Quiz 2

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I. • Linearity: Linear

We may test for linearity by checking that:

$$ax_1(t) + bx_2(t) = ay_1(t) + by_2(t)$$

First, we find:

$$ax_1(t) + bx_2(t) = ae^{2t}x_1(t-1)\cos\left(\frac{\pi}{4}t\right) + be^{2t}x_2(t-1)\cos\left(\frac{\pi}{4}t\right)$$

And then we find:

$$ay_1(t) + by_2(t) = ae^{2t}x_1(t-1)\cos\left(\frac{\pi}{4}t\right) + be^{2t}x_2(t-1)\cos\left(\frac{\pi}{4}t\right)$$

Therefore, because the condition from above is met, the system is linear

• Time-Variance: **Time-Varying**

We may text for time-variance by checking:

$$x(t - t_o) = y(t - t_o)$$

First, we find:

$$x(t - t_o) = e^{2t}x(t - t_o - 1)\cos\left(\frac{\pi}{4}t\right)$$

Then, we find:

$$y(t - t_o) = e^{2(t - t_o)}x(t - t_o - 1)\cos\left(\frac{\pi}{4}(t - t_o)\right)$$

Therefore, because $x(t - t_o) \neq y(t - t_o)$, the system is time-varying

• Causality: Causal — By observation, we may see that the function depends on only past or present values of t, and, therefore, it is causal

- Stability: Unstable We may find whether the function is stable by integrating over its entire range and determining whether the value is finite. By observation, the positive exponential, e^{2t} , would diverge, and, therefore, the integrate would evaluate to infinity. Therefore, the system is unstable
- Invertibility: Non-invertible We know that a system is non-invertible if two values of t produce the same response. Since the sinusoid oscillates, we may observe that there are many repeated values. Most evidently, we may see that y(t) would be zero for every t = 4n + 2. Therefore, the system is not invertible
- II. A. We may find $y_1[n]$ by taking $y_1[n] = x_1[n] * h[n]$. Given that $x_1[n]$ consists only of a delta function, we may use the sifting property to evaluate:

$$x[n] * \delta[n - n_o] = x[n - n_o]$$

We may write our case as:

$$y_1[n] = h[n] * (5\delta[n-2])$$

 $y_1[n] = 5h[n-2]$

Since we know the system is linear and time invariant, we may write:

$$y_1[n] = 5\left(\frac{1}{4}\right)^{n-2}u[n-2]$$

B. To simplify analysis, we may define $x_2[n] = 4(\delta[n+1] + \delta[n] + \delta[n-1])$. Using the same sifting property as part (A), we write:

$$y_2[n] = h[n] * x_2[n]$$

$$y_2[n] = 4h[n] * (\delta[n+1] + \delta[n] + \delta[n-1])$$

$$y_2[n] = 4h[n+1] + 4h[n] + 4h[n-1]$$

We may write this as:

$$y_2[n] = 4\left(\frac{1}{4}\right)^{n+1}u[n+1] + 4\left(\frac{1}{4}\right)^nu[n] + 4\left(\frac{1}{4}\right)^{n-1}u[n-1]$$

Given that $4 = \frac{1}{4}^{-1}$, we may simplify this as:

$$y_2[n] = \left(\frac{1}{4}\right)^n u[n+1] + \left(\frac{1}{4}\right)^{n-1} u[n] + \left(\frac{1}{4}\right)^{n-2} u[n-1]$$