Homework 3

Michael Brodskiy

Professor: I. Salama

October 2, 2024

1. Classifying systems as memory-less, time-invariant, linear, causal, and/or stable:

(a)
$$y(t) = 5e^{4t}x(t-1)$$

- Memory: **not** memory-less; the x(t-1) term means the system relies on values other than the present value; therefore, it is not memory-less
- Time-Invariant: **not** time-invariant; we may see that, $y(t t_o)$ changes the t value in the exponential and x(t) statement, while $x(t t_o)$ changes only the x(t) statement; thus, it is not time-invariant, since $x(t t_o) \neq y(t t_o)$
- Linear: the system is linear (see below) because $ax_1(t) + bx_2(t) = ay_1(t) + by_2(t)$

$$ax_1(t) + bx_2(t) \to a5e^{4t}x_1(t-1) + b5e^{4t}x_2(t-1)$$

 $ay_1(t) + by_2(t) \to a5e^{4t}x_1(t-1) + b5e^{4t}x_2(t-1)$

- Causal: the system is causal , because it only depends on past or present values (ex. $t=0 \to y(t)=5e^{4(0)}x(-1)$)
- Stable: Given that the system depends on an exponential e^{4t} , its maximum value is unbounded and, therefore, it is **unstable**

(b)
$$y(t) = \int_{-\infty}^{\frac{t}{2}} x(\tau) d\tau$$

- Memory: **not** memory-less; the system depends on a shift of the t parameter (t/2), and, therefore, does not always depend on the current value of time
- Time-Invariant: **not** time-invariant; $y(t t_o) \neq x(t t_o)$ (see below)

$$x(t - t_o) \to \int_{-\infty}^{\frac{t}{2}} x(\tau - t_o) d\tau$$
$$y(t - t_o) \to \int_{-\infty}^{\frac{(t - t_o)}{2}} x(\tau - t_o) d\tau$$
$$\therefore x(t - t_o) \neq y(t - t_o)$$

• Linear: the system **is** linear; it follows both the superposition and homogeneity principles (see below)

$$ay_{1}(t) + by_{2}(t) \to a \int_{-\infty}^{\frac{t}{2}} x_{1}(\tau) d\tau + b \int_{-\infty}^{\frac{t}{2}} x_{2}(\tau) d\tau$$

$$ax_{1}(t) + bx_{2}(t) \to a \int_{-\infty}^{\frac{t}{2}} x_{1}(\tau) d\tau + b \int_{-\infty}^{\frac{t}{2}} x_{2}(\tau) d\tau$$

$$\therefore ax_{1}(t) + bx_{2}(t) = ay_{1}(t) + by_{2}(t)$$

- Causal: the system **is not** causal; integration depends on future values when t < 0
- Stable: the system is **not** stable (see below)

$$y(t) = \int_{-\infty}^{\frac{t}{2}} x(\tau) d\tau$$

$$h(t) = \int_{-\infty}^{\frac{t}{2}} \delta(\tau) d\tau = \begin{cases} 0, & t < 0 \\ 1, & t > 0 \end{cases}$$

$$h(t) \to u(t)$$

$$\int_{-\infty}^{\infty} h(t) dt = \infty$$

(c)
$$y(t) = 4 + 5\frac{d^2}{dt^2}x(t)$$

- Memory: the system is **not** memory-less; the use of a differential implies that the system depends on past values
- Time-Invariant: the system is time-invariant (see below)

$$x(t - t_o) \to 4 + 5\frac{d^2}{dt^2}x(t - t_o)$$
$$y(t - t_o) \to 4 + 5\frac{d^2}{dt^2}x(t - t_o)$$
$$\therefore x(t - t_o) = y(t - t_o)$$

• Linear: the system is **not** linear (see below)

$$ax_1(t) + bx_2(t) = \left(4 + 5a\frac{d^2}{dt^2}x_1(t)\right) + \left(4 + 5b\frac{d^2}{dt^2}x_2(t)\right)$$
$$ay_1(t) + by_2(t) = a\left(4 + 5\frac{d^2}{dt^2}x_1(t)\right) + b\left(4 + 5\frac{d^2}{dt^2}x_2(t)\right)$$
$$\therefore ax_1(t) + bx_2(t) \neq ay_1(t) + by_2(t)$$

- Causal: the system is causal because it only depends on past or present values
- Stable: the system is **unstable** because it is unbounded

(d)
$$y(t) = \begin{cases} 0, & t < 0 \\ x(t-2) + 2x(t), & t \ge 0 \end{cases}$$

- Memory: the system is **not** memory-less, since the x(t-2) term depends on a past value
- Time-Invariant: the system is **not** time-invariant (see below)

$$x(t - t_o) \to \begin{cases} 0, & t < 0 \\ x(t - 2 - t_o) + 2x(t - t_o), & t \ge 0 \end{cases}$$
$$y(t - t_o) \to \begin{cases} 0, & t < 2 \\ x(t - 2 - t_o) + 2x(t - t_o), & t \ge 2 \end{cases}$$
$$\therefore x(t - t_o) \neq y(t - t_o)$$

• Linear: the system **is** linear (see below)

$$ax_{1}(t) + bx_{2}(t) \rightarrow \begin{cases} 0, & t < 0 \\ ax_{1}(t-2) + 2ax_{1}(t) + bx_{2}(t-2) + 2bx_{2}(t), & t \ge 0 \end{cases}$$

$$ay_{1}(t) + by_{2}(t) \rightarrow \begin{cases} 0, & t < 0 \\ ax_{1}(t-2) + 2ax_{1}(t) + bx_{2}(t-2) + 2bx_{2}(t), & t \ge 0 \end{cases}$$

$$\therefore ax_{1}(t) + bx_{2}(t) = ay_{1}(t) + by_{2}(t)$$

- Causal: the system is causal because it only depends on past or present values
- Stable: the system is stable, because it does not tend to diverge

Problem 1 can be tabulated as follows:

System	a	b	c	d
Memory-Less	no	no	no	no
Time-Invariant	no	no	yes	no
Linear	yes	yes	no	yes
Causal	yes	no	yes	yes
Stable	no	no	no	yes

2. Classifying systems as memory-less, time-invariant, linear, causal, and/or stable:

(a)
$$y[n] = x[n+1] - 2x[n-4]$$

- Memory: system is **not** memory-less, as it depends on past and future values
- Time-Invariant: system is time-invariant (see below)

$$x[n - n_o] = x[n + 1 - n_o] - 2x[n - 4 - n_o]$$
$$y[n - n_o] = x[n + 1 - n_o] - 2x[n - 4 - n_o]$$
$$\therefore x[n - n_o] = y[n - n_o]$$

• Linear: system is linear (see below)

$$ax_1[n] + bx_2[n] = a(x_1[n+1] - 2x_1[n-4]) + b(x_2[n+1] - 2x_2[n-4])$$

$$ay_1[n] + by_2[n] = a(x_1[n+1] - 2x_1[n-4]) + b(x_2[n+1] - 2x_2[n-4])$$

$$\therefore ay_1[n] + by_2[n] = ax_1[n] + bx_2[n]$$

- Causal: system is **not** causal, as it depends on past and present values
- Stable: system is stable because y[n] is finite
- (b) $y[n] = \text{Even} \{x[n-1]\}$

To simplify analysis, we can express the even function as:

$$\frac{x[n] + x^*[-n]}{2} \to \frac{x[n-1] + x^*[-n+1]}{2}$$

- Memory: system is **not** memory-less, as it depends on future values
- Time-Invariant: system is time-invariant (see below)

$$x[n - n_o] = \text{Even} \{x[n - 1 - n_o]\}$$
$$y[n - n_o] = \text{Even} \{x[n - 1 - n_o]\}$$
$$\therefore x[n - n_o] = y[n - n_o]$$

• Linear: system is **not** linear (see below); note that this is because a or b may be complex. Given this, for a purely real signal, the system can be classified as linear; however, due to the need to use the 'conjugate' for the even function, in the case of a complex signal, this is non-linear

$$ax_1[n] + bx_2[n] = \frac{ax_1[n-1] + a^*x_1^*[-n+1]}{2} + \frac{bx_2[n-1] + b^*x_2^*[-n+1]}{2}$$

$$ay_1[n] + by_2[n] = \frac{ax_1[n-1] + ax_1^*[-n+1]}{2} + \frac{bx_2[n-1] + bx_2^*[-n+1]}{2}$$

$$\therefore ay_1[n] + by_2[n] \neq ax_1[n] + bx_2[n]$$

- Causal: system is **not** causal, as it depends on a future value
- Stable: system is stable because y[n] is finite
- (c) y[n] = 5x[3n+1]
 - Memory: system is **not** memory-less, as it depends on non-present values
 - Time-Invariant: system is **not** time-invariant (see below)

$$x[n - n_o] = 5x[3n - n_o + 1]$$

 $y[n - n_o] = 5x[3n - 3n_o + 1]$
 $\therefore x[n - n_o] \neq y[n - n_o]$

• Linear: system is linear (see below)

$$ax_1[n] + bx_2[n] = 5ax_1[3n+1] + 5bx_2[3n+1]$$

 $ay_1[n] + by_2[n] = 5ax_1[3n+1] + 5bx_2[3n+1]$
 $\therefore ay_1[n] + by_2[n] = ax_1[n] + bx_2[n]$

- Causal: system is **not** causal, as it depends on a future value
- Stable: system is stable because y[n] is finite

(d)
$$y[n] = \begin{cases} 0, & n = 2\\ x[n], & \text{otherwise} \end{cases}$$

- Memory: system is memory-less; it does not depend on past or present values
- Time-Invariant: system is **not** time-invariant (see below)

$$x[n - n_o] = \begin{cases} 0, & n = 2\\ x[n - n_o], & \text{otherwise} \end{cases}$$
$$y[n - n_o] = \begin{cases} 0, & n = 2 + n_o\\ x[n - n_o], & \text{otherwise} \end{cases}$$
$$\therefore x[n - n_o] \neq y[n - n_o]$$

• Linear: system is linear (see below)

$$ax_1[n] + bx_2[n] = \begin{cases} 0, & n = 2\\ ax_1[n] + bx_2[n], & \text{otherwise} \end{cases}$$

 $ay_1[n] + by_2[n] = \begin{cases} 0, & n = 2\\ ax_1[n] + bx_2[n], & \text{otherwise} \end{cases}$
 $\therefore ay_1[n] + by_2[n] = ax_1[n] + bx_2[n]$

- Causal: system is causal, as it depends on only past or present values
- Stable: system is stable because y[n] is finite
- 3. (a) We may begin by constructing the expression for the convolution sum:

$$y[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$$

This gets us:

$$y[n] = \sum_{k=-\infty}^{\infty} \left(\frac{1}{4}\right)^{k-2} u[k-2]u[n-k+1]$$

We may observe the following:

$$x[n] \neq 0, \quad n \geq 2$$

$$h[n] \neq 0, \quad n \geq -1$$

Integrating this into the convolution sum, we may see that the expression is nonzero (unit functions both exist) for $k \geq 2$, and that $k \leq n + 1$. Thus, we get:

$$y[n] = \sum_{k=2}^{n+1} \left(\frac{1}{4}\right)^{k-2}$$

Using the expansion for series, we obtain:

$$y[n] = \frac{1 - (.25)^{n-1}}{1 - .25}$$
$$y[n] = \frac{4}{3} \left[1 - \left(\frac{1}{4}\right)^{n-1} \right] \text{ for } n \ge 2$$

This can be sketched as:

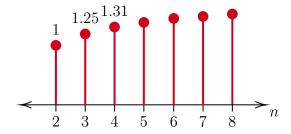


Figure 1: Sketch of y[n]

(b) Per the time-shifting property, we know that:

$$y[n] = x[n] * h[n] \to y_1[n] = y[n-3] = x[n-3] * h[n]$$

Which gives us:

$$y_1[n] = \frac{4}{3} \left[1 - \left(\frac{1}{4}\right)^{n-4} \right] \text{ for } n \ge 5$$

(c) Per the time-shifting property, we know that:

$$y[n] = x[n] * h[n] \to y_2[n] = y[n-2] = x[n] * h[n-2]$$

$$y_2[n] = \frac{4}{3} \left[1 - \left(\frac{1}{4}\right)^{n-3} \right] \text{ for } n \ge 4$$

(d) Per the time-shifting property, we know that:

$$y[n] = x[n] * h[n] \to y_3[n] = y[n+1] = x[n-2] * h[n+3]$$

$$y_3[n] = \frac{4}{3} \left[1 - \left(\frac{1}{4}\right)^n \right] \text{ for } n \ge 1$$

4. To simplify the analysis, we can defined the given functions as:

$$x[n] = u[n-1] - u[n-3]$$
$$h[n] = u[n-5] - u[n-10]$$

From here, we apply the sum:

$$y[n] = \sum_{k=-\infty}^{\infty} (u[k-1] - u[k-3])(u[n-k-5] - u[n-k-10])$$

$$y[n] = \sum_{k=-\infty}^{\infty} u[k-1]u[n-k-5] - u[k-3]u[n-k-5] - u[k-1]u[n-k-10] + u[k-3]u[n-k-10]$$

By observation, we find:

Term
$$1 \neq 0$$
, $n-5 \geq k \geq 1$
Term $2 \neq 0$, $n-5 \geq k \geq 3$
Term $3 \neq 0$, $n-10 \geq k \geq 1$
Term $4 \neq 0$, $n-10 > k > 3$

We see the smallest non-zero value for which a term exists is $k \geq 1$, and the largest value for which a term exists is n-5. We can apply these bounds:

$$y[n] = \sum_{k=1}^{n-5} u[k-1]u[n-k-5] - u[k-3]u[n-k-5] - u[k-1]u[n-k-10] + u[k-3]u[n-k-10]$$

We can break the sum down by looking at 'zones' for the terms. For k = 1, 2, two terms exist:

$$y_1[n] = \sum_{k=1}^{2} u[k-1]u[n-k-5] - u[k-1]u[n-k-10]$$
$$y_1[n] = u[n-6] - u[n-11] + u[n-7] - u[n-12]$$

- 5.
- 6. (a)
 - (b)
 - (c)
- 7.
- 8. (a)
 - (b)
- 9. (a)
 - (b)