Homework 4

Michael Brodskiy

Professor: I. Salama

October 11, 2024

1. (a) We begin by taking the Laplace transform to get:

$$H(s) = -\frac{1}{s-1}$$
 and $X(s) = \frac{2}{s} \left[e^{-s} - e^{-2s} \right]$

We then multiply the two to get:

$$Y(s) = X(s)H(s)$$

$$Y(s) = -\frac{2}{s(s-1)} \left[e^{-s} - e^{-2s} \right]$$

Using partial fraction decomposition, we may write the equivalent such that:

$$-\frac{2}{s(s-1)} = \frac{A}{s-1} + \frac{B}{s} = As + B(s-1)$$

We use s = 0, 1 to get:

$$A = -2, B = 2 \rightarrow -\frac{2}{s-1} + \frac{2}{s}$$

We now distribute this in the above case to get:

$$Y(s) = -\frac{2}{s-1} \left[e^{-s} - e^{-2s} \right] + \frac{2}{s} \left[e^{-s} - e^{-2s} \right]$$
$$Y(s) = -\frac{2e^{-s}}{s-1} + \frac{2e^{-2s}}{s-1} + \frac{2e^{-s}}{s} - \frac{2e^{-2s}}{s}$$

Finally, we take the inverse transform to get:

$$y(t) = -2u(1-t) + 2e^{t-1}u(1-t) + 2u(2-t) - 2e^{t-2}u(2-t)$$

(b) Differentiating one of the inputs is the same as differentiating the output. Thus, we may say:

$$g(t) = \frac{d}{dt}[y(t)]$$

$$g(t) = 2e^{t-1}u(1-t) - 2e^{t-2}u(2-t)$$

- (c) As stated in (b) g(t) = (d/dt)[y(t)]
- (d) z(t) is the same as g(t). Since taking the differential is a linear operation, it does not matter if this is done to the impulse response or to x(t). Therefore, we get:
- (e) By linearity of the transform, we may say:

$$y_1(t) = 2y(t-1)$$

Therefore, we may obtain:

$$y_1(t) = -4u(2-t) + 4e^{t-2}u(2-t) + 4u(3-t) - 4e^{t-3}u(3-t)$$

- 2. (a)
 - (b)
 - (c)
 - (d)
- 3. (a) Given the set up, we may write:

$$\left(\frac{1}{4}\right)^n u[n] - A\left(\frac{1}{4}\right)^{n-1} u[n-1] = \delta[n]$$

We may redefine the delta as:

$$\left(\frac{1}{4}\right)^n u[n] - A\left(\frac{1}{4}\right)^{n-1} u[n-1] = u[n] - u[n-1]$$

Thus, we see that we need the exponential term to cancel. We can do this by simply taking:

$$\left(\frac{1}{4}\right)^n = A\left(\frac{1}{4}\right)^{n-1}$$

Dividing the exponential from one side to the other, we see:

$$A = \left(\frac{1}{4}\right)^1$$

$$A = \frac{1}{4}$$

(b) By definition, with h[n] and $g[n] = h_{inv}[n]$, we know:

$$h[n]*g[n] = \delta[n]$$

Using the equation from part (a), we know:

$$h[n] - Ah[n-1] = \delta[n]$$

By the properties of convolution, we know that:

$$x[n] * \delta[n - n_o] = x[n - n_o]$$

Thus, we may expand to write:

$$h[n] * \delta[n] - Ah[n] * \delta[n-1] = \delta[n]$$

$$h[n] * (\delta[n] - A\delta[n-1]) = \delta[n]$$

Thus, combining this with the definition of inverse, we may write:

$$g[n] = \delta[n] - \frac{1}{4}\delta[n-1]$$

(c)

- 4. (a)
 - (b)
 - (c)
 - (d)
- 5. (a) For the given system, we may see that, for t < 0, the response may be non-zero (more precisely, it is non-zero for $-\infty < t < 5$); therefore, the system is not causal. We check for stability below:

$$\int_{-\infty}^{5} e^{-3t} dt$$
$$e^{-3t} |_{5}$$

$$-\frac{e^{-3t}}{3}\Big|_{-\infty}^5 = \infty$$

Therefore, the system is <u>not stable</u>

(b) We may see that, for the given system, for t < 0, the response may be non-zero (more precisely, it is non-zero for t > -10); therefore, the system is <u>not causal</u>. We check for stability below:

$$\int_{-10}^{\infty} e^{-4t} dt$$

$$-\frac{e^{-4t}}{4} - 10^{\infty} = \frac{e^{40}}{4} < \infty$$

Thus, we see that the system is stable

(c) We may rewrite the function as:

$$x(t) = \begin{cases} e^{-2t}, & t \ge 0\\ e^{2t}, & t < 0 \end{cases}$$

Because the value of the function is non-zero when t < 0, we can see that it is not causal

We may check for stability below:

$$\int_{-\infty}^{0} e^{2t} dt + \int_{0}^{\infty} e^{-2t} dt$$
$$\frac{e^{2t}}{2} \Big|_{-\infty}^{0} - \frac{e^{-2t}}{2} \Big|_{0}^{\infty} = 1$$

Therefore, we may see that the system is stable

(d) We may see that, because the system is zero for $t \leq 0$, it is causal. We now check for stability:

$$\int_{2}^{\infty} 3e^{-2t} - e^{-.05t + 5} dt$$
$$3e^{-2t} - e^{-.05t + 5} \Big|_{2}^{\infty} = e^{4.9} - \frac{3}{e^4} < \infty$$

Therefore, we may see that the system is stable

6. We may begin by observing that x(t) may be expressed as a summation of impulses, written as:

$$x(t) = \sum_{n = -\infty}^{\infty} \delta(t - nT)$$

Convolving this with h(t), by the property that $x(t) * \delta(t - t_o) = x(t - t_o)$, we may write:

$$y(t) = \sum_{n=-\infty}^{\infty} h(t - nT)$$

To expand this, we may write:

$$y(t) = \cdots + h(t+3T) + h(t+2T) + h(t+T) + h(t) + h(t-T) + h(t-2T) + h(t-3T) + \cdots$$

We begin by analyzing the T=1 case. Summing these graphically, we obtain:

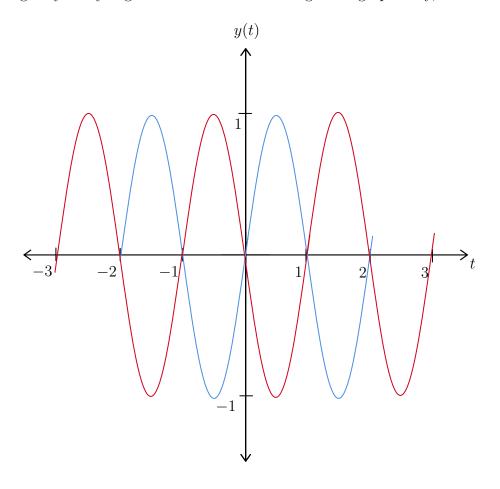


Figure 1: T = 1 Case Graphically Summed

For ease of interpretation, the graph above shows the sum expanded above, with n even cases in red and n odd in blue. We may thus see that, summing the two, we simply obtain y(t) = 0, or a flat line on the t axis. Applying similar logic to t = 2, we may draw the corresponding sinusoids to find:

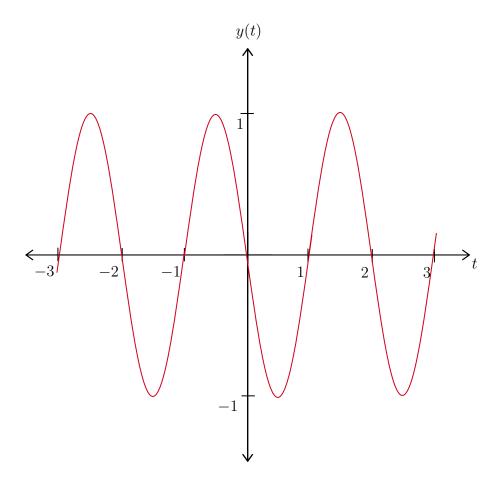


Figure 2: T = 2 Case Graphically Summed

We may observe that this sinusoid consists solely of the even sinusoids from Figure 1. This makes sense, as using T=2 effectively doubles every n, making the shift even. Therefore, we obtain the solution shown in Figure 2. We may write this as:

$$y(t) = \dots + h(t+6) + h(t+4) + h(t+2) + h(t) + h(t-2) + h(t-4) + h(t-6) + \dots$$
$$y(t) = \sum_{n=-\infty}^{\infty} h(t-2n)$$

7. (a) Given the form of x(t), we know y(t) is of the form:

$$y(t) = Ae^{(-1+2j)t}$$

Plugging this into the given equation, we get:

$$A(-1+2j)e^{(-1+2j)t} + 3Ae^{(-1+2j)t} = e^{(-1+2j)t}$$

This simplifies to:

$$A(-1+2j) + 3A = 1$$
$$A = \frac{1}{2j+2}$$

And gives us the particular equation:

$$y_p(t) = \frac{e^{(-1+2j)t}}{2j+2}$$

We can now find the homogenous solution, with general form of y(t):

$$y_h(t) = Ae^{\lambda t}$$

Using our equation, we may obtain:

$$A\lambda e^{\lambda t} + 3Ae^{\lambda t} = 0$$
$$\lambda = -3$$

Combing the two we get:

$$y(t) = Ae^{-3t} + \frac{e^{(-1+2j)t}}{2j+2}$$

Applying the initial rest condition, we get:

$$0 = A + \frac{1}{2j+2}$$
$$A = -\frac{1}{2j+2}$$

Thus, ensuring that there is a response only for t > 0, we finally get:

$$y(t) = \frac{1}{2+2j} \left[e^{(-1+2j)t} - e^{-3t} \right] u(t)$$

(b) We can expand our answer from (a):

$$y(t) = \frac{1}{2+2j} \left[e^{-t} \cos(2t) + je^{-t} \sin(2t) - e^{-3t} \right] u(t)$$

Multiplying by the conjugate, we get:

$$y(t) = (.25 - .25j) \left[e^{-t} \cos(2t) + j e^{-t} \sin(2t) - e^{-3t} \right] u(t)$$
$$y(t) = \left[.25e^{-t} \cos(2t) + .25e^{-t} \sin(2t) - .25e^{-3t} \right] u(t)$$

Therefore, our output becomes:

$$y(t) = \left[.25e^{-t}\sin(2t) + .25e^{-t}\cos(2t) - .25e^{-3t} \right] u(t)$$

8. • We know that the equations governing time response of an inductor and capacitor are (respectively):

$$y(t) = L \frac{di(t)}{dt}$$
 and $i(t) = C \frac{dV_c(t)}{dt}$

We know that the voltage across the capacitor will be the difference between the voltage supplied and the voltage across the inductor; thus, we may write:

$$i(t) = C\frac{d}{dt}[x(t) - y(t)]$$

Inserting this into the inductor equation, we get:

$$y(t) = L \frac{d}{dt} \left[C \frac{d}{dt} \left[x(t) - y(t) \right] \right]$$

$$y(t) = LC \frac{d^2}{dt^2} \left[x(t) - y(t) \right]$$

Putting similar terms to one side, we may write:

$$\frac{d^2y(t)}{dt^2} + \frac{1}{LC}y(t) = \frac{d^2x(t)}{dt^2}$$

Inserting known values:

$$\frac{d^2y(t)}{dt^2} + 25y(t) = \frac{d^2x(t)}{dt^2}$$

• Taking $x(t) \to 0$, we find the homogenous solution form as:

$$\frac{d^2y(t)}{dt^2} + 25y(t) = 0$$

Using the provided equation, we insert into the above:

$$[K_1\omega_1^2 e^{j\omega_1 t} + K_2\omega_2^2 e^{j\omega_2 t}] + 25[K_1 e^{j\omega_1 t} + K_2 e^{j\omega_2 t}] = 0$$

Dividing by the exponentials, we get:

$$K_1\omega_1^2 + K_2\omega_2^2 + 25K_1 + 25K_2 = 0$$

By observation, we may see that:

$$\omega_1 = \omega_2 = \pm 5$$

• From part (b), we see that the natural (homogenous) response may be modeled by:

$$y(t) = Ae^{j5t} + Be^{-j5t}$$

We may take $A = \frac{1}{2}(a+b)$ and $B = \frac{1}{2}(a-b)$. We then apply Euler's Law to get:

$$y(t) = a\cos(5t) + b\sin(5t)$$

We may thus observe that the natural response is sinusoidal in nature.