CS 5602 Introduction to Cryptography Lecture 09 Category Theory Chinese Remainder Theorem

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Categories

- A category C is a triple (Obj, Morph, °) where
- Obj are the objects of the category
- Morph are the morphisms between members of Obj
- \bullet If A, B \in Obj, hom $_{c}$ (A,B), or just hom(A,B) if the category is clear, denotes the morphisms from A to B
- Some people call members of hom, homomorphisms, but morphisms is a bit more general
- If $f \in hom(A_iB)$, we write $f: A \rightarrow B$
- ° is an operator called composition

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Moving 2/26 Class

- I need to be at a University of Missouri System event on Tuesday 2/26
- Consequently, I will not be here to give the lecture
- Instead I will give that lecture online, Friday 2/22 from 7:30 8:45 pm
- The lecture will be recorded and you will be able to access the recording in case you can't connect Friday evening
- More details later this week

Categories

- A category C is a triple (Obj, Morph, °) where
- ° is an operator called composition and it seeks to put together morphisms
- In general if $f \in hom(A,B)$ and $g \in hom(B,C)$ then $g^{\circ}f \in hom(A,C)$
- Note hom(A,B) can be empty if $A \neq B$
- In general we get the following picture:



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Category Theory

- This is a very abstract theory, sometime referred to as the theory of "abstract nonsense"
- I have found it a useful way to think about entities of all sorts
- Will give a short introduction to the theory and motivate it with examples

Categories

- · Additional requirements
- ° is associative, i.e., h°(g°f) = (h°g)°f where h ∈ hom(C,D), g ∈ hom(B,C) and f ∈ hom(A,B)
- For every A ∈ Obj, there is an identity morphism in hom(A,A), often denoted by 1_A or id_A, that has the following properties
- For all B ∈ Obj, and f ∈ hom(A,B) and g ∈ hom(B,A), we have f = $f^{\circ}id_{A}$ and g = $id_{A}^{\circ}g$

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Diagram Chasing

• Diagrams play a big part in category theory





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Monomorphism If we have the diagrams below f is a monomorphism iff $f \circ g_1 = f \circ g_2 \Rightarrow g_1 = g_2$

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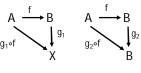
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More on Categories

- Sometimes people write fg instead of f°g if there is no confusion
- Sometimes they will write f(g) and use functional notation
- I will try to use ° consistently at the beginning
- It turns out that the ideas that have been presented to you about injective, surjective and bijective can be generalized to categories
- We will often just write morphisms f, g and $g^{\circ}f$ without always stating that $f \in hom(A,B), g \in hom(B,C)$ and $g^{\circ}f$ in hom(A,C)
- You are expected to supply the objects and homs so that everything makes sense
- Categories are all about the morphisms!

Epimorphism

If we have the diagrams below



f is a epimorphism iff $g_1 \circ f$ = $g_2 \circ f \Rightarrow g_1 = g_2$

Types of Morphisms

An endomorphism is any morphism that belongs to hom(A,A), i.e., it is a morphism from an object to itself

A monomorphism (monic morphism) is a morphism f such that for all morphisms g_1 and g_2 if $f^*g_1 = f^*g_2$ then $g_1 = g_2$ (injection)

• Equivalent to left cancellation

• An epimorphism (epic morphism) is a morphism f such that for all morphisms g_1 and g_2 if $g_1^*f = g_2^*f$ then $g_1 = g_2$ (surjection)

• Equivalent to right cancellation

• A *bimorphism* is a morphism that is both a monomorphism and an epimorphism (bijection)

An automorphism is a morphism that is both a bimorphism and a endormorphism, i.e., it is a member of hom(A,A) that is a bimorphism

Example: The Category of Sets

- · What are the objects?
- What are the morphisms?
- Functions between sets
- What is °?
- Regular function composition
- · Is it a category?
- Yes! Why?

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Sets Form A Category

- Function composition is associative
- There is an identity function for sets
- How about a theorem to prove?
- You might wonder how there is anything to prove since we apparently have not done much

Theorems 2 and 3

- A function in the category of sets is an epimorphism iff it is surjective
- A function in the category of sets is a bimorphism iff it is bijective
- Proof: These will be on the next homework
- Notice that we have generalized the ideas of injective, surjective and bijective in a very general way that has no mention of elements
- Notice the similarity with groups and cancellation laws

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Theorem 1

- A function (morphism) in the category of sets is a monomorphism iff it is injective
- Proof: We break it into two parts (injective → monomorphism) and (monomorphism → injective)
- Suppose f: A → B is injective and suppose g₁: X → A and g₂: X → A
 are such that f°g₁ = f°g₂. This means that for all x ∈ X, f(g₁(x)) = f(g₂(x))
- Since f is injective, this means that $g_1(x) = g_2(x) \forall x$, so $g_1 = g_2$. Thus, f is a monomorphism
- Suppose that f is a monomorphism, but not injective

The Category of Graphs

- The objects are graphs
- Graphs are pairs (V, E) where V is a set of vertices and E is a set of one or two element subsets of V called edges
- · What would be the morphisms for this category?
- You would start out with functions between sets of vertices, but what would be helpful if you wanted to acknowledge the graph structures?
- Definition: if $G=(V_1,E_1)$ and $H=(V_2,E_2)$ are graphs, $f\in hom(G,H)$ means that $f\colon V_1\to V_2$ such that if $\{a,b\}\in E_1$, then $\{f(a),f(b)\}\in E_2$
- In other words, morphisms in the category of graphs preserve edges

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Theorem 1

- If f is not injective, $\exists x, y \in A$ such that $x \neq y$ and f(x) = f(y)
- Let $S = \{1\}$ and let $g_1: S \rightarrow A$ be given by $g_1(1) = x$
- Let $q_2: S \rightarrow A$ be given by $q_2(1) = y$
- Clearly g₁ ≠ g₂
- Note that $f^\circ g_1 = f^\circ g_2$ but $g_1 \neq g_2$ which contradicts the assumption that f is a monomorphism

The Category of Graphs

• Is this a category?

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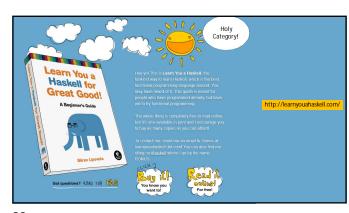
- Function composition is associative
- The identity function on vertices is the identity morphism in the category
- Proving that the identity function is the identity morphism will be a homework exercise

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The Category of Directed Graphs

- It is probably not surprising for you to learn that Directed Graphs are naturally a category
- The morphisms are maps between vertices that preserve arrows
- In other words, if G = (V₁, A₁) and H = (V₂, A₂) are digraphs, f ∈ hom(G,H) means that f: V₁ \rightarrow V₂ such that if (a,b) ∈ A₁, then (f(a), f(b)) ∈ A₂
- Can we say that the Category of Graphs is somehow related to the Category of Digraphs?
- Hold onto that thought for a bit, while we ponder other categories or non-categories



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More Categories

- The category of relations, R₁(A), on a set A. hom(R₁,R₂) = { f : A \rightarrow A | aR₁b \rightarrow f(a)R₂f(b)}
- The category of relations, $R_2(A)$, on a set A. hom $(R_1,R_2) = \{ f : A \rightarrow A \mid aR_1b \text{ iff } f(a)R_2f(b) \}$
- The preceding two categories are different
- It's all about the morphisms!
- Example, let A = { 1, 2, 3}, R₁ = { (1,3), (2, 3) }, R₂ = {(1,1)} and f: A → A be given by f(1) = f(2) = f(3) = 1. Note that $f ∈ hom_{R1}(R_1, R_2)$, but $f ∉ hom_{R2}(R_1, R_2)$ because $f(1)R_2f(2)$ but it is False that $1R_12$.

Theorem

- \bullet Suppose in $R_2(A),$ hom($R_1,R_2)\neq\emptyset$ and R_2 is an equivalence relation then R_1 is an equivalence relation
- Proof

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- Let $a \in A$. Since R_2 is an equivalence relation, $f(a)R_2f(a)$, so by the definition of $R_2(A)$, we see that aR_1a . Thus, R_1 is reflexive.
- Let a, b ∈ A and suppose aR₁b. We know that f(a)R₂f(b), but since R₂ is an equivalence relation, f(b)R₂f(a) and therefore bR₂a. Thus, R₁ is symmetric.
- Let $a,b,c\in A$ and suppose aR_1b and bR_1c . It follows that $f(a)R_2f(b)$ and $f(b)R_2f(c)$. Since R_2 is an equivalence relation, $f(a)R_2f(c)$, whence aR_1c . thus, R_1 is transitive. We now see that R_1 is an equivalence relation

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Still More Categories

- The category of partially ordered sets with the morphisms being order preserving maps between them: a ≤ b → f(a) ≤ f(b)
- Many other mathematical objects form categories!
- Groups, rings, fields, vector spaces, etc....
- The programming language Haskell borrows many ideas from Category Theory
- The chief category in Haskell is called Hask
- The objects of Hask are Haskell types and morphisms are Haskell functions not enough time to present this further

Functors

- Before we noticed that we had two similar categories, Graphs and Digraphs
- It would be nice to have some notion of when categories are related
- This is the idea of a functor
- Let A and B be categories, F: A → B is called a functor if for each object X in A, F(X) is an object in B
- \bullet For each morphism $f\in hom(X,Y),\, F(f)\in hom(F(X),\, F(Y))$ such that
- $F(id_X) = id_{F(X)}$ and
- $F(g^{\circ}f) = F(g)^{\circ} F(f)$

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Functor from Graphs to Digraphs

- • For each G = (V, E) associate the digraph D = (V, A) where (a,b) \in A iff $\{a,\,b\}$ in E
- Note that this adds two arrows for each edge in G except for self-loops in G which give rise to just a self-loop in D
- You would have to show that the identity morphisms are preserved and composition is preserved, but this is pretty straightforward

More Functors

- Let Group be the category of groups where $\text{Hom}(G_1,G_2)$ consists of all group homomorphisms from $G_1\to G_2$
- Note that Hom(G₁,G₂) ≠ Ø because you always have the trivial homorphism where f(q) = 1 ∀ q ∈ G₁
- Let Ring be the category of rings with morphisms being ring homomorphisms
- Let Field be the category of fields with morphisms being field homomorphisms
- • We have all sorts of functors available, for example RG: Ring \rightarrow Group where RG(R) is the (R,+) group
- Consider FG: Field → Group where FG(F) = (F {0},*)
- etc.

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Functor from Digraphs to Graphs

- For each digraph D = (V, A) define a graph G = (V, E) where $\{a,b\}$ in E iff either $(a,b) \in A$ or $(b,a) \in A$
- Note that this basically takes the direction off the arrows
- If you have arrows (a,b) and (b,a) you still only get one edge {a, b}

Applications to Computer Science

- Very important in understanding the semantics of programming languages
- People are very concerned about scaling up programs without errors
- Imperative languages have side-effects which lead to bugs and security holes
- Functional programming languages seek to secure as much of the code as possible
- Much of this work is very abstract and mathematical
- A key feature of the Haskell Programming Language

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Functor from Graphs to Digraphs

- What might this look like?
- \bullet I will ask you this question on the next homework

Category Theory for Computing Science

Michael Barr Charles Wells

http://www.math.mcgill.ca/triples/Barr-Wells-ctcs.pdf

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Category Theory A Gentle Introduction A Gentle Introduction to Category Theory — the calculational approach— Peter Smith University of Cambridge [http://www.logicmatters.net/resources/pdfs/Gentleintro] Maarten M. Fokkinga https://fis.utwente.nl/ws/portalfiles/portal/6141835

Equations

- $7x = 3 \pmod{143}$ has the unique solution x = 123
- Where did that come from?
- 2x = 3 (mod 8) has no solution because 2x is always even and can never have a remainder of 3 mod 8
- 11x = 22 (mod 143) has the following 11 solutions: 2, 15, 28, 41, 54, 67, 80, 93, 106, 119, and 132 (do you see a pattern?)
- · Let's approach this systematically

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Studying \mathbb{Z}_n

- You have already gotten the notion that integers modulo n will be very important in cryptography
- \bullet We will now begin a deeper look at \mathbb{Z}_n and its very interesting properties
- We know that \mathbb{Z}_n is an additive abelian group, but $\mathbb{Z}_n-\{0\}$ is only a multiplicative group if n is a prime
- We know that the elements $q\in\mathbb{Z}_n-\{0\}$ that are relatively prime to n form an abelian, multiplicative group and that this is the largest subset of $\mathbb{Z}_n-\{0\}$ that is a multiplicative subgroup
- If p and q are integers such that GCD(p,q) = 1 we say that p and q are coprime or relatively prime

Solving $ax = b \pmod{n}$

- Note that if ax = b (mod n) this means that \exists c such that ax + cn = b
- Note that if g = GCD(a,n), then (ax + cn) % g = 0
- In particular, there is no solution if $b\%g \neq 0$
- Recall the equations
- 7x = 3 (mod 143), GCD(7,143) = 1 and 3%1 = 0
- $2x = 3 \pmod{8}$, GCD(2,8) = 2 and $3\%2 \neq 0$
- 11x = 22 (mod 143), GCD(11,143) = 11 and 22%11 = 0
- Is b%g = 0 sufficient for there to be a solution of ax = b (mod n)?

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Equations mod n

- Suppose we have equations of the form $a^*x = b \pmod{n}$
- Here are some questions
- Can we always find at least one solution for the above equation?
- Can there be more than one solution for such an equation?
- \bullet If there can be more than one solution, how many solutions can there be?
- Try some equations
- 7x = 3 (mod 143)
- $2x = 3 \pmod{8}$
- 11x = 22 (mod 143)

Solving $ax = b \pmod{n}$

- Suppose b%g = 0, then b = k*g
- Note that from the extended GCD algorithm, \exists s and t such that $g = s^*a + t^*n$, which means that $k^*s^*a + k^*t^*n = k^*g \pmod{n}$ which means that $k^*s^*a = b \pmod{n}$
- Applying this to the equation 7X = 3 (mod 143) we see that GCD(7,143) = 1, 7*41 - 2*143 = 287 - 286 = 1
- Thus, the solution is 3*41 = 123 and indeed 123*7 = 3 + 6*143
- Similarly, for 11x = 22 (mod 143) we see that 1*11 +0*143 = 11, and since 22/11 = 2, we see that x = 2 is a solution of this equation

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Multiple Solutions of $ax = b \pmod{n}$

- Suppose ax = b (mod n) and ay = b (mod n), where x and y are < n
- Then a(x-y) = 0 mod n
- So a(x-y) = kn for some k
- We know that g = GCD(a,n) so a = pg and n =qg where GCD(p,q) = 1
- Write pg(x-y) = kqg so p(x-y) = kq, since p and q are coprime, (x-y) = dg and k = dp
- Thus we see that x = y + dq for some d
- If GCD(a,n) = 1, n = q and (x-y) = 0 (mod n), i.e, the solution is unique

The Chinese Remainder Theorem – Wikipedia (edited)

- The Chinese remainder theorem is a theorem of number theory, which states that if one knows the remainders of the division of an integer n by several integers, then one can determine uniquely the remainder of the division of n by the product of these integers, under the condition that the divisors are pairwise coprime.
- The earliest known statement of the theorem is by the Chinese mathematician Sunzi in the 3rd century AD (not quite 2000 years).
- The Chinese remainder theorem is widely used for computing with large integers, as it allows replacing a computation for which one knows a bound on the size of the result by several similar computations on small integers.
- The Chinese remainder theorem (expressed in terms of congruences) is true over every principal ideal domain. It has been generalized to any commutative ring, with a formulation involving ideals.

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Multiple Solutions of $ax = b \pmod{n}$

- \bullet If GCD(a,n), given a solution y we can see that y + q will be another solution
- \bullet You can generate all solutions by starting at any solution and adding q = n/g repeatedly
- For 11x = 22, we could start with the solution 2 and repeatedly add 143/11 = 13 to get other solutions
- You can start at any solution and derive all the other solutions by adding n/g repeatedly
- You don't have to start with the smallest root since the repeated additions will just wrap around
- Note that the solutions form a subset of \mathbb{Z}_n that is closed under addition and subtraction, but it need not be a subgroup, since 0 might not be in it

The Chinese Remainder Theorem

- The original statement was (Wikipedia)
- There are certain things whose number is unknown. If we count them by threes, we have two left over; by fives, we have three left over; and by sevens, two are left over. How many things are there? (Sunzi, 3rd Century AD)
- $x = 2 \pmod{3}$, $x = 3 \pmod{5}$, and $x = 2 \pmod{7}$
- x = 128
- The first complete solution was published by a Chinese mathematician in 1247

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Systems of Linear Equations

- Consider the system of linear equations
- 1. $x = b_1 \pmod{n_1}$
- 2. $x = b_2 \pmod{n_2}$
- 3. $x = b_3 \pmod{n_3}$
- 4. ..
- 5. $x = b_k \pmod{n_k}$
- Note that the coefficients are all 1 so we know each equation has a unique solution (GCD(1,k) = 1 \forall k)
- · When can we find a solution to the entire system of equations
- This leads us to the Chinese Remainder Theorem

The Chinese Remainder Theorem (CRT)

- Theorem (CRT): Let s and t be coprimes, then the map $f: \mathbb{Z}_{s^*t} \to \mathbb{Z}_s \times \mathbb{Z}_t$ given by f(m) = (m%s, m%t) is a bijection.
- Proof: We first prove that f is an injection. Suppose f(m) = f(n) for two distinct integers.
- This means that m%s = n%s and m%t = n%t
- This means that $(m-n) = 0 \pmod{s}$ and $(m-n) = 0 \pmod{t}$
- This means that (m-n) is divisible by s and by t
- Since s and t are coprime, (m-n) is divisible by s*t, so $m = n \pmod{s*t}$
- Thus, f is an injection
- $\bullet \text{ Note that } \|\mathbb{Z}_{s^*t}\| = s^*t = \|\mathbb{Z}_s\|^* \|\mathbb{Z}_t\| = \|\mathbb{Z}_s \times \mathbb{Z}_t\| \text{ so f must be a bijection}.$

Remarks on the CRT

- Note that the proof we gave was non-constructive in the sense that we know there is a unique solution for each set of equations, but we do not know how to find the solution for each set of equations
- We know that if GCD(s,t) = 1, then $\exists a$, b such that a*s + b*t = 1
- Note that 1 = 1%s = (a*s+b*t)%s = (b*t)%s and 1 = (a*s)%t
- Suppose we want to solve x%s = m and x%t = n
- Consider the value x = n*a*s + m*b*t
- x%s = (n*a*s+m*b*t)%s = (m*b*t)%s = (m%s)*((b*t)%s) = m%s = m
- Similarly, x%t = n%t = n

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Remarks on the CRT

- Note that this result is generally not true if GCD(s,t) ≠ 1
- For example, let s = 4 and t = 6 then (1%4,1%6) = (13%4,13%6) and in general (x%4,x%6) = ((x+12)%4,(x+12)%6)
- In general, we want LCM(s,t) = s*t which happens iff s and t are coprime
- Note LCM(s,t) = s*t/GCD(s,t)