Linear Equations

Michael Brodskiy

Professor: Meetal Shah

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• A first-order linear differential equation takes the form:

$$a_1(x)\frac{dy}{dx} + a_0(x)y = g(x)$$

• The standard form (where $P(x) = \frac{a_0(x)}{a_1(x)}$ and f(x) = g(x)) is as follows:

$$\frac{dy}{dx} + P(x)y = f(x)$$

• The solution of such differential equations may be obtained by using the product rule:

$$\frac{d}{dx}[\mu(x)y] = \mu \frac{dy}{dx} + \frac{d\mu}{dx}y = \mu \frac{dy}{dx} + \mu Py$$

This is proven true when:

$$\frac{d\mu}{dx} = \mu P$$
, or $\mu(x) = c_2 e^{\int P(x) dx}$

- This value is known as the integrating factor, I
- Solving a Linear First-Order Equation
 - 1. First, rearrange the equation into standard form
 - 2. Find the integrating factor by locating P(x)
 - 3. Multiply both sides by the integrating factor (and add constant c).
 - 4. Then, solve for y
- Values of x where $a_1(x) = 0$ are known as singular points $(a_1(x))$ is the coefficient of $\frac{dy}{dx}$

- A transient term is one that approaches zero as x approaches infinity (ex. e^{-x})
- When either P(x) or f(x) is a piecewise-defined function, the equation is said to be a piecewise-linear differential equation
- Two important functions defined by integrals exist. These are the error function and the complimentary error function, respectively:

$$erf(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt \quad erfc(x) = \frac{2}{\sqrt{\pi}} \int_x^\infty e^{-t^2} dt$$

• These two functions are related by an identity:

$$erf(x) + erfc(x) = 1$$