## Homework 4

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April 4, 2023

Listing 1: Problem 1

```
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2
3
                          HW4Prob1Brodskiy.py
             Filename:
             Assignment: Homework 4 Problem 1
             Title: Matrix Common Term Finder
          Description:
                          Takes in a matrix and returns terms common to
                          all rows of the matrix
10
               Version:
                          1.0
11
               Created:
                          04/01/2023
12
             Revision:
                          N/A
13
                Python:
                          Python 3.9.2
14
15
                Author:
                          M. Brodskiy
16
17
18
   ,, ,, ,,
19
20
   import numpy as np
21
22
   def comMatTerms(A):
23
24
       uniqMatTerms = np.unique(A)
25
       comTerms = []
26
27
       for uniqVal in uniqMatTerms:
28
29
            B = [A = uniqVal]
30
            addTerm = True
31
32
            for row in B:
33
                 for j in row:
34
                      if (True not in j):
35
                          addTerm = False
36
37
            if addTerm:
38
                 comTerms.append(uniqVal)
39
40
       return np. array (comTerms)
41
```

The same can be done for columns if the transpose of the inputted matrix, A.T, were used in the same function.

Listing 2: Problem 2

```
וו וו וו
2
3
                         HW4Prob2Brodskiy.py
             Filename:
             Assignment: Homework 4 Problem 2
5
             Title: Plot Generator
7
         Description:
                         Generates two types of plots for given
       functions
9
              Version:
                         1.0
10
                         04/01/2023
              Created:
11
             Revision:
                         N/A
12
               Python:
                         Python 3.9.2
13
14
               Author:
                        M. Brodskiy
15
16
17
   ,, ,, ,,
18
19
   import numpy as np
20
   import matplotlib.pyplot as plt
21
  x = np. linspace(-1.5, 1.5, 1000)
23
  y = np. linspace(-1, 1, 1000)
24
25
   def onePlot():
26
       plt.figure()
27
       plt.plot(y, np.sin(np.exp(2*x)), y, np.cos(np.exp(-2*x)), '-r'
28
       plt.grid(axis='both', color='grey', linewidth=0.5, ls='dotted'
29
          , alpha=0.7)
       plt.title ("Two Sinusoidal Functions on One Graph")
30
       plt.xlabel("x-axis from -1.5 to 1.5")
31
       plt.ylabel("$y$-axis from -1 to 1")
32
       plt.legend(["y_1=\sin(e^{2x})", "y_2=\cos(e^{2x})"])
33
       plt.text(.1, 1.05, \$ \sin(e^{2x})), horizontalalignment=
34
          center', verticalalignment='center')
       plt.text(-.6, 1.05, '\frac{1}{\cos(e^{-2x})}', horizontalalignment='
35
          center', verticalalignment='center')
36
   def twoPlot():
37
       plt.figure()
38
```

```
plt.subplot (2, 1, 1)
39
       plt.plot(y, np.sin(np.exp(2*x)), '-b')
40
       plt.title("Two Sinusoidal Functions on Two Graphs")
41
       plt.ylabel("\$\sin(e^{2x})$")
42
       plt.grid(axis='both', color='grey', linewidth=0.5, ls='dotted'
          , alpha=0.7
       plt.text(-.1, .9, \$ \sin(e^{2x})); horizontalalignment='center
44
          ', vertical alignment = 'center')
       plt.legend(["y_1 = \sin(e^{2x})"])
45
       plt.subplot(2, 1, 2)
46
       plt.plot(y, np.cos(np.exp(-2*x)), '-r')
47
       plt.xlabel("$x$-axis")
48
       plt.ylabel("\$ \cos(e^{-2x})")
49
       plt.legend(["$y_2=\cos(e^{-2x})"])
50
       plt.text(-.1, .75, .4 \cos(e^{-2x})), horizontalalignment=
51
          center', verticalalignment='center')
       plt.grid(axis='both', color='grey', linewidth=0.5, ls='dotted'
52
          , alpha=0.7)
53
  onePlot()
54
  twoPlot()
55
  plt.show()
```

Listing 3: Problem 3

```
וו וו וו
 2
 3
                                                                         HW4Prob3Brodskiy.py
                                      Filename:
                                      Assignment: Homework 4 Problem 3
 5
                                      Title: Plot Generator 2.0
 7
                            Description:
                                                                          Generates a plot from parametric function
 9
                                         Version:
                                                                          1.0
10
                                         Created:
                                                                          04/01/2023
11
                                      Revision:
                                                                         N/A
12
                                             Python:
                                                                          Python 3.9.2
13
14
                                             Author:
                                                                         M. Brodskiy
15
16
17
         ,, ,, ,,
18
19
         import numpy as np
20
         import matplotlib.pyplot as plt
21
22
         t = np.linspace(-4 * np.pi, 4 * np.pi, 1000)
        x = np.cos(t) + 2 * np.cos(t / 4)
24
        y = np. sin(t) - 2 * np. sin(t / 4)
25
26
         def parametrize():
27
                      plt.figure()
28
                      plt.plot(y, x)
29
                      plt.grid(axis='both', color='grey', linewidth=0.5, ls='dotted'
30
                                , alpha=0.7)
                      plt. title ("\frac{t}{4} \right  vs. \frac{t}{4} \right  vs. \frac{t}{4}
31
                               (t)+2\cos \left( \frac{t}{4} \right)
                      plt. xlabel("\$ \cos(t)+2\cos\left(t\right)4\\right)$")
32
                      plt.ylabel("\frac{t}{4} \setminus \sin(t) - 2 \sin \left( \frac{t}{4} \right)")
33
                      plt.text(0, 0, "$y=\sin(t)-2\sin\left(\dfrac{t}{4}\\right)
34
                               nx=\cos(t)+2\cos\left(t\right); ", quantized on the state of the stat
                               horizontalalignment='center', verticalalignment='center')
35
         parametrize()
36
         plt.show()
```

Listing 4: Problem 4

```
,, ,, ,,
2
3
                          HW4Prob4Brodskiy.py
             Filename:
             Assignment: Homework 4 Problem 4
5
             Title: Point Class Creator
7
          Description:
                          Defines a Point Class
9
              Version:
                          1.0
10
              Created:
                          04/01/2023
11
             Revision:
                          N/A
12
               Python:
                          Python 3.9.2
13
14
               Author:
                          M. Brodskiy
15
16
17
   ,, ,, ,,
18
19
   import numpy as np
20
21
   class Point:
22
23
       def_{-init_{-}}(self, x, y, z = 0):
24
            self.x = x
25
            self.y = y
26
            self.z = z
27
28
       @property
29
       def _r (self):
30
            return np.sqrt((self.x ** 2) + (self.y ** 2) + (self.z **
31
               2))
32
       def __str__(self):
33
            return str ((self.x, self.y, self.z))
34
35
       def = eq_{-}(self, other):
36
            return (self._r = other._r)
37
38
       def __lt__(self, other):
39
            return (self._r < other._r)
40
41
       def __le__ (self, other):
42
```

```
return self = other or self < other
44
       def = gt = (self, other):
45
           return not self <= other
46
47
       def_{--}ge_{--}(self, other):
48
           return not self < other
49
50
       def __ne__(self, other):
51
           return not self = other
52
53
       def __add__(self, other):
54
           return Point(self.x + other.x, self.y + other.y, self.z +
55
               other.z)
56
       def __iadd__(self, other):
57
           return Point(self.x + other.x, self.y + other.y, self.z +
58
               other.z)
59
       def asdict(self):
60
           return { 'x': self.x, 'y': self.y, 'z': self.z}
61
62
   cur_point = Point(1, 2, 3)
63
   print(cur_point._r)
   cur_point._r = 5 # Read-only attribute modification causes error
65
   print(cur_point._r)
```

Listing 5: Problem 5

```
,, ,, ,,
2
3
              Filename: HW4Prob5Brodskiy.py
              Assignment: Homework 4 Problem 5
5
              Title: Circle Class
7
          Description:
                           Defines a Circle Class, based on Point
9
               Version:
                            1.0
10
               Created:
                            04/01/2023
11
              Revision:
                           N/A
12
                Python:
                           Python 3.9.2
13
14
                Author:
                           M. Brodskiy
15
16
17
   ,, ,, ,,
18
19
   import matplotlib.pyplot as plt
20
   import numpy as np
21
22
   class Point:
23
24
        \operatorname{def} = \operatorname{init}_{--}(\operatorname{self}, x, y, z = 0):
25
             self.x = x
26
             self.y = y
27
             self.z = z
28
29
        @property
30
        def _r (self):
31
             return np.sqrt((self.x ** 2) + (self.y ** 2) + (self.z **
32
                2))
33
        def = str_{-}(self):
34
             return str ((self.x, self.y, self.z))
35
36
        def = eq = (self, other):
37
             return (self._r = other._r)
38
39
        def_{-1}t_{-}(self, other):
40
             return (self._r < other._r)
41
42
```

```
def __le__(self, other):
            return self = other or self < other
44
45
       def_{-gt_{-}}(self, other):
46
           return not self <= other
47
48
       def_{--}ge_{--}(self, other):
49
           return not self < other
50
51
       def = ne_{-}(self, other):
52
           return not self = other
53
54
       def __add__(self, other):
55
           return Point(self.x + other.x, self.y + other.y, self.z +
56
               other.z)
57
       def __iadd__(self, other):
58
            return Point(self.x + other.x, self.y + other.y, self.z +
59
               other.z)
60
       def asdict (self):
61
           return { 'x':self.x, 'y':self.y, 'z':self.z}
62
63
   class Circle():
65
66
       def __init__(self, center, radius):
67
            self.center = center
68
            self._radius = radius
69
70
       @property
71
       def radius(self):
72
           return self._radius
73
74
       @radius.setter
75
       def radius (self, rad):
76
            if (rad < 0): raise ValueError("Negative numbers are not
77
               permitted for radius values")
           else: self._radius = rad
78
79
       def draw(self):
80
           t = np.linspace(-np.pi, np.pi, 1000)
81
           y = (self._radius * np.sin(t)) + self.center.x
           x = (self._radius * np.cos(t)) + self.center.y
83
```

```
plt.figure()
85
           plt.plot(y, x)
86
           plt.grid(axis='both', color='grey', linewidth=0.5, ls='
87
              dotted', alpha=0.7)
           plt.title(f"Circle of radius {self._radius} centered at ({
              self.center.x}, {self.center.y})")
           plt.xlabel("$x$-axis")
           plt.ylabel("$y$-axis")
90
           plt.legend(['(x-\$)' + str(self.center.x) + '\$)^2 + (y-\$)' +
91
              str(self.center.y) + '$)^2=$' + str(self.radius ** 2)
           plt.text(self.center.x, self.center.y, '$(x-$' + str(self.
92
              center.x) + ^{3}^2+(y-^{3} + ^{3}center.y) + ^{3}^2=^{3}
              + str(self._radius ** 2), horizontalalignment='center'
              , verticalalignment='center')
           plt.show()
93
94
  c = Circle(Point(1,4), 2)
95
  c.draw()
96
```

Listing 6: Problem 6

```
,, ,, ,,
2
3
             Filename:
                          HW4Prob6Brodskiy.py
             Assignment: Homework 4 Problem 6
5
             Title: Sphere Class
7
          Description:
                          Defines a Sphere Class, based on Point
9
              Version:
                          1.0
10
              Created:
                          04/01/2023
11
             Revision:
                          N/A
12
               Python:
                          Python 3.9.2
13
14
               Author:
                         M. Brodskiy
15
16
17
   ,, ,, ,,
18
19
   import matplotlib.pyplot as plt
20
   import numpy as np
21
22
   class Point:
23
24
       def = init_{-}(self, x, y, z = 0):
25
            self.x = x
26
            self.y = y
27
            self.z = z
28
29
       @property
30
       def _r (self):
31
            return np.sqrt((self.x ** 2) + (self.y ** 2) + (self.z **
32
               2))
33
       def = str_{-}(self):
34
            return str ((self.x, self.y, self.z))
35
36
       def = eq = (self, other):
37
            return (self._r = other._r)
38
39
       def = -lt = (self, other):
40
            return (self._r < other._r)
41
42
```

```
def __le__(self, other):
            return self = other or self < other
44
45
       def_{-gt_{-}}(self, other):
46
            return not self <= other
47
48
       def_{--}ge_{--}(self, other):
49
            return not self < other
50
51
       def = ne_{-}(self, other):
52
            return not self = other
53
54
       def __add__(self, other):
55
            return Point(self.x + other.x, self.y + other.y, self.z +
56
               other.z)
57
       def __iadd__(self, other):
58
            return Point(self.x + other.x, self.y + other.y, self.z +
59
               other.z)
60
       def asdict (self):
61
            return { 'x': self.x, 'y': self.y, 'z': self.z}
62
63
   class Sphere:
65
       def __init__(self, center, radius):
66
            self.center = center
67
            self._radius = radius
68
69
       @property
70
       def radius (self):
71
            return self._radius
72
73
       @radius.setter
74
       def radius (self, rad):
75
            if (rad < 0): raise ValueError("Negative numbers are not
76
               permitted for radius values")
            else: self._radius = rad
77
78
       @property
79
       def _vol(self):
80
            return (4.0 / 3.0) * np.pi * self._radius ** 3
81
82
       def = str_{-}(self):
83
            return f"The volume of the sphere centered at {self.center
```

```
} with a radius of {self._radius} is equal to {self.
               _vol:.2f}."
85
   class centeredSphere:
86
       def __init__(self, radius):
88
            self.center = Point(0,0,0)
89
            self._radius = radius
90
91
       @property
92
       def radius (self):
93
            return self._radius
94
95
       @radius.setter
96
       def radius (self, rad):
97
            if (rad < 0): raise ValueError("Negative numbers are not
98
               permitted for radius values")
            else: self._radius = rad
99
100
       @property
101
       def _vol(self):
102
            return (4.0 / 3.0) * np.pi * self._radius ** 3
103
104
       def = str_{-}(self):
105
            return f"The volume of the sphere centered at the origin
106
               with a radius of {self._radius} is equal to {self._vol
               :.2 f }."
107
   not Origin = [Sphere (Point (np. random. randint (0,6), np. random. randint
108
      (0,6), np.random.randint(0,6)), np.random.randint(1,6)), Sphere
      Point (np. random. randint (0,6), np. random. randint (0,6), np. random.
      randint (0,6), np.random.randint (1,6), Sphere (Point (np.random.
      randint(0,6), np. random. randint(0,6), np. random. randint(0,6)), np
      . random. randint (1,6)), Sphere (Point (np. random. randint (0,6), np.
      random.randint(0,6),np.random.randint(0,6)), np.random.randint
      (1,6))
109
   Origin = [centeredSphere(np.random.randint(5,11)), centeredSphere(
110
      np.random.randint(5,11))
111
   allSphere = notOrigin + Origin
112
   for i in allSphere:
113
       print(i)
```