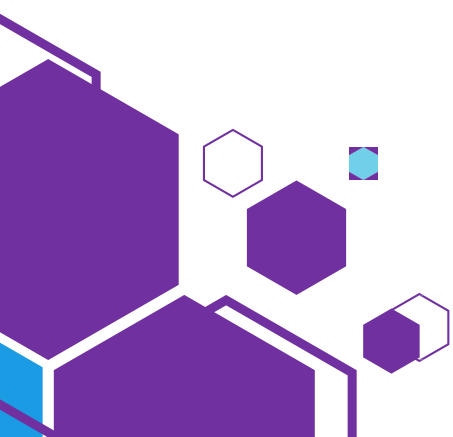


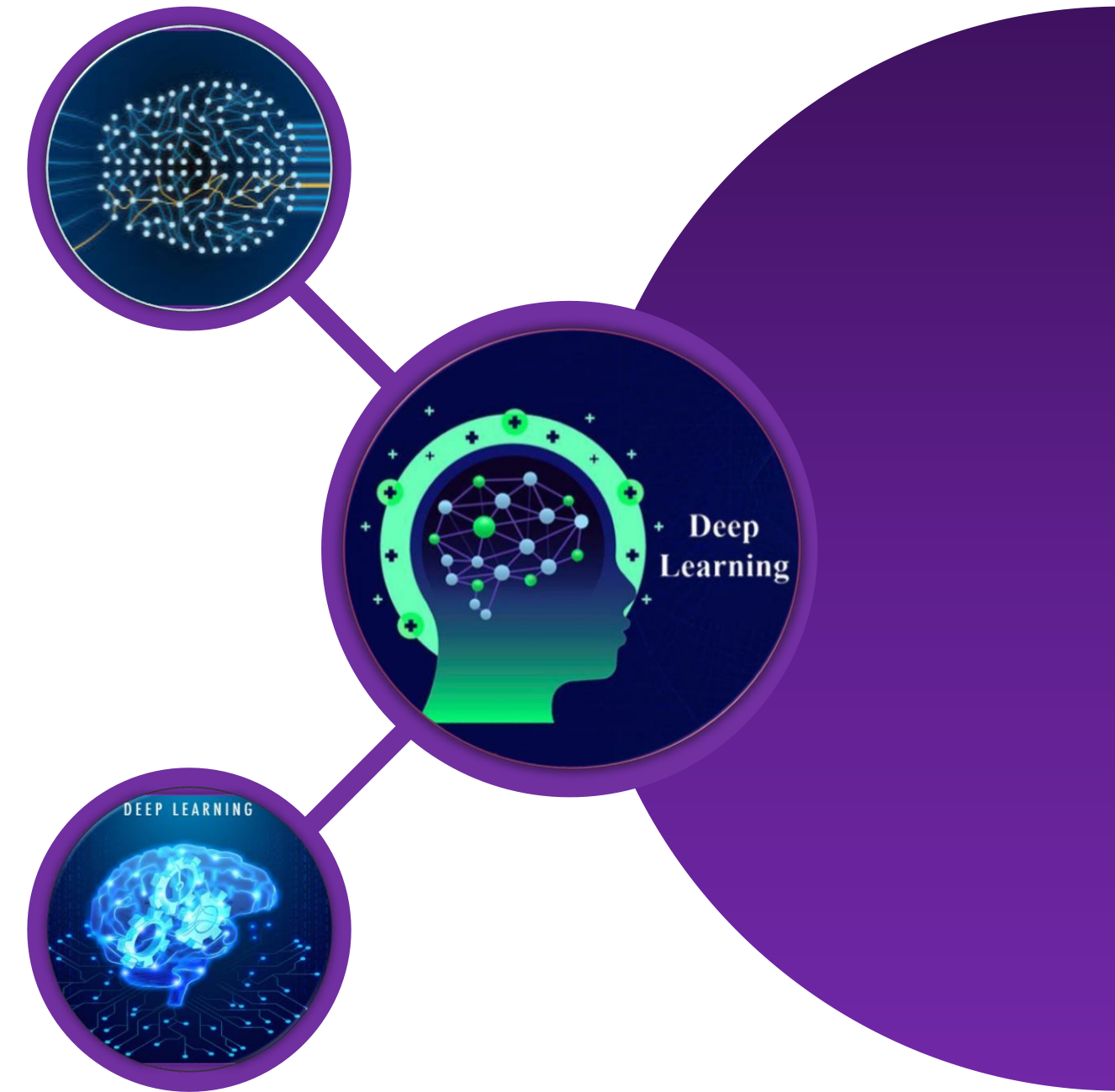
(RNN-LSTM-GRU)



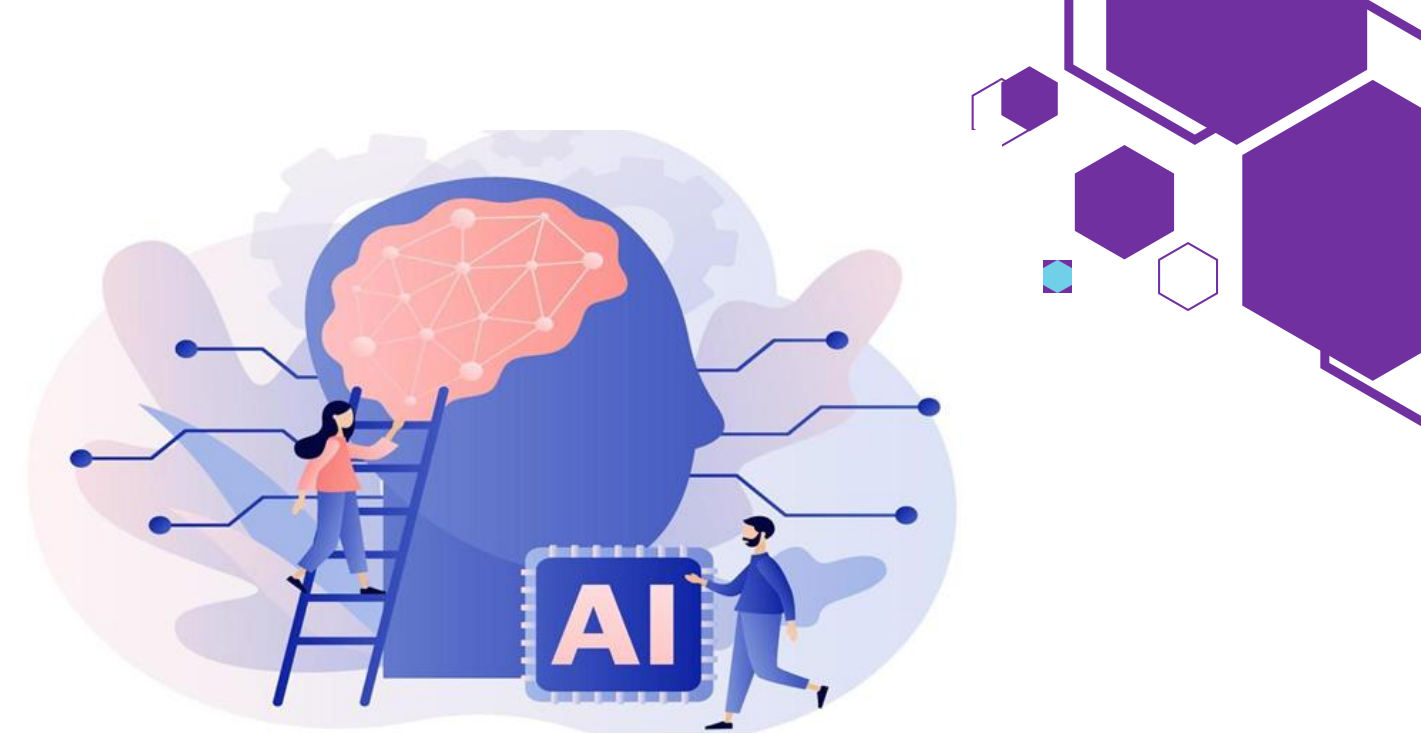


# PRESENTATION CONTENT LIST

- 01 RNN
- 02 LSTM
- 03 GRU
- 04 RNN Topologies

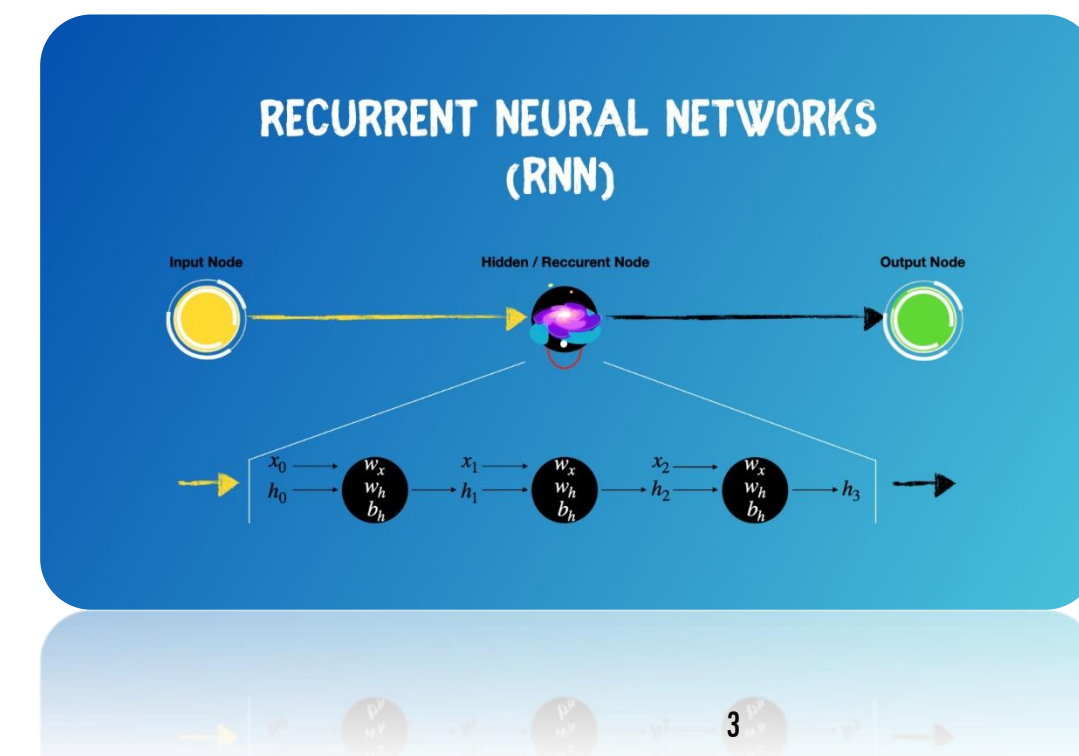
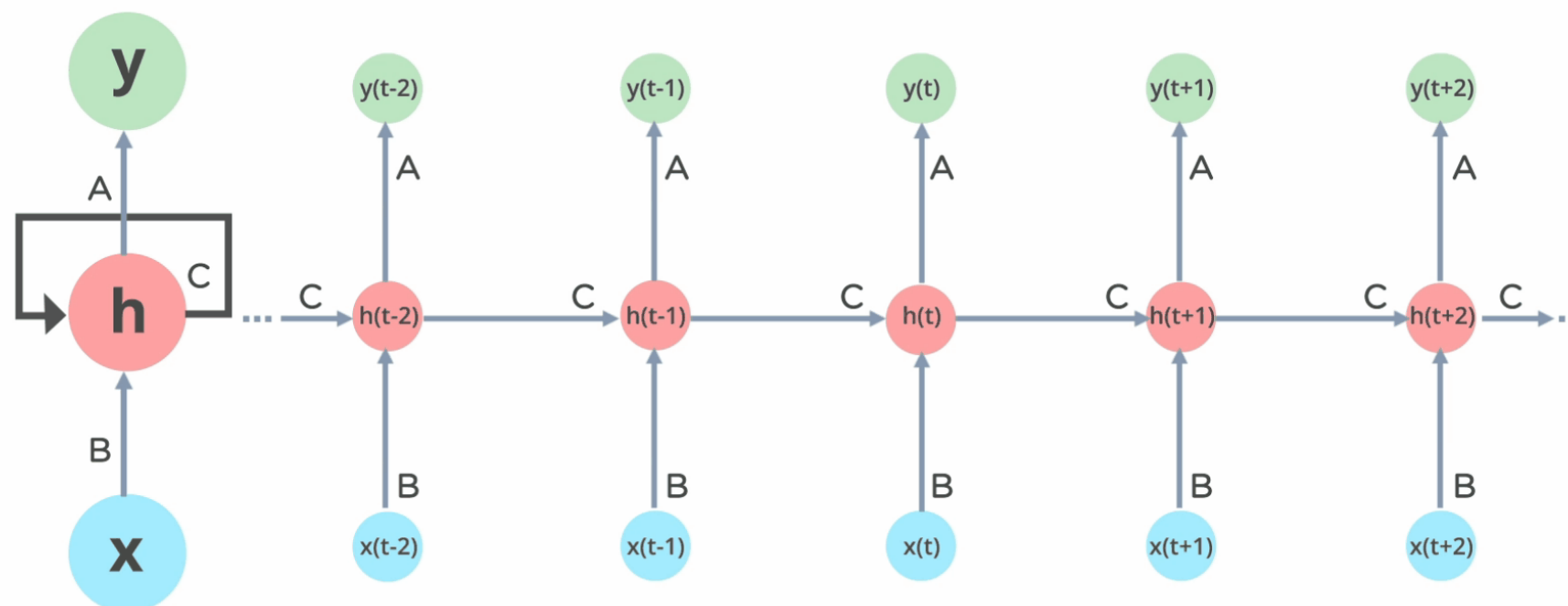


# 01 RNN



Recurrent Neural Networks (RNNs): are a family of networks that are suitable for learning representations of sequential data like text in Natural Language Processing (NLP).

- The idea behind RNNs is to make use of sequential information.
- In a traditional neural network, we assume that all inputs (and outputs) are independent of each other.
- But for many tasks that is a very bad idea. If we want to predict the next word in a sentence, we better know which words came before it.

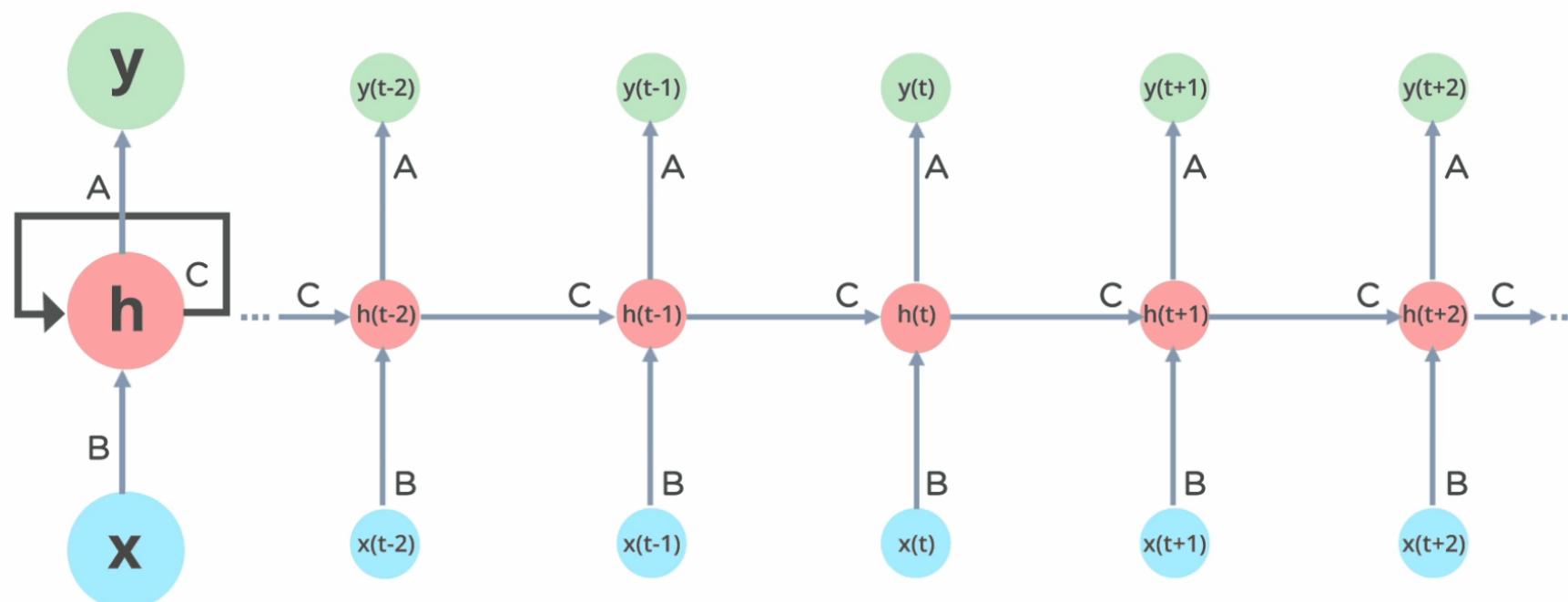


# 01 RNN



Recurrent Neural Networks (RNNs): are a family of networks that are suitable for learning representations of sequential data like text in Natural Language Processing (NLP).

- RNNs are called recurrent because they perform the same task for every element of a sequence, with the output being dependent on the previous computations.
- Another way to think about RNNs is that they have a “memory” which captures information about what has been calculated so far.
- In theory RNNs can make use of information in arbitrarily long sequences, but in practice they are limited to looking back only a few steps.



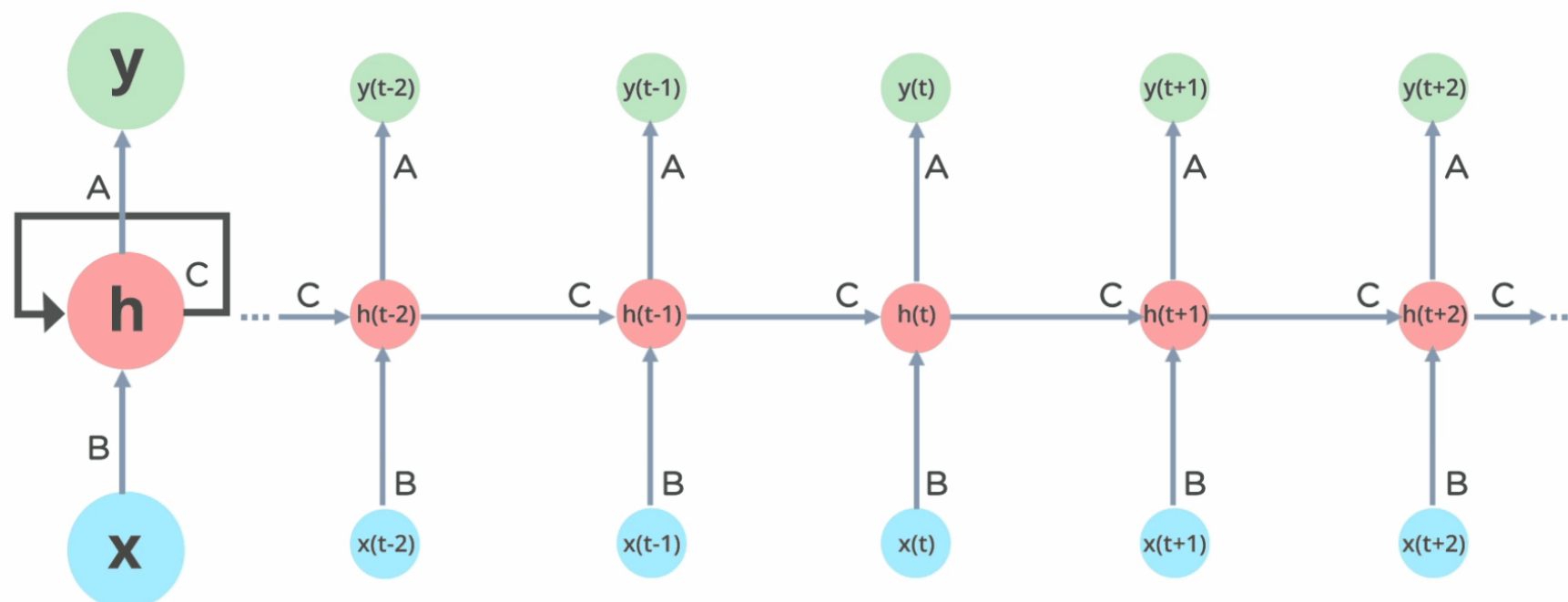


# 01 RNN



Recurrent Neural Networks (RNNs): are a family of networks that are suitable for learning representations of sequential data like text in Natural Language Processing (NLP).

- The above diagram shows a RNN being unrolled (or unfolded) into a full network.
- For example, if the sequence we care about is a sentence of 5 words, the network would be unrolled into a 5-layer neural network, one layer for each word.

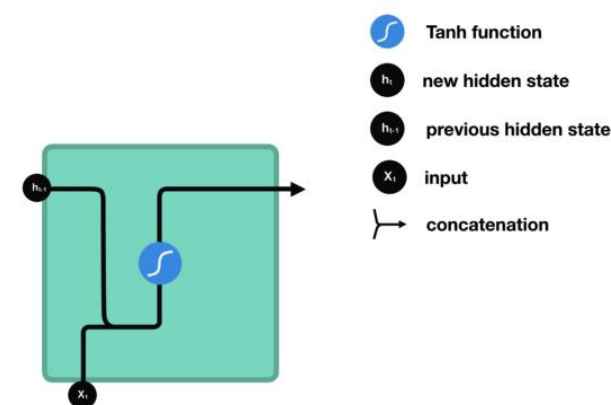


# 01 RNN

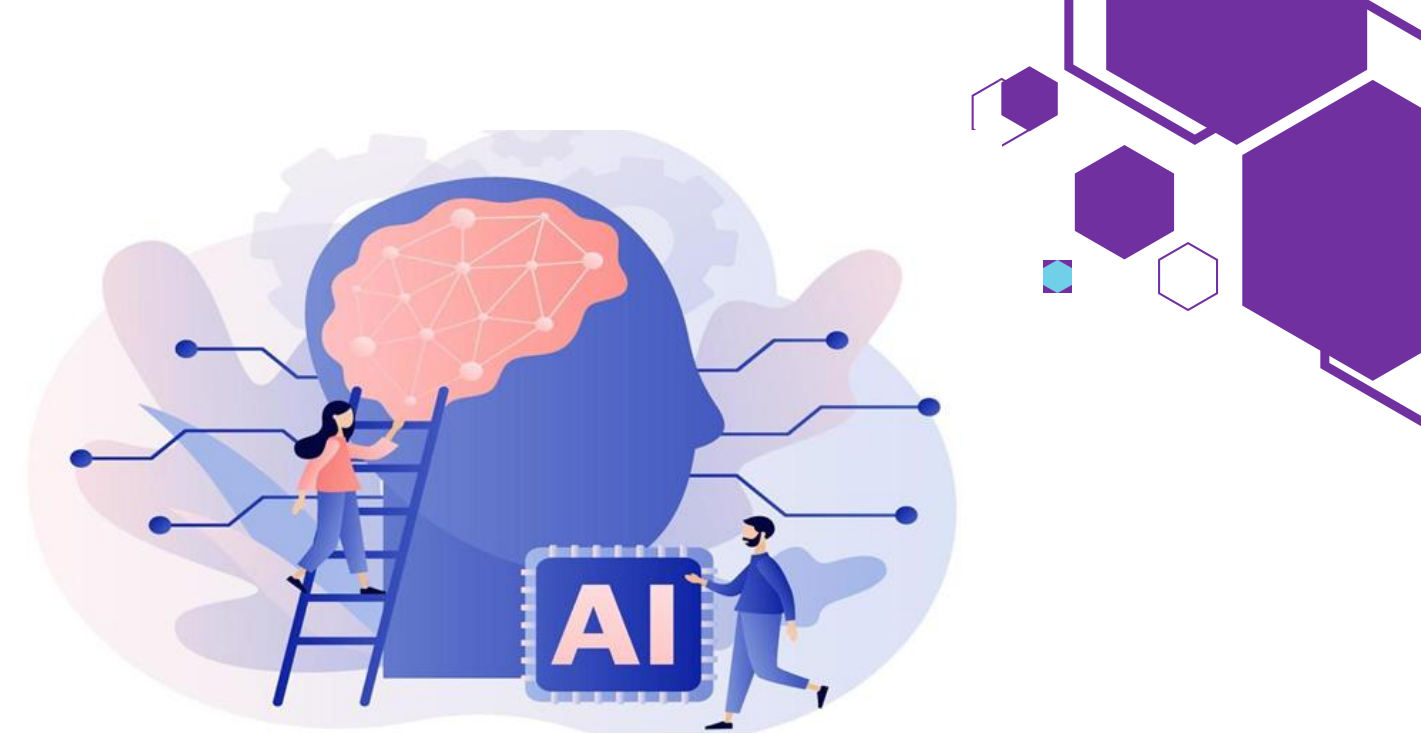


Recurrent Neural Networks (RNNs): are a family of networks that are suitable for learning representations of sequential data like text in Natural Language Processing (NLP).

- Time series data, such as stock prices, also exhibit a dependence on past data, called the secular trend.
- RNN cells incorporate this dependence by having a hidden state, or memory, that holds the essence of the past.
- The value of the hidden state at any point in time is a function of the value of the hidden state at the previous time step and the value of the input at the current time step, that is:  $h_t = \tanh(W * h_{t-1} + U * X_t)$
- $h_t$  and  $h_{t-1}$  are the values of the hidden states at the time steps  $t$  and  $t-1$  respectively, and  $x_t$  is the value of the input at time  $t$ .
- The above equation is recursive, that is,  $h_{t-1}$  can be represented in terms of  $h_{t-2}$  and  $x_{t-1}$ , and so on, until the beginning of the sequence.



# 01 Vanishing gradient



When doing back propagation, each node in a layer calculates its gradient with respect to the effects of the gradients in the layer before it.

- Just like traditional neural networks, training the RNN also involves backpropagation.
- The difference in this case is that since the parameters are shared by all time steps, the gradient at each output depends not only on the current time step, but also on the previous ones.
- This process is called backpropagation through time (BPTT).
- Regular RNNs might have a difficulty in learning long range dependencies.
- This kind of dependencies between sequence data is called long-term dependencies because the distance between the relevant information and the point where it is needed to make a prediction is very wide.
- **RNNs can't learn long-range dependencies!**

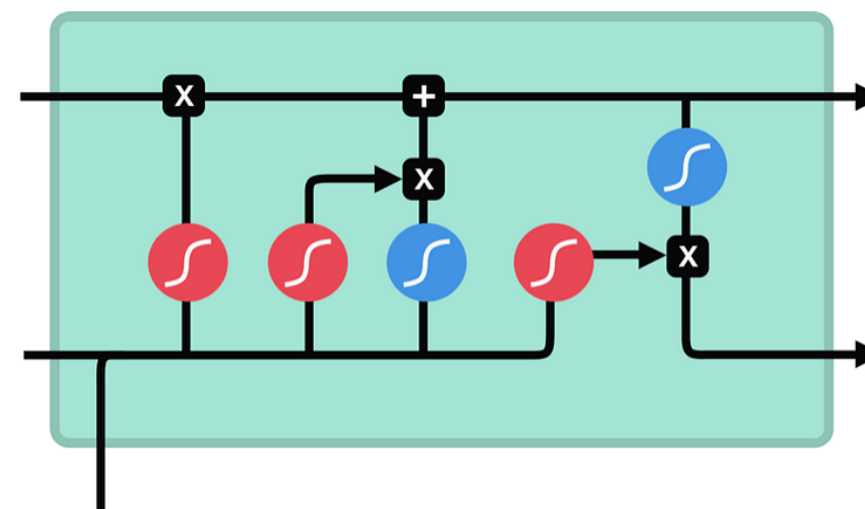


## 02 LSTM



Similar in nature to RNNs but have additional features to help fight the short-term memory issue of RNNs.

While there are a few approaches to minimize the problem of vanishing gradients, such as proper initialization of the  $W$  matrix, using a ReLU instead of tanh layers, and pre-training the layers using unsupervised methods, the most popular solution is to use the LSTM or GRU architectures.



sigmoid



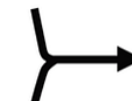
tanh



pointwise  
multiplication



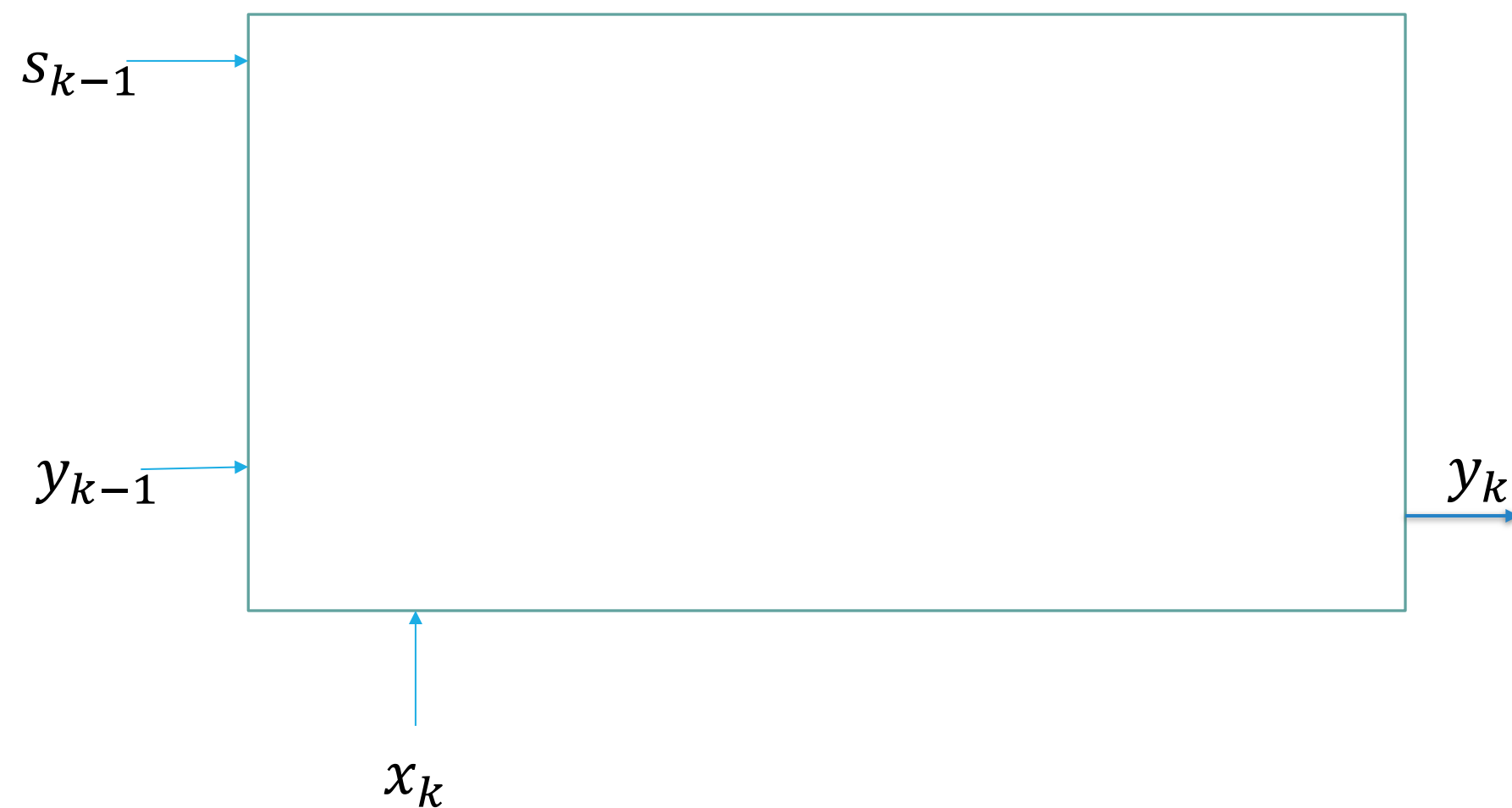
pointwise  
addition



vector  
concatenation

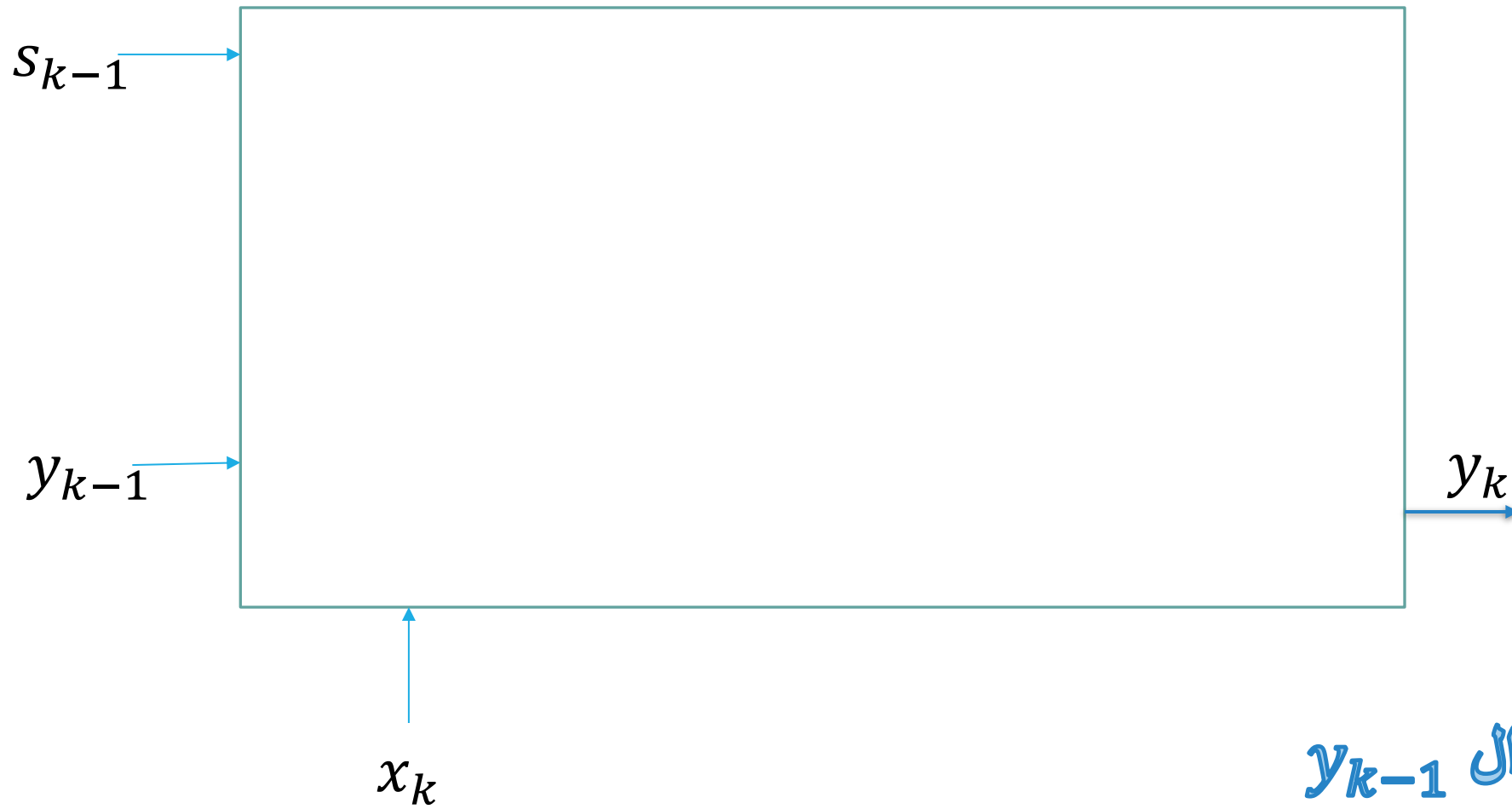


## 02 LSTM



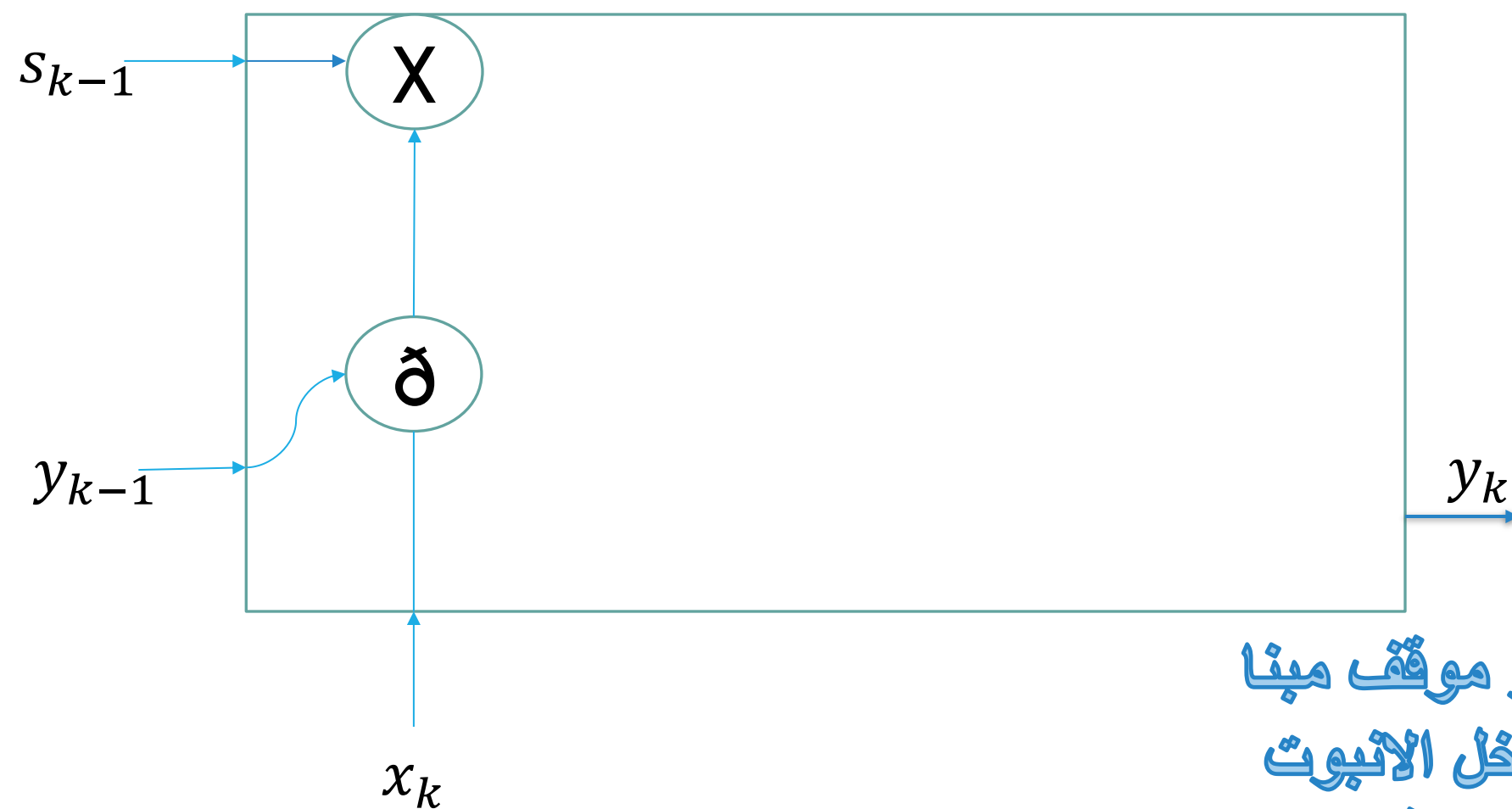
- انا دلوقتي عايز اخذ قرار معين  $y_k$   
القرار ده هيعتمد على 3 حاجات:
- 1- الانبوت اللي جايلى  $x_k$  الى انا شايفه دلوقتي
  - 2- اخر قرار انا اخدته  $y_{k-1}$
  - 3- وكل القرارات اللي اخدتها قبل كده ال history بتاعي يعني  $s_{k-1}$

## 02 LSTM



- 1- وليكن قولتك فلان يقول عليك كلام وحش يبقى ده ال  $x_k$
- 2- فلان ده انا اخر موقف كان معاه كان ايه موقف رجوله ولا بيع ده ال  $y_{k-1}$
- 3- طب تعالى بقى نرجع بالذاكره ونقلب في الماضي كل اللي فات مبينى ومبينوا كان عامل ايه ده ال  $s_{k-1}$  يبقى هتربط الموقف اللي حصل دلوقتي باخر موقف حصل وبكل المواقف القديمه اللي مبنكوا من يوم معرفته وعلى اساسه هاخذ قرار الى هو مثلا عفا الله عما سلف ولا اقطع علاقتي بيه ولا احذو من التعامل بس معاه ولا ايه

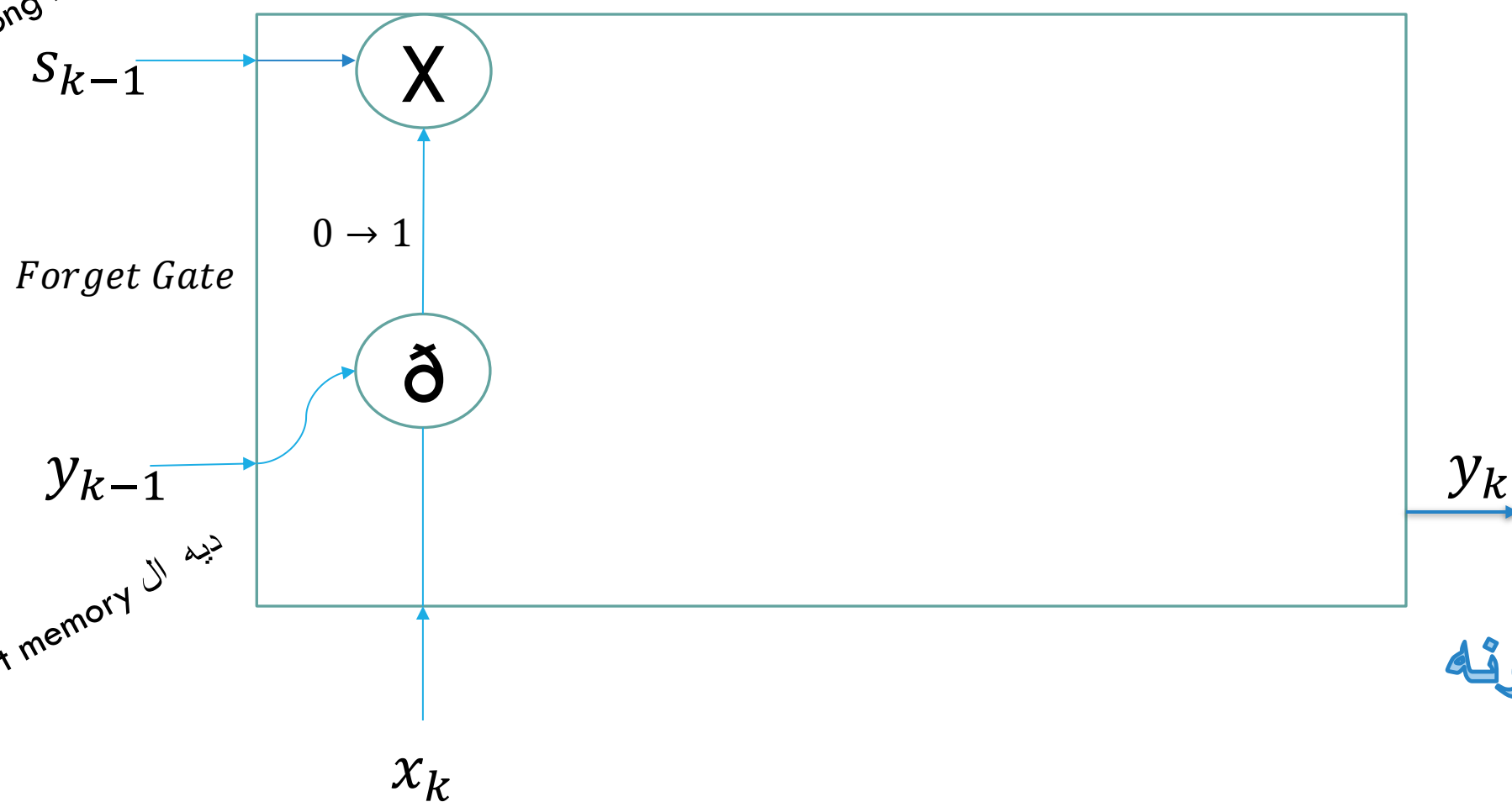
## 02 LSTM



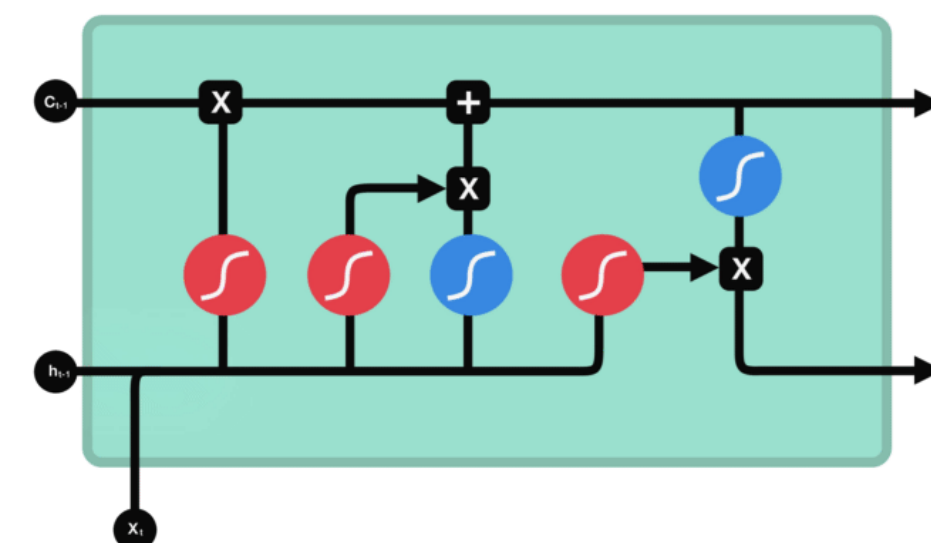
اكثر حاجة هيبقى ليها تأثير على قرارى هيبقى الكلام اللى جايلى واخر موقف مبنا  
انما التاريخ الأسود اللى مبنا مش هيبقى ليه تأثير قوى عشان كده مدخل الانبوت  
والاوت السابق على sigmoid بحيث اشوف التاريخ الأسود هياثر بنسبه قد ايه  
مش يمكن الموقف اللى حصل واخر موقف مبنا يعينى انى اشوف التاريخ  
فالانبوت بتاع ال sigmoid وقتها هيبقى بصفر فمش هبص عاليستورى واقطع علاقتى بيه

## 02 LSTM

دیه ال long memory



دیه ال short memory



$C_{t-1}$  previous cell state  
 $f_t$  forget gate output

بما ان دیه بتعتمد علی انی هآخذ قد ایه من الذکرایات والحآجات المدفونه  
 فهنسمیها forget gate

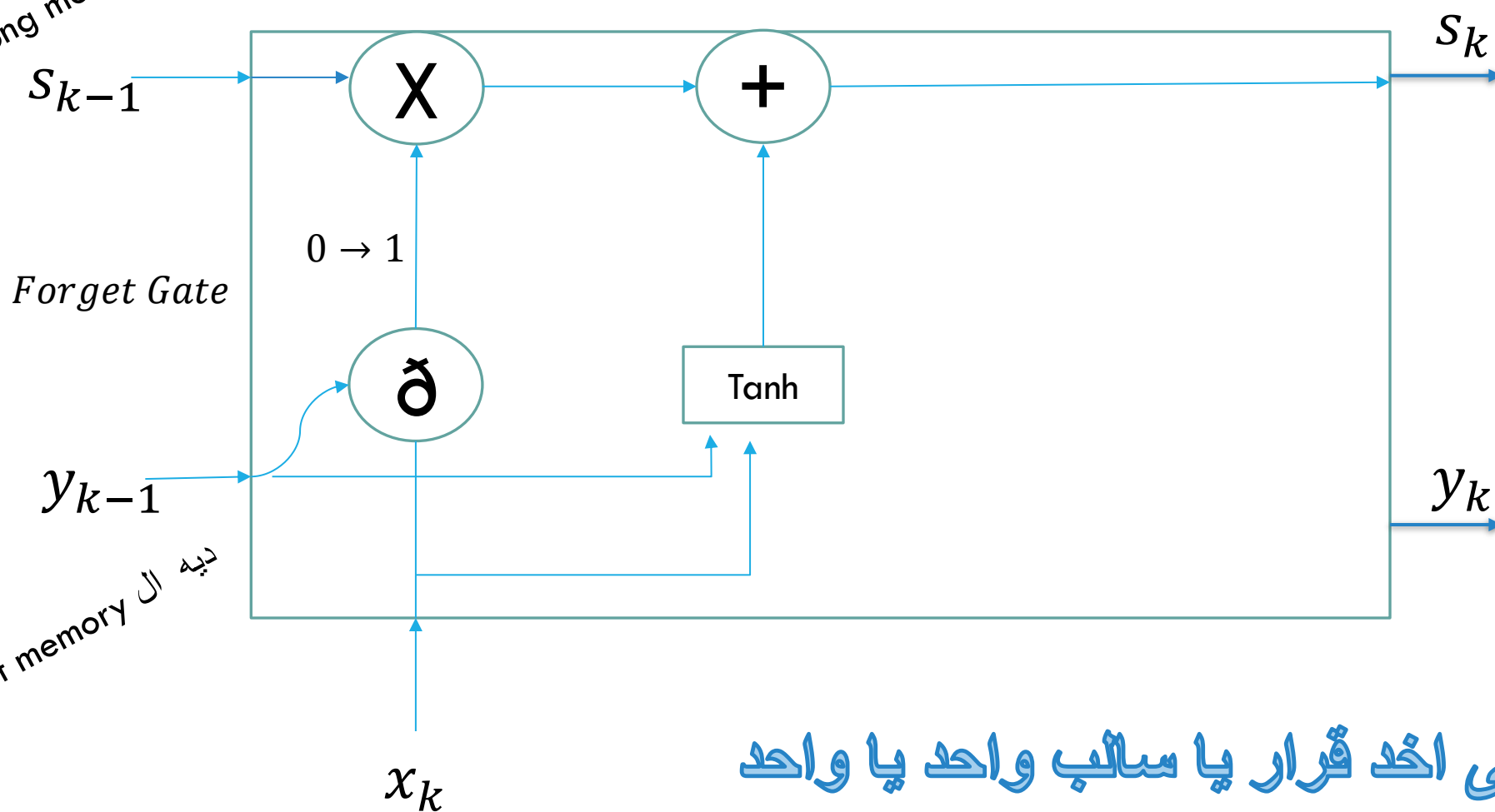
- **Forget gate:** Information from the previous hidden state and information from the current input is passed through the sigmoid activation function.
- Values come out between 0 and 1
- Decides what information should be thrown away or kept



## 02 LSTM

ديه ال long memory

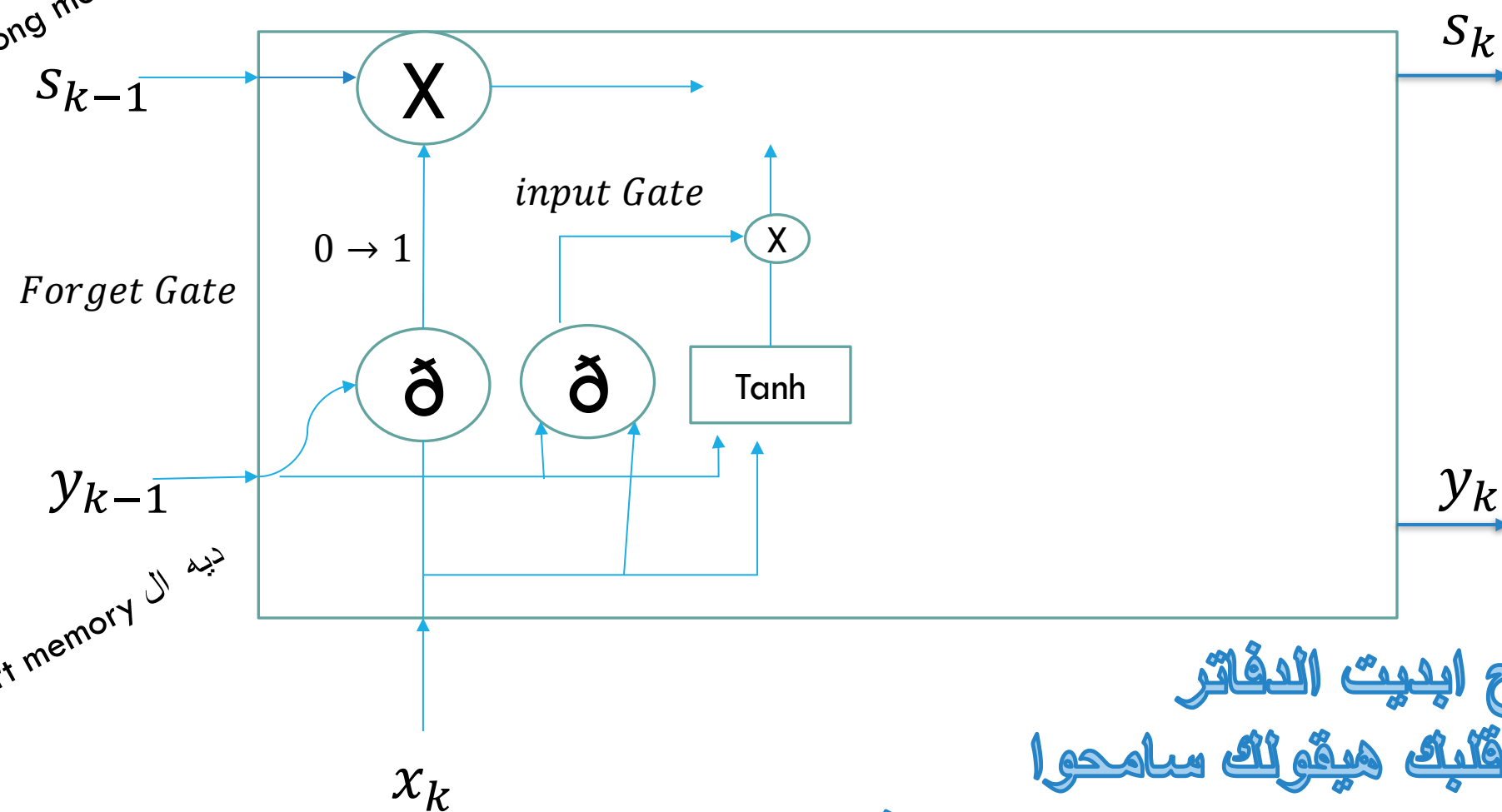
ديه ال short memory



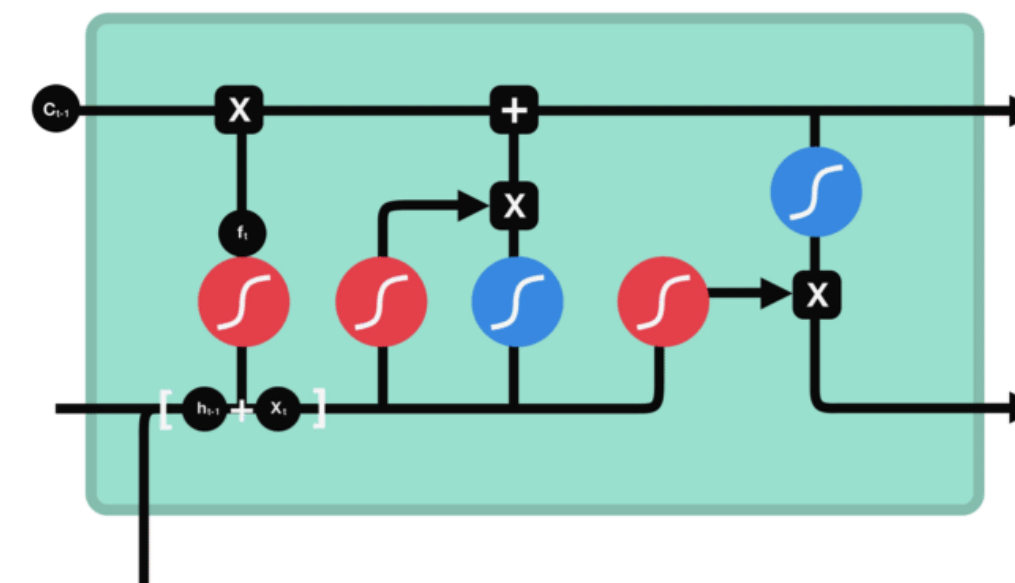
دلوقتى عايز اكون ال state الجديده بمعنى بايديت الدفاتر القديمه  
فهاخد الانيوت والاوئيوت القديم وادخلهم على tanh ديه اللى هتخلينى اخذ قرار يا سالب واحد يا واحد  
فهاخد القرار ده اجمعوا على الاوئيوت اللى جايلى من ال history

## 02 LSTM

ديه ال long memory



ديه ال short memory



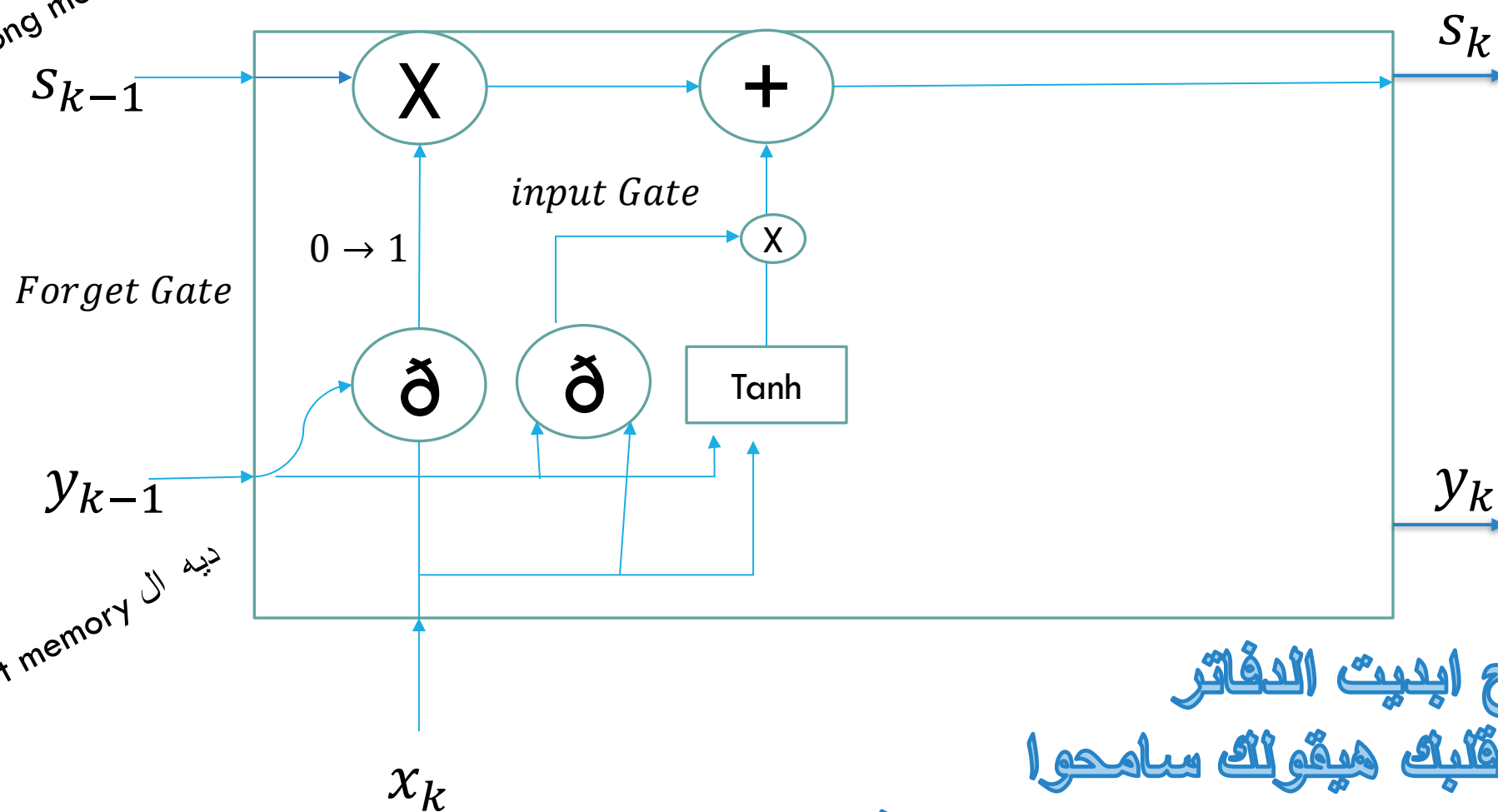
- $C_{t-1}$  previous cell state
- $f_t$  forget gate output
- $i_t$  input gate output
- $C_t$  candidate

مين قال يعنى ان انت بناء على اللي انت شايفه والموقف الماضى روح ابديت الدفاتر  
فانا طيب حبتين فالقرار بتاع ال tanh اللي هيقللى اقطع علاقتك بيه قلبك هيقلوك سامحوا  
فهاخد الانبوت الحالي والابوت السابق وادخله على sigmoid جديده اخلى الابوت بتاعها يضرب في اوت التانش  
فديه هسميها input gate الى هو انبوت جديد للتاريخ بتاعى

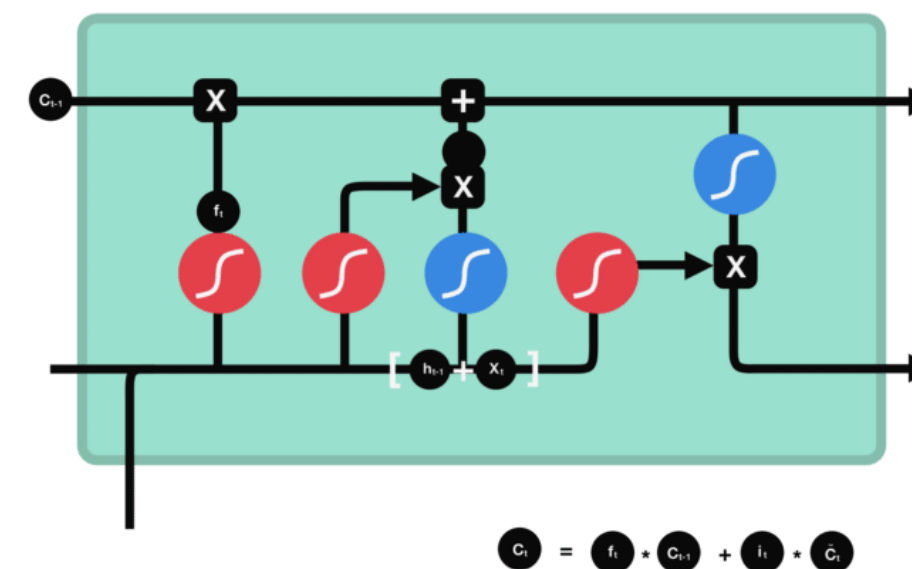
- Input gate  
Decides what new information we're going to store in the cell state

## 02 LSTM

ديه ال long memory



ديه ال short memory



- $C_{t-1}$  previous cell state
- $f_t$  forget gate output
- $i_t$  input gate output
- $\tilde{C}_t$  candidate
- $C_t$  new cell state

$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

مين قال يعنى ان انت بناء على اللي انت شايفه والموقف الماضى روح ابديت الدفاتر  
فانا طيب حبتين فالقرار بتاع ال tanh اللي هيقللى اقطع علاقتك بيه قلبك هيقلوك سامحوا  
فهاخد الانبوت الحالي والابوت السابق وادخله على sigmoid جديده اخلى الابوت بتاعها يضرب في اوت التانش  
فديه هسميها input gate الى هو انبوت جديد للتاريخ بتاعى

- Cell state

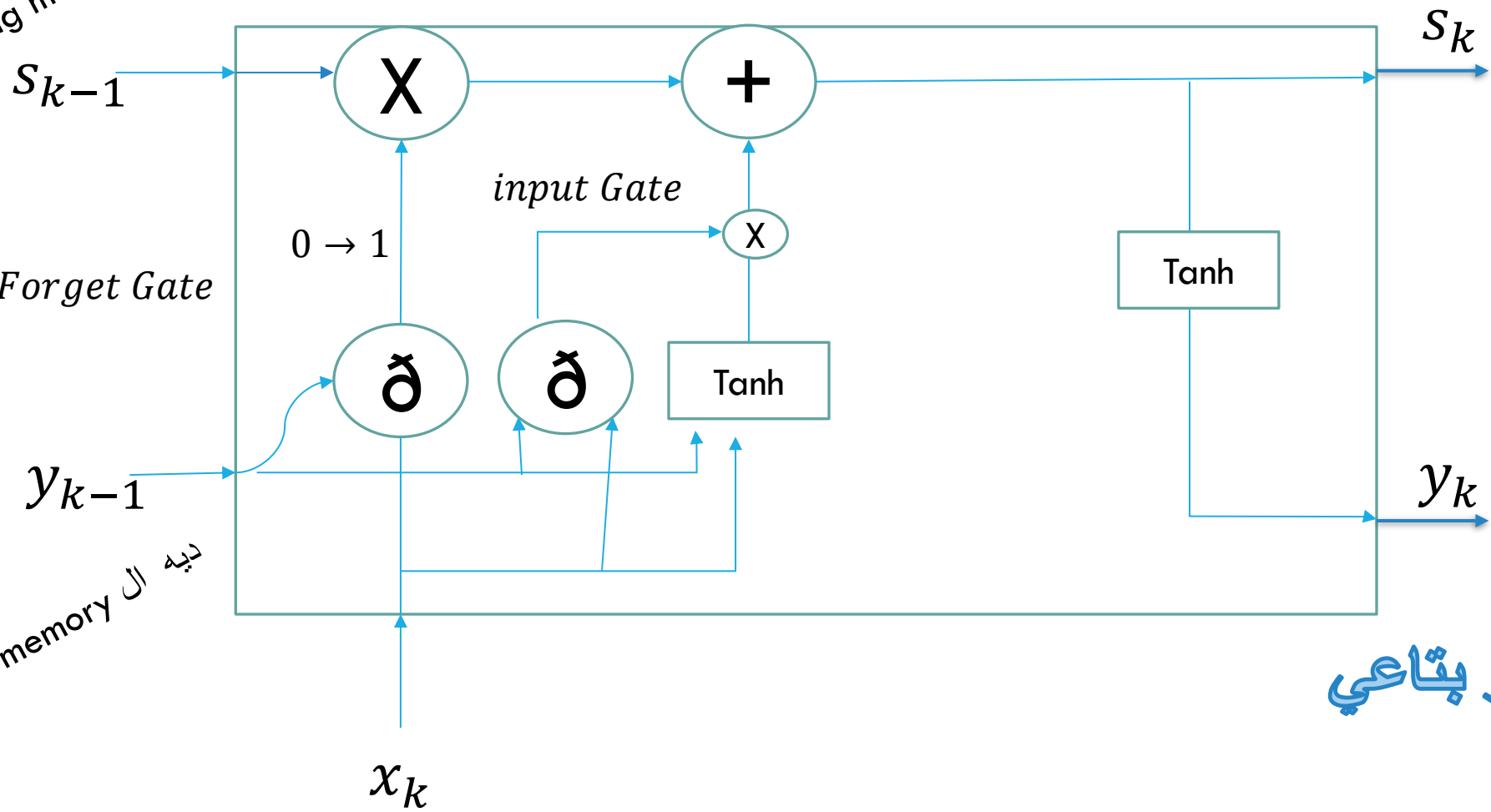
Use outputs of previous gates to update current cell state

## 02 LSTM

دیه ال long memory

Forget Gate

دیه ال short memory

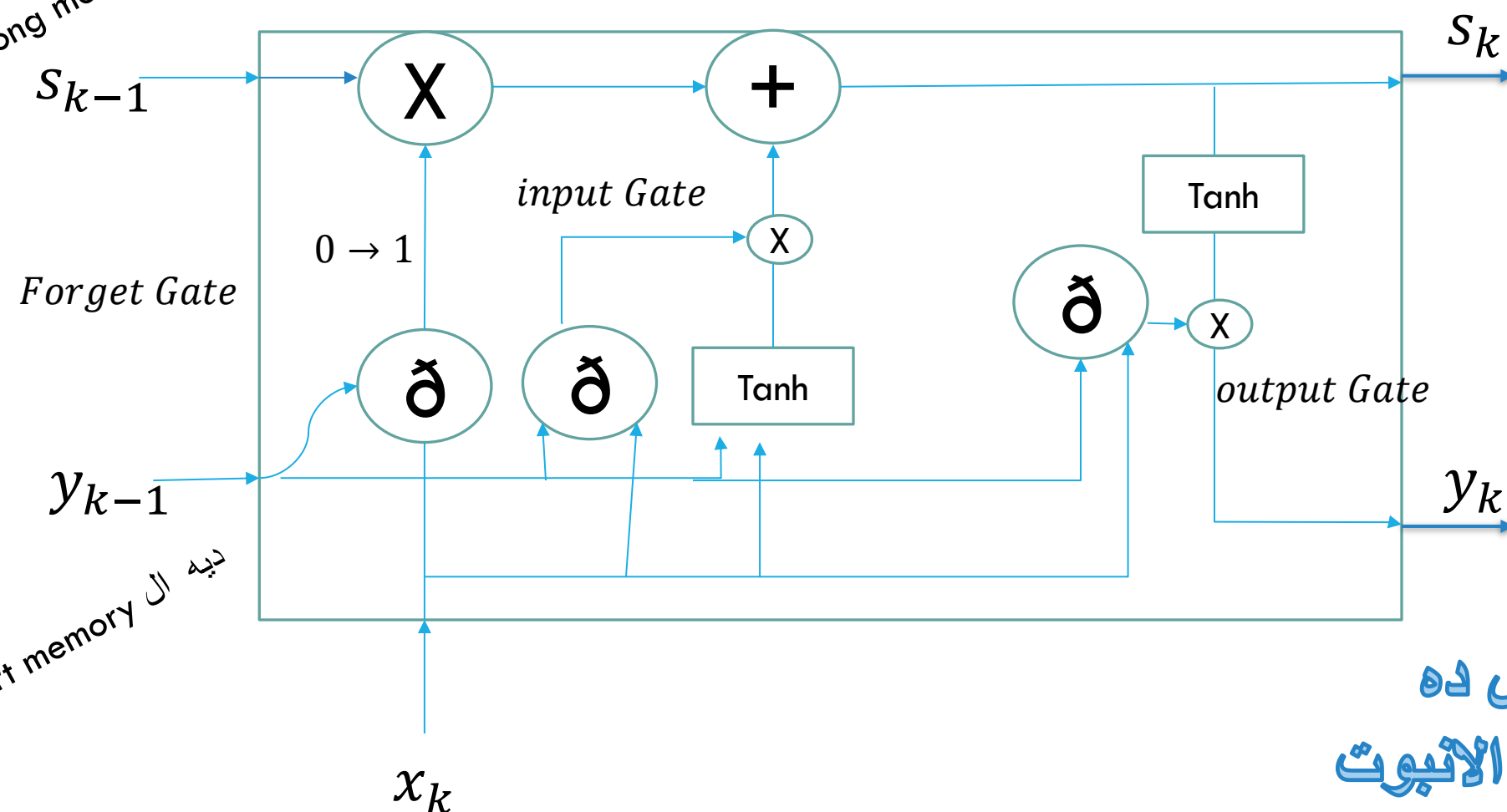


بما ان دیه مساعده ان انا اخذ قرار فلیه مطلعش منها الاوتیوت القرار بتاعي  
یعنی ادخلوا على tanh بالشکل ده

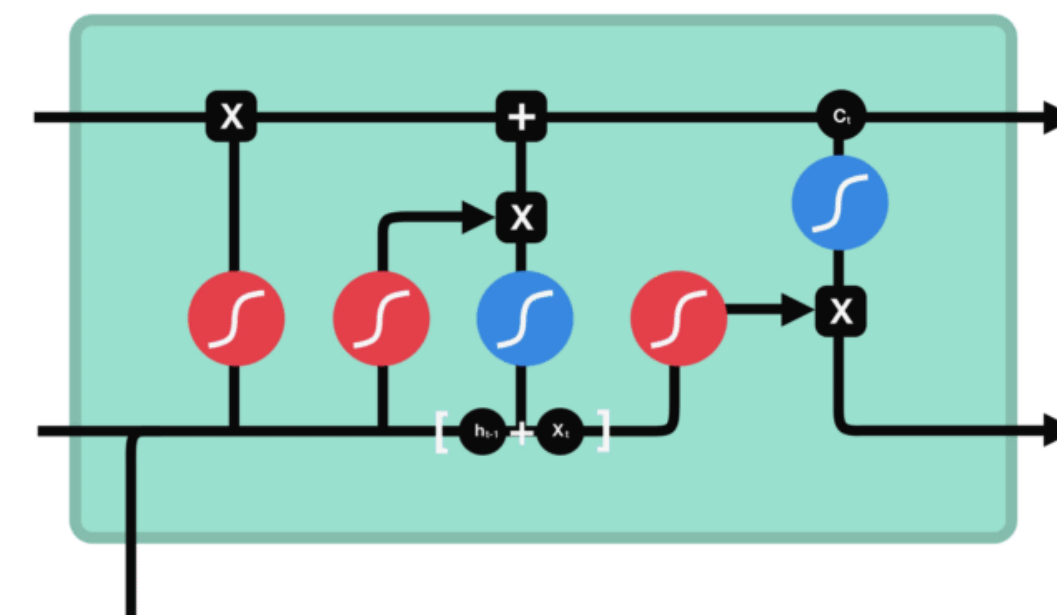


## 02 LSTM

ديه ال long memory



ديه ال short memory

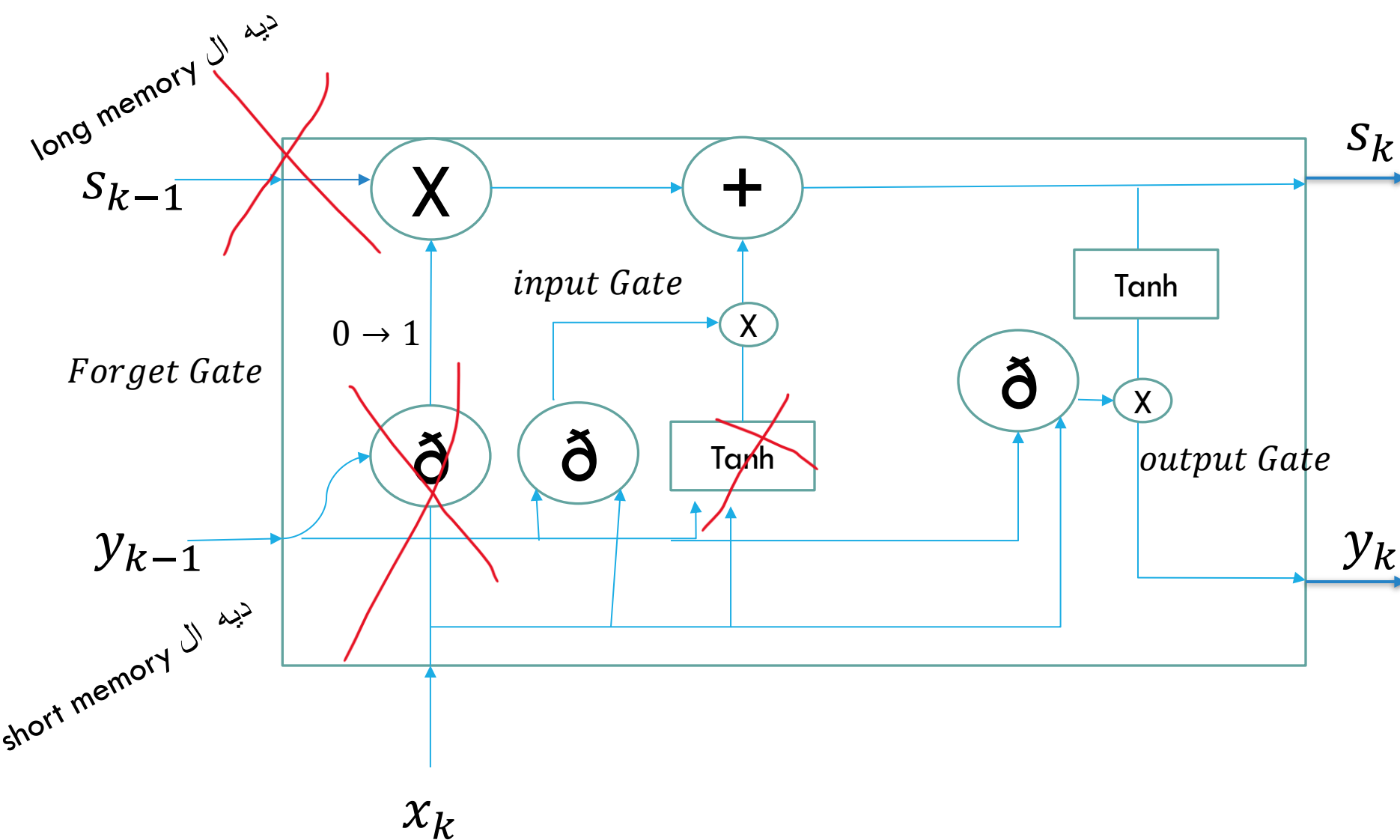


- $C_{t-1}$  previous cell state
- $f_t$  forget gate output
- $i_t$  input gate output
- $c_t$  candidate
- $C_t$  new cell state
- $o_t$  output gate output
- $h_t$  hidden state

بما ان ديه مساعده ان انا اخذ قرار فليه مخلص منها الاوتبوت بالشكل ده  
 قلبك الحنين هيقلوك لا القرار اللى اخدته متاخدوش كله فرجت اخدت الاوتبوت  
 مع الاوتبوت السابق دخلتهم على sigmoid وضربت الناتج في القرار بتاعى  
 ديه اللى هي ال output gate يتاعى.

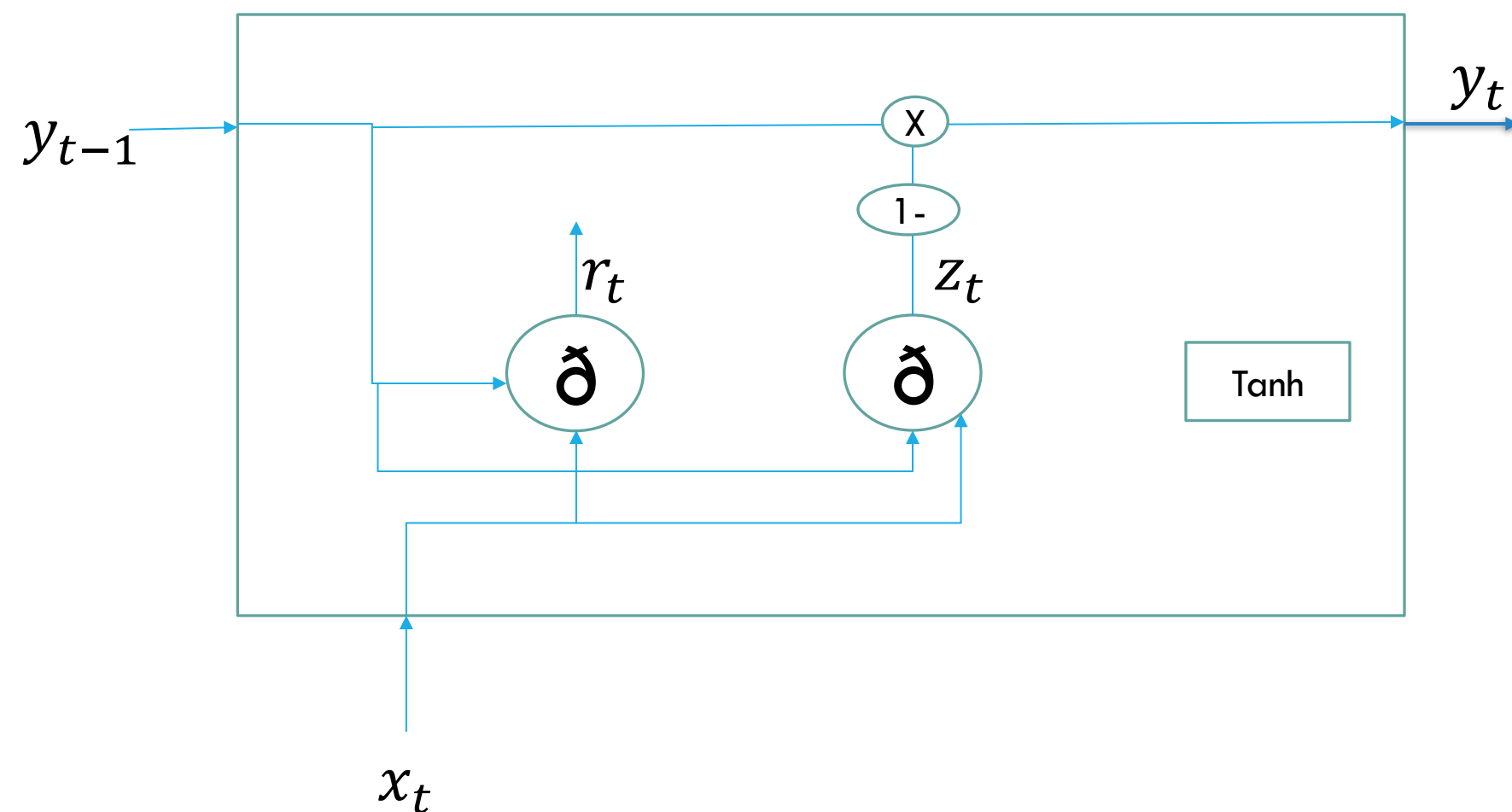
- Output gate  
 Decides what new information to pass along as our hidden state

# 03 GRU



طب لیه التعقید ده کله مش ممکن أقول بس ان  $y_k = F(x_k, y_{k-1})$  وکده کده ال  $y_{k-1}$  بتعتمد علی ال  $y_{k-2}$  وهکذا....  
 یبقی هنلغی الجزء بتاع ال history وبتابعیه هنلغی جزء ال sigmoid بتاعه  
 وکمان جزء ال tanh الی کان پیادیت ال history

# 03 GRU

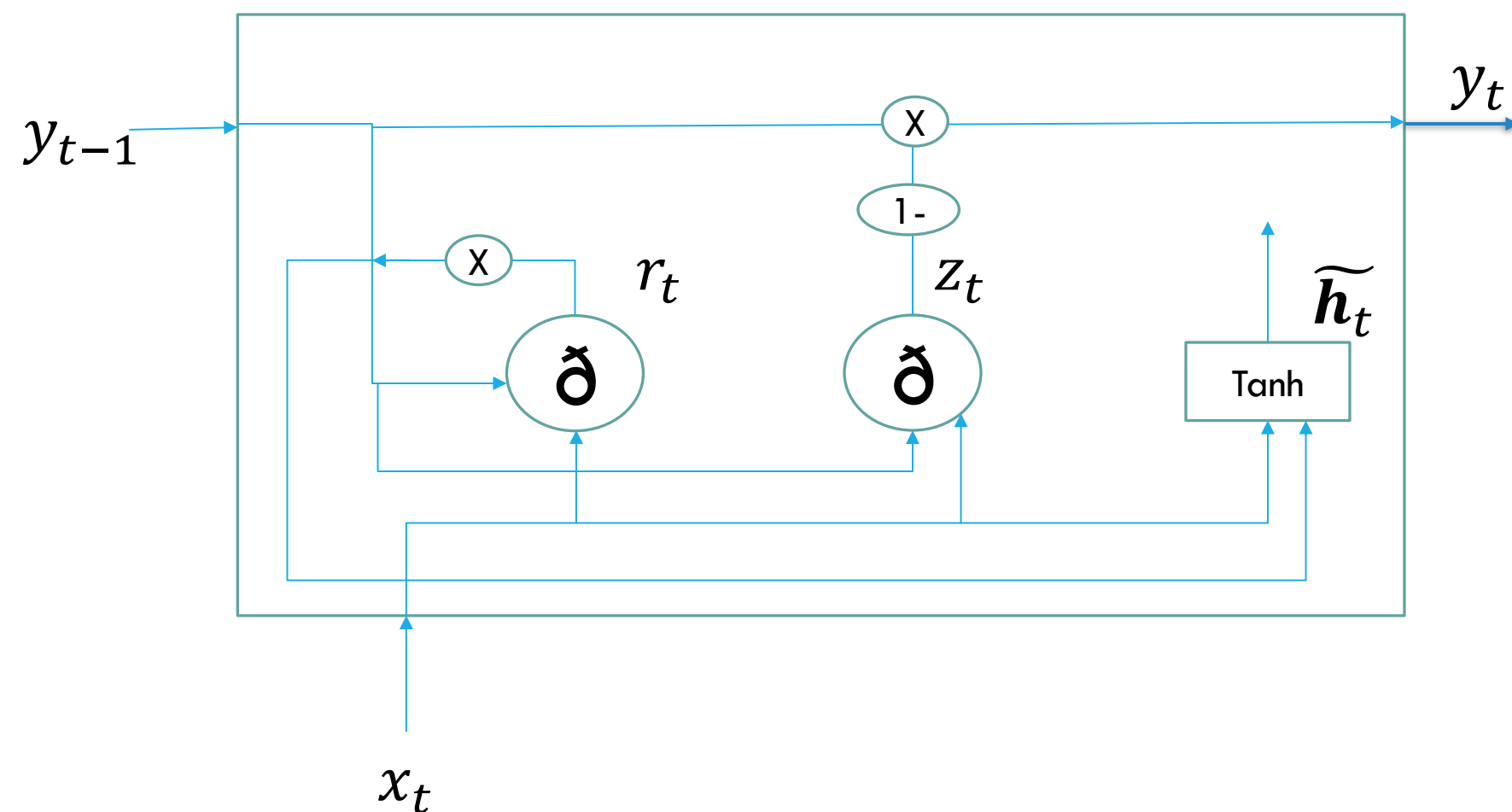


$$z_t = \delta(y_{t-1}, x_t)$$

$$r_t = \delta(y_{t-1}, x_t)$$

طب ليه التعقيد ده كله مش ممكن أقول بس ان  $y_t = F(x_t, y_{t-1})$  وكده كده ال  $y_{t-1}$  بتعتمد على ال  $y_{t-2}$  وهكذا....  
 يبقى هنلغي الجزء بتاع ال history وبالتالي هنلغي جزء ال sigmoid بتاعه  
 وكمان جزء ال tanh اللى كان بيأيدت ال history

# 03 GRU



$$z_t = \delta(y_{t-1}, x_t)$$

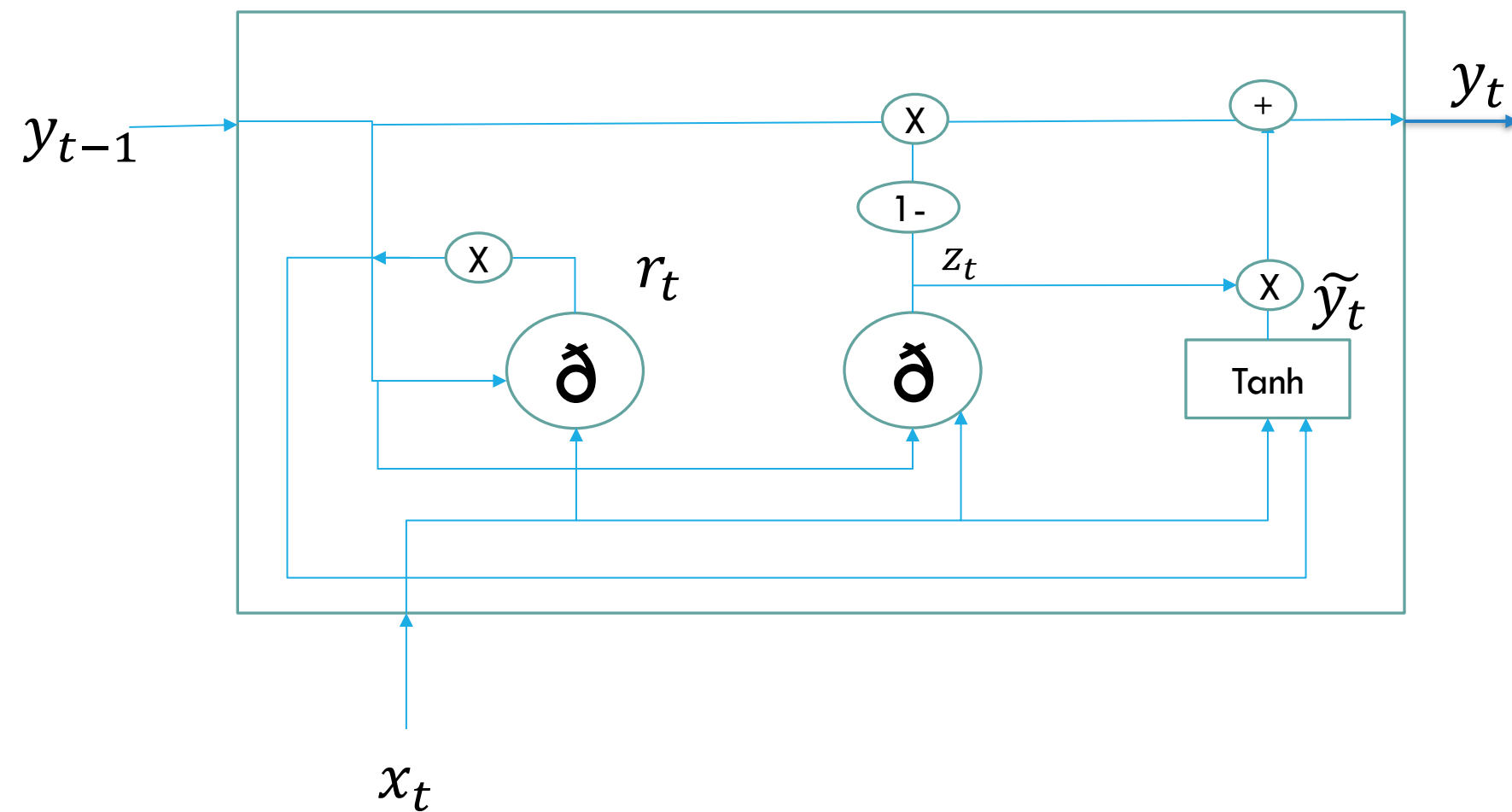
$$r_t = \delta(y_{t-1}, x_t)$$

$$\tilde{h}_t = \tanh(r_t * y_{t-1}, x_t)$$

طب ليه التعقيد ده كله مش ممكن أقول بس ان  $y_t = F(x_t, y_{t-1})$  وكده كده ال  $y_{t-1}$  بتعتمد على ال  $y_{t-2}$  وهكذا....  
يبقى هنلغي الجزء بتاع ال history وبالتالي هنلغي جزء ال sigmoid بتاعه  
وكمان جزء ال tanh اللي كان بيأيدت ال history



# 03 GRU

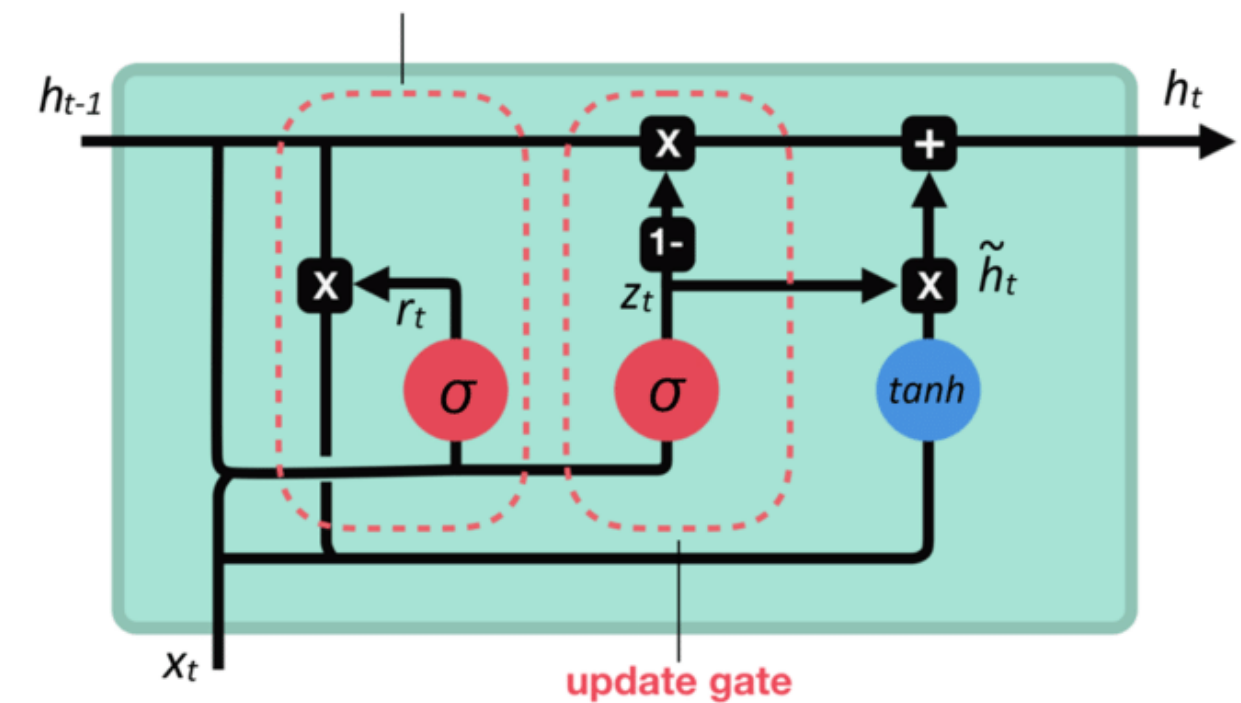
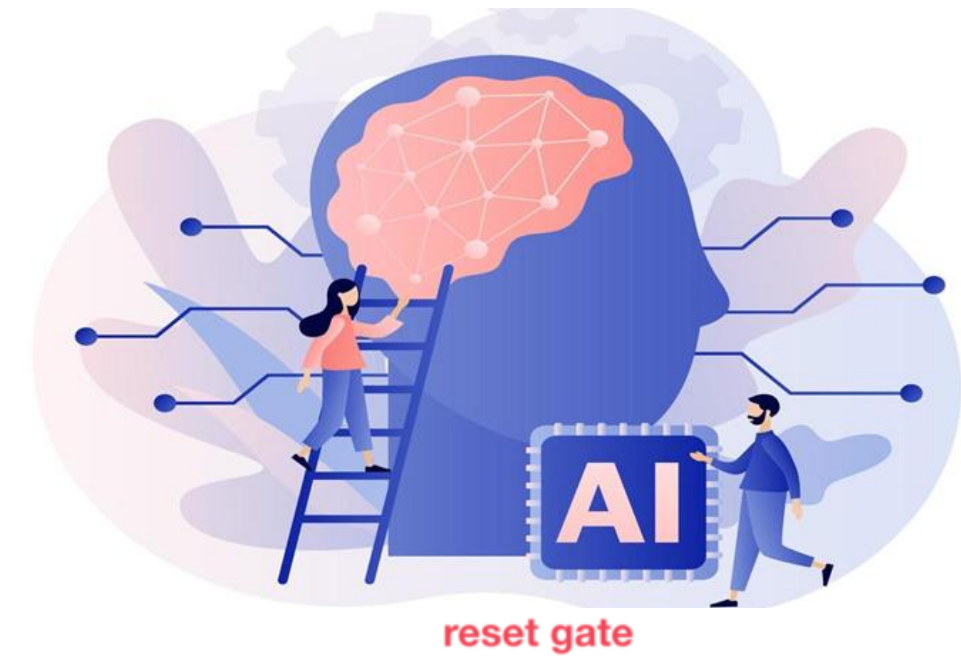


$$z_t = \delta(y_{t-1}, x_t)$$

$$r_t = \delta(y_{t-1}, x_t)$$

$$\tilde{y}_t = \tanh(r_t * y_{t-1}, x_t)$$

$$y_t = (1 - z_t) * y_{t-1} + z_t * \tilde{y}_t$$



طب ليه التعقيد ده كله مش ممكن أقول بس ان  $y_t = F(x_t, y_{t-1})$

وكده كده ال  $y_{t-1}$  بتعتمد على ال  $y_{t-2}$  وهكذا....

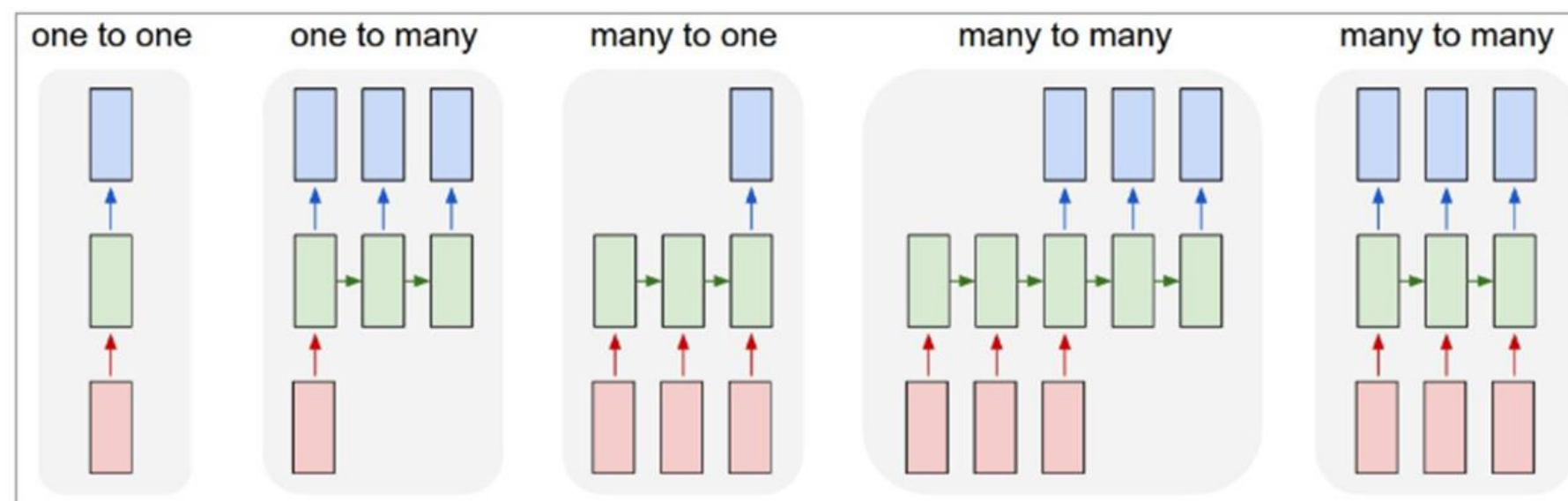
يبقى هنلغي الجزء بتاع ال history وبالتالي هنلغي جزء ال sigmoid بتاعه

وكمان جزء ال tanh اللى كان بيأيدت ال history

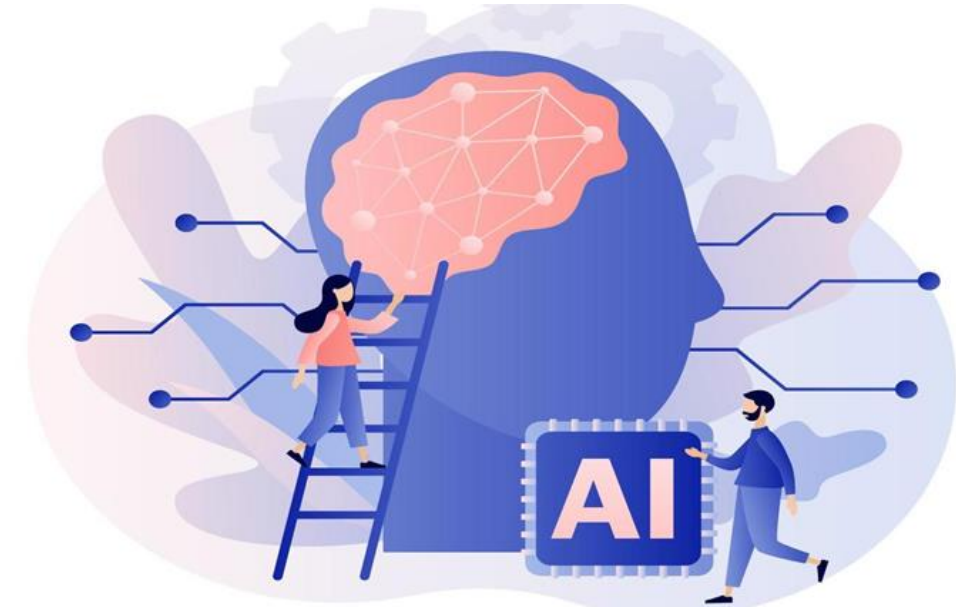
# 01 RNN topologies



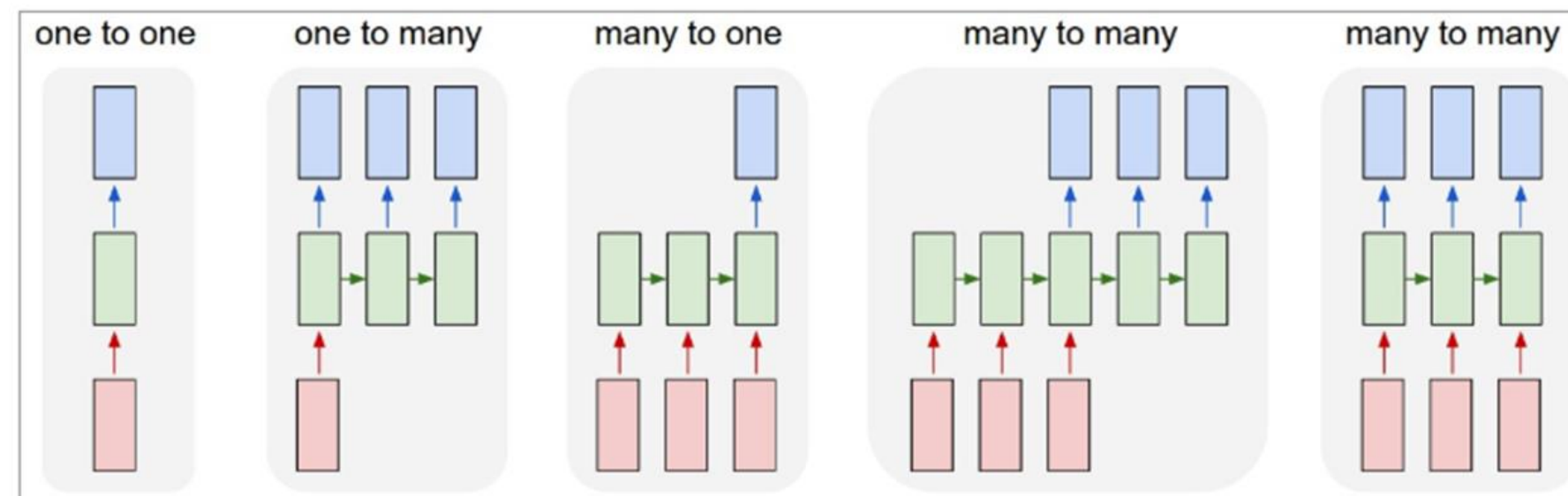
- The APIs for MLP and CNN architectures are limited. Both architectures accept a fixed-size tensor as input and produce a fixed-size tensor as output; and they perform the transformation from input to output in a fixed number of steps given by the number of layers in the model.
- RNNs don't have this limitation—you can have sequences in the input, the output, or both. This means that RNNs can be arranged in many ways to solve specific problems.
- RNNs combine the input vector with the previous state vector to produce a new state vector. This can be thought of as similar to running a program with some inputs and some internal variables.



# 01 RNN topologies



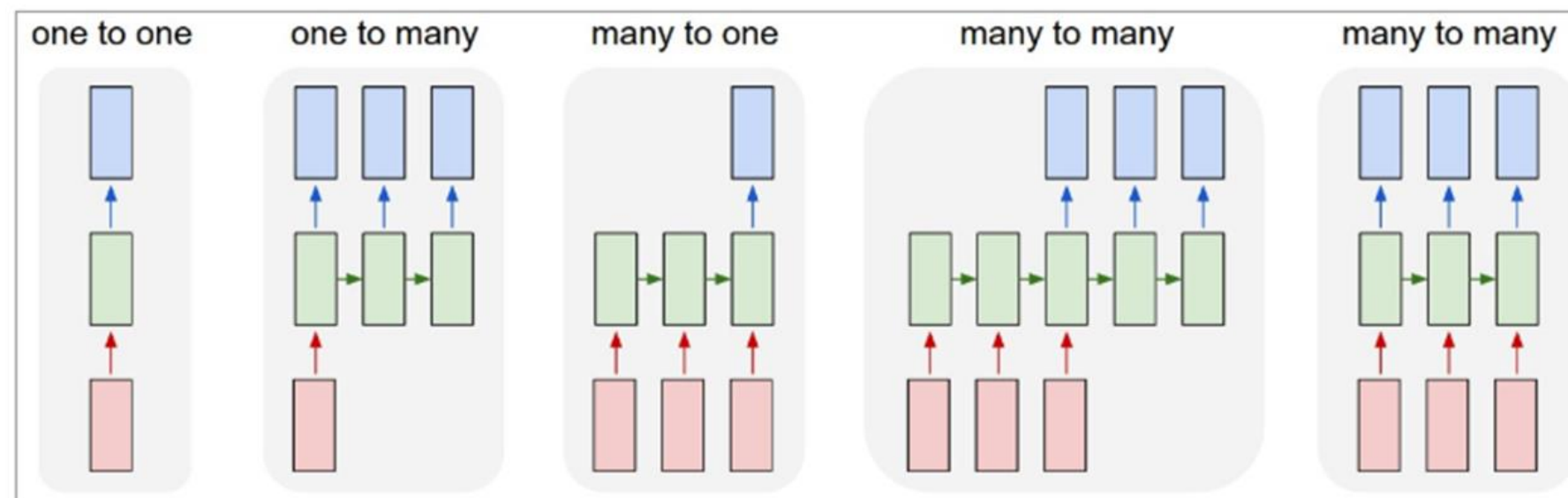
- The RNNs are more exciting because they allow us to operate over sequences of vectors: Sequences in the input, the output, or in the most general case both.
- This property of being able to work with sequences gives rise to a number of common topologies shown below:
- In the above diagram each rectangle is a vector and arrows represent functions (e.g. matrix multiply).
- Input vectors are in red, output vectors are in blue and green vectors hold the RNN's state.



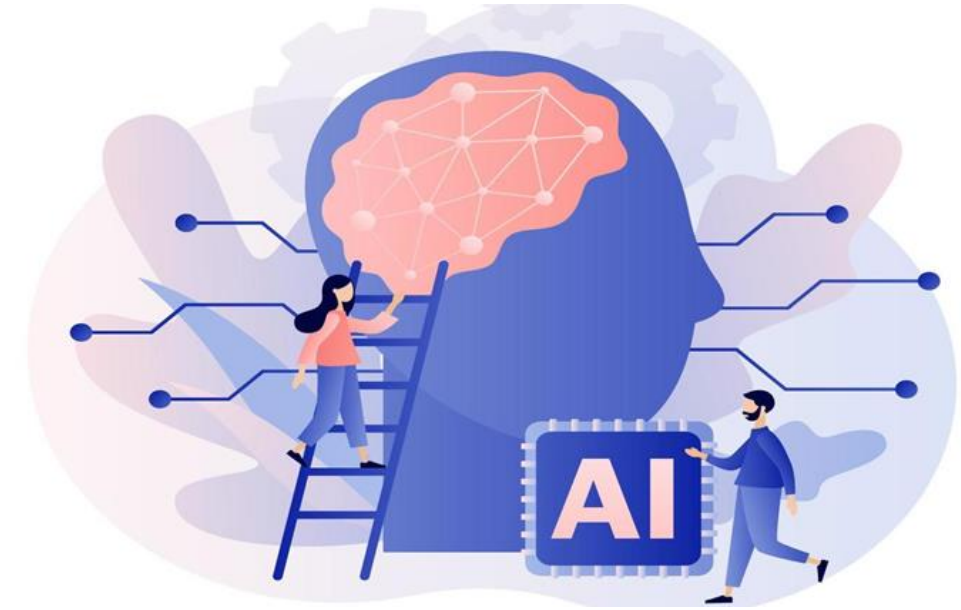
# 01 RNN topologies



- From left to right:
  1. Vanilla mode of processing without RNN, from fixed-sized input to fixed-sized output (e.g. image classification).
  2. Sequence output (e.g. image captioning takes an image and outputs a sentence of words).
  3. Sequence input (e.g. sentiment analysis where a given sentence is classified as expressing positive or negative sentiment).
  4. Sequence input and sequence output (e.g. Machine Translation: an RNN reads a sentence in English and then outputs a sentence in French).
  5. Synced sequence input and output (e.g. video classification where we wish to label each frame of the video).







# Thank You...!

End ↩