

# Untitled

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Discrete Optimization course on Coursera : <https://www.coursera.org/learn/discrete-optimization/home/welcome>

Week 1:

## 1 Knap sack problem

```
In [15]: from time import time
         from IPython.display import Image

In [16]: # [value, weight]
         items = [ [1,2],[1,2],[1,2],[10,5],[10,5],[13,8],[7,3] ]
         K = 10

In [17]: n = len(items)
```

### 1.1 Greedy procedure

#### 1. lightest first:

```
In [19]: def greedy1(K,items):
         n = len(items)
         # Sorting by ascending weight
         items.sort(key=lambda x: x[1])
         print("sorted by weight: %s" % items)
         selected_value = 0
         selected_weight = 0
         selected = []
         i = 0

         # Packing lightest items first
         while selected_weight < K:
             if i>=n:
                 break;
             if selected_weight+items[i][1] <= K:
                 selected.append(items[i])
                 selected_weight += items[i][1]
                 selected_value += items[i][0]
                 i += 1
```

```

        else:
            break;
    return selected, selected_weight, selected_value

selected, selected_weight, selected_value = greedy1(10,items)
print("for a weight of %d" % selected_weight)
print("for a value of %d" % selected_value)
print("Selected items to pack are : \n %s " % selected)

```

sorted by weight: [[1, 2], [1, 2], [1, 2], [7, 3], [10, 5], [10, 5], [13, 8]]  
for a weight of 9  
for a value of 10  
Selected items to pack are :  
[[1, 2], [1, 2], [1, 2], [7, 3]]

#### #### 2. Most valuable first

```

In [20]: def greedy0(K,items):
    n = len(items)
    # Sorting by descending value
    items.sort(key=lambda x: x[0], reverse=True)
    print("sorted by value: %s" % items)
    selected_value = 0
    selected_weight = 0
    selected = []

    # Packing most valuable first if it still fits
    for i in range(n):
        if selected_weight+items[i][1] <= K:
            selected.append(items[i])
            selected_weight += items[i][1]
            selected_value += items[i][0]
    return selected, selected_weight, selected_value

selected, selected_weight, selected_value = greedy0(10,items)
print("for a weight of %d" % selected_weight)
print("for a value of %d" % selected_value)
print("Selected items to pack are : \n %s " % selected)

```

sorted by value: [[13, 8], [10, 5], [10, 5], [7, 3], [1, 2], [1, 2], [1, 2]]  
for a weight of 10  
for a value of 14  
Selected items to pack are :  
[[13, 8], [1, 2]]

### 3. Value density

```
In [21]: def greedy(K,items):
    n = len(items)
    # Sorting by density : ie. value / weight
    items.sort(key=lambda x: x[0]/x[1], reverse=True)
    print("sorted by value density: %s" % items)
    selected_value = 0
    selected_weight = 0
    selected = []

    # Packing most valuable first if it still fits
    for i in range(n):
        if selected_weight+items[i][1] <= K:
            selected.append(items[i])
            selected_weight += items[i][1]
            selected_value += items[i][0]
    return selected, selected_weight, selected_value

selected, selected_weight, selected_value = greedy(10,items)
print("for a weight of %d" % selected_weight)
print("for a value of %d" % selected_value)
print("Selected items to pack are : \n%s " % selected)

sorted by value density: [[7, 3], [10, 5], [10, 5], [13, 8], [1, 2], [1, 2], [1, 2]]
for a weight of 10
for a value of 18
Selected items to pack are :
[[7, 3], [10, 5], [1, 2]]
```

#### 1.1.1 Overview:

- Depends on the chosen heuristic
- quick to design  
can be very fast to run
- no guarantee on quality  
feasibility needs to be easy  
quality varies between instances

## 1.2 Modeling

maximisation problem

- Decision variable:

$$\begin{cases} x_i = 1 := \text{pack the } i - \text{th item} \\ x_i = 0 := \text{Don't pack the } i - \text{th item} \end{cases}$$

- Problem Constraint:

$$\sum_{i \in I} w_i x_i \leq K$$

- Objective function:

$$\sum_{i \in I} v_i x_i$$

## 1.3 Dynamic programming

- Finds Best Solution
- Divide and conquer / Bottom up computation technique
- We denote  $o(k,j)$  the optimal solution for the alternative problem with maximum capacity  $k$  and for the items  $1..j$  to solve the original problem  $o(K,n)$
- Procedure:
  - If item fits:  $O(k,j) = \max\{ O(k,j-1), v_j + O(k-w_j, j-1) \}$
  - If it doesn't  $O(k,j) = O(k,j-1)$

recursion starting from  $o(k,0)=0$  for all  $k$

**1. Top down version :** Inefficient and not a dynamic programming solution

```
In [7]: def o(k,j):
        if j==0: #first recursion term
            return 0
        elif items[j-1][1] <= k: #if item fits
            return max(o(k,j-1), items[j-1][0]+o(k-items[j-1][1],j-1) )
        else: #if item doesn't fit
            return o(k,j-1)

        start = time()
        print("Optimal reachable value : %d" % o(10,n))
        print("run time : %f ms" % (1000*(time()-start)))
```

```
Optimal reachable value : 20
run time : 0.489473 ms
```

1. **Bottom up version** :  $O(Kn)$  solution but not polynomial because of the capacity  $K \rightarrow \log_2 K$  bits

$\Rightarrow$  pseudo-polynomial

In [8]: Image("TableDynamicProgramming1.png")

Out[8]:

► How to find which items to select?

Capacity	0	1	2	3
0	0	0	0	0
1	0	0	0	0
2	0	0	0	3
3	0	0	0	3
4	0	5	5	5
5	0	5	6	6
6	0	5	6	8
7	0	5	6	9
8	0	5	6	9
9	0	5	11	11

$v_1=5$   $v_2=6$   $v_3=3$   
 $w_1=4$   $w_2=5$   $w_3=2$

In [9]: Image("TableDynamicProgramming2.png")

Out[9]:

► How to find which items to select?

Capacity	0	1	2	3
0	0	0	0	0
1	0	0	0	0
2	0	0	0	3
3	0	0	0	3
4	0	5	5	5
5	0	5	6	6
6	0	5	6	8
7	0	5	6	9
8	0	5	6	9
9	0	5	11	11

Take items 1 and 2      Trace back

```

In [10]: # A python improvement using memoization
         from functools import lru_cache

         @lru_cache(maxsize = 250)
         def dp_o(k,j,items):
             if j==0: #first recursion term
                 return 0
             elif items[j-1][1] <= k: #if item fits
                 return max(o(k,j-1), items[j-1][0]+o(k-items[j-1][1],j-1) )
             else: #if item doesn't fit
                 return o(k,j-1)

         start = time()
         print("Optimal reachable value : %d" % dp_o(K,n,items))
         print("run time : %f ms" % (1000*(time()-start)))

```

Optimal reachable value : 20  
run time : 0.268459 ms

```

In [22]: def dynamic_prog(K,items):
         # Explicit dynamic programming implementation
         n = len(items)
         dp_table = []
         j_col = []

         # first column of zeros
         for k in range(K+1):
             j_col.append(0)
         dp_table.append(j_col)
         # filling other columns
         for j in range(n):
             j_col = []
             for k in range(K+1):
                 if items[j][1] <= k: #item fits
                     j_col.append( max( dp_table[j][k], items[j][0]+dp_table[j][k-items[j][1]] ) )
                 else:
                     j_col.append( dp_table[j][k] )
             dp_table.append(j_col)

         return dp_table

         dp_table = dynamic_prog(10,items)
         start = time()
         print("Optimal reachable value : %d" % dp_table[n][K])
         print("run time : %f ms" % (1000*(time()-start)))

```

Optimal reachable value : 20  
run time : 0.215054 ms

## 1.4 Branch and bound

```
In [24]: items2 = [[45,5],[48,8],[35,3]]
         dynamic_prog(10,items2)[len(items2)][10]
```

Out[24]: 80

maximize  $45x_1 + 48x_2 + 35x_3$

subject to  $\begin{cases} 5x_1 + 8x_2 + 3x_3 \leq 10 \\ x_i \in \{0,1\} \end{cases}, i \in \{1,2,3\}$

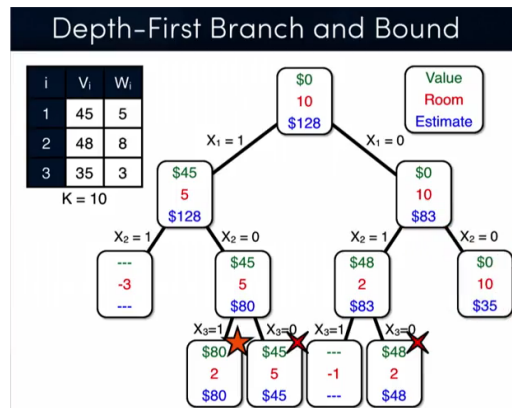
**Branching:** split problem into a number of subproblems ~ exhaustive search

**Bounding:** find an optimistic estimate; an upper bound for the maximization problems.

1. **Relaxation: removing capacity constraint:** Choosing all available items.

```
In [25]: Image("NoConstraint_B&B.png")
```

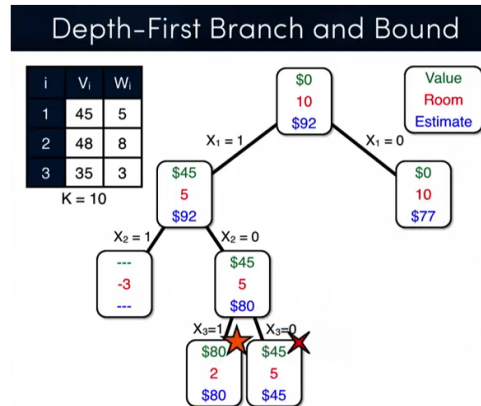
Out[25]:



1. **Linear Relaxation:** maximize  $45x_1 + 48x_2 + 35x_3$   
subject to  $\begin{cases} 5x_1 + 8x_2 + 3x_3 \leq 100 \\ x_i \leq 1 \end{cases}$

```
In [27]: Image("LinearRelax_B&B.png")
```

Out [27] :



At each step, we bound by the value given by the linear relaxation which can be easily solved thanks to the greedy algorithm using density value and taking fractions of the objects if needed.

We stop the exploration as the estimate (77) is lower than the already retrieved solution (80)

## 1.5 Search Strategies

**Depth-first:** go deeper in the tree and prune when a node's estimation is worse than the best solution found memory efficient : at most one whole branch so the number of the items ##### Best-first: always explore the node with the best estimation ##### Least discrepancy: - avoid mistakes (defined by trusting a greedy heuristic) - explore the space by allowing an increasing number of mistakes through waves

- probes the search space eg. heuristic is going left

In [28] : `Image("LDS.png")`

Out [28] :



# LDS Branch and Bound

