

If your model is underfitting the training data, adding more training examples will not help. You need to use a more complex model or come up with better features.

Now let's look at the learning curves of a 10th-degree polynomial model on the same data (Figure 4-16):

```
from sklearn.pipeline import Pipeline
polynomial_regression = Pipeline([
        ("poly_features", PolynomialFeatures(degree=10, include_bias=False)),
        ("lin_reg", LinearRegression()),
    ])
plot_learning_curves(polynomial_regression, X, y)
```

These learning curves look a bit like the previous ones, but there are two very important differences:

- The error on the training data is much lower than with the Linear Regression
- There is a gap between the curves. This means that the model performs significantly better on the training data than on the validation data, which is the hallmark of an overfitting model. However, if you used a much larger training set, the two curves would continue to get closer.

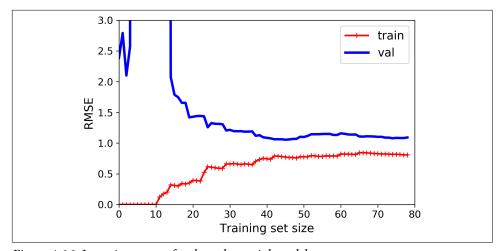


Figure 4-16. Learning curves for the polynomial model



One way to improve an overfitting model is to feed it more training data until the validation error reaches the training error.

The Bias/Variance Tradeoff

An important theoretical result of statistics and Machine Learning is the fact that a model's generalization error can be expressed as the sum of three very different errors:

Bias

This part of the generalization error is due to wrong assumptions, such as assuming that the data is linear when it is actually quadratic. A high-bias model is most likely to underfit the training data.¹⁰

Variance

This part is due to the model's excessive sensitivity to small variations in the training data. A model with many degrees of freedom (such as a high-degree polynomial model) is likely to have high variance, and thus to overfit the training data.

Irreducible error

This part is due to the noisiness of the data itself. The only way to reduce this part of the error is to clean up the data (e.g., fix the data sources, such as broken sensors, or detect and remove outliers).

Increasing a model's complexity will typically increase its variance and reduce its bias. Conversely, reducing a model's complexity increases its bias and reduces its variance. This is why it is called a tradeoff.

Regularized Linear Models

As we saw in Chapters 1 and 2, a good way to reduce overfitting is to regularize the model (i.e., to constrain it): the fewer degrees of freedom it has, the harder it will be for it to overfit the data. For example, a simple way to regularize a polynomial model is to reduce the number of polynomial degrees.

For a linear model, regularization is typically achieved by constraining the weights of the model. We will now look at Ridge Regression, Lasso Regression, and Elastic Net, which implement three different ways to constrain the weights.

¹⁰ This notion of bias is not to be confused with the bias term of linear models.

Ridge Regression

Ridge Regression (also called *Tikhonov regularization*) is a regularized version of Linear Regression: a regularization term equal to $\alpha \sum_{i=1}^{n} \theta_i^2$ is added to the cost function. This forces the learning algorithm to not only fit the data but also keep the model weights as small as possible. Note that the regularization term should only be added to the cost function during training. Once the model is trained, you want to evaluate the model's performance using the unregularized performance measure.



It is quite common for the cost function used during training to be different from the performance measure used for testing. Apart from regularization, another reason why they might be different is that a good training cost function should have optimization-friendly derivatives, while the performance measure used for testing should be as close as possible to the final objective. A good example of this is a classifier trained using a cost function such as the log loss (discussed in a moment) but evaluated using precision/recall.

The hyperparameter α controls how much you want to regularize the model. If $\alpha = 0$ then Ridge Regression is just Linear Regression. If α is very large, then all weights end up very close to zero and the result is a flat line going through the data's mean. Equation 4-8 presents the Ridge Regression cost function.¹¹

Equation 4-8. Ridge Regression cost function

$$J(\mathbf{\theta}) = \text{MSE}(\mathbf{\theta}) + \alpha \frac{1}{2} \sum_{i=1}^{n} \theta_i^2$$

Note that the bias term θ_0 is not regularized (the sum starts at i=1, not 0). If we define \mathbf{w} as the vector of feature weights (θ_1 to θ_n), then the regularization term is simply equal to $\frac{1}{2}(\|\mathbf{w}\|_2)^2$, where $\|\mathbf{w}\|_2$ represents the ℓ_2 norm of the weight vector. For Gradient Descent, just add $\alpha \mathbf{w}$ to the MSE gradient vector (Equation 4-6).



It is important to scale the data (e.g., using a StandardScaler) before performing Ridge Regression, as it is sensitive to the scale of the input features. This is true of most regularized models.

¹¹ It is common to use the notation $J(\theta)$ for cost functions that don't have a short name; we will often use this notation throughout the rest of this book. The context will make it clear which cost function is being discussed.

¹² Norms are discussed in Chapter 2.

Figure 4-17 shows several Ridge models trained on some linear data using different α value. On the left, plain Ridge models are used, leading to linear predictions. On the right, the data is first expanded using PolynomialFeatures(degree=10), then it is scaled using a StandardScaler, and finally the Ridge models are applied to the resulting features: this is Polynomial Regression with Ridge regularization. Note how increasing α leads to flatter (i.e., less extreme, more reasonable) predictions; this reduces the model's variance but increases its bias.

As with Linear Regression, we can perform Ridge Regression either by computing a closed-form equation or by performing Gradient Descent. The pros and cons are the same. Equation 4-9 shows the closed-form solution (where **A** is the $(n + 1) \times (n + 1)$ identity matrix¹³ except with a 0 in the top-left cell, corresponding to the bias term).

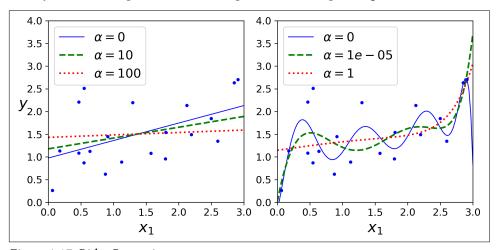


Figure 4-17. Ridge Regression

Equation 4-9. Ridge Regression closed-form solution

$$\widehat{\mathbf{\theta}} = \left(\mathbf{X}^T \mathbf{X} + \alpha \mathbf{A} \right)^{-1} \quad \mathbf{X}^T \quad \mathbf{y}$$

Here is how to perform Ridge Regression with Scikit-Learn using a closed-form solution (a variant of Equation 4-9 using a matrix factorization technique by André-Louis Cholesky):

```
>>> from sklearn.linear_model import Ridge
>>> ridge_reg = Ridge(alpha=1, solver="cholesky")
>>> ridge_reg.fit(X, y)
```

¹³ A square matrix full of 0s except for 1s on the main diagonal (top-left to bottom-right).

```
>>> ridge_reg.predict([[1.5]])
array([[1.55071465]])
```

And using Stochastic Gradient Descent:14

```
>>> sgd_reg = SGDRegressor(penalty="l2")
>>> sgd_reg.fit(X, y.ravel())
>>> sgd_reg.predict([[1.5]])
array([1.47012588])
```

The penalty hyperparameter sets the type of regularization term to use. Specifying "l2" indicates that you want SGD to add a regularization term to the cost function equal to half the square of the ℓ_2 norm of the weight vector: this is simply Ridge Regression.

Lasso Regression

Least Absolute Shrinkage and Selection Operator Regression (simply called Lasso Regression) is another regularized version of Linear Regression: just like Ridge Regression, it adds a regularization term to the cost function, but it uses the ℓ_1 norm of the weight vector instead of half the square of the ℓ_2 norm (see Equation 4-10).

Equation 4-10. Lasso Regression cost function

$$J(\mathbf{\theta}) = \text{MSE}(\mathbf{\theta}) + \alpha \sum_{i=1}^{n} |\theta_i|$$

Figure 4-18 shows the same thing as Figure 4-17 but replaces Ridge models with Lasso models and uses smaller α values.

¹⁴ Alternatively you can use the Ridge class with the "sag" solver. Stochastic Average GD is a variant of SGD. For more details, see the presentation "Minimizing Finite Sums with the Stochastic Average Gradient Algorithm" by Mark Schmidt et al. from the University of British Columbia.

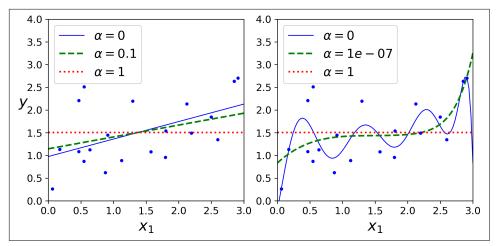


Figure 4-18. Lasso Regression

An important characteristic of Lasso Regression is that it tends to completely eliminate the weights of the least important features (i.e., set them to zero). For example, the dashed line in the right plot on Figure 4-18 (with $\alpha = 10^{-7}$) looks quadratic, almost linear: all the weights for the high-degree polynomial features are equal to zero. In other words, Lasso Regression automatically performs feature selection and outputs a *sparse model* (i.e., with few nonzero feature weights).

You can get a sense of why this is the case by looking at Figure 4-19: on the top-left plot, the background contours (ellipses) represent an unregularized MSE cost function ($\alpha=0$), and the white circles show the Batch Gradient Descent path with that cost function. The foreground contours (diamonds) represent the ℓ_1 penalty, and the triangles show the BGD path for this penalty only ($\alpha\to\infty$). Notice how the path first reaches $\theta_1=0$, then rolls down a gutter until it reaches $\theta_2=0$. On the top-right plot, the contours represent the same cost function plus an ℓ_1 penalty with $\alpha=0.5$. The global minimum is on the $\theta_2=0$ axis. BGD first reaches $\theta_2=0$, then rolls down the gutter until it reaches the global minimum. The two bottom plots show the same thing but uses an ℓ_2 penalty instead. The regularized minimum is closer to $\theta=0$ than the unregularized minimum, but the weights do not get fully eliminated.

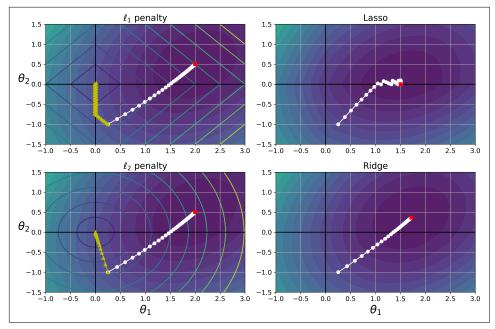


Figure 4-19. Lasso versus Ridge regularization



On the Lasso cost function, the BGD path tends to bounce across the gutter toward the end. This is because the slope changes abruptly at $\theta_2 = 0$. You need to gradually reduce the learning rate in order to actually converge to the global minimum.

The Lasso cost function is not differentiable at $\theta_i = 0$ (for $i = 1, 2, \dots, n$), but Gradient Descent still works fine if you use a *subgradient vector* \mathbf{g}^{15} instead when any $\theta_i = 0$. Equation 4-11 shows a subgradient vector equation you can use for Gradient Descent with the Lasso cost function.

Equation 4-11. Lasso Regression subgradient vector

$$g(\boldsymbol{\theta}, J) = \nabla_{\boldsymbol{\theta}} \operatorname{MSE}(\boldsymbol{\theta}) + \alpha \begin{pmatrix} \operatorname{sign}(\theta_{1}) \\ \operatorname{sign}(\theta_{2}) \\ \vdots \\ \operatorname{sign}(\theta_{n}) \end{pmatrix} \quad \text{where } \operatorname{sign}(\theta_{i}) = \begin{cases} -1 & \text{if } \theta_{i} < 0 \\ 0 & \text{if } \theta_{i} = 0 \\ +1 & \text{if } \theta_{i} > 0 \end{cases}$$

¹⁵ You can think of a subgradient vector at a nondifferentiable point as an intermediate vector between the gradient vectors around that point.

Here is a small Scikit-Learn example using the Lasso class. Note that you could instead use an SGDRegressor(penalty="l1").

```
>>> from sklearn.linear_model import Lasso
>>> lasso_reg = Lasso(alpha=0.1)
>>> lasso_reg.fit(X, y)
>>> lasso_reg.predict([[1.5]])
array([1.53788174])
```

Elastic Net

Elastic Net is a middle ground between Ridge Regression and Lasso Regression. The regularization term is a simple mix of both Ridge and Lasso's regularization terms, and you can control the mix ratio r. When r = 0, Elastic Net is equivalent to Ridge Regression, and when r = 1, it is equivalent to Lasso Regression (see Equation 4-12).

Equation 4-12. Elastic Net cost function

$$J(\mathbf{\theta}) = \text{MSE}(\mathbf{\theta}) + r\alpha \sum_{i=1}^{n} \left| \theta_i \right| + \frac{1-r}{2} \alpha \sum_{i=1}^{n} \theta_i^2$$

So when should you use plain Linear Regression (i.e., without any regularization), Ridge, Lasso, or Elastic Net? It is almost always preferable to have at least a little bit of regularization, so generally you should avoid plain Linear Regression. Ridge is a good default, but if you suspect that only a few features are actually useful, you should prefer Lasso or Elastic Net since they tend to reduce the useless features' weights down to zero as we have discussed. In general, Elastic Net is preferred over Lasso since Lasso may behave erratically when the number of features is greater than the number of training instances or when several features are strongly correlated.

Here is a short example using Scikit-Learn's ElasticNet (l1_ratio corresponds to the mix ratio r):

```
>>> from sklearn.linear_model import ElasticNet
>>> elastic_net = ElasticNet(alpha=0.1, l1_ratio=0.5)
>>> elastic_net.fit(X, y)
>>> elastic net.predict([[1.5]])
array([1.54333232])
```

Early Stopping

A very different way to regularize iterative learning algorithms such as Gradient Descent is to stop training as soon as the validation error reaches a minimum. This is called early stopping. Figure 4-20 shows a complex model (in this case a high-degree Polynomial Regression model) being trained using Batch Gradient Descent. As the epochs go by, the algorithm learns and its prediction error (RMSE) on the training set naturally goes down, and so does its prediction error on the validation set. However,

after a while the validation error stops decreasing and actually starts to go back up. This indicates that the model has started to overfit the training data. With early stopping you just stop training as soon as the validation error reaches the minimum. It is such a simple and efficient regularization technique that Geoffrey Hinton called it a "beautiful free lunch."

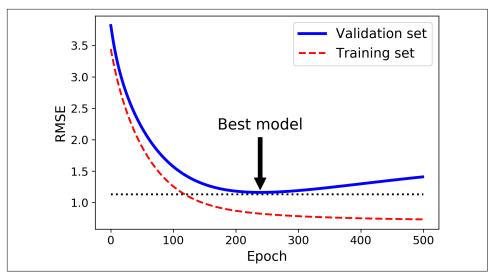


Figure 4-20. Early stopping regularization



With Stochastic and Mini-batch Gradient Descent, the curves are not so smooth, and it may be hard to know whether you have reached the minimum or not. One solution is to stop only after the validation error has been above the minimum for some time (when you are confident that the model will not do any better), then roll back the model parameters to the point where the validation error was at a minimum.

Here is a basic implementation of early stopping:

```
minimum_val_error = float("inf")
best_epoch = None
best_model = None
for epoch in range(1000):
    sgd_reg.fit(X_train_poly_scaled, y_train) # continues where it left off
    y_val_predict = sgd_reg.predict(X_val_poly_scaled)
    val_error = mean_squared_error(y_val, y_val_predict)
    if val_error < minimum_val_error:
        minimum_val_error = val_error
        best_epoch = epoch
        best_model = clone(sqd_reg)</pre>
```

Note that with warm_start=True, when the fit() method is called, it just continues training where it left off instead of restarting from scratch.

Logistic Regression

As we discussed in Chapter 1, some regression algorithms can be used for classification as well (and vice versa). Logistic Regression (also called Logit Regression) is commonly used to estimate the probability that an instance belongs to a particular class (e.g., what is the probability that this email is spam?). If the estimated probability is greater than 50%, then the model predicts that the instance belongs to that class (called the positive class, labeled "1"), or else it predicts that it does not (i.e., it belongs to the negative class, labeled "0"). This makes it a binary classifier.

Estimating Probabilities

So how does it work? Just like a Linear Regression model, a Logistic Regression model computes a weighted sum of the input features (plus a bias term), but instead of outputting the result directly like the Linear Regression model does, it outputs the *logistic* of this result (see Equation 4-13).

Equation 4-13. Logistic Regression model estimated probability (vectorized form)

$$\hat{p} = h_{\mathbf{\theta}}(\mathbf{x}) = \sigma(\mathbf{x}^T \mathbf{\theta})$$

The logistic—noted $\sigma(\cdot)$ —is a *sigmoid function* (i.e., *S*-shaped) that outputs a number between 0 and 1. It is defined as shown in Equation 4-14 and Figure 4-21.

Equation 4-14. Logistic function

$$\sigma(t) = \frac{1}{1 + \exp(-t)}$$