## Magnetic Fields in Matter

## Michael Brodskiy

Professor: D. Wood

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• Torque on a Dipole

$$\vec{N} = \vec{m} \times \vec{B}$$

- This is akin to the torque on an electric dipole:

$$\vec{N} = \vec{p} \times \vec{E}$$

- We can calculate the torque to be:

$$\vec{N} = m\vec{B}\sin(\theta)$$

- The energy can be defined as:

$$U = -\vec{m} \cdot \vec{B}$$

- The bound bulk and surface currents can be defined as:

$$\vec{J_b} = \vec{\nabla} \times \vec{M}$$
 and  $\vec{K_b} = \vec{M} \times \hat{\mathbf{n}}$ 

- For a uniform magnetized sphere:

$$\vec{J_b} = 0$$
 and  $\vec{K_b} = M\sin(\theta)\hat{\phi}$ 

$$\vec{A}(r) = \frac{\mu_o}{4\pi} \int \frac{\vec{J}_b}{R} d\tau + \frac{\mu_o}{4\pi} \int \frac{\vec{K}_b}{R} da$$

• Auxiliary Field  $(\vec{H})$ 

$$\vec{H} = \frac{1}{\mu_o} \vec{B} - \vec{M} \Rightarrow \vec{B} = \mu(\vec{H} + \vec{M})$$

- From this formula, we can get:

$$\vec{\nabla} \times \vec{H} = \frac{\vec{\nabla} \times \vec{B}}{\mu_o} - \vec{\nabla} \times \vec{M}$$

- Which can become:

$$\vec{\nabla} \times \vec{H} = \vec{J} - \vec{J_b} = \vec{J_F}$$

• Linear Materials

$$\vec{M} = \chi_m \vec{H}$$

– This is not quite the same as the  $\vec{E}$  case, where  $\vec{p} = \varepsilon_o \chi_e \vec{E}$ 

$$\vec{B} = \mu_o(\vec{H} + \vec{M}) = \mu_o(1 + \chi_m)\vec{H}$$
$$\mu = \mu_o(1 + \chi_m)$$

- Unlike dielectrics,  $\chi_m$  could be either positive or negative
- Paramagnetism signifies  $\chi_m > 0$ , more exactly  $10^{-6} \le \chi_m \le 10^{-1}$ , which means  $\vec{m}$  aligns with  $\vec{B}$
- Diamagnetic materials signify that  $-10^{-9} \le \chi_m \le -10^{-4}$
- Ferromagnetism signifies that the domains of magnetic dipoles align with an external magnetic field, which strengthens the field
  - \* Hysteresis causes the magnetic field to "lag behind" in a ferromagnetic, even when the inducing magnet/magnetic field is gone