

## Homework 3

1. Express the following fractions as a sum of their partial fractions

(a)  $\frac{3s+4}{s^2+3s+2}$

(b)  $\frac{3s^2+8s+6}{(s+1)^2(s+2)}$

a).  $\frac{3s+4}{s^2+3s+2} = \frac{3s+4}{(s+2)(s+1)} = \frac{2}{s+2} + \frac{1}{s+1}$

b).  $\frac{3s^2+8s+6}{(s+1)^2(s+2)} = \frac{2}{s+2} + \frac{1}{s+1} + \frac{1}{(s+1)^2}$

2. Consider the ordinary differential equation

$$\ddot{x} + 5\dot{x} + 6x = u.$$

(a) Determine the state-space representation  $\dot{z} = f(z, u)$  for this ordinary differential equation.

(b) Show that  $f(z)$  can be written in the form  $Az + Bu$ , where  $A$  is a  $2 \times 2$  matrix and  $B$  is a  $2 \times 1$  vector. Find  $A$  and  $B$ .

a).  $\begin{cases} x_1 = x \\ x_2 = \dot{x} \end{cases} \Rightarrow \begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = -5x_2 - 6x_1 + u \end{cases} \Rightarrow \dot{z} = \begin{bmatrix} x_2 \\ u - 5x_2 - 6x_1 \end{bmatrix}$

b).  $\dot{z} = \underbrace{\begin{bmatrix} 0 & 1 \\ -6 & -5 \end{bmatrix}}_{A_{2 \times 2}} \cdot z + \underbrace{\begin{bmatrix} 0 \\ u \end{bmatrix}}_{B_{2 \times 1}}$

3. Consider the time-invariant ordinary differential equation

$$\ddot{x} + 10\dot{x} + 9x = 0$$

(a) Determine its characteristic polynomial.

(b) Determine the solution  $x(t)$  for this ordinary differential equation, given that  $x(0) = 0$  and  $\dot{x}(0) = 8$ .

(c) Determine a state-space representation of the form  $\dot{z} = Az$  for this ordinary differential equation, where  $A$  is a  $2 \times 2$  matrix; that is, find  $A$ .

(d) Determine the polynomial in  $\lambda$  by computing  $\det(A - \lambda I)$ ; here  $I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  is an identity matrix. How does this polynomial compare with the characteristic polynomial obtained in (a)?

$$\begin{aligned} \text{a). } \left. \begin{aligned} \text{let } x &= e^{\lambda t} \\ \therefore \dot{x} &= \lambda e^{\lambda t} \\ \ddot{x} &= \lambda^2 e^{\lambda t} \end{aligned} \right\} \Rightarrow \lambda^2 e^{\lambda t} + 10\lambda e^{\lambda t} + 9e^{\lambda t} = 0 \\ \therefore \lambda^2 + 10\lambda + 9 = (\lambda + 9)(\lambda + 1) = 0 \end{aligned}$$

b). From a) we know  $\lambda_1 = -9, \lambda_2 = -1$

$$\therefore x_1 = e^{-9t}, x_2 = e^{-t}$$

$$x = c_1 e^{-9t} + c_2 e^{-t}$$

$$\therefore \begin{cases} x(0) = 0 \\ \dot{x}(0) = 8 \end{cases} \therefore \begin{cases} c_1 + c_2 = 0 \\ -9c_1 - c_2 = 8 \end{cases} \therefore \begin{cases} c_1 = -1 \\ c_2 = 1 \end{cases}$$

$$\therefore x = e^{-t} - e^{-9t}$$

$$\text{c). } \begin{cases} x_1 = x \\ x_2 = \dot{x} \end{cases} \Rightarrow \begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = -10x_2 - 9x_1 \end{cases} \Rightarrow \dot{z} = \begin{bmatrix} 0 & 1 \\ -9 & -10 \end{bmatrix} \cdot z, \quad A = \begin{bmatrix} 0 & 1 \\ -9 & -10 \end{bmatrix}$$

$$\text{d). } A - \lambda_1 I = \begin{bmatrix} 0 & 1 \\ -9 & -10 \end{bmatrix} - \begin{bmatrix} -9 & 0 \\ 0 & -9 \end{bmatrix} = \begin{bmatrix} 9 & 1 \\ -9 & -1 \end{bmatrix} \therefore \det = 0$$

$$A - \lambda_2 I = \begin{bmatrix} 0 & 1 \\ -9 & -10 \end{bmatrix} - \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ -9 & -9 \end{bmatrix} \therefore \det = 0$$

$\therefore$  Computing  $\det(A - \lambda I) = 0$  we get the same  $\lambda$  in a).

4. Consider a first-order system

$$\tau \dot{y} + y = ku(t), \quad y(0) = y_0$$

where  $\tau > 0$  and  $k$  are constants.

(a) *free response*: determine the free response, that is find  $y(t)$  when  $u(t) = 0$  and  $y_0 \neq 0$ . Show that the steady state response  $y_{ss}(t) = \lim_{t \rightarrow \infty} y(t) = 0$ . 通解

(b) *sinusoidal response*:

i. determine the *sinusoidal* response, that is find  $y(t)$  when  $u(t) = A \sin \omega t$  and  $y_0 \neq 0$ .

ii. let  $G(s) = \frac{k}{\tau s + 1}$ . Show that the *steady-state* sinusoidal response

$$y_{ss}(t) = \lim_{t \rightarrow \infty} y(t) = A|G(j\omega)| \sin(\omega t + \phi), \text{ where } \phi = \angle G(j\omega)$$

[Hint: It is enough to show that  $\lim_{t \rightarrow \infty} \{y(t) - A|G(j\omega)| \sin(\omega t + \phi)\} = 0$ ]

a.  $\therefore \tau \cdot y' + y = 0$

$$\therefore \tau \cdot \frac{dy}{dt} = -y$$

$$\int \tau \frac{dy}{y} = \int \frac{-1}{dt}$$

$$\tau \ln y = -t + C$$

$$y = e^{-\frac{t}{\tau} + C}$$

$$\therefore y(0) = y_0 \therefore y = e^{-\frac{t}{\tau}} + y_0 - 1$$

$$\therefore y_{ss}(t) = e^{-\frac{t}{\tau}} \Rightarrow \lim_{t \rightarrow \infty} y_{ss}(t) = 0$$

b. i).  $\tau \cdot y' + y = k \cdot A \cdot \sin(\omega t)$

From a) we know  $y_H = C_1 e^{-\frac{t}{\tau}}$ ,  $\lambda = -\frac{1}{\tau}$

For the  $y_p$  of  $u(t) = A \cdot \sin(\omega t)$

$$y_p = C_2 \cdot \sin(\omega t) + C_3 \cdot \cos(\omega t)$$

$$\therefore y_p' = \omega C_2 \cdot \cos(\omega t) - \omega C_3 \cdot \sin(\omega t)$$

$$\therefore \begin{cases} C_3 + \omega \tau C_2 = 0 \\ C_2 - \omega \tau C_3 = k \cdot A \end{cases} \Rightarrow \begin{cases} C_2 = \frac{kA}{1 + \omega^2 \tau^2} \\ C_3 = \frac{-kA \omega \tau}{1 + \omega^2 \tau^2} \end{cases}$$

$$\therefore y = y_H + y_p = C_1 \cdot e^{-\frac{t}{\tau}} + C_2 \cdot \sin(\omega t) + C_3 \cdot \cos(\omega t)$$

b ii).

$$|G(j\omega)| = \left| \frac{k}{\tau j\omega + 1} \right| = \left| \frac{k(1 - j\tau\omega)}{1 + \tau^2 \omega^2} \right| = \frac{k}{\sqrt{1 + \tau^2 \omega^2}}$$

$$\lim_{t \rightarrow \infty} y(t) = C_2 \sin(\omega t) + C_3 \cos(\omega t)$$

$$= \frac{kA}{1 + \omega^2 \tau^2} \sin(\omega t) - \frac{kA \omega \tau}{1 + \omega^2 \tau^2} \cos(\omega t)$$

$$= \frac{kA}{\sqrt{1 + \omega^2 \tau^2}} \left[ \frac{1}{\sqrt{1 + \omega^2 \tau^2}} \sin(\omega t) - \frac{\omega \tau}{\sqrt{1 + \omega^2 \tau^2}} \cos(\omega t) \right]$$

$$= A \cdot |G(j\omega)| \cdot \sin(\omega t + \phi)$$

q.e.d

5. Solve the following ordinary differential equations with given initial conditions:

✓(a)  $\dot{x} + x = \cos t$ ,  $x(0) = 1$

✓(b)  $\ddot{y} + 4\dot{y} + 3y = 2e^{-t}$ ,  $y(0) = 0$ ;  $\dot{y}(0) = 0.5$

✓(c)  $\ddot{x} + x = e^{-t}$ ,  $x(0) = 1$ ;  $\dot{x}(0) = \frac{1}{2}$

✓(d)  $\frac{d^4x}{dt^4} + 2\ddot{x} + x = 0$ ,  $x(0) = 1$ ;  $\dot{x}(0) = 1$ ;  $\ddot{x}(0) = -1$ ;  $\ddot{\ddot{x}}(0) = -3$

a).  $x' + x = \cos t$

① For  $x_H$

$$\left. \begin{array}{l} x' + x = 0 \\ x(0) = 1 \end{array} \right\} \Rightarrow x_H = e^{-t}$$

② For  $x_P$

$$x_P = C_1 \sin t + C_2 \cos t$$

$$\therefore x(0) = 1$$

$$\therefore C_1 \cos t - C_2 \sin t + C_1 \sin t + C_2 \cos t = \cos t$$

$$\begin{cases} C_1 + C_2 = 1 \\ C_1 - C_2 = 0 \end{cases} \Rightarrow \begin{cases} C_1 = \frac{1}{2} \\ C_2 = \frac{1}{2} \end{cases} \Rightarrow x_P = \frac{1}{2} \sin t + \frac{1}{2} \cos t$$

$$\therefore x = x_H + x_P = \frac{1}{2} e^{-t} + \frac{1}{2} \sin t + \frac{1}{2} \cos t$$

b). ① For  $y_H$ .  $y'' + 4y' + 3y = 0$

$$\therefore \lambda_1 = -3, \lambda_2 = -1$$

$$y_1 = e^{-3t}, y_2 = e^{-t}$$

$$\therefore y_H = C_1 e^{-3t} + C_2 e^{-t}$$

② For  $y_P$ .

$$\therefore y_P = C_3 \cdot t e^{-t}$$

$$\therefore y_P' = -C_3 t e^{-t} + C_3 e^{-t}$$

$$y_P'' = C_3 t e^{-t} - C_3 e^{-t} - C_3 e^{-t} = C_3 t e^{-t} - 2C_3 e^{-t}$$

$$\therefore C_3 = 1 \quad \therefore y_P = t e^{-t}$$

$$\therefore \begin{cases} x(0) = 1 \\ \dot{x}(0) = \frac{1}{2} \end{cases} \Rightarrow \begin{cases} C_1 = \frac{1}{4} \\ C_2 = -\frac{1}{4} \end{cases}$$

$$\therefore y = y_P + y_H = \frac{1}{4} e^{-3t} - \frac{1}{4} e^{-t} + t e^{-t}$$

c). For  $x_H$ .  $\ddot{x} + x = 0$

$$\therefore \lambda^2 + 1 = 0$$

$$\therefore \lambda = \pm i$$

$$\therefore x_1 = \cos t, x_2 = \sin t$$

For  $x_P$ .  $e^{-t}$

$$\therefore x_P = C_3 \cdot e^{-t}$$

$$\therefore x_P'' = C_3 e^{-t}$$

$$\therefore C_3 = \frac{1}{2}, x_P = \frac{1}{2} e^{-t}$$

$$\therefore x = C_1 \cos t + C_2 \sin t + \frac{1}{2} e^{-t}$$

$$\therefore \begin{cases} x(0) = 1 \\ \dot{x}(0) = \frac{1}{2} \end{cases} \Rightarrow \begin{cases} C_1 = \frac{1}{2} \\ C_2 = 1 \end{cases} \therefore x = \frac{1}{2} \cos t + \sin t + \frac{1}{2} e^{-t}$$

d). For  $x_H$

$$\therefore \lambda^4 + 2\lambda^2 + 1 = 0$$

$$\therefore (\lambda^2 + 1)^2 = 0$$

$$\therefore \lambda_1 = i, \lambda_2 = i, \lambda_3 = -i, \lambda_4 = -i$$

$$\therefore x_1 = \cos t, x_2 = t \cos t$$

$$x_3 = \sin t, x_4 = t \sin t$$

$$\therefore x = C_1 \cos t + C_2 t \cos t + C_3 \sin t + C_4 t \sin t$$

$$\therefore \begin{cases} x(0) = 1 \\ \dot{x}(0) = 1 \\ \ddot{x}(0) = -1 \\ \ddot{\ddot{x}}(0) = -3 \end{cases} \Rightarrow \begin{cases} C_1 = 1 \\ C_2 = 1 \\ C_3 = 0 \\ C_4 = 0 \end{cases} \Rightarrow x = \cos t + t \cos t$$

6. For a third-order, linear, time-invariant, homogenous ordinary differential equation with certain initial conditions, the solution is given by

$$x(t) = e^{-2t} + e^{-3t}(\cos t + \sin t)$$

- Determine the roots of the characteristic equation for this ordinary differential equation.
- Determine the characteristic polynomial for this ordinary differential equation.
- Determine the ordinary differential equation.
- Determine the initial conditions  $x(0)$ ,  $\dot{x}(0)$ , and  $\ddot{x}(0)$ .
- Determine the solution to this ordinary differential equation when  $x(0) = 1$ ,  $\dot{x}(0) = -2$ , and  $\ddot{x}(0) = -4$ .

a).  $\therefore x(t) = e^{-2t} + e^{-3t}(\cos t + \sin t)$

$\therefore \lambda_1 = -2, \lambda_2 = -3+i, \lambda_3 = -3-i$

b).  $(\lambda+2)[(\lambda+3)^2+1] = 0$

c).  $(\lambda+2)[(\lambda+3)^2+1] = 0$

$$(\lambda+2)[\lambda^2+6\lambda+10] = 0$$

$$\lambda^3+8\lambda^2+22\lambda+20 = 0$$

$$\ddot{x} + 8\dot{x} + 22x = 0$$

e). Fundamental Solution

$$x_1 = e^{-2t}$$

$$x_2 = e^{-3t} \cos t$$

$$x_3 = e^{-3t} \sin t$$

$$\therefore x = c_1 e^{-2t} + c_2 e^{-3t} \cos t + c_3 e^{-3t} \sin t$$

$$\therefore \begin{cases} x(0)=1 \\ \dot{x}(0)=-2 \\ \ddot{x}(0)=-4 \end{cases} \Rightarrow \begin{cases} c_1 = -3 \\ c_2 = +4 \\ c_3 = +4 \end{cases}$$

$$\therefore x = -3e^{-2t} + 4e^{-3t}(\cos t + \sin t)$$

d).  $\therefore x(t) = e^{-2t} + e^{-3t}(\cos t + \sin t)$

$$\therefore \dot{x}(t) = -2e^{-2t} - 3e^{-3t}(\cos t + \sin t) + e^{-3t}(\cos t - \sin t)$$

$$= -2e^{-2t} + e^{-3t}(-4\sin t - 2\cos t)$$

$$\ddot{x}(t) = 4e^{-2t} + 3e^{-3t}(4\sin t + 2\cos t) + e^{-3t}(-4\cos t + 2\sin t)$$

$$= 4e^{-2t} + e^{-3t}(14\sin t + 2\cos t)$$

$$\therefore \begin{cases} x(0) = 1 \\ \dot{x}(0) = -2 \\ \ddot{x}(0) = -4 \end{cases}$$