

LidarView Presentation - IGN

2023-06-29 G.Ferret

Summary

- Kitware quick overview
- Overview of VTK / ParaView
- LidarView : A Paraview Based App
- ParaView/ LidarView for distributed applications
- Potential applications to aerial lidar data



Kitware quick overview

Kitware / Leader in AI & scientific open source solutions

Software development

Based on open source tools
300+ active projects worldwide



230 employees Worldwide

6 offices across USA/Europe



25 years of expertise

Kitware USA, 1998
Kitware Europe, 2010



Sustained Growth

Since creation of the company
100% employee-owned



Most staff with PhD or Master

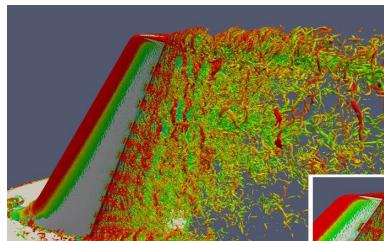
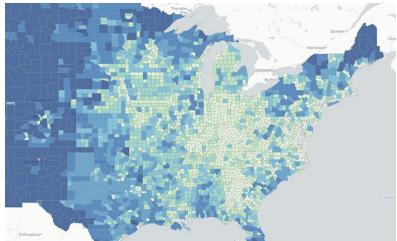
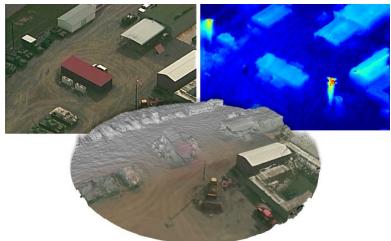
High Level customer expertise

Revenue 2020

\$39M consolidated



Areas of expertise / Built on open source



Computer
Vision



Data and
Analytics



Scientific
Computing

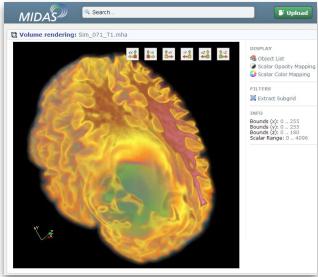


Medical
Computing

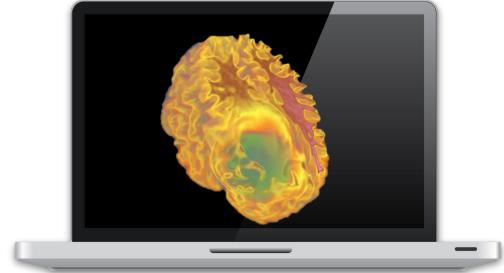


Software
Solutions

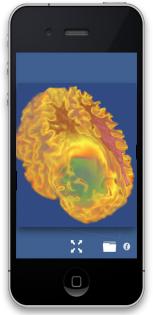
Applications / Universal Platforms



Web



Desktop



Mobile



Cloud /HPC

kitware
Platforms



3D Slicer

ParaView

KWIVER

imstk

VTK

Pulse
Physiology Engine

CMake

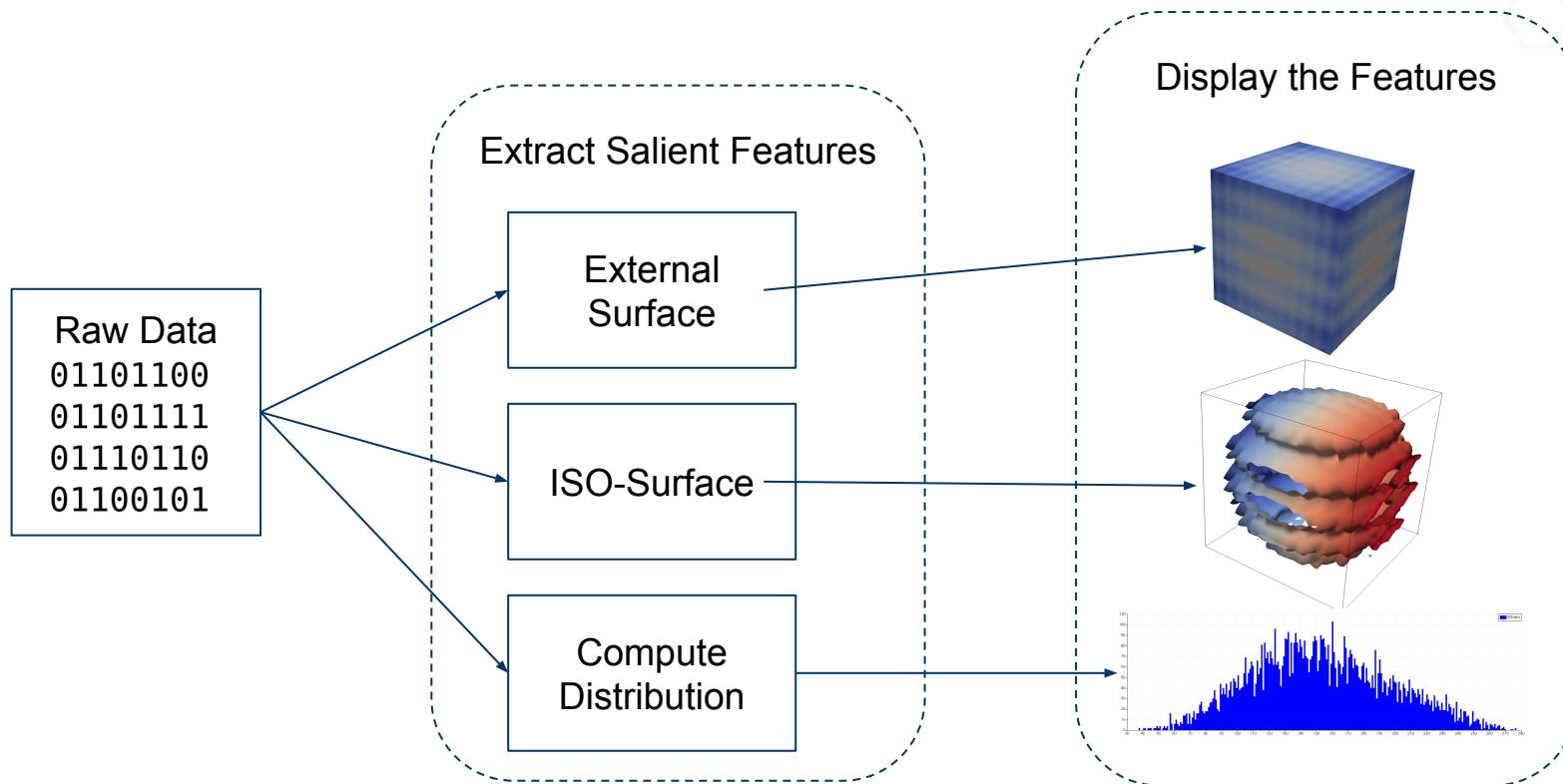
Resonant

tomviz

STK

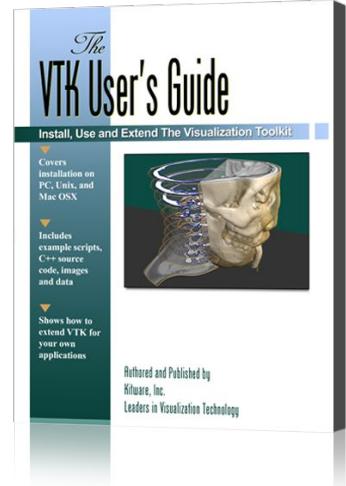
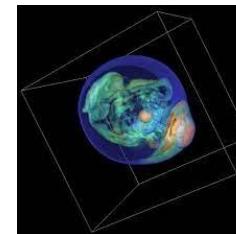
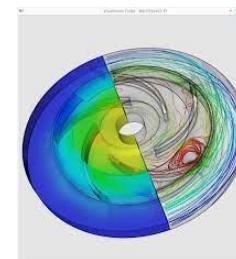
Overview of VTK / ParaView

Scientific Visualization Basics



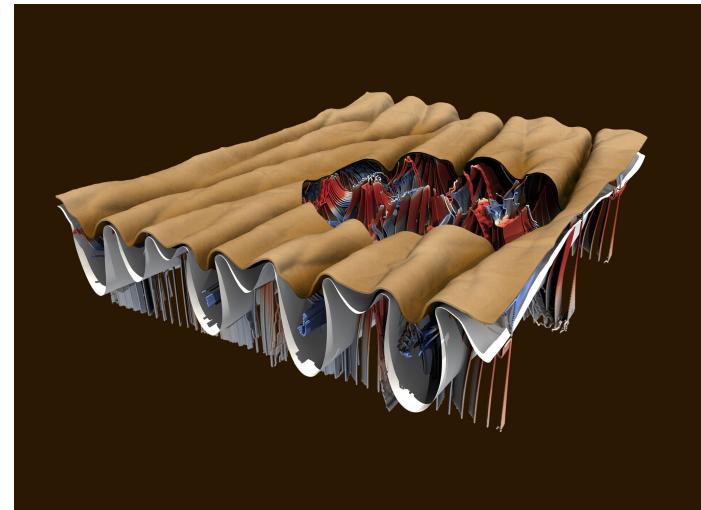
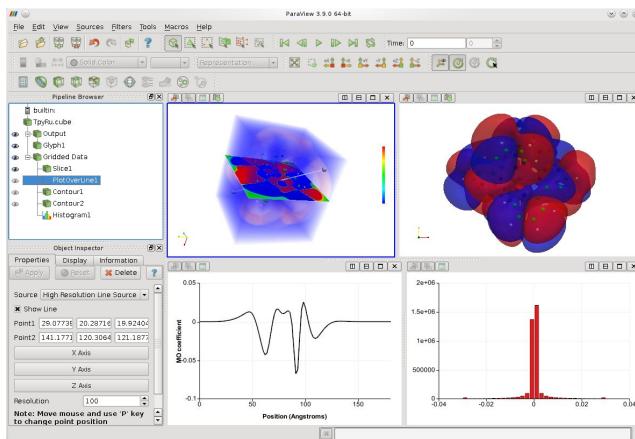
VTK / Cross-Platform Visualization Toolkit (1993)

- Open-source (BSD-3 licence), freely available, cross-platform toolkit for post-processing and visualization of scientific data



ParaView / High-Performance Post-Processing (2002)

- Open-source, multi-platform, data analysis and visualization application
- Analysis of extremely large datasets using distributed memory computing resources

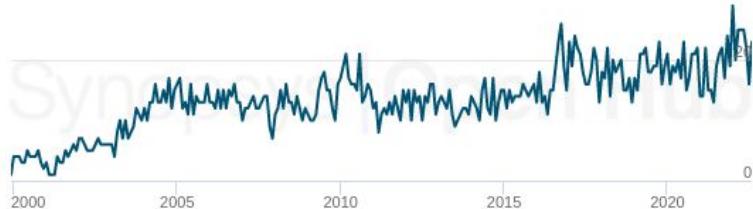


ParaView Community

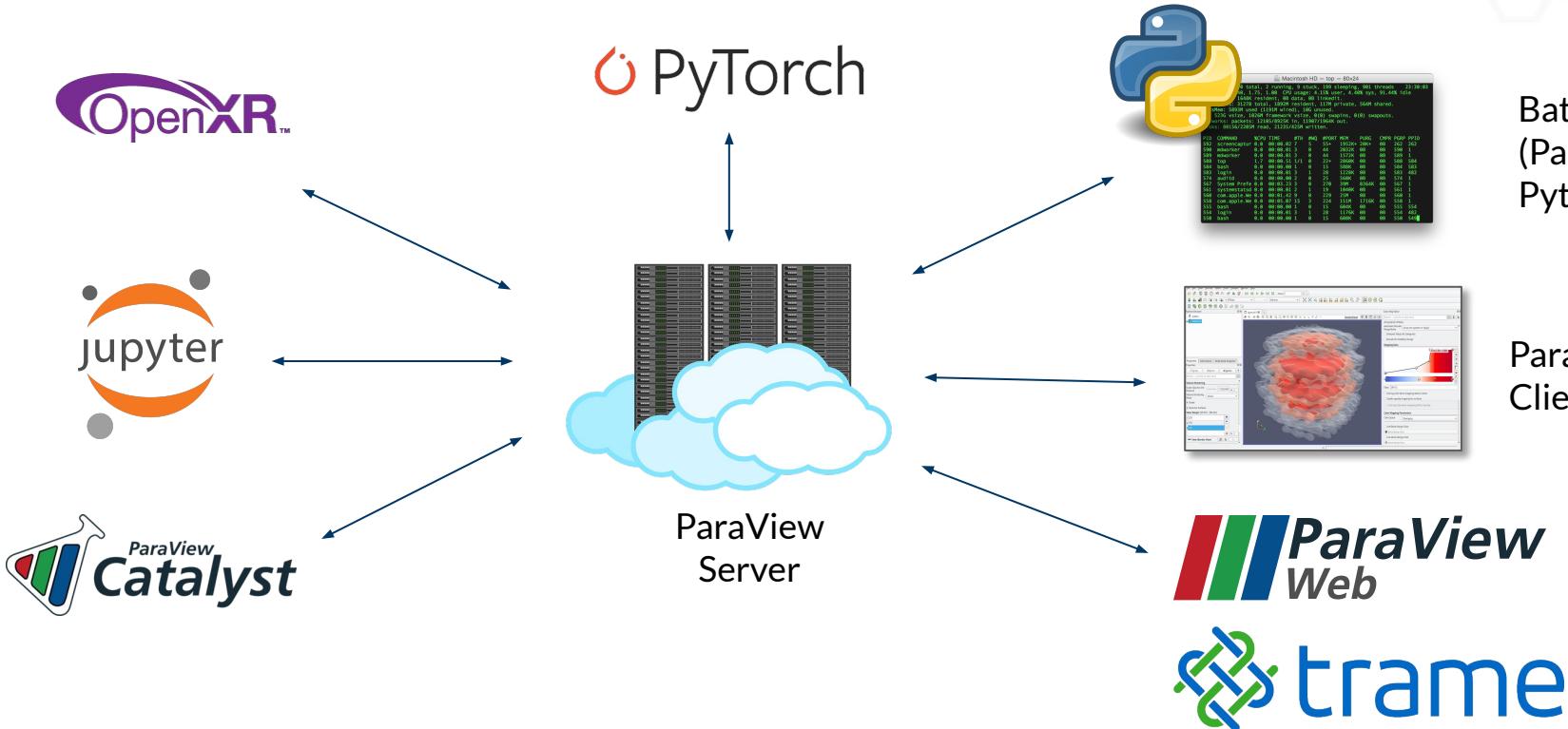
- Open Source Software (BSD license)
- Run on most of Top500 HPC
- 300000+ download yearly from Kitware servers
 - More users via other unknown download channel (Linux packaging, Enterprise distribution...)
- 157k commits made by 339 contributors since 2000
- 1.6M lines of code



Contributors per Month



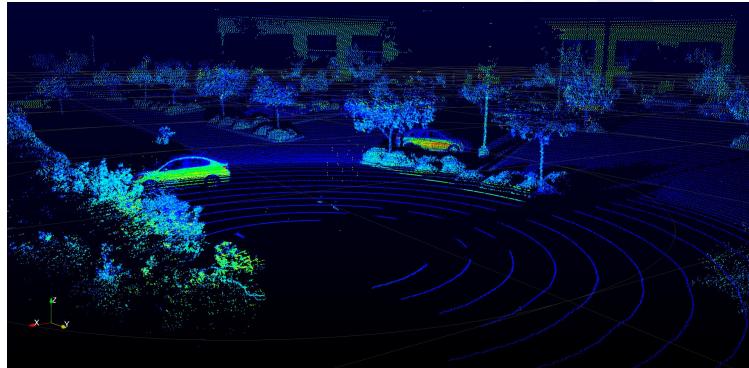
ParaView Ecosystem



LidarView : A Paraview based app

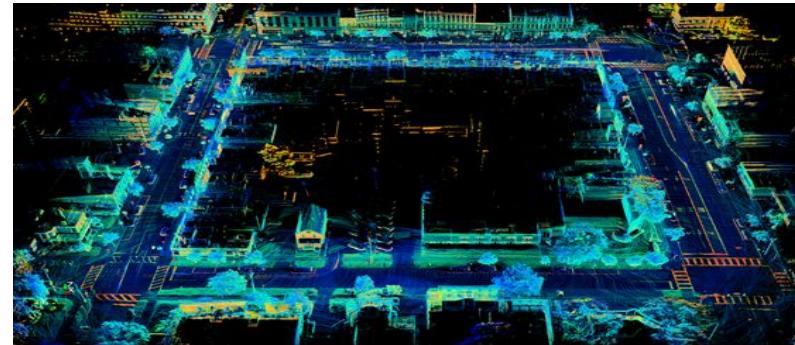
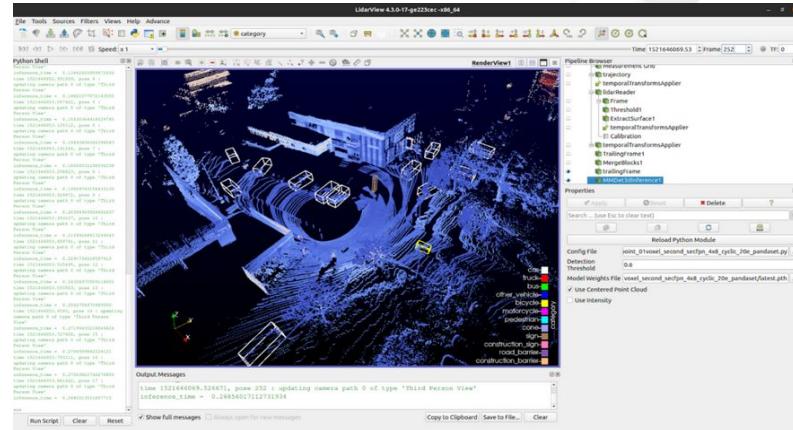
LidarView A Visualization and Analytics Toolkit

- Easy to use ParaView-based application with a Graphical User Interface (GUI)
- Real-time open source software to visualize, record and perform analysis of LiDAR data
 - Extensible/Adaptable to Support Various LiDAR and enables vendor specific apps
- Also Allows opening las files (since V4.4.0)
- Continuously evolving toolkit to enhance and improve upon vendor interface, analytics and automation
- VR available for visualization and interaction
- Developed LidarView based applications for LiDAR vendors
- Permissive Open Source Licensing



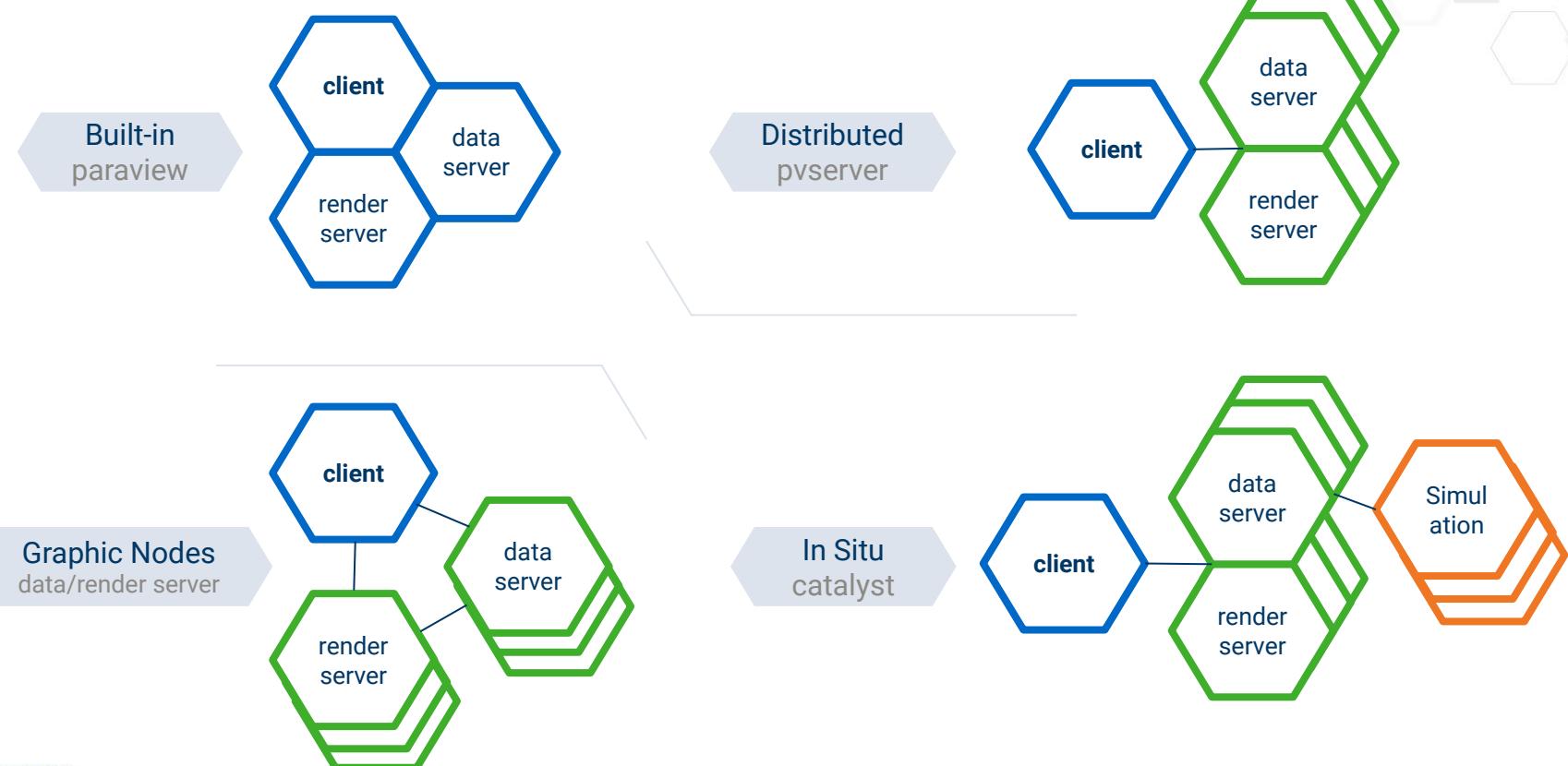
LidarView : Point Cloud processing Capabilities

- ➊ SLAM :
 - Enables trajectory estimation and map reconstruction from it
 - Fuses external sensors (IMU,GPS, Wheel Odometer, Camera...) for more robustness, accuracy and point colorization
- ➋ Deep Learning
 - Enables usage of DL libraries such as PyTorch, TensorFlow or MMDetection3D toolkit for Deep Learning applications
- ➌ Ongoing : Embedding most useful PCL functionalities as filters
- ➍ Anything you can think of (on temporal or static data), through Python or C++ implementation thanks for modular interfacing
- ➎ Can be done at big scale thanks for Paraview distributed computing capabilities

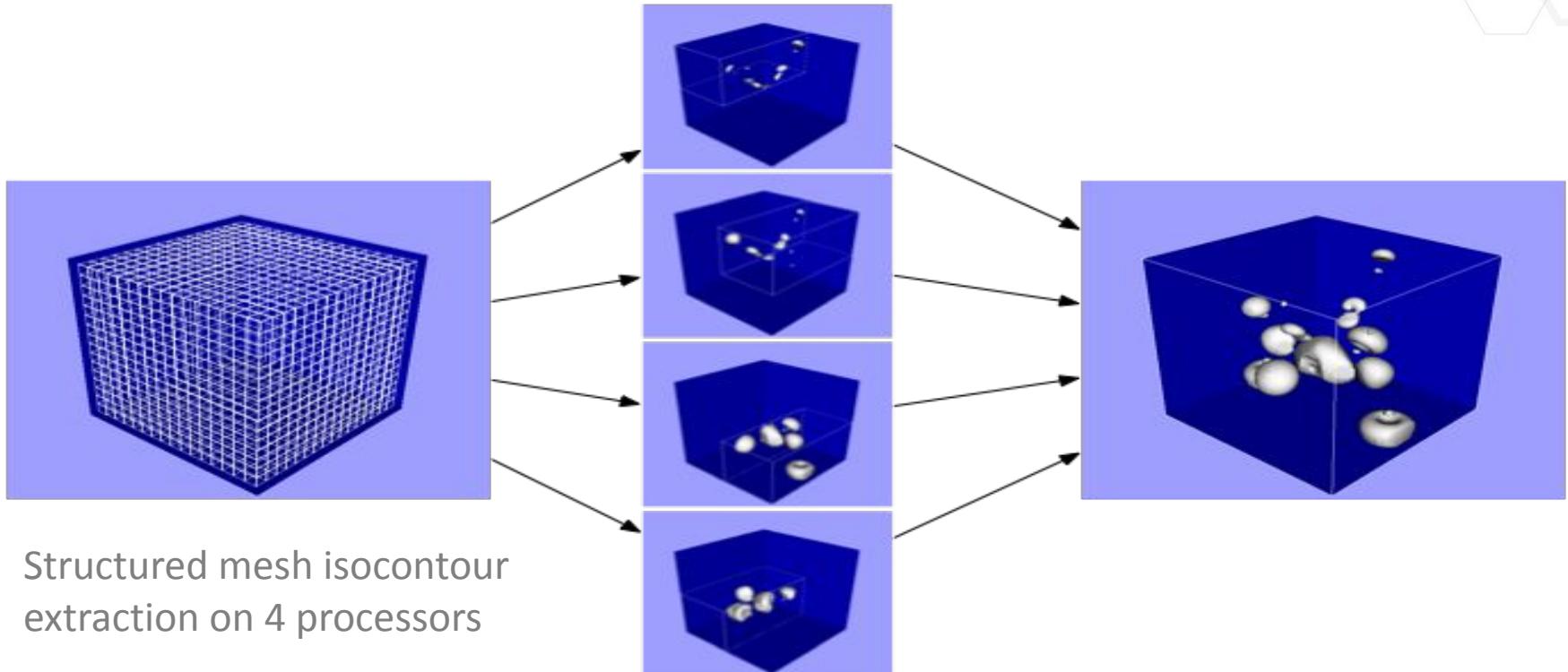


ParaView / LidarView for Distributed computation

ParaView's Client Server Architecture



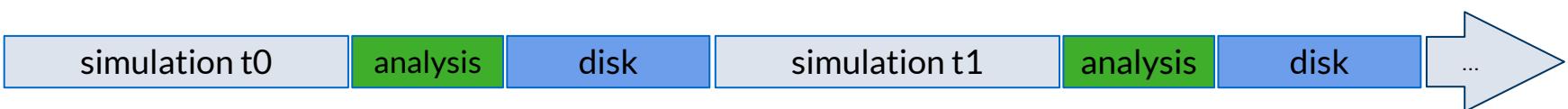
ParaView: Distributed Processing of the data



In-situ analysis, with Paraview Catalyst



- **Concurrent** analysis and visualization tasks during simulation
 - Reduce I/O
 - Increase value of stored data
 - Zero-copy analysis
 - Visualization or data reduction can be done at up to each timestep
(highly configurable through Python scripting and GUI)

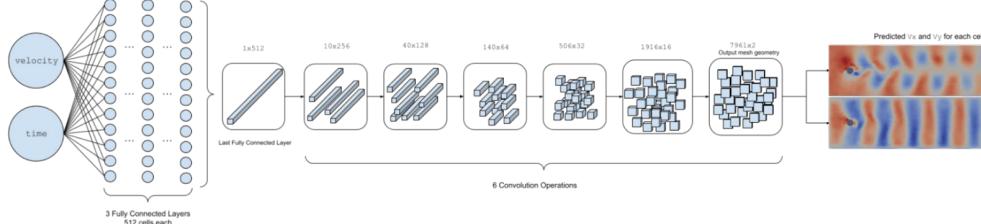


Deep Learning in Paraview

- Goal : Mimic the behavior of a CFD simulation with deep learning to accelerate it (based on EDF's [Code Saturne](#) CFD solver)
- Rendered as it learns in paraview (results and training monitoring)

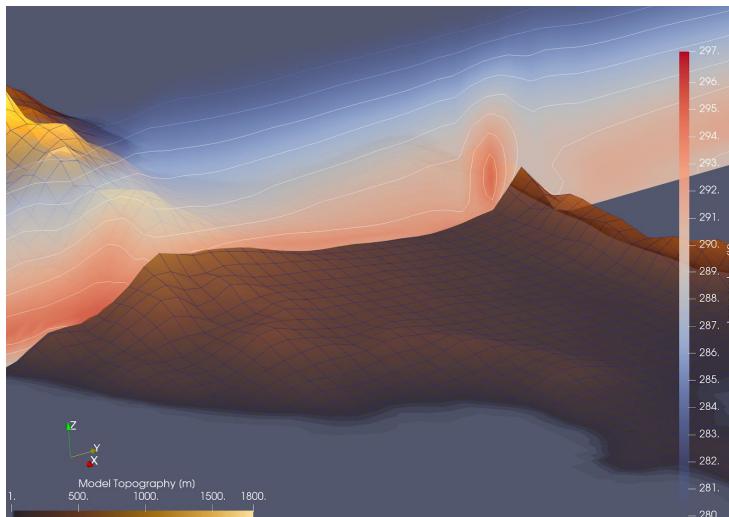
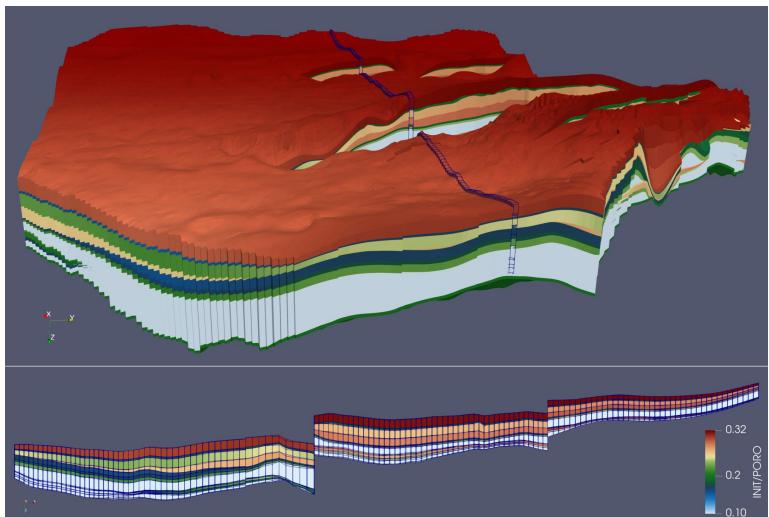
Kàrmàn Vortex
Street surrogate
model build with

 PyTorch



<https://www.kitware.com/deep-learning-surrogate-models-in-paraview-viewing-inference-results-and-monitoring-the-training-process-in-real-time-with-catalyst/>

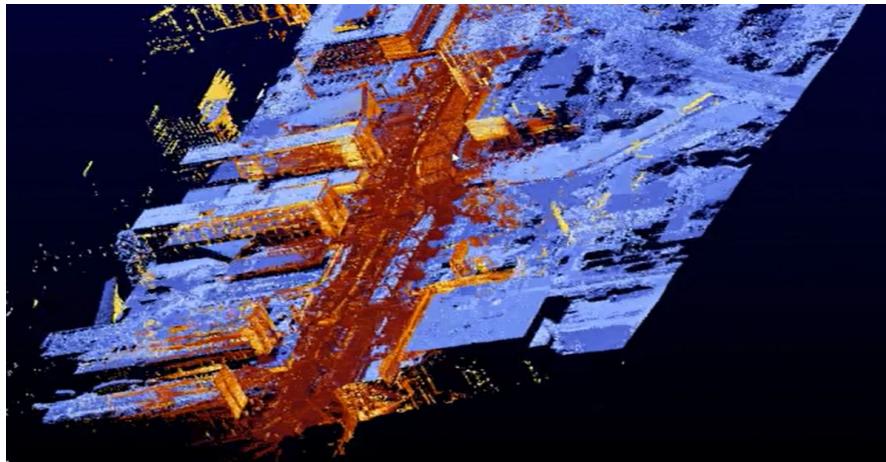
Some examples of scaled rendering



Applications for Aerial LiDAR processing

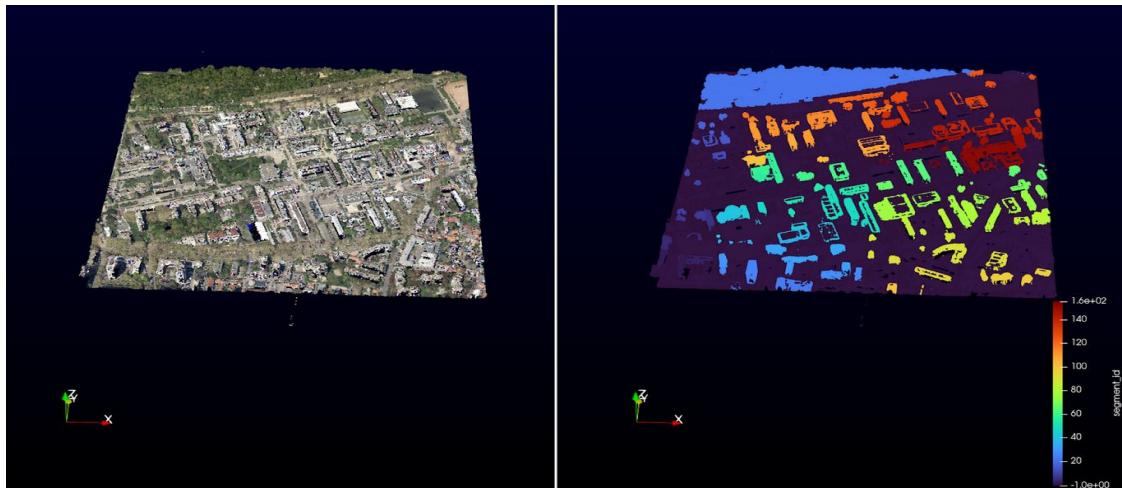
Perspective applications for Aerial LiDAR processing : Multimodal point cloud analysis

- Run SLAM algorithm to aggregate map from the ground (potentially colorized)
- Register it to aerial point cloud (based on initial guess from GPS coordinate, refined with ICP like methods)



Perspective applications for Aerial LiDAR processing : Unsupervised segmentation and automatic dimension extraction

Use Unsupervised segmentation method on massive data and Extract metrics for each georeferenced object



Left :
RGB visualization in LidarView of las
from provided by Grand Lyon (as of
2018)

Right :
Visualization of Segment-lidar (based on Meta's Segment Anything)
results, from
<https://github.com/Yarroudh/segment-lidar>

Perspective applications for Aerial LiDAR processing : Merge with photogrammetry based models

Use lidar scans to improve photogrammetry based reconstruction accuracy



Credits : <https://www.kitware.com/3d-reconstruction-from-satellite-images/>



Take Part in the First ParaView User Day Europe!

Lyon, France - September 19th, 2023

- Inspiring keynotes
- Lightning talks by users
- Kitware one-to-one hands-on sessions
- Demo space
- ParaView dinner (optional)

Join the experience and present!

We understand the value of your expertise, if you want to share with the community, you can submit a presentation title and summary to present during the event.





Thank You!

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