MATPOWER Reference Manual

Release 8.0b1

Ray Zimmerman

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Contents

1 Introduction

The purpose of this *Reference Manual* is to provide reference documentation on each class and function in MATPOWER.

This documentation is automatically generated from the corresponding help text in the Matlab source for each function, class, property or method.

The GitHub icon in the upper right of each reference page links to the corresponding source file in the master branch on GitHub.

Currently, this manual includes *only* classes and functions that make up the new **MP-Core** and the **flexible** and **legacy** MATPOWER frameworks, but not the other legacy MATPOWER functions or the included packages MP-Opt-Model, MIPS, MP-Test, or MOST.

2 Functions

2.1 Top-Level Simulation Functions

These are top-level functions intended as user commands for running power flow (PF), continuation power flow (CPF), optimal power flow (OPF) and other custom simulation or optimization tasks.

2.1.1 run_mp

run_mp(*task_class*, *d*, *mpopt*, *varargin*)

run_mp() (page 3) - Run any MATPOWER simulation.

```
run_mp(task_class, d, mpopt)
run_mp(task_class, d, mpopt, ...)
task = run_mp(...)
```

This is **the** main function in the **flexible framework** for running MATPOWER. It creates the task object, applying any specified extensions, runs the task, and prints or saves the solution, if desired.

It is typically called from one of the wrapper functions such as *run_pf()* (page 4), *run_cpf()* (page 5), or *run_opf()* (page 5).

Inputs

- **task_class** (*function handle*) – handle to constructor of default task class for type of task to be run, e.g. *mp.task_pf* (page 18) for power flow, *mp.task_cpf* (page 20) for CPF, and *mp.task_opf* (page 21) for OPF
- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (mpc)
- **mpopt** (*struct*) – MATPOWER options struct

  Additional optional inputs can be provided as *<name>, <val>* pairs, with the following options:

  – 'print_fname' - file name for saving pretty-printed output

  – 'soln_fname' - file name for saving solved case

– 'mpx' - MATPOWER extension or cell array of MATPOWER extensions to apply

Output

task (*mp.task* (page 7)) – task object containing the solved run including the data, network, and mathematical model objects.

Solution results are available in the data model, and its elements, contained in the returned task object. For example:

```
task = run_opf('case9');
lam_p = task.dm.elements.bus.tab.lam_p  % nodal price
pg = task.dm.elements.gen.tab.pg        % generator active dispatch
```

See also *run_pf()* (page 4), *run_cpf()* (page 5), *run_opf()* (page 5), *mp.task* (page 7).

2.1.2 run_pf

run_pf(*varargin*)

run_pf() (page 4) - Run a power flow.

```
run_pf(d, mpopt)
run_pf(d, mpopt, ...)
task = run_pf(...)
```

This is the main function used to run power flow (PF) problems via the **flexible MATPOWER framework**.

This function is a simple wrapper around *run_mp()* (page 3), calling it with the first argument set to `@mp.task_pf`.

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct

  Additional optional inputs can be provided as <*name*>, <*val*> pairs, with the following options:

  – 'print_fname' - file name for saving pretty-printed output

  – 'soln_fname' - file name for saving solved case

  – 'mpx' - MATPOWER extension or cell array of MATPOWER extensions to apply

Output

task (*mp.task_pf* (page 18)) – task object containing the solved run including the data, network, and mathematical model objects.

Solution results are available in the data model, and its elements, contained in the returned task object. For example:

```
task = run_pf('case9');
va = task.dm.elements.bus.tab.va    % bus voltage angles
pg = task.dm.elements.gen.tab.pg    % generator active dispatch
```

See also *run_mp()* (page 3), *mp.task_pf* (page 18).

2.1.3 run_cpf

run_cpf(*varargin*)

run_cpf() (page 5) Run a continuation power flow.

```
run_cpf(d, mpopt)
run_cpf(d, mpopt, ...)
task = run_cpf(...)
```

This is the main function used to run continuation power flow (CPF) problems via the **flexible MATPOWER framework**.

This function is a simple wrapper around *run_mp()* (page 3), calling it with the first argument set to `@mp.task_cpf`.

Inputs

- **d** – data source specification, currently assumed to be a cell array of two MATPOWER case names or case structs (`mpc`), the first being the base case, the second the target case
- **mpopt** (*struct*) – MATPOWER options struct

  Additional optional inputs can be provided as <*name*>, <*val*> pairs, with the following options:

  – `'print_fname'` - file name for saving pretty-printed output

  – `'soln_fname'` - file name for saving solved case

  – `'mpx'` - MATPOWER extension or cell array of MATPOWER extensions to apply

Output

task (*mp.task_cpf* (page 20)) – task object containing the solved run including the data, network, and mathematical model objects.

Solution results are available in the data model, and its elements, contained in the returned task object. For example:

```
task = run_cpf({'case9', 'case9target'});
vm = task.dm.elements.bus.tab.vm    % bus voltage magnitudes
pg = task.dm.elements.gen.tab.pg    % generator active dispatch
```

See also *run_mp()* (page 3), *mp.task_cpf* (page 20).

2.1.4 run_opf

run_opf(*varargin*)

run_opf() (page 5) Run an optimal power flow.

```
run_opf(d, mpopt)
run_opf(d, mpopt, ...)
task = run_opf(...)
```

This is the main function used to run optimal power flow (OPF) problems via the **flexible MATPOWER framework**.

This function is a simple wrapper around *run_mp()* (page 3), calling it with the first argument set to `@mp.task_opf`.

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct

  Additional optional inputs can be provided as <*name*>, <*val*> pairs, with the following options:

  – `'print_fname'` - file name for saving pretty-printed output

  – `'soln_fname'` - file name for saving solved case

  – `'mpx'` - MATPOWER extension or cell array of MATPOWER extensions to apply

Output

task (*mp.task_opf* (page 21)) – task object containing the solved run including the data, network, and mathematical model objects.

Solution results are available in the data model, and its elements, contained in the returned task object. For example:

```
task = run_opf('case9');
lam_p = task.dm.elements.bus.tab.lam_p  % nodal price
pg = task.dm.elements.gen.tab.pg        % generator active dispatch
```

See also *run_mp()* (page 3), *mp.task_opf* (page 21).

2.2 Other Functions

2.2.1 mp_table_class

mp_table_class()

mp_table_class() (page 6) - Returns handle to constructor for `table` or *mp_table* (page 156).

Returns a handle to `table` constructor, if it is available, otherwise to *mp_table* (page 156) constructor. Useful for table-based code that is compatible with both MATLAB (using native tables) and Octave (using *mp_table* (page 156) or the `table` implementation from Tablicious, if available).

```
% Works in MATLAB or Octave, which does not (yet) natively support table().
table_class = mp_table_class();
T = table_class(var1, var2, ...);
```

See also `table`, *mp_table* (page 156).

3 Classes

3.1 Task Classes

3.1.1 Core Task Classes

mp.task

class mp.**task**

Bases: `handle`

mp.task (page 7) - MATPOWER task abstract base class.

Each task type (e.g. power flow, CPF, OPF) will inherit from *mp.task* (page 7).

Provides properties and methods related to the specific problem specification being solved (e.g. power flow, continuation power flow, optimal power flow, etc.). In particular, it coordinates all interactions between the 3 (data, network, mathematical) model layers.

The model objects, and indirectly their elements, as well as the solution success flag and messages from the mathematical model solver, are available in the properties of the task object.

mp.task Properties:

- *tag* (page 9) - task tag - e.g. 'PF', 'CPF', 'OPF'
- *name* (page 9) - task name - e.g. 'Power Flow', etc.
- *dmc* (page 9) - data model converter object
- *dm* (page 9) - data model object
- *nm* (page 9) - network model object
- *mm* (page 9) - mathematical model object
- *mm_opt* (page 9) - solve options for mathematical model
- *i_dm* (page 9) - iteration counter for data model loop
- *i_nm* (page 9) - iteration counter for network model loop

- *i_mm* (page 9) - iteration counter for math model loop
- *success* (page 9) - success flag, 1 - math model solved, 0 - didn't solve
- *message* (page 9) - output message
- *et* (page 9) - elapsed time (seconds) for *run()* (page 9) method

mp.task Methods:

- *run()* (page 9) - execute the task
- *next_mm()* (page 10) - controls iterations over mathematical models
- *next_nm()* (page 10) - controls iterations over network models
- *next_dm()* (page 10) - controls iterations over data models
- *run_pre()* (page 11) - called at beginning of *run()* (page 9) method
- *run_post()* (page 11) - called at end of *run()* (page 9) method
- *print_soln()* (page 11) - display pretty-printed results
- *print_soln_header()* (page 11) - display success/failure, elapsed time
- *save_soln()* (page 12) - save solved case to file
- *dm_converter_class()* (page 12) - get data model converter constructor
- *dm_converter_class_mpc2_default()* (page 12) - get default data model converter constructor
- *dm_converter_create()* (page 12) - create data model converter object
- *data_model_class()* (page 13) - get data model constructor
- *data_model_class_default()* (page 13) - get default data model constructor
- *data_model_create()* (page 13) - create data model object
- *data_model_build()* (page 14) - create and build data model object
- *data_model_build_pre()* (page 14) - called at beginning of *data_model_build()* (page 14)
- *data_model_build_post()* (page 14) - called at end of *data_model_build()* (page 14)
- *network_model_class()* (page 14) - get network model constructor
- *network_model_class_default()* (page 15) - get default network model constructor
- *network_model_create()* (page 15) - create network model object
- *network_model_build()* (page 15) - create and build network model object
- *network_model_build_pre()* (page 15) - called at beginning of *network_model_build()* (page 15)
- *network_model_build_post()* (page 16) - called at end of *network_model_build()* (page 15)
- *network_model_x_soln()* (page 16) - update network model state from math model solution
- *network_model_update()* (page 16) - update net model state/soln from math model soln
- *math_model_class()* (page 16) - get mathematical model constructor
- *math_model_class_default()* (page 17) - get default mathematical model constructor
- *math_model_create()* (page 17) - create mathematical model object
- *math_model_build()* (page 17) - create and build mathematical model object

- `math_model_opt()` (page 18) - get options struct to pass to `mm.solve()`

See the sec_task section in the *MATPOWER Developer's Manual* for more information.

See also `mp.data_model` (page 27), `mp.net_model` (page 90), `mp.math_model` (page 121), `mp.dm_converter` (page 59).

Property Summary

tag

(char array) task `tag` (page 9) - e.g. 'PF', 'CPF', 'OPF'

name

(char array) task `name` (page 9) - e.g. 'Power Flow', etc.

dmc

(`mp.dm_converter` (page 59)) data model converter object

dm

(`mp.data_model` (page 27)) data model object

nm

(`mp.net_model` (page 90)) network model object

mm

(`mp.math_model` (page 121)) mathematical model object

mm_opt

(struct) solve options for mathematical model

i_dm

(integer) iteration counter for data model loop

i_nm

(integer) iteration counter for network model loop

i_mm

(integer) iteration counter for math model loop

success

(integer) `success` (page 9) flag, 1 - math model solved, 0 - didn't solve

message

(char array) output `message` (page 9)

et

(double) elapsed time (seconds) for `run()` (page 9) method

Method Summary

run(*d*, *mpopt*, *mpx*)

Execute the task.

```
task.run(d, mpopt)
task.run(d, mpopt, mpx)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)

- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of `mp.extension` (page 170)) – MATPOWER Extensions

Output

task (`mp.task` (page 7)) – task object containing the solved `run()` (page 9) including the data, network, and mathematical model objects.

Execute the task, creating the data model converter and the data, network and mathematical model objects, solving the math model and propagating the solution back to the data model.

See the sec_task section in the *MATPOWER Developer's Manual* for more information.

next_mm(*mm*, *nm*, *dm*, *mpopt*, *mpx*)

Controls iterations over mathematical models.

```
[mm, nm, dm] = task.next_mm(mm, nm, dm, mpoopt, mpx)
```

Inputs

- **mm** (`mp.math_model` (page 121)) – mathmatical model object
- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of `mp.extension` (page 170)) – MATPOWER Extensions

Output

- **mm** (`mp.math_model` (page 121)) – new or updated mathmatical model object, or empty matrix
- **nm** (`mp.net_model` (page 90)) – potentially updated network model object
- **dm** (`mp.data_model` (page 27)) – potentially updated data model object

Called automatically by `run()` (page 9) method. Subclasses can override this method to return a new or updated math model object for use in the next iteration or an empty matrix (the default) if finished.

next_nm(*mm*, *nm*, *dm*, *mpopt*, *mpx*)

Controls iterations over network models.

```
[nm, dm] = task.next_nm(mm, nm, dm, mpoopt, mpx)
```

Inputs

- **mm** (`mp.math_model` (page 121)) – mathmatical model object
- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of `mp.extension` (page 170)) – MATPOWER Extensions

Output

- **nm** (`mp.net_model` (page 90)) – new or updated network model object, or empty matrix
- **dm** (`mp.data_model` (page 27)) – potentially updated data model object

Called automatically by `run()` (page 9) method. Subclasses can override this method to return a new or updated network model object for use in the next iteration or an empty matrix (the default) if finished.

next_dm(*mm*, *nm*, *dm*, *mpopt*, *mpx*)

Controls iterations over data models.

```
dm = task.next_dm(mm, nm, dm, mpoopt, mpx)
```

Inputs

- **mm** (`mp.math_model` (page 121)) – mathmatical model object
- **nm** (`mp.net_model` (page 90)) – network model object

- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of `mp.extension` (page 170)) – MATPOWER Extensions

Output

dm (`mp.data_model` (page 27)) – new or updated data model object, or empty matrix

Called automatically by `run()` (page 9) method. Subclasses can override this method to return a new or updated data model object for use in the next iteration or an empty matrix (the default) if finished.

run_pre(*d*, *mpopt*)

Called at beginning of `run()` (page 9) method.

```
[d, mpopt] = task.run_pre(d, mpopt)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct

Outputs

- **d** – updated value of corresponding input
- **mpopt** (*struct*) – updated value of corresponding input

Subclasses can override this method to update the input data or options before beginning the run.

run_post(*mm*, *nm*, *dm*, *mpopt*)

Called at end of `run()` (page 9) method.

```
task.run_post(mm, nm, dm, mpopt)
```

Inputs

- **mm** (`mp.math_model` (page 121)) – mathmatical model object
- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

task (`mp.task` (page 7)) – task object

Subclasses can override this method to do any final processing after the run is complete.

print_soln(*mpopt*, *fname*)

Display the pretty-printed results.

```
task.print_soln(mpopt)
task.print_soln(mpopt, fname)
```

Inputs

- **mpopt** (*struct*) – MATPOWER options struct
- **fname** (*char array*) – file name for saving pretty-printed output

Display to standard output and/or save to a file the pretty-printed solved case.

print_soln_header(*mpopt*, *fd*)

Display solution header information.

```
task.print_soln_header(mpopt, fd)
```

Inputs

- **mpopt** (*struct*) – MATPOWER options struct

- **fd** (*integer*) – file identifier (1 for standard output)

Called by `print_soln()` (page 11) to print success/failure, elapsed time, etc. to a file identifier.

save_soln(*fname*)

Save the solved case to a file.

```
task.save_soln(fname)
```

Input
fname (*char array*) – file name for saving solved case

dm_converter_class(*d*, *mpopt*, *mpx*)

Get data model converter constructor.

```
dmc_class = task.dm_converter_class(d, mpopt, mpx)
```

Inputs
- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of `mp.extension` (page 170)) – MATPOWER Extensions

Output
dmc_class (*function handle*) – handle to the constructor to be used to instantiate the data model converter object

Called by `dm_converter_create()` (page 12) to determine the class to use for the data model converter object. Handles any modifications specified by MATPOWER options or extensions.

dm_converter_class_mpc2_default()

Get default data model converter constructor.

```
dmc_class = task.dm_converter_class_mpc2_default()
```

Output
dmc_class (*function handel*) – handle to default constructor to be used to instantiate the data model converter object

Called by `dm_converter_class()` (page 12) to determine the default class to use for the data model converter object when the input is a version 2 MATPOWER case struct.

dm_converter_create(*d*, *mpopt*, *mpx*)

Create data model converter object.

```
dmc = task.dm_converter_create(d, mpopt, mpx)
```

Inputs
- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of `mp.extension` (page 170)) – MATPOWER Extensions

Output
dmc (`mp.dm_converter` (page 59)) – data model converter object, ready to build

Called by `dm_converter_build()` (page 12) method to instantiate the data model converter object. Handles any modifications to data model converter elements specified by MATPOWER options or extensions.

dm_converter_build(*d*, *mpopt*, *mpx*)

Create and build data model converter object.

```
dmc = task.dm_converter_build(d, mpopt, mpx)
```

Inputs
- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (mpc)
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of *mp.extension* (page 170)) – MATPOWER Extensions

Output
dmc (*mp.dm_converter* (page 59)) – data model converter object, ready for use

Called by *run()* (page 9) method to instantiate and build the data model converter object, including any modifications specified by MATPOWER options or extensions.

data_model_class(*d*, *mpopt*, *mpx*)

Get data model constructor.

```
dm_class = task.data_model_class(d, mpopt, mpx)
```

Inputs
- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (mpc)
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of *mp.extension* (page 170)) – MATPOWER Extensions

Output
dm_class (*function handle*) – handle to the constructor to be used to instantiate the data model object

Called by *data_model_create()* (page 13) to determine the class to use for the data model object. Handles any modifications specified by MATPOWER options or extensions.

data_model_class_default()

Get default data model constructor.

```
dm_class = task.data_model_class_default()
```

Output
dm_class (*function handel*) – handle to default constructor to be used to instantiate the data model object

Called by *data_model_class()* (page 13) to determine the default class to use for the data model object.

data_model_create(*d*, *mpopt*, *mpx*)

Create data model object.

```
dm = task.data_model_create(d, mpopt, mpx)
```

Inputs
- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (mpc)
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of *mp.extension* (page 170)) – MATPOWER Extensions

Output
dm (*mp.data_model* (page 27)) – data model object, ready to build

Called by *data_model_build()* (page 14) to instantiate the data model object. Handles any modifications to data model elements specified by MATPOWER options or extensions.

data_model_build(*d*, *dmc*, *mpopt*, *mpx*)

Create and build data model object.

```
dm = task.data_model_create(d, dmc, mpopt, mpx)
```

Inputs
- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (mpc)
- **dmc** (*mp.dm_converter* (page 59)) – data model converter object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of *mp.extension* (page 170)) – MATPOWER Extensions

Output
dm (*mp.data_model* (page 27)) – data model object, ready for use

Called by *run()* (page 9) method to instantiate and build the data model object, including any modifications specified by MATPOWER options or extensions.

data_model_build_pre(*dm*, *d*, *dmc*, *mpopt*)

Called at beginning of *data_model_build()* (page 14).

```
[dm, d] = task.data_model_build_pre(dm, d, dmc, mpopt)
```

Inputs
- **dm** (*mp.data_model* (page 27)) – data model object
- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (mpc)
- **dmc** (*mp.dm_converter* (page 59)) – data model converter object
- **mpopt** (*struct*) – MATPOWER options struct

Outputs
- **dm** (*mp.data_model* (page 27)) – updated data model object
- **d** – updated value of corresponding input

Called just *before* calling the data model's build() method. In this base class, this method does nothing.

data_model_build_post(*dm*, *dmc*, *mpopt*)

Called at end of *data_model_build()* (page 14).

```
dm = task.data_model_build_post(dm, dmc, mpopt)
```

Inputs
- **dm** (*mp.data_model* (page 27)) – data model object
- **dmc** (*mp.dm_converter* (page 59)) – data model converter object
- **mpopt** (*struct*) – MATPOWER options struct

Output
dm (*mp.data_model* (page 27)) – updated data model object

Called just *after* calling the data model's build() method. In this base class, this method does nothing.

network_model_class(*dm*, *mpopt*, *mpx*)

Get network model constructor.

```
nm_class = task.network_model_class(dm, mpopt, mpx)
```

Inputs

- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of `mp.extension` (page 170)) – MATPOWER Extensions

Output

nm_class (*function handle*) – handle to the constructor to be used to instantiate the network model object

Called by `network_model_create()` (page 15) to determine the class to use for the network model object. Handles any modifications specified by MATPOWER options or extensions.

network_model_class_default(*dm*, *mpopt*)

Get default network model constructor.

```
nm_class = task.network_model_class_default(dm, mpopt)
```

Inputs

- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

nm_class (*function handle*) – handle to default constructor to be used to instantiate the network model object

Called by `network_model_class()` (page 14) to determine the default class to use for the network model object.

Note: This is an abstract method that must be implemented by a subclass.

network_model_create(*dm*, *mpopt*, *mpx*)

Create network model object.

```
nm = task.network_model_create(dm, mpopt, mpx)
```

Inputs

- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of `mp.extension` (page 170)) – MATPOWER Extensions

Output

nm (`mp.net_model` (page 90)) – network model object, ready to build

Called by `network_model_build()` (page 15) to instantiate the network model object. Handles any modifications to network model elements specified by MATPOWER options or extensions.

network_model_build(*dm*, *mpopt*, *mpx*)

Create and build network model object.

```
nm = task.network_model_build(dm, mpopt, mpx)
```

Inputs

- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of `mp.extension` (page 170)) – MATPOWER Extensions

Output

nm (`mp.net_model` (page 90)) – network model object, ready for use

Called by `run()` (page 9) method to instantiate and build the network model object, including any modifications specified by MATPOWER options or extensions.

network_model_build_pre(*nm*, *dm*, *mpopt*)

Called at beginning of `network_model_build()` (page 15).

```
nm = task.network_model_build_pre(nm, dm, mpopt)
```

Inputs
- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output
nm (`mp.net_model` (page 90)) – updated network model object

Called just *before* calling the network model's build() method. In this base class, this method does nothing.

network_model_build_post(*nm*, *dm*, *mpopt*)

Called at end of `network_model_build()` (page 15).

```
nm = task.network_model_build_post(nm, dm, mpopt)
```

Inputs
- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output
nm (`mp.net_model` (page 90)) – updated network model object

Called just *after* calling the network model's build() method. In this base class, this method does nothing.

network_model_x_soln(*mm*, *nm*)

Update network model state from math model solution.

```
nm = task.network_model_x_soln(mm, nm)
```

Inputs
- **mm** (`mp.math_model` (page 121)) – mathmatical model object
- **nm** (`mp.net_model` (page 90)) – network model object

Output
nm (`mp.net_model` (page 90)) – updated network model object

Called by `network_model_update()` (page 16).

network_model_update(*mm*, *nm*)

Update network model state, solution values from math model solution.

```
nm = task.network_model_update(mm, nm)
```

Inputs
- **mm** (`mp.math_model` (page 121)) – mathmatical model object
- **nm** (`mp.net_model` (page 90)) – network model object

Output
nm (`mp.net_model` (page 90)) – updated network model object

Called by `run()` (page 9) method.

math_model_class(*nm*, *dm*, *mpopt*, *mpx*)

Get mathematical model constructor.

```
mm_class = task.math_model_class(nm, dm, mpopt, mpx)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of *mp.extension* (page 170)) – MATPOWER Extensions

Output

mm_class (*function handle*) – handle to the constructor to be used to instantiate the mathematical model object

Called by *math_model_create()* (page 17) to determine the class to use for the mathematical model object. Handles any modifications specified by MATPOWER options or extensions.

math_model_class_default(*nm*, *dm*, *mpopt*)

Get default mathematical model constructor.

```
mm_class = task.math_model_class_default(nm, dm, mpopt)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

mm_class (*function handle*) – handle to the constructor to be used to instantiate the mathematical model object

Called by *math_model_class()* (page 16) to determine the default class to use for the mathematical model object.

Note: This is an abstract method that must be implemented by a subclass.

math_model_create(*nm*, *dm*, *mpopt*, *mpx*)

Create mathematical model object.

```
mm = task.math_model_create(nm, dm, mpopt, mpx)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of *mp.extension* (page 170)) – MATPOWER Extensions

Output

mm (*mp.math_model* (page 121)) – mathmatical model object, ready to build

Called by *math_model_build()* (page 17) to instantiate the mathematical model object. Handles any modifications to mathematical model elements specified by MATPOWER options or extensions.

math_model_build(*nm*, *dm*, *mpopt*, *mpx*)

Create and build mathematical model object.

```
mm = task.math_model_build(nm, dm, mpopt, mpx)
```

Inputs

- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of *mp.extension* (page 170)) – MATPOWER Extensions

Output

mm (*mp.math_model* (page 121)) – mathmatical model object, ready for use

Called by *run()* (page 9) method to instantiate and build the mathematical model object, including any modifications specified by MATPOWER options or extensions.

math_model_opt(*mm*, *nm*, *dm*, *mpopt*)

Get the options struct to pass to `mm.solve()`.

```
opt = task.math_model_opt(mm, nm, dm, mpopt)
```

Inputs

- **mm** (*mp.math_model* (page 121)) – mathmatical model object
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

opt (*struct*) – options struct for mathematical model solve() method

Called by *run()* (page 9) method.

mp.task_pf

class mp.**task_pf**

Bases: *mp.task* (page 7)

mp.task_pf (page 18) - MATPOWER task for power flow (PF).

Provides task implementation for the power flow problem.

This includes the handling of iterative runs to enforce generator reactive power limits, if requested.

mp.task_pf Properties:

- *tag* (page 19) - task tag 'PF'
- *name* (page 19) - task name 'Power Flow'
- *dc* (page 19) - `true` if using DC network model
- *iterations* (page 19) - total number of power flow iterations
- *ref* (page 19) - current ref node indices
- *ref0* (page 19) - initial ref node indices
- *va_ref0* (page 19) - initial ref node voltage angles
- *fixed_q_idx* (page 19) - indices of fixed Q gens
- *fixed_q_qty* (page 19) - Q output of fixed Q gens

mp.task_pf Methods:

- *run_pre()* (page 19) - set `dc` property

- `next_dm()` (page 19) - optionally iterate to enforce generator reactive limits
- `enforce_q_lims()` (page 19) - implementation of generator reactive limits
- `network_model_class_default()` (page 19) - select default network model constructor
- `network_model_build_post()` (page 19) - initialize properties for reactive limits
- `network_model_x_soln()` (page 19) - correct the voltage angles if necessary
- `math_model_class_default()` (page 20) - select default math model constructor

See also `mp.task` (page 7).

Property Summary

`tag = 'PF'`

`name = 'Power Flow'`

`dc`

`true` if using DC network model (from `mpopt.model`, cached in `run_pre()` (page 19))

`iterations`

(integer) total number of power flow `iterations` (page 19)

`ref`

(integer) current `ref` (page 19) node indices

`ref0`

(integer) initial ref node indices

`va_ref0`

(double) initial ref node voltage angles

`fixed_q_idx`

(integer) indices of fixed Q gens

`fixed_q_qty`

(double) Q output of fixed Q gens

Method Summary

`run_pre`(*d*, *mpopt*)

Set `dc` property after calling superclass `run_pre()` (page 11).

`next_dm`(*mm*, *nm*, *dm*, *mpopt*, *mpx*)

Implement optional iterations to enforce generator reactive limits.

`enforce_q_lims`(*nm*, *dm*, *mpopt*)

Used by `next_dm()` (page 19) to implement enforcement of generator reactive limits.

`network_model_class_default`(*dm*, *mpopt*)

Implement selector for default network model constructor depending on `mpopt.model` and `mpopt.pf.v_cartesian`.

`network_model_build_post`(*nm*, *dm*, *mpopt*)

Initialize `mp.task_pf` (page 18) properties, if non-empty AC case with generator reactive limits enforced.

network_model_x_soln(*mm*, *nm*)

Call superclass `network_model_x_soln()` (page 16) then correct the voltage angle if the ref node has been changed.

math_model_class_default(*nm*, *dm*, *mpopt*)

Implement selector for default mathematical model constructor depending on `mpopt.model`, `mpopt.pf.v_cartesian`, and `mpopt.pf.current_balance`.

mp.task_cpf

class mp.task_cpf

Bases: `mp.task_pf` (page 18)

`mp.task_cpf` (page 20) - MATPOWER task for continuation power flow (CPF).

Provides task implementation for the continuation power flow problem.

This includes the iterative solving of the mathematical model (using warm restarts) after updating the problem data, e.g. when enforcing certain limits.

mp.task_cpf Properties:

- `warmstart` (page 20) - warm start data

mp.task_cpf Methods:

- `task_cpf()` (page 20) - constructor, inherits from `mp.task_pf` (page 18) constructor
- `run_pre()` (page 21) - call superclass `run_pre()` (page 19) for base and target inputs
- `next_mm()` (page 21) - handle warm start of continuation iterations
- `dm_converter_class()` (page 21) - select data model converter class
- `data_model_class_default()` (page 21) - select default data model constructor
- `data_model_build()` (page 21) - build base and target data models
- `network_model_build()` (page 21) - build base and target network models
- `network_model_x_soln()` (page 21) - update network model solution
- `network_model_update()` (page 21) - evaluate port injection solution
- `math_model_class_default()` (page 21) - select default math model constructor
- `math_model_opt()` (page 21) - add warmstart parameters to math model solve options

See also `mp.task` (page 7), `mp.task_pf` (page 18).

Constructor Summary

task_cpf()

Constructor, inherits from `mp.task_pf` (page 18) constructor.

Property Summary

warmstart

(struct) warm start data, with fields:
- clam - corrector parameter lambda
- plam - predictor parameter lambda

- cV - corrector complex voltage vector
- pV - predictor complex voltage vector

Method Summary

run_pre(*d*, *mpopt*)

Call superclass *run_pre()* (page 19) for base and target inputs.

next_mm(*mm*, *nm*, *dm*, *mpopt*, *mpx*)

Handle warm start of continuation iterations, after problem data update.

dm_converter_class(*d*, *mpopt*, *mpx*)

Implement selector for data model converter class based on superclass constructor.

data_model_class_default()

Implement selector for default data model constructor.

data_model_build(*d*, *dmc*, *mpopt*, *mpx*)

Call superclass `data_model_build()` for base and target models.

network_model_build(*dm*, *mpopt*, *mpx*)

Call superclass `network_model_build()` for base and target models.

network_model_x_soln(*mm*, *nm*)

Call superclass *network_model_x_soln()* (page 19) then update solution in target network model.

network_model_update(*mm*, *nm*)

Call superclass `network_model_update()` then update port injection solution by interpolating with parameter lambda.

math_model_class_default(*nm*, *dm*, *mpopt*)

Implement selector for default mathematical model constructor depending on `mpopt.pf.v_cartesian` and `mpopt.pf.current_balance`.

math_model_opt(*mm*, *nm*, *dm*, *mpopt*)

Call superclass `math_model_opt()` then add warmstart parameters, if available.

mp.task_opf

class mp.task_opf

Bases: *mp.task* (page 7)

mp.task_opf (page 21) - MATPOWER task for optimal power flow (OPF).

Provides task implementation for the optimal power flow problem.

mp.task_opf Properties:

- `tag` - task tag 'OPF'
- `name` - task name 'Optimal Power Flow'
- *dc* (page 22) - `true` if using DC network model

mp.task_opf Methods:

- *run_pre()* (page 22) - set `dc` property
- *print_soln_header()* (page 22) - add printout of objective function value

- `data_model_class_default()` (page 22) - select default data model constructor
- `data_model_build_post()` (page 22) - adjust bus voltage limits, if requested
- `network_model_class_default()` (page 22) - select default network model constructor
- `math_model_class_default()` (page 22) - select default math model constructor

See also `mp.task` (page 7).

Property Summary

dc

`true` if using DC network model (from `mpopt.model`, cached in `run_pre()` (page 22))

Method Summary

run_pre(*d*, *mpopt*)

Set `dc` property after calling superclass `run_pre()` (page 11), then check for unsupported AC OPF solver selection.

print_soln_header(*mpopt*, *fd*)

Call superclass `print_soln_header()` (page 11) the print out the objective function value.

data_model_class_default()

Implement selector for default data model constructor.

data_model_build_post(*dm*, *dmc*, *mpopt*)

Call superclass `data_model_build_post()` (page 14) then adjust bus voltage magnitude limits based on generator `vm_setpoint`, if requested.

network_model_class_default(*dm*, *mpopt*)

Implement selector for default network model constructor depending on `mpopt.model` and `mpopt.opf.v_cartesian`.

math_model_class_default(*nm*, *dm*, *mpopt*)

Implement selector for default mathematical model constructor depending on `mpopt.model`, `mpopt.opf.v_cartesian`, and `mpopt.opf.current_balance`.

3.1.2 Legacy Task Classes

Used by MP-Core when called by the *legacy MATPOWER framework*.

mp.task_pf_legacy

class mp.**task_pf_legacy**

Bases: `mp.task_pf` (page 18), `mp.task_shared_legacy` (page 26)

`mp.task_pf_legacy` (page 22) - MATPOWER task for legacy power flow (PF).

Adds functionality needed by the *legacy MATPOWER framework* to the task implementation for the power flow problem. This consists of pre-processing some input data and exporting and packaging result data.

mp.task_pf Methods:

- `run_pre()` (page 23) - pre-process inputs that are for legacy framework only

- `run_post()` (page 23) - export results back to data model source
- `legacy_post_run()` (page 23) - post-process *legacy framework* outputs

See also `mp.task_pf` (page 18), `mp.task` (page 7), `mp.task_shared_legacy` (page 26).

Method Summary

run_pre(*d*, *mpopt*)

Pre-process inputs that are for *legacy framework* only.

```
[d, mpopt] = task.run_pre(d, mpopt)
```

Inputs
- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct

Outputs
- **d** – updated value of corresponding input
- **mpopt** (*struct*) – updated value of corresponding input

Call `run_pre_legacy()` (page 27) method before calling parent.

run_post(*mm*, *nm*, *dm*, *mpopt*)

Export results back to data model source.

```
task.run_post(mm, nm, dm, mpopt)
```

Inputs
- **mm** (`mp.math_model` (page 121)) – mathmatical model object
- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output
task (`mp.task` (page 7)) – task object

Calls `mp.dm_converter.export()` (page 60) and saves the result in the data model `source` property.

legacy_post_run(*mpopt*)

Post-process *legacy framework* outputs.

```
[results, success] = task.legacy_post_run(mpopt)
```

Input
mpopt (*struct*) – MATPOWER options struct

Outputs
- **results** (*struct*) – results struct for *legacy MATPOWER framework*, see Table 4.1 in legacy MATPOWER User's Manual.
- **success** (*integer*) – 1 - succeeded, 0 - failed

Extract `results` and `success` and save the task object in `results.task` before returning.

mp.task_cpf_legacy

class mp.**task_cpf_legacy**

Bases: *mp.task_cpf* (page 20), *mp.task_shared_legacy* (page 26)

mp.task_cpf (page 20) - MATPOWER task for legacy continuation power flow (CPF).

Adds functionality needed by the *legacy MATPOWER framework* to the task implementation for the continuation power flow problem. This consists of pre-processing some input data and exporting and packaging result data.

mp.task_pf Methods:

- *run_pre()* (page 24) - pre-process inputs that are for legacy framework only
- *run_post()* (page 24) - export results back to data model source
- *legacy_post_run()* (page 24) - post-process *legacy framework* outputs

See also *mp.task_cpf* (page 20), *mp.task* (page 7), *mp.task_shared_legacy* (page 26).

Method Summary

run_pre(*d*, *mpopt*)

Pre-process inputs that are for *legacy framework* only.

```
[d, mpopt] = task.run_pre(d, mpopt)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (mpc)
- **mpopt** (*struct*) – MATPOWER options struct

Outputs

- **d** – updated value of corresponding input
- **mpopt** (*struct*) – updated value of corresponding input

Call *run_pre_legacy()* (page 27) method for both input cases before calling parent.

run_post(*mm*, *nm*, *dm*, *mpopt*)

Export results back to data model source.

```
task.run_post(mm, nm, dm, mpopt)
```

Inputs

- **mm** (*mp.math_model* (page 121)) – mathmatical model object
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

task (*mp.task* (page 7)) – task object

Calls *mp.dm_converter.export()* (page 60) and saves the result in the data model `source` property.

legacy_post_run(*mpopt*)

Post-process *legacy framework* outputs.

```
[results, success] = task.legacy_post_run(mpopt)
```

Input

mpopt (*struct*) – MATPOWER options struct

Outputs

- **results** (*struct*) – results struct for *legacy MATPOWER framework*, see Table 5.1 in legacy MATPOWER User's Manual.
- **success** (*integer*) – 1 - succeeded, 0 - failed

Extract `results` and `success` and save the task object in `results.task` before returning.

mp.task_opf_legacy

class `mp.task_opf_legacy`

Bases: `mp.task_opf` (page 21), `mp.task_shared_legacy` (page 26)

`mp.task_opf` (page 21) - MATPOWER task for legacy optimal power flow (OPF).

Adds functionality needed by the *legacy MATPOWER framework* to the task implementation for the optimal power flow problem. This consists of pre-processing some input data and exporting and packaging result data, as well as using some legacy specific model sub-classes.

mp.task_pf Methods:

- `run_pre()` (page 25) - pre-process inputs that are for legacy framework only
- `run_post()` (page 25) - export results back to data model source
- `dm_converter_class_mpc2_default()` (page 26) - set to `mp.dm_converter_mpc2_legacy` (page 62)
- `data_model_build_post()` (page 26) - get data model converter to do more input pre-processing
- `math_model_class_default()` (page 26) - use legacy math model subclasses
- `legacy_post_run()` (page 26) - post-process *legacy framework* outputs

See also `mp.task_opf` (page 21), `mp.task` (page 7), `mp.task_shared_legacy` (page 26).

Method Summary

run_pre(*d*, *mpopt*)

Pre-process inputs that are for *legacy framework* only.

```
[d, mpopt] = task.run_pre(d, mpopt)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct

Outputs

- **d** – updated value of corresponding input
- **mpopt** (*struct*) – updated value of corresponding input

Call `run_pre_legacy()` (page 27) method before calling parent.

run_post(*mm*, *nm*, *dm*, *mpopt*)

Export results back to data model source.

```
task.run_post(mm, nm, dm, mpopt)
```

Inputs

- **mm** (`mp.math_model` (page 121)) – mathmatical model object

- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

task (`mp.task` (page 7)) – task object

Calls `mp.dm_converter.export()` (page 60) and saves the result in the data model `source` property.

dm_converter_class_mpc2_default()

Set to `mp.dm_converter_mpc2_legacy` (page 62).

```
dmc_class = task.dm_converter_class_mpc2_default()
```

data_model_build_post(*dm*, *dmc*, *mpopt*)

Get data model converter to do more input pre-processing after calling superclass `data_model_build_post()` (page 22).

math_model_class_default(*nm*, *dm*, *mpopt*)

Use legacy math model subclasses to support legacy costs and callbacks.

Uses math model variations that inherit from `mp.mm_shared_opf_legacy` (page 142) (compatible with the legacy `opf_model`), in order to support legacy cost functions and callback functions that expect to find the MATPOWER case struct in `mm.mpc`.

legacy_post_run(*mpopt*)

Post-process *legacy framework* outputs.

```
[results, success, raw] = task.legacy_post_run(mpopt)
```

Input

mpopt (*struct*) – MATPOWER options struct

Outputs

- **results** (*struct*) – results struct for *legacy MATPOWER framework*, see Table 6.1 in legacy MATPOWER User's Manual.
- **success** (*integer*) – 1 - succeeded, 0 - failed
- **raw** (*struct*) – see `raw` field in Table 6.1 in legacy MATPOWER User's Manual.

Extract `results` and `success` and save the task object in `results.task` before returning. This method also creates and populates numerous other fields expected in the legacy OPF `results` struct, such as `f`, `x`, `om`, `mu`, `g`, `dg`, `raw`, `var`, `nle`, `nli`, `lin`, and `cost`. Based on code from the legacy functions `opf_execute()`, `dcopf_solver()`, and `nlpopf_solver()`.

mp.task_shared_legacy

class mp.**task_shared_legacy**

Bases: `handle`

`mp.task_shared_legacy` (page 26) - Shared legacy task functionality.

Provides legacy task functionality shared across different tasks (e.g. PF, CPF, OPF), specifically, the pre-processing of input data for the experimental system-wide ZIP load data.

mp.task_pf Methods:

- `run_pre_legacy()` (page 27) - handle experimental system-wide ZIP load inputs

See also `mp.task` (page 7).

Method Summary

run_pre_legacy(*d*, *mpopt*)

Handle experimental system-wide ZIP load inputs.

```
[d, mpopt] = task.run_pre_legacy(d, mpopt)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct

Outputs

- **d** – updated value of corresponding input
- **mpopt** (*struct*) – updated value of corresponding input

Moves the legacy experimental system-wide ZIP load data from `mpopt.exp.sys_wide_zip_loads` to `d.sys_wide_zip_loads` to make it available to the data model converter (`mp.dmce_load_mpc2` (page 70)).

Called by `run_pre()` (page 11).

3.2 Data Model Classes

3.2.1 Containers

mp.data_model

class `mp.data_model`

Bases: `mp.element_container` (page 165)

`mp.data_model` (page 27) - Base class for MATPOWER **data model** objects.

The data model object encapsulates the input data provided by the user for the problem of interest and the output data presented back to the user upon completion. It corresponds roughly to the `mpc` (MATPOWER case) and `results` structs used throughout the legacy MATPOWER implementation, but encapsulated in an object with additional functionality. It includes tables of data for each type of element in the system.

A data model object is primarily a container for data model element (`mp.dm_element` (page 35)) objects. Concrete data model classes may be specific to the task.

By convention, data model variables are named `dm` and data model class names begin with `mp.data_model`.

mp.data_model Properties:

- `base_mva` (page 28) - system per unit MVA base
- `base_kva` (page 28) - system per unit kVA base
- `source` (page 28) - source of data, e.g. `mpc` (MATPOWER case struct)
- `userdata` (page 28) - arbitrary user data

mp.data_model Methods:

- *data_model()* (page 28) - constructor, assign default data model element classes
- *copy()* (page 29) - make duplicate of object
- *build()* (page 29) - create, add, and build element objects
- *count()* (page 29) - count instances of each element and remove if count is zero
- *initialize()* (page 29) - initialize (online/offline) status of each element
- *update_status()* (page 29) - update (online/offline) status based on connectivity, etc
- *build_params()* (page 30) - extract/convert/calculate parameters for online elements
- *online()* (page 30) - get number of online elements of named type
- *display()* (page 30) - display the data model object
- *pretty_print()* (page 30) - pretty print data model to console or file
- *pp_flags()* (page 31) - from options, build flags to control pretty printed output
- *pp_section_label()* (page 31) - construct section header lines for output
- *pp_section_list()* (page 31) - return list of section tags
- *pp_have_section()* (page 32) - return true if section exists for object
- *pp_section()* (page 32) - pretty print the given section
- *pp_get_headers()* (page 32) - construct pretty printed lines for section headers
- *pp_get_headers_cnt()* (page 32) - construct pretty printed lines for **cnt** section headers
- *pp_get_headers_ext()* (page 33) - construct pretty printed lines for **ext** section headers
- *pp_data()* (page 33) - pretty print the data for the given section
- *set_bus_v_lims_via_vg()* (page 33) - set gen bus voltage limits based on gen voltage setpoints

See the sec_data_model section in the *MATPOWER Developer's Manual* for more information.

See also *mp.task* (page 7), *mp.net_model* (page 90), *mp.math_model* (page 121), *mp.dm_converter* (page 59).

Constructor Summary

data_model()

Constructor, assign default data model element classes.

```
dm = mp.data_model()
```

Property Summary

base_mva

(double) system per unit MVA base, for balanced single-phase systems/sections, must be provided if system includes any `'bus'` elements

base_kva

(double) system per unit kVA base, for unbalanced 3-phase systems/sections, must be provided if system includes any `'bus3p'` elements

source

source (page 28) of data, e.g. `mpc` (MATPOWER case struct) `userdata = struct()`

(struct) arbitrary user data

Method Summary

`copy()`

Create a duplicate of the data model object, calling the `copy()` (page 40) method on each element.

```
new_dm = dm.copy()
```

`build(d, dmc)`

Create and add data model element objects.

```
dm.build(d, dmc)
```

Inputs

- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for `mp.dm_converter_mpc2` (page 61))
- **dmc** (`mp.dm_converter` (page 59)) – data model converter

Create the data model element objects by instantiating each class in the `element_classes` (page 165) property and adding the resulting object to the `elements` (page 165) property. Then proceed through the following additional `build()` (page 29) stages for each element.

- Import
- Count
- Initialize
- Update status
- Build parameters

See the sec_building_data_model section in the *MATPOWER Developer's Manual* for more information.

`count()`

Count instances of each element and remove if `count()` (page 29) is zero.

```
dm.count()
```

Call each element's `count()` (page 40) method to determine the number of instances of that element in the data, and remove the element type from `elements` (page 165) if the count is 0.

Called by `build()` (page 29) to perform its **count** stage. See the sec_building_data_model section in the *MATPOWER Developer's Manual* for more information.

`initialize()`

Initialize (online/offline) status of each element.

```
dm.initialize()
```

Call each element's `initialize()` (page 40) method to `initialize()` (page 29) statuses and create ID to row index mappings.

Called by `build()` (page 29) to perform its **initialize** stage. See the sec_building_data_model section in the *MATPOWER Developer's Manual* for more information.

`update_status()`

Update (online/offline) status based on connectivity, etc.

```
dm.update_status()
```

Call each element's `update_status()` (page 41) method to update statuses based on connectivity or other criteria and define element properties containing number and row indices of online elements, indices of offline elements, and mapping of row indices to indices in online and offline element lists.

Called by `build()` (page 29) to perform its **update status** stage. See the sec_building_data_model section in the *MATPOWER Developer's Manual* for more information.

build_params()

Extract/convert/calculate parameters for online elements.

```
dm.build_params()
```

Call each element's `build_params()` (page 41) method to build parameters as necessary for online elements from the original data tables (e.g. p.u. conversion, initial state, etc.) and store them in element-specific properties.

Called by `build()` (page 29) to perform its **build parameters** stage. See the sec_building_data_model section in the *MATPOWER Developer's Manual* more information.

online(*name*)

Get number of online elements of named type.

```
n = dm.online(name)
```

Input
name (*char array*) – name of element type (e.g. `'bus'`, `'gen'`) as returned by the element's `name()` (page 37) method

Output
n (*integer*) – number of online elements

display()

Display the data model object.

This method is called automatically when omitting a semicolon on a line that retuns an object of this class.

Displays the details of the data model elements.

pretty_print(*mpopt*, *fd*)

Pretty print data model to console or file.

```
dm.pretty_print(mpopt)
dm.pretty_print(mpopt, fd)
[dm, out] = dm.pretty_print(mpopt, fd)
```

Inputs
- **mpopt** (*struct*) – MATPOWER options struct
- **fd** (*integer*) – *(optional, default = 1)* file identifier to use for printing, (1 for standard output, 2 for standard error)

Outputs
- **dm** (`mp.data_model` (page 27)) – the data model object
- **out** (*struct*) – struct of output control flags

Displays the model parameters to a pretty-printed text format. The result can be output either to the console or to a file.

The output is organized into sections and each element type controls its own output for each section. The default sections are:
- **cnt** - counts, number of online, offline, and total elements of this type

- **sum** - summary, e.g. total amount of capacity, load, line loss, etc.
- **ext** - extremes, e.g. min and max voltages, nodal prices, etc.
- **det** - details, table of detailed data, e.g. voltages, prices for buses, dispatch, limits for generators, etc.

pp_flags(*mpopt*)

From options, build flags to control pretty printed output.

```
[out, add] = dm.pp_flags(mpopt)
```

Input

mpopt (*struct*) – MATPOWER options struct

Outputs

- **out** (*struct*) – struct of output control flags

```
out
  .all    (-1, 0 or 1)
  .any    (0 or 1)
  .sec
    .cnt
      .all    (-1, 0 or 1)
      .any    (0 or 1)
    .sum    (same as cnt)
    .ext    (same as cnt)
    .det
      .all    (-1, 0 or 1)
      .any    (0 or 1)
      .elm
        .<name>    (0 or 1)
```

where <name> is the name of the corresponding element type.

- **add** (*struct*) – additional data for subclasses to use

```
add
  .s0
    .<name> = 0
  .s1
    .<name> = 1
  .suppress    (-1, 0 or 1)
  .names    (cell array of element names)
  .ne       (number of element names)
```

See also pretty_print() (page 30).

pp_section_label(*label*, *blank_line*)

Construct pretty printed lines for section label.

```
h = dm.pp_section_label(label, blank_line)
```

Inputs

- **label** (*char array*) – label for the section header
- **blank_line** (*boolean*) – include a blank line before the section label if true

Output

h (*cell array of char arrays*) – individual lines of section label

See also pretty_print() (page 30).

pp_section_list(*out*)

Return list of section tags.

```
sections = dm.pp_section_list(out)
```

Input
out (*struct*) – struct of output control flags (see `pp_flags()` (page 31) for details)

Output
sections (*cell array of char arrays*) – e.g. `{'cnt', 'sum', 'ext', 'det'}`

See also `pretty_print()` (page 30).

pp_have_section(*section*, *mpopt*)

Return true if section exists for object with given options.

```
TorF = dm.pp_have_section(section, mpopt)
```

Inputs
- **section** (*char array*) – e.g. `'cnt'`, `'sum'`, `'ext'`, or `'det'`
- **mpopt** (*struct*) – MATPOWER options struct

Output
TorF (*boolean*) – true if section exists

See also `pretty_print()` (page 30).

pp_section(*section*, *out_s*, *mpopt*, *fd*)

Pretty print the given section.

```
dm.pp_section(section, out_s, mpopt, fd)
```

Inputs
- **section** (*char array*) – e.g. `'cnt'`, `'sum'`, `'ext'`, or `'det'`
- **out_s** (*struct*) – output control flags for the section, `out_s = out.sec.(section)`
- **mpopt** (*struct*) – MATPOWER options struct
- **fd** (*integer*) – *(optional, default = 1)* file identifier to use for printing, (1 for standard output, 2 for standard error)

See also `pretty_print()` (page 30).

pp_get_headers(*section*, *out_s*, *mpopt*)

Construct pretty printed lines for section headers.

```
h = dm.pp_get_headers(section, out_s, mpopt)
```

Inputs
- **section** (*char array*) – e.g. `'cnt'`, `'sum'`, `'ext'`, or `'det'`
- **out_s** (*struct*) – output control flags for the section, `out_s = out.sec.(section)`
- **mpopt** (*struct*) – MATPOWER options struct

Output
h (*cell array of char arrays*) – individual lines of section headers

See also `pretty_print()` (page 30).

pp_get_headers_cnt(*out_s*, *mpopt*)

Construct pretty printed lines for **cnt** section headers.

```
h = dm.pp_get_headers_cnt(out_s, mpopt)
```

Inputs

- **out_s** (*struct*) – output control flags for the section, `out_s = out.sec.(section)`
- **mpopt** (*struct*) – MATPOWER options struct

Output

h (*cell array of char arrays*) – individual lines of **cnt** section headers

See also `pretty_print()` (page 30), `pp_get_headers()` (page 32).

pp_get_headers_ext(*out_s*, *mpopt*)

Construct pretty printed lines for **ext** section headers.

```
h = dm.pp_get_headers_cnt(out_s, mpopt)
```

Inputs

- **out_s** (*struct*) – output control flags for the section, `out_s = out.sec.(section)`
- **mpopt** (*struct*) – MATPOWER options struct

Output

h (*cell array of char arrays*) – individual lines of **ext** section headers

See also `pretty_print()` (page 30), `pp_get_headers()` (page 32).

pp_get_headers_other(*section*, *out_s*, *mpopt*)

Construct pretty printed lines for other section headers.

Returns nothing in base class, but subclasses can implement other section types (e.g. `'lim'` for OPF).

```
h = dm.pp_get_headers_other(section, out_s, mpopt)
```

Inputs

- **section** (*char array*) – e.g. `'cnt'`, `'sum'`, `'ext'`, or `'det'`
- **out_s** (*struct*) – output control flags for the section, `out_s = out.sec.(section)`
- **mpopt** (*struct*) – MATPOWER options struct

Output

h (*cell array of char arrays*) – individual lines of **ext** section headers

See also `pretty_print()` (page 30), `pp_get_headers()` (page 32).

pp_data(*section*, *out_s*, *mpopt*, *fd*)

Pretty print the data for the given section.

```
dm.pp_data(section, out_s, mpopt, fd)
```

Inputs

- **section** (*char array*) – e.g. `'cnt'`, `'sum'`, `'ext'`, or `'det'`
- **out_s** (*struct*) – output control flags for the section, `out_s = out.sec.(section)`
- **mpopt** (*struct*) – MATPOWER options struct
- **fd** (*integer*) – *(optional, default = 1)* file identifier to use for printing, (1 for standard output, 2 for standard error)

See also `pretty_print()` (page 30), `pp_section()` (page 32).

set_bus_v_lims_via_vg(*use_vg*)

Set gen bus voltage limits based on gen voltage setpoints.

```
dm.set_bus_v_lims_via_vg(use_vg)
```

Input

use_vg (*double*) – 1 if voltage setpoint should be used, 0 for original bus voltage bounds, or fractional value between 0 and 1 for bounds interpolated between the two.

mp.data_model_cpf

class mp.**data_model_cpf**

Bases: *mp.data_model* (page 27)

mp.data_model_cpf (page 34) - MATPOWER **data model** for CPF tasks.

The purpose of this class is to include CPF-specific subclasses for the load and shunt elements, which need to be able to provide versions of their model parameters that are parameterized by the continuation parameter λ.

data_model_cpf Methods:

- *data_model_cpf()* (page 34) - constructor, assign default data model element classes

See also *mp.data_model* (page 27).

Constructor Summary

data_model_cpf()

Constructor, assign default data model element classes.

Create an empty data model object and assign the default data model element classes, which are the same as those defined by the base class, except for loads and shunts.

```
dm = mp.data_model_cpf()
```

mp.data_model_opf

class mp.**data_model_opf**

Bases: *mp.data_model* (page 27)

mp.data_model_opf (page 34) - MATPOWER **data model** for OPF tasks.

The purpose of this class is to include OPF-specific subclasses for its elements and to handle pretty-printing output for **lim** sections.

mp.data_model_opf Methods:

- *data_model_opf()* (page 34) - constructor, assign default data model element classes
- *pp_flags()* (page 35) - add flags for **lim** sections
- *pp_section_list()* (page 35) - append `'lim'` tag for **lim** sections to default list
- *pp_get_headers_other()* (page 35) - construct headers for **lim** section headers

See also *mp.data_model* (page 27).

Constructor Summary

data_model_opf()

Constructor, assign default data model element classes.

Create an empty data model object and assign the default data model element classes, each specific to OPF.

```
dm = mp.data_model_opf()
```

Method Summary

pp_flags(*mpopt*)

Add flags for **lim** sections.

See *mp.data_model.pp_flags()* (page 31).

pp_section_list(*out*)

Append `'lim'` tag for **lim** section to default list.

See *mp.data_model.pp_section_list()* (page 31).

pp_get_headers_other(*section*, *out_s*, *mpopt*)

Construct pretty printed lines for **lim** section headers.

See *mp.data_model.pp_get_headers_other()* (page 33).

3.2.2 Elements

mp.dm_element

class mp.**dm_element**

Bases: `handle`

mp.dm_element (page 35) - Abstract base class for MATPOWER **data model element** objects.

A data model element object encapsulates all of the input and output data for a particular element type. All data model element classes inherit from *mp.dm_element* (page 35) and each element type typically implements its own subclass. A given data model element object contains the data for all instances of that element type, stored in one or more table data structures.

Defines the following columns in the main data table, which are inherited by all subclasses:

Name	Type	Description
`uid`	*integer*	unique ID
`name`	*char array*	element name
`status`	*boolean*	true = online, false = offline
`source_uid`	*undefined*	intended for any info required to link back to element instance in source data

By convention, data model element variables are named `dme` and data model element class names begin with `mp.dme`.

In addition to being containers for the data itself, data model elements are responsible for handling the on/off status of each element, preparation of parameters needed by network and mathematical models, definition of connections with other elements, defining solution data to be updated when exporting, and pretty-printing of data to the console or file.

Elements that create nodes (e.g. buses) are called **junction** elements. Elements that define ports (e.g. generators, branches, loads) can connect the ports of a particular instance to the nodes of a particular instance of a junction element by specifying two pieces of information for each port:

- the **type** of junction element it connects to
- the **index** of the specific junction element

mp.dm_element Properties:

- *tab* (page 37) - main data table
- *nr* (page 37) - total number of rows in table
- *n* (page 37) - number of online elements
- *ID2i* (page 37) - max(ID) x 1 vector, maps IDs to row indices
- *on* (page 37) - `n` x 1 vector of row indices of online elements
- *off* (page 37) - (`nr-n`) x 1 vector of row indices of offline elements
- *i2on* (page 37) - `nr` x 1 vector mapping row index to index in `on`/`off` respectively

mp.dm_element Methods:

- *name()* (page 37) - get name of element type, e.g. `'bus'`, `'gen'`
- *label()* (page 38) - get singular label for element type, e.g. `'Bus'`, `'Generator'`
- *labels()* (page 38) - get plural label for element type, e.g. `'Buses'`, `'Generators'`
- *cxn_type()* (page 38) - type(s) of junction element(s) to which this element connects
- *cxn_idx_prop()* (page 38) - name(s) of property(ies) containing indices of junction elements
- *cxn_type_prop()* (page 39) - name(s) of property(ies) containing types of junction elements
- *table_exists()* (page 39) - check for existence of data in main data table
- *main_table_var_names()* (page 39) - names of variables (columns) in main data table
- *export_vars()* (page 39) - names of variables to be exported by DMCE to data source
- *export_vars_offline_val()* (page 40) - values of export variables for offline elements
- *dm_converter_element()* (page 40) - get corresponding data model converter element
- *copy()* (page 40) - create a duplicate of the data model element object
- *count()* (page 40) - determine number of instances of this element in the data
- *initialize()* (page 40) - initialize (online/offline) status of each element
- *ID()* (page 41) - return unique ID's for all or indexed rows
- *init_status()* (page 41) - initialize `status` column
- *update_status()* (page 41) - update (online/offline) status based on connectivity, etc
- *build_params()* (page 41) - extract/convert/calculate parameters for online elements
- *rebuild()* (page 42) - rebuild object, calling *count()* (page 40), *initialize()* (page 40), *build_params()* (page 41)
- *display()* (page 42) - display the data model element object
- *pretty_print()* (page 42) - pretty-print data model element to console or file
- *pp_have_section()* (page 42) - true if pretty-printing for element has specified section

- `pp_rows()` (page 43) - indices of rows to include in pretty-printed output
- `pp_get_headers()` (page 43) - get pretty-printed headers for this element/section
- `pp_get_footers()` (page 43) - get pretty-printed footers for this element/section
- `pp_data()` (page 43) - pretty-print the data for this element/section
- `pp_have_section_cnt()` (page 43) - true if pretty-printing for element has **counts** section
- `pp_data_cnt()` (page 44) - pretty-print the **counts** data for this element
- `pp_have_section_sum()` (page 44) - true if pretty-printing for element has **summary** section
- `pp_data_sum()` (page 44) - pretty-print the **summary** data for this element
- `pp_have_section_ext()` (page 44) - true if pretty-printing for element has **extremes** section
- `pp_data_ext()` (page 44) - pretty-print the **extremes** data for this element
- `pp_have_section_det()` (page 44) - true if pretty-printing for element has **details** section
- `pp_get_title_det()` (page 44) - get title of **details** section for this element
- `pp_get_headers_det()` (page 45) - get pretty-printed **details** headers for this element
- `pp_get_footers_det()` (page 45) - get pretty-printed **details** footers for this element
- `pp_data_det()` (page 45) - pretty-print the **details** data for this element
- `pp_data_row_det()` (page 45) - get pretty-printed row of **details** data for this element

See the sec_dm_element section in the *MATPOWER Developer's Manual* for more information.

See also `mp.data_model` (page 27).

Property Summary

`tab`

(table) main data table

`nr`

(integer) total number of rows in table

`n`

(integer) number of online elements

`ID2i`

(integer) max(ID) x 1 vector, maps IDs to row indices

`on`

(integer) `n` x 1 vector of row indices of online elements

`off`

(integer) (`nr-n`) x 1 vector of row indices of offline elements

`i2on`

(integer) `nr` x 1 vector mapping row index to index in `on`/`off` respectively

Method Summary

name()

Get name of element type, e.g. 'bus', 'gen'.

```
name = dme.name()
```

Output
name (*char array*) – name of element type, must be a valid struct field name

Implementation provided by an element type specific subclass.

label()

Get singular label for element type, e.g. 'Bus', 'Generator'.

```
label = dme.label()
```

Output
label (*char array*) – user-visible label for element type, when singular

Implementation provided by an element type specific subclass.

labels()

Get plural label for element type, e.g. 'Buses', 'Generators'.

```
label = dme.labels()
```

Output
label (*char array*) – user-visible label for element type, when plural

Implementation provided by an element type specific subclass.

cxn_type()

Type(s) of junction element(s) to which this element connects.

```
name = dme.cxn_type()
```

Output
name (*char array or cell array of char arrays*) – name(s) of type(s) of junction elements, i.e. node-creating elements (e.g. 'bus'), to which this element connects

Assuming an element with *nc* connections, there are three options for the return value:

1. Single char array with one type that applies to all connections, *cxn_idx_prop()* (page 38) returns *empty*.
2. Cell array with *nc* elements, one for each connection, *cxn_idx_prop()* (page 38) returns *empty*.
3. Cell array of valid junction element types, *cxn_idx_prop()* (page 38) return value *not empty*.

See the sec_dm_element_cxn section in the *MATPOWER Developer's Manual* for more information.

Implementation provided by an element type specific subclass.

See also *cxn_idx_prop()* (page 38), *cxn_type_prop()* (page 39).

cxn_idx_prop()

Name(s) of property(ies) containing indices of junction elements.

```
name = dme.cxn_idx_prop()
```

Output
name (*char array or cell array of char arrays*) – name(s) of property(ies) containing indices of junction elements that define connections (e.g. {'fbus', 'tbus'})

See the sec_dm_element_cxn section in the *MATPOWER Developer's Manual* for more information.

Implementation provided by an element type specific subclass.

See also `cxn_type()` (page 38), `cxn_type_prop()` (page 39).

cxn_type_prop()

Name(s) of property(ies) containing types of junction elements.

```
name = dme.cxn_type_prop()
```

Output

name (*char array or cell array of char arrays*) – name(s) of properties containing type of junction elements for each connection

Note: If not empty, dimension must match `cxn_idx_prop()` (page 38)

This is only used if the junction element type can vary by individual element, e.g. some elements of this type connect to one kind of bus, some to another kind. Otherwise, it returns an empty string and the junction element types for the connections are determined solely by `cxn_type()` (page 38).

See the sec_dm_element_cxn section in the *MATPOWER Developer's Manual* for more information.

Implementation provided by an element type specific subclass.

See also `cxn_type()` (page 38), `cxn_idx_prop()` (page 38).

table_exists()

Check for existence of data in main data table.

```
TorF = dme.table_exists()
```

Output

TorF (*boolean*) – true if main data table is not empty

main_table_var_names()

Names of variables (columns) in main data table.

```
names = dme.main_table_var_names()
```

Output

names (*cell array of char arrays*) – names of variables (columns) in main table

This base class includes the following variables `{'uid', 'name', 'status', 'source_uid'}` which are common to all element types and should therefore be included in all subclasses. That is, subclass methods should append their additional fields to those returned by this parent method. For example, a subclass method would like something like the following:

```
function names = main_table_var_names(obj)
    names = horzcat( main_table_var_names@mp.dm_element(obj), ...
    {'subclass_var1', 'subclass_var2'} );
end
```

export_vars()

Names of variables to be exported by DMCE to data source.

```
vars = dme.export_vars()
```

Output

vars (*cell array of char arrays*) – names of variables to export

Return the names of the variables the data model converter element needs to export to the data source. This is typically the list of variables updated by the solution process, e.g. bus voltages, line flows, etc.

export_vars_offline_val()

Values of export variables for offline elements.

```
s = dme.export_vars_offline_val()
```

Output

s (*struct*) – keys are export variable names, values are the corresponding values to assign to these variables for offline elements.

Returns a struct defining the values of export variables for offline elements. Called by *mp.mm_element.data_model_update()* (page 145) to define how to set export variables for offline elements.

Export variables not found in the struct are not modified.

For example, `s = struct('va', 0, 'vm', 1)` would assign the value 0 to the `va` variable and 1 to the `vm` variable for any offline elements.

See also *export_vars()* (page 39).

dm_converter_element(*dmc*, *name*)

Get corresponding data model converter element.

```
dmce = dme.dm_converter_element(dmc, name)
```

Inputs

- **dmc** (*mp.dm_converter* (page 59)) – data model converter object
- **name** (*char array*) – name of element type

Output

dmce (*mp.dmc_element* (page 62)) – data model converter element object

copy()

Create a duplicate of the data model element object.

```
new_dme = dme.copy()
```

Output

new_dme (*mp.dm_element* (page 35)) – *copy()* (page 40) of data model element object

count(*dm*)

Determine number of instances of this element in the data.

Store the count in the `nr` property.

```
nr = dme.count(dm);
```

Input

dm (*mp.data_model* (page 27)) – data model

Output

nr (*integer*) – number of instances (rows of data)

Called for each element by the *count()* (page 29) method of *mp.data_model* (page 27) during the **count** stage of a data model build.

See the sec_building_data_model section in the *MATPOWER Developer's Manual* for more information.

initialize(*dm*)

Initialize a newly created data model element object.

```
dme.initialize(dm)
```

Input
dm (*mp.data_model* (page 27)) – data model

Initialize the (online/offline) status of each element and create a mapping of ID to row index in the `ID2i` element property, then call *init_status()* (page 41).

Called for each element by the *initialize()* (page 29) method of *mp.data_model* (page 27) during the **initialize** stage of a data model build.

See the sec_building_data_model section in the *MATPOWER Developer's Manual* for more information.

ID(*idx*)

Return unique ID's for all or indexed rows.

```
uid = dme.ID()
uid = dme.ID(idx)
```

Input
idx (*integer*) – *(optional)* row index vector

Return an *nr* x 1 vector of unique IDs for all rows, i.e. a map of row index to unique ID or, if a row index vector is provided just the ID's of the indexed rows.

init_status(*dm*)

Initialize `status` column.

```
dme.init_status(dm)
```

Input
dm (*mp.data_model* (page 27)) – data model

Called by *initialize()* (page 40). Does nothing in the base class.

update_status(*dm*)

Update (online/offline) status based on connectivity, etc.

```
dme.update_status(dm)
```

Input
dm (*mp.data_model* (page 27)) – data model

Update status of each element based on connectivity or other criteria and define element properties containing number and row indices of online elements (`n` and `on`), indices of offline elements (`off`), and mapping (`i2on`) of row indices to corresponding entries in `on` or `off`.

Called for each element by the *update_status()* (page 29) method of *mp.data_model* (page 27) during the **update status** stage of a data model build.

See the sec_building_data_model section in the *MATPOWER Developer's Manual* for more information.

build_params(*dm*)

Extract/convert/calculate parameters for online elements.

```
dme.build_params(dm)
```

Input
dm (`mp.data_model` (page 27)) – data model

Extract/convert/calculate parameters as necessary for online elements from the original data tables (e.g. p.u. conversion, initial state, etc.) and store them in element-specific properties.

Called for each element by the `build_params()` (page 30) method of `mp.data_model` (page 27) during the **build parameters** stage of a data model build.

See the sec_building_data_model section in the *MATPOWER Developer's Manual* for more information.

Does nothing in the base class.

rebuild(*dm*)

Rebuild object, calling `count()` (page 40), `initialize()` (page 40), `build_params()` (page 41).

```
dme.rebuild(dm)
```

Input
dm (`mp.data_model` (page 27)) – data model

Typically used after modifying data in the main table.

display()

Display the data model element object.

This method is called automatically when omitting a semicolon on a line that retuns an object of this class.

Displays the details of the elements, including total number of rows, number of online elements, and the main data table.

pretty_print(*dm*, *section*, *out_e*, *mpopt*, *fd*, *pp_args*)

Pretty print data model element to console or file.

```
dme.pretty_print(dm, section, out_e, mpopt, fd, pp_args)
```

Inputs
- **dm** (`mp.data_model` (page 27)) – data model
- **section** (*char array*) – section identifier, e.g. `'cnt'`, `'sum'`, `'ext'`, or `'det'`, for **counts**, **summary**, **extremes**, or **details** sections, respectively
- **out_e** (*boolean*) – output control flag for this element/section
- **mpopt** (*struct*) – MATPOWER options struct
- **fd** (*integer*) – *(optional, default = 1)* file identifier to use for printing, (1 for standard output, 2 for standard error)
- **pp_args** (*struct*) – arbitrary struct of additional pretty printing arguments passed to all sub-methods, allowing a single sub-method to be used for multiple output portions (e.g. for active and reactive power) by passing in a different argument; by convention, arguments for a `branch` element, for example, are passed in `pp_args.branch`, etc.

pp_have_section(*section*, *mpopt*, *pp_args*)

True if pretty-printing for element has specified section.

```
TorF = dme.pp_have_section(section, mpopt, pp_args)
```

Inputs
see `pretty_print()` (page 42) for details
Output
TorF (*boolean*) – true if output includes specified section

Implementation handled by section-specific *pp_have_section* methods or *pp_have_section_other()* (page 58).

See also *pp_have_section_cnt()* (page 43), *pp_have_section_sum()* (page 44), *pp_have_section_ext()* (page 44), *pp_have_section_det()* (page 44).

pp_rows(*dm*, *section*, *out_e*, *mpopt*, *pp_args*)

Indices of rows to include in pretty-printed output.

```
rows = dme.pp_rows(dm, section, out_e, mpopt, pp_args)
```

Inputs

see *pretty_print()* (page 42) for details

Output

rows (*integer*) – index vector of rows to be included in output

- 0 = no rows
- -1 = all rows

Includes all rows by default.

pp_get_headers(*dm*, *section*, *out_e*, *mpopt*, *pp_args*)

Get pretty-printed headers for this element/section.

```
h = dme.pp_get_headers(dm, section, out_e, mpopt, pp_args)
```

Inputs

see *pretty_print()* (page 42) for details

Output

h (*cell array of char arrays*) – lines of pretty printed header output for this element/section

Empty by default for counts, summary and extremes sections, and handled by *pp_get_headers_det()* (page 45) for details section.

pp_get_footers(*dm*, *section*, *out_e*, *mpopt*, *pp_args*)

Get pretty-printed footers for this element/section.

```
f = dme.pp_get_footers(dm, section, out_e, mpopt, pp_args)
```

Inputs

see *pretty_print()* (page 42) for details

Output

f (*cell array of char arrays*) – lines of pretty printed footer output for this element/section

Empty by default for counts, summary and extremes sections, and handled by *pp_get_headers_det()* (page 45) for details section.

pp_data(*dm*, *section*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

Pretty-print the data for this element/section.

```
dme.pp_data(dm, section, rows, out_e, mpopt, fd, pp_args)
```

Inputs

- **rows** (*integer*) – indices of rows to include, from *pp_rows()* (page 43)
- **...** – see *pretty_print()* (page 42) for details of other inputs

Implementation handled by section-specific *pp_data* methods or *pp_data_other()* (page 58).

See also *pp_data_cnt()* (page 44), *pp_data_sum()* (page 44), *pp_data_ext()* (page 44), *pp_data_det()* (page 45).

pp_have_section_cnt(*mpopt*, *pp_args*)

True if pretty-printing for element has **counts** section.

```
TorF = dme.pp_have_section_cnt(mpopt, pp_args)
```

Default is **true**.

See also *pp_have_section()* (page 42).

pp_data_cnt(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

Pretty-print the **counts** data for this element.

```
dme.pp_data_cnt(dm, rows, out_e, mpopt, fd, pp_args)
```

See also *pp_data()* (page 43).

pp_have_section_sum(*mpopt*, *pp_args*)

True if pretty-printing for element has **summary** section.

```
TorF = dme.pp_have_section_sum(mpopt, pp_args)
```

Default is **false**.

See also *pp_have_section()* (page 42).

pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

Pretty-print the **summary** data for this element.

```
dme.pp_data_sum(dm, rows, out_e, mpopt, fd, pp_args)
```

Does nothing by default.

See also *pp_data()* (page 43).

pp_have_section_ext(*mpopt*, *pp_args*)

True if pretty-printing for element has **extremes** section.

```
TorF = dme.pp_have_section_ext(mpopt, pp_args)
```

Default is **false**.

See also *pp_have_section()* (page 42).

pp_data_ext(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

Pretty-print the **extremes** data for this element.

```
dme.pp_data_ext(dm, rows, out_e, mpopt, fd, pp_args)
```

Does nothing by default.

See also *pp_data()* (page 43).

pp_have_section_det(*mpopt*, *pp_args*)

True if pretty-printing for element has **details** section.

```
TorF = dme.pp_have_section_det(mpopt, pp_args)
```

Default is **false**.

See also *pp_have_section()* (page 42).

pp_get_title_det(*mpopt*, *pp_args*)

Get title of **details** section for this element.

```
str = dme.pp_get_title_det(mpopt, pp_args)
```

Inputs
see *pretty_print()* (page 42) for details

Output
str (*char array*) – title of details section, e.g. `'Bus Data'`, `'Generator Data'`, etc.

Called by *pp_get_headers_det()* (page 45) to insert title into detail section header.

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

Get pretty-printed **details** headers for this element.

```
h = dme.pp_get_headers_det(dm, out_e, mpopt, pp_args)
```

See also *pp_get_headers()* (page 43).

pp_get_footers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

Get pretty-printed **details** footers for this element.

```
f = dme.pp_get_footers_det(dm, out_e, mpopt, pp_args)
```

Empty by default.

See also *pp_get_footers()* (page 43).

pp_data_det(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

Pretty-print the **details** data for this element.

```
dme.pp_data_det(dm, rows, out_e, mpopt, fd, pp_args)
```

Calls *pp_data_row_det()* (page 45) for each row.

See also *pp_data()* (page 43), *pp_data_row_det()* (page 45).

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

Get pretty-printed row of **details** data for this element.

```
str = dme.pp_data_row_det(dm, k, out_e, mpopt, fd, pp_args)
```

Inputs
- **k** (*integer*) – index of row to print
- **...** – see *pretty_print()* (page 42) for details of other inputs

Output
str (*char array*) – row of data *(without newline)*

Called by *pp_data_det()* (page 45) for each row.

mp.dme_branch

class mp.**dme_branch**

Bases: *mp.dm_element* (page 35)

mp.dme_branch (page 46) - Data model element for branch.

Implements the data element model for branch elements, including transmission lines and transformers.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
`bus_fr`	*integer*	bus ID (`uid`) of "from" bus
`bus_to`	*integer*	bus ID (`uid`) of "to" bus
`r`	*double*	per unit series resistance
`x`	*double*	per unit series reactance
`g_fr`	*double*	per unit shunt conductance at "from" end
`b_fr`	*double*	per unit shunt susceptance at "from" end
`g_to`	*double*	per unit shunt conductance at "to" end
`b_to`	*double*	per unit shunt susceptance at "to" end
`sm_ub_a`	*double*	long term apparent power rating (MVA)
`sm_ub_b`	*double*	short term apparent power rating (MVA)
`sm_ub_c`	*double*	emergency apparent power rating (MVA)
`cm_ub_a`	*double*	long term current magnitude rating (MVA equivalent at 1 p.u. voltage)
`cm_ub_b`	*double*	short term current magnitude rating (MVA equivalent at 1 p.u. voltage)
`cm_ub_c`	*double*	emergency current magnitude rating (MVA equivalent at 1 p.u. voltage)
`vad_lb`	*double*	voltage angle difference lower bound
`vad_ub`	*double*	voltage angle difference upper bound
`tm`	*double*	transformer off-nominal turns ratio
`ta`	*double*	transformer phase-shift angle (degrees)
`pl_fr`	*double*	active power injection at "from" end
`ql_fr`	*double*	reactive power injection at "from" end
`pl_to`	*double*	active power injection at "to" end
`ql_to`	*double*	reactive power injection at "to" end

Property Summary

fbus

bus index vector for "from" port (port 1) (all branches)

tbus

bus index vector for "to" port (port 2) (all branches)

r

series resistance (p.u.) for branches that are on

x

series reactance (p.u.) for branches that are on

g_fr

shunt conductance (p.u.) at "from" end for branches that are on

g_to

shunt conductance (p.u.) at "to" end for branches that are on

b_fr
shunt susceptance (p.u.) at "from" end for branches that are on

b_to
shunt susceptance (p.u.) at "to" end for branches that are on

tm
transformer off-nominal turns ratio for branches that are on

ta
xformer phase-shift angle (radians) for branches that are on

rate_a
long term flow limit (p.u.) for branches that are on

Method Summary

name()

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

export_vars()

export_vars_offline_val()

initialize(*dm*)

update_status(*dm*)

build_params(*dm*)

pp_data_cnt(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_sum(*mpopt*, *pp_args*)

pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_branch_opf

class mp.dme_branch_opf

Bases: *mp.dme_branch* (page 46), *mp.dme_shared_opf* (page 58)

mp.dme_branch_opf (page 48) - Data model element for branch for OPF.

To parent class *mp.dme_branch* (page 46), adds shadow prices on flow and angle difference limits, and pretty-printing for **lim** sections.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
`mu_flow_fr_ub`	*double*	shadow price on flow constraint at "from" end *(u/MVA)*[1]
`mu_flow_to_ub`	*double*	shadow price on flow constraint at "to" end *(u/MVA)*[1]
`mu_vad_lb`	*double*	shadow price on lower bound of voltage angle difference constraint *(u/degree)*[1]
`mu_vad_ub`	*double*	shadow price on upper bound of voltage angle difference constraint *(u/degree)*[1]

Method Summary

main_table_var_names()

export_vars()

export_vars_offline_val()

pretty_print(*dm*, *section*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_lim(*mpopt*, *pp_args*)

pp_binding_rows_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_get_title_lim(*mpopt*, *pp_args*)

pp_get_headers_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_lim(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

[1] Here *u* denotes the units of the objective function, e.g. USD.

mp.dme_bus

class mp.**dme_bus**

Bases: *mp.dm_element* (page 35)

mp.dme_bus (page 49) - Data model element for bus.

Implements the data element model for bus elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
`base_kv`	*double*	base voltage *(kV)*
`type`	*integer*	bus type (1 = PQ, 2 = PV, 3 = ref, 4 = isolated)
`area`	*integer*	area number
`zone`	*integer*	loss zone
`vm_lb`	*double*	voltage magnitude lower bound *(p.u.)*
`vm_ub`	*double*	voltage magnitude upper bound *(p.u.)*
`va`	*double*	voltage angle *(degrees)*
`vm`	*double*	voltage magnitude *(p.u.)*

Property Summary

type

node *type* (page 49) vector for buses that are on

vm_start

initial voltage magnitudes (p.u.) for buses that are on

va_start

initial voltage angles (radians) for buses that are on

vm_lb

voltage magnitude lower bounds for buses that are on

vm_ub

voltage magnitude upper bounds for buses that are on

vm_control

true if voltage is controlled, for buses that are on

Method Summary

name()

label()

labels()

main_table_var_names()

export_vars()

export_vars_offline_val()

init_status(*dm*)

update_status(*dm*)

build_params(*dm*)

pp_data_cnt(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_ext(*mpopt*, *pp_args*)

pp_data_ext(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

set_bus_type_ref(*dm*, *idx*)

set_bus_type_pv(*dm*, *idx*)

set_bus_type_pq(*dm*, *idx*)

mp.dme_bus_opf

class mp.**dme_bus_opf**

Bases: `mp.dme_bus` (page 49), `mp.dme_shared_opf` (page 58)

`mp.dme_bus_opf` (page 50) - Data model element for bus for OPF.

To parent class `mp.dme_bus` (page 49), adds shadow prices on power balance and voltage magnitude limits, and pretty-printing for **lim** sections.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
`lam_p`	*double*	active power nodal price, i.e. shadow price on active power balance constraint *(u/MW)*[1]
`lam_q`	*double*	reactive power nodal price, i.e. shadow price on reactive power balance constraint *(u/MVAr)*[1]
`mu_vm_lb`	*double*	shadow price on voltage magnitude lower bound *(u/p.u.)*[1]
`mu_vm_ub`	*double*	shadow price on voltage magnitude upper bound *(u/p.u.)*[1]

Method Summary

main_table_var_names()

export_vars()

export_vars_offline_val()

[1] Here *u* denotes the units of the objective function, e.g. USD.

pp_data_ext(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_lim(*mpopt*, *pp_args*)

pp_binding_rows_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_get_headers_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_lim(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_gen

class mp.**dme_gen**

Bases: `mp.dm_element` (page 35)

`mp.dme_gen` (page 51) - Data model element for generator.

Implements the data element model for generator elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
bus	*integer*	bus ID (uid)
vm_setpoint	*double*	voltage magnitude setpoint *(p.u.)*
pg_lb	*double*	active power output lower bound *(MW)*
pg_ub	*double*	active power output upper bound *(MW)*
qg_lb	*double*	reactive power output lower bound *(MVAr)*
qg_ub	*double*	reactive power output upper bound *(MVAr)*
pg	*double*	active power output *(MW)*
qg	*double*	reactive power output *(MVAr)*
startup_cost_cold	*double*	cold startup cost *(USD)*
pc1	*double*	lower active power output of PQ capability curve *(MW)*
pc2	*double*	upper active power output of PQ capability curve *(MW)*
qc1_lb	*double*	lower bound on reactive power output at pc1 *(MVAr)*
qc1_ub	*double*	upper bound on reactive power output at pc1 *(MVAr)*
qc2_lb	*double*	lower bound on reactive power output at pc2 *(MVAr)*
qc2_ub	*double*	upper bound on reactive power output at pc2 *(MVAr)*

Property Summary

bus

`bus` (page 51) index vector (all gens)

bus_on

vector of indices into online buses for gens that are on

pg_start

initial active power (p.u.) for gens that are on

qg_start
initial reactive power (p.u.) for gens that are on

vm_setpoint
generator voltage setpoint for gens that are on

pg_lb
active power lower bound (p.u.) for gens that are on

pg_ub
active power upper bound (p.u.) for gens that are on

qg_lb
reactive power lower bound (p.u.) for gens that are on

qg_ub
reactive power upper bound (p.u.) for gens that are on

Method Summary

name()

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

export_vars()

export_vars_offline_val()

have_cost()

initialize(*dm*)

update_status(*dm*)

apply_vm_setpoint(*dm*)

build_params(*dm*)

violated_q_lims(*dm*, *mpopt*)

isload(*idx*)

pp_have_section_sum(*mpopt*, *pp_args*)

pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_get_footers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_gen_opf

class mp.**dme_gen_opf**

Bases: *mp.dme_gen* (page 51), *mp.dme_shared_opf* (page 58)

mp.dme_gen_opf (page 53) - Data model element for generator for OPF.

To parent class *mp.dme_gen* (page 51), adds costs, shadow prices on active and reactive generation limits, and pretty-printing for **lim** sections.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
`cost_pg`	*mp.cost_table*	active power cost *(u/MW)*[1]
`cost_qg`	*mp.cost_table*	reactive power cost *(u/MVAr)*[1]
`mu_pg_lb`	*double*	shadow price on active power output lower bound *(u/MW)*[1]
`mu_pg_ub`	*double*	shadow price on active power output upper bound *(u/MW)*[1]
`mu_qg_lb`	*double*	shadow price on reactive power output lower bound *(u/MVAr)*[1]
`mu_qg_ub`	*double*	shadow price on reactive power output upper bound *(u/MVAr)*[1]

The cost tables `cost_pg` and `cost_qg` are defined as tables with the following columns:

See also *mp.cost_table* (page 161).

Method Summary

main_table_var_names()

export_vars()

export_vars_offline_val()

have_cost()

build_cost_params(*dm*, *dc*)

max_pwl_gencost()

pretty_print(*dm*, *section*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_lim(*mpopt*, *pp_args*)

pp_binding_rows_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_get_headers_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_lim(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

[1] Here *u* denotes the units of the objective function, e.g. USD.

mp.dme_load

class mp.**dme_load**

Bases: *mp.dm_element* (page 35)

mp.dme_load (page 54) - Data model element for load.

Implements the data element model for load elements, using a ZIP load model.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
`bus`	*integer*	bus ID (`uid`)
`pd`	*double*	p_p, active constant power demand *(MW)*
`qd`	*double*	q_p, reactive constant power demand *(MVAr)*
`pd_i`	*double*	p_i, active nominal[1] constant current demand *(MW)*
`qd_i`	*double*	q_i, reactive nominal[1] constant current demand *(MVAr)*
`pd_z`	*double*	p_z, active nominal[1] constant impedance demand *(MW)*
`qd_z`	*double*	q_z, reactive nominal[1] constant impedance demand *(MVAr)*
`p`	*double*	p, total active demand *(MW)*
`q`	*double*	q, total reactive demand *(MVAr)*

Implements a ZIP load model, where each load has three components, and total demand for the load *i* is given by

$$\begin{aligned} \mathrm{s} &= \mathrm{s}_p + \mathrm{s}_i|\mathrm{v}| + \mathrm{s}_z|\mathrm{v}|^2 \\ p + jq &= (p_p + jq_p) + (p_i + jq_i)|\mathrm{v}| + (p_z + jq_z)|\mathrm{v}|^2 \end{aligned} \tag{3.1}$$

Property Summary

bus

bus (page 54) index vector (all loads)

pd

active power demand (p.u.) for constant power loads that are on

qd

reactive power demand (p.u.) for constant power loads that are on

pd_i

active power demand (p.u.) for constant current loads that are on

qd_i

reactive power demand (p.u.) for constant current loads that are on

pd_z

active power demand (p.u.) for constant impedance loads that are on

qd_z

reactive power demand (p.u.) for constant impedance loads that are on

Method Summary

name()

[1] *Nominal* means for a voltage of 1 p.u.

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

count(*dm*)

update_status(*dm*)

build_params(*dm*)

pp_have_section_sum(*mpopt*, *pp_args*)

pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_get_footers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_load_cpf

class mp.**dme_load_cpf**

Bases: *mp.dme_load* (page 54)

mp.dme_load_cpf (page 55) - Data model element for load for CPF.

To parent class *mp.dme_load* (page 54), adds method for adjusting model parameters based on value of continuation parameter λ, and overrides export_vars to export these updated parameter values.

Method Summary

export_vars()

parameterized(*dm*, *dmb*, *dmt*, *lam*)

mp.dme_load_opf

class mp.**dme_load_opf**

Bases: *mp.dme_load* (page 54), *mp.dme_shared_opf* (page 58)

mp.dme_load_opf (page 55) - Data model element for load for OPF.

To parent class *mp.dme_load* (page 54), adds pretty-printing for **lim** sections.

mp.dme_shunt_cpf

class mp.**dme_shunt_cpf**

Bases: *mp.dme_shunt* (page 56)

mp.dme_shunt_cpf (page 56) - Data model element for shunt for CPF.

To parent class *mp.dme_shunt* (page 56), adds method for adjusting model parameters based on value of continuation parameter λ, and overrides *export_vars()* (page 56) to export these updated parameter values.

Method Summary

export_vars()

parameterized(*dm*, *dmb*, *dmt*, *lam*)

mp.dme_shunt

class mp.**dme_shunt**

Bases: *mp.dm_element* (page 35)

mp.dme_shunt (page 56) - Data model element for shunt.

Implements the data element model for shunt elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
bus	*integer*	bus ID (uid)
gs	*double*	g_s, shunt conductance, specified as nominal[1] active power demand *(MW)*
bs	*double*	b_s, shunt susceptance, specified as nominal[1] reactive power injection *(MVAr)*
p	*double*	p, total active power absorbed *(MW)*
q	*double*	q, total reactive power absorbed *(MVAr)*

Property Summary

bus

bus (page 56) index vector (all shunts)

gs

shunt conductance (p.u. active power demanded at

[1] *Nominal* means for a voltage of 1 p.u.

bs

V = 1.0 p.u.) for shunts that are on

Method Summary

name()

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

count(*dm*)

update_status(*dm*)

build_params(*dm*)

pp_have_section_sum(*mpopt*, *pp_args*)

pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_get_footers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_shunt_opf

class mp.**dme_shunt_opf**

Bases: *mp.dme_shunt* (page 56), *mp.dme_shared_opf* (page 58)

mp.dme_shunt_opf (page 57) - Data model element for shunt for OPF.

To parent class *mp.dme_shunt* (page 56), adds pretty-printing for **lim** sections.

3.2.3 Element Mixins

mp.dme_shared_opf

class mp.**dme_shared_opf**

Bases: handle

mp.dme_shared_opf (page 58) - Mixin class for OPF **data model element** objects.

For all elements of *mp.data_model_opf* (page 34), adds shared functionality for pretty-printing of **lim** sections.

Property Summary

ctol
constraint violation tolerance

ptol
shadow price tolerance

Method Summary

pp_set_tols_lim(*mpopt*)

pp_have_section_other(*section*, *mpopt*, *pp_args*)

pp_rows_other(*dm*, *section*, *out_e*, *mpopt*, *pp_args*)

pp_get_headers_other(*dm*, *section*, *out_e*, *mpopt*, *pp_args*)

pp_get_footers_other(*dm*, *section*, *out_e*, *mpopt*, *pp_args*)

pp_data_other(*dm*, *section*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_lim(*mpopt*, *pp_args*)

pp_rows_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_binding_rows_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_get_title_lim(*mpopt*, *pp_args*)

pp_get_headers_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_get_footers_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_lim(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_data_row_lim(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

3.3 Data Model Converter Classes

3.3.1 Containers

mp.dm_converter

class mp.**dm_converter**

Bases: *mp.element_container* (page 165)

mp.dm_converter (page 59) - Abstract base class for MATPOWER **data model converter** objects.

A data model converter provides the ability to convert data between a data model and a specific data source or format, such as the PSS/E RAW format or version 2 of the MATPOWER case format. It is used, for example, during the import stage of the data model build process.

A data model converter object is primarily a container for data model converter element (*mp.dmc_element* (page 62)) objects. Concrete data model converter classes are specific to the type or format of the data source.

By convention, data model converter variables are named `dmc` and data model converter class names begin with `mp.dm_converter`.

mp.dm_converter Methods:

- *format_tag()* (page 59) - return char array identifier for data source/format
- *copy()* (page 59) - make duplicate of object
- *build()* (page 59) - create and add element objects
- *import()* (page 59) - import data from a data source into a data model
- *export()* (page 60) - export data from a data model to a data source
- *init_export()* (page 60) - initialize a data source for export
- *save()* (page 60) - save data source to a file
- *display()* (page 60) - display the data model converter object

See the sec_dm_converter section in the *MATPOWER Developer's Manual* for more information.

See also *mp.data_model* (page 27), *mp.task* (page 7).

Method Summary

format_tag()

Return a short char array identifier for data source/format.

```
tag = dmc.format_tag()
```

E.g. the subclass for the MATPOWER case format returns `'mpc2'`.

Note: This is an abstract method that must be implemented by a subclass.

copy()

Create a duplicate of the data model converter object, calling the `copy()` method on each element.

```
new_dmc = dmc.copy()
```

build()

Create and add data model converter element objects.

```
dmc.build()
```

Create the data model converter element objects by instantiating each class in the *element_classes* (page 165) property and adding the resulting object to the *elements* (page 165) property.

import(*dm*, *d*)

Import data from a data source into a data model.

```
dm = dmc.import(dm, d)
```

Inputs
- **dm** (*mp.data_model* (page 27)) – data model
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))

Output

dm (*mp.data_model* (page 27)) – updated data model

Calls the *import()* (page 59) method for each data model converter element and its corresponding data model element.

export(*dm*, *d*)

Export data from a data model to a data source.

```
d = dmc.export(dm, d)
```

Inputs
- **dm** (*mp.data_model* (page 27)) – data model
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))

Output

d – updated data source

Calls the *export()* (page 60) method for each data model converter element and its corresponding data model element.

init_export(*dm*)

Initialize a data source for export.

```
d = dmc.export(dm)
```

Input

dm (*mp.data_model* (page 27)) – data model

Output

d – new empty data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))

Creates a new data source of the appropriate type in preparation for calling *export()* (page 60).

save(*fname*, *d*)

Save data source to a file.

```
fname_out = dmc.save(fname, d)
```

Inputs
- **fname** (*char array*)
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))

Output

fname_out (*char array*) – final file name after saving, possibly modified from input (e.g. extension added)

Note: This is an abstract method that must be implemented by a subclass.

display()

Display the data model converter object.

This method is called automatically when omitting a semicolon on a line that retuns an object of this class.

Displays the details of the data model converter elements.

mp.dm_converter_mpc2

class mp.**dm_converter_mpc2**

Bases: *mp.dm_converter* (page 59)

mp.dm_converter_mpc2 (page 61) - MATPOWER **data model converter** for MATPOWER case v2.

This class implements importing/exporting of data models for version 2 of the classic MATPOWER case format. That is, the *data source* **d** for this class is expected to be a MATPOWER case struct.

mp.dm_converter_mpc2 Methods:

- *dm_converter_mpc2()* (page 61) - constructor
- *format_tag()* (page 61) - return char array identifier for data source/format ('mpc2')
- *import()* (page 61) - import data from a MATPOWER case struct into a data model
- export() - export data from a data model to a MATPOWER case struct
- *save()* (page 61) - save MATPOWER case struct to a file

See also *mp.dm_converter* (page 59).

Constructor Summary

dm_converter_mpc2()

Specify the element classes for handling MATPOWER case format.

Method Summary

format_tag()

Return identifier tag 'mpc2' for version 2 MATPOWER case format.

import(*dm*, *d*)

Import data from a version 2 MATPOWER case struct into a data model.

init_export(*dm*)

Initialize a MATPOWER case struct for export.

save(*fname*, *d*)

Save a MATPOWER case struct to a file.

mp.dm_converter_mpc2_legacy

class mp.**dm_converter_mpc2_legacy**

Bases: *mp.dm_converter_mpc2* (page 61)

mp.dm_converter_mpc2_legacy (page 62) - Legacy MATPOWER **data model converter** for MATPOWER case v2.

Adds to *mp.dm_converter_mpc2* (page 61) the ability to handle legacy user customization.

mp.dm_converter_mpc2_legacy Methods:

- *legacy_user_mod_inputs()* (page 62) - pre-process legacy inputs for use-defined customization
- *legacy_user_nln_constraints()* (page 62) - pre-process legacy inputs for user-defined nonlinear constraints

See also *mp.dm_converter* (page 59), *mp.dm_converter_mpc2* (page 61), *mp.task_opf_legacy* (page 25).

Method Summary

legacy_user_mod_inputs(*dm*, *mpopt*, *dc*)

Handle pre-processing of inputs related to legacy user-defined variables, costs, and constraints. This includes optional `mpc` fields `A`, `l`, `u`, `N`, `fparm`, `H1`, `Cw`, `z0`, `zl`, `zu` and `user_constraints`.

legacy_user_nln_constraints(*dm*, *mpopt*)

Handle pre-processing of inputs related to legacy user-defined non-linear constraints, specifically optional `mpc` fields `user_constraints.nle` and `user_constraints.nli`.

Called by *legacy_user_mod_inputs()* (page 62) method.

3.3.2 Elements

mp.dmc_element

class mp.**dmc_element**

Bases: `handle`

mp.dmc_element (page 62)- Abstract base class for **data model converter element** objects.

A data model converter element object implements the functionality needed to import and export a particular element type from and to a given data format. All data model converter element classes inherit from *mp.dmc_element* (page 62) and each element type typically implements its own subclass.

By convention, data model converter element variables are named `dmce` and data model converter element class names begin with `mp.dmce`.

Typically, much of the import/export functionality for a particular concrete subclass can be defined simply by implementing the *table_var_map()* (page 65) method.

mp.dmc_element Methods:

- *name()* (page 63) - get name of element type, e.g. `'bus'`, `'gen'`
- *data_model_element()* (page 63) - get corresponding data model element
- *data_field()* (page 63) - get name of field in data source corresponding to default data table

- `data_subs()` (page 64) - get subscript reference struct for accessing data source
- `data_exists()` (page 64) - check if default field exists in data source
- `get_import_spec()` (page 64) - get import specification
- `get_export_spec()` (page 64) - get export specification
- `get_import_size()` (page 65) - get dimensions of data to be imported
- `get_export_size()` (page 65) - get dimensions of data to be exported
- `table_var_map()` (page 65) - get variable map for import/export
- `import()` (page 65) - import data from data source into data model element
- `import_table_values()` (page 66) - import table values for given import specification
- `get_input_table_values()` (page 66) - get values to insert in data model element table
- `import_col()` (page 66) - extract and optionally modify values from data source column
- `export()` (page 67) - export data from data model element to data source
- `export_table_values()` (page 67) - export table values for given import specification
- `init_export_data()` (page 67) - initialize data source for export from data model element
- `default_export_data_table()` (page 68) - create default (empty) data table for data source
- `default_export_data_nrows()` (page 68) - get number of rows `default_export_data_table()` (page 68)
- `export_col()` (page 68) - export a variable (table column) to the data source

See the sec_dmc_element section in the *MATPOWER Developer's Manual* for more information.

See also `mp.dm_converter` (page 59).

Method Summary

name()

Get name of element type, e.g. `'bus'`, `'gen'`.

```
name = dmce.name()
```

Output
name (*char array*) – name of element type, must be a valid struct field name

Implementation provided by an element type specific subclass.

data_model_element(*dm*, *name*)

Get the corresponding data model element.

```
dme = dmce.data_model_element(dm, name)
```

Inputs
- **dm** (`mp.data_model` (page 27)) – data model object
- **name** (*char array*) – name of element type

Output
dme (`mp.dm_element` (page 35)) – data model element object

`data_field()`

Get name of field in data source corresponding to default data table.

```
df = dmce.data_field()
```

Output
df (*char array*) – field name

`data_subs()`

Get subscript reference struct for accessing data source.

```
s = dmce.data_subs()
```

Output
s (*struct*) – same as the `s` input argument to the built-in `subsref()`, to access this element's data in data source, with fields:

- `type` – character vector or string containing `'()'`, `'{}'`, or `'.'` specifying the subscript type
- `subs` – cell array, character vector, or string containing the actual subscripts

The default implementation in this base class uses the return value of the `data_field()` (page 63) method to access a field of the data source struct. That is:

```
s = struct('type', '.', 'subs', dmce.data_field());
```

`data_exists(d)`

Check if default field exists in data source.

```
TorF = dmce.data_exists(d)
```

Input
d – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for `mp.dm_converter_mpc2` (page 61))

Output
TorF (*boolean*) – true if field exists

Check if value returned by `data_field()` (page 63) exists as a field in `d`.

`get_import_spec(dme, d)`

Get import specification.

```
spec = dmce.get_import_spec(dme, d)
```

Inputs
- **dme** (`mp.dm_element` (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for `mp.dm_converter_mpc2` (page 61))

Output
spec (*struct*) – import specification, with keys:

- `'subs'` - subscript reference struct for accessing data source, as returned by `data_subs()` (page 64)
- `'nr'`, `'nc'`, `'r'` - number of rows, number of columns, row index vector, as returned by `get_import_size()` (page 65)
- `'vmap'` - variable map, as returned by `table_var_map()` (page 65)

See also `get_export_spec()` (page 64).

get_export_spec(*dme*, *d*)

Get export specification.

```
spec = dmce.get_export_spec(dme, d)
```

Inputs

- **dme** (*mp.dm_element* (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))

Output

spec (*struct*) – export specification, see *get_import_spec()* (page 64)

See also *get_import_spec()* (page 64).

get_import_size(*d*)

Get dimensions of data to be imported.

```
[nr, nc, r] = dmce.get_import_size(d)
```

Input

d – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))

Outputs

- **nr** (*integer*) – number of rows of data
- **nc** (*integer*) – number of columns of data
- **r** (*integer*) – optional index vector *(empty by default)* of rows in data source field that correspond to data to be imported

get_export_size(*dme*)

Get dimensions of data to be exported.

```
[nr, nc, r] = dmce.get_export_size(dme)
```

Input

dme (*mp.dm_element* (page 35)) – data model element object

Outputs

- **nr** (*integer*) – number of rows of data
- **nc** (*integer*) – number of columns of data
- **r** (*integer*) – optional index vector *(empty by default)* of rows in main table of `dme` that correspond to data to be exported

table_var_map(*dme*, *d*)

Get variable map for import/export.

```
vmap = dmce.table_var_map(dme, d)
```

Inputs

- **dme** (*mp.dm_element* (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))

Output

vmap (*struct*) – variable map, see `tab_var_map` in the *MATPOWER Developer's Manual* for details

This method initializes each entry to `{'col', []}` by default, so subclasses only need to assign `vmap.(vn){2}` for columns that map directly from a column of the data source.

import(*dme*, *d*, *var_names*, *ridx*)

Import data from data source into data model element.

```
dme = dmce.import(dme, d, var_names, ridx)
```

Inputs
- **dme** (`mp.dm_element` (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for `mp.dm_converter_mpc2` (page 61))
- **var_names** (*cell array*) – *(optional)* list of names of variables (columns of main table) to import *(default is all variables)*
- **ridx** (*integer*) – *(optional)* vector of row indices of data to import *(default is all rows)*

Output
dme (`mp.dm_element` (page 35)) – updated data model element object

See also `export()` (page 67).

import_table_values(*dme*, *d*, *spec*, *var_names*, *ridx*)

Import table values for given import specification.

```
dme = dmce.import_table_values(dme, d, spec, var_names, ridx)
```

Inputs
- **dme** (`mp.dm_element` (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for `mp.dm_converter_mpc2` (page 61))
- **spec** (*struct*) – import specification, see `get_import_spec()` (page 64)
- **var_names** (*cell array*) – *(optional)* list of names of variables (columns of main table) to import *(default is all variables)*
- **ridx** (*integer*) – *(optional)* vector of row indices of data to import *(default is all rows)*

Output
dme (`mp.dm_element` (page 35)) – updated data model element object

Called by `import()` (page 65).

get_input_table_values(*d*, *spec*, *var_names*, *ridx*)

Get values to insert in data model element table.

```
vals = dmce.get_input_table_values(d, spec, var_names, ridx)
```

Inputs
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for `mp.dm_converter_mpc2` (page 61))
- **spec** (*struct*) – import specification, see `get_import_spec()` (page 64)
- **var_names** (*cell array*) – *(optional)* list of names of variables (columns of main table) to import *(default is all variables)*
- **ridx** (*integer*) – *(optional)* vector of row indices of data to import *(default is all rows)*

Output
vals (*cell array*) – values to assign to table columns in data model element

Called by `import_table_values()` (page 66).

import_col(*d*, *spec*, *vn*, *c*, *sf*)

Extract and optionally modify values from data source column.

```
vals = dmce.import_col(d, spec, vn, c, sf)
```

Inputs
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))
- **spec** (*struct*) – import specification, see *get_import_spec()* (page 64)
- **vn** (*char array*) – variable name
- **c** (*integer*) – column index for data in data source
- **sf** (*double or function handle*) – *(optional)* scale factor, function is called as *sf(dmce, vn)*

Output
vals (*cell array*) – values to assign to table columns in data model element

Called by *get_input_table_values()* (page 66).

export(*dme*, *d*, *var_names*, *ridx*)

Export data from data model element to data source.

```
d = dmce.export(dme, d, var_names, ridx)
```

Inputs
- **dme** (*mp.dm_element* (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))
- **var_names** (*cell array*) – *(optional)* list of names of variables (columns of main table) to export *(default is all variables)*
- **ridx** (*integer*) – *(optional)* vector of row indices of data to export *(default is all rows)*

Output
d – updated data source

See also *import()* (page 65).

export_table_values(*dme*, *d*, *spec*, *var_names*, *ridx*)

Export table values for given import specification.

```
d = dmce.export_table_values(dme, d, spec, var_names, ridx)
```

Inputs
- **dme** (*mp.dm_element* (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))
- **spec** (*struct*) – export specification, see *get_export_spec()* (page 64)
- **var_names** (*cell array*) – *(optional)* list of names of variables (columns of main table) to export *(default is all variables)*
- **ridx** (*integer*) – *(optional)* vector of row indices of data to export *(default is all rows)*

Output
d – updated data source

Called by *export()* (page 67).

init_export_data(*dme*, *d*, *spec*)

Initialize data source for export from data model element.

```
d = dmce.init_export_data(dme, d, spec)
```

Inputs
- **dme** (*mp.dm_element* (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))
- **spec** (*struct*) – export specification, see *get_export_spec()* (page 64)

Output
d – updated data source

Called by `export_table_values()` (page 67).

`default_export_data_table`(*spec*)

Create default (empty) data table for data source.

```
dt = dmce.default_export_data_table(spec)
```

Input
spec (*struct*) – export specification, see `get_export_spec()` (page 64)
Output
dt – data table for data source, type depends on implementing subclass

Called by `init_export_data()` (page 67).

`default_export_data_nrows`(*spec*)

Get number of rows for `default_export_data_table()` (page 68).

```
nr = default_export_data_nrows(spec)
```

Input
spec (*struct*) – export specification, see `get_export_spec()` (page 64)
Output
nr (*integer*) – number of rows

Called by `default_export_data_table()` (page 68).

`export_col`(*dme*, *d*, *spec*, *vn*, *ridx*, *c*, *sf*)

Export a variable (table column) to the data source.

```
d = dmce.export_col(dme, d, spec, vn, ridx, c, sf)
```

Inputs
- **dme** (`mp.dm_element` (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for `mp.dm_converter_mpc2` (page 61))
- **spec** (*struct*) – export specification, see `get_export_spec()` (page 64)
- **vn** (*char array*) – variable name
- **ridx** (*integer*) – *(optional)* vector of row indices of data to export *(default is all rows)*
- **c** (*integer*) – column index for data in data source
- **sf** (*double or function handle*) – *(optional)* scale factor, function is called as *sf(dmce, vn)*

Output
d – updated data source

Called by `export_table_values()` (page 67).

mp.dmce_branch_mpc2

class mp.**dmce_branch_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_branch_mpc2 (page 69) - Data model converter element for branch for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

default_export_data_table(*spec*)

mp.dmce_bus_mpc2

class mp.**dmce_bus_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_bus_mpc2 (page 69) - Data model converter element for bus for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

init_export_data(*dme*, *d*, *spec*)

default_export_data_table(*spec*)

bus_name_import(*mpc*, *spec*, *vn*, *c*)

bus_name_export(*dme*, *mpc*, *spec*, *vn*, *ridx*, *c*)

bus_status_import(*mpc*, *spec*, *vn*, *c*)

mp.dmce_gen_mpc2

class mp.**dmce_gen_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_gen_mpc2 (page 69) - Data model converter element for generator for MATPOWER case v2.

Property Summary

pwl1

indices of single-block piecewise linear costs, all gens *(automatically converted to linear cost)*

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

default_export_data_table(*spec*)

start_cost_import(*mpc*, *spec*, *vn*)

start_cost_export(*dme*, *mpc*, *spec*, *vn*, *ridx*)

gen_cost_import(*mpc*, *spec*, *vn*, *p_or_q*)

gen_cost_export(*dme*, *mpc*, *spec*, *vn*, *p_or_q*, *ridx*)

static **gencost2cost_table**(*gencost*)

static **cost_table2gencost**(*gencost0*, *cost*, *ridx*)

mp.dmce_load_mpc2

class mp.**dmce_load_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_load_mpc2 (page 70) - Data model converter element for load for MATPOWER case v2.

Property Summary

bus

Method Summary

name()

data_field()

get_import_size(*mpc*)

get_export_size(*dme*)

table_var_map(*dme*, *mpc*)

scale_factor_fcn(*vn*, *zip_sf*)

sys_wide_zip_loads(*mpc*)

mp.dmce_shunt_mpc2

class mp.**dmce_shunt_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_shunt_mpc2 (page 71) - Data model converter element for shunt for MATPOWER case v2.

Property Summary

bus

Method Summary

name()

data_field()

get_import_size(*mpc*)

get_export_size(*dme*)

table_var_map(*dme*, *mpc*)

3.4 Network Model Classes

3.4.1 Containers

mp.form

class mp.**form**

Bases: handle

mp.form (page 71) - Abstract base class for MATPOWER **formulation**.

Used as a mix-in class for all **network model element** classes. That is, each concrete network model element class must inherit, at least indirectly, from both *mp.nm_element* (page 107) and *mp.form* (page 71).

mp.form (page 71) provides properties and methods that are specific to the network model formulation (e.g. DC version, AC polar power version, etc.).

For more details, see the sec_net_model_formulations section in the *MATPOWER Developer's Manual* and the derivations in *MATPOWER Technical Note 5*.

mp.form Properties:

subclasses provide properties for model parameters

mp.form Methods:

- *form_name()* (page 72) - get char array w/name of formulation
- *form_tag()* (page 72) - get char array w/short label of formulation
- *model_params()* (page 72) - get cell array of names of model parameters
- *model_vvars()* (page 72) - get cell array of names of voltage state variables
- *model_zvars()* (page 72) - get cell array of names of non-voltage state variables

- *get_params()* (page 73) - get network model element parameters
- *find_form_class()* (page 73) - get name of network element object's formulation subclass

See also *mp.nm_element* (page 107).

Method Summary

form_name()

Get user-readable name of formulation, e.g. `'DC'`, `'AC-cartesian'`, `'AC-polar'`.

```
name  = nme.form_name()
```

Output
name (*char array*) – name of formulation

Note: This is an abstract method that must be implemented by a subclass.

form_tag()

Get short label of formulation, e.g. `'dc'`, `'acc'`, `'acp'`.

```
tag  = nme.form_tag()
```

Output
tag (*char array*) – short label of formulation

Note: This is an abstract method that must be implemented by a subclass.

model_params()

Get cell array of names of model parameters.

```
params  = nme.model_params()
```

Output
params (*cell array of char arrays*) – names of object properies for model parameters

Note: This is an abstract method that must be implemented by a subclass.

model_vvars()

Get cell array of names of voltage state variables.

```
vtypes = nme.model_vvars()
```

Output
vtypes (*cell array of char arrays*) – names of network object properties for voltage state variables

The network model object, which inherits from mp_idx_manager, uses these values as set types for tracking its voltage state variables.

Note: This is an abstract method that must be implemented by a subclass.

model_zvars()

Get cell array of names of non-voltage state variables.

```
vtypes = nme.model_zvars()
```

Output
vtypes (*cell array of char arrays*) – names of network object properties for voltage state variables

The network model object, which inherits from mp_idx_manager, uses these values as set types for tracking its non-voltage state variables.

Note: This is an abstract method that must be implemented by a subclass.

get_params(*idx*, *names*)

Get network model element parameters.

```
[p1, p2, ..., pN] = nme.get_params(idx)
pA = nme.get_params(idx, nameA)
[pA, pB, ...] = nme.get_params(idx, {nameA, nameB, ...})
```

Inputs

- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns parameters corresponding to all ports
- **names** (*char array or cell array of char arrays*) – *(optional)* name(s) of parameters to return

Outputs

- **p1, p2, ..., pN** – full set of parameters in canonical order
- **pA, pB** – parameters specified by `names`

If a particular parameter in the object is empty, this method returns a sparse zero matrix or vector of the appropriate size.

find_form_class()

Get name of network element object's formulation subclass.

```
form_class = nme.find_form_class()
```

Output

form_class (*char array*)

Selects from this netork model elements parent classes, the *mp.form* (page 71) subclass, that is not a subclass of *mp.nm_element* (page 107), with the longest inheritance path back to *mp.form* (page 71).

mp.form_ac

class mp.**form_ac**

Bases: *mp.form* (page 71)

mp.form_ac (page 73) - Abstract base class for MATPOWER AC **formulations**.

Used as a mix-in class for all **network model element** classes with an AC network model formulation. That is, each concrete network model element class with an AC formulation must inherit, at least indirectly, from both *mp.nm_element* (page 107) and *mp.form_ac* (page 73).

mp.form_ac (page 73) defines the complex port injections as functions of the state variables $\mathbf{x}$, that is, the complex voltages $\mathbf{v}$ and non-voltage states $\mathbf{z}$. The are defined in terms of 3 compoents, the linear current injection and linear power injection components,

$$\begin{aligned} \mathbf{i}^{lin}(\mathbf{x}) &= \begin{bmatrix} \underline{\mathbf{Y}} & \underline{\mathbf{L}} \end{bmatrix} \mathbf{x} + \underline{\mathbf{i}} \\ &= \underline{\mathbf{Y}}\mathbf{v} + \underline{\mathbf{L}}\mathbf{z} + \underline{\mathbf{i}} \end{aligned} \tag{3.2}$$

$$\begin{aligned} \mathbf{s}^{lin}(\mathbf{x}) &= \begin{bmatrix} \underline{\mathbf{M}} & \underline{\mathbf{N}} \end{bmatrix} \mathbf{x} + \underline{\mathbf{s}} \\ &= \underline{\mathbf{M}}\mathbf{v} + \underline{\mathbf{N}}\mathbf{z} + \underline{\mathbf{s}}, \end{aligned} \tag{3.3}$$

and an arbitrary nonlinear injection component represented by $\mathbf{s}^{nln}(\mathbf{x})$ or $\mathbf{i}^{nln}(\mathbf{x})$. The full complex power and current port injection functions implemented by *mp.form_ac* (page 73), are respectively

$$
\begin{aligned}
\mathbf{g}^S(\mathbf{x}) &= \left[{}^{\smallsetminus}\mathbf{v}_{\smallsetminus}\right] \left(\mathbf{i}^{lin}(\mathbf{x})\right)^* + \mathbf{s}^{lin}(\mathbf{x}) + \mathbf{s}^{nln}(\mathbf{x}) \\
&= \left[{}^{\smallsetminus}\mathbf{v}_{\smallsetminus}\right] \left(\underline{\mathbf{Y}}\mathbf{v} + \underline{\mathbf{L}}\mathbf{z} + \underline{\mathbf{i}}\right)^* + \underline{\mathbf{M}}\mathbf{v} + \underline{\mathbf{N}}\mathbf{z} + \underline{\mathbf{s}} + \mathbf{s}^{nln}(\mathbf{x})
\end{aligned}
\tag{3.4}
$$

$$
\begin{aligned}
\mathbf{g}^I(\mathbf{x}) &= \mathbf{i}^{lin}(\mathbf{x}) + \left[{}^{\smallsetminus}\mathbf{s}^{lin}(\mathbf{x})_{\smallsetminus}\right]^* \mathbf{\Lambda}^* + \mathbf{i}^{nln}(\mathbf{x}) \\
&= \underline{\mathbf{Y}}\mathbf{v} + \underline{\mathbf{L}}\mathbf{z} + \underline{\mathbf{i}} + \left[{}^{\smallsetminus}\underline{\mathbf{M}}\mathbf{v} + \underline{\mathbf{N}}\mathbf{z} + \underline{\mathbf{s}}_{\smallsetminus}\right]^* \mathbf{\Lambda}^* + \mathbf{i}^{nln}(\mathbf{x})
\end{aligned}
\tag{3.5}
$$

where $\underline{\mathbf{Y}}$, $\underline{\mathbf{L}}$, $\underline{\mathbf{M}}$, $\underline{\mathbf{N}}$, $\underline{\mathbf{i}}$, and $\underline{\mathbf{s}}$, along with $\mathbf{s}^{nln}(\mathbf{x})$ or $\mathbf{i}^{nln}(\mathbf{x})$, are the model parameters.

For more details, see the sec_nm_formulations_ac section in the *MATPOWER Developer's Manual* and the derivations in *MATPOWER Technical Note 5*.

mp.form_dc Properties:

- *Y* (page 75) - $n_p n_k \times n_n$ matrix $\underline{\mathbf{Y}}$ of model parameters
- *L* (page 75) - $n_p n_k \times n_\mathbf{z}$ matrix $\underline{\mathbf{L}}$ of model parameters
- *M* (page 75) - $n_p n_k \times n_n$ matrix $\underline{\mathbf{M}}$ of model parameters
- *N* (page 75) - $n_p n_k \times n_\mathbf{z}$ matrix $\underline{\mathbf{N}}$ of model parameters
- *i* (page 75) - $n_p n_k \times 1$ vector $\underline{\mathbf{i}}$ of model parameters
- *s* (page 75) - $n_p n_k \times 1$ vector $\underline{\mathbf{s}}$ of model parameters
- `params_ncols` - specify number of columns for each parameter
- *inln* (page 75) - function to compute $\mathbf{i}^{nln}(\mathbf{x})$
- *snln* (page 75) - function to compute $\mathbf{s}^{nln}(\mathbf{x})$
- *inln_hess* (page 75) - function to compute Hessian of $\mathbf{i}^{nln}(\mathbf{x})$
- *snln_hess* (page 75) - function to compute Hessian of $\mathbf{s}^{nln}(\mathbf{x})$

mp.form_dc Methods:

- *model_params()* (page 76) - get network model element parameters (`{'Y', 'L', 'M', 'N', 'i', 's'}`)
- *model_zvars()* (page 76) - get cell array of names of non-voltage state variables (`{'zr', 'zi'}`)
- *port_inj_current()* (page 76) - compute port current injections from network state
- *port_inj_power()* (page 76) - compute port power injections from network state
- *port_inj_current_hess()* (page 77) - compute Hessian of port current injections
- *port_inj_power_hess()* (page 78) - compute Hessian of port power injections
- *port_inj_current_jac()* (page 78) - abstract method to compute voltage-related Jacobian terms
- *port_inj_current_hess_v()* (page 78) - abstract method to compute voltage-related Hessian terms
- *port_inj_current_hess_vz()* (page 78) - abstract method to compute voltage-related Hessian terms
- *port_inj_power_jac()* (page 78) - abstract method to compute voltage-related Jacobian terms
- *port_inj_power_hess_v()* (page 78) - abstract method to compute voltage-related Hessian terms
- *port_inj_power_hess_vz()* (page 79) - abstract method to compute voltage-related Hessian terms

- `port_apparent_power_lim_fcn()` (page 79) - compute port squared apparent power injection constraints
- `port_active_power_lim_fcn()` (page 79) - compute port active power injection constraints
- `port_active_power2_lim_fcn()` (page 79) - compute port squared active power injection constraints
- `port_current_lim_fcn()` (page 80) - compute port squared current injection constraints
- `port_apparent_power_lim_hess()` (page 80) - compute port squared apparent power injection Hessian
- `port_active_power_lim_hess()` (page 81) - compute port active power injection Hessian
- `port_active_power2_lim_hess()` (page 81) - compute port squared active power injection Hessian
- `port_current_lim_hess()` (page 81) - compute port squared current injection Hessian
- `aux_data_va_vm()` (page 82) - abstract method to return voltage angles/magnitudes from auxiliary data

See also `mp.form` (page 71), `mp.form_acc` (page 82), `mp.form_acp` (page 86), `mp.form_dc` (page 88), `mp.nm_element` (page 107).

Property Summary

`Y = []`

(double) $n_p n_k \times n_n$ matrix $\underline{\mathbf{Y}}$ of model parameter coefficients for $\mathbf{v}$

`L = []`

(double) $n_p n_k \times n_\mathbf{z}$ matrix $\underline{\mathbf{L}}$ of model parameter coefficients for $\mathbf{z}$

`M = []`

(double) $n_p n_k \times n_n$ matrix $\underline{\mathbf{M}}$ of model parameter coefficients for $\mathbf{v}$

`N = []`

(double) $n_p n_k \times n_\mathbf{z}$ matrix $\underline{\mathbf{N}}$ of model parameter coefficients for $\mathbf{z}$

`i = []`

(double) $n_p n_k \times 1$ vector $\underline{\mathbf{i}}$ of model parameters

`s = []`

(double) $n_p n_k \times 1$ vector $\underline{\mathbf{s}}$ of model parameters

`param_ncols = struct('Y',2,'L',3,'M',2,'N',3,'i',1,'s',1)`

(struct) specify number of columns for each parameter, where

- 1 => single column (i.e. a vector)
- 2 => n_p columns
- 3 => $n_\mathbf{z}$ columns

`inln = ''`

(function handle) function to compute $\mathbf{i}^{nln}(\mathbf{x})$

`snln = ''`

(function handle) function to compute $\mathbf{s}^{nln}(\mathbf{x})$

`inln_hess = ''`

(function handle) function to compute Hessian of $\mathbf{i}^{nln}(\mathbf{x})$

snln_hess = ''

(function handle) function to compute Hessian of $s^{nln}(x)$

Method Summary

model_params()

Get cell array of names of model parameters, i.e. `{'Y', 'L', 'M', 'N', 'i', 's'}`.

See `mp.form.model_params()` (page 72).

model_zvars()

Get cell array of names of non-voltage state variables, i.e. `{'zr', 'zi'}`.

See `mp.form.model_zvars()` (page 72).

port_inj_current(*x_*, *sysx*, *idx*)

Compute port complex current injections from network state.

```
I = nme.port_inj_current(x_, sysx)
I = nme.port_inj_current(x_, sysx, idx)
[I, Iv1, Iv2] = nme.port_inj_current(...)
[I, Iv1, Iv2, Izr, Izi] = nme.port_inj_current(...)
```

Compute the complex current injections for all or a selected subset of ports and, optionally, the components of the Jacobian, that is, the sparse matrices of partial derivatives with respect to each real component of the state. The voltage portion, which depends on the formulation (polar vs cartesian), is delegated to the `port_inj_current_jac()` method implemented by the appropriate subclass.

The state can be provided as a stacked aggregate of the state variables (port voltages and non-voltage states) for the full collection of network model elements of this type, or as the combined state for the entire network.

Inputs

- **x_** (*complex double*) – state vector x
- **sysx** (*0 or 1*) – which state is provided in `x_`
  - 0 – class aggregate state
  - 1 – *(default)* full system state
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs

- **I** (*complex double*) – vector of port complex current injections, $g^I(x)$
- **Iv1** (*complex double*) – Jacobian of port complex current injections w.r.t 1st voltage component, g^I_θ (polar) or g^I_u (cartesian)
- **Iv2** (*complex double*) – Jacobian of port complex current injections w.r.t 2nd voltage component, g^I_ν (polar) or g^I_w (cartesian)
- **Izr** (*complex double*) – Jacobian of port complex current injections w.r.t real part of non-voltage state, $g^I_{z_r}$
- **Izi** (*complex double*) – Jacobian of port complex current injections w.r.t imaginary part of non-voltage state, $g^I_{z_i}$

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also `port_inj_power()` (page 76).

port_inj_power(*x_*, *sysx*, *idx*)

Compute port complex power injections from network state.

```
S = nme.port_inj_power(x_, sysx)
S = nme.port_inj_power(x_, sysx, idx)
```

(continues on next page)

(continued from previous page)

```
[S, Sv1, Sv2] = nme.port_inj_power(...)
[S, Sv1, Sv2, Szr, Szi] = nme.port_inj_power(...)
```

Compute the complex power injections for all or a selected subset of ports and, optionally, the components of the Jacobian, that is, the sparse matrices of partial derivatives with respect to each real component of the state. The voltage portion, which depends on the formulation (polar vs cartesian), is delegated to the `port_inj_power_jac()` method implemented by the appropriate subclass.

The state can be provided as a stacked aggregate of the state variables (port voltages and non-voltage states) for the full collection of network model elements of this type, or as the combined state for the entire network.

Inputs

- **x_** (*complex double*) – state vector $\mathbf{x}$
- **sysx** (*0 or 1*) – which state is provided in `x_`
  - 0 – class aggregate state
  - 1 – *(default)* full system state
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs

- **S** (*complex double*) – vector of port complex power injections, $\mathbf{g}^S(\mathbf{x})$
- **Sv1** (*complex double*) – Jacobian of port complex power injections w.r.t 1st voltage component, $\mathbf{g}^S_{\boldsymbol{\theta}}$ (polar) or $\mathbf{g}^S_{\boldsymbol{u}}$ (cartesian)
- **Sv2** (*complex double*) – Jacobian of port complex power injections w.r.t 2nd voltage component, $\mathbf{g}^S_{\boldsymbol{\nu}}$ (polar) or $\mathbf{g}^S_{\boldsymbol{w}}$ (cartesian)
- **Szr** (*complex double*) – Jacobian of port complex power injections w.r.t real part of non-voltage state, $\mathbf{g}^S_{\boldsymbol{z}_r}$
- **Szi** (*complex double*) – Jacobian of port complex power injections w.r.t imaginary part of non-voltage state, $\mathbf{g}^S_{\boldsymbol{z}_i}$.

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also `port_inj_current()` (page 76).

port_inj_current_hess(*x_*, *lam*, *sysx*, *idx*)

Compute Hessian of port current injections from network state.

```
H = nme.port_inj_current_hess(x_, lam)
H = nme.port_inj_current_hess(x_, lam, sysx)
H = nme.port_inj_current_hess(x_, lam, sysx, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by muliplying the transpose of the port current injection Jacobian by a vector $\boldsymbol{\lambda}$.

Inputs

- **x_** (*complex double*) – state vector $\mathbf{x}$
- **lam** (*double*) – vector $\boldsymbol{\lambda}$ of multipliers, one for each port
- **sysx** (*0 or 1*) – which state is provided in `x_`
  - 0 – class aggregate state
  - 1 – *(default)* full system state
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs

H (*complex double*) – sparse Hessian matrix of port complex current injections corresponding to specified $\boldsymbol{\lambda}$, namely $\mathbf{g}^I_{\mathbf{xx}}(\boldsymbol{\lambda})$

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also `port_inj_current()` (page 76).

port_inj_power_hess(*x_*, *lam*, *sysx*, *idx*)

Compute Hessian of port power injections from network state.

```
H = nme.port_inj_power_hess(x_, lam)
H = nme.port_inj_power_hess(x_, lam, sysx)
H = nme.port_inj_power_hess(x_, lam, sysx, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by muliplying the transpose of the port power injection Jacobian by a vector $\boldsymbol{\lambda}$.

Inputs

- **x_** (*complex double*) – state vector $\mathbf{x}$
- **lam** (*double*) – vector $\boldsymbol{\lambda}$ of multipliers, one for each port
- **sysx** (*0 or 1*) – which state is provided in `x_`
  - 0 – class aggregate state
  - 1 – *(default)* full system state
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs

H (*complex double*) – sparse Hessian matrix of port complex power injections corresponding to specified $\boldsymbol{\lambda}$, namely $\mathbf{g}^S_{\mathbf{xx}}(\boldsymbol{\lambda})$

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also `port_inj_power()` (page 76).

port_inj_current_jac(*n*, *v_*, *Y*, *M*, *invdiagvic*, *diagSlincJ*)

Abstract method to compute voltage-related Jacobian terms.

Called by `port_inj_current()` (page 76) to compute voltage-related Jacobian terms. See `mp.form_acc.port_inj_current_jac()` (page 83) and `mp.form_acp.port_inj_current_jac()` (page 87) for details.

port_inj_current_hess_v(*x_*, *lam*, *v_*, *z_*, *diaginvic*, *Y*, *M*, *diagSlincJ*, *dlamJ*)

Abstract method to compute voltage-related Hessian terms.

Called by `port_inj_current_hess()` (page 77) to compute voltage-related Hessian terms. See `mp.form_acc.port_inj_current_hess_v()` (page 83) and `mp.form_acp.port_inj_current_hess_v()` (page 87) for details.

port_inj_current_hess_vz(*x_*, *lam*, *v_*, *z_*, *diaginvic*, *N*, *dlamJ*)

Abstract method to compute voltage-related Hessian terms.

Called by `port_inj_current_hess()` (page 77) to compute voltage/non-voltage-related Hessian terms. See `mp.form_acc.port_inj_current_hess_vz()` (page 83) and `mp.form_acp.port_inj_current_hess_vz()` (page 87) for details.

port_inj_power_jac(*n*, *v_*, *Y*, *M*, *diagv*, *diagvi*, *diagIlincJ*)

Abstract method to compute voltage-related Jacobian terms.

Called by `port_inj_power()` (page 76) to compute voltage-related Jacobian terms. See `mp.form_acc.port_inj_power_jac()` (page 84) and `mp.form_acp.port_inj_power_jac()` (page 87) for details.

port_inj_power_hess_v(*x_*, *lam*, *v_*, *z_*, *diagvi*, *Y*, *M*, *diagIlincJ*, *dlamJ*)

Abstract method to compute voltage-related Hessian terms.

Called by `port_inj_power_hess()` (page 78) to compute voltage-related Hessian terms. See `mp.form_acc.port_inj_power_hess_v()` (page 84) and `mp.form_acp.port_inj_power_hess_v()` (page 87) for details.

port_inj_power_hess_vz(*x_*, *lam*, *v_*, *z_*, *diagvi*, *L*, *dlamJ*)

Abstract method to compute voltage-related Hessian terms.

Called by `port_inj_power_hess()` (page 78) to compute voltage/non-voltage-related Hessian terms. See `mp.form_acc.port_inj_power_hess_vz()` (page 84) and `mp.form_acp.port_inj_power_hess_vz()` (page 88) for details.

port_apparent_power_lim_fcn(*x_*, *nm*, *idx*, *hmax*)

Compute port squared apparent power injection constraints.

```
h = nme.port_apparent_power_lim_fcn(x_, nm, idx, hmax)
[h, dh] = nme.port_apparent_power_lim_fcn(x_, nm, idx, hmax)
```

Compute constraint function and optionally the Jacobian for the limit on port squared apparent power injections based on complex outputs of `port_inj_power()` (page 76).

Inputs

- **x_** (*complex double*) – state vector $\mathbf{x}$
- **nm** (`mp.net_model` (page 90)) – network model object
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports
- **hmax** (*double*) – vector of squared apparent power limits

Outputs

- **h** (*double*) – constraint function, $\boldsymbol{h}^{\mathrm{flow}}(\boldsymbol{x})$
- **dh** (*double*) – constraint Jacobian, $\boldsymbol{h}^{\mathrm{flow}}_{\boldsymbol{x}}$

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also `port_inj_power()` (page 76).

port_active_power_lim_fcn(*x_*, *nm*, *idx*, *hmax*)

Compute port active power injection constraints.

```
h = nme.port_active_power_lim_fcn(x_, nm, idx, hmax)
[h, dh] = nme.port_active_power_lim_fcn(x_, nm, idx, hmax)
```

Compute constraint function and optionally the Jacobian for the limit on port active power injections based on complex outputs of `port_inj_power()` (page 76).

Inputs

- **x_** (*complex double*) – state vector $\mathbf{x}$
- **nm** (`mp.net_model` (page 90)) – network model object
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports
- **hmax** (*double*) – vector of active power limits

Outputs

- **h** (*double*) – constraint function, $\boldsymbol{h}^{\mathrm{flow}}(\boldsymbol{x})$
- **dh** (*double*) – constraint Jacobian, $\boldsymbol{h}^{\mathrm{flow}}_{\boldsymbol{x}}$

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also `port_inj_power()` (page 76).

port_active_power2_lim_fcn(*x_*, *nm*, *idx*, *hmax*)

Compute port squared active power injection constraints.

```
h = nme.port_active_power2_lim_fcn(x_, nm, idx, hmax)
[h, dh] = nme.port_active_power2_lim_fcn(x_, nm, idx, hmax)
```

Compute constraint function and optionally the Jacobian for the limit on port squared active power injections based on complex outputs of *port_inj_power()* (page 76).

Inputs

- **x_** (*complex double*) – state vector $\mathbf{x}$
- **nm** (*mp.net_model* (page 90)) – network model object
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports
- **hmax** (*double*) – vector of squared active power limits

Outputs

- **h** (*double*) – constraint function, $\boldsymbol{h}^{\mathrm{flow}}(\boldsymbol{x})$
- **dh** (*double*) – constraint Jacobian, $\boldsymbol{h}_{\boldsymbol{x}}^{\mathrm{flow}}$

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also *port_inj_power()* (page 76).

port_current_lim_fcn(*x_*, *nm*, *idx*, *hmax*)

Compute port squared current injection constraints.

```
h = nme.port_current_lim_fcn(x_, nm, idx, hmax)
[h, dh] = nme.port_current_lim_fcn(x_, nm, idx, hmax)
```

Compute constraint function and optionally the Jacobian for the limit on port squared current injections based on complex outputs of *port_inj_current()* (page 76).

Inputs

- **x_** (*complex double*) – state vector $\mathbf{x}$
- **nm** (*mp.net_model* (page 90)) – network model object
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports
- **hmax** (*double*) – vector of squared current limits

Outputs

- **h** (*double*) – constraint function, $\boldsymbol{h}^{\mathrm{flow}}(\boldsymbol{x})$
- **dh** (*double*) – constraint Jacobian, $\boldsymbol{h}_{\boldsymbol{x}}^{\mathrm{flow}}$

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also *port_inj_current()* (page 76).

port_apparent_power_lim_hess(*x_*, *lam*, *nm*, *idx*)

Compute port squared apparent power injection Hessian.

```
d2H = nme.port_apparent_power_lim_hess(x_, lam, nm, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by muliplying the transpose of the constraint Jacobian by a vector $\boldsymbol{\mu}$. Results are based on the complex outputs of *port_inj_power()* (page 76) and *port_inj_power_hess()* (page 78).

Inputs

- **x_** (*complex double*) – state vector $\mathbf{x}$
- **lam** (*double*) – vector $\boldsymbol{\mu}$ of multipliers, one for each port
- **nm** (*mp.net_model* (page 90)) – network model object
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs
d2H (*double*) – sparse constraint Hessian matrix, $\boldsymbol{h}^{\text{flow}}_{\boldsymbol{xx}}(\boldsymbol{\mu})$

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also `port_inj_power()` (page 76), `port_inj_power_hess()` (page 78).

port_active_power_lim_hess(*x_*, *lam*, *nm*, *idx*)

Compute port active power injection Hessian.

```
d2H = nme.port_active_power_lim_hess(x_, lam, nm, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by muliplying the transpose of the constraint Jacobian by a vector $\boldsymbol{\mu}$. Results are based on the complex outputs of `port_inj_power()` (page 76) and `port_inj_power_hess()` (page 78).

Inputs
- **x_** (*complex double*) – state vector $\mathbf{x}$
- **lam** (*double*) – vector $\boldsymbol{\mu}$ of multipliers, one for each port
- **nm** (`mp.net_model` (page 90)) – network model object
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs
d2H (*double*) – sparse constraint Hessian matrix, $\boldsymbol{h}^{\text{flow}}_{\boldsymbol{xx}}(\boldsymbol{\mu})$

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also `port_inj_power()` (page 76), `port_inj_power_hess()` (page 78).

port_active_power2_lim_hess(*x_*, *lam*, *nm*, *idx*)

Compute port squared active power injection Hessian.

```
d2H = nme.port_active_power2_lim_hess(x_, lam, nm, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by muliplying the transpose of the constraint Jacobian by a vector $\boldsymbol{\mu}$. Results are based on the complex outputs of `port_inj_power()` (page 76) and `port_inj_power_hess()` (page 78).

Inputs
- **x_** (*complex double*) – state vector $\mathbf{x}$
- **lam** (*double*) – vector $\boldsymbol{\mu}$ of multipliers, one for each port
- **nm** (`mp.net_model` (page 90)) – network model object
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs
d2H (*double*) – sparse constraint Hessian matrix, $\boldsymbol{h}^{\text{flow}}_{\boldsymbol{xx}}(\boldsymbol{\mu})$

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also `port_inj_power()` (page 76), `port_inj_power_hess()` (page 78).

port_current_lim_hess(*x_*, *lam*, *nm*, *idx*)

Compute port squared current injection Hessian.

```
d2H = nme.port_current_lim_hess(x_, lam, nm, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by muliplying the transpose of the constraint Jacobian by a vector $\boldsymbol{\mu}$. Results are based on the complex outputs of `port_inj_current()` (page 76) and `port_inj_current_hess()` (page 77).

Inputs
- **x_** (*complex double*) – state vector $\mathbf{x}$
- **lam** (*double*) – vector $\boldsymbol{\mu}$ of multipliers, one for each port
- **nm** (`mp.net_model` (page 90)) – network model object
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs
d2H (*double*) – sparse constraint Hessian matrix, $\boldsymbol{h}_{\boldsymbol{xx}}^{\text{flow}}(\boldsymbol{\mu})$

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also `port_inj_current()` (page 76), `port_inj_current_hess()` (page 77).

aux_data_va_vm(*ad*)

Abstract method to return voltage angles/magnitudes from auxiliary data.

```
[va, vm] = nme.aux_data_va_vm(ad)
```

Input
ad (*struct*) – struct of auxiliary data

Outputs
- **va** (*double*) – vector of voltage angles corresponding to voltage information stored in auxiliary data
- **vm** (*double*) – vector of voltage magnitudes corresponding to voltage information stored in auxiliary data

Implemented by `mp.form_acc.aux_data_va_vm()` (page 84) and `mp.form_acp.aux_data_va_vm()` (page 88).

mp.form_acc

class mp.**form_acc**

Bases: `mp.form_ac` (page 73)

`mp.form_acc` (page 82) - Base class for MATPOWER AC cartesian **formulations**.

Used as a mix-in class for all **network model element** classes with an AC network model formulation with a **cartesian** repesentation for voltages. That is, each concrete network model element class with an AC cartesian formulation must inherit, at least indirectly, from both `mp.nm_element` (page 107) and `mp.form_acc` (page 82).

Provides implementation of evaluation of voltage-related Jacobian and Hessian terms needed by some `mp.form_ac` (page 73) methods.

mp.form_dc Methods:

- `form_name()` (page 83) - get char array w/name of formulation (`'AC-cartesian'`)
- `form_tag()` (page 83) - get char array w/short label of formulation (`'acc'`)
- `model_vvars()` (page 83) - get cell array of names of voltage state variables (`{'vr', 'vi'}`)
- `port_inj_current_jac()` (page 83) - compute voltage-related terms of current injection Jacobian
- `port_inj_current_hess_v()` (page 83) - compute voltage-related terms of current injection Hessian
- `port_inj_current_hess_vz()` (page 83) - compute voltage/non-voltage-related terms of current injection Hessian

- *port_inj_power_jac()* (page 84) - compute voltage-related terms of power injection Jacobian
- *port_inj_power_hess_v()* (page 84) - compute voltage-related terms of power injection Hessian
- *port_inj_power_hess_vz()* (page 84) - compute voltage/non-voltage-related terms of power injection Hessian
- *aux_data_va_vm()* (page 84) - return voltage angles/magnitudes from auxiliary data
- *va_fcn()* (page 84) - compute voltage angle constraints and Jacobian
- *va_hess()* (page 85) - compute voltage angle Hessian
- *vm2_fcn()* (page 85) - compute squared voltage magnitude constraints and Jacobian
- *vm2_hess()* (page 85) - compute squared voltage magnitude Hessian

For more details, see the sec_nm_formulations_ac section in the *MATPOWER Developer's Manual* and the derivations in *MATPOWER Technical Note 5*.

See also `mp.form` (page 71), `mp.form_ac` (page 73), `mp.form_acp` (page 86), `mp.nm_element` (page 107).

Method Summary

form_name()

Get user-readable name of formulation, i.e. `'AC-cartesian'`.

See *mp.form.form_name()* (page 72).

form_tag()

Get short label of formulation, i.e. `'acc'`.

See *mp.form.form_tag()* (page 72).

model_vvars()

Get cell array of names of voltage state variables, i.e. `{'vr', 'vi'}`.

See *mp.form.model_vvars()* (page 72).

port_inj_current_jac(*n*, *v_*, *Y*, *M*, *invdiagvic*, *diagSlincJ*)

Compute voltage-related terms of current injection Jacobian.

```
[Iu, Iw] = nme.port_inj_current_jac(n, v_, Y, M, invdiagvic, diagSlincJ)
```

Called by *mp.form_ac.port_inj_current()* (page 76) to compute voltage-related Jacobian terms.

port_inj_current_hess_v(*x_*, *lam*, *v_*, *z_*, *diaginvic*, *Y*, *M*, *diagSlincJ*, *dlamJ*)

Compute voltage-related terms of current injection Hessian.

```
[Iuu, Iuw, Iww] = nme.port_inj_current_hess_v(x_, lam)
[Iuu, Iuw, Iww] = nme.port_inj_current_hess_v(x_, lam, sysx)
[Iuu, Iuw, Iww] = nme.port_inj_current_hess_v(x_, lam, sysx, idx)
[...] = nme.port_inj_current_hess_vz(x_, lam, v_, z_, diaginvic, Y, M,
↪diagSlincJ, dlamJ)
```

Called by *mp.form_ac.port_inj_current_hess()* (page 77) to compute voltage-related Hessian terms.

port_inj_current_hess_vz(*x_*, *lam*, *v_*, *z_*, *diaginvic*, *N*, *dlamJ*)

Compute voltage/non-voltage-related terms of current injection Hessian.

```
[Iuzr, Iuzi, Iwzr, Iwzi] = nme.port_inj_current_hess_vz(x_, lam)
[...] = nme.port_inj_current_hess_vz(x_, lam, sysx)
[...] = nme.port_inj_current_hess_vz(x_, lam, sysx, idx)
[...] = nme.port_inj_current_hess_vz(x_, lam, v_, z_, diaginvic, N, dlamJ)
```

Called by `mp.form_ac.port_inj_current_hess()` (page 77) to compute voltage/non-voltage-related Hessian terms.

port_inj_power_jac(*n*, *v_*, *Y*, *M*, *diagv*, *diagvi*, *diagIlincJ*)

Compute voltage-related terms of power injection Jacobian.

```
[Su, Sw] = nme.port_inj_power_jac(...)
```

Called by `mp.form_ac.port_inj_power()` (page 76) to compute voltage-related Jacobian terms.

port_inj_power_hess_v(*x_*, *lam*, *v_*, *z_*, *diagvi*, *Y*, *M*, *diagIlincJ*, *dlamJ*)

Compute voltage-related terms of power injection Hessian.

```
[Suu, Suw, Sww] = nme.port_inj_power_hess_v(x_, lam)
[Suu, Suw, Sww] = nme.port_inj_power_hess_v(x_, lam, sysx)
[Suu, Suw, Sww] = nme.port_inj_power_hess_v(x_, lam, sysx, idx)
[...] = nme.port_inj_power_hess_v(x_, lam, v_, z_, diagvi, Y, M, diagIlincJ,
↪ dlamJ)
```

Called by `mp.form_ac.port_inj_power_hess()` (page 78) to compute voltage-related Hessian terms.

port_inj_power_hess_vz(*x_*, *lam*, *v_*, *z_*, *diagvi*, *L*, *dlamJ*)

Compute voltage/non-voltage-related terms of power injection Hessian.

```
[Suzr, Suzi, Swzr, Swzi] = nme.port_inj_power_hess_vz(x_, lam)
[...] = nme.port_inj_power_hess_vz(x_, lam, sysx)
[...] = nme.port_inj_power_hess_vz(x_, lam, sysx, idx)
[...] = nme.port_inj_power_hess_vz(x_, lam, v_, z_, diagvi, L, dlamJ)
```

Called by `mp.form_ac.port_inj_power_hess()` (page 78) to compute voltage/non-voltage-related Hessian terms.

aux_data_va_vm(*ad*)

Return voltage angles/magnitudes from auxiliary data.

```
[va, vm] = nme.aux_data_va_vm(ad)
```

Connverts from cartesian voltage data stored in `ad.vr` and `ad.vi`.

Input

ad (*struct*) – struct of auxiliary data

Outputs

- **va** (*double*) – vector of voltage angles corresponding to voltage information stored in auxiliary data
- **vm** (*double*) – vector of voltage magnitudes corresponding to voltage information stored in auxiliary data

va_fcn(*xx*, *idx*, *lim*)

Compute voltage angle constraints and Jacobian.

```
g = nme.va_fcn(xx, idx, lim)
[g, dg] = nme.va_fcn(xx, idx, lim)
```

Compute constraint function and optionally the Jacobian for voltage angle limits.

Inputs

- **xx** (*1 x 2 cell array*) – real part of complex voltage in `xx{1}`, imaginary part in `xx{2}`
- **idx** (*integer*) – index of subset of voltages of interest to include in constraint; if empty, include all
- **lim** (*double or cell array of double*) – constraint bound(s), can be a vector, for equality constraints or an upper bound, or a cell array with `{va_lb, va_ub}` for dual-bound constraints

Outputs

- **g** (*double*) – constraint function, $\boldsymbol{g}(\boldsymbol{x})$
- **dg** (*double*) – constraint Jacobian, $\boldsymbol{g_x}$

`va_hess`(*xx*, *lam*, *idx*)

Compute voltage angle Hessian.

```
d2G = nme.va_hess(xx, lam, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of voltages. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by muliplying the transpose of the constraint Jacobian by a vector $\boldsymbol{\lambda}$.

Inputs

- **xx** (*1 x 2 cell array*) – real part of complex voltage in `xx{1}`, imaginary part in `xx{2}`
- **lam** (*double*) – vector $\boldsymbol{\lambda}$ of multipliers, one for each constraint
- **idx** (*integer*) – index of subset of voltages of interest to include in constraint; if empty, include all

Outputs

d2G (*double*) – sparse constraint Hessian, $\boldsymbol{g_{xx}}(\boldsymbol{\lambda})$

`vm2_fcn`(*xx*, *idx*, *lim*)

Compute squared voltage magnitude constraints and Jacobian.

```
g = nme.vm2_fcn(xx, idx, lim)
[g, dg] = nme.vm2_fcn(xx, idx, lim)
```

Compute constraint function and optionally the Jacobian for squared voltage magnitude limits.

Inputs

- **xx** (*1 x 2 cell array*) – real part of complex voltage in `xx{1}`, imaginary part in `xx{2}`
- **idx** (*integer*) – index of subset of voltages of interest to include in constraint; if empty, include all
- **lim** (*double or cell array of double*) – constraint bound(s), can be a vector, for equality constraints or an upper bound, or a cell array with `{vm2_lb, vm2_ub}` for dual-bound constraints

Outputs

- **g** (*double*) – constraint function, $\boldsymbol{g}(\boldsymbol{x})$
- **dg** (*double*) – constraint Jacobian, $\boldsymbol{g_x}$

`vm2_hess`(*xx*, *lam*, *idx*)

Compute squared voltage magnitude Hessian.

```
d2G = nme.vm2_hess(xx, lam, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of voltages. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by muliplying the transpose of the constraint Jacobian by a vector $\boldsymbol{\lambda}$.

Inputs

- **xx** (*1 x 2 cell array*) – real part of complex voltage in `xx{1}`, imaginary part in `xx{2}`
- **lam** (*double*) – vector $\boldsymbol{\lambda}$ of multipliers, one for each constraint
- **idx** (*integer*) – index of subset of voltages of interest to include in constraint; if empty, include all

Outputs

d2G (*double*) – sparse constraint Hessian, $\boldsymbol{g_{xx}}(\boldsymbol{\lambda})$

mp.form_acp

class mp.form_acp

Bases: *mp.form_ac* (page 73)

mp.form_acp (page 86) - Base class for MATPOWER AC polar **formulations**.

Used as a mix-in class for all **network model element** classes with an AC network model formulation with a **polar** repesentation for voltages. That is, each concrete network model element class with an AC polar formulation must inherit, at least indirectly, from both *mp.nm_element* (page 107) and *mp.form_acp* (page 86).

Provides implementation of evaluation of voltage-related Jacobian and Hessian terms needed by some *mp.form_ac* (page 73) methods.

mp.form_dc Methods:

- *form_name()* (page 86) - get char array w/name of formulation (`'AC-polar'`)
- *form_tag()* (page 87) - get char array w/short label of formulation (`'acp'`)
- *model_vvars()* (page 87) - get cell array of names of voltage state variables (`{'va', 'vm'}`)
- *port_inj_current_jac()* (page 87) - compute voltage-related terms of current injection Jacobian
- *port_inj_current_hess_v()* (page 87) - compute voltage-related terms of current injection Hessian
- *port_inj_current_hess_vz()* (page 87) - compute voltage/non-voltage-related terms of current injection Hessian
- *port_inj_power_jac()* (page 87) - compute voltage-related terms of power injection Jacobian
- *port_inj_power_hess_v()* (page 87) - compute voltage-related terms of power injection Hessian
- *port_inj_power_hess_vz()* (page 88) - compute voltage/non-voltage-related terms of power injection Hessian
- *aux_data_va_vm()* (page 88) - return voltage angles/magnitudes from auxiliary data

For more details, see the sec_nm_formulations_ac section in the *MATPOWER Developer's Manual* and the derivations in *MATPOWER Technical Note 5*.

See also *mp.form* (page 71), *mp.form_ac* (page 73), *mp.form_acc* (page 82), *mp.nm_element* (page 107).

Method Summary

form_name()

Get user-readable name of formulation, i.e. 'AC-polar'.

See *mp.form.form_name()* (page 72).

form_tag()

Get short label of formulation, i.e. 'acp'.

See *mp.form.form_tag()* (page 72).

model_vvars()

Get cell array of names of voltage state variables, i.e. {'va', 'vm'}.

See *mp.form.model_vvars()* (page 72).

port_inj_current_jac(*n*, *v_*, *Y*, *M*, *invdiagvic*, *diagSlincJ*)

Compute voltage-related terms of current injection Jacobian.

```
[Iva, Ivm] = nme.port_inj_current_jac(n, v_, Y, M, invdiagvic, diagSlincJ)
```

Called by *mp.form_ac.port_inj_current()* (page 76) to compute voltage-related Jacobian terms.

port_inj_current_hess_v(*x_*, *lam*, *v_*, *z_*, *diaginvic*, *Y*, *M*, *diagSlincJ*, *dlamJ*)

Compute voltage-related terms of current injection Hessian.

```
[Ivava, Ivavm, Ivmvm] = nme.port_inj_current_hess_v(x_, lam)
[Ivava, Ivavm, Ivmvm] = nme.port_inj_current_hess_v(x_, lam, sysx)
[Ivava, Ivavm, Ivmvm] = nme.port_inj_current_hess_v(x_, lam, sysx, idx)
[...] = nme.port_inj_current_hess_vz(x_, lam, v_, z_, diaginvic, Y, M,
↪diagSlincJ, dlamJ)
```

Called by *mp.form_ac.port_inj_current_hess()* (page 77) to compute voltage-related Hessian terms.

port_inj_current_hess_vz(*x_*, *lam*, *v_*, *z_*, *diaginvic*, *N*, *dlamJ*)

Compute voltage/non-voltage-related terms of current injection Hessian.

```
[Ivazr, Ivazi, Ivmzr, Ivmzi] = nme.port_inj_current_hess_vz(x_, lam)
[...] = nme.port_inj_current_hess_vz(x_, lam, sysx)
[...] = nme.port_inj_current_hess_vz(x_, lam, sysx, idx)
[...] = nme.port_inj_current_hess_vz(x_, lam, v_, z_, diaginvic, N, dlamJ)
```

Called by *mp.form_ac.port_inj_current_hess()* (page 77) to compute voltage/non-voltage-related Hessian terms.

port_inj_power_jac(*n*, *v_*, *Y*, *M*, *diagv*, *diagvi*, *diagIlincJ*)

Compute voltage-related terms of power injection Jacobian.

```
[Sva, Svm] = nme.port_inj_power_jac(...)
```

Called by *mp.form_ac.port_inj_power()* (page 76) to compute voltage-related Jacobian terms.

port_inj_power_hess_v(*x_*, *lam*, *v_*, *z_*, *diagvi*, *Y*, *M*, *diagIlincJ*, *dlamJ*)

Compute voltage-related terms of power injection Hessian.

```
[Svava, Svavm, Svmvm] = nme.port_inj_power_hess_v(x_, lam)
[Svava, Svavm, Svmvm] = nme.port_inj_power_hess_v(x_, lam, sysx)
[Svava, Svavm, Svmvm] = nme.port_inj_power_hess_v(x_, lam, sysx, idx)
[...] = nme.port_inj_power_hess_v(x_, lam, v_, z_, diagvi, Y, M, diagIlincJ,
↪ dlamJ)
```

Called by *mp.form_ac.port_inj_power_hess()* (page 78) to compute voltage-related Hessian terms.

port_inj_power_hess_vz(*x_*, *lam*, *v_*, *z_*, *diagvi*, *L*, *dlamJ*)

Compute voltage/non-voltage-related terms of power injection Hessian.

```
[Svazr, Svazi, Svmzr, Svmzi] = nme.port_inj_power_hess_vz(x_, lam)
[...] = nme.port_inj_power_hess_vz(x_, lam, sysx)
[...] = nme.port_inj_power_hess_vz(x_, lam, sysx, idx)
[...] = nme.port_inj_power_hess_vz(x_, lam, v_, z_, diagvi, L, dlamJ)
```

Called by *mp.form_ac.port_inj_power_hess()* (page 78) to compute voltage/non-voltage-related Hessian terms.

aux_data_va_vm(*ad*)

Return voltage angles/magnitudes from auxiliary data.

```
[va, vm] = nme.aux_data_va_vm(ad)
```

Simply returns voltage data stored in `ad.va` and `ad.vm`.

Input

ad (*struct*) – struct of auxiliary data

Outputs

- **va** (*double*) – vector of voltage angles corresponding to voltage information stored in auxiliary data
- **vm** (*double*) – vector of voltage magnitudes corresponding to voltage information stored in auxiliary data

mp.form_dc

class mp.**form_dc**

Bases: *mp.form* (page 71)

mp.form_dc (page 88) - Base class for MATPOWER DC **formulations**.

Used as a mix-in class for all **network model element** classes with a DC network model formulation. That is, each concrete network model element class with a DC formulation must inherit, at least indirectly, from both *mp.nm_element* (page 107) and *mp.form_dc* (page 88).

mp.form_dc (page 88) defines the port active power injection as a linear function of the state variables $\boldsymbol{x}$, that is, the voltage angles $\boldsymbol{\theta}$ and non-voltage states $\boldsymbol{z}$, as

$$\begin{aligned} \boldsymbol{g}^P(\boldsymbol{x}) &= \left[\begin{array}{cc} \underline{\boldsymbol{B}} & \underline{\boldsymbol{K}} \end{array} \right] \boldsymbol{x} + \underline{\boldsymbol{p}} \\ &= \underline{\boldsymbol{B}}\boldsymbol{\theta} + \underline{\boldsymbol{K}}\boldsymbol{z} + \underline{\boldsymbol{p}}, \end{aligned} \tag{3.6}$$

where $\underline{\boldsymbol{B}}$, $\underline{\boldsymbol{K}}$, and $\underline{\boldsymbol{p}}$ are the model parameters.

For more details, see the sec_nm_formulations_dc section in the *MATPOWER Developer's Manual* and the derivations in *MATPOWER Technical Note 5*.

mp.form_dc Properties:

- *B* (page 89) - $n_p n_k \times n_n$ matrix $\underline{\boldsymbol{B}}$ of model parameters
- *K* (page 89) - $n_p n_k \times n_z$ matrix $\underline{\boldsymbol{K}}$ of model parameters
- *p* (page 89) - $n_p n_k \times 1$ vector $\underline{\boldsymbol{p}}$ of model parameters
- `params_ncols` - specify number of columns for each parameter

mp.form_dc Methods:

- `form_name()` (page 89) - get char array w/name of formulation (`'DC'`)
- `form_tag()` (page 89) - get char array w/short label of formulation (`'dc'`)
- `model_params()` (page 89) - get network model element parameters (`{'B', 'K', 'p'}`)
- `model_vvars()` (page 89) - get cell array of names of voltage state variables (`{'va'}`)
- `model_zvars()` (page 90) - get cell array of names of non-voltage state variables (`{'z'}`)
- `port_inj_power()` (page 90) - compute port power injections from network state

See also `mp.form` (page 71), `mp.form_ac` (page 73), `mp.nm_element` (page 107).

Property Summary

B = []

(double) $n_p n_k \times n_n$ matrix $\underline{\boldsymbol{B}}$ of model parameter coefficients for $\boldsymbol{\theta}$

K = []

(double) $n_p n_k \times n_z$ matrix $\underline{\boldsymbol{K}}$ of model parameter coefficients for $\boldsymbol{z}$

p = []

(double) $n_p n_k \times 1$ vector $\underline{\boldsymbol{p}}$ of model parameters

param_ncols = struct('B',2,'K',3,'p',1)

(struct) specify number of columns for each parameter, where

- 1 => single column (i.e. a vector)
- 2 => n_p columns
- 3 => n_z columns

Method Summary

form_name()

Get user-readable name of formulation, i.e. `'DC'`.

See `mp.form.form_name()` (page 72).

form_tag()

Get short label of formulation, i.e. `'dc'`.

See `mp.form.form_tag()` (page 72).

model_params()

Get cell array of names of model parameters, i.e. `{'B', 'K', 'p'}`.

See `mp.form.model_params()` (page 72).

model_vvars()

Get cell array of names of voltage state variables, i.e. {'va'}.

See *mp.form.model_vvars()* (page 72).

model_zvars()

Get cell array of names of non-voltage state variables, i.e. {'z'}.

See *mp.form.model_zvars()* (page 72).

port_inj_power(*x*, *sysx*, *idx*)

Compute port power injections from network state.

```
P = nme.port_inj_power(x, sysx, idx)
```

Compute the active power injections for all or a selected subset of ports.

The state can be provided as a stacked aggregate of the state variables (port voltages and non-voltage states) for the full collection of network model elements of this type, or as the combined state for the entire network.

Inputs

- **x** (*double*) – state vector $\boldsymbol{x}$
- **sysx** (*0 or 1*) – which state is provided in x
  - 0 – class aggregate state
  - 1 – *(default)* full system state
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns injections corresponding to all ports

Outputs

P (*double*) – vector of port power injections, $\boldsymbol{g}^P(\boldsymbol{x})$

mp.net_model

class mp.**net_model**

Bases: *mp.nm_element* (page 107), *mp.element_container* (page 165), mp_idx_manager

mp.net_model (page 90) - Abstract base class for MATPOWER **network model** objects.

The network model defines the states of and connections between network elements, as well as the parameters and functions defining the relationships between states and port injections. A given network model implements a specific network model **formulation**, and defines sets of **nodes**, **ports**, and **states**.

A network model object is primarily a container for network model element (*mp.nm_element* (page 107)) objects and *is itself* a network model element. All network model classes inherit from *mp.net_model* (page 90) and therefore also from *mp.element_container* (page 165), mp_idx_manager, and *mp.nm_element* (page 107). Concrete network model classes are also formulation-specific, inheriting from a corresponding subclass of *mp.form* (page 71).

By convention, network model variables are named nm and network model class class names begin with mp.net_model.

mp.net_model Properties:

- *the_np* (page 92) - total number of ports
- *the_nz* (page 92) - total number of non-voltage states
- *nv* (page 92) - total number of (real) voltage variables

- *node* (page 92) - mp_idx_manager data for nodes
- *port* (page 92) - mp_idx_manager data for ports
- *state* (page 92) - mp_idx_manager data for non-voltage states

mp.net_model Methods:

- *name()* (page 92) - return name of this network element type (`'network'`)
- *np()* (page 92) - return number of ports for this network element
- *nz()* (page 92) - return number of *(possibly complex)* non-voltage states for this network element
- *build()* (page 92) - create, add, and build network model element objects
- *add_nodes()* (page 92) - elements add nodes, then add corresponding voltage variables
- *add_states()* (page 93) - elements add states, then add corresponding state variables
- *build_params()* (page 93) - build incidence matrices, parameters, add ports for each element
- *stack_matrix_params()* (page 93) - form network matrix parameter by stacking corresponding element parameters
- *stack_vector_params()* (page 93) - form network vector parameter by stacking corresponding element parameters
- *add_vvars()* (page 94) - add voltage variable(s) for each network node
- *add_zvars()* (page 94) - add non-voltage state variable(s) for each network state
- *def_set_types()* (page 94) - define node, state, and port set types for mp_idx_manager
- *init_set_types()* (page 94) - initialize structures for tracking/indexing nodes, states, ports
- *display()* (page 94) - display the network model object
- *add_node()* (page 95) - add named set of nodes
- *add_port()* (page 95) - add named set of ports
- *add_state()* (page 95) - add named set of states
- *set_type_idx_map()* (page 95) - map node/port/state index back to named set & index within set
- *set_type_label()* (page 96) - create a user-readable label to identify a node, port, or state
- *add_var()* (page 96) - add a set of variables to the model
- *params_var()* (page 97) - return initial value, bounds, and variable type for variables
- *get_node_idx()* (page 98) - get index information for named node set
- *get_port_idx()* (page 98) - get index information for named port set
- *get_state_idx()* (page 98) - get index information for named state set
- *node_types()* (page 98) - get node type information
- *ensure_ref_node()* (page 99) -
- *set_node_type_ref()* (page 99) - make the specified node a reference node
- *set_node_type_pv()* (page 100) - make the specified node a PV node
- *set_node_type_pq()* (page 100) - make the specified node a PQ node

See the sec_net_model section in the *MATPOWER Developer's Manual* for more information.

See also `mp.form` (page 71), `mp.nm_element` (page 107), `mp.task` (page 7), `mp.data_model` (page 27), `mp.math_model` (page 121).

Property Summary

the_np = 0

(integer) total number of ports

the_nz = 0

(integer) total number of non-voltage states

nv = 0

(integer) total number of (real) voltage variables

node = []

(struct) mp_idx_manager data for nodes

port = []

(struct) mp_idx_manager data for ports

state = []

(struct) mp_idx_manager data for non-voltage states

Method Summary

name()

Return the name of this network element type (`'network'`).

```
name = nm.name()
```

np()

Return the number of ports for this network element.

```
np = nm.np()
```

nz()

Return the number of *(possibly complex)* non-voltage states for this network element.

```
nz = nm.nz()
```

build(*dm*)

Create, add, and `build()` (page 92) network model element objects.

```
nm.build(dm)
```

Input

dm (`mp.data_model` (page 27)) – data model object

Create and add network model element objects, add nodes and states, and build the parameters for all elements.

See also `add_nodes()` (page 92), `add_states()` (page 93), `build_params()` (page 93).

add_nodes(*nm*, *dm*)

Elements add nodes, then add corresponding voltage variables.

```
nm.add_nodes(nm, dm)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object

Each element can add its nodes, then the network model itself can add additional nodes, and finally corresponding voltage variables are added for each node.

See also *add_vvars()* (page 94), *add_states()* (page 93).

add_states(*nm*, *dm*)

Elements add states, then add corresponding state variables.

```
nm.add_states(nm, dm)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object

Each element can add its states, then corresponding non-voltage state variables are added for each state.

See also *add_zvars()* (page 94), *add_nodes()* (page 92).

build_params(*nm*, *dm*)

Build incidence matrices and parameters, and add ports for each element.

```
nm.build_params(nm, dm)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object

For each element, build connection and state variable incidence matrices and element parameters, and add ports. Then construct the full network connection and state variable incidence matrices.

stack_matrix_params(*name*, *vnotz*)

Form network matrix parameter by stacking corresponding element parameters.

```
M = nm.stack_matrix_params(name, vnotz)
```

Inputs
- **name** (*char array*) – name of the parameter of interest
- **vnotz** (*boolean*) – true if columns of parameter correspond to voltage variables, false otherwise

Output
M (*double*) – matrix parameter of interest for the full network

A given matrix parameter (e.g. `Y`) for the full network is formed by stacking the corresponding matrix parameters for each element along the matrix block diagonal.

stack_vector_params(*name*)

Form network vector parameter by stacking corresponding element parameters.

```
v = nm.stack_vector_params(name)
```

Input

name (*char array*) – name of the parameter of interest

Output

v (*double*) – vector parameter of interest for the full network

A given vector parameter (e.g. `s`) for the full network is formed by vertically stacking the corresponding vector parameters for each element.

add_vvars(*nm*, *dm*, *idx*)

Add voltage variable(s) for each network node.

```
nm.add_vvars(nm, dm)
nm.add_vvars(nm, dm, idx)
```

Inputs

- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **idx** (*integer*) – index for name and indexed variables *(currently unused here)*

Also updates the `nv` property.

See also *add_zvars()* (page 94), *add_nodes()* (page 92).

add_zvars(*nm*, *dm*, *idx*)

Add non-voltage state variable(s) for each network state.

```
nm.add_zvars(nm, dm)
nm.add_zvars(nm, dm, idx)
```

Inputs

- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **idx** (*cell array*) – indices for named and indexed variables *(currently unused here)*

See also *add_vvars()* (page 94), *add_states()* (page 93).

def_set_types()

Define node, state, and port set types for mp_idx_manager.

```
nm.def_set_types()
```

Define the following set types:

- `'node'` - NODES
- `'state'` - STATES
- `'port'` - PORTS

See also `mp_idx_manager`.

init_set_types()

Initialize structures for tracking/indexing nodes, states, ports.

```
nm.init_set_types()
```

See also `mp_idx_manager`.

display()

Display the network model object.

This method is called automatically when omitting a semicolon on a line that retuns an object of this class.

Displays the details of the nodes, ports, states, voltage variables, non-voltage state variables, and network model elements.

See also `mp_idx_manager`.

add_node(*name*, *idx*, *N*)

Add named set of nodes.

```
nm.add_node(name, N)
nm.add_node(name, idx, N)
```

Inputs

- **name** (*char array*) – name for set of nodes
- **idx** (*cell array*) – indices for named, indexed set of nodes
- **N** (*integer*) – number of nodes in set

See also `mp_idx_manager.add_named_set`.

add_port(*name*, *idx*, *N*)

Add named set of ports.

```
nm.add_port(name, N)
nm.add_port(name, idx, N)
```

Inputs

- **name** (*char array*) – name for set of ports
- **idx** (*cell array*) – indices for named, indexed set of ports
- **N** (*integer*) – number of ports in set

See also `mp_idx_manager.add_named_set`.

add_state(*name*, *idx*, *N*)

Add named set of states.

```
nm.add_state(name, N)
nm.add_state(name, idx, N)
```

Inputs

- **name** (*char array*) – name for set of states
- **idx** (*cell array*) – indices for named, indexed set of states
- **N** (*integer*) – number of states in set

See also `mp_idx_manager.add_named_set`.

set_type_idx_map(*set_type*, *idxs*, *dm*, *group_by_name*)

Map node/port/state index back to named set & index within set.

```
s = obj.set_type_idx_map(set_type)
s = obj.set_type_idx_map(set_type, idxs)
s = obj.set_type_idx_map(set_type, idxs, dm)
s = obj.set_type_idx_map(set_type, idxs, dm, group_by_name)
```

Inputs

- **set_type** (*char array*) – `'node'`, `'port'`, or `'state'`
- **idxs** (*integer*) – vector of indices, defaults to `[1:ns]'`, where `ns` is the full dimension of the set corresponding to the all elements for the specified set type (i.e. node, port, or state)
- **dm** (`mp.data_model` (page 27)) – data model object

- **group_by_name** (*boolean*) – if true, results are consolidated, with a single entry in `s` for each unique name/idx pair, where the `i` and `j` fields are vectors

Output

s (*struct*) – index map of same dimensions as `idxs`, unless `group_by_name` is true, in which case it is 1 dimensional

Returns a struct of same dimensions as `idxs` specifying, for each index, the corresponding named set and element within the named set for the specified `set_type`. The return struct has the following fields:

- `name` : name of corresponding set
- `idx` : cell array of indices for the name, if named set is indexed
- `i` : index of element within the set
- `e` : external index (i.e. corresponding row in data model)
- `ID` : external ID (i.e. corresponding element ID in data model)
- `j` : (only if `group_by_name` == 1), corresponding index of set type, equal to a particular element of `idxs`

Examples:

```
s = nm.set_type_idx_map('node', 87, dm));
s = nm.set_type_idx_map('port', [38; 49; 93], dm));
s = nm.set_type_idx_map('state'));
s = nm.set_type_idx_map('node', [], dm, 1));
```

set_type_label(*set_type*, *idxs*, *dm*)

Create a user-readable label to identify a node, port, or state.

```
label = nm.set_type_label(set_type, idxs)
label = nm.set_type_label(set_type, idxs, dm)
```

Inputs

- **set_type** (*char array*) – `'node'`, `'port'`, or `'state'`
- **idxs** (*integer*) – vector of indices
- **dm** (*mp.data_model* (page 27)) – data model object

Output

label (*cell array*) – same dimensions as `idxs`, where each entry is a char array

Example:

```
labels = nm.set_type_label('port', [1;6;15;20], dm)

labels =

  4×1 cell array

    {'gen 1'      }
    {'load 3'     }
    {'branch(1) 9'}
    {'branch(2) 5'}
```

add_var(*vtype*, *name*, *idx*, *varargin*)

Add a set of variables to the model.

```
nm.add_var(vtype, name, N, v0, vl, vu, vt)
nm.add_var(vtype, name, N, v0, vl, vu)
nm.add_var(vtype, name, N, v0, vl)
```

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```
nm.add_var(vtype, name, N, v0)
nm.add_var(vtype, name, N)
nm.add_var(vtype, name, idx_list, N, v0, vl, vu, vt)
nm.add_var(vtype, name, idx_list, N, v0, vl, vu)
nm.add_var(vtype, name, idx_list, N, v0, vl)
nm.add_var(vtype, name, idx_list, N, v0)
nm.add_var(vtype, name, idx_list, N)
```

Inputs

- **vtype** (*char array*) – variable type, must be a valid struct field name
- **name** (*char array*) – name of variable set
- **idx_list** (*cell array*) – optional index list
- **N** (*integer*) – number of variables in the set
- **v0** (*double*) – N x 1 col vector, initial value of variables, default is `0`
- **vl** (*double*) – N x 1 col vector, lower bounds, default is `-Inf`
- **vu** (*double*) – N x 1 col vector, upper bounds, default is `Inf`
- **vt** (*char*) – scalar or 1 x N row vector, variable type, default is `'C'`, valid element values are:
  - `'C'` - continuous
  - `'I'` - integer
  - `'B'` - binary

Essentially identical to the `add_var()` method from opt_model of MP-Opt-Model, with the addition of a variable type (`vtype`).

See also `opt_model.add_var`.

params_var(*vtype*, *name*, *idx*)

Return initial value, bounds, and variable type for variables.

```
[v0, vl, vu] = nm.params_var(vtype)
[v0, vl, vu] = nm.params_var(vtype, name)
[v0, vl, vu] = nm.params_var(vtype, name, idx_list)
[v0, vl, vu, vt] = nm.params_var(...)
```

Inputs

- **vtype** (*char array*) – variable type, must be a valid struct field name
- **name** (*char array*) – name of variable set
- **idx_list** (*cell array*) – optional index list

Outputs

- **v0** (*double*) – N x 1 col vector, initial value of variables
- **vl** (*double*) – N x 1 col vector, lower bounds
- **vu** (*double*) – N x 1 col vector, upper bounds
- **vt** (*char*) – scalar or 1 x N row vector, variable type, valid element values are:
  - `'C'` - continuous
  - `'I'` - integer
  - `'B'` - binary

Essentially identical to the `params_var()` method from opt_model of MP-Opt-Model, with the addition of a variable type (`vtype`).

Returns the initial value `v0`, lower bound `vl` and upper bound `vu` for the full variable vector, or for a specific named or named and indexed variable set. Optionally also returns a corresponding char vector `vt` of variable types, where `'C'`, `'I'` and `'B'` represent continuous, integer, and binary variables, respectively.

Examples:

```
[vr0, vrmin, vrmax] = obj.params_var('vr');
[pg0, pg_lb, pg_ub] = obj.params_var('zr', 'pg');
[zij0, zij_lb, zij_ub, ztype] = obj.params_var('zi', 'z', {i, j});
```

See also `opt_model.params_var`.

get_node_idx(*name*)

Get index information for named node set.

```
[i1 iN] = nm.get_node_idx(name)
nidx = nm.get_node_idx(name)
```

Input

name (*char array*) – name of node set

Outputs

- **i1** (*integer*) – index of first node for `name`
- **iN** (*integer*) – index of last node for `name`
- **nidx** (*integer or cell array*) – indices of nodes for `name`, equal to either `[i1:iN]'` or `{[i1(1):iN(1)]', ..., [i1(n):iN(n)]'}`

get_port_idx(*name*)

Get index information for named port set.

```
[i1 iN] = nm.get_port_idx(name)
pidx = nm.get_port_idx(name)
```

Input

name (*char array*) – name of port set

Outputs

- **i1** (*integer*) – index of first port for `name`
- **iN** (*integer*) – index of last port for `name`
- **pidx** (*integer or cell array*) – indices of ports for `name`, equal to either `[i1:iN]'` or `{[i1(1):iN(1)]', ..., [i1(n):iN(n)]'}`

get_state_idx(*name*)

Get index information for named state set.

```
[i1 iN] = nm.get_state_idx(name)
sidx = nm.get_state_idx(name)
```

Input

name (*char array*) – name of state set

Outputs

- **i1** (*integer*) – index of first state for `name`
- **iN** (*integer*) – index of last state for `name`
- **sidx** (*integer or cell array*) – indices of states for `name`, equal to either `[i1:iN]'` or `{[i1(1):iN(1)]', ..., [i1(n):iN(n)]'}`

node_types(*nm*, *dm*, *idx*, *skip_ensure_ref*)

Get node type information.

```
ntv           = nm.node_types(nm, dm)
[ntv, by_elm] = nm.node_types(nm, dm)
```

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```
[ref, pv, pq]         = nm.node_types(nm, dm)
[ref, pv, pq, by_elm] = nm.node_types(nm, dm)
... = nm.node_types(nm, dm, idx)
... = nm.node_types(nm, dm, idx, skip_ensure_ref)
```

Inputs

- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **idx** (*integer*) – index *(not used in base method)*
- **skip_ensure_ref** (*boolean*) – unless true, if there is no reference node, the first PV node will be converted to a new reference

Outputs

- **ntv** (*integer*) – node type vector, valid element values are:
  - `mp.NODE_TYPE.REF` (page 169)
  - `mp.NODE_TYPE.PV` (page 169)
  - `mp.NODE_TYPE.PQ` (page 169)
- **ref** (*integer*) – vector of indices of reference nodes
- **pv** (*integer*) – vector of indices of PV nodes
- **pq** (*integer*) – vector of indices of PQ nodes
- **by_elm** (*struct*) – `by_elm(k)` is struct for k-th node-creating element type, with fields:
  - `'name'` - name of corresponding node-creating element type
  - `'ntv'` - node type vector (if `by_elm` is 2nd output arg)
  - `'ref'/'pv'/'pq'` - index vectors into elements of corresponding node-creating element type (if `by_elm` is 4th output arg)

See also `mp.NODE_TYPE` (page 169), `ensure_ref_node()` (page 99).

ensure_ref_node(*dm*, *ref*, *pv*, *pq*)

Ensure there is at least one reference node.

```
[ref, pv, pq] = nm.ensure_ref_node(dm, ref, pv, pq)
ntv = nm.ensure_ref_node(dm, ntv)
```

Inputs

- **dm** (`mp.data_model` (page 27)) – data model object
- **ref** (*integer*) – vector of indices of reference nodes
- **pv** (*integer*) – vector of indices of PV nodes
- **pq** (*integer*) – vector of indices of PQ nodes
- **ntv** (*integer*) – node type vector, valid element values are:
  - `mp.NODE_TYPE.REF` (page 169)
  - `mp.NODE_TYPE.PV` (page 169)
  - `mp.NODE_TYPE.PQ` (page 169)

Outputs

- **ref** (*integer*) – updated vector of indices of reference nodes
- **pv** (*integer*) – updated vector of indices of PV nodes
- **pq** (*integer*) – updated vector of indices of PQ nodes
- **ntv** (*integer*) – updated node type vector

set_node_type_ref(*dm*, *idx*)

Make the specified node a reference node.

```
nm.set_node_type_ref(dm, idx)
```

Inputs

- **dm** (*mp.data_model* (page 27)) – data model object
- **idx** (*integer*) – index of node to modify, this is the internal network model element index

Set the specified node to type *mp.NODE_TYPE.REF* (page 169).

set_node_type_pv(*dm*, *idx*)

Make the specified node a PV node.

```
nm.set_node_type_pv(dm, idx)
```

Inputs

- **dm** (*mp.data_model* (page 27)) – data model object
- **idx** (*integer*) – index of node to modify, this is the internal network model element index

Set the specified node to type *mp.NODE_TYPE.PV* (page 169).

set_node_type_pq(*dm*, *idx*)

Make the specified node a PQ node.

```
nm.set_node_type_pq(dm, idx)
```

Inputs

- **dm** (*mp.data_model* (page 27)) – data model object
- **idx** (*integer*) – index of node to modify, this is the internal network model element index

Set the specified node to type *mp.NODE_TYPE.PQ* (page 169).

mp.net_model_ac

class mp.net_model_ac

Bases: *mp.net_model* (page 90)

mp.net_model_ac (page 100) - Abstract base class for MATPOWER AC **network model** objects.

Explicitly a subclass of *mp.net_model* (page 90) and implicitly assumed to be a subclass of *mp.form_ac* (page 73) as well.

mp.net_model_ac Properties:

- zr - vector of real part of complex non-voltage states, z_r
- zi - vector of imaginary part of complex non-voltage states, z_i

mp.net_model_ac Methods:

- *def_set_types()* (page 101) - add non-voltage state variable set types for mp_idx_manager
- *build_params()* (page 101) - build incidence matrices, parameters, add ports for each element
- *port_inj_nln()* (page 101) - compute general nonlinear port injection functions and Jacobians
- *port_inj_nln_hess()* (page 102) - compute general nonlinear port injection Hessian
- *nodal_complex_current_balance()* (page 102) - compute nodal complex current balance constraints
- *nodal_complex_power_balance()* (page 102) - compute nodal complex power balance constraints
- *nodal_complex_current_balance_hess()* (page 103) - compute nodal complex current balance Hessian

- `nodal_complex_power_balance_hess()` (page 103) - compute nodal complex power balance Hessian
- `port_inj_soln()` (page 103) - compute the network port power injections at the solution
- `get_va()` (page 103) - get node voltage angle vector

See also `mp.net_model` (page 90), `mp.form` (page 71), `mp.form_ac` (page 73), `mp.nm_element` (page 107).

Method Summary

def_set_types()

Add non-voltage state variable set types for mp_idx_manager.

```
nm.def_set_types()
```

Add the following set types:
- `'zr'` - NON-VOLTAGE VARS REAL (zr)
- `'zi'` - NON-VOLTAGE VARS IMAG (zi)

See also `mp.net_model.def_set_types()` (page 94), `mp_idx_manager`.

build_params(*nm*, *dm*)

Build incidence matrices and parameters, and add ports for each element.

```
nm.build_params(nm, dm)
```

Inputs
- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object

Call the parent method to do most of the work, then build the aggregate network model parameters and add the general nonlinear function terms, $\mathrm{s}^{nln}(\mathbf{x})$ or $\mathbf{i}^{nln}(\mathbf{x})$, for any elements that define them.

port_inj_nln(*si*, *x_*, *sysx*, *idx*)

Compute general nonlinear port injection functions and Jacobians

```
g = nm.port_inj_nln(si, x_, sysx, idx)
[g, gv1, gv2] = nm.port_inj_nln(si, x_, sysx, idx)
[g, gv1, gv2, gzr, gzi] = nm.port_inj_nln(si, x_, sysx, idx)
```

Compute and assemble the functions, and optionally Jacobians, for the general nonlinear injection functions $\mathrm{s}^{nln}(\mathbf{x})$ and $\mathbf{i}^{nln}(\mathbf{x})$ for the full aggregate network model, for all or a selected subset of ports.

Inputs
- **si** (`'S'` or `'I'`) – select power or current injection function:
  - `'S'` for complex power $\mathrm{s}^{nln}(\mathbf{x})$
  - `'I'` for complex current $\mathbf{i}^{nln}(\mathbf{x})$
- **x_** (*complex double*) – state vector $\mathbf{x}$
- **sysx** (*0 or 1*) – which state is provided in `x_`
  - 0 – class aggregate state
  - 1 – *(default)* full system state
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs
- **g** (*complex double*) – nonlinear injection function, $\mathrm{s}^{nln}(\mathbf{x})$ (or $\mathbf{i}^{nln}(\mathbf{x})$)
- **gv1** (*complex double*) – Jacobian w.r.t. 1st voltage variable, $\mathrm{s}^{nln}_{\boldsymbol{\theta}}$ or $\mathrm{s}^{nln}_{\boldsymbol{u}}$ (or $\mathbf{i}^{nln}_{\boldsymbol{\theta}}$ or $\mathbf{i}^{nln}_{\boldsymbol{u}}$)
- **gv2** (*complex double*) – Jacobian w.r.t. 2nd voltage variable, $\mathrm{s}^{nln}_{\boldsymbol{\nu}}$ or $\mathrm{s}^{nln}_{\boldsymbol{w}}$ (or $\mathbf{i}^{nln}_{\boldsymbol{\nu}}$ or $\mathbf{i}^{nln}_{\boldsymbol{w}}$)

- **gzr** (*complex double*) – Jacobian w.r.t. real non-voltage variable, $\mathbf{s}_{z_r}^{nln}$ (or $\mathbf{i}_{z_r}^{nln}$)
- **gzi** (*complex double*) – Jacobian w.r.t. imaginary non-voltage variable, $\mathbf{s}_{z_i}^{nln}$ (or $\mathbf{i}_{z_i}^{nln}$)

See also `port_inj_nln_hess()` (page 102).

port_inj_nln_hess(*si*, *x_*, *lam*, *sysx*, *idx*)

Compute general nonlinear port injection Hessian.

```
H = nm.port_inj_nln_hess(si, x_, lam)
H = nm.port_inj_nln_hess(si, x_, lam, sysx)
H = nm.port_inj_nln_hess(si, x_, lam, sysx, idx)
```

Compute and assemble the Hessian for the general nonlinear injection functions $\mathbf{s}^{nln}(\mathbf{x})$ and $\mathbf{i}^{nln}(\mathbf{x})$ for the full aggregate network model, for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by muliplying the transpose of the corresponding Jacobian by a vector $\boldsymbol{\lambda}$.

Inputs

- **si** (`'S'` or `'I'`) – select power or current injection function:
  - `'S'` for complex power $\mathbf{s}^{nln}(\mathbf{x})$
  - `'I'` for complex current $\mathbf{i}^{nln}(\mathbf{x})$
- **x_** (*complex double*) – state vector $\mathbf{x}$
- **lam** (*double*) – vector $\boldsymbol{\lambda}$ of multipliers, one for each port
- **sysx** (*0 or 1*) – which state is provided in `x_`
  - 0 – class aggregate state
  - 1 – *(default)* full system state
- **idx** (*integer*) – *(optional)* vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Output

H (*complex double*) – sparse Hessian matrix, $\mathbf{s}_{\boldsymbol{xx}}^{nln}(\boldsymbol{\lambda})$ or $\mathbf{i}_{\boldsymbol{xx}}^{nln}(\boldsymbol{\lambda})$

See also `port_inj_nln()` (page 101).

nodal_complex_current_balance(*x_*)

Compute nodal complex current balance constraints.

```
G = nm.nodal_complex_current_balance(x_)
[G, Gv1, Gv2, Gzr, Gzi] = nm.nodal_complex_current_balance(x_)
```

Compute constraint function and optionally the Jacobian for the complex current balance equality constraints based on outputs of `mp.form_ac.port_inj_current()` (page 76) and the node incidence matrix.

Input

x_ (*complex double*) – state vector $\mathbf{x}$ (full system state)

Outputs

- **G** (*complex double*) – nodal complex current balance constraint function, $\mathbf{g}^{\mathrm{kcl}}(\boldsymbol{x})$
- **Gv1** (*complex double*) – Jacobian w.r.t. 1st voltage variable, $\mathbf{g}_{\boldsymbol{\theta}}^{\mathrm{kcl}}$ or $\mathbf{g}_{\boldsymbol{u}}^{\mathrm{kcl}}$
- **Gv2** (*complex double*) – Jacobian w.r.t. 2nd voltage variable, $\mathbf{g}_{\boldsymbol{\nu}}^{\mathrm{kcl}}$ or $\mathbf{g}_{\boldsymbol{w}}^{\mathrm{kcl}}$
- **Gzr** (*complex double*) – Jacobian w.r.t. real non-voltage variable, $\mathbf{g}_{z_r}^{\mathrm{kcl}}$
- **Gzi** (*complex double*) – Jacobian w.r.t. imaginary non-voltage variable, $\mathbf{g}_{z_i}^{\mathrm{kcl}}$

See also `mp.form_ac.port_inj_current()` (page 76), `nodal_complex_current_balance_hess()` (page 103).

nodal_complex_power_balance(*x_*)

Compute nodal complex power balance constraints.

```
G = nm.nodal_complex_power_balance(x_)
[G, Gv1, Gv2, Gzr, Gzi] = nm.nodal_complex_power_balance(x_)
```

Compute constraint function and optionally the Jacobian for the complex power balance equality constraints based on outputs of `mp.form_ac.port_inj_power()` (page 76) and the node incidence matrix.

Input

x_ (*complex double*) – state vector $\mathbf{x}$ (full system state)

Outputs

- **G** (*complex double*) – nodal complex power balance constraint function, $\mathrm{g}^{\mathrm{kcl}}(\boldsymbol{x})$
- **Gv1** (*complex double*) – Jacobian w.r.t. 1st voltage variable, $\mathrm{g}_{\boldsymbol{\theta}}^{\mathrm{kcl}}$ or $\mathrm{g}_{\boldsymbol{u}}^{\mathrm{kcl}}$
- **Gv2** (*complex double*) – Jacobian w.r.t. 2nd voltage variable, $\mathrm{g}_{\boldsymbol{\nu}}^{\mathrm{kcl}}$ or $\mathrm{g}_{\boldsymbol{w}}^{\mathrm{kcl}}$
- **Gzr** (*complex double*) – Jacobian w.r.t. real non-voltage variable, $\mathrm{g}_{z_r}^{\mathrm{kcl}}$
- **Gzi** (*complex double*) – Jacobian w.r.t. imaginary non-voltage variable, $\mathrm{g}_{z_i}^{\mathrm{kcl}}$

See also `mp.form_ac.port_inj_power()` (page 76), `nodal_complex_power_balance_hess()` (page 103).

nodal_complex_current_balance_hess(*x_*, *lam*)

Compute nodal complex current balance Hessian.

```
d2G = nm.nodal_complex_current_balance_hess(x_, lam)
```

Compute the Hessian of the nodal complex current balance constraint. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by muliplying the transpose of the constraint Jacobian by a vector $\boldsymbol{\lambda}$. Based on `mp.form_ac.port_inj_current_hess()` (page 77).

Inputs

- **x_** (*complex double*) – state vector $\mathbf{x}$ (full system state)
- **lam** (*double*) – vector $\boldsymbol{\lambda}$ of multipliers, one for each node

Output

d2G (*complex double*) – sparse Hessian matrix, $\mathrm{g}_{\boldsymbol{xx}}^{\mathrm{kcl}}(\boldsymbol{\lambda})$

See also `mp.form_ac.port_inj_current_hess()` (page 77), `nodal_complex_current_balance()` (page 102).

nodal_complex_power_balance_hess(*x_*, *lam*)

Compute nodal complex power balance Hessian.

```
d2G = nm.nodal_complex_power_balance_hess(x_, lam)
```

Compute the Hessian of the nodal complex power balance constraint. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by muliplying the transpose of the constraint Jacobian by a vector $\boldsymbol{\lambda}$. Based on `mp.form_ac.port_inj_power_hess()` (page 78).

Inputs

- **x_** (*complex double*) – state vector $\mathbf{x}$ (full system state)
- **lam** (*double*) – vector $\boldsymbol{\lambda}$ of multipliers, one for each node

Output

d2G (*complex double*) – sparse Hessian matrix, $\mathrm{g}_{\boldsymbol{xx}}^{\mathrm{kcl}}(\boldsymbol{\lambda})$

See also `mp.form_ac.port_inj_power_hess()` (page 78), `nodal_complex_power_balance()` (page 102).

port_inj_soln()

Compute the network port power injections at the solution.

```
nm.port_inj_soln()
```

Takes the solved network state, computes the port power injections, and saves them in `nm.soln.gs_`.

get_va(*idx*)

Get node voltage angle vector.

```
va = nm.get_va()
va = nm.get_va(idx)
```

Get vector of node voltage angles for all or a selected subset of nodes. Values come from the solution if available, otherwise from the provided initial voltages.

Input

idx (*integer*) – index of subset of voltages of interest; if missing or empty, include all

Output

va (*double*) – vector of voltage angles

mp.net_model_acc

class mp.**net_model_acc**

Bases: *mp.net_model_ac* (page 100), *mp.form_acc* (page 82)

mp.net_model_acc (page 104) - Concrete class for MATPOWER AC cartesian **network model** objects.

This network model class and all of its network model element classes are specific to the AC cartesian formulation and therefore inherit from *mp.form_acc* (page 82).

mp.net_model_acc Properties:

- vr - vector of real part of complex voltage state variables, u
- vi - vector of imaginary part of complex voltage state variables, w

mp.net_model_acc Methods:

- *net_model_acc()* (page 104) - constructor, assign default network model element classes
- *def_set_types()* (page 104) - add voltage state variable set types for mp_idx_manager
- *initial_voltage_angle()* (page 105) - get vector of initial node voltage angles

See also *mp.net_model_ac* (page 100), *mp.net_model* (page 90), *mp.form_acc* (page 82), *mp.form_ac* (page 73), *mp.form* (page 71), *mp.nm_element* (page 107).

Constructor Summary

net_model_acc()

Constructor, assign default network model element classes.

```
nm = net_model_acc()
```

This network model class and all of its network model element classes are specific to the AC cartesian formulation and therefore inherit from *mp.form_acc* (page 82).

Method Summary

def_set_types()

Add voltage state variable set types for mp_idx_manager.

```
nm.def_set_types()
```

Add the following set types:

- 'vr' - REAL VOLTAGE VARS (vr)
- 'vi' - IMAG VOLTAGE VARS (vi)

See also *mp.net_model_ac.def_set_types()* (page 101), *mp.net_model.def_set_types()* (page 94), `mp_idx_manager`.

initial_voltage_angle(*idx*)

Get vector of initial node voltage angles.

```
va = nm.initial_voltage_angle()
va = nm.initial_voltage_angle(idx)
```

Get vector of initial node voltage angles for all or a selected subset of nodes.

Input

idx (*integer*) – index of subset of voltages of interest; if missing or empty, include all

Output

va (*double*) – vector of initial voltage angles

mp.net_model_acp

class mp.**net_model_acp**

Bases: *mp.net_model_ac* (page 100), *mp.form_acp* (page 86)

mp.net_model_acp (page 105) - Concrete class for MATPOWER AC polar **network model** objects.

This network model class and all of its network model element classes are specific to the AC polar formulation and therefore inherit from *mp.form_acp* (page 86).

mp.net_model_acp Properties:

- `va` - vector of angles of complex voltage state variables, θ
- `vm` - vector of magnitudes of complex voltage state variables, ν

mp.net_model_acp Methods:

- *net_model_acp()* (page 105) - constructor, assign default network model element classes
- *def_set_types()* (page 105) - add voltage state variable set types for mp_idx_manager
- *initial_voltage_angle()* (page 106) - get vector of initial node voltage angles

See also *mp.net_model_ac* (page 100), *mp.net_model* (page 90), *mp.form_acp* (page 86), *mp.form_ac* (page 73), *mp.form* (page 71), *mp.nm_element* (page 107).

Constructor Summary

net_model_acp()

Constructor, assign default network model element classes.

```
nm = net_model_acp()
```

This network model class and all of its network model element classes are specific to the AC polar formulation and therefore inherit from *mp.form_acp* (page 86).

Method Summary

def_set_types()

Add voltage state variable set types for mp_idx_manager.

```
nm.def_set_types()
```

Add the following set types:

- 'va' - VOLTAGE ANG VARS (va)
- 'vm' - VOLTAGE MAG VARS (vm)

See also *mp.net_model_ac.def_set_types()* (page 101), *mp.net_model.def_set_types()* (page 94), mp_idx_manager.

initial_voltage_angle(*idx*)

Get vector of initial node voltage angles.

```
va = nm.initial_voltage_angle()
va = nm.initial_voltage_angle(idx)
```

Get vector of initial node voltage angles for all or a selected subset of nodes.

Input

idx (*integer*) – index of subset of voltages of interest; if missing or empty, include all

Output

va (*double*) – vector of initial voltage angles

mp.net_model_dc

class mp.**net_model_dc**

Bases: *mp.net_model* (page 90), *mp.form_dc* (page 88)

mp.net_model_dc (page 106) - Concrete class for MATPOWER DC **network model** objects.

This network model class and all of its network model element classes are specific to the DC formulation and therefore inherit from *mp.form_dc* (page 88).

mp.net_model_dc Properties:

- *va* (page 107) - vector of voltage states (voltage angles $\boldsymbol{\theta}$)
- *z* (page 107) - vector of non-voltage states $\boldsymbol{z}$

mp.net_model_dc Methods:

- *net_model_dc()* (page 106) - constructor, assign default network model element classes
- *def_set_types()* (page 107) - add voltage and non-voltage variable set types for mp_idx_manager
- *build_params()* (page 107) - build incidence matrices, parameters, add ports for each element
- *port_inj_soln()* (page 107) - compute the network port injections at the solution

See also *mp.net_model* (page 90), *mp.form_dc* (page 88), *mp.form* (page 71), *mp.nm_element* (page 107).

Constructor Summary

net_model_dc()

Constructor, assign default network model element classes.

```
nm = net_model_dc()
```

This network model class and all of its network model element classes are specific to the DC formulation and therefore inherit from *mp.form_dc* (page 88).

Property Summary

va = []

(double) vector of voltage states (voltage angles $\boldsymbol{\theta}$)

z = []

(double) vector of non-voltage states $\boldsymbol{z}$

Method Summary

def_set_types()

Add voltage and non-voltage variable set types for mp_idx_manager.

```
nm.def_set_types()
```

Add the following set types:

- `'va'` - VOLTAGE VARS (va)
- `'z'` - NON-VOLTAGE VARS (z)

See also *mp.net_model.def_set_types()* (page 94), `mp_idx_manager`.

build_params(*nm*, *dm*)

Build incidence matrices and parameters, and add ports for each element.

```
nm.build_params(nm, dm)
```

Inputs

- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object

Call the parent method to do most of the work, then build the aggregate network model parameters.

port_inj_soln()

Compute the network port injections at the solution.

```
nm.port_inj_soln()
```

Takes the solved network state, computes the port power injections, and saves them in `nm.soln.gp`.

3.4.2 Elements

mp.nm_element

class mp.nm_element

Bases: `handle`

mp.nm_element (page 107) - Abstract base class for MATPOWER **network model element** objects.

A network model element object encapsulates all of the network model parameters for a particular element type. All network model element classes inherit from *mp.nm_element* (page 107) and also, like the container, from a formulation-specific subclass of *mp.form* (page 71). Each element type typically implements its own subclasses, which are further subclassed per formulation. A given network model element object contains the aggregate network model parameters for all online instances of that element type, stored in the set of matrices and vectors that correspond to the formulation.

By convention, network model element variables are named `nme` and network model element class names begin with `mp.nme`.

mp.mm_element Properties:

- *nk* (page 108) - number of elements of this type
- *C* (page 108) - stacked sparse element-node incidence matrices
- *D* (page 109) - stacked sparse incidence matrices for z-variables
- *soln* (page 109) - struct for storing solved states, quantities

mp.mm_element Methods:

- *name()* (page 109) - get name of element type, e.g. `'bus'`, `'gen'`
- *np()* (page 109) - number of ports per element of this type
- *nn()* (page 109) - number of nodes per element, created by this element type
- *nz()* (page 109) - number of non-voltage state variables per element of this type
- *data_model_element()* (page 109) - get the corresponding data model element
- *math_model_element()* (page 109) - get the corresponding math model element
- *count()* (page 110) - get number of online elements in `dm`, set `nk`
- *add_nodes()* (page 110) - add nodes to network model
- *add_states()* (page 110) - add non-voltage states to network model
- *add_vvars()* (page 110) - add real-valued voltage variables to network object
- *add_zvars()* (page 111) - add real-valued non-voltage state variables to network object
- *build_params()* (page 111) - build model parameters from data model
- *get_nv_()* (page 111) - get number of *(possibly complex)* voltage variables
- *x2vz()* (page 111) - get port voltages and non-voltage states from combined state vector
- *node_indices()* (page 112) - construct node indices from data model element connection info
- *incidence_matrix()* (page 112) - construct stacked incidence matrix from set of index vectors
- *node_types()* (page 113) - get node type information
- *set_node_type_ref()* (page 113) - make the specified node a reference node
- *set_node_type_pv()* (page 113) - make the specified node a PV node
- *set_node_type_pq()* (page 114) - make the specified node a PQ node
- *display()* (page 114) - display the network model element object

See the sec_nm_element section in the *MATPOWER Developer's Manual* for more information.

See also *mp.net_model* (page 90).

Property Summary

nk = 0

(integer) number of elements of this type

`C = []`

(sparse integer matrix) stacked element-node incidence matrices, where `C(i,kk)` is 1 if port j of element k is connected to node i, and `kk = k + (j-1)*np`

`D = []`

(sparse integer matrix) stacked incidence matrices for z-variables (non-voltage state variables), where `D(i,kk)` is 1 if z-variable j of element k is the i-th system z-variable and `kk = k + (j-1)*nz`

`soln`

(struct) for storing solved states, quantities

Method Summary

`name()`

Get name of element type, e.g. `'bus'`, `'gen'`.

```
name = nme.name()
```

Output
name (*char array*) – name of element type, must be a valid struct field name

Implementation provided by an element type specific subclass.

`np()`

Number of ports per element of this type.

```
np = nme.np()
```

Output
np (*integer*) – number of ports per element of this type

`nn()`

Number of nodes per element, created by this element type.

```
nn = nme.nn()
```

Output
nn (*integer*) – number of ports per element of this type

`nz()`

Number of non-voltage state variables per element of this type.

```
nz = nme.nz()
```

Output
nz (*integer*) – number of non-voltage state variables per element of this type

`data_model_element(dm, name)`

Get the corresponding data model element.

```
dme = nme.data_model_element(dm, name)
```

Inputs
- **dm** (`mp.data_model` (page 27)) – data model object
- **name** (*char array*) – name of element type

Output
dme (`mp.dm_element` (page 35)) – data model element object

math_model_element(*mm*, *name*)

Get the corresponding math model element.

```
mme = nme.math_model_element(mm, name)
```

Inputs
- **mm** (*mp.math_model* (page 121)) – math model object
- **name** (*char array*) – name of element type

Output
mme (*mp.mm_element* (page 143)) – math model element object

count(*dm*)

Get number of online elements of this type in dm, set nk.

```
nk = nme.count(dm)
```

Input
dm (*mp.data_model* (page 27)) – data model object

Output
nk (*integer*) – number of online elements of this type

add_nodes(*nm*, *dm*)

Add nodes to network model for this element.

```
nme.add_nodes(nm, dm)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object

Add nodes to the network model object, based on value *nn* returned by *nn()* (page 109). Calls the network model's *add_node()* (page 95) *nn* times.

add_states(*nm*, *dm*)

Add non-voltage states to network model for this element.

```
nme.add_states(nm, dm)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object

Add non-voltage states to the network model object, based on value *nz* returned by *nz()* (page 109). Calls the network model's *add_state()* (page 95) *nz* times.

add_vvars(*nm*, *dm*, *idx*)

Add real-valued voltage variables to network object.

```
nme.add_vvars(nm, dm, idx)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object

Add real-valued voltage variables (*v*-variables) to the network model object, for each port. Implementation depends on the specific formulation (i.e. subclass of *mp.form* (page 71)).

For example, consider an element with *np* ports and an AC formulation with polar voltage representation. The actual port voltages are complex, but this method would call the network model's `add_var()` (page 96) twice for each port, once for the voltage angle variables and once for the voltage magnitude variables.

Implemented by a formulation-specific subclass.

add_zvars(*nm*, *dm*, *idx*)

Add real-valued non-voltage state variables to network object.

```
nme.add_zvars(nm, dm, idx)
```

Inputs

- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **idx** (*cell array*) – indices for named and indexed variables

Add real-valued non-voltage state variables (z-variables) to the network model object. Implementation depends on the specific formulation (i.e. subclass of `mp.form` (page 71)).

For example, consider an element with *nz* z-variables and a formulation in which these are complex. This method would call the network model's `add_var()` (page 96) twice for each complex z-variable, once for the variables representing the real part and once for the imaginary part.

Implemented by a formulation-specific subclass.

build_params(*nm*, *dm*)

Build model parameters from data model.

```
nme.build_params(nm, dm)
```

Inputs

- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object

Construction of incidence matrices `C` and `D` are handled in this base class. Building of the formulation-specific model parameters must be implemented by a formulation-specific subclass. The subclass should call its parent in order to construct the incidence matrices.

See also `incidence_matrix()` (page 112), `node_indices()` (page 112).

get_nv_(*sysx*)

Get number of *(possibly complex)* voltage variables.

```
nv_ = nme.get_nv_(sysx)
```

Input

sysx (*boolean*) – if true the state `x_` refers to the full *(possibly complex)* system state *(all node voltages and system non-voltage states)*, otherwise it is the state vector for this specific element type *(port voltages and element non-voltage states)*

Output

nv_ (*integer*) – number of *(possibly complex)* voltage variables in the state variable `x_`, whose meaning depends on the `sysx` input

x2vz(*x_*, *sysx*, *idx*)

Get port voltages and non-voltage states from combined state vector.

```
[v_, z_, vi_] = nme.x2vz(x_, sysx, idx)
```

Inputs
- **x_** (*double*) – *possibly complex* state vector
- **sysx** (*boolean*) – if true the state `x_` refers to the full *(possibly complex)* system state *(all node voltages and system non-voltage states)*, otherwise it is the state vector for this specific element type *(port voltages and element non-voltage states)*
- **idx** (*integer*) – vector of port indices of interest

Outputs
- **v_** (*double*) – vector of *(possibly complex)* port voltages
- **z_** (*double*) – vector of *(possibly complex)* non-voltage state variables
- **vi_** (*double*) – vector of *(possibly complex)* port voltages for selected ports only, as indexed by `idx`

This method extracts voltage and non-voltage states from a combined state vector, optionally with voltages for specific ports only.

Note, that this method can operate on multiple state vectors simultaneously, by specifying `x_` as a matrix. In this case, each output will have the same number of columns, one for each column of the input `x_`.

node_indices(*nm*, *dm*, *cxn_type*, *cxn_idx_prop*, *cxn_type_prop*)

Construct node indices from data model element connection info.

```
nidxs = nme.node_indices(nm, dm)
nidxs = nme.node_indices(nm, dm, cxn_type, cxn_idx_prop)
nidxs = nme.node_indices(nm, dm, cxn_type, cxn_idx_prop, cxn_type_prop)
```

Inputs
- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **cxn_type** (*char array or cell array of char arrays*) – name(s) of type(s) of junction elements, i.e. node-creating elements (e.g. `'bus'`), to which this element connects; see `mp.dm_element.cxn_type()` (page 38) for more info
- **cxn_idx_prop** (*char array or cell array of char arrays*) – name(s) of property(ies) containing indices of junction elements that define connections (e.g. `{'fbus', 'tbus'}`); see `mp.dm_element.cxn_idx_prop()` (page 38) for more info
- **cxn_type_prop** (*char array or cell array of char arrays*) – name(s) of properties containing type of junction elements for each connection, defaults to `''` if `cxn_type` and `cxn_type_prop` are provided, but not `cxn_type_prop`; see `mp.dm_element.cxn_type_prop()` (page 39) for more info

Output
nidxs (*cell array*) – 1 x *np* cell array of node index vectors for each port

This method constructs the node index vectors for each port. That is, element *p* of `nidxs` is the vector of indices of the nodes to which port *p* of these elements are connected. These node indices can be used to construct the element-node incidence matrices that form `C`.

By default, the connection information is obtained from the corresponding data model element, as described in the sec_dm_element_cxn section in the *MATPOWER Developer's Manual*.

See also `incidence_matrix()` (page 112), `mp.dm_element.cxn_type()` (page 38), `mp.dm_element.cxn_idx_prop()` (page 38), `mp.dm_element.cxn_type_prop()` (page 39).

incidence_matrix(*m*, *varargin*)

Construct stacked incidence matrix from set of index vectors.

```
CD = nme.incidence_matrix(m, idx1, idx2, ...)
```

Inputs

- **m** (*integer*) – total number of nodes or states
- **idx1** (*integer*) – index vector for nodes corresponding to this element's first port, or state variables corresponding to this element's first non-voltage state
- **idx2** (*integer*) – same as `idx1` for second port or non-voltage state, and so on

Output

CD (*sparse matrix*) – stacked incidence matrix (`C` for ports, `D` for states)

Forms an *m* x *n* incidence matrix for each input index vector `idx`, where *n* is the dimension of `idx`, and column `j` of the corresponding incidence matrix consists of all zeros with a 1 in row `idx(j)`.

These incidence matrices are then stacked horizontally to form a single matrix return value.

node_types(*nm*, *dm*, *idx*)

Get node type information.

```
ntv            = nme.node_types(nm, dm)
[ref, pv, pq] = nme.node_types(nm, dm)
          ... = nme.node_types(nm, dm, idx)
```

Inputs

- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **idx** (*integer*) – index *(not used in base method)*

Outputs

- **ntv** (*integer*) – node type vector, valid element values are:
  - *mp.NODE_TYPE.REF* (page 169)
  - *mp.NODE_TYPE.PV* (page 169)
  - *mp.NODE_TYPE.PQ* (page 169)
- **ref** (*integer*) – vector of indices of reference nodes
- **pv** (*integer*) – vector of indices of PV nodes
- **pq** (*integer*) – vector of indices of PQ nodes

See also *mp.NODE_TYPE* (page 169).

set_node_type_ref(*dm*, *idx*)

Make the specified node a reference node.

```
nme.set_node_type_ref(dm, idx)
```

Inputs

- **dm** (*mp.data_model* (page 27)) – data model object
- **idx** (*integer*) – index of node to modify, this is the internal network model element index

Set the specified node to type *mp.NODE_TYPE.REF* (page 169).

Implementation provided by node-creating subclass.

set_node_type_pv(*dm*, *idx*)

Make the specified node a PV node.

```
nme.set_node_type_pv(dm, idx)
```

Inputs

- **dm** (*mp.data_model* (page 27)) – data model object
- **idx** (*integer*) – index of node to modify, this is the internal network model element index

Set the specified node to type *mp.NODE_TYPE.PV* (page 169).

Implementation provided by node-creating subclass.

set_node_type_pq(*dm*, *idx*)

Make the specified node a PQ node.

```
nme.set_node_type_pq(dm, idx)
```

Inputs
- **dm** (*mp.data_model* (page 27)) – data model object
- **idx** (*integer*) – index of node to modify, this is the internal network model element index

Set the specified node to type *mp.NODE_TYPE.PQ* (page 169).

Implementation provided by node-creating subclass.

display()

Display the network model element object.

This method is called automatically when omitting a semicolon on a line that retuns an object of this class.

Displays the details of the elements, including total number of elements, nodes per element, ports per element, non-voltage state per element, formulation name, tag, and class, and names and dimensions of the model parameters.

mp.nme_branch

class mp.nme_branch

Bases: *mp.nm_element* (page 107)

mp.nme_branch (page 114) - Network model element abstract base class for branch.

Implements the network model element for branch elements, including transmission lines and transformers, with 2 ports per branch.

Method Summary

name()

np()

mp.nme_branch_ac

class mp.nme_branch_ac

Bases: *mp.nme_branch* (page 114)

mp.nme_branch_ac (page 114) - Network model element abstract base class for branch for AC formulations.

Implements building of the admittance parameter $\underline{\mathbf{Y}}$ for branches.

Method Summary

build_params(*nm*, *dm*)

Builds the admittance parameter $\underline{\mathbf{Y}}$ for branches.

mp.nme_branch_acc

class mp.**nme_branch_acc**

Bases: *mp.nme_branch_ac* (page 114), *mp.form_acc* (page 82)

mp.nme_branch_acc (page 115) - Network model element for branch for AC cartesian voltage formulations.

Implements functions for the voltage angle difference limits and their derivatives and inherits from *mp.form_acc* (page 82).

Method Summary

ang_diff_fcn(*xx*, *Aang*, *lang*, *uang*)

ang_diff_hess(*xx*, *lambda*, *Aang*)

mp.nme_branch_acp

class mp.**nme_branch_acp**

Bases: *mp.nme_branch_ac* (page 114), *mp.form_acp* (page 86)

mp.nme_branch_acp (page 115) - Network model element for branch for AC polar voltage formulations.

Inherits from *mp.form_acp* (page 86).

mp.nme_branch_dc

class mp.**nme_branch_dc**

Bases: *mp.nme_branch* (page 114), *mp.form_dc* (page 88)

mp.nme_branch_dc (page 115) - Network model element for branch for DC formulations.

Implements building of the branch parameters $\underline{\boldsymbol{B}}$ and $\underline{\boldsymbol{p}}$, and inherits from *mp.form_dc* (page 88).

Method Summary

build_params(*nm*, *dm*)

mp.nme_bus

class mp.**nme_bus**

Bases: *mp.nm_element* (page 107)

mp.nme_bus (page 116) - Network model element abstract base class for bus.

Implements the network model element for bus elements, with 1 node per bus.

Implements node type methods.

Method Summary

name()

nn()

node_types(*nm*, *dm*, *idx*)

set_node_type_ref(*nm*, *dm*, *idx*)

set_node_type_pv(*nm*, *dm*, *idx*)

set_node_type_pq(*nm*, *dm*, *idx*)

mp.nme_bus_acc

class mp.**nme_bus_acc**

Bases: *mp.nme_bus* (page 116), *mp.form_acc* (page 82)

mp.nme_bus_acc (page 116) - Network model element for bus for AC cartesian voltage formulations.

Adds voltage variables `Vr` and `Vi` to the network model and inherits from *mp.form_acc* (page 82).

Method Summary

add_vvars(*nm*, *dm*, *idx*)

mp.nme_bus_acp

class mp.**nme_bus_acp**

Bases: *mp.nme_bus* (page 116), *mp.form_acp* (page 86)

mp.nme_bus_acp (page 116) - Network model element for bus for AC cartesian polar formulations.

Adds voltage variables `Va` and `Vm` to the network model and inherits from *mp.form_acp* (page 86).

Method Summary

add_vvars(*nm*, *dm*, *idx*)

mp.nme_bus_dc

class mp.**nme_bus_dc**

Bases: *mp.nme_bus* (page 116), *mp.form_dc* (page 88)

mp.nme_bus_dc (page 117) - Network model element for bus for DC formulations.

Adds voltage variable `Va` to the network model and inherits from *mp.form_dc* (page 88).

Method Summary

add_vvars(*nm*, *dm*, *idx*)

mp.nme_gen

class mp.**nme_gen**

Bases: *mp.nm_element* (page 107)

mp.nme_gen (page 117) - Network model element abstract base class for generator.

Implements the network model element for generator elements, with 1 port and 1 non-voltage state per generator.

Method Summary

name()

np()

nz()

mp.nme_gen_ac

class mp.**nme_gen_ac**

Bases: *mp.nme_gen* (page 117)

mp.nme_gen_ac (page 117) - Network model element abstract base class for generator for AC formulations.

Adds non-voltage state variables `Pg` and `Qg` to the network model and builds the parameter $\underline{\mathbf{N}}$.

Method Summary

add_zvars(*nm*, *dm*, *idx*)

build_params(*nm*, *dm*)

mp.nme_gen_acc

class mp.**nme_gen_acc**

Bases: *mp.nme_gen_ac* (page 117), *mp.form_acc* (page 82)

mp.nme_gen_acc (page 118) - Network model element for generator for AC cartesian voltage formulations.

Inherits from *mp.form_acc* (page 82).

mp.nme_gen_acp

class mp.**nme_gen_acp**

Bases: *mp.nme_gen_ac* (page 117), *mp.form_acp* (page 86)

mp.nme_gen_acp (page 118) - Network model element for generator for AC polar voltage formulations.

Inherits from *mp.form_acp* (page 86).

mp.nme_gen_dc

class mp.**nme_gen_dc**

Bases: *mp.nme_gen* (page 117), *mp.form_dc* (page 88)

mp.nme_gen_dc (page 118) - Network model element for generator for DC formulations.

Adds non-voltage state variable `Pg` to the network model, builds the parameter $\underline{\boldsymbol{K}}$, and inherits from *mp.form_dc* (page 88).

Method Summary

add_zvars(*nm*, *dm*, *idx*)

build_params(*nm*, *dm*)

mp.nme_load

class mp.**nme_load**

Bases: *mp.nm_element* (page 107)

mp.nme_load (page 118) - Network model element abstract base class for load.

Implements the network model element for load elements, with 1 port per load.

Method Summary

name()

np()

mp.nme_load_ac

class mp.**nme_load_ac**

Bases: *mp.nme_load* (page 118)

mp.nme_load_ac (page 119) - Network model element abstract base class for load for AC formulations.

Builds the parameters $\underline{\mathbf{s}}$ and $\underline{\mathbf{Y}}$ and nonlinear functions $\mathbf{s}^{nln}(\mathbf{x})$ and $\mathbf{i}^{nln}(\mathbf{x})$.

Method Summary

build_params(*nm*, *dm*)

port_inj_current_nln(*Sd*, *x_*, *sysx*, *idx*)

port_inj_power_nln(*Sd*, *x_*, *sysx*, *idx*)

mp.nme_load_acc

class mp.**nme_load_acc**

Bases: *mp.nme_load_ac* (page 119), *mp.form_acc* (page 82)

mp.nme_load_acc (page 119) - Network model element for load for AC cartesian voltage formulations.

Inherits from *mp.form_acc* (page 82).

mp.nme_load_acp

class mp.**nme_load_acp**

Bases: *mp.nme_load_ac* (page 119), *mp.form_acp* (page 86)

mp.nme_load_acp (page 119) - Network model element for load for AC polar voltage formulations.

Inherits from *mp.form_acp* (page 86).

mp.nme_load_dc

class mp.**nme_load_dc**

Bases: *mp.nme_load* (page 118), *mp.form_dc* (page 88)

mp.nme_load_dc (page 119) - Network model element for load for DC formulations.

Builds the parameter $\underline{\boldsymbol{p}}$ and inherits from *mp.form_dc* (page 88).

Method Summary

build_params(*nm*, *dm*)

mp.nme_shunt

class mp.**nme_shunt**

Bases: *mp.nm_element* (page 107)

mp.nme_shunt (page 120) - Network model element abstract base class for shunt.

Implements the network model element for shunt elements, with 1 port per shunt.

Method Summary

name()

np()

mp.nme_shunt_ac

class mp.**nme_shunt_ac**

Bases: *mp.nme_shunt* (page 120)

mp.nme_shunt_ac (page 120) - Network model element abstract base class for shunt for AC formulations.

Builds the parameter $\underline{\mathbf{Y}}$.

Method Summary

build_params(*nm*, *dm*)

mp.nme_shunt_acc

class mp.**nme_shunt_acc**

Bases: *mp.nme_shunt_ac* (page 120), *mp.form_acc* (page 82)

mp.nme_shunt_acc (page 120) - Network model element for shunt for AC cartesian voltage formulations.

Inherits from *mp.form_acc* (page 82).

mp.nme_shunt_acp

class mp.**nme_shunt_acp**

Bases: *mp.nme_shunt_ac* (page 120), *mp.form_acp* (page 86)

mp.nme_shunt_acp (page 120) - Network model element for shunt for AC polar voltage formulations.

Inherits from *mp.form_acp* (page 86).

mp.nme_shunt_dc

class mp.**nme_shunt_dc**

Bases: *mp.nme_shunt* (page 120), *mp.form_dc* (page 88)

mp.nme_shunt_dc (page 121) - Network model element for shunt for DC formulations.

Builds the parameter $\underline{p}$ and inherits from *mp.form_dc* (page 88).

Method Summary

build_params(*nm*, *dm*)

3.5 Mathematical Model Classes

3.5.1 Containers

mp.math_model

class mp.**math_model**

Bases: *mp.element_container* (page 165), `opt_model`

mp.math_model (page 121) - Abstract base class for MATPOWER **mathematical model** objects.

The mathematical model, or math model, formulates and defines the mathematical problem to be solved. That is, it determines the variables, constraints, and objective that define the problem. This takes on different forms depending on the task *(e.g. power flow, optimal power flow, etc.)* and the formulation *(e.g. DC, AC-polar-power, etc.)*.

A math model object is a container for math model element (*mp.mm_element* (page 143)) objects and it is also an MP-Opt-Model (opt_model) object. All math model classes inherit from *mp.math_model* (page 121) and therefore also from *mp.element_container* (page 165), opt_model, and mp_idx_manager. Concrete math model classes are task and formulation specific. They also sometimes inherit from abstract mix-in classes that are shared across tasks or formulations.

By convention, math model variables are named `mm` and math model class names begin with `mp.math_model`.

mp.math_model Properties:

- *aux_data* (page 122) - auxiliary data relevant to the model

mp.math_model Methods:

- *task_tag()* (page 122) - returns task tag, e.g. `'PF'`, `'OPF'`
- *task_name()* (page 122) - returns task name, e.g. `'Power Flow'`, `'Optimal Power Flow'`
- *form_tag()* (page 122) - returns network formulation tag, e.g. `'dc'`, `'acps'`
- *form_name()* (page 122) - returns network formulation name, e.g. `'DC'`, `'AC-polar-power'`
- *build()* (page 122) - create, add, and build math model element objects
- *display()* (page 123) - display the math model object
- *add_aux_data()* (page 123) - builds auxiliary data and adds it to the model

- *build_base_aux_data()* (page 123) - builds base auxiliary data, including node types & variable initial values
- *add_vars()* (page 123) - add variables to the model
- *add_system_vars()* (page 123) - add system variables to the model
- *add_constraints()* (page 124) - add constraints to the model
- *add_system_constraints()* (page 124) - add system constraints to the model
- *add_node_balance_constraints()* (page 124) - add node balance constraints to the model
- *add_costs()* (page 124) - add costs to the model
- *add_system_costs()* (page 125) - add system costs to the model
- *solve_opts()* (page 125) - return an options struct to pass to the solver
- *update_nm_vars()* (page 125) - update network model variables from math model solution
- *data_model_update()* (page 126) - update data model from math model solution
- *network_model_x_soln()* (page 126) - convert solved state from math model to network model solution

See the sec_math_model section in the *MATPOWER Developer's Manual* for more information.

See also *mp.task* (page 7), *mp.data_model* (page 27), *mp.net_model* (page 90).

Property Summary

aux_data

(struct) auxiliary data relevant to the model, e.g. can be passed to model constraint functions

Method Summary

task_tag()

Returns task tag, e.g. 'PF', 'OPF'.

```
tag = mm.task_tag()
```

task_name()

Returns task name, e.g. 'Power Flow', 'Optimal Power Flow'.

```
name = mm.task_name()
```

form_tag()

Returns network formulation tag, e.g. 'dc', 'acps'.

```
tag = mm.form_tag()
```

form_name()

Returns network formulation name, e.g. 'DC', 'AC-polar-power'.

```
name = mm.form_name()
```

build(*nm*, *dm*, *mpopt*)

Create, add, and *build()* (page 122) math model element objects.

```
mm.build(nm, dm, mpopt);
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Create and add network model objects, create and add auxiliary data, and add variables, constraints, and costs.

display()

Display the math model object.

This method is called automatically when omitting a semicolon on a line that retuns an object of this class.

Displays the details of the variables, constraints, costs, and math model elements.

See also `mp_idx_manager`.

add_aux_data(*nm*, *dm*, *mpopt*)

Builds auxiliary data and adds it to the model.

```
mm.add_aux_data(nm, dm, mpopt)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Calls the build_aux_data() method and assigns the result to the `aux_data` property. The base build_aux_data() method, which simply calls *build_base_aux_data()* (page 123), is defined in *mp.mm_shared_pfcpf* (page 138) (and in *mp.math_model_opf* (page 131)) allowing it to be shared across math models for different tasks (PF and CPF).

build_base_aux_data(*nm*, *dm*, *mpopt*)

Builds base auxiliary data, including node types & variable initial values.

```
ad = mm.build_base_aux_data(nm, dm, mpopt)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output
ad (*struct*) – struct of auxiliary data

add_vars(*nm*, *dm*, *mpopt*)

Add variables to the model.

```
mm.add_vars(nm, dm, mpopt)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Adds system variables, then calls the *add_vars()* (page 144) method for each math model element.

add_system_vars(*nm*, *dm*, *mpopt*)

Add system variables to the model.

```
mm.add_system_vars(nm, dm, mpopt)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Variables which correspond to a specific math model element should be added by that element's *add_vars()* (page 144) method. Other variables can be added by *add_system_vars()* (page 123). In this base class this method does nothing.

add_constraints(*nm*, *dm*, *mpopt*)

Add constraints to the model.

```
mm.add_constraints(nm, dm, mpopt)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Adds system constraints, then calls the *add_constraints()* (page 144) method for each math model element.

add_system_constraints(*nm*, *dm*, *mpopt*)

Add system constraints to the model.

```
mm.add_system_constraints(nm, dm, mpopt)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Constraints which correspond to a specific math model element should be added by that element's *add_constraints()* (page 144) method. Other constraints can be added by *add_system_constraints()* (page 124). In this base class, it simply calls *add_node_balance_constraints()* (page 124).

add_node_balance_constraints(*nm*, *dm*, *mpopt*)

Add node balance constraints to the model.

```
mm.add_node_balance_constraints(nm, dm, mpopt)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

In this base class this method does nothing.

add_costs(*nm*, *dm*, *mpopt*)

Add costs to the model.

```
mm.add_costs(nm, dm, mpopt)
```

Inputs
- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Adds system costs, then calls the `add_costs()` (page 145) method for each math model element.

add_system_costs(*nm*, *dm*, *mpopt*)

Add system costs to the model.

```
mm.add_system_costs(nm, dm, mpopt)
```

Inputs
- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Costs which correspond to a specific math model element should be added by that element's `add_costs()` (page 145) method. Other variables can be added by `add_system_costs()` (page 125). In this base class this method does nothing.

solve_opts(*nm*, *dm*, *mpopt*)

Return an options struct to pass to the solver.

```
opt = mm.solve_opts(nm, dm, mpopt)
```

Inputs
- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output
opt (*struct*) – options struct for solver

In this base class, returns an empty struct.

update_nm_vars(*mmx*, *nm*)

Update network model variables from math model solution.

```
nm_vars = mm.update_nm_vars(mmx, nm)
```

Inputs
- **mmx** (*double*) – vector of math model variable `x`
- **nm** (`mp.net_model` (page 90)) – network model object

Output
nm_vars (*struct*) – updated network model variables

Returns a struct with the network model variables as fields. The `mm.aux_data.var_map` cell array is used to track mappings of math model variables back to network model variables. Each entry is itself a 7-element cell array of the form

```
{nm_var_type, nm_i1, nm_iN, nm_idx, mm_i1, mm_iN, mm_idx}
```

where
- `nm_var_type` - network model variable type (e.g. `va`, `vm`, `zr`, `zi`)
- `nm_i1` - starting index for network model variable type
- `nm_iN` - ending index for network model variable type

- `nm_idx` - vector of indices for network model variable type
- `mm_i1` - starting index for math model variable
- `mm_iN` - ending index for math model variable
- `mm_idx` - vector of indices for math model variable

Uses either `i1:iN` (if `i1` is not empty) or `idx` as the indices, unless both are empty, in which case it uses `':'`.

data_model_update(*nm*, *dm*, *mpopt*)

Update data model from math model solution.

```
dm = mm.data_model_update(nm, dm, mpopt)
```

Inputs
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output
dm (*mp.data_model* (page 27)) – updated data model object

Calls the *data_model_update()* (page 145) method for each math model element.

network_model_x_soln(*nm*)

Convert solved state from math model to network model solution.

```
nm = mm.network_model_x_soln(nm)
```

Input
nm (*mp.net_model* (page 90)) – network model object

Output
nm (*mp.net_model* (page 90)) – updated network model object

Calls convert_x_m2n() to which is defined in a subclass of in *mp.mm_shared_pfcpf* (page 138) (and of *mp.math_model_opf* (page 131)) allowing it to be shared across math models for different tasks (PF and CPF).

mp.math_model_pf

class mp.**math_model_pf**

Bases: *mp.math_model* (page 121)

mp.math_model_pf (page 126) - Abstract base class for power flow (PF) **math model** objects.

Implements setting up of solver options from MATPOWER options struct.

Method Summary

task_tag()

task_name()

add_costs(*nm*, *dm*, *mpopt*)

add_system_vars(*nm*, *dm*, *mpopt*)

solve_opts(*nm*, *dm*, *mpopt*)

mp.math_model_pf_ac

class mp.**math_model_pf_ac**

Bases: *mp.math_model_pf* (page 126)

mp.math_model_pf_ac (page 127) - Power flow (PF) **math model** for AC formulations.

Provides AC-specific and PF-specific subclasses for elements.

Constructor Summary

math_model_pf_ac()

mp.math_model_pf_acci

class mp.**math_model_pf_acci**

Bases: *mp.math_model_pf_ac* (page 127), *mp.mm_shared_pfcpf_acci* (page 140)

mp.math_model_pf_acci (page 127) - Power flow (PF) **math model** for AC-cartesian-current formulation.

Implements formulation-specific node balance constraints and inherits from formulation-specific class for shared PF/CPF code.

Method Summary

form_tag()

form_name()

add_node_balance_constraints(*nm*, *dm*, *mpopt*)

mp.math_model_pf_accs

class mp.**math_model_pf_accs**

Bases: *mp.math_model_pf_ac* (page 127), *mp.mm_shared_pfcpf_accs* (page 140)

mp.math_model_pf_accs (page 127) - Power flow (PF) **math model** for AC-cartesian-power formulation.

Implements formulation-specific node balance constraints and inherits from formulation-specific class for shared PF/CPF code.

Method Summary

form_tag()

form_name()

`add_node_balance_constraints`(*nm*, *dm*, *mpopt*)

mp.math_model_pf_acpi

class mp.**math_model_pf_acpi**

Bases: *mp.math_model_pf_ac* (page 127), *mp.mm_shared_pfcpf_acpi* (page 141)

mp.math_model_pf_acpi (page 128) - Power flow (PF) **math model** for AC-polar-current formulation.

Implements formulation-specific node balance constraints and inherits from formulation-specific class for shared PF/CPF code.

Method Summary

`form_tag`()

`form_name`()

`add_node_balance_constraints`(*nm*, *dm*, *mpopt*)

mp.math_model_pf_acps

class mp.**math_model_pf_acps**

Bases: *mp.math_model_pf_ac* (page 127), *mp.mm_shared_pfcpf_acps* (page 141)

mp.math_model_pf_acps (page 128) - Power flow (PF) **math model** for AC-polar-power formulation.

Implements formulation-specific node balance constraints and inherits from formulation-specific class for shared PF/CPF code.

Also includes implementations of methods specific to fast-decoupled power flow.

Method Summary

`form_tag`()

`form_name`()

`add_node_balance_constraints`(*nm*, *dm*, *mpopt*)

`gs_x_update`(*x*, *f*, *nm*, *dm*, *mpopt*)

`zg_x_update`(*x*, *f*, *nm*, *dm*, *mpopt*)

`fd_jac_approx`(*nm*, *dm*, *mpopt*)

`fdpf_B_matrix_models`(*dm*, *alg*)

mp.math_model_pf_dc

class mp.**math_model_pf_dc**

Bases: *mp.math_model_pf* (page 126), *mp.mm_shared_pfcpf_dc* (page 141)

mp.math_model_pf_dc (page 129) - Power flow (PF) **math model** for DC formulation.

Provides formulation-specific and PF-specific subclasses for elements and implements formulation-specific node balance constraints.

Overrides the default *solve_opts()* (page 129) method.

Constructor Summary

math_model_pf_dc()

Method Summary

form_tag()

form_name()

add_node_balance_constraints(*nm*, *dm*, *mpopt*)

solve_opts(*nm*, *dm*, *mpopt*)

mp.math_model_cpf_acc

class mp.**math_model_cpf_acc**

Bases: mp.math_model_cpf

mp.math_model_cpf_acc (page 129) - Abstract base class for AC cartesian CPF **math model** objects.

Provides formulation-specific and CPF-specific subclasses for elements.

Constructor Summary

math_model_cpf_acc()

Constructor, assign default network model element classes.

```
mm = math_model_cpf_acc()
```

mp.math_model_cpf_acci

class mp.**math_model_cpf_acci**

Bases: *mp.math_model_cpf_acc* (page 129), *mp.mm_shared_pfcpf_acci* (page 140)

mp.math_model_cpf_acci (page 129) - CPF **math model** for AC-cartesian-current formulation.

Implements formulation-specific and CPF-specific node balance constraint.

Method Summary

form_tag()

form_name()

add_node_balance_constraints(*nm*, *dm*, *mpopt*)

mp.math_model_cpf_accs

class mp.**math_model_cpf_accs**

Bases: *mp.math_model_cpf_acc* (page 129), *mp.mm_shared_pfcpf_accs* (page 140)

mp.math_model_cpf_accs (page 130) - CPF **math model** for AC-cartesian-power formulation.

Implements formulation-specific and CPF-specific node balance constraint.

Method Summary

form_tag()

form_name()

add_node_balance_constraints(*nm*, *dm*, *mpopt*)

mp.math_model_cpf_acp

class mp.**math_model_cpf_acp**

Bases: `mp.math_model_cpf`

mp.math_model_cpf_acp (page 130) - Abstract base class for AC polar CPF **math model** objects.

Provides formulation-specific and CPF-specific subclasses for elements and implementations of event and callback functions for handling voltage limits.

Constructor Summary

math_model_cpf_acp()

Constructor, assign default network model element classes.

```
mm = math_model_cpf_acp()
```

Method Summary

event_vlim(*cx*, *opt*, *nm*, *dm*, *mpopt*)

callback_vlim(*k*, *nx*, *cx*, *px*, *s*, *opt*, *nm*, *dm*, *mpopt*)

mp.math_model_cpf_acpi

class mp.**math_model_cpf_acpi**

Bases: *mp.math_model_cpf_acp* (page 130), *mp.mm_shared_pfcpf_acpi* (page 141)

mp.math_model_cpf_acpi (page 131) - CPF **math model** for AC-polar-current formulation.

Implements formulation-specific and CPF-specific node balance constraint.

Method Summary

form_tag()

form_name()

add_node_balance_constraints(*nm*, *dm*, *mpopt*)

mp.math_model_cpf_acps

class mp.**math_model_cpf_acps**

Bases: *mp.math_model_cpf_acp* (page 130), *mp.mm_shared_pfcpf_acps* (page 141)

mp.math_model_cpf_acps (page 131) - CPF **math model** for AC-polar-power formulation.

Implements formulation-specific and CPF-specific node balance constraint.

Provides methods for warm-starting solver with updated data.

Method Summary

form_tag()

form_name()

add_node_balance_constraints(*nm*, *dm*, *mpopt*)

expand_z_warmstart(*nm*, *ad*, *varargin*)

solve_opts_warmstart(*opt*, *ws*, *nm*)

mp.math_model_opf

class mp.**math_model_opf**

Bases: *mp.math_model* (page 121)

mp.math_model_opf (page 131) - Abstract base class for optimal power flow (OPF) **math model** objects.

Provide implementations for adding system variables to the mathematical model and creating an interior starting point.

Method Summary

task_tag()

task_name()

build_aux_data(*nm*, *dm*, *mpopt*)

add_system_vars(*nm*, *dm*, *mpopt*)

interior_x0(*mm*, *nm*, *dm*, *x0*)

interior_va(*nm*, *dm*)

mp.math_model_opf_ac

class mp.**math_model_opf_ac**

Bases: *mp.math_model_opf* (page 131)

mp.math_model_opf_ac (page 132) - Abstract base class for AC OPF **math model** objects.

Provide implementation of nodal current and power balance functions and their derivatives, and setup of solver options.

Method Summary

nodal_current_balance_fcn(*x*, *nm*)

nodal_power_balance_fcn(*x*, *nm*)

nodal_current_balance_hess(*x*, *lam*, *nm*)

nodal_power_balance_hess(*x*, *lam*, *nm*)

solve_opts(*nm*, *dm*, *mpopt*)

mp.math_model_opf_acc

class mp.**math_model_opf_acc**

Bases: *mp.math_model_opf_ac* (page 132)

mp.math_model_opf_acc (page 132) - Abstract base class for AC cartesian OPF **math model** objects.

Provides formulation-specific and OPF-specific subclasses for elements.

Implements *convert_x_m2n()* (page 132) to convert from math model state to network model state.

Constructor Summary

math_model_opf_acc()

Method Summary

convert_x_m2n(*mmx*, *nm*)

interior_va(*nm*, *dm*)

mp.math_model_opf_acci

class mp.**math_model_opf_acci**

Bases: *mp.math_model_opf_acc* (page 132)

mp.math_model_opf_acci (page 133) - OPF **math model** for AC-cartesian-current formulation.

Implements formulation-specific and OPF-specific node balance constraint and node balance price methods.

Method Summary

form_tag()

form_name()

add_node_balance_constraints(*nm*, *dm*, *mpopt*)

node_power_balance_prices(*nm*)

mp.math_model_opf_acci_legacy

class mp.**math_model_opf_acci_legacy**

Bases: *mp.math_model_opf_acci* (page 133), *mp.mm_shared_opf_legacy* (page 142)

mp.math_model_opf_acci_legacy (page 133) - OPF **math model** for AC-cartesian-current formulation w/legacy extensions.

Provides formluation-specific methods for handling legacy user customization of OPF problem.

Constructor Summary

math_model_opf_acci_legacy()

Method Summary

add_named_set(*varargin*)

def_set_types()

init_set_types()

build(*nm*, *dm*, *mpopt*)

add_vars(*nm*, *dm*, *mpopt*)

add_system_costs(*nm*, *dm*, *mpopt*)

add_system_constraints(*nm*, *dm*, *mpopt*)

legacy_user_var_names()

mp.math_model_opf_accs

class mp.**math_model_opf_accs**

Bases: *mp.math_model_opf_acc* (page 132)

mp.math_model_opf_accs (page 134) - OPF **math model** for AC-cartesian-power formulation.

Implements formulation-specific and OPF-specific node balance constraint and node balance price methods.

Method Summary

form_tag()

form_name()

add_node_balance_constraints(*nm*, *dm*, *mpopt*)

node_power_balance_prices(*nm*)

mp.math_model_opf_accs_legacy

class mp.**math_model_opf_accs_legacy**

Bases: *mp.math_model_opf_accs* (page 134), *mp.mm_shared_opf_legacy* (page 142)

mp.math_model_opf_accs_legacy (page 134) - OPF **math model** for AC-cartesian-power formulation w/legacy extensions.

Provides formluation-specific methods for handling legacy user customization of OPF problem.

Constructor Summary

math_model_opf_accs_legacy()

Method Summary

add_named_set(*varargin*)

def_set_types()

init_set_types()

build(*nm*, *dm*, *mpopt*)

add_vars(*nm*, *dm*, *mpopt*)

add_system_costs(*nm*, *dm*, *mpopt*)

add_system_constraints(*nm*, *dm*, *mpopt*)

legacy_user_var_names()

mp.math_model_opf_acp

class mp.**math_model_opf_acp**

Bases: *mp.math_model_opf_ac* (page 132)

mp.math_model_opf_acp (page 135) - Abstract base class for AC polar OPF **math model** objects.

Provides formulation-specific and OPF-specific subclasses for elements.

Implements *convert_x_m2n()* (page 135) to convert from math model state to network model state.

Constructor Summary

math_model_opf_acp()

Method Summary

convert_x_m2n(*mmx*, *nm*)

mp.math_model_opf_acpi

class mp.**math_model_opf_acpi**

Bases: *mp.math_model_opf_acp* (page 135)

mp.math_model_opf_acpi (page 135) - OPF **math model** for AC-polar-current formulation.

Implements formulation-specific and OPF-specific node balance constraint and node balance price methods.

Method Summary

form_tag()

form_name()

add_node_balance_constraints(*nm*, *dm*, *mpopt*)

node_power_balance_prices(*nm*)

mp.math_model_opf_acpi_legacy

class mp.**math_model_opf_acpi_legacy**

Bases: *mp.math_model_opf_acpi* (page 135), *mp.mm_shared_opf_legacy* (page 142)

mp.math_model_opf_acpi_legacy (page 135) - OPF **math model** for AC-polar-current formulation w/legacy extensions.

Provides formluation-specific methods for handling legacy user customization of OPF problem.

Constructor Summary

math_model_opf_acpi_legacy()

Method Summary

`add_named_set(varargin)`

`def_set_types()`

`init_set_types()`

`build(nm, dm, mpopt)`

`add_vars(nm, dm, mpopt)`

`add_system_costs(nm, dm, mpopt)`

`add_system_constraints(nm, dm, mpopt)`

`legacy_user_var_names()`

mp.math_model_opf_acps

`class mp.math_model_opf_acps`

Bases: `mp.math_model_opf_acp` (page 135)

`mp.math_model_opf_acps` (page 136) - OPF **math model** for AC-polar-power formulation.

Implements formulation-specific and OPF-specific node balance constraint and node balance price methods.

Method Summary

`form_tag()`

`form_name()`

`add_node_balance_constraints(nm, dm, mpopt)`

`node_power_balance_prices(nm)`

mp.math_model_opf_acps_legacy

`class mp.math_model_opf_acps_legacy`

Bases: `mp.math_model_opf_acps` (page 136), `mp.mm_shared_opf_legacy` (page 142)

`mp.math_model_opf_acps_legacy` (page 136) - OPF **math model** for AC-polar-power formulation w/legacy extensions.

Provides formluation-specific methods for handling legacy user customization of OPF problem.

Constructor Summary

`math_model_opf_acps_legacy()`

Method Summary

`add_named_set(varargin)`

def_set_types()

init_set_types()

build(*nm*, *dm*, *mpopt*)

add_vars(*nm*, *dm*, *mpopt*)

add_system_costs(*nm*, *dm*, *mpopt*)

add_system_constraints(*nm*, *dm*, *mpopt*)

legacy_user_var_names()

mp.math_model_opf_dc

class mp.**math_model_opf_dc**

Bases: *mp.math_model_opf* (page 131)

mp.math_model_opf_dc (page 137) - Optimal Power flow (OPF) **math model** for DC formulation.

Provides formulation-specific and OPF-specific subclasses for elements.

Provides implementation of nodal balance constraint method and setup of solver options.

Implements *convert_x_m2n()* (page 137) to convert from math model state to network model state.

Constructor Summary

math_model_opf_dc()

Method Summary

form_tag()

form_name()

convert_x_m2n(*mmx*, *nm*)

add_node_balance_constraints(*nm*, *dm*, *mpopt*)

solve_opts(*nm*, *dm*, *mpopt*)

mp.math_model_opf_dc_legacy

class mp.**math_model_opf_dc_legacy**

Bases: *mp.math_model_opf_dc* (page 137), *mp.mm_shared_opf_legacy* (page 142)

mp.math_model_opf_dc (page 137) - OPF **math model** for DC formulation w/legacy extensions.

Provides formluation-specific methods for handling legacy user customization of OPF problem.

Constructor Summary

math_model_opf_dc_legacy(*mpc*)

Method Summary

add_named_set(*varargin*)

def_set_types()

init_set_types()

build(*nm*, *dm*, *mpopt*)

add_vars(*nm*, *dm*, *mpopt*)

add_system_costs(*nm*, *dm*, *mpopt*)

add_system_constraints(*nm*, *dm*, *mpopt*)

legacy_user_var_names()

3.5.2 Container Mixins

mp.mm_shared_pfcpf

class mp.**mm_shared_pfcpf**

Bases: handle

mp.mm_shared_pfcpf (page 138) - Mixin class for PF/CPF **math model** objects.

An abstract mixin class inherited by all power flow (PF) and continuation power flow (CPF) **math model** objects.

Method Summary

build_aux_data(*nm*, *dm*, *mpopt*)

mp.mm_shared_pfcpf_ac

class mp.**mm_shared_pfcpf_ac**

Bases: *mp.mm_shared_pfcpf* (page 138)

mp.mm_shared_pfcpf_ac (page 138) - Mixin class for AC PF/CPF **math model** objects.

An abstract mixin class inherited by all AC power flow (PF) and continuation power flow (CPF) **math model** objects.

Method Summary

add_system_varset_pf(*nm*, *vvar*, *typ*)

update_z(*nm*, *v_*, *z_*, *ad*, *Sinj*, *idx*)

update_z() (page 138) - Update/allocate active/reactive injections at slack/PV nodes.

Update/allocate slack know active power injections and slack/PV node reactive power injections.

mp.mm_shared_pfcpf_ac_i

class mp.**mm_shared_pfcpf_ac_i**

Bases: `handle`

mp.mm_shared_pfcpf_ac_i (page 139) - Mixin class for AC-current PF/CPF **math model** objects.

An abstract mixin class inherited by all AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a current balance formuation.

Code shared between AC cartesian and polar formulations with current balance belongs in this class.

Method Summary

build_aux_data_i(*nm*, *ad*)

mp.mm_shared_pfcpf_acc

class mp.**mm_shared_pfcpf_acc**

Bases: *mp.mm_shared_pfcpf_ac* (page 138)

mp.mm_shared_pfcpf_acc (page 139) - Mixin class for AC cartesian PF/CPF **math model** objects.

An abstract mixin class inherited by all AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a cartesian voltage formuation.

Method Summary

convert_x_m2n(*mmx*, *nm*, *only_v*)

convert_x_m2n() (page 139) - Convert math model state to network model state.

```
x = mm.pf_convert(mmx, nm)
[v, z] = mm.pf_convert(mmx, nm)
[v, z, x] = mm.pf_convert(mmx, nm,)
 ... = mm.pf_convert(mmx, nm, only_v)
```

mp.mm_shared_pfcpf_acci

class mp.**mm_shared_pfcpf_acci**

Bases: *mp.mm_shared_pfcpf_acc* (page 139), *mp.mm_shared_pfcpf_ac_i* (page 139)

mp.mm_shared_pfcpf_acci (page 140) - Mixin class for AC-cartesian-current PF/CPF **math model** objects.

An abstract mixin class inherited by AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a cartesian voltage and current balance formuation.

Method Summary

build_aux_data(*nm*, *dm*, *mpopt*)

add_system_vars_pf(*nm*, *dm*, *mpopt*)

node_balance_equations(*x*, *nm*)

mp.mm_shared_pfcpf_accs

class mp.**mm_shared_pfcpf_accs**

Bases: *mp.mm_shared_pfcpf_acc* (page 139)

mp.mm_shared_pfcpf_accs (page 140) - Mixin class for AC-cartesian-power PF/CPF **math model** objects.

An abstract mixin class inherited by AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a cartesian voltage and power balance formuation.

Method Summary

add_system_vars_pf(*nm*, *dm*, *mpopt*)

node_balance_equations(*x*, *nm*)

mp.mm_shared_pfcpf_acp

class mp.**mm_shared_pfcpf_acp**

Bases: *mp.mm_shared_pfcpf_ac* (page 138)

mp.mm_shared_pfcpf_acp (page 140) - Mixin class for AC polar PF/CPF **math model** objects.

An abstract mixin class inherited by all AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a polar voltage formuation.

Method Summary

convert_x_m2n(*mmx*, *nm*, *only_v*)

convert_x_m2n() (page 140) - Convert math model state to network model state.

```
x = mm.pf_convert(mmx, nm)
[v, z] = mm.pf_convert(mmx, nm)
[v, z, x] = mm.pf_convert(mmx, nm)
... = mm.pf_convert(mmx, nm, only_v)
```

mp.mm_shared_pfcpf_acpi

class mp.**mm_shared_pfcpf_acpi**

Bases: *mp.mm_shared_pfcpf_acp* (page 140), *mp.mm_shared_pfcpf_ac_i* (page 139)

mp.mm_shared_pfcpf_acpi (page 141) - Mixin class for AC-polar-current PF/CPF **math model** objects.

An abstract mixin class inherited by AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a polar voltage and current balance formuation.

Method Summary

build_aux_data(*nm*, *dm*, *mpopt*)

add_system_vars_pf(*nm*, *dm*, *mpopt*)

node_balance_equations(*x*, *nm*)

mp.mm_shared_pfcpf_acps

class mp.**mm_shared_pfcpf_acps**

Bases: *mp.mm_shared_pfcpf_acp* (page 140)

mp.mm_shared_pfcpf_acps (page 141) - Mixin class for AC-polar-power PF/CPF **math model** objects.

An abstract mixin class inherited by AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a polar voltage and power balance formuation.

Method Summary

build_aux_data(*nm*, *dm*, *mpopt*)

add_system_vars_pf(*nm*, *dm*, *mpopt*)

node_balance_equations(*x*, *nm*, *fdpf*)

mp.mm_shared_pfcpf_dc

class mp.**mm_shared_pfcpf_dc**

Bases: *mp.mm_shared_pfcpf* (page 138)

mp.mm_shared_pfcpf_dc (page 141) - Mixin class for DC power flow (PF) **math model** objects.

An abstract mixin class inherited by DC power flow (PF) **math model** objects.

Method Summary

build_aux_data(*nm*, *dm*, *mpopt*)

add_system_vars_pf(*nm*, *dm*, *mpopt*)

convert_x_m2n(*mmx*, *nm*, *only_v*)

convert_x_m2n() (page 142) - Convert math model state to network model state.

```
x = mm.pf_convert(mmx, nm)
[v, z] = mm.pf_convert(mmx, nm)
[v, z, x] = mm.pf_convert(mmx, nm)
... = mm.pf_convert(mmx, nm, only_v)
```

update_z(*nm*, *v*, *z*, *ad*)

update_z() (page 142) - Update/allocate slack node active power injections.

mp.mm_shared_opf_legacy

class mp.**mm_shared_opf_legacy**

Bases: handle

mp.mm_shared_opf_legacy (page 142) - Mixin class for legacy optimal power flow (OPF) **math model** objects.

An abstract mixin class inherited by optimal power flow (OPF) **math model** objects that need to handle legacy user customization mechanisms.

Method Summary

def_set_types_legacy()

init_set_types_legacy()

get_mpc(*om*)

build_legacy(*nm*, *dm*, *mpopt*)

add_legacy_user_vars(*nm*, *dm*, *mpopt*)

add_legacy_user_costs(*nm*, *dm*, *dc*)

add_legacy_user_constraints(*nm*, *dm*, *mpopt*)

add_legacy_user_constraints_ac(*nm*, *dm*, *mpopt*)

add_legacy_cost(*om*, *name*, *idx*, *varargin*)

add_legacy_cost() (page 142) - Add a set of user costs to the model

```
mm.add_legacy_cost(name, cp)
mm.add_legacy_cost(name, idx, varsets)
mm.add_legacy_cost(name, idx_list, cp)
mm.add_legacy_cost(name, idx_list, cp, varsets)
```

eval_legacy_cost(*om*, *x*, *name*, *idx*)

eval_legacy_cost() (page 142) - Evaluate individual or full set of legacy user costs.

```
f = mm.eval_legacy_cost(x ...)
[f, df] = mm.eval_legacy_cost(x ...)
[f, df, d2f] = mm.eval_legacy_cost(x ...)
[f, df, d2f] = mm.eval_legacy_cost(x, name)
[f, df, d2f] = mm.eval_legacy_cost(x, name, idx_list)
```

params_legacy_cost(*om*, *name*, *idx*)

params_legacy_cost() (page 143) - Return cost parameters for legacy user-defined costs.

```
cp = mm.params_legacy_cost()
cp = mm.params_legacy_cost(name)
cp = mm.params_legacy_cost(name, idx)
[cp, vs] = mm.params_legacy_cost(...)
[cp, vs, i1, iN] = mm.params_legacy_cost(...)
```

3.5.3 Elements

mp.mm_element

class mp.**mm_element**

Bases: handle

mp.mm_element (page 143) - Abstract base class for MATPOWER **mathematical model element** objects.

A math model element object typically does not contain any data, but only the methods that are used to build the math model and update the corresponding data model element once the math model has been solved.

All math model element classes inherit from *mp.mm_element* (page 143). Each element type typically implements its own subclasses, which are further subclassed where necessary per task and formulation, as with the container class.

By convention, math model element variables are named `mme` and math model element class names begin with `mp.mme`.

mp.mm_element Methods:

- *name()* (page 144) - get name of element type, e.g. 'bus', 'gen'
- *data_model_element()* (page 144) - get corresponding data model element
- *network_model_element()* (page 144) - get corresponding network model element
- *add_vars()* (page 144) - add math model variables for this element
- *add_constraints()* (page 144) - add math model constraints for this element
- *add_costs()* (page 145) - add math model costs for this element
- *data_model_update()* (page 145) - update the corresponding data model element
- *data_model_update_off()* (page 145) - update offline elements in corresponding data model element
- *data_model_update_on()* (page 145) - update online elements in corresponding data model element

See the sec_mm_element section in the *MATPOWER Developer's Manual* for more information.

See also `mp.math_model` (page 121).

Method Summary

`name()`

Get name of element type, e.g. `'bus'`, `'gen'`.

```
name = mme.name()
```

Output
name (*char array*) – name of element type, must be a valid struct field name

Implementation provided by an element type specific subclass.

`data_model_element(dm, name)`

Get corresponding data model element.

```
dme = mme.data_model_element(dm, name)
```

Inputs
- **dm** (`mp.data_model` (page 27)) – data model object
- **name** (*char array*) – name of element type

Output
dme (`mp.dm_element` (page 35)) – data model element object

`network_model_element(nm, name)`

Get corresponding network model element.

```
nme = mme.network_model_element(nm, name)
```

Inputs
- **nm** (`mp.net_model` (page 90)) – network model object
- **name** (*char array*) – name of element type

Output
nme (`mp.nm_element` (page 107)) – network model element object

`add_vars(mm, nm, dm, mpopt)`

Add math model variables for this element.

```
mme.add_vars(mm, nm, dm, mpopt)
```

Inputs
- **mm** (`mp.math_model` (page 121)) – mathmatical model object
- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Implementation provided by a subclass.

`add_constraints(mm, nm, dm, mpopt)`

Add math model constraints for this element.

```
mme.add_constraints(obj, mm, nm, dm, mpopt)
```

Inputs
- **mm** (`mp.math_model` (page 121)) – mathmatical model object

- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Implementation provided by a subclass.

add_costs(*mm*, *nm*, *dm*, *mpopt*)

Add math model costs for this element.

```
mme.add_costs(obj, mm, nm, dm, mpopt)
```

Inputs

- **mm** (*mp.math_model* (page 121)) – mathmatical model object
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Implementation provided by a subclass.

data_model_update(*mm*, *nm*, *dm*, *mpopt*)

Update the corresponding data model element.

```
mme.data_model_update(mm, nm, dm, mpopt)
```

Inputs

- **mm** (*mp.math_model* (page 121)) – mathmatical model object
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Call *data_model_update_off()* (page 145) then *data_model_update_on()* (page 145) to update the data model for this element based on the math model solution.

See also *data_model_update_off()* (page 145), *data_model_update_on()* (page 145).

data_model_update_off(*mm*, *nm*, *dm*, *mpopt*)

Update offline elements in the corresponding data model element.

```
mme.data_model_update_off(mm, nm, dm, mpopt)
```

Inputs

- **mm** (*mp.math_model* (page 121)) – mathmatical model object
- **nm** (*mp.net_model* (page 90)) – network model object
- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Set export variables for offline elements based on specs returned by *mp.dm_element.export_vars_offline_val()* (page 40).

See also *data_model_update()* (page 145), *data_model_update_on()* (page 145).

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

Update online elements in the corresponding data model element.

```
mme.data_model_update_on(mm, nm, dm, mpopt)
```

Inputs

- **mm** (*mp.math_model* (page 121)) – mathmatical model object
- **nm** (*mp.net_model* (page 90)) – network model object

- **dm** (`mp.data_model` (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Extract the math model solution relevant to this particular element and update the corresponding data model element for online elements accordingly.

Implementation provided by a subclass.

See also `data_model_update()` (page 145), `data_model_update_off()` (page 145).

mp.mme_branch

class mp.**mme_branch**

Bases: `mp.mm_element` (page 143)

`mp.mme_branch` (page 146) - Math model element abstract base class for branch.

Abstract math model element base class for branch elements, including transmission lines and transformers.

Method Summary

name()

mp.mme_branch_pf_ac

class mp.**mme_branch_pf_ac**

Bases: `mp.mme_branch` (page 146)

`mp.mme_branch_pf_ac` (page 146) - Math model element for branch for AC power flow.

Math model element class for branch elements, including transmission lines and transformers, for AC power flow problems.

Implements updating the output data in the corresponding data model element for in-service branches from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_branch_pf_dc

class mp.**mme_branch_pf_dc**

Bases: `mp.mme_branch` (page 146)

`mp.mme_branch_pf_dc` (page 146) - Math model element for branch for DC power flow.

Math model element class for branch elements, including transmission lines and transformers, for DC power flow problems.

Implements updating the output data in the corresponding data model element for in-service branches from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_branch_opf

class mp.**mme_branch_opf**

Bases: *mp.mme_branch* (page 146)

mp.mme_branch_opf (page 147) - Math model element abstract base class for branch for OPF.

Math model element abstract base class for branch elements, including transmission lines and transformers, for OPF problems.

Implements methods to prepare data required for angle difference limit constraints and to extract shadow prices for these constraints from the math model solution.

Method Summary

ang_diff_params(*dm*, *ignore*)

ang_diff_prices(*mm*, *nme*)

mp.mme_branch_opf_ac

class mp.**mme_branch_opf_ac**

Bases: *mp.mme_branch_opf* (page 147)

mp.mme_branch_opf_ac (page 147) - Math model element abstract base class for branch for AC OPF.

Math model element abstract base class for branch elements, including transmission lines and transformers, for AC OPF problems.

Implements methods for adding of branch flow constraints and for updating the output data in the corresponding data model element for in-service branches from the math model solution.

Method Summary

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_branch_opf_acc

class mp.**mme_branch_opf_acc**

Bases: *mp.mme_branch_opf_ac* (page 147)

mp.mme_branch_opf_acc (page 148) - Math model element for branch for AC cartesian voltage OPF.

Math model element class for branch elements, including transmission lines and transformers, for AC cartesian voltage OPF problems.

Implements method for adding branch angle difference constraints and overrides method to extract shadow prices for these constraints from the math model solution.

Method Summary

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

ang_diff_prices(*mm*, *nme*)

mp.mme_branch_opf_acp

class mp.**mme_branch_opf_acp**

Bases: *mp.mme_branch_opf_ac* (page 147)

mp.mme_branch_opf_acp (page 148) - Math model element for branch for AC polar voltage OPF.

Math model element class for branch elements, including transmission lines and transformers, for AC polar voltage OPF problems.

Implements method for adding branch angle difference constraints.

Method Summary

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_branch_opf_dc

class mp.**mme_branch_opf_dc**

Bases: *mp.mme_branch_opf* (page 147)

mp.mme_branch_opf_dc (page 148) - Math model element for branch for DC OPF.

Math model element class for branch elements, including transmission lines and transformers, for DC OPF problems.

Implements methods for adding of branch flow and angle difference constraints and for updating the output data in the corresponding data model element for in-service branches from the math model solution.

Method Summary

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_bus

class mp.**mme_bus**

Bases: *mp.mm_element* (page 143)

mp.mme_bus (page 149) - Math model element abstract base class for bus.

Abstract math model element base class for bus elements.

Method Summary

name()

mp.mme_bus_pf_ac

class mp.**mme_bus_pf_ac**

Bases: *mp.mme_bus* (page 149)

mp.mme_bus_pf_ac (page 149) - Math model element for bus for AC power flow.

Math model element class for bus elements for AC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service buses from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_bus_pf_dc

class mp.**mme_bus_pf_dc**

Bases: *mp.mme_bus* (page 149)

mp.mme_bus_pf_dc (page 149) - Math model element for bus for DC power flow.

Math model element class for bus elements for DC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service buses from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_bus_opf_ac

class mp.**mme_bus_opf_ac**

Bases: *mp.mme_bus* (page 149)

mp.mme_bus_opf_ac (page 150) - Math model element abstract base class for bus for AC OPF.

Abstract math model element class for bus elements for AC OPF problems.

Implements method for forming an interior initial point for voltage magnitudes.

Method Summary

interior_vm(*mm*, *nm*, *dm*)
return vm equal to avg of clipped limits

mp.mme_bus_opf_acc

class mp.**mme_bus_opf_acc**

Bases: *mp.mme_bus_opf_ac* (page 150)

mp.mme_bus_opf_acc (page 150) - Math model element for bus for AC cartesian voltage OPF.

Math model element class for bus elements for AC cartesian voltage OPF problems.

Implements methods for adding constraints for reference voltage angle, fixed voltage magnitudes and voltage magnitude limits, for forming an interior initial point and for updating the output data in the corresponding data model element for in-service buses from the math model solution.

Method Summary

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

interior_x0(*mm*, *nm*, *dm*, *x0*)

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_bus_opf_acp

class mp.**mme_bus_opf_acp**

Bases: *mp.mme_bus_opf_ac* (page 150)

mp.mme_bus_opf_acp (page 150) - Math model element for bus for AC polar voltage OPF.

Math model element class for bus elements for AC polar voltage OPF problems.

Implements methods for forming an interior initial point and for updating the output data in the corresponding data model element for in-service buses from the math model solution.

Method Summary

interior_x0(*mm*, *nm*, *dm*, *x0*)

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_bus_opf_dc

`class mp.mme_bus_opf_dc`

Bases: *mp.mme_bus* (page 149)

mp.mme_bus_opf_dc (page 151) - Math model element for bus for DC OPF.

Math model element class for bus elements for DC OPF problems.

Implements methods for forming an interior initial point and for updating the output data in the corresponding data model element for in-service buses from the math model solution.

Method Summary

interior_x0(*mm*, *nm*, *dm*, *x0*)

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_gen

`class mp.mme_gen`

Bases: *mp.mm_element* (page 143)

mp.mme_gen (page 151) - Math model element abstract base class for generator.

Abstract math model element base class for generator elements.

Method Summary

name()

mp.mme_gen_pf_ac

`class mp.mme_gen_pf_ac`

Bases: *mp.mme_gen* (page 151)

mp.mme_gen_pf_ac (page 151) - Math model element for generator for AC power flow.

Math model element class for generator elements for AC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service generators from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_gen_pf_dc

class mp.**mme_gen_pf_dc**

Bases: *mp.mme_gen* (page 151)

mp.mme_gen_pf_dc (page 152) - Math model element for generator for DC power flow.

Math model element class for generator elements for DC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service generators from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_gen_opf

class mp.**mme_gen_opf**

Bases: *mp.mme_gen* (page 151)

mp.mme_gen_opf (page 152) - Math model element abstract base class for generator for OPF.

Math model element abstract base class for generator elements for OPF problems.

Implements methods to add costs, including piecewise linear cost variables, and to form an interior initial point for cost variables.

Property Summary

cost

struct for *cost* (page 152) parameters with fields:

- poly_p - polynomial costs for active power, struct returned by *mp.cost_table.poly_params()* (page 162), with fields:
  - have_quad_cost
  - i0, i1, i2, i3
  - k, c, Q
- poly_q - polynomial costs for reactive power *(same struct as* poly_p *)*
- pwl - piecewise linear costs for actve & reactive struct returned by *mp.cost_table.pwl_params()* (page 163), with fields:
  - n, i, A, b

Method Summary

add_vars(*mm*, *nm*, *dm*, *mpopt*)

add_costs(*mm*, *nm*, *dm*, *mpopt*)

interior_x0(*mm*, *nm*, *dm*, *x0*)

mp.mme_gen_opf_ac

class mp.**mme_gen_opf_ac**

Bases: *mp.mme_gen_opf* (page 152)

mp.mme_gen_opf_ac (page 153) - Math model element for generator for AC OPF.

Math model element class for generator elements for AC OPF problems.

Implements methods for buliding and adding PQ capability constraints, dispatchable load power factor constraints, polynomial costs, and for updating the output data in the corresponding data model element for in-service generators from the math model solution.

Method Summary

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

add_costs(*mm*, *nm*, *dm*, *mpopt*)

pq_capability_constraint(*dme*, *base_mva*)

from legacy `makeApq()`

has_pq_cap(*gen*, *upper_lower*)

from legacy `hasPQcap()`

disp_load_constant_pf_constraint(*dm*)

from legacy `makeAvl()`

build_cost_params(*dm*)

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_gen_opf_dc

class mp.**mme_gen_opf_dc**

Bases: *mp.mme_gen_opf* (page 152)

mp.mme_gen_opf_dc (page 153) - Math model element for generator for DC OPF.

Math model element class for generator elements for DC OPF problems.

Implements methods for buliding cost parameters, adding piecewise linear cost constraints, and for updating the output data in the corresponding data model element for in-service generators from the math model solution.

Method Summary

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

build_cost_params(*dm*)

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_load

class mp.**mme_load**

Bases: *mp.mm_element* (page 143)

mp.mme_load (page 154) - Math model element abstract base class for load.

Abstract math model element base class for load elements.

Method Summary

name()

mp.mme_load_pf_ac

class mp.**mme_load_pf_ac**

Bases: *mp.mme_load* (page 154)

mp.mme_load_pf_ac (page 154) - Math model element for load for AC power flow.

Math model element class for load elements for AC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service loads from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_load_pf_dc

class mp.**mme_load_pf_dc**

Bases: *mp.mme_load* (page 154)

mp.mme_load_pf_dc (page 154) - Math model element for load for DC power flow.

Math model element class for load elements for DC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service loads from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_load_cpf

class mp.**mme_load_cpf**

Bases: *mp.mme_load_pf_ac* (page 154)

mp.mme_load_cpf (page 155) - Math model element for load for CPF.

Math model element class for load elements for AC CPF problems.

Implements method for updating the output data in the corresponding data model element for in-service loads from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_shunt

class mp.**mme_shunt**

Bases: *mp.mm_element* (page 143)

mp.mme_shunt (page 155) - Math model element abstract base class for shunt.

Abstract math model element base class for shunt elements.

Method Summary

name()

mp.mme_shunt_pf_ac

class mp.**mme_shunt_pf_ac**

Bases: *mp.mme_shunt* (page 155)

mp.mme_shunt_pf_ac (page 155) - Math model element for shunt for AC power flow.

Math model element class for shunt elements for AC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service shunts from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_shunt_pf_dc

class mp.**mme_shunt_pf_dc**

Bases: *mp.mme_shunt* (page 155)

mp.mme_shunt_pf_dc (page 156) - Math model element for shunt for DC power flow.

Math model element class for shunt elements for DC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service shunts from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_shunt_cpf

class mp.**mme_shunt_cpf**

Bases: *mp.mme_shunt_pf_ac* (page 155)

mp.mme_shunt_cpf (page 156) - Math model element for shunt for CPF.

Math model element class for shunt elements for AC CPF problems.

Implements method for updating the output data in the corresponding data model element for in-service shunts from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

3.6 Miscellaneous Classes

3.6.1 mp_table

class mp_table

mp_table (page 156) - Very basic table-compatible class for Octave or older Matlab.

```
T = mp_table(var1, var2, ...);
T = mp_table(..., 'VariableNames', {name1, name2, ...}});
T = mp_table(..., 'RowNames', {name1, name2, ...}});
T = mp_table(..., 'DimensionNames', {name1, name2, ...}});
```

Implements a very basic table array class focused the ability to store and access named variables of different types in a way that is compatible with MATLAB's built-in table class. Other features, such as table joining, etc., are not implemented.

Important: Since the dot syntax `T.<var_name>` is used to access table variables, you must use a functional syntax `<method>(T,...)`, as opposed to the object-oriented `T.<method>(...)`, to call mp_table methods.

mp_table Methods:

- *mp_table()* (page 157) - construct object
- *istable()* (page 157) - true for *mp_table* (page 156) objects
- *size()* (page 157) - dimensions of table
- *isempty()* (page 157) - true if table has no columns or no rows
- *end()* (page 158) - used to index last row or variable/column
- *subsref()* (page 158) - indexing a table to retrieve data
- *subsasgn()* (page 158) - indexing a table to assign data
- *horzcat()* (page 159) - concatenate tables horizontally
- *vertcat()* (page 159) - concatenate tables vertically
- *display()* (page 159) - display table contents

See also `table`.

Constructor Summary

mp_table(*varargin*)

Constructs the object.

```
T = mp_table(var1, var2, ...)
T = mp_table(..., 'VariableNames', {name1, name2, ...})
T = mp_table(..., 'RowNames', {name1, name2, ...})
T = mp_table(..., 'DimensionNames', {name1, name2, ...})
```

Method Summary

istable()

Returns true.

```
TorF = istable(T)
```

Unfortunately, this is not really useful until Octave implements a built-in *istable()* (page 157) that this can override.

size(*dim*)

Returns dimensions of table.

```
[m, n] = size(T)
m = size(T, 1)
n = size(T, 2)
```

isempty()

Returns `true` if the table has no columns or no rows.

```
TorF = isempty(T)
```

end(*k*, *n*)

Used to index the last row or column of the table.

```
last_var = T{:, end}
last_row = T(end, :)
```

subsref(*s*)

Called when indexing a table to retrieve data.

```
sub_T = T(i, *)
sub_T = T(i1:iN, *)
sub_T = T(:, *)
sub_T = T(*, j)
sub_T = T(*, j1:jN)
sub_T = T(*, :)
sub_T = T(*, <str>)
sub_T = T(*, <cell>)
var_<name> = T.<name>
val = T.<name>(i)
val = T.<name>(i1:iN)
val = T.<name>{i}
val = T.<name>{i1:iN}
val = T.<name>(*, :)
val = T.<name>(*, j)
var_<j> = T{:, j}
var_<str> = T{:, <str>}
val = T{i, *}
val = T{i1:iN, *}
val = T{:, *}
val = T{*, j}
val = T{*, j1:jN}
val = T{*, :}
val = T{*, <str>}
val = T{*, <cell>}
```

subsasgn(*s*, *b*)

Called when indexing a table to assign data.

```
T(i, *) = sub_T
T(i1:iN, *) = sub_T
T(:, *) = sub_T
T(*, j) = sub_T
T(*, j1:jN) = sub_T
T(*, :) = sub_T
T(*,  <str>) = sub_T
T(*,  <cell>) = sub_T
T.<name> = val
T.<name>(i) = val
T.<name>(i1:iN) = val
T.<name>{i} = val
T.<name>{i1:iN} = val
```

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```
T.<name>(*, :) = val
T.<name>(*, j) = val
T{:, j} = var_<j>
T{:, <str>} = var_<str>
T{i, *} = val
T{i1:iN, *} = val
T{:, *} = val
T{*, j} = val
T{*, j1:jN} = val
T{*, :} = val
T{*, <str>} = val
T{*, <cell>} = val
```

horzcat(*varargin*)

Concatenate tables horizontally.

```
T = [T1 T2]
```

vertcat(*varargin*)

Concatenate tables vertically.

```
T = [T1; T2]
```

display()

Display the table contents.

This method is called automatically when omitting a semicolon on a line that retuns an object of this class.

By default it displays only the first and last 10 rows if there are more than 25 rows.

Does not currently display the contents of any nested tables.

static extract_named_args(*args*)

Extracts special named constructor arguments.

```
[var_names, row_names, dim_names, args] = extract_named_args(var1, var2, ...
↪)
[...] = extract_named_args(..., 'VariableNames', {name1, name2, ...})
[...] = extract_named_args(..., 'RowNames', {name1, name2, ...})
[...] = extract_named_args(..., 'DimensionNames', {name1, name2, ...})
```

Used to extract named arguments, `'VariableNames'`, `'RowNames'`, and `'DimensionNames'`, to pass to constructor.

3.6.2 mp_table_subclass

class mp_table_subclass

mp_table_subclass (page 160) - Class that acts like a table but isn't one.

Addresses two issues with inheriting from **table** classes (table) or *mp_table* (page 156)).

1. In MATLAB, table is a sealed class, so you cannot inherit from it. You can, however, use a subclass of *mp_table* (page 156), but that can result in the next issue under Octave.
2. While nesting of tables works just fine in general, when using *mp_table* (page 156) in Octave (at least up through 8.4.0), you cannot nest a subclass of *mp_table* (page 156) inside another *mp_table* (page 156) object because of this bug: https://savannah.gnu.org/bugs/index.php?65037.

To work around these issues, your "table subclass" can inherit from **this** class. An object of this class **isn't** a table or *mp_table* (page 156) object, but rather it **contains** one and attempts to act like one. That is, it delegates method calls (currently only those available in *mp_table* (page 156), listed below) to the contained table object.

The class of the contained table object is either table or *mp_table* (page 156) and is determined by *mp_table_class()* (page 6).

Limitations

1. The Octave bug mentioned above also affects tables that inherit from *mp_table_subclass* (page 160). That is, such tables can be nested inside tables of type table or *mp_table* (page 156), but not inside tables that are or inherit from *mp_table_subclass* (page 160).
2. In MATLAB, when nesting an *mp_table_subclass* (page 160) object within another *mp_table_subclass* (page 160) object, one cannot use multi-level indexing directly. E.g. If T2 is a variable in T1 and x is a variable in T2, attempting `x = T1.T2.x` will result in an error. The indexing must be done in multiple steps `T2 = T1.T2; x = T2.x`. Note: This only applies to MATLAB, where the contained table is a table. It works just fine in Octave, where the contained table is an *mp_table* (page 156).

Important: Since the dot syntax `T.<var_name>` is used to access table variables, you must use a functional syntax `<method>(T,...)`, as opposed to the object-oriented `T.<method>(...)`, to call methods of this class or subclasses, as with mp_table.

---

mp.mp_table_subclass Properties:

- tab - *(table or mp_table)* contained table object this class emulates

mp.cost_table Methods:

- mp_table_subclass() - construct object
- *get_table()* (page 161) - return the table stored in tab
- *set_table()* (page 161) - assign a table to tab
- istable() - true for *mp_table* (page 156) objects
- size() - dimensions of table
- isempty() - true if table has no columns or no rows
- end() - used to index last row or variable/column
- subsref() - indexing a table to retrieve data

- `subsasgn()` - indexing a table to assign data
- `horzcat()` - concatenate tables horizontally
- `vertcat()` - concatenate tables vertically
- `display()` - display table contents

See also *mp_table* (page 156), *mp_table_class()* (page 6).

Method Summary

get_table()

```
T = get_table(obj)
```

set_table(*T*)

```
set_table(obj, T)
```

3.6.3 mp.cost_table

class mp.cost_table

Bases: *mp_table_subclass* (page 160)

mp.cost_table (page 161) - Table for (polynomial and piecewise linear) cost parameters.

```
T = cost_table(poly_n, poly_coef, pwl_n, pwl_qty, pwl_cost);
```

Important: Since the dot syntax `T.<var_name>` is used to access table variables, you must use a functional syntax `<method>(T,...)`, as opposed to the object-oriented `T.<method>(...)`, to call standard mp.cost_table methods.

Standard table subscripting syntax is not available within methods of this class (references built-in `subsref()` and `subsasgn()` rather than the versions overridden by the table class). For this reason, some method implementations are delegated to static methods in *mp.cost_table_utils* (page 164) where that syntax is available, making the code more readable.

mp.cost_table Methods:

- *cost_table()* (page 162) - construct object
- *poly_params()* (page 162) - create struct of polynomial parameters from *mp.cost_table* (page 161)
- *pwl_params()* (page 163) - create struct of piecewise linear parameters from *mp.cost_table* (page 161)
- *max_pwl_cost()* (page 163) - get maximum cost component used to specify pwl costs

An *mp.cost_table* (page 161) has the following columns:

Name	Type	Description
poly_n	*integer*	n_{poly}, number of coefficients in polynomial cost curve, $f_{\text{poly}}(x) = c_0 + c_1 x ... + c_N x^N$, where $n_{\text{poly}} = N + 1$
poly_co	*double*	matrix of coefficients c_j, of polynomial cost $f_{\text{poly}}(x)$, where c_j is found in column $j + 1$
pwl_n	*double*	n_{pwl}, number of data points $(x_1, f_1), (x_2, f_2), ..., (x_N, f_N)$ defining a piecewise linear cost curve, $f_{\text{pwl}}(x)$ where $N = n_{\text{pwl}}$
pwl_qty	*double*	matrix of *quantiy* coordinates x_j for piecwise linear cost $f_{\text{pwl}}(x)$, where x_j is found in column j
pwl_cos	*double*	matrix of *cost* coordinates f_j for piecwise linear cost $f_{\text{pwl}}(x)$, where f_j is found in column j

See also *mp.cost_table_utils* (page 164), *mp_table_subclass* (page 160).

Constructor Summary

cost_table(*varargin*)

```
T = cost_table()
T = cost_table(poly_n, poly_coef, pwl_n, pwl_qty, pwl_cost)
```

For descriptions of the inputs, see the corresponding column in the class documentation above.

Inputs

- **poly_n** (*col vector of integers*)
- **poly_coef** (*matrix of doubles*)
- **pwl_n** (*col vector of integers*)
- **pwl_qty** (*matrix of doubles*)
- **pwl_cost** (*matrix of doubles*)

Outputs

T (*mp.cost_table* (page 161)) – the cost table object

Method Summary

poly_params(*idx*, *pu_base*)

```
p = poly_params(obj, idx, pu_base)
```

Inputs

- **obj** (*mp.cost_table* (page 161)) – the cost table
- **idx** – (integer) : index vector of rows of interest, empty for all rows
- **pu_base** (*double*) – base used to scale quantities to per unit

Outputs

p (*struct*) – polynomial cost parameters, struct with fields:

- `have_quad_cost` - true if any polynmial costs have order quadratic or less
- `i0` - row indices for constant costs
- `i1` - row indices for linear costs
- `i2` - row indices for quadratic costs
- `i3` - row indices for order 3 or higher costs
- `k` - constant term for all quadratic and lower order costs
- `c` - linear term for all quadratic and lower order costs
- `Q` - quadratic term for all quadratic and lower order costs

Implementation in `mp.cost_table_utils.poly_params()` (page 164).

pwl_params(*idx*, *pu_base*, *varargin*)

```
p = pwl_params(obj, idx, pu_base)
p = pwl_params(obj, idx, pu_base, ng, dc)
```

Inputs
- **obj** (`mp.cost_table` (page 161)) – the cost table
- **idx** – (integer) : index vector of rows of interest, empty for all rows
- **pu_base** (*double*) – base used to scale quantities to per unit
- **ng** (*integer*) – number of units, default is # of rows in cost
- **dc** (*boolean*) – true if DC formulation (ng variables), otherwise AC formulation (2*ng variables), default is 1

Outputs

p (*struct*) – piecewise linear cost parameters, struct with fields:
- `n` - number of piecewise linear costs
- `i` - row indices for piecewise linear costs
- `A` - constraint coefficient matrix for CCV formulation
- `b` - constraint RHS vector for CCV formulation

Implementation in `mp.cost_table_utils.pwl_params()` (page 165).

max_pwl_cost()

```
maxc = max_pwl_cost(obj)
```

Input

obj (`mp.cost_table` (page 161)) – the cost table

Output

maxc (*double*) – maximum cost component of all breakpoints used to specify piecewise linear costs

Implementation in `mp.cost_table_utils.max_pwl_cost()` (page 165).

static poly_cost_fcn(*xx*, *x_scale*, *ccm*, *idx*)

```
f = mp.cost_table.poly_cost_fcn(xx, x_scale, ccm, idx)
[f, df] = mp.cost_table.poly_cost_fcn(...)
[f, df, d2f] = mp.cost_table.poly_cost_fcn(...)
```

Evaluates the sum of a set of polynomial cost functions $f(x) = \sum_{i \in I} f_i(x_i)$, and optionally the gradient and Hessian.

Inputs
- **xx** (*single element cell array of double*) – first element is a vector of the pre-scaled quantities x/α used to compute the costs
- **x_scale** (*double*) – scalar α used to scale the quantity value before evaluating the polynomial cost
- **ccm** (*double*) – cost coefficient matrix, element *(i,j)* is the coefficient of the *(j-1)* order term for cost *i*
- **idx** (*integer*) – index vector of subset I of rows of `xx{1}` and `ccm` of interest

Outputs
- **f** (*double*) – value of cost function $f(x)$
- **df** (*vector of double*) – (optional) gradient of cost function
- **d2f** (*matrix of double*) – (optional) Hessian of cost function

static eval_poly_fcn(*c*, *x*)

```
f = mp.cost_table.eval_poly_fcn(c, x)
```

Evaluate a vector of polynomial functions, where ...

```
f = c(:,1) + c(:,2) .* x + c(:,3) .* x^2 + ...
```

Inputs

- **c** (*matrix of double*) – coefficient matrix, element *(i,j)* is the coefficient of the *(j-1)* order term for *i*-th element of *f*
- **x** (*vector of double*) – vector of input values

Outputs

f (*vector of double*) – value of functions

static diff_poly_fcn(*c*)

```
c = mp.cost_table.diff_poly_fcn(c)
```

Compute the coefficient matrix for the derivatives of a set of polynomial functions from the coefficients of the functions.

Inputs

c (*matrix of double*) – coefficient matrix for the functions, element *(i,j)* is the coefficient of the *(j-1)* order term of the *i*-th function

Outputs

c (*matrix of double*) – coefficient matrix for the derivatives of the functions, element *(i,j)* is the coefficient of the *(j-1)* order term of the derivative of the *i*-th function

3.6.4 mp.cost_table_utils

class mp.cost_table_utils

mp.cost_table_utils (page 164) - Static methods for *mp.cost_table* (page 161).

Contains the implementation of some methods that would ideally belong in *mp.cost_table* (page 161).

Within classes that inherit from *mp_table_subclass* (page 160), such as *mp.cost_table* (page 161), any subscripting to access the elements of the table must be done through explicit calls to the table's `subsref()` and `subsasgn()` methods. That is, the normal table subscripting syntax will not work, so working with the table becomes extremely cumbersome.

This purpose of this class is to provide the implementation for *mp.cost_table* (page 161) methods that **do** allow access to that table via normal table subscripting syntax.

mp.cost_table_util Methods:

- *poly_params()* (page 164) - create struct of polynomial parameters from *mp.cost_table* (page 161)
- *pwl_params()* (page 165) - create struct of piecewise linear parameters from *mp.cost_table* (page 161)
- *max_pwl_cost()* (page 165) - get maximum cost component used to specify pwl costs

See also *mp.cost_table* (page 161).

Method Summary

static poly_params(*cost*, *idx*, *pu_base*)

```
p = mp.cost_table_utils.poly_params(cost, idx, pu_base)
```

Implementation for `mp.cost_table.poly_params()` (page 162). See `mp.cost_table.poly_params()` (page 162) for details.

static pwl_params(*cost*, *idx*, *pu_base*, *ng*, *dc*)

```
p = mp.cost_table_utils.pwl_params(cost, idx, pu_base)
p = mp.cost_table_utils.pwl_params(cost, idx, pu_base, ng, dc)
```

Implementation for `mp.cost_table.pwl_params()` (page 163). See `mp.cost_table.pwl_params()` (page 163) for details.

static max_pwl_cost(*cost*)

```
maxc = mp.cost_table_utils.max_pwl_cost(cost)
```

Implementation for `mp.cost_table.max_pwl_cost()` (page 163). See `mp.cost_table.max_pwl_cost()` (page 163) for details.

3.6.5 mp.element_container

class mp.element_container

Bases: handle

`mp.element_container` (page 165) - Mix-in class to handle named/ordered element object array.

Implements an element container that is used for MATPOWER model and data model converter objects. Provides the properties to store the constructors for each element and the elements themselves. Also provides a method to modify an existing set of element constructors.

mp.element_container Properties:

- `element_classes` (page 165) - cell array of element constructors
- `elements` (page 165) - a `mp.mapped_array` (page 166) to hold the element objects

mp.element_container Methods:

- `modify_element_classes()` (page 165) - modify an existing set of element constructors

See also `mp.mapped_array` (page 166).

Property Summary

element_classes

Cell array of function handles of constructors for individual elements, filled by constructor of subclass.

elements

A mapped array (`mp.mapped_array` (page 166)) to hold the element objects included inside this container object.

Method Summary

modify_element_classes(*class_list*)

Modify an existing set of element constructors.

```
obj.modify_element_classes(class_list)
```

Input

class_list (*cell array*) – list of **element class modifiers**, where each modifier is one of the following:

1. a handle to a constructor to **append** to `obj.element_classes`, *or*
2. a char array `B`, indicating to **remove** any element `E` in the list for which `isa(E(), B)` is `true`, *or*
3. a 2-element cell array `{A,B}` where `A` is a handle to a constructor to **replace** any element `E` in the list for which `isa(E(), B)` is `true`, i.e. `B` is a char array

Also accepts a single element class modifier of type 1 or 2 *(A single type 3 modifier has to be enclosed in a single-element cell array to keep it from being interpreted as a list of 2 modifiers)*.

Can be used to modify the list of element constructors in the `element_classes` property by appending, removing, or replacing entries. See `tab_element_class_modifiers` in the *MATPOWER Developer's Manual* for more information.

3.6.6 mp.mapped_array

class `mp.mapped_array`

Bases: `handle`

mp.mapped_array (page 166) - Cell array indexed by name as well as numeric index.

Currently, arrays are only 1-D.

Example usage:

```
% create a mapped array object
ma = mp.mapped_array({30, 40, 50}, {'width', 'height', 'depth'});

% treat it like a cell array
ma{3} = 60;
height = ma{2};
for i = 1:length(ma)
    disp( ma{i} );
end

% treat it like a struct
ma.width = 20;
depth = ma.depth;

% add elements
ma.add_elements({'red', '25 lbs'}, {'color', 'weight'});

% delete elements
ma.delete_elements([3 5]);
ma.delete_elements('height');
```

(continues on next page)

(continued from previous page)

```
% check for named element
ma.has_name('color');
```

mp.mapped_array Methods:

- *mapped_array()* (page 167) - constructor
- *copy()* (page 167) - create a duplicate of the mapped array object
- *length()* (page 167) - return number of elements in mapped array
- *size()* (page 167) - return dimensions of mapped array
- *add_names()* (page 168) - add or modify names of elements
- *add_elements()* (page 168) - append elements to the end of the mapped array
- *delete_elements()* (page 168) - delete elements from the mapped array
- *has_name()* (page 168) - return `true` if the name exists in the mapped array
- *name2idx()* (page 168) - return the index corresponding to a name
- *subsref()* (page 168) - called when indexing a mapped array to retrieve data
- *subsasgn()* (page 169) - called when indexing a mapped array to assign data
- *display()* (page 169) - display the mapped array structure

Constructor Summary

mapped_array(*varargin*)

```
obj = mp.mapped_array(vals)
obj = mp.mapped_array(vals, names)
```

Inputs

- **vals** (*cell array*) – values to be stored
- **names** (*cell array of char arrays*) – names for each element in `vals`, where a valid name is any valid variable name that is not one of the methods of this class. If names are not provided, it is equivalent to a cell array, except that names can be added later.

Method Summary

copy()

Create a duplicate of the mapped array object.

```
new_obj = obj.copy();
```

length()

Return number of elements in mapped array.

```
num_elements = obj.length();
```

size(*dim*)

Return dimensions of mapped array. First dimension is 1, second matches the length.

```
[m, n] = obj.size();
m = obj.size(1);
n = obj.size(2);
```

add_names(*i0*, *names*)

Add or modify names of elements.

```
obj.add_names(i0, names)
```

Inputs
- **i0** (*cell array*) – index of element corresponding to first name provided in `names`
- **names** (*char array or cell array of char arrays*) – the names to assign

Adds or overwrites the names for elements starting at the specified index.

add_elements(*vals*, *names*)

Append elements to the end of the mapped array.

```
obj.add_elements(vals);
obj.add_elements(vals, names);
```

Inputs
- **vals** – single value or cell array of values
- **names** (*char array or cell array of char arrays*) – (optional) corresponding names

The two arguments must be both cell arrays of the same dimension or a single value and single name.

See also `delete_elements()` (page 168).

delete_elements(*refs*)

Delete elements from the mapped array.

```
obj.delete_elements(idx);
obj.delete_elements(names);
```

Inputs
- **idx** (*scalar or vector integer*) – index(indices) of element(s) to delete
- **names** (*char array or cell array of char arrays*) – name(s) of element(s) to delete

See also `add_elements()` (page 168).

has_name(*name*)

Return `true` if the name exists in the mapped array.

```
TorF = obj.has_name(name);
```

Input
name (*char array*) – name to check

name2idx(*name*)

Return the numerical index in the array corrsponding to a name.

```
idx = obj.name2idx(name);
```

Input
name (*char array*) – name corresponding to desired index

subsref(s)

Called when indexing a table to retrieve data.

```
val = obj.<name>;
val = obj{idx};
```

subsasgn(s, b)

Called when indexing a table to assign data.

```
obj.<name> = val;
obj{idx} = val;
```

display()

Display the mapped array structure.

This method is called automatically when omitting a semicolon on a line that retuns an object of this class.

3.6.7 mp.NODE_TYPE

class mp.NODE_TYPE

mp.NODE_TYPE (page 169) - Defines enumerated type for node types.

mp.NODE_TYPE Properties:

- *PQ* (page 169) - PQ node (= 1)
- *PV* (page 169) - PV node (= 2)
- *REF* (page 169) - reference node (= 3)
- *NONE* (page 169) - isolated node (= 4)

mp.NODE_TYPE Methods:

- *is_valid()* (page 169) - returns true if the value is a valid node type

All properties are `Constant` properties and the class is a `Sealed` class. So the properties function as global constants which do not create an instance of the class, e.g. *mp.NODE_TYPE.REF* (page 169).

Property Summary

PQ = 1

PQ node

PV = 2

PV node

REF = 3

reference node

NONE = 4

isolated node

Method Summary

static is_valid(*val*)

Returns true if the value is a valid node type.

```
TorF = mp.NODE_TYPE.is_valid(val)
```

Input

val (*integer*) – node type value to check for validity

Output

TorF (*boolean*) – true if `val` is a valid node type

3.7 MATPOWER Extension Classes

3.7.1 Base

mp.extension

class mp.extension

Bases: `handle`

mp.extension (page 170) - Abstract base class for MATPOWER extensions.

This class serves as the framework for the **MATPOWER extension** API, providing a way to bundle a set of class additions and modifications together into a single named package.

By default the methods in this class do nothing, but they can be overridden to customize essentially any aspect of a MATPOWER run. The first 5 methods are used to modify the default classes used to construct the task, data model converter, data, network, and/or mathematical model objects. The last 4 methods are used to add to or modify the classes used to construct the elements for each of the container types.

By convention, MATPOWER extension objects (or cell arrays of them) are named `mpx` and MATPOWER extension class names begin with `mp.xt`.

mp.extension Methods:

- *task_class()* (page 171) - return handle to constructor for task object
- `dmc_class()` - return handle to constructor for data model converter object
- `dm_class()` - return handle to constructor for data model object
- `nm_class()` - return handle to constructor for network model object
- `mm_class()` - return handle to constructor for mathematical object
- *dmc_element_classes()* (page 172) - return element class modifiers for data model converter elements
- *dm_element_classes()* (page 172) - return element class modifiers for data model elements
- *nm_element_classes()* (page 172) - return element class modifiers for network model elements
- *mm_element_classes()* (page 172) - return element class modifiers for mathematical model elements

See the sec_customizing and sec_extensions sections in the *MATPOWER Developer's Manual* for more information, and specifically the sec_element_classes section and the tab_element_class_modifiers table for details on *element class modifiers*.

Example MATPOWER extensions:

- `mp.xt_reserves` (page 173) - adds fixed zonal reserves to OPF
- `mp.xt_3p` (page 178) - adds example prototype unbalanced three-phase elements for AC PF, CPF, and OPF

See also `mp.task` (page 7), `mp.dm_converter` (page 59), `mp.data_model` (page 27), `mp.net_model` (page 90), `mp.math_model` (page 121), `mp.dmc_element` (page 62), `mp.dm_element` (page 35), `mp.nm_element` (page 107), `mp.mm_element` (page 143).

Method Summary

task_class(*task_class*, *mpopt*)

Return handle to constructor for task object.

```
task_class = mpx.task_class(task_class, mpopt)
```

Inputs
- **task_class** (*function handle*) – default task constructor
- **mpopt** (*struct*) – MATPOWER options struct

Output
task_class (*function handle*) – updated task constructor

dm_converter_class(*dmc_class*, *fmt*, *mpopt*)

Return handle to constructor for data model converter object.

```
dmc_class = mpx.dm_converter_class(dmc_class, fmt, mpopt)
```

Inputs
- **dmc_class** (*function handle*) – default data model converter constructor
- **fmt** (*char array*) – data format tag, e.g. `'mpc2'`
- **mpopt** (*struct*) – MATPOWER options struct

Output
dmc_class (*function handle*) – updated data model converter constructor

data_model_class(*dm_class*, *task_tag*, *mpopt*)

Return handle to constructor for data model object.

```
dm_class = mpx.data_model_class(dm_class, task_tag, mpopt)
```

Inputs
- **dm_class** (*function handle*) – default data model constructor
- **task_tag** (*char array*) – task tag, e.g. `'PF'`, `'CPF'`, `'OPF'`
- **mpopt** (*struct*) – MATPOWER options struct

Output
dm_class (*function handle*) – updated data model constructor

network_model_class(*nm_class*, *task_tag*, *mpopt*)

Return handle to constructor for network model object.

```
nm_class = mpx.network_model_class(nm_class, task_tag, mpopt)
```

Inputs
- **nm_class** (*function handle*) – default network model constructor

- **task_tag** (*char array*) – task tag, e.g. 'PF', 'CPF', 'OPF'
- **mpopt** (*struct*) – MATPOWER options struct

Output

nm_class (*function handle*) – updated network model constructor

`math_model_class`(*mm_class*, *task_tag*, *mpopt*)

Return handle to constructor for mathematical model object.

```
mm_class = mpx.math_model_class(mm_class, task_tag, mpopt)
```

Inputs

- **mm_class** (*function handle*) – default math model constructor
- **task_tag** (*char array*) – task tag, e.g. 'PF', 'CPF', 'OPF'
- **mpopt** (*struct*) – MATPOWER options struct

Output

mm_class (*function handle*) – updated math model constructor

`dmc_element_classes`(*dmc_class*, *fmt*, *mpopt*)

Return element class modifiers for data model converter elements.

```
dmc_elements = mpx.dmc_element_classes(dmc_class, fmt, mpopt)
```

Inputs

- **dmc_class** (*function handle*) – data model converter constructor
- **fmt** (*char array*) – data format tag, e.g. 'mpc2'
- **mpopt** (*struct*) – MATPOWER options struct

Output

dmc_elements (*cell array*) – element class modifiers (see tab_element_class_modifiers in the *MATPOWER Developer's Manual*)

`dm_element_classes`(*dm_class*, *task_tag*, *mpopt*)

Return element class modifiers for data model elements.

```
dm_elements = mpx.dm_element_classes(dm_class, task_tag, mpopt)
```

Inputs

- **dm_class** (*function handle*) – data model constructor
- **task_tag** (*char array*) – task tag, e.g. 'PF', 'CPF', 'OPF'
- **mpopt** (*struct*) – MATPOWER options struct

Output

dm_elements (*cell array*) – element class modifiers (see tab_element_class_modifiers in the *MATPOWER Developer's Manual*)

`nm_element_classes`(*nm_class*, *task_tag*, *mpopt*)

Return element class modifiers for network model elements.

```
nm_elements = mpx.nm_element_classes(nm_class, task_tag, mpopt)
```

Inputs

- **nm_class** (*function handle*) – network model constructor
- **task_tag** (*char array*) – task tag, e.g. 'PF', 'CPF', 'OPF'
- **mpopt** (*struct*) – MATPOWER options struct

Output

nm_elements (*cell array*) – element class modifiers (see tab_element_class_modifiers in the *MATPOWER Developer's Manual*)

mm_element_classes(*mm_class*, *task_tag*, *mpopt*)

Return element class modifiers for mathematical model elements.

```
mm_elements = mpx.mm_element_classes(mm_class, task_tag, mpopt)
```

Inputs
- **mm_class** (*function handle*) – mathematical model constructor
- **task_tag** (*char array*) – task tag, e.g. `'PF'`, `'CPF'`, `'OPF'`
- **mpopt** (*struct*) – MATPOWER options struct

Output

mm_elements (*cell array*) – element class modifiers (see tab_element_class_modifiers in the *MATPOWER Developer's Manual*)

3.7.2 OPF Fixed Zonal Reserves Extension

mp.xt_reserves

class mp.**xt_reserves**

Bases: *mp.extension* (page 170)

mp.xt_reserves (page 173) - MATPOWER extension for OPF with fixed zonal reserves.

For OPF problems, this extension adds two types of elements to the data and mathematical model containers, as well as the data model converter.

The `'reserve_gen'` element handles all of the per-generator aspects, such as reserve cost and quantity limit parameters, reserve variables, and constraints on reserve capacity.

The `'reserve_zone'` element handles the per-zone aspects, such as generator/zone mappings, zonal reserve requirement parameters and constraints, and zonal reserve prices.

mp.xt_reserves Methods:

- *dmc_element_classes()* (page 173) - add two classes to data model converter elements
- *dm_element_classes()* (page 173) - add two classes to data model elements
- *mm_element_classes()* (page 174) - add two classes to mathematical model elements

See the sec_customizing and sec_extensions sections in the *MATPOWER Developer's Manual* for more information, and specifically the sec_element_classes section and the tab_element_class_modifiers table for details on *element class modifiers*.

See also *mp.extension* (page 170).

Method Summary

dmc_element_classes(*dmc_class*, *fmt*, *mpopt*)

Add two classes to data model converter elements.

For `'mpc2` data formats, adds the classes:
- *mp.dmce_reserve_gen_mpc2* (page 174)
- *mp.dmce_reserve_zone_mpc2* (page 175)

dm_element_classes(*dm_class*, *task_tag*, *mpopt*)

Add two classes to data model elements.

For 'OPF' tasks, adds the classes:

- *mp.dme_reserve_gen* (page 175)
- *mp.dme_reserve_zone* (page 176)

mm_element_classes(*mm_class*, *task_tag*, *mpopt*)

Add two classes to mathematical model elements.

For 'OPF' tasks, adds the classes:

- *mp.mme_reserve_gen* (page 177)
- *mp.mme_reserve_zone* (page 178)

Other classes belonging to *mp.xt_reserves* (page 173) extension:

mp.dmce_reserve_gen_mpc2

class mp.**dmce_reserve_gen_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_reserve_gen_mpc2 (page 174) - Data model converter element for reserve generator for MATPOWER case v2.

Method Summary

name()

data_field()

data_subs()

get_import_size(*mpc*)

get_export_size(*dme*)

table_var_map(*dme*, *mpc*)

import_cost(*mpc*, *spec*, *vn*)

import_qty(*mpc*, *spec*, *vn*)

import_ramp(*mpc*, *spec*, *vn*)

import(*dme*, *mpc*, *varargin*)

mp.dmce_reserve_zone_mpc2

class mp.**dmce_reserve_zone_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_reserve_zone_mpc2 (page 175) - Data model converter element for reserve zone for MATPOWER case v2.

Method Summary

name()

data_field()

data_subs()

table_var_map(*dme*, *mpc*)

import_req(*mpc*, *spec*, *vn*)

import_zones(*mpc*, *spec*, *vn*)

mp.dme_reserve_gen

class mp.**dme_reserve_gen**

Bases: *mp.dm_element* (page 35), *mp.dme_shared_opf* (page 58)

mp.dme_reserve_gen (page 175) - Data model element for reserve generator.

Implements the data element model for reserve generator elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
gen	*integer*	ID (uid) of corresponding generator
cost	*double*	reserve cost *(u/MW)*[1]
qty	*double*	available reserve quantity *(MW)*
ramp10	*double*	10-minute ramp rate *(MW)*
r	*double*	r, reserve allocation *(MW)*
r_lb	*double*	lower bound on reserve allocation *(MW)*
r_ub	*double*	upper bound on reserve allocation *(MW)*
total_cost	*double*	total cost of allocated reserves *(u)*[1]
prc	*double*	reserve price *(u/MVAr)*[1]
mu_lb	*double*	shadow price on r lower bound *(u/MW)*[1]
mu_ub	*double*	shadow price on r upper bound *(u/MW)*[1]
mu_pg_ub	*double*	shadow price on capacity constraint *(u/MW)*[1]

Property Summary

gen

index of online gens (for online reserve gens)

[1] Here *u* denotes the units of the objective function, e.g. USD.

r_ub
upper bound on reserve qty (p.u.) for units that are on

Method Summary

name()

label()

labels()

main_table_var_names()

export_vars()

export_vars_offline_val()

update_status(*dm*)

build_params(*dm*)

pp_have_section_sum(*mpopt*, *pp_args*)

pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_lim(*mpopt*, *pp_args*)

pp_binding_rows_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_get_headers_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_lim(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_get_footers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

mp.dme_reserve_zone

class mp.**dme_reserve_zone**

Bases: `mp.dm_element` (page 35), `mp.dme_shared_opf` (page 58)

`mp.dme_reserve_zone` (page 176) - Data model element for reserve zone.

Implements the data element model for reserve zone elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
`req`	*double*	zonal reserve requirement *(MW)*
`zones`	*integer*	matrix defining generators included in the zone
`prc`	*double*	zonal reserve price *(u/MW)*[1]

Property Summary

zones
zone map for online *zones* (page 177) / gens

req
reserve requirement in p.u. for each active zone

Method Summary

name()

label()

labels()

main_table_var_names()

export_vars()

export_vars_offline_val()

update_status(*dm*)

build_params(*dm*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.mme_reserve_gen

class mp.**mme_reserve_gen**

Bases: *mp.mm_element* (page 143)

mp.mme_reserve_gen (page 177) - Mathematical model element for reserve generator.

Math model element class for reserve generator elements.

Implements methods for adding reserve variables, costs, and per-generator reserve constraints, and for updating the output data in the corresponding data model element for in-service reserve generators from the math model solution.

Method Summary

name()

add_vars(*mm*, *nm*, *dm*, *mpopt*)

add_costs(*mm*, *nm*, *dm*, *mpopt*)

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

[1] Here *u* denotes the units of the objective function, e.g. USD.

mp.mme_reserve_zone

class mp.**mme_reserve_zone**

Bases: *mp.mm_element* (page 143)

mp.mme_reserve_zone (page 178) - Mathematical model element for reserve zone.

Math model element class for reserve zone elements.

Implements methods for adding reserve zone constraints, and for updating the output data in the corresponding data model element for in-service reserve zones from the math model solution.

Method Summary

name()

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

3.7.3 Three-Phase Prototype Extension

mp.xt_3p

class mp.**xt_3p**

Bases: *mp.extension* (page 170)

mp.xt_3p (page 178) - MATPOWER extension to add unbalanced three-phase elements.

For AC power flow, continuation power flow, and optimial power flow problems, adds six new element types:

- 'bus3p' - 3-phase bus
- 'gen3p' - 3-phase generator
- 'load3p' - 3-phase load
- 'line3p' - 3-phase distribution line
- 'xfmr3p' - 3-phase transformer
- 'buslink' - 3-phase to single phase linking element

No changes are required for the task or container classes, so only the `..._element_classes` methods are overridden.

The set of data model element classes depends on the task, with each OPF class inheriting from the corresponding class used for PF and CPF.

The set of network model element classes depends on the formulation, specifically whether cartesian or polar representations are used for voltages.

And the set of mathematical model element classes depends on both the task and the formulation.

mp.xt_3p Methods:

- *dmc_element_classes()* (page 179) - add six classes to data model converter elements
- *dm_element_classes()* (page 179) - add six classes to data model elements

- `nm_element_classes()` (page 179) - add six classes to network model elements
- `mm_element_classes()` (page 180) - add six classes to mathematical model elements

See the sec_customizing and sec_extensions sections in the *MATPOWER Developer's Manual* for more information, and specifically the sec_element_classes section and the tab_element_class_modifiers table for details on *element class modifiers*.

See also `mp.extension` (page 170).

Method Summary

dmc_element_classes(*dmc_class*, *fmt*, *mpopt*)

Add six classes to data model converter elements.

For 'mpc2 data formats, adds the classes:

- `mp.dmce_bus3p_mpc2` (page 180)
- `mp.dmce_gen3p_mpc2` (page 180)
- `mp.dmce_load3p_mpc2` (page 181)
- `mp.dmce_line3p_mpc2` (page 181)
- `mp.dmce_xfmr3p_mpc2` (page 182)
- `mp.dmce_buslink_mpc2` (page 182)

dm_element_classes(*dm_class*, *task_tag*, *mpopt*)

Add six classes to data model elements.

For 'PF' and 'CPF' tasks, adds the classes:

- `mp.dme_bus3p` (page 182)
- `mp.dme_gen3p` (page 184)
- `mp.dme_load3p` (page 185)
- `mp.dme_line3p` (page 187)
- `mp.dme_xfmr3p` (page 189)
- `mp.dme_buslink` (page 190)

For 'OPF' tasks, adds the classes:

- `mp.dme_bus3p_opf` (page 191)
- `mp.dme_gen3p_opf` (page 191)
- `mp.dme_load3p_opf` (page 192)
- `mp.dme_line3p_opf` (page 192)
- `mp.dme_xfmr3p_opf` (page 192)
- `mp.dme_buslink_opf` (page 192)

nm_element_classes(*nm_class*, *task_tag*, *mpopt*)

Add six classes to network model elements.

For *cartesian* voltage formulations, adds the classes:

- `mp.nme_bus3p_acc` (page 193)
- `mp.nme_gen3p_acc` (page 194)
- `mp.nme_load3p` (page 194)
- `mp.nme_line3p` (page 195)
- `mp.nme_xfmr3p` (page 195)
- `mp.nme_buslink_acc` (page 196)

For *polar* voltage formulations, adds the classes:

- `mp.nme_bus3p_acp` (page 193)
- `mp.nme_gen3p_acp` (page 194)
- `mp.nme_load3p` (page 194)
- `mp.nme_line3p` (page 195)
- `mp.nme_xfmr3p` (page 195)
- `mp.nme_buslink_acp` (page 196)

mm_element_classes(*mm_class*, *task_tag*, *mpopt*)

Add five classes to mathematical model elements.

For 'PF' and 'CPF' tasks, adds the classes:

- *mp.mme_bus3p* (page 196)
- *mp.mme_gen3p* (page 197)
- *mp.mme_line3p* (page 197)
- *mp.mme_xfmr3p* (page 197)
- *mp.mme_buslink_pf_acc* (page 198) *(cartesian)* or *mp.mme_buslink_pf_acp* (page 199) *(polar)*

For 'OPF' tasks, adds the classes:

- *mp.mme_bus3p_opf_acc* (page 199) *(cartesian)* or *mp.mme_bus3p_opf_acp* (page 199) *(polar)*
- *mp.mme_gen3p_opf* (page 200)
- *mp.mme_line3p_opf* (page 200)
- *mp.mme_xfmr3p_opf* (page 200)
- *mp.mme_buslink_opf_acc* (page 201) *(cartesian)* or *mp.mme_buslink_opf_acp* (page 201) *(polar)*

Data model converter element classes belonging to *mp.xt_3p* (page 178) extension:

mp.dmce_bus3p_mpc2

class mp.**dmce_bus3p_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_bus3p_mpc2 (page 180) - Data model converter element for 3-phase bus for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

bus_status_import(*mpc*, *spec*, *vn*, *c*)

mp.dmce_gen3p_mpc2

class mp.**dmce_gen3p_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_gen3p_mpc2 (page 180) - Data model converter element for 3-phase generator for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

mp.dmce_load3p_mpc2

class mp.**dmce_load3p_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_load3p_mpc2 (page 181) - Data model converter element for 3-phase load for MATPOWER case v2.

Property Summary

bus

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

mp.dmce_line3p_mpc2

class mp.**dmce_line3p_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_line3p_mpc2 (page 181) - Data model converter element for 3-phase line for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

create_line_construction_table(*dme*, *lc*)

import(*dme*, *mpc*, *varargin*)

mp.dmce_xfmr3p_mpc2

class mp.**dmce_xfmr3p_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_xfmr3p_mpc2 (page 182) - Data model converter element for 3-phase transformer for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

mp.dmce_buslink_mpc2

class mp.**dmce_buslink_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_buslink_mpc2 (page 182) - Data model converter element for 1-to-3-phase buslink for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

Data model element classes belonging to *mp.xt_3p* (page 178) extension:

mp.dme_bus3p

class mp.**dme_bus3p**

Bases: *mp.dm_element* (page 35)

mp.dme_bus3p (page 182) - Data model element for 3-phase bus.

Implements the data element model for 3-phase bus elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
type	*integer*	bus type (1 = PQ, 2 = PV, 3 = ref, 4 = isolated)
base_kv	*double*	base voltage *(kV)*
vm1	*double*	phase 1 voltage magnitude *(p.u.)*
vm2	*double*	phase 2 voltage magnitude *(p.u.)*
vm3	*double*	phase 3 voltage magnitude *(p.u.)*
va1	*double*	phase 1 voltage angle *(degrees)*
va2	*double*	phase 2 voltage angle *(degrees)*
va3	*double*	phase 3 voltage angle *(degrees)*

Property Summary

type

node *type* (page 183) vector for buses that are on

vm1_start

initial phase 1 voltage magnitudes (p.u.) for buses that are on

vm2_start

initial phase 2 voltage magnitudes (p.u.) for buses that are on

vm3_start

initial phase 3 voltage magnitudes (p.u.) for buses that are on

va1_start

initial phase 1 voltage angles (radians) for buses that are on

va2_start

initial phase 2 voltage angles (radians) for buses that are on

va3_start

initial phase 3 voltage angles (radians) for buses that are on

vm_control

true if voltage is controlled, for buses that are on

Method Summary

name()

label()

labels()

main_table_var_names()

init_status(*dm*)

update_status(*dm*)

build_params(*dm*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_gen3p

class mp.**dme_gen3p**

Bases: *mp.dm_element* (page 35)

mp.dme_gen3p (page 184) - Data model element for 3-phase generator.

Implements the data element model for 3-phase generator elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
bus	*integer*	bus ID (uid) of 3-phase bus
vm1_setpoint	*double*	phase 1 voltage magnitude setpoint *(p.u.)*
vm2_setpoint	*double*	phase 2 voltage magnitude setpoint *(p.u.)*
vm3_setpoint	*double*	phase 3 voltage magnitude setpoint *(p.u.)*
pg1	*double*	phase 1 active power output *(kW)*
pg2	*double*	phase 2 active power output *(kW)*
pg3	*double*	phase 3 active power output *(kW)*
qg1	*double*	phase 1 reactive power output *(kVAr)*
qg2	*double*	phase 2 reactive power output *(kVAr)*
qg3	*double*	phase 3 reactive power output *(kVAr)*

Property Summary

bus

bus (page 184) index vector (all gens)

bus_on

vector of indices into online buses for gens that are on

pg1_start

initial phase 1 active power (p.u.) for gens that are on

pg2_start

initial phase 2 active power (p.u.) for gens that are on

pg3_start

initial phase 3 active power (p.u.) for gens that are on

qg1_start

initial phase 1 reactive power (p.u.) for gens that are on

qg2_start

initial phase 2 reactive power (p.u.) for gens that are on

qg3_start

initial phase 3 reactive power (p.u.) for gens that are on

vm1_setpoint

phase 1 generator voltage setpoint for gens that are on

vm2_setpoint
phase 2 generator voltage setpoint for gens that are on

vm3_setpoint
phase 3 generator voltage setpoint for gens that are on

Method Summary

name()

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

initialize(*dm*)

update_status(*dm*)

apply_vm_setpoint(*dm*)

build_params(*dm*)

pp_have_section_sum(*mpopt*, *pp_args*)

pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_load3p

class mp.**dme_load3p**

Bases: `mp.dm_element` (page 35)

`mp.dme_load3p` (page 185) - Data model element for 3-phase load.

Implements the data element model for 3-phase load elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
bus	*integer*	bus ID (`uid`) of 3-phase bus
pd1	*double*	phase 1 active power demand *(kW)*
pd2	*double*	phase 2 active power demand *(kW)*
pd3	*double*	phase 3 active power demand *(kW)*
pf1	*double*	phase 1 power factor
pf2	*double*	phase 2 power factor
pf3	*double*	phase 3 power factor

Property Summary

bus
: bus (page 186) index vector (all loads)

pd1
: phase 1 active power demand (p.u.) for loads that are on

pd2
: phase 2 active power demand (p.u.) for loads that are on

pd3
: phase 3 active power demand (p.u.) for loads that are on

pf1
: phase 1 power factor for loads that are on

pf2
: phase 2 power factor for loads that are on

pf3
: phase 3 power factor for loads that are on

Method Summary

name()

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

initialize(*dm*)

update_status(*dm*)

build_params(*dm*)

pp_have_section_sum(*mpopt*, *pp_args*)

pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_line3p

class mp.**dme_line3p**

Bases: *mp.dm_element* (page 35)

mp.dme_line3p (page 187) - Data model element for 3-phase line.

Implements the data element model for 3-phase distribution line elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
`bus_fr`	*integer*	bus ID (`uid`) of "from" 3-phase bus
`bus_to`	*integer*	bus ID (`uid`) of "to" 3-phase bus
`lc`	*double*	index into line construction table
`len`	*double*	line length *(?)*
`pl1_fr`	*double*	phase 1 active power injection at "from" end *(kW)*
`ql1_fr`	*double*	phase 1 reactive power injection at "from" end *(kVAr)*
`pl2_fr`	*double*	phase 2 active power injection at "from" end *(kW)*
`ql2_fr`	*double*	phase 2 reactive power injection at "from" end *(kVAr)*
`pl3_fr`	*double*	phase 3 active power injection at "from" end *(kW)*
`ql3_fr`	*double*	phase 3 reactive power injection at "from" end *(kVAr)*
`pl1_to`	*double*	phase 1 active power injection at "to" end *(kW)*
`ql1_to`	*double*	phase 1 reactive power injection at "to" end *(kVAr)*
`pl2_to`	*double*	phase 2 active power injection at "to" end *(kW)*
`ql2_to`	*double*	phase 2 reactive power injection at "to" end *(kVAr)*
`pl3_to`	*double*	phase 3 active power injection at "to" end *(kW)*
`ql3_to`	*double*	phase 3 reactive power injection at "to" end *(kVAr)*

The line construction table in the `lc_tab` property is defined as a table with the following columns:

Name	Type	Description
`id`	*integer*	unique line construction ID, referenced from `lc` column of main data table
`r`	*double*	6 resistence parameters for forming symmetric 3x3 series impedance matrix
`x`	*double*	6 reactance parameters for forming symmetric 3x3 series impedance matrix
`c`	*double*	6 susceptance parameters for forming symmetric 3x3 shunt susceptance matrix

Property Summary

fbus

bus index vector for "from" bus (all lines)

tbus

bus index vector for "to" bus (all lines)

freq

system frequency, in Hz

lc
index into lc_tab for lines that are on

len
length for lines that are on

lc_tab
line construction table

ys
cell array of 3x3 series admittance matrices for lc rows

yc
cell array of 3x3 shunt admittance matrices for lc rows

Method Summary

name()

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

lc_table_var_names()

create_line_construction_table(*id*, *r*, *x*, *c*)

initialize(*dm*)

update_status(*dm*)

build_params(*dm*)

vec2symmat(*v*)
Make a symmetric matrix from a vector of 6 values.

symmat2vec(*M*)
Extract a vector of 6 values from a matrix assumed to be symmetric.

pretty_print(*dm*, *section*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_sum(*mpopt*, *pp_args*)

pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_xfmr3p

class mp.**dme_xfmr3p**

Bases: *mp.dm_element* (page 35)

mp.dme_xfmr3p (page 189) - Data model element for 3-phase transformer.

Implements the data element model for 3-phase transformer elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
bus_fr	*integer*	bus ID (uid) of "from" 3-phase bus
bus_to	*integer*	bus ID (uid) of "to" 3-phase bus
r	*double*	series resistance *(p.u.)*
x	*double*	series reactance *(p.u.)*
base_kva	*double*	transformer kVA base *(kVA)*
base_kv	*double*	transformer kV base *(kV)*
pl1_fr	*double*	phase 1 active power injection at "from" end *(kW)*
ql1_fr	*double*	phase 1 reactive power injection at "from" end *(kVAr)*
pl2_fr	*double*	phase 2 active power injection at "from" end *(kW)*
ql2_fr	*double*	phase 2 reactive power injection at "from" end *(kVAr)*
pl3_fr	*double*	phase 3 active power injection at "from" end *(kW)*
ql3_fr	*double*	phase 3 reactive power injection at "from" end *(kVAr)*
pl1_to	*double*	phase 1 active power injection at "to" end *(kW)*
ql1_to	*double*	phase 1 reactive power injection at "to" end *(kVAr)*
pl2_to	*double*	phase 2 active power injection at "to" end *(kW)*
ql2_to	*double*	phase 2 reactive power injection at "to" end *(kVAr)*
pl3_to	*double*	phase 3 active power injection at "to" end *(kW)*
ql3_to	*double*	phase 3 reactive power injection at "to" end *(kVAr)*

Property Summary

fbus

bus index vector for "from" bus (all transformers)

tbus

bus index vector for "to" bus (all transformers)

r

series resistance (p.u.) for transformers that are on

x

series reactance (p.u.) for transformers that are on

Method Summary

name()

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

initialize(*dm*)

update_status(*dm*)

build_params(*dm*)

pretty_print(*dm*, *section*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_sum(*mpopt*, *pp_args*)

pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_buslink

class mp.**dme_buslink**

Bases: `mp.dm_element` (page 35)

`mp.dme_buslink` (page 190) - Data model element for 1-to-3-phase buslink.

Implements the data element model for 1-to-3-phase buslink elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
bus	*integer*	bus ID (`uid`) of single phase bus
bus3p	*integer*	bus ID (`uid`) of 3-phase bus

Property Summary

bus

`bus` (page 190) index vector (all buslinks)

bus3p

`bus3p` (page 190) index vector (all buslinks)

pg1_start

initial phase 1 active power (p.u.) for buslinks that are on

pg2_start

initial phase 2 active power (p.u.) for buslinks that are on

pg3_start

initial phase 3 active power (p.u.) for buslinks that are on

qg1_start

initial phase 1 reactive power (p.u.) for buslinks that are on

qg2_start
initial phase 2 reactive power (p.u.) for buslinks that are on

qg3_start
initial phase 3 reactive power (p.u.) for buslinks that are on

Method Summary

name()

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

initialize(*dm*)

update_status(*dm*)

build_params(*dm*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_bus3p_opf

class mp.**dme_bus3p_opf**

Bases: *mp.dme_bus3p* (page 182), *mp.dme_shared_opf* (page 58)

mp.dme_bus3p_opf (page 191) - Data model element for 3-phase bus for OPF.

To parent class *mp.dme_bus3p* (page 182), adds pretty-printing for **lim** sections.

mp.dme_gen3p_opf

class mp.**dme_gen3p_opf**

Bases: *mp.dme_gen3p* (page 184), *mp.dme_shared_opf* (page 58)

mp.dme_gen3p_opf (page 191) - Data model element for 3-phase generator for OPF.

To parent class *mp.dme_gen3p* (page 184), adds pretty-printing for **lim** sections.

mp.dme_load3p_opf

class mp.**dme_load3p_opf**

Bases: *mp.dme_load3p* (page 185), *mp.dme_shared_opf* (page 58)

mp.dme_load3p_opf (page 192) - Data model element for 3-phase load for OPF.

To parent class *mp.dme_load3p* (page 185), adds pretty-printing for **lim** sections.

mp.dme_line3p_opf

class mp.**dme_line3p_opf**

Bases: *mp.dme_line3p* (page 187), *mp.dme_shared_opf* (page 58)

mp.dme_line3p_opf (page 192) - Data model element for 3-phase line for OPF.

To parent class *mp.dme_line3p* (page 187), adds pretty-printing for **lim** sections.

mp.dme_xfmr3p_opf

class mp.**dme_xfmr3p_opf**

Bases: *mp.dme_xfmr3p* (page 189), *mp.dme_shared_opf* (page 58)

mp.dme_xfmr3p_opf (page 192) - Data model element for 3-phase transformer for OPF.

To parent class *mp.dme_xfmr3p* (page 189), adds pretty-printing for **lim** sections.

mp.dme_buslink_opf

class mp.**dme_buslink_opf**

Bases: *mp.dme_buslink* (page 190), *mp.dme_shared_opf* (page 58)

mp.dme_buslink_opf (page 192) - Data model element for 1-to-3-phase buslink for OPF.

To parent class *mp.dme_buslink* (page 190), adds pretty-printing for **lim** sections.

Network model element classes belonging to *mp.xt_3p* (page 178) extension:

mp.nme_bus3p

class mp.**nme_bus3p**

Bases: *mp.nm_element* (page 107)

mp.nme_bus3p (page 192) - Network model element abstract base class for 3-phase bus.

Implements the network model element for 3-phase bus elements, with 3 nodes per 3-phase bus.

Implements *node_types()* (page 193) method.

Method Summary

name()

nn()

node_types(*nm*, *dm*, *idx*)

```
ntv = nme.node_types(nm, dm, idx)
[ref, pv, pq] = nme.node_types(nm, dm, idx)
```

Called by the *node_types()* (page 98) method of *mp.net_model* (page 90).

mp.nme_bus3p_acc

class mp.**nme_bus3p_acc**

Bases: *mp.nme_bus3p* (page 192), *mp.form_acc* (page 82)

mp.nme_bus3p_acc (page 193) - Network model element for 3-phase bus, AC cartesian voltage formulation.

Adds voltage variables `Vr3` and `Vi3` to the network model and inherits from *mp.form_acc* (page 82).

Method Summary

add_vvars(*nm*, *dm*, *idx*)

mp.nme_bus3p_acp

class mp.**nme_bus3p_acp**

Bases: *mp.nme_bus3p* (page 192), *mp.form_acp* (page 86)

mp.nme_bus3p_acp (page 193) - Network model element for 3-phase bus, AC polar voltage formulation.

Adds voltage variables `Va3` and `Vm3` to the network model and inherits from *mp.form_acp* (page 86).

Method Summary

add_vvars(*nm*, *dm*, *idx*)

mp.nme_gen3p

class mp.**nme_gen3p**

Bases: *mp.nm_element* (page 107)

mp.nme_gen3p (page 193) - Network model element abstract base class for 3-phase generator.

Implements the network model element for 3-phase generator elements, with 3 ports and 3 non-voltage states per 3-phase generator.

Adds non-voltage state variables `Pg3` and `Qg3` to the network model and builds the parameter $\underline{\mathbf{N}}$.

Method Summary

name()

np()

nz()

add_zvars(*nm*, *dm*, *idx*)

build_params(*nm*, *dm*)

mp.nme_gen3p_acc

class mp.**nme_gen3p_acc**

Bases: *mp.nme_gen3p* (page 193), *mp.form_acc* (page 82)

mp.nme_gen3p_acc (page 194) - Network model element for 3-phase generator, AC cartesian voltage formulation.

Inherits from *mp.form_acc* (page 82).

mp.nme_gen3p_acp

class mp.**nme_gen3p_acp**

Bases: *mp.nme_gen3p* (page 193), *mp.form_acp* (page 86)

mp.nme_gen3p_acp (page 194) - Network model element for 3-phase generator, AC polar voltage formulation.

Inherits from *mp.form_acp* (page 86).

mp.nme_load3p

class mp.**nme_load3p**

Bases: *mp.nm_element* (page 107), *mp.form_acp* (page 86)

mp.nme_load3p (page 194) - Network model element for 3-phase load.

Implements the network model element for 3-phase load elements, with 3 ports per 3-phase load.

Builds the parameter s and inherits from *mp.form_acp* (page 86).

Method Summary

name()

np()

build_params(*nm*, *dm*)

mp.nme_line3p

class mp.**nme_line3p**

Bases: *mp.nm_element* (page 107), *mp.form_acp* (page 86)

mp.nme_line3p (page 195) - Network model element for 3-phase line.

Implements the network model element for 3-phase line elements, with 6 ports per 3-phase line.

Implements building of the admittance parameter $\underline{\mathbf{Y}}$ for 3-phase lines and inherits from *mp.form_acp* (page 86).

Method Summary

name()

np()

build_params(*nm*, *dm*)

vec2symmat_stacked(*vv*)

mp.nme_xfmr3p

class mp.**nme_xfmr3p**

Bases: *mp.nm_element* (page 107), *mp.form_acp* (page 86)

mp.nme_xfmr3p (page 195) - Network model element for 3-phase transformer.

Implements the network model element for 3-phase transformer elements, with 6 ports per transformer.

Implements building of the admittance parameter $\underline{\mathbf{Y}}$ for 3-phase transformers and inherits from *mp.form_acp* (page 86).

Method Summary

name()

np()

build_params(*nm*, *dm*)

mp.nme_buslink

class mp.**nme_buslink**

Bases: *mp.nm_element* (page 107)

mp.nme_buslink (page 195) - Network model element abstract base class for 1-to-3-phase buslink.

Implements the network model element for 1-to-3-phase buslink elements, with 4 ports and 3 non-voltage states per buslink.

Adds non-voltage state variables `Plink` and `Qlink` to the network model, builds the parameter $\underline{\mathbf{N}}$, and constructs voltage constraints.

Method Summary

name()

np()

nz()

add_zvars(*nm*, *dm*, *idx*)

build_params(*nm*, *dm*)

voltage_constraints()

mp.nme_buslink_acc

class mp.**nme_buslink_acc**

Bases: *mp.nme_buslink* (page 195), *mp.form_acc* (page 82)

mp.nme_buslink_acc (page 196) - Network model element for 1-to-3-phase buslink, AC cartesian voltage formulation.

Inherits from *mp.form_acc* (page 82).

mp.nme_buslink_acp

class mp.**nme_buslink_acp**

Bases: *mp.nme_buslink* (page 195), *mp.form_acp* (page 86)

mp.nme_buslink_acp (page 196) - Network model element for 1-to-3-phase buslink, AC polar voltage formulation.

Inherits from *mp.form_acp* (page 86).

Mathematical model element classes belonging to *mp.xt_3p* (page 178) extension:

mp.mme_bus3p

class mp.**mme_bus3p**

Bases: *mp.mm_element* (page 143)

mp.mme_bus3p (page 196) - Math model element for 3-phase bus.

Math model element base class for 3-phase bus elements.

Implements method for updating the output data in the corresponding data model element for in-service 3-phase buses from the math model solution.

Method Summary

name()

`data_model_update_on`(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_gen3p

`class mp.mme_gen3p`

Bases: *mp.mm_element* (page 143)

mp.mme_gen3p (page 197) - Math model element for 3-phase generator.

Math model element base class for 3-phase generator elements.

Implements method for updating the output data in the corresponding data model element for in-service 3-phase generators from the math model solution.

Method Summary

`name`()

`data_model_update_on`(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_line3p

`class mp.mme_line3p`

Bases: *mp.mm_element* (page 143)

mp.mme_line3p (page 197) - Math model element for 3-phase line.

Math model element base class for 3-phase line elements.

Implements method for updating the output data in the corresponding data model element for in-service 3-phase lines from the math model solution.

Method Summary

`name`()

`data_model_update_on`(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_xfmr3p

`class mp.mme_xfmr3p`

Bases: *mp.mm_element* (page 143)

mp.mme_xfmr3p (page 197) - Math model element for 3-phase transformer.

Math model element base class for 3-phase transformer elements.

Implements method for updating the output data in the corresponding data model element for in-service 3-phase transformers from the math model solution.

Method Summary

name()

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_buslink

class mp.**mme_buslink**

Bases: *mp.mm_element* (page 143)

mp.mme_buslink (page 198) - Math model element abstract base class for 1-to-3-phase buslink.

Abstract math model element base class for 1-to-3-phase buslink elements.

Method Summary

name()

mp.mme_buslink_pf_ac

class mp.**mme_buslink_pf_ac**

Bases: *mp.mme_buslink* (page 198)

mp.mme_buslink_pf_ac (page 198) - Math model element abstract base class for 1-to-3-phase buslink for AC PF/CPF.

Abstract math model element base class for 1-to-3-phase buslink elements for AC power flow and CPF problems.

Implements methods for adding per-phase active and reactive power variables and for forming and adding voltage and reactive power constraints.

Method Summary

add_vars(*mm*, *nm*, *dm*, *mpopt*)

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

voltage_constraints(*nme*, *ad*)

mp.mme_buslink_pf_acc

class mp.**mme_buslink_pf_acc**

Bases: *mp.mme_buslink_pf_ac* (page 198)

mp.mme_buslink_pf_acc (page 198) - Math model element for 1-to-3-phase buslink for AC cartesian voltage PF/CPF.

Math model element class for 1-to-3-phase buslink elements for AC cartesian power flow and CPF problems.

Implements methods for adding constraints to match voltages across each buslink.

Method Summary

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

pf_va_fcn(*nme*, *xx*, *A*, *b*)

pf_vm_fcn(*nme*, *xx*, *A*, *b*)

mp.mme_buslink_pf_acp

class mp.**mme_buslink_pf_acp**

Bases: *mp.mme_buslink_pf_ac* (page 198)

mp.mme_buslink_pf_acp (page 199) - Math model element for 1-to-3-phase buslink for AC polar voltage PF/CPF.

Math model element class for 1-to-3-phase buslink elements for AC polar power flow and CPF problems.

Implements method for adding constraints to match voltages across each buslink.

Method Summary

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_bus3p_opf_acc

class mp.**mme_bus3p_opf_acc**

Bases: *mp.mme_bus3p* (page 196)

mp.mme_bus3p_opf_acc (page 199) - Math model element for 3-phase bus for AC cartesian voltage OPF.

Math model element class for 3-phase bus elements for AC cartesian voltage OPF problems.

Implements method for forming an interior initial point.

Method Summary

interior_x0(*mm*, *nm*, *dm*, *x0*)

mp.mme_bus3p_opf_acp

class mp.**mme_bus3p_opf_acp**

Bases: *mp.mme_bus3p* (page 196)

mp.mme_bus3p_opf_acp (page 199) - Math model element for 3-phase bus for AC polar voltage OPF.

Math model element class for 3-phase bus elements for AC polar voltage OPF problems.

Implements method for forming an interior initial point.

Method Summary

interior_x0(*mm*, *nm*, *dm*, *x0*)

mp.mme_gen3p_opf

class mp.**mme_gen3p_opf**

Bases: *mp.mme_gen3p* (page 197)

mp.mme_gen3p_opf (page 200) - Math model element for 3-phase generator for OPF.

Math model element class for 1-to-3-phase generator elements for OPF problems.

Implements (currently empty) method for forming an interior initial point.

Method Summary

interior_x0(*mm*, *nm*, *dm*, *x0*)

mp.mme_line3p_opf

class mp.**mme_line3p_opf**

Bases: *mp.mme_line3p* (page 197)

mp.mme_line3p_opf (page 200) - Math model element for 3-phase line for OPF.

Math model element class for 3-phase line elements for OPF problems.

Implements (currently empty) method for forming an interior initial point.

Method Summary

interior_x0(*mm*, *nm*, *dm*, *x0*)

mp.mme_xfmr3p_opf

class mp.**mme_xfmr3p_opf**

Bases: *mp.mme_xfmr3p* (page 197)

mp.mme_xfmr3p_opf (page 200) - Math model element for 3-phase transformer for OPF.

Math model element class for 3-phase transformer elements for OPF problems.

Implements (currently empty) method for forming an interior initial point.

Method Summary

interior_x0(*mm*, *nm*, *dm*, *x0*)

mp.mme_buslink_opf

class mp.**mme_buslink_opf**

Bases: *mp.mme_buslink* (page 198)

mp.mme_buslink_opf (page 201) - Math model element abstract base class for 1-to-3-phase buslink for OPF.

Abstract math model element base class for 1-to-3-phase buslink elements for OPF problems.

Implements (currently empty) method for forming an interior initial point.

Method Summary

interior_x0(*mm*, *nm*, *dm*, *x0*)

mp.mme_buslink_opf_acc

class mp.**mme_buslink_opf_acc**

Bases: *mp.mme_buslink_opf* (page 201)

mp.mme_buslink_opf_acc (page 201) - Math model element for 1-to-3-phase buslink for AC cartesian voltage OPF.

Math model element class for 1-to-3-phase buslink elements for AC cartesian OPF problems.

Implements methods for adding constraints to match voltages across each buslink.

Method Summary

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

va_fcn(*nme*, *xx*, *A*, *b*)

va_hess(*nme*, *xx*, *lam*, *A*)

vm2_fcn(*nme*, *xx*, *A*, *b*)

vm2_hess(*nme*, *xx*, *lam*, *A*)

mp.mme_buslink_opf_acp

class mp.**mme_buslink_opf_acp**

Bases: *mp.mme_buslink_opf* (page 201)

mp.mme_buslink_opf_acp (page 201) - Math model element for 1-to-3-phase buslink for AC polar voltage OPF.

Math model element class for 1-to-3-phase buslink elements for AC polar OPF problems.

Implements method for adding constraints to match voltages across each buslink.

Method Summary

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

3.7.4 Legacy DC Line Extension

mp.xt_legacy_dcline

class mp.**xt_legacy_dcline**

Bases: *mp.extension* (page 170)

mp.xt_legacy_dcline (page 202) - MATPOWER extension to add legacy DC line elements.

For AC and DC power flow, continuation power flow, and optimial power flow problems, adds a new element type:

- 'legacy_dcline' - legacy DC line

No changes are required for the task or container classes, so only the ..._element_classes methods are overridden.

The set of data model element classes depends on the task, with each OPF class inheriting from the corresponding class used for PF and CPF.

The set of network model element classes depends on the formulation, specifically whether cartesian or polar representations are used for voltages.

And the set of mathematical model element classes depends on both the task and the formulation.

mp.xt_legacy_dcline Methods:

- *dmc_element_classes()* (page 202) - add a class to data model converter elements
- *dm_element_classes()* (page 202) - add a class to data model elements
- *nm_element_classes()* (page 202) - add a class to network model elements
- *mm_element_classes()* (page 203) - add a class to mathematical model elements

See the sec_customizing and sec_extensions sections in the *MATPOWER Developer's Manual* for more information, and specifically the sec_element_classes section and the tab_element_class_modifiers table for details on *element class modifiers*.

See also *mp.extension* (page 170).

Method Summary

dmc_element_classes(*dmc_class*, *fmt*, *mpopt*)

Add a class to data model converter elements.

For 'mpc2 data formats, adds the classes:
- *mp.dmce_legacy_dcline_mpc2* (page 203)

dm_element_classes(*dm_class*, *task_tag*, *mpopt*)

Add a class to data model elements.

For 'PF' and 'CPF' tasks, adds the class:
- *mp.dme_legacy_dcline* (page 204)

For 'OPF' tasks, adds the class:
- *mp.dme_legacy_dcline_opf* (page 206)

nm_element_classes(*nm_class*, *task_tag*, *mpopt*)

Add a class to network model elements.

For DC formulations, adds the class:

- *mp.nme_legacy_dcline_dc* (page 208)

For AC *cartesian* voltage formulations, adds the class:

- *mp.nme_legacy_dcline_acc* (page 208)

For AC *polar* voltage formulations, adds the class:

- *mp.nme_legacy_dcline_acp* (page 208)

mm_element_classes(*mm_class*, *task_tag*, *mpopt*)

Add a class to mathematical model elements.

For 'PF' and 'CPF' tasks, adds the class:

- *mp.mme_legacy_dcline_pf_dc* (page 209) *(DC formulation)* or
- *mp.mme_legacy_dcline_pf_ac* (page 209) *(AC formulation)*

For 'OPF' tasks, adds the class:

- *mp.mme_legacy_dcline_opf_dc* (page 210) *(DC formulation)* or
- *mp.mme_legacy_dcline_opf_ac* (page 210) *(AC formulation)*

Data model converter element class belonging to *mp.xt_legacy_dcline* (page 202) extension:

mp.dmce_legacy_dcline_mpc2

class mp.**dmce_legacy_dcline_mpc2**

Bases: *mp.dmc_element* (page 62)

mp.dmce_legacy_dcline_mpc2 (page 203) - Data model converter element for legacy DC line for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

default_export_data_table(*spec*)

dcline_cost_import(*mpc*, *spec*, *vn*)

dcline_cost_export(*dme*, *mpc*, *spec*, *vn*, *ridx*)

Data model element classes belonging to *mp.xt_legacy_dcline* (page 202) extension:

mp.dme_legacy_dcline

class `mp.dme_legacy_dcline`

Bases: `mp.dm_element` (page 35)

`mp.dme_legacy_dcline` (page 204) - Data model element for legacy DC line.

Implements the data element model for legacy DC line elements, with linear line losses.

$$p_{\mathrm{loss}} = l_0 + l_1 p_{\mathrm{fr}}$$

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
`bus_fr`	*integer*	bus ID (`uid`) of "from" bus
`bus_to`	*integer*	bus ID (`uid`) of "to" bus
`loss0`	*double*	l_0, constant term of loss function (MW)
`loss1`	*double*	l_1, linear coefficient of loss function (MW/MW)
`vm_setpoint_fr`	*double*	per unit "from" bus voltage magnitude setpoint
`vm_setpoint_to`	*double*	per unit "to" bus voltage magnitude setpoint
`p_fr_lb`	*double*	lower bound on MW flow at "from" port
`p_fr_ub`	*double*	upper bound on MW flow at "from" port
`q_fr_lb`	*double*	lower bound on MVAr injection into "from" bus
`q_fr_ub`	*double*	upper bound on MVAr injection into "from" bus
`q_to_lb`	*double*	lower bound on MVAr injection into "to" bus
`q_to_ub`	*double*	upper bound on MVAr injection into "to" bus
`p_fr`	*double*	MW flow at "from" end ("from" –> "to")
`q_fr`	*double*	MVAr injection into "from" bus
`p_to`	*double*	MW flow at "to" end ("from" –> "to")
`q_to`	*double*	MVAr injection into "to" bus

Property Summary

`fbus`

bus index vector for "from" port (port 1) (all DC lines)

`tbus`

bus index vector for "to" port (port 2) (all DC lines)

`fbus_on`

vector of "from" bus indices into online buses (in-service DC lines)

`tbus_on`

vector of "to" bus indices into online buses (in-service DC lines)

`loss0`

constant term of loss function (p.u.) (in-service DC lines)

`loss1`

linear coefficient of loss function (in-service DC lines)

`p_fr_start`

initial active power (p.u.) at "from" port (in-service DC lines)

`p_to_start`

initial active power (p.u.) at "to" port (in-service DC lines)

q_fr_start
initial reactive power (p.u.) at "from" port (in-service DC lines)

q_to_start
initial reactive power (p.u.) at "to" port (in-service DC lines)

vm_setpoint_fr
from bus voltage magnitude setpoint (p.u.) (in-service DC lines)

vm_setpoint_to
to bus voltage magnitude setpoint (p.u.) (in-service DC lines)

p_fr_lb
p.u. lower bound on active power flow at "from" port (in-service DC lines)

p_fr_ub
p.u. upper bound on active power flow at "from" port (in-service DC lines)

q_fr_lb
p.u. lower bound on reactive power flow at "from" port (in-service DC lines)

q_fr_ub
p.u. upper bound on reactive power flow at "from" port (in-service DC lines)

q_to_lb
p.u. lower bound on reactive power flow at "to" port (in-service DC lines)

q_to_ub
p.u. upper bound on reactive power flow at "to" port (in-service DC lines)

Method Summary

name()

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

export_vars()

export_vars_offline_val()

have_cost()

initialize(*dm*)

update_status(*dm*)

apply_vm_setpoints(*dm*)

build_params(*dm*)

pp_have_section_sum(*mpopt*, *pp_args*)

pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_legacy_dcline_opf

class mp.**dme_legacy_dcline_opf**

Bases: `mp.dme_legacy_dcline` (page 204), `mp.dme_shared_opf` (page 58)

`mp.dme_legacy_dcline_opf` (page 206) - Data model element for legacy DC line for OPF.

To parent class `mp.dme_legacy_dcline` (page 204), adds costs, shadow prices on active and reactive flow limits, and pretty-printing for **lim** sections.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
`cost_pg`	*mp.cost_table*	cost of active power flow *(u/MW)*[1]
`mu_p_fr_lb`	*double*	shadow price on MW flow lower bound at “from” end *(u/MW)*[1]
`mu_p_fr_ub`	*double*	shadow price on MW flow upper bound at “from” end *(u/MW)*[1]
`mu_q_fr_lb`	*double*	shadow price on lower bound of MVAr injection at “from” bus *(u/degree)*[1]
`mu_q_fr_ub`	*double*	shadow price on upper bound of MVAr injection at “from” bus *(u/degree)*[1]
`mu_q_to_lb`	*double*	shadow price on lower bound of MVAr injection at “to” bus *(u/degree)*[1]
`mu_q_to_ub`	*double*	shadow price on upper bound of MVAr injection at “to” bus *(u/degree)*[1]

Method Summary

main_table_var_names()

export_vars()

export_vars_offline_val()

have_cost()

build_cost_params(*dm*)

pretty_print(*dm*, *section*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_lim(*mpopt*, *pp_args*)

pp_binding_rows_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

[1] Here *u* denotes the units of the objective function, e.g. USD.

pp_get_headers_lim(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_lim(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

Network model element classes belonging to `mp.xt_legacy_dcline` (page 202) extension:

mp.nme_legacy_dcline

class mp.**nme_legacy_dcline**

Bases: *mp.nm_element* (page 107)

mp.nme_legacy_dcline (page 207) - Network model element abstract base class for legacy DC line.

Implements the network model element for legacy DC line elements, with 2 ports and 2 non-voltage states per DC line.

Method Summary

name()

np()

nz()

mp.nme_legacy_dcline_ac

class mp.**nme_legacy_dcline_ac**

Bases: *mp.nme_legacy_dcline* (page 207)

mp.nme_legacy_dcline_ac (page 207) - Network model element abstract base class for legacy DC line for AC formulation.

Adds non-voltage state variables `Pdcf`, `Qdcf`, `Pdct`, and `Qdct` to the network model and builds the parameter $\underline{\mathbf{N}}$.

Method Summary

add_zvars(*nm*, *dm*, *idx*)

build_params(*nm*, *dm*)

mp.nme_legacy_dcline_acc

class mp.**nme_legacy_dcline_acc**

Bases: *mp.nme_legacy_dcline_ac* (page 207), *mp.form_acc* (page 82)

mp.nme_legacy_dcline_acc (page 208) - Network model element for legacy DC line for for AC cartesian voltage formulations.

Inherits from *mp.form_acc* (page 82).

mp.nme_legacy_dcline_acp

class mp.**nme_legacy_dcline_acp**

Bases: *mp.nme_legacy_dcline_ac* (page 207), *mp.form_acp* (page 86)

mp.nme_legacy_dcline_acp (page 208) - Network model element for legacy DC line for for AC polar voltage formulations.

Inherits from *mp.form_acp* (page 86).

mp.nme_legacy_dcline_dc

class mp.**nme_legacy_dcline_dc**

Bases: *mp.nme_legacy_dcline* (page 207), *mp.form_dc* (page 88)

mp.nme_legacy_dcline_dc (page 208) - Network model element for legacy DC line for DC formulation.

Adds non-voltage state variables `Pdcf` and `Pdct` to the network model and builds the parameter $\underline{\boldsymbol{K}}$.

Method Summary

add_zvars(*nm*, *dm*, *idx*)

build_params(*nm*, *dm*)

Mathematical model element classes belonging to *mp.xt_legacy_dcline* (page 202) extension:

mp.mme_legacy_dcline

class mp.**mme_legacy_dcline**

Bases: *mp.mm_element* (page 143)

mp.mme_legacy_dcline (page 208) - Math model element abstract base class for legacy DC line.

Abstract math model element base class for legacy DC line elements.

Method Summary

name()

mp.mme_legacy_dcline_pf_ac

class mp.**mme_legacy_dcline_pf_ac**

Bases: *mp.mme_legacy_dcline* (page 208)

mp.mme_legacy_dcline_pf_ac (page 209) - Math model element for legacy DC line for AC power flow.

Math model element class for legacy DC line elements for AC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service DC lines from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_legacy_dcline_pf_dc

class mp.**mme_legacy_dcline_pf_dc**

Bases: *mp.mme_legacy_dcline* (page 208)

mp.mme_legacy_dcline_pf_dc (page 209) - Math model element for legacy DC line for DC power flow.

Math model element class for legacy DC line elements for DC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service DC lines from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_legacy_dcline_opf

class mp.**mme_legacy_dcline_opf**

Bases: *mp.mme_legacy_dcline* (page 208)

mp.mme_legacy_dcline_opf (page 209) - Math model element abstract base class for legacy DC line for OPF.

Math model element abstract base class for legacy DC line elements for OPF problems.

Implements methods to add costs, including piecewise linear cost variables, and to form an interior initial point for cost variables.

Property Summary

cost

struct for *cost* (page 209) parameters with fields:

- poly - polynomial costs for active power, struct with fields:
  - have_quad_cost
  - i0, i1, i2, i3
  - k, c, Q

- pwl - piecewise linear costs for actve power, struct with fields:
  - n, i, A, b

Method Summary

build_cost_params(*dm*)

add_vars(*mm*, *nm*, *dm*, *mpopt*)

add_constraints(*mm*, *nm*, *dm*, *mpopt*)

add_costs(*mm*, *nm*, *dm*, *mpopt*)

interior_x0(*mm*, *nm*, *dm*, *x0*)

mp.mme_legacy_dcline_opf_ac

class mp.**mme_legacy_dcline_opf_ac**

Bases: *mp.mme_legacy_dcline_opf* (page 209)

mp.mme_legacy_dcline_opf_ac (page 210) - Math model element for legacy DC line for AC OPF.

Math model element class for legacy DC line elements for AC OPF problems.

Implements method for updating the output data in the corresponding data model element for in-service DC lines from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

mp.mme_legacy_dcline_opf_dc

class mp.**mme_legacy_dcline_opf_dc**

Bases: *mp.mme_legacy_dcline_opf* (page 209)

mp.mme_legacy_dcline_opf_dc (page 210) - Math model element for legacy DC line for DC OPF.

Math model element class for legacy DC line elements for DC OPF problems.

Implements method for updating the output data in the corresponding data model element for in-service DC lines from the math model solution.

Method Summary

data_model_update_on(*mm*, *nm*, *dm*, *mpopt*)

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