


550 nm, Green Light

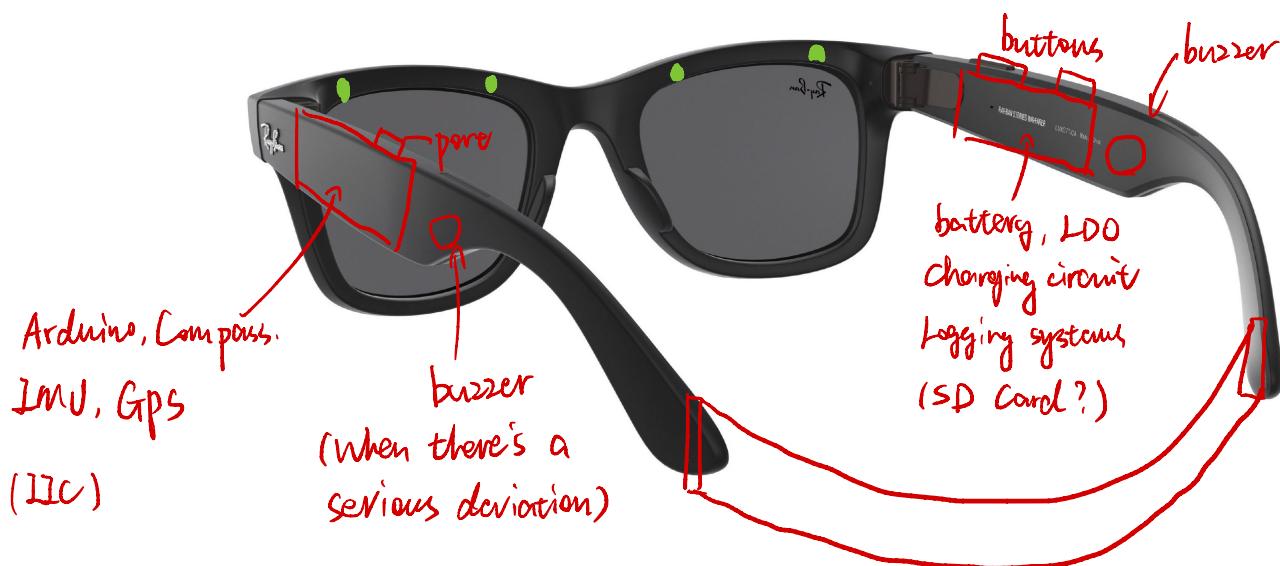
peripheral vision

haptic

ergonomic

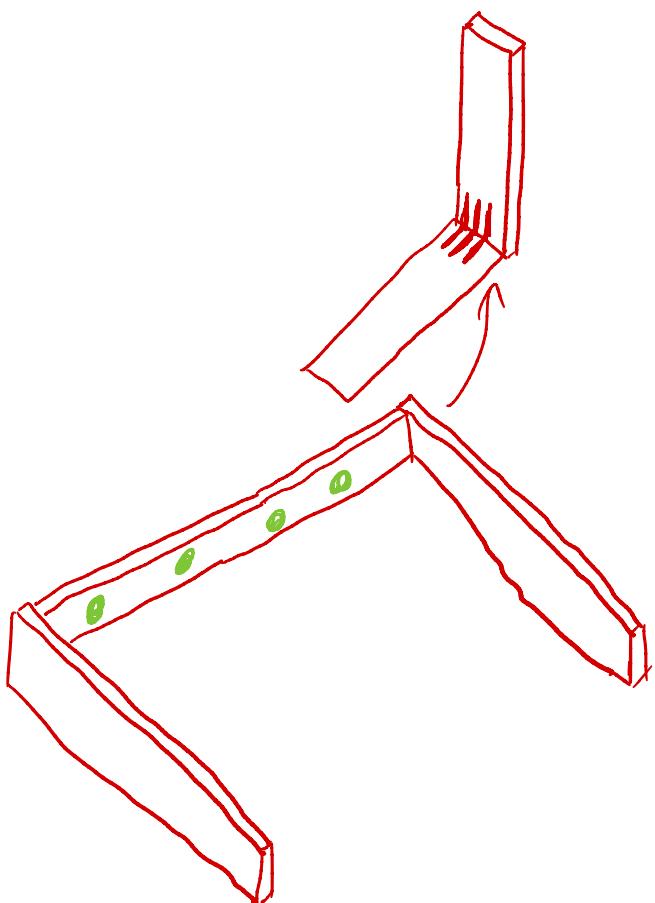
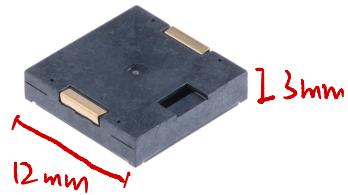
turn on/off

bone conduction



Arduino → ATmega328 / 4809

SHD buzzer

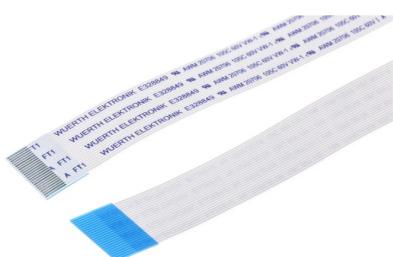


Pin Description:

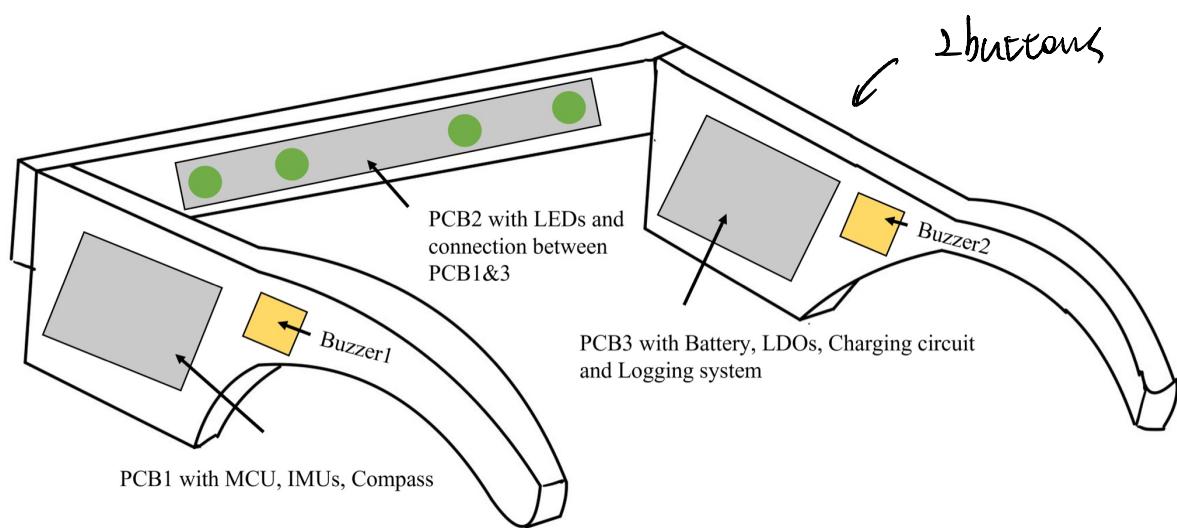
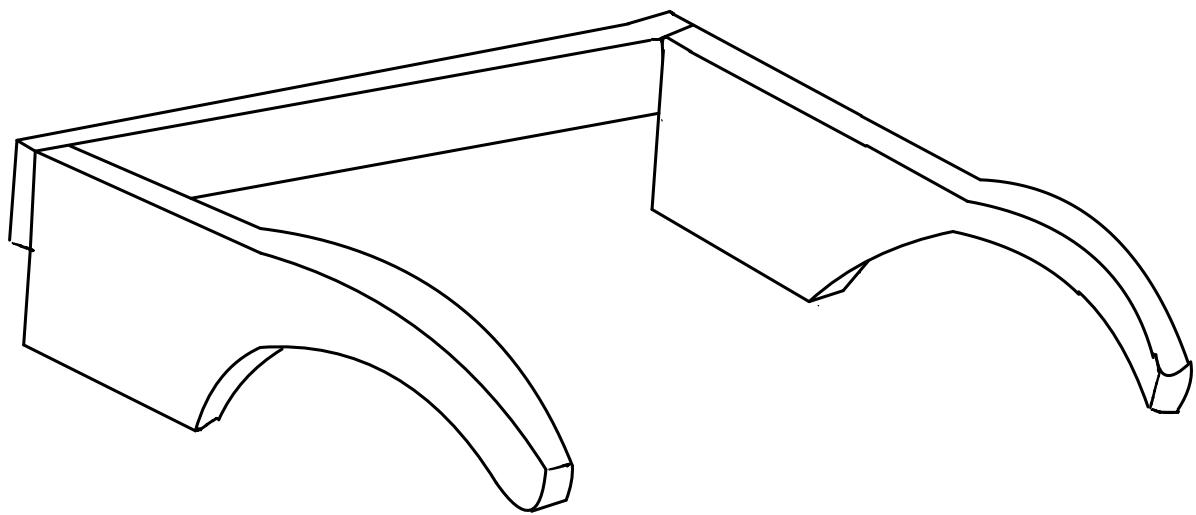


PIN	PIN Name	I/O	Description
1	GND	G	Ground
2	TX	O	Serial Data Output.
3	RX	I	Serial Data Input.
4	VCC	I	DC 3.0V - 5.5V supply input, Typical: 5.0V

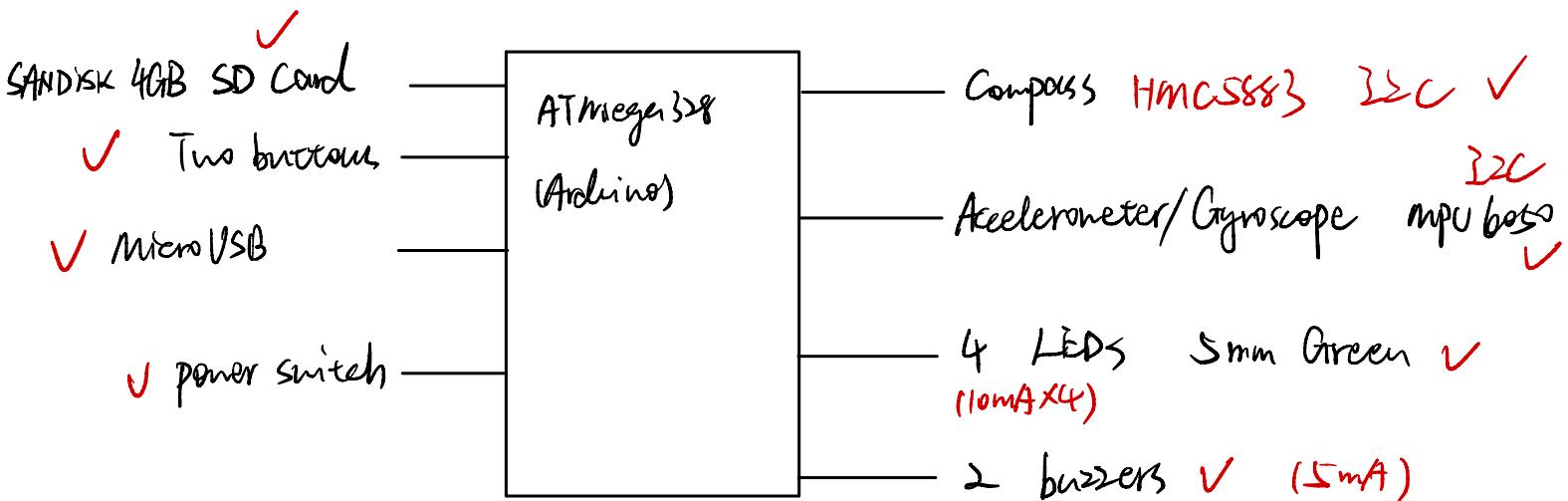
UART/DIe



feedback, LED, audio, intensity, piezo (gesture), software, state machine, press (short/long), power consumption, risk management, economic, time for use



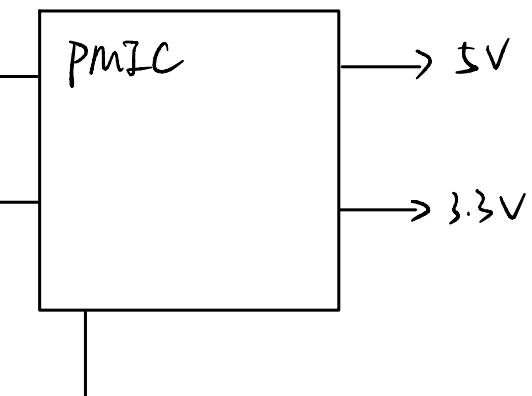
16MHz oscillator ✓



10x30x5 250mAh

✓ Battery

charging



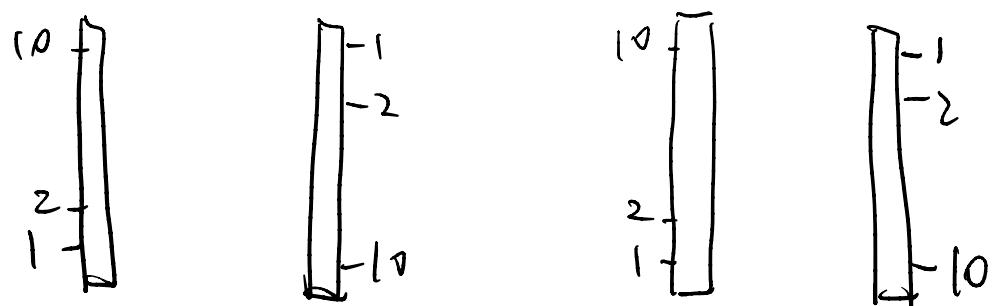
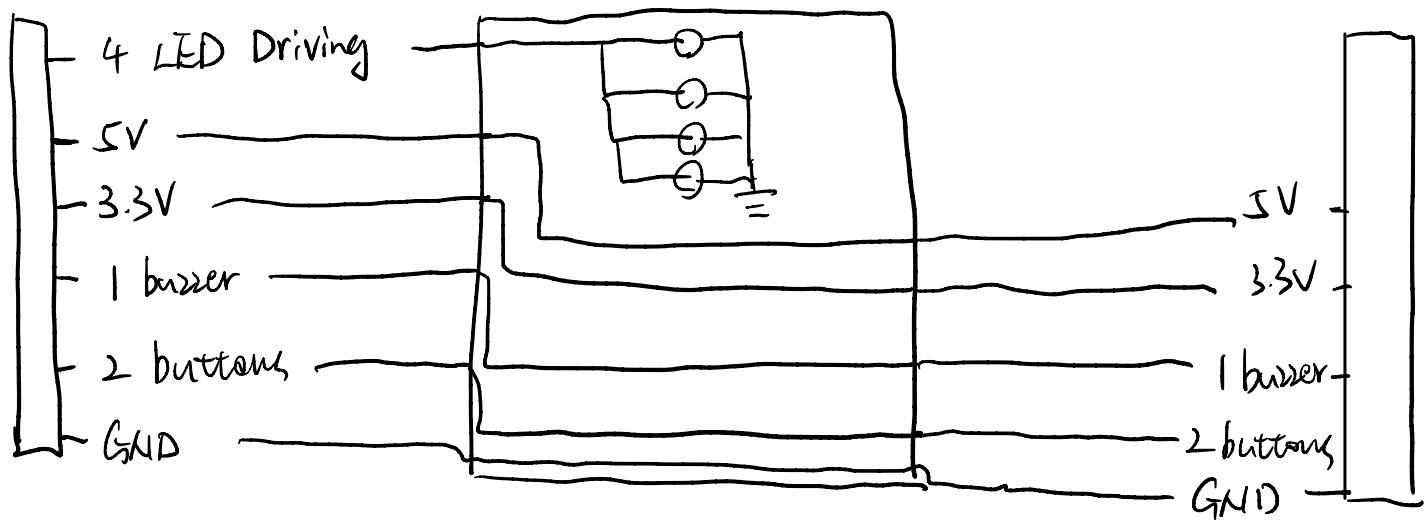
FFC/connector
↑
different side contact

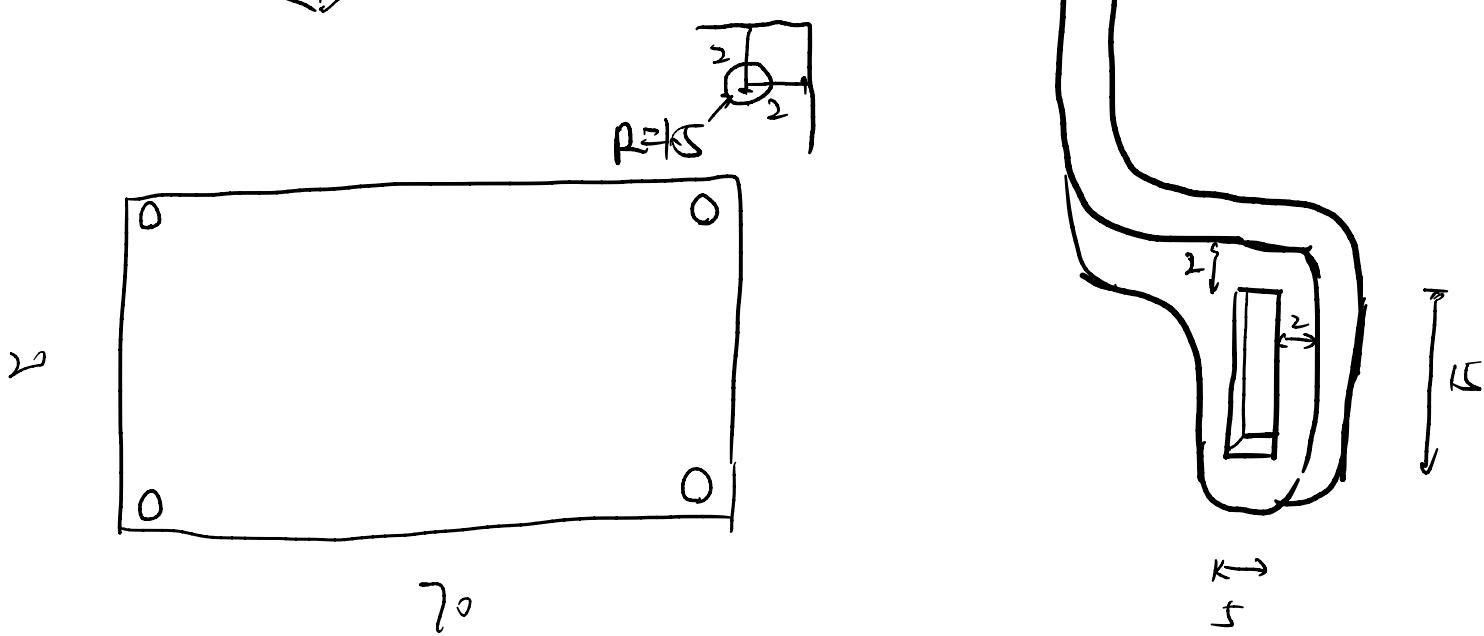
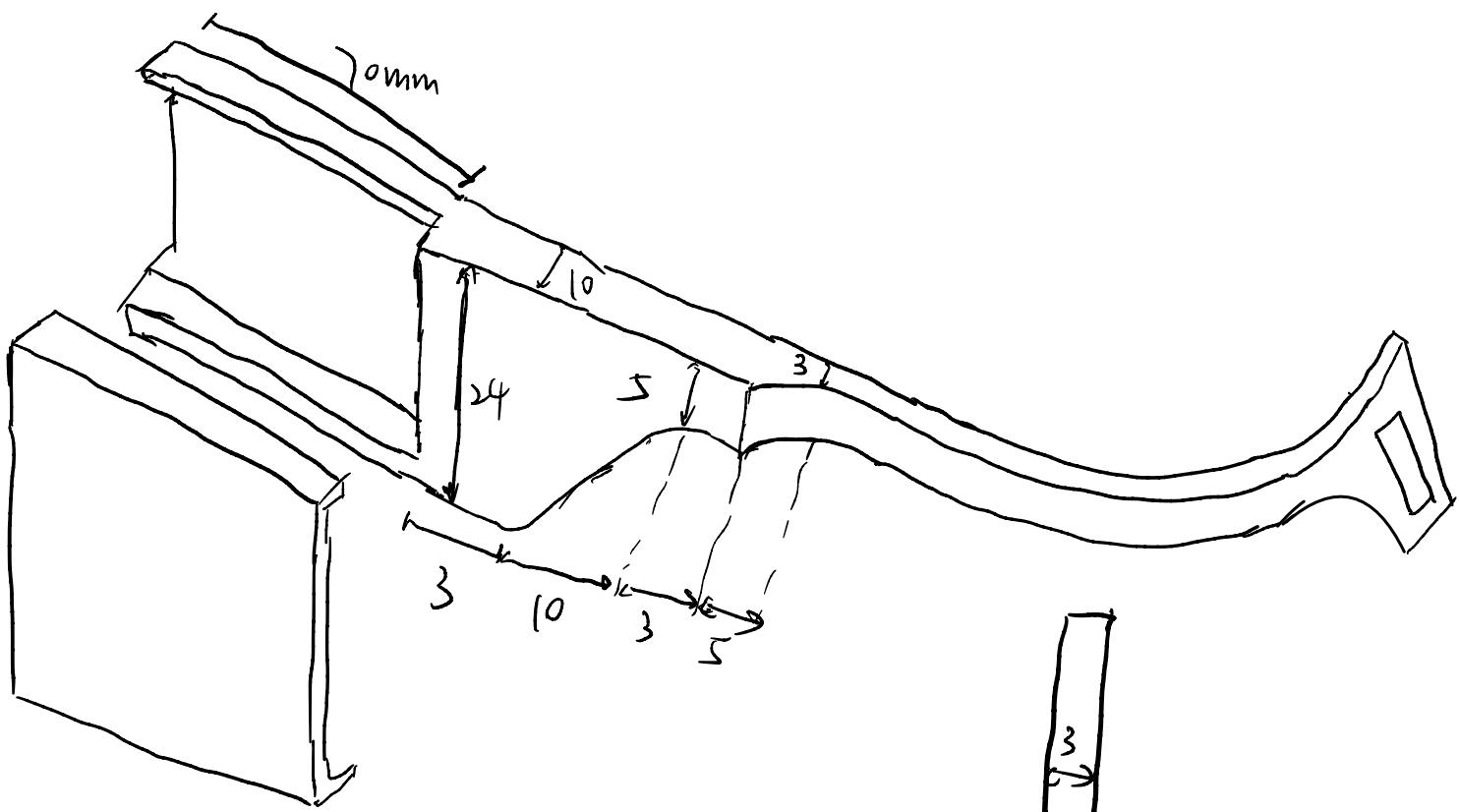
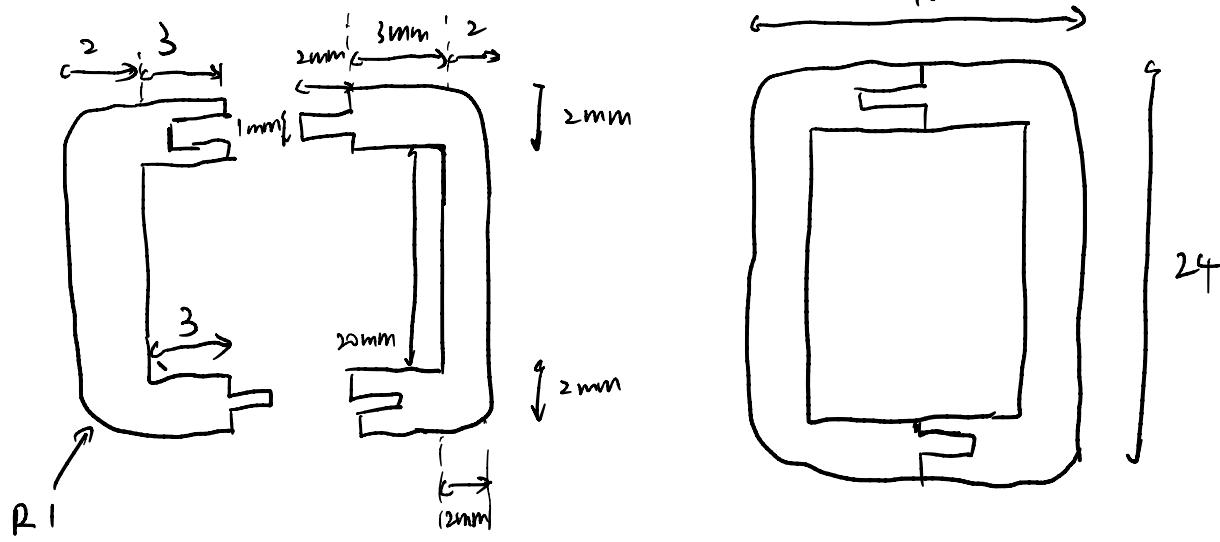
Disconnect battery
when connect to PC

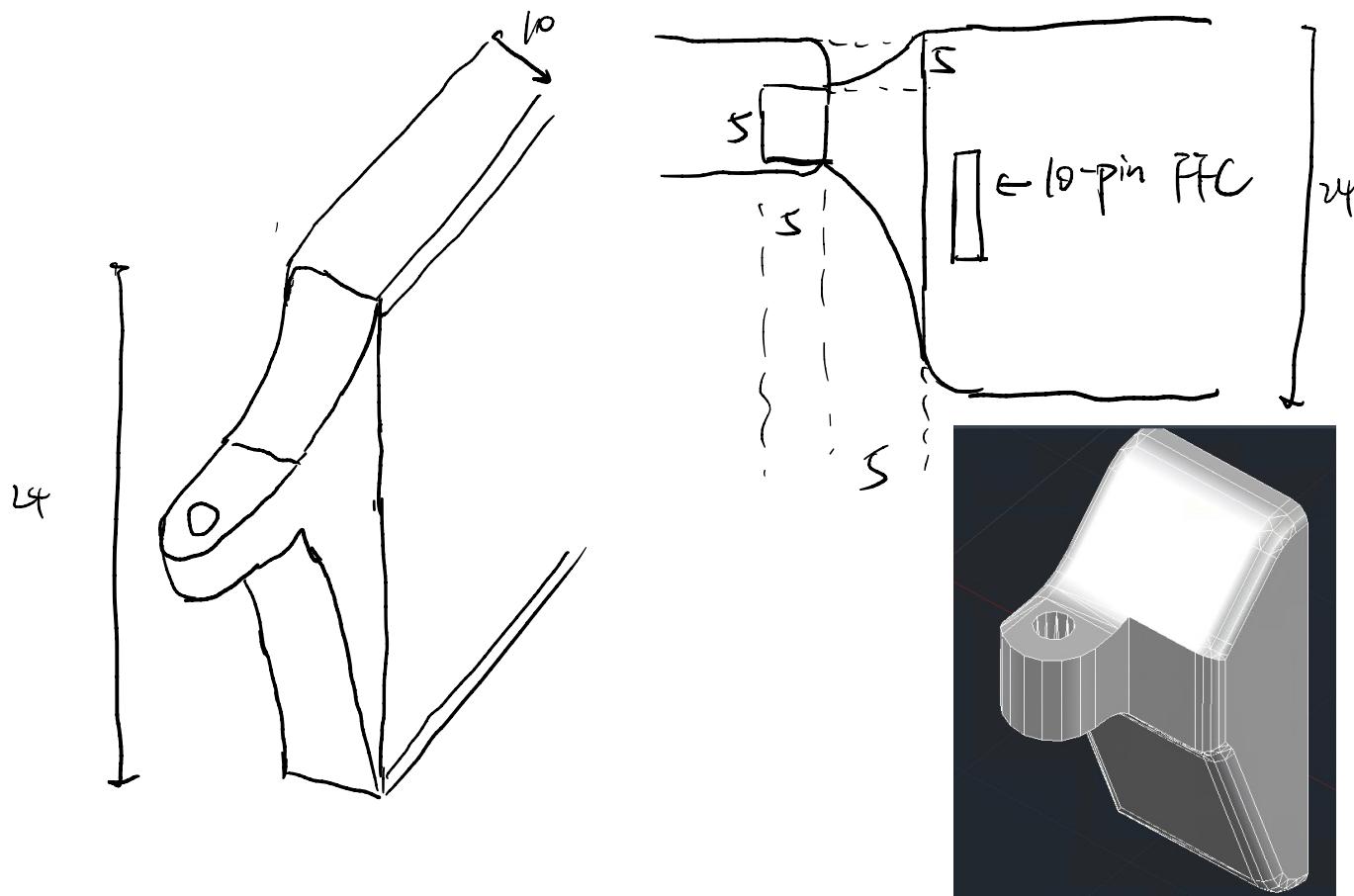
Voltage translators 3.3V \Rightarrow 5V \Rightarrow I₂C ✓

Q1: Separate LDO for sensors?

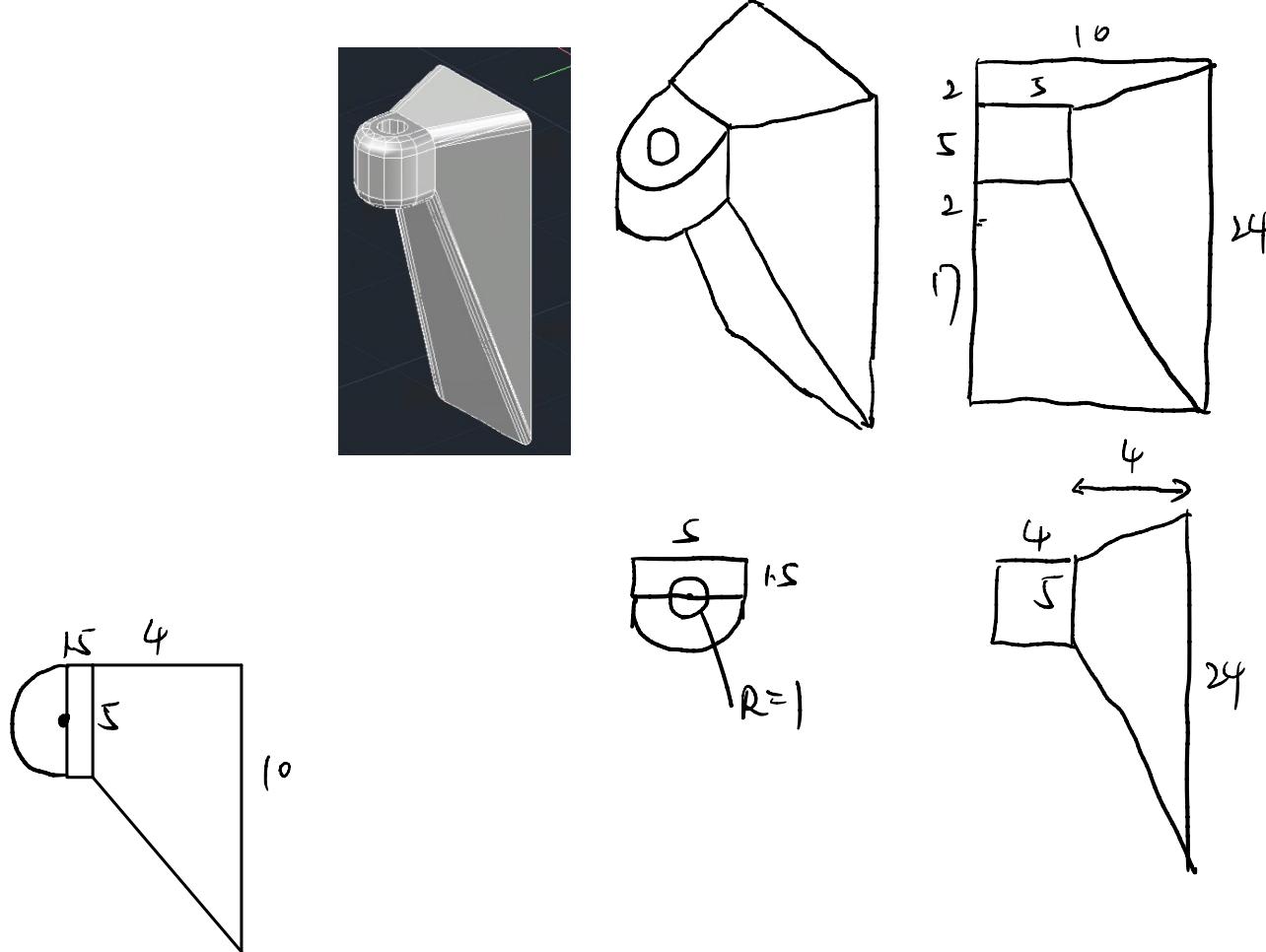
Q2: Not available in preferred supplier. → desolder



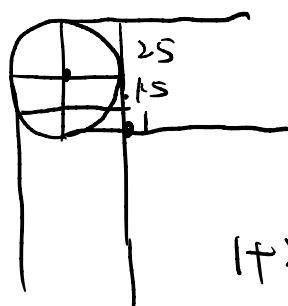
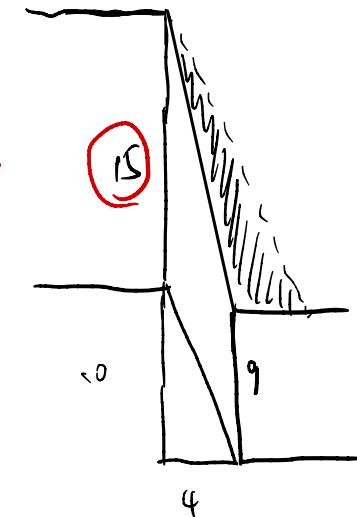
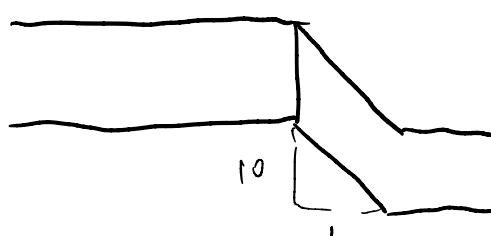
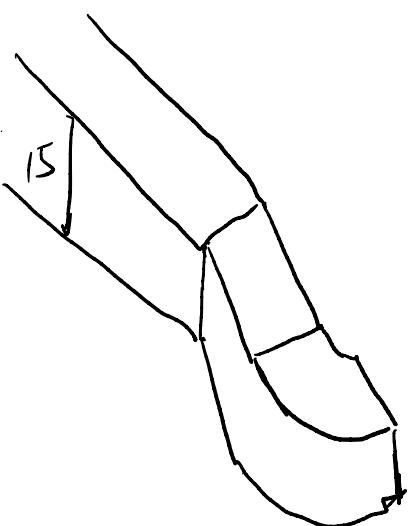
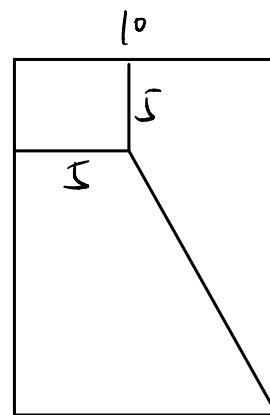
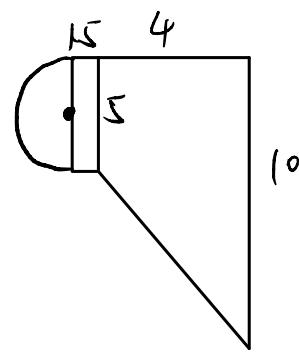
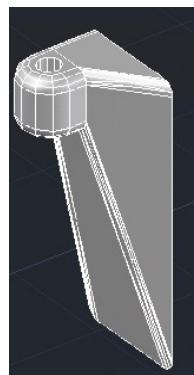




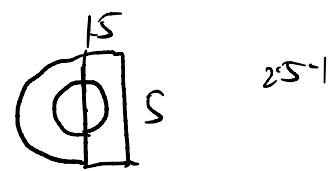
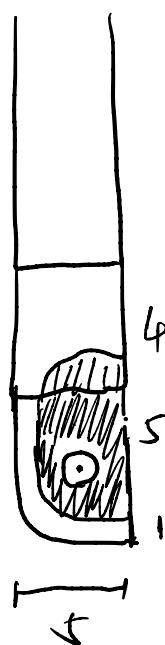
Design V2



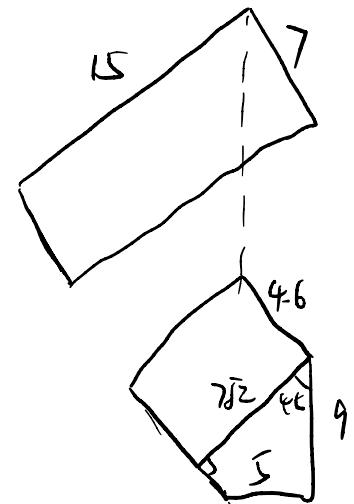
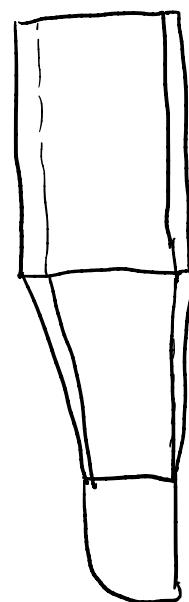
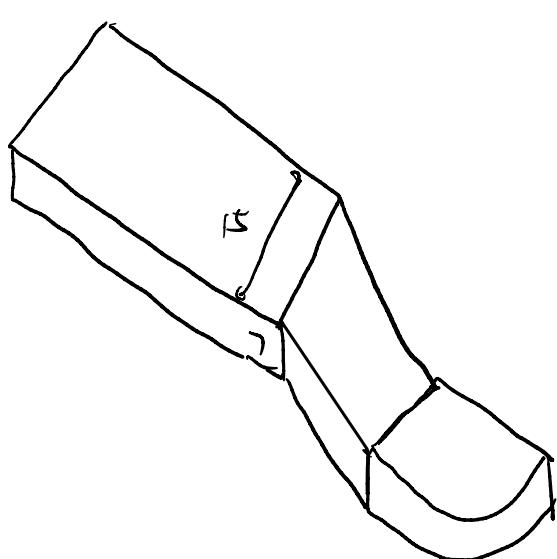
Design V3

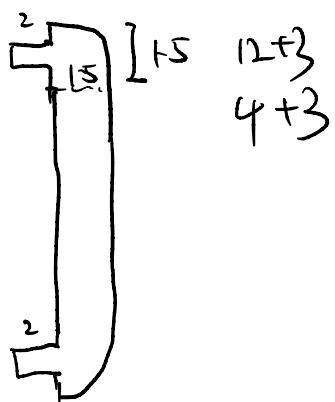
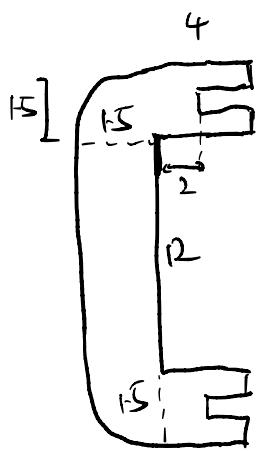


1+25+5

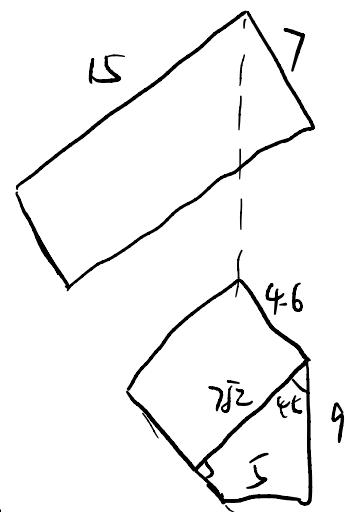


25-1





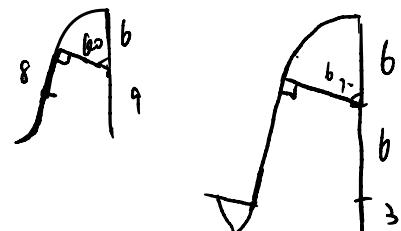
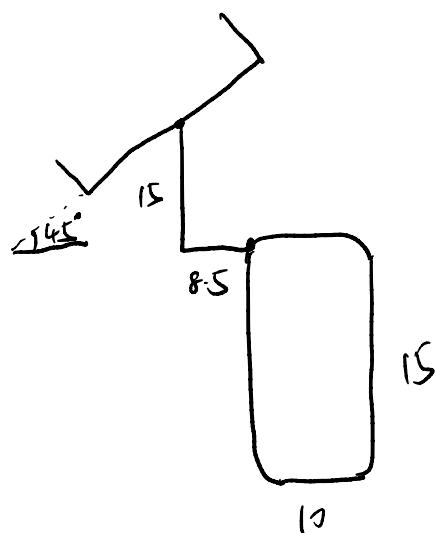
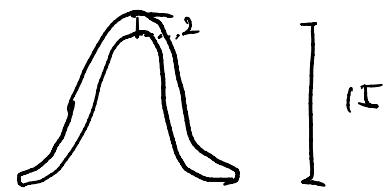
$12+3$
 $4+3$



JO.3

89.713

129.125



$$\delta = 13.5$$

$$\theta = 1^\circ$$

calibrate mpu6050 / HMC5883L
check the presence of micro SD

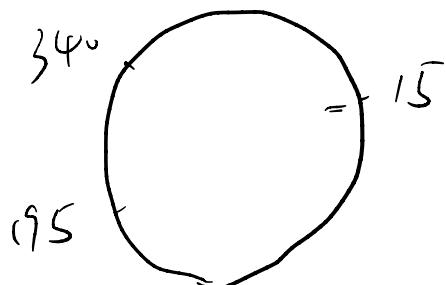
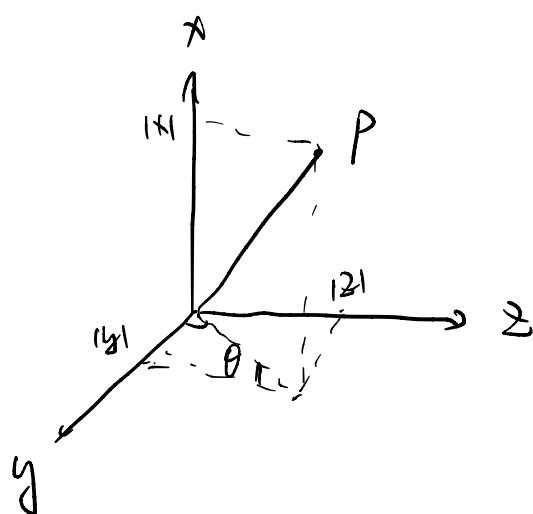
stage 0

- blinking all LEDs
waiting for user to press Button 1
{ otherwise stay here forever

stage 1

{
 Button 1 pressed.
 Record the current 5883 reading.
 Setting it as the desired direction
 Light up LEDs accordingly
 Power up buzzer to alert with big deviation
 writing readings mpu/5883 to micro SD
 at 50Hz
 Look to another direction if B1 pressed
 again
 return to stage 0 if B2 pressed

Additional button functions } Turn on/off the buzzer
} adjust the brightness of LEDs



$$360 + 15 - 340$$

heading $(15 \sim 95) \Rightarrow \text{Deltor}(0, 180)$

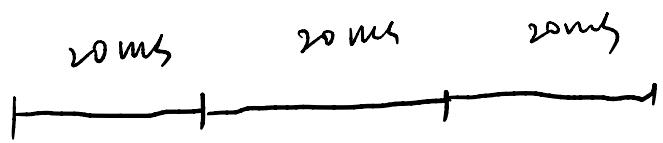
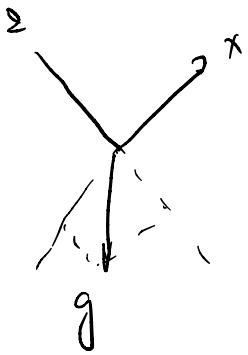
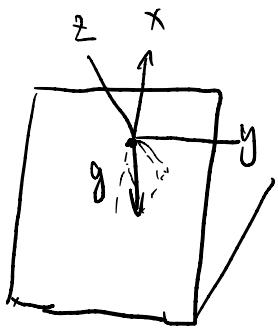
heading $(195 \sim 360, 0 \sim 15) \Rightarrow \text{Deltor}(-180, 0)$

if $\delta > 180^\circ$ $(-15, 0)$

heading $-360 - \text{target}$

if $\delta < 180^\circ$

$360 - \text{target} + \text{heading}$



fx int16 (2 byte)

