

# 1 Example working (as a guideline of code/documentation to generate)

## 1.1 Problem definition

Coordinates:  $(x, t)$ , so solution function is  $u(x, t)$

$$\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} = 0$$

Dirichlet on left boundary:

$$u(0, t) = 0$$

Dirichlet on bottom boundary:

$$u(x, 0) = e^{-(x-3)^2}$$

Domain:  $x \in [0, 6], t \in [0, 3]$

## 1.2 Solution method

### 1.2.1 Stencil

Use stencil with values:  $u_{i-1, j}$  and  $u_{i, j-1}$  with Taylor series expanded about  $u_{i, j}$ . The unknown in the stencil is  $u_{i, j}$ .

### 1.2.2 Approximations

Method will be used on the computational domain, with coordinates  $(p, q)$ , where nodes are spaced by 1 in each direction.

$$\frac{\partial u}{\partial p} = u_{i, j} - u_{i-1, j}$$

$$\frac{\partial u}{\partial q} = u_{i, j} - u_{i, j-1}$$

On a simple grid physical domain with computational domain axes being linearly scaled  $x$  and  $t$  axes:

$$\frac{\partial u}{\partial x} = \frac{1}{\Delta x} \frac{\partial u}{\partial p}$$

$$\frac{\partial u}{\partial t} = \frac{1}{\Delta t} \frac{\partial u}{\partial q}$$

Of course,  $\frac{1}{\Delta x}$  and  $\frac{1}{\Delta t}$  would be computed once and reused.

On a more complex physical domain with a coordinate transform applied:

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial p} \frac{\partial p}{\partial x} + \frac{\partial u}{\partial q} \frac{\partial q}{\partial x}$$

$$\frac{\partial u}{\partial t} = \frac{\partial u}{\partial p} \frac{\partial p}{\partial t} + \frac{\partial u}{\partial q} \frac{\partial q}{\partial t}$$

where the derivatives from the coordinate transforms would be previously calculated at each point in the mesh.

### 1.2.3 Substituting equation

With the simple computational domain:

$$\frac{1}{\Delta t}(u_{i,j} - u_{i,j-1}) + c \frac{1}{\Delta x}(u_{i,j} - u_{i-1,j}) = 0$$

Then solve for  $u_{i,j}$ :

$$\begin{aligned} \left(\frac{1}{\Delta t} + c \frac{1}{\Delta x}\right) u_{i,j} &= \frac{1}{\Delta t} u_{i,j-1} + c \frac{1}{\Delta x} u_{i-1,j} \\ u_{i,j} &= \frac{1}{\frac{1}{\Delta t} + c \frac{1}{\Delta x}} \left( \frac{1}{\Delta t} u_{i,j-1} + c \frac{1}{\Delta x} u_{i-1,j} \right) \end{aligned}$$

With the complex domain:

$$\begin{aligned} \frac{\partial u}{\partial p} \frac{\partial p}{\partial t} + \frac{\partial u}{\partial q} \frac{\partial q}{\partial t} + c \frac{\partial u}{\partial p} \frac{\partial p}{\partial x} + c \frac{\partial u}{\partial q} \frac{\partial q}{\partial x} &= 0 \\ \frac{\partial u}{\partial p} \left( \frac{\partial p}{\partial t} + c \frac{\partial p}{\partial x} \right) + \frac{\partial u}{\partial q} \left( \frac{\partial q}{\partial t} + c \frac{\partial q}{\partial x} \right) &= 0 \\ \left( \frac{\partial p}{\partial t} + c \frac{\partial p}{\partial x} \right) (u_{i,j} - u_{i-1,j}) + \left( \frac{\partial q}{\partial t} + c \frac{\partial q}{\partial x} \right) (u_{i,j} - u_{i,j-1}) &= 0 \\ \left( \frac{\partial p}{\partial t} + c \frac{\partial p}{\partial x} + \frac{\partial q}{\partial t} + c \frac{\partial q}{\partial x} \right) u_{i,j} &= \left( \frac{\partial p}{\partial t} + c \frac{\partial p}{\partial x} \right) u_{i-1,j} + \left( \frac{\partial q}{\partial t} + c \frac{\partial q}{\partial x} \right) u_{i,j-1} \\ u_{i,j} &= \frac{1}{\frac{\partial p}{\partial t} + c \frac{\partial p}{\partial x} + \frac{\partial q}{\partial t} + c \frac{\partial q}{\partial x}} \left( \left( \frac{\partial p}{\partial t} + c \frac{\partial p}{\partial x} \right) u_{i-1,j} + \left( \frac{\partial q}{\partial t} + c \frac{\partial q}{\partial x} \right) u_{i,j-1} \right) \end{aligned}$$