make a final identification, of  $\lambda = \lambda_*$  (thereby conflating the two different maps, the first is a map from  $E$  to  $F$ , the second is a map from  $L(E^p, F)$  into  $L(E^p, G)$ ).

### Proposition 3.2: Linear maps commute with $D^p$

If  $p \geq 2$ ,  $f \in C^p(E, F)$ ,  $\lambda \in L(F, G)$ , then

$$D^p(\lambda \circ f) = \lambda \circ D^p f$$

Where we have identified  $\lambda$  as the same map that acts on  $L(E^p, F)$  to produce another map in  $L(E^p, G)$ ,

and suppressed the point  $x$ .

*Proof.* Use induction on  $p$ . ■

**Proposition 3.3:  $C^p$  is closed under composition**

If  $f \in C^p(E, F)$ , and  $g \in C^p(F, G)$ , then  $g \circ f \in C^p(E, G)$ .

*Proof.* Postponed. ■

**Proposition 3.4: Taylor's Formula**

Let  $f \in C^p(U, F)$ , where  $U \overset{\circ}{\subseteq} E$ . For  $x \in U$  and  $y \in E$  such that  $L = \{x + ty, 0 \leq t \leq 1\}$  is contained in  $U$ , then

$$f(x + y) = f(x) + \left( \sum_{i=\underline{p-1}} \frac{D^i f(x) \cdot (y^{(i)})}{(p-1)!} \right) + R_p \quad (62)$$

where  $\cdot(y^{(i)})$  denotes the application of  $y$ , consecutively for  $i$  times. The remainder  $R_p$  is given by eq. (63)

$$R_p = \int_0^1 \frac{(1-t)^{p-1}}{(p-1)!} D^p f(x + ty) dt \cdot (y^{(p)}) \quad (63)$$

Furthermore, we include the  $p$ th term in the series using eq. (64)

$$f(x + y) = f(x) + \sum_{i=\underline{p}} \frac{D^i f(x) \cdot (y^{(i)})}{i!} + \theta(y) \quad (64)$$

where  $\theta$  is defined for small  $y$ , and  $o(|y|^p)$ .

$$|\theta(y)| \leq \sup_{0 \leq t \leq 1} \frac{|D^p f(x + ty) - D^p f(x)|}{p!} |y|^p \quad (65)$$

*Proof.* Postponed. ■