



MATPOWER Reference Manual

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Contents

1	Introduction	1
2	Functions	3
2.1	Top-Level Simulation Functions	3
2.2	Other Functions	6
3	Classes	7
3.1	Task Classes	7
3.2	Data Model Classes	27
3.3	Data Model Converter Classes	58
3.4	Network Model Classes	71
3.5	Mathematical Model Classes	121
3.6	Miscellaneous Classes	156
3.7	MATPOWER Extension Classes	170
4	Tests	211
4.1	MATPOWER Tests	211
4.2	MATPOWER Test Data	214
5	Legacy	217
5.1	Legacy Class	217
5.2	Legacy Functions	223
5.3	Legacy Tests	369
	Index	383

The purpose of this *Reference Manual* is to provide reference documentation on each class and function in MATPOWER. This documentation is automatically generated from the corresponding help text in the Matlab source for each function, class, property or method.

The GitHub icon in the upper right of each reference page links to the corresponding source file in the master branch on GitHub.

Currently, this manual includes *only* classes and functions that make up the new **MP-Core** and the **flexible** and **legacy** MATPOWER frameworks, but not the other legacy MATPOWER functions or the included packages [MP-Opt-Model](#), [MIPS](#), [MP-Test](#), or [MOST](#).

2.1 Top-Level Simulation Functions

These are top-level functions intended as user commands for running power flow (PF), continuation power flow (CPF), optimal power flow (OPF) and other custom simulation or optimization tasks.

2.1.1 run_mp

`run_mp(task_class, d, mpopt, varargin)`

[`run_mp\(\)`](#) (page 3) - Run any MATPOWER simulation.

```
run_mp(task_class, d, mpopt)
run_mp(task_class, d, mpopt, ...)
task = run_mp(...)
```

This is **the** main function in the **flexible framework** for running MATPOWER. It creates the task object, applying any specified extensions, runs the task, and prints or saves the solution, if desired.

It is typically called from one of the wrapper functions such as [`run_pf\(\)`](#) (page 4), [`run_cpf\(\)`](#) (page 5), or [`run_opf\(\)`](#) (page 5).

Inputs

- **task_class** (*function handle*) – handle to constructor of default task class for type of task to be run, e.g. [`mp.task_pf`](#) (page 18) for power flow, [`mp.task_cpf`](#) (page 20) for CPF, and [`mp.task_opf`](#) (page 21) for OPF
- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct

Additional optional inputs can be provided as `<name>`, `<val>` pairs, with the following options:

- `'print_fname'` - file name for saving pretty-printed output
- `'soln_fname'` - file name for saving solved case

- 'mpx' - MATPOWER extension or cell array of MATPOWER extensions to apply

Output

task (*mp.task* (page 7)) – task object containing the solved run including the data, network, and mathematical model objects.

Solution results are available in the data model, and its elements, contained in the returned task object. For example:

```
task = run_opf('case9');  
lam_p = task.dm.elements.bus.tab.lam_p    % nodal price  
pg = task.dm.elements.gen.tab.pg          % generator active dispatch
```

See also *run_pf()* (page 4), *run_cpf()* (page 5), *run_opf()* (page 5), *mp.task* (page 7).

2.1.2 run_pf

run_pf(*varargin*)

run_pf() (page 4) - Run a power flow.

```
run_pf(d, mpopt)  
run_pf(d, mpopt, ...)  
task = run_pf(...)
```

This is the main function used to run power flow (PF) problems via the **flexible MATPOWER framework**.

This function is a simple wrapper around *run_mp()* (page 3), calling it with the first argument set to @mp.task_pf.

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (mpc)
- **mpopt** (*struct*) – MATPOWER options struct

Additional optional inputs can be provided as <name>, <val> pairs, with the following options:

- 'print_fname' - file name for saving pretty-printed output
- 'soln_fname' - file name for saving solved case
- 'mpx' - MATPOWER extension or cell array of MATPOWER extensions to apply

Output

task (*mp.task_pf* (page 18)) – task object containing the solved run including the data, network, and mathematical model objects.

Solution results are available in the data model, and its elements, contained in the returned task object. For example:

```
task = run_pf('case9');  
va = task.dm.elements.bus.tab.va          % bus voltage angles  
pg = task.dm.elements.gen.tab.pg          % generator active dispatch
```

See also *run_mp()* (page 3), *mp.task_pf* (page 18).

2.1.3 run_cpf

run_cpf(varargin)

[run_cpf\(\)](#) (page 5) Run a continuation power flow.

```
run_cpf(d, mpopt)
run_cpf(d, mpopt, ...)
task = run_cpf(...)
```

This is the main function used to run continuation power flow (CPF) problems via the **flexible MATPOWER framework**.

This function is a simple wrapper around [run_mp\(\)](#) (page 3), calling it with the first argument set to @mp.task_cpf.

Inputs

- **d** – data source specification, currently assumed to be a cell array of two MATPOWER case names or case structs (mpc), the first being the base case, the second the target case
- **mpopt** (*struct*) – MATPOWER options struct

Additional optional inputs can be provided as <name>, <val> pairs, with the following options:

- 'print_fname' - file name for saving pretty-printed output
- 'soln_fname' - file name for saving solved case
- 'mpx' - MATPOWER extension or cell array of MATPOWER extensions to apply

Output

task ([mp.task_cpf](#) (page 20)) – task object containing the solved run including the data, network, and mathematical model objects.

Solution results are available in the data model, and its elements, contained in the returned task object. For example:

```
task = run_cpf({'case9', 'case9target'});
vm = task.dm.elements.bus.tab.vm      % bus voltage magnitudes
pg = task.dm.elements.gen.tab.pg      % generator active dispatch
```

See also [run_mp\(\)](#) (page 3), [mp.task_cpf](#) (page 20).

2.1.4 run_opf

run_opf(varargin)

[run_opf\(\)](#) (page 5) Run an optimal power flow.

```
run_opf(d, mpopt)
run_opf(d, mpopt, ...)
task = run_opf(...)
```

This is the main function used to run optimal power flow (OPF) problems via the **flexible MATPOWER framework**.

This function is a simple wrapper around `run_mp()` (page 3), calling it with the first argument set to `@mp.taskopf`.

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (mpc)

- **mpopt** (*struct*) – MATPOWER options struct

Additional optional inputs can be provided as `<name>`, `<val>` pairs, with the following options:

- 'print_fname' - file name for saving pretty-printed output
- 'soln_fname' - file name for saving solved case
- 'mpx' - MATPOWER extension or cell array of MATPOWER extensions to apply

Output

task (`mp.taskopf` (page 21)) – task object containing the solved run including the data, network, and mathematical model objects.

Solution results are available in the data model, and its elements, contained in the returned task object. For example:

```
task = run_opf('case9');  
lam_p = task.dm.elements.bus.tab.lam_p    % nodal price  
pg = task.dm.elements.gen.tab.pg          % generator active dispatch
```

See also `run_mp()` (page 3), `mp.taskopf` (page 21).

2.2 Other Functions

2.2.1 mp_table_class

`mp_table_class()`

`mp_table_class()` (page 6) - Returns handle to constructor for `table` or `mp_table` (page 156).

Returns a handle to `table` constructor, if it is available, otherwise to `mp_table` (page 156) constructor. Useful for table-based code that is compatible with both MATLAB (using native tables) and Octave (using `mp_table` (page 156) or the `table` implementation from Tablicious, if available).

```
% Works in MATLAB or Octave, which does not (yet) natively support table().  
table_class = mp_table_class();  
T = table_class(var1, var2, ...);
```

See also `table`, `mp_table` (page 156).

3.1 Task Classes

3.1.1 Core Task Classes

`mp.task`

class `mp.task`

Bases: `handle`

`mp.task` (page 7) - MATPOWER task abstract base class.

Each task type (e.g. power flow, CPF, OPF) will inherit from `mp.task` (page 7).

Provides properties and methods related to the specific problem specification being solved (e.g. power flow, continuation power flow, optimal power flow, etc.). In particular, it coordinates all interactions between the 3 (data, network, mathematical) model layers.

The model objects, and indirectly their elements, as well as the solution success flag and messages from the mathematical model solver, are available in the properties of the task object.

`mp.task` Properties:

- `tag` (page 9) - task tag - e.g. 'PF', 'CPF', 'OPF'
- `name` (page 9) - task name - e.g. 'Power Flow', etc.
- `dmc` (page 9) - data model converter object
- `dm` (page 9) - data model object
- `nm` (page 9) - network model object
- `mm` (page 9) - mathematical model object
- `mm_opt` (page 9) - solve options for mathematical model
- `i_dm` (page 9) - iteration counter for data model loop
- `i_nm` (page 9) - iteration counter for network model loop

- `i_mm` (page 9) - iteration counter for math model loop
- `success` (page 9) - success flag, 1 - math model solved, 0 - didn't solve
- `message` (page 9) - output message
- `et` (page 9) - elapsed time (seconds) for `run()` (page 9) method

mp.task Methods:

- `run()` (page 9) - execute the task
- `next_mm()` (page 10) - controls iterations over mathematical models
- `next_nm()` (page 10) - controls iterations over network models
- `next_dm()` (page 10) - controls iterations over data models
- `run_pre()` (page 11) - called at beginning of `run()` (page 9) method
- `run_post()` (page 11) - called at end of `run()` (page 9) method
- `print_soln()` (page 11) - display pretty-printed results
- `print_soln_header()` (page 11) - display success/failure, elapsed time
- `save_soln()` (page 12) - save solved case to file
- `dm_converter_class()` (page 12) - get data model converter constructor
- `dm_converter_class_mpc2_default()` (page 12) - get default data model converter constructor
- `dm_converter_create()` (page 12) - create data model converter object
- `data_model_class()` (page 13) - get data model constructor
- `data_model_class_default()` (page 13) - get default data model constructor
- `data_model_create()` (page 13) - create data model object
- `data_model_build()` (page 14) - create and build data model object
- `data_model_build_pre()` (page 14) - called at beginning of `data_model_build()` (page 14)
- `data_model_build_post()` (page 14) - called at end of `data_model_build()` (page 14)
- `network_model_class()` (page 14) - get network model constructor
- `network_model_class_default()` (page 15) - get default network model constructor
- `network_model_create()` (page 15) - create network model object
- `network_model_build()` (page 15) - create and build network model object
- `network_model_build_pre()` (page 15) - called at beginning of `network_model_build()` (page 15)
- `network_model_build_post()` (page 16) - called at end of `network_model_build()` (page 15)
- `network_model_x_soln()` (page 16) - update network model state from math model solution
- `network_model_update()` (page 16) - update net model state/soln from math model soln
- `math_model_class()` (page 16) - get mathematical model constructor
- `math_model_class_default()` (page 17) - get default mathematical model constructor
- `math_model_create()` (page 17) - create mathematical model object
- `math_model_build()` (page 17) - create and build mathematical model object

- `math_model_opt()` (page 18) - get options struct to pass to `mm.solve()`

See the `sec_task` section in the *MATPOWER Developer's Manual* for more information.

See also `mp.data_model` (page 27), `mp.net_model` (page 90), `mp.math_model` (page 121), `mp.dm_converter` (page 59).

Property Summary

tag

(*char array*) task `tag` (page 9) - e.g. 'PF', 'CPF', 'OPF'

name

(*char array*) task `name` (page 9) - e.g. 'Power Flow', etc.

dmc

(`mp.dm_converter` (page 59)) data model converter object

dm

(`mp.data_model` (page 27)) data model object

nm

(`mp.net_model` (page 90)) network model object

mm

(`mp.math_model` (page 121)) mathematical model object

mm_opt

(*struct*) solve options for mathematical model

i_dm

(*integer*) iteration counter for data model loop

i_nm

(*integer*) iteration counter for network model loop

i_mm

(*integer*) iteration counter for math model loop

success

(*integer*) `success` (page 9) flag, 1 - math model solved, 0 - didn't solve

message

(*char array*) output `message` (page 9)

et

(*double*) elapsed time (seconds) for `run()` (page 9) method

Method Summary

run(d, mpopt, mpx)

Execute the task.

```
task.run(d, mpopt)
task.run(d, mpopt, mpx)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)

- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

task ([mp.task](#) (page 7)) – task object containing the solved [run\(\)](#) (page 9) including the data, network, and mathematical model objects.

Execute the task, creating the data model converter and the data, network and mathematical model objects, solving the math model and propagating the solution back to the data model.

See the `sec_task` section in the [MATPOWER Developer's Manual](#) for more information.

next_mm(*mm, nm, dm, mpopt, mpx*)

Controls iterations over mathematical models.

```
[mm, nm, dm] = task.next_mm(mm, nm, dm, mpopt, mpx)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

- **mm** ([mp.math_model](#) (page 121)) – new or updated mathematical model object, or empty matrix
- **nm** ([mp.net_model](#) (page 90)) – potentially updated network model object
- **dm** ([mp.data_model](#) (page 27)) – potentially updated data model object

Called automatically by [run\(\)](#) (page 9) method. Subclasses can override this method to return a new or updated math model object for use in the next iteration or an empty matrix (the default) if finished.

next_nm(*mm, nm, dm, mpopt, mpx*)

Controls iterations over network models.

```
[nm, dm] = task.next_nm(mm, nm, dm, mpopt, mpx)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

- **nm** ([mp.net_model](#) (page 90)) – new or updated network model object, or empty matrix
- **dm** ([mp.data_model](#) (page 27)) – potentially updated data model object

Called automatically by [run\(\)](#) (page 9) method. Subclasses can override this method to return a new or updated network model object for use in the next iteration or an empty matrix (the default) if finished.

next_dm(*mm, nm, dm, mpopt, mpx*)

Controls iterations over data models.

```
dm = task.next_dm(mm, nm, dm, mpopt, mpx)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object

- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

dm ([mp.data_model](#) (page 27)) – new or updated data model object, or empty matrix

Called automatically by [run\(\)](#) (page 9) method. Subclasses can override this method to return a new or updated data model object for use in the next iteration or an empty matrix (the default) if finished.

run_pre(d, mpopt)

Called at beginning of [run\(\)](#) (page 9) method.

```
[d, mpopt] = task.run_pre(d, mpopt)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (**mpc**)
- **mpopt** (*struct*) – MATPOWER options struct

Outputs

- **d** – updated value of corresponding input
- **mpopt** (*struct*) – updated value of corresponding input

Subclasses can override this method to update the input data or options before beginning the run.

run_post(mm, nm, dm, mpopt)

Called at end of [run\(\)](#) (page 9) method.

```
task.run_post(mm, nm, dm, mpopt)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

task ([mp.task](#) (page 7)) – task object

Subclasses can override this method to do any final processing after the run is complete.

print_soln(mpop, fname)

Display the pretty-printed results.

```
task.print_soln(mpop)
task.print_soln(mpop, fname)
```

Inputs

- **mpopt** (*struct*) – MATPOWER options struct
- **fname** (*char array*) – file name for saving pretty-printed output

Display to standard output and/or save to a file the pretty-printed solved case.

print_soln_header(mpop, fd)

Display solution header information.

```
task.print_soln_header(mpop, fd)
```

Inputs

- **mpopt** (*struct*) – MATPOWER options struct

- **fd** (*integer*) – file identifier (1 for standard output)

Called by [print_soln\(\)](#) (page 11) to print success/failure, elapsed time, etc. to a file identifier.

save_soln(fname)

Save the solved case to a file.

```
task.save_soln(fname)
```

Input

fname (*char array*) – file name for saving solved case

dm_converter_class(d, mpopt, mpx)

Get data model converter constructor.

```
dmc_class = task.dm_converter_class(d, mpopt, mpx)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (*mpc*)
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

dmc_class (*function handle*) – handle to the constructor to be used to instantiate the data model converter object

Called by [dm_converter_create\(\)](#) (page 12) to determine the class to use for the data model converter object. Handles any modifications specified by MATPOWER options or extensions.

dm_converter_class_mpc2_default()

Get default data model converter constructor.

```
dmc_class = task.dm_converter_class_mpc2_default()
```

Output

dmc_class (*function handle*) – handle to default constructor to be used to instantiate the data model converter object

Called by [dm_converter_class\(\)](#) (page 12) to determine the default class to use for the data model converter object when the input is a version 2 MATPOWER case struct.

dm_converter_create(d, mpopt, mpx)

Create data model converter object.

```
dmc = task.dm_converter_create(d, mpopt, mpx)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (*mpc*)
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

dmc ([mp.dm_converter](#) (page 59)) – data model converter object, ready to build

Called by [dm_converter_build\(\)](#) (page 12) method to instantiate the data model converter object. Handles any modifications to data model converter elements specified by MATPOWER options or extensions.

dm_converter_build(*d*, *mpopt*, *mpx*)

Create and build data model converter object.

```
dmc = task.dm_converter_build(d, mpopt, mpx)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

dmc ([mp.dm_converter](#) (page 59)) – data model converter object, ready for use

Called by [run\(\)](#) (page 9) method to instantiate and build the data model converter object, including any modifications specified by MATPOWER options or extensions.

data_model_class(*d*, *mpopt*, *mpx*)

Get data model constructor.

```
dm_class = task.data_model_class(d, mpopt, mpx)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

dm_class (*function handle*) – handle to the constructor to be used to instantiate the data model object

Called by [data_model_create\(\)](#) (page 13) to determine the class to use for the data model object. Handles any modifications specified by MATPOWER options or extensions.

data_model_class_default()

Get default data model constructor.

```
dm_class = task.data_model_class_default()
```

Output

dm_class (*function handle*) – handle to default constructor to be used to instantiate the data model object

Called by [data_model_class\(\)](#) (page 13) to determine the default class to use for the data model object.

data_model_create(*d*, *mpopt*, *mpx*)

Create data model object.

```
dm = task.data_model_create(d, mpopt, mpx)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

dm ([mp.data_model](#) (page 27)) – data model object, ready to build

Called by `data_model_build()` (page 14) to instantiate the data model object. Handles any modifications to data model elements specified by MATPOWER options or extensions.

data_model_build(*d*, *dmc*, *mpopt*, *mpx*)

Create and build data model object.

```
dm = task.data_model_create(d, dmc, mpopt, mpx)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **dmc** (`mp.dm_converter` (page 59)) – data model converter object
- **mpopt** (`struct`) – MATPOWER options struct
- **mpx** (cell array of `mp.extension` (page 170)) – MATPOWER Extensions

Output

dm (`mp.data_model` (page 27)) – data model object, ready for use

Called by `run()` (page 9) method to instantiate and build the data model object, including any modifications specified by MATPOWER options or extensions.

data_model_build_pre(*dm*, *d*, *dmc*, *mpopt*)

Called at beginning of `data_model_build()` (page 14).

```
[dm, d] = task.data_model_build_pre(dm, d, dmc, mpopt)
```

Inputs

- **dm** (`mp.data_model` (page 27)) – data model object
- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **dmc** (`mp.dm_converter` (page 59)) – data model converter object
- **mpopt** (`struct`) – MATPOWER options struct

Outputs

- **dm** (`mp.data_model` (page 27)) – updated data model object
- **d** – updated value of corresponding input

Called just *before* calling the data model's `build()` method. In this base class, this method does nothing.

data_model_build_post(*dm*, *dmc*, *mpopt*)

Called at end of `data_model_build()` (page 14).

```
dm = task.data_model_build_post(dm, dmc, mpopt)
```

Inputs

- **dm** (`mp.data_model` (page 27)) – data model object
- **dmc** (`mp.dm_converter` (page 59)) – data model converter object
- **mpopt** (`struct`) – MATPOWER options struct

Output

dm (`mp.data_model` (page 27)) – updated data model object

Called just *after* calling the data model's `build()` method. In this base class, this method does nothing.

network_model_class(*dm*, *mpopt*, *mpx*)

Get network model constructor.

```
nm_class = task.network_model_class(dm, mpopt, mpx)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

nm_class (*function handle*) – handle to the constructor to be used to instantiate the network model object

Called by [network_model_create\(\)](#) (page 15) to determine the class to use for the network model object. Handles any modifications specified by MATPOWER options or extensions.

network_model_class_default(*dm, mpopt*)

Get default network model constructor.

```
nm_class = task.network_model_class_default(dm, mpopt)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

nm_class (*function handle*) – handle to default constructor to be used to instantiate the network model object

Called by [network_model_class\(\)](#) (page 14) to determine the default class to use for the network model object.

Note: This is an abstract method that must be implemented by a subclass.

network_model_create(*dm, mpopt, mpx*)

Create network model object.

```
nm = task.network_model_create(dm, mpopt, mpx)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

nm ([mp.net_model](#) (page 90)) – network model object, ready to build

Called by [network_model_build\(\)](#) (page 15) to instantiate the network model object. Handles any modifications to network model elements specified by MATPOWER options or extensions.

network_model_build(*dm, mpopt, mpx*)

Create and build network model object.

```
nm = task.network_model_build(dm, mpopt, mpx)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

nm ([mp.net_model](#) (page 90)) – network model object, ready for use

Called by [run\(\)](#) (page 9) method to instantiate and build the network model object, including any modifications specified by MATPOWER options or extensions.

network_model_build_pre(*nm, dm, mpopt*)

Called at beginning of [network_model_build\(\)](#) (page 15).

```
nm = task.network_model_build_pre(nm, dm, mpopt)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

nm ([mp.net_model](#) (page 90)) – updated network model object

Called just *before* calling the network model’s `build()` method. In this base class, this method does nothing.

network_model_build_post(*nm, dm, mpopt*)

Called at end of [network_model_build\(\)](#) (page 15).

```
nm = task.network_model_build_post(nm, dm, mpopt)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

nm ([mp.net_model](#) (page 90)) – updated network model object

Called just *after* calling the network model’s `build()` method. In this base class, this method does nothing.

network_model_x_soln(*mm, nm*)

Update network model state from math model solution.

```
nm = task.network_model_x_soln(mm, nm)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object

Output

nm ([mp.net_model](#) (page 90)) – updated network model object

Called by [network_model_update\(\)](#) (page 16).

network_model_update(*mm, nm*)

Update network model state, solution values from math model solution.

```
nm = task.network_model_update(mm, nm)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object

Output

nm ([mp.net_model](#) (page 90)) – updated network model object

Called by [run\(\)](#) (page 9) method.

math_model_class(*nm*, *dm*, *mpopt*, *mpx*)

Get mathematical model constructor.

```
mm_class = task.math_model_class(nm, dm, mpopt, mpx)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

mm_class (*function handle*) – handle to the constructor to be used to instantiate the mathematical model object

Called by [math_model_create\(\)](#) (page 17) to determine the class to use for the mathematical model object. Handles any modifications specified by MATPOWER options or extensions.

math_model_class_default(*nm*, *dm*, *mpopt*)

Get default mathematical model constructor.

```
mm_class = task.math_model_class_default(nm, dm, mpopt)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

mm_class (*function handle*) – handle to the constructor to be used to instantiate the mathematical model object

Called by [math_model_class\(\)](#) (page 16) to determine the default class to use for the mathematical model object.

Note: This is an abstract method that must be implemented by a subclass.

math_model_create(*nm*, *dm*, *mpopt*, *mpx*)

Create mathematical model object.

```
mm = task.math_model_create(nm, dm, mpopt, mpx)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

mm ([mp.math_model](#) (page 121)) – mathematical model object, ready to build

Called by [math_model_build\(\)](#) (page 17) to instantiate the mathematical model object. Handles any modifications to mathematical model elements specified by MATPOWER options or extensions.

math_model_build(*nm*, *dm*, *mpopt*, *mpx*)

Create and build mathematical model object.

```
mm = task.math_model_build(nm, dm, mpopt, mpx)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct
- **mpx** (cell array of [mp.extension](#) (page 170)) – MATPOWER Extensions

Output

mm ([mp.math_model](#) (page 121)) – mathematical model object, ready for use

Called by [run\(\)](#) (page 9) method to instantiate and build the mathematical model object, including any modifications specified by MATPOWER options or extensions.

math_model_opt(*mm, nm, dm, mpopt*)

Get the options struct to pass to `mm.solve()`.

```
opt = task.math_model_opt(mm, nm, dm, mpopt)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

opt (*struct*) – options struct for mathematical model solve() method

Called by [run\(\)](#) (page 9) method.

mp.task_pf

class mp.task_pf

Bases: [mp.task](#) (page 7)

[mp.task_pf](#) (page 18) - MATPOWER task for power flow (PF).

Provides task implementation for the power flow problem.

This includes the handling of iterative runs to enforce generator reactive power limits, if requested.

mp.task_pf Properties:

- [tag](#) (page 19) - task tag 'PF'
- [name](#) (page 19) - task name 'Power Flow'
- [dc](#) (page 19) - true if using DC network model
- [iterations](#) (page 19) - total number of power flow iterations
- [ref](#) (page 19) - current ref node indices
- [ref0](#) (page 19) - initial ref node indices
- [va_ref0](#) (page 19) - initial ref node voltage angles
- [fixed_q_idx](#) (page 19) - indices of fixed Q gens
- [fixed_q_qty](#) (page 19) - Q output of fixed Q gens

mp.task_pf Methods:

- [run_pre\(\)](#) (page 19) - set dc property

- [next_dm\(\)](#) (page 19) - optionally iterate to enforce generator reactive limits
- [enforce_q_lims\(\)](#) (page 19) - implementation of generator reactive limits
- [network_model_class_default\(\)](#) (page 19) - select default network model constructor
- [network_model_build_post\(\)](#) (page 19) - initialize properties for reactive limits
- [network_model_x_soln\(\)](#) (page 19) - correct the voltage angles if necessary
- [math_model_class_default\(\)](#) (page 20) - select default math model constructor

See also [mp.task](#) (page 7).

Property Summary

tag = 'PF'

name = 'Power Flow'

dc
true if using DC network model (from `mpopt.model`, cached in [run_pre\(\)](#) (page 19))

iterations
(integer) total number of power flow [iterations](#) (page 19)

ref
(integer) current [ref](#) (page 19) node indices

ref0
(integer) initial ref node indices

va_ref0
(double) initial ref node voltage angles

fixed_q_idx
(integer) indices of fixed Q gens

fixed_q_qty
(double) Q output of fixed Q gens

Method Summary

run_pre(*d*, *mpopt*)
Set dc property after calling superclass [run_pre\(\)](#) (page 11).

next_dm(*nm*, *nm*, *dm*, *mpopt*, *mpx*)
Implement optional iterations to enforce generator reactive limits.

enforce_q_lims(*nm*, *dm*, *mpopt*)
Used by [next_dm\(\)](#) (page 19) to implement enforcement of generator reactive limits.

network_model_class_default(*dm*, *mpopt*)
Implement selector for default network model constructor depending on `mpopt.model` and `mpopt.pf.v_cartesian`.

network_model_build_post(*nm*, *dm*, *mpopt*)
Initialize [mp.task_pf](#) (page 18) properties, if non-empty AC case with generator reactive limits enforced.

network_model_x_soln(*mm, nm*)

Call superclass [network_model_x_soln\(\)](#) (page 16) then correct the voltage angle if the ref node has been changed.

math_model_class_default(*nm, dm, mpopt*)

Implement selector for default mathematical model constructor depending on `mpopt.model`, `mpopt.pf.v_cartesian`, and `mpopt.pf.current_balance`.

mp.task_cpf**class mp.task_cpf**

Bases: [mp.task_pf](#) (page 18)

[mp.task_cpf](#) (page 20) - MATPOWER task for continuation power flow (CPF).

Provides task implementation for the continuation power flow problem.

This includes the iterative solving of the mathematical model (using warm restarts) after updating the problem data, e.g. when enforcing certain limits.

mp.task_cpf Properties:

- [warmstart](#) (page 20) - warm start data

mp.task_cpf Methods:

- [task_cpf\(\)](#) (page 20) - constructor, inherits from [mp.task_pf](#) (page 18) constructor
- [run_pre\(\)](#) (page 21) - call superclass [run_pre\(\)](#) (page 19) for base and target inputs
- [next_mm\(\)](#) (page 21) - handle warm start of continuation iterations
- [dm_converter_class\(\)](#) (page 21) - select data model converter class
- [data_model_class_default\(\)](#) (page 21) - select default data model constructor
- [data_model_build\(\)](#) (page 21) - build base and target data models
- [network_model_build\(\)](#) (page 21) - build base and target network models
- [network_model_x_soln\(\)](#) (page 21) - update network model solution
- [network_model_update\(\)](#) (page 21) - evaluate port injection solution
- [math_model_class_default\(\)](#) (page 21) - select default math model constructor
- [math_model_opt\(\)](#) (page 21) - add warmstart parameters to math model solve options

See also [mp.task](#) (page 7), [mp.task_pf](#) (page 18).

Constructor Summary**task_cpf()**

Constructor, inherits from [mp.task_pf](#) (page 18) constructor.

Property Summary**warmstart**

(*struct*) warm start data, with fields:

- `clam` - corrector parameter lambda
- `plam` - predictor parameter lambda

- cV - corrector complex voltage vector
- pV - predictor complex voltage vector

Method Summary

run_pre(*d*, *mpopt*)

Call superclass [run_pre\(\)](#) (page 19) for base and target inputs.

next_mm(*mm*, *nm*, *dm*, *mpopt*, *mpx*)

Handle warm start of continuation iterations, after problem data update.

dm_converter_class(*d*, *mpopt*, *mpx*)

Implement selector for data model converter class based on superclass constructor.

data_model_class_default()

Implement selector for default data model constructor.

data_model_build(*d*, *dmc*, *mpopt*, *mpx*)

Call superclass [data_model_build\(\)](#) for base and target models.

network_model_build(*dm*, *mpopt*, *mpx*)

Call superclass [network_model_build\(\)](#) for base and target models.

network_model_x_soln(*mm*, *nm*)

Call superclass [network_model_x_soln\(\)](#) (page 19) then update solution in target network model.

network_model_update(*mm*, *nm*)

Call superclass [network_model_update\(\)](#) then update port injection solution by interpolating with parameter lambda.

math_model_class_default(*nm*, *dm*, *mpopt*)

Implement selector for default mathematical model constructor depending on `mpopt.pf.v_cartesian` and `mpopt.pf.current_balance`.

math_model_opt(*mm*, *nm*, *dm*, *mpopt*)

Call superclass [math_model_opt\(\)](#) then add warmstart parameters, if available.

mp.task_opf

class mp.task_opf

Bases: [mp.task](#) (page 7)

[mp.task_opf](#) (page 21) - MATPOWER task for optimal power flow (OPF).

Provides task implementation for the optimal power flow problem.

mp.task_opf Properties:

- tag - task tag 'OPF'
- name - task name 'Optimal Power Flow'
- dc (page 22) - true if using DC network model

mp.task_opf Methods:

- [run_pre\(\)](#) (page 22) - set dc property
- [print_soln_header\(\)](#) (page 22) - add printout of objective function value

- `data_model_class_default()` (page 22) - select default data model constructor
- `data_model_build_post()` (page 22) - adjust bus voltage limits, if requested
- `network_model_class_default()` (page 22) - select default network model constructor
- `math_model_class_default()` (page 22) - select default math model constructor

See also `mp.task` (page 7).

Property Summary

dc

true if using DC network model (from `mpopt.model`, cached in `run_pre()` (page 22))

Method Summary

run_pre(*d*, *mpopt*)

Set dc property after calling superclass `run_pre()` (page 11), then check for unsupported AC OPF solver selection.

print_soln_header(*mpopt*, *fd*)

Call superclass `print_soln_header()` (page 11) then print out the objective function value.

data_model_class_default()

Implement selector for default data model constructor.

data_model_build_post(*dm*, *dmc*, *mpopt*)

Call superclass `data_model_build_post()` (page 14) then adjust bus voltage magnitude limits based on generator `vm_setpoint`, if requested.

network_model_class_default(*dm*, *mpopt*)

Implement selector for default network model constructor depending on `mpopt.model` and `mpopt.opf.v_cartesian`.

math_model_class_default(*nm*, *dm*, *mpopt*)

Implement selector for default mathematical model constructor depending on `mpopt.model`, `mpopt.opf.v_cartesian`, and `mpopt.opf.current_balance`.

3.1.2 Legacy Task Classes

Used by MP-Core when called by the *legacy MATPOWER framework*.

mp.task_pf_legacy

class mp.task_pf_legacy

Bases: `mp.task_pf` (page 18), `mp.task_shared_legacy` (page 26)

`mp.task_pf_legacy` (page 22) - MATPOWER task for legacy power flow (PF).

Adds functionality needed by the *legacy MATPOWER framework* to the task implementation for the power flow problem. This consists of pre-processing some input data and exporting and packaging result data.

mp.task_pf Methods:

- `run_pre()` (page 23) - pre-process inputs that are for legacy framework only

- [run_post\(\)](#) (page 23) - export results back to data model source
- [legacy_post_run\(\)](#) (page 23) - post-process *legacy framework* outputs

See also [mp.task_pf](#) (page 18), [mp.task](#) (page 7), [mp.task_shared_legacy](#) (page 26).

Method Summary

run_pre(d, mpopt)

Pre-process inputs that are for *legacy framework* only.

```
[d, mpopt] = task.run_pre(d, mpopt)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct

Outputs

- **d** – updated value of corresponding input
- **mpopt** (*struct*) – updated value of corresponding input

Call [run_pre_legacy\(\)](#) (page 27) method before calling parent.

run_post(mm, nm, dm, mpopt)

Export results back to data model source.

```
task.run_post(mm, nm, dm, mpopt)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

task ([mp.task](#) (page 7)) – task object

Calls [mp.dm_converter.export\(\)](#) (page 60) and saves the result in the data model source property.

legacy_post_run(mpop)

Post-process *legacy framework* outputs.

```
[results, success] = task.legacy_post_run(mpop)
```

Input

mpopt (*struct*) – MATPOWER options struct

Outputs

- **results** (*struct*) – results struct for *legacy MATPOWER framework*, see Table 4.1 in [legacy MATPOWER User's Manual](#).
- **success** (*integer*) – 1 - succeeded, 0 - failed

Extract **results** and **success** and save the task object in **results.task** before returning.

mp.task_cpf_legacy

class mp.task_cpf_legacy

Bases: [mp.task_cpf](#) (page 20), [mp.task_shared_legacy](#) (page 26)

[mp.task_cpf](#) (page 20) - MATPOWER task for legacy continuation power flow (CPF).

Adds functionality needed by the *legacy MATPOWER framework* to the task implementation for the continuation power flow problem. This consists of pre-processing some input data and exporting and packaging result data.

mp.task_pf Methods:

- [run_pre\(\)](#) (page 24) - pre-process inputs that are for legacy framework only
- [run_post\(\)](#) (page 24) - export results back to data model source
- [legacy_post_run\(\)](#) (page 24) - post-process *legacy framework* outputs

See also [mp.task_cpf](#) (page 20), [mp.task](#) (page 7), [mp.task_shared_legacy](#) (page 26).

Method Summary

run_pre(d, mpopt)

Pre-process inputs that are for *legacy framework* only.

[d, mpopt] = task.run_pre(d, mpopt)

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (mpc)
- **mpopt** (*struct*) – MATPOWER options struct

Outputs

- **d** – updated value of corresponding input
- **mpopt** (*struct*) – updated value of corresponding input

Call [run_pre_legacy\(\)](#) (page 27) method for both input cases before calling parent.

run_post(mm, nm, dm, mpopt)

Export results back to data model source.

task.run_post(mm, nm, dm, mpopt)

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

task ([mp.task](#) (page 7)) – task object

Calls [mp.dm_converter.export\(\)](#) (page 60) and saves the result in the data model source property.

legacy_post_run(mpop)

Post-process *legacy framework* outputs.

[results, success] = task.legacy_post_run(mpop)

Input

mpopt (*struct*) – MATPOWER options struct

Outputs

- **results** (*struct*) – results struct for *legacy MATPOWER framework*, see Table 5.1 in *legacy MATPOWER User's Manual*.
- **success** (*integer*) – 1 - succeeded, 0 - failed

Extract results and success and save the task object in `results.task` before returning.

mp.task_opf_legacy

class mp.task_opf_legacy

Bases: [mp.task_opf](#) (page 21), [mp.task_shared_legacy](#) (page 26)

[mp.task_opf](#) (page 21) - MATPOWER task for legacy optimal power flow (OPF).

Adds functionality needed by the *legacy MATPOWER framework* to the task implementation for the optimal power flow problem. This consists of pre-processing some input data and exporting and packaging result data, as well as using some legacy specific model sub-classes.

mp.task_opf Methods:

- [run_pre\(\)](#) (page 25) - pre-process inputs that are for legacy framework only
- [run_post\(\)](#) (page 25) - export results back to data model source
- [dm_converter_class_mpc2_default\(\)](#) (page 26) - set to [mp.dm_converter_mpc2_legacy](#) (page 62)
- [data_model_build_post\(\)](#) (page 26) - get data model converter to do more input pre-processing
- [math_model_class_default\(\)](#) (page 26) - use legacy math model subclasses
- [legacy_post_run\(\)](#) (page 26) - post-process *legacy framework* outputs

See also [mp.task_opf](#) (page 21), [mp.task](#) (page 7), [mp.task_shared_legacy](#) (page 26).

Method Summary

run_pre(*d*, *mpopt*)

Pre-process inputs that are for *legacy framework* only.

```
[d, mpo] = task.run_pre(d, mpo)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (`mpc`)
- **mpopt** (*struct*) – MATPOWER options struct

Outputs

- **d** – updated value of corresponding input
- **mpopt** (*struct*) – updated value of corresponding input

Call [run_pre_legacy\(\)](#) (page 27) method before calling parent.

run_post(*mm*, *nm*, *dm*, *mpopt*)

Export results back to data model source.

```
task.run_post(mm, nm, dm, mpo)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

task ([mp.task](#) (page 7)) – task object

Calls [mp.dm_converter.export\(\)](#) (page 60) and saves the result in the data model source property.

dm_converter_class_mpc2_default()

Set to [mp.dm_converter_mpc2_legacy](#) (page 62).

```
dmc_class = task.dm_converter_class_mpc2_default()
```

data_model_build_post(dm, dmc, mpopt)

Get data model converter to do more input pre-processing after calling superclass [data_model_build_post\(\)](#) (page 22).

math_model_class_default(nm, dm, mpopt)

Use legacy math model subclasses to support legacy costs and callbacks.

Uses math model variations that inherit from [mp.mmm_shared_opf_legacy](#) (page 142) (compatible with the legacy [opf_model](#) (page 217)), in order to support legacy cost functions and callback functions that expect to find the MATPOWER case struct in `mmm.mpc`.

legacy_post_run(mpop)

Post-process *legacy framework* outputs.

```
[results, success, raw] = task.legacy_post_run(mpop)
```

Input

mpopt (*struct*) – MATPOWER options struct

Outputs

- **results** (*struct*) – results struct for *legacy MATPOWER framework*, see Table 6.1 in legacy [MATPOWER User's Manual](#).
- **success** (*integer*) – 1 - succeeded, 0 - failed
- **raw** (*struct*) – see raw field in Table 6.1 in legacy [MATPOWER User's Manual](#).

Extract results and success and save the task object in `results.task` before returning. This method also creates and populates numerous other fields expected in the legacy OPF results struct, such as `f`, `x`, `om`, `mu`, `g`, `dg`, `raw`, `var`, `nle`, `nli`, `lin`, and `cost`. Based on code from the legacy functions [opf_execute\(\)](#) (page 290), [dcopf_solver\(\)](#) (page 284), and [nlpopf_solver\(\)](#) (page 285).

mp.task_shared_legacy**class mp.task_shared_legacy**

Bases: `handle`

[mp.task_shared_legacy](#) (page 26) - Shared legacy task functionality.

Provides legacy task functionality shared across different tasks (e.g. PF, CPF, OPF), specifically, the pre-processing of input data for the experimental system-wide ZIP load data.

mp.task_pf Methods:

- [run_pre_legacy\(\)](#) (page 27) - handle experimental system-wide ZIP load inputs

See also [mp.task](#) (page 7).

Method Summary

run_pre_legacy(*d*, *mpopt*)

Handle experimental system-wide ZIP load inputs.

```
[d, mpopt] = task.run_pre_legacy(d, mpopt)
```

Inputs

- **d** – data source specification, currently assumed to be a MATPOWER case name or case struct (**mpc**)
- **mpopt** (*struct*) – MATPOWER options struct

Outputs

- **d** – updated value of corresponding input
- **mpopt** (*struct*) – updated value of corresponding input

Moves the legacy experimental system-wide ZIP load data from `mpopt.exp.sys_wide_zip_loads` to `d.sys_wide_zip_loads` to make it available to the data model converter ([mp.dmce_load_mpc2](#) (page 70)).

Called by [run_pre\(\)](#) (page 11).

3.2 Data Model Classes

3.2.1 Containers

mp.data_model

class mp.data_model

Bases: [mp.element_container](#) (page 165)

[mp.data_model](#) (page 27) - Base class for MATPOWER **data model** objects.

The data model object encapsulates the input data provided by the user for the problem of interest and the output data presented back to the user upon completion. It corresponds roughly to the **mpc** (MATPOWER case) and **results** structs used throughout the legacy MATPOWER implementation, but encapsulated in an object with additional functionality. It includes tables of data for each type of element in the system.

A data model object is primarily a container for data model element ([mp.dm_element](#) (page 35)) objects. Concrete data model classes may be specific to the task.

By convention, data model variables are named **dm** and data model class names begin with `mp.data_model`.

mp.data_model Properties:

- [base_mva](#) (page 28) - system per unit MVA base
- [base_kva](#) (page 28) - system per unit kVA base
- [source](#) (page 28) - source of data, e.g. **mpc** (MATPOWER case struct)
- [userdata](#) (page 28) - arbitrary user data

mp.data_model Methods:

- `data_model()` (page 28) - constructor, assign default data model element classes
- `copy()` (page 29) - make duplicate of object
- `build()` (page 29) - create, add, and build element objects
- `count()` (page 29) - count instances of each element and remove if count is zero
- `initialize()` (page 29) - initialize (online/offline) status of each element
- `update_status()` (page 29) - update (online/offline) status based on connectivity, etc
- `build_params()` (page 30) - extract/convert/calculate parameters for online elements
- `online()` (page 30) - get number of online elements of named type
- `display()` (page 30) - display the data model object
- `pretty_print()` (page 30) - pretty print data model to console or file
- `pp_flags()` (page 31) - from options, build flags to control pretty printed output
- `pp_section_label()` (page 31) - construct section header lines for output
- `pp_section_list()` (page 31) - return list of section tags
- `pp_have_section()` (page 32) - return true if section exists for object
- `pp_section()` (page 32) - pretty print the given section
- `pp_get_headers()` (page 32) - construct pretty printed lines for section headers
- `pp_get_headers_cnt()` (page 32) - construct pretty printed lines for **cnt** section headers
- `pp_get_headers_ext()` (page 33) - construct pretty printed lines for **ext** section headers
- `pp_data()` (page 33) - pretty print the data for the given section
- `set_bus_v_lims_via_vg()` (page 33) - set gen bus voltage limits based on gen voltage setpoints

See the `sec_data_model` section in the *MATPOWER Developer's Manual* for more information.

See also `mp.task` (page 7), `mp.net_model` (page 90), `mp.math_model` (page 121), `mp.dm_converter` (page 59).

Constructor Summary

`data_model()`

Constructor, assign default data model element classes.

```
dm = mp.data_model()
```

Property Summary

`base_mva`

(*double*) system per unit MVA base, for balanced single-phase systems/sections, must be provided if system includes any 'bus' elements

`base_kva`

(*double*) system per unit kVA base, for unbalanced 3-phase systems/sections, must be provided if system includes any 'bus3p' elements

`source`

source (page 28) of data, e.g. `mpc` (MATPOWER case struct)

userdata = struct()

(*struct*) arbitrary user data

Method Summary

copy()

Create a duplicate of the data model object, calling the [copy\(\)](#) (page 40) method on each element.

```
new_dm = dm.copy()
```

build(d, dmc)

Create and add data model element objects.

```
dm.build(d, dmc)
```

Inputs

- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for [mp.dm_converter_mpc2](#) (page 61))
- **dmc** ([mp.dm_converter](#) (page 59)) – data model converter

Create the data model element objects by instantiating each class in the [element_classes](#) (page 165) property and adding the resulting object to the [elements](#) (page 165) property. Then proceed through the following additional [build\(\)](#) (page 29) stages for each element.

- Import
- Count
- Initialize
- Update status
- Build parameters

See the `sec_building_data_model` section in the *MATPOWER Developer's Manual* for more information.

count()

Count instances of each element and remove if [count\(\)](#) (page 29) is zero.

```
dm.count()
```

Call each element's [count\(\)](#) (page 40) method to determine the number of instances of that element in the data, and remove the element type from [elements](#) (page 165) if the count is 0.

Called by [build\(\)](#) (page 29) to perform its **count** stage. See the `sec_building_data_model` section in the *MATPOWER Developer's Manual* for more information.

initialize()

Initialize (online/offline) status of each element.

```
dm.initialize()
```

Call each element's [initialize\(\)](#) (page 40) method to [initialize\(\)](#) (page 29) statuses and create ID to row index mappings.

Called by [build\(\)](#) (page 29) to perform its **initialize** stage. See the `sec_building_data_model` section in the *MATPOWER Developer's Manual* for more information.

update_status()

Update (online/offline) status based on connectivity, etc.

```
dm.update_status()
```

Call each element's `update_status()` (page 41) method to update statuses based on connectivity or other criteria and define element properties containing number and row indices of online elements, indices of offline elements, and mapping of row indices to indices in online and offline element lists.

Called by `build()` (page 29) to perform its **update status** stage. See the `sec_building_data_model` section in the *MATPOWER Developer's Manual* for more information.

build_params()

Extract/convert/calculate parameters for online elements.

```
dm.build_params()
```

Call each element's `build_params()` (page 41) method to build parameters as necessary for online elements from the original data tables (e.g. p.u. conversion, initial state, etc.) and store them in element-specific properties.

Called by `build()` (page 29) to perform its **build parameters** stage. See the `sec_building_data_model` section in the *MATPOWER Developer's Manual* more information.

online(name)

Get number of online elements of named type.

```
n = dm.online(name)
```

Input

name (*char array*) – name of element type (e.g. 'bus', 'gen') as returned by the element's `name()` (page 37) method

Output

n (*integer*) – number of online elements

display()

Display the data model object.

This method is called automatically when omitting a semicolon on a line that returns an object of this class.

Displays the details of the data model elements.

pretty_print(mpop, fd)

Pretty print data model to console or file.

```
dm.pretty_print(mpop)
dm.pretty_print(mpop, fd)
[dm, out] = dm.pretty_print(mpop, fd)
```

Inputs

- **mpopt** (*struct*) – MATPOWER options struct
- **fd** (*integer*) – (*optional, default = 1*) file identifier to use for printing, (1 for standard output, 2 for standard error)

Outputs

- **dm** (*mp.data_model* (page 27)) – the data model object
- **out** (*struct*) – struct of output control flags

Displays the model parameters to a pretty-printed text format. The result can be output either to the console or to a file.

The output is organized into sections and each element type controls its own output for each section. The default sections are:

- **cnt** - counts, number of online, offline, and total elements of this type

- **sum** - summary, e.g. total amount of capacity, load, line loss, etc.
- **ext** - extremes, e.g. min and max voltages, nodal prices, etc.
- **det** - details, table of detailed data, e.g. voltages, prices for buses, dispatch, limits for generators, etc.

pp_flags(mpopt)

From options, build flags to control pretty printed output.

```
[out, add] = dm.pp_flags(mpop)
```

Input

mpopt (*struct*) – MATPOWER options struct

Outputs

- **out** (*struct*) – struct of output control flags

```
out
  .all      (-1, 0 or 1)
  .any      (0 or 1)
  .sec
    .cnt
      .all      (-1, 0 or 1)
      .any      (0 or 1)
      .sum      (same as cnt)
      .ext      (same as cnt)
      .det
        .all      (-1, 0 or 1)
        .any      (0 or 1)
        .elm
          .<name>    (0 or 1)
```

where <name> is the name of the corresponding element type.

- **add** (*struct*) – additional data for subclasses to use

```
add
  .s0
    .<name> = 0
  .s1
    .<name> = 1
  .suppress      (-1, 0 or 1)
  .names         (cell array of element names)
  .ne            (number of element names)
```

See also [pretty_print\(\)](#) (page 30).

pp_section_label(label, blank_line)

Construct pretty printed lines for section label.

```
h = dm.pp_section_label(label, blank_line)
```

Inputs

- **label** (*char array*) – label for the section header
- **blank_line** (*boolean*) – include a blank line before the section label if true

Output

h (*cell array of char arrays*) – individual lines of section label

See also [pretty_print\(\)](#) (page 30).

pp_section_list(out)

Return list of section tags.

```
sections = dm.pp_section_list(out)
```

Input

out (*struct*) – struct of output control flags (see [pp_flags\(\)](#) (page 31) for details)

Output

sections (*cell array of char arrays*) – e.g. {'cnt', 'sum', 'ext', 'det'}

See also [pretty_print\(\)](#) (page 30).

pp_have_section(section, mpopt)

Return true if section exists for object with given options.

```
TorF = dm.pp_have_section(section, mpopt)
```

Inputs

- **section** (*char array*) – e.g. 'cnt', 'sum', 'ext', or 'det'
- **mpopt** (*struct*) – MATPOWER options struct

Output

TorF (*boolean*) – true if section exists

See also [pretty_print\(\)](#) (page 30).

pp_section(section, out_s, mpopt, fd)

Pretty print the given section.

```
dm.pp_section(section, out_s, mpopt, fd)
```

Inputs

- **section** (*char array*) – e.g. 'cnt', 'sum', 'ext', or 'det'
- **out_s** (*struct*) – output control flags for the section, `out_s = out.sec(section)`
- **mpopt** (*struct*) – MATPOWER options struct
- **fd** (*integer*) – (*optional, default = 1*) file identifier to use for printing, (1 for standard output, 2 for standard error)

See also [pretty_print\(\)](#) (page 30).

pp_get_headers(section, out_s, mpopt)

Construct pretty printed lines for section headers.

```
h = dm.pp_get_headers(section, out_s, mpopt)
```

Inputs

- **section** (*char array*) – e.g. 'cnt', 'sum', 'ext', or 'det'
- **out_s** (*struct*) – output control flags for the section, `out_s = out.sec(section)`
- **mpopt** (*struct*) – MATPOWER options struct

Output

h (*cell array of char arrays*) – individual lines of section headers

See also [pretty_print\(\)](#) (page 30).

pp_get_headers_cnt(out_s, mpopt)

Construct pretty printed lines for **cnt** section headers.

```
h = dm.pp_get_headers_cnt(out_s, mpopt)
```

Inputs

- **out_s** (*struct*) – output control flags for the section, `out_s = out.sec.(section)`
- **mpopt** (*struct*) – MATPOWER options struct

Output

h (*cell array of char arrays*) – individual lines of **cnt** section headers

See also [pretty_print\(\)](#) (page 30), [pp_get_headers\(\)](#) (page 32).

pp_get_headers_ext(*out_s, mpopt*)

Construct pretty printed lines for **ext** section headers.

```
h = dm.pp_get_headers_ext(out_s, mpopt)
```

Inputs

- **out_s** (*struct*) – output control flags for the section, `out_s = out.sec.(section)`
- **mpopt** (*struct*) – MATPOWER options struct

Output

h (*cell array of char arrays*) – individual lines of **ext** section headers

See also [pretty_print\(\)](#) (page 30), [pp_get_headers\(\)](#) (page 32).

pp_get_headers_other(*section, out_s, mpopt*)

Construct pretty printed lines for other section headers.

Returns nothing in base class, but subclasses can implement other section types (e.g. 'lim' for OPF).

```
h = dm.pp_get_headers_other(section, out_s, mpopt)
```

Inputs

- **section** (*char array*) – e.g. 'cnt', 'sum', 'ext', or 'det'
- **out_s** (*struct*) – output control flags for the section, `out_s = out.sec.(section)`
- **mpopt** (*struct*) – MATPOWER options struct

Output

h (*cell array of char arrays*) – individual lines of **ext** section headers

See also [pretty_print\(\)](#) (page 30), [pp_get_headers\(\)](#) (page 32).

pp_data(*section, out_s, mpopt, fd*)

Pretty print the data for the given section.

```
dm.pp_data(section, out_s, mpopt, fd)
```

Inputs

- **section** (*char array*) – e.g. 'cnt', 'sum', 'ext', or 'det'
- **out_s** (*struct*) – output control flags for the section, `out_s = out.sec.(section)`
- **mpopt** (*struct*) – MATPOWER options struct
- **fd** (*integer*) – (*optional, default = 1*) file identifier to use for printing, (1 for standard output, 2 for standard error)

See also [pretty_print\(\)](#) (page 30), [pp_section\(\)](#) (page 32).

set_bus_v_lims_via_vg(*use_vg*)

Set gen bus voltage limits based on gen voltage setpoints.

```
dm.set_bus_v_lims_via_vg(use_vg)
```

Input

use_vg (*double*) – 1 if voltage setpoint should be used, 0 for original bus voltage bounds, or fractional value between 0 and 1 for bounds interpolated between the two.

mp.data_model_cpf

class mp.data_model_cpf

Bases: [mp.data_model](#) (page 27)

[mp.data_model_cpf](#) (page 34) - MATPOWER **data model** for CPF tasks.

The purpose of this class is to include CPF-specific subclasses for the load and shunt elements, which need to be able to provide versions of their model parameters that are parameterized by the continuation parameter λ .

data_model_cpf Methods:

- [data_model_cpf\(\)](#) (page 34) - constructor, assign default data model element classes

See also [mp.data_model](#) (page 27).

Constructor Summary

data_model_cpf()

Constructor, assign default data model element classes.

Create an empty data model object and assign the default data model element classes, which are the same as those defined by the base class, except for loads and shunts.

```
dm = mp.data_model_cpf()
```

mp.data_model_opf

class mp.data_model_opf

Bases: [mp.data_model](#) (page 27)

[mp.data_model_opf](#) (page 34) - MATPOWER **data model** for OPF tasks.

The purpose of this class is to include OPF-specific subclasses for its elements and to handle pretty-printing output for **lim** sections.

mp.data_model_opf Methods:

- [data_model_opf\(\)](#) (page 34) - constructor, assign default data model element classes
- [pp_flags\(\)](#) (page 35) - add flags for **lim** sections
- [pp_section_list\(\)](#) (page 35) - append 'lim' tag for **lim** sections to default list
- [pp_get_headers_other\(\)](#) (page 35) - construct headers for **lim** section headers

See also [mp.data_model](#) (page 27).

Constructor Summary

data_model_opf()

Constructor, assign default data model element classes.

Create an empty data model object and assign the default data model element classes, each specific to OPF.

```
dm = mp.data_model_opf()
```

Method Summary

pp_flags(*mpopt*)

Add flags for **lim** sections.

See [mp.data_model.pp_flags\(\)](#) (page 31).

pp_section_list(*out*)

Append 'lim' tag for **lim** section to default list.

See [mp.data_model.pp_section_list\(\)](#) (page 31).

pp_get_headers_other(*section, out_s, mpop*)

Construct pretty printed lines for **lim** section headers.

See [mp.data_model.pp_get_headers_other\(\)](#) (page 33).

3.2.2 Elements

mp.dm_element

class mp.dm_element

Bases: `handle`

[mp.dm_element](#) (page 35) - Abstract base class for MATPOWER **data model element** objects.

A data model element object encapsulates all of the input and output data for a particular element type. All data model element classes inherit from [mp.dm_element](#) (page 35) and each element type typically implements its own subclass. A given data model element object contains the data for all instances of that element type, stored in one or more table data structures.

Defines the following columns in the main data table, which are inherited by all subclasses:

Name	Type	Description
uid	<i>integer</i>	unique ID
name	<i>char array</i>	element name
status	<i>boolean</i>	true = online, false = offline
source_uid	<i>undefined</i>	intended for any info required to link back to element instance in source data

By convention, data model element variables are named `dme` and data model element class names begin with `mp.dme`.

In addition to being containers for the data itself, data model elements are responsible for handling the on/off status of each element, preparation of parameters needed by network and mathematical models, definition of connections with other elements, defining solution data to be updated when exporting, and pretty-printing of data to the console or file.

Elements that create nodes (e.g. buses) are called **junction** elements. Elements that define ports (e.g. generators, branches, loads) can connect the ports of a particular instance to the nodes of a particular instance of a junction element by specifying two pieces of information for each port:

- the **type** of junction element it connects to
- the **index** of the specific junction element

mp.dm_element Properties:

- *tab* (page 37) - main data table
- *nr* (page 37) - total number of rows in table
- *n* (page 37) - number of online elements
- *ID2i* (page 37) - max(ID) x 1 vector, maps IDs to row indices
- *on* (page 37) - n x 1 vector of row indices of online elements
- *off* (page 37) - (nr-n) x 1 vector of row indices of offline elements
- *i2on* (page 37) - nr x 1 vector mapping row index to index in on/off respectively

mp.dm_element Methods:

- *name()* (page 37) - get name of element type, e.g. 'bus', 'gen'
- *label()* (page 38) - get singular label for element type, e.g. 'Bus', 'Generator'
- *labels()* (page 38) - get plural label for element type, e.g. 'Buses', 'Generators'
- *cxn_type()* (page 38) - type(s) of junction element(s) to which this element connects
- *cxn_idx_prop()* (page 38) - name(s) of property(ies) containing indices of junction elements
- *cxn_type_prop()* (page 39) - name(s) of property(ies) containing types of junction elements
- *table_exists()* (page 39) - check for existence of data in main data table
- *main_table_var_names()* (page 39) - names of variables (columns) in main data table
- *export_vars()* (page 39) - names of variables to be exported by DMCE to data source
- *export_vars_offline_val()* (page 40) - values of export variables for offline elements
- *dm_converter_element()* (page 40) - get corresponding data model converter element
- *copy()* (page 40) - create a duplicate of the data model element object
- *count()* (page 40) - determine number of instances of this element in the data
- *initialize()* (page 40) - initialize (online/offline) status of each element
- *ID()* (page 41) - return unique ID's for all or indexed rows
- *init_status()* (page 41) - initialize status column
- *update_status()* (page 41) - update (online/offline) status based on connectivity, etc
- *build_params()* (page 41) - extract/convert/calculate parameters for online elements
- *rebuild()* (page 42) - rebuild object, calling *count()* (page 40), *initialize()* (page 40), *build_params()* (page 41)
- *display()* (page 42) - display the data model element object
- *pretty_print()* (page 42) - pretty-print data model element to console or file
- *pp_have_section()* (page 42) - true if pretty-printing for element has specified section

- `pp_rows()` (page 43) - indices of rows to include in pretty-printed output
- `pp_get_headers()` (page 43) - get pretty-printed headers for this element/section
- `pp_get_footers()` (page 43) - get pretty-printed footers for this element/section
- `pp_data()` (page 43) - pretty-print the data for this element/section
- `pp_have_section_cnt()` (page 43) - true if pretty-printing for element has **counts** section
- `pp_data_cnt()` (page 44) - pretty-print the **counts** data for this element
- `pp_have_section_sum()` (page 44) - true if pretty-printing for element has **summary** section
- `pp_data_sum()` (page 44) - pretty-print the **summary** data for this element
- `pp_have_section_ext()` (page 44) - true if pretty-printing for element has **extremes** section
- `pp_data_ext()` (page 44) - pretty-print the **extremes** data for this element
- `pp_have_section_det()` (page 44) - true if pretty-printing for element has **details** section
- `pp_get_title_det()` (page 44) - get title of **details** section for this element
- `pp_get_headers_det()` (page 45) - get pretty-printed **details** headers for this element
- `pp_get_footers_det()` (page 45) - get pretty-printed **details** footers for this element
- `pp_data_det()` (page 45) - pretty-print the **details** data for this element
- `pp_data_row_det()` (page 45) - get pretty-printed row of **details** data for this element

See the `sec_dm_element` section in the *MATPOWER Developer's Manual* for more information.

See also `mp.data_model` (page 27).

Property Summary

tab

(*table*) main data table

nr

(*integer*) total number of rows in table

n

(*integer*) number of online elements

ID2i

(*integer*) $\max(\text{ID}) \times 1$ vector, maps IDs to row indices

on

(*integer*) $n \times 1$ vector of row indices of online elements

off

(*integer*) $(nr-n) \times 1$ vector of row indices of offline elements

i2on

(*integer*) $nr \times 1$ vector mapping row index to index in `on/off` respectively

Method Summary

name()

Get name of element type, e.g. 'bus', 'gen'.

```
name = dme.name()
```

Output

name (*char array*) – name of element type, must be a valid struct field name

Implementation provided by an element type specific subclass.

label()

Get singular label for element type, e.g. 'Bus', 'Generator'.

```
label = dme.label()
```

Output

label (*char array*) – user-visible label for element type, when singular

Implementation provided by an element type specific subclass.

labels()

Get plural label for element type, e.g. 'Buses', 'Generators'.

```
label = dme.labels()
```

Output

label (*char array*) – user-visible label for element type, when plural

Implementation provided by an element type specific subclass.

cnxn_type()

Type(s) of junction element(s) to which this element connects.

```
name = dme.cxn_type()
```

Output

name (*char array or cell array of char arrays*) – name(s) of type(s) of junction elements, i.e. node-creating elements (e.g. 'bus'), to which this element connects

Assuming an element with *nc* connections, there are three options for the return value:

1. Single char array with one type that applies to all connections, [cnxn_idx_prop\(\)](#) (page 38) returns *empty*.
2. Cell array with *nc* elements, one for each connection, [cnxn_idx_prop\(\)](#) (page 38) returns *empty*.
3. Cell array of valid junction element types, [cnxn_idx_prop\(\)](#) (page 38) return value *not empty*.

See the `sec_dm_element_cxn` section in the *MATPOWER Developer's Manual* for more information.

Implementation provided by an element type specific subclass.

See also [cnxn_idx_prop\(\)](#) (page 38), [cnxn_type_prop\(\)](#) (page 39).

cnxn_idx_prop()

Name(s) of property(ies) containing indices of junction elements.

```
name = dme.cxn_idx_prop()
```

Output

name (*char array or cell array of char arrays*) – name(s) of property(ies) containing indices of junction elements that define connections (e.g. {'fbus', 'tbus'})

See the `sec_dm_element_cxn` section in the *MATPOWER Developer's Manual* for more information.

Implementation provided by an element type specific subclass.

See also `cxn_type()` (page 38), `cxn_type_prop()` (page 39).

`cxn_type_prop()`

Name(s) of property(ies) containing types of junction elements.

```
name = dme.cxn_type_prop()
```

Output

name (*char array or cell array of char arrays*) – name(s) of properties containing type of junction elements for each connection

Note: If not empty, dimension must match `cxn_idx_prop()` (page 38)

This is only used if the junction element type can vary by individual element, e.g. some elements of this type connect to one kind of bus, some to another kind. Otherwise, it returns an empty string and the junction element types for the connections are determined solely by `cxn_type()` (page 38).

See the `sec_dm_element_cxn` section in the *MATPOWER Developer's Manual* for more information.

Implementation provided by an element type specific subclass.

See also `cxn_type()` (page 38), `cxn_idx_prop()` (page 38).

`table_exists()`

Check for existence of data in main data table.

```
TorF = dme.table_exists()
```

Output

TorF (*boolean*) – true if main data table is not empty

`main_table_var_names()`

Names of variables (columns) in main data table.

```
names = dme.main_table_var_names()
```

Output

names (*cell array of char arrays*) – names of variables (columns) in main table

This base class includes the following variables {'uid', 'name', 'status', 'source_uid'} which are common to all element types and should therefore be included in all subclasses. That is, subclass methods should append their additional fields to those returned by this parent method. For example, a subclass method would like something like the following:

```
function names = main_table_var_names(obj)
    names = horzcat( main_table_var_names@mp.dm_element(obj), ...
        {'subclass_var1', 'subclass_var2'} );
end
```

`export_vars()`

Names of variables to be exported by DMCE to data source.

```
vars = dme.export_vars()
```

Output

vars (*cell array of char arrays*) – names of variables to export

Return the names of the variables the data model converter element needs to export to the data source. This is typically the list of variables updated by the solution process, e.g. bus voltages, line flows, etc.

export_vars_offline_val()

Values of export variables for offline elements.

```
s = dme.export_vars_offline_val()
```

Output

s (*struct*) – keys are export variable names, values are the corresponding values to assign to these variables for offline elements.

Returns a struct defining the values of export variables for offline elements. Called by *mp.mm_element.data_model_update()* (page 145) to define how to set export variables for offline elements.

Export variables not found in the struct are not modified.

For example, *s* = *struct*('va', 0, 'vm', 1) would assign the value 0 to the *va* variable and 1 to the *vm* variable for any offline elements.

See also *export_vars()* (page 39).

dm_converter_element(dmc, name)

Get corresponding data model converter element.

```
dmce = dme.dm_converter_element(dmc, name)
```

Inputs

- *dmc* (*mp.dm_converter* (page 59)) – data model converter object
- *name* (*char array*) – name of element type

Output

dmce (*mp.dmce_element* (page 62)) – data model converter element object

copy()

Create a duplicate of the data model element object.

```
new_dme = dme.copy()
```

Output

new_dme (*mp.dm_element* (page 35)) – *copy()* (page 40) of data model element object

count(dm)

Determine number of instances of this element in the data.

Store the count in the *nr* property.

```
nr = dme.count(dm);
```

Input

dm (*mp.data_model* (page 27)) – data model

Output

nr (*integer*) – number of instances (rows of data)

Called for each element by the *count()* (page 29) method of *mp.data_model* (page 27) during the **count** stage of a data model build.

See the *sec_building_data_model* section in the *MATPOWER Developer's Manual* for more information.

initialize(dm)

Initialize a newly created data model element object.

```
dme.initialize(dm)
```

Input

dm (*mp.data_model* (page 27)) – data model

Initialize the (online/offline) status of each element and create a mapping of ID to row index in the ID2i element property, then call *init_status()* (page 41).

Called for each element by the *initialize()* (page 29) method of *mp.data_model* (page 27) during the **initialize** stage of a data model build.

See the *sec_building_data_model* section in the *MATPOWER Developer's Manual* for more information.

ID(idx)

Return unique ID's for all or indexed rows.

```
uid = dme.ID()
uid = dme.ID(idx)
```

Input

idx (*integer*) – (*optional*) row index vector

Return an *nr* x 1 vector of unique IDs for all rows, i.e. a map of row index to unique ID or, if a row index vector is provided just the ID's of the indexed rows.

init_status(dm)

Initialize status column.

```
dme.init_status(dm)
```

Input

dm (*mp.data_model* (page 27)) – data model

Called by *initialize()* (page 40). Does nothing in the base class.

update_status(dm)

Update (online/offline) status based on connectivity, etc.

```
dme.update_status(dm)
```

Input

dm (*mp.data_model* (page 27)) – data model

Update status of each element based on connectivity or other criteria and define element properties containing number and row indices of online elements (*n* and *on*), indices of offline elements (*off*), and mapping (*i2on*) of row indices to corresponding entries in *on* or *off*.

Called for each element by the *update_status()* (page 29) method of *mp.data_model* (page 27) during the **update status** stage of a data model build.

See the *sec_building_data_model* section in the *MATPOWER Developer's Manual* for more information.

build_params(dm)

Extract/convert/calculate parameters for online elements.

```
dme.build_params(dm)
```

Input

dm ([mp.data_model](#) (page 27)) – data model

Extract/convert/calculate parameters as necessary for online elements from the original data tables (e.g. p.u. conversion, initial state, etc.) and store them in element-specific properties.

Called for each element by the [build_params\(\)](#) (page 30) method of [mp.data_model](#) (page 27) during the **build parameters** stage of a data model build.

See the `sec_building_data_model` section in the *MATPOWER Developer's Manual* for more information.

Does nothing in the base class.

rebuild(dm)

Rebuild object, calling [count\(\)](#) (page 40), [initialize\(\)](#) (page 40), [build_params\(\)](#) (page 41).

```
dme.rebuild(dm)
```

Input

dm ([mp.data_model](#) (page 27)) – data model

Typically used after modifying data in the main table.

display()

Display the data model element object.

This method is called automatically when omitting a semicolon on a line that returns an object of this class.

Displays the details of the elements, including total number of rows, number of online elements, and the main data table.

pretty_print(dm, section, out_e, mpopt, fd, pp_args)

Pretty print data model element to console or file.

```
dme.pretty_print(dm, section, out_e, mpopt, fd, pp_args)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model
- **section** (*char array*) – section identifier, e.g. 'cnt', 'sum', 'ext', or 'det', for **counts**, **summary**, **extremes**, or **details** sections, respectively
- **out_e** (*boolean*) – output control flag for this element/section
- **mpopt** (*struct*) – MATPOWER options struct
- **fd** (*integer*) – (*optional, default = 1*) file identifier to use for printing, (1 for standard output, 2 for standard error)
- **pp_args** (*struct*) – arbitrary struct of additional pretty printing arguments passed to all sub-methods, allowing a single sub-method to be used for multiple output portions (e.g. for active and reactive power) by passing in a different argument; by convention, arguments for a branch element, for example, are passed in `pp_args.branch`, etc.

pp_have_section(section, mpopt, pp_args)

True if pretty-printing for element has specified section.

```
TorF = dme.pp_have_section(section, mpopt, pp_args)
```

Inputs

see [pretty_print\(\)](#) (page 42) for details

Output

TorF (*boolean*) – true if output includes specified section

Implementation handled by section-specific `pp_have_section` methods or `pp_have_section_other()` (page 58).

See also `pp_have_section_cnt()` (page 43), `pp_have_section_sum()` (page 44), `pp_have_section_ext()` (page 44), `pp_have_section_det()` (page 44).

pp_rows(*dm, section, out_e, mpopt, pp_args*)

Indices of rows to include in pretty-printed output.

```
rows = dme.pp_rows(dm, section, out_e, mpopt, pp_args)
```

Inputs

see `pretty_print()` (page 42) for details

Output

rows (*integer*) – index vector of rows to be included in output

- 0 = no rows
- -1 = all rows

Includes all rows by default.

pp_get_headers(*dm, section, out_e, mpopt, pp_args*)

Get pretty-printed headers for this element/section.

```
h = dme.pp_get_headers(dm, section, out_e, mpopt, pp_args)
```

Inputs

see `pretty_print()` (page 42) for details

Output

h (*cell array of char arrays*) – lines of pretty printed header output for this element/section

Empty by default for counts, summary and extremes sections, and handled by `pp_get_headers_det()` (page 45) for details section.

pp_get_footers(*dm, section, out_e, mpopt, pp_args*)

Get pretty-printed footers for this element/section.

```
f = dme.pp_get_footers(dm, section, out_e, mpopt, pp_args)
```

Inputs

see `pretty_print()` (page 42) for details

Output

f (*cell array of char arrays*) – lines of pretty printed footer output for this element/section

Empty by default for counts, summary and extremes sections, and handled by `pp_get_headers_det()` (page 45) for details section.

pp_data(*dm, section, rows, out_e, mpopt, fd, pp_args*)

Pretty-print the data for this element/section.

```
dme.pp_data(dm, section, rows, out_e, mpopt, fd, pp_args)
```

Inputs

- **rows** (*integer*) – indices of rows to include, from `pp_rows()` (page 43)
- ... – see `pretty_print()` (page 42) for details of other inputs

Implementation handled by section-specific `pp_data` methods or `pp_data_other()` (page 58).

See also `pp_data_cnt()` (page 44), `pp_data_sum()` (page 44), `pp_data_ext()` (page 44), `pp_data_det()` (page 45).

pp_have_section_cnt(*mpopt*, *pp_args*)

True if pretty-printing for element has **counts** section.

```
TorF = dme.pp_have_section_cnt(mpop, pp_args)
```

Default is **true**.

See also [pp_have_section\(\)](#) (page 42).

pp_data_cnt(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

Pretty-print the **counts** data for this element.

```
dme.pp_data_cnt(dm, rows, out_e, mpopt, fd, pp_args)
```

See also [pp_data\(\)](#) (page 43).

pp_have_section_sum(*mpopt*, *pp_args*)

True if pretty-printing for element has **summary** section.

```
TorF = dme.pp_have_section_sum(mpop, pp_args)
```

Default is **false**.

See also [pp_have_section\(\)](#) (page 42).

pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

Pretty-print the **summary** data for this element.

```
dme.pp_data_sum(dm, rows, out_e, mpopt, fd, pp_args)
```

Does nothing by default.

See also [pp_data\(\)](#) (page 43).

pp_have_section_ext(*mpopt*, *pp_args*)

True if pretty-printing for element has **extremes** section.

```
TorF = dme.pp_have_section_ext(mpop, pp_args)
```

Default is **false**.

See also [pp_have_section\(\)](#) (page 42).

pp_data_ext(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

Pretty-print the **extremes** data for this element.

```
dme.pp_data_ext(dm, rows, out_e, mpopt, fd, pp_args)
```

Does nothing by default.

See also [pp_data\(\)](#) (page 43).

pp_have_section_det(*mpopt*, *pp_args*)

True if pretty-printing for element has **details** section.

```
TorF = dme.pp_have_section_det(mpop, pp_args)
```

Default is **false**.

See also [pp_have_section\(\)](#) (page 42).

pp_get_title_det(*mpopt*, *pp_args*)

Get title of **details** section for this element.

```
str = dme.pp_get_title_det(mpop, pp_args)
```

Inputs

see [pretty_print\(\)](#) (page 42) for details

Output

str (*char array*) – title of details section, e.g. 'Bus Data', 'Generator Data', etc.

Called by [pp_get_headers_det\(\)](#) (page 45) to insert title into detail section header.

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

Get pretty-printed **details** headers for this element.

```
h = dme.pp_get_headers_det(dm, out_e, mpopt, pp_args)
```

See also [pp_get_headers\(\)](#) (page 43).

pp_get_footers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

Get pretty-printed **details** footers for this element.

```
f = dme.pp_get_footers_det(dm, out_e, mpopt, pp_args)
```

Empty by default.

See also [pp_get_footers\(\)](#) (page 43).

pp_data_det(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

Pretty-print the **details** data for this element.

```
dme.pp_data_det(dm, rows, out_e, mpopt, fd, pp_args)
```

Calls [pp_data_row_det\(\)](#) (page 45) for each row.

See also [pp_data\(\)](#) (page 43), [pp_data_row_det\(\)](#) (page 45).

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

Get pretty-printed row of **details** data for this element.

```
str = dme.pp_data_row_det(dm, k, out_e, mpopt, fd, pp_args)
```

Inputs

- **k** (*integer*) – index of row to print
- ... – see [pretty_print\(\)](#) (page 42) for details of other inputs

Output

str (*char array*) – row of data (*without newline*)

Called by [pp_data_det\(\)](#) (page 45) for each row.

mp.dme_branch

class mp.dme_branch

Bases: [mp.dm_element](#) (page 35)

[mp.dme_branch](#) (page 46) - Data model element for branch.

Implements the data element model for branch elements, including transmission lines and transformers.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
<code>bus_fr</code>	<i>integer</i>	bus ID (uid) of “from” bus
<code>bus_to</code>	<i>integer</i>	bus ID (uid) of “to” bus
<code>r</code>	<i>double</i>	per unit series resistance
<code>x</code>	<i>double</i>	per unit series reactance
<code>g_fr</code>	<i>double</i>	per unit shunt conductance at “from” end
<code>b_fr</code>	<i>double</i>	per unit shunt susceptance at “from” end
<code>g_to</code>	<i>double</i>	per unit shunt conductance at “to” end
<code>b_to</code>	<i>double</i>	per unit shunt susceptance at “to” end
<code>sm_ub_a</code>	<i>double</i>	long term apparent power rating (MVA)
<code>sm_ub_b</code>	<i>double</i>	short term apparent power rating (MVA)
<code>sm_ub_c</code>	<i>double</i>	emergency apparent power rating (MVA)
<code>cm_ub_a</code>	<i>double</i>	long term current magnitude rating (MVA equivalent at 1 p.u. voltage)
<code>cm_ub_b</code>	<i>double</i>	short term current magnitude rating (MVA equivalent at 1 p.u. voltage)
<code>cm_ub_c</code>	<i>double</i>	emergency current magnitude rating (MVA equivalent at 1 p.u. voltage)
<code>vad_lb</code>	<i>double</i>	voltage angle difference lower bound
<code>vad_ub</code>	<i>double</i>	voltage angle difference upper bound
<code>tm</code>	<i>double</i>	transformer off-nominal turns ratio
<code>ta</code>	<i>double</i>	transformer phase-shift angle (degrees)
<code>pl_fr</code>	<i>double</i>	active power injection at “from” end
<code>ql_fr</code>	<i>double</i>	reactive power injection at “from” end
<code>pl_to</code>	<i>double</i>	active power injection at “to” end
<code>ql_to</code>	<i>double</i>	reactive power injection at “to” end

Property Summary

fbus

bus index vector for “from” port (port 1) (all branches)

tbus

bus index vector for “to” port (port 2) (all branches)

r

series resistance (p.u.) for branches that are on

x

series reactance (p.u.) for branches that are on

g_fr

shunt conductance (p.u.) at “from” end for branches that are on

g_to

shunt conductance (p.u.) at “to” end for branches that are on

b_fr
shunt susceptance (p.u.) at “from” end for branches that are on

b_to
shunt susceptance (p.u.) at “to” end for branches that are on

tm
transformer off-nominal turns ratio for branches that are on

ta
transformer phase-shift angle (radians) for branches that are on

rate_a
long term flow limit (p.u.) for branches that are on

Method Summary

name()

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

export_vars()

export_vars_offline_val()

initialize(dm)

update_status(dm)

build_params(dm)

pp_data_cnt(dm, rows, out_e, mpopt, fd, pp_args)

pp_have_section_sum(mpop, pp_args)

pp_data_sum(dm, rows, out_e, mpopt, fd, pp_args)

pp_get_headers_det(dm, out_e, mpopt, pp_args)

pp_have_section_det(mpop, pp_args)

pp_data_row_det(dm, k, out_e, mpopt, fd, pp_args)

`mp.dme_branch_opf`

class `mp.dme_branch_opf`

Bases: `mp.dme_branch` (page 46), `mp.dme_shared_opf` (page 58)

`mp.dme_branch_opf` (page 48) - Data model element for branch for OPF.

To parent class `mp.dme_branch` (page 46), adds shadow prices on flow and angle difference limits, and pretty-printing for **lim** sections.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
<code>mu_flow_fr_u</code>	<i>double</i>	shadow price on flow constraint at “from” end (u/MVA) ¹
<code>mu_flow_to_u</code>	<i>double</i>	shadow price on flow constraint at “to” end (u/MVA) ¹
<code>mu_vad_lb</code>	<i>double</i>	shadow price on lower bound of voltage angle difference constraint ($u/degree$) ¹
<code>mu_vad_ub</code>	<i>double</i>	shadow price on upper bound of voltage angle difference constraint ($u/degree$) ¹

Method Summary

`main_table_var_names()`

`export_vars()`

`export_vars_offline_val()`

`pretty_print(dm, section, out_e, mpopt, fd, pp_args)`

`pp_have_section_lim(mpop, pp_args)`

`pp_binding_rows_lim(dm, out_e, mpopt, pp_args)`

`pp_get_title_lim(mpop, pp_args)`

`pp_get_headers_lim(dm, out_e, mpopt, pp_args)`

`pp_data_row_lim(dm, k, out_e, mpopt, fd, pp_args)`

¹ Here u denotes the units of the objective function, e.g. USD.

mp.dme_bus

class mp.dme_bus

Bases: [mp.dm_element](#) (page 35)

[mp.dme_bus](#) (page 49) - Data model element for bus.

Implements the data element model for bus elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
base_kv	<i>double</i>	base voltage (<i>kV</i>)
type	<i>integer</i>	bus type (1 = PQ, 2 = PV, 3 = ref, 4 = isolated)
area	<i>integer</i>	area number
zone	<i>integer</i>	loss zone
vm_lb	<i>double</i>	voltage magnitude lower bound (<i>p.u.</i>)
vm_ub	<i>double</i>	voltage magnitude upper bound (<i>p.u.</i>)
va	<i>double</i>	voltage angle (<i>degrees</i>)
vm	<i>double</i>	voltage magnitude (<i>p.u.</i>)

Property Summary

type

node [type](#) (page 49) vector for buses that are on

vm_start

initial voltage magnitudes (*p.u.*) for buses that are on

va_start

initial voltage angles (radians) for buses that are on

vm_lb

voltage magnitude lower bounds for buses that are on

vm_ub

voltage magnitude upper bounds for buses that are on

vm_control

true if voltage is controlled, for buses that are on

Method Summary

name()

label()

labels()

main_table_var_names()

export_vars()

export_vars_offline_val()

init_status(dm)

```

update_status(dm)

build_params(dm)

pp_data_cnt(dm, rows, out_e, mpopt, fd, pp_args)

pp_have_section_ext(mpop, pp_args)

pp_data_ext(dm, rows, out_e, mpopt, fd, pp_args)

pp_have_section_det(mpop, pp_args)

pp_get_headers_det(dm, out_e, mpopt, pp_args)

pp_data_row_det(dm, k, out_e, mpopt, fd, pp_args)

set_bus_type_ref(dm, idx)

set_bus_type_pv(dm, idx)

set_bus_type_pq(dm, idx)

```

mp.dme_bus_opf

class mp.dme_bus_opf

Bases: [mp.dme_bus](#) (page 49), [mp.dme_shared_opf](#) (page 58)

[mp.dme_bus_opf](#) (page 50) - Data model element for bus for OPF.

To parent class [mp.dme_bus](#) (page 49), adds shadow prices on power balance and voltage magnitude limits, and pretty-printing for **lim** sections.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
lam_p	<i>dou- ble</i>	active power nodal price, i.e. shadow price on active power balance constraint (u/MW) ¹
lam_q	<i>dou- ble</i>	reactive power nodal price, i.e. shadow price on reactive power balance constraint ($u/MVAr$) ¹
mu_vm_ll	<i>dou- ble</i>	shadow price on voltage magnitude lower bound ($u/p.u.$) ¹
mu_vm_ul	<i>dou- ble</i>	shadow price on voltage magnitude upper bound ($u/p.u.$) ¹

Method Summary

```

main_table_var_names()

export_vars()

export_vars_offline_val()

```

¹ Here u denotes the units of the objective function, e.g. USD.

```

pp_data_ext(dm, rows, out_e, mpopt, fd, pp_args)
pp_get_headers_det(dm, out_e, mpopt, pp_args)
pp_data_row_det(dm, k, out_e, mpopt, fd, pp_args)
pp_have_section_lim(mpop, pp_args)
pp_binding_rows_lim(dm, out_e, mpopt, pp_args)
pp_get_headers_lim(dm, out_e, mpopt, pp_args)
pp_data_row_lim(dm, k, out_e, mpopt, fd, pp_args)

```

mp.dme_gen

class mp.dme_gen

Bases: [mp.dm_element](#) (page 35)

[mp.dme_gen](#) (page 51) - Data model element for generator.

Implements the data element model for generator elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
bus	<i>integer</i>	bus ID (uid)
vm_setpoint	<i>double</i>	voltage magnitude setpoint (<i>p.u.</i>)
pg_lb	<i>double</i>	active power output lower bound (<i>MW</i>)
pg_ub	<i>double</i>	active power output upper bound (<i>MW</i>)
qg_lb	<i>double</i>	reactive power output lower bound (<i>MVar</i>)
qg_ub	<i>double</i>	reactive power output upper bound (<i>MVar</i>)
pg	<i>double</i>	active power output (<i>MW</i>)
qg	<i>double</i>	reactive power output (<i>MVar</i>)
startup_cost_cold	<i>double</i>	cold startup cost (<i>USD</i>)
pc1	<i>double</i>	lower active power output of PQ capability curve (<i>MW</i>)
pc2	<i>double</i>	upper active power output of PQ capability curve (<i>MW</i>)
qc1_lb	<i>double</i>	lower bound on reactive power output at pc1 (<i>MVar</i>)
qc1_ub	<i>double</i>	upper bound on reactive power output at pc1 (<i>MVar</i>)
qc2_lb	<i>double</i>	lower bound on reactive power output at pc2 (<i>MVar</i>)
qc2_ub	<i>double</i>	upper bound on reactive power output at pc2 (<i>MVar</i>)

Property Summary

bus

[bus](#) (page 51) index vector (all gens)

bus_on

vector of indices into online buses for gens that are on

pg_start

initial active power (*p.u.*) for gens that are on

qg_start

initial reactive power (p.u.) for gens that are on

vm_setpoint

generator voltage setpoint for gens that are on

pg_lb

active power lower bound (p.u.) for gens that are on

pg_ub

active power upper bound (p.u.) for gens that are on

qg_lb

reactive power lower bound (p.u.) for gens that are on

qg_ub

reactive power upper bound (p.u.) for gens that are on

Method Summary

name()

label()

labels()

cnx_type()

cnx_idx_prop()

main_table_var_names()

export_vars()

export_vars_offline_val()

have_cost()

initialize(*dm*)

update_status(*dm*)

apply_vm_setpoint(*dm*)

build_params(*dm*)

violated_q_lims(*dm*, *mpopt*)

isload(*idx*)

pp_have_section_sum(*mpopt*, *pp_args*)

pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)

pp_have_section_det(*mpopt*, *pp_args*)

pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_get_footers_det(*dm*, *out_e*, *mpopt*, *pp_args*)

pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_gen_opf

class mp.dme_gen_opf

Bases: [mp.dme_gen](#) (page 51), [mp.dme_shared_opf](#) (page 58)

[mp.dme_gen_opf](#) (page 53) - Data model element for generator for OPF.

To parent class [mp.dme_gen](#) (page 51), adds costs, shadow prices on active and reactive generation limits, and pretty-printing for **lim** sections.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
<code>cost_pg</code>	mp.cost_table	active power cost (u/MW) ¹
<code>cost_qg</code>	mp.cost_table	reactive power cost ($u/MVAr$) ¹
<code>mu_pg_lb</code>	<i>double</i>	shadow price on active power output lower bound (u/MW) ¹
<code>mu_pg_ub</code>	<i>double</i>	shadow price on active power output upper bound (u/MW) ¹
<code>mu_qg_lb</code>	<i>double</i>	shadow price on reactive power output lower bound ($u/MVAr$) ¹
<code>mu_qg_ub</code>	<i>double</i>	shadow price on reactive power output upper bound ($u/MVAr$) ¹

The cost tables `cost_pg` and `cost_qg` are defined as tables with the following columns:

See also [mp.cost_table](#) (page 161).

Method Summary

```

main_table_var_names()
export_vars()
export_vars_offline_val()
have_cost()
build_cost_params(dm, dc)
max_pwl_gencost()
pretty_print(dm, section, out_e, mpopt, fd, pp_args)
pp_have_section_lim(mpop, pp_args)
pp_binding_rows_lim(dm, out_e, mpopt, pp_args)
pp_get_headers_lim(dm, out_e, mpopt, pp_args)
pp_data_row_lim(dm, k, out_e, mpopt, fd, pp_args)

```

¹ Here u denotes the units of the objective function, e.g. USD.

mp.dme_load

class mp.dme_load

Bases: [mp.dm_element](#) (page 35)

[mp.dme_load](#) (page 54) - Data model element for load.

Implements the data element model for load elements, using a ZIP load model.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
<code>bus</code>	<i>integer</i>	bus ID (<code>uid</code>)
<code>pd</code>	<i>double</i>	p_p , active constant power demand (<i>MW</i>)
<code>qd</code>	<i>double</i>	q_p , reactive constant power demand (<i>MVar</i>)
<code>pd_i</code>	<i>double</i>	p_i , active nominal ¹ constant current demand (<i>MW</i>)
<code>qd_i</code>	<i>double</i>	q_i , reactive nominal ¹ constant current demand (<i>MVar</i>)
<code>pd_z</code>	<i>double</i>	p_z , active nominal ¹ constant impedance demand (<i>MW</i>)
<code>qd_z</code>	<i>double</i>	q_z , reactive nominal ¹ constant impedance demand (<i>MVar</i>)
<code>p</code>	<i>double</i>	p , total active demand (<i>MW</i>)
<code>q</code>	<i>double</i>	q , total reactive demand (<i>MVar</i>)

Implements a ZIP load model, where each load has three components, and total demand for the load i is given by

$$\begin{aligned} s &= s_p + s_i|v| + s_z|v|^2 \\ p + jq &= (p_p + jq_p) + (p_i + jq_i)|v| + (p_z + jq_z)|v|^2 \end{aligned} \tag{3.1}$$

Property Summary

bus

[bus](#) (page 54) index vector (all loads)

pd

active power demand (p.u.) for constant power loads that are on

qd

reactive power demand (p.u.) for constant power loads that are on

pd_i

active power demand (p.u.) for constant current loads that are on

qd_i

reactive power demand (p.u.) for constant current loads that are on

pd_z

active power demand (p.u.) for constant impedance loads that are on

qd_z

reactive power demand (p.u.) for constant impedance loads that are on

Method Summary

name()

¹ *Nominal* means for a voltage of 1 p.u.

```

label()
labels()
cxn_type()
cxn_idx_prop()
main_table_var_names()
count(dm)
update_status(dm)
build_params(dm)
pp_have_section_sum(mpop, pp_args)
pp_data_sum(dm, rows, out_e, mpop, fd, pp_args)
pp_have_section_det(mpop, pp_args)
pp_get_headers_det(dm, out_e, mpop, pp_args)
pp_get_footers_det(dm, out_e, mpop, pp_args)
pp_data_row_det(dm, k, out_e, mpop, fd, pp_args)

```

mp.dme_load_cpf

class mp.dme_load_cpf

Bases: [mp.dme_load](#) (page 54)

[mp.dme_load_cpf](#) (page 55) - Data model element for load for CPF.

To parent class [mp.dme_load](#) (page 54), adds method for adjusting model parameters based on value of continuation parameter λ , and overrides `export_vars` to export these updated parameter values.

Method Summary

```

export_vars()

parameterized(dm, dmb, dmt, lam)

```

mp.dme_load_opf

class mp.dme_load_opf

Bases: [mp.dme_load](#) (page 54), [mp.dme_shared_opf](#) (page 58)

[mp.dme_load_opf](#) (page 55) - Data model element for load for OPF.

To parent class [mp.dme_load](#) (page 54), adds pretty-printing for **lim** sections.

`mp.dme_shunt_cpf`

`class mp.dme_shunt_cpf`

Bases: `mp.dme_shunt` (page 56)

`mp.dme_shunt_cpf` (page 56) - Data model element for shunt for CPF.

To parent class `mp.dme_shunt` (page 56), adds method for adjusting model parameters based on value of continuation parameter λ , and overrides `export_vars()` (page 56) to export these updated parameter values.

Method Summary

`export_vars()`

`parameterized(dm, dmb, dmt, lam)`

`mp.dme_shunt`

`class mp.dme_shunt`

Bases: `mp.dm_element` (page 35)

`mp.dme_shunt` (page 56) - Data model element for shunt.

Implements the data element model for shunt elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
bus	<i>integer</i>	bus ID (uid)
gs	<i>double</i>	g_s , shunt conductance, specified as nominal ¹ active power demand (<i>MW</i>)
bs	<i>double</i>	b_s , shunt susceptance, specified as nominal ¹ reactive power injection (<i>MVar</i>)
p	<i>double</i>	p , total active power absorbed (<i>MW</i>)
q	<i>double</i>	q , total reactive power absorbed (<i>MVar</i>)

Property Summary

bus

`bus` (page 56) index vector (all shunts)

gs

shunt conductance (p.u. active power demanded at

¹ *Nominal* means for a voltage of 1 p.u.

bs

V = 1.0 p.u.) for shunts that are on

Method Summary

name()
label()
labels()
cxn_type()
cxn_idx_prop()
main_table_var_names()
count(*dm*)
update_status(*dm*)
build_params(*dm*)
pp_have_section_sum(*mpopt*, *pp_args*)
pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)
pp_have_section_det(*mpopt*, *pp_args*)
pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)
pp_get_footers_det(*dm*, *out_e*, *mpopt*, *pp_args*)
pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)

mp.dme_shunt_opf

class mp.dme_shunt_opf

Bases: [mp.dme_shunt](#) (page 56), [mp.dme_shared_opf](#) (page 58)

[mp.dme_shunt_opf](#) (page 57) - Data model element for shunt for OPF.

To parent class [mp.dme_shunt](#) (page 56), adds pretty-printing for **lim** sections.

3.2.3 Element Mixins

mp.dme_shared_opf

class mp.dme_shared_opf

Bases: handle

[mp.dme_shared_opf](#) (page 58) - Mixin class for OPF **data model element** objects.

For all elements of [mp.data_model_opf](#) (page 34), adds shared functionality for pretty-printing of **lim** sections.

Property Summary

ctol

constraint violation tolerance

ptol

shadow price tolerance

Method Summary

pp_set_tols_lim(mpopt)

pp_have_section_other(section, mpop, pp_args)

pp_rows_other(dm, section, out_e, mpop, pp_args)

pp_get_headers_other(dm, section, out_e, mpop, pp_args)

pp_get_footers_other(dm, section, out_e, mpop, pp_args)

pp_data_other(dm, section, rows, out_e, mpop, fd, pp_args)

pp_have_section_lim(mpopt, pp_args)

pp_rows_lim(dm, out_e, mpop, pp_args)

pp_binding_rows_lim(dm, out_e, mpop, pp_args)

pp_get_title_lim(mpopt, pp_args)

pp_get_headers_lim(dm, out_e, mpop, pp_args)

pp_get_footers_lim(dm, out_e, mpop, pp_args)

pp_data_lim(dm, rows, out_e, mpop, fd, pp_args)

pp_data_row_lim(dm, k, out_e, mpop, fd, pp_args)

3.3 Data Model Converter Classes

3.3.1 Containers

mp.dm_converter

class mp.dm_converter

Bases: [mp.element_container](#) (page 165)

[mp.dm_converter](#) (page 59) - Abstract base class for MATPOWER **data model converter** objects.

A data model converter provides the ability to convert data between a data model and a specific data source or format, such as the PSS/E RAW format or version 2 of the MATPOWER case format. It is used, for example, during the import stage of the data model build process.

A data model converter object is primarily a container for data model converter element ([mp.dmc_element](#) (page 62)) objects. Concrete data model converter classes are specific to the type or format of the data source.

By convention, data model converter variables are named `dmc` and data model converter class names begin with `mp.dm_converter`.

mp.dm_converter Methods:

- [format_tag\(\)](#) (page 59) - return char array identifier for data source/format
- [copy\(\)](#) (page 59) - make duplicate of object
- [build\(\)](#) (page 59) - create and add element objects
- [import\(\)](#) (page 59) - import data from a data source into a data model
- [export\(\)](#) (page 60) - export data from a data model to a data source
- [init_export\(\)](#) (page 60) - initialize a data source for export
- [save\(\)](#) (page 60) - save data source to a file
- [display\(\)](#) (page 60) - display the data model converter object

See the `sec_dm_converter` section in the *MATPOWER Developer's Manual* for more information.

See also [mp.data_model](#) (page 27), [mp.task](#) (page 7).

Method Summary

format_tag()

Return a short char array identifier for data source/format.

```
tag = dmc.format_tag()
```

E.g. the subclass for the MATPOWER case format returns `'mpc2'`.

Note: This is an abstract method that must be implemented by a subclass.

copy()

Create a duplicate of the data model converter object, calling the `copy()` method on each element.

```
new_dmc = dmc.copy()
```

build()

Create and add data model converter element objects.

```
dmc.build()
```

Create the data model converter element objects by instantiating each class in the [element_classes](#) (page 165) property and adding the resulting object to the [elements](#) (page 165) property.

import(*dm*, *d*)

Import data from a data source into a data model.

```
dm = dmc.import(dm, d)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for [mp.dm_converter_mpc2](#) (page 61))

Output

dm ([mp.data_model](#) (page 27)) – updated data model

Calls the [import\(\)](#) (page 59) method for each data model converter element and its corresponding data model element.

export(*dm*, *d*)

Export data from a data model to a data source.

```
d = dmc.export(dm, d)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for [mp.dm_converter_mpc2](#) (page 61))

Output

d – updated data source

Calls the [export\(\)](#) (page 60) method for each data model converter element and its corresponding data model element.

init_export(*dm*)

Initialize a data source for export.

```
d = dmc.export(dm)
```

Input

dm ([mp.data_model](#) (page 27)) – data model

Output

d – new empty data source, type depends on the implementing subclass (e.g. MATPOWER case struct for [mp.dm_converter_mpc2](#) (page 61))

Creates a new data source of the appropriate type in preparation for calling [export\(\)](#) (page 60).

save(*fname*, *d*)

Save data source to a file.

```
fname_out = dmc.save(fname, d)
```

Inputs

- **fname** (*char array*)
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for [mp.dm_converter_mpc2](#) (page 61))

Output

fname_out (*char array*) – final file name after saving, possibly modified from input (e.g. extension added)

Note: This is an abstract method that must be implemented by a subclass.

display()

Display the data model converter object.

This method is called automatically when omitting a semicolon on a line that returns an object of this class.

Displays the details of the data model converter elements.

mp.dm_converter_mpc2**class mp.dm_converter_mpc2**

Bases: [mp.dm_converter](#) (page 59)

[mp.dm_converter_mpc2](#) (page 61) - MATPOWER **data model converter** for MATPOWER case v2.

This class implements importing/exporting of data models for version 2 of the classic MATPOWER case format. That is, the *data source d* for this class is expected to be a MATPOWER case struct.

mp.dm_converter_mpc2 Methods:

- [dm_converter_mpc2\(\)](#) (page 61) - constructor
- [format_tag\(\)](#) (page 61) - return char array identifier for data source/format ('mpc2')
- [import\(\)](#) (page 61) - import data from a MATPOWER case struct into a data model
- [export\(\)](#) - export data from a data model to a MATPOWER case struct
- [save\(\)](#) (page 61) - save MATPOWER case struct to a file

See also [mp.dm_converter](#) (page 59).

Constructor Summary**dm_converter_mpc2()**

Specify the element classes for handling MATPOWER case format.

Method Summary**format_tag()**

Return identifier tag 'mpc2' for version 2 MATPOWER case format.

import(dm, d)

Import data from a version 2 MATPOWER case struct into a data model.

init_export(dm)

Initialize a MATPOWER case struct for export.

save(fname, d)

Save a MATPOWER case struct to a file.

mp.dm_converter_mpc2_legacy

class mp.dm_converter_mpc2_legacy

Bases: [mp.dm_converter_mpc2](#) (page 61)

[mp.dm_converter_mpc2_legacy](#) (page 62) - Legacy MATPOWER **data model converter** for MATPOWER case v2.

Adds to [mp.dm_converter_mpc2](#) (page 61) the ability to handle legacy user customization.

mp.dm_converter_mpc2_legacy Methods:

- [legacy_user_mod_inputs\(\)](#) (page 62) - pre-process legacy inputs for use-defined customization
- [legacy_user_nln_constraints\(\)](#) (page 62) - pre-process legacy inputs for user-defined nonlinear constraints

See also [mp.dm_converter](#) (page 59), [mp.dm_converter_mpc2](#) (page 61), [mp.taskopf_legacy](#) (page 25).

Method Summary

legacy_user_mod_inputs(*dm, mpopt, dc*)

Handle pre-processing of inputs related to legacy user-defined variables, costs, and constraints. This includes optional mpc fields A, l, u, N, fparm, H1, Cw, z0, z1, zu and user_constraints.

legacy_user_nln_constraints(*dm, mpopt*)

Handle pre-processing of inputs related to legacy user-defined non-linear constraints, specifically optional mpc fields user_constraints.nle and user_constraints.nli.

Called by [legacy_user_mod_inputs\(\)](#) (page 62) method.

3.3.2 Elements

mp.dmc_element

class mp.dmc_element

Bases: `handle`

[mp.dmc_element](#) (page 62)- Abstract base class for **data model converter element** objects.

A data model converter element object implements the functionality needed to import and export a particular element type from and to a given data format. All data model converter element classes inherit from [mp.dmc_element](#) (page 62) and each element type typically implements its own subclass.

By convention, data model converter element variables are named `dmce` and data model converter element class names begin with `mp.dmce`.

Typically, much of the import/export functionality for a particular concrete subclass can be defined simply by implementing the [table_var_map\(\)](#) (page 65) method.

mp.dmc_element Methods:

- [name\(\)](#) (page 63) - get name of element type, e.g. 'bus', 'gen'
- [data_model_element\(\)](#) (page 63) - get corresponding data model element
- [data_field\(\)](#) (page 63) - get name of field in data source corresponding to default data table

- `data_subs()` (page 64) - get subscript reference struct for accessing data source
- `data_exists()` (page 64) - check if default field exists in data source
- `get_import_spec()` (page 64) - get import specification
- `get_export_spec()` (page 64) - get export specification
- `get_import_size()` (page 65) - get dimensions of data to be imported
- `get_export_size()` (page 65) - get dimensions of data to be exported
- `table_var_map()` (page 65) - get variable map for import/export
- `import()` (page 65) - import data from data source into data model element
- `import_table_values()` (page 66) - import table values for given import specification
- `get_input_table_values()` (page 66) - get values to insert in data model element table
- `import_col()` (page 66) - extract and optionally modify values from data source column
- `export()` (page 67) - export data from data model element to data source
- `export_table_values()` (page 67) - export table values for given import specification
- `init_export_data()` (page 67) - initialize data source for export from data model element
- `default_export_data_table()` (page 68) - create default (empty) data table for data source
- `default_export_data_nrows()` (page 68) - get number of rows `default_export_data_table()` (page 68)
- `export_col()` (page 68) - export a variable (table column) to the data source

See the `sec_dmc_element` section in the *MATPOWER Developer's Manual* for more information.

See also `mp.dm_converter` (page 59).

Method Summary

`name()`

Get name of element type, e.g. 'bus', 'gen'.

```
name = dmce.name()
```

Output

name (*char array*) – name of element type, must be a valid struct field name

Implementation provided by an element type specific subclass.

`data_model_element(dm, name)`

Get the corresponding data model element.

```
dme = dmce.data_model_element(dm, name)
```

Inputs

- **dm** (`mp.data_model` (page 27)) – data model object
- **name** (*char array*) – name of element type

Output

dme (`mp.dm_element` (page 35)) – data model element object

data_field()

Get name of field in data source corresponding to default data table.

```
df = dmce.data_field()
```

Output

df (*char array*) – field name

data_subs()

Get subscript reference struct for accessing data source.

```
s = dmce.data_subs()
```

Output

s (*struct*) – same as the **s** input argument to the built-in `subsref()`, to access this element's data in data source, with fields:

- **type** – character vector or string containing '()', '{}', or '.' specifying the subscript type
- **subs** – cell array, character vector, or string containing the actual subscripts

The default implementation in this base class uses the return value of the `data_field()` (page 63) method to access a field of the data source struct. That is:

```
s = struct('type', '.', 'subs', dmce.data_field());
```

data_exists(d)

Check if default field exists in data source.

```
TorF = dmce.data_exists(d)
```

Input

d – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for `mp.dm_converter_mpc2` (page 61))

Output

TorF (*boolean*) – true if field exists

Check if value returned by `data_field()` (page 63) exists as a field in **d**.

get_import_spec(dme, d)

Get import specification.

```
spec = dmce.get_import_spec(dme, d)
```

Inputs

- **dme** (`mp.dm_element` (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for `mp.dm_converter_mpc2` (page 61))

Output

spec (*struct*) – import specification, with keys:

- **'subs'** - subscript reference struct for accessing data source, as returned by `data_subs()` (page 64)
- **'nr', 'nc', 'r'** - number of rows, number of columns, row index vector, as returned by `get_import_size()` (page 65)
- **'vmap'** - variable map, as returned by `table_var_map()` (page 65)

See also `get_export_spec()` (page 64).

get_export_spec(*dme*, *d*)

Get export specification.

```
spec = dmce.get_export_spec(dme, d)
```

Inputs

- **dme** (*mp.dm_element* (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))

Output

spec (*struct*) – export specification, see *get_import_spec()* (page 64)

See also *get_import_spec()* (page 64).

get_import_size(*d*)

Get dimensions of data to be imported.

```
[nr, nc, r] = dmce.get_import_size(d)
```

Input

d – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))

Outputs

- **nr** (*integer*) – number of rows of data
- **nc** (*integer*) – number of columns of data
- **r** (*integer*) – optional index vector (*empty by default*) of rows in data source field that correspond to data to be imported

get_export_size(*dme*)

Get dimensions of data to be exported.

```
[nr, nc, r] = dmce.get_export_size(dme)
```

Input

dme (*mp.dm_element* (page 35)) – data model element object

Outputs

- **nr** (*integer*) – number of rows of data
- **nc** (*integer*) – number of columns of data
- **r** (*integer*) – optional index vector (*empty by default*) of rows in main table of *dme* that correspond to data to be exported

table_var_map(*dme*, *d*)

Get variable map for import/export.

```
vmap = dmce.table_var_map(dme, d)
```

Inputs

- **dme** (*mp.dm_element* (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))

Output

vmap (*struct*) – variable map, see *tab_var_map* in the *MATPOWER Developer's Manual* for details

This method initializes each entry to { 'col', [] } by default, so subclasses only need to assign *vmap*.(vn){2} for columns that map directly from a column of the data source.

import(*dme*, *d*, *var_names*, *ridx*)

Import data from data source into data model element.

```
dme = dmce.import(dme, d, var_names, ridx)
```

Inputs

- **dme** (*mp.dm_element* (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))
- **var_names** (*cell array*) – (optional) list of names of variables (columns of main table) to import (*default is all variables*)
- **ridx** (*integer*) – (optional) vector of row indices of data to import (*default is all rows*)

Output

dme (*mp.dm_element* (page 35)) – updated data model element object

See also [export\(\)](#) (page 67).

import_table_values(*dme*, *d*, *spec*, *var_names*, *ridx*)

Import table values for given import specification.

```
dme = dmce.import_table_values(dme, d, spec, var_names, ridx)
```

Inputs

- **dme** (*mp.dm_element* (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))
- **spec** (*struct*) – import specification, see [get_import_spec\(\)](#) (page 64)
- **var_names** (*cell array*) – (optional) list of names of variables (columns of main table) to import (*default is all variables*)
- **ridx** (*integer*) – (optional) vector of row indices of data to import (*default is all rows*)

Output

dme (*mp.dm_element* (page 35)) – updated data model element object

Called by [import\(\)](#) (page 65).

get_input_table_values(*d*, *spec*, *var_names*, *ridx*)

Get values to insert in data model element table.

```
vals = dmce.get_input_table_values(d, spec, var_names, ridx)
```

Inputs

- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))
- **spec** (*struct*) – import specification, see [get_import_spec\(\)](#) (page 64)
- **var_names** (*cell array*) – (optional) list of names of variables (columns of main table) to import (*default is all variables*)
- **ridx** (*integer*) – (optional) vector of row indices of data to import (*default is all rows*)

Output

vals (*cell array*) – values to assign to table columns in data model element

Called by [import_table_values\(\)](#) (page 66).

import_col(*d*, *spec*, *vn*, *c*, *sf*)

Extract and optionally modify values from data source column.

```
vals = dmce.import_col(d, spec, vn, c, sf)
```

Inputs

- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for `mp.dm_converter_mpc2` (page 61))
- **spec** (*struct*) – import specification, see `get_import_spec()` (page 64)
- **vn** (*char array*) – variable name
- **c** (*integer*) – column index for data in data source
- **sf** (*double or function handle*) – (optional) scale factor, function is called as `sf(dmce, vn)`

Output

vals (*cell array*) – values to assign to table columns in data model element

Called by `get_input_table_values()` (page 66).

export(*dme, d, var_names, ridx*)

Export data from data model element to data source.

```
d = dmce.export(dme, d, var_names, ridx)
```

Inputs

- **dme** (*mp.dm_element* (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for `mp.dm_converter_mpc2` (page 61))
- **var_names** (*cell array*) – (optional) list of names of variables (columns of main table) to export (*default is all variables*)
- **ridx** (*integer*) – (optional) vector of row indices of data to export (*default is all rows*)

Output

d – updated data source

See also `import()` (page 65).

export_table_values(*dme, d, spec, var_names, ridx*)

Export table values for given import specification.

```
d = dmce.export_table_values(dme, d, spec, var_names, ridx)
```

Inputs

- **dme** (*mp.dm_element* (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for `mp.dm_converter_mpc2` (page 61))
- **spec** (*struct*) – export specification, see `get_export_spec()` (page 64)
- **var_names** (*cell array*) – (optional) list of names of variables (columns of main table) to export (*default is all variables*)
- **ridx** (*integer*) – (optional) vector of row indices of data to export (*default is all rows*)

Output

d – updated data source

Called by `export()` (page 67).

init_export_data(*dme, d, spec*)

Initialize data source for export from data model element.

```
d = dmce.init_export_data(dme, d, spec)
```

Inputs

- **dme** (*mp.dm_element* (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for `mp.dm_converter_mpc2` (page 61))
- **spec** (*struct*) – export specification, see `get_export_spec()` (page 64)

Output

d – updated data source

Called by [export_table_values\(\)](#) (page 67).

default_export_data_table(spec)

Create default (empty) data table for data source.

```
dt = dmce.default_export_data_table(spec)
```

Input

spec (*struct*) – export specification, see [get_export_spec\(\)](#) (page 64)

Output

dt – data table for data source, type depends on implementing subclass

Called by [init_export_data\(\)](#) (page 67).

default_export_data_nrows(spec)

Get number of rows for [default_export_data_table\(\)](#) (page 68).

```
nr = default_export_data_nrows(spec)
```

Input

spec (*struct*) – export specification, see [get_export_spec\(\)](#) (page 64)

Output

nr (*integer*) – number of rows

Called by [default_export_data_table\(\)](#) (page 68).

export_col(dme, d, spec, vn, ridx, c, sf)

Export a variable (table column) to the data source.

```
d = dmce.export_col(dme, d, spec, vn, ridx, c, sf)
```

Inputs

- **dme** (*mp.dm_element* (page 35)) – data model element object
- **d** – data source, type depends on the implementing subclass (e.g. MATPOWER case struct for *mp.dm_converter_mpc2* (page 61))
- **spec** (*struct*) – export specification, see [get_export_spec\(\)](#) (page 64)
- **vn** (*char array*) – variable name
- **ridx** (*integer*) – (*optional*) vector of row indices of data to export (*default is all rows*)
- **c** (*integer*) – column index for data in data source
- **sf** (*double or function handle*) – (*optional*) scale factor, function is called as *sf(dmce, vn)*

Output

d – updated data source

Called by [export_table_values\(\)](#) (page 67).

mp.dmce_branch_mpc2

class mp.dmce_branch_mpc2

Bases: [mp.dmc_element](#) (page 62)

[mp.dmce_branch_mpc2](#) (page 69) - Data model converter element for branch for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

default_export_data_table(*spec*)

mp.dmce_bus_mpc2

class mp.dmce_bus_mpc2

Bases: [mp.dmc_element](#) (page 62)

[mp.dmce_bus_mpc2](#) (page 69) - Data model converter element for bus for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

init_export_data(*dme*, *d*, *spec*)

default_export_data_table(*spec*)

bus_name_import(*mpc*, *spec*, *vn*, *c*)

bus_name_export(*dme*, *mpc*, *spec*, *vn*, *ridx*, *c*)

bus_status_import(*mpc*, *spec*, *vn*, *c*)

mp.dmce_gen_mpc2

class mp.dmce_gen_mpc2

Bases: [mp.dmc_element](#) (page 62)

[mp.dmce_gen_mpc2](#) (page 69) - Data model converter element for generator for MATPOWER case v2.

Property Summary

pwl1

indices of single-block piecewise linear costs, all gens (*automatically converted to linear cost*)

Method Summary

name()

data_field()

table_var_map(*dme, mpc*)

default_export_data_table(*spec*)

start_cost_import(*mpc, spec, vn*)

start_cost_export(*dme, mpc, spec, vn, ridx*)

gen_cost_import(*mpc, spec, vn, p_or_q*)

gen_cost_export(*dme, mpc, spec, vn, p_or_q, ridx*)

static gencost2cost_table(*gencost*)

static cost_table2gencost(*gencost0, cost, ridx*)

mp.dmce_load_mpc2

class mp.dmce_load_mpc2

Bases: [mp.dmc_element](#) (page 62)

[mp.dmce_load_mpc2](#) (page 70) - Data model converter element for load for MATPOWER case v2.

Property Summary

bus

Method Summary

name()

data_field()

get_import_size(*mpc*)

get_export_size(*dme*)

table_var_map(*dme, mpc*)

scale_factor_fcn(*vn, zip_sf*)

sys_wide_zip_loads(*mpc*)

mp.dmce_shunt_mpc2

class mp.dmce_shunt_mpc2

Bases: [mp.dmc_element](#) (page 62)

[mp.dmce_shunt_mpc2](#) (page 71) - Data model converter element for shunt for MATPOWER case v2.

Property Summary

bus

Method Summary

name()

data_field()

get_import_size(mpc)

get_export_size(dme)

table_var_map(dme, mpc)

3.4 Network Model Classes

3.4.1 Containers

mp.form

class mp.form

Bases: handle

[mp.form](#) (page 71) - Abstract base class for MATPOWER **formulation**.

Used as a mix-in class for all **network model element** classes. That is, each concrete network model element class must inherit, at least indirectly, from both [mp.nm_element](#) (page 107) and [mp.form](#) (page 71).

[mp.form](#) (page 71) provides properties and methods that are specific to the network model formulation (e.g. DC version, AC polar power version, etc.).

For more details, see the sec_net_model_formulations section in the *MATPOWER Developer's Manual* and the derivations in *MATPOWER Technical Note 5*.

mp.form Properties:

subclasses provide properties for model parameters

mp.form Methods:

- [form_name\(\)](#) (page 72) - get char array w/name of formulation
- [form_tag\(\)](#) (page 72) - get char array w/short label of formulation
- [model_params\(\)](#) (page 72) - get cell array of names of model parameters
- [model_vvars\(\)](#) (page 72) - get cell array of names of voltage state variables
- [model_zvars\(\)](#) (page 72) - get cell array of names of non-voltage state variables

- `get_params()` (page 73) - get network model element parameters
- `find_form_class()` (page 73) - get name of network element object's formulation subclass

See also `mp.nm_element` (page 107).

Method Summary

`form_name()`

Get user-readable name of formulation, e.g. 'DC', 'AC-cartesian', 'AC-polar'.

```
name = nme.form_name()
```

Output

name (*char array*) – name of formulation

Note: This is an abstract method that must be implemented by a subclass.

`form_tag()`

Get short label of formulation, e.g. 'dc', 'acc', 'acp'.

```
tag = nme.form_tag()
```

Output

tag (*char array*) – short label of formulation

Note: This is an abstract method that must be implemented by a subclass.

`model_params()`

Get cell array of names of model parameters.

```
params = nme.model_params()
```

Output

params (*cell array of char arrays*) – names of object properties for model parameters

Note: This is an abstract method that must be implemented by a subclass.

`model_vvars()`

Get cell array of names of voltage state variables.

```
vtypes = nme.model_vvars()
```

Output

vtypes (*cell array of char arrays*) – names of network object properties for voltage state variables

The network model object, which inherits from `mp_idx_manager`, uses these values as set types for tracking its voltage state variables.

Note: This is an abstract method that must be implemented by a subclass.

`model_zvars()`

Get cell array of names of non-voltage state variables.

```
vtypes = nme.model_zvars()
```

Output

vtypes (*cell array of char arrays*) – names of network object properties for voltage state variables

The network model object, which inherits from `mp_idx_manager`, uses these values as set types for tracking its non-voltage state variables.

Note: This is an abstract method that must be implemented by a subclass.

`get_params(idx, names)`

Get network model element parameters.

```
[p1, p2, ..., pN] = nme.get_params(idx)
pA = nme.get_params(idx, nameA)
[pA, pB, ...] = nme.get_params(idx, {nameA, nameB, ...})
```

Inputs

- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns parameters corresponding to all ports
- **names** (*char array or cell array of char arrays*) – (*optional*) name(s) of parameters to return

Outputs

- **p1, p2, ..., pN** – full set of parameters in canonical order
- **pA, pB** – parameters specified by **names**

If a particular parameter in the object is empty, this method returns a sparse zero matrix or vector of the appropriate size.

`find_form_class()`

Get name of network element object's formulation subclass.

```
form_class = nme.find_form_class()
```

Output

form_class (*char array*)

Selects from this network model elements parent classes, the `mp.form` (page 71) subclass, that is not a subclass of `mp.nm_element` (page 107), with the longest inheritance path back to `mp.form` (page 71).

`mp.form_ac`

`class mp.form_ac`

Bases: `mp.form` (page 71)

`mp.form_ac` (page 73) - Abstract base class for MATPOWER AC **formulations**.

Used as a mix-in class for all **network model element** classes with an AC network model formulation. That is, each concrete network model element class with an AC formulation must inherit, at least indirectly, from both `mp.nm_element` (page 107) and `mp.form_ac` (page 73).

`mp.form_ac` (page 73) defines the complex port injections as functions of the state variables **x**, that is, the complex voltages **v** and non-voltage states **z**. They are defined in terms of 3 components, the linear current injection and linear power injection components,

$$\begin{aligned} \mathbf{i}^{lin}(\mathbf{x}) &= \begin{bmatrix} \mathbf{Y} & \mathbf{L} \end{bmatrix} \mathbf{x} + \mathbf{i} \\ &= \mathbf{Y}\mathbf{v} + \mathbf{L}\mathbf{z} + \mathbf{i} \end{aligned} \quad (3.2)$$

$$\begin{aligned} \mathbf{s}^{lin}(\mathbf{x}) &= \begin{bmatrix} \mathbf{M} & \mathbf{N} \end{bmatrix} \mathbf{x} + \mathbf{s} \\ &= \mathbf{M}\mathbf{v} + \mathbf{N}\mathbf{z} + \mathbf{s}, \end{aligned} \quad (3.3)$$

and an arbitrary nonlinear injection component represented by $s^{nln}(\mathbf{x})$ or $i^{nln}(\mathbf{x})$. The full complex power and current port injection functions implemented by `mp.form_ac` (page 73), are respectively

$$\begin{aligned} \mathbf{g}^S(\mathbf{x}) &= [\mathbf{v}] (\mathbf{i}^{lin}(\mathbf{x}))^* + \mathbf{s}^{lin}(\mathbf{x}) + \mathbf{s}^{nln}(\mathbf{x}) \\ &= [\mathbf{v}] (\mathbf{Y}\mathbf{v} + \mathbf{L}\mathbf{z} + \mathbf{i})^* + \mathbf{M}\mathbf{v} + \mathbf{N}\mathbf{z} + \mathbf{s} + \mathbf{s}^{nln}(\mathbf{x}) \end{aligned} \quad (3.4)$$

$$\begin{aligned} \mathbf{g}^I(\mathbf{x}) &= \mathbf{i}^{lin}(\mathbf{x}) + [\mathbf{s}^{lin}(\mathbf{x})]^* \mathbf{\Lambda}^* + \mathbf{i}^{nln}(\mathbf{x}) \\ &= \mathbf{Y}\mathbf{v} + \mathbf{L}\mathbf{z} + \mathbf{i} + [\mathbf{M}\mathbf{v} + \mathbf{N}\mathbf{z} + \mathbf{s}]^* \mathbf{\Lambda}^* + \mathbf{i}^{nln}(\mathbf{x}) \end{aligned} \quad (3.5)$$

where \mathbf{Y} , \mathbf{L} , \mathbf{M} , \mathbf{N} , \mathbf{i} , and \mathbf{s} , along with $s^{nln}(\mathbf{x})$ or $i^{nln}(\mathbf{x})$, are the model parameters.

For more details, see the `sec_nm_formulations_ac` section in the *MATPOWER Developer's Manual* and the derivations in *MATPOWER Technical Note 5*.

mp.form_dc Properties:

- Y (page 75) - $n_p n_k \times n_n$ matrix \mathbf{Y} of model parameters
- L (page 75) - $n_p n_k \times n_z$ matrix \mathbf{L} of model parameters
- M (page 75) - $n_p n_k \times n_n$ matrix \mathbf{M} of model parameters
- N (page 75) - $n_p n_k \times n_z$ matrix \mathbf{N} of model parameters
- i (page 75) - $n_p n_k \times 1$ vector \mathbf{i} of model parameters
- s (page 75) - $n_p n_k \times 1$ vector \mathbf{s} of model parameters
- `params_ncols` - specify number of columns for each parameter
- `inln` (page 75) - function to compute $i^{nln}(\mathbf{x})$
- `snln` (page 75) - function to compute $s^{nln}(\mathbf{x})$
- `inln_hess` (page 75) - function to compute Hessian of $i^{nln}(\mathbf{x})$
- `snln_hess` (page 75) - function to compute Hessian of $s^{nln}(\mathbf{x})$

mp.form_dc Methods:

- `model_params()` (page 76) - get network model element parameters (`{'Y', 'L', 'M', 'N', 'i', 's'}`)
- `model_zvars()` (page 76) - get cell array of names of non-voltage state variables (`{'zr', 'zi'}`)
- `port_inj_current()` (page 76) - compute port current injections from network state
- `port_inj_power()` (page 76) - compute port power injections from network state
- `port_inj_current_hess()` (page 77) - compute Hessian of port current injections
- `port_inj_power_hess()` (page 78) - compute Hessian of port power injections
- `port_inj_current_jac()` (page 78) - abstract method to compute voltage-related Jacobian terms
- `port_inj_current_hess_v()` (page 78) - abstract method to compute voltage-related Hessian terms
- `port_inj_current_hess_vz()` (page 78) - abstract method to compute voltage-related Hessian terms
- `port_inj_power_jac()` (page 78) - abstract method to compute voltage-related Jacobian terms
- `port_inj_power_hess_v()` (page 78) - abstract method to compute voltage-related Hessian terms
- `port_inj_power_hess_vz()` (page 79) - abstract method to compute voltage-related Hessian terms

- `port_apparent_power_lim_fcn()` (page 79) - compute port squared apparent power injection constraints
- `port_active_power_lim_fcn()` (page 79) - compute port active power injection constraints
- `port_active_power2_lim_fcn()` (page 79) - compute port squared active power injection constraints
- `port_current_lim_fcn()` (page 80) - compute port squared current injection constraints
- `port_apparent_power_lim_hess()` (page 80) - compute port squared apparent power injection Hessian
- `port_active_power_lim_hess()` (page 81) - compute port active power injection Hessian
- `port_active_power2_lim_hess()` (page 81) - compute port squared active power injection Hessian
- `port_current_lim_hess()` (page 81) - compute port squared current injection Hessian
- `aux_data_va_vm()` (page 82) - abstract method to return voltage angles/magnitudes from auxiliary data

See also `mp.form` (page 71), `mp.form_acc` (page 82), `mp.form_acp` (page 86), `mp.form_dc` (page 88), `mp.nm_element` (page 107).

Property Summary

Y = []
(double) $n_p n_k \times n_n$ matrix **Y** of model parameter coefficients for **v**

L = []
(double) $n_p n_k \times n_z$ matrix **L** of model parameter coefficients for **z**

M = []
(double) $n_p n_k \times n_n$ matrix **M** of model parameter coefficients for **v**

N = []
(double) $n_p n_k \times n_z$ matrix **N** of model parameter coefficients for **z**

i = []
(double) $n_p n_k \times 1$ vector **i** of model parameters

s = []
(double) $n_p n_k \times 1$ vector **s** of model parameters

param_ncols = `struct('Y',2,'L',3,'M',2,'N',3,'i',1,'s',1)`
(struct) specify number of columns for each parameter, where

- 1 => single column (i.e. a vector)
- 2 => n_p columns
- 3 => n_z columns

inln = ''
(function handle) function to compute $\mathbf{i}^{nln}(\mathbf{x})$

snln = ''
(function handle) function to compute $\mathbf{s}^{nln}(\mathbf{x})$

inln_hess = ''
(function handle) function to compute Hessian of $\mathbf{i}^{nln}(\mathbf{x})$

snln_hess = ''

(function handle) function to compute Hessian of $s^{nln}(\mathbf{x})$

Method Summary

model_params()

Get cell array of names of model parameters, i.e. {'Y', 'L', 'M', 'N', 'i', 's'}.

See [mp.form.model_params\(\)](#) (page 72).

model_zvars()

Get cell array of names of non-voltage state variables, i.e. {'zr', 'zi'}.

See [mp.form.model_zvars\(\)](#) (page 72).

port_inj_current(x_, sysx, idx)

Compute port complex current injections from network state.

```
I = nme.port_inj_current(x_, sysx)
I = nme.port_inj_current(x_, sysx, idx)
[I, Iv1, Iv2] = nme.port_inj_current(...)
[I, Iv1, Iv2, Izr, Izi] = nme.port_inj_current(...)
```

Compute the complex current injections for all or a selected subset of ports and, optionally, the components of the Jacobian, that is, the sparse matrices of partial derivatives with respect to each real component of the state. The voltage portion, which depends on the formulation (polar vs cartesian), is delegated to the `port_inj_current_jac()` method implemented by the appropriate subclass.

The state can be provided as a stacked aggregate of the state variables (port voltages and non-voltage states) for the full collection of network model elements of this type, or as the combined state for the entire network.

Inputs

- **x_** (complex double) – state vector \mathbf{x}
- **sysx** (0 or 1) – which state is provided in $\mathbf{x}_$
 - 0 – class aggregate state
 - 1 – (default) full system state
- **idx** (integer) – (optional) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs

- **I** (complex double) – vector of port complex current injections, $\mathbf{g}^I(\mathbf{x})$
- **Iv1** (complex double) – Jacobian of port complex current injections w.r.t 1st voltage component, \mathbf{g}_{θ}^I (polar) or \mathbf{g}_u^I (cartesian)
- **Iv2** (complex double) – Jacobian of port complex current injections w.r.t 2nd voltage component, \mathbf{g}_v^I (polar) or \mathbf{g}_w^I (cartesian)
- **Izr** (complex double) – Jacobian of port complex current injections w.r.t real part of non-voltage state, $\mathbf{g}_{z_r}^I$
- **Izi** (complex double) – Jacobian of port complex current injections w.r.t imaginary part of non-voltage state, $\mathbf{g}_{z_i}^I$

For details on the derivations of the formulas used, see [MATPOWER Technical Note 5](#).

See also [port_inj_power\(\)](#) (page 76).

port_inj_power(x_, sysx, idx)

Compute port complex power injections from network state.

```
S = nme.port_inj_power(x_, sysx)
S = nme.port_inj_power(x_, sysx, idx)
```

(continues on next page)

(continued from previous page)

```
[S, Sv1, Sv2] = nme.port_inj_power(...)
[S, Sv1, Sv2, Szr, Szi] = nme.port_inj_power(...)
```

Compute the complex power injections for all or a selected subset of ports and, optionally, the components of the Jacobian, that is, the sparse matrices of partial derivatives with respect to each real component of the state. The voltage portion, which depends on the formulation (polar vs cartesian), is delegated to the `port_inj_power_jac()` method implemented by the appropriate subclass.

The state can be provided as a stacked aggregate of the state variables (port voltages and non-voltage states) for the full collection of network model elements of this type, or as the combined state for the entire network.

Inputs

- **x_** (*complex double*) – state vector \mathbf{x}
- **sysx** (*0 or 1*) – which state is provided in **x_**
 - 0 – class aggregate state
 - 1 – (*default*) full system state
- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs

- **S** (*complex double*) – vector of port complex power injections, $\mathbf{g}^S(\mathbf{x})$
- **Sv1** (*complex double*) – Jacobian of port complex power injections w.r.t 1st voltage component, \mathbf{g}_θ^S (polar) or \mathbf{g}_u^S (cartesian)
- **Sv2** (*complex double*) – Jacobian of port complex power injections w.r.t 2nd voltage component, \mathbf{g}_ν^S (polar) or \mathbf{g}_w^S (cartesian)
- **Szr** (*complex double*) – Jacobian of port complex power injections w.r.t real part of non-voltage state, $\mathbf{g}_{z_r}^S$
- **Szi** (*complex double*) – Jacobian of port complex power injections w.r.t imaginary part of non-voltage state, $\mathbf{g}_{z_i}^S$.

For details on the derivations of the formulas used, see [MATPOWER Technical Note 5](#).

See also [port_inj_current\(\)](#) (page 76).

port_inj_current_hess(x_, lam, sysx, idx)

Compute Hessian of port current injections from network state.

```
H = nme.port_inj_current_hess(x_, lam)
H = nme.port_inj_current_hess(x_, lam, sysx)
H = nme.port_inj_current_hess(x_, lam, sysx, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by multiplying the transpose of the port current injection Jacobian by a vector $\boldsymbol{\lambda}$.

Inputs

- **x_** (*complex double*) – state vector \mathbf{x}
- **lam** (*double*) – vector $\boldsymbol{\lambda}$ of multipliers, one for each port
- **sysx** (*0 or 1*) – which state is provided in **x_**
 - 0 – class aggregate state
 - 1 – (*default*) full system state
- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs

H (*complex double*) – sparse Hessian matrix of port complex current injections corresponding to specified $\boldsymbol{\lambda}$, namely $\mathbf{g}_{\mathbf{xx}}^I(\boldsymbol{\lambda})$

For details on the derivations of the formulas used, see [MATPOWER Technical Note 5](#).

See also [port_inj_current\(\)](#) (page 76).

port_inj_power_hess(*x_*, *lam*, *sysx*, *idx*)

Compute Hessian of port power injections from network state.

```
H = nme.port_inj_power_hess(x_, lam)
H = nme.port_inj_power_hess(x_, lam, sysx)
H = nme.port_inj_power_hess(x_, lam, sysx, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by multiplying the transpose of the port power injection Jacobian by a vector λ .

Inputs

- **x_** (*complex double*) – state vector \mathbf{x}
- **lam** (*double*) – vector λ of multipliers, one for each port
- **sysx** (*0 or 1*) – which state is provided in **x_**
 - 0 – class aggregate state
 - 1 – (*default*) full system state
- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs

H (*complex double*) – sparse Hessian matrix of port complex power injections corresponding to specified λ , namely $\mathbf{g}_{\mathbf{xx}}^S(\lambda)$

For details on the derivations of the formulas used, see [MATPOWER Technical Note 5](#).

See also [port_inj_power\(\)](#) (page 76).

port_inj_current_jac(*n*, *v_*, *Y*, *M*, *invdiagvic*, *diagSlincJ*)

Abstract method to compute voltage-related Jacobian terms.

Called by [port_inj_current\(\)](#) (page 76) to compute voltage-related Jacobian terms. See [mp.form_acc.port_inj_current_jac\(\)](#) (page 83) and [mp.form_acp.port_inj_current_jac\(\)](#) (page 87) for details.

port_inj_current_hess_v(*x_*, *lam*, *v_*, *z_*, *diaginvic*, *Y*, *M*, *diagSlincJ*, *diamJ*)

Abstract method to compute voltage-related Hessian terms.

Called by [port_inj_current_hess\(\)](#) (page 77) to compute voltage-related Hessian terms. See [mp.form_acc.port_inj_current_hess_v\(\)](#) (page 83) and [mp.form_acp.port_inj_current_hess_v\(\)](#) (page 87) for details.

port_inj_current_hess_vz(*x_*, *lam*, *v_*, *z_*, *diaginvic*, *N*, *diamJ*)

Abstract method to compute voltage-related Hessian terms.

Called by [port_inj_current_hess\(\)](#) (page 77) to compute voltage/non-voltage-related Hessian terms. See [mp.form_acc.port_inj_current_hess_vz\(\)](#) (page 83) and [mp.form_acp.port_inj_current_hess_vz\(\)](#) (page 87) for details.

port_inj_power_jac(*n*, *v_*, *Y*, *M*, *diagv*, *diagvi*, *diagIlincJ*)

Abstract method to compute voltage-related Jacobian terms.

Called by [port_inj_power\(\)](#) (page 76) to compute voltage-related Jacobian terms. See [mp.form_acc.port_inj_power_jac\(\)](#) (page 84) and [mp.form_acp.port_inj_power_jac\(\)](#) (page 87) for details.

port_inj_power_hess_v(*x_*, *lam*, *v_*, *z_*, *diagvi*, *Y*, *M*, *diagIlincJ*, *diamJ*)

Abstract method to compute voltage-related Hessian terms.

Called by `port_inj_power_hess()` (page 78) to compute voltage-related Hessian terms. See `mp.form_acc.port_inj_power_hess_v()` (page 84) and `mp.form_acp.port_inj_power_hess_v()` (page 87) for details.

port_inj_power_hess_vz(*x_*, *lam*, *v_*, *z_*, *diagvi*, *L*, *diamJ*)

Abstract method to compute voltage-related Hessian terms.

Called by `port_inj_power_hess()` (page 78) to compute voltage/non-voltage-related Hessian terms. See `mp.form_acc.port_inj_power_hess_vz()` (page 84) and `mp.form_acp.port_inj_power_hess_vz()` (page 88) for details.

port_apparent_power_lim_fcn(*x_*, *nm*, *idx*, *hmax*)

Compute port squared apparent power injection constraints.

```
h = nme.port_apparent_power_lim_fcn(x_, nm, idx, hmax)
[h, dh] = nme.port_apparent_power_lim_fcn(x_, nm, idx, hmax)
```

Compute constraint function and optionally the Jacobian for the limit on port squared apparent power injections based on complex outputs of `port_inj_power()` (page 76).

Inputs

- **x_** (*complex double*) – state vector \mathbf{x}
- **nm** (`mp.net_model` (page 90)) – network model object
- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports
- **hmax** (*double*) – vector of squared apparent power limits

Outputs

- **h** (*double*) – constraint function, $\mathbf{h}^{\text{flow}}(\mathbf{x})$
- **dh** (*double*) – constraint Jacobian, $\mathbf{h}_x^{\text{flow}}$

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also `port_inj_power()` (page 76).

port_active_power_lim_fcn(*x_*, *nm*, *idx*, *hmax*)

Compute port active power injection constraints.

```
h = nme.port_active_power_lim_fcn(x_, nm, idx, hmax)
[h, dh] = nme.port_active_power_lim_fcn(x_, nm, idx, hmax)
```

Compute constraint function and optionally the Jacobian for the limit on port active power injections based on complex outputs of `port_inj_power()` (page 76).

Inputs

- **x_** (*complex double*) – state vector \mathbf{x}
- **nm** (`mp.net_model` (page 90)) – network model object
- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports
- **hmax** (*double*) – vector of active power limits

Outputs

- **h** (*double*) – constraint function, $\mathbf{h}^{\text{flow}}(\mathbf{x})$
- **dh** (*double*) – constraint Jacobian, $\mathbf{h}_x^{\text{flow}}$

For details on the derivations of the formulas used, see *MATPOWER Technical Note 5*.

See also `port_inj_power()` (page 76).

port_active_power2_lim_fcn(*x_*, *nm*, *idx*, *hmax*)

Compute port squared active power injection constraints.

```
h = nme.port_active_power2_lim_fcn(x_, nm, idx, hmax)
[h, dh] = nme.port_active_power2_lim_fcn(x_, nm, idx, hmax)
```

Compute constraint function and optionally the Jacobian for the limit on port squared active power injections based on complex outputs of [port_inj_power\(\)](#) (page 76).

Inputs

- **x_** (*complex double*) – state vector \mathbf{x}
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports
- **hmax** (*double*) – vector of squared active power limits

Outputs

- **h** (*double*) – constraint function, $\mathbf{h}^{\text{flow}}(\mathbf{x})$
- **dh** (*double*) – constraint Jacobian, $\mathbf{h}_x^{\text{flow}}$

For details on the derivations of the formulas used, see [MATPOWER Technical Note 5](#).

See also [port_inj_power\(\)](#) (page 76).

port_current_lim_fcn(*x_, nm, idx, hmax*)

Compute port squared current injection constraints.

```
h = nme.port_current_lim_fcn(x_, nm, idx, hmax)
[h, dh] = nme.port_current_lim_fcn(x_, nm, idx, hmax)
```

Compute constraint function and optionally the Jacobian for the limit on port squared current injections based on complex outputs of [port_inj_current\(\)](#) (page 76).

Inputs

- **x_** (*complex double*) – state vector \mathbf{x}
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports
- **hmax** (*double*) – vector of squared current limits

Outputs

- **h** (*double*) – constraint function, $\mathbf{h}^{\text{flow}}(\mathbf{x})$
- **dh** (*double*) – constraint Jacobian, $\mathbf{h}_x^{\text{flow}}$

For details on the derivations of the formulas used, see [MATPOWER Technical Note 5](#).

See also [port_inj_current\(\)](#) (page 76).

port_apparent_power_lim_hess(*x_, lam, nm, idx*)

Compute port squared apparent power injection Hessian.

```
d2H = nme.port_apparent_power_lim_hess(x_, lam, nm, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by multiplying the transpose of the constraint Jacobian by a vector $\boldsymbol{\mu}$. Results are based on the complex outputs of [port_inj_power\(\)](#) (page 76) and [port_inj_power_hess\(\)](#) (page 78).

Inputs

- **x_** (*complex double*) – state vector \mathbf{x}
- **lam** (*double*) – vector $\boldsymbol{\mu}$ of multipliers, one for each port
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs**d2H** (*double*) – sparse constraint Hessian matrix, $h_{xx}^{\text{flow}}(\mu)$ For details on the derivations of the formulas used, see [MATPOWER Technical Note 5](#).See also [port_inj_power\(\)](#) (page 76), [port_inj_power_hess\(\)](#) (page 78).**port_active_power_lim_hess**(*x_*, *lam*, *nm*, *idx*)

Compute port active power injection Hessian.

```
d2H = nme.port_active_power_lim_hess(x_, lam, nm, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by multiplying the transpose of the constraint Jacobian by a vector μ . Results are based on the complex outputs of [port_inj_power\(\)](#) (page 76) and [port_inj_power_hess\(\)](#) (page 78).

Inputs

- **x_** (*complex double*) – state vector x
- **lam** (*double*) – vector μ of multipliers, one for each port
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs**d2H** (*double*) – sparse constraint Hessian matrix, $h_{xx}^{\text{flow}}(\mu)$ For details on the derivations of the formulas used, see [MATPOWER Technical Note 5](#).See also [port_inj_power\(\)](#) (page 76), [port_inj_power_hess\(\)](#) (page 78).**port_active_power2_lim_hess**(*x_*, *lam*, *nm*, *idx*)

Compute port squared active power injection Hessian.

```
d2H = nme.port_active_power2_lim_hess(x_, lam, nm, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by multiplying the transpose of the constraint Jacobian by a vector μ . Results are based on the complex outputs of [port_inj_power\(\)](#) (page 76) and [port_inj_power_hess\(\)](#) (page 78).

Inputs

- **x_** (*complex double*) – state vector x
- **lam** (*double*) – vector μ of multipliers, one for each port
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs**d2H** (*double*) – sparse constraint Hessian matrix, $h_{xx}^{\text{flow}}(\mu)$ For details on the derivations of the formulas used, see [MATPOWER Technical Note 5](#).See also [port_inj_power\(\)](#) (page 76), [port_inj_power_hess\(\)](#) (page 78).**port_current_lim_hess**(*x_*, *lam*, *nm*, *idx*)

Compute port squared current injection Hessian.

```
d2H = nme.port_current_lim_hess(x_, lam, nm, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by multiplying the transpose of the constraint Jacobian by a vector μ . Results are based on the complex outputs of [port_inj_current\(\)](#) (page 76) and [port_inj_current_hess\(\)](#) (page 77).

Inputs

- **x_** (*complex double*) – state vector \mathbf{x}
- **lam** (*double*) – vector $\boldsymbol{\mu}$ of multipliers, one for each port
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs

d2H (*double*) – sparse constraint Hessian matrix, $\mathbf{h}_{xx}^{\text{flow}}(\boldsymbol{\mu})$

For details on the derivations of the formulas used, see [MATPOWER Technical Note 5](#).

See also [port_inj_current\(\)](#) (page 76), [port_inj_current_hess\(\)](#) (page 77).

aux_data_va_vm(ad)

Abstract method to return voltage angles/magnitudes from auxiliary data.

```
[va, vm] = nme.aux_data_va_vm(ad)
```

Input

ad (*struct*) – struct of auxiliary data

Outputs

- **va** (*double*) – vector of voltage angles corresponding to voltage information stored in auxiliary data
- **vm** (*double*) – vector of voltage magnitudes corresponding to voltage information stored in auxiliary data

Implemented by [mp.form_acc.aux_data_va_vm\(\)](#) (page 84) and [mp.form_acp.aux_data_va_vm\(\)](#) (page 88).

mp.form_acc**class mp.form_acc**

Bases: [mp.form_ac](#) (page 73)

[mp.form_acc](#) (page 82) - Base class for MATPOWER AC cartesian **formulations**.

Used as a mix-in class for all **network model element** classes with an AC network model formulation with a **cartesian** representation for voltages. That is, each concrete network model element class with an AC cartesian formulation must inherit, at least indirectly, from both [mp.nm_element](#) (page 107) and [mp.form_acc](#) (page 82).

Provides implementation of evaluation of voltage-related Jacobian and Hessian terms needed by some [mp.form_ac](#) (page 73) methods.

mp.form_dc Methods:

- [form_name\(\)](#) (page 83) - get char array w/name of formulation ('AC-cartesian')
- [form_tag\(\)](#) (page 83) - get char array w/short label of formulation ('acc')
- [model_vvars\(\)](#) (page 83) - get cell array of names of voltage state variables ({'vr', 'vi'})
- [port_inj_current_jac\(\)](#) (page 83) - compute voltage-related terms of current injection Jacobian
- [port_inj_current_hess_v\(\)](#) (page 83) - compute voltage-related terms of current injection Hessian
- [port_inj_current_hess_vz\(\)](#) (page 83) - compute voltage/non-voltage-related terms of current injection Hessian

- `port_inj_power_jac()` (page 84) - compute voltage-related terms of power injection Jacobian
- `port_inj_power_hess_v()` (page 84) - compute voltage-related terms of power injection Hessian
- `port_inj_power_hess_vz()` (page 84) - compute voltage/non-voltage-related terms of power injection Hessian
- `aux_data_va_vm()` (page 84) - return voltage angles/magnitudes from auxiliary data
- `va_fcn()` (page 84) - compute voltage angle constraints and Jacobian
- `va_hess()` (page 85) - compute voltage angle Hessian
- `vm2_fcn()` (page 85) - compute squared voltage magnitude constraints and Jacobian
- `vm2_hess()` (page 85) - compute squared voltage magnitude Hessian

For more details, see the `sec_nm_formulations_ac` section in the *MATPOWER Developer's Manual* and the derivations in *MATPOWER Technical Note 5*.

See also `mp.form` (page 71), `mp.form_ac` (page 73), `mp.form_acp` (page 86), `mp.nm_element` (page 107).

Method Summary

`form_name()`

Get user-readable name of formulation, i.e. 'AC-cartesian'.

See `mp.form.form_name()` (page 72).

`form_tag()`

Get short label of formulation, i.e. 'acc'.

See `mp.form.form_tag()` (page 72).

`model_vvars()`

Get cell array of names of voltage state variables, i.e. {'vr', 'vi'}.

See `mp.form.model_vvars()` (page 72).

`port_inj_current_jac(n, v_, Y, M, invdiagvic, diagSlineJ)`

Compute voltage-related terms of current injection Jacobian.

```
[Iu, Iw] = nme.port_inj_current_jac(n, v_, Y, M, invdiagvic, diagSlineJ)
```

Called by `mp.form_ac.port_inj_current()` (page 76) to compute voltage-related Jacobian terms.

`port_inj_current_hess_v(x_, lam, v_, z_, diaginvic, Y, M, diagSlineJ, dlamJ)`

Compute voltage-related terms of current injection Hessian.

```
[Iuu, Iuw, Iww] = nme.port_inj_current_hess_v(x_, lam)
[Iuu, Iuw, Iww] = nme.port_inj_current_hess_v(x_, lam, sysx)
[Iuu, Iuw, Iww] = nme.port_inj_current_hess_v(x_, lam, sysx, idx)
[...] = nme.port_inj_current_hess_vz(x_, lam, v_, z_, diaginvic, Y, M,
    diagSlineJ, dlamJ)
```

Called by `mp.form_ac.port_inj_current_hess()` (page 77) to compute voltage-related Hessian terms.

`port_inj_current_hess_vz(x_, lam, v_, z_, diaginvic, N, dlamJ)`

Compute voltage/non-voltage-related terms of current injection Hessian.


```
[Iuzr, Iuzi, Iwzr, Iwzi] = nme.port_inj_current_hess_vz(x_, lam)
[...] = nme.port_inj_current_hess_vz(x_, lam, sysx)
[...] = nme.port_inj_current_hess_vz(x_, lam, sysx, idx)
[...] = nme.port_inj_current_hess_vz(x_, lam, v_, z_, diaginvic, N, dlamJ)
```

Called by `mp.form_ac.port_inj_current_hess()` (page 77) to compute voltage/non-voltage-related Hessian terms.

port_inj_power_jac(*n*, *v_*, *Y*, *M*, *diagv*, *diagvi*, *diagIlineJ*)

Compute voltage-related terms of power injection Jacobian.

```
[Su, Sw] = nme.port_inj_power_jac(...)
```

Called by `mp.form_ac.port_inj_power()` (page 76) to compute voltage-related Jacobian terms.

port_inj_power_hess_v(*x_*, *lam*, *v_*, *z_*, *diagvi*, *Y*, *M*, *diagIlineJ*, *dlamJ*)

Compute voltage-related terms of power injection Hessian.

```
[Suu, Suw, Sww] = nme.port_inj_power_hess_v(x_, lam)
[Suu, Suw, Sww] = nme.port_inj_power_hess_v(x_, lam, sysx)
[Suu, Suw, Sww] = nme.port_inj_power_hess_v(x_, lam, sysx, idx)
[...] = nme.port_inj_power_hess_v(x_, lam, v_, z_, diagvi, Y, M, diagIlineJ,
↪ dlamJ)
```

Called by `mp.form_ac.port_inj_power_hess()` (page 78) to compute voltage-related Hessian terms.

port_inj_power_hess_vz(*x_*, *lam*, *v_*, *z_*, *diagvi*, *L*, *dlamJ*)

Compute voltage/non-voltage-related terms of power injection Hessian.

```
[Suzr, Suzi, Swzr, Swzi] = nme.port_inj_power_hess_vz(x_, lam)
[...] = nme.port_inj_power_hess_vz(x_, lam, sysx)
[...] = nme.port_inj_power_hess_vz(x_, lam, sysx, idx)
[...] = nme.port_inj_power_hess_vz(x_, lam, v_, z_, diagvi, L, dlamJ)
```

Called by `mp.form_ac.port_inj_power_hess()` (page 78) to compute voltage/non-voltage-related Hessian terms.

aux_data_va_vm(*ad*)

Return voltage angles/magnitudes from auxiliary data.

```
[va, vm] = nme.aux_data_va_vm(ad)
```

Converts from cartesian voltage data stored in *ad.vr* and *ad.vi*.

Input

ad (*struct*) – struct of auxiliary data

Outputs

- **va** (*double*) – vector of voltage angles corresponding to voltage information stored in auxiliary data
- **vm** (*double*) – vector of voltage magnitudes corresponding to voltage information stored in auxiliary data

va_fcn(*xx*, *idx*, *lim*)

Compute voltage angle constraints and Jacobian.


```
g = nme.va_fcn(xx, idx, lim)
[g, dg] = nme.va_fcn(xx, idx, lim)
```

Compute constraint function and optionally the Jacobian for voltage angle limits.

Inputs

- **xx** (*1 x 2 cell array*) – real part of complex voltage in **xx{1}**, imaginary part in **xx{2}**
- **idx** (*integer*) – index of subset of voltages of interest to include in constraint; if empty, include all
- **lim** (*double or cell array of double*) – constraint bound(s), can be a vector, for equality constraints or an upper bound, or a cell array with {**va_lb**, **va_ub**} for dual-bound constraints

Outputs

- **g** (*double*) – constraint function, $g(x)$
- **dg** (*double*) – constraint Jacobian, g_x

va_hess(xx, lam, idx)

Compute voltage angle Hessian.

```
d2G = nme.va_hess(xx, lam, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of voltages. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by multiplying the transpose of the constraint Jacobian by a vector λ .

Inputs

- **xx** (*1 x 2 cell array*) – real part of complex voltage in **xx{1}**, imaginary part in **xx{2}**
- **lam** (*double*) – vector λ of multipliers, one for each constraint
- **idx** (*integer*) – index of subset of voltages of interest to include in constraint; if empty, include all

Outputs

- **d2G** (*double*) – sparse constraint Hessian, $g_{xx}(\lambda)$

vm2_fcn(xx, idx, lim)

Compute squared voltage magnitude constraints and Jacobian.

```
g = nme.vm2_fcn(xx, idx, lim)
[g, dg] = nme.vm2_fcn(xx, idx, lim)
```

Compute constraint function and optionally the Jacobian for squared voltage magnitude limits.

Inputs

- **xx** (*1 x 2 cell array*) – real part of complex voltage in **xx{1}**, imaginary part in **xx{2}**
- **idx** (*integer*) – index of subset of voltages of interest to include in constraint; if empty, include all
- **lim** (*double or cell array of double*) – constraint bound(s), can be a vector, for equality constraints or an upper bound, or a cell array with {**vm2_lb**, **vm2_ub**} for dual-bound constraints

Outputs

- **g** (*double*) – constraint function, $g(x)$
- **dg** (*double*) – constraint Jacobian, g_x

vm2_hess(xx, lam, idx)

Compute squared voltage magnitude Hessian.

```
d2G = nme.vm2_hess(xx, lam, idx)
```

Compute a sparse Hessian matrix for all or a selected subset of voltages. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by multiplying the transpose of the constraint Jacobian by a vector λ .

Inputs

- **xx** (*1 x 2 cell array*) – real part of complex voltage in **xx{1}**, imaginary part in **xx{2}**
- **lam** (*double*) – vector λ of multipliers, one for each constraint
- **idx** (*integer*) – index of subset of voltages of interest to include in constraint; if empty, include all

Outputs

d2G (*double*) – sparse constraint Hessian, $g_{xx}(\lambda)$

mp.form_acp

class mp.form_acp

Bases: [mp.form_ac](#) (page 73)

[mp.form_acp](#) (page 86) - Base class for MATPOWER AC polar **formulations**.

Used as a mix-in class for all **network model element** classes with an AC network model formulation with a **polar** representation for voltages. That is, each concrete network model element class with an AC polar formulation must inherit, at least indirectly, from both [mp.nm_element](#) (page 107) and [mp.form_acp](#) (page 86).

Provides implementation of evaluation of voltage-related Jacobian and Hessian terms needed by some [mp.form_ac](#) (page 73) methods.

mp.form_dc Methods:

- [form_name\(\)](#) (page 86) - get char array w/name of formulation ('AC-polar')
- [form_tag\(\)](#) (page 87) - get char array w/short label of formulation ('acp')
- [model_vvars\(\)](#) (page 87) - get cell array of names of voltage state variables ({'va', 'vm'})
- [port_inj_current_jac\(\)](#) (page 87) - compute voltage-related terms of current injection Jacobian
- [port_inj_current_hess_v\(\)](#) (page 87) - compute voltage-related terms of current injection Hessian
- [port_inj_current_hess_vz\(\)](#) (page 87) - compute voltage/non-voltage-related terms of current injection Hessian
- [port_inj_power_jac\(\)](#) (page 87) - compute voltage-related terms of power injection Jacobian
- [port_inj_power_hess_v\(\)](#) (page 87) - compute voltage-related terms of power injection Hessian
- [port_inj_power_hess_vz\(\)](#) (page 88) - compute voltage/non-voltage-related terms of power injection Hessian
- [aux_data_va_vm\(\)](#) (page 88) - return voltage angles/magnitudes from auxiliary data

For more details, see the `sec_nm_formulations_ac` section in the *MATPOWER Developer's Manual* and the derivations in *MATPOWER Technical Note 5*.

See also [mp.form](#) (page 71), [mp.form_ac](#) (page 73), [mp.form_acc](#) (page 82), [mp.nm_element](#) (page 107).

Method Summary

form_name()

Get user-readable name of formulation, i.e. 'AC-polar'.

See [mp.form.form_name\(\)](#) (page 72).

form_tag()

Get short label of formulation, i.e. 'acp'.

See [mp.form.form_tag\(\)](#) (page 72).

model_vvars()

Get cell array of names of voltage state variables, i.e. {'va', 'vm'}.

See [mp.form.model_vvars\(\)](#) (page 72).

port_inj_current_jac(*n, v_, Y, M, invdiagvic, diagSlincJ*)

Compute voltage-related terms of current injection Jacobian.

```
[Iva, Ivm] = nme.port_inj_current_jac(n, v_, Y, M, invdiagvic, diagSlincJ)
```

Called by [mp.form_ac.port_inj_current\(\)](#) (page 76) to compute voltage-related Jacobian terms.

port_inj_current_hess_v(*x_, lam, v_, z_, diaginvic, Y, M, diagSlincJ, dlamJ*)

Compute voltage-related terms of current injection Hessian.

```
[Ivava, Ivavm, Ivmvm] = nme.port_inj_current_hess_v(x_, lam)
[Ivava, Ivavm, Ivmvm] = nme.port_inj_current_hess_v(x_, lam, sysx)
[Ivava, Ivavm, Ivmvm] = nme.port_inj_current_hess_v(x_, lam, sysx, idx)
[...] = nme.port_inj_current_hess_vz(x_, lam, v_, z_, diaginvic, Y, M,
    ↪diagSlincJ, dlamJ)
```

Called by [mp.form_ac.port_inj_current_hess\(\)](#) (page 77) to compute voltage-related Hessian terms.

port_inj_current_hess_vz(*x_, lam, v_, z_, diaginvic, N, dlamJ*)

Compute voltage/non-voltage-related terms of current injection Hessian.

```
[Ivazr, Ivazi, Ivmzr, Ivmzi] = nme.port_inj_current_hess_vz(x_, lam)
[...] = nme.port_inj_current_hess_vz(x_, lam, sysx)
[...] = nme.port_inj_current_hess_vz(x_, lam, sysx, idx)
[...] = nme.port_inj_current_hess_vz(x_, lam, v_, z_, diaginvic, N, dlamJ)
```

Called by [mp.form_ac.port_inj_current_hess\(\)](#) (page 77) to compute voltage/non-voltage-related Hessian terms.

port_inj_power_jac(*n, v_, Y, M, diagv, diagvi, diagIlincJ*)

Compute voltage-related terms of power injection Jacobian.

```
[Sva, Svm] = nme.port_inj_power_jac(...)
```

Called by [mp.form_ac.port_inj_power\(\)](#) (page 76) to compute voltage-related Jacobian terms.

port_inj_power_hess_v(*x_, lam, v_, z_, diagvi, Y, M, diagIlincJ, dlamJ*)

Compute voltage-related terms of power injection Hessian.

```
[Svava, Svavm, Svmvm] = nme.port_inj_power_hess_v(x_, lam)
[Svava, Svavm, Svmvm] = nme.port_inj_power_hess_v(x_, lam, sysx)
[Svava, Svavm, Svmvm] = nme.port_inj_power_hess_v(x_, lam, sysx, idx)
[...] = nme.port_inj_power_hess_v(x_, lam, v_, z_, diagvi, Y, M, diagIlinecJ,
↪ dlamJ)
```

Called by `mp.form_ac.port_inj_power_hess()` (page 78) to compute voltage-related Hessian terms.

port_inj_power_hess_vz(*x_*, *lam*, *v_*, *z_*, *diagvi*, *L*, *dlamJ*)

Compute voltage/non-voltage-related terms of power injection Hessian.

```
[Svazr, Svazi, Svmzr, Svmzi] = nme.port_inj_power_hess_vz(x_, lam)
[...] = nme.port_inj_power_hess_vz(x_, lam, sysx)
[...] = nme.port_inj_power_hess_vz(x_, lam, sysx, idx)
[...] = nme.port_inj_power_hess_vz(x_, lam, v_, z_, diagvi, L, dlamJ)
```

Called by `mp.form_ac.port_inj_power_hess()` (page 78) to compute voltage/non-voltage-related Hessian terms.

aux_data_va_vm(*ad*)

Return voltage angles/magnitudes from auxiliary data.

```
[va, vm] = nme.aux_data_va_vm(ad)
```

Simply returns voltage data stored in `ad.va` and `ad.vm`.

Input

ad (*struct*) – struct of auxiliary data

Outputs

- **va** (*double*) – vector of voltage angles corresponding to voltage information stored in auxiliary data
- **vm** (*double*) – vector of voltage magnitudes corresponding to voltage information stored in auxiliary data

mp.form_dc

class mp.form_dc

Bases: `mp.form` (page 71)

`mp.form_dc` (page 88) - Base class for MATPOWER DC formulations.

Used as a mix-in class for all **network model element** classes with a DC network model formulation. That is, each concrete network model element class with a DC formulation must inherit, at least indirectly, from both `mp.nm_element` (page 107) and `mp.form_dc` (page 88).

`mp.form_dc` (page 88) defines the port active power injection as a linear function of the state variables \mathbf{x} , that is, the voltage angles θ and non-voltage states \mathbf{z} , as

$$\begin{aligned} \mathbf{g}^P(\mathbf{x}) &= \begin{bmatrix} \underline{B} & \underline{K} \end{bmatrix} \mathbf{x} + \underline{p} \\ &= \underline{B}\theta + \underline{K}\mathbf{z} + \underline{p}, \end{aligned} \tag{3.6}$$

where \underline{B} , \underline{K} , and \underline{p} are the model parameters.

For more details, see the `sec_nm_formulations_dc` section in the *MATPOWER Developer's Manual* and the derivations in *MATPOWER Technical Note 5*.

mp.form_dc Properties:

- \underline{B} (page 89) - $n_p n_k \times n_n$ matrix \underline{B} of model parameters
- \underline{K} (page 89) - $n_p n_k \times n_z$ matrix \underline{K} of model parameters
- \underline{p} (page 89) - $n_p n_k \times 1$ vector \underline{p} of model parameters
- `params_ncols` - specify number of columns for each parameter

mp.form_dc Methods:

- `form_name()` (page 89) - get char array w/name of formulation ('DC')
- `form_tag()` (page 89) - get char array w/short label of formulation ('dc')
- `model_params()` (page 89) - get network model element parameters ({'B', 'K', 'p'})
- `model_vvars()` (page 89) - get cell array of names of voltage state variables ({'va'})
- `model_zvars()` (page 90) - get cell array of names of non-voltage state variables ({'z'})
- `port_inj_power()` (page 90) - compute port power injections from network state

See also `mp.form` (page 71), `mp.form_ac` (page 73), `mp.nm_element` (page 107).

Property Summary

B = []

(double) $n_p n_k \times n_n$ matrix \underline{B} of model parameter coefficients for θ

K = []

(double) $n_p n_k \times n_z$ matrix \underline{K} of model parameter coefficients for z

p = []

(double) $n_p n_k \times 1$ vector \underline{p} of model parameters

param_ncols = `struct('B',2,'K',3,'p',1)`

(struct) specify number of columns for each parameter, where

- 1 => single column (i.e. a vector)
- 2 => n_p columns
- 3 => n_z columns

Method Summary

form_name()

Get user-readable name of formulation, i.e. 'DC'.

See `mp.form.form_name()` (page 72).

form_tag()

Get short label of formulation, i.e. 'dc'.

See `mp.form.form_tag()` (page 72).

model_params()

Get cell array of names of model parameters, i.e. {'B', 'K', 'p'}.

See `mp.form.model_params()` (page 72).

model_vvars()

Get cell array of names of voltage state variables, i.e. {'va'}.

See [mp.form.model_vvars\(\)](#) (page 72).

model_zvars()

Get cell array of names of non-voltage state variables, i.e. {'z'}.

See [mp.form.model_zvars\(\)](#) (page 72).

port_inj_power(x, sysx, idx)

Compute port power injections from network state.

```
P = nme.port_inj_power(x, sysx, idx)
```

Compute the active power injections for all or a selected subset of ports.

The state can be provided as a stacked aggregate of the state variables (port voltages and non-voltage states) for the full collection of network model elements of this type, or as the combined state for the entire network.

Inputs

- **x** (*double*) – state vector \mathbf{x}
- **sysx** (*0 or 1*) – which state is provided in **x**
 - 0 – class aggregate state
 - 1 – (*default*) full system state
- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns injections corresponding to all ports

Outputs

P (*double*) – vector of port power injections, $\mathbf{g}^P(\mathbf{x})$

mp.net_model**class mp.net_model**

Bases: [mp.nm_element](#) (page 107), [mp.element_container](#) (page 165), [mp_idx_manager](#)

[mp.net_model](#) (page 90) - Abstract base class for MATPOWER **network model** objects.

The network model defines the states of and connections between network elements, as well as the parameters and functions defining the relationships between states and port injections. A given network model implements a specific network model **formulation**, and defines sets of **nodes**, **ports**, and **states**.

A network model object is primarily a container for network model element ([mp.nm_element](#) (page 107)) objects and *is itself* a network model element. All network model classes inherit from [mp.net_model](#) (page 90) and therefore also from [mp.element_container](#) (page 165), [mp_idx_manager](#), and [mp.nm_element](#) (page 107). Concrete network model classes are also formulation-specific, inheriting from a corresponding subclass of [mp.form](#) (page 71).

By convention, network model variables are named **nm** and network model class names begin with **mp.net_model**.

mp.net_model Properties:

- [the_np](#) (page 92) - total number of ports
- [the_nz](#) (page 92) - total number of non-voltage states
- [nv](#) (page 92) - total number of (real) voltage variables

- `node` (page 92) - `mp_idx_manager` data for nodes
- `port` (page 92) - `mp_idx_manager` data for ports
- `state` (page 92) - `mp_idx_manager` data for non-voltage states

mp.net_model Methods:

- `name()` (page 92) - return name of this network element type ('network')
- `np()` (page 92) - return number of ports for this network element
- `nz()` (page 92) - return number of (*possibly complex*) non-voltage states for this network element
- `build()` (page 92) - create, add, and build network model element objects
- `add_nodes()` (page 92) - elements add nodes, then add corresponding voltage variables
- `add_states()` (page 93) - elements add states, then add corresponding state variables
- `build_params()` (page 93) - build incidence matrices, parameters, add ports for each element
- `stack_matrix_params()` (page 93) - form network matrix parameter by stacking corresponding element parameters
- `stack_vector_params()` (page 93) - form network vector parameter by stacking corresponding element parameters
- `add_vvars()` (page 94) - add voltage variable(s) for each network node
- `add_zvars()` (page 94) - add non-voltage state variable(s) for each network state
- `def_set_types()` (page 94) - define node, state, and port set types for `mp_idx_manager`
- `init_set_types()` (page 94) - initialize structures for tracking/indexing nodes, states, ports
- `display()` (page 94) - display the network model object
- `add_node()` (page 95) - add named set of nodes
- `add_port()` (page 95) - add named set of ports
- `add_state()` (page 95) - add named set of states
- `set_type_idx_map()` (page 95) - map node/port/state index back to named set & index within set
- `set_type_label()` (page 96) - create a user-readable label to identify a node, port, or state
- `add_var()` (page 96) - add a set of variables to the model
- `params_var()` (page 97) - return initial value, bounds, and variable type for variables
- `get_node_idx()` (page 98) - get index information for named node set
- `get_port_idx()` (page 98) - get index information for named port set
- `get_state_idx()` (page 98) - get index information for named state set
- `node_types()` (page 98) - get node type information
- `ensure_ref_node()` (page 99) -
- `set_node_type_ref()` (page 99) - make the specified node a reference node
- `set_node_type_pv()` (page 100) - make the specified node a PV node
- `set_node_type_pq()` (page 100) - make the specified node a PQ node

See the `sec_net_model` section in the *MATPOWER Developer's Manual* for more information.

See also `mp.form` (page 71), `mp.nm_element` (page 107), `mp.task` (page 7), `mp.data_model` (page 27), `mp.math_model` (page 121).

Property Summary

the_np = 0
(integer) total number of ports

the_nz = 0
(integer) total number of non-voltage states

nv = 0
(integer) total number of (real) voltage variables

node = []
(struct) `mp_idx_manager` data for nodes

port = []
(struct) `mp_idx_manager` data for ports

state = []
(struct) `mp_idx_manager` data for non-voltage states

Method Summary

name()
Return the name of this network element type ('network').

```
name = nm.name()
```

np()
Return the number of ports for this network element.

```
np = nm.np()
```

nz()
Return the number of (possibly complex) non-voltage states for this network element.

```
nz = nm.nz()
```

build(dm)
Create, add, and `build()` (page 92) network model element objects.

```
nm.build(dm)
```

Input

dm (`mp.data_model` (page 27)) – data model object

Create and add network model element objects, add nodes and states, and build the parameters for all elements.

See also `add_nodes()` (page 92), `add_states()` (page 93), `build_params()` (page 93).

add_nodes(nm, dm)

Elements add nodes, then add corresponding voltage variables.


```
nm.add_nodes(nm, dm)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object

Each element can add its nodes, then the network model itself can add additional nodes, and finally corresponding voltage variables are added for each node.

See also [add_vvars\(\)](#) (page 94), [add_states\(\)](#) (page 93).

add_states(nm, dm)

Elements add states, then add corresponding state variables.

```
nm.add_states(nm, dm)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object

Each element can add its states, then corresponding non-voltage state variables are added for each state.

See also [add_zvars\(\)](#) (page 94), [add_nodes\(\)](#) (page 92).

build_params(nm, dm)

Build incidence matrices and parameters, and add ports for each element.

```
nm.build_params(nm, dm)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object

For each element, build connection and state variable incidence matrices and element parameters, and add ports. Then construct the full network connection and state variable incidence matrices.

stack_matrix_params(name, vnotz)

Form network matrix parameter by stacking corresponding element parameters.

```
M = nm.stack_matrix_params(name, vnotz)
```

Inputs

- **name** (*char array*) – name of the parameter of interest
- **vnotz** (*boolean*) – true if columns of parameter correspond to voltage variables, false otherwise

Output

M (*double*) – matrix parameter of interest for the full network

A given matrix parameter (e.g. **Y**) for the full network is formed by stacking the corresponding matrix parameters for each element along the matrix block diagonal.

stack_vector_params(name)

Form network vector parameter by stacking corresponding element parameters.

```
v = nm.stack_vector_params(name)
```

Input

name (*char array*) – name of the parameter of interest

Output

v (*double*) – vector parameter of interest for the full network

A given vector parameter (e.g. **s**) for the full network is formed by vertically stacking the corresponding vector parameters for each element.

add_vvars(*nm, dm, idx*)

Add voltage variable(s) for each network node.

```
nm.add_vvars(nm, dm)
nm.add_vvars(nm, dm, idx)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **idx** (*integer*) – index for name and indexed variables (*currently unused here*)

Also updates the **nv** property.

See also [add_zvars\(\)](#) (page 94), [add_nodes\(\)](#) (page 92).

add_zvars(*nm, dm, idx*)

Add non-voltage state variable(s) for each network state.

```
nm.add_zvars(nm, dm)
nm.add_zvars(nm, dm, idx)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **idx** (*cell array*) – indices for named and indexed variables (*currently unused here*)

See also [add_vvars\(\)](#) (page 94), [add_states\(\)](#) (page 93).

def_set_types()

Define node, state, and port set types for **mp_idx_manager**.

```
nm.def_set_types()
```

Define the following set types:

- 'node' - NODES
- 'state' - STATES
- 'port' - PORTS

See also **mp_idx_manager**.

init_set_types()

Initialize structures for tracking/indexing nodes, states, ports.

```
nm.init_set_types()
```

See also **mp_idx_manager**.

display()

Display the network model object.

This method is called automatically when omitting a semicolon on a line that returns an object of this class.

Displays the details of the nodes, ports, states, voltage variables, non-voltage state variables, and network model elements.

See also `mp_idx_manager`.

add_node(*name*, *idx*, *N*)

Add named set of nodes.

```
nm.add_node(name, N)
nm.add_node(name, idx, N)
```

Inputs

- **name** (*char array*) – name for set of nodes
- **idx** (*cell array*) – indices for named, indexed set of nodes
- **N** (*integer*) – number of nodes in set

See also `mp_idx_manager.add_named_set()`.

add_port(*name*, *idx*, *N*)

Add named set of ports.

```
nm.add_port(name, N)
nm.add_port(name, idx, N)
```

Inputs

- **name** (*char array*) – name for set of ports
- **idx** (*cell array*) – indices for named, indexed set of ports
- **N** (*integer*) – number of ports in set

See also `mp_idx_manager.add_named_set()`.

add_state(*name*, *idx*, *N*)

Add named set of states.

```
nm.add_state(name, N)
nm.add_state(name, idx, N)
```

Inputs

- **name** (*char array*) – name for set of states
- **idx** (*cell array*) – indices for named, indexed set of states
- **N** (*integer*) – number of states in set

See also `mp_idx_manager.add_named_set()`.

set_type_idx_map(*set_type*, *idxs*, *dm*, *group_by_name*)

Map node/port/state index back to named set & index within set.

```
s = obj.set_type_idx_map(set_type)
s = obj.set_type_idx_map(set_type, idxs)
s = obj.set_type_idx_map(set_type, idxs, dm)
s = obj.set_type_idx_map(set_type, idxs, dm, group_by_name)
```

Inputs

- **set_type** (*char array*) – 'node', 'port', or 'state'
- **idxs** (*integer*) – vector of indices, defaults to `[1:ns]'`, where `ns` is the full dimension of the set corresponding to the all elements for the specified set type (i.e. node, port, or state)
- **dm** (*mp.data_model* (page 27)) – data model object

- **group_by_name** (*boolean*) – if true, results are consolidated, with a single entry in **s** for each unique name/idx pair, where the **i** and **j** fields are vectors

Output

s (*struct*) – index map of same dimensions as **idxs**, unless **group_by_name** is true, in which case it is 1 dimensional

Returns a struct of same dimensions as **idxs** specifying, for each index, the corresponding named set and element within the named set for the specified **set_type**. The return struct has the following fields:

- **name** : name of corresponding set
- **idx** : cell array of indices for the name, if named set is indexed
- **i** : index of element within the set
- **e** : external index (i.e. corresponding row in data model)
- **ID** : external ID (i.e. corresponding element ID in data model)
- **j** : (only if **group_by_name** == 1), corresponding index of set type, equal to a particular element of **idxs**

Examples:

```
s = nm.set_type_idx_map('node', 87, dm));
s = nm.set_type_idx_map('port', [38; 49; 93], dm));
s = nm.set_type_idx_map('state');
s = nm.set_type_idx_map('node', [], dm, 1));
```

set_type_label(*set_type, idxs, dm*)

Create a user-readable label to identify a node, port, or state.

```
label = nm.set_type_label(set_type, idxs)
label = nm.set_type_label(set_type, idxs, dm)
```

Inputs

- **set_type** (*char array*) – 'node', 'port', or 'state'
- **idxs** (*integer*) – vector of indices
- **dm** (*mp.data_model* (page 27)) – data model object

Output

label (*cell array*) – same dimensions as **idxs**, where each entry is a char array

Example:

```
labels = nm.set_type_label('port', [1;6;15;20], dm)

labels =

4x1 cell array

    {'gen 1'      }
    {'load 3'      }
    {'branch(1) 9'}
    {'branch(2) 5'}
```

add_var(*vtype, name, idx, varargin*)

Add a set of variables to the model.

```
nm.add_var(vtype, name, N, v0, v1, vu, vt)
nm.add_var(vtype, name, N, v0, v1, vu)
nm.add_var(vtype, name, N, v0, v1)
```

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```

nm.add_var(vtype, name, N, v0)
nm.add_var(vtype, name, N)
nm.add_var(vtype, name, idx_list, N, v0, vl, vu, vt)
nm.add_var(vtype, name, idx_list, N, v0, vl, vu)
nm.add_var(vtype, name, idx_list, N, v0, vl)
nm.add_var(vtype, name, idx_list, N, v0)
nm.add_var(vtype, name, idx_list, N)

```

Inputs

- **vtype** (*char array*) – variable type, must be a valid struct field name
- **name** (*char array*) – name of variable set
- **idx_list** (*cell array*) – optional index list
- **N** (*integer*) – number of variables in the set
- **v0** (*double*) – N x 1 col vector, initial value of variables, default is 0
- **vl** (*double*) – N x 1 col vector, lower bounds, default is -Inf
- **vu** (*double*) – N x 1 col vector, upper bounds, default is Inf
- **vt** (*char*) – scalar or 1 x N row vector, variable type, default is 'C', valid element values are:
 - 'C' - continuous
 - 'I' - integer
 - 'B' - binary

Essentially identical to the `add_var()` method from `opt_model` of MP-Opt-Model, with the addition of a variable type (`vtype`).

See also `opt_model.add_var()`.

params_var(vtype, name, idx)

Return initial value, bounds, and variable type for variables.

```

[v0, vl, vu] = nm.params_var(vtype)
[v0, vl, vu] = nm.params_var(vtype, name)
[v0, vl, vu] = nm.params_var(vtype, name, idx_list)
[v0, vl, vu, vt] = nm.params_var(...)

```

Inputs

- **vtype** (*char array*) – variable type, must be a valid struct field name
- **name** (*char array*) – name of variable set
- **idx_list** (*cell array*) – optional index list

Outputs

- **v0** (*double*) – N x 1 col vector, initial value of variables
- **vl** (*double*) – N x 1 col vector, lower bounds
- **vu** (*double*) – N x 1 col vector, upper bounds
- **vt** (*char*) – scalar or 1 x N row vector, variable type, valid element values are:
 - 'C' - continuous
 - 'I' - integer
 - 'B' - binary

Essentially identical to the `params_var()` method from `opt_model` of MP-Opt-Model, with the addition of a variable type (`vtype`).

Returns the initial value `v0`, lower bound `vl` and upper bound `vu` for the full variable vector, or for a specific named or named and indexed variable set. Optionally also returns a corresponding char vector `vt` of variable types, where 'C', 'I' and 'B' represent continuous, integer, and binary variables, respectively.

Examples:

```
[vr0, vrmin, vrmax] = obj.params_var('vr');
[pg0, pg_lb, pg_ub] = obj.params_var('zr', 'pg');
[zij0, zij_lb, zij_ub, ztype] = obj.params_var('zi', 'z', {i, j});
```

See also `opt_model.params_var()`.

get_node_idx(name)

Get index information for named node set.

```
[i1 iN] = nm.get_node_idx(name)
nidx = nm.get_node_idx(name)
```

Input

name (*char array*) – name of node set

Outputs

- **i1** (*integer*) – index of first node for name
- **iN** (*integer*) – index of last node for name
- **nidx** (*integer or cell array*) – indices of nodes for name, equal to either `[i1:iN]'` or `{[i1(1):iN(1)]', ..., [i1(n):iN(n)]'}`

get_port_idx(name)

Get index information for named port set.

```
[i1 iN] = nm.get_port_idx(name)
pidx = nm.get_port_idx(name)
```

Input

name (*char array*) – name of port set

Outputs

- **i1** (*integer*) – index of first port for name
- **iN** (*integer*) – index of last port for name
- **pidx** (*integer or cell array*) – indices of ports for name, equal to either `[i1:iN]'` or `{[i1(1):iN(1)]', ..., [i1(n):iN(n)]'}`

get_state_idx(name)

Get index information for named state set.

```
[i1 iN] = nm.get_state_idx(name)
sidx = nm.get_state_idx(name)
```

Input

name (*char array*) – name of state set

Outputs

- **i1** (*integer*) – index of first state for name
- **iN** (*integer*) – index of last state for name
- **sidx** (*integer or cell array*) – indices of states for name, equal to either `[i1:iN]'` or `{[i1(1):iN(1)]', ..., [i1(n):iN(n)]'}`

node_types(nm, dm, idx, skip_ensure_ref)

Get node type information.

```
ntv          = nm.node_types(nm, dm)
[ntv, by_elm] = nm.node_types(nm, dm)
```

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```
[ref, pv, pq] = nm.node_types(nm, dm)
[ref, pv, pq, by_elm] = nm.node_types(nm, dm)
... = nm.node_types(nm, dm, idx)
... = nm.node_types(nm, dm, idx, skip_ensure_ref)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **idx** (*integer*) – index (*not used in base method*)
- **skip_ensure_ref** (*boolean*) – unless true, if there is no reference node, the first PV node will be converted to a new reference

Outputs

- **ntv** (*integer*) – node type vector, valid element values are:
 - [mp.NODE_TYPE.REF](#) (page 169)
 - [mp.NODE_TYPE.PV](#) (page 169)
 - [mp.NODE_TYPE.PQ](#) (page 169)
- **ref** (*integer*) – vector of indices of reference nodes
- **pv** (*integer*) – vector of indices of PV nodes
- **pq** (*integer*) – vector of indices of PQ nodes
- **by_elm** (*struct*) – **by_elm(k)** is struct for k-th node-creating element type, with fields:
 - 'name' - name of corresponding node-creating element type
 - 'ntv' - node type vector (if **by_elm** is 2nd output arg)
 - 'ref'/'pv'/'pq' - index vectors into elements of corresponding node-creating element type (if **by_elm** is 4th output arg)

See also [mp.NODE_TYPE](#) (page 169), [ensure_ref_node\(\)](#) (page 99).

ensure_ref_node(dm, ref, pv, pq)

Ensure there is at least one reference node.

```
[ref, pv, pq] = nm.ensure_ref_node(dm, ref, pv, pq)
ntv = nm.ensure_ref_node(dm, ntv)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model object
- **ref** (*integer*) – vector of indices of reference nodes
- **pv** (*integer*) – vector of indices of PV nodes
- **pq** (*integer*) – vector of indices of PQ nodes
- **ntv** (*integer*) – node type vector, valid element values are:
 - [mp.NODE_TYPE.REF](#) (page 169)
 - [mp.NODE_TYPE.PV](#) (page 169)
 - [mp.NODE_TYPE.PQ](#) (page 169)

Outputs

- **ref** (*integer*) – updated vector of indices of reference nodes
- **pv** (*integer*) – updated vector of indices of PV nodes
- **pq** (*integer*) – updated vector of indices of PQ nodes
- **ntv** (*integer*) – updated node type vector

set_node_type_ref(dm, idx)

Make the specified node a reference node.

```
nm.set_node_type_ref(dm, idx)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model object
- **idx** (*integer*) – index of node to modify, this is the internal network model element index

Set the specified node to type [mp.NODE_TYPE.REF](#) (page 169).

set_node_type_pv(dm, idx)

Make the specified node a PV node.

```
nm.set_node_type_pv(dm, idx)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model object
- **idx** (*integer*) – index of node to modify, this is the internal network model element index

Set the specified node to type [mp.NODE_TYPE.PV](#) (page 169).

set_node_type_pq(dm, idx)

Make the specified node a PQ node.

```
nm.set_node_type_pq(dm, idx)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model object
- **idx** (*integer*) – index of node to modify, this is the internal network model element index

Set the specified node to type [mp.NODE_TYPE.PQ](#) (page 169).

mp.net_model_ac

class mp.net_model_ac

Bases: [mp.net_model](#) (page 90)

[mp.net_model_ac](#) (page 100) - Abstract base class for MATPOWER AC **network model** objects.

Explicitly a subclass of [mp.net_model](#) (page 90) and implicitly assumed to be a subclass of [mp.form_ac](#) (page 73) as well.

mp.net_model_ac Properties:

- **zr** - vector of real part of complex non-voltage states, z_r
- **zi** - vector of imaginary part of complex non-voltage states, z_i

mp.net_model_ac Methods:

- [def_set_types\(\)](#) (page 101) - add non-voltage state variable set types for `mp_idx_manager`
- [build_params\(\)](#) (page 101) - build incidence matrices, parameters, add ports for each element
- [port_inj_nln\(\)](#) (page 101) - compute general nonlinear port injection functions and Jacobians
- [port_inj_nln_hess\(\)](#) (page 102) - compute general nonlinear port injection Hessian
- [nodal_complex_current_balance\(\)](#) (page 102) - compute nodal complex current balance constraints
- [nodal_complex_power_balance\(\)](#) (page 102) - compute nodal complex power balance constraints
- [nodal_complex_current_balance_hess\(\)](#) (page 103) - compute nodal complex current balance Hessian

- `nodal_complex_power_balance_hess()` (page 103) - compute nodal complex power balance Hessian
- `port_inj_soln()` (page 103) - compute the network port power injections at the solution
- `get_va()` (page 103) - get node voltage angle vector

See also `mp.net_model` (page 90), `mp.form` (page 71), `mp.form_ac` (page 73), `mp.nm_element` (page 107).

Method Summary

`def_set_types()`

Add non-voltage state variable set types for `mp_idx_manager`.

```
nm.def_set_types()
```

Add the following set types:

- 'zr' - NON-VOLTAGE VARS REAL (zr)
- 'zi' - NON-VOLTAGE VARS IMAG (zi)

See also `mp.net_model.def_set_types()` (page 94), `mp_idx_manager`.

`build_params(nm, dm)`

Build incidence matrices and parameters, and add ports for each element.

```
nm.build_params(nm, dm)
```

Inputs

- **nm** (`mp.net_model` (page 90)) – network model object
- **dm** (`mp.data_model` (page 27)) – data model object

Call the parent method to do most () of the work, then build the aggregate network model parameters and add the general nonlinear function terms, $s^{nl_n}(\mathbf{x})$ or $i^{nl_n}(\mathbf{x})$, for any elements that define them.

`port_inj_nln(si, x_, sysx, idx)`

Compute general nonlinear port injection functions and Jacobians

```
g = nm.port_inj_nln(si, x_, sysx, idx)
[g, gv1, gv2] = nm.port_inj_nln(si, x_, sysx, idx)
[g, gv1, gv2, gvr, gvi] = nm.port_inj_nln(si, x_, sysx, idx)
```

Compute and assemble the functions, and optionally Jacobians, for the general nonlinear injection functions $s^{nl_n}(\mathbf{x})$ and $i^{nl_n}(\mathbf{x})$ for the full aggregate network model, for all or a selected subset of ports.

Inputs

- **si** ('S' or 'I') – select power or current injection function:
 - 'S' for complex power $s^{nl_n}(\mathbf{x})$
 - 'I' for complex current $i^{nl_n}(\mathbf{x})$
- **x_** (complex double) – state vector \mathbf{x}
- **sysx** (0 or 1) – which state is provided in $\mathbf{x}_$
 - 0 – class aggregate state
 - 1 – (default) full system state
- **idx** (integer) – (optional) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Outputs

- **g** (complex double) – nonlinear injection function, $s^{nl_n}(\mathbf{x})$ (or $i^{nl_n}(\mathbf{x})$)
- **gv1** (complex double) – Jacobian w.r.t. 1st voltage variable, $s_{\theta}^{nl_n}$ or $s_u^{nl_n}$ (or $i_{\theta}^{nl_n}$ or $i_u^{nl_n}$)
- **gv2** (complex double) – Jacobian w.r.t. 2nd voltage variable, $s_v^{nl_n}$ or $s_w^{nl_n}$ (or $i_v^{nl_n}$ or $i_w^{nl_n}$)

- **g_{zr}** (*complex double*) – Jacobian w.r.t. real non-voltage variable, $s_{z_r}^{nl}$ (or $i_{z_r}^{nl}$)
- **g_{zi}** (*complex double*) – Jacobian w.r.t. imaginary non-voltage variable, $s_{z_i}^{nl}$ (or $i_{z_i}^{nl}$)

See also [port_inj_nln_hess\(\)](#) (page 102).

port_inj_nln_hess(*si, x_, lam, sysx, idx*)

Compute general nonlinear port injection Hessian.

```
H = nm.port_inj_nln_hess(si, x_, lam)
H = nm.port_inj_nln_hess(si, x_, lam, sysx)
H = nm.port_inj_nln_hess(si, x_, lam, sysx, idx)
```

Compute and assemble the Hessian for the general nonlinear injection functions $s^{nl}(\mathbf{x})$ and $i^{nl}(\mathbf{x})$ for the full aggregate network model, for all or a selected subset of ports. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by multiplying the transpose of the corresponding Jacobian by a vector λ .

Inputs

- **si** ('S' or 'I') – select power or current injection function:
 - 'S' for complex power $s^{nl}(\mathbf{x})$
 - 'I' for complex current $i^{nl}(\mathbf{x})$
- **x_** (*complex double*) – state vector \mathbf{x}
- **lam** (*double*) – vector λ of multipliers, one for each port
- **sysx** (0 or 1) – which state is provided in **x_**
 - 0 – class aggregate state
 - 1 – (*default*) full system state
- **idx** (*integer*) – (*optional*) vector of indices of ports of interest, if empty or missing, returns results corresponding to all ports

Output

H (*complex double*) – sparse Hessian matrix, $s_{xx}^{nl}(\lambda)$ or $i_{xx}^{nl}(\lambda)$

See also [port_inj_nln\(\)](#) (page 101).

nodal_complex_current_balance(*x_*)

Compute nodal complex current balance constraints.

```
G = nm.nodal_complex_current_balance(x_)
[G, Gv1, Gv2, Gzr, Gzi] = nm.nodal_complex_current_balance(x_)
```

Compute constraint function and optionally the Jacobian for the complex current balance equality constraints based on outputs of [mp.form_ac.port_inj_current\(\)](#) (page 76) and the node incidence matrix.

Input

x_ (*complex double*) – state vector \mathbf{x} (full system state)

Outputs

- **G** (*complex double*) – nodal complex current balance constraint function, $\mathbf{g}^{kcl}(\mathbf{x})$
- **Gv1** (*complex double*) – Jacobian w.r.t. 1st voltage variable, $\mathbf{g}_{\theta}^{kcl}$ or \mathbf{g}_u^{kcl}
- **Gv2** (*complex double*) – Jacobian w.r.t. 2nd voltage variable, \mathbf{g}_v^{kcl} or \mathbf{g}_w^{kcl}
- **Gzr** (*complex double*) – Jacobian w.r.t. real non-voltage variable, $\mathbf{g}_{z_r}^{kcl}$
- **Gzi** (*complex double*) – Jacobian w.r.t. imaginary non-voltage variable, $\mathbf{g}_{z_i}^{kcl}$

See also [mp.form_ac.port_inj_current\(\)](#) (page 76), [nodal_complex_current_balance_hess\(\)](#) (page 103).

nodal_complex_power_balance(*x_*)

Compute nodal complex power balance constraints.

```
G = nm.nodal_complex_power_balance(x_)
[G, Gv1, Gv2, Gzr, Gzi] = nm.nodal_complex_power_balance(x_)
```

Compute constraint function and optionally the Jacobian for the complex power balance equality constraints based on outputs of `mp.form_ac.port_inj_power()` (page 76) and the node incidence matrix.

Input

\mathbf{x}_- (*complex double*) – state vector \mathbf{x} (full system state)

Outputs

- \mathbf{G} (*complex double*) – nodal complex power balance constraint function, $\mathbf{g}^{\text{kcl}}(\mathbf{x})$
- $\mathbf{Gv1}$ (*complex double*) – Jacobian w.r.t. 1st voltage variable, $\mathbf{g}_{\theta}^{\text{kcl}}$ or $\mathbf{g}_u^{\text{kcl}}$
- $\mathbf{Gv2}$ (*complex double*) – Jacobian w.r.t. 2nd voltage variable, $\mathbf{g}_v^{\text{kcl}}$ or $\mathbf{g}_w^{\text{kcl}}$
- \mathbf{Gzr} (*complex double*) – Jacobian w.r.t. real non-voltage variable, $\mathbf{g}_{z_r}^{\text{kcl}}$
- \mathbf{Gzi} (*complex double*) – Jacobian w.r.t. imaginary non-voltage variable, $\mathbf{g}_{z_i}^{\text{kcl}}$

See also `mp.form_ac.port_inj_power()` (page 76), `nodal_complex_power_balance_hess()` (page 103).

`nodal_complex_current_balance_hess(x_, lam)`

Compute nodal complex current balance Hessian.

```
d2G = nm.nodal_complex_current_balance_hess(x_, lam)
```

Compute the Hessian of the nodal complex current balance constraint. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by multiplying the transpose of the constraint Jacobian by a vector λ . Based on `mp.form_ac.port_inj_current_hess()` (page 77).

Inputs

- \mathbf{x}_- (*complex double*) – state vector \mathbf{x} (full system state)
- \mathbf{lam} (*double*) – vector λ of multipliers, one for each node

Output

$\mathbf{d2G}$ (*complex double*) – sparse Hessian matrix, $\mathbf{g}_{xx}^{\text{kcl}}(\lambda)$

See also `mp.form_ac.port_inj_current_hess()` (page 77), `nodal_complex_current_balance()` (page 102).

`nodal_complex_power_balance_hess(x_, lam)`

Compute nodal complex power balance Hessian.

```
d2G = nm.nodal_complex_power_balance_hess(x_, lam)
```

Compute the Hessian of the nodal complex power balance constraint. Rather than a full, 3-dimensional Hessian, it computes the Jacobian of the vector obtained by multiplying the transpose of the constraint Jacobian by a vector λ . Based on `mp.form_ac.port_inj_power_hess()` (page 78).

Inputs

- \mathbf{x}_- (*complex double*) – state vector \mathbf{x} (full system state)
- \mathbf{lam} (*double*) – vector λ of multipliers, one for each node

Output

$\mathbf{d2G}$ (*complex double*) – sparse Hessian matrix, $\mathbf{g}_{xx}^{\text{kcl}}(\lambda)$

See also `mp.form_ac.port_inj_power_hess()` (page 78), `nodal_complex_power_balance()` (page 102).

`port_inj_soln()`

Compute the network port power injections at the solution.

```
nm.port_inj_soln()
```

Takes the solved network state, computes the port power injections, and saves them in `nm.soln.gs_`.

`get_va(idx)`

Get node voltage angle vector.

```
va = nm.get_va()  
va = nm.get_va(idx)
```

Get vector of node voltage angles for all or a selected subset of nodes. Values come from the solution if available, otherwise from the provided initial voltages.

Input

idx (*integer*) – index of subset of voltages of interest; if missing or empty, include all

Output

va (*double*) – vector of voltage angles

mp.net_model_acc

class mp.net_model_acc

Bases: [mp.net_model_ac](#) (page 100), [mp.form_acc](#) (page 82)

[mp.net_model_acc](#) (page 104) - Concrete class for MATPOWER AC cartesian **network model** objects.

This network model class and all of its network model element classes are specific to the AC cartesian formulation and therefore inherit from [mp.form_acc](#) (page 82).

mp.net_model_acc Properties:

- **vr** - vector of real part of complex voltage state variables, *u*
- **vi** - vector of imaginary part of complex voltage state variables, *w*

mp.net_model_acc Methods:

- [net_model_acc\(\)](#) (page 104) - constructor, assign default network model element classes
- [def_set_types\(\)](#) (page 104) - add voltage state variable set types for `mp_idx_manager`
- [initial_voltage_angle\(\)](#) (page 105) - get vector of initial node voltage angles

See also [mp.net_model_ac](#) (page 100), [mp.net_model](#) (page 90), [mp.form_acc](#) (page 82), [mp.form_ac](#) (page 73), [mp.form](#) (page 71), [mp.nm_element](#) (page 107).

Constructor Summary

net_model_acc()

Constructor, assign default network model element classes.

```
nm = net_model_acc()
```

This network model class and all of its network model element classes are specific to the AC cartesian formulation and therefore inherit from [mp.form_acc](#) (page 82).

Method Summary

def_set_types()

Add voltage state variable set types for `mp_idx_manager`.

```
nm.def_set_types()
```

Add the following set types:

- 'vr' - REAL VOLTAGE VARS (vr)
- 'vi' - IMAG VOLTAGE VARS (vi)

See also [mp.net_model_ac.def_set_types\(\)](#) (page 101), [mp.net_model.def_set_types\(\)](#) (page 94), [mp_idx_manager](#).

initial_voltage_angle(*idx*)

Get vector of initial node voltage angles.

```
va = nm.initial_voltage_angle()
va = nm.initial_voltage_angle(idx)
```

Get vector of initial node voltage angles for all or a selected subset of nodes.

Input

idx (*integer*) – index of subset of voltages of interest; if missing or empty, include all

Output

va (*double*) – vector of initial voltage angles

mp.net_model_acp

class mp.net_model_acp

Bases: [mp.net_model_ac](#) (page 100), [mp.form_acp](#) (page 86)

[mp.net_model_acp](#) (page 105) - Concrete class for MATPOWER AC polar **network model** objects.

This network model class and all of its network model element classes are specific to the AC polar formulation and therefore inherit from [mp.form_acp](#) (page 86).

mp.net_model_acp Properties:

- **va** - vector of angles of complex voltage state variables, θ
- **vm** - vector of magnitudes of complex voltage state variables, ν

mp.net_model_acp Methods:

- [net_model_acp\(\)](#) (page 105) - constructor, assign default network model element classes
- [def_set_types\(\)](#) (page 105) - add voltage state variable set types for [mp_idx_manager](#)
- [initial_voltage_angle\(\)](#) (page 106) - get vector of initial node voltage angles

See also [mp.net_model_ac](#) (page 100), [mp.net_model](#) (page 90), [mp.form_acp](#) (page 86), [mp.form_ac](#) (page 73), [mp.form](#) (page 71), [mp.nm_element](#) (page 107).

Constructor Summary

net_model_acp()

Constructor, assign default network model element classes.

```
nm = net_model_acp()
```

This network model class and all of its network model element classes are specific to the AC polar formulation and therefore inherit from [mp.form_acp](#) (page 86).

Method Summary

def_set_types()

Add voltage state variable set types for [mp_idx_manager](#).

```
nm.def_set_types()
```

Add the following set types:

- 'va' - VOLTAGE ANG VARS (va)
- 'vm' - VOLTAGE MAG VARS (vm)

See also [mp.net_model.ac.def_set_types\(\)](#) (page 101), [mp.net_model.def_set_types\(\)](#) (page 94), [mp_idx_manager](#).

initial_voltage_angle(idx)

Get vector of initial node voltage angles.

```
va = nm.initial_voltage_angle()
va = nm.initial_voltage_angle(idx)
```

Get vector of initial node voltage angles for all or a selected subset of nodes.

Input

idx (*integer*) – index of subset of voltages of interest; if missing or empty, include all

Output

va (*double*) – vector of initial voltage angles

mp.net_model_dc

class mp.net_model_dc

Bases: [mp.net_model](#) (page 90), [mp.form_dc](#) (page 88)

[mp.net_model_dc](#) (page 106) - Concrete class for MATPOWER DC **network model** objects.

This network model class and all of its network model element classes are specific to the DC formulation and therefore inherit from [mp.form_dc](#) (page 88).

mp.net_model_dc Properties:

- **va** (page 107) - vector of voltage states (voltage angles θ)
- **z** (page 107) - vector of non-voltage states z

mp.net_model_dc Methods:

- [net_model_dc\(\)](#) (page 106) - constructor, assign default network model element classes
- [def_set_types\(\)](#) (page 107) - add voltage and non-voltage variable set types for [mp_idx_manager](#)
- [build_params\(\)](#) (page 107) - build incidence matrices, parameters, add ports for each element
- [port_inj_soln\(\)](#) (page 107) - compute the network port injections at the solution

See also [mp.net_model](#) (page 90), [mp.form_dc](#) (page 88), [mp.form](#) (page 71), [mp.nm_element](#) (page 107).

Constructor Summary

net_model_dc()

Constructor, assign default network model element classes.

```
nm = net_model_dc()
```

This network model class and all of its network model element classes are specific to the DC formulation and therefore inherit from [mp.form_dc](#) (page 88).

Property Summary

va = []
(double) vector of voltage states (voltage angles θ)

z = []
(double) vector of non-voltage states z

Method Summary**def_set_types()**

Add voltage and non-voltage variable set types for `mp_idx_manager`.

```
nm.def_set_types()
```

Add the following set types:

- 'va' - VOLTAGE VARS (va)
- 'z' - NON-VOLTAGE VARS (z)

See also [mp.net_model.def_set_types\(\)](#) (page 94), `mp_idx_manager`.

build_params(nm, dm)

Build incidence matrices and parameters, and add ports for each element.

```
nm.build_params(nm, dm)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object

Call the parent method to do most () of the work, then build the aggregate network model parameters.

port_inj_soln()

Compute the network port injections at the solution.

```
nm.port_inj_soln()
```

Takes the solved network state, computes the port power injections, and saves them in `nm.soln.gp`.

3.4.2 Elements

mp.nm_element**class mp.nm_element**

Bases: `handle`

[mp.nm_element](#) (page 107) - Abstract base class for MATPOWER **network model element** objects.

A network model element object encapsulates all of the network model parameters for a particular element type. All network model element classes inherit from [mp.nm_element](#) (page 107) and also, like the container, from a formulation-specific subclass of [mp.form](#) (page 71). Each element type typically implements its own subclasses, which are further subclassed per formulation. A given network model element object contains the aggregate network model parameters for all online instances of that element type, stored in the set of matrices and vectors that correspond to the formulation.

By convention, network model element variables are named `nme` and network model element class names begin with `mp.nme`.

mp.mm_element Properties:

- `nk` (page 108) - number of elements of this type
- `C` (page 108) - stacked sparse element-node incidence matrices
- `D` (page 109) - stacked sparse incidence matrices for z -variables
- `soln` (page 109) - struct for storing solved states, quantities

mp.mm_element Methods:

- `name()` (page 109) - get name of element type, e.g. 'bus', 'gen'
- `np()` (page 109) - number of ports per element of this type
- `nn()` (page 109) - number of nodes per element, created by this element type
- `nz()` (page 109) - number of non-voltage state variables per element of this type
- `data_model_element()` (page 109) - get the corresponding data model element
- `math_model_element()` (page 109) - get the corresponding math model element
- `count()` (page 110) - get number of online elements in `dm`, set `nk`
- `add_nodes()` (page 110) - add nodes to network model
- `add_states()` (page 110) - add non-voltage states to network model
- `add_vvars()` (page 110) - add real-valued voltage variables to network object
- `add_zvars()` (page 111) - add real-valued non-voltage state variables to network object
- `build_params()` (page 111) - build model parameters from data model
- `get_nv_()` (page 111) - get number of (*possibly complex*) voltage variables
- `x2vz()` (page 111) - get port voltages and non-voltage states from combined state vector
- `node_indices()` (page 112) - construct node indices from data model element connection info
- `incidence_matrix()` (page 112) - construct stacked incidence matrix from set of index vectors
- `node_types()` (page 113) - get node type information
- `set_node_type_ref()` (page 113) - make the specified node a reference node
- `set_node_type_pv()` (page 113) - make the specified node a PV node
- `set_node_type_pq()` (page 114) - make the specified node a PQ node
- `display()` (page 114) - display the network model element object

See the `sec_nm_element` section in the *MATPOWER Developer's Manual* for more information.

See also `mp.net_model` (page 90).

Property Summary

`nk = 0`

(integer) number of elements of this type

C = []

(*sparse integer matrix*) stacked element-node incidence matrices, where $C(i, kk)$ is 1 if port j of element k is connected to node i , and $kk = k + (j-1)*np$

D = []

(*sparse integer matrix*) stacked incidence matrices for z -variables (non-voltage state variables), where $D(i, kk)$ is 1 if z -variable j of element k is the i -th system z -variable and $kk = k + (j-1)*nz$

soln

(*struct*) for storing solved states, quantities

Method Summary

name()

Get name of element type, e.g. 'bus', 'gen'.

```
name = nme.name()
```

Output

name (*char array*) – name of element type, must be a valid struct field name

Implementation provided by an element type specific subclass.

np()

Number of ports per element of this type.

```
np = nme.np()
```

Output

np (*integer*) – number of ports per element of this type

nn()

Number of nodes per element, created by this element type.

```
nn = nme.nn()
```

Output

nn (*integer*) – number of ports per element of this type

nz()

Number of non-voltage state variables per element of this type.

```
nz = nme.nz()
```

Output

nz (*integer*) – number of non-voltage state variables per element of this type

data_model_element(dm, name)

Get the corresponding data model element.

```
dme = nme.data_model_element(dm, name)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model object
- **name** (*char array*) – name of element type

Output

dme ([mp.dm_element](#) (page 35)) – data model element object

math_model_element(*mm, name*)

Get the corresponding math model element.

```
mme = nme.math_model_element(mm, name)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – math model object
- **name** (*char array*) – name of element type

Output**mme** ([mp.mm_element](#) (page 143)) – math model element object**count**(*dm*)Get number of online elements of this type in *dm*, set *nk*.

```
nk = nme.count(dm)
```

Input**dm** ([mp.data_model](#) (page 27)) – data model object**Output****nk** (*integer*) – number of online elements of this type**add_nodes**(*nm, dm*)

Add nodes to network model for this element.

```
nme.add_nodes(nm, dm)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object

Add nodes to the network model object, based on value *nm* returned by [nn\(\)](#) (page 109). Calls the network model's [add_node\(\)](#) (page 95) *nm* times.**add_states**(*nm, dm*)

Add non-voltage states to network model for this element.

```
nme.add_states(nm, dm)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object

Add non-voltage states to the network model object, based on value *nz* returned by [nz\(\)](#) (page 109). Calls the network model's [add_state\(\)](#) (page 95) *nz* times.**add_vvars**(*nm, dm, idx*)

Add real-valued voltage variables to network object.

```
nme.add_vvars(nm, dm, idx)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object

Add real-valued voltage variables (*v*-variables) to the network model object, for each port. Implementation depends on the specific formulation (i.e. subclass of [mp.form](#) (page 71)).

For example, consider an element with np ports and an AC formulation with polar voltage representation. The actual port voltages are complex, but this method would call the network model's `add_var()` (page 96) twice for each port, once for the voltage angle variables and once for the voltage magnitude variables.

Implemented by a formulation-specific subclass.

add_zvars(*nm, dm, idx*)

Add real-valued non-voltage state variables to network object.

```
nme.add_zvars(nm, dm, idx)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **idx** (*cell array*) – indices for named and indexed variables

Add real-valued non-voltage state variables (z -variables) to the network model object. Implementation depends on the specific formulation (i.e. subclass of [mp.form](#) (page 71)).

For example, consider an element with nz z -variables and a formulation in which these are complex. This method would call the network model's `add_var()` (page 96) twice for each complex z -variable, once for the variables representing the real part and once for the imaginary part.

Implemented by a formulation-specific subclass.

build_params(*nm, dm*)

Build model parameters from data model.

```
nme.build_params(nm, dm)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object

Construction of incidence matrices C and D are handled in this base class. Building of the formulation-specific model parameters must be implemented by a formulation-specific subclass. The subclass should call its parent in order to construct the incidence matrices.

See also [incidence_matrix\(\)](#) (page 112), [node_indices\(\)](#) (page 112).

get_nv_(*sysx*)

Get number of (*possibly complex*) voltage variables.

```
nv_ = nme.get_nv_(sysx)
```

Input

sysx (*boolean*) – if true the state $\mathbf{x}_\text{}$ refers to the full (*possibly complex*) system state (*all node voltages and system non-voltage states*), otherwise it is the state vector for this specific element type (*port voltages and element non-voltage states*)

Output

nv_ (*integer*) – number of (*possibly complex*) voltage variables in the state variable $\mathbf{x}_\text{}$, whose meaning depends on the **sysx** input

x2vz(*x_, sysx, idx*)

Get port voltages and non-voltage states from combined state vector.

```
[v_, z_, vi_] = nme.x2vz(x_, sysx, idx)
```

Inputs

- **x_** (*double*) – possibly complex state vector
- **sysx** (*boolean*) – if true the state **x_** refers to the full (possibly complex) system state (all node voltages and system non-voltage states), otherwise it is the state vector for this specific element type (port voltages and element non-voltage states)
- **idx** (*integer*) – vector of port indices of interest

Outputs

- **v_** (*double*) – vector of (possibly complex) port voltages
- **z_** (*double*) – vector of (possibly complex) non-voltage state variables
- **vi_** (*double*) – vector of (possibly complex) port voltages for selected ports only, as indexed by **idx**

This method extracts voltage and non-voltage states from a combined state vector, optionally with voltages for specific ports only.

Note, that this method can operate on multiple state vectors simultaneously, by specifying **x_** as a matrix. In this case, each output will have the same number of columns, one for each column of the input **x_**.

node_indices(*nm, dm, cxn_type, cxn_idx_prop, cxn_type_prop*)

Construct node indices from data model element connection info.

```
nidxs = nme.node_indices(nm, dm)
nidxs = nme.node_indices(nm, dm, cxn_type, cxn_idx_prop)
nidxs = nme.node_indices(nm, dm, cxn_type, cxn_idx_prop, cxn_type_prop)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **cxn_type** (*char array or cell array of char arrays*) – name(s) of type(s) of junction elements, i.e. node-creating elements (e.g. 'bus'), to which this element connects; see [mp.dm_element.cxn_type\(\)](#) (page 38) for more info
- **cxn_idx_prop** (*char array or cell array of char arrays*) – name(s) of property(ies) containing indices of junction elements that define connections (e.g. {'fbus', 'tbus'}); see [mp.dm_element.cxn_idx_prop\(\)](#) (page 38) for more info
- **cxn_type_prop** (*char array or cell array of char arrays*) – name(s) of properties containing type of junction elements for each connection, defaults to '' if **cxn_type** and **cxn_type_prop** are provided, but not **cxn_type_prop**; see [mp.dm_element.cxn_type_prop\(\)](#) (page 39) for more info

Output

nidxs (*cell array*) – 1 x *np* cell array of node index vectors for each port

This method constructs the node index vectors for each port. That is, element *p* of **nidxs** is the vector of indices of the nodes to which port *p* of these elements are connected. These node indices can be used to construct the element-node incidence matrices that form **C**.

By default, the connection information is obtained from the corresponding data model element, as described in the `sec_dm_element_cxn` section in the *MATPOWER Developer's Manual*.

See also [incidence_matrix\(\)](#) (page 112), [mp.dm_element.cxn_type\(\)](#) (page 38), [mp.dm_element.cxn_idx_prop\(\)](#) (page 38), [mp.dm_element.cxn_type_prop\(\)](#) (page 39).

incidence_matrix(*m, varargin*)

Construct stacked incidence matrix from set of index vectors.

```
CD = nme.incidence_matrix(m, idx1, idx2, ...)
```

Inputs

- **m** (*integer*) – total number of nodes or states
- **idx1** (*integer*) – index vector for nodes corresponding to this element's first port, or state variables corresponding to this element's first non-voltage state
- **idx2** (*integer*) – same as **idx1** for second port or non-voltage state, and so on

Output

CD (*sparse matrix*) – stacked incidence matrix (C for ports, D for states)

Forms an $m \times n$ incidence matrix for each input index vector **idx**, where n is the dimension of **idx**, and column j of the corresponding incidence matrix consists of all zeros with a 1 in row **idx**(j).

These incidence matrices are then stacked horizontally to form a single matrix return value.

node_types(*nm, dm, idx*)

Get node type information.

```
ntv          = nme.node_types(nm, dm)
[ref, pv, pq] = nme.node_types(nm, dm)
...          = nme.node_types(nm, dm, idx)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **idx** (*integer*) – index (*not used in base method*)

Outputs

- **ntv** (*integer*) – node type vector, valid element values are:
 - [mp.NODE_TYPE.REF](#) (page 169)
 - [mp.NODE_TYPE.PV](#) (page 169)
 - [mp.NODE_TYPE.PQ](#) (page 169)
- **ref** (*integer*) – vector of indices of reference nodes
- **pv** (*integer*) – vector of indices of PV nodes
- **pq** (*integer*) – vector of indices of PQ nodes

See also [mp.NODE_TYPE](#) (page 169).

set_node_type_ref(*dm, idx*)

Make the specified node a reference node.

```
nme.set_node_type_ref(dm, idx)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model object
- **idx** (*integer*) – index of node to modify, this is the internal network model element index

Set the specified node to type [mp.NODE_TYPE.REF](#) (page 169).

Implementation provided by node-creating subclass.

set_node_type_pv(*dm, idx*)

Make the specified node a PV node.

```
nme.set_node_type_pv(dm, idx)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model object
- **idx** (*integer*) – index of node to modify, this is the internal network model element index

Set the specified node to type [mp.NODE_TYPE.PV](#) (page 169).

Implementation provided by node-creating subclass.

set_node_type_pq(*dm*, *idx*)

Make the specified node a PQ node.

```
nme.set_node_type_pq(dm, idx)
```

Inputs

- **dm** (*mp.data_model* (page 27)) – data model object
- **idx** (*integer*) – index of node to modify, this is the internal network model element index

Set the specified node to type *mp.NODE_TYPE.PQ* (page 169).

Implementation provided by node-creating subclass.

display()

Display the network model element object.

This method is called automatically when omitting a semicolon on a line that returns an object of this class.

Displays the details of the elements, including total number of elements, nodes per element, ports per element, non-voltage state per element, formulation name, tag, and class, and names and dimensions of the model parameters.

mp.nme_branch

class mp.nme_branch

Bases: *mp.nm_element* (page 107)

mp.nme_branch (page 114) - Network model element abstract base class for branch.

Implements the network model element for branch elements, including transmission lines and transformers, with 2 ports per branch.

Method Summary

name()

np()

mp.nme_branch_ac

class mp.nme_branch_ac

Bases: *mp.nme_branch* (page 114)

mp.nme_branch_ac (page 114) - Network model element abstract base class for branch for AC formulations.

Implements building of the admittance parameter \underline{Y} for branches.

Method Summary

build_params(*nm*, *dm*)

Builds the admittance parameter \underline{Y} for branches.

mp.nme_branch_acc

class mp.nme_branch_acc

Bases: [mp.nme_branch_ac](#) (page 114), [mp.form_acc](#) (page 82)

[mp.nme_branch_acc](#) (page 115) - Network model element for branch for AC cartesian voltage formulations.

Implements functions for the voltage angle difference limits and their derivatives and inherits from [mp.form_acc](#) (page 82).

Method Summary

ang_diff_fcn(*xx*, *Aang*, *lang*, *uang*)

ang_diff_hess(*xx*, *lambda*, *Aang*)

mp.nme_branch_acp

class mp.nme_branch_acp

Bases: [mp.nme_branch_ac](#) (page 114), [mp.form_acp](#) (page 86)

[mp.nme_branch_acp](#) (page 115) - Network model element for branch for AC polar voltage formulations.

Inherits from [mp.form_acp](#) (page 86).

mp.nme_branch_dc

class mp.nme_branch_dc

Bases: [mp.nme_branch](#) (page 114), [mp.form_dc](#) (page 88)

[mp.nme_branch_dc](#) (page 115) - Network model element for branch for DC formulations.

Implements building of the branch parameters \underline{B} and \underline{p} , and inherits from [mp.form_dc](#) (page 88).

Method Summary

build_params(*nm*, *dm*)

mp.nme_bus

class mp.nme_bus

Bases: [mp.nm_element](#) (page 107)

[mp.nme_bus](#) (page 116) - Network model element abstract base class for bus.

Implements the network model element for bus elements, with 1 node per bus.

Implements node type methods.

Method Summary

name()

nn()

node_types(*nm, dm, idx*)

set_node_type_ref(*nm, dm, idx*)

set_node_type_pv(*nm, dm, idx*)

set_node_type_pq(*nm, dm, idx*)

mp.nme_bus_acc

class mp.nme_bus_acc

Bases: [mp.nme_bus](#) (page 116), [mp.form_acc](#) (page 82)

[mp.nme_bus_acc](#) (page 116) - Network model element for bus for AC cartesian voltage formulations.

Adds voltage variables V_r and V_i to the network model and inherits from [mp.form_acc](#) (page 82).

Method Summary

add_vvars(*nm, dm, idx*)

mp.nme_bus_acp

class mp.nme_bus_acp

Bases: [mp.nme_bus](#) (page 116), [mp.form_acp](#) (page 86)

[mp.nme_bus_acp](#) (page 116) - Network model element for bus for AC cartesian polar formulations.

Adds voltage variables V_a and V_m to the network model and inherits from [mp.form_acp](#) (page 86).

Method Summary

add_vvars(*nm, dm, idx*)

mp.nme_bus_dc

class mp.nme_bus_dc

Bases: [mp.nme_bus](#) (page 116), [mp.form_dc](#) (page 88)

[mp.nme_bus_dc](#) (page 117) - Network model element for bus for DC formulations.

Adds voltage variable V_a to the network model and inherits from [mp.form_dc](#) (page 88).

Method Summary

add_vvars(*nm, dm, idx*)

mp.nme_gen

class mp.nme_gen

Bases: [mp.nm_element](#) (page 107)

[mp.nme_gen](#) (page 117) - Network model element abstract base class for generator.

Implements the network model element for generator elements, with 1 port and 1 non-voltage state per generator.

Method Summary

name()

np()

nz()

mp.nme_gen_ac

class mp.nme_gen_ac

Bases: [mp.nme_gen](#) (page 117)

[mp.nme_gen_ac](#) (page 117) - Network model element abstract base class for generator for AC formulations.

Adds non-voltage state variables P_g and Q_g to the network model and builds the parameter \underline{N} .

Method Summary

add_zvars(*nm, dm, idx*)

build_params(*nm, dm*)

mp.nme_gen_acc

class mp.nme_gen_acc

Bases: [mp.nme_gen_ac](#) (page 117), [mp.form_acc](#) (page 82)

[mp.nme_gen_acc](#) (page 118) - Network model element for generator for AC cartesian voltage formulations.

Inherits from [mp.form_acc](#) (page 82).

mp.nme_gen_acp

class mp.nme_gen_acp

Bases: [mp.nme_gen_ac](#) (page 117), [mp.form_acp](#) (page 86)

[mp.nme_gen_acp](#) (page 118) - Network model element for generator for AC polar voltage formulations.

Inherits from [mp.form_acp](#) (page 86).

mp.nme_gen_dc

class mp.nme_gen_dc

Bases: [mp.nme_gen](#) (page 117), [mp.form_dc](#) (page 88)

[mp.nme_gen_dc](#) (page 118) - Network model element for generator for DC formulations.

Adds non-voltage state variable P_g to the network model, builds the parameter \underline{K} , and inherits from [mp.form_dc](#) (page 88).

Method Summary

add_zvars(*nm*, *dm*, *idx*)

build_params(*nm*, *dm*)

mp.nme_load

class mp.nme_load

Bases: [mp.nm_element](#) (page 107)

[mp.nme_load](#) (page 118) - Network model element abstract base class for load.

Implements the network model element for load elements, with 1 port per load.

Method Summary

name()

np()

mp.nme_load_ac

class mp.nme_load_ac

Bases: [mp.nme_load](#) (page 118)

[mp.nme_load_ac](#) (page 119) - Network model element abstract base class for load for AC formulations.

Builds the parameters \underline{s} and \underline{Y} and nonlinear functions $\mathbf{s}^{nl_n}(\mathbf{x})$ and $\mathbf{i}^{nl_n}(\mathbf{x})$.

Method Summary

build_params(*nm*, *dm*)

port_inj_current_nln(*Sd*, *x_*, *sysx*, *idx*)

port_inj_power_nln(*Sd*, *x_*, *sysx*, *idx*)

mp.nme_load_acc

class mp.nme_load_acc

Bases: [mp.nme_load_ac](#) (page 119), [mp.form_acc](#) (page 82)

[mp.nme_load_acc](#) (page 119) - Network model element for load for AC cartesian voltage formulations.

Inherits from [mp.form_acc](#) (page 82).

mp.nme_load_acp

class mp.nme_load_acp

Bases: [mp.nme_load_ac](#) (page 119), [mp.form_acp](#) (page 86)

[mp.nme_load_acp](#) (page 119) - Network model element for load for AC polar voltage formulations.

Inherits from [mp.form_acp](#) (page 86).

mp.nme_load_dc

class mp.nme_load_dc

Bases: [mp.nme_load](#) (page 118), [mp.form_dc](#) (page 88)

[mp.nme_load_dc](#) (page 119) - Network model element for load for DC formulations.

Builds the parameter \underline{p} and inherits from [mp.form_dc](#) (page 88).

Method Summary

build_params(*nm*, *dm*)

mp.nme_shunt

class mp.nme_shunt

Bases: [mp.nm_element](#) (page 107)

[mp.nme_shunt](#) (page 120) - Network model element abstract base class for shunt.

Implements the network model element for shunt elements, with 1 port per shunt.

Method Summary

name()

np()

mp.nme_shunt_ac

class mp.nme_shunt_ac

Bases: [mp.nme_shunt](#) (page 120)

[mp.nme_shunt_ac](#) (page 120) - Network model element abstract base class for shunt for AC formulations.

Builds the parameter Y.

Method Summary

build_params(*nm*, *dm*)

mp.nme_shunt_acc

class mp.nme_shunt_acc

Bases: [mp.nme_shunt_ac](#) (page 120), [mp.form_acc](#) (page 82)

[mp.nme_shunt_acc](#) (page 120) - Network model element for shunt for AC cartesian voltage formulations.

Inherits from [mp.form_acc](#) (page 82).

mp.nme_shunt_acp

class mp.nme_shunt_acp

Bases: [mp.nme_shunt_ac](#) (page 120), [mp.form_acp](#) (page 86)

[mp.nme_shunt_acp](#) (page 120) - Network model element for shunt for AC polar voltage formulations.

Inherits from [mp.form_acp](#) (page 86).

mp.nme_shunt_dc

class mp.nme_shunt_dc

Bases: [mp.nme_shunt](#) (page 120), [mp.form_dc](#) (page 88)

[mp.nme_shunt_dc](#) (page 121) - Network model element for shunt for DC formulations.

Builds the parameter p and inherits from [mp.form_dc](#) (page 88).

Method Summary

build_params(*nm, dm*)

3.5 Mathematical Model Classes

3.5.1 Containers

mp.math_model

class mp.math_model

Bases: [mp.element_container](#) (page 165), [opt_model](#)

[mp.math_model](#) (page 121) - Abstract base class for MATPOWER **mathematical model** objects.

The mathematical model, or math model, formulates and defines the mathematical problem to be solved. That is, it determines the variables, constraints, and objective that define the problem. This takes on different forms depending on the task (*e.g. power flow, optimal power flow, etc.*) and the formulation (*e.g. DC, AC-polar-power, etc.*).

A math model object is a container for math model element ([mp.mm_element](#) (page 143)) objects and it is also an MP-Opt-Model ([opt_model](#)) object. All math model classes inherit from [mp.math_model](#) (page 121) and therefore also from [mp.element_container](#) (page 165), [opt_model](#), and [mp_idx_manager](#). Concrete math model classes are task and formulation specific. They also sometimes inherit from abstract mix-in classes that are shared across tasks or formulations.

By convention, math model variables are named `mm` and math model class names begin with `mp.math_model`.

mp.math_model Properties:

- [aux_data](#) (page 122) - auxiliary data relevant to the model

mp.math_model Methods:

- [task_tag\(\)](#) (page 122) - returns task tag, e.g. 'PF', 'OPF'
- [task_name\(\)](#) (page 122) - returns task name, e.g. 'Power Flow', 'Optimal Power Flow'
- [form_tag\(\)](#) (page 122) - returns network formulation tag, e.g. 'dc', 'acps'
- [form_name\(\)](#) (page 122) - returns network formulation name, e.g. 'DC', 'AC-polar-power'
- [build\(\)](#) (page 122) - create, add, and build math model element objects
- [display\(\)](#) (page 123) - display the math model object
- [add_aux_data\(\)](#) (page 123) - builds auxiliary data and adds it to the model

- [`build_base_aux_data\(\)`](#) (page 123) - builds base auxiliary data, including node types & variable initial values
- [`add_vars\(\)`](#) (page 123) - add variables to the model
- [`add_system_vars\(\)`](#) (page 123) - add system variables to the model
- [`add_constraints\(\)`](#) (page 124) - add constraints to the model
- [`add_system_constraints\(\)`](#) (page 124) - add system constraints to the model
- [`add_node_balance_constraints\(\)`](#) (page 124) - add node balance constraints to the model
- [`add_costs\(\)`](#) (page 124) - add costs to the model
- [`add_system_costs\(\)`](#) (page 125) - add system costs to the model
- [`solve_opts\(\)`](#) (page 125) - return an options struct to pass to the solver
- [`update_nm_vars\(\)`](#) (page 125) - update network model variables from math model solution
- [`data_model_update\(\)`](#) (page 126) - update data model from math model solution
- [`network_model_x_soln\(\)`](#) (page 126) - convert solved state from math model to network model solution

See the `sec_math_model` section in the [MATPOWER Developer's Manual](#) for more information.

See also [`mp.task`](#) (page 7), [`mp.data_model`](#) (page 27), [`mp.net_model`](#) (page 90).

Property Summary

`aux_data`

(*struct*) auxiliary data relevant to the model, e.g. can be passed to model constraint functions

Method Summary

`task_tag()`

Returns task tag, e.g. 'PF', 'OPF'.

```
tag = mm.task_tag()
```

`task_name()`

Returns task name, e.g. 'Power Flow', 'Optimal Power Flow'.

```
name = mm.task_name()
```

`form_tag()`

Returns network formulation tag, e.g. 'dc', 'acps'.

```
tag = mm.form_tag()
```

`form_name()`

Returns network formulation name, e.g. 'DC', 'AC-polar-power'.

```
name = mm.form_name()
```

`build(nm, dm, mpop)`

Create, add, and [`build\(\)`](#) (page 122) math model element objects.

```
mm.build(nm, dm, mpopt);
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Create and add network model objects, create and add auxiliary data, and add variables, constraints, and costs.

display()

Display the math model object.

This method is called automatically when omitting a semicolon on a line that returns an object of this class.

Displays the details of the variables, constraints, costs, and math model elements.

See also `mp_idx_manager`.

add_aux_data(nm, dm, mpopt)

Builds auxiliary data and adds it to the model.

```
mm.add_aux_data(nm, dm, mpopt)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Calls the `build_aux_data()` method and assigns the result to the `aux_data` property. The base `build_aux_data()` method, which simply calls [build_base_aux_data\(\)](#) (page 123), is defined in [mp.mm_shared_pfcopf](#) (page 138) (and in [mp.math_model_opf](#) (page 131)) allowing it to be shared across math models for different tasks (PF and CPF).

build_base_aux_data(nm, dm, mpopt)

Builds base auxiliary data, including node types & variable initial values.

```
ad = mm.build_base_aux_data(nm, dm, mpopt)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

ad (*struct*) – struct of auxiliary data

add_vars(nm, dm, mpopt)

Add variables to the model.

```
mm.add_vars(nm, dm, mpopt)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Adds system variables, then calls the [add_vars\(\)](#) (page 144) method for each math model element.

add_system_vars(*nm, dm, mpopt*)

Add system variables to the model.

```
mm.add_system_vars(nm, dm, mpopt)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Variables which correspond to a specific math model element should be added by that element's [add_vars\(\)](#) (page 144) method. Other variables can be added by [add_system_vars\(\)](#) (page 123). In this base class this method does nothing.

add_constraints(*nm, dm, mpopt*)

Add constraints to the model.

```
mm.add_constraints(nm, dm, mpopt)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Adds system constraints, then calls the [add_constraints\(\)](#) (page 144) method for each math model element.

add_system_constraints(*nm, dm, mpopt*)

Add system constraints to the model.

```
mm.add_system_constraints(nm, dm, mpopt)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Constraints which correspond to a specific math model element should be added by that element's [add_constraints\(\)](#) (page 144) method. Other constraints can be added by [add_system_constraints\(\)](#) (page 124). In this base class, it simply calls [add_node_balance_constraints\(\)](#) (page 124).

add_node_balance_constraints(*nm, dm, mpopt*)

Add node balance constraints to the model.

```
mm.add_node_balance_constraints(nm, dm, mpopt)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

In this base class this method does nothing.

add_costs(*nm, dm, mpopt*)

Add costs to the model.


```
mm.add_costs(nm, dm, mpopt)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Adds system costs, then calls the [add_costs\(\)](#) (page 145) method for each math model element.

```
add_system_costs(nm, dm, mpopt)
```

Add system costs to the model.

```
mm.add_system_costs(nm, dm, mpopt)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Costs which correspond to a specific math model element should be added by that element's [add_costs\(\)](#) (page 145) method. Other variables can be added by [add_system_costs\(\)](#) (page 125). In this base class this method does nothing.

```
solve_opts(nm, dm, mpopt)
```

Return an options struct to pass to the solver.

```
opt = mm.solve_opts(nm, dm, mpopt)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Output

opt (*struct*) – options struct for solver

In this base class, returns an empty struct.

```
update_nm_vars(mmx, nm)
```

Update network model variables from math model solution.

```
nm_vars = mm.update_nm_vars(mmx, nm)
```

Inputs

- **mmx** (*double*) – vector of math model variable x
- **nm** ([mp.net_model](#) (page 90)) – network model object

Output

nm_vars (*struct*) – updated network model variables

Returns a struct with the network model variables as fields. The `mm.aux_data.var_map` cell array is used to track mappings of math model variables back to network model variables. Each entry is itself a 7-element cell array of the form

```
{nm_var_type, nm_i1, nm_iN, nm_idx, mm_i1, mm_iN, mm_idx}
```

where

- **nm_var_type** - network model variable type (e.g. va, vm, zr, zi)
- **nm_i1** - starting index for network model variable type
- **nm_iN** - ending index for network model variable type

- `nm_idx` - vector of indices for network model variable type
- `mm_i1` - starting index for math model variable
- `mm_iN` - ending index for math model variable
- `mm_idx` - vector of indices for math model variable

Uses either `i1:iN` (if `i1` is not empty) or `idx` as the indices, unless both are empty, in which case it uses `':'`.

`data_model_update(nm, dm, mpopt)`

Update data model from math model solution.

```
dm = mm.data_model_update(nm, dm, mpopt)
```

Inputs

- **`nm`** ([mp.net_model](#) (page 90)) – network model object
- **`dm`** ([mp.data_model](#) (page 27)) – data model object
- **`mpopt`** (*struct*) – MATPOWER options struct

Output

`dm` ([mp.data_model](#) (page 27)) – updated data model object

Calls the [data_model_update\(\)](#) (page 145) method for each math model element.

`network_model_x_soln(nm)`

Convert solved state from math model to network model solution.

```
nm = mm.network_model_x_soln(nm)
```

Input

`nm` ([mp.net_model](#) (page 90)) – network model object

Output

`nm` ([mp.net_model](#) (page 90)) – updated network model object

Calls `convert_x_m2n()` to which is defined in a subclass of in [mp.mm_shared_pfcpf](#) (page 138) (and of [mp.math_model_opf](#) (page 131)) allowing it to be shared across math models for different tasks (PF and CPF).

`mp.math_model_pf`

`class mp.math_model_pf`

Bases: [mp.math_model](#) (page 121)

[mp.math_model_pf](#) (page 126) - Abstract base class for power flow (PF) **math model** objects.

Implements setting up of solver options from MATPOWER options struct.

Method Summary

`task_tag()`

`task_name()`

`add_costs(nm, dm, mpopt)`

`add_system_vars(nm, dm, mpopt)`

`solve_opts(nm, dm, mpopt)`

`mp.math_model_pf_ac`

class `mp.math_model_pf_ac`

Bases: `mp.math_model_pf` (page 126)

`mp.math_model_pf_ac` (page 127) - Power flow (PF) **math model** for AC formulations.

Provides AC-specific and PF-specific subclasses for elements.

Constructor Summary

`math_model_pf_ac()`

`mp.math_model_pf_acci`

class `mp.math_model_pf_acci`

Bases: `mp.math_model_pf_ac` (page 127), `mp.mm_shared_pfcpf_acci` (page 140)

`mp.math_model_pf_acci` (page 127) - Power flow (PF) **math model** for AC-cartesian-current formulation.

Implements formulation-specific node balance constraints and inherits from formulation-specific class for shared PF/CPF code.

Method Summary

`form_tag()`

`form_name()`

`add_node_balance_constraints(nm, dm, mpopt)`

`mp.math_model_pf_accs`

class `mp.math_model_pf_accs`

Bases: `mp.math_model_pf_ac` (page 127), `mp.mm_shared_pfcpf_accs` (page 140)

`mp.math_model_pf_accs` (page 127) - Power flow (PF) **math model** for AC-cartesian-power formulation.

Implements formulation-specific node balance constraints and inherits from formulation-specific class for shared PF/CPF code.

Method Summary

`form_tag()`

`form_name()`

`add_node_balance_constraints(nm, dm, mpopt)`

mp.math_model_pf_acpi

class `mp.math_model_pf_acpi`

Bases: `mp.math_model_pf_ac` (page 127), `mp.mm_shared_pfcpf_acpi` (page 141)

`mp.math_model_pf_acpi` (page 128) - Power flow (PF) **math model** for AC-polar-current formulation.

Implements formulation-specific node balance constraints and inherits from formulation-specific class for shared PF/CPF code.

Method Summary

`form_tag()`

`form_name()`

`add_node_balance_constraints(nm, dm, mpopt)`

mp.math_model_pf_acps

class `mp.math_model_pf_acps`

Bases: `mp.math_model_pf_ac` (page 127), `mp.mm_shared_pfcpf_acps` (page 141)

`mp.math_model_pf_acps` (page 128) - Power flow (PF) **math model** for AC-polar-power formulation.

Implements formulation-specific node balance constraints and inherits from formulation-specific class for shared PF/CPF code.

Also includes implementations of methods specific to fast-decoupled power flow.

Method Summary

`form_tag()`

`form_name()`

`add_node_balance_constraints(nm, dm, mpopt)`

`gs_x_update(x, f, nm, dm, mpopt)`

`zg_x_update(x, f, nm, dm, mpopt)`

`fd_jac_approx(nm, dm, mpopt)`

`fdpf_B_matrix_models(dm, alg)`

mp.math_model_pf_dc

class mp.math_model_pf_dc

Bases: [mp.math_model_pf](#) (page 126), [mp.mm_shared_pfcpf_dc](#) (page 141)

[mp.math_model_pf_dc](#) (page 129) - Power flow (PF) **math model** for DC formulation.

Provides formulation-specific and PF-specific subclasses for elements and implements formulation-specific node balance constraints.

Overrides the default [solve_opts\(\)](#) (page 129) method.

Constructor Summary

math_model_pf_dc()

Method Summary

form_tag()

form_name()

add_node_balance_constraints(nm, dm, mpopt)

solve_opts(nm, dm, mpopt)

mp.math_model_cpf_acc

class mp.math_model_cpf_acc

Bases: mp.math_model_cpf

[mp.math_model_cpf_acc](#) (page 129) - Abstract base class for AC cartesian CPF **math model** objects.

Provides formulation-specific and CPF-specific subclasses for elements.

Constructor Summary

math_model_cpf_acc()

Constructor, assign default network model element classes.

```
mm = math_model_cpf_acc()
```

mp.math_model_cpf_acci

class mp.math_model_cpf_acci

Bases: [mp.math_model_cpf_acc](#) (page 129), [mp.mm_shared_pfcpf_acci](#) (page 140)

[mp.math_model_cpf_acci](#) (page 129) - CPF **math model** for AC-cartesian-current formulation.

Implements formulation-specific and CPF-specific node balance constraint.

Method Summary

```
form_tag()
form_name()
add_node_balance_constraints(nm, dm, mpopt)
```

mp.math_model_cpf_accs

class mp.math_model_cpf_accs

Bases: [mp.math_model_cpf_acc](#) (page 129), [mp.mm_shared_pfcpf_accs](#) (page 140)
[mp.math_model_cpf_accs](#) (page 130) - CPF **math model** for AC-cartesian-power formulation.
Implements formulation-specific and CPF-specific node balance constraint.

Method Summary

```
form_tag()
form_name()
add_node_balance_constraints(nm, dm, mpopt)
```

mp.math_model_cpf_acp

class mp.math_model_cpf_acp

Bases: mp.math_model_cpf
[mp.math_model_cpf_acp](#) (page 130) - Abstract base class for AC polar CPF **math model** objects.
Provides formulation-specific and CPF-specific subclasses for elements and implementations of event and call-back functions for handling voltage limits.

Constructor Summary

```
math_model_cpf_acp()
    Constructor, assign default network model element classes.
```

```
mm = math_model_cpf_acp()
```

Method Summary

```
event_vlim(cx, opt, nm, dm, mpopt)
callback_vlim(k, nx, cx, px, s, opt, nm, dm, mpopt)
```

mp.math_model_cpf_acpi

class mp.math_model_cpf_acpi

Bases: [mp.math_model_cpf_acp](#) (page 130), [mp.mm_shared_pfcpi_acpi](#) (page 141)

[mp.math_model_cpf_acpi](#) (page 131) - CPF **math model** for AC-polar-current formulation.

Implements formulation-specific and CPF-specific node balance constraint.

Method Summary

form_tag()

form_name()

add_node_balance_constraints(nm, dm, mpopt)

mp.math_model_cpf_acps

class mp.math_model_cpf_acps

Bases: [mp.math_model_cpf_acp](#) (page 130), [mp.mm_shared_pfcpi_acps](#) (page 141)

[mp.math_model_cpf_acps](#) (page 131) - CPF **math model** for AC-polar-power formulation.

Implements formulation-specific and CPF-specific node balance constraint.

Provides methods for warm-starting solver with updated data.

Method Summary

form_tag()

form_name()

add_node_balance_constraints(nm, dm, mpopt)

expand_z_warmstart(nm, ad, varargin)

solve_opts_warmstart(opt, ws, nm)

mp.math_model_opf

class mp.math_model_opf

Bases: [mp.math_model](#) (page 121)

[mp.math_model_opf](#) (page 131) - Abstract base class for optimal power flow (OPF) **math model** objects.

Provide implementations for adding system variables to the mathematical model and creating an interior starting point.

Method Summary

task_tag()

```
task_name()

build_aux_data(nm, dm, mpopt)

add_system_vars(nm, dm, mpopt)

interior_x0(nm, dm, x0)

interior_va(nm, dm)
```

mp.math_model_opf_ac

class mp.math_model_opf_ac

Bases: [mp.math_model_opf](#) (page 131)

[mp.math_model_opf_ac](#) (page 132) - Abstract base class for AC OPF **math model** objects.

Provide implementation of nodal current and power balance functions and their derivatives, and setup of solver options.

Method Summary

```
nodal_current_balance_fcn(x, nm)

nodal_power_balance_fcn(x, nm)

nodal_current_balance_hess(x, lam, nm)

nodal_power_balance_hess(x, lam, nm)

solve_opts(nm, dm, mpopt)
```

mp.math_model_opf_acc

class mp.math_model_opf_acc

Bases: [mp.math_model_opf_ac](#) (page 132)

[mp.math_model_opf_acc](#) (page 132) - Abstract base class for AC cartesian OPF **math model** objects.

Provides formulation-specific and OPF-specific subclasses for elements.

Implements [convert_x_m2n\(\)](#) (page 132) to convert from math model state to network model state.

Constructor Summary

```
math_model_opf_acc()
```

Method Summary

```
convert_x_m2n(mmx, nm)

interior_va(nm, dm)
```


`mp.math_model_opf_acci`

class `mp.math_model_opf_acci`

Bases: `mp.math_model_opf_acc` (page 132)

`mp.math_model_opf_acci` (page 133) - OPF **math model** for AC-cartesian-current formulation.

Implements formulation-specific and OPF-specific node balance constraint and node balance price methods.

Method Summary

`form_tag()`

`form_name()`

`add_node_balance_constraints(nm, dm, mpopt)`

`node_power_balance_prices(nm)`

`mp.math_model_opf_acci_legacy`

class `mp.math_model_opf_acci_legacy`

Bases: `mp.math_model_opf_acci` (page 133), `mp.mm_shared_opf_legacy` (page 142)

`mp.math_model_opf_acci_legacy` (page 133) - OPF **math model** for AC-cartesian-current formulation w/legacy extensions.

Provides formulation-specific methods for handling legacy user customization of OPF problem.

Constructor Summary

`math_model_opf_acci_legacy()`

Method Summary

`add_named_set(varargin)`

`def_set_types()`

`init_set_types()`

`build(nm, dm, mpopt)`

`add_vars(nm, dm, mpopt)`

`add_system_costs(nm, dm, mpopt)`

`add_system_constraints(nm, dm, mpopt)`

`legacy_user_var_names()`

mp.math_model_opf_accs

class mp.math_model_opf_accs

Bases: [mp.math_model_opf_acc](#) (page 132)

[mp.math_model_opf_accs](#) (page 134) - OPF **math model** for AC-cartesian-power formulation.

Implements formulation-specific and OPF-specific node balance constraint and node balance price methods.

Method Summary

form_tag()

form_name()

add_node_balance_constraints(*nm, dm, mpopt*)

node_power_balance_prices(*nm*)

mp.math_model_opf_accs_legacy

class mp.math_model_opf_accs_legacy

Bases: [mp.math_model_opf_accs](#) (page 134), [mp.mm_shared_opf_legacy](#) (page 142)

[mp.math_model_opf_accs_legacy](#) (page 134) - OPF **math model** for AC-cartesian-power formulation w/legacy extensions.

Provides formulation-specific methods for handling legacy user customization of OPF problem.

Constructor Summary

math_model_opf_accs_legacy()

Method Summary

add_named_set(*varargin*)

def_set_types()

init_set_types()

build(*nm, dm, mpopt*)

add_vars(*nm, dm, mpopt*)

add_system_costs(*nm, dm, mpopt*)

add_system_constraints(*nm, dm, mpopt*)

legacy_user_var_names()

mp.math_model_opf_acp

class mp.math_model_opf_acp

Bases: [mp.math_model_opf_ac](#) (page 132)

[mp.math_model_opf_acp](#) (page 135) - Abstract base class for AC polar OPF **math model** objects.

Provides formulation-specific and OPF-specific subclasses for elements.

Implements [convert_x_m2n\(\)](#) (page 135) to convert from math model state to network model state.

Constructor Summary

math_model_opf_acp()

Method Summary

convert_x_m2n(*mmx*, *nm*)

mp.math_model_opf_acpi

class mp.math_model_opf_acpi

Bases: [mp.math_model_opf_acp](#) (page 135)

[mp.math_model_opf_acpi](#) (page 135) - OPF **math model** for AC-polar-current formulation.

Implements formulation-specific and OPF-specific node balance constraint and node balance price methods.

Method Summary

form_tag()

form_name()

add_node_balance_constraints(*nm*, *dm*, *mpopt*)

node_power_balance_prices(*nm*)

mp.math_model_opf_acpi_legacy

class mp.math_model_opf_acpi_legacy

Bases: [mp.math_model_opf_acpi](#) (page 135), [mp.mm_shared_opf_legacy](#) (page 142)

[mp.math_model_opf_acpi_legacy](#) (page 135) - OPF **math model** for AC-polar-current formulation w/legacy extensions.

Provides formulation-specific methods for handling legacy user customization of OPF problem.

Constructor Summary

math_model_opf_acpi_legacy()

Method Summary

```
add_named_set(varargin)
def_set_types()
init_set_types()
build(nm, dm, mpopt)
add_vars(nm, dm, mpopt)
add_system_costs(nm, dm, mpopt)
add_system_constraints(nm, dm, mpopt)
legacy_user_var_names()
```

mp.math_model_opf_acps

class `mp.math_model_opf_acps`

Bases: [mp.math_model_opf_acp](#) (page 135)

[mp.math_model_opf_acps](#) (page 136) - OPF **math model** for AC-polar-power formulation.

Implements formulation-specific and OPF-specific node balance constraint and node balance price methods.

Method Summary

```
form_tag()
form_name()
add_node_balance_constraints(nm, dm, mpopt)
node_power_balance_prices(nm)
```

mp.math_model_opf_acps_legacy

class `mp.math_model_opf_acps_legacy`

Bases: [mp.math_model_opf_acps](#) (page 136), [mp.mm_shared_opf_legacy](#) (page 142)

[mp.math_model_opf_acps_legacy](#) (page 136) - OPF **math model** for AC-polar-power formulation w/legacy extensions.

Provides formulation-specific methods for handling legacy user customization of OPF problem.

Constructor Summary

```
math_model_opf_acps_legacy()
```

Method Summary

```
add_named_set(varargin)
```

```

def_set_types()
init_set_types()
build(nm, dm, mpopt)
add_vars(nm, dm, mpopt)
add_system_costs(nm, dm, mpopt)
add_system_constraints(nm, dm, mpopt)
legacy_user_var_names()

```

mp.math_model_opf_dc

class mp.math_model_opf_dc

Bases: [mp.math_model_opf](#) (page 131)

[mp.math_model_opf_dc](#) (page 137) - Optimal Power flow (OPF) **math model** for DC formulation.

Provides formulation-specific and OPF-specific subclasses for elements.

Provides implementation of nodal balance constraint method and setup of solver options.

Implements [convert_x_m2n\(\)](#) (page 137) to convert from math model state to network model state.

Constructor Summary

```
math_model_opf_dc()
```

Method Summary

```
form_tag()
```

```
form_name()
```

```
convert_x_m2n(mmx, nm)
```

```
add_node_balance_constraints(nm, dm, mpopt)
```

```
solve_opts(nm, dm, mpopt)
```

mp.math_model_opf_dc_legacy

class mp.math_model_opf_dc_legacy

Bases: [mp.math_model_opf_dc](#) (page 137), [mp.mm_shared_opf_legacy](#) (page 142)

[mp.math_model_opf_dc](#) (page 137) - OPF **math model** for DC formulation w/legacy extensions.

Provides formulation-specific methods for handling legacy user customization of OPF problem.

Constructor Summary

```
math_model_opf_dc_legacy(mpc)
```

Method Summary

```
add_named_set(varargin)
```

```
def_set_types()
```

```
init_set_types()
```

```
build(nm, dm, mpopt)
```

```
add_vars(nm, dm, mpopt)
```

```
add_system_costs(nm, dm, mpopt)
```

```
add_system_constraints(nm, dm, mpopt)
```

```
legacy_user_var_names()
```

3.5.2 Container Mixins

`mp.mm_shared_pfcpf`

```
class mp.mm_shared_pfcpf
```

Bases: `handle`

[`mp.mm_shared_pfcpf`](#) (page 138) - Mixin class for PF/CPF **math model** objects.

An abstract mixin class inherited by all power flow (PF) and continuation power flow (CPF) **math model** objects.

Method Summary

```
build_aux_data(nm, dm, mpopt)
```

`mp.mm_shared_pfcpf_ac`

```
class mp.mm_shared_pfcpf_ac
```

Bases: [`mp.mm_shared_pfcpf`](#) (page 138)

[`mp.mm_shared_pfcpf_ac`](#) (page 138) - Mixin class for AC PF/CPF **math model** objects.

An abstract mixin class inherited by all AC power flow (PF) and continuation power flow (CPF) **math model** objects.

Method Summary

```
add_system_varset_pf(nm, vvar, typ)
```

update_z(*nm*, *v_*, *z_*, *ad*, *Sinj*, *idx*)

[*update_z\(\)*](#) (page 138) - Update/allocate active/reactive injections at slack/PV nodes.

Update/allocate slack know active power injections and slack/PV node reactive power injections.

mp.mm_shared_pfcpf_ac_i

class `mp.mm_shared_pfcpf_ac_i`

Bases: `handle`

[*mp.mm_shared_pfcpf_ac_i*](#) (page 139) - Mixin class for AC-current PF/CPF **math model** objects.

An abstract mixin class inherited by all AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a current balance formulation.

Code shared between AC cartesian and polar formulations with current balance belongs in this class.

Method Summary

build_aux_data_i(*nm*, *ad*)

mp.mm_shared_pfcpf_acc

class `mp.mm_shared_pfcpf_acc`

Bases: [*mp.mm_shared_pfcpf_ac*](#) (page 138)

[*mp.mm_shared_pfcpf_acc*](#) (page 139) - Mixin class for AC cartesian PF/CPF **math model** objects.

An abstract mixin class inherited by all AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a cartesian voltage formulation.

Method Summary

convert_x_m2n(*mmx*, *nm*, *only_v*)

[*convert_x_m2n\(\)*](#) (page 139) - Convert math model state to network model state.

```
x = mm.pf_convert(mmx, nm)
[v, z] = mm.pf_convert(mmx, nm)
[v, z, x] = mm.pf_convert(mmx, nm,)
... = mm.pf_convert(mmx, nm, only_v)
```

mp.mm_shared_pfcpf_acci

class mp.mm_shared_pfcpf_acci

Bases: [mp.mm_shared_pfcpf_acc](#) (page 139), [mp.mm_shared_pfcpf_ac_i](#) (page 139)

[mp.mm_shared_pfcpf_acci](#) (page 140) - Mixin class for AC-cartesian-current PF/CPF **math model** objects.

An abstract mixin class inherited by AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a cartesian voltage and current balance formulation.

Method Summary

```
build_aux_data(nm, dm, mpopt)
add_system_vars_pf(nm, dm, mpopt)
node_balance_equations(x, nm)
```

mp.mm_shared_pfcpf_accs

class mp.mm_shared_pfcpf_accs

Bases: [mp.mm_shared_pfcpf_acc](#) (page 139)

[mp.mm_shared_pfcpf_accs](#) (page 140) - Mixin class for AC-cartesian-power PF/CPF **math model** objects.

An abstract mixin class inherited by AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a cartesian voltage and power balance formulation.

Method Summary

```
add_system_vars_pf(nm, dm, mpopt)
node_balance_equations(x, nm)
```

mp.mm_shared_pfcpf_acp

class mp.mm_shared_pfcpf_acp

Bases: [mp.mm_shared_pfcpf_ac](#) (page 138)

[mp.mm_shared_pfcpf_acp](#) (page 140) - Mixin class for AC polar PF/CPF **math model** objects.

An abstract mixin class inherited by all AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a polar voltage formulation.

Method Summary

```
convert_x_m2n(mmx, nm, only_v)
convert\_x\_m2n\(\) (page 140) - Convert math model state to network model state.
```

```
x = mm.pf_convert(mmx, nm)
[v, z] = mm.pf_convert(mmx, nm)
[v, z, x] = mm.pf_convert(mmx, nm)
... = mm.pf_convert(mmx, nm, only_v)
```


mp.mm_shared_pfcpf_acpi

class mp.mm_shared_pfcpf_acpi

Bases: [mp.mm_shared_pfcpf_acp](#) (page 140), [mp.mm_shared_pfcpf_ac_i](#) (page 139)

[mp.mm_shared_pfcpf_acpi](#) (page 141) - Mixin class for AC-polar-current PF/CPF **math model** objects.

An abstract mixin class inherited by AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a polar voltage and current balance formulation.

Method Summary

build_aux_data(nm, dm, mpopt)

add_system_vars_pf(nm, dm, mpopt)

node_balance_equations(x, nm)

mp.mm_shared_pfcpf_acps

class mp.mm_shared_pfcpf_acps

Bases: [mp.mm_shared_pfcpf_acp](#) (page 140)

[mp.mm_shared_pfcpf_acps](#) (page 141) - Mixin class for AC-polar-power PF/CPF **math model** objects.

An abstract mixin class inherited by AC power flow (PF) and continuation power flow (CPF) **math model** objects that use a polar voltage and power balance formulation.

Method Summary

build_aux_data(nm, dm, mpopt)

add_system_vars_pf(nm, dm, mpopt)

node_balance_equations(x, nm, fdpf)

mp.mm_shared_pfcpf_dc

class mp.mm_shared_pfcpf_dc

Bases: [mp.mm_shared_pfcpf](#) (page 138)

[mp.mm_shared_pfcpf_dc](#) (page 141) - Mixin class for DC power flow (PF) **math model** objects.

An abstract mixin class inherited by DC power flow (PF) **math model** objects.

Method Summary

build_aux_data(nm, dm, mpopt)

add_system_vars_pf(*nm, dm, mpopt*)

convert_x_m2n(*mmx, nm, only_v*)

[convert_x_m2n\(\)](#) (page 142) - Convert math model state to network model state.

```
x = mm.pf_convert(mmx, nm)
[v, z] = mm.pf_convert(mmx, nm)
[v, z, x] = mm.pf_convert(mmx, nm)
... = mm.pf_convert(mmx, nm, only_v)
```

update_z(*nm, v, z, ad*)

[update_z\(\)](#) (page 142) - Update/allocate slack node active power injections.

mp.mm_shared_opf_legacy

class mp.mm_shared_opf_legacy

Bases: handle

[mp.mm_shared_opf_legacy](#) (page 142) - Mixin class for legacy optimal power flow (OPF) **math model** objects.

An abstract mixin class inherited by optimal power flow (OPF) **math model** objects that need to handle legacy user customization mechanisms.

Method Summary

def_set_types_legacy()

init_set_types_legacy()

get_mpc(*om*)

build_legacy(*nm, dm, mpopt*)

add_legacy_user_vars(*nm, dm, mpopt*)

add_legacy_user_costs(*nm, dm, dc*)

add_legacy_user_constraints(*nm, dm, mpopt*)

add_legacy_user_constraints_ac(*nm, dm, mpopt*)

add_legacy_cost(*om, name, idx, varargin*)

[add_legacy_cost\(\)](#) (page 142) - Add a set of user costs to the model

```
mm.add_legacy_cost(name, cp)
mm.add_legacy_cost(name, idx, varsets)
mm.add_legacy_cost(name, idx_list, cp)
mm.add_legacy_cost(name, idx_list, cp, varsets)
```

eval_legacy_cost(*om, x, name, idx*)

[eval_legacy_cost\(\)](#) (page 142) - Evaluate individual or full set of legacy user costs.

```
f = mm.eval_legacy_cost(x ...)
[f, df] = mm.eval_legacy_cost(x ...)
[f, df, d2f] = mm.eval_legacy_cost(x ...)
[f, df, d2f] = mm.eval_legacy_cost(x, name)
[f, df, d2f] = mm.eval_legacy_cost(x, name, idx_list)
```

params_legacy_cost(*om, name, idx*)

[params_legacy_cost\(\)](#) (page 143) - Return cost parameters for legacy user-defined costs.

```
cp = mm.params_legacy_cost()
cp = mm.params_legacy_cost(name)
cp = mm.params_legacy_cost(name, idx)
[cp, vs] = mm.params_legacy_cost(...)
[cp, vs, i1, iN] = mm.params_legacy_cost(...)
```

3.5.3 Elements

mp.mm_element

class mp.mm_element

Bases: handle

[mp.mm_element](#) (page 143) - Abstract base class for MATPOWER **mathematical model element** objects.

A math model element object typically does not contain any data, but only the methods that are used to build the math model and update the corresponding data model element once the math model has been solved.

All math model element classes inherit from [mp.mm_element](#) (page 143). Each element type typically implements its own subclasses, which are further subclassed where necessary per task and formulation, as with the container class.

By convention, math model element variables are named `mme` and math model element class names begin with `mp.mme`.

mp.mm_element Methods:

- [name\(\)](#) (page 144) - get name of element type, e.g. 'bus', 'gen'
- [data_model_element\(\)](#) (page 144) - get corresponding data model element
- [network_model_element\(\)](#) (page 144) - get corresponding network model element
- [add_vars\(\)](#) (page 144) - add math model variables for this element
- [add_constraints\(\)](#) (page 144) - add math model constraints for this element
- [add_costs\(\)](#) (page 145) - add math model costs for this element
- [data_model_update\(\)](#) (page 145) - update the corresponding data model element
- [data_model_update_off\(\)](#) (page 145) - update offline elements in corresponding data model element
- [data_model_update_on\(\)](#) (page 145) - update online elements in corresponding data model element

See the `sec_mm_element` section in the *MATPOWER Developer's Manual* for more information.

See also [mp.math_model](#) (page 121).

Method Summary

name()

Get name of element type, e.g. 'bus', 'gen'.

```
name = mme.name()
```

Output

name (*char array*) – name of element type, must be a valid struct field name

Implementation provided by an element type specific subclass.

data_model_element(dm, name)

Get corresponding data model element.

```
dme = mme.data_model_element(dm, name)
```

Inputs

- **dm** ([mp.data_model](#) (page 27)) – data model object
- **name** (*char array*) – name of element type

Output

dme ([mp.dm_element](#) (page 35)) – data model element object

network_model_element(nm, name)

Get corresponding network model element.

```
nme = mme.network_model_element(nm, name)
```

Inputs

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **name** (*char array*) – name of element type

Output

nme ([mp.nm_element](#) (page 107)) – network model element object

add_vars(mm, nm, dm, mpopt)

Add math model variables for this element.

```
mme.add_vars(mm, nm, dm, mpopt)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Implementation provided by a subclass.

add_constraints(mm, nm, dm, mpopt)

Add math model constraints for this element.

```
mme.add_constraints(obj, mm, nm, dm, mpopt)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object

- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Implementation provided by a subclass.

add_costs(*mm, nm, dm, mpopt*)

Add math model costs for this element.

```
mme.add_costs(obj, mm, nm, dm, mpopt)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Implementation provided by a subclass.

data_model_update(*mm, nm, dm, mpopt*)

Update the corresponding data model element.

```
mme.data_model_update(mm, nm, dm, mpopt)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Call [data_model_update_off\(\)](#) (page 145) then [data_model_update_on\(\)](#) (page 145) to update the data model for this element based on the math model solution.

See also [data_model_update_off\(\)](#) (page 145), [data_model_update_on\(\)](#) (page 145).

data_model_update_off(*mm, nm, dm, mpopt*)

Update offline elements in the corresponding data model element.

```
mme.data_model_update_off(mm, nm, dm, mpopt)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object
- **dm** ([mp.data_model](#) (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Set export variables for offline elements based on specs returned by [mp.dm_element.export_vars_offline_val\(\)](#) (page 40).

See also [data_model_update\(\)](#) (page 145), [data_model_update_on\(\)](#) (page 145).

data_model_update_on(*mm, nm, dm, mpopt*)

Update online elements in the corresponding data model element.

```
mme.data_model_update_on(mm, nm, dm, mpopt)
```

Inputs

- **mm** ([mp.math_model](#) (page 121)) – mathematical model object
- **nm** ([mp.net_model](#) (page 90)) – network model object

- **dm** (*mp.data_model* (page 27)) – data model object
- **mpopt** (*struct*) – MATPOWER options struct

Extract the math model solution relevant to this particular element and update the corresponding data model element for online elements accordingly.

Implementation provided by a subclass.

See also *data_model_update()* (page 145), *data_model_update_off()* (page 145).

mp.mme_branch

class mp.mme_branch

Bases: *mp.mm_element* (page 143)

mp.mme_branch (page 146) - Math model element abstract base class for branch.

Abstract math model element base class for branch elements, including transmission lines and transformers.

Method Summary

name()

mp.mme_branch_pf_ac

class mp.mme_branch_pf_ac

Bases: *mp.mme_branch* (page 146)

mp.mme_branch_pf_ac (page 146) - Math model element for branch for AC power flow.

Math model element class for branch elements, including transmission lines and transformers, for AC power flow problems.

Implements updating the output data in the corresponding data model element for in-service branches from the math model solution.

Method Summary

data_model_update_on(*mm, nm, dm, mpopt*)

mp.mme_branch_pf_dc

class mp.mme_branch_pf_dc

Bases: *mp.mme_branch* (page 146)

mp.mme_branch_pf_dc (page 146) - Math model element for branch for DC power flow.

Math model element class for branch elements, including transmission lines and transformers, for DC power flow problems.

Implements updating the output data in the corresponding data model element for in-service branches from the math model solution.

Method Summary

data_model_update_on(*mm, nm, dm, mpopt*)

mp.mme_branch_opf**class mp.mme_branch_opf**

Bases: [mp.mme_branch](#) (page 146)

[mp.mme_branch_opf](#) (page 147) - Math model element abstract base class for branch for OPF.

Math model element abstract base class for branch elements, including transmission lines and transformers, for OPF problems.

Implements methods to prepare data required for angle difference limit constraints and to extract shadow prices for these constraints from the math model solution.

Method Summary

ang_diff_params(*dm, ignore*)

ang_diff_prices(*mm, nme*)

mp.mme_branch_opf_ac**class mp.mme_branch_opf_ac**

Bases: [mp.mme_branch_opf](#) (page 147)

[mp.mme_branch_opf_ac](#) (page 147) - Math model element abstract base class for branch for AC OPF.

Math model element abstract base class for branch elements, including transmission lines and transformers, for AC OPF problems.

Implements methods for adding of branch flow constraints and for updating the output data in the corresponding data model element for in-service branches from the math model solution.

Method Summary

add_constraints(*mm, nm, dm, mpopt*)

data_model_update_on(*mm, nm, dm, mpopt*)

mp.mme_branch_opf_acc

class mp.mme_branch_opf_acc

Bases: [mp.mme_branch_opf_ac](#) (page 147)

[mp.mme_branch_opf_acc](#) (page 148) - Math model element for branch for AC cartesian voltage OPF.

Math model element class for branch elements, including transmission lines and transformers, for AC cartesian voltage OPF problems.

Implements method for adding branch angle difference constraints and overrides method to extract shadow prices for these constraints from the math model solution.

Method Summary

add_constraints(*mm, nm, dm, mpopt*)

ang_diff_prices(*mm, nme*)

mp.mme_branch_opf_acp

class mp.mme_branch_opf_acp

Bases: [mp.mme_branch_opf_ac](#) (page 147)

[mp.mme_branch_opf_acp](#) (page 148) - Math model element for branch for AC polar voltage OPF.

Math model element class for branch elements, including transmission lines and transformers, for AC polar voltage OPF problems.

Implements method for adding branch angle difference constraints.

Method Summary

add_constraints(*mm, nm, dm, mpopt*)

mp.mme_branch_opf_dc

class mp.mme_branch_opf_dc

Bases: [mp.mme_branch_opf](#) (page 147)

[mp.mme_branch_opf_dc](#) (page 148) - Math model element for branch for DC OPF.

Math model element class for branch elements, including transmission lines and transformers, for DC OPF problems.

Implements methods for adding of branch flow and angle difference constraints and for updating the output data in the corresponding data model element for in-service branches from the math model solution.

Method Summary

add_constraints(*mm, nm, dm, mpopt*)

`data_model_update_on(mm, nm, dm, mpopt)`

mp.mme_bus

class `mp.mme_bus`

Bases: [`mp.mm_element`](#) (page 143)

[`mp.mme_bus`](#) (page 149) - Math model element abstract base class for bus.

Abstract math model element base class for bus elements.

Method Summary

`name()`

mp.mme_bus_pf_ac

class `mp.mme_bus_pf_ac`

Bases: [`mp.mme_bus`](#) (page 149)

[`mp.mme_bus_pf_ac`](#) (page 149) - Math model element for bus for AC power flow.

Math model element class for bus elements for AC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service buses from the math model solution.

Method Summary

`data_model_update_on(mm, nm, dm, mpopt)`

mp.mme_bus_pf_dc

class `mp.mme_bus_pf_dc`

Bases: [`mp.mme_bus`](#) (page 149)

[`mp.mme_bus_pf_dc`](#) (page 149) - Math model element for bus for DC power flow.

Math model element class for bus elements for DC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service buses from the math model solution.

Method Summary

`data_model_update_on(mm, nm, dm, mpopt)`

mp.mme_bus_opf_ac

class mp.mme_bus_opf_ac

Bases: [mp.mme_bus](#) (page 149)

[mp.mme_bus_opf_ac](#) (page 150) - Math model element abstract base class for bus for AC OPF.

Abstract math model element class for bus elements for AC OPF problems.

Implements method for forming an interior initial point for voltage magnitudes.

Method Summary

interior_vm(*mm, nm, dm*)
return vm equal to avg of clipped limits

mp.mme_bus_opf_acc

class mp.mme_bus_opf_acc

Bases: [mp.mme_bus_opf_ac](#) (page 150)

[mp.mme_bus_opf_acc](#) (page 150) - Math model element for bus for AC cartesian voltage OPF.

Math model element class for bus elements for AC cartesian voltage OPF problems.

Implements methods for adding constraints for reference voltage angle, fixed voltage magnitudes and voltage magnitude limits, for forming an interior initial point and for updating the output data in the corresponding data model element for in-service buses from the math model solution.

Method Summary

add_constraints(*mm, nm, dm, mpopt*)
interior_x0(*mm, nm, dm, x0*)
data_model_update_on(*mm, nm, dm, mpopt*)

mp.mme_bus_opf_acp

class mp.mme_bus_opf_acp

Bases: [mp.mme_bus_opf_ac](#) (page 150)

[mp.mme_bus_opf_acp](#) (page 150) - Math model element for bus for AC polar voltage OPF.

Math model element class for bus elements for AC polar voltage OPF problems.

Implements methods for forming an interior initial point and for updating the output data in the corresponding data model element for in-service buses from the math model solution.

Method Summary

interior_x0(*mm, nm, dm, x0*)

data_model_update_on(*mm, nm, dm, mpop*)

mp.mme_bus_opf_dc

class mp.mme_bus_opf_dc

Bases: [mp.mme_bus](#) (page 149)

[mp.mme_bus_opf_dc](#) (page 151) - Math model element for bus for DC OPF.

Math model element class for bus elements for DC OPF problems.

Implements methods for forming an interior initial point and for updating the output data in the corresponding data model element for in-service buses from the math model solution.

Method Summary

interior_x0(*mm, nm, dm, x0*)

data_model_update_on(*mm, nm, dm, mpop*)

mp.mme_gen

class mp.mme_gen

Bases: [mp.mm_element](#) (page 143)

[mp.mme_gen](#) (page 151) - Math model element abstract base class for generator.

Abstract math model element base class for generator elements.

Method Summary

name()

mp.mme_gen_pf_ac

class mp.mme_gen_pf_ac

Bases: [mp.mme_gen](#) (page 151)

[mp.mme_gen_pf_ac](#) (page 151) - Math model element for generator for AC power flow.

Math model element class for generator elements for AC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service generators from the math model solution.

Method Summary

data_model_update_on(*mm, nm, dm, mpop*)

mp.mme_gen_pf_dc

class mp.mme_gen_pf_dc

Bases: [mp.mme_gen](#) (page 151)

[mp.mme_gen_pf_dc](#) (page 152) - Math model element for generator for DC power flow.

Math model element class for generator elements for DC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service generators from the math model solution.

Method Summary

data_model_update_on(mm, nm, dm, mpopt)

mp.mme_gen_opf

class mp.mme_gen_opf

Bases: [mp.mme_gen](#) (page 151)

[mp.mme_gen_opf](#) (page 152) - Math model element abstract base class for generator for OPF.

Math model element abstract base class for generator elements for OPF problems.

Implements methods to add costs, including piecewise linear cost variables, and to form an interior initial point for cost variables.

Property Summary

cost

struct for [cost](#) (page 152) parameters with fields:

- **poly_p** - polynomial costs for active power, struct returned by [mp.cost_table.poly_params\(\)](#) (page 162), with fields:
 - **have_quad_cost**
 - **i0, i1, i2, i3**
 - **k, c, Q**
- **poly_q** - polynomial costs for reactive power (*same struct as poly_p*)
- **pwl** - piecewise linear costs for active & reactive struct returned by [mp.cost_table.pwl_params\(\)](#) (page 163), with fields:
 - **n, i, A, b**

Method Summary

add_vars(mm, nm, dm, mpopt)

add_costs(mm, nm, dm, mpopt)

interior_x0(mm, nm, dm, x0)

mp.mme_gen_opf_ac

class mp.mme_gen_opf_ac

Bases: [mp.mme_gen_opf](#) (page 152)

[mp.mme_gen_opf_ac](#) (page 153) - Math model element for generator for AC OPF.

Math model element class for generator elements for AC OPF problems.

Implements methods for buliding and adding PQ capability constraints, dispatchable load power factor constraints, polynomial costs, and for updating the output data in the corresponding data model element for in-service generators from the math model solution.

Method Summary

add_constraints(*mm, nm, dm, mpopt*)

add_costs(*mm, nm, dm, mpopt*)

pq_capability_constraint(*dme, base_mva*)
from legacy [makeApq\(\)](#) (page 286)

has_pq_cap(*gen, upper_lower*)
from legacy [hasPQcap\(\)](#) (page 336)

disp_load_constant_pf_constraint(*dm*)
from legacy [makeAvl\(\)](#) (page 287)

build_cost_params(*dm*)

data_model_update_on(*mm, nm, dm, mpopt*)

mp.mme_gen_opf_dc

class mp.mme_gen_opf_dc

Bases: [mp.mme_gen_opf](#) (page 152)

[mp.mme_gen_opf_dc](#) (page 153) - Math model element for generator for DC OPF.

Math model element class for generator elements for DC OPF problems.

Implements methods for buliding cost parameters, adding piecewise linear cost constraints, and for updating the output data in the corresponding data model element for in-service generators from the math model solution.

Method Summary

add_constraints(*mm, nm, dm, mpopt*)

build_cost_params(*dm*)

data_model_update_on(*mm, nm, dm, mpopt*)

mp.mme_load

class mp.mme_load

Bases: [mp.mm_element](#) (page 143)

[mp.mme_load](#) (page 154) - Math model element abstract base class for load.

Abstract math model element base class for load elements.

Method Summary

name()

mp.mme_load_pf_ac

class mp.mme_load_pf_ac

Bases: [mp.mme_load](#) (page 154)

[mp.mme_load_pf_ac](#) (page 154) - Math model element for load for AC power flow.

Math model element class for load elements for AC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service loads from the math model solution.

Method Summary

data_model_update_on(*mm, nm, dm, mpop*)

mp.mme_load_pf_dc

class mp.mme_load_pf_dc

Bases: [mp.mme_load](#) (page 154)

[mp.mme_load_pf_dc](#) (page 154) - Math model element for load for DC power flow.

Math model element class for load elements for DC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service loads from the math model solution.

Method Summary

data_model_update_on(*mm, nm, dm, mpop*)

mp.mme_load_cpf

class mp.mme_load_cpf

Bases: [mp.mme_load_pf_ac](#) (page 154)

[mp.mme_load_cpf](#) (page 155) - Math model element for load for CPF.

Math model element class for load elements for AC CPF problems.

Implements method for updating the output data in the corresponding data model element for in-service loads from the math model solution.

Method Summary

data_model_update_on(mm, nm, dm, mpop)

mp.mme_shunt

class mp.mme_shunt

Bases: [mp.mm_element](#) (page 143)

[mp.mme_shunt](#) (page 155) - Math model element abstract base class for shunt.

Abstract math model element base class for shunt elements.

Method Summary

name()

mp.mme_shunt_pf_ac

class mp.mme_shunt_pf_ac

Bases: [mp.mme_shunt](#) (page 155)

[mp.mme_shunt_pf_ac](#) (page 155) - Math model element for shunt for AC power flow.

Math model element class for shunt elements for AC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service shunts from the math model solution.

Method Summary

data_model_update_on(mm, nm, dm, mpop)

mp.mme_shunt_pf_dc

class mp.mme_shunt_pf_dc

Bases: [mp.mme_shunt](#) (page 155)

[mp.mme_shunt_pf_dc](#) (page 156) - Math model element for shunt for DC power flow.

Math model element class for shunt elements for DC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service shunts from the math model solution.

Method Summary

data_model_update_on(*mm, nm, dm, mpopt*)

mp.mme_shunt_cpf

class mp.mme_shunt_cpf

Bases: [mp.mme_shunt_pf_ac](#) (page 155)

[mp.mme_shunt_cpf](#) (page 156) - Math model element for shunt for CPF.

Math model element class for shunt elements for AC CPF problems.

Implements method for updating the output data in the corresponding data model element for in-service shunts from the math model solution.

Method Summary

data_model_update_on(*mm, nm, dm, mpopt*)

3.6 Miscellaneous Classes

3.6.1 mp_table

class mp_table

[mp_table](#) (page 156) - Very basic table-compatible class for Octave or older Matlab.

```
T = mp_table(var1, var2, ...);  
T = mp_table(..., 'VariableNames', {name1, name2, ...});  
T = mp_table(..., 'RowNames', {name1, name2, ...});  
T = mp_table(..., 'DimensionNames', {name1, name2, ...});
```

Implements a very basic table array class focused the ability to store and access named variables of different types in a way that is compatible with MATLAB's built-in table class. Other features, such as table joining, etc., are not implemented.

Important: Since the dot syntax `T.<var_name>` is used to access table variables, you must use a functional syntax `<method>(T, ...)`, as opposed to the object-oriented `T.<method>(...)`, to call `mp_table` methods.

mp_table Methods:

- `mp_table()` (page 157) - construct object
- `istable()` (page 157) - true for `mp_table` (page 156) objects
- `size()` (page 157) - dimensions of table
- `isempty()` (page 157) - true if table has no columns or no rows
- `end()` (page 158) - used to index last row or variable/column
- `subsref()` (page 158) - indexing a table to retrieve data
- `subsasgn()` (page 158) - indexing a table to assign data
- `horzcat()` (page 159) - concatenate tables horizontally
- `vertcat()` (page 159) - concatenate tables vertically
- `display()` (page 159) - display table contents

See also `table`.

Constructor Summary

mp_table(*varargin*)

Constructs the object.

```
T = mp_table(var1, var2, ...)
T = mp_table(..., 'VariableNames', {name1, name2, ...})
T = mp_table(..., 'RowNames', {name1, name2, ...})
T = mp_table(..., 'DimensionNames', {name1, name2, ...})
```

Method Summary

istable()

Returns true.

```
TorF = istable(T)
```

Unfortunately, this is not really useful until Octave implements a built-in `istable()` (page 157) that this can override.

size(*dim*)

Returns dimensions of table.

```
[m, n] = size(T)
m = size(T, 1)
n = size(T, 2)
```

isempty()

Returns `true` if the table has no columns or no rows.

```
TorF = isempty(T)
```

end(*k, n*)

Used to index the last row or column of the table.

```
last_var = T{:, end}  
last_row = T(end, :)
```

subsref(*s*)

Called when indexing a table to retrieve data.

```
sub_T = T(i, *)  
sub_T = T(i1:iN, *)  
sub_T = T(:, *)  
sub_T = T(*, j)  
sub_T = T(*, j1:jN)  
sub_T = T(*, :)  
sub_T = T(*, <str>)  
sub_T = T(*, <cell>)  
var_<name> = T.<name>  
val = T.<name>(i)  
val = T.<name>(i1:iN)  
val = T.<name>{i}  
val = T.<name>{i1:iN}  
val = T.<name>(*, :)  
val = T.<name>(*, j)  
var_<j> = T{:, j}  
var_<str> = T{:, <str>}  
val = T{i, *}  
val = T{i1:iN, *}  
val = T{:, *}  
val = T{* , j}  
val = T{* , j1:jN}  
val = T{* , :}  
val = T{* , <str>}  
val = T{* , <cell>}
```

subsasgn(*s, b*)

Called when indexing a table to assign data.

```
T(i, *) = sub_T  
T(i1:iN, *) = sub_T  
T(:, *) = sub_T  
T(*, j) = sub_T  
T(*, j1:jN) = sub_T  
T(*, :) = sub_T  
T(*, <str>) = sub_T  
T(*, <cell>) = sub_T  
T.<name> = val  
T.<name>(i) = val  
T.<name>(i1:iN) = val  
T.<name>{i} = val  
T.<name>{i1:iN} = val
```

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```

T.<name>(*, :) = val
T.<name>(*, j) = val
T{:, j} = var_<j>
T{:, <str>} = var_<str>
T{i, *} = val
T{i1:iN, *} = val
T{:, *} = val
T{*, j} = val
T{*, j1:jN} = val
T{*, :} = val
T{*, <str>} = val
T{*, <cell>} = val

```

horzcat(varargin)

Concatenate tables horizontally.

```
T = [T1 T2]
```

vertcat(varargin)

Concatenate tables vertically.

```
T = [T1; T2]
```

display()

Display the table contents.

This method is called automatically when omitting a semicolon on a line that returns an object of this class.

By default it displays only the first and last 10 rows if there are more than 25 rows.

Does not currently display the contents of any nested tables.

static extract_named_args(args)

Extracts special named constructor arguments.

```

[var_names, row_names, dim_names, args] = extract_named_args(var1, var2, ...
↪)
[...] = extract_named_args(..., 'VariableNames', {name1, name2, ...})
[...] = extract_named_args(..., 'RowNames', {name1, name2, ...})
[...] = extract_named_args(..., 'DimensionNames', {name1, name2, ...})

```

Used to extract named arguments, 'VariableNames', 'RowNames', and 'DimensionNames', to pass to constructor.

3.6.2 mp_table_subclass

class mp_table_subclass

mp_table_subclass (page 160) - Class that acts like a table but isn't one.

Addresses two issues with inheriting from **table** classes (**table**) or *mp_table* (page 156)).

1. In MATLAB, **table** is a sealed class, so you cannot inherit from it. You can, however, use a subclass of *mp_table* (page 156), but that can result in the next issue under Octave.
2. While nesting of tables works just fine in general, when using *mp_table* (page 156) in Octave (at least up through 8.4.0), you cannot nest a subclass of *mp_table* (page 156) inside another *mp_table* (page 156) object because of this bug: <https://savannah.gnu.org/bugs/index.php?65037>.

To work around these issues, your “table subclass” can inherit from **this** class. An object of this class **isn't** a **table** or *mp_table* (page 156) object, but rather it **contains** one and attempts to act like one. That is, it delegates method calls (currently only those available in *mp_table* (page 156), listed below) to the contained table object.

The class of the contained table object is either **table** or *mp_table* (page 156) and is determined by *mp_table_class()* (page 6).

Limitations

1. The Octave bug mentioned above also affects tables that inherit from *mp_table_subclass* (page 160). That is, such tables can be nested inside tables of type **table** or *mp_table* (page 156), but not inside tables that are or inherit from *mp_table_subclass* (page 160).
2. In MATLAB, when nesting an *mp_table_subclass* (page 160) object within another *mp_table_subclass* (page 160) object, one cannot use multi-level indexing directly. E.g. If T2 is a variable in T1 and x is a variable in T2, attempting `x = T1.T2.x` will result in an error. The indexing must be done in multiple steps `T2 = T1.T2; x = T2.x`. Note: This only applies to MATLAB, where the contained table is a **table**. It works just fine in Octave, where the contained table is an *mp_table* (page 156).

Important: Since the dot syntax `T.<var_name>` is used to access table variables, you must use a functional syntax `<method>(T, ...)`, as opposed to the object-oriented `T.<method>(...)`, to call methods of this class or subclasses, as with *mp_table*.

mp.mp_table_subclass Properties:

- `tab` - (*table* or *mp_table*) contained table object this class emulates

mp.cost_table Methods:

- `mp_table_subclass()` - construct object
- `get_table()` (page 161) - return the table stored in `tab`
- `set_table()` (page 161) - assign a table to `tab`
- `istable()` - true for *mp_table* (page 156) objects
- `size()` - dimensions of table
- `isempty()` - true if table has no columns or no rows
- `end()` - used to index last row or variable/column
- `subsref()` - indexing a table to retrieve data

- `subsasgn()` - indexing a table to assign data
- `horzcat()` - concatenate tables horizontally
- `vertcat()` - concatenate tables vertically
- `display()` - display table contents

See also [mp_table](#) (page 156), [mp_table_class\(\)](#) (page 6).

Method Summary

`get_table()`

```
T = get_table(obj)
```

`set_table(T)`

```
set_table(obj, T)
```

3.6.3 mp.cost_table

class `mp.cost_table`

Bases: [mp_table_subclass](#) (page 160)

[mp.cost_table](#) (page 161) - Table for (polynomial and piecewise linear) cost parameters.

```
T = cost_table(poly_n, poly_coef, pwl_n, pwl_qty, pwl_cost);
```

Important: Since the dot syntax `T.<var_name>` is used to access table variables, you must use a functional syntax `<method>(T, ...)`, as opposed to the object-oriented `T.<method>(...)`, to call standard `mp.cost_table` methods.

Standard table subscripting syntax is not available within methods of this class (references built-in `subsref()` and `subsasgn()` rather than the versions overridden by the table class). For this reason, some method implementations are delegated to static methods in [mp.cost_table_utils](#) (page 164) where that syntax is available, making the code more readable.

`mp.cost_table` Methods:

- [cost_table\(\)](#) (page 162) - construct object
- [poly_params\(\)](#) (page 162) - create struct of polynomial parameters from [mp.cost_table](#) (page 161)
- [pwl_params\(\)](#) (page 163) - create struct of piecewise linear parameters from [mp.cost_table](#) (page 161)
- [max_pwl_cost\(\)](#) (page 163) - get maximum cost component used to specify pwl costs

An [mp.cost_table](#) (page 161) has the following columns:

Name	Type	Description
<code>poly_n</code>	<i>integer</i>	n_{poly} , number of coefficients in polynomial cost curve, $f_{\text{poly}}(x) = c_0 + c_1x + \dots + c_Nx^N$, where $n_{\text{poly}} = N + 1$
<code>poly_coef</code>	<i>double</i>	matrix of coefficients c_j , of polynomial cost $f_{\text{poly}}(x)$, where c_j is found in column $j + 1$
<code>pwl_n</code>	<i>double</i>	n_{pwl} , number of data points $(x_1, f_1), (x_2, f_2), \dots, (x_N, f_N)$ defining a piecewise linear cost curve, $f_{\text{pwl}}(x)$ where $N = n_{\text{pwl}}$
<code>pwl_qty</code>	<i>double</i>	matrix of <i>quantity</i> coordinates x_j for piecewise linear cost $f_{\text{pwl}}(x)$, where x_j is found in column j
<code>pwl_cost</code>	<i>double</i>	matrix of <i>cost</i> coordinates f_j for piecewise linear cost $f_{\text{pwl}}(x)$, where f_j is found in column j

See also [mp.cost_table_utils](#) (page 164), [mp_table_subclass](#) (page 160).

Constructor Summary

cost_table(varargin)

```
T = cost_table()
T = cost_table(poly_n, poly_coef, pwl_n, pwl_qty, pwl_cost)
```

For descriptions of the inputs, see the corresponding column in the class documentation above.

Inputs

- **poly_n** (*col vector of integers*)
- **poly_coef** (*matrix of doubles*)
- **pwl_n** (*col vector of integers*)
- **pwl_qty** (*matrix of doubles*)
- **pwl_cost** (*matrix of doubles*)

Outputs

T ([mp.cost_table](#) (page 161)) – the cost table object

Method Summary

poly_params(idx, pu_base)

```
p = poly_params(obj, idx, pu_base)
```

Inputs

- **obj** ([mp.cost_table](#) (page 161)) – the cost table
- **idx** – (integer) : index vector of rows of interest, empty for all rows
- **pu_base** (*double*) – base used to scale quantities to per unit

Outputs

- p** (*struct*) – polynomial cost parameters, struct with fields:
- **have_quad_cost** - true if any polynomial costs have order quadratic or less
 - **i0** - row indices for constant costs
 - **i1** - row indices for linear costs
 - **i2** - row indices for quadratic costs
 - **i3** - row indices for order 3 or higher costs
 - **k** - constant term for all quadratic and lower order costs
 - **c** - linear term for all quadratic and lower order costs
 - **Q** - quadratic term for all quadratic and lower order costs

Implementation in `mp.cost_table_utils.poly_params()` (page 164).

pwl_params(*idx*, *pu_base*, *varargin*)

```
p = pwl_params(obj, idx, pu_base)
p = pwl_params(obj, idx, pu_base, ng, dc)
```

Inputs

- **obj** (`mp.cost_table` (page 161)) – the cost table
- **idx** – (integer) : index vector of rows of interest, empty for all rows
- **pu_base** (*double*) – base used to scale quantities to per unit
- **ng** (*integer*) – number of units, default is # of rows in cost
- **dc** (*boolean*) – true if DC formulation (ng variables), otherwise AC formulation (2*ng variables), default is 1

Outputs

- **p** (*struct*) – piecewise linear cost parameters, struct with fields:
 - **n** - number of piecewise linear costs
 - **i** - row indices for piecewise linear costs
 - **A** - constraint coefficient matrix for CCV formulation
 - **b** - constraint RHS vector for CCV formulation

Implementation in `mp.cost_table_utils.pwl_params()` (page 165).

max_pwl_cost()

```
maxc = max_pwl_cost(obj)
```

Input

- **obj** (`mp.cost_table` (page 161)) – the cost table

Output

- **maxc** (*double*) – maximum cost component of all breakpoints used to specify piecewise linear costs

Implementation in `mp.cost_table_utils.max_pwl_cost()` (page 165).

static poly_cost_fcn(*xx*, *x_scale*, *ccm*, *idx*)

```
f = mp.cost_table.poly_cost_fcn(xx, x_scale, ccm, idx)
[f, df] = mp.cost_table.poly_cost_fcn(...)
[f, df, d2f] = mp.cost_table.poly_cost_fcn(...)
```

Evaluates the sum of a set of polynomial cost functions $f(x) = \sum_{i \in I} f_i(x_i)$, and optionally the gradient and Hessian.

Inputs

- **xx** (*single element cell array of double*) – first element is a vector of the pre-scaled quantities x/α used to compute the costs
- **x_scale** (*double*) – scalar α used to scale the quantity value before evaluating the polynomial cost
- **ccm** (*double*) – cost coefficient matrix, element (i,j) is the coefficient of the $(j-1)$ order term for cost i
- **idx** (*integer*) – index vector of subset I of rows of **xx**{1} and **ccm** of interest

Outputs

- **f** (*double*) – value of cost function $f(x)$
- **df** (*vector of double*) – (optional) gradient of cost function
- **d2f** (*matrix of double*) – (optional) Hessian of cost function

static eval_poly_fcn(c, x)

```
f = mp.cost_table.eval_poly_fcn(c, x)
```

Evaluate a vector of polynomial functions, where ...

```
f = c(:,1) + c(:,2) .* x + c(:,3) .* x^2 + ...
```

Inputs

- **c** (*matrix of double*) – coefficient matrix, element (i,j) is the coefficient of the $(j-1)$ order term for i -th element of f
- **x** (*vector of double*) – vector of input values

Outputs

f (*vector of double*) – value of functions

static diff_poly_fcn(c)

```
c = mp.cost_table.diff_poly_fcn(c)
```

Compute the coefficient matrix for the derivatives of a set of polynomial functions from the coefficients of the functions.

Inputs

c (*matrix of double*) – coefficient matrix for the functions, element (i,j) is the coefficient of the $(j-1)$ order term of the i -th function

Outputs

c (*matrix of double*) – coefficient matrix for the derivatives of the functions, element (i,j) is the coefficient of the $(j-1)$ order term of the derivative of the i -th function

3.6.4 mp.cost_table_utils

class mp.cost_table_utils

[mp.cost_table_utils](#) (page 164) - Static methods for [mp.cost_table](#) (page 161).

Contains the implementation of some methods that would ideally belong in [mp.cost_table](#) (page 161).

Within classes that inherit from [mp_table_subclass](#) (page 160), such as [mp.cost_table](#) (page 161), any subscripting to access the elements of the table must be done through explicit calls to the table's `subsref()` and `subsasgn()` methods. That is, the normal table subscripting syntax will not work, so working with the table becomes extremely cumbersome.

This purpose of this class is to provide the implementation for [mp.cost_table](#) (page 161) methods that **do** allow access to that table via normal table subscripting syntax.

mp.cost_table_util Methods:

- [poly_params\(\)](#) (page 164) - create struct of polynomial parameters from [mp.cost_table](#) (page 161)
- [pwl_params\(\)](#) (page 165) - create struct of piecewise linear parameters from [mp.cost_table](#) (page 161)
- [max_pwl_cost\(\)](#) (page 165) - get maximum cost component used to specify pwl costs

See also [mp.cost_table](#) (page 161).

Method Summary

static `poly_params(cost, idx, pu_base)`

```
p = mp.cost_table_utils.poly_params(cost, idx, pu_base)
```

Implementation for `mp.cost_table.poly_params()` (page 162). See `mp.cost_table.poly_params()` (page 162) for details.

static `pwl_params(cost, idx, pu_base, ng, dc)`

```
p = mp.cost_table_utils.pwl_params(cost, idx, pu_base)
p = mp.cost_table_utils.pwl_params(cost, idx, pu_base, ng, dc)
```

Implementation for `mp.cost_table.pwl_params()` (page 163). See `mp.cost_table.pwl_params()` (page 163) for details.

static `max_pwl_cost(cost)`

```
maxc = mp.cost_table_utils.max_pwl_cost(cost)
```

Implementation for `mp.cost_table.max_pwl_cost()` (page 163). See `mp.cost_table.max_pwl_cost()` (page 163) for details.

3.6.5 mp.element_container

class `mp.element_container`

Bases: `handle`

`mp.element_container` (page 165) - Mix-in class to handle named/ordered element object array.

Implements an element container that is used for MATPOWER model and data model converter objects. Provides the properties to store the constructors for each element and the elements themselves. Also provides a method to modify an existing set of element constructors.

mp.element_container Properties:

- `element_classes` (page 165) - cell array of element constructors
- `elements` (page 165) - a `mp.mapped_array` (page 166) to hold the element objects

mp.element_container Methods:

- `modify_element_classes()` (page 165) - modify an existing set of element constructors

See also `mp.mapped_array` (page 166).

Property Summary

element_classes

Cell array of function handles of constructors for individual elements, filled by constructor of subclass.

elements

A mapped array (`mp.mapped_array` (page 166)) to hold the element objects included inside this container object.

Method Summary

modify_element_classes(*class_list*)

Modify an existing set of element constructors.

```
obj.modify_element_classes(class_list)
```

Input

class_list (*cell array*) – list of **element class modifiers**, where each modifier is one of the following:

1. a handle to a constructor to **append** to `obj.element_classes`, *or*
2. a char array B, indicating to **remove** any element E in the list for which `isa(E(), B)` is `true`, *or*
3. a 2-element cell array {A,B} where A is a handle to a constructor to **replace** any element E in the list for which `isa(E(), B)` is `true`, i.e. B is a char array

Also accepts a single element class modifier of type 1 or 2 (*A single type 3 modifier has to be enclosed in a single-element cell array to keep it from being interpreted as a list of 2 modifiers*).

Can be used to modify the list of element constructors in the `element_classes` property by appending, removing, or replacing entries. See `tab_element_class_modifiers` in the *MATPOWER Developer's Manual* for more information.

3.6.6 mp.mapped_array

class mp.mapped_array

Bases: handle

mp.mapped_array (page 166) - Cell array indexed by name as well as numeric index.

Currently, arrays are only 1-D.

Example usage:

```
% create a mapped array object
ma = mp.mapped_array({30, 40, 50}, {'width', 'height', 'depth'});

% treat it like a cell array
ma{3} = 60;
height = ma{2};
for i = 1:length(ma)
    disp( ma{i} );
end

% treat it like a struct
ma.width = 20;
depth = ma.depth;

% add elements
ma.add_elements({'red', '25 lbs'}, {'color', 'weight'});

% delete elements
ma.delete_elements([3 5]);
ma.delete_elements('height');
```

(continues on next page)

(continued from previous page)

```
% check for named element
ma.has_name('color');
```

mp.mapped_array Methods:

- *mapped_array()* (page 167) - constructor
- *copy()* (page 167) - create a duplicate of the mapped array object
- *length()* (page 167) - return number of elements in mapped array
- *size()* (page 167) - return dimensions of mapped array
- *add_names()* (page 168) - add or modify names of elements
- *add_elements()* (page 168) - append elements to the end of the mapped array
- *delete_elements()* (page 168) - delete elements from the mapped array
- *has_name()* (page 168) - return true if the name exists in the mapped array
- *name2idx()* (page 168) - return the index corresponding to a name
- *subsref()* (page 168) - called when indexing a mapped array to retrieve data
- *subsasgn()* (page 169) - called when indexing a mapped array to assign data
- *display()* (page 169) - display the mapped array structure

Constructor Summary**mapped_array**(varargin)

```
obj = mp.mapped_array(vals)
obj = mp.mapped_array(vals, names)
```

Inputs

- **vals** (*cell array*) – values to be stored
- **names** (*cell array of char arrays*) – names for each element in vals, where a valid name is any valid variable name that is not one of the methods of this class. If names are not provided, it is equivalent to a cell array, except that names can be added later.

Method Summary**copy()**

Create a duplicate of the mapped array object.

```
new_obj = obj.copy();
```

length()

Return number of elements in mapped array.

```
num_elements = obj.length();
```

size(dim)

Return dimensions of mapped array. First dimension is 1, second matches the length.

```
[m, n] = obj.size();  
m = obj.size(1);  
n = obj.size(2);
```

add_names(i0, names)

Add or modify names of elements.

```
obj.add_names(i0, names)
```

Inputs

- **i0** (*cell array*) – index of element corresponding to first name provided in names
- **names** (*char array or cell array of char arrays*) – the names to assign

Adds or overwrites the names for elements starting at the specified index.

add_elements(vals, names)

Append elements to the end of the mapped array.

```
obj.add_elements(vals);  
obj.add_elements(vals, names);
```

Inputs

- **vals** – single value or cell array of values
- **names** (*char array or cell array of char arrays*) – (optional) corresponding names

The two arguments must be both cell arrays of the same dimension or a single value and single name.

See also [delete_elements\(\)](#) (page 168).

delete_elements(refs)

Delete elements from the mapped array.

```
obj.delete_elements(idx);  
obj.delete_elements(names);
```

Inputs

- **idx** (*scalar or vector integer*) – index(indices) of element(s) to delete
- **names** (*char array or cell array of char arrays*) – name(s) of element(s) to delete

See also [add_elements\(\)](#) (page 168).

has_name(name)

Return true if the name exists in the mapped array.

```
TorF = obj.has_name(name);
```

Input

name (*char array*) – name to check

name2idx(name)

Return the numerical index in the array corresponding to a name.

```
idx = obj.name2idx(name);
```

Input

name (*char array*) – name corresponding to desired index

subsref(*s*)

Called when indexing a table to retrieve data.

```
val = obj.<name>;
val = obj{idx};
```

subsasgn(*s*, *b*)

Called when indexing a table to assign data.

```
obj.<name> = val;
obj{idx} = val;
```

display()

Display the mapped array structure.

This method is called automatically when omitting a semicolon on a line that returns an object of this class.

3.6.7 mp.NODE_TYPE

class mp.NODE_TYPE

[mp.NODE_TYPE](#) (page 169) - Defines enumerated type for node types.

mp.NODE_TYPE Properties:

- [PQ](#) (page 169) - PQ node (= 1)
- [PV](#) (page 169) - PV node (= 2)
- [REF](#) (page 169) - reference node (= 3)
- [NONE](#) (page 169) - isolated node (= 4)

mp.NODE_TYPE Methods:

- [is_valid\(\)](#) (page 169) - returns true if the value is a valid node type

All properties are Constant properties and the class is a Sealed class. So the properties function as global constants which do not create an instance of the class, e.g. [mp.NODE_TYPE.REF](#) (page 169).

Property Summary

PQ = 1

PQ node

PV = 2

PV node

REF = 3

reference node

NONE = 4

isolated node

Method Summary

static `is_valid(val)`

Returns true if the value is a valid node type.

`TorF = mp.NODE_TYPE.is_valid(val)`

Input

val (*integer*) – node type value to check for validity

Output

TorF (*boolean*) – true if `val` is a valid node type

3.7 MATPOWER Extension Classes

3.7.1 Base

`mp.extension`

class `mp.extension`

Bases: `handle`

[`mp.extension`](#) (page 170) - Abstract base class for MATPOWER extensions.

This class serves as the framework for the **MATPOWER extension** API, providing a way to bundle a set of class additions and modifications together into a single named package.

By default the methods in this class do nothing, but they can be overridden to customize essentially any aspect of a MATPOWER run. The first 5 methods are used to modify the default classes used to construct the task, data model converter, data, network, and/or mathematical model objects. The last 4 methods are used to add to or modify the classes used to construct the elements for each of the container types.

By convention, MATPOWER extension objects (or cell arrays of them) are named `mpx` and MATPOWER extension class names begin with `mp.xt`.

`mp.extension` Methods:

- [`task_class\(\)`](#) (page 171) - return handle to constructor for task object
- [`dmc_class\(\)`](#) - return handle to constructor for data model converter object
- [`dm_class\(\)`](#) - return handle to constructor for data model object
- [`nm_class\(\)`](#) - return handle to constructor for network model object
- [`mm_class\(\)`](#) - return handle to constructor for mathematical object
- [`dmc_element_classes\(\)`](#) (page 172) - return element class modifiers for data model converter elements
- [`dm_element_classes\(\)`](#) (page 172) - return element class modifiers for data model elements
- [`nm_element_classes\(\)`](#) (page 172) - return element class modifiers for network model elements
- [`mm_element_classes\(\)`](#) (page 172) - return element class modifiers for mathematical model elements

See the `sec_customizing` and `sec_extensions` sections in the *MATPOWER Developer's Manual* for more information, and specifically the `sec_element_classes` section and the `tab_element_class_modifiers` table for details on *element class modifiers*.

Example MATPOWER extensions:

- `mp.xt_reserves` (page 173) - adds fixed zonal reserves to OPF
- `mp.xt_3p` (page 178) - adds example prototype unbalanced three-phase elements for AC PF, CPF, and OPF

See also `mp.task` (page 7), `mp.dm_converter` (page 59), `mp.data_model` (page 27), `mp.net_model` (page 90), `mp.math_model` (page 121), `mp.dmc_element` (page 62), `mp.dm_element` (page 35), `mp.nm_element` (page 107), `mp.mm_element` (page 143).

Method Summary

task_class(*task_class*, *mpopt*)

Return handle to constructor for task object.

```
task_class = mpx.task_class(task_class, mpopt)
```

Inputs

- **task_class** (*function handle*) – default task constructor
- **mpopt** (*struct*) – MATPOWER options struct

Output

task_class (*function handle*) – updated task constructor

dm_converter_class(*dmc_class*, *fmt*, *mpopt*)

Return handle to constructor for data model converter object.

```
dmc_class = mpx.dm_converter_class(dmc_class, fmt, mpopt)
```

Inputs

- **dmc_class** (*function handle*) – default data model converter constructor
- **fmt** (*char array*) – data format tag, e.g. 'mpc2'
- **mpopt** (*struct*) – MATPOWER options struct

Output

dmc_class (*function handle*) – updated data model converter constructor

data_model_class(*dm_class*, *task_tag*, *mpopt*)

Return handle to constructor for data model object.

```
dm_class = mpx.data_model_class(dm_class, task_tag, mpopt)
```

Inputs

- **dm_class** (*function handle*) – default data model constructor
- **task_tag** (*char array*) – task tag, e.g. 'PF', 'CPF', 'OPF'
- **mpopt** (*struct*) – MATPOWER options struct

Output

dm_class (*function handle*) – updated data model constructor

network_model_class(*nm_class*, *task_tag*, *mpopt*)

Return handle to constructor for network model object.

```
nm_class = mpx.network_model_class(nm_class, task_tag, mpopt)
```

Inputs

- **nm_class** (*function handle*) – default network model constructor

- **task_tag** (*char array*) – task tag, e.g. 'PF', 'CPF', 'OPF'
- **mpopt** (*struct*) – MATPOWER options struct

Output

nm_class (*function handle*) – updated network model constructor

math_model_class(*mm_class, task_tag, mpopt*)

Return handle to constructor for mathematical model object.

```
mm_class = mpx.math_model_class(mm_class, task_tag, mpopt)
```

Inputs

- **mm_class** (*function handle*) – default math model constructor
- **task_tag** (*char array*) – task tag, e.g. 'PF', 'CPF', 'OPF'
- **mpopt** (*struct*) – MATPOWER options struct

Output

mm_class (*function handle*) – updated math model constructor

dmc_element_classes(*dmc_class, fmt, mpopt*)

Return element class modifiers for data model converter elements.

```
dmc_elements = mpx.dmc_element_classes(dmc_class, fmt, mpopt)
```

Inputs

- **dmc_class** (*function handle*) – data model converter constructor
- **fmt** (*char array*) – data format tag, e.g. 'mpc2'
- **mpopt** (*struct*) – MATPOWER options struct

Output

dmc_elements (*cell array*) – element class modifiers (see `tab_element_class_modifiers` in the *MATPOWER Developer's Manual*)

dm_element_classes(*dm_class, task_tag, mpopt*)

Return element class modifiers for data model elements.

```
dm_elements = mpx.dm_element_classes(dm_class, task_tag, mpopt)
```

Inputs

- **dm_class** (*function handle*) – data model constructor
- **task_tag** (*char array*) – task tag, e.g. 'PF', 'CPF', 'OPF'
- **mpopt** (*struct*) – MATPOWER options struct

Output

dm_elements (*cell array*) – element class modifiers (see `tab_element_class_modifiers` in the *MATPOWER Developer's Manual*)

nm_element_classes(*nm_class, task_tag, mpopt*)

Return element class modifiers for network model elements.

```
nm_elements = mpx.nm_element_classes(nm_class, task_tag, mpopt)
```

Inputs

- **nm_class** (*function handle*) – network model constructor
- **task_tag** (*char array*) – task tag, e.g. 'PF', 'CPF', 'OPF'
- **mpopt** (*struct*) – MATPOWER options struct

Output

nm_elements (*cell array*) – element class modifiers (see `tab_element_class_modifiers` in the *MATPOWER Developer's Manual*)

mm_element_classes(*mm_class*, *task_tag*, *mpopt*)

Return element class modifiers for mathematical model elements.

```
mm_elements = mpx.mm_element_classes(mm_class, task_tag, mpopt)
```

Inputs

- **mm_class** (*function handle*) – mathematical model constructor
- **task_tag** (*char array*) – task tag, e.g. 'PF', 'CPF', 'OPF'
- **mpopt** (*struct*) – MATPOWER options struct

Output

mm_elements (*cell array*) – element class modifiers (see `tab_element_class_modifiers` in the *MATPOWER Developer's Manual*)

3.7.2 OPF Fixed Zonal Reserves Extension

mp.xt_reserves

class `mp.xt_reserves`

Bases: `mp.extension` (page 170)

`mp.xt_reserves` (page 173) - MATPOWER extension for OPF with fixed zonal reserves.

For OPF problems, this extension adds two types of elements to the data and mathematical model containers, as well as the data model converter.

The 'reserve_gen' element handles all of the per-generator aspects, such as reserve cost and quantity limit parameters, reserve variables, and constraints on reserve capacity.

The 'reserve_zone' element handles the per-zone aspects, such as generator/zone mappings, zonal reserve requirement parameters and constraints, and zonal reserve prices.

mp.xt_reserves Methods:

- `dmc_element_classes()` (page 173) - add two classes to data model converter elements
- `dm_element_classes()` (page 173) - add two classes to data model elements
- `mm_element_classes()` (page 174) - add two classes to mathematical model elements

See the `sec_customizing` and `sec_extensions` sections in the *MATPOWER Developer's Manual* for more information, and specifically the `sec_element_classes` section and the `tab_element_class_modifiers` table for details on *element class modifiers*.

See also `mp.extension` (page 170).

Method Summary

dmc_element_classes(*dmc_class*, *fnt*, *mpopt*)

Add two classes to data model converter elements.

For 'mpc2' data formats, adds the classes:

- `mp.dmce_reserve_gen_mpc2` (page 174)
- `mp.dmce_reserve_zone_mpc2` (page 175)

dm_element_classes(*dm_class*, *task_tag*, *mpopt*)

Add two classes to data model elements.

For 'OPF' tasks, adds the classes:

- [mp.dme_reserve_gen](#) (page 175)
- [mp.dme_reserve_zone](#) (page 176)

mm_element_classes(*mm_class*, *task_tag*, *mpopt*)

Add two classes to mathematical model elements.

For 'OPF' tasks, adds the classes:

- [mp.mme_reserve_gen](#) (page 177)
- [mp.mme_reserve_zone](#) (page 178)

Other classes belonging to [mp.xt_reserves](#) (page 173) extension:

[mp.dmce_reserve_gen_mpc2](#)

class [mp.dmce_reserve_gen_mpc2](#)

Bases: [mp.dmc_element](#) (page 62)

[mp.dmce_reserve_gen_mpc2](#) (page 174) - Data model converter element for reserve generator for MATPOWER case v2.

Method Summary

name()

data_field()

data_subs()

get_import_size(*mpc*)

get_export_size(*dme*)

table_var_map(*dme*, *mpc*)

import_cost(*mpc*, *spec*, *vn*)

import_qty(*mpc*, *spec*, *vn*)

import_ramp(*mpc*, *spec*, *vn*)

import(*dme*, *mpc*, *varargin*)

mp.dmce_reserve_zone_mpc2

class mp.dmce_reserve_zone_mpc2

Bases: [mp.dmc_element](#) (page 62)

[mp.dmce_reserve_zone_mpc2](#) (page 175) - Data model converter element for reserve zone for MATPOWER case v2.

Method Summary

name()

data_field()

data_subs()

table_var_map(*dme*, *mpc*)

import_req(*mpc*, *spec*, *vn*)

import_zones(*mpc*, *spec*, *vn*)

mp.dme_reserve_gen

class mp.dme_reserve_gen

Bases: [mp.dm_element](#) (page 35), [mp.dme_sharedopf](#) (page 58)

[mp.dme_reserve_gen](#) (page 175) - Data model element for reserve generator.

Implements the data element model for reserve generator elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
<code>gen</code>	<i>integer</i>	ID (uid) of corresponding generator
<code>cost</code>	<i>double</i>	reserve cost (u/MW) ¹
<code>qty</code>	<i>double</i>	available reserve quantity (MW)
<code>ramp10</code>	<i>double</i>	10-minute ramp rate (MW)
<code>r</code>	<i>double</i>	r , reserve allocation (MW)
<code>r_lb</code>	<i>double</i>	lower bound on reserve allocation (MW)
<code>r_ub</code>	<i>double</i>	upper bound on reserve allocation (MW)
<code>total_cost</code>	<i>double</i>	total cost of allocated reserves (u) ¹
<code>prc</code>	<i>double</i>	reserve price ($u/MVAr$) ¹
<code>mu_lb</code>	<i>double</i>	shadow price on r lower bound (u/MW) ¹
<code>mu_ub</code>	<i>double</i>	shadow price on r upper bound (u/MW) ¹
<code>mu_pg_ub</code>	<i>double</i>	shadow price on capacity constraint (u/MW) ¹

Property Summary

gen

index of online gens (for online reserve gens)

¹ Here u denotes the units of the objective function, e.g. USD.

r_ub

upper bound on reserve qty (p.u.) for units that are on

Method Summary

name()

label()

labels()

main_table_var_names()

export_vars()

export_vars_offline_val()

update_status(dm)

build_params(dm)

pp_have_section_sum(mpop, pp_args)

pp_data_sum(dm, rows, out_e, pop, fd, pp_args)

pp_have_section_det(mpop, pp_args)

pp_get_headers_det(dm, out_e, pop, pp_args)

pp_data_row_det(dm, k, out_e, pop, fd, pp_args)

pp_have_section_lim(mpop, pp_args)

pp_binding_rows_lim(dm, out_e, pop, pp_args)

pp_get_headers_lim(dm, out_e, pop, pp_args)

pp_data_row_lim(dm, k, out_e, pop, fd, pp_args)

pp_get_footers_det(dm, out_e, pop, pp_args)

mp.dme_reserve_zone

class mp.dme_reserve_zone

Bases: [mp.dm_element](#) (page 35), [mp.dme_sharedopf](#) (page 58)

[mp.dme_reserve_zone](#) (page 176) - Data model element for reserve zone.

Implements the data element model for reserve zone elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
req	double	zonal reserve requirement (<i>MW</i>)
zones	integer	matrix defining generators included in the zone
prc	double	zonal reserve price (<i>u/MW</i>) ¹

Property Summary**zones**

zone map for online [zones](#) (page 177) / gens

req

reserve requirement in p.u. for each active zone

Method Summary**name()****label()****labels()****main_table_var_names()****export_vars()****export_vars_offline_val()****update_status(dm)****build_params(dm)****pp_have_section_det(mpop, pp_args)****pp_get_headers_det(dm, out_e, mpop, pp_args)****pp_data_row_det(dm, k, out_e, mpop, fd, pp_args)****mp.mme_reserve_gen****class mp.mme_reserve_gen**

Bases: [mp.mm_element](#) (page 143)

[mp.mme_reserve_gen](#) (page 177) - Mathematical model element for reserve generator.

Math model element class for reserve generator elements.

Implements methods for adding reserve variables, costs, and per-generator reserve constraints, and for updating the output data in the corresponding data model element for in-service reserve generators from the math model solution.

Method Summary**name()****add_vars(mm, nm, dm, mpop)****add_costs(mm, nm, dm, mpop)****add_constraints(mm, nm, dm, mpop)****data_model_update_on(mm, nm, dm, mpop)**

¹ Here u denotes the units of the objective function, e.g. USD.

mp.mme_reserve_zone

class mp.mme_reserve_zone

Bases: [mp.mm_element](#) (page 143)

[mp.mme_reserve_zone](#) (page 178) - Mathematical model element for reserve zone.

Math model element class for reserve zone elements.

Implements methods for adding reserve zone constraints, and for updating the output data in the corresponding data model element for in-service reserve zones from the math model solution.

Method Summary

name()

add_constraints(*mm, nm, dm, mpopt*)

data_model_update_on(*mm, nm, dm, mpopt*)

3.7.3 Three-Phase Prototype Extension

mp.xt_3p

class mp.xt_3p

Bases: [mp.extension](#) (page 170)

[mp.xt_3p](#) (page 178) - MATPOWER extension to add unbalanced three-phase elements.

For AC power flow, continuation power flow, and optimal power flow problems, adds six new element types:

- 'bus3p' - 3-phase bus
- 'gen3p' - 3-phase generator
- 'load3p' - 3-phase load
- 'line3p' - 3-phase distribution line
- 'xfmr3p' - 3-phase transformer
- 'buslink' - 3-phase to single phase linking element

No changes are required for the task or container classes, so only the `..._element_classes` methods are overridden.

The set of data model element classes depends on the task, with each OPF class inheriting from the corresponding class used for PF and CPF.

The set of network model element classes depends on the formulation, specifically whether cartesian or polar representations are used for voltages.

And the set of mathematical model element classes depends on both the task and the formulation.

mp.xt_3p Methods:

- [dmc_element_classes\(\)](#) (page 179) - add six classes to data model converter elements
- [dm_element_classes\(\)](#) (page 179) - add six classes to data model elements

- [nm_element_classes\(\)](#) (page 179) - add six classes to network model elements
- [mm_element_classes\(\)](#) (page 180) - add six classes to mathematical model elements

See the `sec_customizing` and `sec_extensions` sections in the *MATPOWER Developer's Manual* for more information, and specifically the `sec_element_classes` section and the `tab_element_class_modifiers` table for details on *element class modifiers*.

See also [mp.extension](#) (page 170).

Method Summary

dmc_element_classes(*dmc_class, fmt, mpopt*)

Add six classes to data model converter elements.

For 'mpc2' data formats, adds the classes:

- [mp.dmce_bus3p_mpc2](#) (page 180)
- [mp.dmce_gen3p_mpc2](#) (page 180)
- [mp.dmce_load3p_mpc2](#) (page 181)
- [mp.dmce_line3p_mpc2](#) (page 181)
- [mp.dmce_xfmr3p_mpc2](#) (page 182)
- [mp.dmce_buslink_mpc2](#) (page 182)

dm_element_classes(*dm_class, task_tag, mpopt*)

Add six classes to data model elements.

For 'PF' and 'CPF' tasks, adds the classes:

- [mp.dme_bus3p](#) (page 182)
- [mp.dme_gen3p](#) (page 184)
- [mp.dme_load3p](#) (page 185)
- [mp.dme_line3p](#) (page 187)
- [mp.dme_xfmr3p](#) (page 189)
- [mp.dme_buslink](#) (page 190)

For 'OPF' tasks, adds the classes:

- [mp.dme_bus3p_opf](#) (page 191)
- [mp.dme_gen3p_opf](#) (page 191)
- [mp.dme_load3p_opf](#) (page 192)
- [mp.dme_line3p_opf](#) (page 192)
- [mp.dme_xfmr3p_opf](#) (page 192)
- [mp.dme_buslink_opf](#) (page 192)

nm_element_classes(*nm_class, task_tag, mpopt*)

Add six classes to network model elements.

For *cartesian* voltage formulations, adds the classes:

- [mp.nme_bus3p_acc](#) (page 193)
- [mp.nme_gen3p_acc](#) (page 194)
- [mp.nme_load3p](#) (page 194)
- [mp.nme_line3p](#) (page 195)
- [mp.nme_xfmr3p](#) (page 195)
- [mp.nme_buslink_acc](#) (page 196)

For *polar* voltage formulations, adds the classes:

- [mp.nme_bus3p_acp](#) (page 193)
- [mp.nme_gen3p_acp](#) (page 194)
- [mp.nme_load3p](#) (page 194)
- [mp.nme_line3p](#) (page 195)
- [mp.nme_xfmr3p](#) (page 195)
- [mp.nme_buslink_acp](#) (page 196)

mm_element_classes(*mm_class*, *task_tag*, *mpopt*)

Add five classes to mathematical model elements.

For 'PF' and 'CPF' tasks, adds the classes:

- [*mp.mme_bus3p*](#) (page 196)
- [*mp.mme_gen3p*](#) (page 197)
- [*mp.mme_line3p*](#) (page 197)
- [*mp.mme_xfmr3p*](#) (page 197)
- [*mp.mme_buslink_pf_acc*](#) (page 198) (*cartesian*) or [*mp.mme_buslink_pf_acp*](#) (page 199) (*polar*)

For 'OPF' tasks, adds the classes:

- [*mp.mme_bus3p_opf_acc*](#) (page 199) (*cartesian*) or [*mp.mme_bus3p_opf_acp*](#) (page 199) (*polar*)
- [*mp.mme_gen3p_opf*](#) (page 200)
- [*mp.mme_line3p_opf*](#) (page 200)
- [*mp.mme_xfmr3p_opf*](#) (page 200)
- [*mp.mme_buslink_opf_acc*](#) (page 201) (*cartesian*) or [*mp.mme_buslink_opf_acp*](#) (page 201) (*polar*)

Data model converter element classes belonging to [*mp.xt_3p*](#) (page 178) extension:

[**mp.dmce_bus3p_mpc2**](#)

class [*mp.dmce_bus3p_mpc2*](#)

Bases: [*mp.dmc_element*](#) (page 62)

[*mp.dmce_bus3p_mpc2*](#) (page 180) - Data model converter element for 3-phase bus for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

bus_status_import(*mpc*, *spec*, *vn*, *c*)

[**mp.dmce_gen3p_mpc2**](#)

class [*mp.dmce_gen3p_mpc2*](#)

Bases: [*mp.dmc_element*](#) (page 62)

[*mp.dmce_gen3p_mpc2*](#) (page 180) - Data model converter element for 3-phase generator for MATPOWER case v2.

Method Summary

name()

data_field()

`table_var_map(dme, mpc)`

mp.dmce_load3p_mpc2

class `mp.dmce_load3p_mpc2`

Bases: `mp.dmc_element` (page 62)

`mp.dmce_load3p_mpc2` (page 181) - Data model converter element for 3-phase load for MATPOWER case v2.

Property Summary

bus

Method Summary

name()

data_field()

table_var_map(dme, mpc)

mp.dmce_line3p_mpc2

class `mp.dmce_line3p_mpc2`

Bases: `mp.dmc_element` (page 62)

`mp.dmce_line3p_mpc2` (page 181) - Data model converter element for 3-phase line for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(dme, mpc)

create_line_construction_table(dme, lc)

import(dme, mpc, varargin)

mp.dmce_xfmr3p_mpc2

class mp.dmce_xfmr3p_mpc2

Bases: [mp.dmc_element](#) (page 62)

[mp.dmce_xfmr3p_mpc2](#) (page 182) - Data model converter element for 3-phase transformer for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(dme, mpc)

mp.dmce_buslink_mpc2

class mp.dmce_buslink_mpc2

Bases: [mp.dmc_element](#) (page 62)

[mp.dmce_buslink_mpc2](#) (page 182) - Data model converter element for 1-to-3-phase buslink for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(dme, mpc)

Data model element classes belonging to [mp.xt_3p](#) (page 178) extension:

mp.dme_bus3p

class mp.dme_bus3p

Bases: [mp.dm_element](#) (page 35)

[mp.dme_bus3p](#) (page 182) - Data model element for 3-phase bus.

Implements the data element model for 3-phase bus elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
<code>type</code>	<i>integer</i>	bus type (1 = PQ, 2 = PV, 3 = ref, 4 = isolated)
<code>base_kv</code>	<i>double</i>	base voltage (<i>kV</i>)
<code>vm1</code>	<i>double</i>	phase 1 voltage magnitude (<i>p.u.</i>)
<code>vm2</code>	<i>double</i>	phase 2 voltage magnitude (<i>p.u.</i>)
<code>vm3</code>	<i>double</i>	phase 3 voltage magnitude (<i>p.u.</i>)
<code>va1</code>	<i>double</i>	phase 1 voltage angle (<i>degrees</i>)
<code>va2</code>	<i>double</i>	phase 2 voltage angle (<i>degrees</i>)
<code>va3</code>	<i>double</i>	phase 3 voltage angle (<i>degrees</i>)

Property Summary

`type`

node [type](#) (page 183) vector for buses that are on

`vm1_start`

initial phase 1 voltage magnitudes (*p.u.*) for buses that are on

`vm2_start`

initial phase 2 voltage magnitudes (*p.u.*) for buses that are on

`vm3_start`

initial phase 3 voltage magnitudes (*p.u.*) for buses that are on

`va1_start`

initial phase 1 voltage angles (*radians*) for buses that are on

`va2_start`

initial phase 2 voltage angles (*radians*) for buses that are on

`va3_start`

initial phase 3 voltage angles (*radians*) for buses that are on

`vm_control`

true if voltage is controlled, for buses that are on

Method Summary

`name()`

`label()`

`labels()`

`main_table_var_names()`

`init_status(dm)`

`update_status(dm)`

`build_params(dm)`

`pp_have_section_det(mpop, pp_args)`

`pp_get_headers_det(dm, out_e, mpop, pp_args)`

`pp_data_row_det(dm, k, out_e, mpopt, fd, pp_args)`

`mp.dme_gen3p`

class `mp.dme_gen3p`

Bases: `mp.dm_element` (page 35)

`mp.dme_gen3p` (page 184) - Data model element for 3-phase generator.

Implements the data element model for 3-phase generator elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
<code>bus</code>	<i>integer</i>	bus ID (uid) of 3-phase bus
<code>vm1_setpoint</code>	<i>double</i>	phase 1 voltage magnitude setpoint (<i>p.u.</i>)
<code>vm2_setpoint</code>	<i>double</i>	phase 2 voltage magnitude setpoint (<i>p.u.</i>)
<code>vm3_setpoint</code>	<i>double</i>	phase 3 voltage magnitude setpoint (<i>p.u.</i>)
<code>pg1</code>	<i>double</i>	phase 1 active power output (<i>kW</i>)
<code>pg2</code>	<i>double</i>	phase 2 active power output (<i>kW</i>)
<code>pg3</code>	<i>double</i>	phase 3 active power output (<i>kW</i>)
<code>qg1</code>	<i>double</i>	phase 1 reactive power output (<i>kVAr</i>)
<code>qg2</code>	<i>double</i>	phase 2 reactive power output (<i>kVAr</i>)
<code>qg3</code>	<i>double</i>	phase 3 reactive power output (<i>kVAr</i>)

Property Summary

`bus`

`bus` (page 184) index vector (all gens)

`bus_on`

vector of indices into online buses for gens that are on

`pg1_start`

initial phase 1 active power (p.u.) for gens that are on

`pg2_start`

initial phase 2 active power (p.u.) for gens that are on

`pg3_start`

initial phase 3 active power (p.u.) for gens that are on

`qg1_start`

initial phase 1 reactive power (p.u.) for gens that are on

`qg2_start`

initial phase 2 reactive power (p.u.) for gens that are on

`qg3_start`

initial phase 3 reactive power (p.u.) for gens that are on

`vm1_setpoint`

phase 1 generator voltage setpoint for gens that are on

vm2_setpoint

phase 2 generator voltage setpoint for gens that are on

vm3_setpoint

phase 3 generator voltage setpoint for gens that are on

Method Summary

name()

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

initialize(dm)

update_status(dm)

apply_vm_setpoint(dm)

build_params(dm)

pp_have_section_sum(mpop, pp_args)

pp_data_sum(dm, rows, out_e, mpop, fd, pp_args)

pp_have_section_det(mpop, pp_args)

pp_get_headers_det(dm, out_e, mpop, pp_args)

pp_data_row_det(dm, k, out_e, mpop, fd, pp_args)

mp.dme_load3p

class mp.dme_load3p

Bases: [mp.dm_element](#) (page 35)

[mp.dme_load3p](#) (page 185) - Data model element for 3-phase load.

Implements the data element model for 3-phase load elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
bus	<i>integer</i>	bus ID (uid) of 3-phase bus
pd1	<i>double</i>	phase 1 active power demand (<i>kW</i>)
pd2	<i>double</i>	phase 2 active power demand (<i>kW</i>)
pd3	<i>double</i>	phase 3 active power demand (<i>kW</i>)
pf1	<i>double</i>	phase 1 power factor
pf2	<i>double</i>	phase 2 power factor
pf3	<i>double</i>	phase 3 power factor

Property Summary**bus***bus* (page 186) index vector (all loads)**pd1**

phase 1 active power demand (p.u.) for loads that are on

pd2

phase 2 active power demand (p.u.) for loads that are on

pd3

phase 3 active power demand (p.u.) for loads that are on

pf1

phase 1 power factor for loads that are on

pf2

phase 2 power factor for loads that are on

pf3

phase 3 power factor for loads that are on

Method Summary**name()****label()****labels()****cxn_type()****cxn_idx_prop()****main_table_var_names()****initialize(*dm*)****update_status(*dm*)****build_params(*dm*)****pp_have_section_sum(*mpopt*, *pp_args*)****pp_data_sum(*dm*, *rows*, *out_e*, *mpopt*, *fd*, *pp_args*)****pp_have_section_det(*mpopt*, *pp_args*)****pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)****pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)**

mp.dme_line3p**class** mp.dme_line3pBases: [mp.dm_element](#) (page 35)[mp.dme_line3p](#) (page 187) - Data model element for 3-phase line.

Implements the data element model for 3-phase distribution line elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
bus_fr	integer	bus ID (uid) of “from” 3-phase bus
bus_to	integer	bus ID (uid) of “to” 3-phase bus
lc	double	index into line construction table
len	double	line length (?)
p11_fr	double	phase 1 active power injection at “from” end (kW)
q11_fr	double	phase 1 reactive power injection at “from” end (kVAr)
p12_fr	double	phase 2 active power injection at “from” end (kW)
q12_fr	double	phase 2 reactive power injection at “from” end (kVAr)
p13_fr	double	phase 3 active power injection at “from” end (kW)
q13_fr	double	phase 3 reactive power injection at “from” end (kVAr)
p11_to	double	phase 1 active power injection at “to” end (kW)
q11_to	double	phase 1 reactive power injection at “to” end (kVAr)
p12_to	double	phase 2 active power injection at “to” end (kW)
q12_to	double	phase 2 reactive power injection at “to” end (kVAr)
p13_to	double	phase 3 active power injection at “to” end (kW)
q13_to	double	phase 3 reactive power injection at “to” end (kVAr)

The line construction table in the `lc_tab` property is defined as a table with the following columns:

Name	Type	Description
id	integer	unique line construction ID, referenced from <code>lc</code> column of main data table
r	double	6 resistance parameters for forming symmetric 3x3 series impedance matrix
x	double	6 reactance parameters for forming symmetric 3x3 series impedance matrix
c	double	6 susceptance parameters for forming symmetric 3x3 shunt susceptance matrix

Property Summary**fbus**

bus index vector for “from” bus (all lines)

tbus

bus index vector for “to” bus (all lines)

freq

system frequency, in Hz

lc
index into `lc_tab` for lines that are on

len
length for lines that are on

lc_tab
line construction table

ys
cell array of 3x3 series admittance matrices for lc rows

yc
cell array of 3x3 shunt admittance matrices for lc rows

Method Summary

name()

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

lc_table_var_names()

create_line_construction_table(*id, r, x, c*)

initialize(*dm*)

update_status(*dm*)

build_params(*dm*)

vec2symmat(*v*)
Make a symmetric matrix from a vector of 6 values.

symmat2vec(*M*)
Extract a vector of 6 values from a matrix assumed to be symmetric.

pretty_print(*dm, section, out_e, mpopt, fd, pp_args*)

pp_have_section_sum(*mpopt, pp_args*)

pp_data_sum(*dm, rows, out_e, mpopt, fd, pp_args*)

pp_have_section_det(*mpopt, pp_args*)

pp_get_headers_det(*dm, out_e, mpopt, pp_args*)

pp_data_row_det(*dm, k, out_e, mpopt, fd, pp_args*)

mp.dme_xfmr3p**class** mp.dme_xfmr3pBases: [mp.dm_element](#) (page 35)[mp.dme_xfmr3p](#) (page 189) - Data model element for 3-phase transformer.

Implements the data element model for 3-phase transformer elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
bus_fr	integer	bus ID (uid) of “from” 3-phase bus
bus_to	integer	bus ID (uid) of “to” 3-phase bus
r	double	series resistance (<i>p.u.</i>)
x	double	series reactance (<i>p.u.</i>)
base_kva	double	transformer kVA base (<i>kVA</i>)
base_kv	double	transformer kV base (<i>kV</i>)
p11_fr	double	phase 1 active power injection at “from” end (<i>kW</i>)
q11_fr	double	phase 1 reactive power injection at “from” end (<i>kVAr</i>)
p12_fr	double	phase 2 active power injection at “from” end (<i>kW</i>)
q12_fr	double	phase 2 reactive power injection at “from” end (<i>kVAr</i>)
p13_fr	double	phase 3 active power injection at “from” end (<i>kW</i>)
q13_fr	double	phase 3 reactive power injection at “from” end (<i>kVAr</i>)
p11_to	double	phase 1 active power injection at “to” end (<i>kW</i>)
q11_to	double	phase 1 reactive power injection at “to” end (<i>kVAr</i>)
p12_to	double	phase 2 active power injection at “to” end (<i>kW</i>)
q12_to	double	phase 2 reactive power injection at “to” end (<i>kVAr</i>)
p13_to	double	phase 3 active power injection at “to” end (<i>kW</i>)
q13_to	double	phase 3 reactive power injection at “to” end (<i>kVAr</i>)

Property Summary**fbus**

bus index vector for “from” bus (all transformers)

tbus

bus index vector for “to” bus (all transformers)

rseries resistance (*p.u.*) for transformers that are on**x**series reactance (*p.u.*) for transformers that are on**Method Summary****name()****label()****labels()****cxn_type()****cxn_idx_prop()**

```
main_table_var_names()

initialize(dm)

update_status(dm)

build_params(dm)

pretty_print(dm, section, out_e, mpopt, fd, pp_args)

pp_have_section_sum(mpop, pp_args)

pp_data_sum(dm, rows, out_e, mpopt, fd, pp_args)

pp_have_section_det(mpop, pp_args)

pp_get_headers_det(dm, out_e, mpopt, pp_args)

pp_data_row_det(dm, k, out_e, mpopt, fd, pp_args)
```

mp.dme_buslink

class mp.dme_buslink

Bases: [mp.dm_element](#) (page 35)

[mp.dme_buslink](#) (page 190) - Data model element for 1-to-3-phase buslink.

Implements the data element model for 1-to-3-phase buslink elements.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
bus	<i>integer</i>	bus ID (uid) of single phase bus
bus3p	<i>integer</i>	bus ID (uid) of 3-phase bus

Property Summary

bus

[bus](#) (page 190) index vector (all buslinks)

bus3p

[bus3p](#) (page 190) index vector (all buslinks)

pg1_start

initial phase 1 active power (p.u.) for buslinks that are on

pg2_start

initial phase 2 active power (p.u.) for buslinks that are on

pg3_start

initial phase 3 active power (p.u.) for buslinks that are on

qg1_start

initial phase 1 reactive power (p.u.) for buslinks that are on

qg2_start

initial phase 2 reactive power (p.u.) for buslinks that are on

qg3_start

initial phase 3 reactive power (p.u.) for buslinks that are on

Method Summary**name()****label()****labels()****cxn_type()****cxn_idx_prop()****main_table_var_names()****initialize(*dm*)****update_status(*dm*)****build_params(*dm*)****pp_have_section_det(*mpopt*, *pp_args*)****pp_get_headers_det(*dm*, *out_e*, *mpopt*, *pp_args*)****pp_data_row_det(*dm*, *k*, *out_e*, *mpopt*, *fd*, *pp_args*)****mp.dme_bus3p_opf****class mp.dme_bus3p_opf**Bases: [mp.dme_bus3p](#) (page 182), [mp.dme_shared_opf](#) (page 58)[mp.dme_bus3p_opf](#) (page 191) - Data model element for 3-phase bus for OPF.To parent class [mp.dme_bus3p](#) (page 182), adds pretty-printing for **lim** sections.**mp.dme_gen3p_opf****class mp.dme_gen3p_opf**Bases: [mp.dme_gen3p](#) (page 184), [mp.dme_shared_opf](#) (page 58)[mp.dme_gen3p_opf](#) (page 191) - Data model element for 3-phase generator for OPF.To parent class [mp.dme_gen3p](#) (page 184), adds pretty-printing for **lim** sections.

mp.dme_load3p_opf

class mp.dme_load3p_opf

Bases: [mp.dme_load3p](#) (page 185), [mp.dme_shared_opf](#) (page 58)

[mp.dme_load3p_opf](#) (page 192) - Data model element for 3-phase load for OPF.

To parent class [mp.dme_load3p](#) (page 185), adds pretty-printing for **lim** sections.

mp.dme_line3p_opf

class mp.dme_line3p_opf

Bases: [mp.dme_line3p](#) (page 187), [mp.dme_shared_opf](#) (page 58)

[mp.dme_line3p_opf](#) (page 192) - Data model element for 3-phase line for OPF.

To parent class [mp.dme_line3p](#) (page 187), adds pretty-printing for **lim** sections.

mp.dme_xfmr3p_opf

class mp.dme_xfmr3p_opf

Bases: [mp.dme_xfmr3p](#) (page 189), [mp.dme_shared_opf](#) (page 58)

[mp.dme_xfmr3p_opf](#) (page 192) - Data model element for 3-phase transformer for OPF.

To parent class [mp.dme_xfmr3p](#) (page 189), adds pretty-printing for **lim** sections.

mp.dme_buslink_opf

class mp.dme_buslink_opf

Bases: [mp.dme_buslink](#) (page 190), [mp.dme_shared_opf](#) (page 58)

[mp.dme_buslink_opf](#) (page 192) - Data model element for 1-to-3-phase buslink for OPF.

To parent class [mp.dme_buslink](#) (page 190), adds pretty-printing for **lim** sections.

Network model element classes belonging to [mp.xt_3p](#) (page 178) extension:

mp.nme_bus3p

class mp.nme_bus3p

Bases: [mp.nm_element](#) (page 107)

[mp.nme_bus3p](#) (page 192) - Network model element abstract base class for 3-phase bus.

Implements the network model element for 3-phase bus elements, with 3 nodes per 3-phase bus.

Implements [node_types\(\)](#) (page 193) method.

Method Summary

`name()`

`nm()`

`node_types(nm, dm, idx)`

```
ntv = nme.node_types(nm, dm, idx)
[ref, pv, pq] = nme.node_types(nm, dm, idx)
```

Called by the [node_types\(\)](#) (page 98) method of [mp.net_model](#) (page 90).

`mp.nme_bus3p_acc`

class `mp.nme_bus3p_acc`

Bases: [mp.nme_bus3p](#) (page 192), [mp.form_acc](#) (page 82)

[mp.nme_bus3p_acc](#) (page 193) - Network model element for 3-phase bus, AC cartesian voltage formulation.

Adds voltage variables Vr3 and Vi3 to the network model and inherits from [mp.form_acc](#) (page 82).

Method Summary

`add_vvars(nm, dm, idx)`

`mp.nme_bus3p_acp`

class `mp.nme_bus3p_acp`

Bases: [mp.nme_bus3p](#) (page 192), [mp.form_acp](#) (page 86)

[mp.nme_bus3p_acp](#) (page 193) - Network model element for 3-phase bus, AC polar voltage formulation.

Adds voltage variables Va3 and Vm3 to the network model and inherits from [mp.form_acp](#) (page 86).

Method Summary

`add_vvars(nm, dm, idx)`

`mp.nme_gen3p`

class `mp.nme_gen3p`

Bases: [mp.nm_element](#) (page 107)

[mp.nme_gen3p](#) (page 193) - Network model element abstract base class for 3-phase generator.

Implements the network model element for 3-phase generator elements, with 3 ports and 3 non-voltage states per 3-phase generator.

Adds non-voltage state variables Pg3 and Qg3 to the network model and builds the parameter N.

Method Summary

name()
np()
nz()
add_zvars(*nm*, *dm*, *idx*)
build_params(*nm*, *dm*)

mp.nme_gen3p_acc**class** mp.nme_gen3p_acc

Bases: [mp.nme_gen3p](#) (page 193), [mp.form_acc](#) (page 82)

[mp.nme_gen3p_acc](#) (page 194) - Network model element for 3-phase generator, AC cartesian voltage formulation.

Inherits from [mp.form_acc](#) (page 82).

mp.nme_gen3p_acp**class** mp.nme_gen3p_acp

Bases: [mp.nme_gen3p](#) (page 193), [mp.form_acp](#) (page 86)

[mp.nme_gen3p_acp](#) (page 194) - Network model element for 3-phase generator, AC polar voltage formulation.

Inherits from [mp.form_acp](#) (page 86).

mp.nme_load3p**class** mp.nme_load3p

Bases: [mp.nm_element](#) (page 107), [mp.form_acp](#) (page 86)

[mp.nme_load3p](#) (page 194) - Network model element for 3-phase load.

Implements the network model element for 3-phase load elements, with 3 ports per 3-phase load.

Builds the parameter `s` and inherits from [mp.form_acp](#) (page 86).

Method Summary

name()
np()
build_params(*nm*, *dm*)

mp.nme_line3p

class mp.nme_line3p

Bases: [mp.nm_element](#) (page 107), [mp.form_acp](#) (page 86)

[mp.nme_line3p](#) (page 195) - Network model element for 3-phase line.

Implements the network model element for 3-phase line elements, with 6 ports per 3-phase line.

Implements building of the admittance parameter Y for 3-phase lines and inherits from [mp.form_acp](#) (page 86).

Method Summary

`name()`

`np()`

`build_params(nm, dm)`

`vec2symmat_stacked(vv)`

mp.nme_xfmr3p

class mp.nme_xfmr3p

Bases: [mp.nm_element](#) (page 107), [mp.form_acp](#) (page 86)

[mp.nme_xfmr3p](#) (page 195) - Network model element for 3-phase transformer.

Implements the network model element for 3-phase transformer elements, with 6 ports per transformer.

Implements building of the admittance parameter Y for 3-phase transformers and inherits from [mp.form_acp](#) (page 86).

Method Summary

`name()`

`np()`

`build_params(nm, dm)`

mp.nme_buslink

class mp.nme_buslink

Bases: [mp.nm_element](#) (page 107)

[mp.nme_buslink](#) (page 195) - Network model element abstract base class for 1-to-3-phase buslink.

Implements the network model element for 1-to-3-phase buslink elements, with 4 ports and 3 non-voltage states per buslink.

Adds non-voltage state variables Plink and Qlink to the network model, builds the parameter N, and constructs voltage constraints.

Method Summary

name()
np()
nz()
add_zvars(*nm*, *dm*, *idx*)
build_params(*nm*, *dm*)
voltage_constraints()

mp.nme_buslink_acc

class `mp.nme_buslink_acc`

Bases: `mp.nme_buslink` (page 195), `mp.form_acc` (page 82)

`mp.nme_buslink_acc` (page 196) - Network model element for 1-to-3-phase buslink, AC cartesian voltage formulation.

Inherits from `mp.form_acc` (page 82).

mp.nme_buslink_acp

class `mp.nme_buslink_acp`

Bases: `mp.nme_buslink` (page 195), `mp.form_acp` (page 86)

`mp.nme_buslink_acp` (page 196) - Network model element for 1-to-3-phase buslink, AC polar voltage formulation.

Inherits from `mp.form_acp` (page 86).

Mathematical model element classes belonging to `mp.xt_3p` (page 178) extension:

mp.mme_bus3p

class `mp.mme_bus3p`

Bases: `mp.mm_element` (page 143)

`mp.mme_bus3p` (page 196) - Math model element for 3-phase bus.

Math model element base class for 3-phase bus elements.

Implements method for updating the output data in the corresponding data model element for in-service 3-phase buses from the math model solution.

Method Summary

name()

`data_model_update_on(mm, nm, dm, mpopt)`

mp.mme_gen3p

class `mp.mme_gen3p`

Bases: `mp.mm_element` (page 143)

`mp.mme_gen3p` (page 197) - Math model element for 3-phase generator.

Math model element base class for 3-phase generator elements.

Implements method for updating the output data in the corresponding data model element for in-service 3-phase generators from the math model solution.

Method Summary

`name()`

`data_model_update_on(mm, nm, dm, mpopt)`

mp.mme_line3p

class `mp.mme_line3p`

Bases: `mp.mm_element` (page 143)

`mp.mme_line3p` (page 197) - Math model element for 3-phase line.

Math model element base class for 3-phase line elements.

Implements method for updating the output data in the corresponding data model element for in-service 3-phase lines from the math model solution.

Method Summary

`name()`

`data_model_update_on(mm, nm, dm, mpopt)`

mp.mme_xfmr3p

class `mp.mme_xfmr3p`

Bases: `mp.mm_element` (page 143)

`mp.mme_xfmr3p` (page 197) - Math model element for 3-phase transformer.

Math model element base class for 3-phase transformer elements.

Implements method for updating the output data in the corresponding data model element for in-service 3-phase transformers from the math model solution.

Method Summary

name()

data_model_update_on(*mm, nm, dm, mpopt*)

mp.mme_buslink

class mp.mme_buslink

Bases: [mp.mm_element](#) (page 143)

[mp.mme_buslink](#) (page 198) - Math model element abstract base class for 1-to-3-phase buslink.

Abstract math model element base class for 1-to-3-phase buslink elements.

Method Summary

name()

mp.mme_buslink_pf_ac

class mp.mme_buslink_pf_ac

Bases: [mp.mme_buslink](#) (page 198)

[mp.mme_buslink_pf_ac](#) (page 198) - Math model element abstract base class for 1-to-3-phase buslink for AC PF/CPF.

Abstract math model element base class for 1-to-3-phase buslink elements for AC power flow and CPF problems.

Implements methods for adding per-phase active and reactive power variables and for forming and adding voltage and reactive power constraints.

Method Summary

add_vars(*mm, nm, dm, mpopt*)

add_constraints(*mm, nm, dm, mpopt*)

voltage_constraints(*nme, ad*)

mp.mme_buslink_pf_acc

class mp.mme_buslink_pf_acc

Bases: [mp.mme_buslink_pf_ac](#) (page 198)

[mp.mme_buslink_pf_acc](#) (page 198) - Math model element for 1-to-3-phase buslink for AC cartesian voltage PF/CPF.

Math model element class for 1-to-3-phase buslink elements for AC cartesian power flow and CPF problems.

Implements methods for adding constraints to match voltages across each buslink.

Method Summary

add_constraints(*mm, nm, dm, mpop*)

pf_va_fcn(*nme, xx, A, b*)

pf_vm_fcn(*nme, xx, A, b*)

mp.mme_buslink_pf_acp

class mp.mme_buslink_pf_acp

Bases: [mp.mme_buslink_pf_ac](#) (page 198)

[mp.mme_buslink_pf_acp](#) (page 199) - Math model element for 1-to-3-phase buslink for AC polar voltage PF/CPF.

Math model element class for 1-to-3-phase buslink elements for AC polar power flow and CPF problems.

Implements method for adding constraints to match voltages across each buslink.

Method Summary

add_constraints(*mm, nm, dm, mpop*)

mp.mme_bus3p_opf_acc

class mp.mme_bus3p_opf_acc

Bases: [mp.mme_bus3p](#) (page 196)

[mp.mme_bus3p_opf_acc](#) (page 199) - Math model element for 3-phase bus for AC cartesian voltage OPF.

Math model element class for 3-phase bus elements for AC cartesian voltage OPF problems.

Implements method for forming an interior initial point.

Method Summary

interior_x0(*mm, nm, dm, x0*)

mp.mme_bus3p_opf_acp

class mp.mme_bus3p_opf_acp

Bases: [mp.mme_bus3p](#) (page 196)

[mp.mme_bus3p_opf_acp](#) (page 199) - Math model element for 3-phase bus for AC polar voltage OPF.

Math model element class for 3-phase bus elements for AC polar voltage OPF problems.

Implements method for forming an interior initial point.

Method Summary

interior_x0(*mm, nm, dm, x0*)

mp.mme_gen3p_opf

class mp.mme_gen3p_opf

Bases: [mp.mme_gen3p](#) (page 197)

[mp.mme_gen3p_opf](#) (page 200) - Math model element for 3-phase generator for OPF.

Math model element class for 1-to-3-phase generator elements for OPF problems.

Implements (currently empty) method for forming an interior initial point.

Method Summary

interior_x0(*mm, nm, dm, x0*)

mp.mme_line3p_opf

class mp.mme_line3p_opf

Bases: [mp.mme_line3p](#) (page 197)

[mp.mme_line3p_opf](#) (page 200) - Math model element for 3-phase line for OPF.

Math model element class for 3-phase line elements for OPF problems.

Implements (currently empty) method for forming an interior initial point.

Method Summary

interior_x0(*mm, nm, dm, x0*)

mp.mme_xfmr3p_opf

class mp.mme_xfmr3p_opf

Bases: [mp.mme_xfmr3p](#) (page 197)

[mp.mme_xfmr3p_opf](#) (page 200) - Math model element for 3-phase transformer for OPF.

Math model element class for 3-phase transformer elements for OPF problems.

Implements (currently empty) method for forming an interior initial point.

Method Summary

interior_x0(*mm, nm, dm, x0*)

mp.mme_buslink_opf**class mp.mme_buslink_opf**

Bases: [mp.mme_buslink](#) (page 198)

[mp.mme_buslink_opf](#) (page 201) - Math model element abstract base class for 1-to-3-phase buslink for OPF.

Abstract math model element base class for 1-to-3-phase buslink elements for OPF problems.

Implements (currently empty) method for forming an interior initial point.

Method Summary

interior_x0(*mm, nm, dm, x0*)

mp.mme_buslink_opf_acc**class mp.mme_buslink_opf_acc**

Bases: [mp.mme_buslink_opf](#) (page 201)

[mp.mme_buslink_opf_acc](#) (page 201) - Math model element for 1-to-3-phase buslink for AC cartesian voltage OPF.

Math model element class for 1-to-3-phase buslink elements for AC cartesian OPF problems.

Implements methods for adding constraints to match voltages across each buslink.

Method Summary

add_constraints(*mm, nm, dm, mpopt*)

va_fcn(*nme, xx, A, b*)

va_hess(*nme, xx, lam, A*)

vm2_fcn(*nme, xx, A, b*)

vm2_hess(*nme, xx, lam, A*)

mp.mme_buslink_opf_acp**class mp.mme_buslink_opf_acp**

Bases: [mp.mme_buslink_opf](#) (page 201)

[mp.mme_buslink_opf_acp](#) (page 201) - Math model element for 1-to-3-phase buslink for AC polar voltage OPF.

Math model element class for 1-to-3-phase buslink elements for AC polar OPF problems.

Implements method for adding constraints to match voltages across each buslink.

Method Summary

add_constraints(*mm, nm, dm, mpopt*)

3.7.4 Legacy DC Line Extension

`mp.xt_legacy_dcline`

class `mp.xt_legacy_dcline`

Bases: `mp.extension` (page 170)

`mp.xt_legacy_dcline` (page 202) - MATPOWER extension to add legacy DC line elements.

For AC and DC power flow, continuation power flow, and optimal power flow problems, adds a new element type:

- 'legacy_dcline' - legacy DC line

No changes are required for the task or container classes, so only the `..._element_classes` methods are overridden.

The set of data model element classes depends on the task, with each OPF class inheriting from the corresponding class used for PF and CPF.

The set of network model element classes depends on the formulation, specifically whether cartesian or polar representations are used for voltages.

And the set of mathematical model element classes depends on both the task and the formulation.

`mp.xt_legacy_dcline` Methods:

- `dmc_element_classes()` (page 202) - add a class to data model converter elements
- `dm_element_classes()` (page 202) - add a class to data model elements
- `nm_element_classes()` (page 202) - add a class to network model elements
- `mm_element_classes()` (page 203) - add a class to mathematical model elements

See the `sec_customizing` and `sec_extensions` sections in the *MATPOWER Developer's Manual* for more information, and specifically the `sec_element_classes` section and the `tab_element_class_modifiers` table for details on *element class modifiers*.

See also `mp.extension` (page 170).

Method Summary

`dmc_element_classes(dmc_class, fmt, mpopt)`

Add a class to data model converter elements.

For 'mpc2' data formats, adds the classes:

- `mp.dmce_legacy_dcline_mpc2` (page 203)

`dm_element_classes(dm_class, task_tag, mpopt)`

Add a class to data model elements.

For 'PF' and 'CPF' tasks, adds the class:

- `mp.dme_legacy_dcline` (page 204)

For 'OPF' tasks, adds the class:

- `mp.dme_legacy_dcline_opf` (page 206)

nm_element_classes(*nm_class*, *task_tag*, *mpopt*)

Add a class to network model elements.

For DC formulations, adds the class:

- [mp.nme_legacy_dcline_dc](#) (page 208)

For AC *cartesian* voltage formulations, adds the class:

- [mp.nme_legacy_dcline_acc](#) (page 208)

For AC *polar* voltage formulations, adds the class:

- [mp.nme_legacy_dcline_acp](#) (page 208)

mm_element_classes(*mm_class*, *task_tag*, *mpopt*)

Add a class to mathematical model elements.

For 'PF' and 'CPF' tasks, adds the class:

- [mp.mme_legacy_dcline_pf_dc](#) (page 209) (*DC formulation*) or
- [mp.mme_legacy_dcline_pf_ac](#) (page 209) (*AC formulation*)

For 'OPF' tasks, adds the class:

- [mp.mme_legacy_dcline_opf_dc](#) (page 210) (*DC formulation*) or
- [mp.mme_legacy_dcline_opf_ac](#) (page 210) (*AC formulation*)

Data model converter element class belonging to [mp.xt_legacy_dcline](#) (page 202) extension:

[mp.dmce_legacy_dcline_mpc2](#)

class [mp.dmce_legacy_dcline_mpc2](#)

Bases: [mp.dmc_element](#) (page 62)

[mp.dmce_legacy_dcline_mpc2](#) (page 203) - Data model converter element for legacy DC line for MATPOWER case v2.

Method Summary

name()

data_field()

table_var_map(*dme*, *mpc*)

default_export_data_table(*spec*)

dcline_cost_import(*mpc*, *spec*, *vn*)

dcline_cost_export(*dme*, *mpc*, *spec*, *vn*, *ridx*)

Data model element classes belonging to [mp.xt_legacy_dcline](#) (page 202) extension:

mp.dme_legacy_dcline**class mp.dme_legacy_dcline**Bases: [mp.dm_element](#) (page 35)[mp.dme_legacy_dcline](#) (page 204) - Data model element for legacy DC line.

Implements the data element model for legacy DC line elements, with linear line losses.

$$p_{\text{loss}} = l_0 + l_1 p_{\text{fr}}$$

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
<code>bus_fr</code>	<i>integer</i>	bus ID (uid) of “from” bus
<code>bus_to</code>	<i>integer</i>	bus ID (uid) of “to” bus
<code>loss0</code>	<i>double</i>	l_0 , constant term of loss function (MW)
<code>loss1</code>	<i>double</i>	l_1 , linear coefficient of loss function (MW/MW)
<code>vm_setpoint_fr</code>	<i>double</i>	per unit “from” bus voltage magnitude setpoint
<code>vm_setpoint_to</code>	<i>double</i>	per unit “to” bus voltage magnitude setpoint
<code>p_fr_lb</code>	<i>double</i>	lower bound on MW flow at “from” port
<code>p_fr_ub</code>	<i>double</i>	upper bound on MW flow at “from” port
<code>q_fr_lb</code>	<i>double</i>	lower bound on MVar injection into “from” bus
<code>q_fr_ub</code>	<i>double</i>	upper bound on MVar injection into “from” bus
<code>q_to_lb</code>	<i>double</i>	lower bound on MVar injection into “to” bus
<code>q_to_ub</code>	<i>double</i>	upper bound on MVar injection into “to” bus
<code>p_fr</code>	<i>double</i>	MW flow at “from” end (“from” → “to”)
<code>q_fr</code>	<i>double</i>	MVar injection into “from” bus
<code>p_to</code>	<i>double</i>	MW flow at “to” end (“from” → “to”)
<code>q_to</code>	<i>double</i>	MVar injection into “to” bus

Property Summary**fbus**

bus index vector for “from” port (port 1) (all DC lines)

tbus

bus index vector for “to” port (port 2) (all DC lines)

fbus_on

vector of “from” bus indices into online buses (in-service DC lines)

tbus_on

vector of “to” bus indices into online buses (in-service DC lines)

loss0

constant term of loss function (p.u.) (in-service DC lines)

loss1

linear coefficient of loss function (in-service DC lines)

p_fr_start

initial active power (p.u.) at “from” port (in-service DC lines)

p_to_start

initial active power (p.u.) at “to” port (in-service DC lines)

q_fr_start

initial reactive power (p.u.) at “from” port (in-service DC lines)

q_to_start

initial reactive power (p.u.) at “to” port (in-service DC lines)

vm_setpoint_fr

from bus voltage magnitude setpoint (p.u.) (in-service DC lines)

vm_setpoint_to

to bus voltage magnitude setpoint (p.u.) (in-service DC lines)

p_fr_lb

p.u. lower bound on active power flow at “from” port (in-service DC lines)

p_fr_ub

p.u. upper bound on active power flow at “from” port (in-service DC lines)

q_fr_lb

p.u. lower bound on reactive power flow at “from” port (in-service DC lines)

q_fr_ub

p.u. upper bound on reactive power flow at “from” port (in-service DC lines)

q_to_lb

p.u. lower bound on reactive power flow at “to” port (in-service DC lines)

q_to_ub

p.u. upper bound on reactive power flow at “to” port (in-service DC lines)

Method Summary

name()

label()

labels()

cxn_type()

cxn_idx_prop()

main_table_var_names()

export_vars()

export_vars_offline_val()

have_cost()

initialize(*dm*)

update_status(*dm*)

apply_vm_setpoints(*dm*)

build_params(*dm*)

pp_have_section_sum(*mpopt*, *pp_args*)

```
pp_data_sum(dm, rows, out_e, mpopt, fd, pp_args)
pp_get_headers_det(dm, out_e, mpopt, pp_args)
pp_have_section_det(mpopt, pp_args)
pp_data_row_det(dm, k, out_e, mpopt, fd, pp_args)
```

mp.dme_legacy_dcline_opf

class mp.dme_legacy_dcline_opf

Bases: [mp.dme_legacy_dcline](#) (page 204), [mp.dme_shared_opf](#) (page 58)

[mp.dme_legacy_dcline_opf](#) (page 206) - Data model element for legacy DC line for OPF.

To parent class [mp.dme_legacy_dcline](#) (page 204), adds costs, shadow prices on active and reactive flow limits, and pretty-printing for **lim** sections.

Adds the following columns in the main data table, found in the `tab` property:

Name	Type	Description
<code>cost_pg</code>	<code>mp.cost_table</code>	cost of active power flow (u/MW) ¹
<code>mu_p_fr_lb</code>	<code>double</code>	shadow price on MW flow lower bound at “from” end (u/MW) ¹
<code>mu_p_fr_ub</code>	<code>double</code>	shadow price on MW flow upper bound at “from” end (u/MW) ¹
<code>mu_q_fr_lb</code>	<code>double</code>	shadow price on lower bound of MVar injection at “from” bus ($u/degree$) ¹
<code>mu_q_fr_ub</code>	<code>double</code>	shadow price on upper bound of MVar injection at “from” bus ($u/degree$) ¹
<code>mu_q_to_lb</code>	<code>double</code>	shadow price on lower bound of MVar injection at “to” bus ($u/degree$) ¹
<code>mu_q_to_ub</code>	<code>double</code>	shadow price on upper bound of MVar injection at “to” bus ($u/degree$) ¹

Method Summary

```
main_table_var_names()
export_vars()
export_vars_offline_val()
have_cost()
build_cost_params(dm)
pretty_print(dm, section, out_e, mpopt, fd, pp_args)
pp_have_section_lim(mpopt, pp_args)
pp_binding_rows_lim(dm, out_e, mpopt, pp_args)
```

¹ Here u denotes the units of the objective function, e.g. USD.

```
pp_get_headers_lim(dm, out_e, mpopt, pp_args)
pp_data_row_lim(dm, k, out_e, mpopt, fd, pp_args)
```

Network model element classes belonging to [mp.xt_legacy_dcline](#) (page 202) extension:

mp.nme_legacy_dcline

class mp.nme_legacy_dcline

Bases: [mp.nm_element](#) (page 107)

[mp.nme_legacy_dcline](#) (page 207) - Network model element abstract base class for legacy DC line.

Implements the network model element for legacy DC line elements, with 2 ports and 2 non-voltage states per DC line.

Method Summary

name()

np()

nz()

mp.nme_legacy_dcline_ac

class mp.nme_legacy_dcline_ac

Bases: [mp.nme_legacy_dcline](#) (page 207)

[mp.nme_legacy_dcline_ac](#) (page 207) - Network model element abstract base class for legacy DC line for AC formulation.

Adds non-voltage state variables Pdcf, Qdcf, Pdct, and Qdct to the network model and builds the parameter N.

Method Summary

add_zvars(nm, dm, idx)

build_params(nm, dm)

mp.nme_legacy_dcline_acc

class mp.nme_legacy_dcline_acc

Bases: [mp.nme_legacy_dcline_ac](#) (page 207), [mp.form_acc](#) (page 82)

[mp.nme_legacy_dcline_acc](#) (page 208) - Network model element for legacy DC line for AC cartesian voltage formulations.

Inherits from [mp.form_acc](#) (page 82).

mp.nme_legacy_dcline_acp

class mp.nme_legacy_dcline_acp

Bases: [mp.nme_legacy_dcline_ac](#) (page 207), [mp.form_acp](#) (page 86)

[mp.nme_legacy_dcline_acp](#) (page 208) - Network model element for legacy DC line for AC polar voltage formulations.

Inherits from [mp.form_acp](#) (page 86).

mp.nme_legacy_dcline_dc

class mp.nme_legacy_dcline_dc

Bases: [mp.nme_legacy_dcline](#) (page 207), [mp.form_dc](#) (page 88)

[mp.nme_legacy_dcline_dc](#) (page 208) - Network model element for legacy DC line for DC formulation.

Adds non-voltage state variables Pdcf and Pdct to the network model and builds the parameter **K**.

Method Summary

add_zvars(nm, dm, idx)

build_params(nm, dm)

Mathematical model element classes belonging to [mp.xt_legacy_dcline](#) (page 202) extension:

mp.mme_legacy_dcline

class mp.mme_legacy_dcline

Bases: [mp.mm_element](#) (page 143)

[mp.mme_legacy_dcline](#) (page 208) - Math model element abstract base class for legacy DC line.

Abstract math model element base class for legacy DC line elements.

Method Summary

name()

mp.mme_legacy_dcline_pf_ac

class mp.mme_legacy_dcline_pf_ac

Bases: [mp.mme_legacy_dcline](#) (page 208)

[mp.mme_legacy_dcline_pf_ac](#) (page 209) - Math model element for legacy DC line for AC power flow.

Math model element class for legacy DC line elements for AC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service DC lines from the math model solution.

Method Summary

data_model_update_on(mm, nm, dm, mpopt)

mp.mme_legacy_dcline_pf_dc

class mp.mme_legacy_dcline_pf_dc

Bases: [mp.mme_legacy_dcline](#) (page 208)

[mp.mme_legacy_dcline_pf_dc](#) (page 209) - Math model element for legacy DC line for DC power flow.

Math model element class for legacy DC line elements for DC power flow problems.

Implements method for updating the output data in the corresponding data model element for in-service DC lines from the math model solution.

Method Summary

data_model_update_on(mm, nm, dm, mpopt)

mp.mme_legacy_dcline_opf

class mp.mme_legacy_dcline_opf

Bases: [mp.mme_legacy_dcline](#) (page 208)

[mp.mme_legacy_dcline_opf](#) (page 209) - Math model element abstract base class for legacy DC line for OPF.

Math model element abstract base class for legacy DC line elements for OPF problems.

Implements methods to add costs, including piecewise linear cost variables, and to form an interior initial point for cost variables.

Property Summary

cost

struct for [cost](#) (page 209) parameters with fields:

- poly - polynomial costs for active power, struct with fields:
 - have_quad_cost
 - i0, i1, i2, i3
 - k, c, Q

- `pwl` - piecewise linear costs for active power, struct with fields:
 - `n`, `i`, `A`, `b`

Method Summary

`build_cost_params(dm)`

`add_vars(mm, nm, dm, mpopt)`

`add_constraints(mm, nm, dm, mpopt)`

`add_costs(mm, nm, dm, mpopt)`

`interior_x0(mm, nm, dm, x0)`

`mp.mme_legacy_dcline_opf_ac`

`class mp.mme_legacy_dcline_opf_ac`

Bases: [`mp.mme_legacy_dcline_opf`](#) (page 209)

[`mp.mme_legacy_dcline_opf_ac`](#) (page 210) - Math model element for legacy DC line for AC OPF.

Math model element class for legacy DC line elements for AC OPF problems.

Implements method for updating the output data in the corresponding data model element for in-service DC lines from the math model solution.

Method Summary

`data_model_update_on(mm, nm, dm, mpopt)`

`mp.mme_legacy_dcline_opf_dc`

`class mp.mme_legacy_dcline_opf_dc`

Bases: [`mp.mme_legacy_dcline_opf`](#) (page 209)

[`mp.mme_legacy_dcline_opf_dc`](#) (page 210) - Math model element for legacy DC line for DC OPF.

Math model element class for legacy DC line elements for DC OPF problems.

Implements method for updating the output data in the corresponding data model element for in-service DC lines from the math model solution.

Method Summary

`data_model_update_on(mm, nm, dm, mpopt)`

4.1 MATPOWER Tests

4.1.1 test_matpower

test_matpower(*verbose*, *exit_on_fail*)

[test_matpower\(\)](#) (page 211) - Run all MATPOWER tests.

```
test_matpower
test_matpower(verbose)
test_matpower(verbose, exit_on_fail)
success = test_matpower(...)
```

Runs all of the MATPOWER tests. If *verbose* is true (*false by default*), it prints the details of the individual tests. If *exit_on_fail* is true (*false by default*), it will exit MATLAB or Octave with a status of 1 unless `t_run_tests()` returns `all_ok` true.

See also `t_run_tests()`.

4.1.2 t_mp_mapped_array

t_mp_mapped_array(*quiet*)

[t_mp_mapped_array\(\)](#) (page 211) - Tests for `mp.mapped_array` (page 166).

4.1.3 t_mp_table

t_mp_table(*quiet*)

t_mp_table() (page 212) - Tests for *mp_table* (page 156) (and *table*).

4.1.4 t_mp_data_model

t_mp_data_model(*quiet*)

t_mp_data_model() (page 212) - Tests for *mp.data_model* (page 27).

4.1.5 t_dmc_element

t_dmc_element(*quiet*)

t_dmc_element() (page 212) - Tests for *mp.dmc_element* (page 62).

4.1.6 t_mp_dm_converter_mpc2

t_mp_dm_converter_mpc2(*quiet*)

t_mp_dm_converter_mpc2() (page 212) - Tests for *mp.dm_converter_mpc2* (page 61).

4.1.7 t_nm_element

t_nm_element(*quiet*, *out_ac*)

t_nm_element() (page 212) - Tests for *mp.nm_element* (page 107).

4.1.8 t_port_inj_current_acc

t_port_inj_current_acc(*quiet*)

t_port_inj_current_acc() (page 212) - Tests of *mp.form_ac.port_inj_current()* (page 76) derivatives wrt cartesian V.

4.1.9 t_port_inj_current_acp

t_port_inj_current_acp(*quiet*)

[t_port_inj_current_acp\(\)](#) (page 213) - Tests of *mp.form_ac.port_inj_current()* (page 76) derivatives wrt polar V.

4.1.10 t_port_inj_power_acc

t_port_inj_power_acc(*quiet*)

[t_port_inj_power_acc\(\)](#) (page 213) - Tests of *mp.form_ac.port_inj_power()* (page 76) derivatives wrt cartesian V.

4.1.11 t_port_inj_power_acp

t_port_inj_power_acp(*quiet*)

[t_port_inj_power_acp\(\)](#) (page 213) - Tests of *mp.form_ac.port_inj_power()* (page 76) derivatives wrt polar V.

4.1.12 t_node_test

t_node_test(*quiet*)

[t_node_test\(\)](#) (page 213) - Tests for network model with multiple node-creating elements.

4.1.13 t_run_mp

t_run_mp(*quiet*)

[t_run_mp\(\)](#) (page 213) - Tests for [run_mp\(\)](#) (page 3) and simple creation and solve of models.

4.1.14 t_run_mp_3p

t_run_mp_3p(*quiet*)

[t_run_mp_3p\(\)](#) (page 213) - Tests for [run_pf\(\)](#) (page 4), [run_cpf\(\)](#) (page 5), [run_opf\(\)](#) (page 5) for 3-phase and hybrid test cases.

4.1.15 `t_run_opf_default`

`t_run_opf_default(quiet)`

`t_run_opf_default()` (page 214) - Tests for AC optimal power flow using `run_opf()` (page 5) w/default solver.

4.1.16 `t_pretty_print`

`t_pretty_print(quiet)`

`t_pretty_print()` (page 214) - Tests for pretty printed output.

4.1.17 `t_mpxt_legacy_dcline`

`t_mpxt_legacy_dcline(quiet)`

`t_mpxt_legacy_dcline()` (page 214) - Tests for legacy DC line extension in `mp.xt_legacy_dcline` (page 202).

4.1.18 `t_mpxt_reserves`

`t_mpxt_reserves(quiet)`

`t_mpxt_reserves()` (page 214) - Tests `mp.xt_reserves` (page 173) extension.

4.2 MATPOWER Test Data

4.2.1 `mp_foo_table`

`class mp_foo_table`

Bases: `mp_table_subclass` (page 160)

`mp_foo_table` (page 214) - Subclass of `mp_table_subclass` (page 160) for testing.

4.2.2 `t_case3p_a`

`t_case3p_a()`

`t_case3p_a()` (page 215) - Four bus, unbalanced 3-phase test case.

This data comes from `4Bus-YY-UnB.DSS`, a modified version (with unbalanced load) of `4Bus-YY-Bal.DSS` [1], the OpenDSS 4 bus IEEE test case with grounded-wye to grounded-wye transformer.

[1] <https://sourceforge.net/p/electricdss/code/HEAD/tree/trunk/Distrib/IEEETestCases/4Bus-YY-Bal/4Bus-YY-Bal.DSS>

4.2.3 `t_case3p_b`

`t_case3p_b()`

`t_case3p_b()` (page 215) - Six bus hybrid test case, 2 single-phase buses, 4 3-phase buses.

One bus is a hybrid PQ bus. Three phase bus solution should match `t_case3p_a()` (page 215).

4.2.4 `t_case3p_c`

`t_case3p_c()`

`t_case3p_c()` (page 215) - Six bus hybrid test case, 2 single-phase buses, 4 3-phase buses.

One bus is a hybrid PV bus (PV on single-phase side). Three phase bus solution should match `t_case3p_a()` (page 215).

4.2.5 `t_case3p_d`

`t_case3p_d()`

`t_case3p_d()` (page 215) - Six bus hybrid test case, 2 single-phase buses, 4 3-phase buses.

One bus is a hybrid PV bus (PV on 3-phase side). Three phase bus solution should match `t_case3p_a()` (page 215).

4.2.6 `t_case3p_e`

`t_case3p_e()`

`t_case3p_e()` (page 215) - Five bus hybrid test case, 1 single-phase bus, 4 3-phase buses.

One bus is a hybrid REF bus (REF on single-phase side). Three phase bus solution should match `t_case3p_a()` (page 215).

4.2.7 `t_case3p_f`

`t_case3p_f()`

`t_case3p_f()` (page 216) - 21 bus hybrid test case, 9 single-phase buses, 12 3-phase buses.

Three buses are hybrid PQ buses.

4.2.8 `t_case3p_g`

`t_case3p_g()`

`t_case3p_g()` (page 216) - 21 bus hybrid test case, 9 single-phase buses, 12 3-phase buses.

Three buses are hybrid buses, one REF-PQ, one PV-PQ and the other PQ-PQ. Solutions of three-phase portions should match `t_case3p_a()` (page 215).

4.2.9 `t_case3p_h`

`t_case3p_h()`

`t_case3p_h()` (page 216) - 21 bus hybrid test case, 9 single-phase buses, 12 3-phase buses.

Same as `t_case3p_g()` (page 216), except the PV hybrid bus has the PV on the 3-phase side. Three buses are hybrid buses, one REF-PQ, one PQ-PV and the other PQ-PQ. Solutions of three-phase portions should match `t_case3p_a()` (page 215).

4.2.10 `t_case9_gizmo`

`t_case9_gizmo()`

`t_case9_gizmo()` (page 216) - Power flow data for 9 bus, 3 generator case, with gizmo data.

Please see caseformat for details on the case file format.

This section contains reference documentation for the **legacy MATPOWER framework** (see `sec_two_frameworks` in the *MATPOWER Developer's Manual*) and the rest of the legacy codebase inherited from MATPOWER 7 and earlier.

5.1 Legacy Class

5.1.1 `opf_model`

class `opf_model`

Bases: `opt_model`

[*opf_model*](#) (page 217) - Legacy MATPOWER OPF model class.

```
OM = OPF_MODEL(MPC)
```

This **class** implements the OPF model object used to encapsulate a given OPF problem formulation. It allows **for** access to optimization variables, constraints **and** costs in named blocks, keeping track of the ordering **and** indexing of the blocks as variables, constraints **and** costs are added to the problem.

This **class** is a subclass of `OPT_MODEL` that adds the `'mpc'` field **for** storing the MATPOWER **case struct** used to build the object along with the `get_mpc()` method.

It also adds the `'cost'` field **and** the following three **methods for** implementing the legacy user-defined OPF costs:

```
add_legacy_cost
params_legacy_cost
eval_legacy_cost
```

The following is the structure of the data in the OPF model object.

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```

om
<opt_model fields> - see OPT_MODEL for details
.cost              - data for legacy user-defined costs
  .idx
    .i1 - starting row index within full N matrix
    .iN - ending row index within full N matrix
    .N  - number of rows in this cost block in full N matrix
  .N      - total number of rows in full N matrix
  .NS     - number of cost blocks
  .data   - data for each user-defined cost block
    .N    - see help for ADD_LEGACY_COST for details
    .H    -
    .Cw   -
    .dd   -
    .rr   -
    .kk   -
    .nm   -
    .vs   - cell array of variable sets that define xx for this
            cost block, where the N for this block multiplies xx
  .order  - struct array of names/indices for cost blocks in the
            order they appear in the rows of the full N matrix
    .name  - name of the block, e.g. R
    .idx   - indices for name, {2,3} => R(2,3)
.mpc      - MATPOWER case struct used to create this model object
  .baseMVA
  .bus
  .branch
  .gen
  .gencost
  .A (if present, must have l, u)
  .l
  .u
  .N (if present, must have fparm, H, Cw)
  .fparm
  .H
  .Cw

```

See also `opt_model`.

Constructor Summary

opf_model(*mpc*)

Constructor.

```

om = opf_model()
om = opf_model(mpc)

```

Property Summary

cost = []

data for legacy user-defined costs

```
mpc = struct()
```

MATPOWER case struct from which om was built

Method Summary

```
def_set_types(om)
```

Define set types var, lin, nle, nli, qdc, nlc, cost.

```
init_set_types(om)
```

Initialize data structures for each set type.

```
set_mpc(om, mpc)
```

[set_mpc\(\)](#) (page 219) - Sets the MATPOWER case struct.

```
OM.SET_MPC(MPC)
```

See also [opt_model](#).

```
display(om)
```

[display\(\)](#) (page 219) - Displays the object.

Called when semicolon is omitted at the command-line. Displays the details of the variables, constraints, costs included in the model.

See also [opt_model](#).

```
get_mpc(om)
```

[get_mpc\(\)](#) (page 219) - Returns the MATPOWER case struct.

```
MPC = OM.GET_MPC()
```

See also [opt_model](#).

```
eval_legacy_cost(om, x, name, idx)
```

[eval_legacy_cost\(\)](#) (page 219) - Evaluates individual or full set of legacy user costs.

```
F = OM.EVAL_LEGACY_COST(X ...)
[F, DF] = OM.EVAL_LEGACY_COST(X ...)
[F, DF, D2F] = OM.EVAL_LEGACY_COST(X ...)
[F, DF, D2F] = OM.EVAL_LEGACY_COST(X, NAME)
[F, DF, D2F] = OM.EVAL_LEGACY_COST(X, NAME, IDX_LIST)
Evaluates an individual named set or the full set of legacy user
costs and their derivatives for a given value of the optimization vector
X, based on costs added by ADD_LEGACY_COST.
```

Example:

```
[f, df, d2f] = om.eval_legacy_cost(x)
[f, df, d2f] = om.eval_legacy_cost(x, name)
[f, df, d2f] = om.eval_legacy_cost(x, name, idx)
```

See also [opt_model](#), [add_legacy_cost\(\)](#) (page 221), [params_legacy_cost\(\)](#) (page 219).

```
params_legacy_cost(om, name, idx)
```

[params_legacy_cost\(\)](#) (page 219) - Returns cost parameters for legacy user-defined costs.

```

CP = OM.PARAMS_LEGACY_COST()
CP = OM.PARAMS_LEGACY_COST(NAME)
CP = OM.PARAMS_LEGACY_COST(NAME, IDX_LIST)
[CP, VS] = OM.PARAMS_LEGACY_COST(...)
[CP, VS, I1, IN] = OM.PARAMS_LEGACY_COST(...)

```

With no **input** parameters, it assembles **and** returns the parameters **for** the aggregate legacy user-defined cost from **all** legacy cost sets added using ADD_LEGACY_COST. The values of these parameters are cached **for** subsequent calls. The parameters are contained in the **struct** CP, described below.

If a NAME is provided then it simply returns parameter **struct** CP **for** the corresponding named **set**. Likewise **for** indexed named sets specified by NAME **and** IDX_LIST.

An optional 2nd output argument VS indicates the variable sets used by this cost **set**. The **size** of CP.N will be consistent with VS.

If NAME is provided, optional 3rd **and** 4th output arguments I1 **and** IN indicate the starting **and** ending row indices of the corresponding cost **set** in the **full** aggregate cost matrix CP.N.

Let X refer to the vector formed by combining the corresponding varsets VS, **and** F_U(X, CP) be the cost at X corresponding to the cost parameters contained in CP, where CP is a **struct** with the following fields:

```

N      - nw x nx sparse matrix (optional, identity matrix by default)
Cw     - nw x 1 vector
H      - nw x nw sparse matrix (optional, all zeros by default)
dd, mm - nw x 1 vectors (optional, all ones by default)
rh, kk - nw x 1 vectors (optional, all zeros by default)

```

These parameters are used as follows to compute F_U(X, CP)

```

R = N*X - rh

      /  kk(i),  R(i) < -kk(i)
K(i) = <  0,      -kk(i) <= R(i) <= kk(i)
      \ -kk(i),  R(i) > kk(i)

RR = R + K

U(i) = /  0, -kk(i) <= R(i) <= kk(i)
      \  1, otherwise

DDL(i) = /  1, dd(i) = 1
          \  0, otherwise

DDQ(i) = /  1, dd(i) = 2
          \  0, otherwise

Dl = diag(mm) * diag(U) * diag(DDL)
Dq = diag(mm) * diag(U) * diag(DDQ)

```

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$$w = (Dl + Dq * \text{diag}(RR)) * RR$$

$$F_U(X, CP) = 1/2 * w' * H * w + Cw' * w$$

See also `opt_model`, `add_legacy_cost()` (page 221), `eval_legacy_cost()` (page 219).

add_named_set(*om, set_type, name, idx, N, varargin*)

`add_named_set()` (page 221) - Adds a named set of variables/constraints/costs to the model.

```
----- PRIVATE METHOD -----

This method is intended to be a private method, used internally by
the public methods ADD_VAR, ADD_LIN_CONSTRAINT, ADD_NLN_CONSTRAINT
ADD_QUAD_COST, ADD_NLN_COST and ADD_LEGACY_COST.

Variable Set
    OM.ADD_NAMED_SET('var', NAME, IDX_LIST, N, V0, VL, VU, VT);

Linear Constraint Set
    OM.ADD_NAMED_SET('lin', NAME, IDX_LIST, N, A, L, U, VARSETS);

Nonlinear Inequality Constraint Set
    OM.ADD_NAMED_SET('nle', NAME, IDX_LIST, N, FCN, HESS, COMPUTED_BY,
    ↪VARSETS);

Nonlinear Inequality Constraint Set
    OM.ADD_NAMED_SET('nli', NAME, IDX_LIST, N, FCN, HESS, COMPUTED_BY,
    ↪VARSETS);

Quadratic Cost Set
    OM.ADD_NAMED_SET('qdc', NAME, IDX_LIST, N, CP, VARSETS);

General Nonlinear Cost Set
    OM.ADD_NAMED_SET('nlc', NAME, IDX_LIST, N, FCN, VARSETS);

Legacy Cost Set
    OM.ADD_NAMED_SET('cost', NAME, IDX_LIST, N, CP, VARSETS);
```

See also `opt_model`, `add_var`, `add_lin_constraint`, `add_nln_constraint`, `add_quad_cost`, `add_nln_cost`, `add_legacy_cost()` (page 221).

add_legacy_cost(*om, name, idx, varargin*)

`add_legacy_cost()` (page 221) - Adds a set of user costs to the model.

```
OM.ADD_LEGACY_COST(NAME, CP);
OM.ADD_LEGACY_COST(NAME, CP, VARSETS);
OM.ADD_LEGACY_COST(NAME, IDX_LIST, CP);
OM.ADD_LEGACY_COST(NAME, IDX_LIST, CP, VARSETS);
```

Adds a named block of user-defined costs to the model. Each **set** is defined by the CP **struct** described below. All user-defined sets of costs are combined together into a **single set** of cost parameters in

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a **single** CP **struct** by BULD_COST_PARAMS. This **full** aggregate **set** of cost parameters can be retrieved from the model by GET_COST_PARAMS.

Examples:

```
cp1 = struct('N', N1, 'Cw', Cw1);
cp2 = struct('N', N2, 'Cw', Cw2, 'H', H, 'dd', dd, ...
            'rh', rh, 'kk', kk, 'mm', mm);
om.add_legacy_cost('usr1', cp1, {'Pg', 'Qg', 'z'});
om.add_legacy_cost('usr2', cp2, {'Vm', 'Pg', 'Qg', 'z'});

om.init_indexed_name('c', {2, 3});
for i = 1:2
    for j = 1:3
        om.add_legacy_cost('c', {i, j}, cp(i,j), ...);
    end
end
```

Let x refer to the vector formed by combining the specified VARSETS, and $f_u(x, CP)$ be the cost at x corresponding to the cost parameters contained in CP, where CP is a **struct** with the following fields:

N - $nw \times nx$ **sparse** matrix (optional, identity matrix by default)
Cw - $nw \times 1$ vector
H - $nw \times nw$ **sparse** matrix (optional, **all zeros** by default)
dd, mm - $nw \times 1$ vectors (optional, **all ones** by default)
rh, kk - $nw \times 1$ vectors (optional, **all zeros** by default)

These parameters are used as follows to compute $f_u(x, CP)$

```
R = N*x - rh

      /  kk(i),  R(i) < -kk(i)
K(i) = <  0,      -kk(i) <= R(i) <= kk(i)
      \ -kk(i),  R(i) > kk(i)

RR = R + K

U(i) = /  0, -kk(i) <= R(i) <= kk(i)
      \  1, otherwise

DDL(i) = /  1, dd(i) = 1
        \  0, otherwise

DDQ(i) = /  1, dd(i) = 2
        \  0, otherwise

Dl = diag(mm) * diag(U) * diag(DDL)
Dq = diag(mm) * diag(U) * diag(DDQ)

w = (Dl + Dq * diag(RR)) * RR

f_u(x, CP) = 1/2 * w' * H * w + Cw' * w
```

See also `opt_model`, `params_legacy_cost()` (page 219), `eval_legacy_cost()` (page 219).

`init_indexed_name(om, set_type, name, dim_list)`

`init_indexed_name()` (page 223) - Initializes the dimensions for an indexed named set.

OM.INIT_INDEXED_NAME(SET_TYPE, NAME, DIM_LIST)

Initializes the dimensions **for** an indexed named variable, constraint **or** cost **set**.

Variables, constraints **and** costs are referenced in OPT_MODEL in terms of named sets. The specific **type** of named **set** being referenced is given by SET_TYPE, with the following valid options:

```
SET_TYPE = 'var'    => variable set
SET_TYPE = 'lin'    => linear constraint set
SET_TYPE = 'nle'    => nonlinear equality constraint set
SET_TYPE = 'nli'    => nonlinear inequality constraint set
SET_TYPE = 'qdc'    => quadratic cost set
SET_TYPE = 'nlc'    => nonlinear cost set
SET_TYPE = 'cost'   => legacy cost set
```

Indexed Named Sets

A variable, constraint **or** cost **set** can be identified by a **single** NAME, such as 'Pmismatch', **or** by a name that is indexed by one **or** more indices, such as 'Pmismatch(3,4)'. For an indexed named **set**, before adding the indexed variable, constraint **or** cost sets themselves, the dimensions of the indexed **set** must be **set** by calling INIT_INDEXED_NAME, where DIM_LIST is a **cell** array of the dimensions.

Examples:

```
%% linear constraints with indexed named set 'R(i,j)'
om.init_indexed_name('lin', 'R', {2, 3});
for i = 1:2
    for j = 1:3
        om.add_lin_constraint('R', {i, j}, A{i,j}, ...);
    end
end
```

See also `opt_model`, `add_var`, `add_lin_constraint`, `add_nln_constraint`, `add_quad_cost`, `add_nln_cost`, `add_legacy_cost()` (page 221).

5.2 Legacy Functions

5.2.1 Top-Level Simulation Functions

runpf**runpf**(*casedata*, *mpopt*, *fname*, *solvedcase*)

runpf() - Runs a power flow.

[RESULTS, SUCCESS] = RUNPF(CASEDATA, MPOPT, FNAME, SOLVEDCASE)

Runs a **power** flow (full AC Newton's method by default), optionally returning a RESULTS **struct** and SUCCESS **flag**.

Inputs (all are optional):

CASEDATA : either a MATPOWER **case struct** or a string containing the name of the file with the **case** data (default is 'case9') (see CASEFORMAT and LOADCASE)

MPOPT : MATPOWER options **struct** to override default options can be used to specify the solution algorithm, output options termination tolerances, and more (see MPOPTION).

FNAME : name of a file to which the pretty-printed output will be appended

SOLVEDCASE : name of file to which the solved **case** will be saved in MATPOWER **case** format (M-file will be assumed unless the specified name ends with '.mat')

Outputs (all are optional):

RESULTS : results **struct**, with the following fields:
 (all fields from the **input** MATPOWER **case**, i.e. bus, branch, gen, etc., but with solved voltages, **power** flows, etc.)
 order - **info** used in external <-> internal data conversion
 et - elapsed **time** in seconds
 success - success **flag**, 1 = succeeded, 0 = failed

SUCCESS : the success **flag** can additionally be returned as a second output argument

Calling syntax options:

```
results = runpf;
results = runpf(casedata);
results = runpf(casedata, mpopt);
results = runpf(casedata, mpopt, fname);
results = runpf(casedata, mpopt, fname, solvedcase);
[results, success] = runpf(...);
```

Alternatively, **for** compatibility with previous versions of MATPOWER, some of the results can be returned as individual output arguments:

```
[baseMVA, bus, gen, branch, success, et] = runpf(...);
```

If the pf.enforce_q_lims option is **set** to **true** (default is **false**) then, **if** any generator reactive **power** limit is violated after running the AC **power** flow, the corresponding bus is converted to a PQ bus, with Qg at the limit, and the **case** is re-run. The voltage magnitude at the bus will deviate from the specified value in order to satisfy the reactive **power** limit. If the reference bus is converted to PQ, the first remaining PV bus will be used as the slack bus **for** the next iteration. This may

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result in the **real power** output at this generator being slightly off from the specified values.

Examples:

```
results = runpf('case30');
results = runpf('case30', mpooption('pf.enforce_q_lims', 1));
```

See also rundcpf().

runcpf

runcpf(basecasedata, targetcasedata, mpopt, fname, solvedcase)

runcpf() - Runs a full AC continuation power flow

```
[RESULTS, SUCCESS] = RUNCPF(BASECASEDATA, TARGETCASEDATA, ...
                             MPOPT, FNAME, SOLVEDCASE)
```

Runs a **full** AC continuation **power** flow using a normalized tangent predictor **and** selected parameterization scheme, optionally returning a **RESULTS struct** **and** **SUCCESS flag**. Step **size** can be fixed **or** adaptive.

Inputs (all are optional):

BASECASEDATA : either a MATPOWER **case struct** **or** a string containing the name of the file with the **case** data defining the base loading **and** generation (default is 'case9')
(see CASEFORMAT **and** LOADCASE)

TARGETCASEDATA : either a MATPOWER **case struct** **or** a string containing the name of the file with the **case** data defining the target loading **and** generation (default is 'case9target')

MPOPT : MATPOWER options **struct** to override default options can be used to specify the parameterization, output options, termination criteria, **and** more (see MPOPTION).

FNAME : name of a file to which the pretty-printed output will be appended

SOLVEDCASE : name of file to which the solved **case** will be saved in MATPOWER **case** format (M-file will be assumed unless the specified name ends with '.mat')

Outputs (all are optional):

RESULTS : results **struct**, with the following fields:
(all fields from the **input** MATPOWER **case**, i.e. bus, branch, gen, etc., but with solved voltages, **power** flows, etc.)

order - **info** used in external <-> internal data conversion

et - elapsed **time** in seconds

success - success **flag**, 1 = succeeded, 0 = failed

cpf - CPF output **struct** whose content depends on **any** user callback **functions**, where default contains fields:

done_msg - string with message describing cause of continuation termination

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```

iterations - number of continuation steps performed
lam - (nsteps+1) row vector of lambda values from
      correction steps
lam_hat - (nsteps+1) row vector of lambda values from
      prediction steps
max_lam - maximum value of lambda in RESULTS.cpf.lam
steps - (nsteps+1) row vector of stepsizes taken at each
        continuation step
V - (nb x nsteps+1) complex bus voltages from
    correction steps
V_hat - (nb x nsteps+1) complex bus voltages from
        prediction steps
events - an array of structs of size nevents with the
         following fields:
         k - continuation step number at which event was located
         name - name of event
         idx - index(es) of critical elements in corresponding
              event function, e.g. index of generator reaching VAR
              limit
         msg - descriptive text detailing the event
SUCCESS : the success flag can additionally be returned as
         a second output argument

```

Calling syntax options:

```

results = runcpf;
results = runcpf(basecasedata, targetcasedata);
results = runcpf(basecasedata, targetcasedata, mpopt);
results = runcpf(basecasedata, targetcasedata, mpopt, fname);
results = runcpf(basecasedata, targetcasedata, mpopt, fname, solvedcase)
[results, success] = runcpf(...);

```

If the 'cpf.enforce_q_lims' option is set to true (default is false) then, if any generator reaches its reactive power limits during the AC continuation power flow,

- the corresponding bus is converted to a PQ bus, and the problem is modified to eliminate further reactive transfer on this bus
- the voltage magnitude at the bus will deviate from the specified setpoint to satisfy the reactive power limit,
- if the reference bus is converted to PQ, further real power transfer for the bus is also eliminated, and the first remaining PV bus is selected as the new slack, resulting in the transfers at both reference buses potentially deviating from the specified values
- if all reference and PV buses are converted to PQ, RUNCPF terminates with an infeasibility message.

If the 'cpf.enforce_p_lims' option is set to true (default is false) then, if any generator reaches its maximum active power limit during the AC continuation power flow,

- the problem is modified to eliminate further active transfer by this generator
- if the generator was at the reference bus, it is converted to PV and the first remaining PV bus is selected as the new slack.

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If the `'cpf.enforce_v_lims'` option is `set` to `true` (default is `false`) then the continuation power flow is `set` to terminate `if` any bus voltage magnitude exceeds its minimum `or` maximum limit.

If the `'cpf.enforce_flow_lims'` option is `set` to `true` (default is `false`) then the continuation power flow is `set` to terminate `if` any line MVA flow exceeds its rateA limit.

Possible CPF termination modes:

- when `cpf.stop_at == 'NOSE'`
 - Reached steady state loading limit
 - Nose point eliminated by limit induced bifurcation
- when `cpf.stop_at == 'FULL'`
 - Traced `full` continuation curve
- when `cpf.stop_at == <target_lam_val>`
 - Reached desired lambda
- when `cpf.enforce_p_lims == true`
 - All generators at PMAX
- when `cpf.enforce_q_lims == true`
 - No REF `or` PV buses remaining
- when `cpf.enforce_v_lims == true`
 - Any bus voltage magnitude limit is reached
- when `cpf.enforce_flow_lims == true`
 - Any branch MVA flow limit is reached
- other
 - Base `case` power flow did `not` converge
 - Base `and` target `case` have identical `load and` generation
 - Corrector did `not` converge
 - Could `not` locate `<event_name>` event
 - Too many rollback steps triggered by callbacks

Examples:

```
results = runcpf('case9', 'case9target');
results = runcpf('case9', 'case9target', ...
    mption('cpf.adapt_step', 1));
results = runcpf('case9', 'case9target', ...
    mption('cpf.enforce_q_lims', 1));
results = runcpf('case9', 'case9target', ...
    mption('cpf.stop_at', 'FULL'));
```

See also `mption()`, `runpf()`.

runopf**runopf**(*casedata*, *mpopt*, *fname*, *solvedcase*)

runopf() - Runs an optimal power flow.

[RESULTS, SUCCESS] = RUNOPF(CASEDATA, MPOPT, FNAME, SOLVEDCASE)

Runs an optimal **power** flow (AC OPF by default), optionally returning a RESULTS **struct** and SUCCESS **flag**.

Inputs (all are optional):

CASEDATA : either a MATPOWER **case struct** or a string containing the name of the file with the **case** data (default is 'case9') (see CASEFORMAT and LOADCASE)

MPOPT : MATPOWER options **struct** to override default options can be used to specify the solution algorithm, output options termination tolerances, and more (see MPOPTION).

FNAME : name of a file to which the pretty-printed output will be appended

SOLVEDCASE : name of file to which the solved **case** will be saved in MATPOWER **case** format (M-file will be assumed unless the specified name ends with '.mat')

Outputs (all are optional):

RESULTS : results **struct**, with the following fields:
 (all fields from the **input** MATPOWER **case**, i.e. bus, branch, gen, etc., but with solved voltages, **power** flows, etc.)
 order - **info** used in external <-> internal data conversion
 et - elapsed **time** in seconds
 success - success **flag**, 1 = succeeded, 0 = failed
 (additional OPF fields, see OPF **for** details)

SUCCESS : the success **flag** can additionally be returned as a second output argument

Calling syntax options:

```
results = runopf;
results = runopf(casedata);
results = runopf(casedata, mpopt);
results = runopf(casedata, mpopt, fname);
results = runopf(casedata, mpopt, fname, solvedcase);
[results, success] = runopf(...);
```

Alternatively, **for** compatibility with previous versions of MATPOWER, some of the results can be returned as individual output arguments:

```
[baseMVA, bus, gen, gencost, branch, f, success, et] = runopf(...);
```

Example:

```
results = runopf('case30');
```

See also rundcpf(), runuopf().

runuopf**runuopf**(*casedata*, *mpopt*, *fname*, *solvedcase*)

runuopf() - Runs an optimal power flow with unit-decommitment heuristic.

[RESULTS, SUCCESS] = RUNUOPF(CASEDATA, MPOPT, FNAME, SOLVEDCASE)

Runs an optimal **power** flow (AC OPF by default) with a heuristic which allows it to shut down "**expensive**" generators, optionally returning a RESULTS **struct** and SUCCESS **flag**.

Inputs (all are optional):

CASEDATA : either a MATPOWER **case struct** or a string containing the name of the file with the **case** data (default is 'case9') (see CASEFORMAT and LOADCASE)

MPOPT : MATPOWER options **struct** to override default options can be used to specify the solution algorithm, output options termination tolerances, and more (see MPOPTION).

FNAME : name of a file to which the pretty-printed output will be appended

SOLVEDCASE : name of file to which the solved **case** will be saved in MATPOWER **case** format (M-file will be assumed unless the specified name ends with '.mat')

Outputs (all are optional):

RESULTS : results **struct**, with the following fields:
 (all fields from the input MATPOWER **case**, i.e. bus, branch, gen, etc., but with solved voltages, **power** flows, etc.)
 order - **info** used in external <-> internal data conversion
 et - elapsed **time** in seconds
 success - success **flag**, 1 = succeeded, 0 = failed
 (additional OPF fields, see OPF **for** details)

SUCCESS : the success **flag** can additionally be returned as a second output argument

Calling syntax options:

```
results = runuopf;
results = runuopf(casedata);
results = runuopf(casedata, mpopt);
results = runuopf(casedata, mpopt, fname);
results = runuopf(casedata, mpopt, fname, solvedcase);
[results, success] = runuopf(...);
```

Alternatively, **for** compatibility with previous versions of MATPOWER, some of the results can be returned as individual output arguments:

```
[baseMVA, bus, gen, gencost, branch, f, success, et] = runuopf(...);
```

Example:

```
results = runuopf('case30');
```

See also runopf(), runduopf().

rundcpf**rundcpf**(*casedata*, *mpopt*, *fname*, *solvedcase*)

rundcpf() - Runs a DC power flow.

[RESULTS, SUCCESS] = RUNCDF(CASEDATA, MPOPT, FNAME, SOLVEDCASE)

Runs a DC power flow, optionally returning a RESULTS struct and SUCCESS flag.

Inputs (all are optional):

CASEDATA : either a MATPOWER case struct or a string containing the name of the file with the case data (default is 'case9') (see CASEFORMAT and LOADCASE)

MPOPT : MATPOWER options struct to override default options can be used to specify the solution algorithm, output options termination tolerances, and more (see MPOPTION).

FNAME : name of a file to which the pretty-printed output will be appended

SOLVEDCASE : name of file to which the solved case will be saved in MATPOWER case format (M-file will be assumed unless the specified name ends with '.mat')

Outputs (all are optional):

RESULTS : results struct, with the following fields:
 (all fields from the input MATPOWER case, i.e. bus, branch, gen, etc., but with solved voltages, power flows, etc.)
 order - info used in external <-> internal data conversion
 et - elapsed time in seconds
 success - success flag, 1 = succeeded, 0 = failed

SUCCESS : the success flag can additionally be returned as a second output argument

Calling syntax options:

```
results = rundcpf;
results = rundcpf(casedata);
results = rundcpf(casedata, mpopt);
results = rundcpf(casedata, mpopt, fname);
results = rundcpf(casedata, mpopt, fname, solvedcase);
[results, success] = rundcpf(...);
```

Alternatively, for compatibility with previous versions of MATPOWER, some of the results can be returned as individual output arguments:

```
[baseMVA, bus, gen, branch, success, et] = rundcpf(...);
```

Example:

```
results = rundcpf('case30');
```

See also runpf().

rundcopf**rundcopf**(*casedata, mpopt, fname, solvedcase*)

rundcopf() - Runs a DC optimal power flow.

[RESULTS, SUCCESS] = RUNCOPF(CASEDATA, MPOPT, FNAME, SOLVEDCASE)

Runs a DC optimal **power** flow, optionally returning a RESULTS **struct** and SUCCESS **flag**.

Inputs (all are optional):

CASEDATA : either a MATPOWER **case struct** or a string containing the name of the file with the **case** data (default is 'case9') (see CASEFORMAT and LOADCASE)

MPOPT : MATPOWER options **struct** to override default options can be used to specify the solution algorithm, output options termination tolerances, and more (see MPOPTION).

FNAME : name of a file to which the pretty-printed output will be appended

SOLVEDCASE : name of file to which the solved **case** will be saved in MATPOWER **case** format (M-file will be assumed unless the specified name ends with '.mat')

Outputs (all are optional):

RESULTS : results **struct**, with the following fields:
 (all fields from the input MATPOWER **case**, i.e. bus, branch, gen, etc., but with solved voltages, **power** flows, etc.)
 order - **info** used in external <-> internal data conversion
 et - elapsed **time** in seconds
 success - success **flag**, 1 = succeeded, 0 = failed
 (additional OPF fields, see OPF **for** details)

SUCCESS : the success **flag** can additionally be returned as a second output argument

Calling syntax options:

```
results = rundcopf;
results = rundcopf(casedata);
results = rundcopf(casedata, mpopt);
results = rundcopf(casedata, mpopt, fname);
results = rundcopf(casedata, mpopt, fname, solvedcase);
[results, success] = rundcopf(...);
```

Alternatively, **for** compatibility with previous versions of MATPOWER, some of the results can be returned as individual output arguments:

```
[baseMVA, bus, gen, gencost, branch, f, success, et] = rundcopf(...);
```

Example:

```
results = rundcopf('case30');
```

See also runopf(), runduopf().

runduopf**runduopf**(*casedata, mpopt, fname, solvedcase*)

runduopf() - Runs a DC optimal power flow with unit-decommitment heuristic.

[RESULTS, SUCCESS] = RUNDUOPF(CASEDATA, MPOPT, FNAME, SOLVEDCASE)

Runs a DC optimal **power** flow with a heuristic which allows it to shut down "**expensive**" generators optionally returning a RESULTS **struct** and SUCCESS **flag**.

Inputs (all are optional):

CASEDATA : either a MATPOWER **case struct** or a string containing the name of the file with the **case** data (default is 'case9') (see CASEFORMAT and LOADCASE)

MPOPT : MATPOWER options **struct** to override default options can be used to specify the solution algorithm, output options termination tolerances, and more (see MPOPTION).

FNAME : name of a file to which the pretty-printed output will be appended

SOLVEDCASE : name of file to which the solved **case** will be saved in MATPOWER **case** format (M-file will be assumed unless the specified name ends with '.mat')

Outputs (all are optional):

RESULTS : results **struct**, with the following fields:
 (all fields from the input MATPOWER **case**, i.e. bus, branch, gen, etc., but with solved voltages, **power** flows, etc.)
 order - **info** used in external <-> internal data conversion
 et - elapsed **time** in seconds
 success - success **flag**, 1 = succeeded, 0 = failed
 (additional OPF fields, see OPF **for** details)

SUCCESS : the success **flag** can additionally be returned as a second output argument

Calling syntax options:

```
results = runduopf;
results = runduopf(casedata);
results = runduopf(casedata, mpopt);
results = runduopf(casedata, mpopt, fname);
results = runduopf(casedata, mpopt, fname, solvedcase);
[results, success] = runduopf(...);
```

Alternatively, **for** compatibility with previous versions of MATPOWER, some of the results can be returned as individual output arguments:

```
[baseMVA, bus, gen, gencost, branch, f, success, et] = runduopf(...);
```

Example:

```
results = runduopf('case30');
```

See also rundcpf(), runuopf().

runopf_w_res

runopf_w_res(varargin)

[runopf_w_res\(\)](#) (page 233) - Runs an optimal power flow with fixed zonal reserves.

```

RESULTS = RUNOPF_W_RES(CASEDATA, MPOPT, FNAME, SOLVEDCASE)
[RESULTS, SUCCESS] = RUNOPF_W_RES(CASEDATA, MPOPT, FNAME, SOLVEDCASE)

```

Runs an optimal **power** flow with the addition of reserve requirements specified as a **set** of fixed zonal reserves. See [RUNOPF](#) for a description of the **input** and output arguments, which are the same, with the exception that the **case** file or **struct** CASEDATA must define a **'reserves'** field, which is a **struct** with the following fields:

```

zones    nrz x ng, zone(i, j) = 1, if gen j belongs to zone i
                                0, otherwise
req       nrz x 1, zonal reserve requirement in MW
cost      (ng or ngr) x 1, cost of reserves in $/MW
qty       (ng or ngr) x 1, max quantity of reserves in MW (optional)

```

where nrz is the number of reserve zones and ngr is the number of generators belonging to at least one reserve zone and ng is the total number of generators.

In addition to the normal OPF output, the RESULTS **struct** contains a new **'reserves'** field with the following fields, in addition to those provided in the **input**:

```

R         - ng x 1, reserves provided by each gen in MW
Rmin      - ng x 1, lower limit on reserves provided by each gen, (MW)
Rmax      - ng x 1, upper limit on reserves provided by each gen, (MW)
mu.l      - ng x 1, shadow price on reserve lower limit, ($/MW)
mu.u      - ng x 1, shadow price on reserve upper limit, ($/MW)
mu.Pmax   - ng x 1, shadow price on  $P_g + R \leq P_{max}$  constraint, ($/MW)
prc       - ng x 1, reserve price for each gen equal to maximum of the
              shadow prices on the zonal requirement constraint
              for each zone the generator belongs to

```

See [T_CASE30_USERFCNS](#) for an **example case** file with fixed reserves, and [TOGGLE_RESERVES](#) for the implementation.

Calling syntax options:

```

results = runopf_w_res(casedata);
results = runopf_w_res(casedata, mpopt);
results = runopf_w_res(casedata, mpopt, fname);
results = runopf_w_res(casedata, mpopt, fname, solvedcase);
[results, success] = runopf_w_res(...);

```

Example:

```

results = runopf_w_res('t_case30_userfcns');

```

See also [runopf\(\)](#), [toggle_reserves\(\)](#) (page 304), [t_case30_userfcns\(\)](#) (page 379).

5.2.2 Input/Output Functions

caseformat

caseformat()

caseformat - Defines the MATPOWER case file format.

A MATPOWER **case** file is an M-file or MAT-file that defines or returns a **struct** named `mpc`, referred to as a "MATPOWER case struct". The fields of this **struct** are `baseMVA`, `bus`, `gen`, `branch`, and (optional) `gencost`. With the exception of `baseMVA`, a scalar, each data variable is a matrix, where a row corresponds to a **single** bus, branch, gen, etc. The format of the data is similar to the PTI format described in

<https://labs.ece.uw.edu/pstca/formats/pti.txt>

except where noted. An item marked with (+) indicates that it is included in this data but is **not** part of the PTI format. An item marked with (-) is one that is in the PTI format but is **not** included here. Those marked with (2) were added **for version 2** of the **case** file format. The **columns for** each data matrix are given below.

MATPOWER Case Version Information:

There are two versions of the MATPOWER **case** file format. The current **version** of MATPOWER uses **version 2** of the MATPOWER **case** format internally, and includes a `'version'` field with a value of `'2'` to make the **version** explicit. Earlier versions of MATPOWER used the **version 1 case** format, which defined the data matrices as individual variables, as opposed to fields of a **struct**. Case files in **version 1** format with OPF data also included an (unused) `'areas'` variable. While the **version 1** format has **now** been deprecated, it is still be handled automatically by `LOADCASE` and `SAVECASE` which are able to **load and save case** files in both **version 1 and version 2** formats.

See `IDX_BUS`, `IDX_BRCH`, `IDX_GEN`, `IDX_AREA` and `IDX_COST` regarding constants which can be used as named column indices **for** the data matrices. Also described in the first three are additional results **columns** that are added to the bus, branch and gen matrices by the **power flow and OPF solvers**.

The **case struct** also allows **for** additional fields to be included. The OPF is designed to recognize fields named `A`, `l`, `u`, `H`, `Cw`, `N`, `fparm`, `z0`, `z1` and `zu` as parameters used to directly extend the OPF formulation (see OPF **for** details). Additional standard optional fields include `bus_name`, `gentype` and `genfuel`. Other user-defined fields may also be included and will be automatically loaded by the `LOADCASE function` and, given an appropriate `'savecase'` callback **function** (see `ADD_USERFCN`), saved by the `SAVECASE function`.

Bus Data Format

- 1 bus number (positive integer)
- 2 bus **type**

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```

        PQ bus      = 1
        PV bus      = 2
        reference bus = 3
        isolated bus = 4
3  Pd, real power demand (MW)
4  Qd, reactive power demand (MVar)
5  Gs, shunt conductance (MW demanded at V = 1.0 p.u.)
6  Bs, shunt susceptance (MVar injected at V = 1.0 p.u.)
7  area number, (positive integer)
8  Vm, voltage magnitude (p.u.)
9  Va, voltage angle (degrees)
(-) (bus name)
10 baseKV, base voltage (kV)
11 zone, loss zone (positive integer)
(+) 12 maxVm, maximum voltage magnitude (p.u.)
(+) 13 minVm, minimum voltage magnitude (p.u.)

Generator Data Format
1  bus number
(-) (machine identifier, 0-9, A-Z)
2  Pg, real power output (MW)
3  Qg, reactive power output (MVar)
4  Qmax, maximum reactive power output (MVar)
5  Qmin, minimum reactive power output (MVar)
6  Vg, voltage magnitude setpoint (p.u.)
(-) (remote controlled bus index)
7  mBase, total MVA base of this machine, defaults to baseMVA
(-) (machine impedance, p.u. on mBase)
(-) (step up transformer impedance, p.u. on mBase)
(-) (step up transformer off nominal turns ratio)
8  status, > 0 - machine in service
        <= 0 - machine out of service
(-) (% of total VAR's to come from this gen in order to hold V at
      remote bus controlled by several generators)
9  Pmax, maximum real power output (MW)
10 Pmin, minimum real power output (MW)
(2) 11 Pc1, lower real power output of PQ capability curve (MW)
(2) 12 Pc2, upper real power output of PQ capability curve (MW)
(2) 13 Qc1min, minimum reactive power output at Pc1 (MVar)
(2) 14 Qc1max, maximum reactive power output at Pc1 (MVar)
(2) 15 Qc2min, minimum reactive power output at Pc2 (MVar)
(2) 16 Qc2max, maximum reactive power output at Pc2 (MVar)
(2) 17 ramp rate for load following/AGC (MW/min)
(2) 18 ramp rate for 10 minute reserves (MW)
(2) 19 ramp rate for 30 minute reserves (MW)
(2) 20 ramp rate for reactive power (2 sec timescale) (MVar/min)
(2) 21 APF, area participation factor

Branch Data Format
1  f, from bus number
2  t, to bus number
(-) (circuit identifier)

```

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```

3  r, resistance (p.u.)
4  x, reactance (p.u.)
5  b, total line charging susceptance (p.u.)
6  rateA, MVA rating A (long term rating), set to 0 for unlimited
7  rateB, MVA rating B (short term rating), set to 0 for unlimited
8  rateC, MVA rating C (emergency rating), set to 0 for unlimited
9  tap, transformer off nominal turns ratio, if non-zero
   (taps at "from" bus, impedance at "to" bus, i.e. if  $r = x = b = 0$ ,
    then  $\text{tap} = V_f / V_t$ ;  $\text{tap} = 0$  used to indicate transmission
    line rather than transformer, i.e. mathematically equivalent to
    transformer with  $\text{tap} = 1$ )
10 shift, transformer phase shift angle (degrees), positive => delay
(-) (Gf, shunt conductance at from bus p.u.)
(-) (Bf, shunt susceptance at from bus p.u.)
(-) (Gt, shunt conductance at to bus p.u.)
(-) (Bt, shunt susceptance at to bus p.u.)
11 initial branch status, 1 - in service, 0 - out of service
(2) 12 minimum angle difference,  $\text{angle}(V_f) - \text{angle}(V_t)$  (degrees)
(2) 13 maximum angle difference,  $\text{angle}(V_f) - \text{angle}(V_t)$  (degrees)
   (The voltage angle difference is taken to be unbounded below
    if  $\text{ANGMIN} < -360$  and unbounded above if  $\text{ANGMAX} > 360$ .
    If both parameters are zero, it is unconstrained.)

(+) Generator Cost Data Format
NOTE: If gen has ng rows, then the first ng rows of gencost contain
the cost for active power produced by the corresponding generators.
If gencost has 2*ng rows then rows ng+1 to 2*ng contain the reactive
power costs in the same format.
1  model, 1 - piecewise linear, 2 - polynomial
2  startup, startup cost in US dollars
3  shutdown, shutdown cost in US dollars
4  N (= n+1), number of data points to follow defining an n-segment
   piecewise linear cost function, or of cost coefficients defining
   an n-th order polynomial cost function
5  and following, parameters defining total cost function  $f(p)$ ,
   units of  $f$  and  $p$  are $/hr and MW (or MVar), respectively.
   (MODEL = 1) : p1, f1, p2, f2, ..., pN, fN
               where  $p1 < p2 < \dots < pN$  and the cost  $f(p)$  is defined by
               the coordinates (p1,f1), (p2,f2), ..., (pN,fN) of the
               end/break-points of the piecewise linear cost function
   (MODEL = 2) : cn, ..., c1, c0
               N coefficients of an n-th order polynomial cost function,
               starting with highest order, where cost is
                $f(p) = cn \cdot p^n + \dots + c1 \cdot p + c0$ 

(+) Area Data Format (deprecated)
   (this data is not used by MATPOWER and is no longer necessary for
    version 2 case files with OPF data).
1  i, area number
2  price_ref_bus, reference bus for that area

```

See also `loadcase()`, `savecase()`, `idx_bus()` (page 337), `idx_brch()` (page 336), `idx_gen()` (page 342), `idx_area` `idx_cost()` (page 338).

cdf2mpc

cdf2mpc(cdf_file_name, mpc_name, verbose)

cdf2mpc() - Converts an IEEE CDF data file into a MATPOWER case struct.

```

MPC = CDF2MPC(CDF_FILE_NAME)
MPC = CDF2MPC(CDF_FILE_NAME, VERBOSE)
MPC = CDF2MPC(CDF_FILE_NAME, MPC_NAME)
MPC = CDF2MPC(CDF_FILE_NAME, MPC_NAME, VERBOSE)
[MPC, WARNINGS] = CDF2MPC(CDF_FILE_NAME, ...)

```

Converts an IEEE Common Data Format (CDF) data file into a MATPOWER **case struct**.

Input:

```

CDF_FILE_NAME : name of the IEEE CDF file to be converted
MPC_NAME      : (optional) file name to use to save the resulting
                MATPOWER case
VERBOSE       : 1 (default) to display progress info, 0 otherwise

```

Output(s):

```

MPC          : resulting MATPOWER case struct
WARNINGS     : (optional) cell array of strings containing warning
                messages (included by default in comments of MPC_NAME).

```

The IEEE CDF does **not** include some data need to **run** an optimal **power** flow. This script creates default values **for** some of this data as follows:

Bus data:

```

Vmin = 0.94 p.u.
Vmax = 1.06 p.u.

```

Gen data:

```

Pmin = 0 MW
Pmax = Pg + baseMVA

```

Gen cost data:

Quadratic costs with:

```

c2 = 10 / Pg, c1 = 20, c0 = 0, if Pg is non-zero, and
c2 = 0.01,    c1 = 40, c0 = 0, if Pg is zero

```

This should yield an OPF solution "close" to the existing solution (assuming it is a solved **case**) with lambdas near \$40/MWh. See 'help caseformat' **for** details on the cost curve format.

CDF2MPC may modify some of the data which are "infeasible" **for** running optimal **power** flow. If so, **warning** information will be printed out on screen.

Note: Since our code can **not** handle transformers with variable tap, you may **not** expect to **get** exactly the same **power** flow solution using converted data. This is the **case** when we converted ieee300.cdf.

loadcase

loadcase(casefile)

loadcase() - Load .m or .mat case files or data struct in MATPOWER format.

```
[BASEMVA, BUS, GEN, BRANCH, AREAS, GENCOST] = LOADCASE(CASEFILE)
[BASEMVA, BUS, GEN, BRANCH, GENCOST] = LOADCASE(CASEFILE)
[BASEMVA, BUS, GEN, BRANCH] = LOADCASE(CASEFILE)
MPC = LOADCASE(CASEFILE)
```

Returns the individual data matrices or a struct containing them as fields.

Here CASEFILE is either (1) a struct containing the fields baseMVA, bus, gen, branch and, optionally, areas and/or gencost, or (2) a string containing the name of the file. If CASEFILE contains the extension '.mat' or '.m', then the explicit file is searched. If CASEFILE contains no extension, then LOADCASE looks for a MAT-file first, then for an M-file. If the file does not exist or doesn't define all required matrices, the routine aborts with an appropriate error message.

If the input data is from an M-file or MAT-file defining individual data matrices, or from a struct with out a 'version' field whose GEN matrix has fewer than 21 columns, then it is assumed to be a MATPOWER case file in version 1 format, and will be converted to version 2 format.

mpoption

mpoption(varargin)

mpoption() - Used to set and retrieve a MATPOWER options struct.

```
OPT = MPOPTION
```

Returns the default options struct.

```
OPT = MPOPTION(OVERRIDES)
```

Returns the default options struct, with some fields overridden by values from OVERRIDES, which can be a struct or the name of a function that returns a struct.

```
OPT = MPOPTION(NAME1, VALUE1, NAME2, VALUE2, ...)
```

Same as previous, except override options are specified by NAME, VALUE pairs. This can be used to set any part of the options struct. The names can be individual fields or multi-level field names with embedded periods. The values can be scalars or structs.

For backward compatibility, the NAMES and VALUES may correspond to old-style MATPOWER option names (elements in the old-style options vector) as well.

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```
OPT = MPOPTION(OPT0)
```

Converts an old-style options vector OPT0 into the corresponding options `struct`. If OPT0 is an options `struct` it does nothing.

```
OPT = MPOPTION(OPT0, OVERRIDES)
```

Applies overrides to an existing `set` of options, OPT0, which can be an old-style options vector or an options `struct`.

```
OPT = MPOPTION(OPT0, NAME1, VALUE1, NAME2, VALUE2, ...)
```

Same as above except it uses the old-style options vector OPT0 as a base instead of the old default options vector.

```
OPT_VECTOR = MPOPTION(OPT, [])
```

Creates and returns an old-style options vector from an options `struct` OPT.

Note: The use of old-style MATPOWER options vectors and their names and values has been deprecated and will be removed in a future version of MATPOWER. Until then, all uppercase option names are not permitted for new top-level options.

Examples:

```
mpopt = mpooption('pf.alg', 'FDXB', 'pf.tol', 1e-4);
mpopt = mpooption(mpooption, 'opf.dc.solver', 'CPLEX', 'verbose', 2);
```

The currently defined options are as follows:

name	default	description [options]

Model options:		
model	'AC'	AC vs. DC power flow model
['AC' - use nonlinear AC model & corresponding algorithms/options]		
['DC' - use linear DC model & corresponding algorithms/options]		
Power Flow options:		
pf.alg	'NR'	AC power flow algorithm
['NR' - Newton's method (formulation depends on values of]		
[pf.current_balance and pf.v_cartesian options)]		
['NR-SP' - Newton's method (power mismatch, polar)]		
['NR-SC' - Newton's method (power mismatch, cartesian)]		
['NR-SH' - Newton's method (power mismatch, hybrid)]		
['NR-IP' - Newton's method (current mismatch, polar)]		
['NR-IC' - Newton's method (current mismatch, cartesian)]		
['NR-IH' - Newton's method (current mismatch, hybrid)]		
['FDXB' - Fast-Decoupled (XB version)]		
['FDBX' - Fast-Decoupled (BX version)]		
['GS' - Gauss-Seidel]		
['ZG' - Implicit Z-bus Gauss]		
['PQSUM' - Power Summation method (radial networks only)]		
['ISUM' - Current Summation method (radial networks only)]		
['YSUM' - Admittance Summation method (radial networks only)]		

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```

pf.current_balance      0          type of nodal balance equation
[ 0 - use complex power balance equations ]
[ 1 - use complex current balance equations ]
pf.v_cartesian          0          voltage representation
[ 0 - bus voltage variables represented in polar coordinates ]
[ 1 - bus voltage variables represented in cartesian coordinates ]
[ 2 - hybrid, polar updates computed via modified cartesian Jacobian ]
pf.tol                  1e-8       termination tolerance on per unit
                                   P & Q mismatch
pf.nr.max_it            10         maximum number of iterations for
                                   Newton's method
pf.nr.lin_solver        ''         linear solver passed to MPLINSOLVE to
                                   solve Newton update step
[ '' - default to '\' for small systems, 'LU3' for larger ones ]
[ '\' - built-in backslash operator ]
[ 'LU' - explicit default LU decomposition and back substitution ]
[ 'LU3' - 3 output arg form of LU, Gilbert-Peierls algorithm with ]
[         approximate minimum degree (AMD) reordering ]
[ 'LU4' - 4 output arg form of LU, UMFPACK solver (same as 'LU') ]
[ 'LU5' - 5 output arg form of LU, UMFPACK solver, w/row scaling ]
[ (see MPLINSOLVE for complete list of all options) ]
pf.fd.max_it            30         maximum number of iterations for
                                   fast decoupled method
pf.gs.max_it            1000       maximum number of iterations for
                                   Gauss-Seidel method
pf.zg.max_it            1000       maximum number of iterations for
                                   Implicit Z-bus Gauss method
pf.radial.max_it        20         maximum number of iterations for
                                   radial power flow methods
pf.radial.vcorr         0          perform voltage correction procedure
                                   in distribution power flow
[ 0 - do NOT perform voltage correction ]
[ 1 - perform voltage correction ]
pf.enforce_q_lims       0          enforce gen reactive power limits at
                                   expense of |V|
[ 0 - do NOT enforce limits ]
[ 1 - enforce limits, simultaneous bus type conversion ]
[ 2 - enforce limits, one-at-a-time bus type conversion ]

Continuation Power Flow options:
cpf.parameterization    3          choice of parameterization
[ 1 - natural ]
[ 2 - arc length ]
[ 3 - pseudo arc length ]
cpf.stop_at             'NOSE'     determines stopping criterion
[ 'NOSE' - stop when nose point is reached ]
[ 'FULL' - trace full nose curve ]
[ <lam_stop> - stop upon reaching specified target lambda value ]
cpf.enforce_p_lims      0          enforce gen active power limits
[ 0 - do NOT enforce limits ]
[ 1 - enforce limits, simultaneous bus type conversion ]
cpf.enforce_q_lims      0          enforce gen reactive power limits at

```

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```

                                expense of |V|
    [ 0 - do NOT enforce limits ]
    [ 1 - enforce limits, simultaneous bus type conversion ]
    cpf.enforce_v_lims      0      enforce bus voltage magnitude limits
    [ 0 - do NOT enforce limits ]
    [ 1 - enforce limits, termination on detection ]
    cpf.enforce_flow_lims   0      enforce branch flow MVA limits
    [ 0 - do NOT enforce limits ]
    [ 1 - enforce limits, termination on detection ]
    cpf.step                0.05   continuation power flow step size
    cpf.adapt_step          0      toggle adaptive step size feature
    [ 0 - adaptive step size disabled ]
    [ 1 - adaptive step size enabled ]
    cpf.step_min            1e-4   minimum allowed step size
    cpf.step_max            0.2    maximum allowed step size
    cpf.adapt_step_damping  0.7    damping factor for adaptive step
                                sizing
    cpf.adapt_step_tol      1e-3   tolerance for adaptive step sizing
    cpf.target_lam_tol      1e-5   tolerance for target lambda detection
    cpf.nose_tol            1e-5   tolerance for nose point detection (pu)
    cpf.p_lims_tol          0.01   tolerance for generator active
                                power limit enforcement (MW)
    cpf.q_lims_tol          0.01   tolerance for generator reactive
                                power limit enforcement (MVAR)
    cpf.v_lims_tol          1e-4   tolerance for bus voltage
                                magnitude enforcement (p.u)
    cpf.flow_lims_tol       0.01   tolerance for line MVA flow
                                enforcement (MVA)
    cpf.plot.level          0      control plotting of nose curve
    [ 0 - do not plot nose curve ]
    [ 1 - plot when completed ]
    [ 2 - plot incrementally at each iteration ]
    [ 3 - same as 2, with 'pause' at each iteration ]
    cpf.plot.bus            <empty> index of bus whose voltage is to be
                                plotted
    cpf.user_callback       <empty> string containing the name of a user
                                callback function, or struct with
                                function name, and optional priority
                                and/or args, or cell array of such
                                strings and/or structs, see
                                'help cpf_default_callback' for details

```

Optimal Power Flow options:

name	default	description [options]
opf.ac.solver	'DEFAULT'	AC optimal power flow solver
['DEFAULT']	-	choose default solver, i.e. 'MIPS'
['MIPS']	-	MIPS, MATPOWER Interior Point Solver, primal/dual
['FMINCON']	-	interior point method (pure MATLAB/Octave)
['IPOPT']	-	MATLAB Optimization Toolbox, FMINCON
['IPOPT']	-	IPOPT, requires MEX interface to IPOPT solver
['IPOPT']	-	available from:

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```

[                                     https://github.com/coin-or/Ipopt                               ]
[ 'KNITRO' - Artelys Knitro, requires Artelys Knitro solver,                               ]
[ available from:https://www.artelys.com/solvers/knitro/]
[ 'MINOPF' - MINOPF, MINOS-based solver, requires optional                               ]
[ MEX-based MINOPF package, available from:                                             ]
[ http://www.pserc.cornell.edu/minopf/                                                 ]
[ 'PDIPM' - PDIPM, primal/dual interior point method, requires                         ]
[ optional MEX-based TSPOPF package, available from:                                   ]
[ http://www.pserc.cornell.edu/tspopf/                                                 ]
[ 'SDPOPF' - SDPOPF, solver based on semidefinite relaxation of                         ]
[ OPF problem, requires optional packages:                                             ]
[ SDP_PF, available in extras/sdp_pf                                                  ]
[ YALMIP, available from:                                                             ]
[ https://yalmip.github.io                                                            ]
[ SDP solver such as SeDuMi, available from:                                           ]
[ http://sedumi.ie.lehigh.edu/                                                       ]
[ 'TRALM' - TRALM, trust region based augmented Langrangian                           ]
[ method, requires TSPOPF (see 'PDIPM')                                              ]
opf.dc.solver      'DEFAULT'    DC optimal power flow solver
[ 'DEFAULT' - choose solver based on availability in the following                     ]
[ order: 'GUROBI', 'CPLEX', 'MOSEK', 'OT',                                           ]
[ 'GLPK' (linear costs only), 'BPMPD', 'MIPS'                                         ]
[ 'MIPS' - MIPS, MATPOWER Interior Point Solver, primal/dual                         ]
[ interior point method (pure MATLAB/Octave)                                         ]
[ 'BPMPD' - BPMPD, requires optional MEX-based BPMPD_MEX package                     ]
[ available from: http://www.pserc.cornell.edu/bpmpd/                                 ]
[ 'CLP' - CLP, requires interface to COIN-OP LP solver                               ]
[ available from:https://github.com/coin-or/Clp                                       ]
[ 'CPLEX' - CPLEX, requires CPLEX solver available from:                             ]
[ https://www.ibm.com/analytics/cplex-optimizer                                       ]
[ 'GLPK' - GLPK, requires interface to GLPK solver                                   ]
[ available from: https://www.gnu.org/software/glpk/                                  ]
[ (GLPK does not work with quadratic cost functions)                                ]
[ 'GUROBI' - GUROBI, requires Gurobi optimizer (v. 5+)                               ]
[ available from: https://www.gurobi.com/                                             ]
[ 'IPOPT' - IPOPT, requires MEX interface to IPOPT solver                             ]
[ available from:                                                                     ]
[ https://github.com/coin-or/Ipopt                                                  ]
[ 'MOSEK' - MOSEK, requires MATLAB interface to MOSEK solver                         ]
[ available from: https://www.mosek.com/                                             ]
[ 'OSQP' - OSQP, requires MATLAB interface to OSQP solver                             ]
[ available from: https://osqp.org/                                                 ]
[ 'OT' - MATLAB Optimization Toolbox, QUADPROG, LINPROG                             ]
opf.current_balance 0          type of nodal balance equation
[ 0 - use complex power balance equations                                             ]
[ 1 - use complex current balance equations                                           ]
opf.v_cartesian      0          voltage representation
[ 0 - bus voltage variables represented in polar coordinates                         ]
[ 1 - bus voltage variables represented in cartesian coordinates                     ]
opf.violation        5e-6      constraint violation tolerance
opf.use_vg            0          respect gen voltage setpt [ 0-1 ]
[ 0 - use specified bus Vmin & Vmax, and ignore gen Vg                             ]

```

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```

[ 1 - replace specified bus Vmin & Vmax by corresponding gen Vg ]
[ between 0 and 1 - use a weighted average of the 2 options ]
opf.flow_lim      'S'      quantity limited by branch flow
                        constraints
[ 'S' - apparent power flow (limit in MVA) ]
[ 'P' - active power flow, implemented using P (limit in MW) ]
[ '2' - active power flow, implemented using P^2 (limit in MW) ]
[ 'I' - current magnitude (limit in MVA at 1 p.u. voltage) ]
opf.ignore_angle_lim  0      angle diff limits for branches
[ 0 - include angle difference limits, if specified ]
[ 1 - ignore angle difference limits even if specified ]
opf.softlims.default  1      behavior of OPF soft limits for
                        which parameters are not explicitly
                        provided
[ 0 - do not include softlims if not explicitly specified ]
[ 1 - include softlims w/default values if not explicitly specified ]
opf.start          0      strategy for initializing OPF start pt
[ 0 - default, MATPOWER decides based on solver ]
[ (currently identical to 1) ]
[ 1 - ignore current state in MATPOWER case (only applies to ]
[ fmincon, Ipopt, Knitro and MIPS, which use an interior pt ]
[ estimate; others use current state as with opf.start = 2) ]
[ 2 - use current state in MATPOWER case ]
[ 3 - solve power flow and use resulting state ]
opf.return_raw_der  0      for AC OPF, return constraint and
                        derivative info in results.raw
                        (in fields g, dg, df, d2f) [ 0 or 1 ]

```

Output options:

name	default	description [options]	
verbose	1	amount of progress info printed	
[0 - print no progress info]
[1 - print a little progress info]
[2 - print a lot of progress info]
[3 - print all progress info]
out.all	-1	controls pretty-printing of results	
[-1 - individual flags control what prints]
[0 - do not print anything (overrides individual flags, ignored]
[for files specified as FNAME arg to runpf(), runopf(), etc.)]
[1 - print everything (overrides individual flags)]
out.sys_sum	1	print system summary	[0 or 1]
out.area_sum	0	print area summaries	[0 or 1]
out.bus	1	print bus detail	[0 or 1]
out.branch	1	print branch detail	[0 or 1]
out.gen	0	print generator detail	[0 or 1]
out.lim.all	-1	controls constraint info output	
[-1 - individual flags control what constraint info prints]
[0 - no constraint info (overrides individual flags)]
[1 - binding constraint info (overrides individual flags)]
[2 - all constraint info (overrides individual flags)]
out.lim.v	1	control voltage limit info	

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```

[ 0 - do not print ]
[ 1 - print binding constraints only ]
[ 2 - print all constraints ]
[ (same options for OUT_LINE_LIM, OUT_PG_LIM, OUT_QG_LIM) ]
out.lim.line      1          control line flow limit info
out.lim.pg        1          control gen active power limit info
out.lim.qg        1          control gen reactive pwr limit info
out.force         0          print results even if success
                        flag = 0 [ 0 or 1 ]
out.suppress_detail -1       suppress all output but system summary
[ -1 - suppress details for large systems (> 500 buses) ]
[ 0 - do not suppress any output specified by other flags ]
[ 1 - suppress all output except system summary section ]
[ (overrides individual flags, but not out.all = 1) ]

```

Solver specific options:

name	default	description [options]
MIPS:		
mips.linsolver	''	linear system solver
['' or '\'	build-in backslash \ operator (e.g. x = A \ b)]
['PARDISO'	PARDISO solver (if available)]
mips.feastol	0	feasibility (equality) tolerance (set to opf.violation by default)
mips.gradtol	1e-6	gradient tolerance
mips.comptol	1e-6	complementary condition (inequality) tolerance
mips.costtol	1e-6	optimality tolerance
mips.max_it	150	maximum number of iterations
mips.step_control	0	enable step-size cntrl [0 or 1]
mips.sc.red_it	20	maximum number of reductions per iteration with step control
mips.xi	0.99995	constant used in alpha updates*
mips.sigma	0.1	centering parameter*
mips.z0	1	used to initialize slack variables*
mips.alpha_min	1e-8	returns "Numerically Failed" if either alpha parameter becomes smaller than this value*
mips.rho_min	0.95	lower bound on rho_t*
mips.rho_max	1.05	upper bound on rho_t*
mips.mu_threshold	1e-5	KT multipliers smaller than this value for non-binding constraints are forced to zero
mips.max_stepsize	1e10	returns "Numerically Failed" if the 2-norm of the reduced Newton step exceeds this value*

* See the corresponding Appendix in the manual for details.

CPLEX:

```

cplex.lpmethod      0          solution algorithm for LP problems
[ 0 - automatic: let CPLEX choose ]
[ 1 - primal simplex ]

```

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```

[ 2 - dual simplex ]
[ 3 - network simplex ]
[ 4 - barrier ]
[ 5 - sifting ]
[ 6 - concurrent (dual, barrier, and primal) ]
cplex.qpmethod      0          solution algorithm for QP problems
[ 0 - automatic: let CPLEX choose ]
[ 1 - primal simplex optimizer ]
[ 2 - dual simplex optimizer ]
[ 3 - network optimizer ]
[ 4 - barrier optimizer ]
cplex.opts          <empty>    see CPLEX_OPTIONS for details
cplex.opt_fname     <empty>    see CPLEX_OPTIONS for details
cplex.opt           0          see CPLEX_OPTIONS for details

FMINCON:
fmincon.alg         4          algorithm used by fmincon() for OPF
                        for Opt Toolbox 4 and later
[ 1 - active-set (not suitable for large problems) ]
[ 2 - interior-point, w/default 'bfgs' Hessian approx ]
[ 3 - interior-point, w/ 'lbfgs' Hessian approx ]
[ 4 - interior-point, w/exact user-supplied Hessian ]
[ 5 - interior-point, w/Hessian via finite differences ]
[ 6 - sqp (not suitable for large problems) ]
fmincon.tol_x       1e-4      termination tol on x
fmincon.tol_f       1e-4      termination tol on f
fmincon.max_it      0          maximum number of iterations
                        [ 0 => default ]

GUROBI:
gurobi.method       0          solution algorithm (Method)
[ -1 - automatic, let Gurobi decide ]
[ 0 - primal simplex ]
[ 1 - dual simplex ]
[ 2 - barrier ]
[ 3 - concurrent (LP only) ]
[ 4 - deterministic concurrent (LP only) ]
[ 5 - deterministic concurrent simplex (LP only) ]
gurobi.timelimit    Inf        maximum time allowed (TimeLimit)
gurobi.threads      0          max number of threads (Threads)
gurobi.opts         <empty>    see GUROBI_OPTIONS for details
gurobi.opt_fname    <empty>    see GUROBI_OPTIONS for details
gurobi.opt          0          see GUROBI_OPTIONS for details

IPOPT:
ipopt.opts          <empty>    see IPOPT_OPTIONS for details
ipopt.opt_fname     <empty>    see IPOPT_OPTIONS for details
ipopt.opt           0          see IPOPT_OPTIONS for details

KNITRO:
knitro.tol_x        1e-4      termination tol on x
knitro.tol_f        1e-4      termination tol on f

```

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knitro.maxit	0	maximum number of iterations [0 => default]
knitro.opt_fname	<empty>	name of user-supplied native Knitro options file that overrides all other options
knitro.opt	0	if knitro.opt_fname is empty and knitro.opt is a non-zero integer N then knitro.opt_fname is auto- generated as: 'knitro_user_options_N.txt'
LINPROG:		
linprog	<empty>	LINPROG options passed to OPTIMOPTIONS or OPTIMSET. see LINPROG in the Optimization Toolbox for details
MINOPF:		
minopf.feastol	0 (1e-3)	primal feasibility tolerance (set to opf.violation by default)
minopf.rowtol	0 (1e-3)	row tolerance
minopf.xtol	0 (1e-4)	x tolerance
minopf.majdamp	0 (0.5)	major damping parameter
minopf.mindamp	0 (2.0)	minor damping parameter
minopf.penalty	0 (1.0)	penalty parameter
minopf.major_it	0 (200)	major iterations
minopf.minor_it	0 (2500)	minor iterations
minopf.max_it	0 (2500)	iterations limit
minopf.verbosity	-1	amount of progress info printed [-1 - controlled by 'verbose' option] [0 - print nothing] [1 - print only termination status message] [2 - print termination status and screen progress] [3 - print screen progress, report file (usually fort.9)]
minopf.core	0 (1200*nb + 2*(nb+ng)^2)	memory allocation
minopf.supbasic_lim	0 (2*nb + 2*ng)	superbasics limit
minopf.mult_price	0 (30)	multiple price
MOSEK:		
mosek.lp_alg	0	solution algorithm (MSK_IPAR_OPTIMIZER) for MOSEK 8.x ... (see MOSEK_SYMBCON for a "better way") [0 - automatic: let MOSEK choose] [1 - dual simplex] [2 - automatic: let MOSEK choose] [3 - automatic simplex (MOSEK chooses which simplex method)] [4 - interior point] [6 - primal simplex]
mosek.max_it	0 (400)	interior point max iterations (MSK_IPAR_INTPNT_MAX_ITERATIONS)
mosek.gap_tol	0 (1e-8)	interior point relative gap tol (MSK_DPAR_INTPNT_TOL_REL_GAP)

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mosek.max_time	0 (-1)	maximum time allowed (MSK_DPAR_OPTIMIZER_MAX_TIME)
mosek.num_threads	0 (1)	max number of threads (MSK_IPAR_INTPNT_NUM_THREADS)
mosek.opts	<empty>	see MOSEK_OPTIONS for details
mosek.opt_fname	<empty>	see MOSEK_OPTIONS for details
mosek.opt	0	see MOSEK_OPTIONS for details
OSQP:		
osqp.opts	<empty>	see OSQP_OPTIONS for details
QUADPROG:		
quadprog	<empty>	QUADPROG options passed to OPTIMOPTIONS or OPTIMSET. see QUADPROG in the Optimization Toolbox for details
TSPOPF:		
pdipm.feastol	0	feasibility (equality) tolerance (set to opf.violation by default)
pdipm.gradtol	1e-6	gradient tolerance
pdipm.comptol	1e-6	complementary condition (inequality) tolerance
pdipm.costtol	1e-6	optimality tolerance
pdipm.max_it	150	maximum number of iterations
pdipm.step_control	0	enable step-size cntrl [0 or 1]
pdipm.sc.red_it	20	maximum number of reductions per iteration with step control
pdipm.sc.smooth_ratio	0.04	piecewise linear curve smoothing ratio
tralm.feastol	0	feasibility tolerance (set to opf.violation by default)
tralm.primaltol	5e-4	primal variable tolerance
tralm.dualtol	5e-4	dual variable tolerance
tralm.costtol	1e-5	optimality tolerance
tralm.major_it	40	maximum number of major iterations
tralm.minor_it	40	maximum number of minor iterations
tralm.smooth_ratio	0.04	piecewise linear curve smoothing ratio
Experimental Options:		
exp.use_legacy_core	0	set to 1 to bypass MP-Core and force use of legacy core code for runpf(), runcpf(), runopf().
exp.sys_wide_zip_loads.pw	<empty>	1 x 3 vector of active load fraction to be modeled as constant power, constant current and constant impedance, respectively, where <empty> means use [1 0 0]
exp.sys_wide_zip_loads.qw	<empty>	same for reactive power, where <empty> means use same value as

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for 'pw'

printf

printf(baseMVA, bus, gen, branch, f, success, et, fd, mpopt)

printf() - Prints power flow results.

PRINTF(RESULTS, FD, MPOPT)

PRINTF(BASEMVA, BUS, GEN, BRANCH, F, SUCCESS, ET, FD, MPOPT)

Prints power flow and optimal power flow results to FD (a file descriptor which defaults to STDOUT), with the details of what gets printed controlled by the optional MPOPT argument, which is a MATPOWER options struct (see MPOPTION for details).

The data can either be supplied in a single RESULTS struct, or in the individual arguments: BASEMVA, BUS, GEN, BRANCH, F, SUCCESS and ET, where F is the OPF objective function value, SUCCESS is true if the solution converged and false otherwise, and ET is the elapsed time for the computation in seconds. If F is given, it is assumed that the output is from an OPF run, otherwise it is assumed to be a simple power flow run.

Examples:

```
mpopt = mpoptions('out.gen', 1, 'out.bus', 0, 'out.branch', 0);
[fd, msg] = fopen(fname, 'at');
results = runopf(mpc);
printf(results);
printf(results, fd);
printf(results, fd, mpopt);
printf(baseMVA, bus, gen, branch, f, success, et);
printf(baseMVA, bus, gen, branch, f, success, et, fd);
printf(baseMVA, bus, gen, branch, f, success, et, fd, mpopt);
fclose(fd);
```

psse2mpc

psse2mpc(rawfile_name, mpc_name, verbose, rev)

psse2mpc() - Converts a PSS/E RAW data file into a MATPOWER case struct.

```
MPC = PSSE2MPC(RAWFILE_NAME)
MPC = PSSE2MPC(RAWFILE_NAME, VERBOSE)
MPC = PSSE2MPC(RAWFILE_NAME, VERBOSE, REV)
MPC = PSSE2MPC(RAWFILE_NAME, MPC_NAME)
MPC = PSSE2MPC(RAWFILE_NAME, MPC_NAME, VERBOSE)
MPC = PSSE2MPC(RAWFILE_NAME, MPC_NAME, VERBOSE, REV)
[MPC, WARNINGS] = PSSE2MPC(RAWFILE_NAME, ...)
```

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Converts a PSS/E RAW data file into a MATPOWER **case struct**.

Input:

RAWFILE_NAME : name of the PSS/E RAW file to be converted
(opened directly with FILEREAD)
MPC_NAME : (optional) file name to use to save the resulting
MATPOWER **case**
VERBOSE : 1 (default) to **display** progress **info**, 0 **otherwise**
REV : (optional) assume the **input** file is of this
PSS/E revision number, attempts to determine
REV from the file by default

Output(s):

MPC : resulting MATPOWER **case struct**
WARNINGS : (optional) **cell** array of strings containing **warning**
messages (included by default in comments of MPC_NAME).

NOTE: The data sections to be read in the PSS/E raw file includes:
identification data; bus data; branch data; fixed shunt data;
generator data; transformer data; switched shunt data; **area** data
and hvdc **line** data. Other data sections are currently ignored.

save2psse

save2psse(fname, mpc, rawver)

save2psse() - Saves a MATPOWER case to PSS/E RAW format.

SAVE2PSSE(FNAME, MPC)

FNAME = SAVE2PSSE(FNAME, ...)

Saves a MATPOWER **case struct** MPC as a PSS/E RAW file. The FNAME parameter is a string containing the name of the file to be created **or** overwritten. If FNAME does **not** include a file extension, **'.raw'** will be added. Optionally returns the, possibly updated, filename. Currently exports to RAW format Rev 33.

savecase

savecase(*fname*, *varargin*)

savecase() - Saves a MATPOWER case file, given a filename and the data.

```
SAVECASE(FNAME, CASESTRUCT)
SAVECASE(FNAME, CASESTRUCT, VERSION)
SAVECASE(FNAME, BASEMVA, BUS, GEN, BRANCH)
SAVECASE(FNAME, BASEMVA, BUS, GEN, BRANCH, GENCOST)
SAVECASE(FNAME, BASEMVA, BUS, GEN, BRANCH, AREAS, GENCOST)
SAVECASE(FNAME, COMMENT, CASESTRUCT)
SAVECASE(FNAME, COMMENT, CASESTRUCT, VERSION)
SAVECASE(FNAME, COMMENT, BASEMVA, BUS, GEN, BRANCH)
SAVECASE(FNAME, COMMENT, BASEMVA, BUS, GEN, BRANCH, GENCOST)
SAVECASE(FNAME, COMMENT, BASEMVA, BUS, GEN, BRANCH, AREAS, GENCOST)

FNAME = SAVECASE(FNAME, ...)
```

Writes a MATPOWER **case** file, given a filename and data **struct** or list of data matrices. The FNAME parameter is the name of the file to be created or overwritten. If FNAME ends with **'*.mat*'** it saves the **case** as a MAT-file **otherwise** it saves it as an M-file. Optionally returns the filename, with extension added **if** necessary. The optional COMMENT argument is either string (**single line** comment) or a **cell** array of strings which are inserted as comments. When using a MATPOWER **case struct**, **if** the optional VERSION argument is **'1'** it will modify the data matrices to **version 1** format before saving.

savechgtab

savechgtab(*fname*, *chgtab*, *warnings*)

savechgtab() - Save a change table to a file.

```
SAVECHGTAB(FNAME, CHGTAB)
SAVECHGTAB(FNAME, CHGTAB, WARNINGS)
FNAME = SAVECHGTAB(FNAME, ...)
```

Writes a CHGTAB, suitable **for** use with APPLY_CHANGES to a file specified by FNAME. If FNAME ends with **'*.mat*'** it saves CHGTAB and WARNINGS to a MAT-file as the variables **'*chgtab*'** and **'*warnings*'**, respectively. Otherwise, it saves an M-file **function** that returns the CHGTAB, with the optional WARNINGS in comments.

Optionally returns the filename, with extension added **if** necessary.

Input:

FNAME : name of the file to be saved
CHGTAB : change **table** suitable **for** use with APPLY_CHANGES
WARNINGS : optional **cell** array of **warning** messages (to be included in comments), such as those returned by

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PSSECON2CHGTAB

Output(s):

FNAME : name of the file, with extension added **if** necessary

5.2.3 Data Conversion Functions

ext2int

ext2int(bus, gen, branch, areas)

ext2int() - Converts external to internal indexing.

This **function** has two forms, (1) the old form that operates on **and** returns individual matrices **and** (2) the new form that operates on **and** returns an entire MATPOWER **case struct**.

1. [I2E, BUS, GEN, BRANCH, AREAS] = EXT2INT(BUS, GEN, BRANCH, AREAS)
[I2E, BUS, GEN, BRANCH] = EXT2INT(BUS, GEN, BRANCH)

If the first argument is a matrix, it simply converts from (possibly non-consecutive) external bus numbers to consecutive internal bus numbers which start at 1. Changes are made to BUS, GEN **and** BRANCH, which are returned along with a vector of indices I2E that can be passed to INT2EXT to perform the reverse conversion, where `EXTERNAL_BUS_NUMBER = I2E(INTERNAL_BUS_NUMBER)`. AREAS is completely ignored **and** is only included here **for** backward compatibility of the API.

Examples:

```
[i2e, bus, gen, branch, areas] = ext2int(bus, gen, branch, areas);
[i2e, bus, gen, branch] = ext2int(bus, gen, branch);
```

2. MPC = EXT2INT(MPC)
MPC = EXT2INT(MPC, MPOPT)

If the **input** is a **single** MATPOWER **case struct**, followed optionally by a MATPOWER options **struct**, then **all** isolated buses, off-line generators **and** branches are removed along with **any** generators **or** branches connected to isolated buses. Then the buses are renumbered consecutively, beginning at 1. Any '**ext2int**' callback routines registered in the **case** are also invoked automatically. All of the related indexing information **and** the original data matrices are stored in an '**order**' field in the **struct** to be used by INT2EXT to perform the reverse conversions. If the **case** is already using internal numbering it is returned unchanged.

Examples:

```
mpc = ext2int(mpc);
```

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```
mpc = ext2int(mpc, mpopt);
```

The `'order'` field of MPC used to store the indexing information needed for subsequent internal to external conversion is structured as:

```
order
  state      'i' | 'e'
  ext | int
    bus
    branch
    gen
    gencost
    A
    N
  bus
    e2i
    i2e
    status
      on
      off
  gen
    e2i
    i2e
    status
      on
      off
  branch
    status
      on
      off
```

See also `int2ext()`, `e2i_field()` (page 253), `e2i_data()` (page 252).

e2i_data

`e2i_data(mpc, val, ordering, dim)`

`e2i_data()` (page 252) - Converts data from external to internal indexing.

```
VAL = E2I_DATA(MPC, VAL, ORDERING)
VAL = E2I_DATA(MPC, VAL, ORDERING, DIM)
```

When given a **case struct** that has already been converted to internal indexing, this **function** can be used to convert other data structures as well by passing in 2 or 3 extra parameters in addition to the **case struct**. If the value passed in the 2nd argument is a column vector or cell array, it will be converted according to the ORDERING specified by the 3rd argument (described below). If VAL is an n-dimensional matrix or cell array, then the optional 4th argument (DIM, default = 1) can be used to specify

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which dimension to reorder. The **return** value in this **case** is the value passed in, converted to internal indexing.

The 3rd argument, ORDERING, is used to indicate whether the data corresponds to bus-, gen- or branch-ordered data. It can be one of the following three strings: 'bus', 'gen' or 'branch'. For data structures with multiple blocks of data, ordered by bus, gen or branch, they can be converted with a **single** call by specifying ORDERING as a **cell** array of strings.

Any extra elements, rows, columns, etc. beyond those indicated in ORDERING, are **not** disturbed.

Examples:

```
A_int = e2i_data(mpc, A_ext, {'bus','bus','gen','gen'}, 2);
```

Converts an A matrix **for** user-supplied OPF constraints from external to internal ordering, where the **columns** of the A matrix correspond to bus voltage angles, then voltage magnitudes, then generator **real power** injections and finally generator reactive **power** injections.

```
gencost_int = e2i_data(mpc, gencost_ext, {'gen','gen'}, 1);
```

Converts a GENCOST matrix that has both **real** and reactive **power** costs (in rows 1--ng and ng+1--2*ng, respectively).

See also [i2e_data\(\)](#) (page 255), [e2i_field\(\)](#) (page 253), ext2int().

e2i_field

e2i_field(mpc, field, ordering, dim)

[e2i_field\(\)](#) (page 253) - Converts fields of mpc from external to internal indexing.

This **function** performs several different tasks, depending on the arguments passed.

```
MPC = E2I_FIELD(MPC, FIELD, ORDERING)
```

```
MPC = E2I_FIELD(MPC, FIELD, ORDERING, DIM)
```

When given a **case struct** that has already been converted to internal indexing, this **function** can be used to convert other data structures as well by passing in 2 or 3 extra parameters in addition to the **case struct**.

The 2nd argument is a string or **cell** array of strings, specifying a field in the **case struct** whose value should be converted by a corresponding call to E2I_DATA. The field can contain either a numeric or a **cell** array. The converted value is stored back in the specified field, the original value is saved **for** later use and the

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updated **case struct** is returned. If **FIELD** is a **cell** array of strings, they specify nested fields.

The 3rd and optional 4th arguments are simply passed along to the call to **E2I_DATA**.

Examples:

```
mpc = e2i_field(mpc, {'reserves', 'cost'}, 'gen');
```

Reorders **rows** of **mpc.reserves.cost** to match internal generator ordering.

```
mpc = e2i_field(mpc, {'reserves', 'zones'}, 'gen', 2);
```

Reorders **columns** of **mpc.reserves.zones** to match internal generator ordering.

See also *i2e_field()* (page 256), *e2i_data()* (page 252), *ext2int()*.

int2ext

int2ext(*i2e, bus, gen, branch, areas*)

int2ext() - Converts internal to external bus numbering.

This **function** has two forms, (1) the old form that operates on **and** returns individual matrices **and** (2) the new form that operates on **and** returns an entire MATPOWER **case struct**.

1. **[BUS, GEN, BRANCH, AREAS] = INT2EXT(I2E, BUS, GEN, BRANCH, AREAS)**
[BUS, GEN, BRANCH] = INT2EXT(I2E, BUS, GEN, BRANCH)

Converts from the consecutive internal bus numbers back to the originals using the mapping provided by the **I2E** vector returned from **EXT2INT**, where **EXTERNAL_BUS_NUMBER = I2E(INTERNAL_BUS_NUMBER)**.

AREAS is completely ignored **and** is only included here **for** backward compatibility of the API.

Examples:

```
[bus, gen, branch, areas] = int2ext(i2e, bus, gen, branch, areas);
[bus, gen, branch] = int2ext(i2e, bus, gen, branch);
```

2. **MPC = INT2EXT(MPC)**
MPC = INT2EXT(MPC, MPOPT)

If the **input** is a **single** MATPOWER **case struct**, followed optionally by a MATPOWER options **struct**, then it restores **all** buses, generators **and** branches that were removed because of being isolated **or** off-line, **and** reverts to the original generator ordering **and** original bus numbering. This requires that the **'order'** field created by **EXT2INT** be in place.

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Examples:

```
mpc = int2ext(mpc);
mpc = int2ext(mpc, mpopt);
```

See also `ext2int()`, `i2e_field()` (page 256), `i2e_data()` (page 255).

i2e_data

`i2e_data(mpc, val, oldval, ordering, dim)`

`i2e_data()` (page 255) - Converts data from internal to external indexing.

```
VAL = I2E_DATA(MPC, VAL, OLDVAL, ORDERING)
VAL = I2E_DATA(MPC, VAL, OLDVAL, ORDERING, DIM)
```

For a **case struct** using internal indexing, this **function** can be used to convert other data structures as well by passing in 3 or 4 extra parameters in addition to the **case struct**. If the value passed in the 2nd argument (VAL) is a column vector or cell array, it will be converted according to the ordering specified by the 4th argument (ORDERING, described below). If VAL is an n-dimensional matrix or cell array, then the optional 5th argument (DIM, default = 1) can be used to specify which dimension to reorder. The 3rd argument (OLDVAL) is used to initialize the **return** value before converting VAL to external indexing. In particular, any data corresponding to off-line gens or branches or isolated buses or any connected gens or branches will be taken from OLDVAL, with VAL supplying the rest of the returned data.

The ORDERING argument is used to indicate whether the data corresponds to bus-, gen- or branch-ordered data. It can be one of the following three strings: 'bus', 'gen' or 'branch'. For data structures with multiple blocks of data, ordered by bus, gen or branch, they can be converted with a single call by specifying ORDERING as a cell array of strings.

Any extra elements, rows, columns, etc. beyond those indicated in ORDERING, are not disturbed.

Examples:

```
A_ext = i2e_data(mpc, A_int, A_orig, {'bus','bus','gen','gen'}, 2);
```

Converts an A matrix for user-supplied OPF constraints from internal to external ordering, where the columns of the A matrix correspond to bus voltage angles, then voltage magnitudes, then generator real power injections and finally generator reactive power injections.

```
gencost_ext = i2e_data(mpc, gencost_int, gencost_orig, {'gen','gen'}, 1);
```

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Converts a GENCO matrix that has both **real** and reactive **power** costs (in **rows** 1--ng and ng+1--2*ng, respectively).

See also `e2i_data()` (page 252), `i2e_field()` (page 256), `int2ext()`.

`i2e_field`

`i2e_field(mpc, field, ordering, dim)`

`i2e_field()` (page 256) - Converts fields of mpc from internal to external bus numbering.

```
MPC = I2E_FIELD(MPC, FIELD, ORDERING)
MPC = I2E_FIELD(MPC, FIELD, ORDERING, DIM)
```

For a **case struct** using internal indexing, this **function** can be used to convert other data structures as well by passing in 2 or 3 extra parameters in addition to the **case struct**.

The 2nd argument is a string or cell array of strings, specifying a field in the **case struct** whose value should be converted by a corresponding call to `I2E_DATA`. The field can contain either a numeric or a cell array. The corresponding OLDVAL is taken from where it was stored by `EXT2INT` in `MPC.ORDER.EXT` and the updated **case struct** is returned. If `FIELD` is a cell array of strings, they specify nested fields.

The 3rd and optional 4th arguments are simply passed along to the call to `I2E_DATA`.

Examples:

```
mpc = i2e_field(mpc, {'reserves', 'cost'}, 'gen');
```

Reorders **rows** of `mpc.reserves.cost` to match external generator ordering.

```
mpc = i2e_field(mpc, {'reserves', 'zones'}, 'gen', 2);
```

Reorders **columns** of `mpc.reserves.zones` to match external generator ordering.

See also `e2i_field()` (page 253), `i2e_data()` (page 255), `int2ext()`.

get_reorder

get_reorder(A, idx, dim)

[get_reorder\(\)](#) (page 257) - Returns A with one of its dimensions indexed.

```
B = GET_REORDER(A, IDX, DIM)
```

Returns A(:, ..., :, IDX, :, ..., :), where DIM determines in which dimension to place the IDX.

See also [set_reorder\(\)](#) (page 257).

set_reorder

set_reorder(A, B, idx, dim)

[set_reorder\(\)](#) (page 257) - Assigns B to A with one of the dimensions of A indexed.

```
A = SET_REORDER(A, B, IDX, DIM)
```

Returns A after doing A(:, ..., :, IDX, :, ..., :) = B where DIM determines in which dimension to place the IDX.

If **any** dimension of B is smaller than the corresponding dimension of A, the "extra" elements in A are untouched. If **any** dimension of B is larger than the corresponding dimension of A, then A is padded with **zeros** (if numeric) or empty matrices (if cell array) before performing the assignment.

See also [get_reorder\(\)](#) (page 257).

5.2.4 Power Flow Functions

calc_v_i_sum

calc_v_i_sum(Vslack, nb, nl, f, Zb, Ybf, Ybt, Yd, Sd, pv, Pg, Vg, mpopt)

[calc_v_i_sum\(\)](#) (page 257) - Solves the power flow using the current summation method.

```
[V, Qpv, Sf, St, Sslack, iter, success] = calc_v_i_sum(Vslack, nb, nl, f, Zb, Ybf, Ybt, Yd,
→ Sd, pv, Pg, Vg, tol, iter_max)
```

Solves **for** bus voltages, generator reactive **power**, branch active and reactive **power** flows and slack bus active and reactive **power**. The **input** data consist of slack bus voltage, vector "from bus" indices, branch impedance and shunt admittance, vector of bus shunt admittances and **load** demand, as well as vectors with indices of PV buses with their specified voltages and active powers. It is assumed that the branches are ordered using the principle of oriented ordering: indices of

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sending nodes are smaller than the indices of the receiving nodes. The branch `index` is equal to the `index` of their receiving node. Branch admittances are added in `Yd` and treated as constant admittance bus loads. The applied method is current summation taken from:

D. Shirmohammadi, H. W. Hong, A. Semlyen and G. X. Luo, "A compensation-based power flow method for weakly meshed distribution and transmission networks," IEEE Transactions on Power Systems, vol. 3, no. 2, pp. 753-762, May 1988. <https://doi.org/10.1109/59.192932>

and G. X. Luo and A. Semlyen, "Efficient load flow for large weakly meshed networks," IEEE Transactions on Power Systems, vol. 5, no. 4, pp. 1309-1316, Nov 1990. <https://doi.org/10.1109/59.99382>

See also `radial_pf()` (page 266).

`calc_v_pq_sum`

`calc_v_pq_sum(Vslack, nb, nl, f, Zb, Ybf, Ybt, Yd, Sd, pv, Pg, Vg, mpopt)`

`calc_v_pq_sum()` (page 258) - Solves the power flow using the power summation method.

```
[V, Qpv, Sf, St, Sslack, iter, success] = calc_v_pq_sum(Vslack, nb, nl, f, Zb, Ybf, Ybt, ,
↪ Yd, Sd, pv, Pg, Vg, tol, iter_max)
```

Solves **for** bus voltages, generator reactive **power**, branch active and reactive **power** flows and slack bus active and reactive **power**. The **input** data consist of slack bus voltage, vector "from bus" indices, branch impedance and shunt admittance, vector of bus shunt admittances and load demand, as well as vectors with indices of PV buses with their specified voltages and active powers. It is assumed that the branches are ordered using the principle of oriented ordering: indices of sending nodes are smaller than the indices of the receiving nodes. The branch `index` is equal to the `index` of their receiving node. Branch admittances are added in `Yd` and treated as constant admittance bus loads. The applied method is Voltage correction **power** flow (VCPF) taken from:

D. Rajicic, R. Ackovski and R. Taleski, "Voltage correction power flow," IEEE Transactions on Power Delivery, vol. 9, no. 2, pp. 1056-1062, Apr 1994. <https://doi.org/10.1109/61.296308>

See also `radial_pf()` (page 266).

calc_v_y_sum**calc_v_y_sum**(Vslack, nb, nl, f, Zb, Ybf, Ybt, Yd, Sd, pv, Pg, Vg, mpopt)*calc_v_y_sum()* (page 259) - Solves the power flow using the admittance summation method.

```
[V, Qpv, Sf, St, Sslack, iter, success] = calc_v_y_sum(Vslack,nb,nl,f,Zb,Ybf,Ybt,Yd,
↪Sd,pv,Pg,Vg,tol,iter_max)
```

Solves **for** bus voltages, generator reactive **power**, branch active **and** reactive **power** flows **and** slack bus active **and** reactive **power**. The **input** data consist of slack bus voltage, vector "**from bus**" indices, branch impedance **and** shunt admittance, vector of bus shunt admittances **and** **load** demand, as well as vectors with indices of PV buses with their specified voltages **and** active powers. It is assumed that the branches are ordered using the principle of oriented ordering: indices of sending nodes are smaller than the indices of the receiving nodes. The branch **index** is equal to the **index** of their receiving node. Branch admittances are added in Yd **and** treated as constant admittance bus loads. The applied method is admittance summation taken from: Dragoslav Rajičić, Rubin Taleski, Two novel **methods for** radial **and** weakly meshed network analysis, Electric Power Systems Research, Volume 48, Issue 2, 15 December 1998, Pages 79-87
[https://doi.org/10.1016/S0378-7796\(98\)00067-4](https://doi.org/10.1016/S0378-7796(98)00067-4)

See also *radial_pf()* (page 266).

dcpf**dcpf**(B, Pbus, Va0, ref, pv, pq)*dcpf()* - Solves a DC power flow.

[VA, SUCCESS] = DCPF(B, PBUS, VA0, REF, PV, PQ) solves **for** the bus voltage angles at **all** but the reference bus, given the **full system** B matrix **and** the vector of bus **real power** injections, the initial vector of bus voltage angles (in radians), **and** column vectors with the lists of bus indices **for** the swing bus, PV buses, **and** PQ buses, respectively. Returns a vector of bus voltage angles in radians.

See also *rundcpf()*, *runpf()*.

fdpf**fdpf**(*Ybus, Sbus, V0, Bp, Bpp, ref, pv, pq, mpopt*)

fdpf() - Solves the power flow using a fast decoupled method.

[V, CONVERGED, I] = FDPF(YBUS, SBUS, V0, BP, BPP, REF, PV, PQ, MPOPT) solves **for** bus voltages given the **full system** admittance matrix (**for all** buses), the **complex** bus **power** injection vector (**for all** buses), the initial vector of **complex** bus voltages, the FDPF matrices B prime and B double prime, and column vectors with the lists of bus indices **for** the swing bus, PV buses, and PQ buses, respectively. The bus voltage vector contains the **set** point **for** generator (including ref bus) buses, and the reference **angle** of the swing bus, as well as an initial guess **for** remaining magnitudes and angles. MPOPT is a MATPOWER options vector which can be used to **set** the termination tolerance, maximum number of iterations, and output options (see MPOPTION **for** details). Uses default options **if** this parameter is **not** given. Returns the final **complex** voltages, a **flag** which indicates whether it converged **or not**, and the number of iterations performed.

See also runpf().

gausspf**gausspf**(*Ybus, Sbus, V0, ref, pv, pq, mpopt*)

gausspf() - Solves the power flow using a Gauss-Seidel method.

[V, CONVERGED, I] = GAUSSPF(YBUS, SBUS, V0, REF, PV, PQ, MPOPT) solves **for** bus voltages given the **full system** admittance matrix (**for all** buses), the **complex** bus **power** injection vector (**for all** buses), the initial vector of **complex** bus voltages, and column vectors with the lists of bus indices **for** the swing bus, PV buses, and PQ buses, respectively. The bus voltage vector contains the **set** point **for** generator (including ref bus) buses, and the reference **angle** of the swing bus, as well as an initial guess **for** remaining magnitudes and angles. MPOPT is a MATPOWER options **struct** which can be used to **set** the termination tolerance, maximum number of iterations, and output options (see MPOPTION **for** details). Uses default options **if** this parameter is **not** given. Returns the final **complex** voltages, a **flag** which indicates whether it converged **or not**, and the number of iterations performed.

See also runpf().

make_vcorr

make_vcorr(DD, pv, nb, nl, f, Zb)

make_vcorr() (page 261) - Voltage Correction used in distribution power flow.

```
V_corr = make_vcorr(DD, pv, nb, nl, f, Zb)
```

Calculates voltage corrections with current generators placed at PV buses. Their currents are calculated with the voltage difference at PV buses **break** points and loop impedances. The slack bus voltage is **set** to zero. Details can be seen in D. Rajicic, R. Ackovski and R. Taleski, "Voltage correction power flow," IEEE Transactions on Power Delivery, vol. 9, no. 2, pp. 1056-1062, Apr 1994. <https://doi.org/10.1109/61.296308>

See also *radial_pf()* (page 266).

make_zpv

make_zpv(pv, nb, nl, f, Zb, Yd)

make_zpv() (page 261) - Calculates loop impedances for all PV buses.

```
Zpv = make_zpv(pv, nb, nl, f, Zb, Yd)
```

Loop impedance of a PV bus is defined as impedance of the **path** between the bus and the slack bus. The mutual impedance between two PV buses is the impedance of the joint part of the two **path** going from each of the PV buses to the slack bus. The impedances are calculated as bus voltages in cases when at one of the PV buses we inject current of -1 A. All voltages are calculated with the backward-forward sweep method. The **input** variables are the vector of indicies with "from" buses **for** each branch, the vector of branch impedances and indicies of PV buses.

See also *calc_v_pq_sum()* (page 258).

newtonpf

newtonpf(Ybus, Sbus, V0, ref, pv, pq, mpopt)

newtonpf() - Solves power flow using full Newton's method (power/polar).

```
[V, CONVERGED, I] = NEWTONPF(YBUS, SBUS, V0, REF, PV, PQ, MPOPT)
```

Solves **for** bus voltages using a **full** Newton-Raphson method, using nodal **power balance** equations and **polar** coordinate representation of voltages, given the following inputs:

- YBUS - **full system** admittance matrix (**for all** buses)
- SBUS - handle to **function** that returns the **complex** bus **power** injection vector (**for all** buses), given the bus voltage magnitude vector (**for all** buses)

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V0 - initial vector of **complex** bus voltages
REF - bus **index** of reference bus (voltage ang reference & gen slack)
PV - vector of bus indices **for** PV buses
PQ - vector of bus indices **for** PQ buses
MPOPT - (optional) MATPOWER option **struct**, used to **set** the termination tolerance, maximum number of iterations, and output options (see MPOPTION **for** details).

The bus voltage vector contains the **set** point **for** generator (including ref bus) buses, and the reference **angle** of the swing bus, as well as an initial guess **for** remaining magnitudes and angles.

Returns the final **complex** voltages, a **flag** which indicates whether it converged **or not**, and the number of iterations performed.

See also `runpf()`, `newtonpf_S_cart()` (page 264), `newtonpf_I_polar()` (page 263), `newtonpf_I_cart()` (page 262).

newtonpf_I_cart

newtonpf_I_cart(*Ybus, Sbus, V0, ref, pv, pq, mpopt*)

`newtonpf_I_cart()` (page 262) - Solves power flow using full Newton's method (current/cartesian).

`[V, CONVERGED, I] = NEWTONPF_I_CART(YBUS, SBUS, V0, REF, PV, PQ, MPOPT)`

Solves **for** bus voltages using a **full** Newton-Raphson method, using nodal current **balance** equations and cartesian coordinate representation of voltages, given the following inputs:

YBUS - **full system** admittance matrix (**for all** buses)
SBUS - handle to **function** that returns the **complex** bus **power** injection vector (**for all** buses), given the bus voltage magnitude vector (**for all** buses)
V0 - initial vector of **complex** bus voltages
REF - bus **index** of reference bus (voltage ang reference & gen slack)
PV - vector of bus indices **for** PV buses
PQ - vector of bus indices **for** PQ buses
MPOPT - (optional) MATPOWER option **struct**, used to **set** the termination tolerance, maximum number of iterations, and output options (see MPOPTION **for** details).

The bus voltage vector contains the **set** point **for** generator (including ref bus) buses, and the reference **angle** of the swing bus, as well as an initial guess **for** remaining magnitudes and angles.

Returns the final **complex** voltages, a **flag** which indicates whether it converged **or not**, and the number of iterations performed.

See also `runpf()`, `newtonpf()`, `newtonpf_S_cart()` (page 264), `newtonpf_I_polar()` (page 263).

newtonpf_I_hybrid

newtonpf_I_hybrid(*Ybus, Sbus, V0, ref, pv, pq, mpopt*)

newtonpf_I_hybrid() (page 263) - Solves power flow using full Newton's method (current/hybrid).

```
[V, CONVERGED, I] = NEWTONPF_I_HYBRID(YBUS, SBUS, V0, REF, PV, PQ, MPOPT)
```

Solves **for** bus voltages using a **full** Newton-Raphson method, using nodal current **balance** equations **and** a hybrid representation of voltages, where a **polar** update is computed using a cartesian Jacobian, given the following inputs:

- YBUS - **full system** admittance matrix (**for all** buses)
- SBUS - handle to **function** that returns the **complex** bus **power** injection vector (**for all** buses), given the bus voltage magnitude vector (**for all** buses)
- V0 - initial vector of **complex** bus voltages
- REF - bus **index** of reference bus (voltage ang reference & gen slack)
- PV - vector of bus indices **for** PV buses
- PQ - vector of bus indices **for** PQ buses
- MPOPT - (optional) MATPOWER option **struct**, used to **set** the termination tolerance, maximum number of iterations, **and** output options (see MPOPTION **for** details).

The bus voltage vector contains the **set** point **for** generator (including ref bus) buses, **and** the reference **angle** of the swing bus, as well as an initial guess **for** remaining magnitudes **and** angles.

Returns the final **complex** voltages, a **flag** which indicates whether it converged **or not**, **and** the number of iterations performed.

See also `runpf()`, `newtonpf()`, *newtonpf_S_cart()* (page 264), *newtonpf_I_polar()* (page 263).

newtonpf_I_polar

newtonpf_I_polar(*Ybus, Sbus, V0, ref, pv, pq, mpopt*)

newtonpf_I_polar() (page 263) - Solves power flow using full Newton's method (current/cartesian).

```
[V, CONVERGED, I] = NEWTONPF_I_POLAR(YBUS, SBUS, V0, REF, PV, PQ, MPOPT)
```

Solves **for** bus voltages using a **full** Newton-Raphson method, using nodal current **balance** equations **and** **polar** coordinate representation of voltages, given the following inputs:

- YBUS - **full system** admittance matrix (**for all** buses)
- SBUS - handle to **function** that returns the **complex** bus **power** injection vector (**for all** buses), given the bus voltage magnitude vector (**for all** buses)
- V0 - initial vector of **complex** bus voltages

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REF - bus **index** of reference bus (voltage ang reference & gen slack)
 PV - vector of bus indices **for** PV buses
 PQ - vector of bus indices **for** PQ buses
 MPOPT - (optional) MATPOWER option **struct**, used to **set** the
 termination tolerance, maximum number of iterations, **and**
 output options (see MPOPTION **for** details).

The bus voltage vector contains the **set** point **for** generator
 (including ref bus) buses, **and** the reference **angle** of the swing
 bus, as well as an initial guess **for** remaining magnitudes **and**
 angles.

Returns the final **complex** voltages, a **flag** which indicates whether it
 converged **or not**, **and** the number of iterations performed.

See also `runpf()`, `newtonpf()`, `newtonpf_S_cart()` (page 264), `newtonpf_I_cart()` (page 262).

`newtonpf_S_cart`

`newtonpf_S_cart(Ybus, Sbus, V0, ref, pv, pq, mpopt)`

`newtonpf_S_cart()` (page 264) - Solves power flow using full Newton's method (power/cartesian).

```
[V, CONVERGED, I] = NEWTONPF_S_CART(YBUS, SBUS, V0, REF, PV, PQ, MPOPT)
```

Solves **for** bus voltages using a **full** Newton-Raphson method, using nodal
power balance equations **and** cartesian coordinate representation of
 voltages, given the following inputs:

YBUS - **full system** admittance matrix (**for all** buses)
 SBUS - handle to **function** that returns the **complex** bus **power**
 injection vector (**for all** buses), given the bus voltage
 magnitude vector (**for all** buses)
 V0 - initial vector of **complex** bus voltages
 REF - bus **index** of reference bus (voltage ang reference & gen slack)
 PV - vector of bus indices **for** PV buses
 PQ - vector of bus indices **for** PQ buses
 MPOPT - (optional) MATPOWER option **struct**, used to **set** the
 termination tolerance, maximum number of iterations, **and**
 output options (see MPOPTION **for** details).

The bus voltage vector contains the **set** point **for** generator
 (including ref bus) buses, **and** the reference **angle** of the swing
 bus, as well as an initial guess **for** remaining magnitudes **and**
 angles.

Returns the final **complex** voltages, a **flag** which indicates whether it
 converged **or not**, **and** the number of iterations performed.

See also `runpf()`, `newtonpf()`, `newtonpf_I_polar()` (page 263), `newtonpf_I_cart()` (page 262).

newtonpf_S_hybrid

newtonpf_S_hybrid(Ybus, Sbus, V0, ref, pv, pq, mpop)

[newtonpf_S_hybrid\(\)](#) (page 265) - Solves power flow using full Newton's method (power/hybrid).

```
[V, CONVERGED, I] = NEWTONPF_S_HYBRID(YBUS, SBUS, V0, REF, PV, PQ, MPOPT)
```

Solves **for** bus voltages using a **full** Newton-Raphson method, using nodal **power balance** equations **and** a hybrid representation of voltages, where a **polar** update is computed using a cartesian Jacobian, given the following inputs:

- YBUS - **full system** admittance matrix (**for all** buses)
- SBUS - handle to **function** that returns the **complex** bus **power** injection vector (**for all** buses), given the bus voltage magnitude vector (**for all** buses)
- V0 - initial vector of **complex** bus voltages
- REF - bus **index** of reference bus (voltage ang reference & gen slack)
- PV - vector of bus indices **for** PV buses
- PQ - vector of bus indices **for** PQ buses
- MPOPT - (optional) MATPOWER option **struct**, used to **set** the termination tolerance, maximum number of iterations, **and** output options (see MPOPTION **for** details).

The bus voltage vector contains the **set** point **for** generator (including ref bus) buses, **and** the reference **angle** of the swing bus, as well as an initial guess **for** remaining magnitudes **and** angles.

Returns the final **complex** voltages, a **flag** which indicates whether it converged **or not**, **and** the number of iterations performed.

See also [runpf\(\)](#), [newtonpf\(\)](#), [newtonpf_I_polar\(\)](#) (page 263), [newtonpf_I_cart\(\)](#) (page 262).

order_radial

order_radial(mpc)

[order_radial\(\)](#) (page 265) - Performs oriented ordering to buses and branches.

```
mpc = order_radial(mpc)
```

orders the branches by the the principle of oriented ordering: indicies of sending nodes are smaller than the indicies of the receiving nodes. The branch **index** is equal to the **index** of their receiving node. The ordering is taken from:
D. Rajicic, R. Ackovski **and** R. Taleski, "Voltage correction power flow," IEEE Transactions on Power Delivery, vol. 9, no. 2, pp. 1056-1062, Apr 1994.

See also [radial_pf\(\)](#) (page 266).

pfsoln

pfsoln(baseMVA, bus0, gen0, branch0, Ybus, Yf, Yt, V, ref, pv, pq, mpopt)

pfsoln() - Updates bus, gen, branch data structures to match power flow soln.

```
[BUS, GEN, BRANCH] = PFSOLN(BASEMVA, BUS0, GEN0, BRANCH0, ...
                             YBUS, YF, YT, V, REF, PV, PQ, MPOPT)
```

radial_pf

radial_pf(mpc, mpopt)

radial_pf() (page 266) - Solves the power flow using a backward-forward sweep method.

```
[mpc, success, iterations] = radial_pf(mpc,mpopt)
```

Inputs:

mpc : MATPOWER **case struct** with internal bus numbering
mpopt : MATPOWER options **struct** to override default options
can be used to specify the solution algorithm, output options
termination tolerances, **and** more.

Outputs:

mpc : results **struct** with **all** fields from the **input** MATPOWER **case**,
with solved voltages, active **and** reactive **power** flows
and generator active **and** reactive **power** output.
success : success **flag**, 1 = succeeded, 0 = failed
iterations : number of iterations

See also caseformat, loadcase(), mpoption().

zgausspf

zgausspf(Ybus, Sbus, V0, ref, pv, pq, Bpp, mpopt)

zgausspf() - Solves the power flow using an Implicit Z-bus Gauss method.

```
[V, CONVERGED, I] = ZGAUSSPF(YBUS, SBUS, V0, REF, PV, PQ, BPP, MPOPT)
```

solves **for** bus voltages given the **full system** admittance matrix (**for** **all** buses), the **complex** bus **power** injection vector (**all** buses), the initial vector of **complex** bus voltages, column vectors with the lists of bus indices **for** the swing bus, PV buses, **and** PQ buses, respectively, **and** the fast-decoupled B **double-prime** matrix (**all** buses) **for** Q updates at PV buses. The bus voltage vector contains the **set** point **for** generator (including ref bus) buses, **and** the reference **angle** of the swing bus, as well as an initial guess **for** remaining magnitudes **and** angles. MPOPT is a MATPOWER options **struct** which can be used to **set** the termination tolerance, maximum number of iterations, **and** output options (see MPOPTION **for** details). Uses default options **if** this parameter is **not** given. Returns the final **complex** voltages,

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a **flag** which indicates whether it converged **or not**, **and** the number of iterations performed.

NOTE: This method does **not** scale well with the number of generators **and** seems to have serious problems with some systems with many PV buses.

See also `runpf()`.

5.2.5 Continuation Power Flow Functions

`cpf_corrector`

cpf_corrector(*Ybus, Sbusb, V_hat, ref, pv, pq, lam_hat, Sbusb, Vprv, lamprv, z, step, parameterization, mpopt*)
cpf_corrector() (page 267) - Solves the corrector step of a continuation power flow.

```
[V, CONVERGED, I, LAM] = CPF_CORRECTOR(YBUS, SBUSB, V_HAT, REF, PV, PQ, ...
                                       LAM_HAT, SBUST, VPRV, LPRV, Z, ...
                                       STEP, PARAMETERIZATION, MPOPT)
```

Computes the corrector step of a continuation **power** flow using a **full** Newton method with selected parameterization scheme.

Inputs:

YBUS : **complex** bus admittance matrix
 SBUSB : handle of **function** returning nb x 1 vector of **complex**
 base **case** injections in p.u. **and** derivatives w.r.t. |V|
 V_HAT : predicted **complex** bus voltage vector
 REF : vector of indices **for** REF buses
 PV : vector of indices of PV buses
 PQ : vector of indices of PQ buses
 LAM_HAT : predicted scalar lambda
 SBUST : handle of **function** returning nb x 1 vector of **complex**
 target **case** injections in p.u. **and** derivatives w.r.t. |V|
 VPRV : **complex** bus voltage vector at previous solution
 LAMPRV : scalar lambda value at previous solution
 STEP : continuation step **length**
 Z : normalized tangent prediction vector
 STEP : continuation step **size**
 PARAMETERIZATION : Value of `cpf.parameterization` option.
 MPOPT : Options **struct**

Outputs:

V : **complex** bus voltage solution vector
 CONVERGED : Newton iteration count
 I : Newton iteration count
 LAM : lambda continuation parameter

See also `runcpf()`.

cpf_current_mpc

cpf_current_mpc(mpc, mpct, Ybus, Yf, Yt, ref, pv, pq, V, lam, mpopt)

cpf_current_mpc() (page 268) - Construct mpc for current continuation step.

```
MPC = CPF_CURRENT_MPC(MPC_BASE, MPC_TARGET, YBUS, YF, YT, REF, PV, PQ, V, LAM,
↳ MPOPT)
```

Constructs the MATPOWER **case struct** for the current continuation step based on the MPC_BASE and MPC_TARGET cases and the value of LAM.

cpf_default_callback

cpf_default_callback(k, nx, cx, px, done, rollback, evnts, cb_data, cb_args, results)

cpf_default_callback() (page 268) - Default callback function for CPF.

```
[NX, CX, DONE, ROLLBACK, EVNTS, CB_DATA, RESULTS] =
  CPF_DEFAULT_CALLBACK(K, NX, CX, PX, DONE, ROLLBACK, EVNTS, ...
    CB_DATA, CB_ARGS, RESULTS)
```

Default callback **function** used by RUNCPF that collects the results and optionally, plots the nose curve. Inputs and outputs are defined below, with the RESULTS argument being optional, used only **for** the final call when K is negative.

Inputs:

- K - continuation step iteration count
- NX - next state (corresponding to proposed next step), **struct** with the following fields:
 - lam_hat - value of LAMBDA from predictor
 - V_hat - vector of **complex** bus voltages from predictor
 - lam - value of LAMBDA from corrector
 - V - vector of **complex** bus voltages from corrector
 - z - normalized tangent predictor
 - default_step - default step **size**
 - default_parm - default parameterization
 - this_step - step **size** **for** this step only
 - this_parm - parameterization **for** this step only
 - step - current step **size**
 - parm - current parameterization
 - events** - **struct** array, event **log**
 - cb - user state, **for** callbacks (replaces CB_STATE), the user may add fields containing **any** information the callback **function** would like to pass from one invocation to the next, taking care **not** to step on fields being used by other callbacks, such as the 'default' field used by this default callback
 - ef - **cell** array of event **function** values
- CX - current state (corresponding to most recent successful step)

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(same structure as NX)

PX - previous state (corresponding to last successful step prior to CX)

DONE - `struct`, with `flag` to indicate CPF termination and reason, with fields:

- `flag` - termination flag, 1 => terminate, 0 => continue
- `msg` - string containing reason for termination

ROLLBACK - scalar `flag` to indicate that the current step should be rolled back and retried with a different step size, etc.

EVNTS - `struct` array listing any events detected for this step, see CPF_DETECT_EVENTS for details

CB_DATA - `struct` containing potentially useful "static" data, with the following fields (all based on internal indexing):

- `mpc_base` - MATPOWER case struct of base state
- `mpc_target` - MATPOWER case struct of target state
- `Sbusb` - handle of function returning nb x 1 vector of complex base case injections in p.u. and derivatives w.r.t. |V|
- `Sbust` - handle of function returning nb x 1 vector of complex target case injections in p.u. and derivatives w.r.t. |V|
- `Ybus` - bus admittance matrix
- `Yf` - branch admittance matrix, "from" end of branches
- `Yt` - branch admittance matrix, "to" end of branches
- `pv` - vector of indices of PV buses
- `pq` - vector of indices of PQ buses
- `ref` - vector of indices of REF buses
- `idx_pmax` - vector of generator indices for generators fixed at their PMAX limits
- `mpopt` - MATPOWER options struct

CB_ARGS - arbitrary data structure containing callback arguments

RESULTS - initial value of output struct to be assigned to CPF field of results struct returned by RUNCPF

Outputs:

(all are updated versions of the corresponding input arguments)

NX - user state ('cb' field) should be updated here if ROLLBACK is false

CX - may contain updated 'this_step' or 'this_parm' values to be used if ROLLBACK is true

DONE - callback may have requested termination and set the msg field

ROLLBACK - callback can request a rollback step, even if it was not indicated by an event function

EVNTS - msg field for a given event may be updated

CB_DATA - this data should only be modified if the underlying problem has been changed (e.g. generator limit reached) and should always be followed by a step of zero length, i.e. set NX.this_step to 0. It is the job of any callback modifying CB_DATA to ensure that all data in CB_DATA is kept consistent.

RESULTS - updated version of RESULTS input arg

This function is called in three different contexts, distinguished by the value of K, as follows:

- (1) initial - called with K = 0, without RESULTS input/output args, after base power flow, before 1st CPF step.

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- (2) iterations - called with $K > 0$, without RESULTS input/output args, at each iteration, after predictor-corrector step
- (3) final - called with $K < 0$, with RESULTS input/output args, after exiting predictor-corrector loop, inputs identical to last iteration call, except K which is negated

User Defined CPF Callback Functions:

The user can define their own callback functions which take the same form and are called in the same contexts as CPF_DEFAULT_CALLBACK. These are specified via the MATPOWER option 'cpf.user_callback'. This option can be a string containing the name of the callback function, or a struct with the following fields, where all but the first are optional:

- 'fcn' - string with name of callback function
- 'priority' - numerical value specifying callback priority (default = 20, see CPF_REGISTER_CALLBACK for details)
- 'args' - arbitrary value (any type) passed to the callback as CB_ARGS each time it is invoked

Multiple user callbacks can be registered by assigning a cell array of such strings and/or structs to the 'cpf.user_callback' option.

See also `runcpf()`, `cpf_register_callback()` (page 276).

cpf_detect_events

cpf_detect_events(*cpf_events, cef, pef, step, verbose*)

cpf_detect_events() (page 270) - Detect events from event function values.

```
[ROLLBACK, CRITICAL_EVENTS, CEF] = CPF_DETECT_EVENTS(CPF_EVENTS, CEF, PEF, STEP, ↳
↳VERBOSE)
```

Inputs:

- CPF_EVENTS : struct containing info about registered CPF event fcns
- CEF : cell array of Current Event Function values
- PEF : cell array of Previous Event Function values
- STEP : current step size
- VERBOSE : 0 = no output, otherwise level of verbose output

Outputs:

- ROLLBACK : flag indicating whether any event has requested a rollback step
- CRITICAL_EVENTS : struct array containing information about any detected events, with fields:
 - eidx : event index, in list of registered events
0 if no event detected
 - name : name of event function, empty if none detected
 - zero : 1 if zero has been detected, 0 otherwise
(interval detected or no event detected)
 - idx : index(es) of critical elements in event function
 - step_scale : linearly interpolated estimate of scaling factor

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```

    for current step size required to reach event zero
log      : 1 log the event in the results, 0 don't log the event
          (set to 1 for zero events, 0 otherwise, can be
           modified by callbacks)
msg      : event message, set to something generic like
          'ZERO detected for TARGET_LAM event' or
          'INTERVAL detected for QLIM(3) event', but intended
          to be changed/updated by callbacks
CEF : cell array of Current Event Function values

```

cpf_flim_event

cpf_flim_event(*cb_data, cx*)

[cpf_flim_event\(\)](#) (page 271) - Event function to detect branch flow limit (MVA) violations.

```
EF = CPF_FLIM_EVENT(CB_DATA, CX)
```

CPF event **function** to detect branch flow limit (MVA) violations,
i.e. `max(Sf,St) >= SrateA`.

Inputs:

CB_DATA : **struct** of data **for** callback **functions**
CX : **struct** containing **info** about current point (continuation soln)

Outputs:

EF : event **function** value

cpf_flim_event_cb

cpf_flim_event_cb(*k, nx, cx, px, done, rollback, evnts, cb_data, cb_args, results*)

[cpf_flim_event_cb\(\)](#) (page 271) - Callback to handle FLIM events.

```

[NX, CX, DONE, ROLLBACK, EVNTS, CB_DATA, RESULTS] =
  CPF_NOSE_EVENT_CB(K, NX, CX, PX, DONE, ROLLBACK, EVNTS, ...
    CB_DATA, CB_ARGS, RESULTS)

```

Callback to handle FLIM (branch flow limit violation) **events**,
triggered by event **function** CPF_FLIM_EVENT to indicate the point at which
a branch flow limit is reached.

All branch flows are expected to be within limits **for** the base **case**,
otherwise the continuation terminates.

This **function** sets the msg field of the event when the flow in **any** branch
reaches its limit, raises the DONE.**flag** and sets the DONE.msg.

For details of the input and output arguments see also [cpf_default_callback\(\)](#) (page 268).

cpf_nose_event

cpf_nose_event(*cb_data, cx*)

[cpf_nose_event\(\)](#) (page 272) - Event function to detect the nose point.

```
EF = CPF_NOSE_EVENT(CB_DATA, CX)
```

CPF event **function** to detect the nose point of the continuation curve, based on the **sign** of the lambda component of the tangent vector.

Inputs:

CB_DATA : **struct** of data **for** callback **functions**

CX : **struct** containing **info** about current point (continuation soln)

Outputs:

EF : event **function** value

cpf_nose_event_cb

cpf_nose_event_cb(*k, nx, cx, px, done, rollback, evnts, cb_data, cb_args, results*)

[cpf_nose_event_cb\(\)](#) (page 272) - Callback to handle NOSE events.

```
[NX, CX, DONE, ROLLBACK, EVNTS, CB_DATA, RESULTS] =  
CPF_NOSE_EVENT_CB(K, NX, CX, PX, DONE, ROLLBACK, EVNTS, ...  
CB_DATA, CB_ARGS, RESULTS)
```

Callback to handle NOSE **events**, triggered by event **function** CPF_NOSE_EVENT to indicate the nose point of the continuation curve.

This **function** sets the msg field of the event when the nose point has been found, raises the DONE.**flag** and sets the DONE.msg.

For details of the input and output arguments see also [cpf_default_callback\(\)](#) (page 268).

cpf_p

cpf_p(*parameterization, step, z, V, lam, Vprv, lamprv, pv, pq*)

[cpf_p\(\)](#) (page 272) m - Computes the value of the CPF parameterization function.

```
P = CPF_P(PARAMETERIZATION, STEP, Z, V, LAM, VPRV, LAMPRV, PV, PQ)
```

Computes the value of the parameterization **function** at the current solution point.

Inputs:

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PARAMETERIZATION : Value of cpf.parameterization option
 STEP : continuation step **size**
 Z : normalized tangent prediction vector from previous step
 V : **complex** bus voltage vector at current solution
 LAM : scalar lambda value at current solution
 VPRV : **complex** bus voltage vector at previous solution
 LAMPRV : scalar lambda value at previous solution
 PV : vector of indices of PV buses
 PQ : vector of indices of PQ buses

Outputs:

P : value of the parameterization **function** at the current point

See also [cpf_predictor\(\)](#) (page 274), [cpf_corrector\(\)](#) (page 267).

cpf_p_jac

cpf_p_jac(parameterization, z, V, lam, Vprv, lamprv, pv, pq)

[cpf_p_jac\(\)](#) (page 273) - Computes partial derivatives of CPF parameterization function.

```
[DP_DV, DP_DLAM ] = CPF_P_JAC(PARAMETERIZATION, Z, V, LAM, ...
                               VPRV, LAMPRV, PV, PQ)
```

Computes the partial derivatives of the continuation **power** flow parameterization **function** w.r.t. bus voltages **and** the continuation parameter lambda.

Inputs:

PARAMETERIZATION : Value of cpf.parameterization option.
 Z : normalized tangent prediction vector from previous step
 V : **complex** bus voltage vector at current solution
 LAM : scalar lambda value at current solution
 VPRV : **complex** bus voltage vector at previous solution
 LAMPRV : scalar lambda value at previous solution
 PV : vector of indices of PV buses
 PQ : vector of indices of PQ buses

Outputs:

DP_DV : partial of parameterization **function** w.r.t. voltages
 DP_DLAM : partial of parameterization **function** w.r.t. lambda

See also [cpf_predictor\(\)](#) (page 274), [cpf_corrector\(\)](#) (page 267).

cpf_plim_event

cpf_plim_event(*cb_data, cx*)

[cpf_plim_event\(\)](#) (page 274) - Event function to detect gen active power limit violations.

```
EF = CPF_PLIM_EVENT(CB_DATA, CX)
```

CPF event **function** to detect generator active **power** limit violations, i.e. $P_g \geq P_{max}$.

Inputs:

CB_DATA : **struct** of data **for** callback **functions**
CX : **struct** containing **info** about current point (continuation soln)

Outputs:

EF : event **function** value

cpf_plim_event_cb

cpf_plim_event_cb(*k, nx, cx, px, done, rollback, evnts, cb_data, cb_args, results*)

[cpf_plim_event_cb\(\)](#) (page 274) - Callback to handle PLIM events.

```
[NX, CX, DONE, ROLLBACK, EVNTS, CB_DATA, RESULTS] =  
CPF_PLIM_EVENT_CB(K, NX, CX, PX, DONE, ROLLBACK, EVNTS, ...  
CB_DATA, CB_ARGS, RESULTS)
```

Callback to handle PLIM (generator active **power** limit violation) **events**, triggered by event **function** CPF_PLIM_EVENT to indicate the point at which an **upper** active **power** output limit is reached **for** a generator.

When an active **power** limit is encountered, this **function** **zeros** out subsequent transfers from that generator, chooses a new reference bus **if** necessary, **and** updates the CB_DATA accordingly, setting the next step **size** to zero. The event msg is updated with the details of the changes. It also requests termination **if all** generators reach PMAX.

For details of the input and output arguments see also [cpf_default_callback\(\)](#) (page 268).

cpf_predictor

cpf_predictor(*V, lam, z, step, pv, pq*)

[cpf_predictor\(\)](#) (page 274) - Performs the predictor step for the continuation power flow.

```
[V_HAT, LAM_HAT] = CPF_PREDICTOR(V, LAM, Z, STEP, PV, PQ)
```

Computes a prediction (approximation) to the next solution of the continuation **power** flow using a normalized tangent predictor.

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Inputs:

V : **complex** bus voltage vector at current solution
 LAM : scalar lambda value at current solution
 Z : normalized tangent prediction vector from previous step
 STEP : continuation step **length**
 PV : vector of indices of PV buses
 PQ : vector of indices of PQ buses

Outputs:

V_HAT : predicted **complex** bus voltage vector
 LAM_HAT : predicted lambda continuation parameter

cpf_qlim_event**cpf_qlim_event**(*cb_data, cx*)*cpf_qlim_event()* (page 275) - Event function to detect gen reactive power limit violations.

EF = CPF_QLIM_EVENT(CB_DATA, CX)

CPF event **function** to detect generator reactive **power** limit violations,
 i.e. $Q_g \leq Q_{min}$ or $Q_g \geq Q_{max}$.

Inputs:

CB_DATA : **struct** of data **for** callback **functions**
 CX : **struct** containing **info** about current point (continuation soln)

Outputs:

EF : event **function** value

cpf_qlim_event_cb**cpf_qlim_event_cb**(*k, nx, cx, px, done, rollback, evnts, cb_data, cb_args, results*)*cpf_qlim_event_cb()* (page 275) - Callback to handle QLIM events.

```
[NX, CX, DONE, ROLLBACK, EVNTS, CB_DATA, RESULTS] =
  CPF_QLIM_EVENT_CB(K, NX, CX, PX, DONE, ROLLBACK, EVNTS, ...
    CB_DATA, CB_ARGS, RESULTS)
```

Callback to handle QLIM (generator reactive **power** limit violation) **events**,
 triggered by event **function** CPF_QLIM_EVENT to indicate the point at which
 an **upper** or **lower** reactive **power** output limit is reached **for** a generator.

When a reactive **power** limit is encountered, this **function** **zeros** out
 subsequent transfers from that generator, changes it's bus **type** to PQ,
 chooses a new reference bus **if** necessary, **and** updates the CB_DATA
 accordingly, setting the next step **size** to zero. The event msg is updated

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with the details of the changes. It also requests termination **if** no more PV or REF buses remain.

For details of the input and output arguments see also `cpf_default_callback()` (page 268).

cpf_register_callback

cpf_register_callback(*cpf_callbacks*, *fcn*, *priority*, *args*)

`cpf_register_callback()` (page 276) - Register CPF callback functions.

```
CPF_CALLBACKS = CPF_REGISTER_CALLBACK(CPF_CALLBACKS, FCN, PRIORITY)
```

Registers a CPF callback **function** to be called by RUNCPF.

Inputs:

CPF_CALLBACKS : **struct** containing **info** about registered CPF callback fcns
 FCN : string containing name of callback **function**
 PRIORITY : number that determines order of execution **for** multiple callback **functions**, where higher numbers **run** first, default priority is **20**, where the standard callbacks are called with the following priority:

cpf_flim_event_cb	53
cpf_vlim_event_cb	52
cpf_nose_event_cb	51
cpf_target_lam_event_cb	50
cpf_qlim_event_cb	41
cpf_plim_event_cb	40
cpf_default_callback	0

ARGS : arguments to be passed to the callback each **time** it is invoked

Outputs:

CPF_CALLBACKS : updated **struct** containing **info** about registered CPF callback fcns

User Defined CPF Callback Functions:

The user can define their own callback **functions** which take the same form **and** are called in the same contexts as CPF_DEFAULT_CALLBACK. These are specified via the MATPOWER option '`cpf.user_callback`'. This option can be a string containing the name of the callback **function**, or a **struct** with the following fields, where **all** but the first are optional:

- 'fcn' - string with name of callback **function**
- 'priority' - numerical value specifying callback priority (default = **20**, see CPF_REGISTER_CALLBACK **for** details)
- 'args' - arbitrary value (**any type**) passed to the callback as CB_ARGS each **time** it is invoked

Multiple user callbacks can be registered by assigning a **cell** array of such strings **and/or** structs to the '`cpf.user_callback`' option.

See also `runcpf()`, `cpf_default_callback()` (page 268).

cpf_register_event

cpf_register_event(*cpf_events, name, fcn, tol, locate*)

cpf_register_event() (page 277) - Register event functions.

```
CPF_EVENTS = CPF_REGISTER_EVENT(CPF_EVENTS, NAME, FCN, TOL, LOCATE)
```

Registers a CPF event **function** to be called by RUNCPF.

Inputs:

CPF_EVENTS : **struct** containing **info** about registered CPF event fcns
NAME : string containing event name
FCN : string containing name of event **function**, returning numerical scalar **or** vector value that changes **sign** at location of the event
TOL : scalar **or** vector of same dimension as event **function return** value of tolerance **for** detecting the event, i.e. **abs**(val) <= tol
LOCATE : **flag** indicating whether the event requests a rollback step to locate the event **function** zero

Outputs:

CPF_EVENTS : updated **struct** containing **info** about registered CPF event fcns

cpf_tangent

cpf_tangent(*V, lam, Ybus, Sbusb, Sbust, pv, pq, zprv, Vprv, lamprv, parameterization, direction*)

cpf_tangent() (page 277) - Computes normalized tangent predictor for continuation power flow.

```
Z = CPF_TANGENT(V, LAM, YBUS, SBUSB, SBUST, PV, PQ, ...  
                ZPRV, VPRV, LAMPRV, PARAMETERIZATION, DIRECTION)
```

Computes a normalized tangent predictor **for** the continuation **power** flow.

Inputs:

V : **complex** bus voltage vector at current solution
LAM : scalar lambda value at current solution
YBUS : **complex** bus admittance matrix
SBUSB : handle of **function** returning nb x 1 vector of **complex** base **case** injections in p.u. **and** derivatives w.r.t. |V|
SBUST : handle of **function** returning nb x 1 vector of **complex** target **case** injections in p.u. **and** derivatives w.r.t. |V|
PV : vector of indices of PV buses
PQ : vector of indices of PQ buses
ZPRV : normalized tangent prediction vector from previous step
VPRV : **complex** bus voltage vector at previous solution
LAMPRV : scalar lambda value at previous solution
PARAMETERIZATION : value of cpf.parameterization option.
DIRECTION: continuation direction (+1 **for** postive lambda increase, -1 **otherwise**)

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Outputs:

Z : the normalized tangent prediction vector

cpf_target_lam_event

cpf_target_lam_event(*cb_data, cx*)*cpf_target_lam_event()* (page 278) - Event function to detect a target lambda value.

EF = CPF_TARGET_LAM_EVENT(CB_DATA, CX)

CPF event **function** to detect the completion of the continuation curve
or another target value of lambda.

Inputs:

CB_DATA : **struct** of data **for** callback **functions**CX : **struct** containing **info** about current point (continuation soln)

Outputs:

EF : event **function** value

cpf_target_lam_event_cb

cpf_target_lam_event_cb(*k, nx, cx, px, done, rollback, evnts, cb_data, cb_args, results*)*cpf_target_lam_event_cb()* (page 278) - Callback to handle TARGET_LAM events.[NX, CX, DONE, ROLLBACK, EVNTS, CB_DATA, RESULTS] =
CPF_TARGET_LAM_EVENT_CB(K, NX, CX, PX, DONE, ROLLBACK, EVNTS, ...
CB_DATA, CB_ARGS, RESULTS)Callback to handle TARGET_LAM **events**, triggered by event **function**
CPF_TARGET_LAM_EVENT to indicate that a target lambda value has been
reached or that the **full** continuation curve has been traced.This **function** sets the msg field of the event when the target lambda has
been found, raises the DONE.**flag** and sets the DONE.msg. If the current
or predicted next step overshoot the target lambda, it adjusts the step
size to be exactly **what** is needed to reach the target, and sets the
parameterization **for** that step to be the natural parameterization.For details of the input and output arguments see also *cpf_default_callback()* (page 268).

cpf_vlim_event

cpf_vlim_event(*cb_data, cx*)

[cpf_vlim_event\(\)](#) (page 279) - Event function to detect bus voltage limit violations.

```
EF = CPF_VLIM_EVENT(CB_DATA, CX)
```

CPF event **function** to detect bus voltage limits violations,
i.e. $V_m \leq V_{min}$ or $V_m \geq V_{max}$.

Inputs:

CB_DATA : **struct** of data **for** callback **functions**
CX : **struct** containing **info** about current point (continuation soln)

Outputs:

EF : event **function** value

cpf_vlim_event_cb

cpf_vlim_event_cb(*k, nx, cx, px, done, rollback, evnts, cb_data, cb_args, results*)

[cpf_vlim_event_cb\(\)](#) (page 279) - Callback to handle VLIM events.

```
[NX, CX, DONE, ROLLBACK, EVNTS, CB_DATA, RESULTS] =  
CPF_VLIM_EVENT_CB(K, NX, CX, PX, DONE, ROLLBACK, EVNTS, ...  
CB_DATA, CB_ARGS, RESULTS)
```

Callback to handle VLIM (bus voltage magnitude limit violation) **events**,
triggered by event **function** CPF_VLIM_EVENT to indicate the point at which
an **upper or lower** voltage magnitude limit is reached **for** a bus.

All bus voltages are expected to be within limits **for** the base **case**,
otherwise the continuation terminates.

This **function** sets the msg field of the event when the voltage magnitude
at **any** bus reaches its **upper or lower** limit, raises the DONE.flag and sets
the DONE.msg.

For details of the input and output arguments see also [cpf_default_callback\(\)](#) (page 268).

5.2.6 OPF and Wrapper Functions

opf**opf**(varargin)

opf() - Solves an optimal power flow.

```
[RESULTS, SUCCESS] = OPF(MPC, MPOPT)
```

Returns either a RESULTS **struct** and an optional SUCCESS **flag**, or individual data matrices, the objective **function** value and a SUCCESS **flag**. In the latter **case**, there are additional optional **return** values. See Examples below **for** the possible calling syntax options.

Examples:

Output argument options:

```
results = opf(...)
[results, success] = opf(...)
[bus, gen, branch, f, success] = opf(...)
[bus, gen, branch, f, success, info, et, g, jac, xr, pimul] = opf(...)
```

Input arguments options:

```
opf(mpc)
opf(mpc, mpopt)
opf(mpc, userfcn, mpopt)
opf(mpc, A, l, u)
opf(mpc, A, l, u, mpopt)
opf(mpc, A, l, u, mpopt, N, fparm, H, Cw)
opf(mpc, A, l, u, mpopt, N, fparm, H, Cw, z0, zl, zu)

opf(baseMVA, bus, gen, branch, areas, gencost)
opf(baseMVA, bus, gen, branch, areas, gencost, mpopt)
opf(baseMVA, bus, gen, branch, areas, gencost, userfcn, mpopt)
opf(baseMVA, bus, gen, branch, areas, gencost, A, l, u)
opf(baseMVA, bus, gen, branch, areas, gencost, A, l, u, mpopt)
opf(baseMVA, bus, gen, branch, areas, gencost, A, l, u, ...
    mpopt, N, fparm, H, Cw)
opf(baseMVA, bus, gen, branch, areas, gencost, A, l, u, ...
    mpopt, N, fparm, H, Cw, z0, zl, zu)
```

The data **for** the problem can be specified in one of three ways:

- (1) a string (mpc) containing the file name of a MATPOWER **case** which defines the data matrices baseMVA, bus, gen, branch, and gencost (areas is **not** used at **all**, it is only included **for** backward compatibility of the API).
- (2) a **struct** (mpc) containing the data matrices as fields.
- (3) the individual data matrices themselves.

The optional user parameters **for** user constraints (A, l, u), user costs (N, fparm, H, Cw), user variable initializer (z0), and user variable limits (zl, zu) can also be specified as fields in a **case struct**, either passed in directly or defined in a **case** file referenced by name.

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When specified, A , l , u represent additional linear constraints on the optimization variables, $l \leq A[x; z] \leq u$. If the user specifies an A matrix that has more columns than the number of "x" (OPF) variables, then there are extra linearly constrained "z" variables. For an explanation of the formulation used and instructions for forming the A matrix, see the manual.

A generalized cost on all variables can be applied if input arguments N , $fparm$, H and Cw are specified. First, a linear transformation of the optimization variables is defined by means of $r = N * [x; z]$. Then, to each element of r a function is applied as encoded in the $fparm$ matrix (see manual). If the resulting vector is named w , then H and Cw define a quadratic cost on w : $(1/2)*w'*H*w + Cw * w$. H and N should be sparse matrices and H should also be symmetric.

The optional `mpopt` vector specifies MATPOWER options. If the OPF algorithm is not explicitly set in the options MATPOWER will use the default solver, based on a primal-dual interior point method. For the AC OPF this is `opf.ac.solver = 'MIPS'`, unless the TSPOPF optional package is installed, in which case the default is `'PDIPM'`. For the DC OPF, the default is `opf.dc.solver = 'MIPS'`. See `MPOPTION` for more details on the available OPF solvers and other OPF options and their default values.

The solved case is returned either in a single results struct (described below) or in the individual data matrices, `bus`, `gen` and `branch`. Also returned are the final objective function value (`f`) and a flag which is true if the algorithm was successful in finding a solution (success). Additional optional return values are an algorithm specific return status (`info`), elapsed time in seconds (`et`), the constraint vector (`g`), the Jacobian matrix (`jac`), and the vector of variables (`xr`) as well as the constraint multipliers (`pimul`).

The single results struct is a MATPOWER case struct (`mpc`) with the usual `baseMVA`, `bus`, `branch`, `gen`, `gencost` fields, along with the following additional fields:

```
.order      see 'help ext2int' for details of this field
.et         elapsed time in seconds for solving OPF
.success    1 if solver converged successfully, 0 otherwise
.om         OPF model object, see 'help opf_model'
.x          final value of optimization variables (internal order)
.f          final objective function value
.mu         shadow prices on ...
  .var
    .l      lower bounds on variables
    .u      upper bounds on variables
  .nl
    .l      lower bounds on nonlinear constraints
    .u      upper bounds on nonlinear constraints
  .lin
    .l      lower bounds on linear constraints
```

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```

        .u  upper bounds on linear constraints
.raw      raw solver output in form returned by MINOS, and more
.xr       final value of optimization variables
.pimul    constraint multipliers
.info     solver specific termination code
.output   solver specific output information
        .alg algorithm code of solver used
.g        (optional) constraint values
.dg       (optional) constraint 1st derivatives
.df       (optional) obj fun 1st derivatives (not yet implemented)
.d2f      (optional) obj fun 2nd derivatives (not yet implemented)
.var
        .val optimization variable values, by named block
            .Va voltage angles
            .Vm voltage magnitudes (AC only)
            .Pg real power injections
            .Qg reactive power injections (AC only)
            .y constrained cost variable (only if have pwl costs)
            (other) any user defined variable blocks
        .mu variable bound shadow prices, by named block
            .l lower bound shadow prices
                .Va, Vm, Pg, Qg, y, (other)
            .u upper bound shadow prices
                .Va, Vm, Pg, Qg, y, (other)
        .nle (AC only)
            .lambda shadow prices on nonlinear equality constraints,
                by named block
                .Pmis real power mismatch equations
                .Qmis reactive power mismatch equations
                (other) use defined constraints
        .nli (AC only)
            .mu shadow prices on nonlinear inequality constraints,
                by named block
                .Sf flow limits at "from" end of branches
                .St flow limits at "to" end of branches
                (other) use defined constraints
        .lin
            .mu shadow prices on linear constraints, by named block
                .l lower bounds
                .Pmis real power mismatch equations (DC only)
                .Pf flow limits at "from" end of branches (DC only)
                .Pt flow limits at "to" end of branches (DC only)
                .PQh upper portion of gen PQ-capability curve (AC only)
                .PQl lower portion of gen PQ-capability curve (AC only)
                .vl constant power factor constraint for loads (AC only)
                .ycon basin constraints for CCV for pwl costs
                (other) any user defined constraint blocks
            .u upper bounds
                .Pmis, Pf, Pt, PQh, PQl, vl, ycon, (other)
        .cost user defined cost values, by named block

```

See also `runopf()`, `dcopf()`, `uopf()`, `caseformat`.

dcopf

dcopf(*varargin*)

dcopf() - Solves a DC optimal power flow.

This is a simple wrapper function around **opf**() that sets the `model` option to 'DC' before calling **opf**(). See **opf**() for the details of input and output arguments.

See also **rundcopf**().

fmincopf

fmincopf(*varargin*)

fmincopf() - Solves an AC optimal power flow using FMINCON (Opt Tbx 2.x & later).

Uses algorithm 520. Please see **opf**() for the details of input and output arguments.

uopf

uopf(*varargin*)

uopf() - Solves combined unit decommitment / optimal power flow.

```
[RESULTS, SUCCESS] = UOPF(MPC, MPOPT)
```

Returns either a **RESULTS struct** and an optional **SUCCESS flag**, or individual data matrices, the objective **function** value and a **SUCCESS flag**. In the latter **case**, there are additional optional **return** values. See Examples below **for** the possible calling syntax options.

Examples:

Output argument options:

```
results = uopf(...)
```

```
[results, success] = uopf(...)
```

```
[bus, gen, branch, f, success] = uopf(...)
```

```
[bus, gen, branch, f, success, info, et, g, jac, xr, pimul] = uopf(...)
```

Input arguments options:

```
uopf(mpc)
```

```
uopf(mpc, mpopt)
```

```
uopf(mpc, userfcn, mpopt)
```

```
uopf(mpc, A, l, u)
```

```
uopf(mpc, A, l, u, mpopt)
```

```
uopf(mpc, A, l, u, mpopt, N, fparm, H, Cw)
```

```
uopf(mpc, A, l, u, mpopt, N, fparm, H, Cw, z0, z1, zu)
```

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```

uopf(baseMVA, bus, gen, branch, areas, gencost)
uopf(baseMVA, bus, gen, branch, areas, gencost, mpopt)
uopf(baseMVA, bus, gen, branch, areas, gencost, userfcn, mpopt)
uopf(baseMVA, bus, gen, branch, areas, gencost, A, l, u)
uopf(baseMVA, bus, gen, branch, areas, gencost, A, l, u, mpopt)
uopf(baseMVA, bus, gen, branch, areas, gencost, A, l, u, ...
      mpopt, N, fparm, H, Cw)
uopf(baseMVA, bus, gen, branch, areas, gencost, A, l, u, ...
      mpopt, N, fparm, H, Cw, z0, z1, zu)

```

See OPF **for** more information on **input** and **output** arguments.

Solves a combined unit decommitment **and** optimal **power** flow **for** a **single** **time** period. Uses an algorithm similar to dynamic programming. It proceeds through a sequence of stages, where stage N has N generators shut down, starting with N=0. In each stage, it forms a list of candidates (gens at their Pmin limits) **and** computes the cost with each one of them shut down. It selects the least cost **case** as the starting point **for** the next stage, continuing **until** there are no more candidates to be shut down **or** no more improvement can be gained by shutting something down. If MPOPT.verbose (see MPOPTION) is **true**, it prints progress **info**, **if** it is > 1 it prints the output of each individual opf.

See also opf(), runuopf().

5.2.7 Other OPF Functions

dcopf_solver

dcopf_solver(om, mpopt)

dcopf_solver() (page 284) - Solves a DC optimal power flow.

```
[RESULTS, SUCCESS, RAW] = DCOPF_SOLVER(OM, MPOPT)
```

Inputs are an OPF model object **and** a MATPOWER options **struct**.

Outputs are a RESULTS **struct**, SUCCESS **flag** **and** RAW output **struct**.

RESULTS is a MATPOWER **case struct** (mpc) with the usual baseMVA, bus branch, gen, gencost fields, along with the following additional fields:

.order	see 'help ext2int' for details of this field
.x	final value of optimization variables (internal order)
.f	final objective function value
.mu	shadow prices on ...
.var	
.l	lower bounds on variables
.u	upper bounds on variables

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```

        .lin
            .l lower bounds on linear constraints
            .u upper bounds on linear constraints

SUCCESS    1 if solver converged successfully, 0 otherwise

RAW        raw output in form returned by MINOS
        .xr    final value of optimization variables
        .pimul constraint multipliers
        .info  solver specific termination code
        .output solver specific output information

```

See also `opf()`, `opt_model.solve()`.

nlpopf_solver

nlpopf_solver(*om*, *mpopt*)

nlpopf_solver() (page 285) - Solves AC optimal power flow using MP-Opt-Model.

```

[RESULTS, SUCCESS, RAW] = NLPopf_SOLVER(OM, MPOPT)

Inputs are an OPF model object and a MATPOWER options struct.

Outputs are a RESULTS struct, SUCCESS flag and RAW output struct.

RESULTS is a MATPOWER case struct (mpc) with the usual baseMVA, bus
branch, gen, gencost fields, along with the following additional
fields:
        .order    see 'help ext2int' for details of this field
        .x        final value of optimization variables (internal order)
        .f        final objective function value
        .mu       shadow prices on ...
        .var
            .l lower bounds on variables
            .u upper bounds on variables
        .nln      (deprecated) 2*nb+2*nl - Pmis, Qmis, Sf, St
            .l lower bounds on nonlinear constraints
            .u upper bounds on nonlinear constraints
        .nle      nonlinear equality constraints
        .nli      nonlinear inequality constraints
        .lin
            .l lower bounds on linear constraints
            .u upper bounds on linear constraints

SUCCESS    1 if solver converged successfully, 0 otherwise

RAW        raw output in form returned by MINOS
        .xr    final value of optimization variables
        .pimul constraint multipliers

```

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```
.info solver specific termination code
.output solver specific output information
```

See also `opf()`, `mips()`.

makeAang

makeAang(*baseMVA*, *branch*, *nb*, *mpopt*)

makeAang() (page 286) - Construct constraints for branch angle difference limits.

```
[AANG, LANG, UANG, IANG] = MAKEAANG(BASEMVA, BRANCH, NB, MPOPT)
```

Constructs the parameters **for** the following linear constraint limiting the voltage **angle** differences across branches, where *Va* is the vector of bus voltage angles. NB is the number of buses.

$$LANG \leq AANG * Va \leq UANG$$

IAANG is the vector of indices of branches with **angle** difference limits. The limits are given in the ANGMIN and ANGMAX columns of the branch matrix. Voltage **angle** differences are taken to be unbounded below **if** ANGMIN < -360 and unbounded above **if** ANGMAX > 360. If both ANGMIN and ANGMAX are zero, the **angle** difference is assumed to be unconstrained.

Example:

```
[Aang, lang, uang, iang] = makeAang(baseMVA, branch, nb, mpopt);
```

makeApq

makeApq(*baseMVA*, *gen*)

makeApq() (page 286) - Construct linear constraints for generator capability curves.

```
[APQH, UBPQH, APQL, UBPQL, DATA] = MAKEAPQ(BASEMVA, GEN)
```

Constructs the parameters **for** the following linear constraints implementing trapezoidal generator capability curves, where *Pg* and *Qg* are the **real** and **reactive** generator injections.

$$APQH * [Pg; Qg] \leq UBPQH$$

$$APQL * [Pg; Qg] \leq UBPQL$$

DATA contains additional information as shown below.

Example:

```
[Apqh, ubpqh, Apql, ubpql, data] = makeApq(baseMVA, gen);
```

```
data.h      [QC1MAX-QC2MAX, PC2-PC1]
```

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data.l	[QC2MIN-QC1MIN, PC1-PC2]
data.ipqh	indices of gens with general PQ cap curves (upper)
data.ipql	indices of gens with general PQ cap curves (lower)

makeAvl

makeAvl(baseMVA, gen)*makeAvl*() (page 287) - Construct linear constraints for constant power factor var loads.

```
[AVL, LVL, UVL, IVL] = MAKEAVL(MPC)
[AVL, LVL, UVL, IVL] = MAKEAVL(BASEMVA, GEN) (deprecated)
```

Constructs parameters **for** the following linear constraint enforcing a constant **power factor** constraint **for** dispatchable loads.

$$LVL \leq AVL * [Pg; Qg] \leq UVL$$

IVL is the vector of indices of generators representing variable loads.

Example:

```
[Avl, lvl, uvl, ivl] = makeAvl(mpc);
[Avl, lvl, uvl, ivl] = makeAvl(baseMVA, gen); %% deprecated
```

makeAy

makeAy(baseMVA, ng, gencost, pgbas, qgbas, ybas)*makeAy*() (page 287) - Make the A matrix and RHS for the CCV formulation.

```
[AY, BY] = MAKEAY(BASEMVA, NG, GENCOST, PGBAS, QGBAS, YBAS)
```

Constructs the parameters **for** linear "**basin constraints**" on Pg, Qg and Y used by the CCV cost formulation, expressed as

$$AY * X \leq BY$$

where X is the vector of optimization variables. The starting **index** within the X vector **for** the active, reactive sources and the Y variables should be provided in arguments PGBAS, QGBAS, YBAS. The number of generators is NG.

Assumptions: All generators are in-service. Filter **any** generators that are offline from the GENCOST matrix before calling MAKEAY. Efficiency depends on Qg variables being after Pg variables, and the Y variables must be the last variables within the vector X **for** the dimensions of the resulting AY to be conformable with X.

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Example:

```
[Ay, by] = makeAy(baseMVA, ng, gencost, pgbas, qgbas, ybas);
```

margcost

margcost(*gencost*, *Pg*)

margcost() - Computes marginal cost for generators at given output level.

MARGINALCOST = MARGCOST(GENCOST, PG) computes marginal cost **for** generators given a matrix in gencost format **and** a column vector of generation levels. The **return** value has the same dimensions as PG. Each row of GENCOST is used to evaluate the cost at the points specified in the corresponding row of PG.

opf_args

opf_args(*baseMVA*, *bus*, *gen*, *branch*, *areas*, *gencost*, *Au*, *lbu*, *ubu*, *mpopt*, *N*, *fparm*, *H*, *Cw*, *z0*, *zl*, *zu*)

opf_args() (page 288) - Parses and initializes OPF input arguments.

```
[MPC, MPOPT] = OPF_ARGS( ... )
[BASEMVA, BUS, GEN, BRANCH, GENCOST, A, L, U, MPOPT, ...
 N, FPARM, H, CW, Z0, ZL, ZU, USERFCN] = OPF_ARGS( ... )
```

Returns the **full set** of initialized OPF **input** arguments, filling in default values **for** missing arguments. See Examples below **for** the possible calling syntax options.

Examples:

Output argument options:

```
[mpc, mpopt] = opf_args( ... )
[baseMVA, bus, gen, branch, gencost, A, l, u, mpopt, ...
 N, fparm, H, Cw, z0, zl, zu, userfcn] = opf_args( ... )
```

Input arguments options:

```
opf_args(mpc)
opf_args(mpc, mpopt)
opf_args(mpc, userfcn, mpopt)
opf_args(mpc, A, l, u)
opf_args(mpc, A, l, u, mpopt)
opf_args(mpc, A, l, u, mpopt, N, fparm, H, Cw)
opf_args(mpc, A, l, u, mpopt, N, fparm, H, Cw, z0, zl, zu)

opf_args(baseMVA, bus, gen, branch, areas, gencost)
opf_args(baseMVA, bus, gen, branch, areas, gencost, mpopt)
opf_args(baseMVA, bus, gen, branch, areas, gencost, userfcn, mpopt)
opf_args(baseMVA, bus, gen, branch, areas, gencost, A, l, u)
```

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```

opf_args(baseMVA, bus, gen, branch, areas, gencost, A, l, u, mpop)
opf_args(baseMVA, bus, gen, branch, areas, gencost, A, l, u, ...
        mpop, N, fparm, H, Cw)
opf_args(baseMVA, bus, gen, branch, areas, gencost, A, l, u, ...
        mpop, N, fparm, H, Cw, z0, zl, zu)

```

The data **for** the problem can be specified in one of three ways:

- (1) a string (*mpc*) containing the file name of a MATPOWER **case** which defines the data matrices *baseMVA*, *bus*, *gen*, *branch*, and *gencost* (*areas* is **not** used at **all**, it is only included **for** backward compatibility of the API).
- (2) a **struct** (*mpc*) containing the data matrices as fields.
- (3) the individual data matrices themselves.

The optional user parameters **for** user constraints (*A*, *l*, *u*), user costs (*N*, *fparm*, *H*, *Cw*), user variable initializer (*z0*), and user variable limits (*zl*, *zu*) can also be specified as fields in a **case struct**, either passed in directly or defined in a **case** file referenced by name.

When specified, *A*, *l*, *u* represent additional linear constraints on the optimization variables, $l \leq A[x; z] \leq u$. If the user specifies an *A* matrix that has more **columns** than the number of "*x*" (OPF) variables, then there are extra linearly constrained "*z*" variables. For an explanation of the formulation used and instructions **for** forming the *A* matrix, see the manual.

A generalized cost on **all** variables can be applied **if** input arguments *N*, *fparm*, *H* and *Cw* are specified. First, a linear transformation of the optimization variables is defined by means of $r = N * [x; z]$. Then, to each element of *r* a **function** is applied as encoded in the *fparm* matrix (see manual). If the resulting vector is named *w*, then *H* and *Cw* define a quadratic cost on *w*: $(1/2)*w'*H*w + Cw * w$. *H* and *N* should be **sparse** matrices and *H* should also be symmetric.

The optional *mpopt* vector specifies MATPOWER options. See **MPOPTION** **for** details and default values.

opf_setup

opf_setup(*mpc*, *mpopt*)

opf_setup() (page 289) - Constructs an OPF model object from a MATPOWER case struct.

```
OM = OPF_SETUP(MPC, MPOPT)
```

Assumes that *MPC* is a MATPOWER **case struct** with internal indexing, **all** equipment in-service, etc.

See also *opf*(), *ext2int*(), *opf_execute*() (page 290).

opf_execute

opf_execute(*om*, *mpopt*)

[opf_execute\(\)](#) (page 290) - Executes the OPF specified by an OPF model object.

```
[RESULTS, SUCCESS, RAW] = OPF_EXECUTE(OM, MPOPT)
```

RESULTS are returned with internal indexing, **all** equipment in-service, etc.

See also [opf\(\)](#), [opf_setup\(\)](#) (page 289).

opf_branch_ang_fcn

opf_branch_ang_fcn(*x*, *Aang*, *lang*, *uang*)

[opf_branch_ang_fcn\(\)](#) (page 290) - Evaluates branch angle difference constraints and gradients.

```
[VADIF, DVADIF] = OPF_BRANCH_ANG_FCN(X, AANG, LANG, UANG);
```

Computes the **lower** and **upper** constraints on branch **angle** differences **for** voltages in cartesian coordinates. Computes constraint vectors **and** their gradients. The constraints are of the form:

$Aang * Va \geq lang$

$Aang * Va \leq uang$

where Va is the voltage **angle**, a non-linear **function** of the Vr **and** Vi .

Inputs:

X : optimization vector

AANG : constraint matrix, see MAKEAANG

LANG : **lower** bound vector, see MAKEAANG

UANG : **upper** bound vector, see MAKEAANG

Outputs:

VADIF : constraint vector [$lang - Aang * Va$; $Aang * Va - uang$]

DVADIF : (optional) constraint gradients

Examples:

VaDif = opf_branch_ang_fcn(x, Aang, lang, uang);

[VaDif, dVaDif] = opf_branch_ang_fcn(x, Aang, lang, uang);

See also [opf_branch_ang_hess\(\)](#) (page 291).

opf_branch_ang_hess

opf_branch_ang_hess(*x, lambda, Aang, lang, uang*)

[opf_branch_ang_hess\(\)](#) (page 291) - Evaluates Hessian of branch angle difference constraints.

```
D2VADIF = OPF_BRANCH_ANG_HESS(X, LAMBDA, AANG, LANG, UANG)
```

Hessian evaluation **function for** branch **angle** difference constraints
for voltages in cartesian coordinates.

Inputs:

X : optimization vector
LAMBDA : column vector of Lagrange multipliers on branch **angle**
 difference constraints, **lower**, then **upper**
AANG : constraint matrix, see MAKEAANG
LANG : **lower** bound vector, see MAKEAANG
UANG : **upper** bound vector, see MAKEAANG

Outputs:

D2VADIF : Hessian of branch **angle** difference constraints.

Example:

```
d2VaDif = opf_branch_ang_hess(x, lambda, Aang, lang, uang);
```

See also [opf_branch_ang_fcn\(\)](#) (page 290).

opf_branch_flow_fcn

opf_branch_flow_fcn(*x, mpc, Yf, Yt, il, mpopt*)

[opf_branch_flow_fcn\(\)](#) (page 291) - Evaluates AC branch flow constraints and Jacobian.

```
[H, DH] = OPF_BRANCH_FLOW_FCN(X, OM, YF, YT, IL, MPOPT)
```

Branch flow constraints **for** AC optimal **power** flow.
Computes constraint vectors **and** their gradients.

Inputs:

X : optimization vector
MPC : MATPOWER **case struct**
YF : admittance matrix **for "from" end** of constrained branches
YT : admittance matrix **for "to" end** of constrained branches
IL : vector of branch indices corresponding to branches with
 flow limits (**all** others are assumed to be unconstrained).
 YF **and** YT contain only the **rows** corresponding to IL.
MPOPT : MATPOWER options **struct**

Outputs:

H : vector of inequality constraint values (flow limits)
 where the flow can be apparent **power**, **real power**, or
 current, depending on the value of opf.flow_lim in MPOPT
 (only **for** constrained lines), normally expressed as

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```
(limit^2 - flow^2), except when opf.flow_lim == 'P',
in which case it is simply (limit - flow).
DH : (optional) inequality constraint gradients, column j is
gradient of H(j)
```

Examples:

```
h = opf_branch_flow_fcn(x, mpc, Yf, Yt, il, mpopt);
[h, dh] = opf_branch_flow_fcn(x, mpc, Yf, Yt, il, mpopt);
```

See also [opf_branch_flow_hess\(\)](#) (page 292).

opf_branch_flow_hess

opf_branch_flow_hess(*x, lambda, mpc, Yf, Yt, il, mpopt*)

[opf_branch_flow_hess\(\)](#) (page 292) - Evaluates Hessian of branch flow constraints.

```
D2H = OPF_BRANCH_FLOW_HESS(X, LAMBDA, OM, YF, YT, IL, MPOPT)
```

Hessian evaluation **function for** AC branch flow constraints.

Inputs:

```
X : optimization vector
LAMBDA : column vector of Kuhn-Tucker multipliers on constrained
        branch flows
MPC : MATPOWER case struct
YF : admittance matrix for "from" end of constrained branches
YT : admittance matrix for "to" end of constrained branches
IL : vector of branch indices corresponding to branches with
    flow limits (all others are assumed to be unconstrained).
    YF and YT contain only the rows corresponding to IL.
MPOPT : MATPOWER options struct
```

Outputs:

```
D2H : Hessian of AC branch flow constraints.
```

Example:

```
d2H = opf_branch_flow_hess(x, lambda, mpc, Yf, Yt, il, mpopt);
```

See also [opf_branch_flow_fcn\(\)](#) (page 291).

opf_current_balance_fcn

opf_current_balance_fcn(*x, mpc, Ybus, mpopt*)

[opf_current_balance_fcn\(\)](#) (page 293) - Evaluates AC current balance constraints and their gradients.

```
[G, DG] = OPF_CURRENT_BALANCE_FCN(X, OM, YBUS, MPOPT)
```

Computes the **real** or imaginary current **balance** equality constraints **for** AC optimal **power** flow. Computes constraint vectors **and** their gradients.

Inputs:

X : optimization vector
MPC : MATPOWER **case struct**
YBUS : bus admittance matrix
MPOPT : MATPOWER options **struct**

Outputs:

G : vector of equality constraint values (**real**/imaginary current balances)
DG : (optional) equality constraint gradients

Examples:

```
g = opf_current_balance_fcn(x, mpc, Ybus, mpopt);  
[g, dg] = opf_current_balance_fcn(x, mpc, Ybus, mpopt);
```

See also [opf_power_balance_hess\(\)](#) (page 295).

opf_current_balance_hess

opf_current_balance_hess(*x, lambda, mpc, Ybus, mpopt*)

[opf_current_balance_hess\(\)](#) (page 293) - Evaluates Hessian of current balance constraints.

```
D2G = OPF_CURRENT_BALANCE_HESS(X, LAMBDA, OM, YBUS, MPOPT)
```

Hessian evaluation **function for** AC **real and** imaginary current **balance** constraints.

Inputs:

X : optimization vector
LAMBDA : column vector of Lagrange multipliers on **real and** imaginary current **balance** constraints
MPC : MATPOWER **case struct**
YBUS : bus admittance matrix
MPOPT : MATPOWER options **struct**

Outputs:

D2G : Hessian of current **balance** constraints.

Example:

```
d2G = opf_current_balance_hess(x, lambda, mpc, Ybus, mpopt);
```

See also [opf_current_balance_fcn\(\)](#) (page 293).

opf_gen_cost_fcn

opf_gen_cost_fcn(*x*, *baseMVA*, *gencost*, *ig*)

[opf_gen_cost_fcn\(\)](#) (page 294) - Evaluates polynomial generator costs and derivatives.

```
[F, DF, D2F] = OPF_GEN_COST_FCN(X, BASEMVA, COST)
```

Evaluates the polynomial generator costs and derivatives.

Inputs:

X : single-element cell array with vector of (active or reactive) dispatches (in per unit)
BASEMVA : system per unit base
GENCOST : standard gencost matrix corresponding to dispatch (active or reactive) provided in X
IG : vector of generator indices of interest
MPOPT : MATPOWER options struct

Outputs:

F : sum of generator polynomial costs
DF : (optional) gradient (column vector) of polynomial costs
D2F : (optional) Hessian of polynomial costs

Examples:

```
f = opf_gen_cost_fcn(x, baseMVA, gencost, ig);  
[f, df] = opf_gen_cost_fcn(x, baseMVA, gencost, ig);  
[f, df, d2f] = opf_gen_cost_fcn(x, baseMVA, gencost, ig);
```

opf_legacy_user_cost_fcn

opf_legacy_user_cost_fcn(*x*, *cp*)

[opf_legacy_user_cost_fcn\(\)](#) (page 294) - Evaluates legacy user costs and derivatives.

```
[F, DF, D2F] = OPF_LEGACY_USER_COST_FCN(X, CP)
```

Evaluates the legacy user-defined costs and derivatives.

Inputs:

X : cell array with vectors of optimization variables
CP : legacy user-defined cost parameter struct such as returned by @OPT_MODEL/GET_COST_PARAMS

Outputs:

F : sum of generator polynomial costs
DF : (optional) gradient (column vector) of polynomial costs
D2F : (optional) Hessian of polynomial costs

Examples:

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```
f = opf_legacy_user_cost_fcn(x, cp);
[f, df] = opf_legacy_user_cost_fcn(x, cp);
[f, df, d2f] = opf_legacy_user_cost_fcn(x, cp);
```

opf_power_balance_fcn

opf_power_balance_fcn(*x, mpc, Ybus, mpopt*)

[opf_power_balance_fcn\(\)](#) (page 295) - Evaluates AC power balance constraints and their gradients.

```
[G, DG] = OPF_POWER_BALANCE_FCN(X, OM, YBUS, MPOPT)
```

Computes the active **or** reactive **power balance** equality constraints **for** AC optimal **power** flow. Computes constraint vectors **and** their gradients.

Inputs:

X : optimization vector
MPC : MATPOWER **case struct**
YBUS : bus admittance matrix
MPOPT : MATPOWER options **struct**

Outputs:

G : vector of equality constraint values (active/reactive **power** balances)
DG : (optional) equality constraint gradients

Examples:

```
g = opf_power_balance_fcn(x, mpc, Ybus, mpopt);
[g, dg] = opf_power_balance_fcn(x, mpc, Ybus, mpopt);
```

See also [opf_power_balance_hess\(\)](#) (page 295).

opf_power_balance_hess

opf_power_balance_hess(*x, lambda, mpc, Ybus, mpopt*)

[opf_power_balance_hess\(\)](#) (page 295) - Evaluates Hessian of power balance constraints.

```
D2G = OPF_POWER_BALANCE_HESS(X, LAMBDA, OM, YBUS, MPOPT)
```

Hessian evaluation **function for** AC active **and** reactive **power balance** constraints.

Inputs:

X : optimization vector
LAMBDA : column vector of Lagrange multipliers on active **and** reactive **power balance** constraints
MPC : MATPOWER **case struct**
YBUS : bus admittance matrix
MPOPT : MATPOWER options **struct**

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Outputs:

D2G : Hessian of power balance constraints.

Example:

```
d2G = opf_power_balance_hess(x, lambda, mpc, Ybus, mpopt);
```

See also [opf_power_balance_fcn\(\)](#) (page 295).

opf_veq_fcn

opf_veq_fcn(*x, mpc, idx, mpopt*)

[opf_veq_fcn\(\)](#) (page 296) - Evaluates voltage magnitude equality constraint and gradients.

```
[Veq, dVeq] = OPF_VEQ_FCN(X, MPC, IDX, MPOPT)
```

Computes the voltage magnitudes using real and imaginary part of complex voltage for AC optimal power flow. Computes constraint vectors and their gradients.

Inputs:

X : optimization vector

MPC : MATPOWER case struct

IDX : index of buses whose voltage magnitudes should be fixed

MPOPT : MATPOWER options struct

Outputs:

VEQ : vector of voltage magnitudes

DVEQ : (optional) magnitude gradients

Examples:

```
Veq = opf_veq_fcn(x, mpc, mpopt);
```

```
[Veq, dVeq] = opf_veq_fcn(x, mpc, idx, mpopt);
```

See also [opf_veq_hess\(\)](#) (page 296).

opf_veq_hess

opf_veq_hess(*x, lambda, mpc, idx, mpopt*)

[opf_veq_hess\(\)](#) (page 296) - Evaluates Hessian of voltage magnitude equality constraint.

```
D2VEQ = OPF_VEQ_HESS(X, LAMBDA, MPC, IDX, MPOPT)
```

Hessian evaluation function for voltage magnitudes.

Inputs:

X : optimization vector

LAMBDA : column vector of Lagrange multipliers on active and reactive

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```

    power balance constraints
MPC : MATPOWER case struct
IDX : index of buses whose voltage magnitudes should be fixed
MPOPT : MATPOWER options struct

Outputs:
    D2VEQ : Hessian of voltage magnitudes.

Example:
    d2Veq = opf_veq_hess(x, lambda, mpc, idx, mpopt);

```

See also [opf_veq_fcn\(\)](#) (page 296).

opf_vlim_fcn

opf_vlim_fcn(*x*, *mpc*, *idx*, *mpopt*)

[opf_vlim_fcn\(\)](#) (page 297) - Evaluates voltage magnitudes and their gradients.

```

[Vlims, dVlims] = OPF_VLIM_FCN(X, MPC, IDX, MPOPT)

```

Computes the voltage magnitudes using real and imaginary part of complex voltage for AC optimal power flow. Computes constraint vectors and their gradients.

Inputs:

- X : optimization vector
- MPC : MATPOWER case struct
- IDX : index of buses whose voltage magnitudes should be fixed
- MPOPT : MATPOWER options struct

Outputs:

- VLIMS : vector of voltage magnitudes
- DVLIMS : (optional) magnitude gradients

Examples:

```

Vlims = opf_vlim_fcn(x, mpc, mpopt);
[Vlims, dVlims] = opf_vlim_fcn(x, mpc, idx, mpopt);

```

See also [opf_vlim_hess\(\)](#) (page 298).

opf_vlim_hess

opf_vlim_hess(*x, lambda, mpc, idx, mpopt*)

[opf_vlim_hess\(\)](#) (page 298) - Evaluates Hessian of voltage magnitudes.

```
D2VLIMS = OPF_VLIM_HESS(X, LAMBDA, MPC, IDX, MPOPT)
```

Hessian evaluation **function for** voltage magnitudes.

Inputs:

X : optimization vector
LAMBDA : column vector of Lagrange multipliers on active **and** reactive
 power balance constraints
MPC : MATPOWER **case struct**
IDX : **index** of buses whose voltage magnitudes should be fixed
MPOPT : MATPOWER options **struct**

Outputs:

D2VLIMS : Hessian of voltage magnitudes.

Example:

```
d2Vlims = opf_vlim_hess(x, lambda, mpc, idx, mpopt);
```

See also [opf_vlim_fcn\(\)](#) (page 297).

opf_vref_fcn

opf_vref_fcn(*x, mpc, refs, mpopt*)

[opf_vref_fcn\(\)](#) (page 298) - Evaluates voltage angle reference and their gradients.

```
[Vref, dVref] = OPF_VREF_FCN(X, mpc, ref, MPOPT)
```

Computes the voltage **angle** reference using **real and** imaginary part of **complex**
↪ **voltage for**
AC optimal **power** flow. Computes constraint vectors **and** their gradients.

Inputs:

X : optimization vector
MPC : MATPOWER **case struct**
REFS : reference vector
MPOPT : MATPOWER options **struct**

Outputs:

VREF : vector of voltage **angle** reference
DVREF : (optional) **angle** reference gradients

Examples:

```
Vref = opf_vref_fcn(x, mpc, refs, mpopt);  
[Vref, dVref] = opf_vref_fcn(x, mpc, refs, mpopt);
```

See also [opf_vref_hess\(\)](#) (page 299).

opf_vref_hess

opf_vref_hess(*x, lam, mpc, refs, mpopt*)

[opf_vref_hess\(\)](#) (page 299) - Evaluates Hessian of voltage angle reference.

```
D2VREF = OPF_VREF_HESS(X, LAMBDA, MPC, REFS, MPOPT)
```

Hessian evaluation **function for** voltage **angle** reference.

Inputs:

X : optimization vector
LAMBDA : column vector of Lagrange multipliers on active **and** reactive
 power balance constraints
MPC : MATPOWER **case struct**
REFS : reference vector
MPOPT : MATPOWER options **struct**

Outputs:

D2VREF : Hessian of voltage **angle** reference.

Example:

```
d2Vref = opf_vref_hess(x, lambda, mpc, refs, mpopt);
```

See also [opf_vref_fcn\(\)](#) (page 298).

totcost

totcost(*gencost, Pg*)

[totcost\(\)](#) - Computes total cost for generators at given output level.

TOTALCOST = TOTCOST(GENCOST, PG) computes total cost **for** generators given a matrix in gencost format **and** a column vector **or** matrix of generation levels. The **return** value has the same dimensions as PG. Each row of GENCOST is used to evaluate the cost at the points specified in the corresponding row of PG.

update_mupq

update_mupq(*baseMVA, gen, mu_PQh, mu_PQL, data*)

[update_mupq\(\)](#) (page 299) - Updates values of generator limit shadow prices.

```
GEN = UPDATE_MUPQ(BASEMVA, GEN, MU_PQH, MU_PQL, DATA)
```

Updates the values of MU_PMIN, MU_PMAX, MU_QMIN, MU_QMAX based on **any** shadow prices on the sloped portions of the generator

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capability curve constraints.

MU_PQH - shadow prices on **upper** sloped portion of capability curves
 MU_PQL - shadow prices on **lower** sloped portion of capability curves
 DATA - **"data"** **struct** returned by MAKEAPQ

See also `makeApq()` (page 286).

5.2.8 OPF User Callback Functions

`add_userfcn`

`add_userfcn(mpc, stage, fcn, args, allow_multiple)`

`add_userfcn()` (page 300) - Appends a userfcn to the list to be called for a case.

```
MPC = ADD_USERFCN(MPC, STAGE, FCN)
MPC = ADD_USERFCN(MPC, STAGE, FCN, ARGS)
MPC = ADD_USERFCN(MPC, STAGE, FCN, ARGS, ALLOW_MULTIPLE)
```

A userfcn is a callback **function** that can be called automatically by MATPOWER at one of various stages in a simulation.

MPC : the **case struct**
 STAGE : the name of the stage at which this **function** should be called: ext2int, formulation, int2ext, printpf, savecase
 FCN : the name of the userfcn
 ARGS : (optional) the value to be passed as an argument to the userfcn (typically a **struct**)
 ALLOW_MULTIPLE : (optional) **if** TRUE, allows the same **function** to be added more than once.

Currently there are 5 different callback stages defined. Each stage has a name, **and** by convention, the name of a user-defined callback **function** ends with the name of the stage. The following is a description of each stage, when it is called **and** the **input and** output arguments which vary depending on the stage. The reserves **example** (see RUNOPF_W_RES) is used to illustrate how these callback userfcns might be used.

1. ext2int

Called from EXT2INT immediately after the **case** is converted from external to internal indexing. Inputs are a MATPOWER **case struct** (MPC), freshly converted to internal indexing **and** any (optional) ARGS value supplied via ADD_USERFCN. Output is the (presumably updated) MPC. This is typically used to reorder **any input** arguments that may be needed in internal ordering by the formulation stage.

E.g. `mpc = userfcn_reserves_ext2int(mpc, mpopt, args)`

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2. formulation

Called from OPF after the OPF Model (OM) object has been initialized with the standard OPF formulation, but before calling the solver. Inputs are the OM object and any (optional) ARGS supplied via ADD_USERFCN. Output is the OM object. This is the ideal place to add any additional vars, constraints or costs to the OPF formulation.

E.g. `om = userfcn_reserves_formulation(om, mpopt, args)`

3. int2ext

Called from INT2EXT immediately before the resulting case is converted from internal back to external indexing. Inputs are the RESULTS struct and any (optional) ARGS supplied via ADD_USERFCN. Output is the RESULTS struct. This is typically used to convert any results to external indexing and populate any corresponding fields in the RESULTS struct.

E.g. `results = userfcn_reserves_int2ext(results, mpopt, args)`

4. printpf

Called from PRINTPF after the pretty-printing of the standard OPF output. Inputs are the RESULTS struct, the file descriptor to write to, a MATPOWER options struct, and any (optional) ARGS supplied via ADD_USERFCN. Output is the RESULTS struct. This is typically used for any additional pretty-printing of results.

E.g. `results = userfcn_reserves_printpf(results, fd, mpopt, args)`

5. savecase

Called from SAVECASE when saving a case struct to an M-file after printing all of the other data to the file. Inputs are the case struct, the file descriptor to write to, the variable prefix (typically 'mpc.') and any (optional) ARGS supplied via ADD_USERFCN. Output is the case struct. This is typically used to write any non-standard case struct fields to the case file.

E.g. `mpc = userfcn_reserves_printpf(mpc, fd, prefix, args)`

See also `run_userfcn()` (page 302), `remove_userfcn()` (page 302), `toggle_reserves()` (page 304), `toggle_iflims()` (page 303), `toggle_dcline()` (page 302), `toggle_softlims()` (page 305), `runopf_w_res()` (page 233).

remove_userfcn

remove_userfcn(*mpc, stage, fcn*)

[remove_userfcn\(\)](#) (page 302) - Removes a userfcn from the list to be called for a case.

```
MPC = REMOVE_USERFCN(MPC, STAGE, FCN)
```

A userfcn is a callback **function** that can be called automatically by MATPOWER at one of various stages in a simulation. This **function** removes the last instance of the userfcn **for** the given STAGE with the **function** handle specified by FCN.

See also [add_userfcn\(\)](#) (page 300), [run_userfcn\(\)](#) (page 302), [toggle_reserves\(\)](#) (page 304), [toggle_iflims\(\)](#) (page 303), [runopf_w_res\(\)](#) (page 233).

run_userfcn

run_userfcn(*userfcn, stage, varargin*)

[run_userfcn\(\)](#) (page 302) - Runs the userfcn callbacks for a given stage.

```
RV = RUN_USERFCN(USERFCN, STAGE, VARARGIN)
```

USERFCN : the 'userfcn' field of mpc, populated by ADD_USERFCN
STAGE : the name of the callback stage being executed
(additional arguments) some stages require additional arguments.

Example:

```
mpc = om.get_mpc();  
om = run_userfcn(mpc.userfcn, 'formulation', om);
```

See also [add_userfcn\(\)](#) (page 300), [remove_userfcn\(\)](#) (page 302), [toggle_reserves\(\)](#) (page 304), [toggle_iflims\(\)](#) (page 303), [runopf_w_res\(\)](#) (page 233).

toggle_dcline

toggle_dcline(*mpc, on_off*)

[toggle_dcline\(\)](#) (page 302) - Enable, disable or check status of DC line modeling.

```
MPC = TOGGLE_DCLINE(MPC, 'on')  
MPC = TOGGLE_DCLINE(MPC, 'off')  
T_F = TOGGLE_DCLINE(MPC, 'status')
```

Enables, disables **or** checks the status of a **set** of OPF userfcn callbacks to implement DC lines as a pair of linked generators. While it uses the OPF extension mechanism, this implementation works **for** simple **power** flow as well as OPF problems.

These callbacks expect to **find** a 'dcline' field in the **input** MPC, where MPC.dcline is an *ndc* x 17 matrix with **columns** as defined

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in `IDX_DCLINE`, where `ndc` is the number of DC lines.

The `'int2ext'` callback also packages up flow results and stores them in appropriate `columns` of `MPC.dcline`.

NOTE: Because of the way this extension modifies the number of `rows` in the `gen` and `gencost` matrices, caution must be taken when using it with other extensions that `deal` with generators.

Examples:

```
mpc = loadcase('t_case9_dcline');
mpc = toggle_dcline(mpc, 'on');
results1 = runpf(mpc);
results2 = runopf(mpc);
```

See also `idx_dcline()` (page 341), `add_userfcn()` (page 300), `remove_userfcn()` (page 302), `run_userfcn()` (page 302).

toggle_iflims

`toggle_iflims(mpc, on_off)`

`toggle_iflims()` (page 303) - Enable, disable or check status of set of interface flow limits.

```
MPC = TOGGLE_IFLIMS(MPC, 'on')
MPC = TOGGLE_IFLIMS(MPC, 'off')
T_F = TOGGLE_IFLIMS(MPC, 'status')
```

Enables, disables or checks the status of a `set` of OPF `userfcn` callbacks to implement interface flow limits based on a DC flow model.

These callbacks expect to find an `'if'` field in the `input` `MPC`, where `MPC.if` is a `struct` with the following fields:

<code>map</code>	<code>n x 2</code> , defines each interface in terms of a <code>set</code> of branch indices and directions. Interface <code>I</code> is defined by the <code>set</code> of <code>rows</code> whose 1st col is equal to <code>I</code> . The 2nd column is a branch <code>index</code> multiplied by 1 or -1 respectively <code>for</code> lines whose orientation is the same as or opposite to that of the interface.
<code>lims</code>	<code>nif x 3</code> , defines the DC model flow limits in MW <code>for</code> specified interfaces. The first column is the <code>index</code> of the interface, the 2nd and 3rd <code>columns</code> specify the <code>lower</code> and <code>upper</code> limits on the (DC model) flow across the interface, respectively. Normally, the <code>lower</code> limit is negative, indicating a flow in the opposite direction.

The `'int2ext'` callback also packages up results and stores them in the following output fields of `results.if`:

<code>P</code>	- <code>nif x 1</code> , actual flow across each interface in MW
----------------	--

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```
mu.l    - nif x 1, shadow price on lower flow limit, ($/MW)
mu.u    - nif x 1, shadow price on upper flow limit, ($/MW)
```

See also [add_userfcn\(\)](#) (page 300), [remove_userfcn\(\)](#) (page 302), [run_userfcn\(\)](#) (page 302), [t_case30_userfcns\(\)](#) (page 379).

toggle_reserves

toggle_reserves(*mpc, on_off*)

[toggle_reserves\(\)](#) (page 304) - Enable, disable or check status of fixed reserve requirements.

```
MPC = TOGGLE_RESERVES(MPC, 'on')
MPC = TOGGLE_RESERVES(MPC, 'off')
T_F = TOGGLE_RESERVES(MPC, 'status')
```

Enables, disables or checks the status of a set of OPF userfcn callbacks to implement co-optimization of reserves with fixed zonal reserve requirements.

These callbacks expect to find a 'reserves' field in the input MPC, where MPC.reserves is a struct with the following fields:

```
zones    nrz x ng, zone(i, j) = 1, if gen j belongs to zone i
          0, otherwise
req       nrz x 1, zonal reserve requirement in MW
cost      (ng or ngr) x 1, cost of reserves in $/MW
qty       (ng or ngr) x 1, max quantity of reserves in MW (optional)
```

where nrz is the number of reserve zones and ngr is the number of generators belonging to at least one reserve zone and ng is the total number of generators.

The 'int2ext' callback also packages up results and stores them in the following output fields of results.reserves:

```
R         - ng x 1, reserves provided by each gen in MW
Rmin      - ng x 1, lower limit on reserves provided by each gen, (MW)
Rmax      - ng x 1, upper limit on reserves provided by each gen, (MW)
mu.l      - ng x 1, shadow price on reserve lower limit, ($/MW)
mu.u      - ng x 1, shadow price on reserve upper limit, ($/MW)
mu.Pmax   - ng x 1, shadow price on  $P_g + R \leq P_{max}$  constraint, ($/MW)
prc       - ng x 1, reserve price for each gen equal to maximum of the
            shadow prices on the zonal requirement constraint
            for each zone the generator belongs to
```

See also [runopf_w_res\(\)](#) (page 233), [add_userfcn\(\)](#) (page 300), [remove_userfcn\(\)](#) (page 302), [run_userfcn\(\)](#) (page 302), [t_case30_userfcns\(\)](#) (page 379).

toggle_softlims

toggle_softlims(mpc, on_off)

toggle_softlims() (page 305) - Relax DC optimal power flow branch limits.

```

MPC = TOGGLE_SOFTLIMS(MPC, 'on')
MPC = TOGGLE_SOFTLIMS(MPC, 'off')
T_F = TOGGLE_SOFTLIMS(MPC, 'status')

```

Enables, disables or checks the status of a **set** of OPF userfcn callbacks to implement relaxed inequality constraints **for** an OPF model.

These callbacks expect to **find** a 'softlims' field in the **input** MPC, where MPC.softlims is a **struct** with fields corresponding to the possible limits, namely:

VMIN, VMAX, RATE_A, PMIN, PMAX, QMIN, QMAX, ANGMAX, ANGMIN

Each of these is itself a **struct** with the following fields, **all** of which are optional:

```

idx      index of affected buses, branches, or generators. These are
         row indices into the respective matrices. The default is to
         include all online elements for which the constraint in
         question is not unbounded, except for generators, which also
         exclude those used to model dispatchable loads
         (i.e. those for which isload(gen) is true).

busnum   for bus constraints, such as VMIN and VMAX, the affected
         buses can be specified by a vector of external bus numbers
         in the 'busnum' field instead of bus row indices in the 'idx'
         field. If both are present, 'idx' overrides 'busnum'.

cost     linear marginal cost of exceeding the original limit
         The defaults are set as:
             base_cost x 100 $/pu      for VMAX and VMIN
             base_cost $/MW           for RATE_A, PMAX, and PMIN
             base_cost $/MVar         for QMAX, QMIN
             base_cost $/deg          for ANGMAX, ANGMIN
         where base_cost is the maximum of $1000 and twice the
         maximum generator cost of all online generators.

hl_mod   type of modification to hard limit, hl:
         'none'      : do *not* add soft limit, no change to original
                       hard limit
         'remove'    : add soft limit, relax hard limit by removing
                       it completely
         'replace'   : add soft limit, relax hard limit by replacing
                       original with value specified in hl_val
         'scale'     : add soft limit, relax hard limit by scaling
                       original by value specified in hl_val
         'shift'     : add soft limit, relax hard limit by shifting
                       original by value specified in hl_val

hl_val   value used to modify hard limit according to hl_mod. Ignored
         for 'none' and 'remove', required for 'replace', and optional,
         with the following defaults, for 'scale' and 'shift':
         'scale'    : 2 for positive upper limits or negative lower
                       limits, 0.5 otherwise
         'shift'    : 0.25 for VMAX and VMIN, 10 otherwise

```

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For limits that are left unspecified in the structure, the default behavior is determined by the value of the `mpopt.opf.softlims.default` option. If `mpopt.opf.softlims.default = 0`, then the unspecified softlims are ignored (`hl_mod = 'none'`, i.e. original hard limits left in place). If `mpopt.opf.softlims.default = 1` (default), then the unspecified softlims are enabled with default values, which specify to `'remove'` the hard limit, except in the case of VMIN and PMIN, whose defaults are `set` as follows:

```
.VMIN
  .hl_mod = 'replace'
  .hl_val = 0
.PMIN
  .hl_mod = 'replace'
  .hl_val = 0    for normal generators (PMIN > 0)
  .hl_val = -Inf for generators with PMIN < 0 AND PMAX > 0
```

With `mpopt.opf.softlims.default = 0`, it is still possible to enable a softlim with default values by setting that specification to an empty `struct`. E.g. `mpc.softlims.VMAX = struct()` would enable a default softlim on VMAX.

The `'int2ext'` callback also packages up results and stores them in the following output fields of `results.softlims.(lim)`, where `lim` is one of the above mentioned limits:

```
overload - amount of overload, i.e. violation of hard-limit.
ovl_cost  - total cost of overload in $/hr
```

The shadow prices on the soft limit constraints are also returned in the relevant columns of the respective matrices (`MU_SF`, `MU_ST` for `RATE_A`, `MU_VMAX` for `VMAX`, etc.)

Note: These shadow prices are equal to the corresponding hard limit shadow prices when the soft limits are not violated. When violated, the shadow price on a soft limit constraint is equal to the user-specified soft limit violation cost + the shadow price on any binding remaining hard limit.

See also `add_userfcn()` (page 300), `remove_userfcn()` (page 302), `run_userfcn()` (page 302), `t_opf_softlims()` (page 376).

5.2.9 Power Flow Derivative Functions

dlbr_dV

dIbr_dV(branch, Yf, Yt, V, vcart)

dIbr_dV() (page 307) - Computes partial derivatives of branch currents w.r.t. voltage.

The derivatives can be take with respect to **polar** or cartesian coordinates of voltage, depending on the 5th argument.

```
[DIF_DVA, DIF_DVM, DIT_DVA, DIT_DVM, IF, IT] = DIBR_DV(BRANCH, YF, YT, V)
[DIF_DVA, DIF_DVM, DIT_DVA, DIT_DVM, IF, IT] = DIBR_DV(BRANCH, YF, YT, V, 0)
```

Returns four matrices containing partial derivatives of the **complex** branch currents at "from" and "to" ends of each branch w.r.t voltage magnitude and voltage **angle**, respectively (**for all** buses).

```
[DIF_DVR, DIF_DVI, DIT_DVR, DIT_DVI, IF, IT] = DIBR_DV(BRANCH, YF, YT, V, 1)
```

Returns four matrices containing partial derivatives of the **complex** branch currents at "from" and "to" ends of each branch w.r.t **real** and imaginary parts of voltage, respectively (**for all** buses).

If YF is a **sparse** matrix, the partial derivative matrices will be as well. Optionally returns vectors containing the currents themselves. The following explains the expressions used to form the matrices:

```
If = Yf * V;
```

Polar coordinates:

Partials of V, Vf & If w.r.t. voltage angles

```
dV/dVa = j * diag(V)
dVf/dVa = sparse(1:nl, f, j * V(f)) = j * sparse(1:nl, f, V(f))
dIf/dVa = Yf * dV/dVa = Yf * j * diag(V)
```

Partials of V, Vf & If w.r.t. voltage magnitudes

```
dV/dVm = diag(V./abs(V))
dVf/dVm = sparse(1:nl, f, V(f)./abs(V(f))
dIf/dVm = Yf * dV/dVm = Yf * diag(V./abs(V))
```

Cartesian coordinates:

Partials of V, Vf & If w.r.t. **real** part of **complex** voltage

```
dV/dVr = diag(ones(n,1))
dVf/dVr = Cf
dIf/dVr = Yf
```

where Cf is the connection matrix **for line** & from buses

Partials of V, Vf & If w.r.t. imaginary part of **complex** voltage

```
dV/dVi = j * diag(ones(n,1))
dVf/dVi = j * Cf
```

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```
dIf/dVi = j * Yf
```

Derivations for "to" bus are similar.

Example:

```
[Ybus, Yf, Yt] = makeYbus(baseMVA, bus, branch);
[dIf_dVa, dIf_dVm, dIt_dVa, dIt_dVm, If, It] = ...
    dIbr_dV(branch, Yf, Yt, V);
[dIf_dVr, dIf_dVi, dIt_dVr, dIt_dVi, If, It] = ...
    dIbr_dV(branch, Yf, Yt, V, 1);
```

For more details on the derivations behind the derivative code used in MATPOWER information, see:

- [TN2] R. D. Zimmerman, "AC Power Flows, Generalized OPF Costs and their Derivatives using Complex Matrix Notation", MATPOWER Technical Note 2, February 2010. [Online]. Available: <https://matpower.org/docs/TN2-OPF-Derivatives.pdf> doi: 10.5281/zenodo.3237866
- [TN4] B. Sereeter and R. D. Zimmerman, "AC Power Flows and their Derivatives using Complex Matrix Notation and Cartesian Coordinate Voltages," MATPOWER Technical Note 4, April 2018. [Online]. Available: <https://matpower.org/docs/TN4-OPF-Derivatives-Cartesian.pdf> doi: 10.5281/zenodo.3237909

dSbr_dV

dSbr_dV(branch, Yf, Yt, V, vcart)

dSbr_dV() (page 308) - Computes partial derivatives of branch power flows w.r.t. voltage.

The derivatives can be taken with respect to polar or cartesian coordinates of voltage, depending on the 5th argument.

```
[DSF_DVA, DSF_DVM, DST_DVA, DST_DVM, SF, ST] = DSBR_DV(BRANCH, YF, YT, V)
[DSF_DVA, DSF_DVM, DST_DVA, DST_DVM, SF, ST] = DSBR_DV(BRANCH, YF, YT, V, 0)
```

Returns four matrices containing partial derivatives of the complex branch power flows at "from" and "to" ends of each branch w.r.t voltage magnitude and voltage angle, respectively (for all buses).

```
[DSF_DVR, DSF_DVI, DST_DVR, DST_DVI, SF, ST] = DSBR_DV(BRANCH, YF, YT, V, 1)
```

Returns four matrices containing partial derivatives of the complex branch power flows at "from" and "to" ends of each branch w.r.t real and imaginary parts of voltage, respectively (for all buses).

If YF is a sparse matrix, the partial derivative matrices will be as well. Optionally returns vectors containing the power flows themselves. The following explains the expressions used to form the matrices:

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```
If = Yf * V;
Sf = diag(Vf) * conj(If) = diag(conj(If)) * Vf
```

Polar coordinates:

Partials of V, Vf & If w.r.t. voltage angles

```
dV/dVa = j * diag(V)
dVf/dVa = sparse(1:nl, f, j * V(f)) = j * sparse(1:nl, f, V(f))
dIf/dVa = Yf * dV/dVa = Yf * j * diag(V)
```

Partials of V, Vf & If w.r.t. voltage magnitudes

```
dV/dVm = diag(V./abs(V))
dVf/dVm = sparse(1:nl, f, V(f)./abs(V(f)))
dIf/dVm = Yf * dV/dVm = Yf * diag(V./abs(V))
```

Partials of Sf w.r.t. voltage angles

```
dSf/dVa = diag(Vf) * conj(dIf/dVa)
          + diag(conj(If)) * dVf/dVa
        = diag(Vf) * conj(Yf * j * diag(V))
          + conj(diag(If)) * j * sparse(1:nl, f, V(f))
        = -j * diag(Vf) * conj(Yf * diag(V))
          + j * conj(diag(If)) * sparse(1:nl, f, V(f))
        = j * (conj(diag(If)) * sparse(1:nl, f, V(f))
          - diag(Vf) * conj(Yf * diag(V)))
```

Partials of Sf w.r.t. voltage magnitudes

```
dSf/dVm = diag(Vf) * conj(dIf/dVm)
          + diag(conj(If)) * dVf/dVm
        = diag(Vf) * conj(Yf * diag(V./abs(V)))
          + conj(diag(If)) * sparse(1:nl, f, V(f)./abs(V(f)))
```

Cartesian coordinates:

Partials of V, Vf & If w.r.t. real part of complex voltage

```
dV/dVr = diag(ones(n,1))
dVf/dVr = Cf
dIf/dVr = Yf
```

where Cf is the connection matrix for line & from buses

Partials of V, Vf & If w.r.t. imaginary part of complex voltage

```
dV/dVi = j * diag(ones(n,1))
dVf/dVi = j * Cf
dIf/dVi = j * Yf
```

Partials of Sf w.r.t. real part of complex voltage

```
dSf/dVr = conj(diag(If)) * Cf + diag(Vf) * conj(Yf)
```

Partials of Sf w.r.t. imaginary part of complex voltage

```
dSf/dVi = j * (conj(diag(If)) * Cf - diag(Vf) * conj(Yf))
```

Derivations for "to" bus are similar.

Examples:

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```
[Ybus, Yf, Yt] = makeYbus(baseMVA, bus, branch);
[dSf_dVa, dSf_dVm, dSt_dVa, dSt_dVm, Sf, St] = ...
    dSbr_dV(branch, Yf, Yt, V);
[dSf_dVr, dSf_dVi, dSt_dVr, dSt_dVi, Sf, St] = ...
    dSbr_dV(branch, Yf, Yt, V, 1);
```

For more details on the derivations behind the derivative code used in MATPOWER, see:

- [TN2] R. D. Zimmerman, "AC Power Flows, Generalized OPF Costs and their Derivatives using Complex Matrix Notation", MATPOWER Technical Note 2, February 2010. [Online]. Available: <https://matpower.org/docs/TN2-OPF-Derivatives.pdf>
doi: [10.5281/zenodo.3237866](https://doi.org/10.5281/zenodo.3237866)
- [TN4] B. Sereeter and R. D. Zimmerman, "AC Power Flows and their Derivatives using Complex Matrix Notation and Cartesian Coordinate Voltages," MATPOWER Technical Note 4, April 2018. [Online]. Available: <https://matpower.org/docs/TN4-OPF-Derivatives-Cartesian.pdf>
doi: [10.5281/zenodo.3237909](https://doi.org/10.5281/zenodo.3237909)

dAbr_dV

dAbr_dV(dFf_dV1, dFf_dV2, dFt_dV1, dFt_dV2, Ff, Ft)

dAbr_dV() (page 310) - Partial derivatives of squared flow magnitudes w.r.t voltage.

```
[DAF_DV1, DAF_DV2, DAT_DV1, DAT_DV2] = ...
    DABR_DV(DFF_DV1, DFF_DV2, DFT_DV1, DFT_DV2, FF, FT)
```

returns four matrices containing partial derivatives of the square of the branch flow magnitudes at "from" & "to" ends of each branch w.r.t voltage components (either **angle** and magnitude, respectively, **if polar**, or **real** and imaginary, respectively, **if cartesian**) **for all** buses, given the flows and flow sensitivities. Flows could be **complex current** or **complex or real power**. Notation below is based on **complex power**. The following explains the expressions used to form the matrices:

Let Af refer to the square of the apparent **power** at the "from" end of each branch,

```
Af = abs(Sf).^2
    = Sf .* conj(Sf)
    = Pf.^2 + Qf.^2
```

then ...

Partial w.r.t **real power**,
 $dA_f/dP_f = 2 * \text{diag}(P_f)$

Partial w.r.t **reactive power**,
 $dA_f/dQ_f = 2 * \text{diag}(Q_f)$

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Partial w.r.t V1 & V2 (e.g. Va and Vm, or Vr and Vi)

$$dAf/dV1 = dAf/dPf * dPf/dV1 + dAf/dQf * dQf/dV1$$

$$dAf/dV2 = dAf/dPf * dPf/dV2 + dAf/dQf * dQf/dV2$$

Derivations for "to" bus are similar.

Examples:

%% squared current magnitude

```
[dFf_dV1, dFf_dV2, dFt_dV1, dFt_dV2, Ff, Ft] = ...
```

```
    dIbr_dV(branch(il,:), Yf, Yt, V);
```

```
[dAf_dV1, dAf_dV2, dAt_dV1, dAt_dV2] = ...
```

```
    dAbr_dV(dFf_dV1, dFf_dV2, dFt_dV1, dFt_dV2, Ff, Ft);
```

%% squared apparent power flow

```
[dFf_dV1, dFf_dV2, dFt_dV1, dFt_dV2, Ff, Ft] = ...
```

```
    dSbr_dV(branch(il,:), Yf, Yt, V);
```

```
[dAf_dV1, dAf_dV2, dAt_dV1, dAt_dV2] = ...
```

```
    dAbr_dV(dFf_dV1, dFf_dV2, dFt_dV1, dFt_dV2, Ff, Ft);
```

%% squared real power flow

```
[dFf_dV1, dFf_dV2, dFt_dV1, dFt_dV2, Ff, Ft] = ...
```

```
    dSbr_dV(branch(il,:), Yf, Yt, V);
```

```
dFf_dV1 = real(dFf_dV1);
```

```
dFf_dV2 = real(dFf_dV2);
```

```
dFt_dV1 = real(dFt_dV1);
```

```
dFt_dV2 = real(dFt_dV2);
```

```
[dAf_dV1, dAf_dV2, dAt_dV1, dAt_dV2] = ...
```

```
    dAbr_dV(dFf_dV1, dFf_dV2, dFt_dV1, dFt_dV2, Ff, Ft);
```

See also *dIbr_dV()* (page 307), *dSbr_dV()* (page 308).

For more details on the derivations behind the derivative code used in MATPOWER information, see:

[TN2] R. D. Zimmerman, "AC Power Flows, Generalized OPF Costs and their Derivatives using Complex Matrix Notation", MATPOWER Technical Note 2, February 2010. [Online]. Available: <https://matpower.org/docs/TN2-OPF-Derivatives.pdf>
doi: 10.5281/zenodo.3237866

dImis_dV

dImis_dV(Sbus, Ybus, V, vcart)

dImis_dV() (page 311) - Computes partial derivatives of current balance w.r.t. voltage.

The derivatives can be take with respect to polar or cartesian coordinates of voltage, depending on the 3rd argument.

```
[DIMIS_DVM, DIMIS_DVA] = DIMIS_DV(SBUS, YBUS, V)
```

```
[DIMIS_DVM, DIMIS_DVA] = DIMIS_DV(SBUS, YBUS, V, 0)
```

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Returns two matrices containing partial derivatives of the **complex** bus current **balance** w.r.t voltage magnitude **and** voltage **angle**, respectively (**for all** buses).

```
[DIMIS_DVR, DIMIS_DVI] = DIMIS_DV(SBUS, YBUS, V, 1)
```

Returns two matrices containing partial derivatives of the **complex** bus current **balance** w.r.t the **real and** imaginary parts of voltage, respectively (**for all** buses).

If YBUS is a **sparse** matrix, the **return** values will be also. The following explains the expressions used to form the matrices:

$$I_{mis} = I_{bus} + I_{dg} = Y_{bus} * V - \text{conj}(S_{bus}/V)$$

Polar coordinates:

Partials of V & I_{bus} w.r.t. voltage angles

$$dV/dV_a = j * \text{diag}(V)$$

$$dI/dV_a = Y_{bus} * dV/dV_a = Y_{bus} * j * \text{diag}(V)$$

Partials of V & I_{bus} w.r.t. voltage magnitudes

$$dV/dV_m = \text{diag}(V./\text{abs}(V))$$

$$dI/dV_m = Y_{bus} * dV/dV_m = Y_{bus} * \text{diag}(V./\text{abs}(V))$$

Partials of I_{mis} w.r.t. voltage angles

$$dI_{mis}/dV_a = j * (Y_{bus} * \text{diag}(V) - \text{diag}(\text{conj}(S_{bus}/V)))$$

Partials of I_{mis} w.r.t. voltage magnitudes

$$dI_{mis}/dV_m = Y_{bus} * \text{diag}(V./\text{abs}(V)) + \text{diag}(\text{conj}(S_{bus}/(V * \text{abs}(V))))$$

Cartesian coordinates:

Partials of V & I_{bus} w.r.t. **real** part of **complex** voltage

$$dV/dV_r = \text{diag}(\text{ones}(n,1))$$

$$dI/dV_r = Y_{bus} * dV/dV_r = Y_{bus}$$

Partials of V & I_{bus} w.r.t. imaginary part of **complex** voltage

$$dV/dV_i = j * \text{diag}(\text{ones}(n,1))$$

$$dI/dV_i = Y_{bus} * dV/dV_i = Y_{bus} * j$$

Partials of I_{mis} w.r.t. **real** part of **complex** voltage

$$dI_{mis}/dV_r = Y_{bus} + \text{conj}(\text{diag}(S_{bus}/(V.^2)))$$

Partials of S w.r.t. imaginary part of **complex** voltage

$$dI_{mis}/dV_i = j * (Y_{bus} - \text{diag}(\text{conj}(S_{bus}/(V.^2))))$$

Examples:

```
Sbus = makeSbus(baseMVA, bus, gen);
[Ybus, Yf, Yt] = makeYbus(baseMVA, bus, branch);
[dImis_dVm, dImis_dVa] = dImis_dV(Sbus, Ybus, V);
[dImis_dVr, dImis_dVi] = dImis_dV(Sbus, Ybus, V, 1);
```

For more details on the derivations behind the derivative code used in MATPOWER information, see:

- [TN2] R. D. Zimmerman, "AC Power Flows, Generalized OPF Costs and their Derivatives using Complex Matrix Notation", MATPOWER Technical Note 2, February 2010. [Online]. Available: <https://matpower.org/docs/TN2-OPF-Derivatives.pdf>
doi: [10.5281/zenodo.3237866](https://doi.org/10.5281/zenodo.3237866)
- [TN3] B. Sereeter and R. D. Zimmerman, "Addendum to AC Power Flows and their Derivatives using Complex Matrix Notation: Nodal Current Balance," MATPOWER Technical Note 3, April 2018. [Online]. Available: <https://matpower.org/docs/TN3-More-OPF-Derivatives.pdf>
doi: [10.5281/zenodo.3237900](https://doi.org/10.5281/zenodo.3237900)
- [TN4] B. Sereeter and R. D. Zimmerman, "AC Power Flows and their Derivatives using Complex Matrix Notation and Cartesian Coordinate Voltages," MATPOWER Technical Note 4, April 2018. [Online]. Available: <https://matpower.org/docs/TN4-OPF-Derivatives-Cartesian.pdf>
doi: [10.5281/zenodo.3237909](https://doi.org/10.5281/zenodo.3237909)

dSbus_dV

dSbus_dV(Ybus, V, vcart)

dSbus_dV() (page 313) - Computes partial derivatives of power injection w.r.t. voltage.

The derivatives can be taken with respect to **polar or** cartesian coordinates of voltage, depending on the 3rd argument.

```
[DSBUS_DVA, DSBUS_DVM] = DSBUS_DV(YBUS, V)
[DSBUS_DVA, DSBUS_DVM] = DSBUS_DV(YBUS, V, 0)
```

Returns two matrices containing partial derivatives of the **complex** bus power injections w.r.t voltage **angle and** voltage magnitude, respectively (**for all** buses).

```
[DSBUS_DVR, DSBUS_DVI] = DSBUS_DV(YBUS, V, 1)
```

Returns two matrices containing partial derivatives of the **complex** bus power injections w.r.t the **real and** imaginary parts of voltage, respectively (**for all** buses).

If YBUS is a **sparse** matrix, the **return** values will be also. The following explains the expressions used to form the matrices:

$$S = \text{diag}(V) * \text{conj}(I_{\text{bus}}) = \text{diag}(\text{conj}(I_{\text{bus}})) * V$$

Polar coordinates:

Partials of V & Ibus w.r.t. voltage magnitudes

$$dV/dVm = \text{diag}(V./\text{abs}(V))$$

$$dI/dVm = Y_{\text{bus}} * dV/dVm = Y_{\text{bus}} * \text{diag}(V./\text{abs}(V))$$

Partials of V & Ibus w.r.t. voltage angles

$$dV/dVa = j * \text{diag}(V)$$

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```

dI/dVa = Ybus * dV/dVa = Ybus * j * diag(V)

Partials of S w.r.t. voltage magnitudes
dS/dVm = diag(V) * conj(dI/dVm) + diag(conj(Ibus)) * dV/dVm
        = diag(V) * conj(Ybus * diag(V./abs(V)))
          + conj(diag(Ibus)) * diag(V./abs(V))

Partials of S w.r.t. voltage angles
dS/dVa = diag(V) * conj(dI/dVa) + diag(conj(Ibus)) * dV/dVa
        = diag(V) * conj(Ybus * j * diag(V))
          + conj(diag(Ibus)) * j * diag(V)
        = -j * diag(V) * conj(Ybus * diag(V))
          + conj(diag(Ibus)) * j * diag(V)
        = j * diag(V) * conj(diag(Ibus) - Ybus * diag(V))

Cartesian coordinates:
Partials of V & Ibus w.r.t. real part of complex voltage
dV/dVr = diag(ones(n,1))
dI/dVr = Ybus * dV/dVr = Ybus

Partials of V & Ibus w.r.t. imaginary part of complex voltage
dV/dVi = j * diag(ones(n,1))
dI/dVi = Ybus * dV/dVi = Ybus * j

Partials of S w.r.t. real part of complex voltage
dS/dVr = diag(V) * conj(dI/dVr) + diag(conj(Ibus)) * dV/dVr
        = diag(V) * conj(Ybus) + conj(diag(Ibus))

Partials of S w.r.t. imaginary part of complex voltage
dS/dVi = diag(V) * conj(dI/dVi) + diag(conj(Ibus)) * dV/dVi
        = j * (conj(diag(Ibus)) - diag(V) conj(Ybus))

Examples:
[Ybus, Yf, Yt] = makeYbus(baseMVA, bus, branch);
[dSbus_dVa, dSbus_dVm] = dSbus_dV(Ybus, V);
[dSbus_dVr, dSbus_dVi] = dSbus_dV(Ybus, V, 1);

```

For more details on the derivations behind the derivative code used in MATPOWER information, see:

- [TN2] R. D. Zimmerman, "AC Power Flows, Generalized OPF Costs and their Derivatives using Complex Matrix Notation", MATPOWER Technical Note 2, February 2010. [Online]. Available: <https://matpower.org/docs/TN2-OPF-Derivatives.pdf>
doi: 10.5281/zenodo.3237866
- [TN4] B. Sereeter and R. D. Zimmerman, "AC Power Flows and their Derivatives using Complex Matrix Notation and Cartesian Coordinate Voltages," MATPOWER Technical Note 4, April 2018. [Online]. Available: <https://matpower.org/docs/TN4-OPF-Derivatives-Cartesian.pdf>
doi: 10.5281/zenodo.3237909

d2Ibr_dV2**d2Ibr_dV2**(Ybr, V, mu, vcart)**d2Ibr_dV2**() (page 315) - Computes 2nd derivatives of complex branch current w.r.t. voltage.

The derivatives can be take with respect to **polar** or cartesian coordinates of voltage, depending on the 4th argument.

```
[HAA, HAV, HVA, HVV] = D2IBR_DV2(YBR, V, MU)
[HAA, HAV, HVA, HVV] = D2IBR_DV2(YBR, V, MU, 0)
```

Returns 4 matrices containing the partial derivatives w.r.t. voltage **angle** and magnitude of the product of a vector MU with the 1st partial derivatives of the **complex** branch currents.

```
[HRR, HRI, HIR, HII] = D2IBR_DV2(YBR, V, MU, 1)
```

Returns 4 matrices (**all zeros**) containing the partial derivatives w.r.t. **real** and imaginary part of **complex** voltage of the product of a vector MU with the 1st partial derivatives of the **complex** branch currents.

Takes **sparse** branch admittance matrix YBR, voltage vector V and nl x 1 vector of multipliers MU. Output matrices are **sparse**.

Examples:

```
[Ybus, Yf, Yt] = makeYbus(baseMVA, bus, branch);
Ybr = Yf;
[Haa, Hav, Hva, Hvv] = d2Ibr_dV2(Ybr, V, mu);
```

Here the output matrices correspond to:

```
Haa = d/dVa (dIbr_dVa.' * mu)
Hav = d/dVm (dIbr_dVa.' * mu)
Hva = d/dVa (dIbr_dVm.' * mu)
Hvv = d/dVm (dIbr_dVm.' * mu)
```

```
[Hrr, Hri, Hir, Hii] = d2Ibr_dV2(Ybr, V, mu, 1);
```

Here the output matrices correspond to:

```
Hrr = d/dVr (dIbr_dVr.' * mu)
Hri = d/dVi (dIbr_dVr.' * mu)
Hir = d/dVr (dIbr_dVi.' * mu)
Hii = d/dVi (dIbr_dVi.' * mu)
```

For more details on the derivations behind the derivative code used in MATPOWER information, see:

- [TN2] R. D. Zimmerman, "AC Power Flows, Generalized OPF Costs and their Derivatives using Complex Matrix Notation", MATPOWER Technical Note 2, February 2010. [Online]. Available: <https://matpower.org/docs/TN2-OPF-Derivatives.pdf> doi: 10.5281/zenodo.3237866
- [TN4] B. Sereeter and R. D. Zimmerman, "AC Power Flows and their Derivatives using Complex Matrix Notation and Cartesian Coordinate Voltages," MATPOWER Technical Note 4, April 2018.

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[Online]. Available: <https://matpower.org/docs/TN4-OPF-Derivatives-Cartesian.pdf>
doi: [10.5281/zenodo.3237909](https://doi.org/10.5281/zenodo.3237909)

d2Sbr_dV2

d2Sbr_dV2(Cbr, Ybr, V, mu, vcart)

d2Sbr_dV2() (page 316) - Computes 2nd derivatives of complex brch power flow w.r.t. voltage.

The derivatives can be take with respect to **polar or** cartesian coordinates of voltage, depending on the 5th argument.

```
[HAA, HAV, HVA, HVV] = D2SBR_DV2(CBR, YBR, V, MU)
[HAA, HAV, HVA, HVV] = D2SBR_DV2(CBR, YBR, V, MU, 0)
```

Returns 4 matrices containing the partial derivatives w.r.t. voltage **angle and** magnitude of the product of a vector MU with the 1st partial derivatives of the **complex** branch **power** flows.

```
[HRR, HRI, HIR, HII] = d2Sbr_dV2(CBR, YBR, V, MU, 1)
```

Returns 4 matrices containing the partial derivatives w.r.t. **real and** imaginary part of **complex** voltage of the product of a vector MU with the 1st partial derivatives of the **complex** branch **power** flows.

Takes **sparse** connection matrix CBR, **sparse** branch admittance matrix YBR, voltage vector V and nl x 1 vector of multipliers MU. Output matrices are **sparse**.

Examples:

```
f = branch(:, F_BUS);
Cf = sparse(1:nl, f, ones(nl, 1), nl, nb);
[Ybus, Yf, Yt] = makeYbus(baseMVA, bus, branch);
Cbr = Cf;
Ybr = Yf;
[Haa, Hav, Hva, Hvv] = d2Sbr_dV2(Cbr, Ybr, V, mu);
```

Here the output matrices correspond to:

```
Haa = d/dVa (dSbr_dVa.' * mu)
Hav = d/dVm (dSbr_dVa.' * mu)
Hva = d/dVa (dSbr_dVm.' * mu)
Hvv = d/dVm (dSbr_dVm.' * mu)
```

```
[Hrr, Hri, Hir, Hii] = d2Sbr_dV2(Cbr, Ybr, V, mu, 1);
```

Here the output matrices correspond to:

```
Hrr = d/dVr (dSbr_dVr.' * mu)
Hri = d/dVi (dSbr_dVr.' * mu)
Hir = d/dVr (dSbr_dVi.' * mu)
Hii = d/dVi (dSbr_dVi.' * mu)
```


For more details on the derivations behind the derivative code used in MATPOWER information, see:

- [TN2] R. D. Zimmerman, "AC Power Flows, Generalized OPF Costs and their Derivatives using Complex Matrix Notation", MATPOWER Technical Note 2, February 2010. [Online]. Available: <https://matpower.org/docs/TN2-OPF-Derivatives.pdf>
doi: [10.5281/zenodo.3237866](https://doi.org/10.5281/zenodo.3237866)
- [TN4] B. Sereeter and R. D. Zimmerman, "AC Power Flows and their Derivatives using Complex Matrix Notation and Cartesian Coordinate Voltages," MATPOWER Technical Note 4, April 2018. [Online]. Available: <https://matpower.org/docs/TN4-OPF-Derivatives-Cartesian.pdf>
doi: [10.5281/zenodo.3237909](https://doi.org/10.5281/zenodo.3237909)

d2Abr_dV2

d2Abr_dV2(d2F_dV2, dF_dV1, dF_dV2, F, V, mu)

d2Abr_dV2() (page 317) - Computes 2nd derivatives of |branch flow|^2 w.r.t. V.

The derivatives can be take with respect to **polar** or cartesian coordinates of voltage, depending on the first 3 arguments. Flows could be **complex** current or **complex** or **real** power. Notation below is based on **complex** power.

```
[H11, H12, H21, H22] = D2ABR_DV2(D2F_DV2, DF_DV1, DF_DV2, F, V, MU)
```

Returns 4 matrices containing the partial derivatives w.r.t. voltage components (**angle**, magnitude or **real**, imaginary) of the product of a vector MU with the 1st partial derivatives of the square of the magnitude of branch flows.

Takes as inputs a handle to a **function** that evaluates the 2nd derivatives of the flows (with args V and mu only), **sparse** first derivative matrices of flow, flow vector, voltage vector V and nl x 1 vector of multipliers MU. Output matrices are **sparse**.

Example:

```
f = branch(:, F_BUS);
Cf = sparse(1:nl, f, ones(nl, 1), nl, nb);
[Ybus, Yf, Yt] = makeYbus(baseMVA, bus, branch);
[dSf_dV1, dSf_dV2, dSt_dV1, dSt_dV2, Sf, St] = ...
    dSbr_dV(branch, Yf, Yt, V);
dF_dV1 = dSf_dV1;
dF_dV2 = dSf_dV2;
F = Sf;
d2F_dV2 = @(V, mu)d2Sbr_dV2(Cf, Yf, V, mu, 0);
[H11, H12, H21, H22] = ...
    d2Abr_dV2(d2F_dV2, dF_dV1, dF_dV2, F, V, mu);
```

Here the output matrices correspond to:

```
H11 = d/dV1 (dAF_dV1.' * mu)
H12 = d/dV2 (dAF_dV1.' * mu)
```

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```
H21 = d/dV1 (dAF_dV2.' * mu)
H22 = d/dV2 (dAF_dV2.' * mu)
```

See also `dAbr_dV()` (page 310), `dIbr_dV()` (page 307), `dSbr_dV()` (page 308).

For more details on the derivations behind the derivative code used in MATPOWER information, see:

[TN2] R. D. Zimmerman, "AC Power Flows, Generalized OPF Costs and their Derivatives using Complex Matrix Notation", MATPOWER Technical Note 2, February 2010. [Online]. Available: <https://matpower.org/docs/TN2-OPF-Derivatives.pdf>
doi: [10.5281/zenodo.3237866](https://doi.org/10.5281/zenodo.3237866)

d2Imis_dV2

d2Imis_dV2(Sbus, Ybus, V, lam, vcart)

`d2Imis_dV2()` (page 318) - Computes 2nd derivatives of current balance w.r.t. voltage.

The derivatives can be take with respect to **polar** or cartesian coordinates of voltage, depending on the 5th argument.

```
[GAA, GAV, GVA, GVV] = D2IMIS_DV2(SBUS, YBUS, V, LAM)
[GAA, GAV, GVA, GVV] = D2IMIS_DV2(SBUS, YBUS, V, LAM, 0)
```

Returns 4 matrices containing the partial derivatives w.r.t. voltage **angle** and magnitude of the product of a vector LAM with the 1st partial derivatives of the **complex** bus current **balance**.

```
[GRR, GIR, GRI, GII] = D2IMIS_DV2(SBUS, YBUS, V, LAM, 1)
```

Returns 4 matrices containing the partial derivatives w.r.t. **real** and **imaginary** parts of voltage of the product of a vector LAM with the 1st partial derivatives of the **complex** bus current **balance**.

Takes bus **complex power** injection (gen-load) vector, **sparse** bus admittance matrix YBUS, voltage vector V and nb x 1 vector of multipliers LAM. Output matrices are **sparse**.

Examples:

```
Sbus = makeSbus(baseMVA, bus, gen);
[Ybus, Yf, Yt] = makeYbus(baseMVA, bus, branch);
[Gaa, Gav, Gva, Gvv] = d2Imis_dV2(Sbus, Ybus, V, lam);
```

Here the output matrices correspond to:

```
Gaa = d/dVa (dImis_dVa.' * lam)
Gav = d/dVm (dImis_dVa.' * lam)
Gva = d/dVa (dImis_dVm.' * lam)
Gvv = d/dVm (dImis_dVm.' * lam)
```

```
[Grr, Gri, Gir, Gii] = d2Imis_dV2(Sbus, Ybus, V, lam, 1);
```

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Here the output matrices correspond to:

```
Grr = d/dVr (dImis_dVr.' * lam)
Gri = d/dVi (dImis_dVr.' * lam)
Gir = d/dVr (dImis_dVi.' * lam)
Gii = d/dVi (dImis_dVi.' * lam)
```

For more details on the derivations behind the derivative code used in MATPOWER, see:

- [TN2] R. D. Zimmerman, "AC Power Flows, Generalized OPF Costs and their Derivatives using Complex Matrix Notation", MATPOWER Technical Note 2, February 2010. [Online]. Available: <https://matpower.org/docs/TN2-OPF-Derivatives.pdf>
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- [TN3] B. Sereeter and R. D. Zimmerman, "Addendum to AC Power Flows and their Derivatives using Complex Matrix Notation: Nodal Current Balance," MATPOWER Technical Note 3, April 2018. [Online]. Available: <https://matpower.org/docs/TN3-More-OPF-Derivatives.pdf>
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- [TN4] B. Sereeter and R. D. Zimmerman, "AC Power Flows and their Derivatives using Complex Matrix Notation and Cartesian Coordinate Voltages," MATPOWER Technical Note 4, April 2018. [Online]. Available: <https://matpower.org/docs/TN4-OPF-Derivatives-Cartesian.pdf>
doi: [10.5281/zenodo.3237909](https://doi.org/10.5281/zenodo.3237909)

d2Imis_dVdSg

d2Imis_dVdSg(*Cg*, *V*, *lam*, *vcart*)

d2Imis_dVdSg(*C*) (page 319) - Computes 2nd derivatives of current balance w.r.t. *V* and *Sg*.

The derivatives can be take with respect to **polar** or cartesian coordinates of voltage, depending on the 4th argument.

```
GSV = D2IMIS_DVDSG(CG, V, LAM)
GSV = D2IMIS_DVDSG(CG, V, LAM, 0)
```

Returns a matrix containing the partial derivatives w.r.t. voltage **angle** and magnitude of the product of a vector *LAM* with the 1st partial derivatives of the **real** and reactive **power** generation.

```
GSV = D2IMIS_DVDSG(CG, V, LAM, 1)
```

Returns a matrix containing the partial derivatives w.r.t. **real** and imaginary parts of voltage of the product of a vector *LAM* with the 1st partial derivatives of the **real** and reactive **power** generation.

Takes the generator connection matrix, **complex** voltage vector *V* and *nb* x 1 vector of multipliers *LAM*. Output matrices are **sparse**.

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Examples:

```
Cg = sparse(gen(:, GEN_BUS), 1:ng, -, nb, ng);
Gsv = d2Imis_dVdSg(Cg, V, lam);
```

Here the output matrix corresponds to:

```
Gsv = [ Gpa Gpv;
        Gqa Gqv ];
Gpa = d/dVa (dImis_dPg.' * lam)
Gpv = d/dVm (dImis_dPg.' * lam)
Gqa = d/dVa (dImis_dQg.' * lam)
Gqv = d/dVm (dImis_dQg.' * lam)
```

```
[Grr, Gri, Gir, Gii] = d2Imis_dVdSg(Cg, V, lam, 1);
```

Here the output matrices correspond to:

```
Gsv = [ Gpr Gpi;
        Gqr Gqi ];
Gpr = d/dVr (dImis_dPg.' * lam)
Gpi = d/dVi (dImis_dPg.' * lam)
Gqr = d/dVr (dImis_dQg.' * lam)
Gqi = d/dVi (dImis_dQg.' * lam)
```

For more details on the derivations behind the derivative code used in MATPOWER, see:

- [TN2] R. D. Zimmerman, "AC Power Flows, Generalized OPF Costs and their Derivatives using Complex Matrix Notation", MATPOWER Technical Note 2, February 2010. [Online]. Available: <https://matpower.org/docs/TN2-OPF-Derivatives.pdf>
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- [TN3] B. Sereeter and R. D. Zimmerman, "Addendum to AC Power Flows and their Derivatives using Complex Matrix Notation: Nodal Current Balance," MATPOWER Technical Note 3, April 2018. [Online]. Available: <https://matpower.org/docs/TN3-More-OPF-Derivatives.pdf>
doi: [10.5281/zenodo.3237900](https://doi.org/10.5281/zenodo.3237900)
- [TN4] B. Sereeter and R. D. Zimmerman, "AC Power Flows and their Derivatives using Complex Matrix Notation and Cartesian Coordinate Voltages," MATPOWER Technical Note 4, April 2018. [Online]. Available: <https://matpower.org/docs/TN4-OPF-Derivatives-Cartesian.pdf>
doi: [10.5281/zenodo.3237909](https://doi.org/10.5281/zenodo.3237909)

d2Sbus_dV2**d2Sbus_dV2**(Ybus, V, lam, vcart)*d2Sbus_dV2*() (page 321) - Computes 2nd derivatives of power injection w.r.t. voltage.

The derivatives can be take with respect to **polar** or cartesian coordinates of voltage, depending on the 4th argument.

```
[GAA, GAV, GVA, GVV] = D2SBUS_DV2(YBUS, V, LAM)
[GAA, GAV, GVA, GVV] = D2SBUS_DV2(YBUS, V, LAM, 0)
```

Returns 4 matrices containing the partial derivatives w.r.t. voltage **angle** and magnitude of the product of a vector LAM with the 1st partial derivatives of the **complex** bus **power** injections.

```
[GRR, GIR, GRI, GII] = D2SBUS_DV2(YBUS, V, LAM, 1)
```

Returns 4 matrices containing the partial derivatives w.r.t. **real** and imaginary parts of voltage of the product of a vector LAM with the 1st partial derivatives of the **complex** bus **power** injections.

Takes **sparse** bus admittance matrix YBUS, voltage vector V and nb x 1 vector of multipliers LAM. Output matrices are **sparse**.

Examples:

```
[Ybus, Yf, Yt] = makeYbus(baseMVA, bus, branch);
[Gaa, Gav, Gva, Gvv] = d2Sbus_dV2(Ybus, V, lam);
```

Here the output matrices correspond to:

```
Gaa = d/dVa (dSbus_dVa.' * lam)
Gav = d/dVm (dSbus_dVa.' * lam)
Gva = d/dVa (dSbus_dVm.' * lam)
Gvv = d/dVm (dSbus_dVm.' * lam)
```

```
[Grr, Gri, Gir, Gii] = d2Sbus_dV2(Ybus, V, lam, 1);
```

Here the output matrices correspond to:

```
Grr = d/dVr (dSbus_dVr.' * lam)
Gri = d/dVi (dSbus_dVr.' * lam)
Gir = d/dVr (dSbus_dVi.' * lam)
Gii = d/dVi (dSbus_dVi.' * lam)
```

For more details on the derivations behind the derivative code used in MATPOWER, see:

- [TN2] R. D. Zimmerman, "AC Power Flows, Generalized OPF Costs and their Derivatives using Complex Matrix Notation", MATPOWER Technical Note 2, February 2010. [Online]. Available: <https://matpower.org/docs/TN2-OPF-Derivatives.pdf>
doi: 10.5281/zenodo.3237866
- [TN4] B. Sereeter and R. D. Zimmerman, "AC Power Flows and their Derivatives using Complex Matrix Notation and Cartesian Coordinate Voltages," MATPOWER Technical Note 4, April 2018. [Online]. Available: <https://matpower.org/docs/TN4-OPF-Derivatives-Cartesian>.

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[↪pdf](#)doi: [10.5281/zenodo.3237909](https://doi.org/10.5281/zenodo.3237909)

5.2.10 LP, QP, MILP & MIQP Solver Functions

miqps_matpower

miqps_matpower(varargin)*miqps_matpower()* (page 322) - Deprecated, please use *miqps_master()* instead.

qps_matpower

qps_matpower(varargin)*qps_matpower()* (page 322) - Deprecated, please use *qps_master()* instead.

5.2.11 Matrix Building Functions

makeB

makeB(baseMVA, bus, branch, alg)*makeB()* (page 322) - Builds the FDPF matrices, B prime and B double prime.

```
[BP, BPP] = MAKEB(MPC, ALG)
[BP, BPP] = MAKEB(BASEMVA, BUS, BRANCH, ALG)
```

Returns the two matrices B prime and B double prime used in the fast decoupled power flow. Does appropriate conversions to p.u. ALG is either 'FDXB' or 'FDBX', the corresponding value of MPOPT.pf.alg option specifying the power flow algorithm. Bus numbers must be consecutive beginning at 1 (i.e. internal ordering).

Note: For backward compatibility, ALG can also take on a value of 2 or 3, corresponding to values of the old PF_ALG option. This usage is deprecated and will be removed in a future version.

Example:

```
[Bp, Bpp] = makeB(baseMVA, bus, branch, 'FDXB');
```

See also *fdpf()*.

makeBdc

makeBdc(baseMVA, bus, branch)

[makeBdc\(\)](#) (page 323) - Builds the B matrices and phase shift injections for DC power flow.

```
[BBUS, BF, PBUSINJ, PFINJ] = MAKEBDC(MPC)
[BBUS, BF, PBUSINJ, PFINJ] = MAKEBDC(BASEMVA, BUS, BRANCH)
```

Returns the B matrices and phase shift injection vectors needed for a DC power flow. The bus real power injections are related to bus voltage angles by

$$P = BBUS * Va + PBUSINJ$$

The real power flows at the from end the lines are related to the bus voltage angles by

$$Pf = BF * Va + PFINJ$$

Does appropriate conversions to p.u.

Bus numbers must be consecutive beginning at 1 (i.e. internal ordering).

Example:

```
[Bbus, Bf, Pbusinj, Pfinj] = makeBdc(baseMVA, bus, branch);
```

See also [dcpf\(\)](#).

makeJac

makeJac(baseMVA, bus, branch, gen, fullJac)

[makeJac\(\)](#) (page 323) - Forms the power flow Jacobian.

```
J = MAKEJAC(MPC)
J = MAKEJAC(MPC, FULLJAC)
J = MAKEJAC(BASEMVA, BUS, BRANCH, GEN)
J = MAKEJAC(BASEMVA, BUS, BRANCH, GEN, FULLJAC)
[J, YBUS, YF, YT] = MAKEJAC(MPC)
```

Returns the power flow Jacobian and, optionally, the system admittance matrices. Inputs can be a MATPOWER case struct or individual BASEMVA, BUS, BRANCH and GEN values. Bus numbers must be consecutive beginning at 1 (i.e. internal ordering). If the FULLJAC argument is present and true, it returns the full Jacobian (sensitivities of all bus injections w.r.t all voltage angles/magnitudes) as opposed to the reduced version used in the Newton power flow updates. The units for all quantities are in per unit with radians for voltage angles.

Note: This function builds the Jacobian from scratch, rebuilding the YBUS matrix in the process. You probably don't want to use this in performance critical code.

See also [makeYbus\(\)](#) (page 326), [ext2int\(\)](#).

makeLODF

makeLODF(*branch*, *PTDF*, *mask_bridge*)

makeLODF() (page 324) - Builds the line outage distribution factor matrix.

```

LODF = MAKELODF(BRANCH, PTDF)
LODF = MAKELODF(MPC, PTDF)
LODF = MAKELODF(MPC, PTDF, MASK_BRIDGE)

```

Returns the DC model **line** outage distribution **factor** matrix corresponding to a given PTDF matrix. The LODF matrix is *nbr* x *nbr*, where *nbr* is the number of branches. If the optional MASK_BRIDGE argument is **true**, **columns** corresponding to bridge branches (those whose removal result in islanding) are replaced with **NaN**.

Example:

```

H = makePTDF(mpc);
LODF = makeLODF(branch, H);
LODF = makeLODF(mpc, H);

% mask bridge branches in LODF
makeLODF(mpc, H, 1);

```

See also *makePTDF()* (page 324), *find_bridges()* (page 332).

makePTDF

makePTDF(*baseMVA*, *bus*, *branch*, *slack*, *bus_idx*)

makeLODF() (page 324) - Builds the DC PTDF matrix for a given choice of slack.

```

H = MAKEPTDF(MPC)
H = MAKEPTDF(MPC, SLACK)
H = MAKEPTDF(MPC, SLACK, TXFR)
H = MAKEPTDF(MPC, SLACK, BUS_IDX)
H = MAKEPTDF(BASEMVA, BUS, BRANCH)
H = MAKEPTDF(BASEMVA, BUS, BRANCH, SLACK)
H = MAKEPTDF(BASEMVA, BUS, BRANCH, SLACK, TXFR)
H = MAKEPTDF(BASEMVA, BUS, BRANCH, SLACK, BUS_IDX)

```

Returns the DC PTDF matrix **for** a given choice of slack. The matrix is *nbr* x *nb*, where *nbr* is the number of branches **and** *nb* is the number of buses. The SLACK can be a scalar (**single** slack bus) **or** an *nb* x **1** column vector of weights specifying the proportion of the slack taken up at each bus. If the SLACK is **not** specified the reference bus is used by default. Bus numbers must be consecutive beginning at **1** (i.e. internal ordering).

For convenience, SLACK can also be an *nb* x *nb* matrix, where each column specifies how the slack should be handled **for** injections at that bus. This option only applies when computing the **full** PTDF matrix (i.e. when TXFR **and** BUS_IDX are **not** provided.)

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If TXFR is supplied it must be a matrix (or vector) with nb rows whose columns each sum to zero, where each column defines a specific (slack independent) transfer. E.g. if k-th transfer is from bus i to bus j, TXFR(i, k) = 1 and TXFR(j, k) = -1. In this case H has the same number of columns as TXFR.

If BUS_IDX is supplied, it contains a column vector of bus indices. The columns of H correspond to these indices, but they are computed individually rather than computing the full PTDF matrix and selecting the desired columns.

Examples:

```
H = makePTDF(mpc);
H = makePTDF(baseMVA, bus, branch, 1);
slack = rand(size(bus, 1), 1);
H = makePTDF(mpc, slack);

% for transfer from bus i to bus j
txfr = zeros(nb, 1); txfr(i) = 1; txfr(j) = -1;
H = makePTDF(mpc, slack, txfr);

% for buses i and j only
H = makePTDF(mpc, slack, [i;j]);
```

See also [makeLODF\(\)](#) (page 324).

makeSbus

makeSbus(baseMVA, bus, gen, mpopt, Vm, Sg)

[makeSbus\(\)](#) (page 325) - Builds the vector of complex bus power injections.

```
SBUS = MAKESBUS(BASEMVA, BUS, GEN)
SBUS = MAKESBUS(BASEMVA, BUS, GEN, MPOPT, VM)
SBUS = MAKESBUS(BASEMVA, BUS, GEN, MPOPT, VM, SG)
```

returns the vector of complex bus power injections, that is, generation minus load. Power is expressed in per unit. If the MPOPT and VM arguments are present it evaluates any ZIP loads based on the provided voltage magnitude vector. If VM is empty, it assumes nominal voltage. If SG is provided, it is a complex ng x 1 vector of generator power injections in p.u., and overrides the PG and QG columns in GEN, using GEN only for connectivity information.

```
[SBUS, DSBUS_DVM] = MAKESBUS(BASEMVA, BUS, GEN, MPOPT, VM)
```

With two output arguments, it computes the partial derivative of the bus injections with respect to voltage magnitude, leaving the first return value SBUS empty. If VM is empty, it assumes no voltage dependence and returns a sparse zero matrix.

See also [makeYbus\(\)](#) (page 326).

makeSdzip

makeSdzip(baseMVA, bus, mpopt)

[makeSdzip\(\)](#) (page 326) - Builds vectors of nominal complex bus power demands for ZIP loads.

SD = MAKESDZIP(BASEMVA, BUS, MPOPT) returns a **struct** with three fields, each an nb x 1 vectors. The fields 'z', 'i' and 'p' correspond to the nominal p.u. **complex power** (at 1 p.u. voltage magnitude) of the constant impedance, constant current, and constant **power** portions, respectively of the ZIP load model.

Example:

```
Sd = makeSdzip(baseMVA, bus, mpopt);
```

makeYbus

makeYbus(baseMVA, bus, branch)

[makeYbus\(\)](#) (page 326) - Builds the bus admittance matrix and branch admittance matrices.

```
[YBUS, YF, YT] = MAKEYBUS(MPC)
[YBUS, YF, YT] = MAKEYBUS(BASEMVA, BUS, BRANCH)
```

Returns the **full** bus admittance matrix (i.e. **for all** buses) and the matrices YF and YT which, when multiplied by a **complex** voltage vector, yield the vector currents injected into each **line** from the "from" and "to" buses respectively of each **line**. Does appropriate conversions to p.u. Inputs can be a MATPOWER **case struct** or individual BASEMVA, BUS and BRANCH values. Bus numbers must be consecutive beginning at 1 (i.e. internal ordering).

See also [makeJac\(\)](#) (page 323), [makeSbus\(\)](#) (page 325), ext2int().

5.2.12 Utility Functions

apply_changes

apply_changes(label, mpc, chgtab)

[apply_changes\(\)](#) (page 326) - Applies a set of changes to a MATPOWER case

```
mpc_modified = apply_changes(label, mpc_original, chgtab)
```

Applies the **set** of changes identified by LABEL to the **case** in MPC, where the change sets are specified in CHGTAB.

LABEL is an integer which identifies the **set** of changes of interest

MPC is a MATPOWER **case struct** with at least fields bus, gen and branch

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CHGTAB is the **table** of changes that lists the individual changes required by each change **set**, one "change" per row (multiple **rows** or changes allowed **for** each change **set**). Type "**help idx_ct**" **for** more complete information about the format.

1st column: change **set** label, integer > 0

2nd column: change **set** probability

3rd column: **table** to be modified (1:bus, 2:gen, 3:branch) **or** 4: bus **area** changes, apply to **all** gens/buses/branches in a given **area**; 5: gen **table area** changes apply to **all** generators in a given **area**; **or** 6: branch **area** changes apply to **all** branches connected to buses in a given **area**.

4th column: row of **table** to be modified (**if** 3rd col is 1-3), **or area** number **for** overall changes (**if** 3rd column is 4-6).

5th column: column of **table** to be modified. It is best to use the named column **index** defined in the corresponding **idx_bus**, **idx_gen**, **idx_branch** **or** **idx_cost** M-files in MATPOWER.

6th column: **type** of change: 1: absolute (replace)
2: relative (multiply by **factor**)
3: additive (add to value)

7th column: new value **or** multiplicative **or** additive **factor**

Examples:

```
chgtab = [ ...
    1  0.1  CT_TGEN      2  GEN_STATUS  CT_REP  0;
    2  0.05 CT_TGEN      3  PMAX         CT_REP 100;
    3  0.2  CT_TBRCH     2  BR_STATUS   CT_REP  0;
    4  0.1  CT_TAREALOAD 2  CT_LOAD_ALL_P CT_REL  1.1;
];
```

Description of each change **set**:

1. Turn off generator 2, 10% **probability**.
2. Set generator 3's **max** output to 100 MW, 5% **probability**.
3. Take branch 2 out of service, 20% **probability**.
4. Scale **all** loads in **area** 2 (**real** & reactive, fixed **and** dispatchable) by a **factor** of 1.1, 10% **probability**.

See also **idx_ct()** (page 339).

bustypes

bustypes(bus, gen)

bustypes() - Builds index lists for each type of bus (REF, PV, PQ).

[REF, PV, PQ] = **BUSTYPES**(BUS, GEN)

Generators with "out-of-service" status are treated as PQ buses with zero generation (regardless of Pg/Qg values in gen). Expects **BUS** **and** **GEN** have been converted to use internal consecutive bus numbering.

calc_branch_angle

calc_branch_angle(*mpc*)

[calc_branch_angle\(\)](#) (page 328) - Calculate branch angle differences across active branches

```
DELTA = CALC_BRANCH_ANGLE(MPC)
```

Calculates the **angle** difference (in degrees) across **all** active branches in the MATPOWER **case**. Angles are calculated as the difference between the FROM bus **and** the TO bus.

Input:

MPC - MATPOWER **case struct** (can have external bus numbering)

Output:

DELTA - $n_l \times 1$ vector of branch **angle** differences $A_f - A_t$, where A_f **and** A_t are vectors of voltage angles at "from" **and** "to" ends of each **line** respectively. DELTA is 0 **for** out-of-service branches.

See also [toggle_softlims\(\)](#) (page 305).

case_info

case_info(*mpc*, *fd*)

[case_info\(\)](#) (page 328) - Prints information about islands in a network.

```
CASE_INFO(MPC)
CASE_INFO(MPC, FD)
[GROUPS, ISOLATED] = CASE_INFO(...)
```

Prints out detailed information about a MATPOWER **case**. Optionally prints to an open file, whose file identifier, as returned by FOPEN, is specified in the optional second parameter FD. Optional **return** arguments include GROUPS **and** ISOLATED buses, as returned by FIND_ISLANDS.

compare_case

compare_case(*mpc1*, *mpc2*)

[compare_case\(\)](#) (page 328) - Compares the bus, gen, branch matrices of 2 MATPOWER cases.

```
COMPARE_CASE(MPC1, MPC2)
```

Compares the bus, branch **and** gen matrices of two MATPOWER cases **and** prints a summary of the differences. For each column of the matrix it prints the maximum of **any** non-zero differences.

define_constants

define_constants()

define_constants - Defines useful constants for indexing data, etc.

This is simply a convenience script that defines the constants listed below, consisting primarily of named indices **for** the **columns** of the data matrices: bus, branch, gen **and** gencost. This includes **input columns** defined in caseformat as well as **columns** that are added in the **power** flow **and** OPF output. It also defines constants **for** the change tables used by apply_changes().

bus:

PQ, PV, REF, NONE, BUS_I, BUS_TYPE, PD, QD, GS, BS, BUS_AREA, VM, VA, BASE_KV, ZONE, VMAX, VMIN, LAM_P, LAM_Q, MU_VMAX, MU_VMIN

branch:

F_BUS, T_BUS, BR_R, BR_X, BR_B, RATE_A, RATE_B, RATE_C, TAP, SHIFT, BR_STATUS, PF, QF, PT, QT, MU_SF, MU_ST, ANGMIN, ANGMAX, MU_ANGMIN, MU_ANGMAX

gen:

GEN_BUS, PG, QG, QMAX, QMIN, VG, MBASE, GEN_STATUS, PMAX, PMIN, MU_PMAX, MU_PMIN, MU_QMAX, MU_QMIN, PC1, PC2, QC1MIN, QC1MAX, QC2MIN, QC2MAX, RAMP_AGC, RAMP_10, RAMP_30, RAMP_Q, APF

gencost:

PW_LINEAR, POLYNOMIAL, MODEL, STARTUP, SHUTDOWN, NCOST, COST

change tables:

CT_LABEL, CT_PROB, CT_TABLE, CT_TBUS, CT_TGEN, CT_TBRCH, CT_TAREABUS, CT_TAREAGEN, CT_TAREABRCH, CT_ROW, CT_COL, CT_CHGTYPE, CT_REP, CT_REL, CT_ADD, CT_NEWVAL, CT_TLOAD, CT_TAREALOAD, CT_LOAD_ALL_PQ, CT_LOAD_FIX_PQ, CT_LOAD_DIS_PQ, CT_LOAD_ALL_P, CT_LOAD_FIX_P, CT_LOAD_DIS_P, CT_TGENCOST, CT_TAREAGENCOST, CT_MODCOST_F, CT_MODCOST_X

See CASEFORMAT, IDX_BUS, IDX_BRCH, IDX_GEN, IDX_COST **and** IDX_CT **for** details on the meaning of these constants. Internally DEFINE_CONSTANTS calls IDX_BUS, IDX_BRCH, IDX_GEN, IDX_COST **and** IDX_CT. In performance sensitive code, such as internal MATPOWER **functions** that are called frequently, it is preferred to call these **functions** directly rather than using the DEFINE_CONSTANTS script, which is less efficient.

This script is included **for** convenience **for** interactive use **or** **for** high-level code where maximum performance is **not** a concern.

extract_islands

extract_islands(*mpc*, *varargin*)

extract_islands() (page 330) - Extracts each island in a network with islands.

```

MPC_ARRAY = EXTRACT_ISLANDS(MPC)
MPC_ARRAY = EXTRACT_ISLANDS(MPC, GROUPS)
MPC_K = EXTRACT_ISLANDS(MPC, K)
MPC_K = EXTRACT_ISLANDS(MPC, GROUPS, K)
MPC_K = EXTRACT_ISLANDS(MPC, K, CUSTOM)
MPC_K = EXTRACT_ISLANDS(MPC, GROUPS, K, CUSTOM)

```

Returns a **cell** array of MATPOWER **case** structs **for** each island in the **input case struct**. If the optional second argument is a **cell** array GROUPS it is assumed to be a **cell** array of vectors of bus indices **for** each island (as returned by FIND_ISLANDS). Providing the GROUPS avoids the need **for** another traversal of the network connectivity **and** can save a significant amount of **time** on very large systems. If an additional argument K is included, it indicates which island(s) to **return** and the **return** value is a **single case struct**, rather than a **cell** array. If K is a scalar **or** vector, it specifies the **index**(indices) of the island(s) to include in the resulting **case** file. K can also be the string '**all**' which will include **all** islands. This is the same as simply eliminating **all** isolated buses.

A final optional argument CUSTOM is a **struct** that can be used to indicate custom fields of MPC from which to extract data corresponding to buses generators, branches **or** DC lines. It has the following structure:

```
CUSTOM.<ORDERING>{DIM} = FIELDS
```

<ORDERING> is either '**bus**', '**gen**', '**branch**' **or** '**dcline**' **and** indicates that dimension DIM of FIELDS has dimensions corresponding to this <ORDERING> **and** should have the appropriate dimension extracted as well. FIELDS is a **cell** array, where each element is either a **single** string (field name of MPC) **or** a **cell** array of strings (nested fields of MPC).

Examples:

Extract each island into it's own **case struct**:

```
mpc_list = extract_islands(mpc);
```

Extract the **2nd** (that is, **2nd** largest) island:

```
mpc2 = extract_islands(mpc, 2);
```

Extract the first **and** **3rd** islands without a re-traversals of the network:

```

groups = find_islands(mpc);
mpc1 = extract_islands(mpc, groups, 1);
mpc3 = extract_islands(mpc, groups, 3);

```

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Extract the 2nd island, including custom fields, where `mpc.bus_label{b}` contains a label for bus `b`, and `mpc.gen_name{g}`, `mpc.emissions.rate(g, :)`, and `mpc.genloc(:, g)` contain, respectively, the generator's name, emission rates and location coordinates:

```
custom.bus{1} = {'bus_label'};
custom.gen{1} = {'gen_name', {'emissions', 'rate'}};
custom.gen{2} = {'genloc'};
mpc = extract_islands(mpc, 1, custom);
```

Note: Fields `bus_name`, `gentype` and `genfuel` are handled automatically and do not need to be included in `custom`.

See also `find_islands()` (page 332), `case_info()` (page 328), `connected_components()` (page 352).

feval_w_path

feval_w_path(*fpath*, *fname*, *varargin*)

feval_w_path() (page 331) - Calls a function located by the specified path.

```
FEVAL_W_PATH(FPATH, F, x1, ..., xn)
[y1, ..., yn] = FEVAL_W_PATH(FPATH, F, x1, ..., xn)
```

Identical to the built-in `FEVAL`, except that the function `F` need not be in the MATLAB/Octave path if it is defined in a file in the path specified by `FPATH`. Assumes that the current working directory is always first in the MATLAB/Octave path.

Inputs:

`FPATH` - string containing the path to the function to be called, can be absolute or relative to current working directory
`F` - string containing the name of the function to be called
`x1, ..., xn` - variable number of input arguments to be passed to `F`

Output:

`y1, ..., yn` - variable number arguments returned by `F` (depending on the caller)

Note that any sub-functions located in the directory specified by `FPATH` will also be available to be called by the `F` function.

Examples:

```
% Assume '/opt/testfunctions' is NOT in the MATLAB/Octave path, but
% /opt/testfunctions/mytestfcn.m defines the function mytestfcn()
% which takes 2 input arguments and outputs 1 return argument.
y = feval_w_path('/opt/testfunctions', 'mytestfcn', x1, x2);
```

find_bridges

find_bridges(*mpc*)

find_bridges() (page 332) - Finds bridges in a network.

```
[ISLANDS, BRIDGES, NONBRIDGES] = FIND_BRIDGES(MPC)
```

Returns the islands, bridges **and** non-bridges in a network.

Bridges are filtered out using Tarjan's algorithm. A BRIDGE is a branch whose removal breaks the island to multiple parts. The **return** value BRIDGES is a **cell** array of vectors of the bus indices **for** each island.

find_islands

find_islands(*mpc*)

find_islands() (page 332) - Finds islands in a network.

```
GROUPS = FIND_ISLANDS(MPC)  
[GROUPS, ISOLATED] = FIND_ISLANDS(MPC)
```

Returns the islands in a network. The **return** value GROUPS is a **cell** array of vectors of the bus indices **for** each island. The second **and** optional **return** value ISOLATED is a vector of indices of isolated buses that have no connecting branches.

See also *extract_islands()* (page 330), *connected_components()* (page 352).

genfuels

genfuels()

genfuels() - Return list of standard values for generator fuel types.

```
GF = GENFUELS()
```

Returns a **cell** array of strings containing the following standard generator fuel types **for** use in the optional MPC.GENFUEL field of the MATPOWER **case struct**. This is to be considered an unordered list, where the position of a particular fuel **type** in the list is **not** defined **and** is therefore subject to change.

biomass	- Biomass
coal	- Coal
dfo	- Distillate Fuel Oil (Diesel, F01, F02, F04)
geothermal	- Geothermal
hydro	- Hydro
hydrops	- Hydro Pumped Storage
jetfuel	- Jet Fuel
lng	- Liquefied Natural Gas

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ng	- Natural Gas
nuclear	- Nuclear
oil	- Unspecified Oil
refuse	- Refuse, Municipal Solid Waste
rfo	- Residual Fuel Oil (F05, F06)
solar	- Solar
syncgen	- Synchronous Condensor
wasteheat	- Waste Heat
wind	- Wind
wood	- Wood or Wood Waste
other	- Other
unknown	- Unknown
dl	- Dispatchable Load
ess	- Energy Storage System

Example:

```

if ~ismember(mpc.genfuel{k}, genfuels())
    error('unknown fuel type');
end

```

See also `gentypes()`, `savecase()`.

gentypes

gentypes()

`gentypes()` - Return list of standard values for generator unit types.

```
GT = GENTYPES()
```

Returns a **cell** array of strings containing the following standard two character generator unit types **for** use in the optional MPC.GENTYPE field of the MATPOWER **case struct**. This is to be considered an unordered list, where the position of a particular fuel **type** in the list is **not** defined **and** is therefore subject to change.

From Form EIA-860 Instructions, Table 2. Prime Mover Codes **and** Descriptions
https://www.eia.gov/survey/form/eia_860/instructions.pdf

BA	- Energy Storage, Battery
CE	- Energy Storage, Compressed Air
CP	- Energy Storage, Concentrated Solar Power
FW	- Energy Storage, Flywheel
PS	- Hydraulic Turbine, Reversible (pumped storage)
ES	- Energy Storage, Other
ST	- Steam Turbine, including nuclear, geothermal and solar steam (does not include combined cycle)
GT	- Combustion (Gas) Turbine (includes jet engine design)
IC	- Internal Combustion Engine (diesel, piston, reciprocating)
CA	- Combined Cycle Steam Part
CT	- Combined Cycle Combustion Turbine Part (type of coal or solid must be reported as energy source)

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```

    for integrated coal gasification)
CS - Combined Cycle Single Shaft
    (combustion turbine and steam turbine share a single generator)
CC - Combined Cycle Total Unit
    (use only for plants/generators that are in planning stage,
    for which specific generator details cannot be provided)
HA - Hydrokinetic, Axial Flow Turbine
HB - Hydrokinetic, Wave Buoy
HK - Hydrokinetic, Other
HY - Hydroelectric Turbine (includes turbines associated with
    delivery of water by pipeline)
BT - Turbines Used in a Binary Cycle
    (including those used for geothermal applications)
PV - Photovoltaic
WT - Wind Turbine, Onshore
WS - Wind Turbine, Offshore
FC - Fuel Cell
OT - Other
Additional codes (some from PowerWorld)
UN - Unknown
JE - Jet Engine
NB - ST - Boiling Water Nuclear Reactor
NG - ST - Graphite Nuclear Reactor
NH - ST - High Temperature Gas Nuclear Reactor
NP - ST - Pressurized Water Nuclear Reactor
IT - Internal Combustion Turbo Charged
SC - Synchronous Condenser
DC - represents DC ties
MP - Motor/Pump
W1 - Wind Turbine, Type 1
W2 - Wind Turbine, Type 2
W3 - Wind Turbine, Type 3
W4 - Wind Turbine, Type 4
SV - Static Var Compensator
DL - Dispatchable Load

```

Example:

```

if ~ismember(mpc.gentype{k}, gentypes())
    error('unknown generator unit type');
end

```

See also `genfuels()`, `savecase()`.

get_losses

get_losses(baseMVA, bus, branch)

get_losses() (page 335) - Returns series losses (and reactive injections) per branch.

```

LOSS = GET_LOSSES(RESULTS)
LOSS = GET_LOSSES(BASEMVA, BUS, BRANCH)

[LOSS, CHG] = GET_LOSSES(RESULTS)
[LOSS, FCHG, TCHG] = GET_LOSSES(RESULTS)
[LOSS, FCHG, TCHG, DLOSS_DV] = GET_LOSSES(RESULTS)
[LOSS, FCHG, TCHG, DLOSS_DV, DCHG_DVM] = GET_LOSSES(RESULTS)

```

Computes branch series losses, and optionally reactive injections from line charging, as functions of bus voltages and branch parameters, using the following formulae:

$$\begin{aligned} \text{loss} &= \text{abs}(V_f / \tau - V_t)^2 / (R_s - j X_s) \\ \text{fchg} &= \text{abs}(V_f / \tau)^2 * B_c / 2 \\ \text{tchg} &= \text{abs}(V_t)^2 * B_c / 2 \end{aligned}$$

Optionally, computes the partial derivatives of the line losses with respect to voltage angles and magnitudes.

Input:

RESULTS - a MATPOWER case struct with bus voltages corresponding to a valid power flow solution.
(Can optionally be specified as individual fields BASEMVA, BUS, and BRANCH.)

Output(s):

LOSS - complex NL x 1 vector of losses (in MW), where NL is the number of branches in the system, representing only the losses in the series impedance element of the PI model for each branch.

CHG - NL x 1 vector of total reactive injection for each line (in MVAR), representing the line charging injections of both of the shunt elements of PI model for each branch.

FCHG - Same as CHG, but for the element at the "from" end of the branch only.

TCHG - Same as CHG, but for the element at the "to" end of the branch.

DLOSS_DV - Struct with partial derivatives of LOSS with respect to bus voltages, with fields:

- .a - Partial with respect to bus voltage angles.
- .m - Partial with respect to bus voltage magnitudes.

DCHG_DVM - Struct with partial derivatives of FCHG and TCHG with respect to bus voltage magnitudes, with fields:

- .f - Partial of FCHG with respect to bus voltage magnitudes.
- .t - Partial of TCHG with respect to bus voltage magnitudes.

Example:

```

results = runpf(mybase);
[loss, chg] = get_losses(results);
total_system_real_losses = sum(real(loss));

```

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(continued from previous page)

```
total_system_reac_losses = sum(imag(loss)) - sum(chg);

[loss, fchg, tchg, dloss_dV] = get_losses(results);
```

hasPQcap

hasPQcap(*gen, hilo*)

hasPQcap() (page 336) - Checks for P-Q capability curve constraints.

TORF = HASPQCAP(GEN, HILO) returns a column vector of 1's and 0's. The 1's correspond to rows of the GEN matrix which correspond to generators which have defined a capability curve (with sloped upper and/or lower bound on Q) and require that additional linear constraints be added to the OPF.

The GEN matrix in version 2 of the MATPOWER case format includes columns for specifying a P-Q capability curve for a generator defined as the intersection of two half-planes and the box constraints on P and Q. The two half planes are defined respectively as the area below the line connecting (Pc1, Qc1max) and (Pc2, Qc2max) and the area above the line connecting (Pc1, Qc1min) and (Pc2, Qc2min).

If the optional 2nd argument is 'U' this function returns true only for rows corresponding to generators that require the upper constraint on Q. If it is 'L', only for those requiring the lower constraint. If the 2nd argument is not specified or has any other value it returns true for rows corresponding to gens that require either or both of the constraints.

It is smart enough to return true only if the corresponding linear constraint is not redundant w.r.t the box constraints.

idx_brch

idx_brch()

idx_brch() (page 336) - Defines constants for named column indices to branch matrix.

Example:

```
[F_BUS, T_BUS, BR_R, BR_X, BR_B, RATE_A, RATE_B, RATE_C, ...
TAP, SHIFT, BR_STATUS, PF, QF, PT, QT, MU_SF, MU_ST, ...
ANGMIN, ANGMAX, MU_ANGMIN, MU_ANGMAX] = idx_brch;
```

Some examples of usage, after defining the constants using the line above, are:

```
branch(4, BR_STATUS) = 0; % take branch 4 out of service
Ploss = branch(:, PF) + branch(:, PT); % compute real power loss vector
```

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The `index`, name and meaning of each column of the branch matrix is given below:

columns 1-11 must be included in `input` matrix (in `case` file)

1	F_BUS	f, from bus number
2	T_BUS	t, to bus number
3	BR_R	r, resistance (p.u.)
4	BR_X	x, reactance (p.u.)
5	BR_B	b, total line charging susceptance (p.u.)
6	RATE_A	rateA, MVA rating A (long term rating)
7	RATE_B	rateB, MVA rating B (short term rating)
8	RATE_C	rateC, MVA rating C (emergency rating)
9	TAP	ratio, transformer off nominal turns ratio
10	SHIFT	angle, transformer phase shift angle (degrees)
11	BR_STATUS	initial branch status, 1 - in service, 0 - out of service
12	ANGMIN	minimum angle difference, $\text{angle}(V_f) - \text{angle}(V_t)$ (degrees)
13	ANGMAX	maximum angle difference, $\text{angle}(V_f) - \text{angle}(V_t)$ (degrees)

(The voltage angle difference is taken to be unbounded below if `ANGMIN` < -360 and unbounded above if `ANGMAX` > 360. If both parameters are zero, it is unconstrained.)

columns 14-17 are added to matrix after power flow or OPF solution
they are typically not present in the `input` matrix

14	PF	real power injected into "from" end of branch (MW)
15	QF	reactive power injected into "from" end of branch (MVar)
16	PT	real power injected into "to" end of branch (MW)
17	QT	reactive power injected into "to" end of branch (MVar)

columns 18-21 are added to matrix after OPF solution

they are typically not present in the `input` matrix

		(assume OPF objective function has units, u)
18	MU_SF	Kuhn-Tucker multiplier on MVA limit at "from" bus (u/MVA)
19	MU_ST	Kuhn-Tucker multiplier on MVA limit at "to" bus (u/MVA)
20	MU_ANGMIN	Kuhn-Tucker multiplier lower angle difference limit (u/degree)
21	MU_ANGMAX	Kuhn-Tucker multiplier upper angle difference limit (u/degree)

See also `define_constants`.

idx_bus

idx_bus()

`idx_bus()` (page 337) - Defines constants for named column indices to bus matrix.

Example:

```
[PQ, PV, REF, NONE, BUS_I, BUS_TYPE, PD, QD, GS, BS, BUS_AREA, VM, ...
VA, BASE_KV, ZONE, VMAX, VMIN, LAM_P, LAM_Q, MU_VMAX, MU_VMIN] = idx_bus;
```

Some examples of `usage`, after defining the constants using the `line` above, are:

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```
Pd = bus(4, PD);      % get the real power demand at bus 4
bus(:, VMIN) = 0.95;  % set the min voltage magnitude to 0.95 at all buses
```

The **index**, **name** and **meaning** of each column of the bus matrix is given below:

columns 1-13 must be included in **input** matrix (in **case** file)

1	BUS_I	bus number (positive integer)
2	BUS_TYPE	bus type (1 = PQ, 2 = PV, 3 = ref, 4 = isolated)
3	PD	Pd, real power demand (MW)
4	QD	Qd, reactive power demand (MVar)
5	GS	Gs, shunt conductance (MW demanded at V = 1.0 p.u.)
6	BS	Bs, shunt susceptance (MVar injected at V = 1.0 p.u.)
7	BUS_AREA	area number, (positive integer)
8	VM	Vm, voltage magnitude (p.u.)
9	VA	Va, voltage angle (degrees)
10	BASE_KV	baseKV, base voltage (kV)
11	ZONE	zone, loss zone (positive integer)
12	VMAX	maxVm, maximum voltage magnitude (p.u.)
13	VMIN	minVm, minimum voltage magnitude (p.u.)

columns 14-17 are added to matrix after OPF solution

they are typically **not** present in the **input** matrix

		(assume OPF objective function has units, u)
14	LAM_P	Lagrange multiplier on real power mismatch (u/MW)
15	LAM_Q	Lagrange multiplier on reactive power mismatch (u/MVar)
16	MU_VMAX	Kuhn-Tucker multiplier on upper voltage limit (u/p.u.)
17	MU_VMIN	Kuhn-Tucker multiplier on lower voltage limit (u/p.u.)

additional constants, used to assign/compare values in the BUS_TYPE column

1	PQ	PQ bus
2	PV	PV bus
3	REF	reference bus
4	NONE	isolated bus

See also `define_constants`.

idx_cost

idx_cost()

`idx_cost()` (page 338) - Defines constants for named column indices to `gencost` matrix.

Example:

```
[PW_LINEAR, POLYNOMIAL, MODEL, STARTUP, SHUTDOWN, NCOST, COST] = idx_cost;
```

Some examples of **usage**, after defining the constants using the **line** above, are:

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```

start = gencost(4, STARTUP);           % get startup cost of generator 4
gencost(2, [MODEL, NCOST:COST+1]) = [ POLYNOMIAL 2 30 0 ];
% set the cost of generator 2 to a linear function COST = 30 * Pg

```

The **index**, **name** and **meaning** of each column of the gencost matrix is given below:

columns 1-5

1	MODEL	cost model, 1 = piecewise linear, 2 = polynomial
2	STARTUP	startup cost in US dollars
3	SHUTDOWN	shutdown cost in US dollars
4	NCOST	number $N = n+1$ of data points to follow defining an n -segment piecewise linear cost function , or of cost coefficients defining an n -th order polynomial cost function
5	COST	parameters defining total cost function $f(p)$ begin in this column (MODEL = 1) : $p_1, f_1, p_2, f_2, \dots, p_N, f_N$ where $p_1 < p_2 < \dots < p_N$ and the cost $f(p)$ is defined by the coordinates $(p_1, f_1), (p_2, f_2), \dots, (p_N, f_N)$ of the end/break -points of the piecewise linear cost fcn (MODEL = 2) : c_n, \dots, c_1, c_0 N coefficients of an n -th order polynomial cost function , starting with highest order, where cost is $f(p) = c_n * p^n + \dots + c_1 * p + c_0$

additional constants, used to assign/compare values in the MODEL column

1	PW_LINEAR	piecewise linear generator cost model
2	POLYNOMIAL	polynomial generator cost model

See also `define_constants`.

idx_ct

idx_ct()

`idx_ct()` (page 339) - Defines constants for named column indices to changes table

```

[CT_LABEL, CT_PROB, CT_TABLE, CT_TBUS, CT_TGEN, CT_TBRCH, CT_TAREABUS, ...
CT_TAREAGEN, CT_TAREABRCH, CT_ROW, CT_COL, CT_CHGTYPE, CT_REP, ...
CT_REL, CT_ADD, CT_NEWVAL, CT_TLOAD, CT_TAREALOAD, CT_LOAD_ALL_PQ, ...
CT_LOAD_FIX_PQ, CT_LOAD_DIS_PQ, CT_LOAD_ALL_P, CT_LOAD_FIX_P, ...
CT_LOAD_DIS_P, CT_TGENCOST, CT_TAREAGENCOST, CT_MODCOST_F, ...
CT_MODCOST_X] = idx_ct;

```

CT_LABEL: column of changes **table** where the change **set** label is stored

CT_PROB: column of changes **table** where the probability of the change **set** is stored

CT_TABLE: column of the changes **table** where the **type** of **system** data **table** to be modified is stored;

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```

type CT_TBUS indicates bus table
type CT_TGEN indicates gen table
type CT_TBRCH indicates branch table
type CT_TLOAD indicates a load modification (bus and/or gen tables)
type CT_TAREABUS indicates area-wide change in bus table
type CT_TAREAGEN indicates area-wide change in generator table
type CT_TAREABRCH indicates area-wide change in branch table
type CT_TAREALOAD indicates area-wide change in load
                        (bus and/or gen tables)

```

CT_ROW: column of changes table where the row number in the data table to be modified is stored. A value of "0" in this column has the special meaning "apply to all rows". For an area-wide type of change, the area number is stored here instead.

CT_COL: column of changes table where the number of the column in the data table to be modified is stored
 For CT_TLOAD and CT_TAREALOAD, the value entered in this column is one of the following codes (or its negative), rather than a column index:

```

type CT_LOAD_ALL_PQ modify all loads, real & reactive
type CT_LOAD_FIX_PQ modify only fixed loads, real & reactive
type CT_LOAD_DIS_PQ modify only dispatchable loads, real & reactive
type CT_LOAD_ALL_P modify all loads, real only
type CT_LOAD_FIX_P modify only fixed loads, real only
type CT_LOAD_DIS_P modify only dispatchable loads, real only

```

If the negative of one of these codes is used, then any affected dispatchable loads will have their costs scaled as well.

For CT_TGENCOST and CT_TAREAGENCOST, in addition to an actual column index, this value can also take one of the following codes to indicate a scaling (CT_REL change type) or shifting (CT_ADD change type) of the specified cost functions:

```

type CT_MODCOST_F scales or shifts the cost function vertically
type CT_MODCOST_X scales or shifts the cost function horizontally

```

See MODCOST.

CT_CHGTYPE: column of changes table where the type of change to be made is stored:

```

type CT_REP replaces old value by value in CT_NEWVAL column
type CT_REL multiplies old value by factor in CT_NEWVAL column
type CT_ADD adds value in CT_NEWVAL column to old value

```

See also [apply_changes\(\)](#) (page 326), [modcost\(\)](#).

idx_dcline

idx_dcline()

idx_dcline() (page 341) - Defines constants for named column indices to dcline matrix.

Example:

```
c = idx_dcline;
```

Some examples of *usage*, after defining the constants using the *line* above, are:

```
mpc.dcline(4, c.BR_STATUS) = 0;           % take dcline 4 out of service
```

The *index*, name and meaning of each column of the dcline matrix is given below:

columns 1-17 must be included in *input* matrix (in *case* file)

1	F_BUS	f, "from" bus number
2	T_BUS	t, "to" bus number
3	BR_STATUS	initial dcline status, 1 - in service, 0 - out of service
4	PF	MW flow at "from" bus ("from" -> "to")
5	PT	MW flow at "to" bus ("from" -> "to")
6	QF	MVAr injection at "from" bus ("from" -> "to")
7	QT	MVAr injection at "to" bus ("from" -> "to")
8	VF	voltage setpoint at "from" bus (p.u.)
9	VT	voltage setpoint at "to" bus (p.u.)
10	PMIN	lower limit on PF (MW flow at "from" end)
11	PMAX	upper limit on PF (MW flow at "from" end)
12	QMINF	lower limit on MVAr injection at "from" bus
13	QMAXF	upper limit on MVAr injection at "from" bus
14	QMINT	lower limit on MVAr injection at "to" bus
15	QMAXT	upper limit on MVAr injection at "to" bus
16	LOSS0	constant term of linear loss <i>function</i> (MW)
17	LOSS1	linear term of linear loss <i>function</i> (MW/MW) (loss = LOSS0 + LOSS1 * PF)

columns 18-23 are added to matrix after OPF solution

they are typically *not* present in the *input* matrix

(assume OPF objective *function* has units, u)

18	MU_PMIN	Kuhn-Tucker multiplier on lower flow lim at "from" bus (u/MW)
19	MU_PMAX	Kuhn-Tucker multiplier on upper flow lim at "from" bus (u/MW)
20	MU_QMINF	Kuhn-Tucker multiplier on lower VAR lim at "from" bus (u/MVAr)
21	MU_QMAXF	Kuhn-Tucker multiplier on upper VAR lim at "from" bus (u/MVAr)
22	MU_QMINT	Kuhn-Tucker multiplier on lower VAR lim at "to" bus (u/MVAr)
23	MU_QMAXT	Kuhn-Tucker multiplier on upper VAR lim at "to" bus (u/MVAr)

See also *toggle_dcline()* (page 302).

idx_gen

idx_gen()

idx_gen() (page 342) - Defines constants for named column indices to gen matrix.

Example:

```
[GEN_BUS, PG, QG, QMAX, QMIN, VG, MBASE, GEN_STATUS, PMAX, PMIN, ...
MU_PMAX, MU_PMIN, MU_QMAX, MU_QMIN, PC1, PC2, QC1MIN, QC1MAX, ...
QC2MIN, QC2MAX, RAMP_AGC, RAMP_10, RAMP_30, RAMP_Q, APF] = idx_gen;
```

Some examples of **usage**, after defining the constants using the **line** above, are:

```
Pg = gen(4, PG); % get the real power output of generator 4
gen(:, PMIN) = 0; % set to zero the minimum real power limit of all gens
```

The **index**, name and meaning of each column of the gen matrix is given below:

columns 1-21 must be included in **input** matrix (in **case** file)

1	GEN_BUS	bus number
2	PG	Pg, real power output (MW)
3	QG	Qg, reactive power output (MVar)
4	QMAX	Qmax, maximum reactive power output (MVar)
5	QMIN	Qmin, minimum reactive power output (MVar)
6	VG	Vg, voltage magnitude setpoint (p.u.)
7	MBASE	mBase, total MVA base of machine, defaults to baseMVA
8	GEN_STATUS	status, > 0 - in service, <= 0 - out of service
9	PMAX	Pmax, maximum real power output (MW)
10	PMIN	Pmin, minimum real power output (MW)
11	PC1	Pc1, lower real power output of PQ capability curve (MW)
12	PC2	Pc2, upper real power output of PQ capability curve (MW)
13	QC1MIN	Qc1min, minimum reactive power output at Pc1 (MVar)
14	QC1MAX	Qc1max, maximum reactive power output at Pc1 (MVar)
15	QC2MIN	Qc2min, minimum reactive power output at Pc2 (MVar)
16	QC2MAX	Qc2max, maximum reactive power output at Pc2 (MVar)
17	RAMP_AGC	ramp rate for load following/AGC (MW/min)
18	RAMP_10	ramp rate for 10 minute reserves (MW)
19	RAMP_30	ramp rate for 30 minute reserves (MW)
20	RAMP_Q	ramp rate for reactive power (2 sec timescale) (MVar/min)
21	APF	area participation factor

columns 22-25 are added to matrix after OPF solution

they are typically **not** present in the **input** matrix

(assume OPF objective **function** has units, u)

22	MU_PMAX	Kuhn-Tucker multiplier on upper Pg limit (u/MW)
23	MU_PMIN	Kuhn-Tucker multiplier on lower Pg limit (u/MW)
24	MU_QMAX	Kuhn-Tucker multiplier on upper Qg limit (u/MVar)
25	MU_QMIN	Kuhn-Tucker multiplier on lower Qg limit (u/MVar)

See also `define_constants`.

isload

isload(*gen*)

isload() - Checks for dispatchable loads.

TORF = ISLOAD(GEN) returns a column vector of 1's and 0's. The 1's correspond to rows of the GEN matrix which represent dispatchable loads. The current test is $P_{min} < 0$ AND $P_{max} == 0$. This may need to be revised to allow sensible specification of both elastic demand and pumped storage units.

load2disp

load2disp(*mpc0*, *fname*, *idx*, *voll*)

load2disp() - Converts fixed loads to dispatchable.

```
MPC = LOAD2DISP(MPC0);
MPC = LOAD2DISP(MPC0, FNAME);
MPC = LOAD2DISP(MPC0, FNAME, IDX);
MPC = LOAD2DISP(MPC0, FNAME, IDX, VOLL);
```

Takes a MATPOWER **case** file or struct and converts fixed loads to dispatchable loads and returns the resulting **case struct**. Inputs are as follows:

MPC0 - File name or struct with initial MATPOWER **case**.

FNAME (optional) - Name to use to save resulting MATPOWER **case**. If empty, the **case** will not be saved to a file.

IDX (optional) - Vector of bus indices of loads to be converted. If empty or not supplied, it will convert all loads with positive real power demand.

VOLL (optional) - Scalar or vector specifying the value of lost load to use as the value for the dispatchable loads. If it is a scalar it is used for all loads, if a vector, the dimension must match that of IDX. Default is \$5000 per MWh.

loadshed

loadshed(*gen, ild*)

loadshed() - Returns a vector of curtailments of dispatchable loads.

```
SHED = LOADSHED(GEN)
SHED = LOADSHED(GEN, ILD)
```

Returns a column vector of MW curtailments of dispatchable loads.

Inputs:

GEN - MATPOWER generator matrix
ILD - (optional) NLD x 1 vector of generator indices corresponding to the dispatchable loads of interest, default is **all** dispatchable loads as determined by the ISLOAD() **function**.

Output:

SHED - NLD x 1 vector of the MW curtailment **for** each dispatchable **load** of interest

Example:

```
total_load_shed = max(loadshed(mpc.gen));
```

modcost

modcost(*gencost, alpha, modtype*)

modcost() - Modifies generator costs by shifting or scaling (F or X).

```
NEWGENCOST = MODCOST(GENCOST, ALPHA)
NEWGENCOST = MODCOST(GENCOST, ALPHA, MODTYPE)
```

For each generator cost $F(X)$ (**for real or reactive power**) in GENCOST, this **function** modifies the cost by scaling **or** shifting the **function** by ALPHA, depending on the value of MODTYPE, **and** **and** returns the modified GENCOST. Rows of GENCOST can be a mix of polynomial **or** piecewise linear costs. ALPHA can be a scalar, applied to each row of GENCOST, **or** an NG x 1 vector, where each element is applied to the corresponding row of GENCOST.

MODTYPE takes one of the 4 possible values (let $F_{\text{alpha}}(X)$ denote the modified **function**):

'SCALE_F'	(default)	: $F_{\text{alpha}}(X)$	== $F(X) * \text{ALPHA}$
'SCALE_X'		: $F_{\text{alpha}}(X * \text{ALPHA})$	== $F(X)$
'SHIFT_F'		: $F_{\text{alpha}}(X)$	== $F(X) + \text{ALPHA}$
'SHIFT_X'		: $F_{\text{alpha}}(X + \text{ALPHA})$	== $F(X)$

mpver

mpver(*varargin*)

mpver() - Prints or returns installed MATPOWER version info.

```
mpver
v = mpver
v = mpver('all')
```

When called with an output argument and no input argument, **mpver**() returns the current MATPOWER version numbers. With an input argument (e.g. 'all') it returns a struct with the fields Name, Version, Release, and Date (*all char arrays*). Calling **mpver**() without assigning the return value prints the version and release date of the current installation of MATPOWER, MATLAB (or MATLAB), the Optimization Toolbox, MP-Test, MIPS, MP-Opt-Model, MOST, and any optional MATPOWER packages.

poly2pwl

poly2pwl(*polycost*, *Pmin*, *Pmax*, *npts*)

poly2pwl() - Converts polynomial cost variable to piecewise linear.

PWLCOST = POLY2PWL(POLYCOST, PMIN, PMAX, NPTS) converts the polynomial cost variable POLYCOST into a piece-wise linear cost by evaluating at NPTS evenly spaced points between PMIN and PMAX. If the range does not include 0, then it is evaluated at 0 and NPTS-1 evenly spaced points between PMIN and PMAX.

polycost

polycost(*gencost*, *Pg*, *der*)

polycost() - Evaluates polynomial generator cost & derivatives.

F = POLYCOST(GENCOST, PG) returns the vector of costs evaluated at PG

DF = POLYCOST(GENCOST, PG, 1) returns the vector of first derivatives of costs evaluated at PG

D2F = POLYCOST(GENCOST, PG, 2) returns the vector of second derivatives of costs evaluated at PG

GENCOST must contain only polynomial costs
PG is in MW, not p.u. (works for QG too)

This is a more efficient implementation that what can be done with MATLAB's built-in POLYVAL and POLYDER functions.

pqcost

pqcost(gencost, ng, on)

pqcost() - Splits the gencost variable into two pieces if costs are given for Qg.

[PCOST, QCOST] = PQCOST(GENCOST, NG, ON) checks whether GENCOST has cost information **for** reactive **power** generation (rows ng+1 to 2*ng). If so, it returns the first NG rows in PCOST **and** the last NG rows in QCOST. Otherwise, leaves QCOST empty. Also does some **error** checking. If ON is specified (list of indices of generators which are on **line**) it only returns the **rows** corresponding to these generators.

scale_load

scale_load(dmd, bus, gen, load_zone, opt, gencost)

scale_load() (page 346) - Scales fixed and/or dispatchable loads.

```

MPC = SCALE_LOAD(LOAD, MPC);
MPC = SCALE_LOAD(LOAD, MPC, LOAD_ZONE)
MPC = SCALE_LOAD(LOAD, MPC, LOAD_ZONE, OPT)
BUS = SCALE_LOAD(LOAD, BUS);
[BUS, GEN] = SCALE_LOAD(LOAD, BUS, GEN, LOAD_ZONE, OPT)
[BUS, GEN, GENCOST] = ...
    SCALE_LOAD(LOAD, BUS, GEN, LOAD_ZONE, OPT, GENCOST)

```

Scales active (**and** optionally reactive) loads in each zone by a zone-specific ratio, i.e. $R(k)$ **for** zone k . Inputs are ...

LOAD - Each element specifies the amount of scaling **for** the corresponding load zone, either as a direct scale **factor** **or** as a target quantity. If there are nz load zones this vector has nz elements.

MPC - standard MATPOWER **case struct** **or case** file name

BUS - standard BUS matrix with nb rows, where the fixed active **and** reactive loads available **for** scaling are specified in columns PD **and** QD

GEN - (optional) standard GEN matrix with ng rows, where the dispatchable loads available **for** scaling are specified by columns PG, QG, PMIN, QMIN **and** QMAX (in rows **for** which ISLOAD(GEN) returns **true**). If GEN is empty, it assumes there are no dispatchable loads.

LOAD_ZONE - (optional) nb element vector where the value of each element is either zero **or** the **index** of the load zone to which the corresponding bus belongs. If $LOAD_ZONE(b) = k$ then the loads at bus b will be scaled according to the value of $LOAD(k)$. If $LOAD_ZONE(b) = 0$, the loads at bus b

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will **not** be modified. If LOAD_ZONE is empty, the default is determined by the dimensions of the LOAD vector. If LOAD is a scalar, a **single system**-wide zone including **all** buses is used, i.e. LOAD_ZONE = ONES(nb, 1). If LOAD is a vector, the default LOAD_ZONE is defined as the areas specified in the BUS matrix, i.e. LOAD_ZONE = BUS(:, BUS_AREA), and LOAD should have dimension = MAX(BUS(:, BUS_AREA)).

OPT - (optional) **struct** with three possible fields, 'scale', 'pq' and 'which' that determine the behavior as follows:

OPT.scale (default is 'FACTOR')

'FACTOR' : LOAD consists of direct scale factors, where
 $\text{LOAD}(k) = \text{scale factor } R(k) \text{ for zone } k$
 'QUANTITY' : LOAD consists of target quantities, where
 $\text{LOAD}(k) = \text{desired total active load in MW for zone } k \text{ after scaling by an appropriate } R(k)$

OPT.pq (default is 'PQ')

'PQ' : scale both active and reactive loads
 'P' : scale only active loads

OPT.which (default is 'BOTH' if GEN is provided, else 'FIXED')

'FIXED' : scale only fixed loads
 'DISPATCHABLE' : scale only dispatchable loads
 'BOTH' : scale both fixed and dispatchable loads

OPT.cost : (default = -1) flag to include cost in scaling or not

-1 : include cost if gencost is available
 0 : do not include cost
 1 : include cost (error if gencost not available)

GENCOST - (optional) standard GENCOST matrix with ng (or 2*ng) rows, where the dispatchable load rows are determined by the GEN matrix. If included, the quantity axis of the marginal "cost" or benefit function of any dispatchable loads will be scaled with the size of the load itself (using MODCOST twice, once with MODTYPE equal to SCALE_F and once with SCALE_X).

Examples:

Scale all real and reactive fixed loads up by 10%.

```
bus = scale_load(1.1, bus);
```

Scale all active loads (fixed and dispatchable) at the first 10 buses so their total equals 100 MW, and at next 10 buses so their total equals 50 MW.

```
load_zone = zeros(nb, 1);
load_zone(1:10) = 1;
load_zone(11:20) = 2;
opt = struct('pq', 'P', 'scale', 'QUANTITY');
```

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```
dmd = [100; 50];
[bus, gen] = scale_load(dmd, bus, gen, load_zone, opt);
```

See also `total_load()` (page 348).

total_load

total_load(bus, gen, load_zone, opt, mpopt)

`total_load()` (page 348) - Returns vector of total load in each load zone.

```
PD = TOTAL_LOAD(MPC)
PD = TOTAL_LOAD(MPC, LOAD_ZONE)
PD = TOTAL_LOAD(MPC, LOAD_ZONE, OPT)
PD = TOTAL_LOAD(MPC, LOAD_ZONE, OPT, MPOPT)
PD = TOTAL_LOAD(BUS)
PD = TOTAL_LOAD(BUS, GEN)
PD = TOTAL_LOAD(BUS, GEN, LOAD_ZONE)
PD = TOTAL_LOAD(BUS, GEN, LOAD_ZONE, OPT)
PD = TOTAL_LOAD(BUS, GEN, LOAD_ZONE, OPT, MPOPT)
[PD, QD] = TOTAL_LOAD(...) returns both active and reactive power
demand for each zone.
```

MPC - standard MATPOWER case struct

BUS - standard BUS matrix with nb rows, where the fixed active and reactive loads are specified in columns PD and QD

GEN - (optional) standard GEN matrix with ng rows, where the dispatchable loads are specified by columns PG, QG, PMIN, QMIN and QMAX (in rows for which ISLOAD(GEN) returns true). If GEN is empty, it assumes there are no dispatchable loads.

LOAD_ZONE - (optional) nb element vector where the value of each element is either zero or the index of the load zone to which the corresponding bus belongs. If LOAD_ZONE(b) = k then the loads at bus b will added to the values of PD(k) and QD(k). If LOAD_ZONE is empty, the default is defined as the areas specified in the BUS matrix, i.e. LOAD_ZONE = BUS(:, BUS_AREA) and load will have dimension = MAX(BUS(:, BUS_AREA)). LOAD_ZONE can also take the following string values:

- 'all' - use a single zone for the entire system (return scalar)
- 'area' - use LOAD_ZONE = BUS(:, BUS_AREA), same as default
- 'bus' - use a different zone for each bus (i.e. to compute final values of bus-wise loads, including voltage dependent fixed loads and or dispatchable loads)

OPT - (optional) option struct, with the following fields:

- 'type' - string specifying types of loads to include, default is 'BOTH' if GEN is provided, otherwise 'FIXED'
- 'FIXED' : sum only fixed loads

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```

'DISPATCHABLE' : sum only dispatchable loads
'BOTH'          : sum both fixed and dispatchable loads
'nominal' - 1 : use nominal load for dispatchable loads
            0 : (default) use actual realized load for
                dispatchable loads

```

For backward compatibility with MATPOWER 4.x, OPT can also take the form of a string, with the same options as OPT.type above. In this case, again for backward compatibility, it is the "nominal" load that is computed for dispatchable loads, not the actual realized load. Using a string for OPT is deprecated and will be removed in a future version.

MPOPT - (optional) MATPOWER options struct, which may specify a voltage dependent (ZIP) load model for fixed loads

Examples:

Return the total active load for each area as defined in BUS_AREA.

```
Pd = total_load(bus);
```

Return total active and reactive load, fixed and dispatchable, for entire system.

```
[Pd, Qd] = total_load(bus, gen, 'all');
```

Return the total of the nominal dispatchable loads at buses 10-20.

```
load_zone = zeros(nb, 1);
load_zone(10:20) = 1;
opt = struct('type', 'DISPATCHABLE', 'nominal', 1);
Pd = total_load(mpc, load_zone, opt)
```

See also `scale_load()` (page 346).

5.2.13 Private Feature Detection Functions

have_feature_e4st

have_feature_e4st()

`have_feature_e4st()` (page 349) - Detect availability/version info for E4ST.

Private feature detection function implementing 'e4st' tag for `have_feature()` to detect availability/version of E4ST, the Engineering, Economic, and Environmental Electricity Simulation Tool (<https://e4st.com>).

See also `have_feature()`.

have_feature_minopf

have_feature_minopf()

have_feature_minopf() (page 350) - Detect availability/version info for MINOPF.

Private feature detection function implementing 'minopf' tag for `have_feature()` to detect availability/version of MINOPF, a MINOS-based optimal power flow (OPF) solver.

See also `have_feature()`, `minopf`.

have_feature_most

have_feature_most()

have_feature_most() (page 350) - Detect availability/version info for MOST.

Private feature detection function implementing ':func: `most` ' tag for `have_feature()` to detect availability/version of MOST (MATPOWER Optimal Scheduling Tool).

See also `have_feature()`, `most()`.

have_feature_mp_core

have_feature_mp_core()

have_feature_mp_core() (page 350) - Detect availability of MP-Core.

Private feature detection function implementing 'mp_core' tag for `have_feature()` to detect availability/version of MP-Core.

See also `have_feature()`.

have_feature_pdipmopf

have_feature_pdipmopf()

have_feature_pdipmopf() (page 350) - Detect availability/version info for PDIPMOPF.

Private feature detection function implementing 'pdipmopf' tag for `have_feature()` to detect availability/version of PDIPMOPF, a primal-dual interior point method optimal power flow (OPF) solver included in TSPOPF. (<https://www.pserc.cornell.edu/tspopf>)

See also `have_feature()`, `pdipmopf`.

have_feature_regexp_split

have_feature_regexp_split()

have_feature_regexp_split() (page 351) - Detect availability/version info for REGEXP 'split'.

Private feature detection function implementing 'regexp_split' tag for `have_feature()` to detect support for the 'split' argument to REGEXP.

See also `have_feature()`, `regexp`.

have_feature_scpdipmopf

have_feature_scpdipmopf()

have_feature_scpdipmopf() (page 351) - Detect availability/version info for SCPDIPMOPF.

Private feature detection function implementing 'scpdipmopf' tag for `have_feature()` to detect availability/version of SCPDIPMOPF, step-controlled primal-dual interior point method optimal power flow (OPF) solver included in TSPOPF. (<https://www.pserc.cornell.edu/tspopf>)

See also `have_feature()`, `scpdipmopf`.

have_feature_sdp_pf

have_feature_sdp_pf()

have_feature_sdp_pf() (page 351) - Detect availability/version info for SDP_PF.

Private feature detection function implementing 'sdp_pf' tag for `have_feature()` to detect availability/version of SDP_PF, a MATPOWER extension for applications of semi-definite programming relaxations of power flow equations (https://github.com/MATPOWER/mx-sdp_pf/).

See also `have_feature()`.

have_feature_smartmarket

have_feature_smartmarket()

have_feature_smartmarket() (page 351) - Detect availability/version info for SMARTMARKET.

Private feature detection function implementing 'smartmarket' tag for `have_feature()` to detect availability/version of RUNMARKET and related files for running an energy auction, found under smartmarket in MATPOWER Extras. (<https://github.com/MATPOWER/matpower-extras/>).

See also `have_feature()`, `runmarket`.

have_feature_syngrid

have_feature_syngrid()

have_feature_syngrid() (page 352) - Detect availability/version info for SynGrid.

Private feature detection function implementing 'syngrid' tag for `have_feature()` to detect availability/version of SynGrid, Synthetic Grid Creation for MATPOWER (<https://github.com/MATPOWER/mx-syngrid>).

See also `have_feature()`, `syngrid`.

have_feature_table

have_feature_table()

have_feature_table() (page 352) - Detect availability/version info for table.

Private feature detection function implementing 'table' tag for `have_feature()` to detect availability/version of TABLE, included in MATLAB R2013b and as of this writing in Mar 2024, available for Octave as Tablicious: <https://github.com/apjanke/octave-tablicious>

See also `have_feature()`, `table`.

have_feature_tralmopf

have_feature_tralmopf()

have_feature_tralmopf() (page 352) - Detect availability/version info for TRALMOPF

Private feature detection function implementing 'tralmopf' tag for `have_feature()` to detect availability/version of TRALMOPF, trust region based augmented Lagrangian optimal power flow (OPF) solver included in TSPOPF. (<https://www.pserc.cornell.edu/tspopf>)

See also `have_feature()`, `tralmopf`.

5.2.14 Other Functions

connected_components

`connected_components(C, groups, unvisited)`

connected_components() (page 352) - Returns the connected components of a graph.

```
[GROUPS, ISOLATED] = CONNECTED_COMPONENTS(C)
```

Returns the connected components of a directed graph, specified by a node-branch incidence matrix `C`, where `C(I, J) = -1` if node `J` is connected to the beginning of branch `I`, `1` if it is connected to the end of branch `I`, and zero otherwise. The return value `GROUPS` is a cell array of vectors of the node indices for each component. The second return value `ISOLATED` is a vector of indices of isolated nodes that have no connecting branches.

mpoption_info_clp

mpoption_info_clp(*selector*)

mpoption_info_clp() (page 353) - Returns MATPOWER option info for CLP.

```

DEFAULT_OPTS = MPOPTION_INFO_CLP('D')
VALID_OPTS   = MPOPTION_INFO_CLP('V')
EXCEPTIONS   = MPOPTION_INFO_CLP('E')

```

Returns a structure **for** CLP options **for** MATPOWER containing ...

(1) default options,
 (2) valid options, **or**
 (3) NESTED_STRUCT_COPY exceptions **for** setting options
 ... depending on the value of the **input** argument.

This **function** is used by MPOPTION to **set** default options, check validity of option names **or** modify option setting/copying behavior **for** this subset of optional MATPOWER options.

See also mpooption().

mpoption_info_cplex

mpoption_info_cplex(*selector*)

mpoption_info_cplex() (page 353) - Returns MATPOWER option info for CPLEX.

```

DEFAULT_OPTS = MPOPTION_INFO_CPLEX('D')
VALID_OPTS   = MPOPTION_INFO_CPLEX('V')
EXCEPTIONS   = MPOPTION_INFO_CPLEX('E')

```

Returns a structure **for** CPLEX options **for** MATPOWER containing ...

(1) default options,
 (2) valid options, **or**
 (3) NESTED_STRUCT_COPY exceptions **for** setting options
 ... depending on the value of the **input** argument.

This **function** is used by MPOPTION to **set** default options, check validity of option names **or** modify option setting/copying behavior **for** this subset of optional MATPOWER options.

See also mpooption().

mpoption_info_fmincon

mpoption_info_fmincon(*selector*)

mpoption_info_fmincon() (page 354) - Returns MATPOWER option info for FMINCON.

```
DEFAULT_OPTS = MPOPTION_INFO_FMINCON('D')
VALID_OPTS   = MPOPTION_INFO_FMINCON('V')
EXCEPTIONS   = MPOPTION_INFO_FMINCON('E')
```

Returns a structure **for** FMINCON options **for** MATPOWER containing ...

(1) default options,
(2) valid options, **or**
(3) NESTED_STRUCT_COPY exceptions **for** setting options
... depending on the value of the **input** argument.

This **function** is used by MPOPTION to **set** default options, check validity of option names **or** modify option setting/copying behavior **for** this subset of optional MATPOWER options.

See also mppoption().

mpoption_info_glpk

mpoption_info_glpk(*selector*)

mpoption_info_glpk() (page 354) - Returns MATPOWER option info for GLPK.

```
DEFAULT_OPTS = MPOPTION_INFO_GLPK('D')
VALID_OPTS   = MPOPTION_INFO_GLPK('V')
EXCEPTIONS   = MPOPTION_INFO_GLPK('E')
```

Returns a structure **for** GLPK options **for** MATPOWER containing ...

(1) default options,
(2) valid options, **or**
(3) NESTED_STRUCT_COPY exceptions **for** setting options
... depending on the value of the **input** argument.

This **function** is used by MPOPTION to **set** default options, check validity of option names **or** modify option setting/copying behavior **for** this subset of optional MATPOWER options.

See also mppoption().

mpoption_info_gurobi

mpoption_info_gurobi(*selector*)

mpoption_info_gurobi() (page 355) - Returns MATPOWER option info for Gurobi.

```

DEFAULT_OPTS = MPOPTION_INFO_GUROBI('D')
VALID_OPTS   = MPOPTION_INFO_GUROBI('V')
EXCEPTIONS   = MPOPTION_INFO_GUROBI('E')

```

Returns a structure **for** Gurobi options **for** MATPOWER containing ...

(1) default options,
 (2) valid options, **or**
 (3) NESTED_STRUCT_COPY exceptions **for** setting options
 ... depending on the value of the **input** argument.

This **function** is used by MPOPTION to **set** default options, check validity of option names **or** modify option setting/copying behavior **for** this subset of optional MATPOWER options.

See also mppoption().

mpoption_info_intlinprog

mpoption_info_intlinprog(*selector*)

mpoption_info_intlinprog() (page 355) - Returns MATPOWER option info for INTLINPROG.

```

DEFAULT_OPTS = MPOPTION_INFO_INTLINPROG('D')
VALID_OPTS   = MPOPTION_INFO_INTLINPROG('V')
EXCEPTIONS   = MPOPTION_INFO_INTLINPROG('E')

```

Returns a structure **for** INTLINPROG options **for** MATPOWER containing ...

(1) default options,
 (2) valid options, **or**
 (3) NESTED_STRUCT_COPY exceptions **for** setting options
 ... depending on the value of the **input** argument.

This **function** is used by MPOPTION to **set** default options, check validity of option names **or** modify option setting/copying behavior **for** this subset of optional MATPOWER options.

See also mppoption().

mpoption_info_ipopt

mpoption_info_ipopt(*selector*)

mpoption_info_ipopt() (page 356) - Returns MATPOWER option info for IPOPT.

```
DEFAULT_OPTS = MPOPTION_INFO_IPOPT('D')
VALID_OPTS   = MPOPTION_INFO_IPOPT('V')
EXCEPTIONS   = MPOPTION_INFO_IPOPT('E')
```

Returns a structure **for** IPOPT options **for** MATPOWER containing ...

(1) default options,
(2) valid options, **or**
(3) NESTED_STRUCT_COPY exceptions **for** setting options
... depending on the value of the **input** argument.

This **function** is used by MPOPTION to **set** default options, check validity of option names **or** modify option setting/copying behavior **for** this subset of optional MATPOWER options.

See also mppoption().

mpoption_info_knitro

mpoption_info_knitro(*selector*)

mpoption_info_knitro() (page 356) - Returns MATPOWER option info for Artelys Knitro.

```
DEFAULT_OPTS = MPOPTION_INFO_KNITRO('D')
VALID_OPTS   = MPOPTION_INFO_KNITRO('V')
EXCEPTIONS   = MPOPTION_INFO_KNITRO('E')
```

Returns a structure **for** Knitro options **for** MATPOWER containing ...

(1) default options,
(2) valid options, **or**
(3) NESTED_STRUCT_COPY exceptions **for** setting options
... depending on the value of the **input** argument.

This **function** is used by MPOPTION to **set** default options, check validity of option names **or** modify option setting/copying behavior **for** this subset of optional MATPOWER options.

See also mppoption().

mpoption_info_linprog

mpoption_info_linprog(*selector*)

mpoption_info_linprog() (page 357) - Returns MATPOWER option info for LINPROG.

```

DEFAULT_OPTS = MPOPTION_INFO_LINPROG('D')
VALID_OPTS   = MPOPTION_INFO_LINPROG('V')
EXCEPTIONS   = MPOPTION_INFO_LINPROG('E')

```

Returns a structure **for** LINPROG options **for** MATPOWER containing ...

(1) default options,
 (2) valid options, **or**
 (3) NESTED_STRUCT_COPY exceptions **for** setting options
 ... depending on the value of the **input** argument.

This **function** is used by MPOPTION to **set** default options, check validity of option names **or** modify option setting/copying behavior **for** this subset of optional MATPOWER options.

See also mppoption().

mpoption_info_mips

mpoption_info_mips(*selector*)

mpoption_info_mips() (page 357) - Returns MATPOWER option info for MIPS (optional fields).

```

DEFAULT_OPTS = MPOPTION_INFO_MIPS('D')
VALID_OPTS   = MPOPTION_INFO_MIPS('V')
EXCEPTIONS   = MPOPTION_INFO_MIPS('E')

```

Returns a structure **for** MIPS options **for** MATPOWER containing ...

(1) default options,
 (2) valid options, **or**
 (3) NESTED_STRUCT_COPY exceptions **for** setting options
 ... depending on the value of the **input** argument.

This **function** is used by MPOPTION to **set** default options, check validity of option names **or** modify option setting/copying behavior **for** this subset of optional MATPOWER options.

See also mppoption().

mpoption_info_mosek

mpoption_info_mosek(*selector*)

mpoption_info_mosek() (page 358) - Returns MATPOWER option info for MOSEK.

```
DEFAULT_OPTS = MPOPTION_INFO_MOSEK('D')
VALID_OPTS   = MPOPTION_INFO_MOSEK('V')
EXCEPTIONS   = MPOPTION_INFO_MOSEK('E')
```

Returns a structure **for** MOSEK options **for** MATPOWER containing ...

(1) default options,
(2) valid options, **or**
(3) NESTED_STRUCT_COPY exceptions **for** setting options
... depending on the value of the **input** argument.

This **function** is used by MPOPTION to **set** default options, check validity of option names **or** modify option setting/copying behavior **for** this subset of optional MATPOWER options.

See also mppoption().

mpoption_info_osqp

mpoption_info_osqp(*selector*)

mpoption_info_osqp() (page 358) - Returns MATPOWER option info for OSQP.

```
DEFAULT_OPTS = MPOPTION_INFO_OSQP('D')
VALID_OPTS   = MPOPTION_INFO_OSQP('V')
EXCEPTIONS   = MPOPTION_INFO_OSQP('E')
```

Returns a structure **for** OSQP options **for** MATPOWER containing ...

(1) default options,
(2) valid options, **or**
(3) NESTED_STRUCT_COPY exceptions **for** setting options
... depending on the value of the **input** argument.

This **function** is used by MPOPTION to **set** default options, check validity of option names **or** modify option setting/copying behavior **for** this subset of optional MATPOWER options.

See also mppoption().

mpoption_info_quadprog

mpoption_info_quadprog(*selector*)

mpoption_info_quadprog() (page 359) - Returns MATPOWER option info for QUADPROG.

```

DEFAULT_OPTS = MPOPTION_INFO_QUADPROG('D')
VALID_OPTS   = MPOPTION_INFO_QUADPROG('V')
EXCEPTIONS   = MPOPTION_INFO_QUADPROG('E')

```

Returns a structure **for** QUADPROG options **for** MATPOWER containing ...

(1) default options,
 (2) valid options, **or**
 (3) NESTED_STRUCT_COPY exceptions **for** setting options
 ... depending on the value of the **input** argument.

This **function** is used by MPOPTION to **set** default options, check validity of option names **or** modify option setting/copying behavior **for** this subset of optional MATPOWER options.

See also mppoption().

mpoption_old

mpoption_old(*varargin*)

mpoption_old() (page 359) - Used to set and retrieve old-style MATPOWER options vector.

```

OPT = MPOPTION_OLD
returns the default options vector

```

```

OPT = MPOPTION_OLD(NAME1, VALUE1, NAME2, VALUE2, ...)
returns the default options vector with new values for up to 7
options, NAME# is the name of an option, and VALUE# is the new
value.

```

```

OPT = MPOPTION_OLD(OPT, NAME1, VALUE1, NAME2, VALUE2, ...)
same as above except it uses the options vector OPT as a base
instead of the default options vector.

```

Examples:

```

opt = mppoption_old('PF_ALG', 2, 'PF_TOL', 1e-4);
opt = mppoption_old(opt, 'OPF_ALG', 565, 'VERBOSE', 2);

```

The currently defined options are as follows:

idx	NAME, default	description [options]

power flow options		
1	PF_ALG, 1	AC power flow algorithm
	[1 - Newton's method]
	[2 - Fast-Decoupled (XB version)]
	[3 - Fast-Decoupled (BX version)]

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```

[ 4 - Gauss-Seidel ]
2 - PF_TOL, 1e-8      termination tolerance on per unit
                      P & Q mismatch
3 - PF_MAX_IT, 10     maximum number of iterations for
                      Newton's method
4 - PF_MAX_IT_FD, 30  maximum number of iterations for
                      fast decoupled method
5 - PF_MAX_IT_GS, 1000 maximum number of iterations for
                      Gauss-Seidel method
6 - ENFORCE_Q_LIMS, 0 enforce gen reactive power limits
                      at expense of |V|
[ 0 - do NOT enforce limits ]
[ 1 - enforce limits, simultaneous bus type conversion ]
[ 2 - enforce limits, one-at-a-time bus type conversion ]
10 - PF_DC, 0         DC modeling for power flow & OPF
[ 0 - use AC formulation & corresponding algorithm options ]
[ 1 - use DC formulation, ignore AC algorithm options ]
OPF options
11 - OPF_ALG, 0       solver to use for AC OPF
[ 0 - choose default solver based on availability in the ]
[ following order, 540, 560 ]
[ 500 - MINOPF, MINOS-based solver, requires optional ]
[ MEX-based MINOPF package, available from: ]
[ http://www.pserc.cornell.edu/minopf/ ]
[ 520 - fmincon, MATLAB Optimization Toolbox >= 2.x ]
[ 540 - PDIPM, primal/dual interior point method, requires ]
[ optional MEX-based TSPOPF package, available from: ]
[ http://www.pserc.cornell.edu/tspopf/ ]
[ 545 - SC-PDIPM, step-controlled variant of PDIPM, requires ]
[ TSPOPF (see 540) ]
[ 550 - TRALM, trust region based augmented Lagrangian ]
[ method, requires TSPOPF (see 540) ]
[ 560 - MIPS, MATPOWER Interior Point Solver ]
[ primal/dual interior point method (pure MATLAB) ]
[ 565 - MIPS-sc, step-controlled variant of MIPS ]
[ primal/dual interior point method (pure MATLAB) ]
[ 580 - IPOPT, requires MEX interface to IPOPT solver ]
[ available from: https://projects.coin-or.org/Ipopt/ ]
[ 600 - Artelys Knitro, requires Knitro solver, available from: ]
[ https://www.artelys.com/solvers/knitro/ ]
16 - OPF_VIOLATION, 5e-6 constraint violation tolerance
17 - CONSTR_TOL_X, 1e-4  termination tol on x for fmincon/Knitro
18 - CONSTR_TOL_F, 1e-4  termination tol on f for fmincon/Knitro
19 - CONSTR_MAX_IT, 0    max number of iterations for fmincon
[ 0 => default ]
24 - OPF_FLOW_LIM, 0     qty to limit for branch flow constraints
[ 0 - apparent power flow (limit in MVA) ]
[ 1 - active power flow (limit in MW) ]
[ 2 - current magnitude (limit in MVA at 1 p.u. voltage) ]
25 - OPF_IGNORE_ANG_LIM, 0 ignore angle difference limits for branches
                      even if specified [ 0 or 1 ]
26 - OPF_ALG_DC, 0       solver to use for DC OPF

```

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```

[ 0 - choose default solver based on availability in the ]
[ following order: 500, 600, 700, 100, 300, 200 ]
[ 100 - BPMPD, requires optional MEX-based BPMPD_MEX package ]
[ available from: http://www.pserc.cornell.edu/bpmpd/ ]
[ 200 - MIPS, MATLAB Interior Point Solver ]
[ primal/dual interior point method (pure MATLAB) ]
[ 250 - MIPS-sc, step-controlled variant of MIPS ]
[ 300 - MATLAB Optimization Toolbox, QUADPROG, LINPROG ]
[ 400 - IPOPT, requires MEX interface to IPOPT solver ]
[ available from: https://projects.coin-or.org/Ipopt/ ]
[ 500 - CPLEX, requires MATLAB interface to CPLEX solver ]
[ 600 - MOSEK, requires MATLAB interface to MOSEK solver ]
[ available from: https://www.mosek.com/ ]
[ 700 - GUROBI, requires Gurobi optimizer (v. 5+) ]
[ available from: https://www.gurobi.com ]
output options
31 - VERBOSE, 1 amount of progress info printed
[ 0 - print no progress info ]
[ 1 - print a little progress info ]
[ 2 - print a lot of progress info ]
[ 3 - print all progress info ]
32 - OUT_ALL, -1 controls pretty-printing of results
[ -1 - individual flags control what prints ]
[ 0 - do not print anything ]
[ (overrides individual flags) ]
[ 1 - print everything ]
[ (overrides individual flags) ]
33 - OUT_SYS_SUM, 1 print system summary [ 0 or 1 ]
34 - OUT_AREA_SUM, 0 print area summaries [ 0 or 1 ]
35 - OUT_BUS, 1 print bus detail [ 0 or 1 ]
36 - OUT_BRANCH, 1 print branch detail [ 0 or 1 ]
37 - OUT_GEN, 0 print generator detail [ 0 or 1 ]
(OUT_BUS also includes gen info)
38 - OUT_ALL_LIM, -1 controls what constraint info is printed
[ -1 - individual flags control what constraint info prints ]
[ 0 - no constraint info (overrides individual flags) ]
[ 1 - binding constraint info (overrides individual flags) ]
[ 2 - all constraint info (overrides individual flags) ]
39 - OUT_V_LIM, 1 control output of voltage limit info
[ 0 - do not print ]
[ 1 - print binding constraints only ]
[ 2 - print all constraints ]
[ (same options for OUT_LINE_LIM, OUT_PG_LIM, OUT_QG_LIM) ]
40 - OUT_LINE_LIM, 1 control output of line flow limit info
41 - OUT_PG_LIM, 1 control output of gen P limit info
42 - OUT_QG_LIM, 1 control output of gen Q limit info
44 - OUT_FORCE, 0 print results even if success = 0
[ 0 or 1 ]
52 - RETURN_RAW_DER, 0 return constraint and derivative info
in results.raw (in fields g, dg, df, d2f)
FMINCON options
55 - FMC_ALG, 4 algorithm used by fmincon for OPF

```

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```

                                for Optimization Toolbox 4 and later
[ 1 - active-set ]
[ 2 - interior-point, w/default 'bfgs' Hessian approx ]
[ 3 - interior-point, w/ 'lbfgs' Hessian approx ]
[ 4 - interior-point, w/exact user-supplied Hessian ]
[ 5 - interior-point, w/Hessian via finite differences ]

Artelys Knitro options
  58 - KNITRO_OPT, 0          a non-zero integer N indicates that all
                              Knitro options should be handled by a
                              Knitro options file named
                              'knitro_user_options_N.txt'

IPOPT options
  60 - IPOPT_OPT, 0          See IPOPT_OPTIONS for details.

MINOPF options
  61 - MNS_FEASTOL, 0 (1e-3) primal feasibility tolerance,
                              set to value of OPF_VIOLATION by default
  62 - MNS_ROWTOL, 0 (1e-3) row tolerance
                              set to value of OPF_VIOLATION by default
  63 - MNS_XTOL, 0 (1e-3) x tolerance
                              set to value of CONSTR_TOL_X by default
  64 - MNS_MAJDAMP, 0 (0.5) major damping parameter
  65 - MNS_MINDAMP, 0 (2.0) minor damping parameter
  66 - MNS_PENALTY_PARM, 0 (1.0) penalty parameter
  67 - MNS_MAJOR_IT, 0 (200) major iterations
  68 - MNS_MINOR_IT, 0 (2500) minor iterations
  69 - MNS_MAX_IT, 0 (2500) iterations limit
  70 - MNS_VERBOSITY, -1
      [ -1 - controlled by VERBOSE option ]
      [ 0 - print nothing ]
      [ 1 - print only termination status message ]
      [ 2 - print termination status and screen progress ]
      [ 3 - print screen progress, report file (usually fort.9) ]
  71 - MNS_CORE, 0 (1200 * nb + 2 * (nb + ng)^2) memory allocation
  72 - MNS_SUPBASIC_LIM, 0 (2*nb + 2*ng) superbasics limit
  73 - MNS_MULT_PRICE, 0 (30) multiple price

MIPS (including MIPS-sc), PDIPM, SC-PDIPM, and TRALM options
  81 - PDIPM_FEASTOL, 0      feasibility (equality) tolerance
                              for MIPS, PDIPM and SC-PDIPM, set
                              to value of OPF_VIOLATION by default
  82 - PDIPM_GRADTOL, 1e-6   gradient tolerance for MIPS, PDIPM
                              and SC-PDIPM
  83 - PDIPM_COMPTOL, 1e-6   complementary condition (inequality)
                              tolerance for MIPS, PDIPM and SC-PDIPM
  84 - PDIPM_COSTTOL, 1e-6   optimality tolerance for MIPS, PDIPM
                              and SC-PDIPM
  85 - PDIPM_MAX_IT, 150     maximum number of iterations for MIPS,
                              PDIPM and SC-PDIPM
  86 - SCPDIPM_RED_IT, 20    maximum number of MIPS-sc or SC-PDIPM

```

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87 - TRALM_FEASTOL, 0      reductions per iteration
                           feasibility tolerance for TRALM
                           set to value of OPF_VIOLATION by default
88 - TRALM_PRIMETOL, 5e-4  primal variable tolerance for TRALM
89 - TRALM_DUALTOL, 5e-4   dual variable tolerance for TRALM
90 - TRALM_COSTTOL, 1e-5   optimality tolerance for TRALM
91 - TRALM_MAJOR_IT, 40    maximum number of major iterations
92 - TRALM_MINOR_IT, 100   maximum number of minor iterations
93 - SMOOTHING_RATIO, 0.04 piecewise linear curve smoothing ratio
                           used in SC-PDIPM and TRALM

CPLEX options
95 - CPLEX_LPMETHOD, 0    solution algorithm for continuous LPs
    [ 0 - automatic: let CPLEX choose ]
    [ 1 - primal simplex ]
    [ 2 - dual simplex ]
    [ 3 - network simplex ]
    [ 4 - barrier ]
    [ 5 - sifting ]
    [ 6 - concurrent (dual, barrier, and primal) ]
96 - CPLEX_QPMETHOD, 0    solution algorithm for continuous QPs
    [ 0 - automatic: let CPLEX choose ]
    [ 1 - primal simplex optimizer ]
    [ 2 - dual simplex optimizer ]
    [ 3 - network optimizer ]
    [ 4 - barrier optimizer ]
97 - CPLEX_OPT, 0          See CPLEX_OPTIONS for details

MOSEK options
111 - MOSEK_LP_ALG, 0      solution algorithm for continuous LPs
                           (MSK_IPAR_OPTIMIZER)
    [ 0 - automatic: let MOSEK choose ]
    [ 1 - interior point ]
    [ 4 - primal simplex ]
    [ 5 - dual simplex ]
    [ 6 - primal dual simplex ]
    [ 7 - automatic simplex (MOSEK chooses which simplex method) ]
    [ 10 - concurrent ]
112 - MOSEK_MAX_IT, 0 (400) interior point max iterations
                           (MSK_IPAR_INTPNT_MAX_ITERATIONS)
113 - MOSEK_GAP_TOL, 0 (1e-8) interior point relative gap tolerance
                           (MSK_DPAR_INTPNT_TOL_REL_GAP)
114 - MOSEK_MAX_TIME, 0 (-1) maximum time allowed for solver
                           (MSK_DPAR_OPTIMIZER_MAX_TIME)
115 - MOSEK_NUM_THREADS, 0 (1) maximum number of threads to use
                           (MSK_IPAR_INTPNT_NUM_THREADS)
116 - MOSEK_OPT, 0         See MOSEK_OPTIONS for details

Gurobi options
121 - GRB_METHOD, -1       solution algorithm (Method)
    [ -1 - automatic, let Gurobi decide ]
    [ 0 - primal simplex ]

```

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```

[ 1 - dual simplex ]
[ 2 - barrier ]
[ 3 - concurrent (LP only) ]
[ 4 - deterministic concurrent (LP only) ]
122 - GRB_TIMELIMIT, Inf maximum time allowed for solver (TimeLimit)
123 - GRB_THREADS, 0 (auto) maximum number of threads to use (Threads)
124 - GRB_OPT, 0 See GUROBI_OPTIONS for details

```

psse_convert

psse_convert(warns, data, verbose)

[psse_convert\(\)](#) (page 364) - Converts data read from PSS/E RAW file to MATPOWER case.

```

[MPC, WARNINGS] = PSSE_CONVERT(WARNINGS, DATA)
[MPC, WARNINGS] = PSSE_CONVERT(WARNINGS, DATA, VERBOSE)

```

Converts data read from a **version** RAW data file into a MATPOWER **case struct**.

Input:

WARNINGS : **cell** array of strings containing accumulated warning messages

DATA : **struct** read by PSSE_READ (see PSSE_READ **for** details).

VERBOSE : 1 to display progress info, 0 (default) otherwise

Output:

MPC : a MATPOWER **case struct** created from the PSS/E data

WARNINGS : **cell** array of strings containing updated accumulated warning messages

See also [psse_read\(\)](#) (page 369).

psse_convert_hvdc

psse_convert_hvdc(dc, bus)

[psse_convert_hvdc\(\)](#) (page 364) - Convert HVDC data from PSS/E RAW to MATPOWER.

```

DCLINE = PSSE_CONVERT_HVDC(DC, BUS)

```

Convert **all** two terminal HVDC **line** data read from a PSS/E RAW data file into MATPOWER format. Returns a dcline matrix **for** inclusion in a MATPOWER **case struct**.

Inputs:

DC : matrix of raw two terminal HVDC **line** data returned by PSSE_READ in data.twodc.num

BUS : MATPOWER bus matrix

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Output:

DCLINE : a MATPOWER dcline matrix suitable **for** inclusion in
a MATPOWER **case struct**.

See also [psse_convert\(\)](#) (page 364).

psse_convert_xfmr

psse_convert_xfmr(warns, trans2, trans3, verbose, baseMVA, bus, bus_name)

[psse_convert_xfmr\(\)](#) (page 365) - Convert transformer data from PSS/E RAW to MATPOWER.

```
[XFMR, BUS, WARNINGS] = PSSE_CONVERT_XFMR(WARNINGS, TRANS2, TRANS3, ...
                                         VERBOSE, BASEMVA, BUS)
[XFMR, BUS, WARNINGS, BUS_NAME] = PSSE_CONVERT_XFMR(WARNINGS, TRANS2, ...
                                                    TRANS3, VERBOSE, BASEMVA, BUS, BUS_NAME)
```

Convert **all** transformer data read from a PSS/E RAW data file into MATPOWER format. Returns a branch matrix corresponding to the transformers **and** an updated bus matrix, with additional buses added **for** the star points of three winding transformers.

Inputs:

WARNINGS : **cell** array of strings containing accumulated
warning messages
TRANS2 : matrix of raw two winding transformer data returned
by PSSE_READ in data.trans2.num
TRANS3 : matrix of raw three winding transformer data returned
by PSSE_READ in data.trans3.num
VERBOSE : **1** to **display** progress **info**, **0** (default) **otherwise**
BASEMVA : **system** MVA base
BUS : MATPOWER bus matrix
BUS_NAME: (optional) **cell** array of bus names

Outputs:

XFMR : MATPOWER branch matrix of transformer data
BUS : updated MATPOWER bus matrix, with additional buses
added **for** star points of three winding transformers
WARNINGS : **cell** array of strings containing updated accumulated
warning messages
BUS_NAME: (optional) updated **cell** array of bus names

See also [psse_convert\(\)](#) (page 364).

psse_parse**psse_parse**(records, sections, verbose, rev)*psse_parse()* (page 366) - Parses the data from a PSS/E RAW data file.

```

DATA = PSSE_PARSE(RECORDS, SECTIONS)
DATA = PSSE_PARSE(RECORDS, SECTIONS, VERBOSE)
DATA = PSSE_PARSE(RECORDS, SECTIONS, VERBOSE, REV)
[DATA, WARNINGS] = PSSE_PARSE(RECORDS, SECTIONS, ...)

```

Parses the data from a PSS/E RAW data file (as read by PSSE_READ) into a **struct**.

Inputs:

- RECORDS : **cell** array of strings, corresponding to the lines in the RAW file
- SECTIONS : **struct** array with indices marking the beginning and end of each section, and the name of the section, fields are:
 - first : **index** into RECORDS of first **line** of section
 - last : **index** into RECORDS of last **line** of section
 - name : name of the section, as extracted from the END OF ... DATA comments
- VERBOSE : **1** (default) to **display** progress info, **0** otherwise
- REV : (optional) assume the **input** file is of this PSS/E revision number, attempts to determine REV from the file by default

Output(s):

- DATA : a **struct** with the following fields, each with two sub-fields, 'num' and 'txt' containing the numeric and text data read from the file for the corresponding section
 - id
 - bus
 - load
 - gen
 - shunt
 - branch
 - trans2
 - trans3
 - area
 - twodc
 - swshunt
- WARNINGS : **cell** array of strings containing accumulated warning messages

See also `psse2mpc()`, `psse_read()` (page 369), `psse_parse_section()` (page 367), `psse_parse_line()` (page 367).

psse_parse_line

psse_parse_line(*str*, *t*)

psse_parse_line() (page 367) - Reads and parses a single line from a PSS/E RAW data file.

```
[DATA, COMMENT] = PSSE_PARSE_LINE(FID)
[DATA, COMMENT] = PSSE_PARSE_LINE(FID, TEMPLATE)
[DATA, COMMENT] = PSSE_PARSE_LINE(STR)
[DATA, COMMENT] = PSSE_PARSE_LINE(STR, TEMPLATE)
```

Parses a **single line** from a PSS/E RAW data file, either directly read from the file, **or** passed as a string.

Inputs:

FID : (optional) file id of file from which to read the **line**

STR : string containing the **line** to be parsed

TEMPLATE : (optional) string of characters indicating how to interpret the **type** of the corresponding column, options are as follows:

- d, f **or** g : integer floating point number to be converted via SSCANF with **%d, %f or %g, respectively**.
- D, F **or** G : integer floating point number, possibly enclosed in **single or double** quotes, to be converted via SSCANF with **%d, %f or %g, respectively**.
- c **or** s : character **or** string, possibly enclosed in **single or double** quotes, which are stripped from the string

Note: Data **columns** in STR that have no valid corresponding entry in TEMPLATE (beyond **end** of TEMPLATE, **or** a character other than those listed, e.g. **'.'**) are returned as a string with no conversion. TEMPLATE entries **for** which there is no corresponding column are returned as **NaN or** empty string, depending on the **type**.

Outputs:

DATA : a **cell** array whose elements contain the contents of the corresponding column in the data, converted according to the TEMPLATE.

COMMENT : (optional) possible comment at the **end** of the **line**

psse_parse_section

psse_parse_section(*warns*, *records*, *sections*, *s*, *verbose*, *label*, *template*)

psse_parse_section() (page 367) - Parses the data from a section of a PSS/E RAW data file.

```
[DATA, WARNINGS] = PSSE_PARSE_SECTION(WARNINGS, RECORDS, SECTIONS, SIDX, ...
                                       VERBOSE, LABEL, TEMPLATE)
[DATA, WARNINGS] = PSSE_PARSE_SECTION(WARNINGS, RECORDS, SECTIONS, SIDX, ...
                                       VERBOSE, LABEL)
[DATA, WARNINGS] = PSSE_PARSE_SECTION(WARNINGS, RECORDS, SECTIONS, SIDX, ...
                                       VERBOSE)
[DATA, WARNINGS] = PSSE_PARSE_SECTION(WARNINGS, RECORDS, SECTIONS, SIDX)
```

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```
[DATA, WARNINGS] = PSSE_PARSE_SECTION(WARNINGS, RECORDS, VERBOSE, LABEL, ...
                                     TEMPLATE)
[DATA, WARNINGS] = PSSE_PARSE_SECTION(WARNINGS, RECORDS, VERBOSE, LABEL)
[DATA, WARNINGS] = PSSE_PARSE_SECTION(WARNINGS, RECORDS, VERBOSE)
[DATA, WARNINGS] = PSSE_PARSE_SECTION(WARNINGS, RECORDS)
```

Inputs:

WARNINGS : cell array of strings containing accumulated warning messages

RECORDS : a cell array of strings returned by PSSE_READ

SECTIONS : a struct array returned by PSSE_READ

SIDX : (optional) index if the section to be read if included, the RECORD indices are taken from SECTIONS(SIDX), otherwise use all RECORDS

VERBOSE : 1 to display progress info, 0 (default) otherwise

LABEL : (optional) name for the section, to be compared with the section name typically found in the END OF <LABEL> DATA comment at the end of each section

TEMPLATE : (optional) string of characters indicating how to interpret the type of the corresponding column, options are as follows:

- d, f or g : integer floating point number to be converted via SSCANF with %d, %f or %g, respectively.
- D, F or G : integer floating point number, possibly enclosed in single or double quotes, to be converted via SSCANF with %d, %f or %g, respectively.
- c or s : character or string, possibly enclosed in single or double quotes, which are stripped from the string

Note: Data columns in RECORDS that have no valid corresponding entry in TEMPLATE (beyond end of TEMPLATE, or a character other than those listed, e.g. '.') are returned in DATA.txt with no conversion. TEMPLATE entries for which there is no corresponding column in RECORDS are returned as NaN and empty, respectively, in DATA.num and DATA.txt.

Output:

DATA : a struct with two fields:

- num : matrix containing the numeric data for the section, for columns with no numeric data, num contain NaNs.
- txt : a cell array containing the non-numeric (char/string) data for the section, for columns with numeric data, txt entries are empty

WARNINGS : cell array of strings containing updated accumulated warning messages

See also `psse2mpc()`, `psse_parse()` (page 366).

psse_read

psse_read(rawfile_name, verbose)

psse_read() (page 369) - Reads the data from a PSS/E RAW data file.

```
[RECORDS, SECTIONS] = PSSE_READ(RAWFILE_NAME)
```

```
[RECORDS, SECTIONS] = PSSE_READ(RAWFILE_NAME, VERBOSE)
```

Reads the data from a PSS/E RAW data file into a **cell** array of strings, corresponding to the lines/records in the file. It detects the beginning **and** ending indices of each section as well as **any** Q **record** used to indicate the **end** of the data.

Input:

RAWFILE_NAME : name of the PSS/E RAW file to be read
(opened directly with FILEREAD)

VERBOSE : 1 to **display** progress **info**, 0 (default) **otherwise**

Output:

RECORDS : a **cell** array of strings, one **for** each **line** in the file (new **line** characters **not** included)

SECTIONS : a **struct** array with the following fields

first : **index** into RECORDS of first **line** of the section

last : **index** into RECORDS of last **line** of the section

name : name of the section (**if** available) extracted

from the 'END OF <NAME> DATA, BEGIN ... DATA'

comment typically found in the terminator **line**

See also psse2mpc().

5.3 Legacy Tests

5.3.1 Legacy MATPOWER Tests

t_apply_changes

t_apply_changes(quiet)

t_apply_changes() (page 369) - Tests for *apply_changes()* (page 326).

t_auction_minopf

t_auction_minopf(*quiet*)

[t_auction_minopf\(\)](#) (page 370) - Tests for code in auction.m, using MINOPF solver.

t_auction_mips

t_auction_mips(*quiet*)

[t_auction_mips\(\)](#) (page 370) - Tests for code in auction.m, using MIPS solver.

t_auction_tspopf_pdipm

t_auction_tspopf_pdipm(*quiet*)

[t_auction_tspopf_pdipm\(\)](#) (page 370) - Tests for code in auction.m, using PDIPMOPF solver.

t_chgtab

t_chgtab()

[t_chgtab\(\)](#) (page 370) - Returns a change table for testing [apply_changes\(\)](#) (page 326).

t_cpf

t_cpf(*quiet*)

[t_cpf\(\)](#) (page 370) - Tests for legacy continuation power flow.

t_dcline

t_dcline(*quiet*)

[t_dcline\(\)](#) (page 370) - Tests for DC line extension in [toggle_dcline\(\)](#) (page 302).

t_ext2int2ext

t_ext2int2ext(*quiet*)

[t_ext2int2ext\(\)](#) (page 370) - Tests [ext2int\(\)](#), [int2ext\(\)](#), and related functions.

Includes tests for [get_reorder\(\)](#) (page 257), [set_reorder\(\)](#) (page 257), [e2i_data\(\)](#) (page 252), [i2e_data\(\)](#) (page 255), [e2i_field\(\)](#) (page 253), [i2e_field\(\)](#) (page 256), [ext2int\(\)](#), and [int2ext\(\)](#).

t_feval_w_path**t_feval_w_path**(*quiet*)*t_feval_w_path*() (page 371) - Tests for *feval_w_path*() (page 331).**t_get_losses****t_get_losses**(*quiet*)*t_get_losses*() (page 371) - Tests for *get_losses*() (page 335).**t_hasPQcap****t_hasPQcap**(*quiet*)*t_hasPQcap*() (page 371) - Tests for *hasPQcap*() (page 336).**t_hessian****t_hessian**(*quiet*)*t_hessian*() (page 371) - Numerical tests of 2nd derivative code.**t_islands****t_islands**(*quiet*)*t_islands*() (page 371) - Tests for *find_islands*() (page 332), *extract_islands*() (page 330), *connected_components*() (page 352) and *case_info*() (page 328).**t_jacobian****t_jacobian**(*quiet*)*t_jacobian*() (page 371) - Numerical tests of partial derivative code.

t_load2disp

t_load2disp(*quiet*)

t_load2disp() (page 372) - Tests for load2disp().

t_loadcase

t_loadcase(*quiet*)

t_loadcase() (page 372) - Test that loadcase() works with a struct as well as case file.

t_makeLODF

t_makeLODF(*quiet*)

t_makeLODF() (page 372) - Tests for *makeLODF()* (page 324).

t_makePTDF

t_makePTDF(*quiet*)

t_makePTDF() (page 372) - Tests for *makePTDF()* (page 324).

t_margcost

t_margcost(*quiet*)

t_margcost() (page 372) - Tests for margcost().

t_miqps_matpower

t_miqps_matpower(*quiet*)

t_miqps_matpower() (page 372) - Tests of MIQP solvers via (deprecated) *miqps_matpower()* (page 322).

t_modcost

t_modcost(*quiet*)

t_modcost() (page 372) - Tests for code in modcost().

t_moption

t_moption(*quiet*)

[t_moption\(\)](#) (page 373) - Tests for moption().

t_moption_ov

t_moption_ov()

[t_moption_ov\(\)](#) (page 373) - Example of option overrides from file.

t_off2case

t_off2case(*quiet*)

[t_off2case\(\)](#) (page 373) - Tests for off2case.

t_opf_dc_bpmpd

t_opf_dc_bpmpd(*quiet*)

[t_opf_dc_bpmpd\(\)](#) (page 373) - Tests for legacy DC optimal power flow using BPMPD_MEX solver.

t_opf_dc_clp

t_opf_dc_clp(*quiet*)

[t_opf_dc_clp\(\)](#) (page 373) - Tests for legacy DC optimal power flow using CLP solver.

t_opf_dc_cplex

t_opf_dc_cplex(*quiet*)

[t_opf_dc_cplex\(\)](#) (page 373) - Tests for legacy DC optimal power flow using CPLEX solver.

t_opf_dc_default

t_opf_dc_default(*quiet*)

[t_opf_dc_default\(\)](#) (page 373) - Tests for legacy DC optimal power flow using DEFAULT solver.

t_opf_dc_glpk

t_opf_dc_glpk(*quiet*)

[*t_opf_dc_glpk\(\)*](#) (page 374) - Tests for legacy DC optimal power flow using GLPK solver.

t_opf_dc_gurobi

t_opf_dc_gurobi(*quiet*)

[*t_opf_dc_gurobi\(\)*](#) (page 374) - Tests for legacy DC optimal power flow using Gurobi solver.

t_opf_dc_ipopt

t_opf_dc_ipopt(*quiet*)

[*t_opf_dc_ipopt\(\)*](#) (page 374) - Tests for legacy DC optimal power flow using MIPS solver.

t_opf_dc_mips

t_opf_dc_mips(*quiet*)

[*t_opf_dc_mips\(\)*](#) (page 374) - Tests for legacy DC optimal power flow using MIPS solver.

t_opf_dc_mips_sc

t_opf_dc_mips_sc(*quiet*)

[*t_opf_dc_mips_sc\(\)*](#) (page 374) - Tests for legacy DC optimal power flow using MIPS-sc solver.

t_opf_dc_mosek

t_opf_dc_mosek(*quiet*)

[*t_opf_dc_mosek\(\)*](#) (page 374) - Tests for legacy DC optimal power flow using MOSEK solver.

t_opf_dc_osqp

t_opf_dc_osqp(*quiet*)

[*t_opf_dc_osqp\(\)*](#) (page 374) - Tests for legacy DC optimal power flow using OSQP solver.

t_opf_dc_ot**t_opf_dc_ot**(*quiet*)*t_opf_dc_ot*() (page 375) - Tests for legacy DC optimal power flow using Opt Tbx solvers.**t_opf_default****t_opf_default**(*quiet*)*t_opf_default*() (page 375) - Tests for legacy AC optimal power flow using default solver.**t_opf_fmincon****t_opf_fmincon**(*quiet*)*t_opf_fmincon*() (page 375) - Tests for legacy FMINCON-based optimal power flow.**t_opf_ipopt****t_opf_ipopt**(*quiet*)*t_opf_ipopt*() (page 375) - Tests for legacy IPOPT-based AC optimal power flow.**t_opf_knitro****t_opf_knitro**(*quiet*)*t_opf_knitro*() (page 375) - Tests for legacy Artelys Knitro-based optimal power flow.**t_opf_minopf****t_opf_minopf**(*quiet*)*t_opf_minopf*() (page 375) - Tests for legacy MINOS-based optimal power flow.**t_opf_mips****t_opf_mips**(*quiet*)*t_opf_mips*() (page 375) - Tests for legacy MIPS-based AC optimal power flow.

t_opf_model

t_opf_model(*quiet*)

[*t_opf_model\(\)*](#) (page 376) - Tests for [*opf_model*](#) (page 217).

t_opf_softlims

t_opf_softlims(*quiet*)

[*t_opf_softlims\(\)*](#) (page 376) - Tests for userfcn callbacks (softlims) w/OPF.

Includes high-level tests of soft limits implementations.

t_opf_tspopf_pdipm

t_opf_tspopf_pdipm(*quiet*)

[*t_opf_tspopf_pdipm\(\)*](#) (page 376) - Tests for legacy PDIPM-based optimal power flow.

t_opf_tspopf_scpdipm

t_opf_tspopf_scpdipm(*quiet*)

[*t_opf_tspopf_scpdipm\(\)*](#) (page 376) - Tests for legacy SCPDIPM-based optimal power flow.

t_opf_tspopf_tralm

t_opf_tspopf_tralm(*quiet*)

[*t_opf_tspopf_tralm\(\)*](#) (page 376) - Tests for legacy TRALM-based optimal power flow.

t_opf_userfcns

t_opf_userfcns(*quiet*)

[*t_opf_userfcns\(\)*](#) (page 376) - Tests for userfcn callbacks (reserves/iflms) w/OPF.

Includes high-level tests of reserves and iflms implementations.

t_pf_ac**t_pf_ac**(*quiet*)[t_pf_ac\(\)](#) (page 377) - Tests for legacy AC power flow solvers.**t_pf_dc****t_pf_dc**(*quiet*)[t_pf_dc\(\)](#) (page 377) - Tests for legacy DC power flow solver.**t_pf_radial****t_pf_radial**(*quiet*)[t_pf_radial\(\)](#) (page 377) - Tests for legacy distribution power flow solvers.**t_printpf****t_printpf**(*quiet*)[t_printpf\(\)](#) (page 377) - Tests for `printpf()`.**t_psse****t_psse**(*quiet*)[t_psse\(\)](#) (page 377) - Tests for `psse2mpc()` and related functions.**t_qps_matpower****t_qps_matpower**(*quiet*)[t_qps_matpower\(\)](#) (page 377) - Tests of QP solvers via (deprecated) [qps_matpower\(\)](#) (page 322).**t_runmarket****t_runmarket**(*quiet*)[t_runmarket\(\)](#) (page 377) - Tests for `runmkt`, `smartmkt` and `auction`.

t_runopf_w_res**t_runopf_w_res**(*quiet*)*t_runopf_w_res()* (page 378) - Tests *runopf_w_res()* (page 233) and the associated callbacks.**t_scale_load****t_scale_load**(*quiet*)*t_scale_load()* (page 378) - Tests for *scale_load()* (page 346).**t_total_load****t_total_load**(*quiet*)*t_total_load()* (page 378) - Tests for *total_load()* (page 348).**t_totcost****t_totcost**(*quiet*)*t_totcost()* (page 378) - Tests for *totcost()*.**t_vdep_load****t_vdep_load**(*quiet*)*t_vdep_load()* (page 378) - Test voltage dependent ZIP load model for legacy PF, CPF, OPF.

5.3.2 Legacy MATPOWER Test Data

opf_nle_fcn1**opf_nle_fcn1**(*x*)*opf_nle_fcn1()* (page 378) - Example user-defined nonlinear OPF constraint function.

opf_nle_hess1

opf_nle_hess1(*x*, *lambda*)

[opf_nle_hess1\(\)](#) (page 379) - Example user-defined nonlinear OPF constraint Hessian.

t_auction_case

t_auction_case()

[t_auction_case\(\)](#) (page 379) - Power flow data for testing auction code.

Please see caseformat for details on the case file format.

t_case30_userfcns

t_case30_userfcns()

[t_case30_userfcns\(\)](#) (page 379) - Power flow data for 30 bus, 6 gen case w/reserves & iflms.

Please see caseformat for details on the case file format.

Same as case30.m, but with fixed reserve and interface flow limit data. The reserve data is defined in the fields of mpc.reserves and the interface flow limit data in mpc.if at the bottom of the file.

t_case9_dcline

t_case9_dcline()

[t_case9_dcline\(\)](#) (page 379) - Same as [t_case9_opfv2\(\)](#) (page 380) with addition of DC line data.

Please see caseformat for details on the case file format.

See also [toggle_dcline\(\)](#) (page 302), [idx_dcline\(\)](#) (page 341).

t_case9_opf

t_case9_opf()

[t_case9_opf\(\)](#) (page 379) - Power flow data for 9 bus, 3 generator case, with OPF data.

Please see caseformat for details on the case file format.

t_case9_opfv2

t_case9_opfv2()

t_case9_opfv2() (page 380) - Power flow data for 9 bus, 3 generator case, with OPF data.

Please see caseformat for details on the case file format.

t_case9_pf

t_case9_pf()

t_case9_pf() (page 380) - Power flow data for 9 bus, 3 generator case, no OPF data.

Please see caseformat for details on the case file format.

t_case9_pfv2

t_case9_pfv2()

t_case9_pfv2() (page 380) - Power flow data for 9 bus, 3 generator case, no OPF data.

Please see caseformat for details on the case file format.

t_case9_save2psse

t_case9_save2psse()

t_case9_save2psse() (page 380) - Power flow data to test save2psse().

Please see caseformat for details on the case file format.

t_case_ext

t_case_ext()

t_case_ext() (page 380) - Case data in external format used to test ext2int() and int2ext().

t_case_int

t_case_int()

t_case_int() (page 380) - Case data in internal format used to test ext2int() and int2ext().

t_cpf_cb1**t_cpf_cb1**(*k, nx, cx, px, done, rollback, evnts, cb_data, cb_args, results*)*t_cpf_cb1()* (page 381) - User callback function 1 for continuation power flow testing.**t_cpf_cb2****t_cpf_cb2**(*k, nx, cx, px, done, rollback, evnts, cb_data, cb_args, results*)*t_cpf_cb2()* (page 381) - User callback function 2 for continuation power flow testing.

A

`add_aux_data()` (*mp.math_model* method), 123
`add_constraints()` (*mp.math_model* method), 124
`add_constraints()` (*mp.mm_element* method), 144
`add_constraints()` (*mp.mme_branch_opf_ac* method), 147
`add_constraints()` (*mp.mme_branch_opf_acc* method), 148
`add_constraints()` (*mp.mme_branch_opf_acp* method), 148
`add_constraints()` (*mp.mme_branch_opf_dc* method), 148
`add_constraints()` (*mp.mme_bus_opf_acc* method), 150
`add_constraints()` (*mp.mme_buslink_opf_acc* method), 201
`add_constraints()` (*mp.mme_buslink_opf_acp* method), 201
`add_constraints()` (*mp.mme_buslink_pf_ac* method), 198
`add_constraints()` (*mp.mme_buslink_pf_acc* method), 199
`add_constraints()` (*mp.mme_buslink_pf_acp* method), 199
`add_constraints()` (*mp.mme_gen_opf_ac* method), 153
`add_constraints()` (*mp.mme_gen_opf_dc* method), 153
`add_constraints()` (*mp.mme_legacy_dcline_opf* method), 210
`add_constraints()` (*mp.mme_reserve_gen* method), 177
`add_constraints()` (*mp.mme_reserve_zone* method), 178
`add_costs()` (*mp.math_model* method), 124
`add_costs()` (*mp.math_model_pf* method), 126
`add_costs()` (*mp.mm_element* method), 145
`add_costs()` (*mp.mme_gen_opf* method), 152
`add_costs()` (*mp.mme_gen_opf_ac* method), 153
`add_costs()` (*mp.mme_legacy_dcline_opf* method), 210
`add_costs()` (*mp.mme_reserve_gen* method), 177
`add_elements()` (*mp.mapped_array* method), 168
`add_legacy_cost()` (*mp.mm_shared_opf_legacy* method), 142
`add_legacy_cost()` (*opf_model* method), 221
`add_legacy_user_constraints()` (*mp.mm_shared_opf_legacy* method), 142
`add_legacy_user_constraints_ac()` (*mp.mm_shared_opf_legacy* method), 142
`add_legacy_user_costs()` (*mp.mm_shared_opf_legacy* method), 142
`add_legacy_user_vars()` (*mp.mm_shared_opf_legacy* method), 142
`add_named_set()` (*mp.math_model_opf_acci_legacy* method), 133
`add_named_set()` (*mp.math_model_opf_accs_legacy* method), 134
`add_named_set()` (*mp.math_model_opf_acpi_legacy* method), 135
`add_named_set()` (*mp.math_model_opf_acps_legacy* method), 136
`add_named_set()` (*mp.math_model_opf_dc_legacy* method), 138
`add_named_set()` (*opf_model* method), 221
`add_names()` (*mp.mapped_array* method), 168
`add_node()` (*mp.net_model* method), 95
`add_node_balance_constraints()` (*mp.math_model* method), 124
`add_node_balance_constraints()` (*mp.math_model_cpf_acci* method), 130
`add_node_balance_constraints()` (*mp.math_model_cpf_accs* method), 130
`add_node_balance_constraints()` (*mp.math_model_cpf_acpi* method), 131
`add_node_balance_constraints()` (*mp.math_model_cpf_acps* method), 131
`add_node_balance_constraints()` (*mp.math_model_opf_acci* method), 133
`add_node_balance_constraints()` (*mp.math_model_opf_accs* method), 134
`add_node_balance_constraints()` (*mp.math_model_opf_acpi* method), 135
`add_node_balance_constraints()` (*mp.math_model_opf_acps* method), 136
`add_node_balance_constraints()` (*mp.math_model_opf_dc* method), 137
`add_node_balance_constraints()` (*mp.math_model_pf_acci* method), 127
`add_node_balance_constraints()` (*mp.math_model_pf_accs* method), 127
`add_node_balance_constraints()` (*mp.math_model_pf_acpi* method), 128
`add_node_balance_constraints()` (*mp.math_model_pf_acps* method), 128
`add_node_balance_constraints()` (*mp.math_model_pf_dc* method), 129
`add_nodes()` (*mp.net_model* method), 92
`add_nodes()` (*mp.nm_element* method), 110
`add_port()` (*mp.net_model* method), 95
`add_state()` (*mp.net_model* method), 95
`add_states()` (*mp.net_model* method), 93
`add_states()` (*mp.nm_element* method), 110
`add_system_constraints()` (*mp.math_model* method), 124
`add_system_constraints()` (*mp.math_model_opf_acci_legacy* method), 133
`add_system_constraints()` (*mp.math_model_opf_accs_legacy* method), 134
`add_system_constraints()` (*mp.math_model_opf_acpi_legacy* method), 136
`add_system_constraints()` (*mp.math_model_opf_acps_legacy* method), 137
`add_system_constraints()` (*mp.math_model_opf_dc_legacy* method), 138
`add_system_costs()` (*mp.math_model* method), 125
`add_system_costs()` (*mp.math_model_opf_acci_legacy* method), 133

add_system_costs() (*mp.math_model_opf_accs_legacy method*), 134
 add_system_costs() (*mp.math_model_opf_acpi_legacy method*), 136
 add_system_costs() (*mp.math_model_opf_acps_legacy method*), 137
 add_system_costs() (*mp.math_model_opf_dc_legacy method*), 138
 add_system_vars() (*mp.math_model method*), 123
 add_system_vars() (*mp.math_model_opf method*), 132
 add_system_vars() (*mp.math_model_pf method*), 126
 add_system_vars_pf() (*mp.mm_shared_pfcpf_acci method*), 140
 add_system_vars_pf() (*mp.mm_shared_pfcpf_accs method*), 140
 add_system_vars_pf() (*mp.mm_shared_pfcpf_acpi method*), 141
 add_system_vars_pf() (*mp.mm_shared_pfcpf_acps method*), 141
 add_system_vars_pf() (*mp.mm_shared_pfcpf_dc method*), 141
 add_system_varset_pf() (*mp.mm_shared_pfcpf_ac method*), 138
 add_userfcn() (*built-in function*), 300
 add_var() (*mp.net_model method*), 96
 add_vars() (*mp.math_model method*), 123
 add_vars() (*mp.math_model_opf_acci_legacy method*), 133
 add_vars() (*mp.math_model_opf_accs_legacy method*), 134
 add_vars() (*mp.math_model_opf_acpi_legacy method*), 136
 add_vars() (*mp.math_model_opf_acps_legacy method*), 137
 add_vars() (*mp.math_model_opf_dc_legacy method*), 138
 add_vars() (*mp.mm_element method*), 144
 add_vars() (*mp.nme_buslink_pf_ac method*), 198
 add_vars() (*mp.nme_gen_opf method*), 152
 add_vars() (*mp.nme_legacy_dcline_opf method*), 210
 add_vars() (*mp.nme_reserve_gen method*), 177
 add_vvars() (*mp.net_model method*), 94
 add_vvars() (*mp.nm_element method*), 110
 add_vvars() (*mp.nme_bus3p_acc method*), 193
 add_vvars() (*mp.nme_bus3p_acp method*), 193
 add_vvars() (*mp.nme_bus_acc method*), 116
 add_vvars() (*mp.nme_bus_acp method*), 116
 add_vvars() (*mp.nme_bus_dc method*), 117
 add_zvars() (*mp.net_model method*), 94
 add_zvars() (*mp.nm_element method*), 111
 add_zvars() (*mp.nme_buslink method*), 196
 add_zvars() (*mp.nme_gen3p method*), 194
 add_zvars() (*mp.nme_gen_ac method*), 117
 add_zvars() (*mp.nme_gen_dc method*), 118
 add_zvars() (*mp.nme_legacy_dcline_ac method*), 207
 add_zvars() (*mp.nme_legacy_dcline_dc method*), 208
 ang_diff_fcn() (*mp.nme_branch_acc method*), 115
 ang_diff_hess() (*mp.nme_branch_acc method*), 115
 ang_diff_params() (*mp.nme_branch_opf method*), 147
 ang_diff_prices() (*mp.nme_branch_opf method*), 147
 ang_diff_prices() (*mp.nme_branch_opf_acc method*), 148
 apply_changes() (*built-in function*), 326
 apply_vm_setpoint() (*mp.dme_gen method*), 52
 apply_vm_setpoint() (*mp.dme_gen3p method*), 185
 apply_vm_setpoints() (*mp.dme_legacy_dcline method*), 205
 aux_data (*mp.math_model attribute*), 122
 aux_data_va_vm() (*mp.form_ac method*), 82
 aux_data_va_vm() (*mp.form_acc method*), 84
 aux_data_va_vm() (*mp.form_acp method*), 88

B

B (*mp.form_dc attribute*), 89
 b_fr (*mp.dme_branch attribute*), 46
 b_to (*mp.dme_branch attribute*), 47
 base_kva (*mp.data_model attribute*), 28
 base_mva (*mp.data_model attribute*), 28
 bs (*mp.dme_shunt attribute*), 56
 build() (*mp.data_model method*), 29
 build() (*mp.dm_converter method*), 59

build() (*mp.math_model method*), 122
 build() (*mp.math_model_opf_acci_legacy method*), 133
 build() (*mp.math_model_opf_accs_legacy method*), 134
 build() (*mp.math_model_opf_acpi_legacy method*), 136
 build() (*mp.math_model_opf_acps_legacy method*), 137
 build() (*mp.math_model_opf_dc_legacy method*), 138
 build() (*mp.net_model method*), 92
 build_aux_data() (*mp.math_model_opf method*), 132
 build_aux_data() (*mp.mm_shared_pfcpf method*), 138
 build_aux_data() (*mp.mm_shared_pfcpf_acci method*), 140
 build_aux_data() (*mp.mm_shared_pfcpf_acpi method*), 141
 build_aux_data() (*mp.mm_shared_pfcpf_acps method*), 141
 build_aux_data() (*mp.mm_shared_pfcpf_dc method*), 141
 build_aux_data_i() (*mp.mm_shared_pfcpf_ac_i method*), 139
 build_base_aux_data() (*mp.math_model method*), 123
 build_cost_params() (*mp.dme_gen_opf method*), 53
 build_cost_params() (*mp.dme_legacy_dcline_opf method*), 206
 build_cost_params() (*mp.nme_gen_opf_ac method*), 153
 build_cost_params() (*mp.nme_gen_opf_dc method*), 153
 build_cost_params() (*mp.nme_legacy_dcline_opf method*), 210
 build_legacy() (*mp.mm_shared_opf_legacy method*), 142
 build_params() (*mp.data_model method*), 30
 build_params() (*mp.dm_element method*), 41
 build_params() (*mp.dme_branch method*), 47
 build_params() (*mp.dme_bus method*), 50
 build_params() (*mp.dme_bus3p method*), 183
 build_params() (*mp.dme_buslink method*), 191
 build_params() (*mp.dme_gen method*), 52
 build_params() (*mp.dme_gen3p method*), 185
 build_params() (*mp.dme_legacy_dcline method*), 205
 build_params() (*mp.dme_line3p method*), 188
 build_params() (*mp.dme_load method*), 55
 build_params() (*mp.dme_load3p method*), 186
 build_params() (*mp.dme_reserve_gen method*), 176
 build_params() (*mp.dme_reserve_zone method*), 177
 build_params() (*mp.dme_shunt method*), 57
 build_params() (*mp.dme_xfnr3p method*), 190
 build_params() (*mp.net_model method*), 93
 build_params() (*mp.net_model_ac method*), 101
 build_params() (*mp.net_model_dc method*), 107
 build_params() (*mp.nm_element method*), 111
 build_params() (*mp.nme_branch_ac method*), 114
 build_params() (*mp.nme_branch_dc method*), 115
 build_params() (*mp.nme_buslink method*), 196
 build_params() (*mp.nme_gen3p method*), 194
 build_params() (*mp.nme_gen_ac method*), 117
 build_params() (*mp.nme_gen_dc method*), 118
 build_params() (*mp.nme_legacy_dcline_ac method*), 207
 build_params() (*mp.nme_legacy_dcline_dc method*), 208
 build_params() (*mp.nme_line3p method*), 195
 build_params() (*mp.nme_load3p method*), 194
 build_params() (*mp.nme_load_ac method*), 119
 build_params() (*mp.nme_load_dc method*), 119
 build_params() (*mp.nme_shunt_ac method*), 120
 build_params() (*mp.nme_shunt_dc method*), 121
 build_params() (*mp.nme_xfnr3p method*), 195
 bus (*mp.dmce_load3p_mpc2 attribute*), 181
 bus (*mp.dmce_load_mpc2 attribute*), 70
 bus (*mp.dmce_shunt_mpc2 attribute*), 71
 bus (*mp.dme_buslink attribute*), 190
 bus (*mp.dme_gen attribute*), 51
 bus (*mp.dme_gen3p attribute*), 184
 bus (*mp.dme_load attribute*), 54
 bus (*mp.dme_load3p attribute*), 186
 bus (*mp.dme_shunt attribute*), 56
 bus3p (*mp.dme_buslink attribute*), 190
 bus_name_export() (*mp.dmce_bus_mpc2 method*), 69
 bus_name_import() (*mp.dmce_bus_mpc2 method*), 69

bus_on(*mp.dme_gen* attribute), 51
 bus_on(*mp.dme_gen3p* attribute), 184
 bus_status_import() (*mp.dmce_bus3p_mpc2* method), 180
 bus_status_import() (*mp.dmce_bus_mpc2* method), 69
 bustypes() (built-in function), 327

C

C(*mp.nm_element* attribute), 108
 calc_branch_angle() (built-in function), 328
 calc_v_i_sum() (built-in function), 257
 calc_v_pq_sum() (built-in function), 258
 calc_v_y_sum() (built-in function), 259
 callback_vlim() (*mp.math_model_cpf_acp* method), 130
 case_info() (built-in function), 328
 caseformat() (built-in function), 234
 cdf2mpc() (built-in function), 237
 compare_case() (built-in function), 328
 connected_components() (built-in function), 352
 convert_x_m2n() (*mp.math_model_opf_acc* method), 132
 convert_x_m2n() (*mp.math_model_opf_acp* method), 135
 convert_x_m2n() (*mp.math_model_opf_dc* method), 137
 convert_x_m2n() (*mp.mm_shared_pfcpf_acc* method), 139
 convert_x_m2n() (*mp.mm_shared_pfcpf_acp* method), 140
 convert_x_m2n() (*mp.mm_shared_pfcpf_dc* method), 142
 copy() (*mp.data_model* method), 29
 copy() (*mp.dm_converter* method), 59
 copy() (*mp.dm_element* method), 40
 copy() (*mp.mapped_array* method), 167
 cost(*mp.mme_gen_opf* attribute), 152
 cost(*mp.mme_legacy_dcline_opf* attribute), 209
 cost(*opf_model* attribute), 218
 cost_table (class in *mp*), 161
 cost_table() (*mp.cost_table* method), 162
 cost_table2gencost() (*mp.dmce_gen_mpc2* static method), 70
 cost_table_utils (class in *mp*), 164
 count() (*mp.data_model* method), 29
 count() (*mp.dm_element* method), 40
 count() (*mp.dme_load* method), 55
 count() (*mp.dme_shunt* method), 57
 count() (*mp.nm_element* method), 110
 cpf_corrector() (built-in function), 267
 cpf_current_mpc() (built-in function), 268
 cpf_default_callback() (built-in function), 268
 cpf_detect_events() (built-in function), 270
 cpf_flim_event() (built-in function), 271
 cpf_flim_event_cb() (built-in function), 271
 cpf_nose_event() (built-in function), 272
 cpf_nose_event_cb() (built-in function), 272
 cpf_p() (built-in function), 272
 cpf_p_jac() (built-in function), 273
 cpf_plim_event() (built-in function), 274
 cpf_plim_event_cb() (built-in function), 274
 cpf_predictor() (built-in function), 274
 cpf_qlim_event() (built-in function), 275
 cpf_qlim_event_cb() (built-in function), 275
 cpf_register_callback() (built-in function), 276
 cpf_register_event() (built-in function), 277
 cpf_tangent() (built-in function), 277
 cpf_target_lam_event() (built-in function), 278
 cpf_target_lam_event_cb() (built-in function), 278
 cpf_vlim_event() (built-in function), 279
 cpf_vlim_event_cb() (built-in function), 279
 create_line_construction_table() (*mp.dmce_line3p_mpc2* method), 181
 create_line_construction_table() (*mp.dme_line3p* method), 188
 ctol(*mp.dme_shared_opf* attribute), 58

cxn_idx_prop() (*mp.dm_element* method), 38
 cxn_idx_prop() (*mp.dme_branch* method), 47
 cxn_idx_prop() (*mp.dme_buslink* method), 191
 cxn_idx_prop() (*mp.dme_gen* method), 52
 cxn_idx_prop() (*mp.dme_gen3p* method), 185
 cxn_idx_prop() (*mp.dme_legacy_dcline* method), 205
 cxn_idx_prop() (*mp.dme_line3p* method), 188
 cxn_idx_prop() (*mp.dme_load* method), 55
 cxn_idx_prop() (*mp.dme_load3p* method), 186
 cxn_idx_prop() (*mp.dme_shunt* method), 57
 cxn_idx_prop() (*mp.dme_xfmr3p* method), 189
 cxn_type() (*mp.dm_element* method), 38
 cxn_type() (*mp.dme_branch* method), 47
 cxn_type() (*mp.dme_buslink* method), 191
 cxn_type() (*mp.dme_gen* method), 52
 cxn_type() (*mp.dme_gen3p* method), 185
 cxn_type() (*mp.dme_legacy_dcline* method), 205
 cxn_type() (*mp.dme_line3p* method), 188
 cxn_type() (*mp.dme_load* method), 55
 cxn_type() (*mp.dme_load3p* method), 186
 cxn_type() (*mp.dme_shunt* method), 57
 cxn_type() (*mp.dme_xfmr3p* method), 189
 cxn_type_prop() (*mp.dm_element* method), 39

D

D(*mp.nm_element* attribute), 109
 d2Abr_dV2() (built-in function), 317
 d2Ibr_dV2() (built-in function), 315
 d2Imis_dV2() (built-in function), 318
 d2Imis_dVdSg() (built-in function), 319
 d2Sbr_dV2() (built-in function), 316
 d2Sbus_dV2() (built-in function), 321
 dAbr_dV() (built-in function), 310
 data_exists() (*mp.dmc_element* method), 64
 data_field() (*mp.dmc_element* method), 63
 data_field() (*mp.dmce_branch_mpc2* method), 69
 data_field() (*mp.dmce_bus3p_mpc2* method), 180
 data_field() (*mp.dmce_bus_mpc2* method), 69
 data_field() (*mp.dmce_buslink_mpc2* method), 182
 data_field() (*mp.dmce_gen3p_mpc2* method), 180
 data_field() (*mp.dmce_gen_mpc2* method), 70
 data_field() (*mp.dmce_legacy_dcline_mpc2* method), 203
 data_field() (*mp.dmce_line3p_mpc2* method), 181
 data_field() (*mp.dmce_load3p_mpc2* method), 181
 data_field() (*mp.dmce_load_mpc2* method), 70
 data_field() (*mp.dmce_reserve_gen_mpc2* method), 174
 data_field() (*mp.dmce_reserve_zone_mpc2* method), 175
 data_field() (*mp.dmce_shunt_mpc2* method), 71
 data_field() (*mp.dmce_xfmr3p_mpc2* method), 182
 data_model (class in *mp*), 27
 data_model() (*mp.data_model* method), 28
 data_model_build() (*mp.task* method), 14
 data_model_build() (*mp.task_cpf* method), 21
 data_model_build_post() (*mp.task* method), 14
 data_model_build_post() (*mp.task_opf* method), 22
 data_model_build_post() (*mp.task_opf_legacy* method), 26
 data_model_build_pre() (*mp.task* method), 14
 data_model_class() (*mp.extension* method), 171
 data_model_class() (*mp.task* method), 13
 data_model_class_default() (*mp.task* method), 13
 data_model_class_default() (*mp.task_cpf* method), 21
 data_model_class_default() (*mp.task_opf* method), 22
 data_model_cpf (class in *mp*), 34
 data_model_cpf() (*mp.data_model_cpf* method), 34
 data_model_create() (*mp.task* method), 13
 data_model_element() (*mp.dmc_element* method), 63
 data_model_element() (*mp.mm_element* method), 144

- `data_model_element()` (*mp.nm_element* method), 109
- `data_model_opf` (class in *mp*), 34
- `data_model_opf()` (*mp.data_model_opf* method), 34
- `data_model_update()` (*mp.math_model* method), 126
- `data_model_update()` (*mp.mm_element* method), 145
- `data_model_update_off()` (*mp.mm_element* method), 145
- `data_model_update_on()` (*mp.mm_element* method), 145
- `data_model_update_on()` (*mp.mme_branch_opf_ac* method), 147
- `data_model_update_on()` (*mp.mme_branch_opf_dc* method), 148
- `data_model_update_on()` (*mp.mme_branch_pf_ac* method), 146
- `data_model_update_on()` (*mp.mme_branch_pf_dc* method), 147
- `data_model_update_on()` (*mp.mme_bus3p* method), 196
- `data_model_update_on()` (*mp.mme_bus_opf_acc* method), 150
- `data_model_update_on()` (*mp.mme_bus_opf_acp* method), 150
- `data_model_update_on()` (*mp.mme_bus_opf_dc* method), 151
- `data_model_update_on()` (*mp.mme_bus_pf_ac* method), 149
- `data_model_update_on()` (*mp.mme_bus_pf_dc* method), 149
- `data_model_update_on()` (*mp.mme_gen3p* method), 197
- `data_model_update_on()` (*mp.mme_gen_opf_ac* method), 153
- `data_model_update_on()` (*mp.mme_gen_opf_dc* method), 153
- `data_model_update_on()` (*mp.mme_gen_pf_ac* method), 151
- `data_model_update_on()` (*mp.mme_gen_pf_dc* method), 152
- `data_model_update_on()` (*mp.mme_legacy_dcline_opf_ac* method), 210
- `data_model_update_on()` (*mp.mme_legacy_dcline_opf_dc* method), 210
- `data_model_update_on()` (*mp.mme_legacy_dcline_pf_ac* method), 209
- `data_model_update_on()` (*mp.mme_legacy_dcline_pf_dc* method), 209
- `data_model_update_on()` (*mp.mme_line3p* method), 197
- `data_model_update_on()` (*mp.mme_load_cpf* method), 155
- `data_model_update_on()` (*mp.mme_load_pf_ac* method), 154
- `data_model_update_on()` (*mp.mme_load_pf_dc* method), 154
- `data_model_update_on()` (*mp.mme_reserve_gen* method), 177
- `data_model_update_on()` (*mp.mme_reserve_zone* method), 178
- `data_model_update_on()` (*mp.mme_shunt_cpf* method), 156
- `data_model_update_on()` (*mp.mme_shunt_pf_ac* method), 155
- `data_model_update_on()` (*mp.mme_shunt_pf_dc* method), 156
- `data_model_update_on()` (*mp.mme_xfmr3p* method), 198
- `data_subs()` (*mp.dmc_element* method), 64
- `data_subs()` (*mp.dmce_reserve_gen_mpc2* method), 174
- `data_subs()` (*mp.dmce_reserve_zone_mpc2* method), 175
- `dc` (*mp.task_opf* attribute), 22
- `dc` (*mp.task_pf* attribute), 19
- `dcline_cost_export()` (*mp.dmce_legacy_dcline_mpc2* method), 203
- `dcline_cost_import()` (*mp.dmce_legacy_dcline_mpc2* method), 203
- `dcopf()` (built-in function), 283
- `dcopf_solver()` (built-in function), 284
- `dcpf()` (built-in function), 259
- `def_set_types()` (*mp.math_model_opf_acci_legacy* method), 133
- `def_set_types()` (*mp.math_model_opf_accs_legacy* method), 134
- `def_set_types()` (*mp.math_model_opf_acpi_legacy* method), 136
- `def_set_types()` (*mp.math_model_opf_acps_legacy* method), 136
- `def_set_types()` (*mp.math_model_opf_dc_legacy* method), 138
- `def_set_types()` (*mp.net_model* method), 94
- `def_set_types()` (*mp.net_model_ac* method), 101
- `def_set_types()` (*mp.net_model_acc* method), 104
- `def_set_types()` (*mp.net_model_acp* method), 105
- `def_set_types()` (*mp.net_model_dc* method), 107
- `def_set_types()` (*opf_model* method), 219
- `def_set_types_legacy()` (*mp.mm_shared_opf_legacy* method), 142
- `default_export_data_nrows()` (*mp.dmc_element* method), 68
- `default_export_data_table()` (*mp.dmc_element* method), 68
- `default_export_data_table()` (*mp.dmce_branch_mpc2* method), 69
- `default_export_data_table()` (*mp.dmce_bus_mpc2* method), 69
- `default_export_data_table()` (*mp.dmce_gen_mpc2* method), 70
- `default_export_data_table()` (*mp.dmce_legacy_dcline_mpc2* method), 203
- `define_constants()` (built-in function), 329
- `delete_elements()` (*mp.mapped_array* method), 168
- `dIbr_dV()` (built-in function), 307
- `diff_poly_fcn()` (*mp.cost_table* static method), 164
- `dImis_dV()` (built-in function), 311
- `disp_load_constant_pf_constraint()` (*mp.mme_gen_opf_ac* method), 153
- `display()` (*mp.data_model* method), 30
- `display()` (*mp.dm_converter* method), 60
- `display()` (*mp.dm_element* method), 42
- `display()` (*mp.mapped_array* method), 169
- `display()` (*mp.math_model* method), 123
- `display()` (*mp.net_model* method), 94
- `display()` (*mp.nm_element* method), 114
- `display()` (*mp_table* method), 159
- `display()` (*opf_model* method), 219
- `dm` (*mp.task* attribute), 9
- `dm_converter` (class in *mp*), 59
- `dm_converter_build()` (*mp.task* method), 12
- `dm_converter_class()` (*mp.extension* method), 171
- `dm_converter_class()` (*mp.task* method), 12
- `dm_converter_class()` (*mp.task_cpf* method), 21
- `dm_converter_class_mpc2_default()` (*mp.task* method), 12
- `dm_converter_class_mpc2_legacy()` (*mp.task_opf_legacy* method), 26
- `dm_converter_create()` (*mp.task* method), 12
- `dm_converter_element()` (*mp.dm_element* method), 40
- `dm_converter_mpc2` (class in *mp*), 61
- `dm_converter_mpc2()` (*mp.dm_converter_mpc2* method), 61
- `dm_converter_mpc2_legacy` (class in *mp*), 62
- `dm_element` (class in *mp*), 35
- `dm_element_classes()` (*mp.extension* method), 172
- `dm_element_classes()` (*mp.xt_3p* method), 179
- `dm_element_classes()` (*mp.xt_legacy_dcline* method), 202
- `dm_element_classes()` (*mp.xt_reserves* method), 173
- `dmc` (*mp.task* attribute), 9
- `dmc_element` (class in *mp*), 62
- `dmc_element_classes()` (*mp.extension* method), 172
- `dmc_element_classes()` (*mp.xt_3p* method), 179
- `dmc_element_classes()` (*mp.xt_legacy_dcline* method), 202
- `dmc_element_classes()` (*mp.xt_reserves* method), 173
- `dmce_branch_mpc2` (class in *mp*), 69
- `dmce_bus3p_mpc2` (class in *mp*), 180
- `dmce_bus_mpc2` (class in *mp*), 69
- `dmce_buslink_mpc2` (class in *mp*), 182
- `dmce_gen3p_mpc2` (class in *mp*), 180
- `dmce_gen_mpc2` (class in *mp*), 69
- `dmce_legacy_dcline_mpc2` (class in *mp*), 203
- `dmce_line3p_mpc2` (class in *mp*), 181
- `dmce_load3p_mpc2` (class in *mp*), 181
- `dmce_load_mpc2` (class in *mp*), 70
- `dmce_reserve_gen_mpc2` (class in *mp*), 174
- `dmce_reserve_zone_mpc2` (class in *mp*), 175
- `dmce_shunt_mpc2` (class in *mp*), 71
- `dmce_xfmr3p_mpc2` (class in *mp*), 182
- `dme_branch` (class in *mp*), 46
- `dme_branch_opf` (class in *mp*), 48
- `dme_bus` (class in *mp*), 49
- `dme_bus3p` (class in *mp*), 182
- `dme_bus3p_opf` (class in *mp*), 191
- `dme_bus_opf` (class in *mp*), 50
- `dme_buslink` (class in *mp*), 190
- `dme_buslink_opf` (class in *mp*), 192
- `dme_gen` (class in *mp*), 51

dme_gen3p (class in mp), 184
 dme_gen3p_opf (class in mp), 191
 dme_gen_opf (class in mp), 53
 dme_legacy_dcline (class in mp), 204
 dme_legacy_dcline_opf (class in mp), 206
 dme_line3p (class in mp), 187
 dme_line3p_opf (class in mp), 192
 dme_load (class in mp), 54
 dme_load3p (class in mp), 185
 dme_load3p_opf (class in mp), 192
 dme_load_cpf (class in mp), 55
 dme_load_opf (class in mp), 55
 dme_reserve_gen (class in mp), 175
 dme_reserve_zone (class in mp), 176
 dme_shared_opf (class in mp), 58
 dme_shunt (class in mp), 56
 dme_shunt_cpf (class in mp), 56
 dme_shunt_opf (class in mp), 57
 dme_xfmr3p (class in mp), 189
 dme_xfmr3p_opf (class in mp), 192
 dSbr_dV() (built-in function), 308
 dSbus_dV() (built-in function), 313

E

e2i_data() (built-in function), 252
 e2i_field() (built-in function), 253
 element_classes (mp.element_container attribute), 165
 element_container (class in mp), 165
 elements (mp.element_container attribute), 165
 end() (mp_table method), 158
 enforce_q_lims() (mp.task_pf method), 19
 ensure_ref_node() (mp.net_model method), 99
 et (mp.task attribute), 9
 eval_legacy_cost() (mp.mm_shared_opf_legacy method), 142
 eval_legacy_cost() (opf_model method), 219
 eval_poly_fcn() (mp.cost_table_static method), 163
 event_vlim() (mp.math_model_cpf_acp method), 130
 expand_z_warmstart() (mp.math_model_cpf_acps method), 131
 export() (mp.dm_converter method), 60
 export() (mp.dmc_element method), 67
 export_col() (mp.dmc_element method), 68
 export_table_values() (mp.dmc_element method), 67
 export_vars() (mp.dm_element method), 39
 export_vars() (mp.dme_branch method), 47
 export_vars() (mp.dme_branch_opf method), 48
 export_vars() (mp.dme_bus method), 49
 export_vars() (mp.dme_bus_opf method), 50
 export_vars() (mp.dme_gen method), 52
 export_vars() (mp.dme_gen_opf method), 53
 export_vars() (mp.dme_legacy_dcline method), 205
 export_vars() (mp.dme_legacy_dcline_opf method), 206
 export_vars() (mp.dme_load_cpf method), 55
 export_vars() (mp.dme_reserve_gen method), 176
 export_vars() (mp.dme_reserve_zone method), 177
 export_vars() (mp.dme_shunt_cpf method), 56
 export_vars_offline_val() (mp.dm_element method), 40
 export_vars_offline_val() (mp.dme_branch method), 47
 export_vars_offline_val() (mp.dme_branch_opf method), 48
 export_vars_offline_val() (mp.dme_bus method), 49
 export_vars_offline_val() (mp.dme_bus_opf method), 50
 export_vars_offline_val() (mp.dme_gen method), 52
 export_vars_offline_val() (mp.dme_gen_opf method), 53
 export_vars_offline_val() (mp.dme_legacy_dcline method), 205
 export_vars_offline_val() (mp.dme_legacy_dcline_opf method), 206
 export_vars_offline_val() (mp.dme_reserve_gen method), 176
 export_vars_offline_val() (mp.dme_reserve_zone method), 177

ext2int() (built-in function), 251
 extension (class in mp), 170
 extract_islands() (built-in function), 330
 extract_named_args() (mp_table static method), 159

F

fbus (mp.dme_branch attribute), 46
 fbus (mp.dme_legacy_dcline attribute), 204
 fbus (mp.dme_line3p attribute), 187
 fbus (mp.dme_xfmr3p attribute), 189
 fbus_on (mp.dme_legacy_dcline attribute), 204
 fd_jac_approx() (mp.math_model_pf_acps method), 128
 fdpf() (built-in function), 260
 fdpf_B_matrix_models() (mp.math_model_pf_acps method), 128
 feval_w_path() (built-in function), 331
 find_bridges() (built-in function), 332
 find_form_class() (mp.form method), 73
 find_islands() (built-in function), 332
 fixed_q_idx (mp.task_pf attribute), 19
 fixed_q_qty (mp.task_pf attribute), 19
 fmincopf() (built-in function), 283
 form (class in mp), 71
 form_ac (class in mp), 73
 form_acc (class in mp), 82
 form_acp (class in mp), 86
 form_dc (class in mp), 88
 form_name() (mp.form method), 72
 form_name() (mp.form_acc method), 83
 form_name() (mp.form_acp method), 86
 form_name() (mp.form_dc method), 89
 form_name() (mp.math_model method), 122
 form_name() (mp.math_model_cpf_acci method), 130
 form_name() (mp.math_model_cpf_accs method), 130
 form_name() (mp.math_model_cpf_acpi method), 131
 form_name() (mp.math_model_cpf_acps method), 131
 form_name() (mp.math_model_opf_acci method), 133
 form_name() (mp.math_model_opf_accs method), 134
 form_name() (mp.math_model_opf_acpi method), 135
 form_name() (mp.math_model_opf_acps method), 136
 form_name() (mp.math_model_opf_dc method), 137
 form_name() (mp.math_model_pf_acci method), 127
 form_name() (mp.math_model_pf_accs method), 127
 form_name() (mp.math_model_pf_acpi method), 128
 form_name() (mp.math_model_pf_acps method), 128
 form_name() (mp.math_model_pf_dc method), 129
 form_tag() (mp.form method), 72
 form_tag() (mp.form_acc method), 83
 form_tag() (mp.form_acp method), 87
 form_tag() (mp.form_dc method), 89
 form_tag() (mp.math_model method), 122
 form_tag() (mp.math_model_cpf_acci method), 129
 form_tag() (mp.math_model_cpf_accs method), 130
 form_tag() (mp.math_model_cpf_acpi method), 131
 form_tag() (mp.math_model_cpf_acps method), 131
 form_tag() (mp.math_model_opf_acci method), 133
 form_tag() (mp.math_model_opf_accs method), 134
 form_tag() (mp.math_model_opf_acpi method), 135
 form_tag() (mp.math_model_opf_acps method), 136
 form_tag() (mp.math_model_opf_dc method), 137
 form_tag() (mp.math_model_pf_acci method), 127
 form_tag() (mp.math_model_pf_accs method), 127
 form_tag() (mp.math_model_pf_acpi method), 128
 form_tag() (mp.math_model_pf_acps method), 128
 form_tag() (mp.math_model_pf_dc method), 129
 format_tag() (mp.dm_converter method), 59
 format_tag() (mp.dm_converter_mpc2 method), 61
 freq (mp.dme_line3p attribute), 187

G

g_fr (*mp.dme_branch* attribute), 46
 g_to (*mp.dme_branch* attribute), 46
 gausspf() (built-in function), 260
 gen (*mp.dme_reserve_gen* attribute), 175
 gen_cost_export() (*mp.dmce_gen_mpc2* method), 70
 gen_cost_import() (*mp.dmce_gen_mpc2* method), 70
 gencost2cost_table() (*mp.dmce_gen_mpc2* static method), 70
 genfuels() (built-in function), 332
 gentypes() (built-in function), 333
 get_export_size() (*mp.dmc_element* method), 65
 get_export_size() (*mp.dmce_load_mpc2* method), 70
 get_export_size() (*mp.dmce_reserve_gen_mpc2* method), 174
 get_export_size() (*mp.dmce_shunt_mpc2* method), 71
 get_export_spec() (*mp.dmc_element* method), 64
 get_import_size() (*mp.dmc_element* method), 65
 get_import_size() (*mp.dmce_load_mpc2* method), 70
 get_import_size() (*mp.dmce_reserve_gen_mpc2* method), 174
 get_import_size() (*mp.dmce_shunt_mpc2* method), 71
 get_import_spec() (*mp.dmc_element* method), 64
 get_input_table_values() (*mp.dmc_element* method), 66
 get_losses() (built-in function), 335
 get_mpc() (*mp.mm_shared_opf_legacy* method), 142
 get_mpc() (*opf_model* method), 219
 get_node_idx() (*mp.net_model* method), 98
 get_nv() (*mp.nm_element* method), 111
 get_params() (*mp.form* method), 73
 get_port_idx() (*mp.net_model* method), 98
 get_reorder() (built-in function), 257
 get_state_idx() (*mp.net_model* method), 98
 get_table() (*mp_table_subclass* method), 161
 get_va() (*mp.net_model_ac* method), 103
 gs (*mp.dme_shunt* attribute), 56
 gs_x_update() (*mp.math_model_pf_acps* method), 128

H

has_name() (*mp.mapped_array* method), 168
 has_pq_cap() (*mp.mme_gen_opf_ac* method), 153
 hasPQcap() (built-in function), 336
 have_cost() (*mp.dme_gen* method), 52
 have_cost() (*mp.dme_gen_opf* method), 53
 have_cost() (*mp.dme_legacy_dcline* method), 205
 have_cost() (*mp.dme_legacy_dcline_opf* method), 206
 have_feature_e4st() (built-in function), 349
 have_feature_minopf() (built-in function), 350
 have_feature_most() (built-in function), 350
 have_feature_mp_core() (built-in function), 350
 have_feature_pdipmopf() (built-in function), 350
 have_feature_regexp_split() (built-in function), 351
 have_feature_scpdipmopf() (built-in function), 351
 have_feature_sdp_pf() (built-in function), 351
 have_feature_smartmarket() (built-in function), 351
 have_feature_syngrid() (built-in function), 352
 have_feature_table() (built-in function), 352
 have_feature_tralmopf() (built-in function), 352
 horzcat() (*mp_table* method), 159

I

i (*mp.form_ac* attribute), 75
 i2e_data() (built-in function), 255
 i2e_field() (built-in function), 256
 i2on (*mp.dm_element* attribute), 37
 i_dm (*mp.task* attribute), 9
 i_mm (*mp.task* attribute), 9
 i_nm (*mp.task* attribute), 9
 ID() (*mp.dm_element* method), 41

ID2i (*mp.dm_element* attribute), 37
 idx_brch() (built-in function), 336
 idx_bus() (built-in function), 337
 idx_cost() (built-in function), 338
 idx_ct() (built-in function), 339
 idx_dcline() (built-in function), 341
 idx_gen() (built-in function), 342
 import() (*mp.dm_converter* method), 59
 import() (*mp.dm_converter_mpc2* method), 61
 import() (*mp.dmc_element* method), 65
 import() (*mp.dmce_line3p_mpc2* method), 181
 import() (*mp.dmce_reserve_gen_mpc2* method), 174
 import_col() (*mp.dmc_element* method), 66
 import_cost() (*mp.dmce_reserve_gen_mpc2* method), 174
 import_qty() (*mp.dmce_reserve_gen_mpc2* method), 174
 import_ramp() (*mp.dmce_reserve_gen_mpc2* method), 174
 import_req() (*mp.dmce_reserve_zone_mpc2* method), 175
 import_table_values() (*mp.dmc_element* method), 66
 import_zones() (*mp.dmce_reserve_zone_mpc2* method), 175
 incidence_matrix() (*mp.nm_element* method), 112
 init_export() (*mp.dm_converter* method), 60
 init_export() (*mp.dm_converter_mpc2* method), 61
 init_export_data() (*mp.dmc_element* method), 67
 init_export_data() (*mp.dmce_bus_mpc2* method), 69
 init_indexed_name() (*opf_model* method), 223
 init_set_types() (*mp.math_model_opf_acci_legacy* method), 133
 init_set_types() (*mp.math_model_opf_accs_legacy* method), 134
 init_set_types() (*mp.math_model_opf_acpi_legacy* method), 136
 init_set_types() (*mp.math_model_opf_acps_legacy* method), 137
 init_set_types() (*mp.math_model_opf_dc_legacy* method), 138
 init_set_types() (*mp.net_model* method), 94
 init_set_types() (*opf_model* method), 219
 init_set_types_legacy() (*mp.mm_shared_opf_legacy* method), 142
 init_status() (*mp.dm_element* method), 41
 init_status() (*mp.dme_bus* method), 49
 init_status() (*mp.dme_bus3p* method), 183
 initial_voltage_angle() (*mp.net_model_acc* method), 105
 initial_voltage_angle() (*mp.net_model_acp* method), 106
 initialize() (*mp.data_model* method), 29
 initialize() (*mp.dm_element* method), 40
 initialize() (*mp.dme_branch* method), 47
 initialize() (*mp.dme_buslink* method), 191
 initialize() (*mp.dme_gen* method), 52
 initialize() (*mp.dme_gen3p* method), 185
 initialize() (*mp.dme_legacy_dcline* method), 205
 initialize() (*mp.dme_line3p* method), 188
 initialize() (*mp.dme_load3p* method), 186
 initialize() (*mp.dme_xfmr3p* method), 190
 inln (*mp.form_ac* attribute), 75
 inln_hess (*mp.form_ac* attribute), 75
 int2ext() (built-in function), 254
 interior_va() (*mp.math_model_opf* method), 132
 interior_va() (*mp.math_model_opf_acc* method), 132
 interior_vm() (*mp.mme_bus_opf_ac* method), 150
 interior_x0() (*mp.math_model_opf* method), 132
 interior_x0() (*mp.mme_bus3p_opf_acc* method), 199
 interior_x0() (*mp.mme_bus3p_opf_acp* method), 199
 interior_x0() (*mp.mme_bus_opf_acc* method), 150
 interior_x0() (*mp.mme_bus_opf_acp* method), 150
 interior_x0() (*mp.mme_bus_opf_dc* method), 151
 interior_x0() (*mp.mme_buslink_opf* method), 201
 interior_x0() (*mp.mme_gen3p_opf* method), 200
 interior_x0() (*mp.mme_gen_opf* method), 152
 interior_x0() (*mp.mme_legacy_dcline_opf* method), 210
 interior_x0() (*mp.mme_line3p_opf* method), 200
 interior_x0() (*mp.mme_xfmr3p_opf* method), 200
 is_valid() (*mp.NODE_TYPE* static method), 169

isempty() (*mp.table* method), 157
 isload() (*built-in* function), 343
 isload() (*mp.dme_gen* method), 52
 istable() (*mp.table* method), 157
 iterations (*mp.task_pf* attribute), 19

K

K (*mp.form_dc* attribute), 89

L

L (*mp.form_ac* attribute), 75
 label() (*mp.dm_element* method), 38
 label() (*mp.dme_branch* method), 47
 label() (*mp.dme_bus* method), 49
 label() (*mp.dme_bus3p* method), 183
 label() (*mp.dme_buslink* method), 191
 label() (*mp.dme_gen* method), 52
 label() (*mp.dme_gen3p* method), 185
 label() (*mp.dme_legacy_dcline* method), 205
 label() (*mp.dme_line3p* method), 188
 label() (*mp.dme_load* method), 54
 label() (*mp.dme_load3p* method), 186
 label() (*mp.dme_reserve_gen* method), 176
 label() (*mp.dme_reserve_zone* method), 177
 label() (*mp.dme_shunt* method), 57
 label() (*mp.dme_xfmr3p* method), 189
 labels() (*mp.dm_element* method), 38
 labels() (*mp.dme_branch* method), 47
 labels() (*mp.dme_bus* method), 49
 labels() (*mp.dme_bus3p* method), 183
 labels() (*mp.dme_buslink* method), 191
 labels() (*mp.dme_gen* method), 52
 labels() (*mp.dme_gen3p* method), 185
 labels() (*mp.dme_legacy_dcline* method), 205
 labels() (*mp.dme_line3p* method), 188
 labels() (*mp.dme_load* method), 55
 labels() (*mp.dme_load3p* method), 186
 labels() (*mp.dme_reserve_gen* method), 176
 labels() (*mp.dme_reserve_zone* method), 177
 labels() (*mp.dme_shunt* method), 57
 labels() (*mp.dme_xfmr3p* method), 189
 lc (*mp.dme_line3p* attribute), 187
 lc_tab (*mp.dme_line3p* attribute), 188
 lc_table_var_names() (*mp.dme_line3p* method), 188
 legacy_post_run() (*mp.task_cpf_legacy* method), 24
 legacy_post_run() (*mp.task_opf_legacy* method), 26
 legacy_post_run() (*mp.task_pf_legacy* method), 23
 legacy_user_mod_inputs() (*mp.dm_converter_mpc2_legacy* method), 62
 legacy_user_nln_constraints() (*mp.dm_converter_mpc2_legacy* method), 62
 legacy_user_var_names() (*mp.math_model_opf_acci_legacy* method), 133
 legacy_user_var_names() (*mp.math_model_opf_accs_legacy* method), 134
 legacy_user_var_names() (*mp.math_model_opf_acpi_legacy* method), 136
 legacy_user_var_names() (*mp.math_model_opf_acps_legacy* method), 137
 legacy_user_var_names() (*mp.math_model_opf_dc_legacy* method), 138
 len (*mp.dme_line3p* attribute), 188
 length() (*mp.mapped_array* method), 167
 load2disp() (*built-in* function), 343
 loadcase() (*built-in* function), 238
 loadshed() (*built-in* function), 344
 loss0 (*mp.dme_legacy_dcline* attribute), 204

loss1 (*mp.dme_legacy_dcline* attribute), 204

M

M (*mp.form_ac* attribute), 75
 main_table_var_names() (*mp.dm_element* method), 39
 main_table_var_names() (*mp.dme_branch* method), 47
 main_table_var_names() (*mp.dme_branch_opf* method), 48
 main_table_var_names() (*mp.dme_bus* method), 49
 main_table_var_names() (*mp.dme_bus3p* method), 183
 main_table_var_names() (*mp.dme_bus_opf* method), 50
 main_table_var_names() (*mp.dme_buslink* method), 191
 main_table_var_names() (*mp.dme_gen* method), 52
 main_table_var_names() (*mp.dme_gen3p* method), 185
 main_table_var_names() (*mp.dme_gen_opf* method), 53
 main_table_var_names() (*mp.dme_legacy_dcline* method), 205
 main_table_var_names() (*mp.dme_legacy_dcline_opf* method), 206
 main_table_var_names() (*mp.dme_line3p* method), 188
 main_table_var_names() (*mp.dme_load* method), 55
 main_table_var_names() (*mp.dme_load3p* method), 186
 main_table_var_names() (*mp.dme_reserve_gen* method), 176
 main_table_var_names() (*mp.dme_reserve_zone* method), 177
 main_table_var_names() (*mp.dme_shunt* method), 57
 main_table_var_names() (*mp.dme_xfmr3p* method), 189
 make_vcorr() (*built-in* function), 261
 make_zpv() (*built-in* function), 261
 makeAang() (*built-in* function), 286
 makeApq() (*built-in* function), 286
 makeAvl() (*built-in* function), 287
 makeAy() (*built-in* function), 287
 makeB() (*built-in* function), 322
 makeBdc() (*built-in* function), 323
 makeJac() (*built-in* function), 323
 makeLODF() (*built-in* function), 324
 makePTDF() (*built-in* function), 324
 makeSbus() (*built-in* function), 325
 makeSdzip() (*built-in* function), 326
 makeYbus() (*built-in* function), 326
 mapped_array (*class in mp*), 166
 mapped_array() (*mp.mapped_array* method), 167
 margcost() (*built-in* function), 288
 math_model (*class in mp*), 121
 math_model_build() (*mp.task* method), 17
 math_model_class() (*mp.extension* method), 172
 math_model_class() (*mp.task* method), 16
 math_model_class_default() (*mp.task* method), 17
 math_model_class_default() (*mp.task_cpf* method), 21
 math_model_class_default() (*mp.task_opf* method), 22
 math_model_class_default() (*mp.task_opf_legacy* method), 26
 math_model_class_default() (*mp.task_pf* method), 20
 math_model_cpf_acc (*class in mp*), 129
 math_model_cpf_acc() (*mp.math_model_cpf_acc* method), 129
 math_model_cpf_acci (*class in mp*), 129
 math_model_cpf_accs (*class in mp*), 130
 math_model_cpf_acp (*class in mp*), 130
 math_model_cpf_acp() (*mp.math_model_cpf_acp* method), 130
 math_model_cpf_acpi (*class in mp*), 131
 math_model_cpf_acps (*class in mp*), 131
 math_model_create() (*mp.task* method), 17
 math_model_element() (*mp.nm_element* method), 109
 math_model_opf (*class in mp*), 131
 math_model_opf_ac (*class in mp*), 132
 math_model_opf_acc (*class in mp*), 132
 math_model_opf_acc() (*mp.math_model_opf_acc* method), 132
 math_model_opf_acci (*class in mp*), 133
 math_model_opf_acci_legacy (*class in mp*), 133
 math_model_opf_acci_legacy() (*mp.math_model_opf_acci_legacy* method), 133

`math_model_opf_accs` (class in `mp`), 134
`math_model_opf_accs_legacy` (class in `mp`), 134
`math_model_opf_accs_legacy()`
 (`mp.math_model_opf_accs_legacy` method), 134
`math_model_opf_acp` (class in `mp`), 135
`math_model_opf_acp()` (`mp.math_model_opf_acp` method), 135
`math_model_opf_acpi` (class in `mp`), 135
`math_model_opf_acpi_legacy` (class in `mp`), 135
`math_model_opf_acpi_legacy()`
 (`mp.math_model_opf_acpi_legacy` method), 135
`math_model_opf_acps` (class in `mp`), 136
`math_model_opf_acps_legacy` (class in `mp`), 136
`math_model_opf_acps_legacy()`
 (`mp.math_model_opf_acps_legacy` method), 136
`math_model_opf_dc` (class in `mp`), 137
`math_model_opf_dc()` (`mp.math_model_opf_dc` method), 137
`math_model_opf_dc_legacy` (class in `mp`), 137
`math_model_opf_dc_legacy()` (`mp.math_model_opf_dc_legacy`
 method), 137
`math_model_opt()` (`mp.task` method), 18
`math_model_opt()` (`mp.task_cpf` method), 21
`math_model_pf` (class in `mp`), 126
`math_model_pf_ac` (class in `mp`), 127
`math_model_pf_ac()` (`mp.math_model_pf_ac` method), 127
`math_model_pf_acci` (class in `mp`), 127
`math_model_pf_accs` (class in `mp`), 127
`math_model_pf_acpi` (class in `mp`), 128
`math_model_pf_acps` (class in `mp`), 128
`math_model_pf_dc` (class in `mp`), 129
`math_model_pf_dc()` (`mp.math_model_pf_dc` method), 129
`max_pwl_cost()` (`mp.cost_table` method), 163
`max_pwl_cost()` (`mp.cost_table_utils` static method), 165
`max_pwl_gencost()` (`mp.dme_gen_opf` method), 53
`message` (`mp.task` attribute), 9
`miqps_matpower()` (built-in function), 322
`mm` (`mp.task` attribute), 9
`mm_element` (class in `mp`), 143
`mm_element_classes()` (`mp.extension` method), 172
`mm_element_classes()` (`mp.xt_3p` method), 180
`mm_element_classes()` (`mp.xt_legacy_dcline` method), 203
`mm_element_classes()` (`mp.xt_reserves` method), 174
`mm_opt` (`mp.task` attribute), 9
`mm_shared_opf_legacy` (class in `mp`), 142
`mm_shared_pfcpf` (class in `mp`), 138
`mm_shared_pfcpf_ac` (class in `mp`), 138
`mm_shared_pfcpf_ac_i` (class in `mp`), 139
`mm_shared_pfcpf_acc` (class in `mp`), 139
`mm_shared_pfcpf_acci` (class in `mp`), 140
`mm_shared_pfcpf_accs` (class in `mp`), 140
`mm_shared_pfcpf_acp` (class in `mp`), 140
`mm_shared_pfcpf_acpi` (class in `mp`), 141
`mm_shared_pfcpf_acps` (class in `mp`), 141
`mm_shared_pfcpf_dc` (class in `mp`), 141
`mme_branch` (class in `mp`), 146
`mme_branch_opf` (class in `mp`), 147
`mme_branch_opf_ac` (class in `mp`), 147
`mme_branch_opf_acc` (class in `mp`), 148
`mme_branch_opf_acp` (class in `mp`), 148
`mme_branch_opf_dc` (class in `mp`), 148
`mme_branch_pf_ac` (class in `mp`), 146
`mme_branch_pf_dc` (class in `mp`), 146
`mme_bus` (class in `mp`), 149
`mme_bus3p` (class in `mp`), 196
`mme_bus3p_opf_acc` (class in `mp`), 199
`mme_bus3p_opf_acp` (class in `mp`), 199
`mme_bus_opf_ac` (class in `mp`), 150
`mme_bus_opf_acc` (class in `mp`), 150
`mme_bus_opf_acp` (class in `mp`), 150
`mme_bus_opf_dc` (class in `mp`), 151
`mme_bus_pf_ac` (class in `mp`), 149
`mme_bus_pf_dc` (class in `mp`), 149
`mme_buslink` (class in `mp`), 198
`mme_buslink_opf` (class in `mp`), 201
`mme_buslink_opf_acc` (class in `mp`), 201
`mme_buslink_opf_acp` (class in `mp`), 201
`mme_buslink_pf_ac` (class in `mp`), 198
`mme_buslink_pf_acc` (class in `mp`), 198
`mme_buslink_pf_acp` (class in `mp`), 199
`mme_gen` (class in `mp`), 151
`mme_gen3p` (class in `mp`), 197
`mme_gen3p_opf` (class in `mp`), 200
`mme_gen_opf` (class in `mp`), 152
`mme_gen_opf_ac` (class in `mp`), 153
`mme_gen_opf_dc` (class in `mp`), 153
`mme_gen_pf_ac` (class in `mp`), 151
`mme_gen_pf_dc` (class in `mp`), 152
`mme_legacy_dcline` (class in `mp`), 208
`mme_legacy_dcline_opf` (class in `mp`), 209
`mme_legacy_dcline_opf_ac` (class in `mp`), 210
`mme_legacy_dcline_opf_dc` (class in `mp`), 210
`mme_legacy_dcline_pf_ac` (class in `mp`), 209
`mme_legacy_dcline_pf_dc` (class in `mp`), 209
`mme_line3p` (class in `mp`), 197
`mme_line3p_opf` (class in `mp`), 200
`mme_load` (class in `mp`), 154
`mme_load_cpf` (class in `mp`), 155
`mme_load_pf_ac` (class in `mp`), 154
`mme_load_pf_dc` (class in `mp`), 154
`mme_reserve_gen` (class in `mp`), 177
`mme_reserve_zone` (class in `mp`), 178
`mme_shunt` (class in `mp`), 155
`mme_shunt_cpf` (class in `mp`), 156
`mme_shunt_pf_ac` (class in `mp`), 155
`mme_shunt_pf_dc` (class in `mp`), 156
`mme_xfmr3p` (class in `mp`), 197
`mme_xfmr3p_opf` (class in `mp`), 200
`modcost()` (built-in function), 344
`model_params()` (`mp.form` method), 72
`model_params()` (`mp.form_ac` method), 76
`model_params()` (`mp.form_dc` method), 89
`model_vvars()` (`mp.form` method), 72
`model_vvars()` (`mp.form_acc` method), 83
`model_vvars()` (`mp.form_acp` method), 87
`model_vvars()` (`mp.form_dc` method), 89
`model_zvars()` (`mp.form` method), 72
`model_zvars()` (`mp.form_ac` method), 76
`model_zvars()` (`mp.form_dc` method), 90
`modify_element_classes()` (`mp.element_container` method), 165
`mp_foo_table` (built-in class), 214
`mp_table` (built-in class), 156
`mp_table()` (`mp_table` method), 157
`mp_table_class()` (built-in function), 6
`mp_table_subclass` (built-in class), 160
`mpc` (`opf_model` attribute), 218
`mpoption()` (built-in function), 238
`mpoption_info_clp()` (built-in function), 353
`mpoption_info_cplex()` (built-in function), 353
`mpoption_info_fmincon()` (built-in function), 354
`mpoption_info_glpk()` (built-in function), 354
`mpoption_info_gurobi()` (built-in function), 355
`mpoption_info_intlinprog()` (built-in function), 355
`mpoption_info_ipopt()` (built-in function), 356
`mpoption_info_knitro()` (built-in function), 356
`mpoption_info_linprog()` (built-in function), 357
`mpoption_info_mips()` (built-in function), 357
`mpoption_info_mosek()` (built-in function), 358

mpoption_info_osqp() (built-in function), 358
 mppoption_info_quadprog() (built-in function), 359
 mppoption_old() (built-in function), 359
 mpver() (built-in function), 345

N

n (mp.dm_element attribute), 37
 N (mp.form_ac attribute), 75
 name (mp.task attribute), 9
 name (mp.task_pf attribute), 19
 name() (mp.dm_element method), 37
 name() (mp.dmc_element method), 63
 name() (mp.dmce_branch_mpc2 method), 69
 name() (mp.dmce_bus3p_mpc2 method), 180
 name() (mp.dmce_bus_mpc2 method), 69
 name() (mp.dmce_buslink_mpc2 method), 182
 name() (mp.dmce_gen3p_mpc2 method), 180
 name() (mp.dmce_gen_mpc2 method), 70
 name() (mp.dmce_legacy_dcline_mpc2 method), 203
 name() (mp.dmce_line3p_mpc2 method), 181
 name() (mp.dmce_load3p_mpc2 method), 181
 name() (mp.dmce_load_mpc2 method), 70
 name() (mp.dmce_reserve_gen_mpc2 method), 174
 name() (mp.dmce_reserve_zone_mpc2 method), 175
 name() (mp.dmce_shunt_mpc2 method), 71
 name() (mp.dmce_xfmr3p_mpc2 method), 182
 name() (mp.dme_branch method), 47
 name() (mp.dme_bus method), 49
 name() (mp.dme_bus3p method), 183
 name() (mp.dme_buslink method), 191
 name() (mp.dme_gen method), 52
 name() (mp.dme_gen3p method), 185
 name() (mp.dme_legacy_dcline method), 205
 name() (mp.dme_line3p method), 188
 name() (mp.dme_load method), 54
 name() (mp.dme_load3p method), 186
 name() (mp.dme_reserve_gen method), 176
 name() (mp.dme_reserve_zone method), 177
 name() (mp.dme_shunt method), 57
 name() (mp.dme_xfmr3p method), 189
 name() (mp.mm_element method), 144
 name() (mp.nme_branch method), 146
 name() (mp.nme_bus method), 149
 name() (mp.nme_bus3p method), 196
 name() (mp.nme_buslink method), 198
 name() (mp.nme_gen method), 151
 name() (mp.nme_gen3p method), 197
 name() (mp.nme_legacy_dcline method), 208
 name() (mp.nme_line3p method), 197
 name() (mp.nme_load method), 154
 name() (mp.nme_reserve_gen method), 177
 name() (mp.nme_reserve_zone method), 178
 name() (mp.nme_shunt method), 155
 name() (mp.nme_xfmr3p method), 197
 name() (mp.net_model method), 92
 name() (mp.nm_element method), 109
 name() (mp.nme_branch method), 114
 name() (mp.nme_bus method), 116
 name() (mp.nme_bus3p method), 192
 name() (mp.nme_buslink method), 196
 name() (mp.nme_gen method), 117
 name() (mp.nme_gen3p method), 194
 name() (mp.nme_legacy_dcline method), 207
 name() (mp.nme_line3p method), 195
 name() (mp.nme_load method), 118
 name() (mp.nme_load3p method), 194
 name() (mp.nme_shunt method), 120
 name() (mp.nme_xfmr3p method), 195
 name2idx() (mp.mapped_array method), 168
 net_model (class in mp), 90
 net_model_ac (class in mp), 100
 net_model_acc (class in mp), 104
 net_model_acc() (mp.net_model_acc method), 104
 net_model_acp (class in mp), 105
 net_model_acp() (mp.net_model_acp method), 105
 net_model_dc (class in mp), 106
 net_model_dc() (mp.net_model_dc method), 106
 network_model_build() (mp.task method), 15
 network_model_build() (mp.task_cpf method), 21
 network_model_build_post() (mp.task method), 16
 network_model_build_post() (mp.task_pf method), 19
 network_model_build_pre() (mp.task method), 15
 network_model_class() (mp.extension method), 171
 network_model_class() (mp.task method), 14
 network_model_class_default() (mp.task method), 15
 network_model_class_default() (mp.task_opf method), 22
 network_model_class_default() (mp.task_pf method), 19
 network_model_create() (mp.task method), 15
 network_model_element() (mp.mm_element method), 144
 network_model_update() (mp.task method), 16
 network_model_update() (mp.task_cpf method), 21
 network_model_x_soln() (mp.math_model method), 126
 network_model_x_soln() (mp.task method), 16
 network_model_x_soln() (mp.task_cpf method), 21
 network_model_x_soln() (mp.task_pf method), 19
 newtonpf() (built-in function), 261
 newtonpf_I_cart() (built-in function), 262
 newtonpf_I_hybrid() (built-in function), 263
 newtonpf_I_polar() (built-in function), 263
 newtonpf_S_cart() (built-in function), 264
 newtonpf_S_hybrid() (built-in function), 265
 next_dm() (mp.task method), 10
 next_dm() (mp.task_pf method), 19
 next_mm() (mp.task method), 10
 next_mm() (mp.task_cpf method), 21
 next_nm() (mp.task method), 10
 nk (mp.nm_element attribute), 108
 nlpopf_solver() (built-in function), 285
 nm (mp.task attribute), 9
 nm_element (class in mp), 107
 nm_element_classes() (mp.extension method), 172
 nm_element_classes() (mp.xt_3p method), 179
 nm_element_classes() (mp.xt_legacy_dcline method), 202
 nme_branch (class in mp), 114
 nme_branch_ac (class in mp), 114
 nme_branch_acc (class in mp), 115
 nme_branch_acp (class in mp), 115
 nme_branch_dc (class in mp), 115
 nme_bus (class in mp), 116
 nme_bus3p (class in mp), 192
 nme_bus3p_acc (class in mp), 193
 nme_bus3p_acp (class in mp), 193
 nme_bus_acc (class in mp), 116
 nme_bus_acp (class in mp), 116
 nme_bus_dc (class in mp), 117
 nme_buslink (class in mp), 195
 nme_buslink_acc (class in mp), 196
 nme_buslink_acp (class in mp), 196
 nme_gen (class in mp), 117
 nme_gen3p (class in mp), 193
 nme_gen3p_acc (class in mp), 194
 nme_gen3p_acp (class in mp), 194
 nme_gen_ac (class in mp), 117
 nme_gen_acc (class in mp), 118
 nme_gen_acp (class in mp), 118

nme_gen_dc (class in *mp*), 118
nme_legacy_dcline (class in *mp*), 207
nme_legacy_dcline_ac (class in *mp*), 207
nme_legacy_dcline_acc (class in *mp*), 208
nme_legacy_dcline_acp (class in *mp*), 208
nme_legacy_dcline_dc (class in *mp*), 208
nme_line3p (class in *mp*), 195
nme_load (class in *mp*), 118
nme_load3p (class in *mp*), 194
nme_load_ac (class in *mp*), 119
nme_load_acc (class in *mp*), 119
nme_load_acp (class in *mp*), 119
nme_load_dc (class in *mp*), 119
nme_shunt (class in *mp*), 120
nme_shunt_ac (class in *mp*), 120
nme_shunt_acc (class in *mp*), 120
nme_shunt_acp (class in *mp*), 120
nme_shunt_dc (class in *mp*), 121
nme_xfmr3p (class in *mp*), 195
nn() (*mp.nm_element* method), 109
nn() (*mp.nme_bus* method), 116
nn() (*mp.nme_bus3p* method), 193
nodal_complex_current_balance() (*mp.net_model_ac* method), 102
nodal_complex_current_balance_hess() (*mp.net_model_ac* method), 103
nodal_complex_power_balance() (*mp.net_model_ac* method), 102
nodal_complex_power_balance_hess() (*mp.net_model_ac* method), 103
nodal_current_balance_fcn() (*mp.math_model_opf_ac* method), 132
nodal_current_balance_hess() (*mp.math_model_opf_ac* method), 132
nodal_power_balance_fcn() (*mp.math_model_opf_ac* method), 132
nodal_power_balance_hess() (*mp.math_model_opf_ac* method), 132
node (*mp.net_model* attribute), 92
node_balance_equations() (*mp.mm_shared_pfcpgf_acci* method), 140
node_balance_equations() (*mp.mm_shared_pfcpgf_accs* method), 140
node_balance_equations() (*mp.mm_shared_pfcpgf_acpi* method), 141
node_balance_equations() (*mp.mm_shared_pfcpgf_acps* method), 141
node_indices() (*mp.nm_element* method), 112
node_power_balance_prices() (*mp.math_model_opf_acci* method), 133
node_power_balance_prices() (*mp.math_model_opf_accs* method), 134
node_power_balance_prices() (*mp.math_model_opf_acpi* method), 135
node_power_balance_prices() (*mp.math_model_opf_acps* method), 136
NODE_TYPE (class in *mp*), 169
node_types() (*mp.net_model* method), 98
node_types() (*mp.nm_element* method), 113
node_types() (*mp.nme_bus* method), 116
node_types() (*mp.nme_bus3p* method), 193
NONE (*mp.NODE_TYPE* attribute), 169
np() (*mp.net_model* method), 92
np() (*mp.nm_element* method), 109
np() (*mp.nme_branch* method), 114
np() (*mp.nme_buslink* method), 196
np() (*mp.nme_gen* method), 117
np() (*mp.nme_gen3p* method), 194
np() (*mp.nme_legacy_dcline* method), 207

np() (*mp.nme_line3p* method), 195
np() (*mp.nme_load* method), 118
np() (*mp.nme_load3p* method), 194
np() (*mp.nme_shunt* method), 120
np() (*mp.nme_xfmr3p* method), 195
nr (*mp.dm_element* attribute), 37
nv (*mp.net_model* attribute), 92
nz() (*mp.net_model* method), 92
nz() (*mp.nm_element* method), 109
nz() (*mp.nme_buslink* method), 196
nz() (*mp.nme_gen* method), 117
nz() (*mp.nme_gen3p* method), 194
nz() (*mp.nme_legacy_dcline* method), 207

O

off (*mp.dm_element* attribute), 37
on (*mp.dm_element* attribute), 37
online() (*mp.data_model* method), 30
opf() (built-in function), 280
opf_args() (built-in function), 288
opf_branch_ang_fcn() (built-in function), 290
opf_branch_ang_hess() (built-in function), 291
opf_branch_flow_fcn() (built-in function), 291
opf_branch_flow_hess() (built-in function), 292
opf_current_balance_fcn() (built-in function), 293
opf_current_balance_hess() (built-in function), 293
opf_execute() (built-in function), 290
opf_gen_cost_fcn() (built-in function), 294
opf_legacy_user_cost_fcn() (built-in function), 294
opf_model (built-in class), 217
opf_model() (*opf_model* method), 218
opf_nle_fcn1() (built-in function), 378
opf_nle_hess1() (built-in function), 379
opf_power_balance_fcn() (built-in function), 295
opf_power_balance_hess() (built-in function), 295
opf_setup() (built-in function), 289
opf_veq_fcn() (built-in function), 296
opf_veq_hess() (built-in function), 296
opf_vlim_fcn() (built-in function), 297
opf_vlim_hess() (built-in function), 298
opf_vref_fcn() (built-in function), 298
opf_vref_hess() (built-in function), 299
order_radial() (built-in function), 265

P

p (*mp.form_dc* attribute), 89
p_fr_lb (*mp.dme_legacy_dcline* attribute), 205
p_fr_start (*mp.dme_legacy_dcline* attribute), 204
p_fr_ub (*mp.dme_legacy_dcline* attribute), 205
p_to_start (*mp.dme_legacy_dcline* attribute), 204
param_ncols (*mp.form_ac* attribute), 75
param_ncols (*mp.form_dc* attribute), 89
parameterized() (*mp.dme_load_cpf* method), 55
parameterized() (*mp.dme_shunt_cpf* method), 56
params_legacy_cost() (*mp.mm_shared_opf_legacy* method), 143
params_legacy_cost() (*opf_model* method), 219
params_var() (*mp.net_model* method), 97
pd (*mp.dme_load* attribute), 54
pd1 (*mp.dme_load3p* attribute), 186
pd2 (*mp.dme_load3p* attribute), 186
pd3 (*mp.dme_load3p* attribute), 186
pd_i (*mp.dme_load* attribute), 54
pd_z (*mp.dme_load* attribute), 54
pf1 (*mp.dme_load3p* attribute), 186
pf2 (*mp.dme_load3p* attribute), 186
pf3 (*mp.dme_load3p* attribute), 186
pf_va_fcn() (*mp.mme_buslink_pf_acc* method), 199

pf_vm_fcn() (*mp.mme_buslink_pf_acc* method), 199
 pfsoln() (*built-in* function), 266
 pg1_start (*mp.dme_buslink* attribute), 190
 pg1_start (*mp.dme_gen3p* attribute), 184
 pg2_start (*mp.dme_buslink* attribute), 190
 pg2_start (*mp.dme_gen3p* attribute), 184
 pg3_start (*mp.dme_buslink* attribute), 190
 pg3_start (*mp.dme_gen3p* attribute), 184
 pg_lb (*mp.dme_gen* attribute), 52
 pg_start (*mp.dme_gen* attribute), 51
 pg_ub (*mp.dme_gen* attribute), 52
 poly2pwl() (*built-in* function), 345
 poly_cost_fcn() (*mp.cost_table* static method), 163
 poly_params() (*mp.cost_table* method), 162
 poly_params() (*mp.cost_table_utils* static method), 164
 polycost() (*built-in* function), 345
 port (*mp.net_model* attribute), 92
 port_active_power2_lim_fcn() (*mp.form_ac* method), 79
 port_active_power2_lim_hess() (*mp.form_ac* method), 81
 port_active_power_lim_fcn() (*mp.form_ac* method), 79
 port_active_power_lim_hess() (*mp.form_ac* method), 81
 port_apparent_power_lim_fcn() (*mp.form_ac* method), 79
 port_apparent_power_lim_hess() (*mp.form_ac* method), 80
 port_current_lim_fcn() (*mp.form_ac* method), 80
 port_current_lim_hess() (*mp.form_ac* method), 81
 port_inj_current() (*mp.form_ac* method), 76
 port_inj_current_hess() (*mp.form_ac* method), 77
 port_inj_current_hess_v() (*mp.form_ac* method), 78
 port_inj_current_hess_v() (*mp.form_acc* method), 83
 port_inj_current_hess_v() (*mp.form_acp* method), 87
 port_inj_current_hess_vz() (*mp.form_ac* method), 78
 port_inj_current_hess_vz() (*mp.form_acc* method), 83
 port_inj_current_hess_vz() (*mp.form_acp* method), 87
 port_inj_current_jac() (*mp.form_ac* method), 78
 port_inj_current_jac() (*mp.form_acc* method), 83
 port_inj_current_jac() (*mp.form_acp* method), 87
 port_inj_current_nln() (*mp.nme_load_ac* method), 119
 port_inj_nln() (*mp.net_model_ac* method), 101
 port_inj_nln_hess() (*mp.net_model_ac* method), 102
 port_inj_power() (*mp.form_ac* method), 76
 port_inj_power() (*mp.form_dc* method), 90
 port_inj_power_hess() (*mp.form_ac* method), 78
 port_inj_power_hess_v() (*mp.form_ac* method), 78
 port_inj_power_hess_v() (*mp.form_acc* method), 84
 port_inj_power_hess_v() (*mp.form_acp* method), 87
 port_inj_power_hess_vz() (*mp.form_ac* method), 79
 port_inj_power_hess_vz() (*mp.form_acc* method), 84
 port_inj_power_hess_vz() (*mp.form_acp* method), 88
 port_inj_power_jac() (*mp.form_ac* method), 78
 port_inj_power_jac() (*mp.form_acc* method), 84
 port_inj_power_jac() (*mp.form_acp* method), 87
 port_inj_power_nln() (*mp.nme_load_ac* method), 119
 port_inj_soln() (*mp.net_model_dc* method), 103
 port_inj_soln() (*mp.net_model_dc* method), 107
 pp_binding_rows_lim() (*mp.dme_branch_opf* method), 48
 pp_binding_rows_lim() (*mp.dme_bus_opf* method), 51
 pp_binding_rows_lim() (*mp.dme_gen_opf* method), 53
 pp_binding_rows_lim() (*mp.dme_legacy_dcline_opf* method), 206
 pp_binding_rows_lim() (*mp.dme_reserve_gen* method), 176
 pp_binding_rows_lim() (*mp.dme_shared_opf* method), 58
 pp_data() (*mp.data_model* method), 33
 pp_data() (*mp.dm_element* method), 43
 pp_data_cnt() (*mp.dm_element* method), 44
 pp_data_cnt() (*mp.dme_branch* method), 47
 pp_data_cnt() (*mp.dme_bus* method), 50
 pp_data_det() (*mp.dm_element* method), 45
 pp_data_ext() (*mp.dm_element* method), 44
 pp_data_ext() (*mp.dme_bus* method), 50
 pp_data_ext() (*mp.dme_bus_opf* method), 50
 pp_data_lim() (*mp.dme_shared_opf* method), 58
 pp_data_other() (*mp.dme_shared_opf* method), 58
 pp_data_row_det() (*mp.dm_element* method), 45
 pp_data_row_det() (*mp.dme_branch* method), 47
 pp_data_row_det() (*mp.dme_bus* method), 50
 pp_data_row_det() (*mp.dme_bus3p* method), 183
 pp_data_row_det() (*mp.dme_bus_opf* method), 51
 pp_data_row_det() (*mp.dme_buslink* method), 191
 pp_data_row_det() (*mp.dme_gen* method), 52
 pp_data_row_det() (*mp.dme_gen3p* method), 185
 pp_data_row_det() (*mp.dme_legacy_dcline* method), 206
 pp_data_row_det() (*mp.dme_line3p* method), 188
 pp_data_row_det() (*mp.dme_load* method), 55
 pp_data_row_det() (*mp.dme_load3p* method), 186
 pp_data_row_det() (*mp.dme_reserve_gen* method), 176
 pp_data_row_det() (*mp.dme_reserve_zone* method), 177
 pp_data_row_det() (*mp.dme_shunt* method), 57
 pp_data_row_det() (*mp.dme_xfmr3p* method), 190
 pp_data_row_lim() (*mp.dme_branch_opf* method), 48
 pp_data_row_lim() (*mp.dme_bus_opf* method), 51
 pp_data_row_lim() (*mp.dme_gen_opf* method), 53
 pp_data_row_lim() (*mp.dme_legacy_dcline_opf* method), 207
 pp_data_row_lim() (*mp.dme_reserve_gen* method), 176
 pp_data_row_lim() (*mp.dme_shared_opf* method), 58
 pp_data_sum() (*mp.dm_element* method), 44
 pp_data_sum() (*mp.dme_branch* method), 47
 pp_data_sum() (*mp.dme_gen* method), 52
 pp_data_sum() (*mp.dme_gen3p* method), 185
 pp_data_sum() (*mp.dme_legacy_dcline* method), 205
 pp_data_sum() (*mp.dme_line3p* method), 188
 pp_data_sum() (*mp.dme_load* method), 55
 pp_data_sum() (*mp.dme_load3p* method), 186
 pp_data_sum() (*mp.dme_reserve_gen* method), 176
 pp_data_sum() (*mp.dme_shunt* method), 57
 pp_data_sum() (*mp.dme_xfmr3p* method), 190
 pp_flags() (*mp.data_model* method), 31
 pp_flags() (*mp.data_model_opf* method), 35
 pp_get_footers() (*mp.dm_element* method), 43
 pp_get_footers_det() (*mp.dm_element* method), 45
 pp_get_footers_det() (*mp.dme_gen* method), 52
 pp_get_footers_det() (*mp.dme_load* method), 55
 pp_get_footers_det() (*mp.dme_reserve_gen* method), 176
 pp_get_footers_det() (*mp.dme_shunt* method), 57
 pp_get_footers_lim() (*mp.dme_shared_opf* method), 58
 pp_get_footers_other() (*mp.dme_shared_opf* method), 58
 pp_get_headers() (*mp.data_model* method), 32
 pp_get_headers() (*mp.dm_element* method), 43
 pp_get_headers_cnt() (*mp.data_model* method), 32
 pp_get_headers_det() (*mp.dm_element* method), 45
 pp_get_headers_det() (*mp.dme_branch* method), 47
 pp_get_headers_det() (*mp.dme_bus* method), 50
 pp_get_headers_det() (*mp.dme_bus3p* method), 183
 pp_get_headers_det() (*mp.dme_bus_opf* method), 51
 pp_get_headers_det() (*mp.dme_buslink* method), 191
 pp_get_headers_det() (*mp.dme_gen* method), 52
 pp_get_headers_det() (*mp.dme_gen3p* method), 185
 pp_get_headers_det() (*mp.dme_legacy_dcline* method), 206
 pp_get_headers_det() (*mp.dme_line3p* method), 188
 pp_get_headers_det() (*mp.dme_load* method), 55
 pp_get_headers_det() (*mp.dme_load3p* method), 186
 pp_get_headers_det() (*mp.dme_reserve_gen* method), 176
 pp_get_headers_det() (*mp.dme_reserve_zone* method), 177
 pp_get_headers_det() (*mp.dme_shunt* method), 57
 pp_get_headers_det() (*mp.dme_xfmr3p* method), 190
 pp_get_headers_ext() (*mp.data_model* method), 33
 pp_get_headers_lim() (*mp.dme_branch_opf* method), 48
 pp_get_headers_lim() (*mp.dme_bus_opf* method), 51

pp_get_headers_lim() (mp.dme_gen_opf method), 53
 pp_get_headers_lim() (mp.dme_legacy_dcline_opf method), 206
 pp_get_headers_lim() (mp.dme_reserve_gen method), 176
 pp_get_headers_lim() (mp.dme_shared_opf method), 58
 pp_get_headers_other() (mp.data_model method), 33
 pp_get_headers_other() (mp.dme_shared_opf method), 58
 pp_get_title_det() (mp.dm_element method), 44
 pp_get_title_lim() (mp.dme_branch_opf method), 48
 pp_get_title_lim() (mp.dme_shared_opf method), 58
 pp_have_section() (mp.data_model method), 32
 pp_have_section() (mp.dm_element method), 42
 pp_have_section_cnt() (mp.dm_element method), 43
 pp_have_section_det() (mp.dm_element method), 44
 pp_have_section_det() (mp.dme_branch method), 47
 pp_have_section_det() (mp.dme_bus method), 50
 pp_have_section_det() (mp.dme_bus3p method), 183
 pp_have_section_det() (mp.dme_buslink method), 191
 pp_have_section_det() (mp.dme_gen method), 52
 pp_have_section_det() (mp.dme_gen3p method), 185
 pp_have_section_det() (mp.dme_legacy_dcline method), 206
 pp_have_section_det() (mp.dme_line3p method), 188
 pp_have_section_det() (mp.dme_load method), 55
 pp_have_section_det() (mp.dme_load3p method), 186
 pp_have_section_det() (mp.dme_reserve_gen method), 176
 pp_have_section_det() (mp.dme_reserve_zone method), 177
 pp_have_section_det() (mp.dme_shunt method), 57
 pp_have_section_det() (mp.dme_xfmr3p method), 190
 pp_have_section_ext() (mp.dm_element method), 44
 pp_have_section_ext() (mp.dme_bus method), 50
 pp_have_section_lim() (mp.dme_branch_opf method), 48
 pp_have_section_lim() (mp.dme_bus_opf method), 51
 pp_have_section_lim() (mp.dme_gen_opf method), 53
 pp_have_section_lim() (mp.dme_legacy_dcline_opf method), 206
 pp_have_section_lim() (mp.dme_reserve_gen method), 176
 pp_have_section_lim() (mp.dme_shared_opf method), 58
 pp_have_section_other() (mp.dme_shared_opf method), 58
 pp_have_section_sum() (mp.dm_element method), 44
 pp_have_section_sum() (mp.dme_branch method), 47
 pp_have_section_sum() (mp.dme_gen method), 52
 pp_have_section_sum() (mp.dme_gen3p method), 185
 pp_have_section_sum() (mp.dme_legacy_dcline method), 205
 pp_have_section_sum() (mp.dme_line3p method), 188
 pp_have_section_sum() (mp.dme_load method), 55
 pp_have_section_sum() (mp.dme_load3p method), 186
 pp_have_section_sum() (mp.dme_reserve_gen method), 176
 pp_have_section_sum() (mp.dme_shunt method), 57
 pp_have_section_sum() (mp.dme_xfmr3p method), 190
 pp_rows() (mp.dm_element method), 43
 pp_rows_lim() (mp.dme_shared_opf method), 58
 pp_rows_other() (mp.dme_shared_opf method), 58
 pp_section() (mp.data_model method), 32
 pp_section_label() (mp.data_model method), 31
 pp_section_list() (mp.data_model method), 31
 pp_section_list() (mp.data_model_opf method), 35
 pp_set_tols_lim() (mp.dme_shared_opf method), 58
 PQ (mp.NODE_TYPE attribute), 169
 pq_capability_constraint() (mp.mme_gen_opf_ac method), 153
 pqcost() (built-in function), 346
 pretty_print() (mp.data_model method), 30
 pretty_print() (mp.dm_element method), 42
 pretty_print() (mp.dme_branch_opf method), 48
 pretty_print() (mp.dme_gen_opf method), 53
 pretty_print() (mp.dme_legacy_dcline_opf method), 206
 pretty_print() (mp.dme_line3p method), 188
 pretty_print() (mp.dme_xfmr3p method), 190
 print_soln() (mp.task method), 11
 print_soln_header() (mp.task method), 11
 print_soln_header() (mp.task_opf method), 22
 printf() (built-in function), 248
 psse2mpc() (built-in function), 248
 psse_convert() (built-in function), 364
 psse_convert_hvdc() (built-in function), 364
 psse_convert_xfmr() (built-in function), 365
 psse_parse() (built-in function), 366
 psse_parse_line() (built-in function), 367
 psse_parse_section() (built-in function), 367
 psse_read() (built-in function), 369
 ptol (mp.dme_shared_opf attribute), 58
 PV (mp.NODE_TYPE attribute), 169
 pw11 (mp.dme_gen_mpc2 attribute), 69
 pwl_params() (mp.cost_table method), 163
 pwl_params() (mp.cost_table_utils static method), 165

Q

q_fr_lb (mp.dme_legacy_dcline attribute), 205
 q_fr_start (mp.dme_legacy_dcline attribute), 204
 q_fr_ub (mp.dme_legacy_dcline attribute), 205
 q_to_lb (mp.dme_legacy_dcline attribute), 205
 q_to_start (mp.dme_legacy_dcline attribute), 205
 q_to_ub (mp.dme_legacy_dcline attribute), 205
 qd (mp.dme_load attribute), 54
 qd_i (mp.dme_load attribute), 54
 qd_z (mp.dme_load attribute), 54
 qq1_start (mp.dme_buslink attribute), 190
 qq1_start (mp.dme_gen3p attribute), 184
 qq2_start (mp.dme_buslink attribute), 190
 qq2_start (mp.dme_gen3p attribute), 184
 qq3_start (mp.dme_buslink attribute), 191
 qq3_start (mp.dme_gen3p attribute), 184
 qq_lb (mp.dme_gen attribute), 52
 qq_start (mp.dme_gen attribute), 51
 qq_ub (mp.dme_gen attribute), 52
 qps_matpower() (built-in function), 322

R

r (mp.dme_branch attribute), 46
 r (mp.dme_xfmr3p attribute), 189
 r_ub (mp.dme_reserve_gen attribute), 175
 radial_pf() (built-in function), 266
 rate_a (mp.dme_branch attribute), 47
 rebuild() (mp.dm_element method), 42
 REF (mp.NODE_TYPE attribute), 169
 ref (mp.task_pf attribute), 19
 ref0 (mp.task_pf attribute), 19
 remove_userfcn() (built-in function), 302
 req (mp.dme_reserve_zone attribute), 177
 run() (mp.task method), 9
 run_cpf() (built-in function), 5
 run_mp() (built-in function), 3
 run_opf() (built-in function), 5
 run_pf() (built-in function), 4
 run_post() (mp.task method), 11
 run_post() (mp.task_cpf_legacy method), 24
 run_post() (mp.task_opf_legacy method), 25
 run_post() (mp.task_pf_legacy method), 23
 run_pre() (mp.task method), 11
 run_pre() (mp.task_cpf method), 21
 run_pre() (mp.task_cpf_legacy method), 24
 run_pre() (mp.task_opf method), 22
 run_pre() (mp.task_opf_legacy method), 25
 run_pre() (mp.task_pf method), 19
 run_pre() (mp.task_pf_legacy method), 23
 run_pre_legacy() (mp.task_shared_legacy method), 27
 run_userfcn() (built-in function), 302

runcpf() (built-in function), 225
 rundcopf() (built-in function), 231
 rundcpf() (built-in function), 230
 runduopf() (built-in function), 232
 runopf() (built-in function), 228
 runopf_w_res() (built-in function), 233
 runpf() (built-in function), 224
 runuopf() (built-in function), 229

S

s (mp.form_ac attribute), 75
 save() (mp.dm_converter method), 60
 save() (mp.dm_converter_mpc2 method), 61
 save2psse() (built-in function), 249
 save_soln() (mp.task method), 12
 savecase() (built-in function), 250
 savechgtab() (built-in function), 250
 scale_factor_fcn() (mp.dmce_load_mpc2 method), 70
 scale_load() (built-in function), 346
 set_bus_type_pq() (mp.dme_bus method), 50
 set_bus_type_pv() (mp.dme_bus method), 50
 set_bus_type_ref() (mp.dme_bus method), 50
 set_bus_v_lims_via_vg() (mp.data_model method), 33
 set_mpc() (opf_model method), 219
 set_node_type_pq() (mp.net_model method), 100
 set_node_type_pq() (mp.nm_element method), 114
 set_node_type_pq() (mp.nme_bus method), 116
 set_node_type_pv() (mp.net_model method), 100
 set_node_type_pv() (mp.nm_element method), 113
 set_node_type_pv() (mp.nme_bus method), 116
 set_node_type_ref() (mp.net_model method), 99
 set_node_type_ref() (mp.nm_element method), 113
 set_node_type_ref() (mp.nme_bus method), 116
 set_reorder() (built-in function), 257
 set_table() (mp_table_subclass method), 161
 set_type_idx_map() (mp.net_model method), 95
 set_type_label() (mp.net_model method), 96
 size() (mp.mapped_array method), 167
 size() (mp_table method), 157
 snln (mp.form_ac attribute), 75
 snln_hess (mp.form_ac attribute), 75
 soln (mp.nm_element attribute), 109
 solve_opts() (mp.math_model method), 125
 solve_opts() (mp.math_model_opf_ac method), 132
 solve_opts() (mp.math_model_opf_dc method), 137
 solve_opts() (mp.math_model_pf method), 126
 solve_opts() (mp.math_model_pf_dc method), 129
 solve_opts_warmstart() (mp.math_model_cpf_acps method), 131
 source (mp.data_model attribute), 28
 stack_matrix_params() (mp.net_model method), 93
 stack_vector_params() (mp.net_model method), 93
 start_cost_export() (mp.dmce_gen_mpc2 method), 70
 start_cost_import() (mp.dmce_gen_mpc2 method), 70
 state (mp.net_model attribute), 92
 subsasgn() (mp.mapped_array method), 169
 subsasgn() (mp_table method), 158
 subsref() (mp.mapped_array method), 168
 subsref() (mp_table method), 158
 success (mp.task attribute), 9
 symmat2vec() (mp.dme_line3p method), 188
 sys_wide_zip_loads() (mp.dmce_load_mpc2 method), 70

T

t_apply_changes() (built-in function), 369
 t_auction_case() (built-in function), 379
 t_auction_minopf() (built-in function), 370
 t_auction_mips() (built-in function), 370

t_auction_tspopf_pdipm() (built-in function), 370
 t_case30_userfcns() (built-in function), 379
 t_case3p_a() (built-in function), 215
 t_case3p_b() (built-in function), 215
 t_case3p_c() (built-in function), 215
 t_case3p_d() (built-in function), 215
 t_case3p_e() (built-in function), 215
 t_case3p_f() (built-in function), 216
 t_case3p_g() (built-in function), 216
 t_case3p_h() (built-in function), 216
 t_case9_dcline() (built-in function), 379
 t_case9_gizmo() (built-in function), 216
 t_case9_opf() (built-in function), 379
 t_case9_opfv2() (built-in function), 380
 t_case9_pf() (built-in function), 380
 t_case9_pfv2() (built-in function), 380
 t_case9_save2psse() (built-in function), 380
 t_case_ext() (built-in function), 380
 t_case_int() (built-in function), 380
 t_chgtab() (built-in function), 370
 t_cpf() (built-in function), 370
 t_cpf_cb1() (built-in function), 381
 t_cpf_cb2() (built-in function), 381
 t_dcline() (built-in function), 370
 t_dmc_element() (built-in function), 212
 t_ext2int2ext() (built-in function), 370
 t_feval_w_path() (built-in function), 371
 t_get_losses() (built-in function), 371
 t_hasPQcap() (built-in function), 371
 t_hessian() (built-in function), 371
 t_islands() (built-in function), 371
 t_jacobian() (built-in function), 371
 t_load2disp() (built-in function), 372
 t_loadcase() (built-in function), 372
 t_makeLODF() (built-in function), 372
 t_makePTDF() (built-in function), 372
 t_margcost() (built-in function), 372
 t_miqps_matpower() (built-in function), 372
 t_modcost() (built-in function), 372
 t_mp_data_model() (built-in function), 212
 t_mp_dm_converter_mpc2() (built-in function), 212
 t_mp_mapped_array() (built-in function), 211
 t_mp_table() (built-in function), 212
 t_mpopoption() (built-in function), 373
 t_mpopoption_ov() (built-in function), 373
 t_mpxt_legacy_dcline() (built-in function), 214
 t_mpxt_reserves() (built-in function), 214
 t_nm_element() (built-in function), 212
 t_node_test() (built-in function), 213
 t_off2case() (built-in function), 373
 t_opf_dc_bmpdpd() (built-in function), 373
 t_opf_dc_clp() (built-in function), 373
 t_opf_dc_cplex() (built-in function), 373
 t_opf_dc_default() (built-in function), 373
 t_opf_dc_glpk() (built-in function), 374
 t_opf_dc_gurobi() (built-in function), 374
 t_opf_dc_ipopt() (built-in function), 374
 t_opf_dc_mips() (built-in function), 374
 t_opf_dc_mips_sc() (built-in function), 374
 t_opf_dc_mosek() (built-in function), 374
 t_opf_dc_osqp() (built-in function), 374
 t_opf_dc_ot() (built-in function), 375
 t_opf_default() (built-in function), 375
 t_opf_fmincon() (built-in function), 375
 t_opf_ipopt() (built-in function), 375
 t_opf_knitro() (built-in function), 375
 t_opf_minopf() (built-in function), 375
 t_opf_mips() (built-in function), 375

t_opf_model() (built-in function), 376
 t_opf_softlims() (built-in function), 376
 t_opf_tspopf_pdipm() (built-in function), 376
 t_opf_tspopf_scpdipm() (built-in function), 376
 t_opf_tspopf_tralm() (built-in function), 376
 t_opf_userfcns() (built-in function), 376
 t_pf_ac() (built-in function), 377
 t_pf_dc() (built-in function), 377
 t_pf_radial() (built-in function), 377
 t_port_inj_current_acc() (built-in function), 212
 t_port_inj_current_acp() (built-in function), 213
 t_port_inj_power_acc() (built-in function), 213
 t_port_inj_power_acp() (built-in function), 213
 t_pretty_print() (built-in function), 214
 t_printf() (built-in function), 377
 t_psse() (built-in function), 377
 t_qps_matpower() (built-in function), 377
 t_run_mp() (built-in function), 213
 t_run_mp_3p() (built-in function), 213
 t_run_opf_default() (built-in function), 214
 t_runmarket() (built-in function), 377
 t_runopf_w_res() (built-in function), 378
 t_scale_load() (built-in function), 378
 t_total_load() (built-in function), 378
 t_totcost() (built-in function), 378
 t_vdep_load() (built-in function), 378
 ta (mp.dme_branch attribute), 47
 tab (mp.dm_element attribute), 37
 table_exists() (mp.dm_element method), 39
 table_var_map() (mp.dmc_element method), 65
 table_var_map() (mp.dmce_branch_mpc2 method), 69
 table_var_map() (mp.dmce_bus3p_mpc2 method), 180
 table_var_map() (mp.dmce_bus_mpc2 method), 69
 table_var_map() (mp.dmce_buslink_mpc2 method), 182
 table_var_map() (mp.dmce_gen3p_mpc2 method), 180
 table_var_map() (mp.dmce_gen_mpc2 method), 70
 table_var_map() (mp.dmce_legacy_dcline_mpc2 method), 203
 table_var_map() (mp.dmce_line3p_mpc2 method), 181
 table_var_map() (mp.dmce_load3p_mpc2 method), 181
 table_var_map() (mp.dmce_load_mpc2 method), 70
 table_var_map() (mp.dmce_reserve_gen_mpc2 method), 174
 table_var_map() (mp.dmce_reserve_zone_mpc2 method), 175
 table_var_map() (mp.dmce_shunt_mpc2 method), 71
 table_var_map() (mp.dmce_xfmr3p_mpc2 method), 182
 tag (mp.task attribute), 9
 tag (mp.task_pf attribute), 19
 task (class in mp), 7
 task_class() (mp.extension method), 171
 task_cpf (class in mp), 20
 task_cpf() (mp.task_cpf method), 20
 task_cpf_legacy (class in mp), 24
 task_name() (mp.math_model method), 122
 task_name() (mp.math_model_opf method), 131
 task_name() (mp.math_model_pf method), 126
 task_opf (class in mp), 21
 task_opf_legacy (class in mp), 25
 task_pf (class in mp), 18
 task_pf_legacy (class in mp), 22
 task_shared_legacy (class in mp), 26
 task_tag() (mp.math_model method), 122
 task_tag() (mp.math_model_opf method), 131
 task_tag() (mp.math_model_pf method), 126
 tbus (mp.dme_branch attribute), 46
 tbus (mp.dme_legacy_dcline attribute), 204
 tbus (mp.dme_line3p attribute), 187
 tbus (mp.dme_xfmr3p attribute), 189
 tbus_on (mp.dme_legacy_dcline attribute), 204
 test_matpower() (built-in function), 211

the_np (mp.net_model attribute), 92
 the_nz (mp.net_model attribute), 92
 tm (mp.dme_branch attribute), 47
 toggle_dcline() (built-in function), 302
 toggle_iflims() (built-in function), 303
 toggle_reserves() (built-in function), 304
 toggle_softlims() (built-in function), 305
 total_load() (built-in function), 348
 totcost() (built-in function), 299
 type (mp.dme_bus attribute), 49
 type (mp.dme_bus3p attribute), 183

U

uopf() (built-in function), 283
 update_mupq() (built-in function), 299
 update_nm_vars() (mp.math_model method), 125
 update_status() (mp.data_model method), 29
 update_status() (mp.dm_element method), 41
 update_status() (mp.dme_branch method), 47
 update_status() (mp.dme_bus method), 49
 update_status() (mp.dme_bus3p method), 183
 update_status() (mp.dme_buslink method), 191
 update_status() (mp.dme_gen method), 52
 update_status() (mp.dme_gen3p method), 185
 update_status() (mp.dme_legacy_dcline method), 205
 update_status() (mp.dme_line3p method), 188
 update_status() (mp.dme_load method), 55
 update_status() (mp.dme_load3p method), 186
 update_status() (mp.dme_reserve_gen method), 176
 update_status() (mp.dme_reserve_zone method), 177
 update_status() (mp.dme_shunt method), 57
 update_status() (mp.dme_xfmr3p method), 190
 update_z() (mp.mm_shared_pfcpf_ac method), 138
 update_z() (mp.mm_shared_pfcpf_dc method), 142
 userdata (mp.data_model attribute), 28

V

va (mp.net_model_dc attribute), 107
 va1_start (mp.dme_bus3p attribute), 183
 va2_start (mp.dme_bus3p attribute), 183
 va3_start (mp.dme_bus3p attribute), 183
 va_fcn() (mp.form_acc method), 84
 va_fcn() (mp.mme_buslink_opf_acc method), 201
 va_hess() (mp.form_acc method), 85
 va_hess() (mp.mme_buslink_opf_acc method), 201
 va_ref0 (mp.task_pf attribute), 19
 va_start (mp.dme_bus attribute), 49
 vec2symmat() (mp.dme_line3p method), 188
 vec2symmat_stacked() (mp.mme_line3p method), 195
 vertcat() (mp_table method), 159
 violated_q_lims() (mp.dme_gen method), 52
 vm1_setpoint (mp.dme_gen3p attribute), 184
 vm1_start (mp.dme_bus3p attribute), 183
 vm2_fcn() (mp.form_acc method), 85
 vm2_fcn() (mp.mme_buslink_opf_acc method), 201
 vm2_hess() (mp.form_acc method), 85
 vm2_hess() (mp.mme_buslink_opf_acc method), 201
 vm2_setpoint (mp.dme_gen3p attribute), 184
 vm2_start (mp.dme_bus3p attribute), 183
 vm3_setpoint (mp.dme_gen3p attribute), 185
 vm3_start (mp.dme_bus3p attribute), 183
 vm_control (mp.dme_bus attribute), 49
 vm_control (mp.dme_bus3p attribute), 183
 vm_lb (mp.dme_bus attribute), 49
 vm_setpoint (mp.dme_gen attribute), 52
 vm_setpoint_fr (mp.dme_legacy_dcline attribute), 205
 vm_setpoint_to (mp.dme_legacy_dcline attribute), 205

`vm_start` (*mp.dme_bus* attribute), [49](#)
`vm_ub` (*mp.dme_bus* attribute), [49](#)
`voltage_constraints()` (*mp.mme_buslink_pf_ac* method), [198](#)
`voltage_constraints()` (*mp.nme_buslink* method), [196](#)

W

`warmstart` (*mp.task_cpf* attribute), [20](#)

X

`x` (*mp.dme_branch* attribute), [46](#)
`x` (*mp.dme_xfmr3p* attribute), [189](#)
`x2vz()` (*mp.nm_element* method), [111](#)
`xt_3p` (class in *mp*), [178](#)
`xt_legacy_dcline` (class in *mp*), [202](#)
`xt_reserves` (class in *mp*), [173](#)

Y

`Y` (*mp.form_ac* attribute), [75](#)
`yc` (*mp.dme_line3p* attribute), [188](#)
`ys` (*mp.dme_line3p* attribute), [188](#)

Z

`z` (*mp.net_model_dc* attribute), [107](#)
`zg_x_update()` (*mp.math_model_pf_acps* method), [128](#)
`zgausspf()` (built-in function), [266](#)
`zones` (*mp.dme_reserve_zone* attribute), [177](#)