

## **Network-based crime prediction**

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#### **Big Data and Intelligent Policing**

CPC Project Closing Workshop 7<sup>th</sup> June 2016







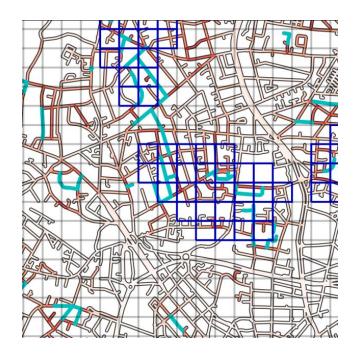






## **Network-based crime prediction**

- Introduction to crime prediction
- Existing grid-based prediction approaches
- Motivating a network-based approach
- Network prediction method
- Accuracy results











## Introduction to crime prediction

Q

How do the police decide where to patrol?

A

Optimise their potential to safeguard the public, deter criminals and increase public confidence.









## Introduction to crime prediction

- Maps have been used for a long time to help guide patrols.
- This is typically retrospective:

"Spatial crime patterns tomorrow will be similar to those last week."

- More recently, digital Geographic Information systems are used to achieve the same outcome faster and with better data.
- Responses are still reactive.











## Introduction to crime prediction

- The use of maps for proactive policing is a relatively new paradigm.
- Send police to the places that will be at risk of crime.



- The space-time patterns of crime events cluster in space and time.
- Modelling these effects allows us to generate forecasts that are more accurate than simply returning to the same locations.







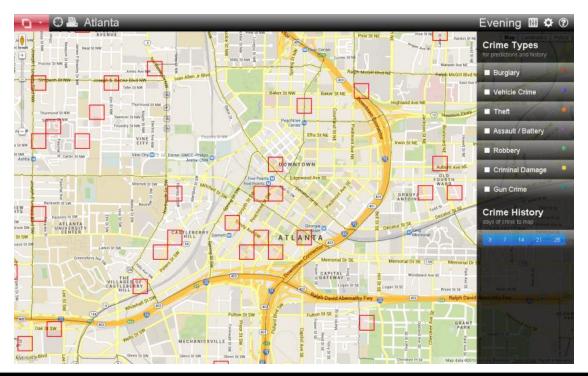






## Grid-based prediction approaches

- Predictions must be reported on an areal unit.
- Existing systems typically highlight the most risky grid squares.











# Motivating a network-based approach Disadvantage (1)

Police patrol streets, not grid squares.

Blue -> red: walking 100 metres.



#### Proportion of road length in grid.







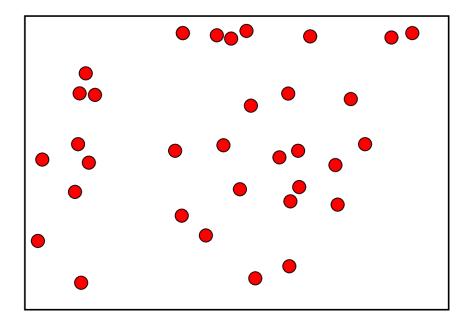




## Motivating a network-based approach

#### Disadvantage (2)

- Many urban crimes occur along streets, so our models should take that into account.
- Typical assumption that crimes occur in planar space.







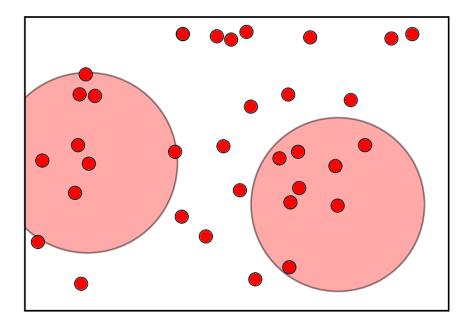




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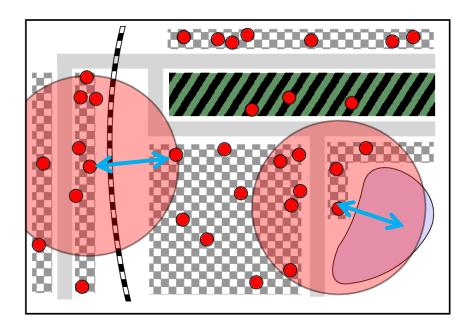




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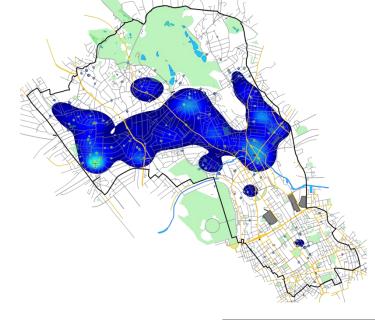


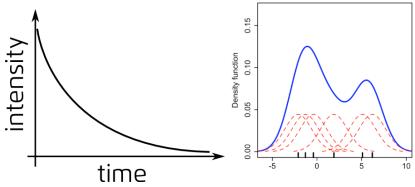






- Our method is based on an extension of an existing approach used to generate heat maps called kernel density estimation (KDE).
- In planar applications, this works by dropping a 2D 'kernel' (bell curve) onto every crime to obtain a smoothed surface.
- The height of the bell curve decays over time.







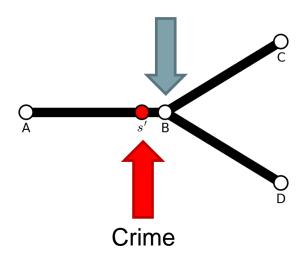


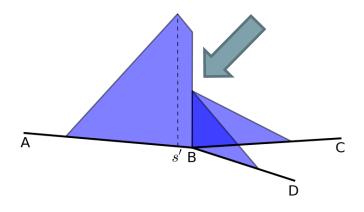




In our network application, we only change the spatial part: this is now defined on the street network.

- > The spatial kernel decreases linearly with distance.
- > Every time the network splits, the kernel splits too.







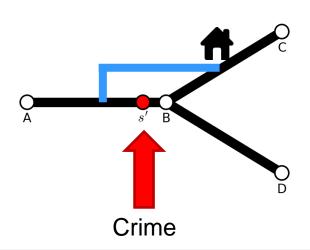


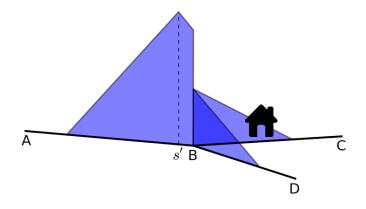




In our network application, we only change the spatial part: this is now defined on the street network.

- > The spatial kernel decreases linearly with distance.
- > Every time the network splits, the kernel splits too.
- > All routes are counted from s' -> B.





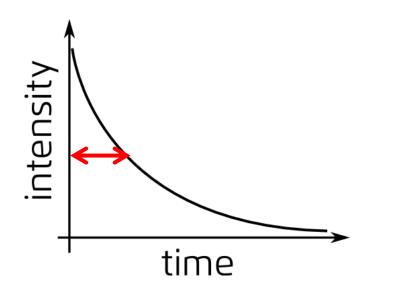


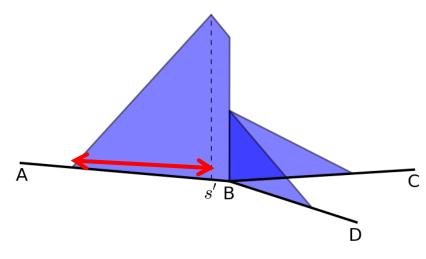






- There are two key parameters here: the bandwidths.
- These should be tailored to the crime type and study area.





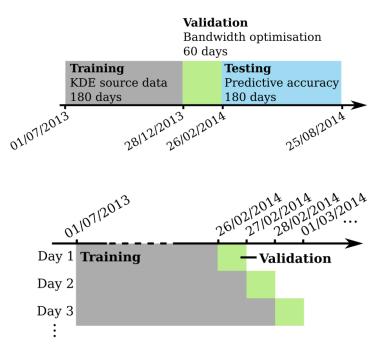


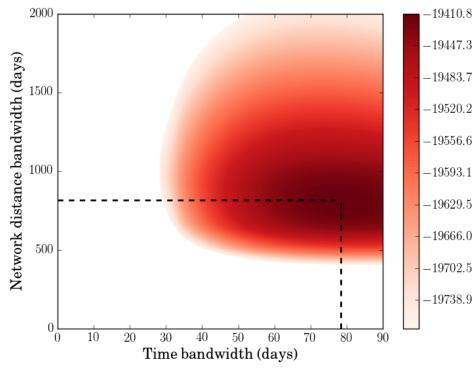






We use a maximum likelihood approach.









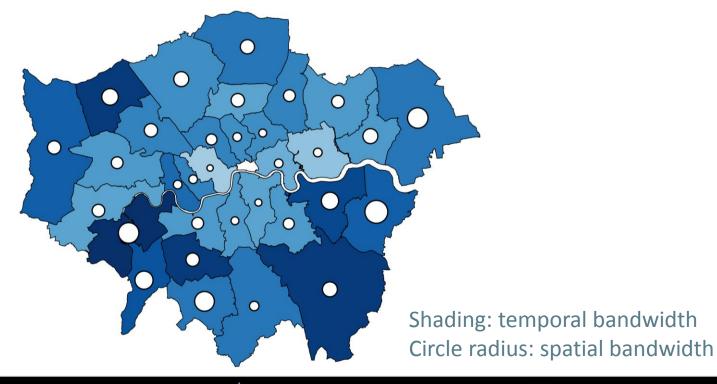




We use a maximum likelihood approach.

The bandwidths vary significantly by location and crime

type.



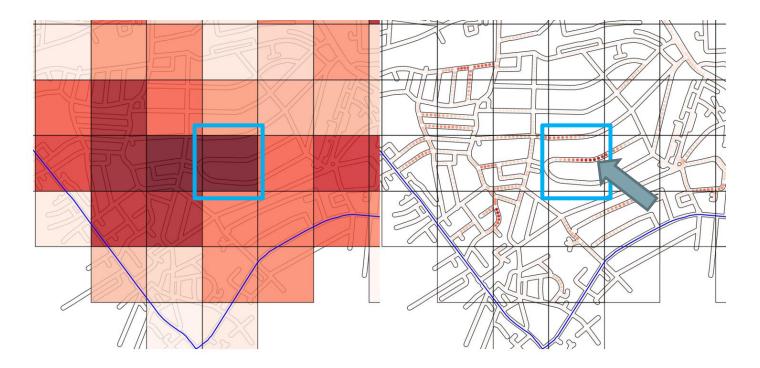








- Using this method, we can produce predictive crime maps with hotspots based on the road network.
- More easily interpreted than grid-based maps.



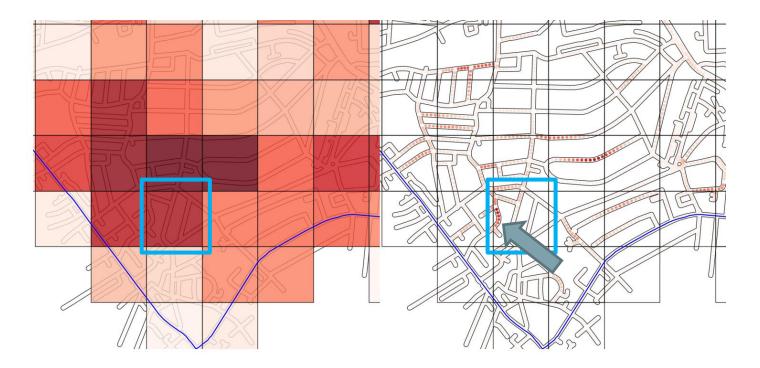








- Using this method, we can produce predictive crime maps with hotspots based on the road network.
- Less ambiguous than grid-based maps.





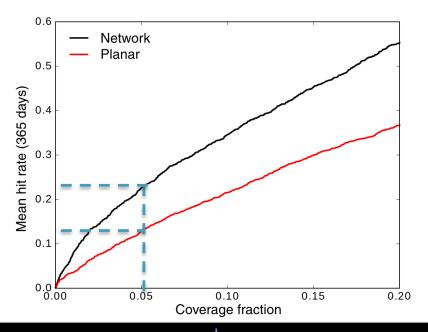






## Accuracy results

- Monsuru will talk more about evaluation methods in the next presentation.
- We compare the network method with a grid-based prediction method using the hit rate. Results are for 1 year of burglary crimes in Camden.
- The network-based approach is almost twice as accurate at 5% coverage.



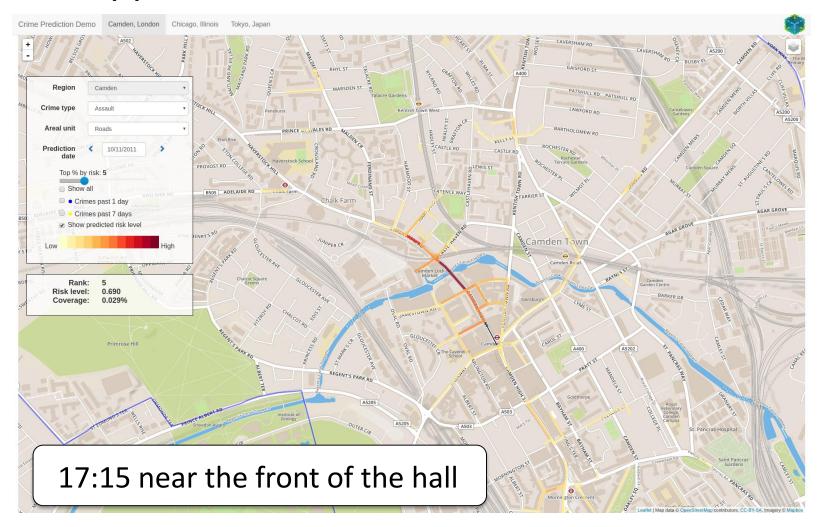








## Demo application











## Thank you!





