

# Section 2

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# 1 Partial Derivatives

- The slope of  $f(x, y)$  depends on the direction in the  $xy$ -plane
  - The slope in the  $x$ -direction is called the partial derivative of  $f$  with respect to  $x$
  - The slope in the  $y$ -direction is called the partial derivative of  $f$  with respect to  $y$
  - Notation:  $\frac{\partial f}{\partial x}$ ,  $\frac{\partial f}{\partial y}$  or  $f_x$ ,  $f_y$
  - For Second Derivatives:  $\frac{\partial^2 f}{\partial x^2}$ ,  $\frac{\partial^2 f}{\partial y^2}$ ,  $\frac{\partial^2 f}{\partial y \partial x}$ ,  $\frac{\partial^2 f}{\partial x \partial y}$  or  $f_{xx}$ ,  $f_{xy}$ ,  $f_{yx}$ ,  $f_{yy}$

If  $f$ ,  $f_x$ ,  $f_y$ , and  $f_{xy}$  are defined in a small disc around  $(x_o, y_o)$  and  $f_{yx}$  is continuous, then:

$$f_{xy} = f_{yx} \\ \text{in that disc}$$

- The gradient of  $f$ 
  - Given  $f(x_1, x_2, \dots, x_n)$ , the gradient of  $f$ ,  $\bar{\nabla} f = \left\langle \frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \dots, \frac{\partial f}{\partial x_n} \right\rangle$
  - It can be computed at a point:  $\bar{\nabla} f(p) = \left\langle \frac{\partial f}{\partial x_1}(p), \frac{\partial f}{\partial x_2}(p), \dots, \frac{\partial f}{\partial x_n}(p) \right\rangle$
  - $\bar{\nabla} f \approx f'(x_o) \Delta x$

# 2 Linear Approximation, Tangent Planes, and the Differential

- In calculus I, the linear approximation is given by:  $f(x) \approx f(a) + f'(a)(x - a)$
- In calculus III, the approximation uses the gradient:  $\Delta f \approx \bar{\nabla} f(p) \cdot \Delta \bar{x}$
- Ex. in  $\mathbb{R}^2$   $z = f(x, y)$ ,  $p = (a, b)$ :

$$\Delta f \approx \bar{\nabla} f(a, b) \cdot \langle x - a, y - b \rangle \Rightarrow f(x, y) - f(a, b) \Rightarrow f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)$$

Thus:

$$f(x, y) \approx f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)$$

We find the linearization of  $f(x, y)$  near  $(a, b)$  (in  $\mathbb{R}^2$ )

- Linearization of  $f(x, y)$  near  $(a, b)$  is denoted by  $L_f(\bar{x}, \bar{p})$ , where  $p$  is the vector  $\langle a, b \rangle$

- *Ex. Given a cylinder of radius  $r = .5$  and a height of  $h = 1$ , estimate the change in volume when the radius is increased by  $.1$  and the height is decreased by  $.1$*

$$V = \pi r^2 h \Rightarrow \Delta V \approx 2\pi(.5)(1)(r - .5) + \pi(.5)^2(h - 1) = \pi(r - .5) + .25\pi(h - 1) \approx$$

$$-.75\pi + \pi r + .25\pi h \Rightarrow -.75\pi + \pi(.6) + .25\pi(.9) = .075\pi$$

- The graph of  $z = L_f(\bar{x}, \bar{p})$  is called the tangent set to  $f$  at  $p$
- Differentials

$$- df = \bar{\nabla} f \cdot d\bar{x}$$

$$- df = f_x dx + f_y dy + f_z dz$$

$$- df = \frac{\partial f}{\partial x_1} dx_1 + \frac{\partial f}{\partial x_2} dx_2 + \cdots + \frac{\partial f}{\partial x_n} dx_n$$

- Relative Differentials

$$- \frac{df}{f}$$

$$- \text{Think of this as a stencil for relative error } \left( \frac{\Delta f}{f} \right)$$

### 3 Differentiation Rules

- Linearity of differentiation

$$1. \nabla(af \pm bg) = a\nabla f \pm b\nabla g$$

- Product rule

$$2. \nabla(fg)(p) = \nabla f(p)g(p) = \nabla g(p)f(p)$$

- Quotient rule

$$3. \nabla \left( \frac{f}{g} \right) \Big|_p = \frac{g(p)\nabla f(p) - f(p)\nabla g(p)}{g^2(p)}$$

- Power rule

$$4. \nabla f^\alpha(p) = \alpha f^{\alpha-1}(p)\nabla f(p)$$

- Chain rule

$$5. \frac{df}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \cdots + \frac{\partial f}{\partial z} \frac{dz}{dt} \Rightarrow \nabla f \cdot \frac{d\bar{x}}{dt}$$

- *Ex.* A particle is moving through space. At  $t = 2$  seconds, the particle is at  $(3, 4, 7)$ , and is moving with velocity  $\langle -2, 1, 5 \rangle$  meters per second. Suppose that there is also an electric potential in space, given by  $\phi(x, y, z) = xy - z^2$  volts. Find the instantaneous rate of change,  $w, r, t$ , time  $t$ , of the electric potential at the particle's position at  $t = 2$  seconds.

$$\left. \frac{d\phi}{dt} \right|_{t=2} = \nabla \phi(\langle 3, 4, 7 \rangle) \cdot \left. \frac{d\bar{p}}{dt} \right|_{t=2} = \nabla \phi(\langle 3, 4, 7 \rangle) \cdot v(2) \Rightarrow$$

$$\nabla \phi = \langle y, x, -2z \rangle(\langle 3, 4, 7 \rangle) = \langle 4, 3, -14 \rangle \Rightarrow \langle 4, 3, -14 \rangle \cdot \langle -2, 1, 5 \rangle = -75 \text{ volts per second}$$