



# MBSE Avionics System Capstone

## MASCO

### Final Demo

**Shawn**

*B.S. Electrical Engineering, Aerospace Systems*

**Luke**

*B.S. Software Engineering*

**Clay**

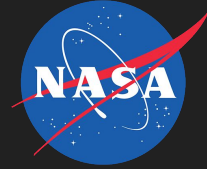
*B.S. Software Engineering*

**Walter**

*B.S. Computer Science, Cybersecurity*

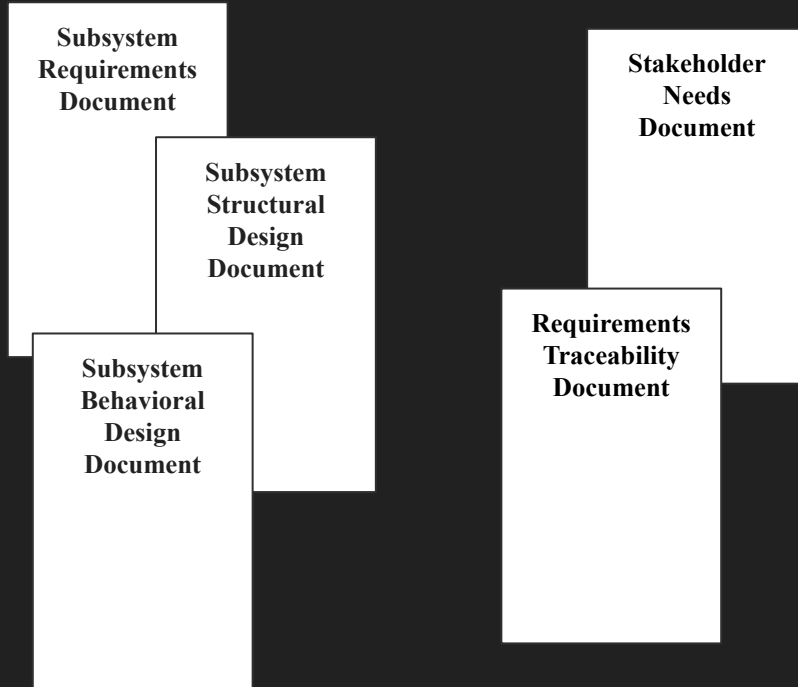
# MASC Project

- Project derived from NASA Johnson Space Center's Spacecraft Software Branch (ER6) studying the Gateway Cislunar Space Station
- Needed to study the application of MBSE to capturing Avionics subsystem design information flow for Gateway
- NASA also wanted to use the system model to perform Failure Mode Effects Analysis (FMEA) on the system design

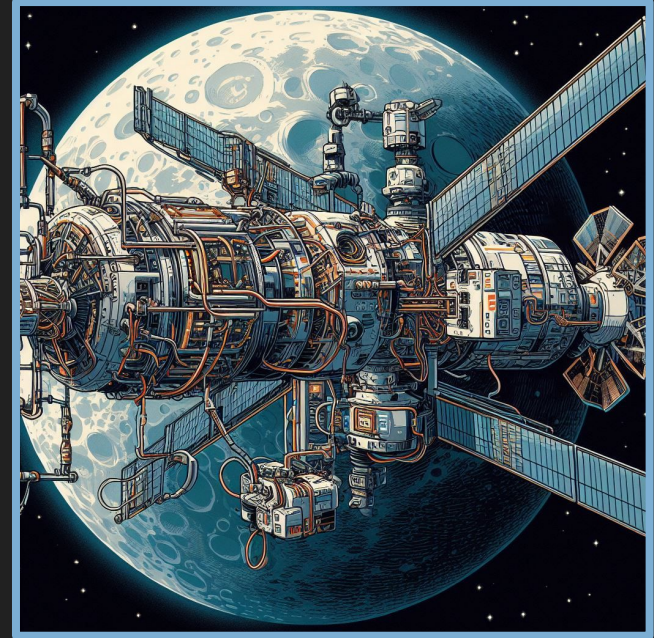


*Gateway Cislunar Space Station*

# MASC Background, Traditional Systems Engineering

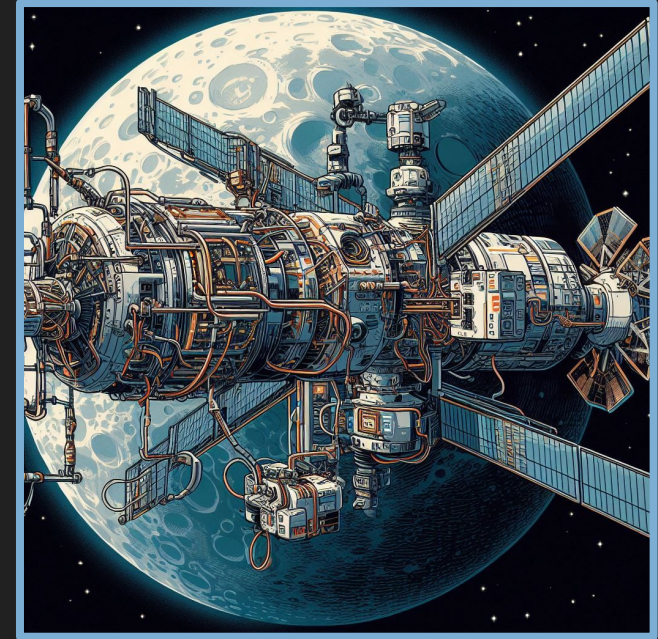
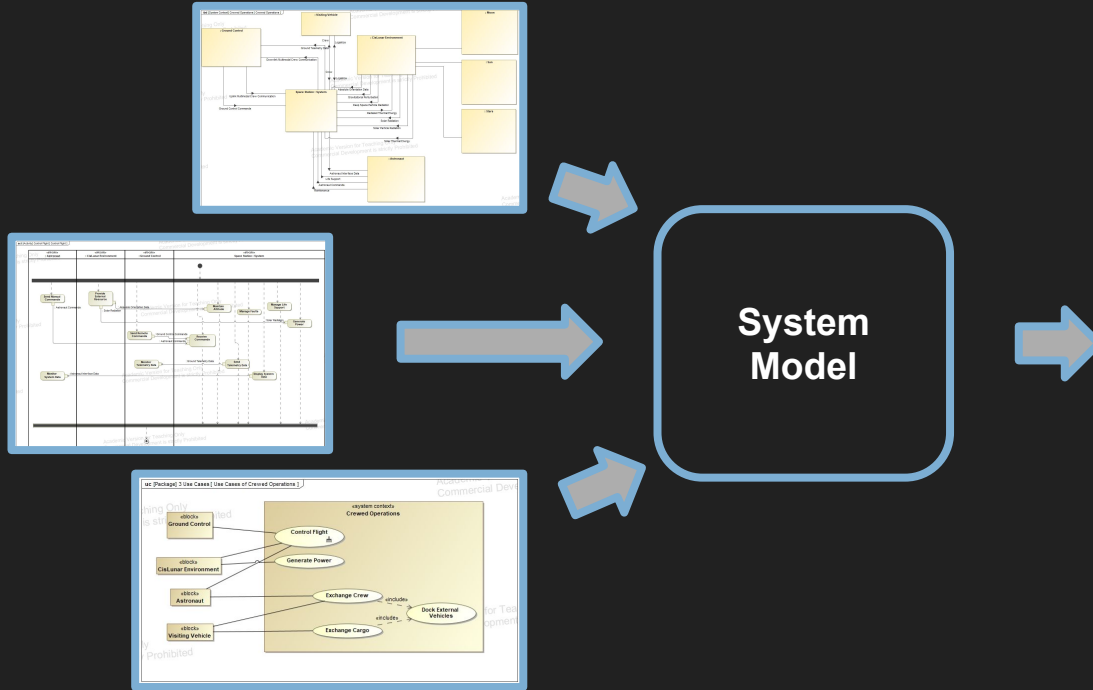


Traditional Systems Engineering uses a document based strategy to define the system



System of Interest  
(Spacecraft Avionics System)

# MASC Background, MBSE



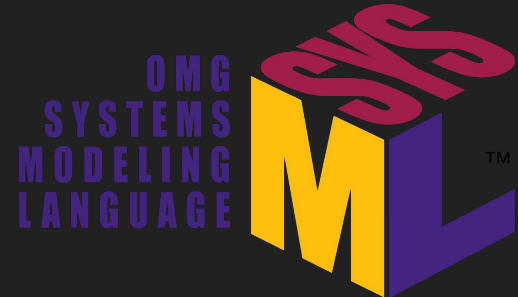
Model-Based Systems Engineering (MBSE) uses various viewpoints to define a system with a dynamic model

System of Interest  
(Spacecraft Avionics System)

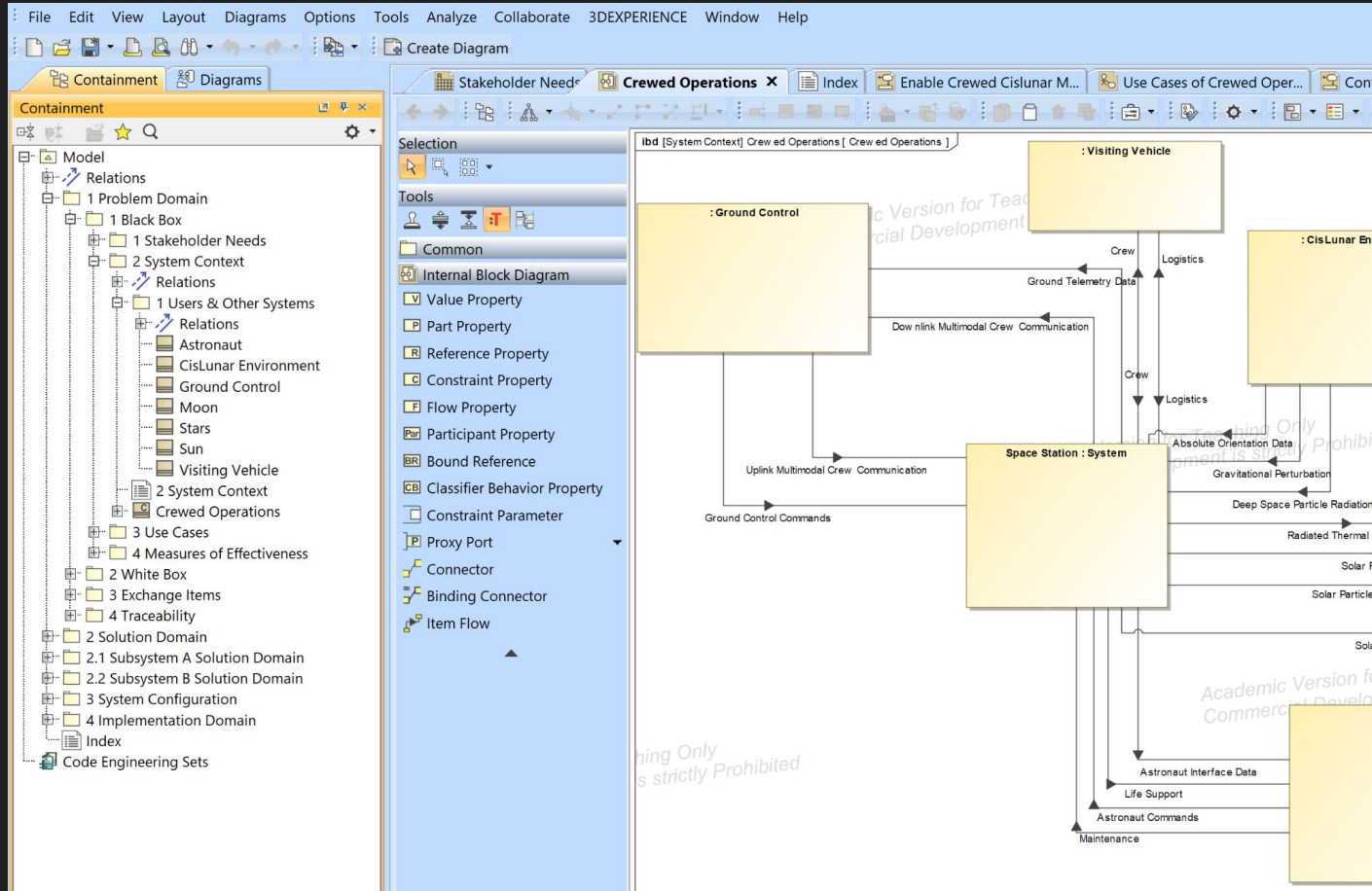


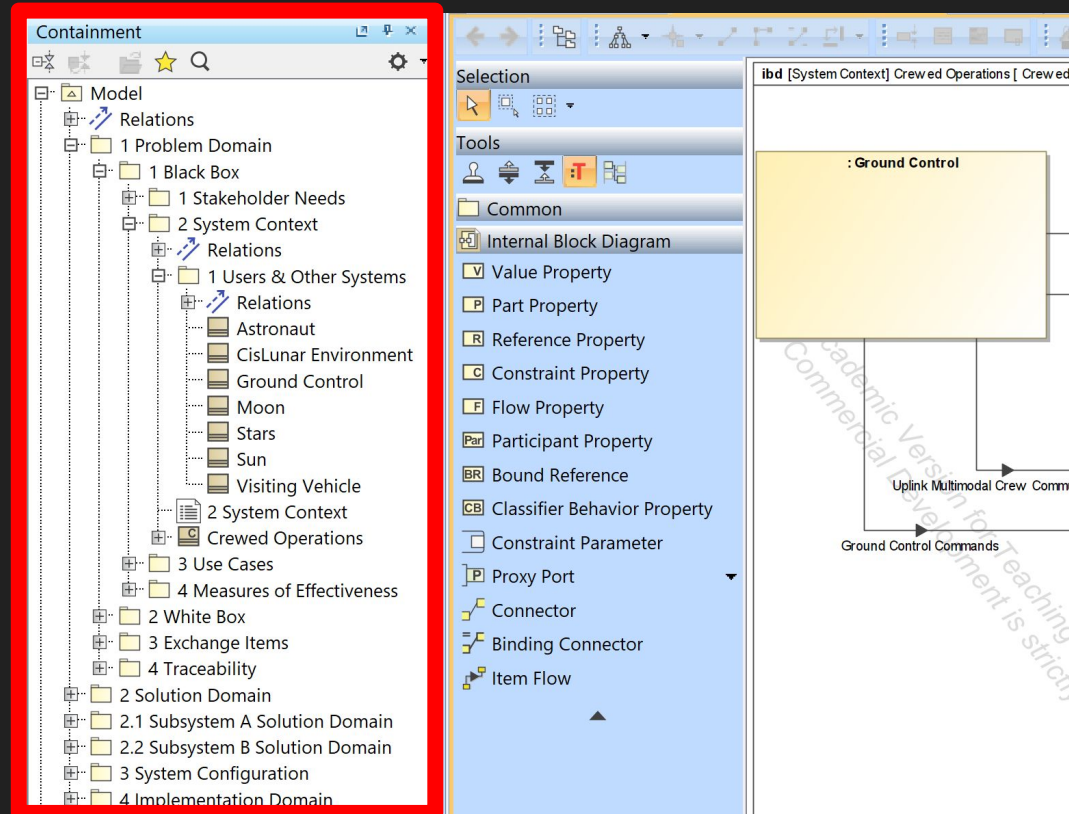
# MASC Customer Needs

- To satisfy the customer needs, MBSE tools, process, and frameworks were researched
- Worked with ERAU Alum and MBSE Subject Matter Expert to identify
  - Dassault Systemes, Magic System of Systems Architect™ Tool
  - Dassault Systems, MagicGrid™ Framework
  - Object Management Group, System Modelling Language (SysML™)
- The MagicGrid™ Framework provided deliverables to guide model development and measure progress
- After this was determined, licensing was the final step to begin work

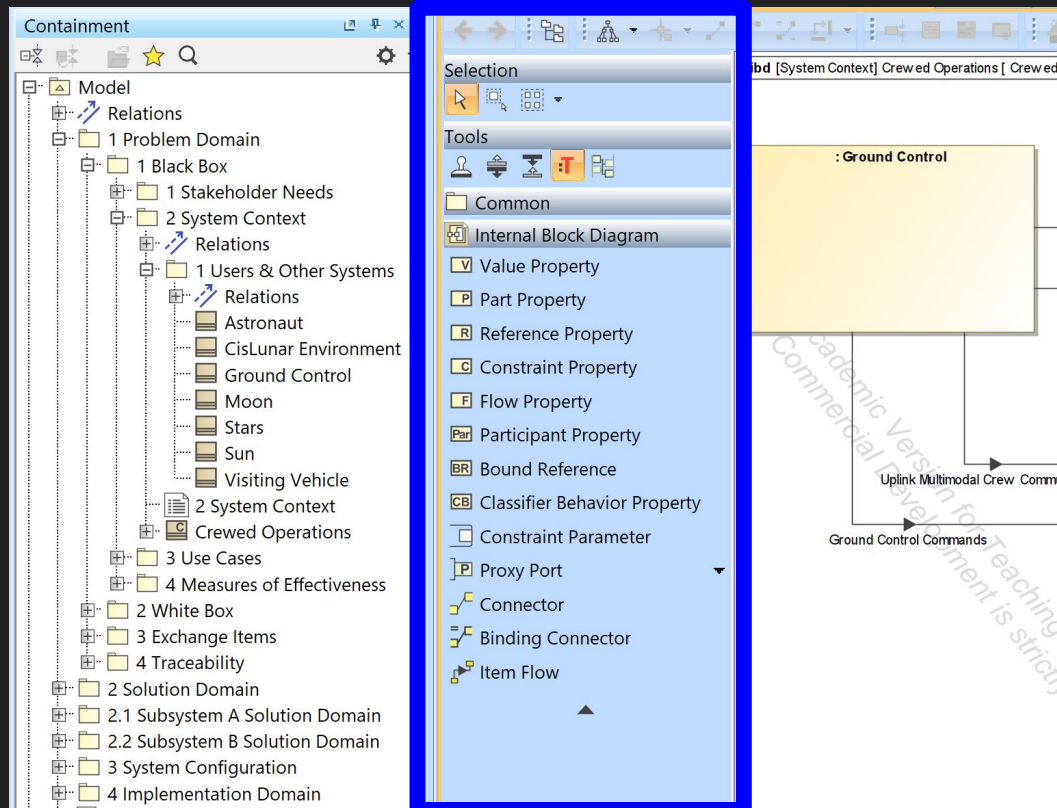


# The MagicDraw Tool



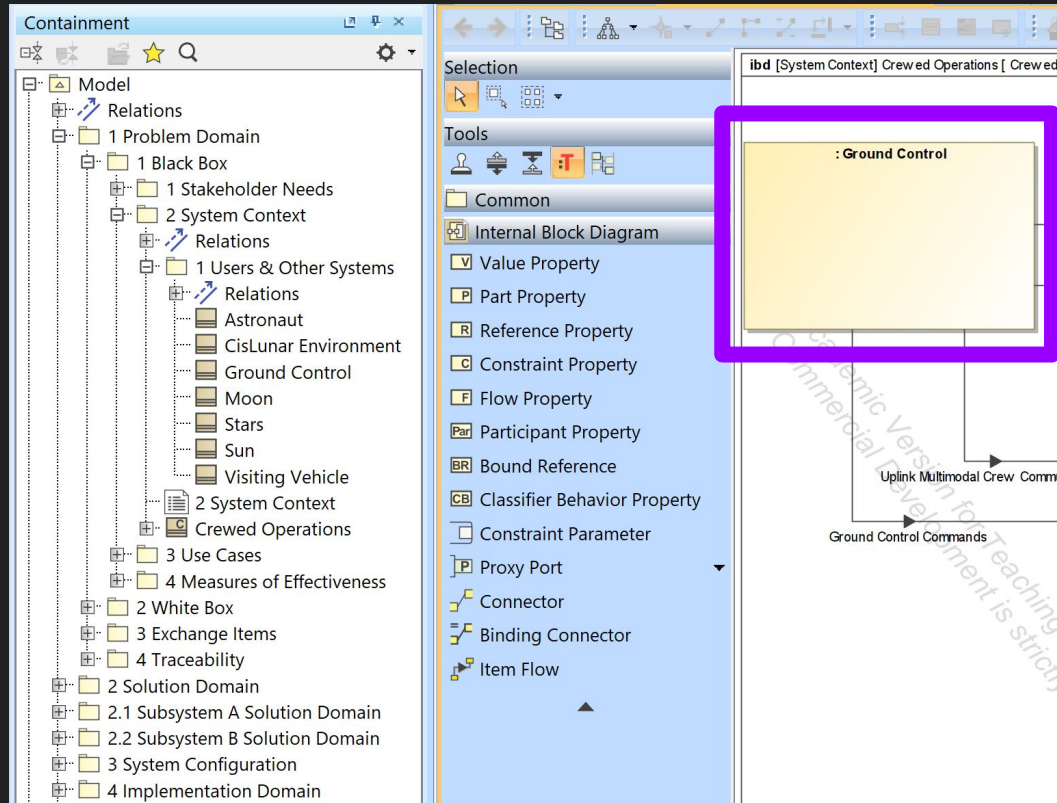


# The MagicDraw Tool

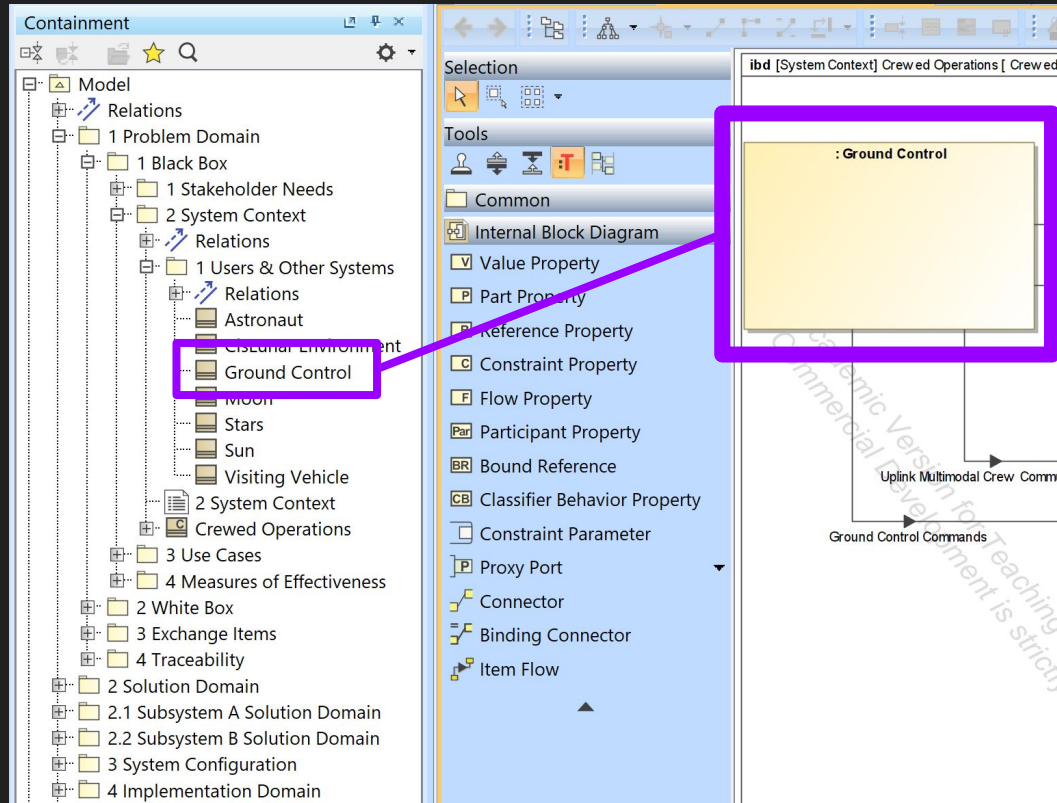




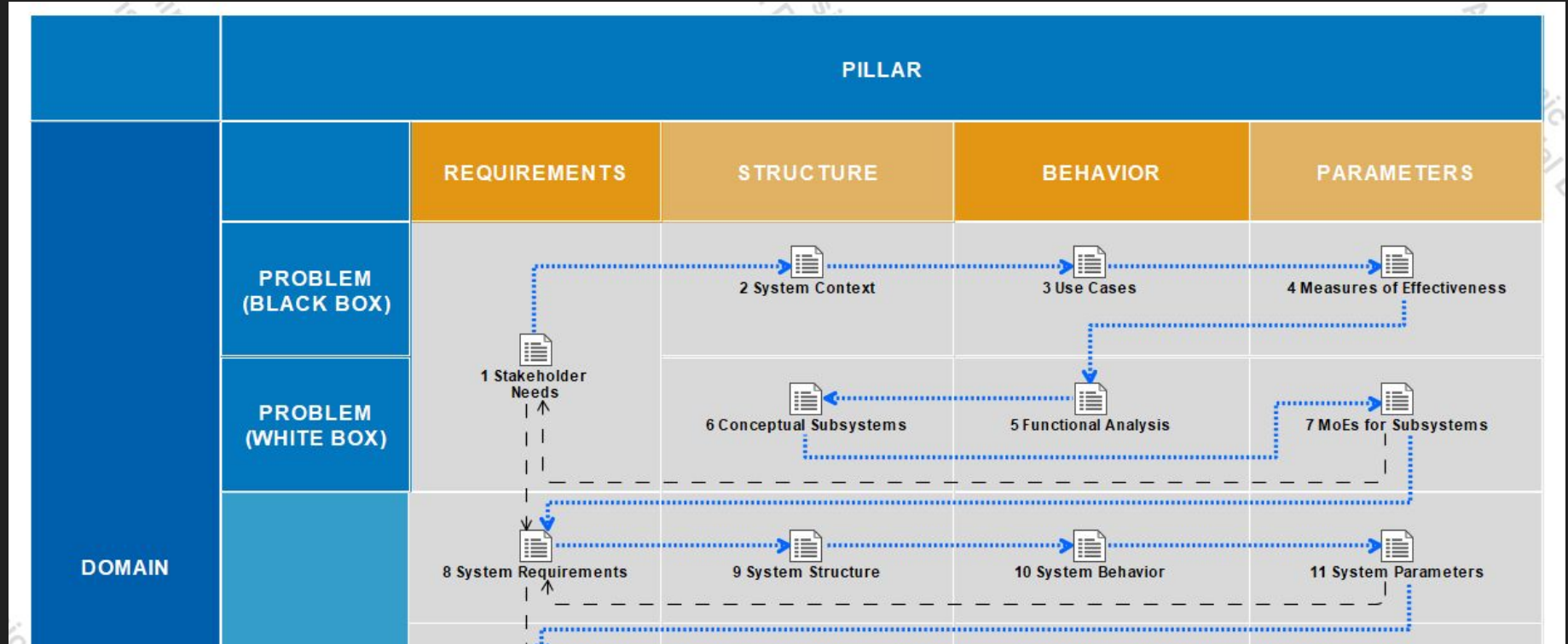
# The MagicDraw Tool



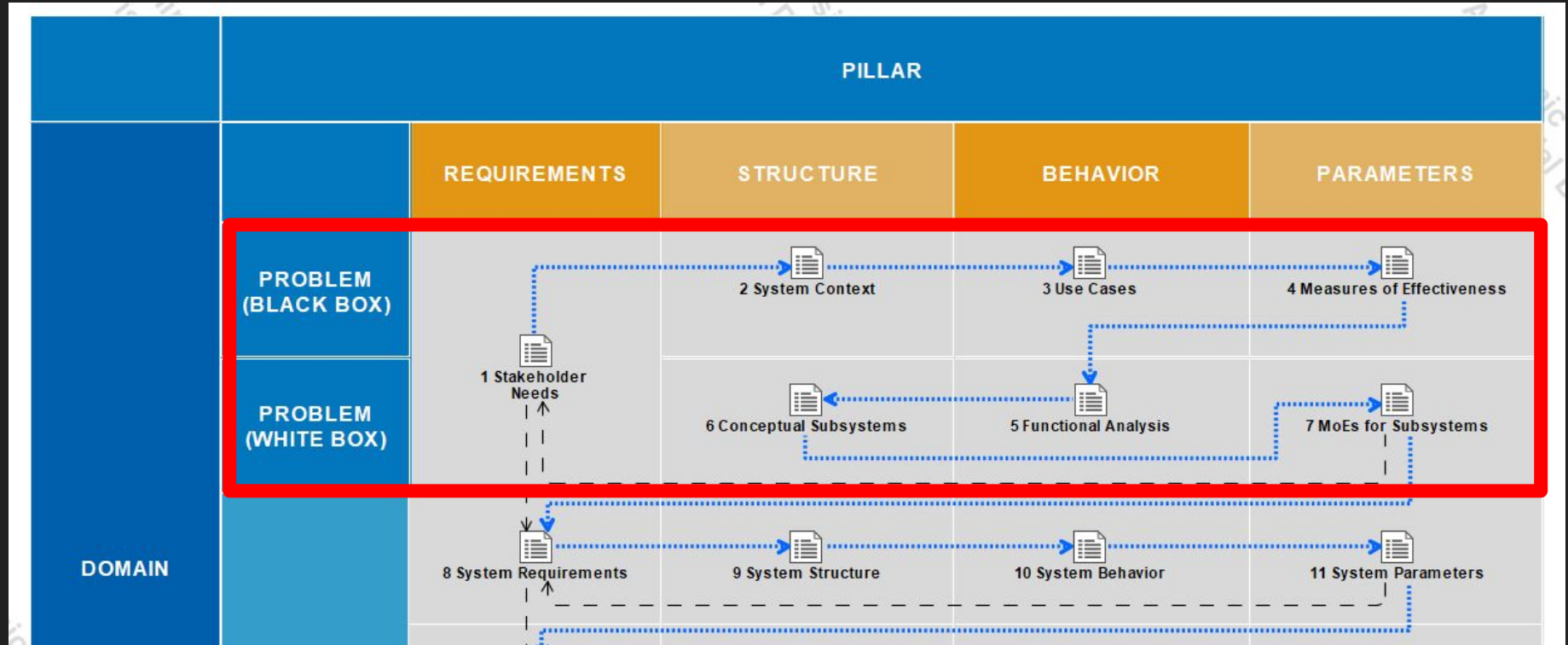
# The MagicDraw Tool



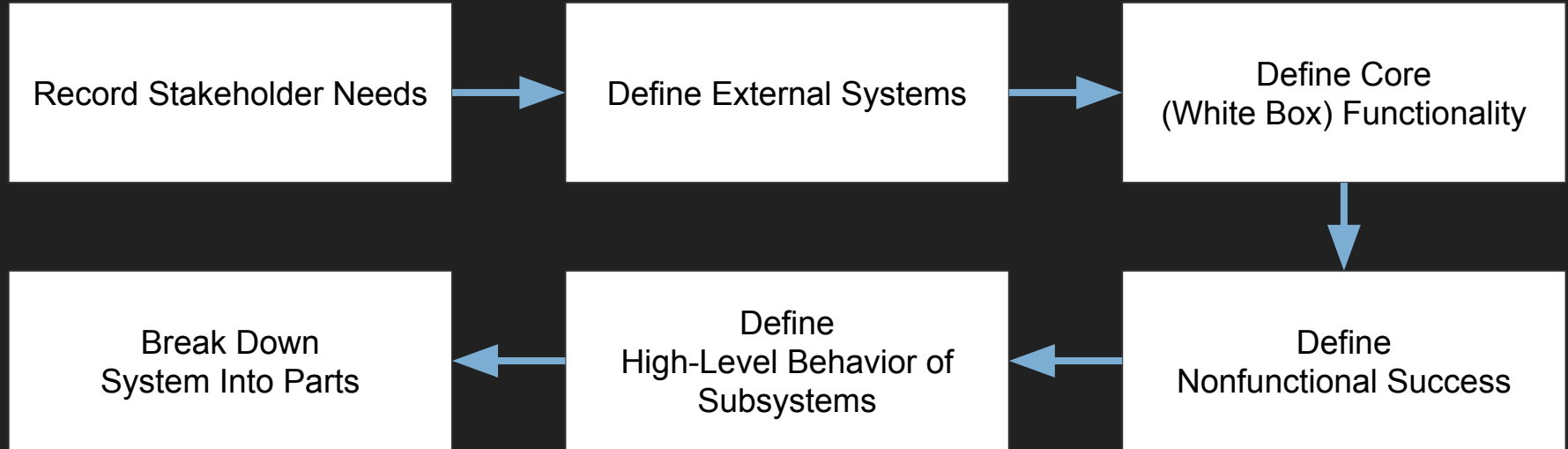
# The MagicGrid Framework



# The MagicGrid Framework

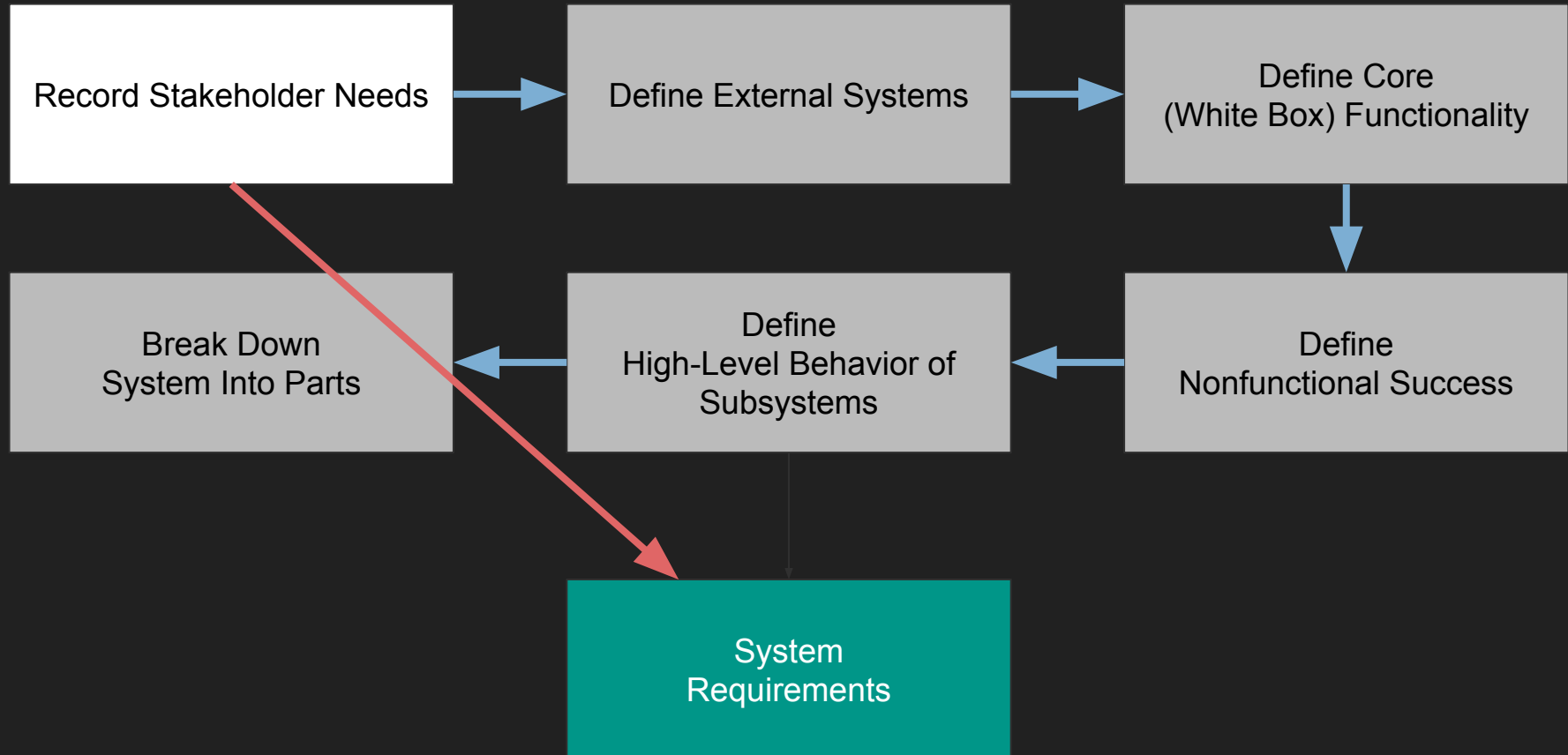


# The MagicGrid Framework

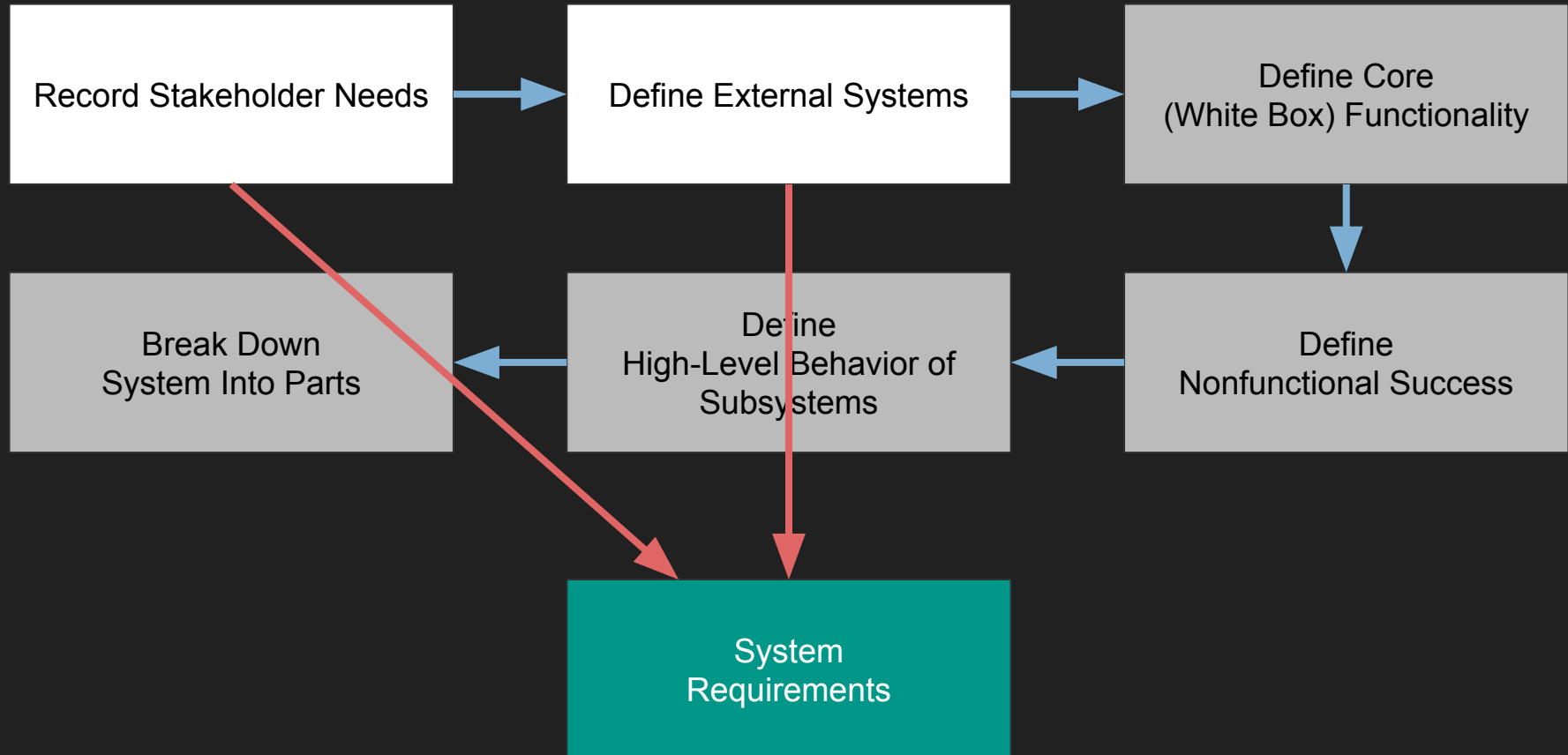




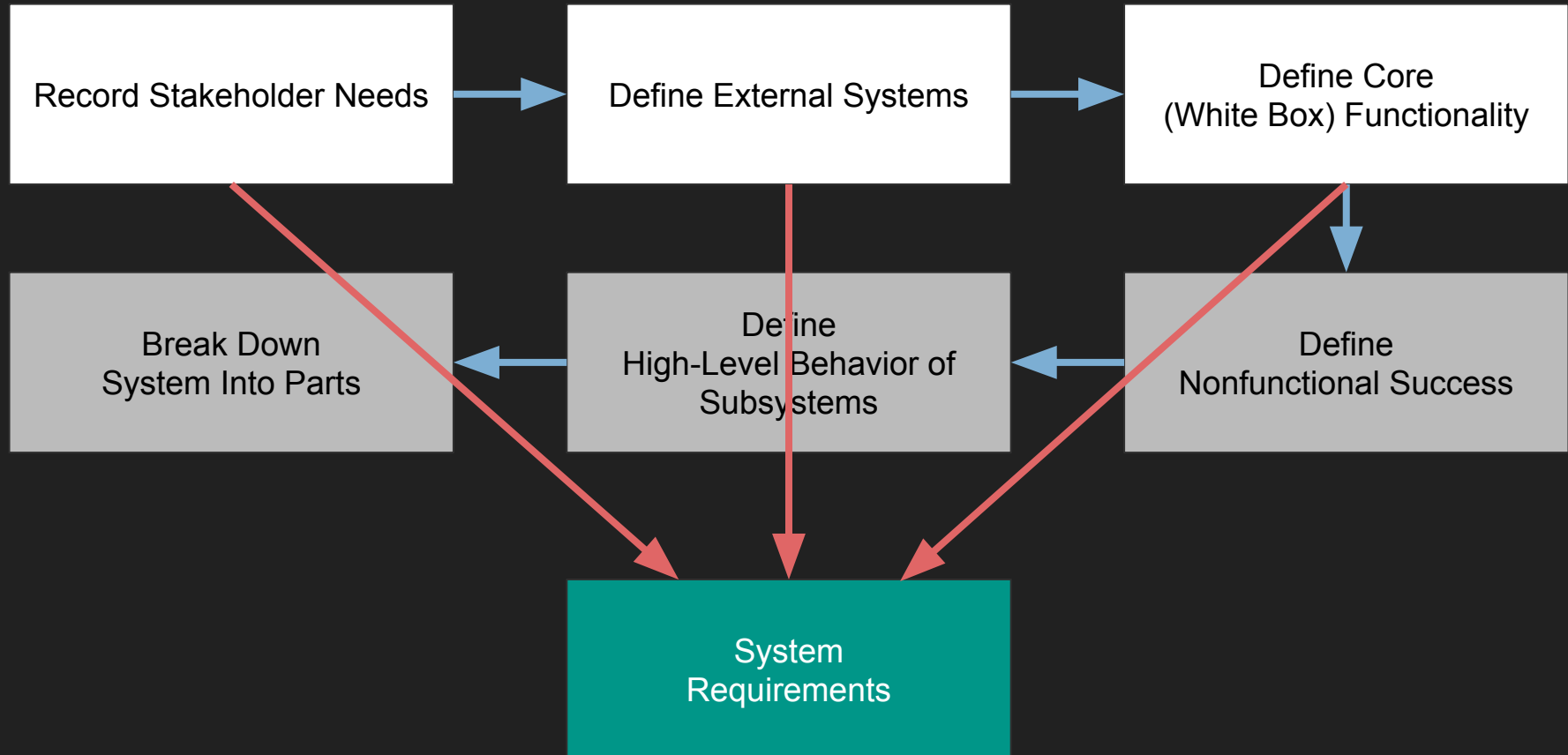
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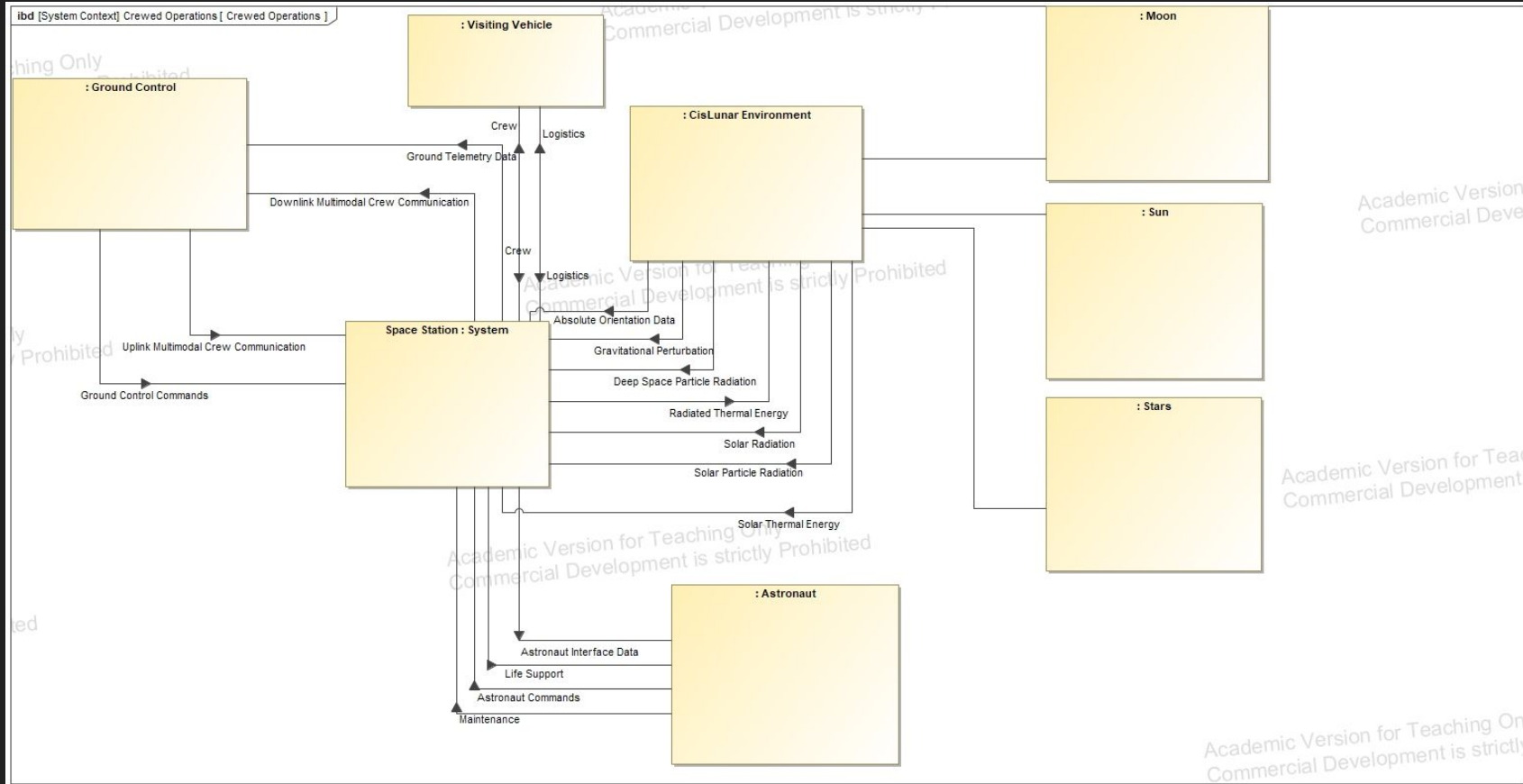
# Our Project Demonstration

# The CCS System (Needs)

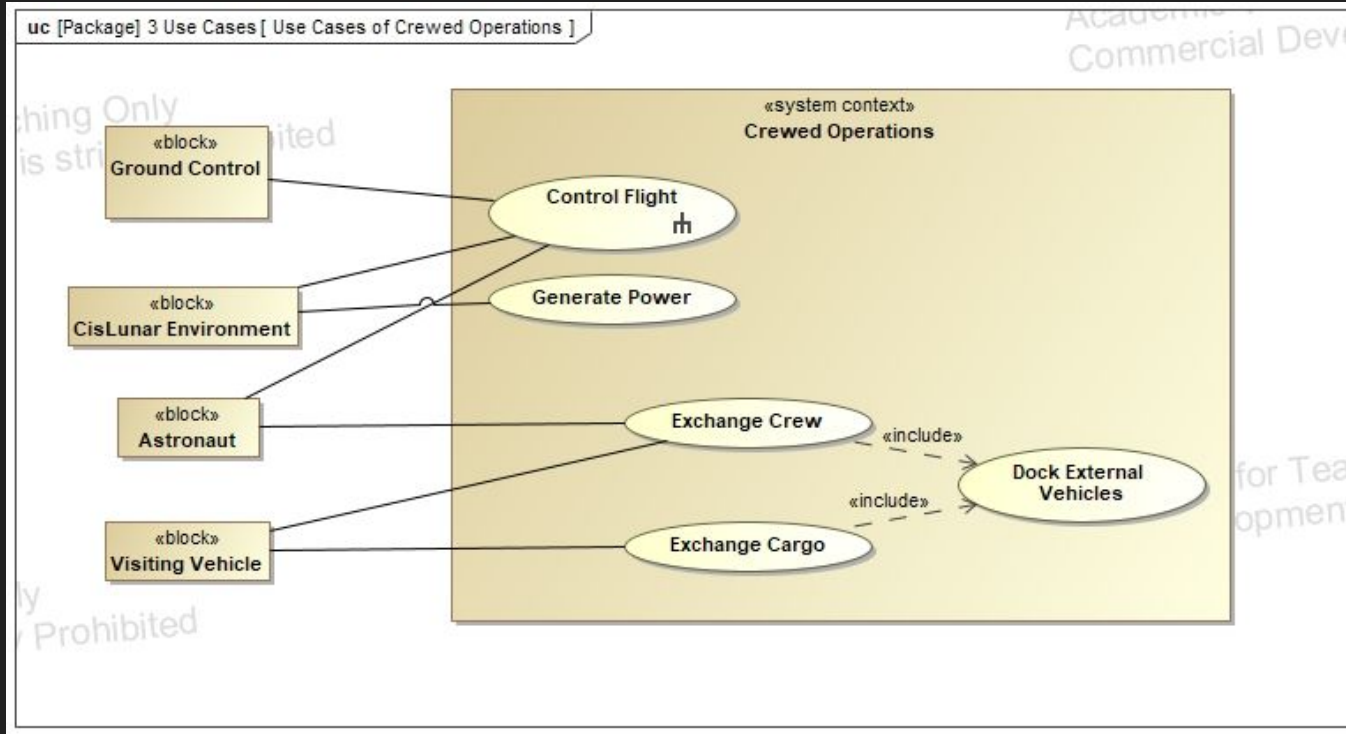
#	Name	Text	Documentation
1	<input type="checkbox"/> <b>R</b> SN-1 User Needs		
2	<input type="checkbox"/> <b>R</b> SN-1.1 Cislunar Crewed Mission	The Sol should facilitate human crewed missions to cislunar space including capabilities that enable surface missions.	Add sources in this field
3	<input type="checkbox"/> <b>R</b> SN-1.2 Exploration Science Mission	The Sol should provide capabilities to meet scientific requirements for lunar discovery and exploration.	Add sources in this field
4	<input type="checkbox"/> <b>R</b> SN-1.3 Forward Compatibility	The Sol should enable, demonstrate, and prove technologies that are enabling for deep space missions.	Add sources in this field
5	<input type="checkbox"/> <b>F</b> SN-1.4 Manual Flight Control	The Sol should allow for manual control of flight dynamics.	Add sources in this field
6	<input type="checkbox"/> <b>F</b> SN-1.5 Automatic Flight Control	The Sol should be able to maintain its orbit.	Add sources in this field
7	<input type="checkbox"/> <b>F</b> SN-1.6 Independent Power	The Sol should produce, store, and regulate its own power.	Add sources in this field
8	<input type="checkbox"/> <b>F</b> SN-1.7 Crew Safety	The Sol should keep the crew alive and safe.	Add sources in this field
9	<input type="checkbox"/> <b>R</b> SN-1.8 Crew Mission Extensability	The Sol should accomodate extended crew mission durations.	Add sources in this field
10	<input type="checkbox"/> <b>F</b> SN-1.9 Extra-Vehicular Activity	The Sol should allow crew to perform extra-vehicular activity.	Add sources in this field
11	<input type="checkbox"/> <b>R</b> SN-1.10 Visiting Vehicle Docking	The Sol should allow for Visiting Vehicles to dock.	Add sources in this field
12	<input type="checkbox"/> <b>R</b> SN-1.11 Vehicular Logistical Tranfer	The Sol should accept the transferring of crew and cargo.	Add sources in this field
13	<input type="checkbox"/> <b>F</b> SN-1.12 Lunar Surface Communication	The Sol should provide communication to the Lunar surface.	Add sources in this field
14	<input type="checkbox"/> <b>R</b> SN-2 Design Constraints		
15	<input type="checkbox"/> <b>R</b> SN-2.1 User Interoperability	The Sol should have to ability to support multiple self, commerical, and international partner objectives.	Add sources in this field
16	<input type="checkbox"/> <b>R</b> SN-2.2 Crew Size	The Sol should accomodate up to 4 crew members.	Add sources in this field
17	<input type="checkbox"/> <b>R</b> SN-2.3 Mission Duration	The Sol should enable 30 to 90 days of crew missions.	Add sources in this field
18	<input type="checkbox"/> <b>R</b> SN-2.4 Orbital Access	The Sol should be easy to access from Earth with current launch vehicles.	Add sources in this field
19	<input type="checkbox"/> <b>R</b> SN-2.5 Earth Communication	The Sol should have continuous communication with Earth.	Add sources in this field



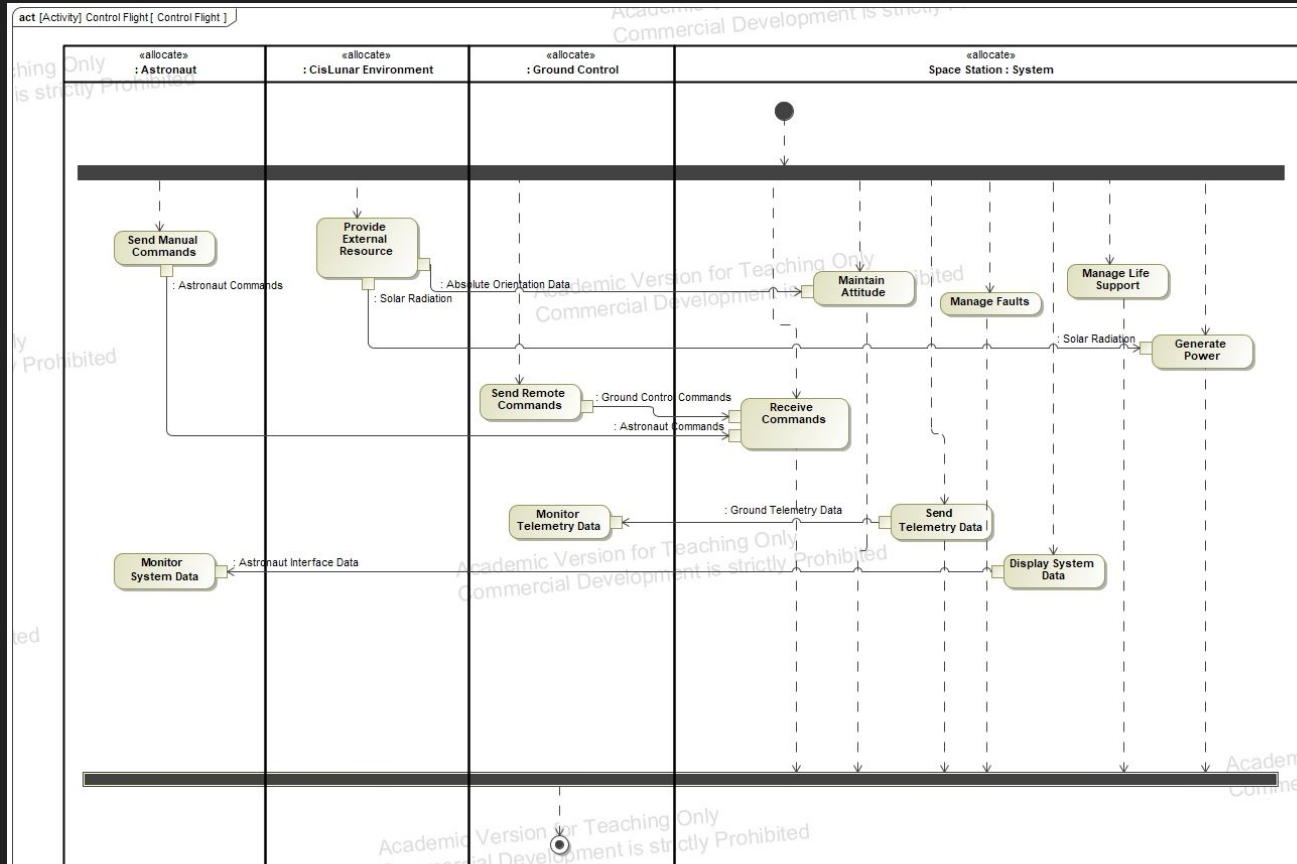
# The CCS System (Context)



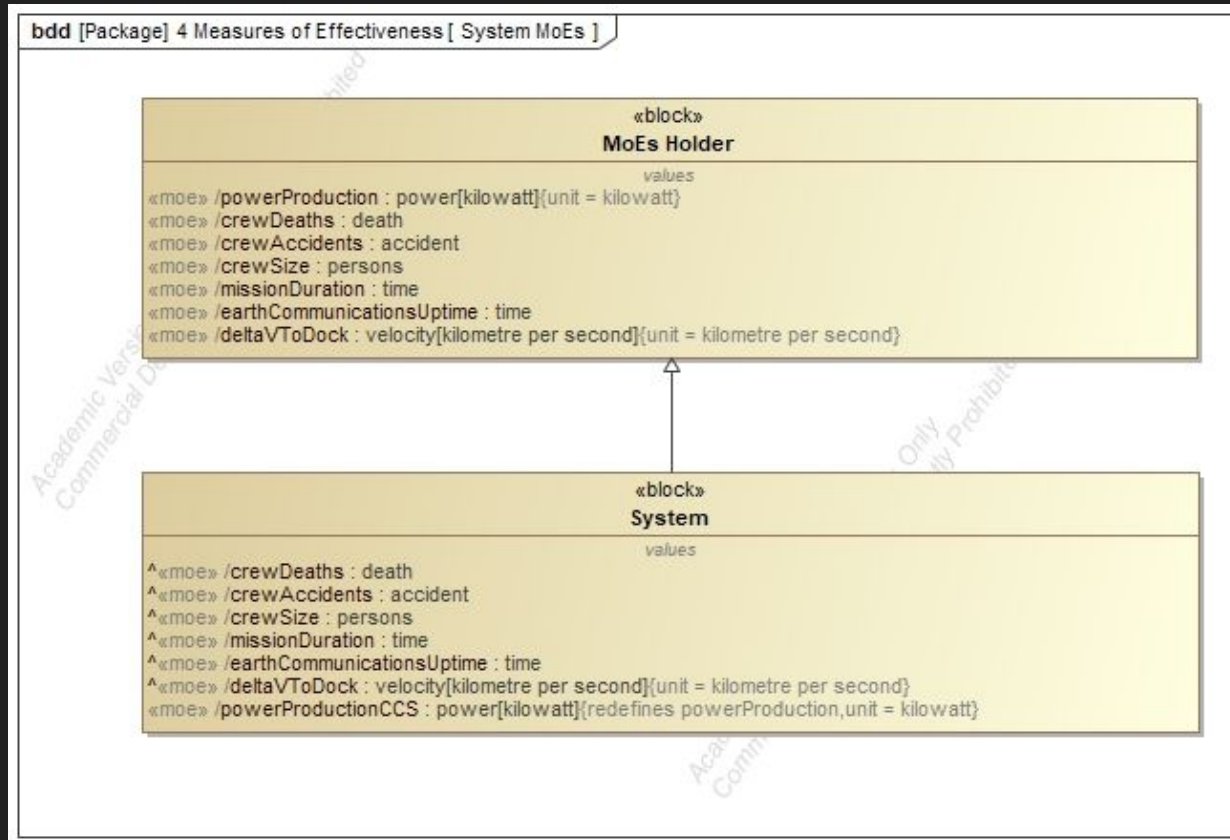
# The CCS System (Use Case)



# The CCS System (Scenario)



# The CCS System (Measures of Effectiveness)



# Lessons Learned

- New way to approach large scale design challenges
- Importance of constant iteration & feedback during each phase
- Black-Box analysis of a new domain is more difficult than initially anticipated
- Methods of scoping down our design to singular subsystem



## Our Experience

- Tool allows for cascading iterations (allows for testing)
- Different model views allowed for greater overall understanding of SOI
- Very easy requirements tracing
- New tool, little documentation
- High learning curve (not beginner friendly)
- Made async work difficult (no version control options)
- Small errors can require massive reworks
- Changing UML mindset to SysML

# Future Work

- Begin working on Solution domain
- Fault Tree Analysis
- Possibly write paper?

Thank you!  
Any Questions?

