

# Minimum Spanning Trees

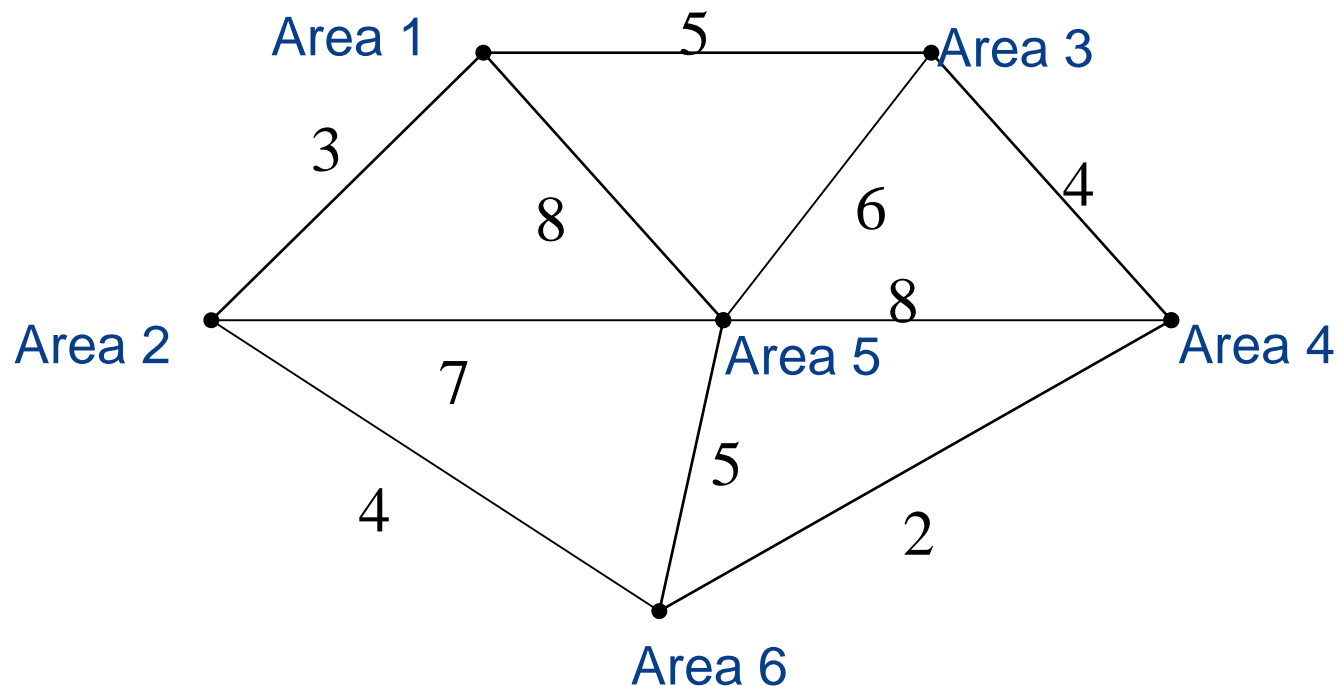
Lecture 15

# Introduction

- Greedy algorithm is a technique for solving problems with the following properties:
  - The problem is an **optimization problem**, to find the solution that **minimizes** or **maximizes** some value (**cost/profit**)
  - The solution can be constructed in a **sequence** of **steps/choices**
  - For each choice point:
    - The choice must be feasible
    - The choice looks good or better than alternatives (Cost)
    - The choice cannot be revoked

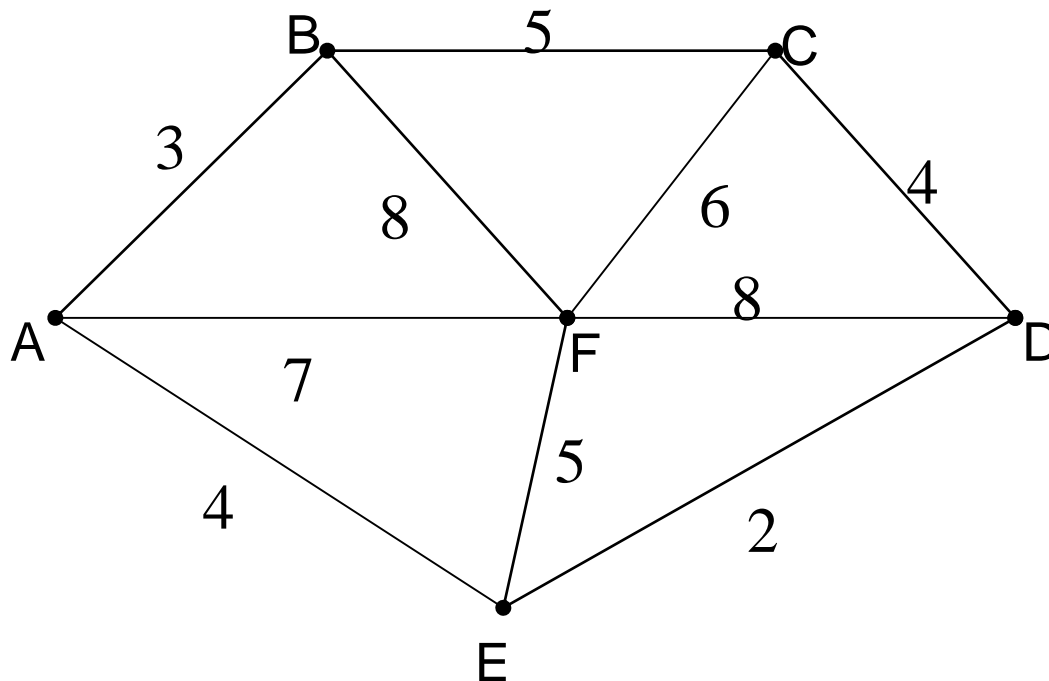
# Example

- A cable company want to connect five villages to their network which currently extends to the market town. What is the minimum length of cable needed?



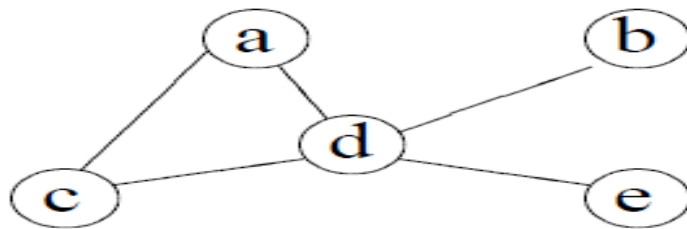
# Example

- We model the situation as a network, then the problem is to find the minimum connector for the network

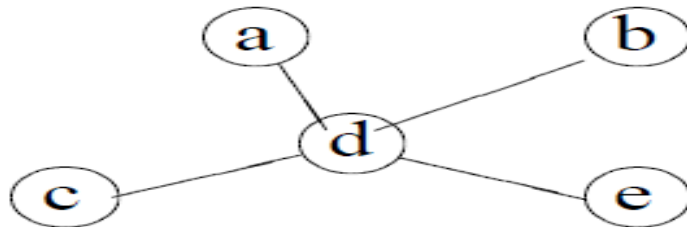


# Spanning Trees

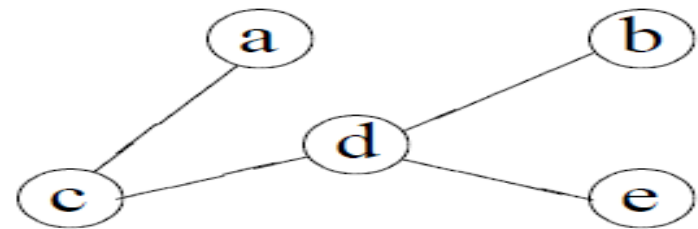
- **Spanning Trees:** A subgraph of a undirected graph is a spanning tree if it is a tree and contains every vertex of given graph



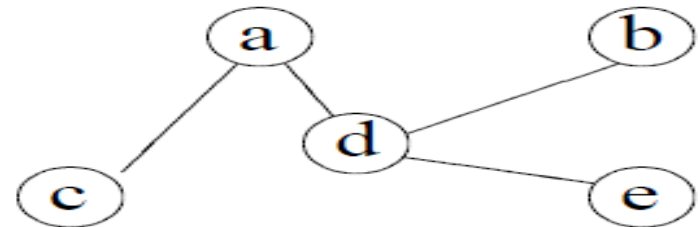
Graph



spanning tree 2



spanning tree 1



spanning tree 3

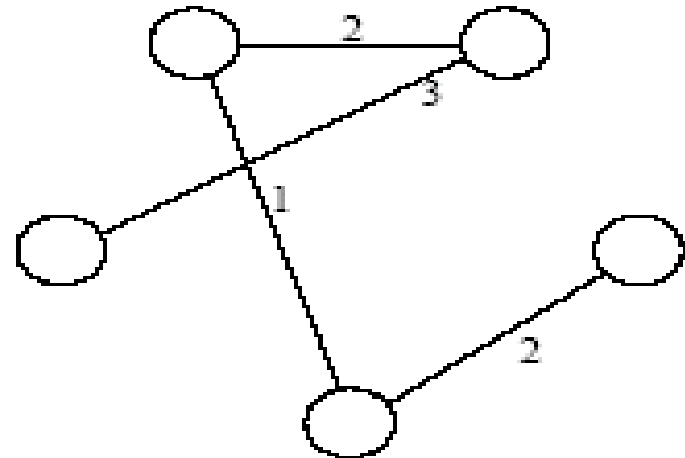
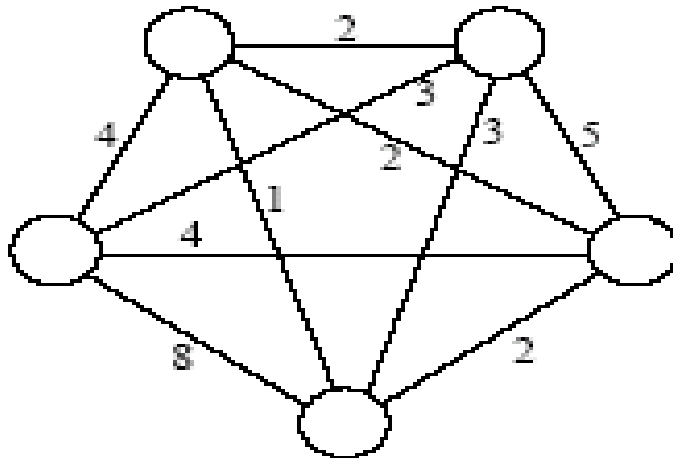
# Minimum Spanning Trees

- A minimum spanning tree (MST) for a graph  $G = (V, E)$  is a **sub graph**  $G_1 = (V_1, E_1)$  of  $G$  contains **all the vertices** of  $G$
- If a graph  $G$  is **not** a **connected** graph, then it cannot have any spanning tree
- A minimum spanning tree (MST) for a weighted graph is a spanning tree with **minimum weight**. All the vertices in the weighted graph will be connected with minimum edge with **minimum weights**

# What Makes A Spanning Tree The Minimum?

## ➤ MST Criterion:

- When the sum of the edge weights in a spanning tree is the minimum over all spanning trees of a graph



# Applications of Minimum-Cost Spanning Trees

- Building **cable networks** that join  $n$  locations with minimum cost
- Building a **road network** that joins  $n$  cities with minimum cost
- Obtaining an independent set of circuit equations for an electrical network

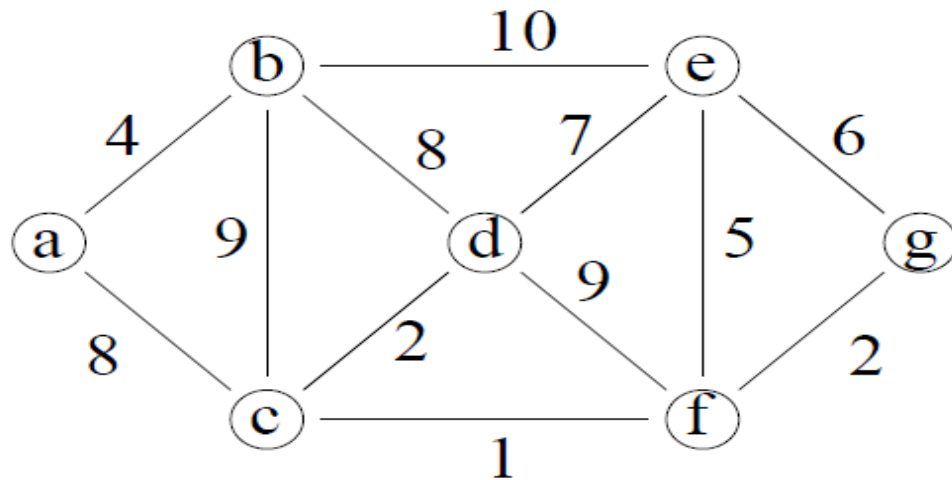


# Prim's Algorithm

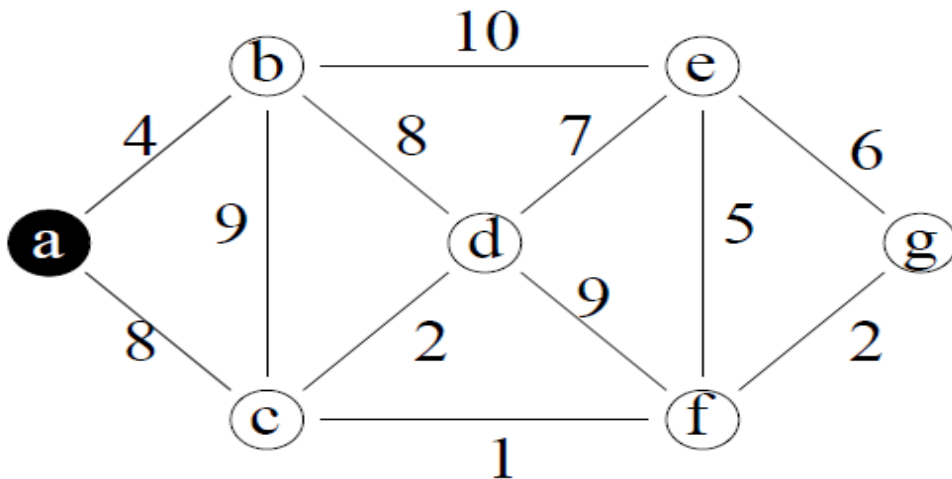
- Finds a minimum spanning tree for a connected weighted undirected graph
- It finds a subset of the edges that forms a tree that includes **every vertex**, where the total weight of all the edges in the tree is **minimized**

- 1) Select **any vertex**
- 2) Select the **shortest** edge connected to that vertex
- 3) Select the shortest edge connected to any vertex **already connected**
- 4) Repeat step 3 until all vertices have been connected

# Prim's Algorithm Example



Connected graph



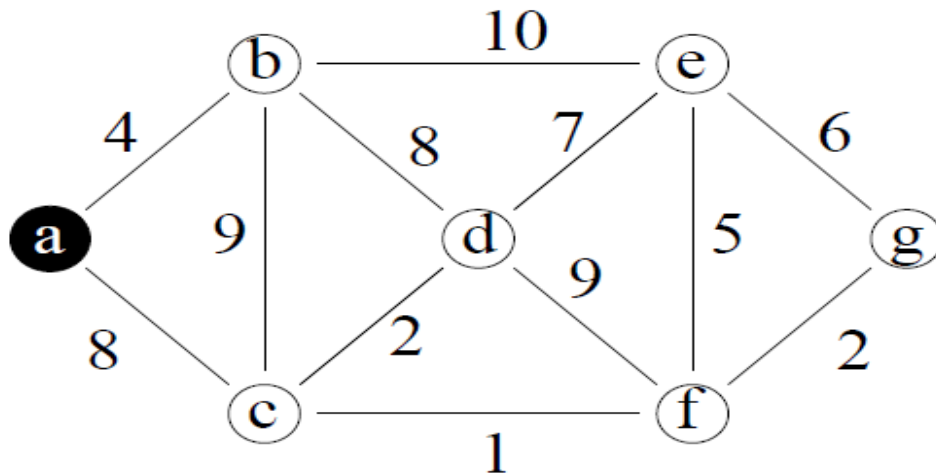
Step 0

$S = \{a\}$

$V \setminus S = \{b, c, d, e, f, g\}$

lightest edge = {a,b}

# Prim's Algorithm Example



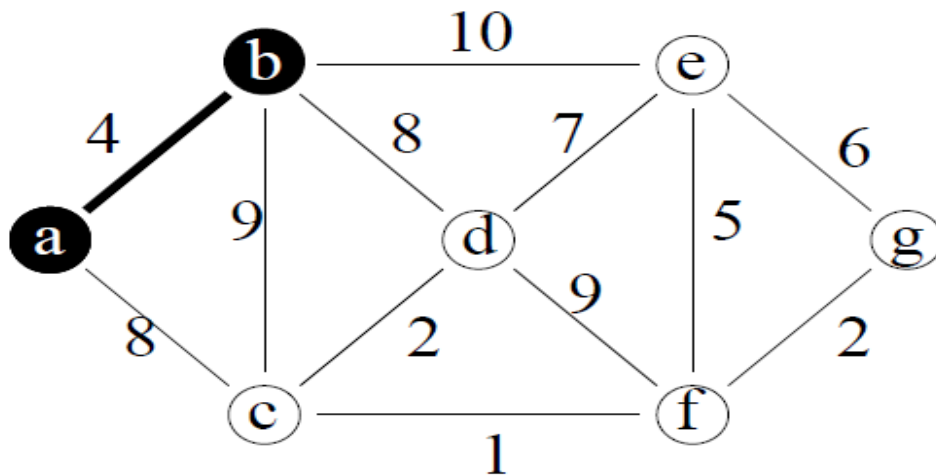
Step 1.1 before

$S = \{a\}$

$V \setminus S = \{b, c, d, e, f, g\}$

$A = \{\}$

lightest edge =  $\{a, b\}$



Step 1.1 after

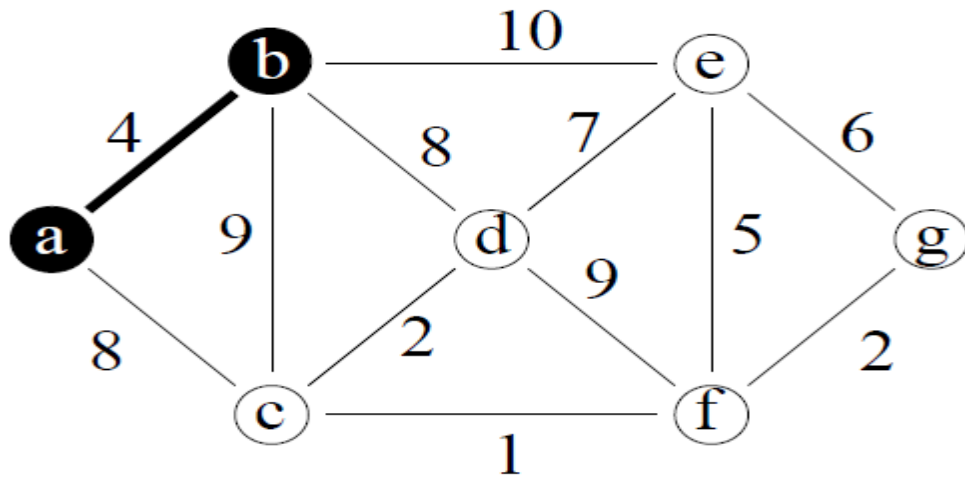
$S = \{a, b\}$

$V \setminus S = \{c, d, e, f, g\}$

$A = \{\{a, b\}\}$

lightest edge =  $\{b, d\}, \{a, c\}$

# Prim's Algorithm Example



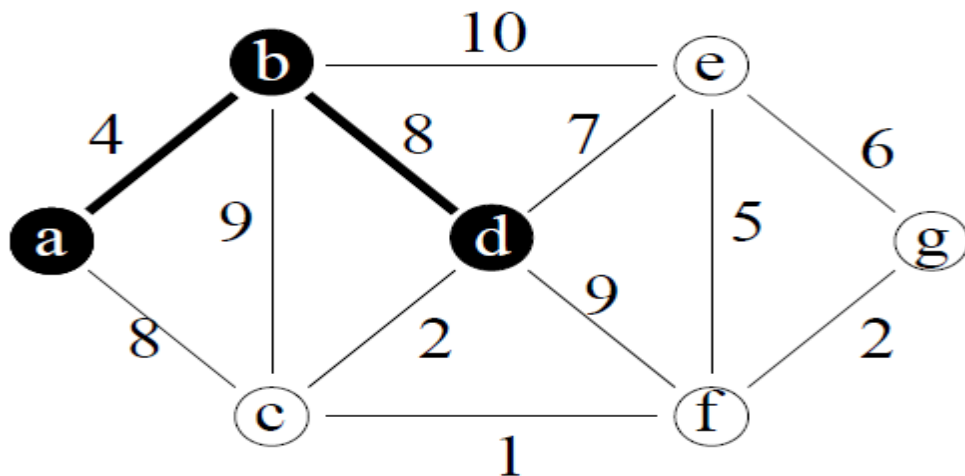
Step 1.2 before

$S = \{a, b\}$

$V \setminus S = \{c, d, e, f, g\}$

$A = \{\{a, b\}\}$

lightest edge =  $\{b, d\}, \{a, c\}$



Step 1.2 after

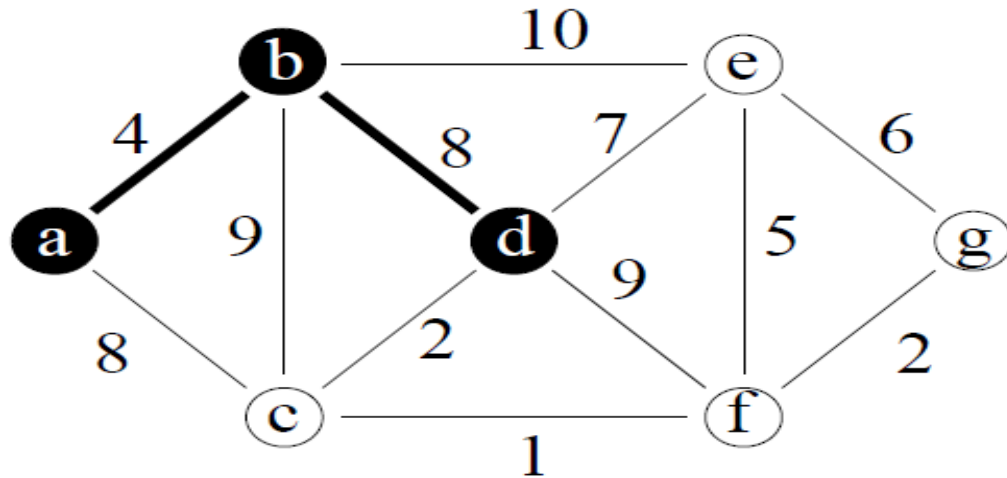
$S = \{a, b, d\}$

$V \setminus S = \{c, e, f, g\}$

$A = \{\{a, b\}, \{b, d\}\}$

lightest edge =  $\{d, c\}$

# Prim's Algorithm Example



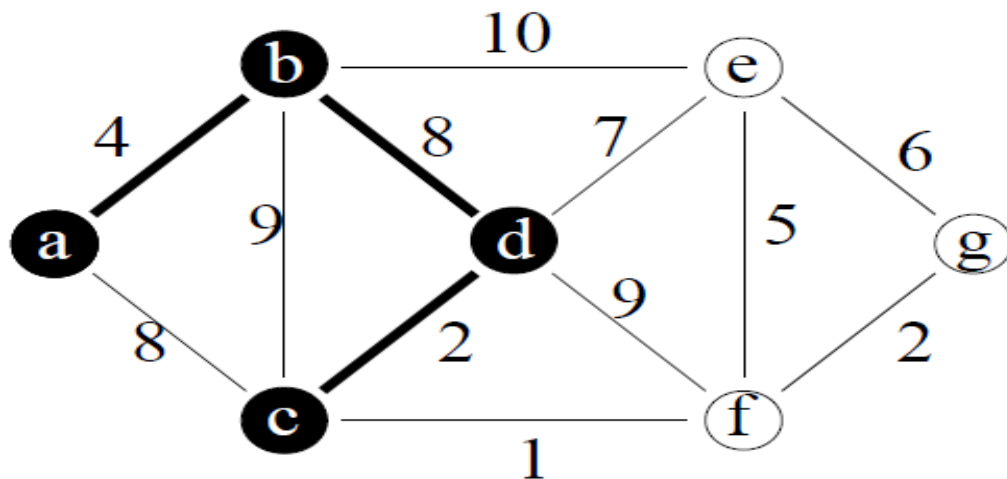
Step 1.3 before

$S = \{a, b, d\}$

$V \setminus S = \{c, e, f, g\}$

$A = \{\{a, b\}, \{b, d\}\}$

lightest edge =  $\{d, c\}$



Step 1.3 after

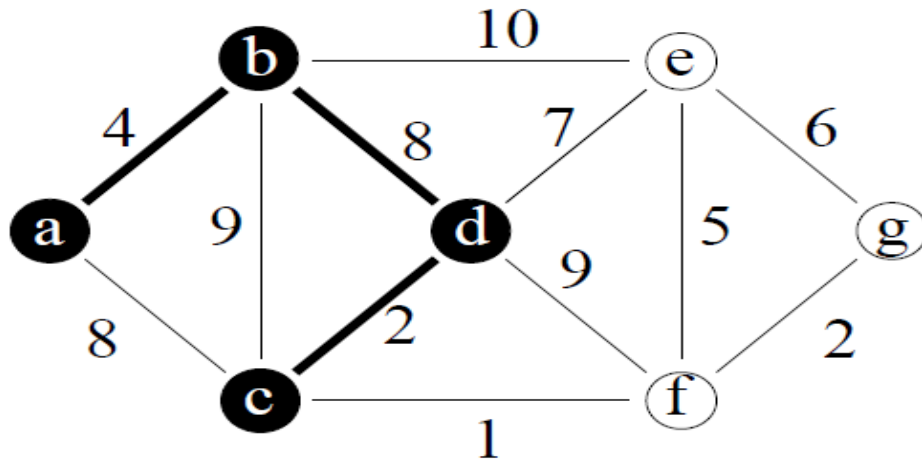
$S = \{a, b, c, d\}$

$V \setminus S = \{e, f, g\}$

$A = \{\{a, b\}, \{b, d\}, \{c, d\}\}$

lightest edge =  $\{c, f\}$

# Prim's Algorithm Example



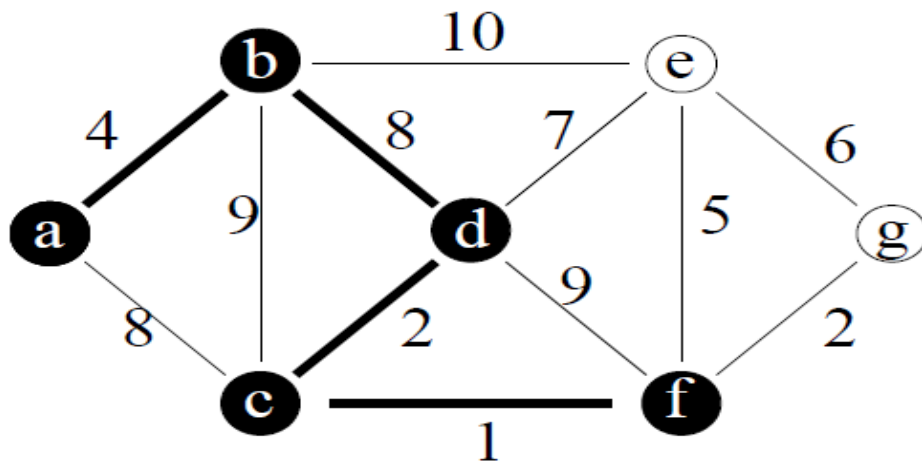
Step 1.4 before

$S = \{a, b, c, d\}$

$V \setminus S = \{e, f, g\}$

$A = \{\{a, b\}, \{b, d\}, \{c, d\}\}$

lightest edge =  $\{c, f\}$



Step 1.4 after

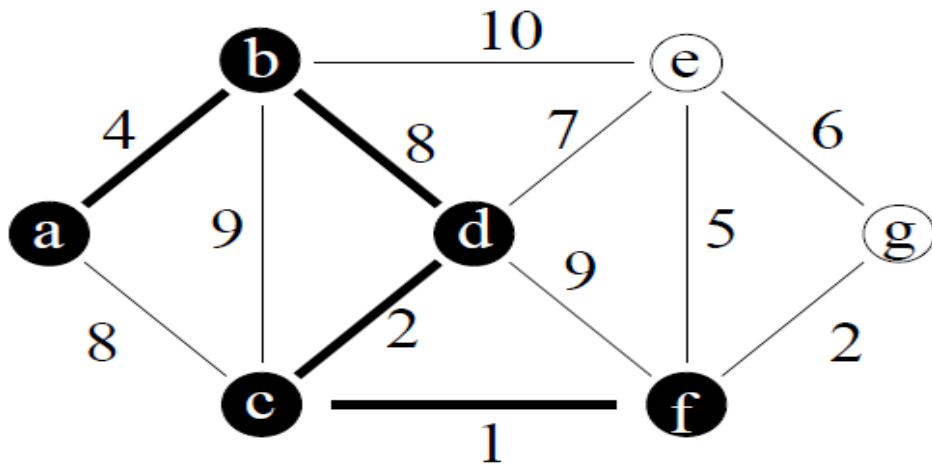
$S = \{a, b, c, d, f\}$

$V \setminus S = \{e, g\}$

$A = \{\{a, b\}, \{b, d\}, \{c, d\}, \{c, f\}\}$

lightest edge =  $\{f, g\}$

# Prim's Algorithm Example



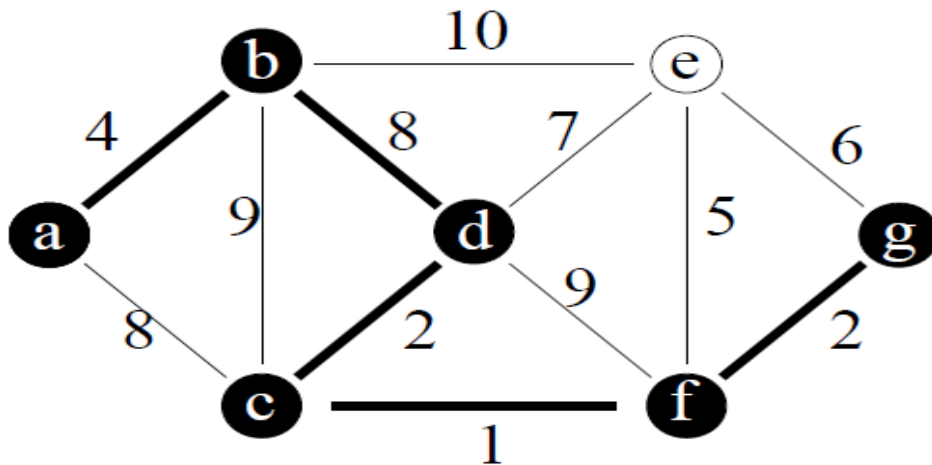
Step 1.5 before

$S = \{a, b, c, d, f\}$

$V \setminus S = \{e, g\}$

$A = \{\{a, b\}, \{b, d\}, \{c, d\}, \{c, f\}\}$

lightest edge =  $\{f, g\}$



Step 1.5 after

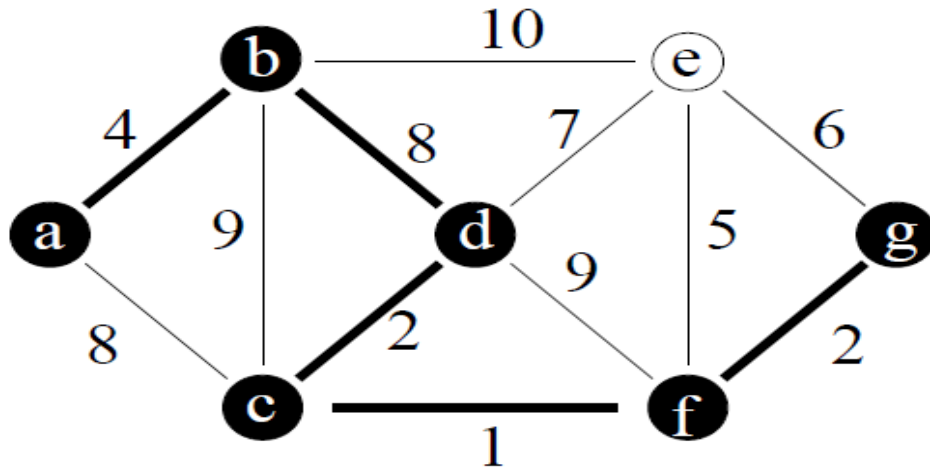
$S = \{a, b, c, d, f, g\}$

$V \setminus S = \{e\}$

$A = \{\{a, b\}, \{b, d\}, \{c, d\}, \{c, f\}, \{f, g\}\}$

lightest edge =  $\{f, e\}$

# Prim's Algorithm Example



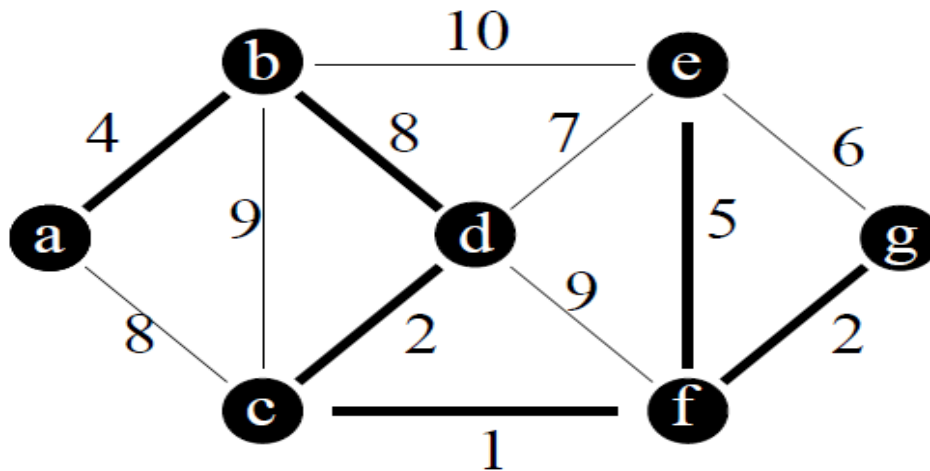
Step 1.6 before

$S = \{a, b, c, d, f, g\}$

$V \setminus S = \{e\}$

$A = \{\{a, b\}, \{b, d\}, \{c, d\}, \{c, f\}, \{f, g\}\}$

lightest edge =  $\{f, e\}$



Step 1.6 after

$S = \{a, b, c, d, e, f, g\}$

$V \setminus S = \{\}$

$A = \{\{a, b\}, \{b, d\}, \{c, d\}, \{c, f\}, \{f, g\}, \{f, e\}\}$

MST completed



# Dijkstra's Algorithm

- Finds shortest (minimum weight) path between a particular pair of vertices in a *weighted* directed graph with nonnegative edge weights
  - solves the "one vertex, shortest path" problem
- Works on both directed and undirected graphs. However, all edges must have nonnegative weights.
- Input: Weighted graph  $G=\{E,V\}$  and source vertex  $v \in V$ , such that all edge weights are nonnegative
- Output: Lengths of shortest paths (or the shortest paths themselves) from a given source vertex  $v \in V$  to all other vertices

# Dijkstra's Algorithm

- It starts by assigning some initial values for the distances from node  $s$  and to every other node in the network
- It operates in steps, where at each step the algorithm improves the distance values
- At each step, the shortest distance from node  $s$  to another node is determined

# Dijkstra's algorithm - Pseudocode

```
dist[s] ← 0
for all v ∈ V - {s}
    do dist[v] ← ∞
S ← ∅
Q ← V
vertices)
while Q ≠ ∅
do u ← mindistance(Q, dist)
   S ← S ∪ {u}
   for all v ∈ neighbors[u]
       do if dist[v] > dist[u] + w(u, v)
           then d[v] ← d[u] + w(u, v)
           (if desired, add traceback code)
return dist
```

(distance to source vertex is zero)

(set all other distances to infinity)

(S, the set of visited vertices is initially empty)

(Q, the queue initially contains all

vertices)

(while the queue is not empty)

(select the element of Q with the min. distance)

(add u to list of visited vertices)

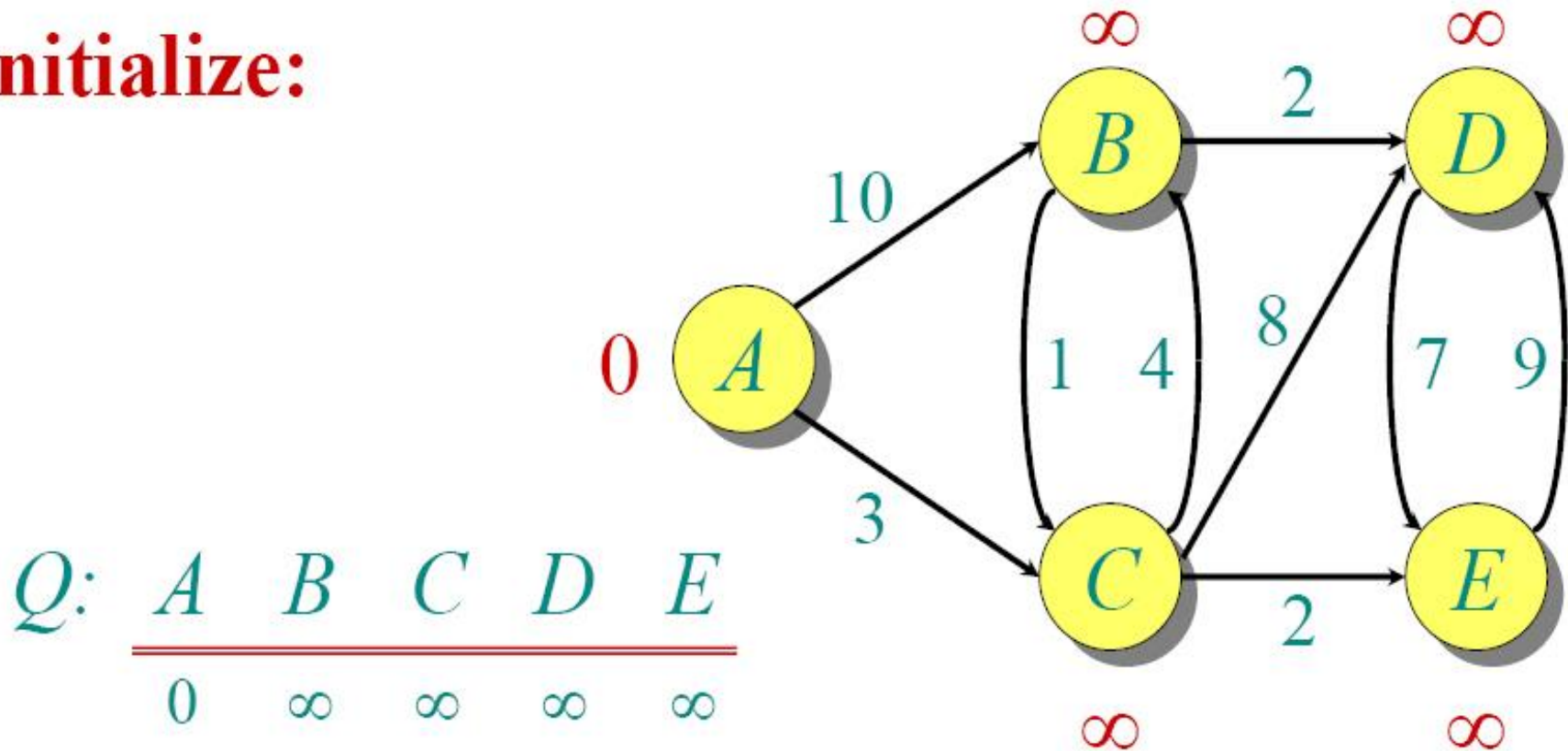
(if new shortest path found)

(set new value of shortest path)

(if desired, add traceback code)

# Dijkstra's Algorithm Example

**Initialize:**

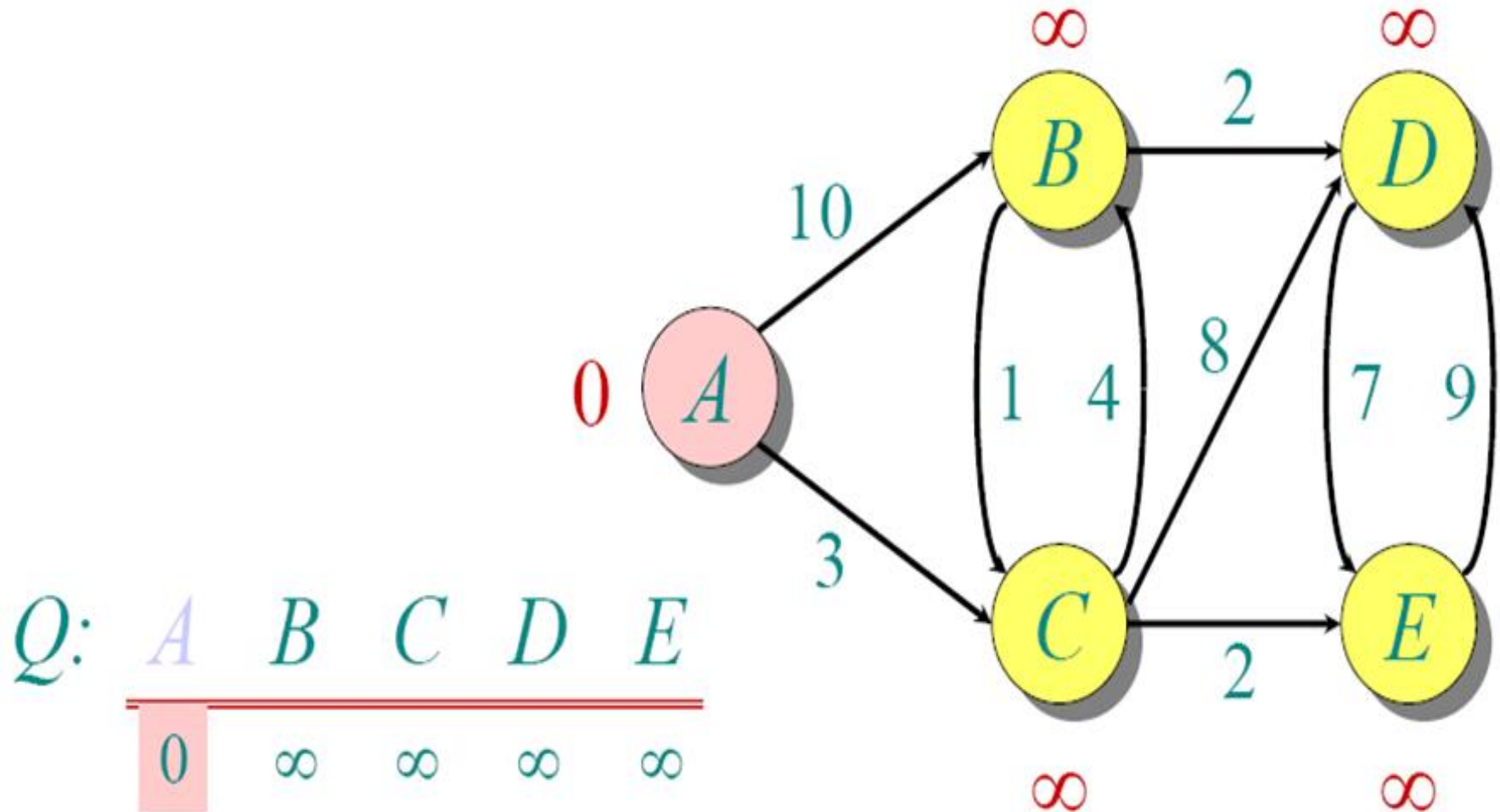


$Q:$

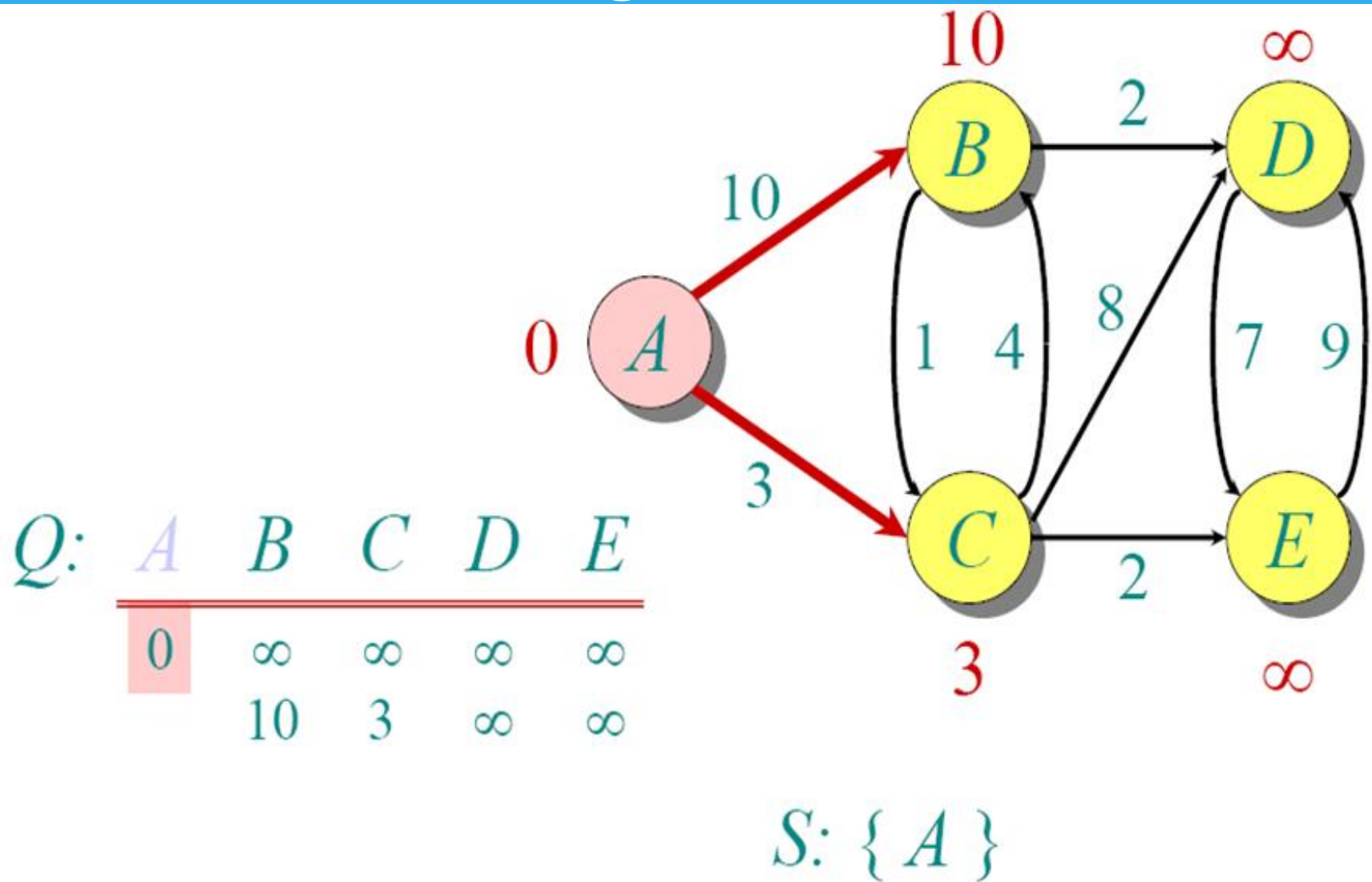
$A$	$B$	$C$	$D$	$E$
<hr/>	<hr/>	<hr/>	<hr/>	<hr/>
0	$\infty$	$\infty$	$\infty$	$\infty$

$S: \{\}$

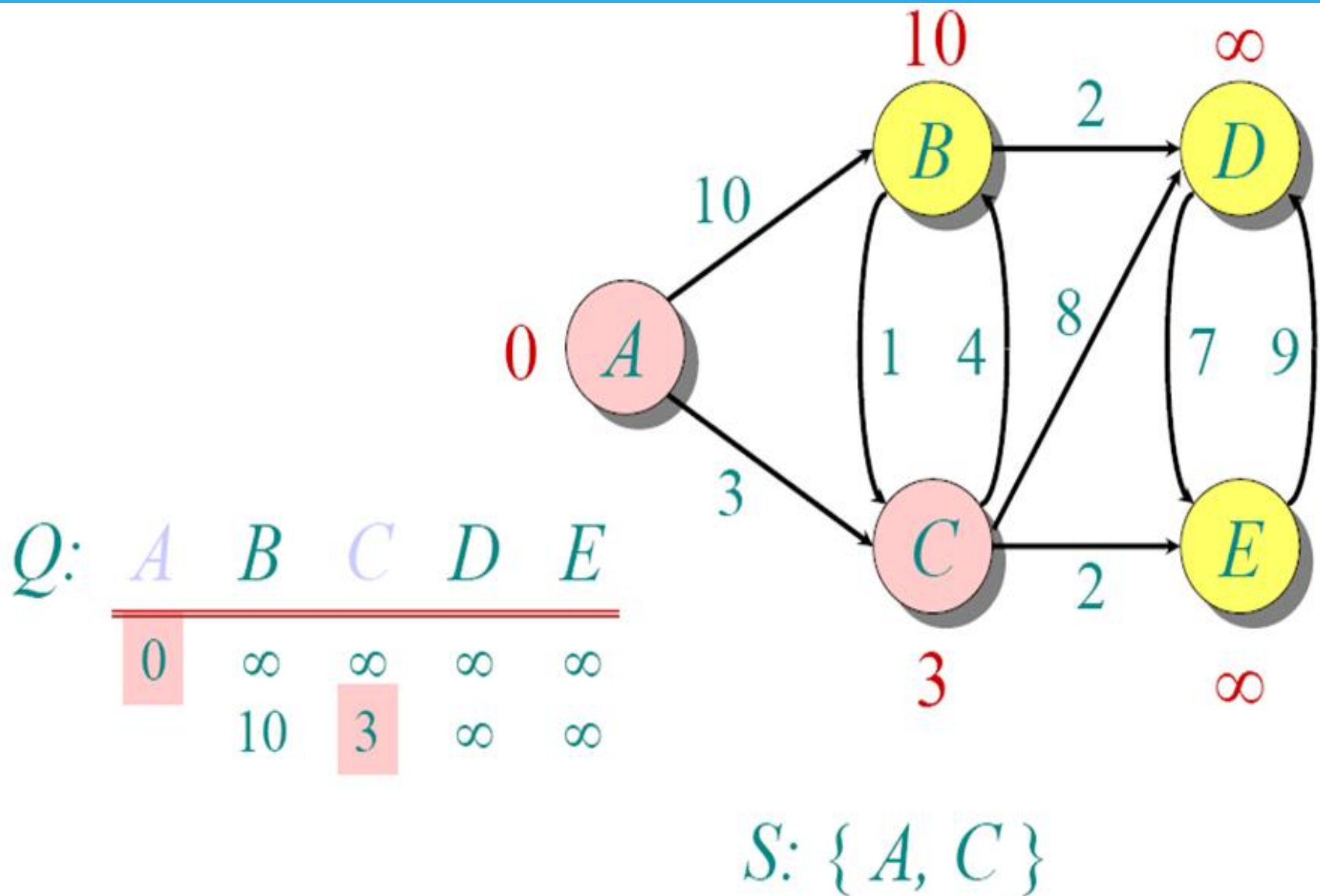
# Dijkstra's Algorithm Example



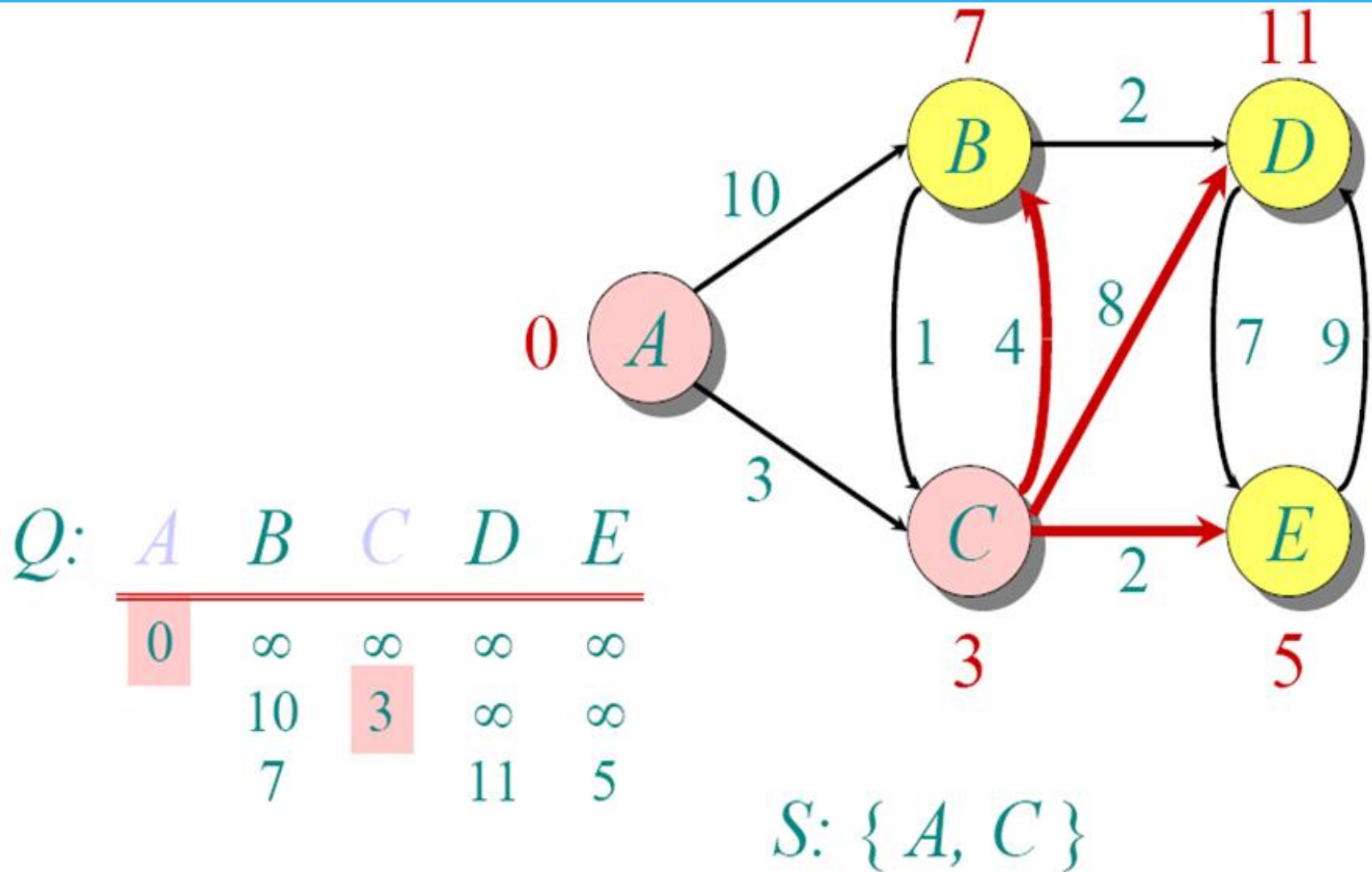
# Dijkstra's Algorithm Example



# Dijkstra's Algorithm Example

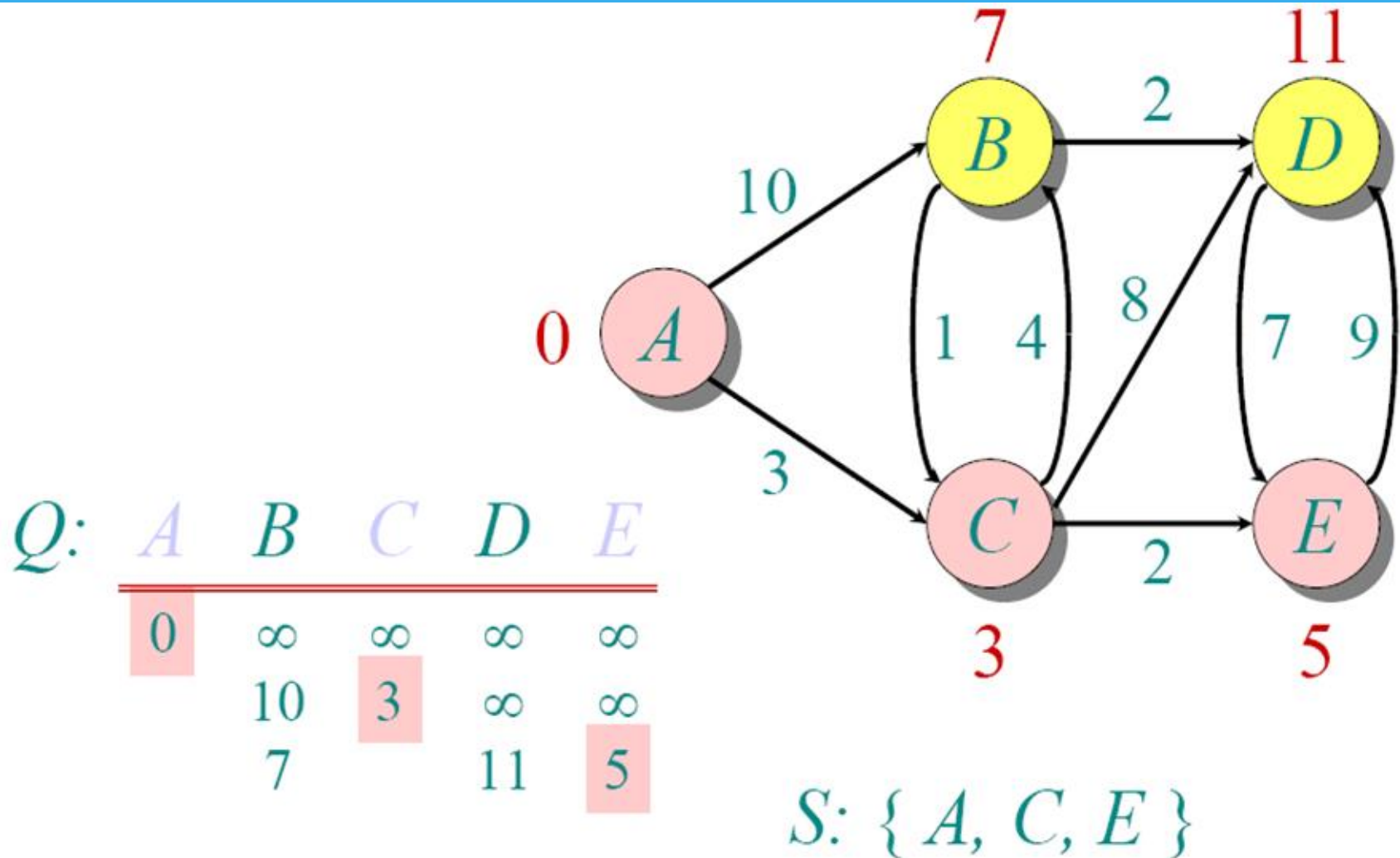


# Dijkstra's Algorithm Example

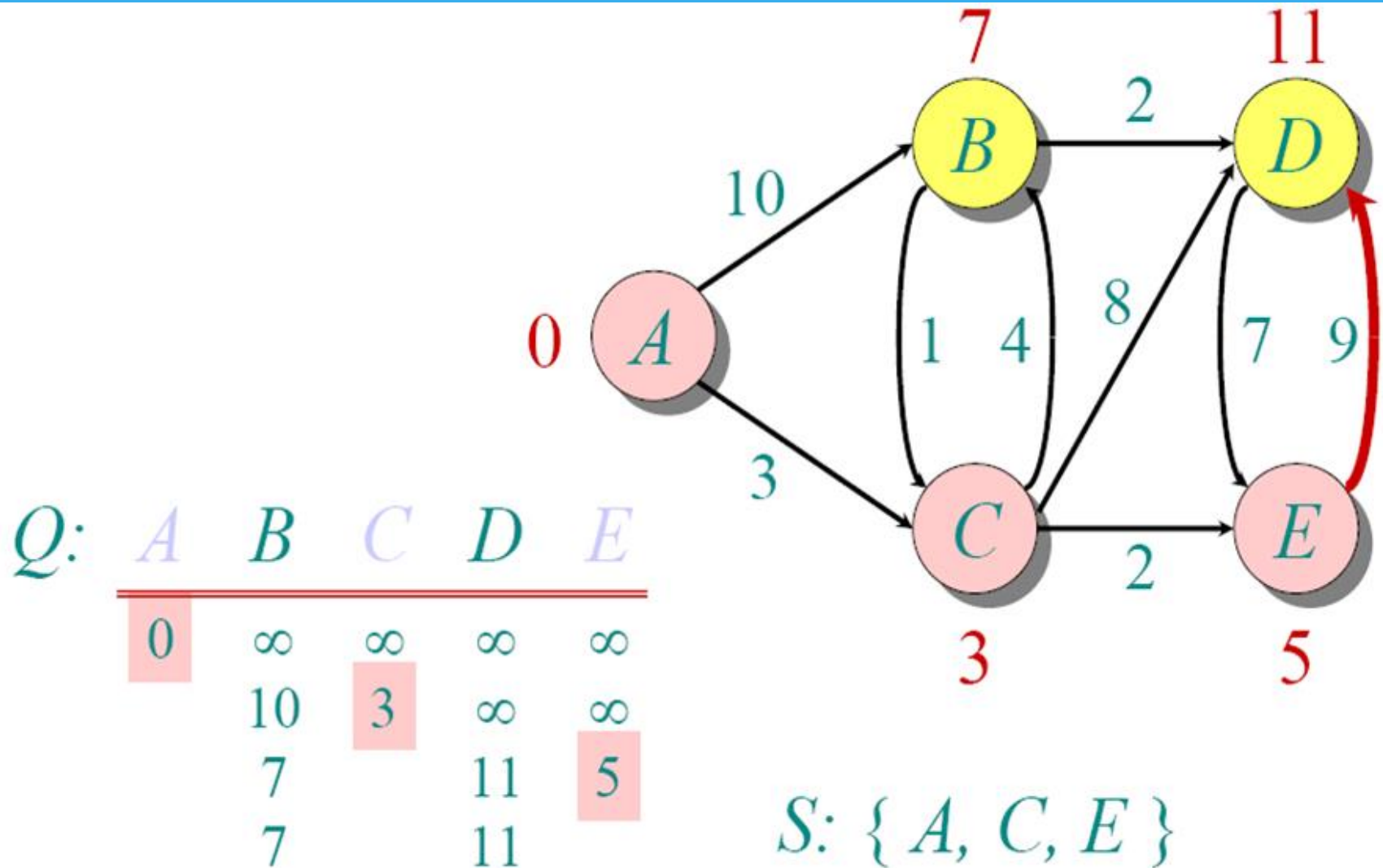




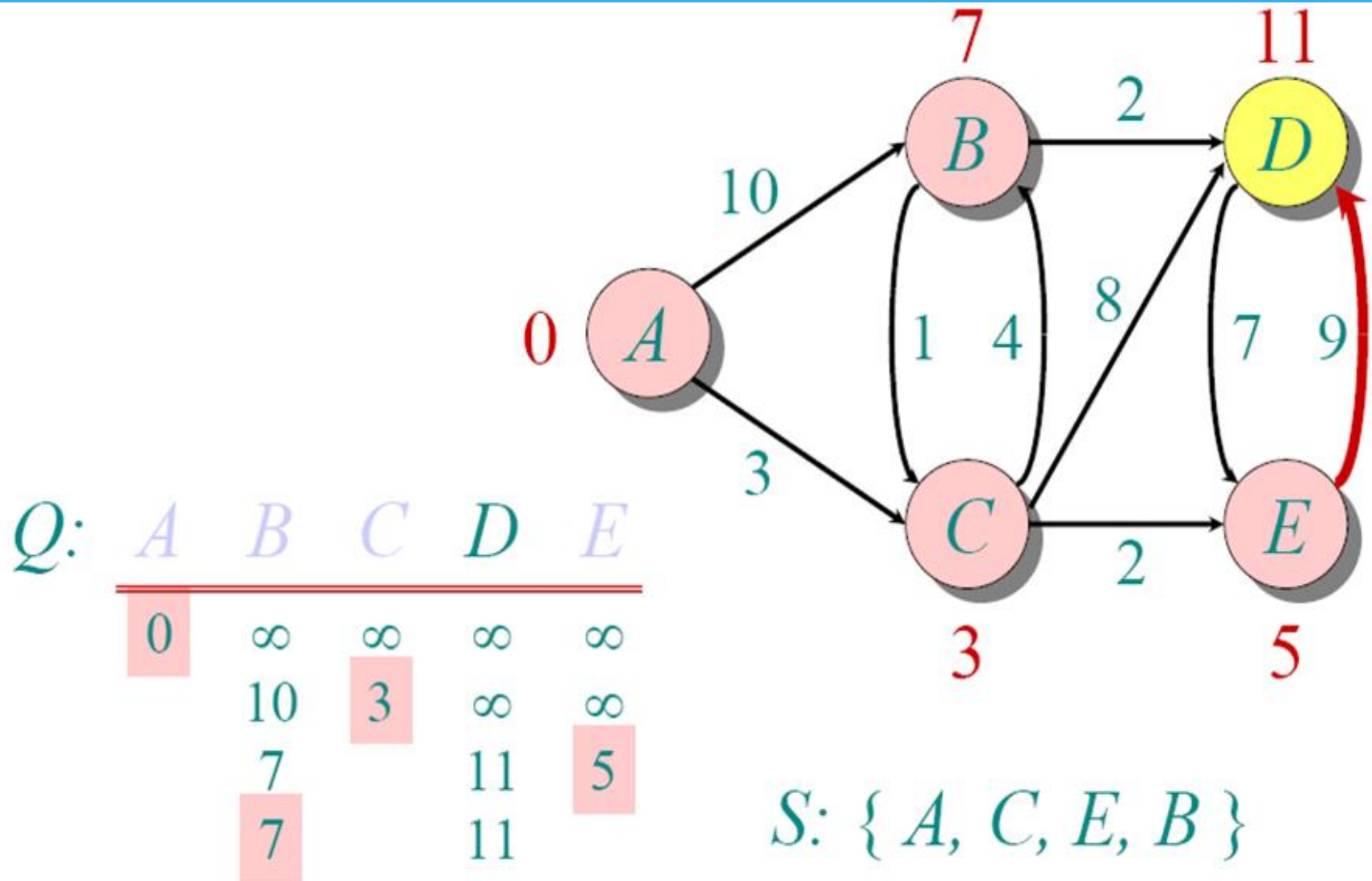
# Dijkstra's Algorithm Example



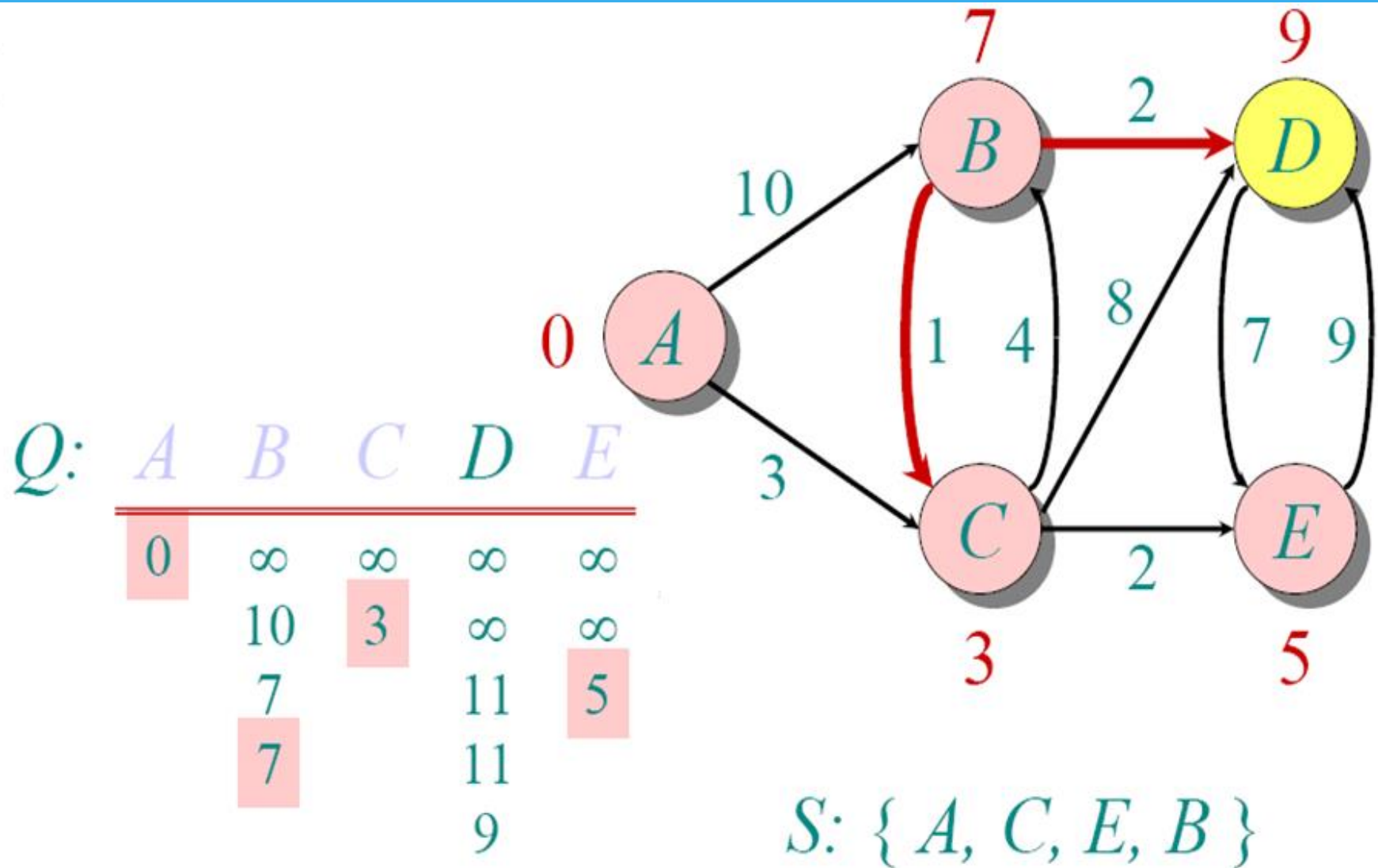
# Dijkstra's Algorithm Example



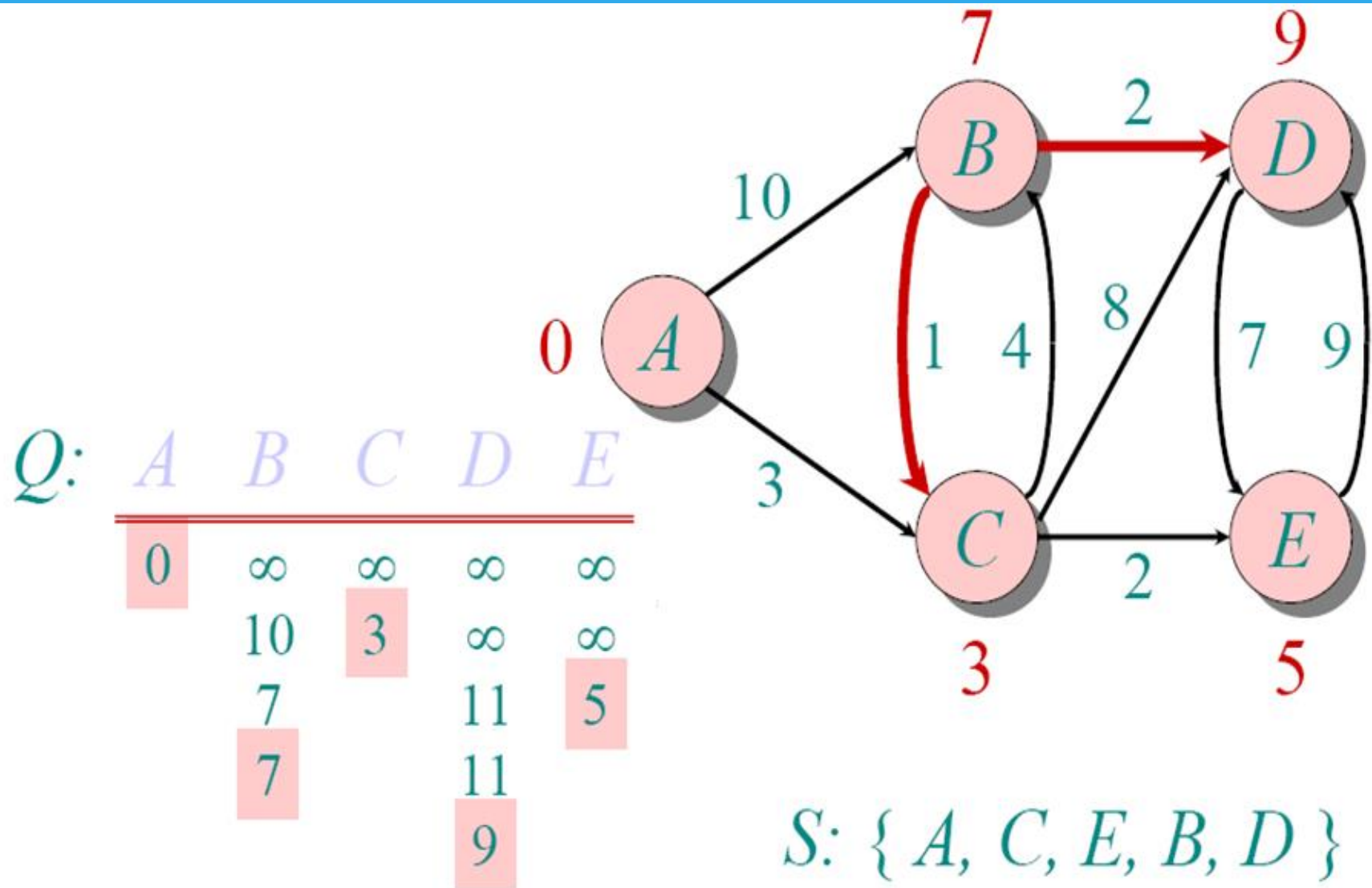
# Dijkstra's Algorithm Example



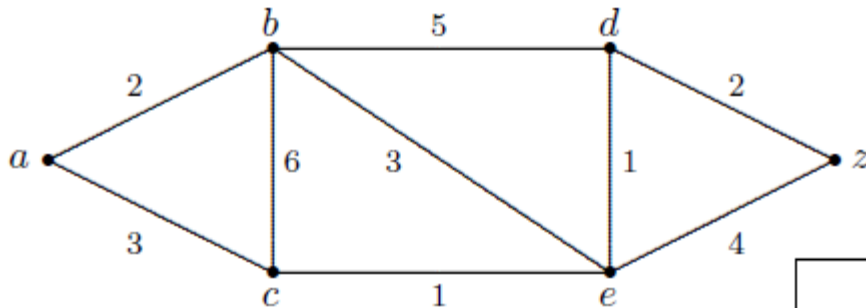
# Dijkstra's Algorithm Example



# Dijkstra's Algorithm Example



# Dijkstra's Algorithm Example 1



$S$	$L(a)$	$L(b)$	$L(c)$	$L(d)$	$L(e)$	$L(z)$
$\emptyset$	<span style="border: 1px solid black;">0</span>	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
$\{a\}$		<span style="border: 1px solid black;">2</span>	3	$\infty$	$\infty$	$\infty$
$\{a, b\}$			<span style="border: 1px solid black;">3</span>	7	5	$\infty$
$\{a, b, c\}$				7	<span style="border: 1px solid black;">4</span>	$\infty$
$\{a, b, c, e\}$				<span style="border: 1px solid black;">5</span>		8
$\{a, b, c, e, d\}$						<span style="border: 1px solid black;">7</span>
$\{a, b, c, e, d, z\}$						

At the last iteration,  $z \notin S$  and  $L(z) = 7$ .  
 We conclude that the cheapest path  
 from  $a$  to  $z$  has a **cost of 7**.