## Section 2

Michael Brodskiy

Professor: A. Martsinkovsky

September 21, 2022

## Contents

Τ.	ist of Figures	
2	Linear Approximation, Tangent Planes, and the Differential	3
1	Partial Derivatives	3

## 1 Partial Derivatives

- The slope of f(x,y) depends on the direction in the xy-plane
  - The slope in the x-direction is called the partial derivative of f with respect to x
  - The slope in the y-direction is called the partial derivative of f with respect to y
  - Notation:  $\frac{\partial f}{\partial x}$ ,  $\frac{\partial f}{\partial y}$  or  $f_x$ ,  $f_y$
  - For Second Derivatives:  $\frac{\partial^2 f}{\partial x^2}$ ,  $\frac{\partial^2 f}{\partial y^2}$ ,  $\frac{\partial^2 f}{\partial y \partial x}$ ,  $\frac{\partial^2 f}{\partial x \partial y}$  or  $f_{xx}$ ,  $f_{xy}$ ,  $f_{yx}$ ,  $f_{yy}$

If  $f, f_x, f_y$ , and  $f_{xy}$  are defined in a small disc around  $(x_o, y_o)$  and  $f_{yx}$  is continuous, then:

$$f_{xy} = f_{yx}$$
 in that disc

- The gradient of f
  - Given  $f(x_1, x_2, ..., x_n)$ , the gradient of f,  $\overline{\nabla} f = \left\langle \frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, ..., \frac{\partial f}{\partial x_n} \right\rangle$
  - It can be computed at a point:  $\overline{\nabla} f(p) = \left\langle \frac{\partial f}{\partial x_1}(p), \frac{\partial f}{\partial x_2}(p), \dots, \frac{\partial f}{\partial x_n}(p) \right\rangle$
  - $\overline{\nabla} f \approx f'(x_o) \Delta x$

## 2 Linear Approximation, Tangent Planes, and the Differential

- In calculus I, the linear approximation is given by:  $f(x) \approx f(a) + f'(a)(x-a)$
- In calculus III, the approximation uses the gradient:  $\Delta f \approx \overline{\nabla} f(p) \cdot \Delta \overline{x}$
- Ex. in  $\mathbb{R}^2$  z = f(x, y), p = (a, b):

$$\Delta f \approx \overline{\nabla} f(a,b) \cdot \langle x-a, y-b \rangle \Rightarrow f(x,y) - f(a,b) \Rightarrow f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b)$$

Thus:

$$f(x,y) \approx f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b)$$

We find the linearization of f(x,y) near (a,b) (in  $\mathbb{R}^2$ )

• Linearization of f(x,y) near (a,b) is denoted by  $L_f(\overline{x},\overline{p})$ , where p is the vector  $\langle a,b\rangle$ 

• Ex. Given a cylinder of radius r = .5 and a height of h = 1, estimate the change in volume when the radius is increased by .1 and the height is decreased by .1

$$V = \pi r^2 h \Rightarrow \Delta V \approx 2\pi (.5)(1)(r - .5) + \pi (.5)^2 (h - 1) = \pi (r - .5) + .25\pi (h - 1) \approx$$
$$-.75\pi + \pi r + .25\pi h \Rightarrow -.75\pi + \pi (.6) + .25\pi (.9) = .075\pi$$

- The graph of  $z = L_f(\overline{x}, \overline{p})$  is called the tangent set to f at p
- Differentials

$$- df = \overline{\nabla} f \cdot d\overline{x}$$

$$- df = f_x dx + f_y dy + f_z dz$$

$$- df = \frac{\partial f}{\partial x_1} dx_1 + \frac{\partial f}{\partial x_2} dx_2 + \dots + \frac{\partial f}{\partial x_n} dx_n$$

- Relative Differentials
  - $-\frac{df}{f}$
  - Think of this as a stencil for relative error  $\left(\frac{\Delta f}{f}\right)$